

NSG-1077

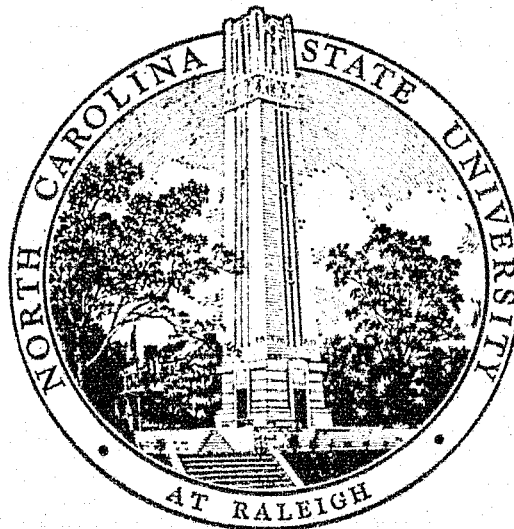
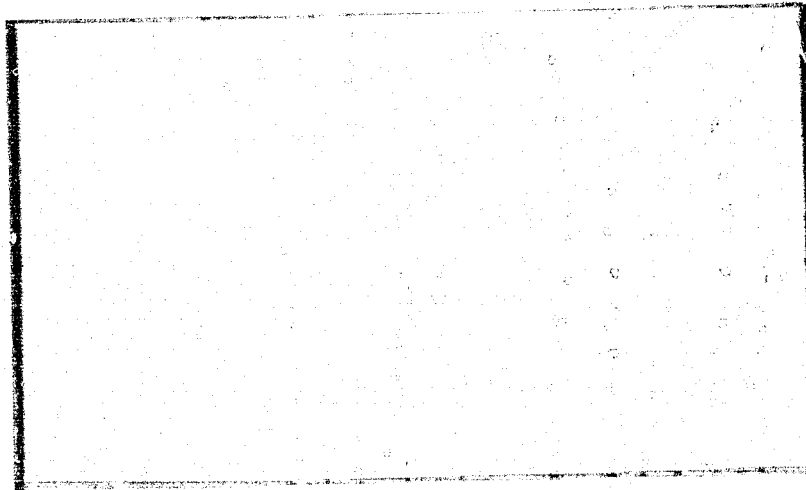
(NASA-CR-158076) FLIGHT TEST EVALUATION OF
PREDICTED LIGHT AIRCRAFT DRAG, PERFORMANCE,
AND STABILITY (North Carolina State Univ.)
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A new technique was developed which permits simultaneous extraction of complete lift, drag, and thrust power curves from time histories of a single aircraft maneuver such as a pullup (from $V_{\max}$ to V_{stall}) and pushover (to $V_{\max}$ for level flight.) The technique is an extension to non-linear equations of motion of the parameter identification methods of Iliff and Taylor and includes provisions for internal data compatibility improvement as well. The technique was shown to be capable of correcting random errors in the most sensitive data channel and yielding highly accurate results. Flow charts, listings, sample inputs and outputs for the relevant routines are provided as appendices. This technique was applied to flight data taken on the ATLIT aircraft. Lack of adequate knowledge of the correct full-throttle thrust horsepower-true air-speed variation and considerable internal data inconsistency made it impossible to apply the trajectory matching features of the technique. The drag and power values obtained from the initial least squares estimate are about 15% less than the "true" values. Compared with predicted values developed using previous work at N. C. State, the extracted drag is generally higher. If one takes into account the rather "dirty" wing and fuselage existing at the time of the tests, however, the predictions are reasonably accurate. The steady state lift measurements agree well with the extracted values only for small values of α . The predicted value of the lift at $\alpha = 0$ is about 33% below that found in steady state tests while the predicted lift slope is 13% below the steady state value. Because the data processing procedure was unable to proceed beyond this initial extraction, detailed performance and stability comparisons with predictions were not attempted.

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NOMENCLATURE

- a_x - linear acceleration along x-body axis.
- B - coefficient used in calculating bias error in α (p. 103).
- c - specific fuel consumption.
- C_D - drag coefficient.
- C_L - lift coefficient.
- C_ℓ - general representation of a parameter (p. 111).
- CLA - rate of change of lift coefficient with angle of attack.
- CLAO - lift coefficient when $\alpha = 0$.
- CLAX - rate of change of lift coefficient with respect to α^x .
- CLQ - rate of change in lift coefficient with pitching velocity.
- D - drag.
- D - weights on elements of cost function.
- d - dimensionless numbers used to scale weights in cost function.
- E_{m_i} - energy, measured at specific point.
- $f(t)$ - function of time.
- $f(\alpha)$ - functional representation for use in Newton-Raphson process (p. 106).
- g - acceleration due to gravity.
- h - altitude.
- $\dot{h}$ - rate of climb.
- $\ddot{h}$ - altitude acceleration.
- $H(n)$ - filter response.
- J - cost function.
- L - lift.
- M - slope.

- $\dot{m}$ - mass flow rate.
- n - number of harmonics.
- P - power (p. 36).
- P - altitude pressure (p. 66).
- P_S - stagnation pressure.
- $\dot{P}$ - time rate of change of pressure.
- q - pitching velocity.
- $\dot{q}$ - pitching acceleration.
- q_c - differential pressure between pitot and static pressures.
- R - gas constant for air.
- r - radial displacement or yaw rate.
- S - area (p. 19).
- S - fit error (p. 38).
- S_T - tail area.
- S_W - wing area.
- T - thrust (p. 36).
- T - total time (p. 53).
- T - local free stream absolute temperature (p. 68).
- t - time.
- T_S - stagnation temperature.
- u - component of aircraft velocity on x-body axis (p. 65).
- u - fluid velocity (p. 70).
- $\dot{u}$ - acceleration along the x-body axis.
- V - velocity of aircraft along flight path.
- $\dot{V}$ - acceleration of aircraft along flight path.
- $\ddot{V}$ - rate of change of vehicle acceleration along flight path.

- W - weight.
- w - component of aircraft velocity along z-body axis.
- $WGTL$ - lower constraint weight.
- $WGTU$ - upper constraint weight.
- x - horizontal displacement.
- X - exponent in lift expression (p. 105).
- X_{ax} - displacement of accelerometer from c.g.
- α - angle of attack.
- $\dot{\alpha}$ - time rate of change of angle of attack.
- γ - flight path angle (p. 36).
- γ - ratio of specific heats (p. 68).
- $\dot{\gamma}$ - flight path angular velocity.
- $\ddot{\gamma}$ - flight path angular acceleration.
- $\ddot{\gamma}^*$ - rate of change of flight path angular acceleration.
- δ^* - displacement thickness.
- θ - pitch angle.
- $\dot{\theta}$ - pitching velocity
- λ - time interval.
- μ - coefficient of viscosity.
- ρ - density.
- τ - time constant.
- ϕ - bank angle.
- ω - frequency.

SUBSCRIPTS

- c - cutoff value.
- DATA - refers to measured value.
- DRAG - refers to values obtained from drag equation.
- fus - fuselage.
- LIFT - refers to values obtained from lift equation.
- N - last point in data set.
- t - tail.
- t_v - vertical tail.

SUPERSCRIPTS

- ' - measured value.
- " - lag-free value.
- ^ - estimated value of the variable.



INTRODUCTION

The value of any predictive procedure depends rather fundamentally upon its success in forecasting the behavior of the item with which it's associated under actual use conditions. Thus, a technique for predicting the lift, drag, and pitching moment of a proposed aircraft is useful to the extent that it foretells the forces and moments which will be experienced by the flight hardware. It is usually in the nature of things that the better the job the technique does, the more difficult and expensive it is to use. Fortunately, the introduction of increasingly sophisticated digital computers has made it possible to increase the rigor of lift, drag, and moment predictive techniques without significant increases in the cost of employing them. This process can be expected to continue as computer capabilities improve.

Even a supposedly rigorous technique, however, may not be useful if it does not do a good job of predicting what actually occurs. The analytical model, for example, may be too crude or important effects may not have been treated at all. It is therefore important that new predictive techniques be evaluated critically under actual use conditions before they are employed extensively for preliminary design activity.

It was intended that this procedure be followed in the case of the predictive techniques developed in Reference 1. The vehicle to which they were applied was a modified Piper Seneca (ATLIT). The predictions of lift, drag, and pitching moment to be encountered during cruise flight were developed using the computer program described in Reference 1 and the vehicle's geometry as obtained from Piper shop drawings. Performance predictions and stability predictions were also made using in these instances the programs described in References 2 and 3. The aircraft itself was then flight tested to determine the parameter values actually experienced. This report outlines the methods by which the parameter predictions were obtained, presents their results, describes the methods by which the parameter values were obtained from flight data, and gives these results.

LIFT AND DRAG PREDICTION

Wing

The ATLIT airplane employs a straight, tapered wing with a GA(W)-1 airfoil section 17% thick. The computational technique distributes 65 regions of constant vorticity on the surface of the airfoil, calculates from this an inviscid flow field and pressure distribution, then determines the boundary layer growth corresponding to this pressure distribution, and recomputes the inviscid flow field of a pseudo airfoil whose ordinates are now the physical airfoil ordinates plus the local values of δ^* with a modification so as to locate the trailing edge stagnation point downstream in the wake. This process goes through four iterations so that the computed pressure distribution obtained after the last potential (inviscid) solution is essentially the same as that used to generate the boundary layer solution which formed the basis for that potential solution. The program gives section lift, drag, and moment. The drag includes both skin friction drag and form drag. However, because of the flow model used, extensive regions of flow separation cannot be treated. For this reason, the data are unreliable above $C_L = 0.8$.

The outputs (lift, drag, and moment vs. α for a given Reynolds number) from the airfoil program are fed into a curve fitting routine which provides polynomial representations of the results for use by the wing program. This program uses lifting line theory to modify the local angle of attack which the airfoil data "sees" according to spanwise changes in twist, camber, thickness, and chord length. Spanwise variations in Reynolds number are handled by providing as input tip and root data at the correct Reynolds number with the program interpolating to obtain the data for other spanwise stations. Inviscid wing-fuselage interference is treated by transforming the fuselage mathematically into a vertical slit and distributing its effects along the span. The output of the program is the three-dimensional lift, drag, and pitching moment of the wing. Note that the drag includes both profile and induced drags.

The same procedure is employed to find the contributions of the tail surfaces to the overall aircraft lift, drag, and moment. The vertical tail was considered to be half of a symmetric surface unaffected by the presence of the horizontal tail. The horizontal tail was assumed to be unaffected by the presence of the vertical tail, propeller slip-stream, or the downwash of the wing.

The input data and results of the various computations are shown in figures 1 through 7.

***** CASE INPUT *****

WHITCOMB/A=-4,-2,0,2,4,6,8,10,12,14/RN=5.7,FREE TRANSITION/M=.15

 NXU NXL IWRITE IALPHA IPUNCH
 38 38 3 0 1

```

XU = 0.0      0.200000E-02 0.500000E-02 0.125000E-01 0.250000E-01 0.375000E-01 0.500000E-01 0.750000E-01
      0.100000E 00 0.125000E 00 0.150000E 00 0.175000E 00 0.200000E 00 0.250000E 00 0.300000E 00 0.350000E 00
      0.400000E 00 0.450000E 00 0.500000E 00 0.550000E 00 0.575000E 00 0.600000E 00 0.625000E 00 0.650000E 00
      0.675000E 00 0.700000E 00 0.725000E 00 0.750000E 00 0.775000E 00 0.800000E 00 0.825000E 00 0.850000E 00
      0.875000E 00 0.900000E 00 0.925000E 00 0.950000E 00 0.975000E 00 0.100000E 01
ZU = 0.0      0.130000E-01 0.204000E-01 0.307000E-01 0.417000E-01 0.496500E-01 0.558900E-01 0.655100E-01
      0.730000E-01 0.790000E-01 0.840000E-01 0.883999E-01 0.919999E-01 0.977000E-01 0.101600E 00 0.104000E 00
      0.104910E 00 0.104450E 00 0.102580E 00 0.991000E-01 0.966800E-01 0.937099E-01 0.900600E-01 0.859900E-01
      0.813600E-01 0.763400E-01 0.709200E-01 0.651300E-01 0.590700E-01 0.528600E-01 0.464600E-01 0.398800E-01
      0.331500E-01 0.263900E-01 0.196100E-01 0.128700E-01 0.609000E-02 0.700000E-03
XL = 0.0      0.200000E-02 0.500000E-02 0.125000E-01 0.250000E-01 0.375000E-01 0.500000E-01 0.750000E-01
      0.100000E 00 0.125000E 00 0.150000E 00 0.175000E 00 0.200000E 00 0.250000E 00 0.300000E 00 0.350000E 00
      0.400000E 00 0.450000E 00 0.500000E 00 0.550000E 00 0.575000E 00 0.600000E 00 0.625000E 00 0.650000E 00
      0.675000E 00 0.700000E 00 0.725000E 00 0.750000E 00 0.775000E 00 0.800000E 00 0.825000E 00 0.850000E 00
      0.875000E 00 0.900000E 00 0.925000E 00 0.950000E 00 0.975000E 00 0.100000E 01
ZL = 0.0      -0.930000E-02 -0.138000E-01 -0.205000E-01 -0.269000E-01 -0.319000E-01 -0.358000E-01 -0.421000E-01
      -0.470000E-01 -0.510000E-01 -0.543000E-01 -0.570000E-01 -0.593000E-01 -0.627000E-01 -0.645000E-01 -0.652000E-01
      -0.649000E-01 -0.635000E-01 -0.610000E-01 -0.570000E-01 -0.540000E-01 -0.508000E-01 -0.469000E-01 -0.428000E-01
      -0.384000E-01 -0.340000E-01 -0.294000E-01 -0.249000E-01 -0.204000E-01 -0.160000E-01 -0.120000E-01 -0.860000E-02
      -0.580000E-02 -0.360000E-02 -0.250000E-02 -0.260000E-02 -0.400000E-02 -0.800000E-02

```

NA = 10 ANGLES OF ATTACK W.R.T. REFERENCE LINE (IALPHA=0) OR W.R.T. LONGEST CHORDLINE (IALPHA=1)

```

-0.400000E 01 -0.200000E 01 0.0      0.200000E 01 0.400000E 01 0.600000E 01
0.800000E 01 0.100000E 02 0.120000E 02 0.140000E 02

```

NM = 1 FSNACH = 0.150000E 00

CREF = 0.100000E 01 SF = 0.100000E 01 TQ = 0.518690E 03 RN = 0.570000E 01 PR = 0.770000E 00 KF = 0.100000E 01

	LTRAN	XTRAN	ZTRAN
UPPER SURFACE	0	0.0	0.0
LOWER SURFACE	0	0.0	0.0

 WHITCOMB/A=-4,-2,0,2,4,6,8,10,12,14/RN=5.7,FREE TRANSITION/M=.15
 FSNACH = 0.15000

```

*****
*   ALPHA      CL      CD      CN(NOSE)    CN(1/4-CHORD)  *
*   -4.000000   -0.023224  0.006249   -0.086099   -0.092000   *
*   -2.000000    0.213498  0.005605   -0.150842   -0.097549   *
*   0.0          0.438189  0.006357   -0.212167   -0.102620   *
*   2.000000    0.666128  0.007707   -0.274192   -0.107695   *
*   4.000000    0.894763  0.009055   -0.335486   -0.112182   *
*   6.000000    1.120211  0.010642   -0.395287   -0.116490   *
*   8.000000    1.338393  0.012475   -0.451681   -0.119905   *
*   10.000000   1.548673  0.015151   -0.504635   -0.122691   *
*   12.000000   1.748252  0.017997   -0.552386   -0.123939   *
*   14.000000   1.928573  0.021817   -0.591455   -0.122314   *
*****

```

FIGURE 1

***** CASE INPUT *****

0009/A=-6,-4,-2,0,2,4,6,8,10,12/FREE TRANSITION/M=.15/RN=3.0/SF=CREF=1.0

NXU NXL IWRITE IALPHA IPUNCH
19 19 3 0 1

XU = 0.0 0.500000E-02 0.125000E-01 0.250000E-01 0.500000E-01 0.750000E-01 0.100000E 00 0.150000E 00
0.200000E 00 0.250000E 00 0.300000E 00 0.400000E 00 0.500000E 00 0.600000E 00 0.700000E 00 0.800000E 00
0.900000E 00 0.950000E 00 0.100000E 01
ZU = 0.0 0.100000E-01 0.142000E-01 0.196100E-01 0.266600E-01 0.315000E-01 0.351200E-01 0.400900E-01
0.430300E-01 0.445600E-01 0.450100E-01 0.435200E-01 0.397100E-01 0.342300E-01 0.274800E-01 0.196700E-01
0.108600E-01 0.605000E-02 0.950000E-03
XL = 0.0 0.500000E-02 0.125000E-01 0.250000E-01 0.500000E-01 0.750000E-01 0.100000E 00 0.150000E 00
0.200000E 00 0.250000E 00 0.300000E 00 0.400000E 00 0.500000E 00 0.600000E 00 0.700000E 00 0.800000E 00
0.900000E 00 0.950000E 00 0.100000E 01
ZL = 0.0 -0.100000E-01-0.142000E-01-0.196100E-01-0.266600E-01-0.315000E-01-0.351200E-01-0.400900E-01
-0.430300E-01-0.445600E-01-0.450100E-01-0.435200E-01-0.397100E-01-0.342300E-01-0.274800E-01-0.196700E-01
-0.108600E-01-0.605000E-02-0.950000E-03

NA = 10 ANGLES OF ATTACK W.R.T. REFERENCE LINE (IALPHA=0) OR W.R.T. LONGEST CHORDLINE (IALPHA=1)

-0.600000E 01 -0.400000E 01 -0.200000E 01 0.0 0.200000E 01 0.400000E 01
0.600000E 01 0.800000E 01 0.100000E 02 0.120000E 02

NM = 1 FSMACH = 0.150000E 00

CREF = 0.100000E 01 SF = 0.100000E 01 TO = 0.518690E 03 RN = 0.300000E 01 PR = 0.770000E 00 KF = 0.100000E 01

	LTRAN	XTRAN	ZTRAN
UPPER SURFACE	0	0.0	0.0
LOWER SURFACE	0	0.0	0.0

0009/A=-6,-4,-2,0,2,4,6,8,10,12/FREE TRANSITION/M=.15/RN=3.0/SF=CREF=1.0
FSMACH = 0.15000

ALPHA	CL	CD	CM(NOSE)	CM(1/4-CHORD)
-6.000000	-0.639027	0.007929	0.161376	0.002287
-4.000000	-0.430504	0.007073	0.110331	0.002844
-2.000000	-0.216409	0.006283	0.055765	0.001641
0.0	0.000019	0.005804	-0.000008	-0.000004
2.000000	0.216441	0.006282	-0.055780	-0.001647
4.000000	0.430541	0.007070	-0.110348	-0.002852
6.000000	0.639190	0.007936	-0.161459	-0.002330
8.000000	0.853717	0.009510	-0.215147	-0.003464
10.000000	1.060093	0.011856	-0.265412	-0.003900
12.000000	1.251046	0.015075	-0.309520	-0.002810

FIGURE 2

ORIGINAL PAGE IS
OF POOR QUALITY


```

*****
*
*               TWO DIMENSIONAL AIRFOIL DATA INPUT
*
*
* WHITCOMB/A=-4,-2,0,2,4,6,8,10,12,14/RN=5.7,FREE TRANSITION/M=.15
* THE NUMBER OF DATA POINTS IS = 10
*
*
*      ALPHA      CL      CD      CM
*
*      -4.000000  -0.023224  0.006249  -0.092000
*      -2.000000  0.213500  0.005605  -0.097549
*      0.0         0.428190  0.006357  -0.102620
*      2.000000  0.666130  0.007707  -0.107690
*      4.000000  0.894760  0.009055  -0.112180
*      6.000000  1.120199  0.010642  -0.116490
*      8.000000  1.338400  0.012475  -0.119910
*      10.000000 1.548699  0.015151  -0.122690
*      12.000000 1.748300  0.017997  -0.123940
*      14.000000 1.928499  0.021817  -0.122310
*
*****

```

```

*****
*
*               TWO DIMENSIONAL CURVE FIT FUNCTION DATA
*               OF THE FORM Y=C(0)+C(1)*X+C(2)*X^2+...
*
*
* WHITCOMB/A=-4,-2,0,2,4,6,8,10,12,14/RN=5.7,FREE TRANSITION/M=.15
*
*
*      C(0)      C(1)      C(2)      C(3)      C(4)
*
* CL VERSUS ALPHA  0.43993  0.11427  -0.00019  0.00002  -0.00000
* CD VERSUS CL     0.00608  -0.00466  0.01623  -0.01096  0.00311
* CM VERSUS CL     -0.09253  -0.02625  0.01076  -0.00997  0.00377
* ALPHA VERSUS CL  -3.81031  8.41611  0.87390  -0.86891  0.32962
*
*
*      DOMAIN=  -4.0000  TO  14.0000
*      DOMAIN=  -0.0232  TO  1.9285
*      DOMAIN=  -0.0232  TO  1.9285
*      DOMAIN=  -0.0232  TO  1.9285
*
*****

```

FIGURE 3

TWO DIMENSIONAL CURVE FIT FUNCTION DATA OF THE FORM $V=C(0)+C(1)*X+C(2)*X^2+...$						
WHITCOMB/A=-4,-2,0,2,4,6,8,10,12,14/RN=5.7, FREE TRANSITION/M=.15						
	C(0)	C(1)	C(2)	C(3)	C(4)	
CL VERSUS ALPHA	0.43993	0.11427	-0.00019	0.00002	-0.00000	DOMAIN= -4.0000 TO 14.0000
CD VERSUS CL	0.00608	-0.00466	0.01623	-0.01096	0.00311	DOMAIN= -0.0232 TO 1.9285
CM VERSUS CL	-0.09253	-0.02625	0.01076	-0.00997	0.00377	DOMAIN= -0.0232 TO 1.9285
ALPHA VERSUS CL	-3.81030	8.41610	0.87385	-0.86887	0.32961	DOMAIN= -0.0232 TO 1.9285
WHITCOMB/A=-4,-2,0,2,4,6,8,10,12,14/RN=5.7, FREE TRANSITION/M=.15						
	C(0)	C(1)	C(2)	C(3)	C(4)	
CL VERSUS ALPHA	0.43993	0.11427	-0.00019	0.00002	-0.00000	DOMAIN= -4.0000 TO 14.0000
CD VERSUS CL	0.00608	-0.00466	0.01623	-0.01096	0.00311	DOMAIN= -0.0232 TO 1.9285
CM VERSUS CL	-0.09253	-0.02625	0.01076	-0.00997	0.00377	DOMAIN= -0.0232 TO 1.9285
ALPHA VERSUS CL	-3.81030	8.41610	0.87385	-0.86887	0.32961	DOMAIN= -0.0232 TO 1.9285

M=.15 WHITCOMB AIRFOIL/RN=5.7 MILLION/17 PERCENT THICK NEW NASA WING

BODY HEIGHT / SPAN	0.11	BODY WIDTH / SPAN	0.10
ASPECT RATIO	10.18	WING HEIGHT / SPAN	-0.04
WING BODY INCIDENCE, DEG	0.0	TIP THICKNESS CHORD	0.17
ROOT THICKNESS CHORD	0.17	GEOMETRIC TWIST, DEG	-3.00
NUMBER OF SPANWISE STATIONS	20.00	AERODYNAMIC TWIST, DEG	-3.00
TAPER RATIO	0.50	REYNOLDS NUMBER	5.70
COORDINATES OF MOMENT REFERENCE POINT		X=	0.0
VALUE OF DISCRIMINANT	0.001000	Z=	0.0

THREE DIMENSIONAL LIFT, DRAG, AND MOMENT DATA					
ALPHA	CL	CDP	CDI	CD	CM
-4.000000	-0.134572	0.006471	0.000845	0.007318	-0.088299
-2.000000	0.063437	0.005717	0.000328	0.006045	-0.093561
0.0	0.259755	0.005686	0.002663	0.008349	-0.098313
2.000000	0.454469	0.006348	0.007784	0.014132	-0.102669
4.000000	0.648288	0.007393	0.015658	0.023051	-0.106861
6.000000	0.841228	0.008643	0.026248	0.034890	-0.110939
8.000000	1.032696	0.010037	0.039469	0.049506	-0.114788
10.000000	1.221716	0.011624	0.055164	0.066788	-0.118148
12.000000	1.405899	0.013535	0.072973	0.086508	-0.120638
14.000000	1.582717	0.015940	0.092385	0.108325	-0.121863

FIGURE 5

TWO DIMENSIONAL CURVE FIT FUNCTION DATA
OF THE FORM $Y=C(0)+C(1)*X+C(2)*X^2+...$

ATLIT HORIZONTAL TAIL SECTION--0009/A=-6,-4,-2,0,2,4,6,8,10,12/RN=3./M=.15

THICKNESS RATIO= 0.09

	C(0)	C(1)	C(2)	C(3)	C(4)	DOMAIN=		
CL VERSUS ALPHA	-0.00109	0.10769	0.00012	-0.00002	-0.00000	-6.0000	TO	12.0000
CD VERSUS CL	0.00608	0.00006	0.00407	-0.00036	0.00131	-0.6390	TO	1.2510
CM VERSUS CL	0.00011	-0.00721	0.00001	0.00685	-0.00310	-0.6390	TO	1.2510
ALPHA VERSUS CL	0.01138	9.28780	-0.11110	0.14829	0.09729	-0.6390	TO	1.2510

ATLIT HORIZONTAL TAIL SECTION--0009/A=-6,-4,-2,0,2,4,6,8,10,12/RN=3./M=.15

THICKNESS RATIO= 0.09

	C(0)	C(1)	C(2)	C(3)	C(4)	DOMAIN=		
CL VERSUS ALPHA	-0.00109	0.10769	0.00012	-0.00002	-0.00000	-6.0000	TO	12.0000
CD VERSUS CL	0.00608	0.00006	0.00407	-0.00036	0.00131	-0.6390	TO	1.2510
CM VERSUS CL	0.00011	-0.00721	0.00001	0.00685	-0.00310	-0.6390	TO	1.2510
ALPHA VERSUS CL	0.01138	9.28780	-0.11110	0.14829	0.09729	-0.6390	TO	1.2510

ATLIT HORIZONTAL TAIL USING NACA 0009 AIRFOIL/RN=3.0 MILLION MACH#=.15

BODY HEIGHT / SPAN = 0.16
ASPECT RATIO = 4.75
WING BODY INCIDENCE, DEG . . . = 0.0
ROOT THICKNESS CHORD = 0.09
NUMBER OF SPANWISE STATIONS . = 20.00
TAPER RATIO = 1.00
COORDINATES OF MOMENT REFERENCE POINT
VALUE OF DISCRIMINANT = 0.001000

BODY WIDTH / SPAN = 0.15
WING HEIGHT / SPAN = 0.0
TIP THICKNESS CHORD = 0.09
GEOMETRIC TWIST, DEG = 0.0
AERODYNAMIC TWIST, DEG = 0.0
REYNOLDS NUMBER = 3.00
X= 0.0 Z= 0.0

THREE DIMENSIONAL LIFT, DRAG, AND MOMENT DATA

ALPHA	CL	CDP	CDI	CD	CM
-6.000000	-0.449000	0.006908	0.017090	0.023998	0.002427
-4.000000	-0.300239	0.006339	0.007641	0.013980	0.002019
-2.000000	-0.150733	0.006026	0.001925	0.007951	0.001169
0.0	-0.000492	0.005933	-0.000000	0.005933	0.000115
2.000000	0.149765	0.006041	0.001901	0.007942	-0.000943
4.000000	0.300187	0.006352	0.007636	0.013988	-0.001863
6.000000	0.450217	0.006890	0.017182	0.024072	-0.002552
8.000000	0.599307	0.007694	0.030441	0.038136	-0.002976
10.000000	0.746855	0.008821	0.047263	0.056084	-0.003152
12.000000	0.892116	0.010332	0.067407	0.077739	-0.003152

FIGURE 6

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TWO DIMENSIONAL CURVE FIT FUNCTION DATA
OF THE FORM $Y=C(0)+C(1)*X+C(2)*X**2+...$

ATLIT VERTICAL TAIL SECTION--0009/A=-6,-4,-2,0,2,4,6,8,10,12/RN=3./N=.15
THICKNESS RATIO= 0.09

	C(0)	C(1)	C(2)	C(3)	C(4)	DOMAIN=	TO
CL VERSUS ALPHA	-0.00109	0.10769	0.00012	-0.00002	-0.00000	-6.0000	12.0000
CD VERSUS CL	0.00608	0.00006	0.00407	-0.00036	0.00131	-0.6390	1.2510
CM VERSUS CL	0.00011	-0.00721	0.00001	0.00685	-0.00310	-0.6390	1.2510
ALPHA VERSUS CL	0.01138	9.28780	-0.11110	0.14829	0.09729	-0.6390	1.2510

ATLIT VERTICAL TAIL SECTION--0009/A=-6,-4,-2,0,2,4,6,8,10,12/RN=3./N=.15
THICKNESS RATIO= 0.09

	C(0)	C(1)	C(2)	C(3)	C(4)	DOMAIN=	TO
CL VERSUS ALPHA	-0.00109	0.10769	0.00012	-0.00002	-0.00000	-6.0000	12.0000
CD VERSUS CL	0.00608	0.00006	0.00407	-0.00036	0.00131	-0.6390	1.2510
CM VERSUS CL	0.00011	-0.00721	0.00001	0.00685	-0.00310	-0.6390	1.2510
ALPHA VERSUS CL	0.01138	9.28780	-0.11110	0.14829	0.09729	-0.6390	1.2510

ATLIT VERTICAL TAIL USING NACA 0009 AIRFOIL/RN=3.0 MILLION/MACH=.15

BODY HEIGHT / SPAN	0.05	BODY WIDTH / SPAN	0.05
ASPECT RATIO	3.60	WING HEIGHT / SPAN	0.0
WING BODY INCIDENCE, DEG	0.0	TIP THICKNESS CHORD	0.09
ROOT THICKNESS CHORD	0.09	GEOMETRIC TWIST, DEG	0.0
NUMBER OF SPANWISE STATIONS	20.00	AERODYNAMIC TWIST, DEG	0.0
TAPER RATIO	0.40	REYNOLDS NUMBER	3.00
COORDINATES OF MOMENT REFERENCE POINT		X=	0.0
VALUE OF DISCRIMINANT	0.001000	Z=	0.0

THREE DIMENSIONAL LIFT, DRAG, AND MOMENT DATA

ALPHA	CL	CDP	CDI	CD	CM
-6.000000	-0.378216	0.006636	0.012877	0.019513	0.002436
-4.000000	-0.252761	0.006277	0.005751	0.012028	0.001845
-2.000000	-0.126856	0.006075	0.001449	0.007524	0.001033
0.0	-0.000549	0.006015	0.000000	0.005015	0.000119
2.000000	0.125829	0.006088	0.001425	0.007514	-0.000797
4.000000	0.252360	0.006295	0.005733	0.012028	-0.001638
6.000000	0.378752	0.006643	0.012913	0.019556	-0.002344
8.000000	0.504801	0.007149	0.022939	0.030087	-0.002878
10.000000	0.630221	0.007833	0.035755	0.043587	-0.003226
12.000000	0.754719	0.008724	0.051280	0.060004	-0.003395

FIGURE 7

Fuselage and Nacelles

The program to compute the forces and moments on isolated, quasi-streamlined bodies having a plane of symmetry represents the half-surface by 560 flat panels of more or less equal area. On each panel is distributed a uniform source whose strength is such that the flow due to all sources is everywhere parallel to the surface. Then, a streamline which goes through the centroid of a particular panel is traced upstream to its inception point. Along this streamline is calculated the boundary layer displacement thickness and skin friction by a momentum integral method. This is done for all 560 panels. At the downstream end of the body the wake is arbitrarily assumed to begin at the upstream end of the last two sets of panels. The angle of the wake leaving the body is determined by the history of the boundary layer displacement up to that point. This wake is then paneled to a stagnation point downstream in the physical wake and the inviscid pressure distribution on the body plus wake body recomputed. The calculated skin friction is integrated over the body to find the skin friction drag and the recomputed pressure distribution is integrated in the normal and axial directions to find the lift and form drag. The same data are also used in computing the pitching moment.

Because the boundary layer routine used is two-dimensional it is not valid when the flow is expanding or contracting rapidly, i.e., near the nose or tail of a body, or when there is a significant cross flow, i.e., at angle of attack. For this reason the aircraft drag computation is reasonable only in the cruise configuration. In the context of an overall drag computation this is not unduly limiting because the wing drag calculation fails for high angles of attack as well. Several attempts were made to extend the angle of attack range of the computation at least for axisymmetric bodies, by using an axisymmetric finite difference boundary layer routine in the plane of symmetry in order to locate the lee-side separation point and then applying the Allen-Perkins (Ref. 4) technique to determine the normal force. However, the computed separation point was not regularly located sufficiently close to physical separation point (as found experimentally) to make this approach viable.

Modeling fuselages and nacelles for the purposes of drag computation as isolated bodies of course ignores interference effects. While it is conceivable that the inviscid aspects of interference could be treated adequately (and in fact have been in many cases), it will require a general three-dimensional boundary layer solution to treat the viscous aspects adequately. Since such solution techniques will be some time in coming, it continues to be necessary to treat these effects empirically. Because other approximations in the model can be expected to yield uncertainties of the same order of magnitude, no attempt was made to account for these effects.

Figures 8 through 11 show the input data and calculated results for the ATLIT fuselage and nacelles.

ATLIT WITH M=21 AND N=29 YIELDING 560 PANELS -- FUSELAGE ONLY

	1	1	21	29							
0.	7.5	16.5	25.5	35.0	45.0	55.0	65.0	75.0	86.5		XFUS10
97.5	108.	118.5	129.5	140.5	151.0	162.0	172.5	184.0	195.5		XFUS20
207.5	220.5	232.0	244.5	256.5	273.0	293.0	312.6	339.0			XFUS29
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000		Y1
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000		Y1
0.0000											Y1
43.250043.	250043.	250043.	250043.	250043.	250043.	250043.	250043.	250043.	250043.	2500	Z1
43.250043.	250043.	250043.	250043.	250043.	250043.	250043.	250043.	250043.	250043.	2500	Z1
43.2500											Z1
0.0000	0.9000	1.8000	2.7750	3.7375	4.7375	5.7875	6.7500	7.5750	8.1250		Z1
8.3250	8.1750	7.6625	6.8750	5.8500	4.8375	3.8000	2.7750	1.8000	0.9000		Y2
0.0000											Y2
38.012538.	025038.	112538.	275038.	512538.	875039.	425040.	162541.	150042.	3125		Y2
43.600044.	862546.	100047.	100047.	900048.	462548.	850049.	125049.	275049.	3500		Z2
49.4000											Z2
0.0000	1.3875	2.6375	4.1625	5.8813	7.6500	9.525011.	225012.	125012.	5625		Z2
12.700012.	525011.	875010.	6875	9.1500	7.4875	5.7875	4.2250	2.7750	1.3875		Y3
0.0000											Y3
35.700035.	718735.	762535.	875036.	087536.	475037.	262538.	712540.	475042.	4375		Z3
44.412546.	400048.	287549.	900051.	100051.	913052.	450052.	775052.	950053.	0500		Z3
53.0750											Z3
0.0000	1.6750	3.4375	5.4500	7.675010.	187512.	775014.	213015.	125015.	4875		Y4
15.588015.	500014.	825013.	475011.	5130	9.3875	7.2500	5.2250	3.3750	1.6500		Y4
0.0000											Y4
34.462534.	462534.	462534.	462534.	512534.	900036.	150037.	887540.	500042.	9125		Z4
45.037547.	487549.	875051.	925053.	475054.	425055.	000055.	338055.	538055.	6250		Z4
55.6630											Z4
0.0000	1.5250	3.4750	5.1750	8.513011.	363014.	375016.	450017.	275017.	6000		Y5
17.675017.	650017.	088015.	675013.	500010.	8380	6.2500	5.9250	3.8130	1.8250		Y5
0.0000											Y5
33.425033.	425033.	425033.	425033.	425033.	575034.	575037.	087539.	900042.	7250		Z5
44.875048.	250051.	000053.	462555.	225056.	313056.	900057.	225057.	388057.	4750		Z5
57.5000											Z5
0.0000	2.1000	4.2375	6.6375	9.362512.	750016.	275018.	225019.	063019.	3750		Y6
19.488019.	500019.	175018.	025015.	688012.	6750	9.7000	6.7000	4.7880	2.1375		Y6
0.0000											Y6
32.262532.	262532.	262532.	262532.	262532.	312533.	250035.	675038.	837541.	9625		Z6
45.025048.	062551.	262554.	100056.	350057.	625058.	263058.	625058.	763058.	8250		Z6
58.8750											Z6
0.0000	2.2500	4.6090	7.109010.	690014.	656018.	594020.	440021.	030021.	2500		Y7
21.340021.	330021.	047019.	780017.	190013.	690010.	3750	3.100	4.7000	2.3100		Y7
0.0000											Y7
31.187	31.187	31.187	31.187	31.187	31.187	31.22	35.281	39.375	42.344		Z7
45.797	49.156	52.563	55.875	58.188	59.422	60.0	60.25	60.42	60.44		Z7
60.44											Z7
0.0000	2.5780	5.2500	8.187511.	656016.	063020.	406022.	270022.	688022.	8600		Y8
22.906022.	950022.	730021.	610018.	780014.	970011.	2500	8.0000	5.1250	2.5000		Y8
0.0000											Y8
30.585030.	585030.	585030.	585030.	585030.	585031.	395035.	022038.	460042.	6320		Z8
46.319049.	945053.	585057.	365059.	898061.	257061.	773061.	960062.	085062.	1160		Z8
62.1160											Z8
0.0000	2.5750	5.2500	8.200011.	675016.	075020.	950022.	825023.	225023.	5750		Y9
23.850023.	975023.	875022.	875019.	950016.	000012.	0500	8.6375	5.4500	2.6750		Y9
0.0000											Y9
29.25	29.25	29.25	29.25	29.25	29.25	30.225	34.05	38.275042.	0750		Z9
45.925049.	775053.	650057.	688060.	538061.	925062.	463062.	650062.	800062.	8130		Z9
62.8380											Z9
0.0000	3.0000	6.750010.	750014.	500019.	250021.	250022.	500023.	500024.	0000		Y10

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24.500024.750024.750023.500020.500016.500012.7500	9.0000	5.7500	2.8750	Y10
0.0000				Y10
27.750027.750027.750027.750027.750030.000034.000037.875041.7500				Z10
45.500049.500053.625057.500060.500062.250063.000063.250063.250063.2500				Z10
63.2500				Z10
0.0000	3.5000	7.750011.875016.125019.875022.750024.750025.500025.8750		Z11
26.000025.500024.875023.625021.750018.750015.000011.0000	7.0000	3.5000		Y11
0.0000				Y11
27.000027.000027.000027.000027.000030.750036.000040.375044.6250				Z11
48.750052.875056.500060.875064.500067.500069.500070.375070.500070.5000				Z11
70.5000				Z11
0.0000	3.7500	7.500011.500015.250020.250024.250025.375025.875026.2500		Y12
26.500026.000025.500025.000024.000021.625017.750013.0000	8.3750	4.1250		Y12
0.0000				Y12
26.585026.585026.585026.585026.585031.585037.835042.335046.7100				Z12
50.835055.085059.335063.460067.835071.835074.085074.960075.085075.0850				Z12
75.0850				Z12
0.0000	4.1250	10.000015.000020.500023.250025.125025.750026.125026.2500		Y13
26.250026.000025.500025.000024.000021.625017.750012.8750	8.3750	4.1250		Y13
0.0000				Y13
25.650025.650025.650025.650025.650028.025033.025038.150042.900047.1500				Z13
51.400055.050059.900064.150068.900073.275075.900076.900077.150077.1500				Z13
77.1500				Z13
0.0000	5.1250	10.250015.000021.625024.000025.500026.000026.200026.3000		Y14
26.500026.300026.250026.250025.500022.875018.750013.5000	8.6250	4.2500		Y14
0.0000				Y14
25.250025.250025.250025.250025.250027.750033.000038.250043.000047.3750				Z14
51.750056.000060.375064.750070.125074.500077.250078.125078.250078.2500				Z14
78.2500				Z14
0.0000	5.0000	10.000014.750022.500023.750025.000025.750026.250026.5000		Y15
26.500026.500026.250026.000025.125022.500018.375013.3750	8.5000	4.2500		Y15
0.0000				Y15
24.750024.750024.750024.750024.750027.370032.620037.620042.250046.6250				Z15
51.000055.250059.500064.250069.125073.500076.000077.000077.250077.2500				Z15
77.2500				Z15
0.0000	4.1250	9.875014.875020.750023.250025.000025.625026.125026.3750		Y16
26.500026.250026.000025.250024.125021.500017.500013.0000	8.2500	4.0000		Y16
0.0000				Y16
24.330024.330024.330024.330024.330026.580031.580036.705041.330045.5800				Z16
49.830053.955058.330062.830067.580071.705	74.58	75.58	75.83	75.83
75.83				Z16
0.0000	4.7500	9.750014.500020.750022.875024.750025.625026.250026.3750		Y17
26.500026.250025.875025.250024.000021.500017.500012.8750	8.3750	4.0000		Y17
0.0000				Y17
23.750023.750023.750023.750023.750026.370031.250036.000040.500044.8750				Z17
49.250053.500057.625062.125066.500070.625073.250074.375074.750074.7500				Z17
74.7500				Z17
0.0000	4.6250	9.500014.000020.250022.500024.500025.250025.750025.8750		Y18
26.000025.750025.125024.375023.000020.500017.875012.5000	8.1250	4.0000		Y18
0.0000				Y18
23.600023.600023.600023.600023.600025.850030.600035.350039.850044.1000				Z18
48.350052.350056.475060.850064.975068.850071.350072.850073.100073.1000				Z18
73.1000				Z18
0.0000	3.8750	9.250014.000019.500021.750023.625024.250024.375024.5000		Y19
24.500024.375024.250023.625022.250019.750016.000012.0000	7.8750	3.7500		Y19
0.0000				Y19
23.000023.000023.000023.000023.000025.250029.750034.625039.000043.1250				Z19
47.000050.750055.000059.000063.000	67.0	69.5	71.0	71.5
71.5				Z19
0.0000	3.7500	9.250013.24	19.00	21.25
			22.50	23.25
				23.625
				23.75
				Y20

FIGURE 8 CONT'D

24.00	23.75	23.50	22.75	21.75	19.25	15.75	12.00	7.75	3.75	Y20
0.0000										Y20
22.6000	22.6000	22.6000	22.6000	22.6000	22.6000	24.8500	29.3500	34.1000	38.9750	42.2250
46.3500	50.1000	54.2250	58.3500	62.2250	66.8500	68.3500	69.6000	70.1000	70.1000	70.1000
0.0000	3.6250	8.7500	13.0000	18.5000	20.2500	21.2500	21.6250	21.7500	21.8750	21.8750
22.0000	21.8750	21.6250	21.0000	19.7500	17.6250	14.7500	11.2500	7.2500	3.5000	0.0000
23.25	23.25	23.25	23.25	23.25	25.50	30.37	34.87	38.875	42.5	46.0000
46.0000	49.5000	53.1250	56.7500	60.2500	63.7500	66.5000	68.0000	68.5000	68.5000	68.5000
0.0000	4.5000	8.3750	12.5000	17.7500	18.5000	19.2500	19.6250	19.8750	20.0000	20.0000
20.0000	19.7500	19.6250	19.3750	18.6250	17.0000	14.2500	10.7500	7.0000	3.3750	0.0000
24.0000	24.0000	24.0000	24.0000	24.0000	27.0000	31.5000	35.5000	39.0000	42.375	45.5000
45.5000	48.6250	52.0000	55.3750	59.0000	62.5000	66.1250	69.6250	73.0000	76.0000	79.0000
0.0000	4.0000	8.0000	12.3000	16.7000	17.3500	18.0000	18.2500	18.4000	18.4500	18.5000
18.5000	18.4000	18.1000	17.6000	17.1000	15.9000	13.5000	10.1500	6.6000	3.2000	0.0000
25.5000	25.5000	25.5000	25.5000	25.5000	28.1000	32.4000	36.1500	39.5000	42.5500	45.5000
45.5000	48.4000	51.4000	54.5000	57.9000	61.4000	64.1000	65.4000	65.5000	65.5000	65.5000
0.0000	4.0000	8.0000	10.0000	15.5500	16.0000	16.4000	16.6000	16.6100	16.6200	16.6250
16.6250	16.6000	16.4000	16.0500	15.4000	14.1500	12.0000	9.1000	6.0000	2.9000	0.0000
27.25	27.25	27.25	27.25	27.25	29.5	33.55	37.40	42.85	45.5	48.1
48.1	50.9	53.7	56.7	59.65	62.05	63.4	63.7	63.72	63.75	63.75
0.0000	4.3750	7.6250	11.1250	13.8750	14.3750	14.6880	14.8130	14.8750	14.9380	15.0000
15.0000	14.8750	14.8130	14.3750	14.0000	12.8750	10.9380	8.3750	5.4375	2.6875	0.0000
26.4200	28.4200	28.4200	28.4200	29.4000	31.7750	34.4000	37.6500	40.2750	42.7750	45.2125
45.2125	47.5250	49.9625	52.5250	55.2750	57.9000	60.0250	61.2750	61.7130	61.9000	61.9630
0.0000	2.4000	4.8000	7.6000	11.4000	12.1500	12.5000	12.6500	12.8000	12.9000	13.0000
13.0000	12.8000	12.5000	12.1000	11.5000	10.6000	9.2000	7.1000	4.8000	2.4000	0.0000
30.0000	30.0000	30.0000	30.0000	30.0000	32.9000	35.9000	38.5000	40.8000	42.9000	45.0000
45.0000	47.0000	49.1000	51.2000	53.4000	55.6000	57.6000	59.0000	60.0000	60.0000	60.0000
0.0000	1.8125	3.8125	6.0000	7.8750	9.1250	9.5000	9.6875	9.8125	9.8750	9.8750
9.8750	9.8125	9.7500	9.5000	9.2500	8.5625	7.3750	5.7500	3.8125	1.8750	0.0000
33.101	33.101	33.101	33.187	34.125	35.875	38.40	40.125	41.875	43.5	45.063
45.063	46.625	48.25	49.875	51.813	53.563	55.188	56.375	57.0	57.188	57.25
0.0000	1.6000	3.2500	4.8500	6.3000	6.9500	7.3500	7.4000	7.4500	7.5000	7.5000
7.5000	7.4000	7.2000	7.0000	6.6000	6.1000	5.4000	4.3000	3.1000	1.6000	0.0000
35.5000	35.5000	35.5000	36.0000	37.3000	38.5500	40.2000	41.7000	43.0000	44.3000	45.5000
45.5000	46.7000	47.9000	49.1000	50.3000	51.6000	52.9000	53.9500	54.7500	55.5000	55.5000
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500
43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500	43.2500
x 2 OUT	45.10.	30.								

14. CRT

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FIGURE 8 CONT'D

ORIGINAL PAGE IS
OF POOR QUALITY

ATLIT NACELLE WITH N=21 AND M=21 YIELDING 400 PANELS ON THE BODY

	1	1	21	21							
0.0	1.5	3.75	6.75	11.25	15.0	20.0	24.5	30.0	34.5		XFUS10
40.0	45.75	51.0	56.5	62.5	68.5	74.	79.5	86.0	94.5		XFUS20
116.0											XFUS21
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000		Y1
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000		Y1
0.0000											Y1
26.5000	26.5000	26.5000	26.5000	26.5000	26.5000	26.5000	26.5000	26.5000	26.5000		Z1
26.5000	26.5000	26.5000	26.5000	26.5000	26.5000	26.5000	26.5000	26.5000	26.5000		Z1
26.5000											Z1
0.0000	1.5000	2.9500	4.5000	6.5000	8.8750	11.8750	15.3200	16.8750	17.3750		Y2
17.6250	17.7500	17.4200	14.7500	11.5000	8.6250	6.3750	4.5000	2.9200	1.3750		Y2
0.0000											Y2
18.0000	18.0000	18.0000	18.0000	18.0800	18.1250	18.3000	19.1250	21.5000	24.2500		Z2
27.0000	29.8000	32.6250	34.5000	35.3750	35.6250	35.7500	35.8750	35.9000	35.9500		Z2
36.0000											Z2
0.0000	1.5000	3.3750	5.2500	7.1250	10.1250	13.5000	16.5000	17.7500	18.0000		Y3
18.1250	18.2500	18.1250	16.0000	12.8750	9.8750	7.3750	5.1250	3.3750	1.6250		Y3
0.0000											Y3
16.0000	16.0000	16.0000	16.0000	16.0000	16.1200	16.3750	17.7500	20.3750	23.3750		Z3
26.2500	29.1250	32.2500	34.3750	35.6250	36.1250	36.2500	36.3750	36.5000	36.5000		Z3
36.5000											Z3
0.	1.703	3.453	5.375	7.719	10.438	13.5	16.25	17.813	18.438		Y4
18.75	18.719	18.234	16.578	13.719	10.672	8.	5.594	3.625	1.7813		Y4
0.											Y4
14.688	14.719	14.813	14.904	15.03	15.28	15.875	17.438	19.922	22.75		Z4
25.813	28.625	31.688	34.125	35.438	36.078	36.406	36.625	36.703	36.75		Z4
36.78											Z4
0.0000	1.7813	3.6250	5.6563	8.0000	10.7500	13.8750	16.6880	18.1250	18.7190		Y5
18.9380	19.0000	18.6250	17.0000	14.1560	11.0000	8.2500	5.8750	3.5635	1.8750		Y5
0.0000											Y5
14.6	14.6	14.631	14.694	14.819	15.069	15.788	17.406	20.	22.938		Z5
26.063	28.969	32.025	34.744	36.275	37.025	37.337	37.525	37.588	37.619		Z5
37.619											Z5
0.0000	1.7813	3.6250	5.6563	8.0000	10.7500	13.8750	16.6880	18.1250	18.7190		Y6
18.9380	19.0000	18.6250	17.0000	14.1560	11.0000	8.2500	5.8750	3.5635	1.8750		Y6
0.0000											Y6
14.7500	14.7500	14.7812	14.8437	14.9687	15.2187	15.9375	17.6562	20.2500	23.1875		Z6
26.3125	29.2188	32.3750	35.0940	37.6250	39.3750	40.7037	42.8750	45.9380	49.9690		Z6
37.9690											Z6
0.0000	1.8750	3.7810	5.9060	8.3750	11.1870	14.3130	16.8120	18.2500	18.7190		Y7
18.9380	19.0000	18.7180	17.2500	14.2500	11.0620	8.6880	5.9380	3.7500	1.8750		Y7
0.0000											Y7
14.8440	14.8440	14.8750	14.9070	15.0000	15.3120	15.7018	16.0000	16.2500	16.6880		Z7
26.6250	29.8120	32.7500	35.4060	37.1250	37.8120	38.1560	38.3120	38.4038	38.440		Z7
38.3750											Z7
0.0000	1.8750	3.7810	5.9060	8.3750	11.1870	14.3130	16.8120	18.2500	18.7190		Y8
18.9380	19.0000	18.7180	17.2500	14.2500	11.0620	8.6880	5.9380	3.7500	1.8750		Y8
0.0000											Y8
15.0940	15.0940	15.1250	15.1570	15.2500	15.5620	16.4070	18.2500	20.8750	23.9380		Z8
26.8750	30.0620	33.0000	35.6560	37.3750	38.0620	38.4060	38.5620	38.5940	38.5940		Z8
38.6250											Z8
0.0000	1.7500	3.7188	5.8438	8.3125	11.2400	14.2810	16.6880	18.0000	18.6250		Y9
18.9060	19.0000	18.8130	17.4380	14.5000	11.1560	8.2813	5.8750	3.7188	1.7500		Y9
0.0000											Y9
15.5000	15.5000	15.5000	15.5000	15.5000	15.7190	16.5620	18.5310	21.2500	24.3120		Z9
27.1250	30.2500	33.3125	36.1560	37.7190	38.3750	38.6250	38.7190	38.7500	38.7800		Z9
38.8750											Z9
0.0000	1.7500	3.7188	5.8438	8.3125	11.2400	14.2810	16.6880	18.0000	18.6250		Y10
18.9060	19.0000	18.8130	17.4380	14.5000	11.1560	8.2813	5.8750	3.7188	1.7500		Y10
0.0000											Y10
15.6250	15.6250	15.6250	15.6250	15.6250	15.8440	16.6870	18.6560	21.3750	24.4370		Z10
27.2500	30.3750	33.4375	36.2810	37.8440	38.5000	38.7500	38.8440	38.8750	38.9050		Z10
39.0000											Z10

FIGURE 9

0.0000	1.7188	3.7188	6.1250	8.312511	4.68014	4.06016	6.56017	7.50018	4.380	Y11
18.813019	0.00018	8.13017	3.75014	1.25010	7.190	7.9375	5.6563	3.5938	1.7500	Y11
0.0000										Y11
16.125016	1.25016	1.25016	1.25016	1.25016	1.25016	7.19018	9.37021	7.19024	5.000	Z11
27.500030	5.62533	7.50036	3.13037	8.75038	3.75038	5.63038	6.56038	6.88038	6.880	Z11
38.7190										Z11
0.0000	1.7188	3.7188	6.1250	8.312511	4.68014	4.06016	6.56017	7.50018	4.380	Y12
18.813019	0.00018	8.13017	3.75014	1.25010	7.190	7.9375	5.6563	3.5938	1.7500	Y12
0.0000										Y12
16.000016	0.000016	0.000016	0.000016	0.000016	0.000016	5.94018	8.12021	5.94024	3.750	Z12
27.375030	4.37533	6.25036	1.88037	7.50038	2.50038	4.38038	5.31038	5.63038	5.630	Z12
38.5940										Z12
0.0000	1.7188	3.7188	6.1250	8.312511	4.68014	4.06016	6.56017	7.50018	4.380	Y13
18.813019	0.00018	8.13017	3.75014	1.25010	7.190	7.9375	5.6563	3.5938	1.7500	Y13
0.0000										Y13
16.406	16.406	16.406	16.406	16.406	16.406	16.95	19.156	21.9	24.63	Z13
27.5	30.494	33.63	36.144	37.656	38.156	38.344	38.438	38.469	38.469	Z13
38.5										Z13
0.0000	1.6250	3.2500	5.1250	7.250010	0.00013	5.00017	0	18.5	19.0000	Y14
19.000019	0.000019	0.000017	5	13.625010	0.0000	7.2500	5.1250	3.25001	6.25	Y14
0.0000										Y14
17.500017	5.70017	6.20017	6.20017	6.70017	7.50017	8.30018	6.25021	5.00024	6.25	Z14
27.750030	7.50033	8.75036	8.75037	7.00037	7.50037	8.30037	8.75037	9.30038	0.0000	Z14
38.0000										Z14
0.0000	1.6250	3.2500	4.8750	7.1250	9.625013	0.00016	7.55018	6.25018	7.500	Y15
18.800018	8.75019	0.00016	85	13.1250	9.6250	7.0000	5.0000	3.1250	1.6250	Y15
0.0000										Y15
18.000018	0.00018	0.00018	0.00018	0.00018	0.75018	1.25018	8.75021	6.25024	7.500	Z15
27.750030	7.50034	0.00036	5.00037	2.50037	3.50037	3.75037	4.00037	4.50037	5.000	Z15
37.5000										Z15
0.0000	1.3750	3.0000	4.5000	5.5000	8.875012	0.00016	3.75018	6.25018	7.500	Y16
18.800018	8.75019	0.00016	0.00011	8.750	8.7500	6.3750	4.5000	2.3750	1.5000	Y16
0.0000										Y16
18.500018	5.00018	5.00018	5.80018	6.00018	6.25018	7.50019	0.00021	3.75024	5.000	Z16
27.500030	5.00033	7.50035	6.25036	1.25036	2.50036	3.00036	3.75036	4.20036	4.500	Z16
36.5000										Z16
0.0000	1.3750	2.7500	4.1250	6.0000	8.125011	1.25015	1.25018	5.00018	6.250	Y17
19.750018	8.75018	5.00014	8.75011	0.0000	8.1250	6.0000	4.1250	2.6250	1.3750	Y17
0.0000										Y17
19.250019	2.50019	2.50019	2.50019	2.50019	3.00019	3.75019	6.25021	3.75024	5.000	Z17
27.500030	5.00033	5.00035	0.00035	3.75035	5.00035	6.25035	6.50035	7.00035	7.500	Z17
35.7500										Z17
0.0000	1.1250	2.3750	3.6250	5.2500	7.1250	9.625013	2.50017	7.50018	5.000	Y18
18.500018	5.00018	0.00013	5.000	9.6250	7.1250	5.1250	3.6250	2.2500	1.1250	Y18
0.0000										Y18
20.3	20.3	20.3	20.3	20.375	20.375	20.5	20.75	21.68	24.5	Z18
27.5	30.375	33.32	34.375	34.5	34.56	34.625	34.64	34.7	34.75	Z18
34.75										Z18
0.0000	1.0000	2.0000	3.0000	4.2500	5.7500	8.000011	1.25015	8.75017	7.500	Y19
17.750017	7.50015	7.50011	1.3750	8.0000	5.8750	4.2500	3.0000	1.8750	0.8750	Y19
0.0000										Y19
21.	21.05	21.05	21.05	21.05	21.125	21.2	21.25	21.75	24.125	Z19
27.	29.75	32.125	32.75	32.8	32.85	32.875	32.9	32.95	33.	Z19
33.										Z19
0.0000	1.2500	3.0000	4.7500	6.7500	9.375011	6.25014	1.25015	0	15.3750	Y20
15.375015	3.75015	3.75014	1.25011	6.250	9.3750	6.7500	4.7500	3.0000	1.2500	Y20
0.0000										Y20
22.750022	7.60022	7.70022	7.90022	8.10022	8.50022	8.75022	9.50023	5.00025	2.500	Z20
26.750028	2.50030	0.00030	5.50030	6.25030	6.50030	6.90030	7.10030	7.30030	7.400	Z20
30.7500										Z20
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	Y21
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	Y21
0.0000										Y21
26.500026	5.00026	5.00026	5.00026	5.00026	5.00026	5.00026	5.00026	5.00026	5.000	Z21
26.500026	5.00026	5.00026	5.00026	5.00026	5.00026	5.00026	5.00026	5.00026	5.000	Z21
26.5000										Z21
X Z OUT	45.	10.	30.							

12. CRT

1

POTENTIAL FLOW PROGRAM SECTION I

ATLIT WITH N=21 AND N=29 YIELDING 560 PANELS -- FUSELAGE ONLY

NO. OF QUADS. = 560
NO. OF SECTIONS= 1
MAX. NO. OF ITERATIONS X FLOW 150

VINF = 160.000000 VD = 0.000160 ROE = 0.002378

REFA = 155.000000 IWRITE = 2

1 PLANES OF SYMMETRY

CONVERGENCE CRITERIA , 0.00010

PRESSURE LIFT AND DRAG COEFFICIENTS

PRESSURE CL = 0.00329
PRESSURE CD = 0.00222
REFERENCE AREA = 155.00000
REYNOLDS NUMBER = 0.2825E 08

FRICTION DRAG COEFFICIENT

FRICTION CD = 0.01057
REFERENCE AREA = 155.00000
REYNOLDS NUMBER = 0.2825E 08
BODY LENGTH = 28.25000

TOTAL BODY COEFFICIENTS

TOTAL BODY CL = 0.00300
TOTAL BODY CD = 0.01299
REFERENCE AREA = 155.00000
REYNOLDS NUMBER = 0.2825E 08
BODY LENGTH = 28.25000

FIGURE 10

POTENTIAL FLOW PROGRAM SECTION I

ATLIT NACELLE WITH N=21 AND N=21 YIELDING 400 PANELS ON THE BODY

NO. OF QUADS. = 400
NO. OF SECTIONS= 1
MAX. NO. OF ITERATIONS X FLOW 150

VINF = 160.000000 VD = 0.000160 ROE = 0.002378

REFA = 155.000000 IWRITE = 2

1 PLANES OF SYMMETRY

CONVERGENCE CRITERIA , 0.00010

PRESSURE LIFT AND DRAG COEFFICIENTS

PRESSURE CL = 0.00230
PRESSURE CD = 0.00391
REFERENCE AREA = 155.00000
REYNOLDS NUMBER = 0.9667E 07

FRICTION DRAG COEFFICIENT

FRICTION CD = 0.00308
REFERENCE AREA = 155.00000
REYNOLDS NUMBER = 0.9667E 07
BODY LENGTH = 9.66667

TOTAL BODY COEFFICIENTS

TOTAL BODY CL = 0.00235
TOTAL BODY CD = 0.00722
REFERENCE AREA = 155.00000
REYNOLDS NUMBER = 0.9667E 07
BODY LENGTH = 9.66667

FIGURE 11

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Protuberances

No accounting for the drag due to protuberances was deemed necessary in the drag buildup since the probable magnitude of these effects is within the uncertainty bounds of the nacelle, fuselage, and interference drag computations.

Calculated and Estimated Lift-Drag Polar

As shown in Table I, summing the results of the previous calculations yields a drag polar represented by the equation

$$C_D = .035832 + .040561 C_L^{1.94} \quad (1)$$

This polar, as indicated previously, does not include the effects of flow separations at the higher lift coefficients. In an effort to develop a more accurate polar upon which to base performance estimates, full scale wind tunnel test data on a similar aircraft (Ref. 5) were examined and fitted by the equation

$$C_D = 0.035 + 0.051 C_L^2 + 0.00138 C_L^{13.42} \quad (2)$$

Plots of these equations are shown in figure 12. Note that the two curves differ little for $C_L < 0.8$. Above $C_L = 0.8$ it is to be expected that equation (2) will more nearly represent the behavior of the ATLIT than equation (1). Despite the fact that equation (2) describes the drag of an unpowered airplane and that drag under some conditions of powered flight may exceed the drag in unpowered flight, equations (1) and (2) were treated as the probable boundaries for the actual ATLIT drag polar. Because of the relatively smaller ATLIT wing area (compared with the aircraft tested in Ref. 5) it is not expected that the ATLIT drag will rise as rapidly with increasing C_L as it does for the aircraft of Ref. 5. Thus, even if the ATLIT drag in powered flight is somewhat greater than in unpowered flight, the drag should be below the boundary given by equation (2).

TABLE I ATLIT DRAG BUILDUP

C.G. @ 26.5% MAC

α_{wing}	$C_{L_{\text{wing}}}$	TRIM $C_{L_{\text{T}}} S_{\text{T}}/S_{\text{W}}$	$C_{D_{\text{T}}} S_{\text{T}}/S_{\text{W}}$	$C_{D_{\text{W}}}$	$C_{D_{\text{TOTAL}}}$	C_L
-4	-.134569	-.003474	.001879	.007316	.038473	-.138043
-2	.063437	.001638	.001852	.006045	.037175	.065075
0	.259752	.006707	.0019772	.008349	.039604	.266459
2	.454464	.011736	.00200	.014132	.04541	.4662
4	.648280	.016741	.00210	.023051	.054429	.66502
6	.841217	.021724	.002184	.034891	.066353	.86294
8	1.032682	.02666	.002265	.049506	.081049	1.05934
10	1.221700	.031549	.002346	.066789	.098413	1.25324
12	1.405880	.036306	.002424	.086509	.118211	1.442
14	1.582697	.040872	.002618	.108327	.140223	1.6235

$$\begin{aligned}
 C_{D_{\text{TOTAL}}} &= C_{D_{\text{W}}} + C_{D_{\text{T}}} S_{\text{T}}/S_{\text{W}} + C_{D_{\text{T}_v}} S_{\text{V}}/S_{\text{W}} + C_{D_{\text{fus}}} + 2 C_{D_{\text{NACELLE}}} \\
 &= C_{D_{\text{W}}} + C_{D_{\text{T}}} S_{\text{T}}/S_{\text{W}} + .0018487 + .01299 + 2(.00722) \\
 &= C_{D_{\text{W}}} + C_{D_{\text{T}}} S_{\text{T}}/S_{\text{W}} + .0292787 \\
 C_L &= C_{L_{\text{W}}} + C_{L_{\text{T}}} S_{\text{T}}/S_{\text{W}}
 \end{aligned}$$

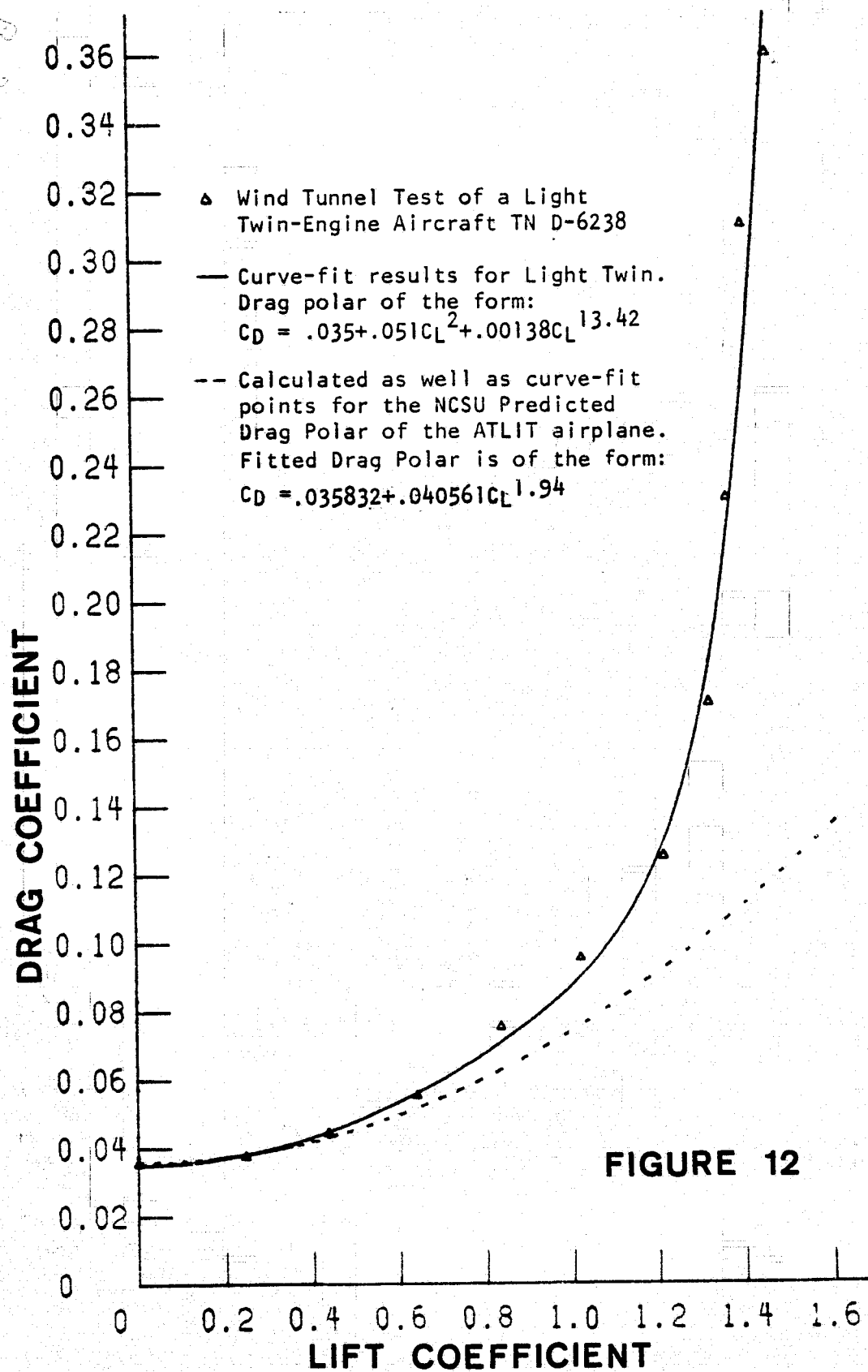


FIGURE 12

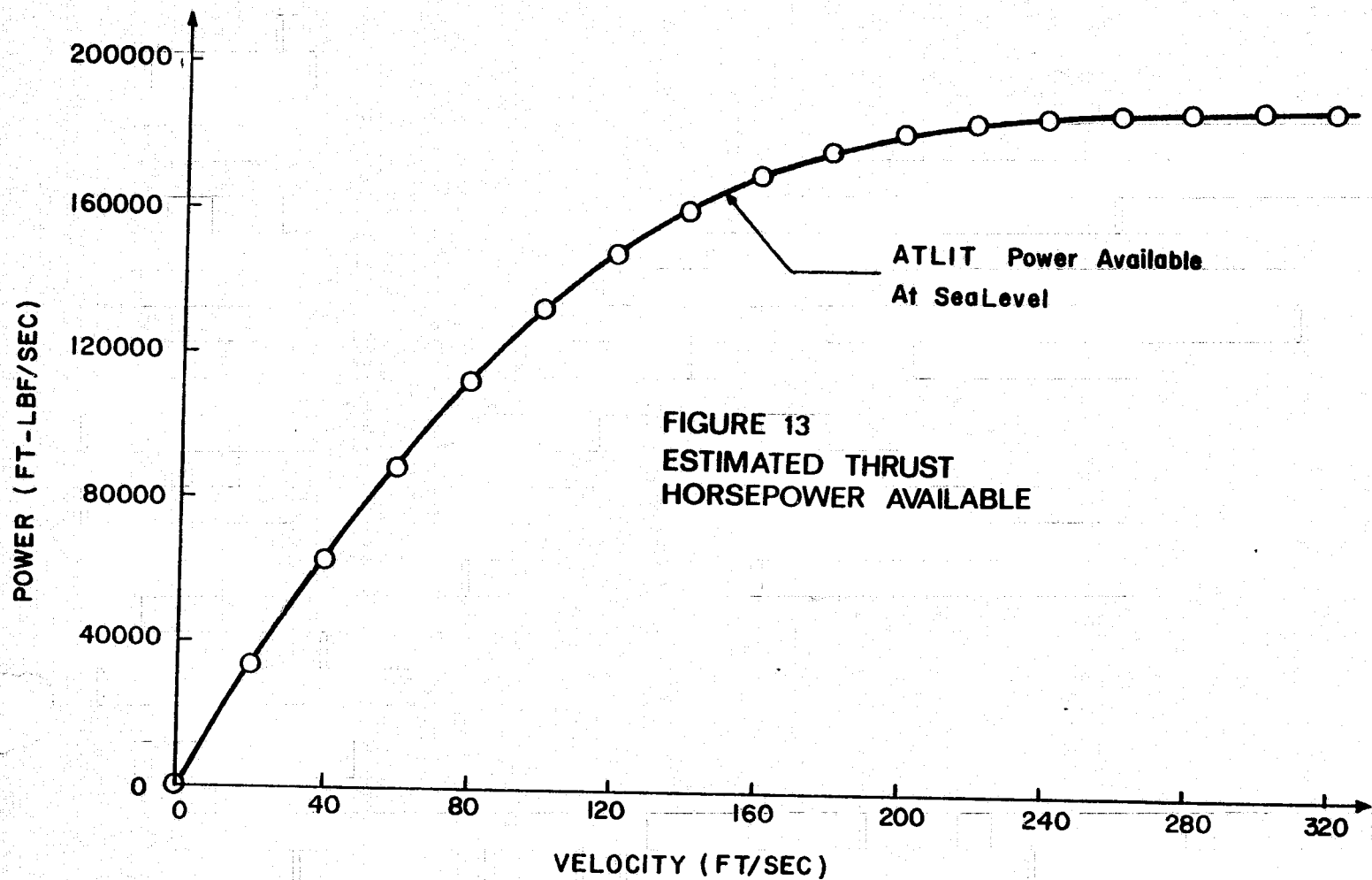


FIGURE 13
ESTIMATED THRUST
HORSEPOWER AVAILABLE

PERFORMANCE PREDICTIONS

The drag polars given by equations (1) and (2) were submitted to the point performance program described in Ref. 2 along with the thrust horsepower data given in figure 13. The latter were derived from engine test cell data and propeller performance charts. They do not include any installation-dependent effects. The data given in Table II represent the output of this program. It will be noted that, compared with the original Seneca, only small improvements in rate-of-climb and cruise speed are expected. This can be explained by the fact that although the airfoil itself offers about a 10% improvement in L/D at $C_L = 0.8$ (the nominal C_L for climb) the wing is responsible for only about 40% of the total drag. Overall aircraft drag is, as a result, only about 4% lower.

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TABLE II . COMPARISON OF PREDICTED ATLIT PERFORMANCE USING THRUST HORSEPOWER DATA SHOWN IN FIG. 13 WITH PIPER SENECA

Performance characteristics	Predicted using light-twin polar from wind tunnel tests (TND-6238) 4200 lbs	Piper Seneca	Predicted using NCSU parabolic polar 4200 lbs
Max. level flight speed (ft/sec)	300.00	286.0	298.9
Min. level flight speed (ft/sec)	123.7	101.2	47.23
Max. rate of climb (ft/sec)	27.1	22.67	28.35
Single engine rate of climb (ft/sec)*	6.06	3.167	7.81
Best rate of climb speed (ft/sec)	168.2	154.0	162.76
Best single engine rate of climb speed (ft/sec)*	155.8	154.0	144.07
Maximum climb angle (degrees)	10.17		12.34°
Maximum climb angle speed (ft/sec)	144.5	132.0	105.42
Best range speed (ft/sec)	167.0	160.0	153.48
Service ceiling (ft)	19,681	18,000	22,525
Absolute ceiling (ft)	21,077	19,400	24,157
Single engine service ceiling (ft)	5,623	3,650	8,852
Single engine absolute ceiling (ft)	7,791	5,000	11,353

* Single engine characteristics were computed using a $C_D = 1.05C_{D_0}$ to account for the vertical tail drag and half the estimated power.

STABILITY PREDICTIONS

The stability predictions for the ATLIT were developed using the aircraft's geometric and inertial parameters and the computer programs described in Ref. 3. The input data and results are shown in figures 14 through 17 and 18 through 21.

PERTINENT AIRPLANE CHARACTERISTICS

DENSITY (SLUGS/FT**3)	=	0.00199	VELOCITY (FT/SEC)	=	286.00000
MASS (SLUGS)	=	124.22400	1VY (SLUG-FT**2)	=	2560.00000
THRUST (POUNDS)	=	0.0	ZJ (FT)	=	0.0
G*CDG(GAMMA) (FT/SEC/SEC)	=	32.00000	G*SGN(GAMMA) (FT/SEC/SEC)	=	0.0
COS(KZ)	=	1.00000	SIN(KZ)	=	0.0
WING AREA (FT**2)	=	155.00000	HORZ. TAIL AREA (FT**2)	=	38.74300
WING SPAN (FT)	=	39.70000	HORZ. TAIL SPAN (FT)	=	13.56000
WING CHORD (FT)	=	4.11000	HORZ. TAIL CHORD (FT)	=	2.85715
WING ASPECT RATIO	=	10.16832	HORZ. TAIL ASPECT RATIO	=	4.74598
WING TAPER RATIO	=	0.50000	HORZ. TAIL TAPER RATIO	=	1.00000
WING ALPHA (DEGREES)	=	0.22900	TAIL ALPHA (DEGREES)	=	-1.63372
1WING (DEGREES)	=	0.50000	ITAIL (DEGREES)	=	0.0
DOWNWASH ANGLE (DEGREES)	=	1.36272	DOWNWASH/ALPHA	=	0.42627
ELEVATOR ANGLE (DEGREES)	=	1.63372	ELEVATOR AREA (FT**2)	=	38.74300
TAIL EFFICIENCY	=	0.90000	ELEVATOR CHORD (FT)	=	2.85715
2-D WING CLA	=	0.12163	2-D TAIL CLA	=	0.11500
CDPIE	=	0.03510	2-D WING CDA	=	0.04670
2-D WING CL	=	0.37984			

DISTANCES

LENGTH OF FUSELAGE (FT)	=	27.67000	WIDTH OF FUSELAGE (FT)	=	4.33000
C.G. TO TAIL-QUARTER-CHORD (FT)	=	16.00000	WING TO TAIL-QUARTER-CHORD (FT)	=	16.00000
C.G. TO WING A.C.(CHORDWISE) (FT)	=	0.0	C.G. TO WING A.C.(VERTICAL) (FT)	=	0.0
NOSE TO WING-QUARTER-CHORD (FT)	=	10.25300	C.G. TO WING-QUARTER-CHORD (FT)	=	0.0
C.G. TO THRUST AXIS (FT)	=	0.0			

LONGITUDINAL STABILITY DERIVATIVES

CL = 0.3174	CLA = 5.6891	CLDA = 3.2591	CLG = 7.6455	CLDE = 0.9419	CLU = 0.0	CT = 0.0
CD = 0.0383	CDA = 0.1610	CDDA = 0.0	CDG = 0.0	CDDE = 0.0	CDJ = 0.0	CTU = 0.0
CM = 0.0	CMA = -1.5001	CMDA = -12.6873	CMG = -29.7635	CMDE = -3.6667	CMJ = 0.0	CTRPM = 0.0

DENOMINATOR ROOTS

ROOT(1) =	-0.01279	+J	-0.14030
ROOT(2) =	-0.01279	+J	0.14030
ROOT(3) =	-4.07258	+J	-4.65815
ROOT(4) =	-4.07258	+J	4.65815

	NATURAL FREQ		DAMPING RATIO	TIME FOR 1/2 DAMPING	SETTLING TIME
	UNDAMPED	DAMPED			
SHORT PERIOD	6.18742	4.65815	0.65820	0.17020	0.73558
PHUGOID	0.14089	0.14030	0.09076	54.20667	234.27487

FIGURE 14

PERTINENT AIRPLANE CHARACTERISTICS

DENSITY (SLUGS/FT**3)	=	0.00199	VELOCITY (FT/SEC)	=	270.00000
MASS (SLUGS)	=	124.22400	TVY (SLUG-FT**2)	=	2.50.00000
THRUST (POUNDS)	=	0.0	ZJ (FT)	=	0.0
G*CS(GAMMA) (FT/SEC/SEC)	=	32.00000	G*SIN(GAMMA) (FT/SEC/SEC)	=	0.0
COS(XZ)	=	1.00000	SIN(XZ)	=	0.0
WING AREA (FT**2)	=	182.73000	HORZ. TAIL AREA (FT**2)	=	38.74300
WING SPAN (FT)	=	39.70000	HORZ. TAIL SPAN (FT)	=	13.56000
WING CHORD (FT)	=	4.75000	HORZ. TAIL CHORD (FT)	=	2.85715
WING ASPECT RATIO	=	8.62524	HORZ. TAIL ASPECT RATIO	=	4.74598
WING TAPER RATIO	=	0.50000	HORZ. TAIL TAPER RATIO	=	1.00000
WING ALPHA (DEGREES)	=	0.22900	TAIL ALPHA (DEGREES)	=	-1.81752
WING (DEGREES)	=	0.50000	ITAIL (DEGREES)	=	0.0
DOWNWASH ANGLE (DEGREES)	=	1.54652	DOWNWASH/ALPHA	=	0.46215
ELEVATOR ANGLE (DEGREES)	=	1.81752	ELEVATOR AREA (FT**2)	=	38.74300
TAIL EFFICIENCY	=	0.90000	ELEVATOR CHORD (FT)	=	2.85715
2-D WING CLA	=	0.12163	2-D TAIL CLA	=	0.11500
COPIE	=	0.03510	2-D WING CDA	=	0.04670
2-D WING CL	=	0.37984			

DISTANCES

LENGTH OF FUSELAGE (FT)	=	27.67000	WIDTH OF FUSELAGE (FT)	=	4.33000
C.G. TO TAIL QUARTER-CHORD (FT)	=	16.00000	WING TO TAIL QUARTER-CHORD (FT)	=	16.00000
C.G. TO WING A.C.(CHORDWISE) (FT)	=	0.0	C.G. TO WING A.C.(VERTICAL) (FT)	=	0.0
NOSE TO WING QUARTER-CHORD (FT)	=	10.25500	C.G. TO WING QUARTER-CHORD (FT)	=	0.0
C.G. TO THRUST AXIS (FT)	=	0.0			

LONGITUDINAL STABILITY DERIVATIVES

CL = 0.3083	CLA = 5.5081	CLDA = 2.7055	CLQ = 5.6115	CLDE = 0.7989	CLU = 0.0	CT = 0.0
CD = 0.0386	CDA = 0.1735	CDDA = 0.0	CDQ = 0.0	CDDE = 0.0	CDJ = 0.0	CTU = 0.0
CM = 0.0	CMA = -0.3582	CMDA = -9.1134	CMQ = -18.9018	CMDE = -2.6912	CMU = 0.0	CTRPM = 0.0

DENOMINATOR ROOTS

ROOT(1) =	-0.01610	+J	-0.11915
ROOT(2) =	-0.01610	+J	0.11915
ROOT(3) =	-4.33009	+J	-0.90362
ROOT(4) =	-4.33009	+J	0.90362

	NATURAL FREQ		DAMPING RATIO	TIME FOR 1/2 DAMPING	SETTLING TIME
	UNDAMPED	DAMPED			
SHORT PERIOD	4.42337	0.90362	0.97891	0.16008	0.69183
PHUGOID	0.12023	0.11915	0.13393	03.04546	186.03745

FIGURE 15

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PERTINENT AIRPLANE CHARACTERISTICS

DENSITY (SLUGS/FT**3) = 0.00238
 MASS (SLUGS) = 124.22400
 THRUST (POUNDS) = 0.0
 G* $\cos(\gamma)$ (FT/SEC/SEC) = 32.03800
 $\cos(\alpha)$ = 1.00000
 WING AREA (FT**2) = 155.00000
 WING SPAN (FT) = 39.70000
 WING CHORD (FT) = 4.11000
 WING ASPECT RATIO = 10.16832
 WING TAPER RATIO = 0.50000
 WING ALPHA (DEGREES) = 5.60050
 I WING (DEGREES) = 0.50000
 DOWNWASH ANGLE (DEGREES) = 3.58157
 ELEVATOR ANGLE (DEGREES) = -1.51893
 TAIL EFFICIENCY = 0.90000
 2-D WING CLA = 0.11606
 CDPIE = 0.03510
 2-D WING CL = 0.99830

VELOCITY (FT/SEC) = 161.00000
 IYY (SLUG-FT**2) = 2560.00000
 ZJ (FT) = 0.0
 G*SIN(γ) (FT/SEC/SEC) = 3.22000
 SIN(α) = 0.0
 HORZ. TAIL AREA (FT**2) = 38.74300
 HORZ. TAIL SPAN (FT) = 13.56000
 HORZ. TAIL CHORD (FT) = 2.85715
 HORZ. TAIL ASPECT RATIO = 4.74598
 HORZ. TAIL TAPER RATIO = 1.00000
 TAIL ALPHA (DEGREES) = 1.51893
 ITAIL (DEGREES) = 0.0
 DOWNWASH/ALPHA = 0.41020
 ELEVATOR AREA (FT**2) = 38.74300
 ELEVATOR CHORD (FT) = 2.85715
 2-D TAIL CLA = 0.11500
 2-D WING COA = 0.03603

DISTANCES

LENGTH OF FUSELAGE (FT) = 27.67000
 C.G. TO TAIL QUARTER-CHORD (FT) = 16.00000
 C.G. TO WING A.C. (CHORDWISE) (FT) = 0.0
 NOSE TO WING QUARTER-CHORD (FT) = 10.25500
 C.G. TO THRUST AXIS (FT) = 0.0

WIDTH OF FUSELAGE (FT) = 4.33000
 WING TO TAIL QUARTER-CHORD (FT) = 16.00000
 C.G. TO WING A.C. (VERTICAL) (FT) = 0.0
 C.G. TO WING QUARTER-CHORD (FT) = 0.0

LONGITUDINAL STABILITY DERIVATIVES

CL = 0.8342 CL α = 5.4747 CL α α = 3.1362 CL α β = 7.6455 CL α δ = 0.9419 CL α $\dot{\delta}$ = 0.0 CT = 0.0
 CD = 0.0571 CD α = 0.3251 CD α α = 0.0 CD α β = 0.0 CD α δ = 0.0 CD α $\dot{\delta}$ = 0.0 CTU = 0.0
 CM = 0.0 CM α = -1.5615 CM α α = -12.2090 CM α β = -29.7635 CM α δ = -3.6667 CM α $\dot{\delta}$ = 0.0 CTRPM = 0.0

DENOMINATOR ROOTS

ROOT(1) = -0.00293 +j -0.24574
 ROOT(2) = -0.00293 +j 0.24574
 ROOT(3) = -2.70232 +j -2.86218
 ROOT(4) = -2.70232 +j 2.86218

	NATURAL FREQ	DAMPING RATIO	TIME FOR 1/2 DAMPING	SETTLING TIME
SHORT PERIOD	UNDAMPED 3.93632 DAMPED 2.86218	0.68651	0.25650	1.10857
PHUGOID	0.24576	0.24574	0.01192	236.65381

FIGURE 16

PERTINENT AIRPLANE CHARACTERISTICS

DENSITY (SLUGS/FT**3)	= 0.00238	VELOCITY (FT/SEC)	= 161.00000
MASS (SLUGS)	= 124.22400	1VY (SLUG-FT**2)	= 2560.00000
THRUST (POUNDS)	= 0.0	ZJ (FT)	= 0.0
G*CDOS(GAMMA) (FT/SEC/SEC)	= 32.03800	G* SIN(GAMMA) (FT/SEC/SEC)	= 3.22000
COS(XZ)	= 1.00000	SIN(XZ)	= 0.0
WING AREA (FT**2)	= 182.73000	HORZ. TAIL AREA (FT**2)	= 38.74300
WING SPAN (FT)	= 39.70000	HORZ. TAIL SPAN (FT)	= 13.56000
WING CHORD (FT)	= 4.75000	HORZ. TAIL CHORD (FT)	= 2.85715
WING ASPECT RATIO	= 8.62524	HORZ. TAIL ASPECT RATIO	= 4.74598
WING TAPER RATIO	= 0.50000	HORZ. TAIL TAPER RATIO	= 1.00000
WING ALPHA (DEGREES)	= 5.00050	TAIL ALPHA (DEGREES)	= 0.0
1WING (DEGREES)	= 0.50000	ITAIL (DEGREES)	= 0.0
DOWNWASH ANGLE (DEGREES)	= 4.06464	DOWNWASH/ALPHA	= 0.46453
ELEVATOR ANGLE (DEGREES)	= -1.03586	ELEVATOR AREA (FT**2)	= 38.74300
TAIL EFFICIENCY	= 0.90000	ELEVATOR CHORD (FT)	= 2.85715
2-D WING CLA	= 0.11606	2-D TAIL CLA	= 0.11500
CDPIE	= 0.03510	2-D WING CDA	= 0.03603
2-D WING CL	= 0.99830		

DISTANCES

LENGTH OF FUSELAGE (FT)	= 27.67000	WIDTH OF FUSELAGE (FT)	= 4.33000
C.G. TO TAIL QUARTER-CHORD (FT)	= 16.00000	WING TO TAIL QUARTER-CHORD (FT)	= 16.00000
C.G. TO WING A.C.(CHORDWISE) (FT)	= 0.0	C.G. TO WING A.C.(VERTICAL) (FT)	= 0.0
NOSE TO WING QUARTER-CHORD (FT)	= 10.25500	C.G. TO WING QUARTER-CHORD (FT)	= 0.0
C.G. TO THRUST AXIS (FT)	= 0.0		

LONGITUDINAL STABILITY DERIVATIVES

CL = 0.8104	CLA = 5.3068	CLDA = 2.6067	CLQ = 5.6115	CLDE = 0.7989	CLU = 0.0	CT = 0.0
CD = 0.0590	CDA = 0.3570	CDDA = 0.0	CDQ = 0.0	CDDE = 0.0	CDJ = 0.0	CTU = 0.0
CM = 0.0	CMA = -0.4291	CMUA = -8.7804	CMQ = -18.9018	CMDE = -2.6912	CMJ = 0.0	CTRPM = 0.0

DENOMINATOR ROOTS

ROOT(1) =	-0.01317	+J	-0.21385
ROOT(2) =	-0.01317	+J	0.21385
ROOT(3) =	-2.86418	+J	-0.72226
ROOT(4) =	-2.86418	+J	0.72226

	NATURAL FREQ	DAMPING RATIO	TIME FOR 1/2 DAMPING	SETTLING TIME
SHORT PERIOD	UNDAMPED 2.95384	DAMPED 0.72226	0.96965	0.24201
PHUGOID	0.21426	0.21385	0.06146	52.63901
				1.04592
				227.49962

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FIGURE 17

PERTINENT AIRPLANE CHARACTERISTICS

RHD = 0.001988	WING AREA = 155.000000	MASS = 124.224000	G* $\cos(\text{GAMMA})$ = 32.000000
U = 286.0000	CHORD = 4.110000	SPAN = 39.3500	G*SIN(GAMMA) = 0.0
IXX = 5250.0000	IXZ = 0.0	IZZ = 7323.0000	CL = 0.317400
SA = 0.0	DIH = 7.000000	ZW = 1.083300	FUSVOL = 285.680651
H = 4.292000	SV = 19.500000	BV = 5.883000	RI = 0.916700
TR = 0.500000	ZV = 2.667000	ETAV = 0.960000	SBS = 80.909591
LF = 27.400000	LT = 16.000000	XM = 10.000000	H1 = 2.833000
M2 = 2.833000	W = 4.330000	SAH = 0.0	CLA2DW = 6.969399
BH = 13.558000	SH = 36.500000	TRH = 1.000000	CLA2DH = 6.589500
BA = 8.600000	CA = 0.662000	SR = 7.600000	ALPHA = 0.003996
CDO = 0.035100	YI = 7.939800	HNOSE = 1.300000	WNOSE = 2.000000
HFCY = 2.833000	WFCY = 4.000000	LFCY = 6.667000	LMH = 10.000000
HBCY = 4.000000	WBCY = 4.250000	LBCY = 13.667000	

LATERAL STABILITY DERIVATIVES

CYB = -0.479767	CLB = -0.165963	CNB = 0.124548	CYP = -0.240417	CLP = -0.586804	CNP = -0.041782
CYR = 0.324597	CLR = 0.099626	CNR = -0.142518	CYDA = 0.0	CLDA = 0.173526	CNDA = -0.014204
CYDR = 0.226060	CLDR = 0.015322	CNDR = -0.088241			

DENOMINATOR ROOTS

ROOT(1) =	-0.30404	+J	-3.01431
ROOT(2) =	-0.30404	+J	3.01431
ROOT(3) =	-4.02414	+J	0.0
ROOT(4) =	-0.01499	+J	0.0
ROOT(5) =	0.0	+J	0.0

	NATURAL FREQ UNDAMPED	FREQ DAMPED	DAMPING RATIO	TIME FOR 1/2 DAMPING	SETTLING TIME
DUTCH ROLL	3.0296	3.0143	0.10036	2.27981	9.85307

FIGURE 18

PERTINENT AIRPLANE CHARACTERISTICS

RHO = 0.001988	WING AREA = 182.730000	MASS = 124.224000	G*COS(GAMMA) = 32.000000
U = 286.0000	CHORD = 4.750000	SPAN = 39.3500	G*SIN(GAMMA) = 0.0
IXX = 5250.0000	IXZ = 0.0	IZZ = 7323.0000	CL = 0.317400
SA = 0.0	DTH = 7.000000	ZW = 1.083300	FUSVOL = 285.680651
H = 4.292000	SV = 19.500000	BV = 5.883000	RI = 0.916700
TR = 0.500000	ZV = 2.667000	ETAV = 0.960000	SBS = 90.909591
LF = 27.400000	LT = 16.000000	XM = 10.000000	HI = 2.833000
H2 = 2.833000	W = 4.330000	SAH = 0.0	CLA2DW = 6.969399
BH = 13.558000	SH = 36.500000	TRH = 1.000000	CLA2DH = 6.589500
BA = 8.600000	CA = 0.662000	SR = 7.600000	ALPHA = 0.003996
CDO = 0.035100	YI = 7.939800	HNOSE = 1.300000	WNOSE = 2.000000
HFCY = 2.833000	WFCY = 4.000000	LFCY = 6.667000	LMH = 10.000000
HBCY = 4.000000	WBCY = 4.250000	LBCY = 13.667000	

LATERAL STABILITY DERIVATIVES

CYB = -0.399758	CLB = -0.163115	CNB = 0.100244	CYP = -0.223734	CLP = -0.536032	CNP = -0.036939
CYR = 0.263831	CLR = 0.094446	CNR = -0.117575	CYDA = 0.0	CLDA = 0.153825	CNDA = -0.012239
CYDR = 0.191755	CLDR = 0.012996	CNDR = -0.074850			

DENOMINATOR ROOTS

ROOT(1) =	-0.28228	+J	-2.96730
ROOT(2) =	-0.28228	+J	2.96730
ROOT(3) =	-4.33740	+J	0.0
ROOT(4) =	-0.01724	+J	0.0
ROOT(5) =	0.0	+J	0.0

	NATURAL FREQ UNDAMPED	DAMPED	DAMPING RATIO	TIME FOR 1/2 DAMPING	SETTLING TIME
DUTCH ROLL	2.9807	2.9673	0.09470	2.45549	10.61234

FIGURE 19

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PERTINENT AIRPLANE CHARACTERISTICS

RHO = 0.002378	WING AREA = 155.000000	MASS = 124.224000	G * COS(GAMMA) = 32.038000
U = 161.0000	CHORD = 4.110000	SPAN = 39.3500	G * SIN(GAMMA) = 3.220000
IXX = 5250.0000	IXZ = 0.0	IZZ = 7323.0000	CL = 0.834200
SA = 0.0	DIH = 7.000000	ZW = 1.083300	FUSVOL = 295.680651
H = 4.292000	SV = 19.500000	BV = 5.883000	R1 = 0.916700
TR = 0.500000	ZV = 2.667000	ETAV = 0.960000	SBS = 80.909591
LF = 27.400000	LT = 16.000000	XM = 10.000000	HI = 2.833000
H2 = 2.833000	W = 4.330000	SAH = 0.0	CLA2DW = 6.650238
BH = 13.558000	SH = 36.500000	TRH = 1.000000	CLA2DH = 6.589500
BA = 8.600000	CA = 0.662000	SR = 7.600000	ALPHA = 0.097747
CDO = 0.035100	YI = 7.939800	HNOSE = 1.300000	WNOSE = 2.000000
HFCY = 2.833000	WFCY = 4.000000	LFCY = 6.667000	LMH = 10.000000
HBCY = 4.000000	WBCY = 4.250000	LBCY = 13.667000	

LATERAL STABILITY DERIVATIVES

CYB = -0.479767	CLB = -0.223541	CNB = 0.130041	CYP = -0.312663	CLP = -0.570755	CNP = -0.090307
CYR = 0.398499	CLR = 0.225509	CNR = -0.136648	CYDA = 0.0	CLDA = 0.178526	CNDA = -0.037332
CYDR = 0.226060	CLDR = 0.015322	CNDR = -0.088241			

DENOMINATOR ROOTS

ROOT(1) = -0.11234	+J	-2.07583
ROOT(2) = -0.11234	+J	2.07583
ROOT(3) = -2.83109	+J	0.0
ROOT(4) = 0.01510	+J	0.0
ROOT(5) = 0.0	+J	0.0

	NATURAL FREQ UNDAMPED	NATURAL FREQ DAMPED	DAMPING RATIO	TIME FOR 1/2 DAMPING	SETTLING TIME
DUTCH ROLL	2.0789	2.0758	0.05404	6.17008	26.66638

FIGURE 20

PERTINENT AIRPLANE CHARACTERISTICS

RHO = 0.002378	WING AREA = 182.730000	MASS = 124.224000	G* $\cos(\text{GAMMA})$ = 32.038000
U = 161.0000	CHORD = 4.750000	SPAN = 39.3500	G* $\sin(\text{GAMMA})$ = 3.220000
IXX = 5250.0000	IXZ = 0.0	IZZ = 7323.0000	CL = 0.834200
SA = 0.0	DIH = 7.000000	ZW = 1.083300	FUSVOL = 285.680651
H = 4.292000	SV = 19.500000	BV = 5.883000	R1 = 0.916700
TR = 0.500000	ZV = 2.667000	ETAV = 0.960000	SBS = 90.909591
LF = 27.400000	LT = 16.000000	XM = 10.000000	H1 = 2.833000
H2 = 2.833000	W = 4.330000	SAH = 0.0	CLA2DW = 6.650238
BH = 13.558000	SH = 36.500000	TRH = 1.000000	CLA2DH = 6.589500
BA = 8.600000	CA = 0.662000	SR = 7.600000	ALPHA = 0.097747
COO = 0.035100	YI = 7.939800	HNOSE = 1.300000	WNOSE = 2.000000
HFCY = 2.833000	WFCY = 4.000000	LFCY = 6.667000	LMH = 10.000000
HBCY = 4.000000	WBCY = 4.250000	LBCY = 13.667000	

LATERAL STABILITY DERIVATIVES

CYB = -0.399758	CLB = -0.235619	CNB = 0.104904	CYP = -0.296921	CLP = -0.522844	CNP = -0.080538
CYR = 0.337733	CLR = 0.218601	CNR = -0.110318	CYDA = 0.0	CLDA = 0.153825	CNDA = -0.032167
CYDR = 0.191755	CLDR = 0.012996	CNDR = -0.074850			

DENOMINATOR ROOTS

ROOT(1) =	-0.07526	+J	-2.09412
ROOT(2) =	-0.07526	+J	2.09412
ROOT(3) =	-3.07710	+J	0.0
ROOT(4) =	-0.01002	+J	0.0
ROOT(5) =	0.0	+J	0.0

	NATURAL FREQ UNDAMPED	DAMPED	DAMPING RATIO	TIME FOR 1/2 DAMPING	SETTLING TIME
DUTCH ROLL	2.0955	2.0941	0.03592	9.21014	39.80514

FIGURE 21

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MEASURING DRAG AND THRUST IN FLIGHT

The Concept

Most techniques for the determination of aircraft drag in flight rely on the fact that when the aircraft is in unaccelerated flight, the forces along its x-axis, principally the thrust and drag, are in balance. Then, if one knows the propulsive thrust for a particular flight condition, he automatically knows the aircraft drag at that condition. Thus, to apply these techniques one must know that $\dot{V} = 0$ as well as the propulsive thrust as a function of flight speed, altitude, and power setting.

This, unfortunately, is not determined easily. Although engine output can be measured accurately on a test stand as a function of altitude and power setting and propeller characteristics can be determined in a test cell as a function of RPM and flight velocity, the flow disturbances caused by putting a cowled engine behind a propeller and mounting the whole on an airplane are not readily determined *a priori*. Hence, efforts have been made from time to time to measure inflight thrust using such techniques as the torque reaction produced by the engine or the vehicle acceleration at constant altitude produced by varying power levels.

The reader will readily appreciate the difficulties which such techniques entail. In the case of the ATLIT aircraft, instrumentation to measure reaction torques was not available and the longitudinal accelerometer provided in the instrument package was not considered a primary test instrument, at least initially. Further, the establishment of really unaccelerated flight at many different speeds is very consuming of flight test time. It is for these reasons that an effort was made to develop an alternate technique to measure thrust and drag simultaneously in accelerated flight.

The origin of the concept is quite simple. Recent workers attempting to extract the values of stability derivatives from flight data have all faced the problem of fitting an analytical model containing thirteen or more undetermined coefficients to a set of four or five simultaneous time histories. That is, the number of unknowns greatly exceeds the number of independent equations one can write to describe the motion. The problem is usually attacked (see Ref. 6 for example) by fitting the equations to the time histories at a number of different times. Theoretically, one need only fit the equation the same number of times as one desires to find coefficient values. In practice, it is fit many, many times and the values which best satisfy the time history in some statistical sense are chosen. If the initial estimates of the parameter values are reasonably accurate, the procedure usually converges on the correct values. However, since the system is not determinant, convergence is not guaranteed.

The problem in determining both drag and thrust simultaneously in flight is that there is one more unknown than there is equation. Mathematically

this means that for any flight condition there are an infinite number of sets of T and D which satisfy the equation. For any T there is only one D, but one can find the corresponding D for any arbitrary choice of T whether it has any physical meaning or not.

Following the fairly successful approach used in stability derivative extraction, it was reasoned that if one would write the equation of motion substituting flight data for different times in the flight, he could create a system of equations equal to the number of unknowns. Formally, the equation of motion of the vehicle along its trajectory in the X-Z terrestrial plane is

$$\frac{\dot{V}}{g} + \sin \gamma = \frac{T - D}{W} . \quad (3)$$

In order to apply the technique, we wish to express the thrust and drag in a polynomial expansion of some easily-measured flight variable with the coefficients to be undetermined constants. Now, the thrust is known to depend primarily upon flight speed for a given power setting so that we choose the representation

$$T = \frac{\cos \alpha}{V} \left[P_0 + P_1 V + P_2 V^2 \right] . \quad (4)$$

In other words, we assume that the power-speed relationship is a parabola. Given the characteristics of most propellers, P_0 and P_1 will be positive and P_2 negative. We insert the $\cos \alpha$ term because we assume that the propeller thrust is always applied along the x-body axis rather than along the flight path. Drag, on the other hand, is always defined with respect to the flight path. We can represent the drag by the equation

$$D = 1/2 \rho S V^2 \left[C_{D0} + C_{D1} \alpha^2 + C_{D2} \alpha^6 \right] , \quad (5)$$

where α is measured from zero lift and the sixth power for the third term was chosen on the basis of curve fits to some actual data. Note, however, that we may alter the model to represent a particular situation more accurately without affecting the validity of the procedure.

Substituting these relationships into the equation of motion yields

$$\frac{W\dot{V}}{g} + W \sin \gamma = \frac{\cos \alpha}{V} \left[P_0 + P_1 V + P_2 V^2 \right] - \frac{1}{2} \rho S V^2 \left[C_{D0} + C_{D1} \alpha^2 + C_{D2} \alpha^6 \right] . \quad (6)$$

This equation has six unknown but constant coefficients. By determining the flight values of γ , W , V , $\dot{V}$, ρ , and α at six different times we create a system of six linear equations in six unknowns. This can then be solved for the values of P_0 , P_1 , P_2 , C_{D_0} , C_{D_1} , and C_{D_2} .

Difficulties in Concept Execution

Unfortunately, this system of equations is what mathematicians call ill-conditioned; that is, very small changes in any of the measured values (α , W , V , $\dot{V}$, γ , ρ) can cause the coefficient values (P_0 , P_1 , etc.) to change radically. Further, the solution guarantees to pass through the six selected points only. For any other speed, acceleration, angle of attack, weight, flight path angle, or altitude, the thrust or drag computed with these six coefficients may be quite wrong. In addition, the coefficient values themselves may be ridiculous (for example, a negative C_{D_1} value), yet the total drag as determined from $C_{D_0} + C_{D_1} \alpha^2 + C_{D_2} \alpha^6$ may be very reasonable.

These problems are to some extent traceable to the adequacy of the analytical model used. A model which does not well represent what actually occurs will, when fit to the data using this procedure, produce nonsense numbers for some of the coefficients, i.e., nonsense numbers in the physical sense but absolutely correct numbers in the mathematical sense. For example, if the speed-power relation should in fact be a constant, then an attempt to fit it with a parabola will usually yield non-zero values for P_1 and P_2 . While for the speeds, etc. at which the data are submitted to the solution routine the sum of the three terms will be correct, individually the values make little physical sense. Thus, a successful solution routine must have a provision for examining the results (at least manually) for reasonableness and for changing the analytical model if the results are not reasonable.

There is also a problem concerned with the selection of the six data sets submitted to the solution routine. The reader will recognize that if one selects six points very close together in speed, the data must be extremely accurate because all significance can be lost in taking the differences between adjacent numbers as one does in solving a system of six equations.

Amelioration of Solution Difficulties

One means of selecting the six points to be submitted to the solution routine so that it will yield reasonable results is to select those points where the velocities are given by

$$V_1 = V_{\min} \text{ for the maneuver}$$

$$V_2 = V_{\max} \text{ for the maneuver}$$

$$V_3 = V_1 \left[\frac{V_2}{V_1} \right]^{1/5}$$

$$V_4 = V_3 \left[\frac{V_2}{V_1} \right]^{1/5}$$

$$V_5 = V_4 \left[\frac{V_2}{V_1} \right]^{1/5}$$

$$V_6 = V_5 \left[\frac{V_2}{V_1} \right]^{1/5} .$$

(7)

This procedure spaces the points over all the available data giving emphasis to the portion of the drag curve when changes with speed are most rapid. Where applied to theoretically-generated data, the original coefficients can be recovered to within 1%.

For a variety of reasons, flight measurements will never be as accurate or as noise-free as theoretically-generated data. One then asks the question, "How can I use the remainder of the data (the sets of α , ρ , γ , V , $\dot{V}$, W beyond the six sets mentioned above) taken during a 30-second maneuver to improve the accuracy of the coefficient extraction procedure?" The classical answer is to fit the assumed form of the curve (equation 6) to the data by a least-squares technique. What this does is to determine those values of the coefficients (P_0 , P_1 , P_2 , C_{D0} , C_{D1} , C_{D2}) which make the sum of the squares of the distances from the curve to each of the data points a minimum. The procedure is the following:

Let S be defined by the equation

$$S = \sum_{i=1}^N \left[\frac{W_i \dot{V}_i}{g} + W_i \sin (\theta_i - \alpha_i) - \frac{\cos \alpha_i}{V_i} P_0 - \cos \alpha_i P_1 - V_i \cos \alpha_i P_2 + \frac{\rho_i S V_i^2}{2} C_{D_0} + \frac{\rho_i S V_i^2}{2} \alpha_i^2 C_{D_1} + \frac{\rho_i S V_i^2}{2} \alpha_i^6 C_{D_2} \right]^2, \quad (8)$$

where the subscript i refers to the value of the variable at the i^{th} time. This equation is a measure of the precision with which the theoretical model with six unknown constants ($P_0, P_1, P_2, C_{D_0}, C_{D_1}, C_{D_2}$) satisfies the experimental data. The closer S is to zero, the better the fit. We wish to minimize the error with respect to all six unknowns. Thus, we set

$$\frac{\partial S}{\partial P_0} = 0 = -2 \sum_{i=1}^N \left[\frac{\cos \alpha_i}{V_i} \right] \left[a_1 - a_2 P_0 - a_3 P_1 - a_4 P_2 + a_5 C_{D_0} + a_6 C_{D_1} + a_7 C_{D_2} \right]$$

$$\frac{\partial S}{\partial P_1} = 0 = -2 \sum_{i=1}^N [a_3] \left[a_1 - a_2 P_0 - a_3 P_1 - a_4 P_2 + a_5 C_{D_0} + a_6 C_{D_1} + a_7 C_{D_2} \right]$$

$$\frac{\partial S}{\partial P_2} = 0 = -2 \sum_{i=1}^N [a_4] \left[a_1 - a_2 P_0 - a_3 P_1 - a_4 P_2 + a_5 C_{D_0} + a_6 C_{D_1} + a_7 C_{D_2} \right]$$

$$\frac{\partial S}{\partial C_{D_0}} = 0 = 2 \sum_{i=1}^N [a_5] \left[a_1 - a_2 P_0 - a_3 P_1 - a_4 P_2 + a_5 C_{D_0} + a_6 C_{D_1} + a_7 C_{D_2} \right]$$

$$\frac{\partial S}{\partial C_{D_1}} = 0 = 2 \sum_{i=1}^N [a_6] \left[a_1 - a_2 P_0 - a_3 P_1 - a_4 P_2 + a_5 C_{D_0} + a_6 C_{D_1} + a_7 C_{D_2} \right]$$

$$\frac{\partial S}{\partial C_{D_2}} = 0 = 2 \sum_{i=1}^N [a_7] \left[a_1 - a_2 P_0 - a_3 P_1 - a_4 P_2 + a_5 C_{D_0} + a_6 C_{D_1} + a_7 C_{D_2} \right] \quad (9)$$

where

$$a_1 = \frac{W_i \dot{V}_i}{g} + W_i \sin (\theta_i - \alpha_i)$$

$$a_2 = \frac{\cos \alpha_i}{V_i}$$

$$a_3 = \cos \alpha_i$$

$$a_4 = V_i \cos \alpha_i$$

$$a_5 = \frac{\rho_i S V_i^2}{2}$$

$$a_6 = \frac{\rho_i S V_i^2}{2} \alpha_i^2$$

$$a_7 = \frac{\rho_i S V_i^2}{2} \alpha_i^6$$

In expanded form these equations may be written

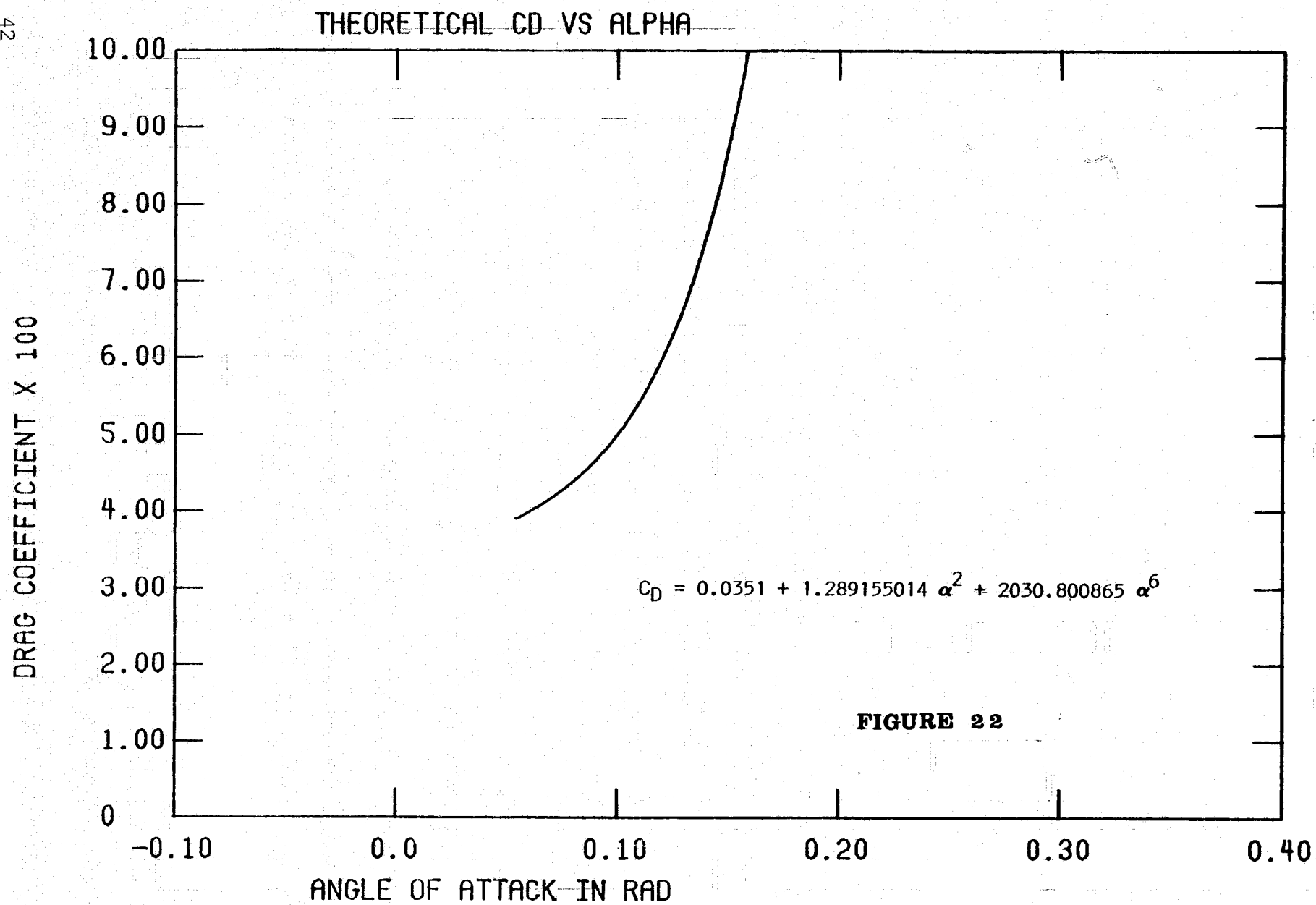
$$\begin{aligned} \sum_{i=1}^N \frac{\cos \alpha_i}{V_i} \left[\frac{W_i \dot{V}_i}{g} + W_i \sin(\theta_i - \alpha_i) \right] &= \sum_{i=1}^N \frac{\cos^2 \alpha_i}{V_i^2} P_0 + \sum_{i=1}^N \frac{\cos^2 \alpha_i}{V_i} P_1 \\ &+ \sum_{i=1}^N \cos^2 \alpha_i P_2 - \sum_{i=1}^N \frac{\rho_i S V_i^2}{2} \cos \alpha_i C_{D_0} \\ &- \sum_{i=1}^N \frac{\rho_i S V_i^2}{2} \alpha_i^2 \cos \alpha_i C_{D_1} + \sum_{i=1}^N \frac{\rho_i S V_i^2}{2} \alpha_i^6 \cos \alpha_i C_{D_2} \end{aligned} \quad (10)$$

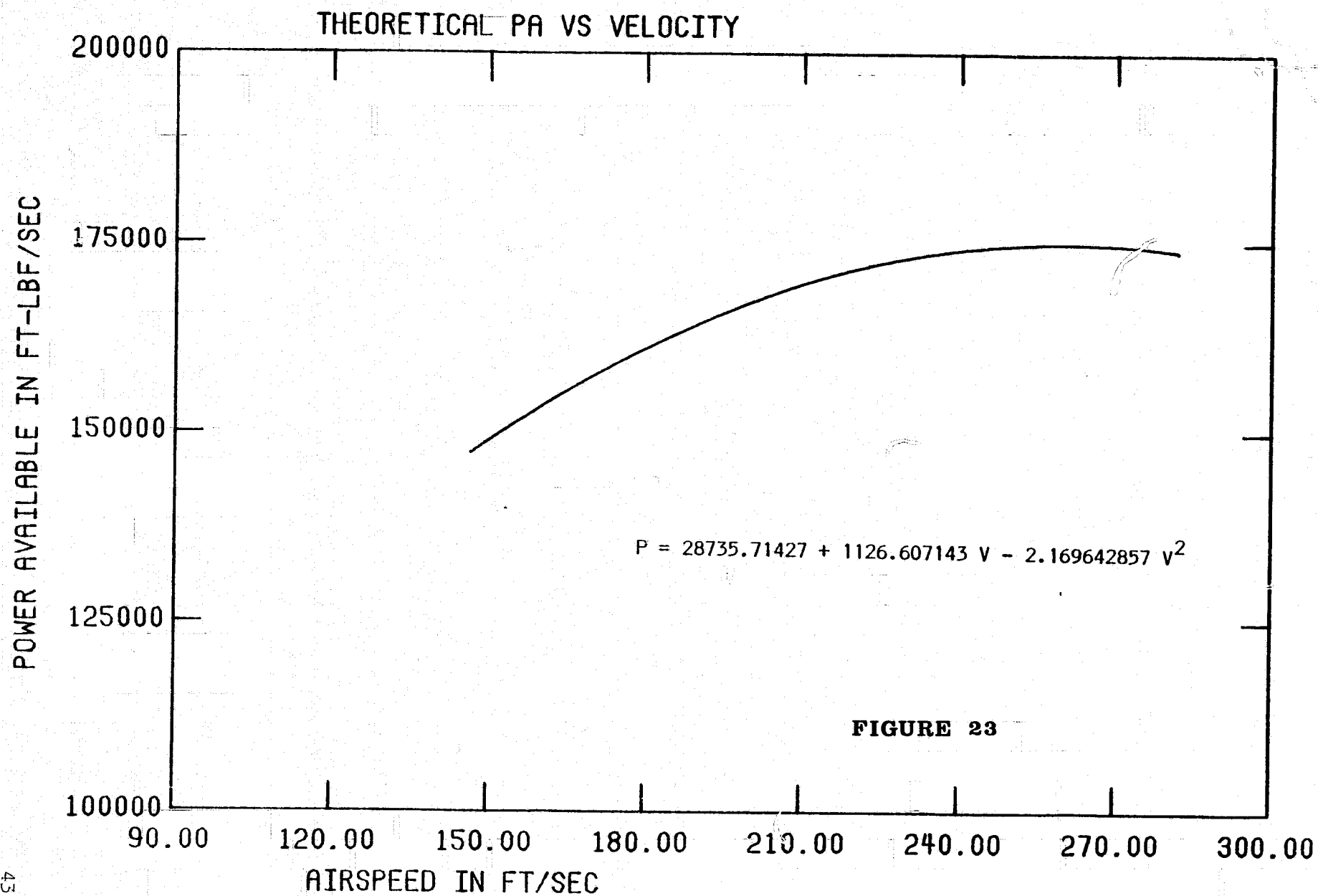
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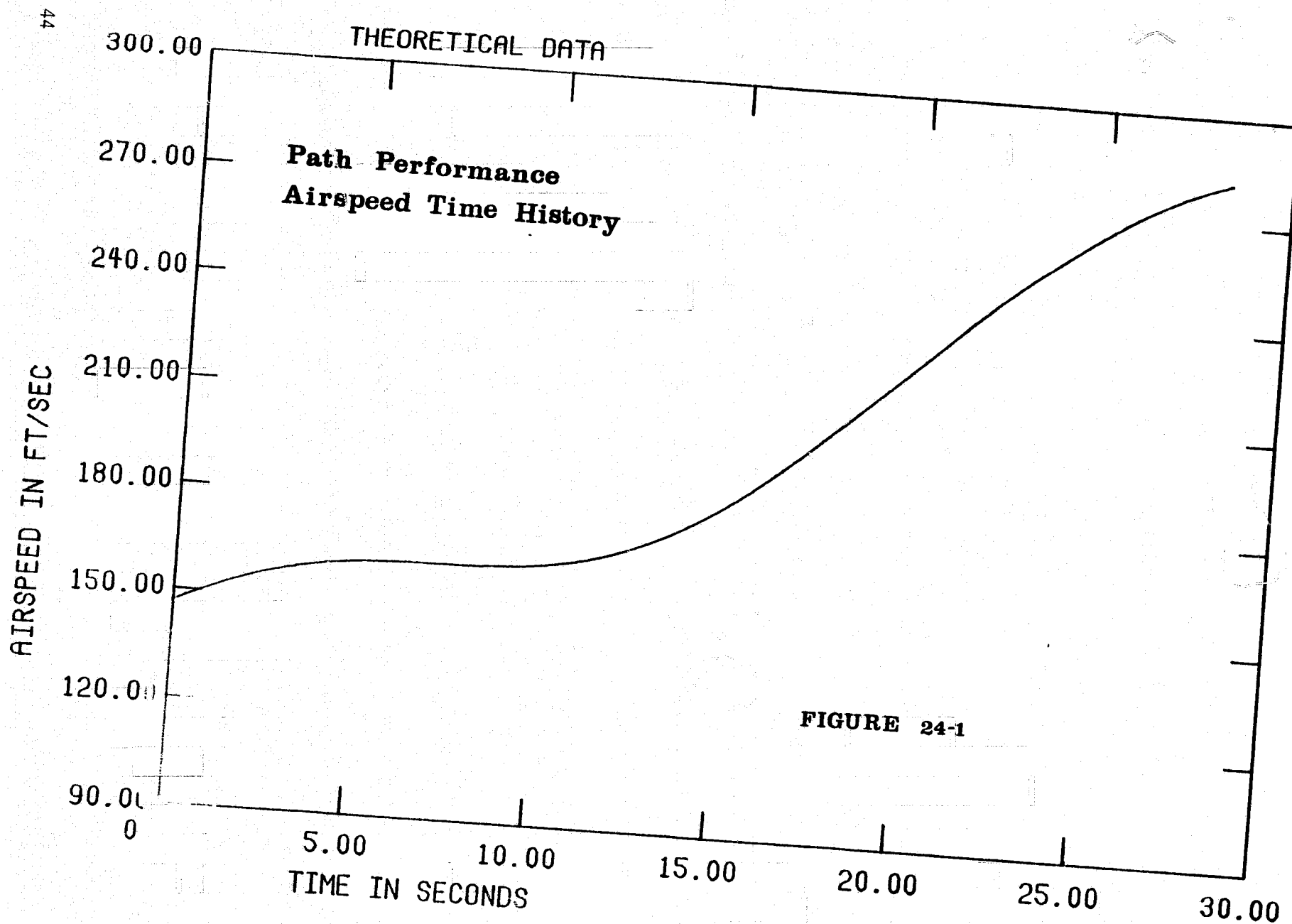
The term $\sum_{i=1}^N \frac{\cos^2 \alpha_i}{V_i^2}$ multiplying P_0 represents a sum of terms $\frac{\cos^2 \alpha}{V}$, for each of the N data points in the set. Once this and the similar sums are formed, one has simply a system of six first order algebraic equations in six unknowns which can be solved with some labor for the values of the six unknown coefficients. These coefficient values provide the "best" fit, using the model

chosen, to the set encompassing all the data points. The coefficient values may change, of course, if data are added to or deleted from the set. Needless to say, the coefficient values may be in error if the data contains spurious signals or if the model chosen does not represent the physical situation adequately. Also if the data points are not well-distributed over the entire speed range, the coefficients which are the principal contributors to the function value in an underrepresented speed region may be in error. As a result of these factors it is necessary to approach the extraction process with some care.

Despite these difficulties, the following example is illustrative of what can be done using this method. Figure 22 shows the assumed drag variation with angle of attack and figure 23 the assumed power variation with speed. These data were then inserted in the NCSU path performance program described in Ref. 2 to obtain time histories of p , α , V , W , $\dot{V}$, and γ . These and related time histories are shown in figure 24. The path performance program is a forward integration scheme which varies the integration step size according to an error criterion. Thus the time histories will all contain very small errors which cause the time histories to differ very slightly from the true values of the functions at any particular time. One cannot, therefore, expect to recover the exact values of the drag and power expressions by proceeding in this fashion. The values of the time histories shown in figure 24 at each 0.1 seconds were then submitted to the least squares routine. The coefficients developed by the program match the first six significant digits of the coefficients in the power and drag functions which were used to generate the time histories. The recovered coefficients, when inserted in the equation with the values of the parameters from PATH at each of almost 300 points, satisfy the equation to within 10^{-19} or better for the sum of all points.

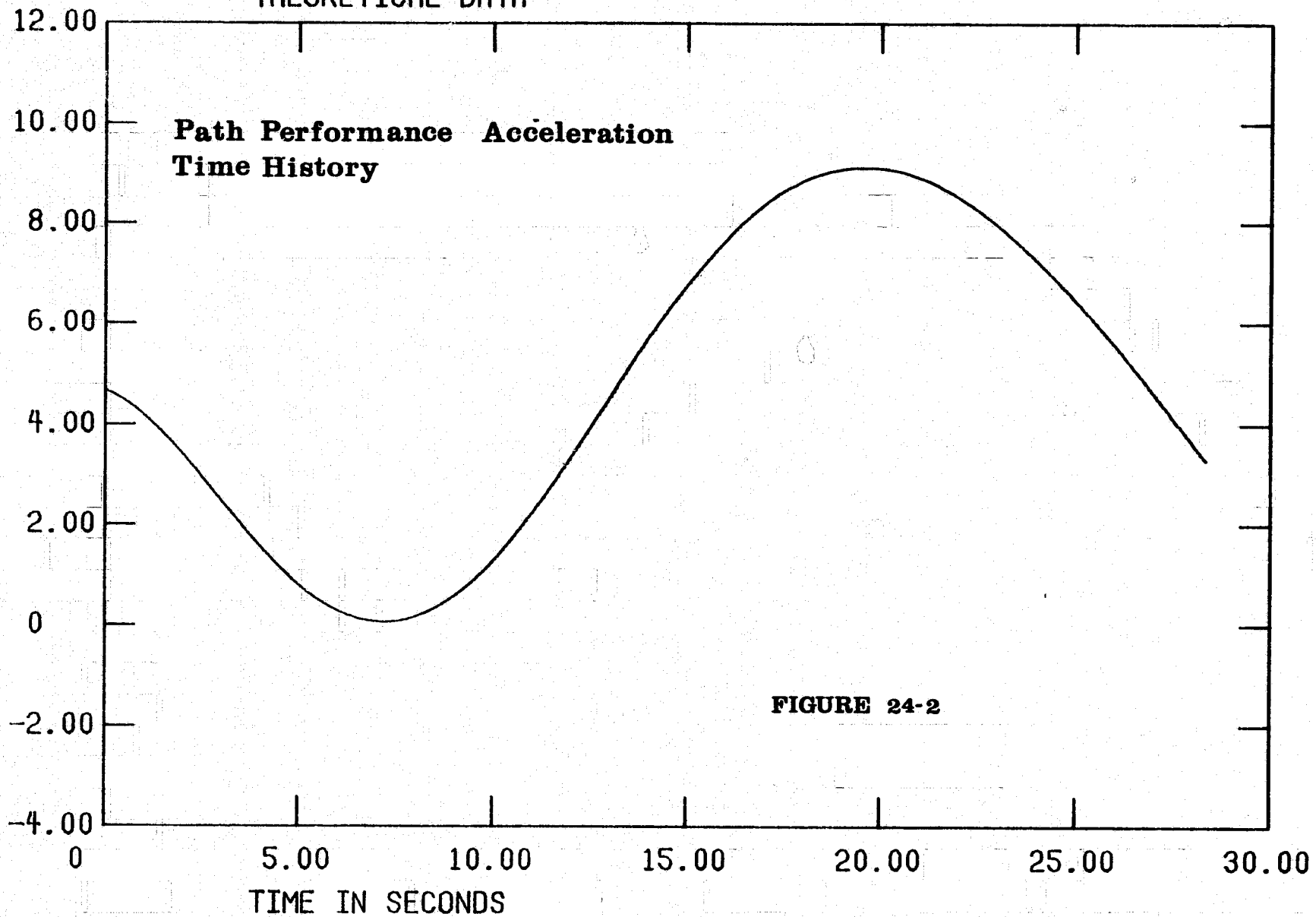


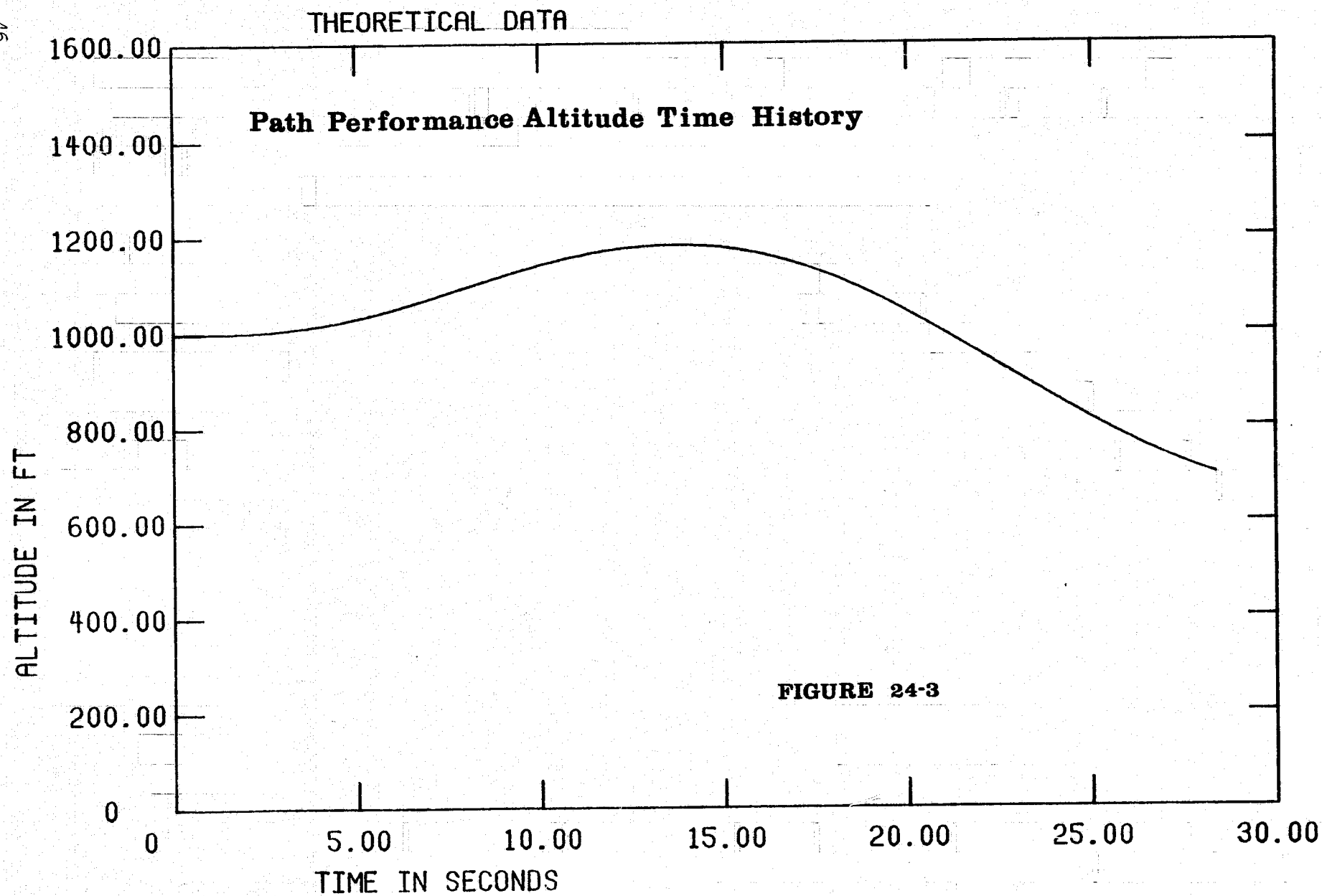


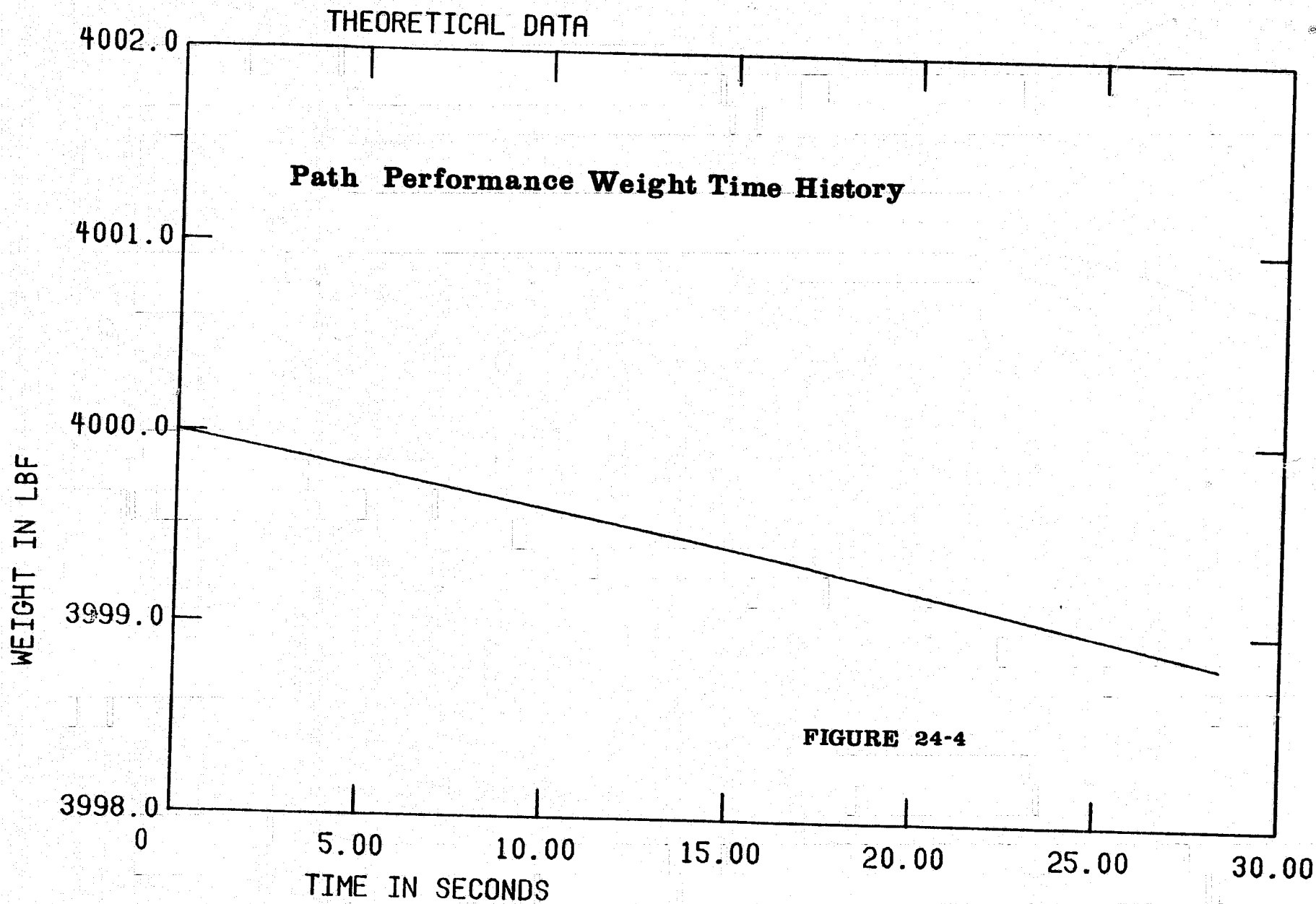


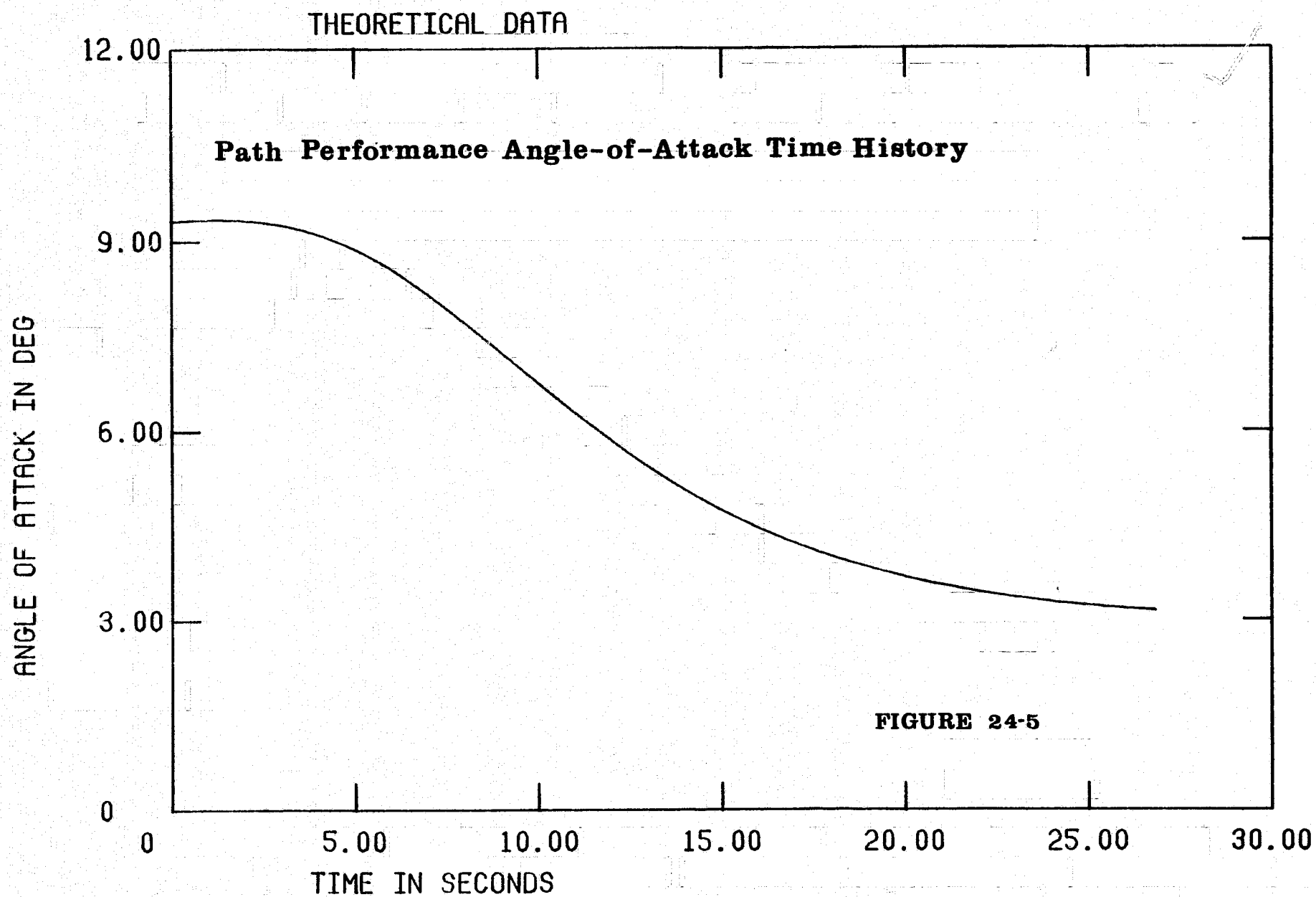
ACCELERATION IN FT/SEC**2

THEORETICAL DATA









ANGLE-OF-ATTACK RATE IN DEG/SEC

THEORETICAL DATA

Derivative of Path Performance
Angle-of-Attack Time History

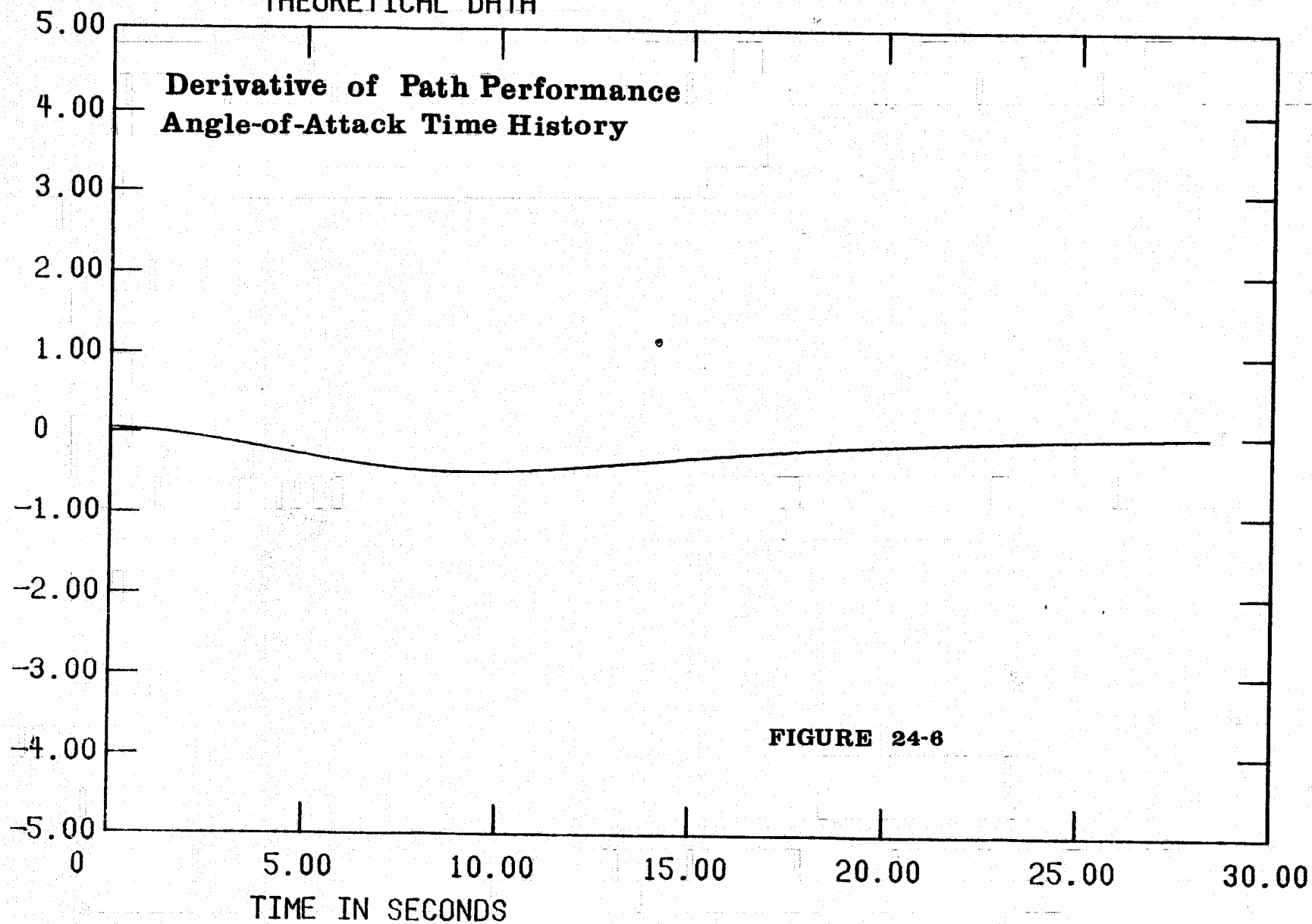
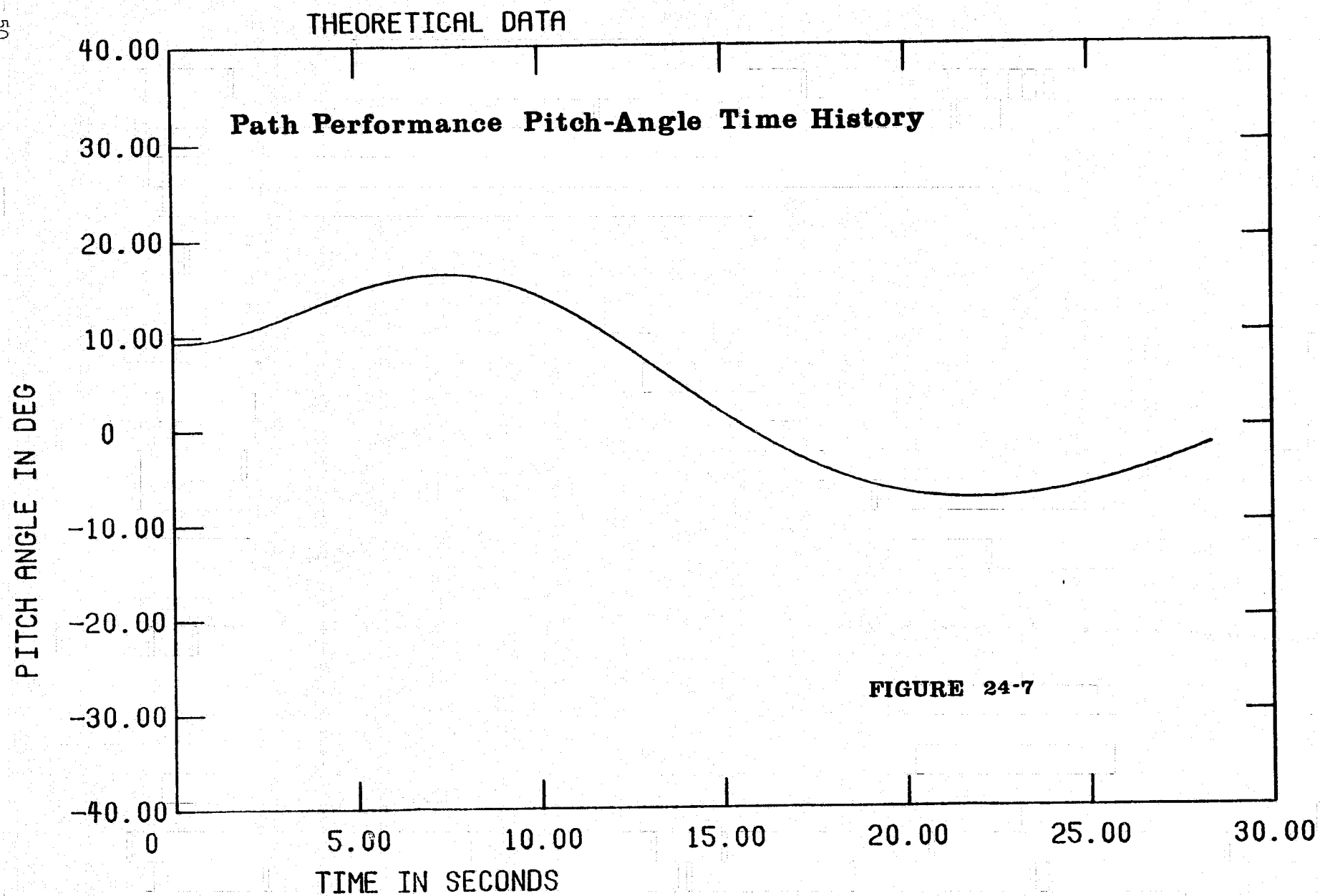


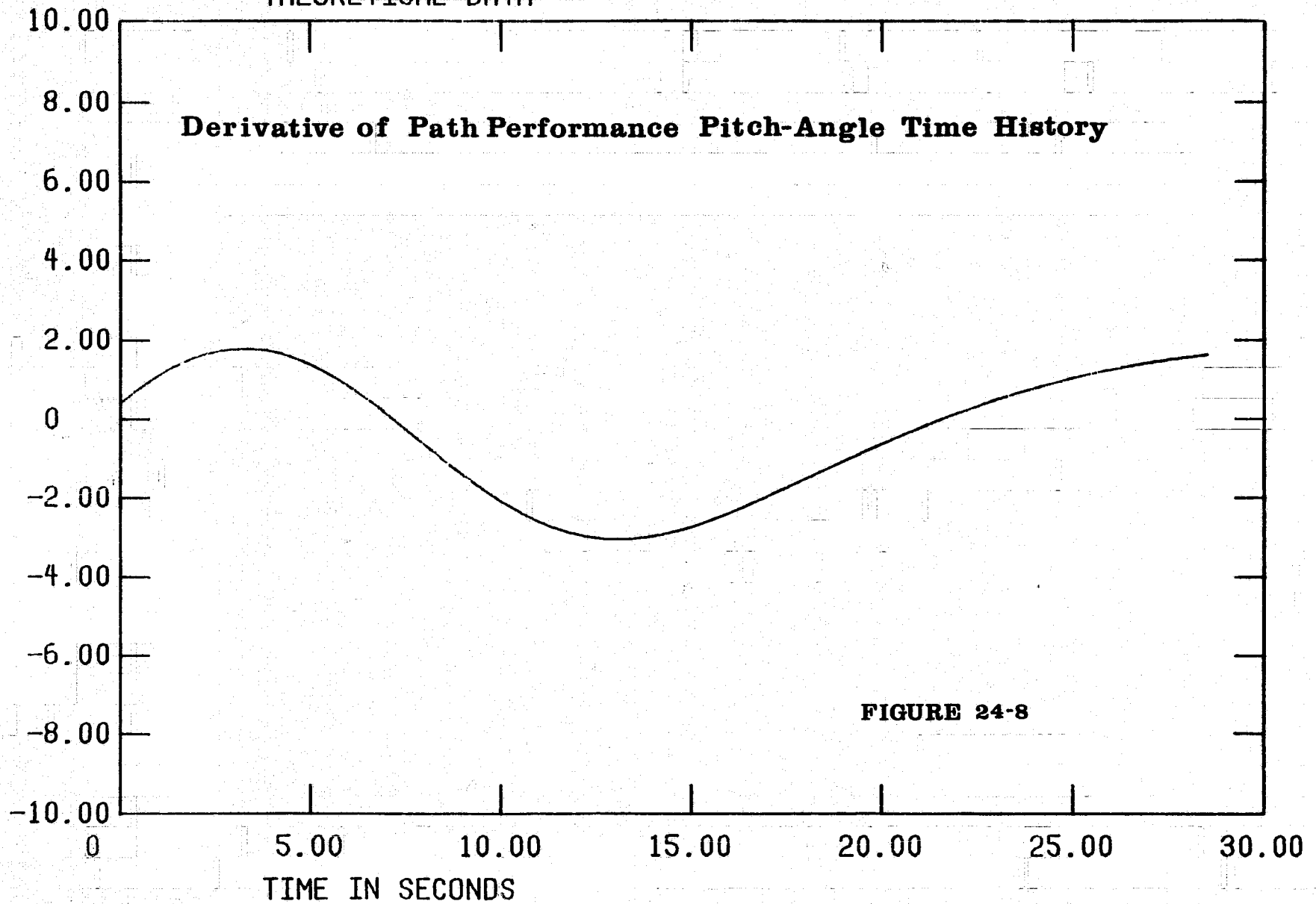
FIGURE 24-6



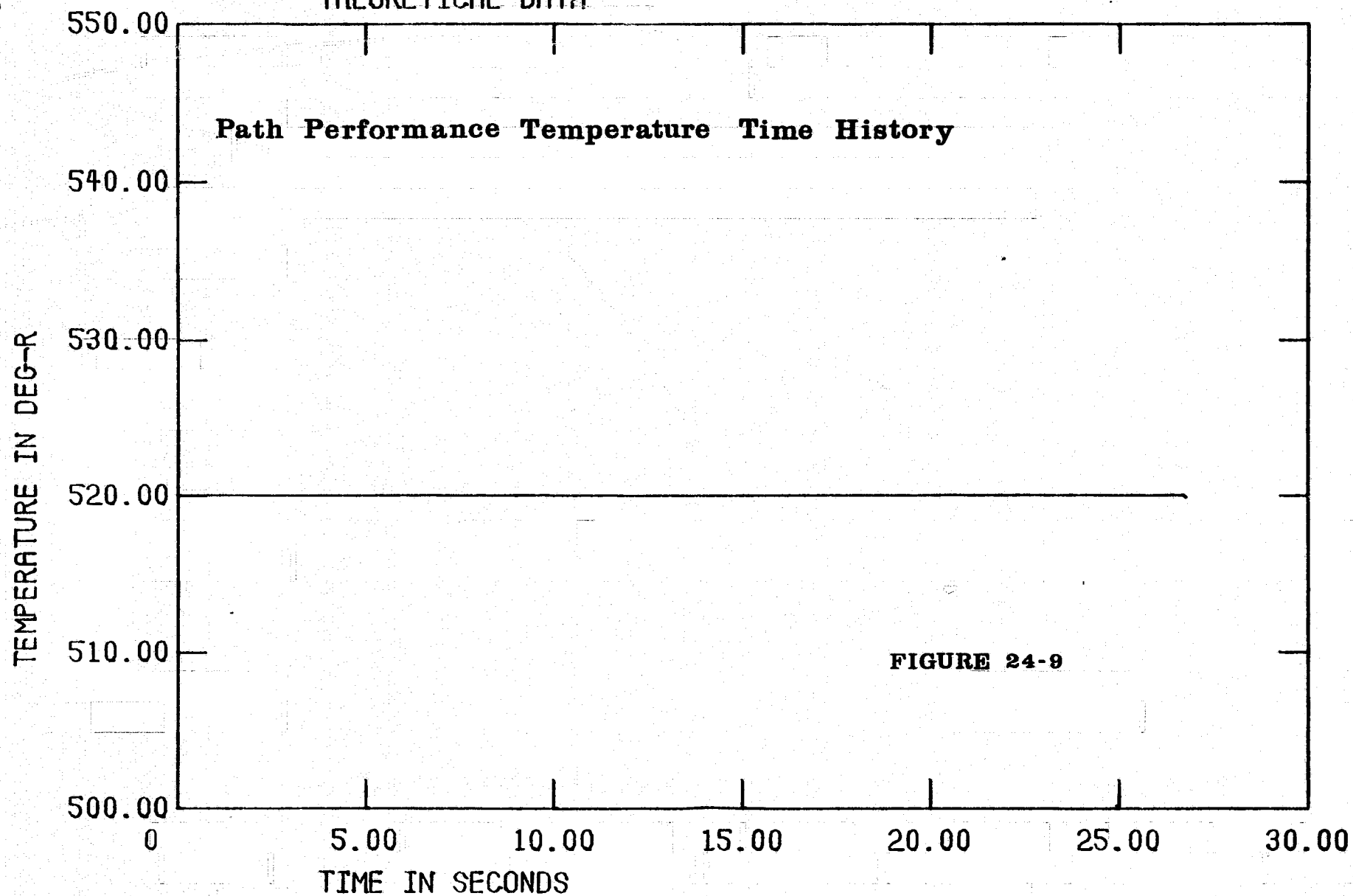
PITCH RATE IN DEG/SEC

THEORETICAL DATA

Derivative of Path Performance Pitch-Angle Time History



THEORETICAL DATA



Data Filtering

All records of the flight of actual aircraft will contain spurious contributions to the data signals arising from electrical noise, instrument errors, structural vibrations, and atmospheric turbulence. Since the model we have chosen to represent the aircraft does not include such effects, it is desirable to remove them, in so far as possible, before submitting the data to the coefficient extraction routine. Not doing so may cause the extraction routine to produce physically-meaningless results.

All filtering schemes proceed from the idea that continuous data signals are composites, each signal made up of sine waves of all frequencies. Each of these sine waves in the composite has a definite amplitude and phase relationship to the other sine waves making up the signal. By suppressing those frequencies which, on the basis of analysis or experience, cannot arise from the aircraft behavior of interest, one can remove most of the spurious contributions to the signal. Traditionally, filtering was done on continuous signals using frequency sensitive passive networks. In the present case, however, the flight data were received in digital form so that the filtering was accomplished mathematically using a computer*.

It is first necessary to represent the data set by its contributing sine waves. Let $f(t_i)$ $i=1,2,3,\dots,N$ represent the points in the data set, i.e., the value of a particular signal at discrete points of time. Let T = the total time over which we choose to make the analysis. Then over the interval $t = 0$ to $t = T$ we obtain a set of N values of the signal which, for reasons of simplicity, we choose to separate by a fixed time interval, $\Delta t = \frac{T}{N-1}$.

In order to reduce the numerical problems encountered with a Fourier series representation of a function, we will let

$$f(t_i) = f_a(t_i) + f_b(t_i) \quad t_1 \leq t_i \leq t_N \quad (11)$$

where

$$f_b(t_i) = f(t_1) + \frac{f(t_N) - f(t_1)}{T} t_i, \quad (12)$$

and

$$f_a(t_i) = f(t_i) - f_b(t_i). \quad (13)$$

* The data are, nevertheless, just digitized samples of continuous functions. For this reason we have chosen to employ mathematical techniques more appropriate to such functions than the more commonly used digital filtering techniques which seem more appropriate to the analysis of data which are inherently trains of impulses.

We will also add to these data the set

$$f(t_i) = f_c(t_i) + f_d(t_i) \quad t_N \leq t_i \leq t_{2N} \quad (14)$$

where

$$f_d(t_i) = f(t_N) - \frac{f(t_{2N}) - f(t_N)}{T} (t_i - T) \quad (15)$$

and

$$f_c(t_i) = f_a(2T - t_i) . \quad (16)$$

By this device, the set described by $f_b(t_i)$, $f_d(t_i)$ can always be represented analytically by

$$f_1(t_i) = f(t_1) + \frac{f(t_N) - f(t_1)}{2} - \frac{4}{\pi^2} \sum_{n=1,3,5,\dots}^{\infty} \frac{f(t_N) - f(t_1)}{N^2} \cos \frac{n\pi t_i}{T} . \quad (17)$$

The set represented by $f_a(t_i)$, $f_c(t_i)$ can be expressed by

$$f_2(t_i) = a_0 + \sum_{n=1,2,3,\dots}^{\infty} a_n \cos \frac{n\pi t_i}{T} , \quad (18)$$

where

$$a_0 = \frac{1}{2T} \int_0^T f_a(t_i) dt + \frac{1}{2T} \int_T^{2T} f_c(t_i) dt , \quad (19)$$

and

$$a_n = \frac{1}{T} \int_0^T f_a(t_i) \cos \frac{n\pi t}{T} dt + \frac{1}{T} \int_T^{2T} f_c(t_i) \cos \frac{n\pi t}{T} dt . \quad (20)$$

To carry out the integrations of (19) and (20), we will assume that $f_a(t)$ and $f_c(t)$ are really continuous functions over the interval of interest. The expression $f_a(t_i)$ represents just the value of this function at time t_i , $t_i - t_N$, rather than being an impulse at t_i with an amplitude equal to $f_a(t_i)$. Since the analytical form of $f_a(t)$ is unknown, we must choose some means to represent it. If an original analog record of the data is available, then the functional form used to represent $f_a(t)$ from t_i to t_{i+1} should be chosen such that it does not vary from the original record by more than some small amount anywhere between t_i and t_{i+1} . Two forms are commonly employed for this purpose: a straight line between two adjacent points and a parabola connecting three adjacent points. The unknown function is therefore represented piecewise by a series of elementary functions of the same form. This provides a function which is everywhere continuous but which has discontinuous slopes at the points where the pieces join. The error criterion chosen determines the maximum value of Δt . Usually, the parabolic form will permit a larger Δt for the same error. Note that by approximating the unknown function in this fashion one is in effect already applying some smoothing in the interval (t_i, t_{i+1}) since the regenerated function can never do more than match the approximate form.

The maximum frequency component that can be defined adequately by these representations is one for which $\omega = \frac{\pi}{2\Delta t}$ radians, that is, one described by five samples. Its linear segment representation has a maximum error of 29% and its parabolic segment representation a maximum error of 6%. For a sampling rate of 10/second we should certainly limit our consideration to frequencies of less than 2.5 Hz.

From the foregoing we conclude that, in the absence of the original analog record, we must assume that the sampling rate represented by the data set was at least four times the highest frequency of interest. We experience no difficulty in evaluating a_n for any n we choose, however; this is in sharp contrast to the usual treatments of sampled data where the highest value of n which may be used without obtaining spurious results is half the sampling rate. We come to this result because the integrations of (19) and (20) are carried out analytically although piecewise - in effect providing an infinite sampling rate. To employ the parabolic representation, we take

$$f_a(t_i) = A t_i^2 + B t_i + C, \quad (21)$$

$$f_a(t_{i+1}) = A t_{i+1}^2 + B t_{i+1} + C, \quad (22)$$

$$f_a(t_{i+2}) = A t_{i+2}^2 + B t_{i+2} + C. \quad (23)$$

Then

$$A = \frac{\left[\frac{f_a(t_i) - f_a(t_{i+1})}{t_i - t_{i+1}} - \frac{f_a(t_{i+1}) - f_a(t_{i+2})}{t_{i+1} - t_{i+2}} \right]}{\left[\frac{t_i^2 - t_{i+1}^2}{t_i - t_{i+1}} - \frac{t_{i+1}^2 - t_{i+2}^2}{t_{i+1} - t_{i+2}} \right]} \quad (24)$$

$$B = \frac{f_a(t_i) - f_a(t_{i+1})}{t_i - t_{i+1}} - \left[\frac{t_i^2 - t_{i+1}^2}{t_i - t_{i+1}} \right] A \quad (25)$$

$$C = f_a(t_i) - A t_i^2 - B t_i \quad (26)$$

and

$$a_0 = \frac{1}{2T} \sum_i \int_i^{i+2} [A t^2 + B t + C] dt = \frac{1}{2T} \sum_i \left[\frac{A t^3}{3} + \frac{B t^2}{2} + C t \right]_i^{i+2} \quad (27)$$

$$\begin{aligned} a_n &= \frac{1}{T} \sum_i \int_i^{i+2} [A t^2 + B t + C] \cos \frac{n\pi t}{T} dt \\ &= \frac{1}{T} \sum_i \left[A \left(2t \frac{T^2}{n^2 \pi^2} \cos \frac{n\pi t}{T} + \frac{T t^2}{n\pi} \sin \frac{n\pi t}{T} - \frac{2T^3}{n^3 \pi^3} \sin \frac{n\pi t}{T} \right) \right. \\ &\quad \left. + B \left(\frac{T^2}{n^2 \pi^2} \cos \frac{n\pi t}{T} + \frac{T t}{n\pi} \sin \frac{n\pi t}{T} \right) + \frac{CT}{n\pi} \sin \frac{n\pi t}{T} \right]_i^{i+2} \quad (28) \end{aligned}$$

When

$$\begin{vmatrix} f_a(t_i) & -t_i^2 & -t_i \\ f_a(t_{i+1}) & -t_{i+1}^2 & -t_{i+1} \\ f_a(t_{i+2}) & -t_{i+2}^2 & -t_{i+2} \end{vmatrix} < 10^{-5}, \quad (29)$$

the curvature of the data record is insufficient to require the use of a parabolic approximation and a linear approximation to $f(t)$ will provide the same result. In this case

$$f_a(t_i) = M t_i + D \quad (30)$$

$$f_a(t_{i+1}) = M t_{i+1} + D, \quad (31)$$

then

$$M = \frac{f_a(t_{i+1}) - f_a(t_i)}{t_{i+1} - t_i} \quad (32)$$

$$D = f_a(t_i) - M t_i \quad (33)$$

and

$$a_0 = \frac{1}{2T} \sum_i \left[\frac{M t^2}{2} + D t \right]_i^{i+1}$$

$$a_n = \frac{1}{T} \sum_i \left[M \left(\frac{T^2}{2\pi^2} \cos \frac{n\pi t}{T} + \frac{Tt}{n\pi} \sin \frac{n\pi t}{T} \right) + \frac{DT}{n\pi} \sin \frac{n\pi t}{T} \right]_i^{i+1}. \quad (34)$$

The complete function is then represented by

$$f(t_i) = f_1(t_i) + f_2(t_i) \quad t_1 \leq t_i \leq t_N. \quad (35)$$

An alternate form of (35) which involves fewer computations is

$$f(t_i) = f(t_1) + \frac{f(t_N) - f(t_1)}{T} t_i + a_0 + \sum_{n=1,2,3,\dots}^{\infty} a_n \cos \left(\frac{n\pi t_i}{T} \right)$$

$$t_1 \leq t_i \leq t_N. \quad (36)$$

Note that through the use of this procedure only deviations from a type of mean function value must be treated numerically. Fewer data points are therefore necessary to fit the function adequately and fewer harmonics must be calculated to regenerate the deviation portion of the function with acceptable accuracy. The reasons for adding the mirror image of the function from t_1 to t_N as a "tail" to the original function are that (a) it makes the function even, possibly reducing the number of coefficients which must be calculated, (b) it improves the coefficient definition because more data are now included in the integration, and (c) it offers the opportunity to calculate $f'(t_1)$ since the coefficients of its series representation will usually decrease in value with increasing numbers of harmonics. This may not be the case if the "tail" is not added.

For those cases better represented by an odd function, i.e., using only sine terms, one has merely to change the sign of $f(t_1)$ to make the function odd. If, however, one is willing to calculate both sine and cosine coefficients and perform the regeneration using both sine and cosine terms, then the "tail" can be dispensed with. Generally, one can obtain a better definition of the function for a given value of n by using both sine and cosine terms. Nevertheless, in some cases an equally good representation can be secured using a sine or a cosine series with less than $2n$ terms. This practice then results in a savings in computational time. The choice as to which procedure to follow is, until more experience with each is obtained, somewhat arbitrary.

The accuracy with which a parabolic fit represents the data over two time intervals depends of course on the size of Δt . The smallest value of Δt is fixed by the data sampling rate. If a smaller time interval is needed to obtain a satisfactory fit, it is necessary to interpolate points between the sampled values. It has been found that a fifth-order Newtonian interpolation formula generally provides a sufficiently accurate representation to generate the required intermediate points. This formula, for even time increments, is

$$\begin{aligned} \phi(t) = & y_0 + \frac{y_1 - y_0}{t_1 - t_0} (t - t_0) + \frac{y_2 - 2y_1 + y_0}{2(t_1 - t_0)^2} (t - t_0)(t - t_1) \\ & + \frac{y_3 - 3y_2 + 3y_1 - y_0}{6(t_1 - t_0)^3} (t - t_0)(t - t_1)(t - t_2) \\ & + \frac{y_4 - 4y_3 + 6y_2 - 4y_1 + y_0}{24(t_1 - t_0)^4} (t - t_0)(t - t_1)(t - t_2)(t - t_3) \\ & + \frac{y_5 - 5y_4 + 10y_3 - 10y_2 + 5y_1 - y_0}{120(t_1 - t_0)^5} (t - t_0)(t - t_1)(t - t_2)(t - t_3)(t - t_4). \end{aligned} \quad (37)$$

$y_0, \dots, y_5$ represent six values of the function one wishes to interpolate between. These y values correspond to times $t_0, \dots, t_5$. $\phi(t)$ can be found using this formula for any t between t_0 and t_5 and it may also be used to extrapolate $\phi(t)$ to a short time before t_0 and a short time after t_5 . Note that $\phi(t_0) \equiv y_0$, etc.

Now if the slope of the parabolic representation of the function at t_2 approaching from the left is different by more than ϵ from the slope of the parabolic representation of the function at t_2 approaching from the right, we calculate $\phi(t_{1/2})$ and $\phi(t_{3/2})$ and fit a parabola first through y_0 , $\phi(t_{1/2})$, and y_1 , and then through y_1 , $\phi(t_{3/2})$, and y_2 , etc. We can continue to divide the intervals in half until the slope difference at t_2 is less than ϵ . As a practical matter, however, more than three such divisions will result in excessively long data sets since we begin with as many as 450 points. Three divisions will result in a set of 3593 points. If ϵ is set to a desirable value, say 10^{-10} , one will usually find that with actual noisy data it will be necessary to interpolate as many points as permissible in order for ϵ to approach this value. With smooth data, multiple interpolations will not be necessary.

Since the procedure described above permits one to describe a signal time history in terms of its harmonic content, it is therefore possible to reduce the amplitudes of or eliminate certain constituent frequencies from the set before regenerating the signal - in essence filtering out the unwanted contributions to any desired degree - without any disruption of the phase relationships among the remaining contributions. This represents a level of filter performance far above that possible with passive elements in analog circuits. The choice of which frequencies to suppress and to what extent can generally be made on the following grounds:

1. If the aircraft itself is fairly rigid, frequencies above the principal stability modes should decline in amplitude at about 12 db per octave. This means that generally there should be little contribution to the vehicle's response to control surface deflections or changes in power level at frequencies above 1 to 2 Hz. If the data show significant harmonic content above these frequencies, it can usually be traced to engine-or-turbulence-induced structural vibrations or to electrical noise in the signal transducer, encoder, or recorder.
2. Spurious signals at lower frequencies can be separated from the data, provided their magnitudes are known a priori.

Following these guidelines we may now proceed to perform the attenuation of the higher frequency harmonics in a more rigorous fashion. It will be observed that attempts to regenerate functions having substantial high frequency content with a truncated series always lead to a function having considerable "ripple". For example, attempts to represent a square wave with a truncated series will always show a ripple or oscillation about the correct value at the leading edge and the trailing edge of the square wave. This phenomenon is not observed when square waves are passed through low-pass filter networks so that there is obviously some difference between the action of a low-pass filter and mere truncation of the generating series.

It has been demonstrated mathematically (Ref. 7) that to avoid these ripples the variation of a_n with n for (28), for example, must be continuous. Truncating the series representation of a function means that $a_n(n)$ is discontinuous at the last value of n (unless of course the value of a_n for this and all higher values of n is already zero). A desirable low-pass digital filter design is, therefore, one which suppresses the a_n 's sharply above a cut-off value for n , one which leaves the values of a_n for $n \leq n_c$ unattenuated, and one which does this in a continuous fashion. One means discussed in the literature (Ref. 7) is to multiply the a_n 's in the series representation by the function $H(n)$, where H is defined by

$$H(n) = \begin{cases} 1 & \text{for } n \leq n_c \\ \cos^2\left(\pi \frac{n - n_c}{n_c}\right) & \text{for } n_c < n < (3/2)n_c \\ 0 & \text{for } n \geq (3/2)n_c \end{cases} \quad (38)$$

$H(n)$, it will be noted, is everywhere continuous and has a continuous first derivative.

The cutoff harmonic can be obtained from the following expression:

$$n_c = \frac{5T}{\pi}$$

This is equivalent to saying that we will accept all the sine waves required to represent the function without attenuation up to a frequency of 10 radians/sec at which point we begin the "rolloff". We accept no energy in the signal beyond a frequency of 15 radians per second. Of course, n_c can be adjusted to match the response characteristics of the airplane under test. With flight records usually running 30-40 seconds n_c will be about 50 and the maximum value of n needed is about 75. With this constraint (36) becomes

$$\overline{f(t_i)} = f(t_i) + \frac{f(t_N) - f(t_1)}{T} t_i + a_0 + \sum_{n=1,2,3,\dots}^{n=75} a_n H(n) \cos\left(\frac{n\pi t_i}{T}\right) \quad (39)$$

$$t_1 \leq t_i \leq t_N$$

Usually, n_c can be adjusted downward if the flight maneuver is carried out with less than maximum aircraft response.

One of the more common types of noise in flight test data is caused by the failure of the digital encoding or conversion device to register the higher order bits. When this happens there is a sudden small jump in the indicated value. These jumps are generally in the same direction and do not occur in a completely random fashion. As a result, they cannot be treated as gaussian noise; further, they introduce a bias error into data filtered by our fourier routine. One means of dealing with this problem is to recognize that the aircraft states are dynamically capable of only finite rates of change. The change in altitude pressure with time, for example, is limited by the airspeed, altitude, and flight path angle. Any pressure change in excess of this value is obviously spurious. In place of the spurious value we can take the value determined from the vehicle dynamics through the following process:

Assume altitude temperature is equal to standard sea level value. Then

$$\dot{P} = 4.26P_o (1 - 6.86 \times 10^{-6}h)^{3.26} (-6.86 \times 10^{-6})\dot{h}$$

But $\dot{h} = V \sin \gamma = V \sin (\theta - \alpha).$

$$\text{So } \dot{P} = 4.26P_o \left(\frac{P}{P_o}\right)^{\frac{3.26}{4.26}} (-6.86 \times 10^{-6}) V \sin (\theta - \alpha).$$

θ and α come from instrument readings. To allow for errors in these values we take as the maximum value

$$\dot{P}_{\max} = -2.922 \times 10^{-5} P_o^{0.2347} P^{0.76526} V \sin [1.2(\theta - \alpha)]. \quad (40)$$

Thus the next pressure value cannot change more than $\dot{P}\Delta t$ from the previous value. If it does, we are justified in replacing the indication by $P_{\text{previous}} + \dot{P}\Delta t$.

Although this procedure will not eliminate the effects of "bit dropout," it will reduce materially the bias and low frequency errors which normally result therefrom. The Fourier procedure is then much more likely to yield the accurate data needed for effective parameter extraction.

Computation of Derivatives

The drag and power extraction scheme presented above requires that at least one parameter ($\dot{\alpha}$) which is not commonly measured be supplied as an input time history. We are therefore forced to differentiate $\alpha(t)$ in some fashion in order to obtain $\dot{\alpha}(t)$. Because of the fourier series representation used in (39), we may easily compute the derivative of this function analytically:

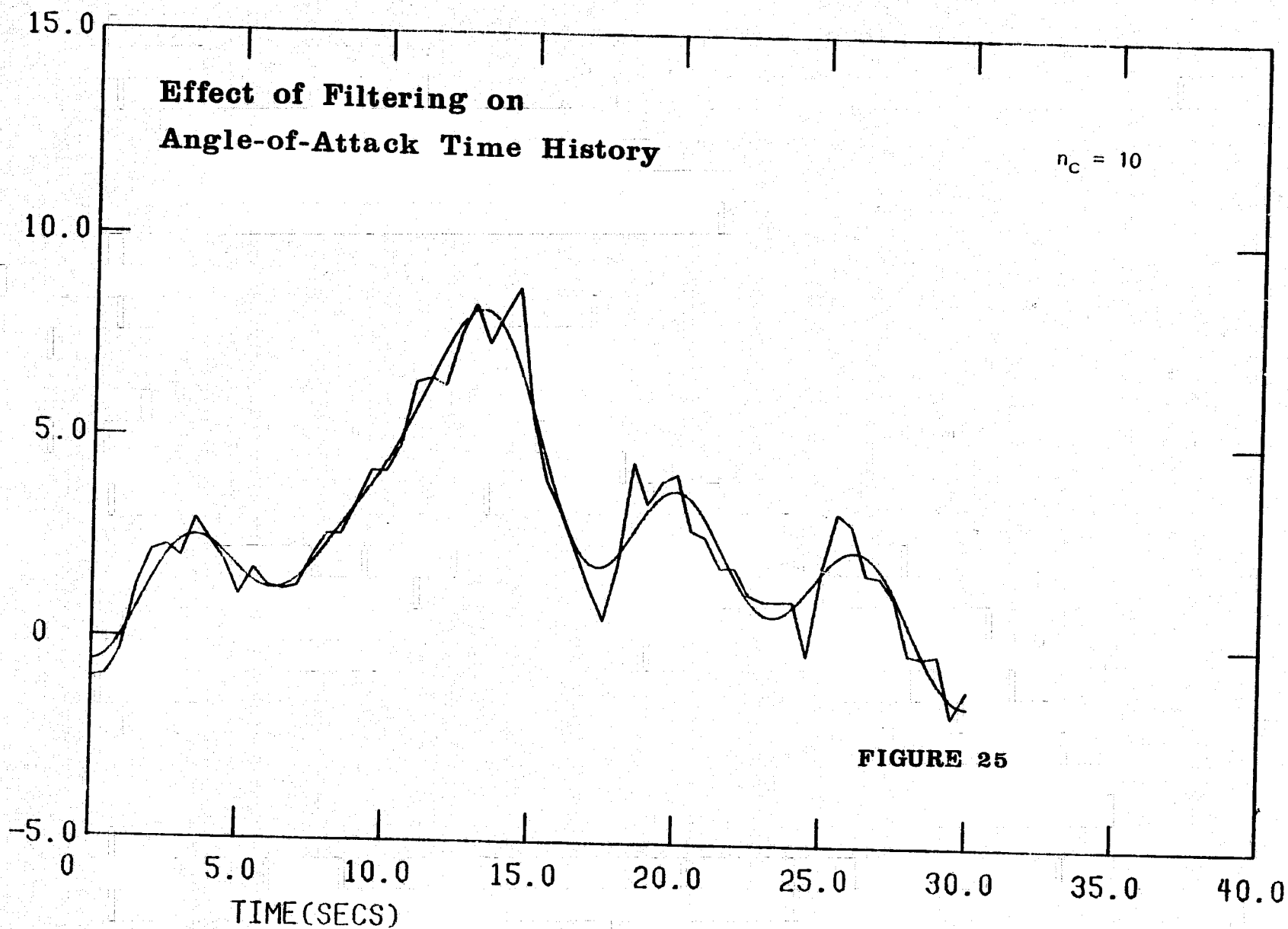
$$f'(t_i) = \frac{f(t_N) - f(t_i)}{T} - \frac{\pi}{T} \sum_{n=1,2,3,\dots}^{n=75} a_n n H(n) \sin\left(\frac{n\pi t_i}{T}\right)$$

$$t_1 \leq t_i \leq t_N \quad (41)$$

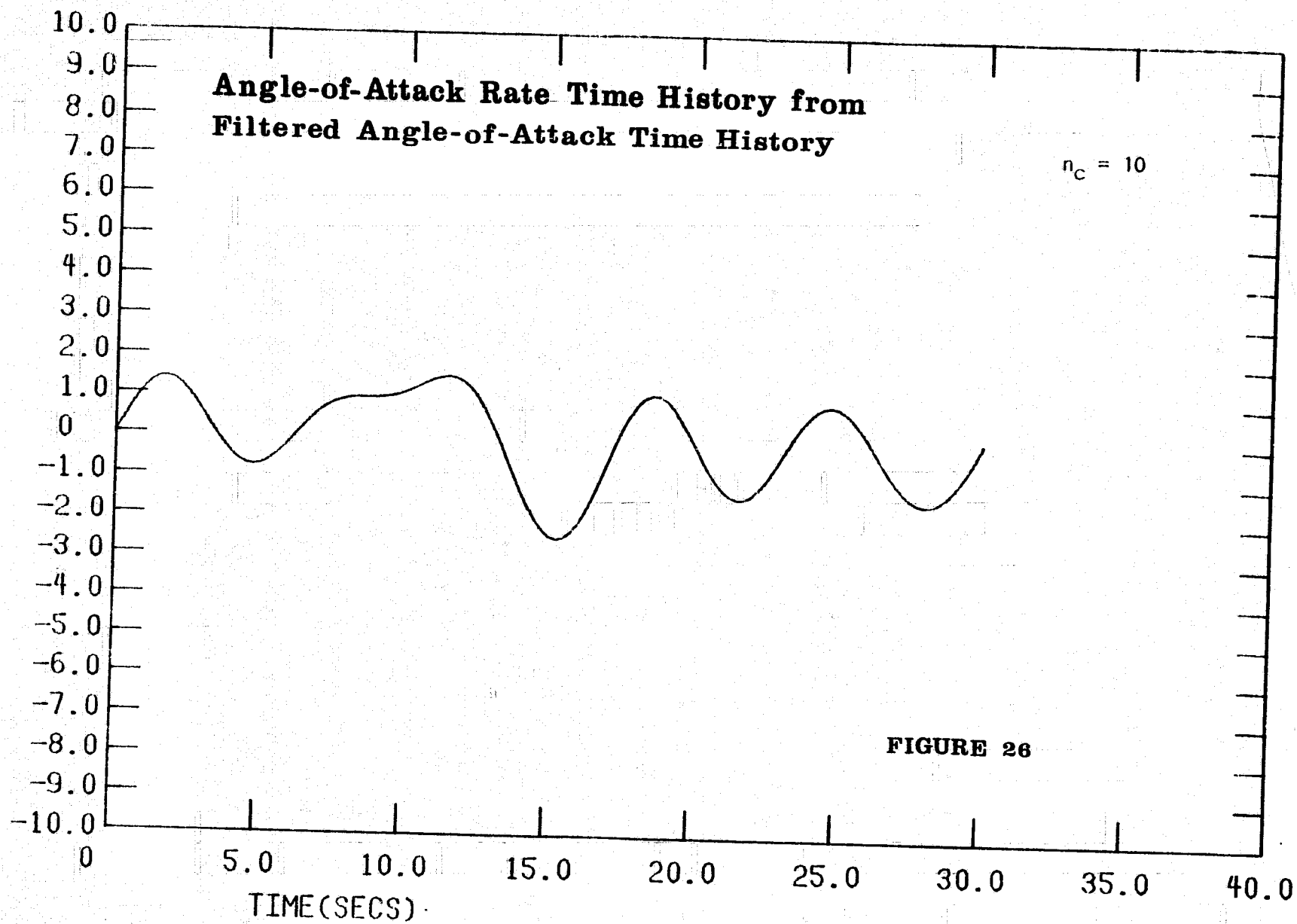
This process may be applied to any data set for which a derivative is needed and for which it is otherwise unavailable.

Some examples of the application of this procedure are shown in figures 25-26. In figure 25 an angle-of-attack time history as read from a "quick look" record is reproduced. Note the high degree of irregularity. This data was read every 1/4 second. When submitted to the fourier analysis routine with $n_c = 10$, the smooth curve shown in figure 25 is obtained. The angle of attack rate is shown in figure 26. The data are quite smooth and appear to be a reliable smoothing of the original. The maneuver for which these data were obtained was a pushover-pullup. The "humps" in the data at roughly 6-second intervals are believed to be a consequence of the excitation of the aircraft's longitudinal short period mode by the maneuver. Calculations indicate the short period mode can be expected to have this period for the test configuration.

ANGLE OF ATTACK(RAD) X 100



ANGLE-OF-ATTACK RATE(RAD/SEC) X 100



Comparison of Computed Acceleration Along the Flight Path with that Determined from Accelerometer Indications

The scheme to extract drag and thrust simultaneously from flight data has been found to require accurate indications of the acceleration along the vehicle's flight path in order to yield acceptable results. Usually it is not possible to locate the measuring instrument (accelerometer) precisely at the vehicle's center of gravity, so that it is necessary to correct the instrument's indication for this fact and then to relate the acceleration along the vehicle's x-body axis to the longitudinal acceleration along the flight path.

Accelerometers are generally masses constrained to move along the axis of a tube and centered by springs at either end. The position of the mass relative to the center of a tube is proportional to the acceleration and is measured electrically. When the aircraft accelerates along the flight path, the mass moves aft of the center of the tube. Now, the same effect is produced when the accelerometer is tilted nose up even though there is no acceleration. Thus, it is necessary to subtract a term $g \sin \theta$ from the accelerometer indication to account for this effect.

If the accelerometer is located x feet in front of the c.g., its mass is caused to move forward as a result of the angular rotation of the aircraft by an amount $x \dot{q}^2$. One must therefore add this term to the accelerometer indication. Similarly, if the accelerometer axis is located z feet below the x-body axis then the accelerometer mass is displaced rearward by an amount proportional to $z \dot{q}$.

The linear acceleration along the x-body axis in terms of the accelerometer indication location, and angular velocity is therefore

$$a_x = a_{x_{ind}} - g \sin \theta + x \dot{q}^2 - z \dot{q} . \quad (42)$$

We desire the acceleration not along the x-body axis but rather along the flight path. We know that for motion in the x-z terrestrial plane

$$a_x = \dot{u} + q w \quad (43)$$

and

$$u = V \cos \alpha \quad (44)$$

$$w = + V \sin \alpha , \quad (45)$$

where V is the velocity of the aircraft along its flight path and u and w are components of this velocity along the principal axes of the aircraft. In terms of (44) and (45)

$$\begin{aligned} a_x &= \dot{V} \cos \alpha - V \dot{\alpha} \sin \alpha + q V \sin \alpha \\ &= \dot{V} \cos \alpha - V(\dot{\alpha} - q) \sin \alpha . \end{aligned} \quad (46)$$

Equating (42) and (46) yields

$$a_{x_{ind}} - g \sin \theta + x q^2 - z \dot{q} = \dot{V} \cos \alpha - V(\dot{\alpha} - q) \sin \alpha . \quad (47)$$

Then solving for $\dot{V}$, one has

$$\dot{V} = \frac{a_{x_{ind}} - g \sin \theta + x q^2 - z \dot{q}}{\cos \alpha} + V(\dot{\alpha} - q) \tan \alpha . \quad (48)$$

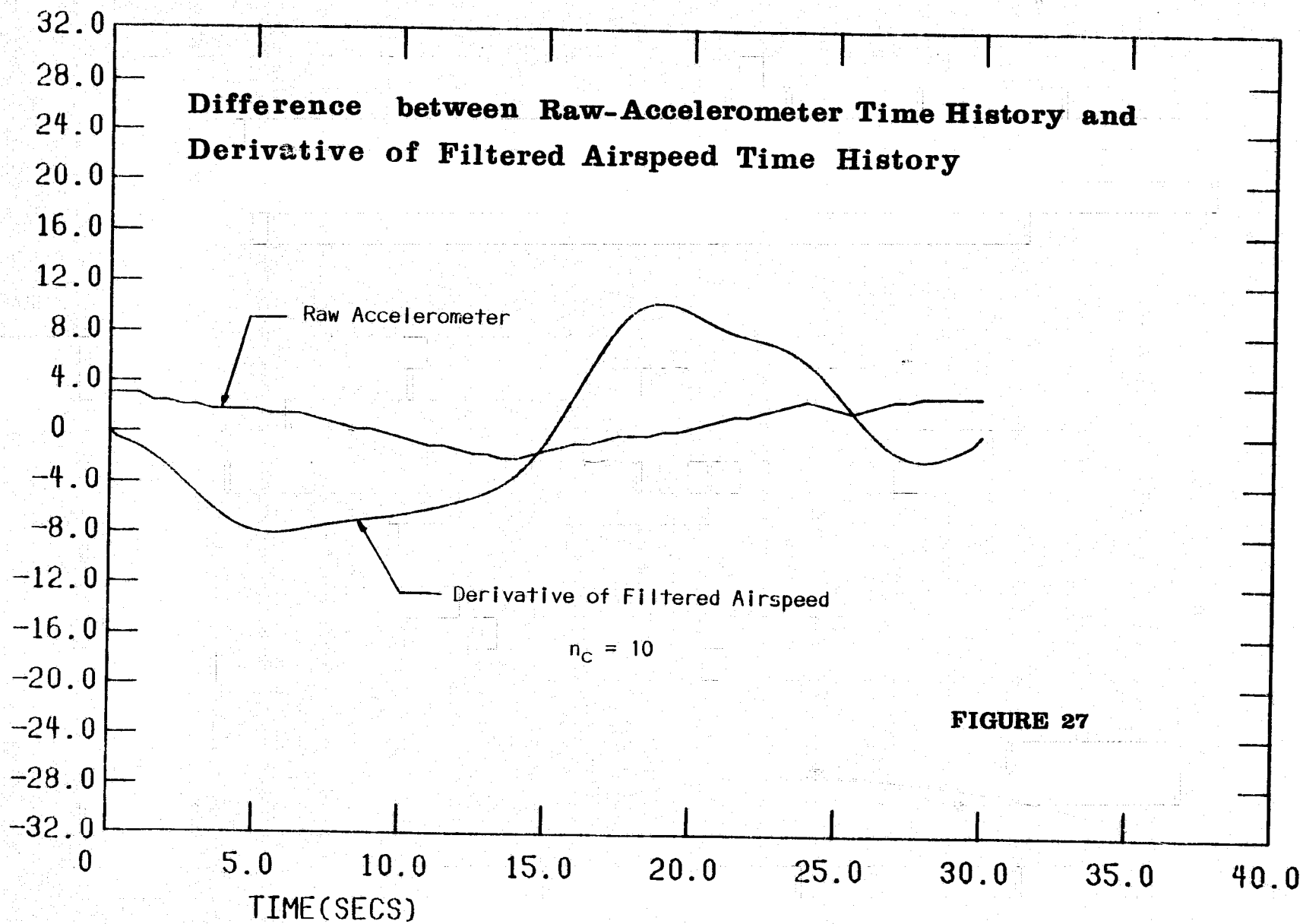
The value given by (48) should now be the same as that obtained by differentiating the variation of true airspeed with time. The differences between a raw accelerometer indication and the derivative of the true airspeed with time for an actual flight record are shown in figure 27.

Of course one does not measure true airspeed directly. An airspeed sensor measures only a pressure difference. This difference is affected by the sensitivity of the pitot and static pressure sources to angle of attack, the disturbance to the free stream pressure at the static pressure source resulting from the presence of the aircraft, the compressibility of the air, and the difference in pneumatic lags of the pitot and static pressure lines. The pneumatic lag also introduces a time delay in the airspeed indication. Since the airspeed indicator is calibrated for standard sea level conditions, any variation in atmospheric temperature will affect the airspeed at a given pressure difference.

The theory of the pitot-static tube assumes that the air is brought to rest at the pitot pressure source adiabatically and that the static source senses the pressure in the free stream (i.e., away from the airplane). With these assumptions, it is easy to show that the true flow velocity is related to the measured pressures by

$$V = \sqrt{\frac{2\gamma RT}{(\gamma-1)} \left\{ \left[\frac{q_c}{P} + 1 \right]^{\frac{\gamma-1}{\gamma}} - 1 \right\}} , \quad (49)$$

ACCELERATION(FT/SEC**2)



where P is the altitude pressure, q_c is the difference between the pitot and static pressures, T is the local free stream absolute temperature, R is the gas constant for air and γ is the ratio of specific heats of air (1.4 for diatomic gases at normal temperatures). The P indication for use in this equation comes from the static pressure source of the pitot-static tube and the T indication from a temperature measuring device. Since one cannot measure the local free stream temperature readily while the vehicle is in motion, temperature sensing devices most often measure the stagnation temperature, T_s , which is related to the free stream temperature by

$$T = \frac{T_s}{\left[\frac{q_c}{P} + 1 \right]^{\frac{\gamma-1}{\gamma}}} \quad (50)$$

In terms of the stagnation temperature, the true airspeed is given by

$$V = \sqrt{\frac{2\gamma RT_s}{(\gamma-1)}} \left\{ 1 - \left[\frac{q_c}{P} + 1 \right]^{\frac{1-\gamma}{\gamma}} \right\} \quad (51)$$

Unfortunately, it is usually not possible to locate the static pressure source on an airplane in a region where the static pressure is the same as the free stream value. Hence, the static pressure indication is in error by an amount ΔP . This "position error" so called is felt in both the altitude and q_c indications. If we call P' the measured altitude pressure and q_c' the measured pressure difference then because

$$q_c' + P' = q_c + P = P_s, \quad (52)$$

and

$$P = P' - \Delta P,$$

one can write

$$\frac{q_c + P}{P} = \frac{q_c' + P'}{P' - \Delta P} = \frac{1 + \frac{P'}{q_c'}}{\frac{P'}{q_c'} - \frac{\Delta P}{q_c'}} \quad (53)$$

in terms of the measured values and the static source position error which is usually determined by flight calibration and is expressed in terms of $\frac{\Delta P}{q_c'}$ as a function of q_c' or indicated airspeed. With this effect included the expression for true airspeed becomes

$$V = \sqrt{\frac{2\gamma RT_s}{(\gamma-1)}} \left\{ 1 - \left[\frac{1 + \frac{P'}{q_c'}}{\frac{P'}{q_c'} - \frac{\Delta P}{q_c'}} \right]^{\frac{1-\gamma}{\gamma}} \right\}. \quad (54)$$

Fortunately, modern pitot-static tubes are relatively insensitive to changes in angle of attack so that the q_c' and P' indications do not depend on the tube's inclination to the airstream over the useful range of aircraft angles of attack. The position error, however, does depend upon angle of attack and aircraft configuration. At steady speed and constant weight the position error can be related, as it commonly is, to q_c' or indicated airspeed, but during maneuvers it may be necessary to employ a correlation with angle of attack instead. Whether this is necessary must be determined by calibration. If it is, one must then determine true airspeed and true angle of attack iteratively.

The compressibility correction mentioned earlier is already included in (54). Conventional airspeed indicators, it may be noted, are simply mechanizations of the equation

$$V_i = \sqrt{\frac{2q_c}{\rho_o}}, \quad (55)$$

where ρ_o is the mass density of the air at standard sea level conditions. If the airspeed indicator calibration includes compressibility effects, equation (49) with standard sea level pressure and temperature is mechanized.

If pneumatic signals transmitted through the pitot and static lines travel at different speeds* then the q_c' and P' values will be in error. In most aircraft with pressure sensors located in the cabin area the pneumatic lines are long enough that their response characteristics can be considered analogous to those of resistance-capacitance electrical circuits. The "resistance" is proportional to length/(diameter)⁴ while the "capacitance" is proportional to system volume. Since the static system includes more instruments than the pitot system and, frequently, larger volumes, the static line diameter must be larger than the pitot or a restriction must be placed in the pitot line in order to keep the response times equal. Even if the line responses are equal, $V(t)$ will lag the correct value by a time which is proportional to h and V .

A procedure by which equation (54) may be modified to account for lag is the following: We begin by recalling that the equation describing the axial motion of a compressible fluid in a tube is

* Speed is used here in the sense of the time or rate at which the transducer indication responds to changes in the aircraft's pressure field. It does not refer to the speed at which acoustic signals are propagated through pneumatic lines.

$$\rho \frac{\partial u}{\partial t} + \rho u \frac{\partial u}{\partial x} = - \frac{\partial P}{\partial x} + \frac{\partial}{\partial x} \left(\mu \frac{\partial u}{\partial x} \right) + \frac{1}{r} \frac{\partial}{\partial r} \left(\mu r \frac{\partial u}{\partial r} \right) . \quad (56)$$

Here u is the fluid velocity, μ the coefficient of viscosity, x the axial distance and r the radial distance. In conjunction with the foregoing, one may also write the equation describing the conservation of matter

$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial u}{\partial x} + u \frac{\partial \rho}{\partial x} = 0 . \quad (57)$$

Examination of the first equation reveals it to be a mixed parabolic and elliptic-type non-linear partial differential equation. As such there are at least two characteristic propagational velocities by which the fluid adjusts itself to changing boundary conditions. One is infinite. The other, as we may discover by temporarily ignoring the effects of fluid viscosity, is approximately what we understand as the speed of sound. This characteristic information transfer mechanism is always present. The importance of the infinite propagational velocity in determining the gross behavior of the fluid motion depends, of course, on the relative importance of the viscous stress terms in the equation.

The reason for relating the foregoing bit of mathematical wisdom is that we cannot solve the equation for typical boundary conditions without prodigious effort and must therefore resort to some gross approximations. Under these conditions it is desirable to extract as much information as possible about the character of the solution of the general equation in order to ascertain the reasonableness of the approximate solutions.

Suppose we model the aircraft static or total pressure systems as a very long straight tube terminated on the instrument end by a finite volume. Let us assume that the flow through this tube is always isothermal, i.e., it is slow enough that heat can be transferred to and from the tube walls as a fluid particle traverses the length of the tube. The pressure in the volume at the instrument end of the tube is then directly proportional to the mass flux through the tube to the volume. Depending upon the ratio of the pressures across the tube and the tube length,

$$\dot{m} \sim P_{\infty} \text{ for short tubes and } P_{\infty}/P_{\text{instrument}} \geq 2 \quad (58)$$

$$\dot{m} \sim \sqrt{P_{\infty} - P_{\text{instrument}}} \text{ for short-to-intermediate length tubes and } P_{\infty}/P_{\text{instrument}} < 2 \quad (59)$$

$$\dot{m} \sim (P_{\infty} - P_{\text{instrument}}) \text{ for very long tubes.} \quad (60)$$

These results can all be obtained from the foregoing equations and the equation of state, $P = \rho RT$, after some manipulation. The first two results are obtained assuming $\mu = 0$. The second assumes in addition that the velocity is slow enough that $\rho \approx \text{constant}$. The third result is obtained by assuming that the viscous stresses are sufficiently important that the terms on the left side of the equation are small by comparison. This of course is only true in very long tubes ($L/D > 100$). The instantaneous rate of change of pressure in the instrument volume is then

$$\dot{P}_{\text{instrument}} = (P_{\infty} - P_{\text{instrument}}) \frac{1}{\tau} \quad (61)$$

where τ is a proportionality constant having the units of time. Note that in general both P_{∞} and $P_{\text{instrument}}$ may change with time. From this expression it is easy to show that in terms of the instrument reading

$$P_{\infty} = P_{\text{instrument}} + \tau \dot{P}_{\text{instrument}} \quad (62)$$

τ is determined empirically by allowing P_{∞} to change instantaneously from one value to another. For this case we may easily write

$$\frac{dP_{\text{instrument}}}{(P_{\infty} - P_{\text{instrument}})} = \frac{dt}{\tau}, \quad (63)$$

whose solution is

$$-\ln(P_{\infty} - P_{\text{instrument}}) = t/\tau + c. \quad (64)$$

the boundary conditions are

$$\text{when } t = 0, P_{\text{instrument}} = P_{\text{instrument}_0}$$

$$\text{when } t \rightarrow \infty, P_{\text{instrument}} \rightarrow P_{\infty},$$

thus

$$P_{\text{instrument}} = P_{\text{instrument}_0} e^{-t/\tau} + P_{\infty}(1 - e^{-t/\tau}). \quad (65)$$

By measuring P_{∞} , $P_{\text{instrument}}$, $P_{\text{instrument}_0}$, and time, τ is readily determined.

The above analysis assumes that a change in P_∞ is instantly communicated to the gas in the instrument volume. Because acoustic waves are the dominant communication mechanism when the fluid is essentially at rest, changes in P_∞ are felt in the instrument volume some λ seconds later with the arrival of the acoustic wave generated by the change in P_∞ . λ can also be measured experimentally. With this effect included the air pressures at the pitot-static opening in terms of the instrument readings are represented by

$$P_\infty(t) = P_{\text{instrument}}(t + \lambda) + \tau \dot{P}_{\text{instrument}}(t + \lambda) \quad (66)$$

Note that P_∞ at t seconds is given in terms of the instrument reading and its instantaneous rate of change at $(t + \lambda)$ seconds.

If now q_c'' is the lag-free value of the impact pressure,

P'' is the lag-free value of the static pressure,

P_s'' is the lag-free value of the stagnation pressure,

τ_1, λ_1 are, respectively, the measured time constants of the stagnation and static systems,

then

$$q_c''(t) = P_s'' - P_s'(t + \lambda_1) + \tau_1 \dot{P}_s'(t + \lambda_1) - P'(t + \lambda_2) - \tau_2 \dot{P}'(t + \lambda_2). \quad (67)$$

$$P''(t) = P'(t + \lambda_2) + \tau_2 \dot{P}'(t + \lambda_2) \quad (68)$$

These values of q_c'' and P'' should be substituted for q_c' and P' in equation (54) to obtain a lag-free value of $V(t)$.

Typical values for the ATLIT flight test system are

$$\tau_1 = 0.040 \text{ seconds}$$

$$\lambda_1 = 0.025 \text{ seconds}$$

$$\tau_2 = 0.150 \text{ seconds}$$

$$\lambda_2 = 0.033 \text{ seconds}$$

$$\dot{V}_{\text{max}} = \pm 8 \text{ ft/sec}^2 @ 120 \text{ ft/sec}$$

$$P_s = 2133 \text{ psf @ S.L. and 120 ft/sec}$$

$$P = 2116 \text{ psf @ S.L.}$$

$$\dot{h} = 35 \text{ ft/sec}$$

With these numbers

$$q_c'' = 2133 - .040 (2.358976) - 2116 + 0.15 (2.1635)$$

$$= 2133 - .094359 - 2116 - .324525 = 17.23 \text{ psf while } q_c' = 17 \text{ psf.}$$

the error in q_c' is therefore 0.23 psf or 1.35% while the error in P is 0.0153%. Thus it appears that if one seeks to minimize data errors a lag correction in the airspeed is required.

When all necessary corrections have been made to the pressure indications, one can create $V(t)$ by use of equation (54). These data can then be submitted to the Fourier analysis procedure to smooth $V(t)$ and to find $\dot{V}(t)$. As noted above, this value should agree closely with that determined from equation (48) if the totality of the data are self-consistent. Observe, however, that the latter computation requires that one input five separate measurements plus the derivatives of two, while the former only requires three measurements plus some calibration data. Thus, it is to be expected that $\dot{V}$ computed from pressure and temperature data will generally be the more reliable value.

Correction of Angle of Attack Indications

In addition to factors such as transducer linearity, gain, and bias, the angle of attack indication is affected by the presence of the carrying aircraft and by its rotation. It will be recognized that for an angle of attack vane located x feet ahead of the c.g. an incremental angle,

$$\Delta\alpha = \tan^{-1} \left(\frac{xq}{V} \right), \quad (69)$$

must be subtracted from the transducer indication to account for vehicle rotation. In addition, there is usually a relationship of the type

$$\alpha_{\text{true}} = C_1 \alpha_{\text{indicated}} + C_2, \quad (70)$$

between the angle of attack measured in the neighborhood of the aircraft and the true (i.e., at infinity) angle of attack. The values of C_1 and C_2 depend

upon the location of the vane relative to the aircraft and the geometry of the aircraft. They are therefore almost always found from flight calibration tests since the flow field about complex shapes such as complete aircraft is almost impossible to determine analytically. Assuming that these coefficients are known, one may write the expression for true angle of attack as

$$\alpha_{\text{true}} = C_1 \left(\alpha_{\text{indicated}} - \tan^{-1} \left(\frac{xq}{V} \right) \right) + C_2 \quad (71)$$

Note that the value of V used in (71) should be that obtained from (54). One may then smooth $\alpha_{\text{true}}(t)$ and compute the derivative, $\dot{\alpha}(t)$, by the Fourier analysis procedure.

Determination of $\rho(t)$

Equation (6) requires as an input $\rho(t)$. This is readily determined from

$$\rho = \frac{(P' - \Delta P)}{RT_s} \left[\frac{1 + \frac{P'}{q_c'}}{\frac{P'}{q_c} - \frac{\Delta P}{q_c'}} \right]^{\frac{\gamma-1}{\gamma}} \quad (72)$$

If the altitude pressure transducer is calibrated in feet, then the appropriate pressure versus altitude function must be employed to convert the indications to pressure values.

The density values may also require smoothing before the data can be inserted into (10).

Conditioning of Other Data Inputs to the Drag and Power Extraction Method

In addition to the velocity, angle of attack, and atmospheric density, equations (10) require $W(t)$ and $\theta(t)$ as inputs. Fortunately, for the maneuvers of interest W changes so little that it can be taken to be constant or at most varying linearly during a maneuver. Usually θ requires no corrections beyond the instrument calibration if the erection mechanism is disabled during the maneuver. Since the indication is sampled and since there may be electrical, airframe, and turbulence-induced noise, smoothing may still be necessary. This is also true for the pitch rate indication, q , which is used in the C_L computation and the α and a_x corrections.

More General Power and Drag Models

In a normally-aspirated engine the manifold pressure and hence the power output for a given throttle setting will usually vary directly with the atmospheric density. Thus, if the maneuver to provide data for the power and drag extraction process involves a change in altitude, there will be a change in power at a given speed corresponding to the change in ρ even if the pilot does not change his throttle setting or RPM. To account for this we need to multiply the expression for power by (Ref. 8)

$$\frac{\rho_{\text{ref}}/\rho_0 - 0.165}{\rho/\rho_0 - 0.165}, \quad (73)$$

where ρ_0 is the standard sea-level value of ρ and ρ_{ref} is the value of ρ at the beginning of the maneuver.

The parabolic form of the speed-power relation used in equation (6) is obviously satisfactory over small differences in speed and should represent the thrust horsepower of fixed-pitch propellers reasonably well over most of the aircraft's speed envelope. The higher efficiency levels provided by a constant speed propeller at the lower speeds, however, makes it necessary to employ a higher order polynomial or other function having additional degrees of freedom (coefficients) to represent the thrust horsepower adequately over a wide speed range. Variants of one such function were chosen for further study:

$$P = P_1 + \frac{P_2}{V^{1/2}} + P_3 V + P_4 V^2 + P_5 V^3 \quad (74)$$

These are shown in Table IIIa.

One will note also that the drag expression is really satisfactory only if α is measured from zero lift. Since the angle reference for flight data is often quite arbitrary, it is difficult to establish the angle for zero lift *a priori*. To accommodate an arbitrary reference, i.e., to replace α by $\alpha - \alpha_0$ in equation (5), requires that the representation for C_D contain all powers of α through 6. We choose, however, to investigate only three variants of the following form which are shown in Table IIIa:

$$C_D = C_{D_0} + C_{D_1} \alpha + C_{D_2} \alpha^2 + C_{D_3} \alpha^3 + C_{D_4} \alpha^6. \quad (75)$$

POWER AND DRAG COEFFICIENT MODELS

- (1) $P = P_0$
- (2) $P = P_0 + P_1/V^{\frac{1}{2}}$
- (3) $P = P_0 + P_2V$
- (4) $P = P_0 + P_1/V^{\frac{1}{2}} + P_2V$
- (5) $P = P_0 + P_2V + P_3V^2$
- (6) $P = P_0 + P_1/V^{\frac{1}{2}} + P_2V + P_3V^2$
- (7) $P = P_0 + P_2V + P_3V^2 + P_4V^3$
- (8) $P = P_0 + P_1/V^{\frac{1}{2}} + P_2V + P_3V^2 + P_4V^3$

$$(1) C_D = C_{D0} + C_{D2}\alpha^2$$

$$(2) C_D = C_{D0} + C_{D2}\alpha^2 + C_{D4}\alpha^6$$

$$(3) C_D = C_{D0} + C_{D1}\alpha + C_{D2}\alpha^2 + C_{D3}\alpha^3 + C_{D4}\alpha^6$$

TABLE III-a

RECOVERED RESULTS WITH VARIOUS MODELS

NOISE-FREE

Model	C_{D0}	C_{D1}	C_{D2}	C_{D3}	C_{D4}
1-1	0.025010125		4.189265490		
1-2	0.027715936		1.840217248		
1-3	0.193206335	-5.536545497	55.990804759	-190.595121623	2218.55390095
2-1	0.041300870		3.314574182		6365.50170689
2-2	0.041723838		1.369905822		
2-3	0.032149511	0.256910853	1.083170012	-6.930257732	1934.85508995
3-1	0.052512561		3.397605844		2636.82627991
3-2	0.053437421		1.223230343		
3-3	0.104358253	-1.981087659	19.854161098	-61.409698497	2098.00447603
4-1	-0.007815849		3.258242555		3230.30712823
4-2	0.047922733		1.291498595		
4-3	0.043314322	0.136168241	0.321188551	2.111106052	2019.91892771
5-1	-0.140402432		3.358351516		2052.79056339
5-2	0.035099999		1.289155014		
5-3	0.035099999	9.0×10^{-10}	1.289155007	1.9×10^{-8}	2030.80086563
6-1	0.851148482		2.718117586		2030.80086599
6-2	0.019408889		1.334792323		
6-3	0.035100000	-1.8×10^{-9}	1.289155029	-4.1×10^{-8}	1977.60389095
7-1	7.097803213		-2.479854764		2030.80086584
7-2	0.035099997		1.289155018		
7-3	0.035099849	3.35×10^{-7}	1.289152488	6.77×10^{-6}	2030.80086585
8-1	-6.419749124		8.756565254		2030.80087789
8-2	0.035099983		1.289155030		
8-3	0.035100002	-9.7×10^{-8}	1.289155975	-3.4×10^{-6}	2030.80086168
					2030.80094408

TABLE III-b

RECOVERED RESULTS WITH VARIOUS MODELS

NOISE-FREE

Model	P ₀	P ₁	P ₂	P ₃	P ₄
1-1	172998.85079				
1-2	157655.47027				
1-3	127308.04933				
2-1	371192.98528	-2517765.9582			
2-2	334247.89394	-2218423.0065			
2-3	357094.45551	-2438740.6304			
3-1	69229.86429		701.819787		
3-2	60885.13175		660.124537		
3-3	84876.34799		410.940847		
4-1	1497321.54687	-11640184.7950	-2759.609819		
4-2	190924.27594	-1057400.1205	347.238354		
4-3	208960.25776	-1218458.9820	321.099439		
5-1	-272355.27164		5603.220066	-22.8622086	
5-2	28735.71416		1126.607146	-2.1696429	
5-3	28735.71414		1126.607143	-2.1696428	
6-1	11652672.75547	-77120339.5902	-52677.486678	142.0135471	
6-2	18.26865	-1.35 × 10 ⁻¹⁰	1536.512079	-4.0512608	
6-3	28735.71427	-1.71 × 10 ⁻⁵	1126.607143	-2.1696429	
7-1	-1038549.98441		20472.763195	-119.6962928	1.496383665
7-2	28735.71431		1126.607142	-2.1696429	-5.35 × 10 ⁻¹⁰
7-3	28735.71429		1126.607056	-2.1696417	-2.80 × 10 ⁻⁸
8-1	25533616.98900	-1.6 × 10 ⁸	-133353.421168	433.4378086	-1.726554460
8-2	28735.71427	4.5 × 10 ⁻⁷	1126.607134	-2.1696427	-3.2 × 10 ⁻⁹
8-3	28735.71633	3.2 × 10 ⁻⁴	1126.607117	-2.1696428	-2.2 × 10 ⁻¹⁰

TABLE III-c

The three drag expressions and the eight power expressions give us a total of 24 analytical models with which we can attempt to fit experimental data. It will probably be necessary to employ all of the models or at least this number of models until experience with data for a particular aircraft permits one to discard those models which do not apply. The results obtained by fitting all these models to the theoretical data of figure 24 are shown in Table IIIb. If one compares the results for case 5-2 with figures 22 and 23, one will see immediately the very good agreement which the extraction method can provide.

One may also ask why should one also employ a model which is simply a reduced form of a more general model? The answer lies in the extreme sensitivity of the coefficient solutions to small errors in the data. Generally, the more general models are more sensitive to these errors so that under these circumstances a simpler form may yield reasonable results whereas the more general form may yield nonsense numbers. It should be recalled that since any power, if accompanied by a suitable drag, will solve the equation of motion, these physically absurd numbers are legitimate mathematical solutions. How then does one determine whether the solutions obtained are reasonable?

The first means of assessing the reasonableness of the solution set is to use them along with the experimental data in the proper form of equation (8). For 300 data points a value of $S < 10^{-13}$ generally indicates coefficient values within 1% or so of the correct values. (For the exact coefficient values, $S < 10^{-21}$.) Coefficient values in error by 5%, for example, may still be of interest, but with errors of this size it may become difficult to identify the best model and coefficient set merely by checking to see which model gives the smallest value of S . $S_{\min}$ will now be on the order of 10^{-6} for 300 points, but the coefficient set for $S_{\min}$ may give absurd powers and drags. For this reason it is desirable to add a second constraint which an acceptable model and coefficient set must satisfy: The horsepower for any speed must be positive and less than Y ($Y = 400$ for ATLIT); C_D must be positive and less than Z ($Z = 0.12$ for ATLIT) for any α . One frequently finds that with noisy data very few of the 24 coefficient sets satisfy this second constraint.

Effect of Data Errors on Coefficient Extractions

We have noted above that by operating on exact data it is possible for the coefficient extraction procedure to recover the values of the coefficients in the power and drag polynomials to six significant figures. We have also noted that this procedure is quite sensitive to data inaccuracies. In order to place some quantitative bound on this sensitivity, the exact input data were artificially degraded and resubmitted to the coefficient extraction procedure to determine how the coefficient values were altered. Two types of degradation were employed: random noise and constant bias. For the random noise a random number generator was employed at each 0.1 seconds of each trace and the output scaled so as to be 1% of the maximum value of the function, e.g., 1% of the maximum value of $V(t)$ during the maneuver. These scaled noise values were then added to the exact function values to obtain the degraded data. For this experiment, all data which would normally be measured in flight were degraded. This was too noisy. No coefficient set would satisfy the reasonableness criterion.

The data were then filtered with $n_c = 10$. For comparison, the filtered and unfiltered data are shown in figure 28. Note that the filtering routine does a very good job of removing the high frequency noise. Note also that employing a random number generator in the manner indicated means that the random noise usually has a non-zero mean (bias error). Despite the filtering, the coefficient extraction routine would not yield reasonable results. It also failed for $n_c = 6$ and $n_c = 4$. The magnitude of the random contributions was then reduced from 1% of maximum signal to 0.1%. With no filtering the extraction procedure again failed. However, with filtering ($n_c = 6$), two models gave reasonable results. These were

$$P = 371959.0785 - \frac{2702612.22}{V^{1/2}}$$

$$C_D = .00676 + 1.52053\alpha - 18.77305\alpha^2 + 87.8915\alpha^3 - 1295.7649\alpha^6$$

and

$$P = 16594.89367 + 1308.3421V - 3.024425V^2$$

$$C_D = .027766 + 1.345608\alpha^2 + 1985.1565\alpha^6.$$

The second of these (see also Table IV) is the correct functional form. Although the coefficient values for this form individually are in error by as much as 73%, the recovered power, for example, is only in error by 6.3% at 200 ft/sec. The errors in drag are even smaller.

RECOVERED RESULTS WITH RESIDUAL NOISE

1/10 of 1% Random Noise
 $n_c = 6$

Model 2-3

$$P_0 = 371959.0785$$

$$P_1 = -2702612.2226$$

$$C_{D0} = 0.006761$$

$$C_{D1} = 1.520529$$

$$C_{D2} = -18.773051$$

$$C_{D3} = 87.891504$$

$$C_{D4} = -1295.764876$$

Model 5-2

$$P_0 = 16594.89367$$

$$P_2 = 1308.34213$$

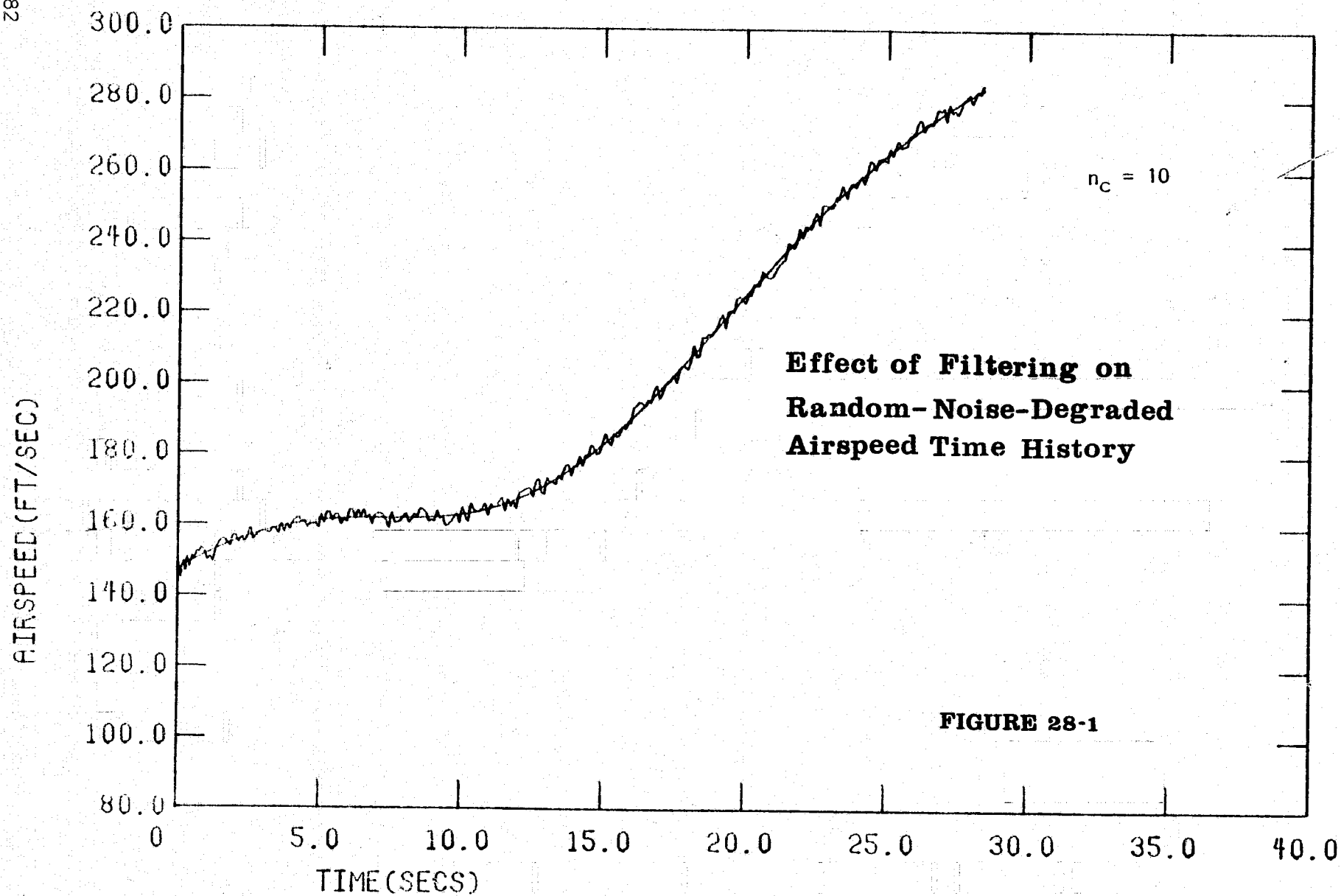
$$P_3 = -3.02442$$

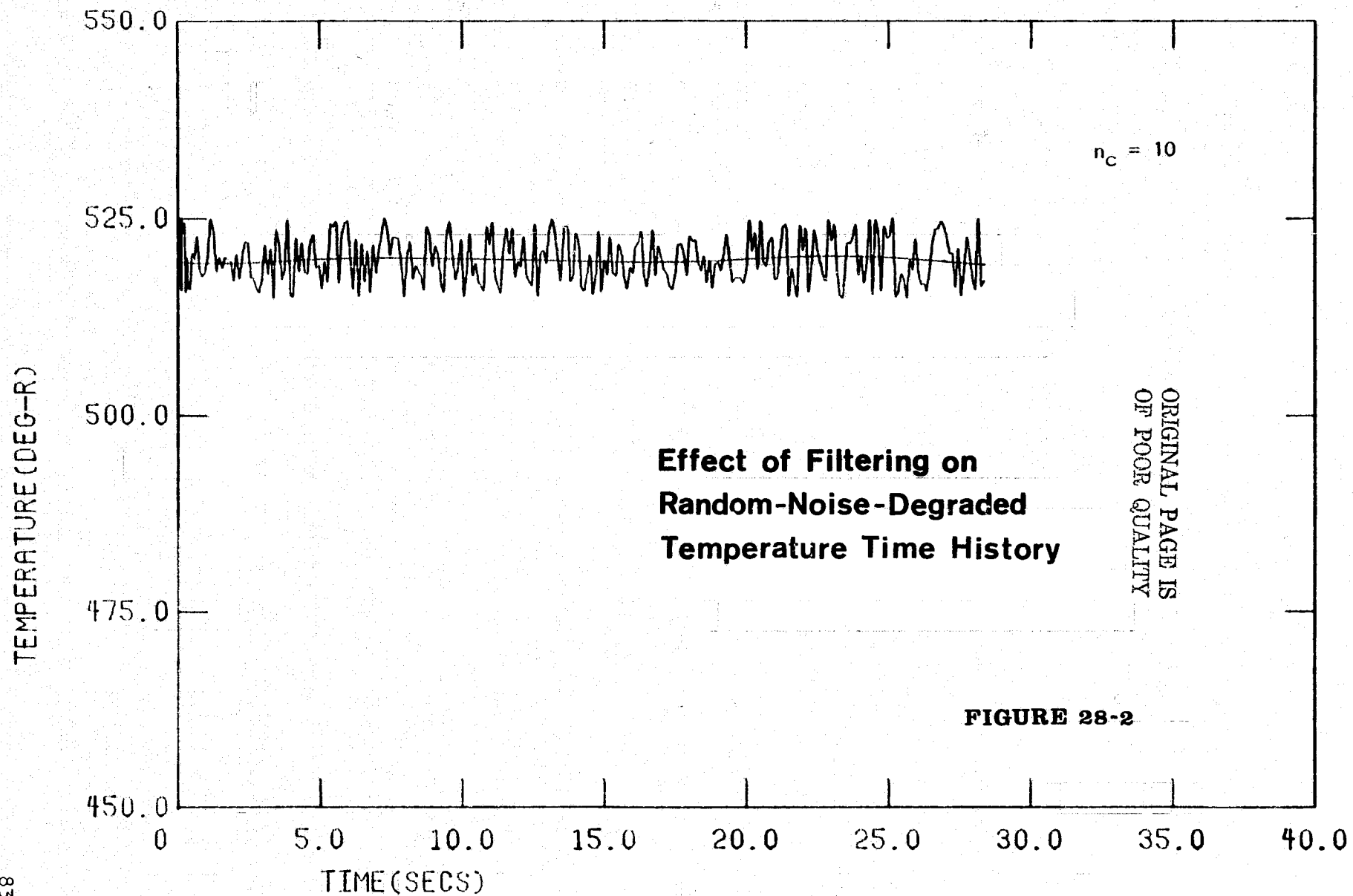
$$C_{D0} = 0.02777$$

$$C_{D2} = 1.34561$$

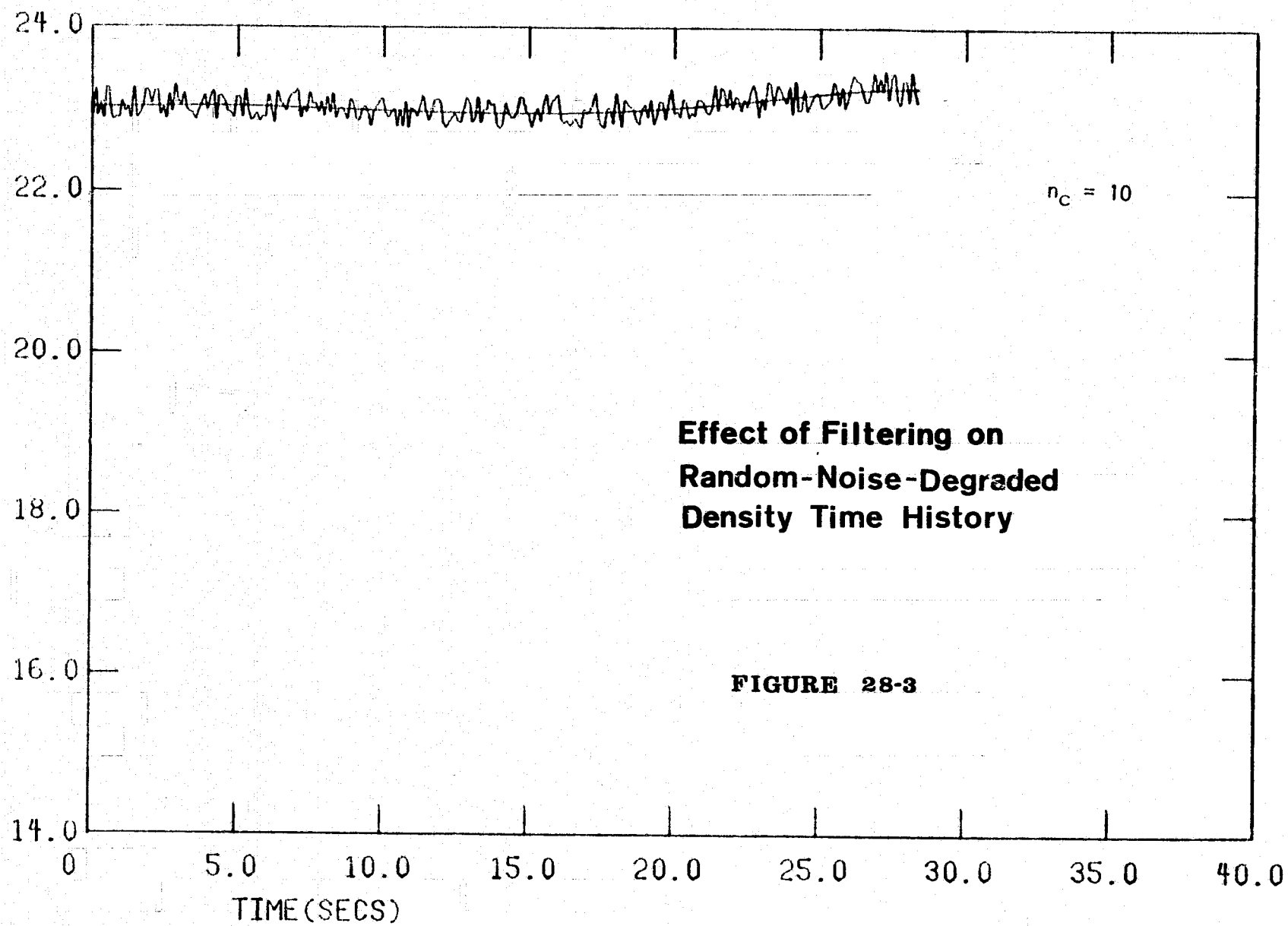
$$C_{D4} = 1985.15652$$

TABLE IV

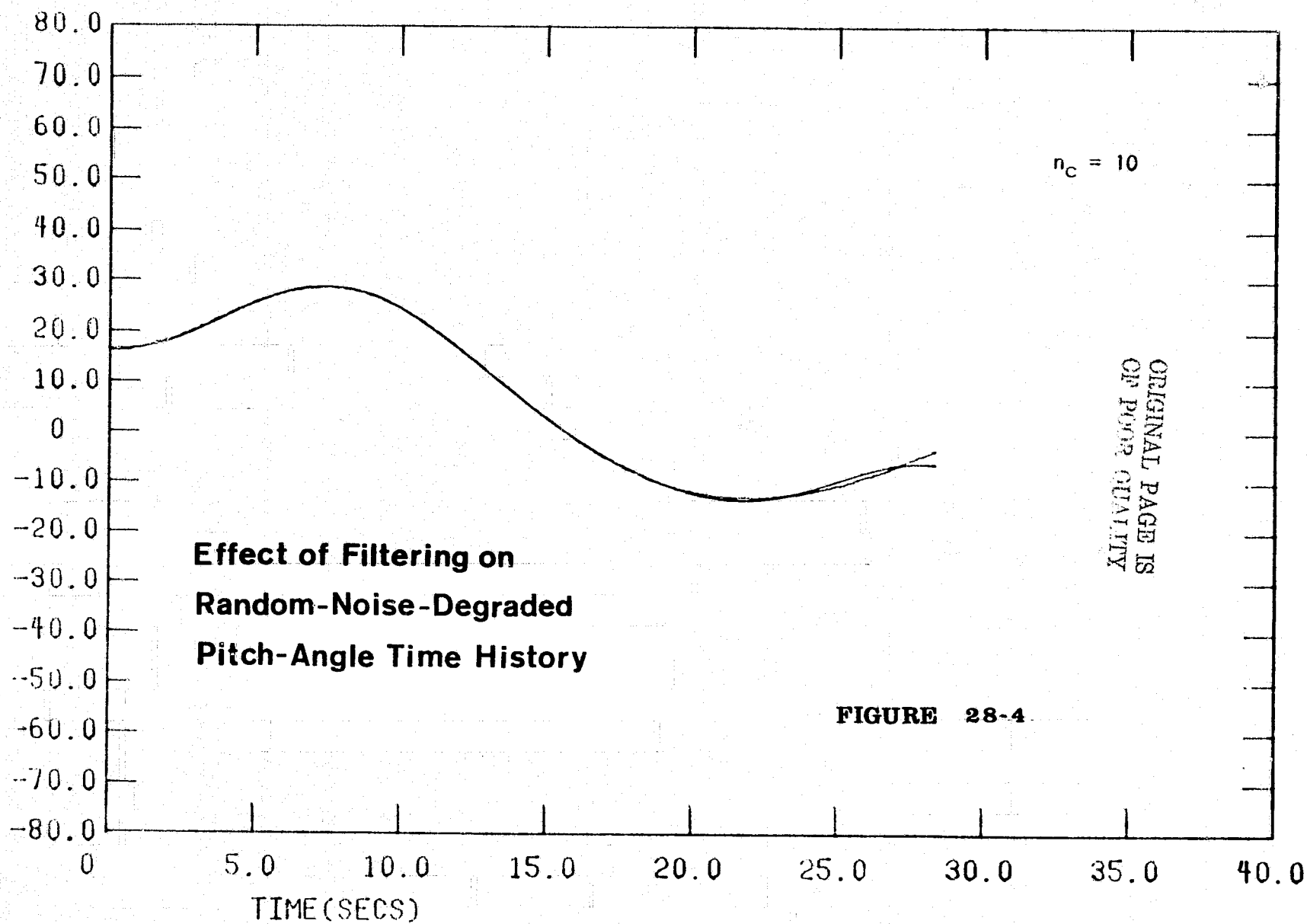




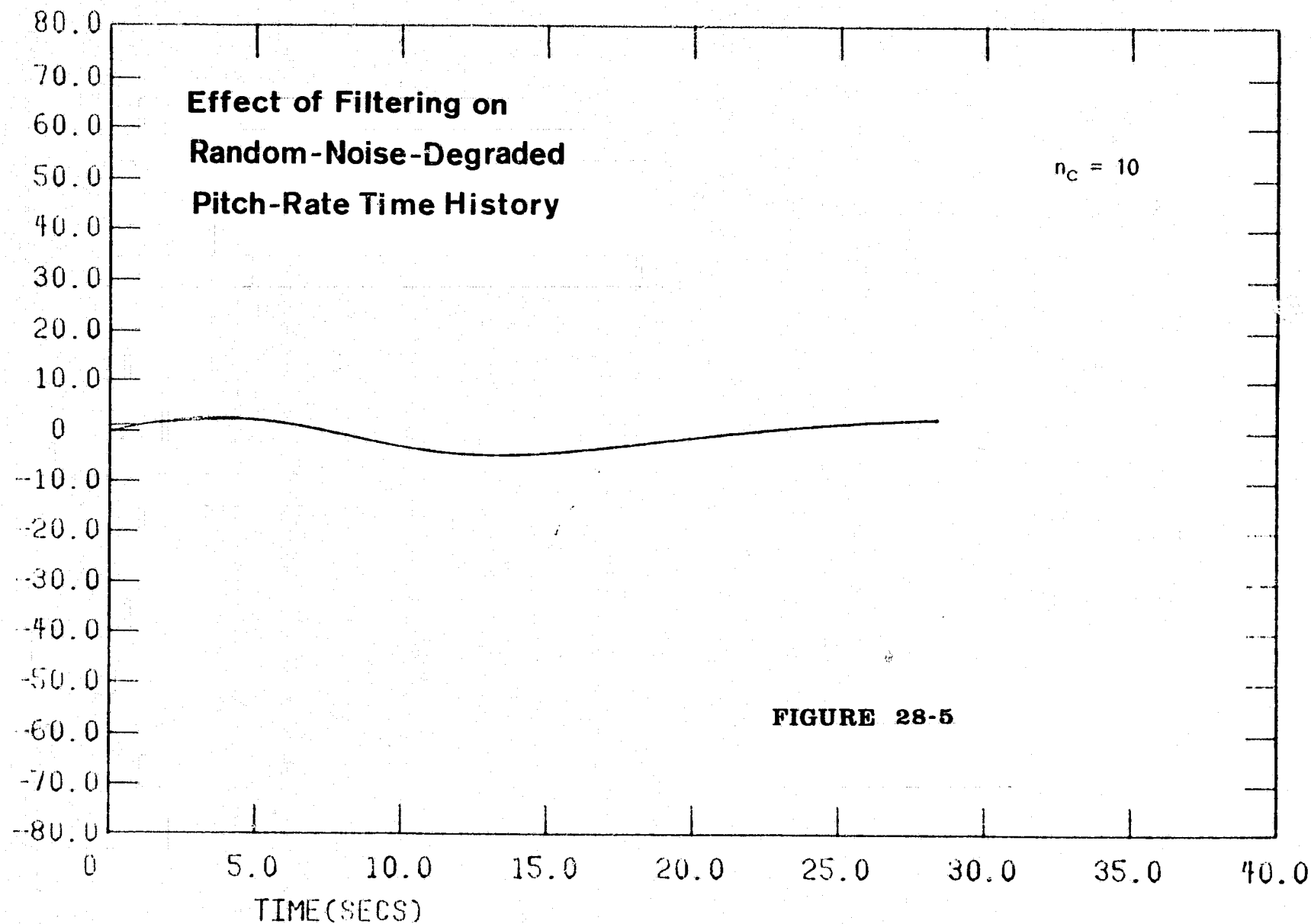
DENSITY(SLUG/FT**3) X 10000



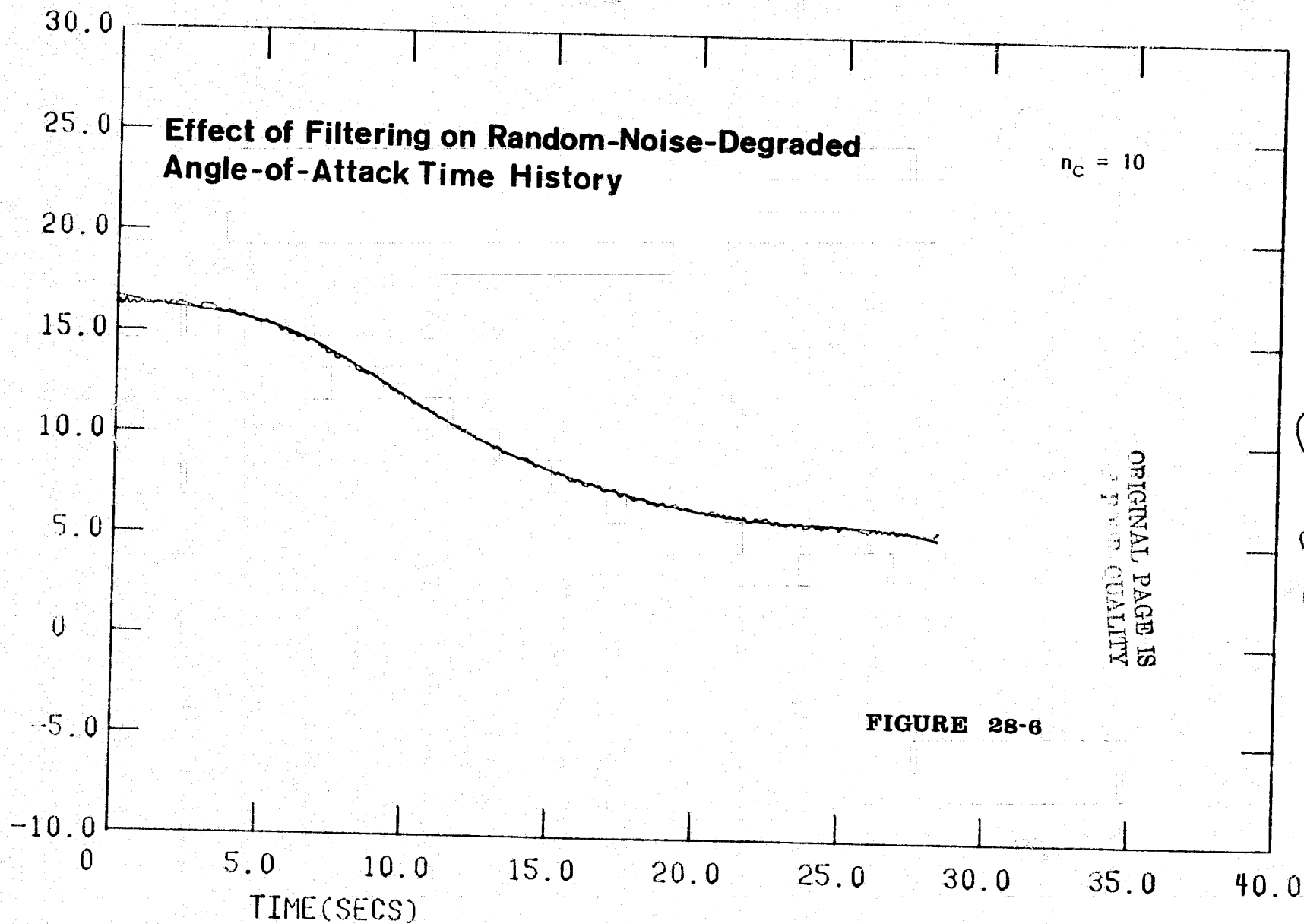
PITCH ANGLE(RADIANS) X 100



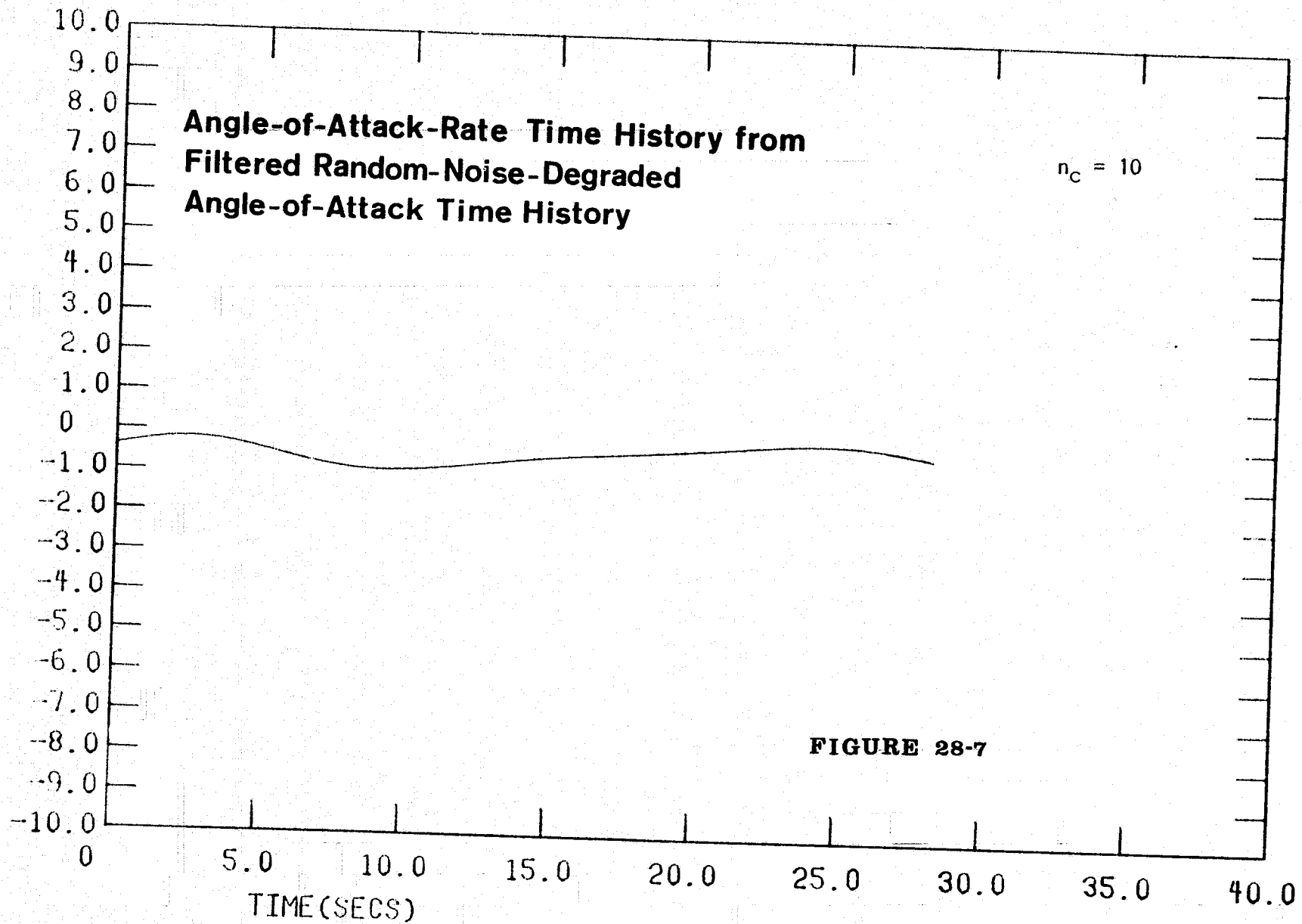
PITCH RATE(RAD/SEC) X 100



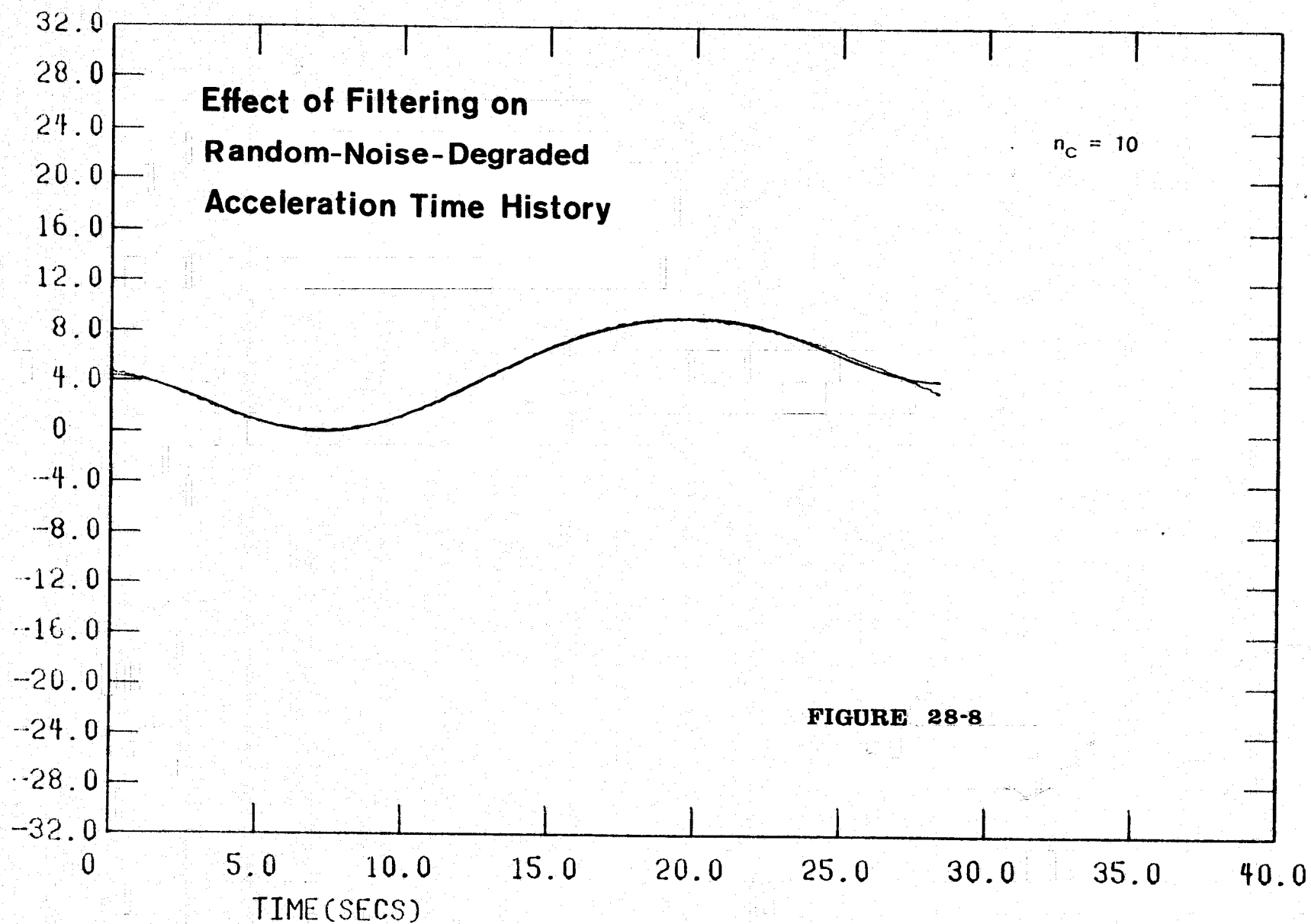
ANGLE OF ATTACK(RAD) X 100



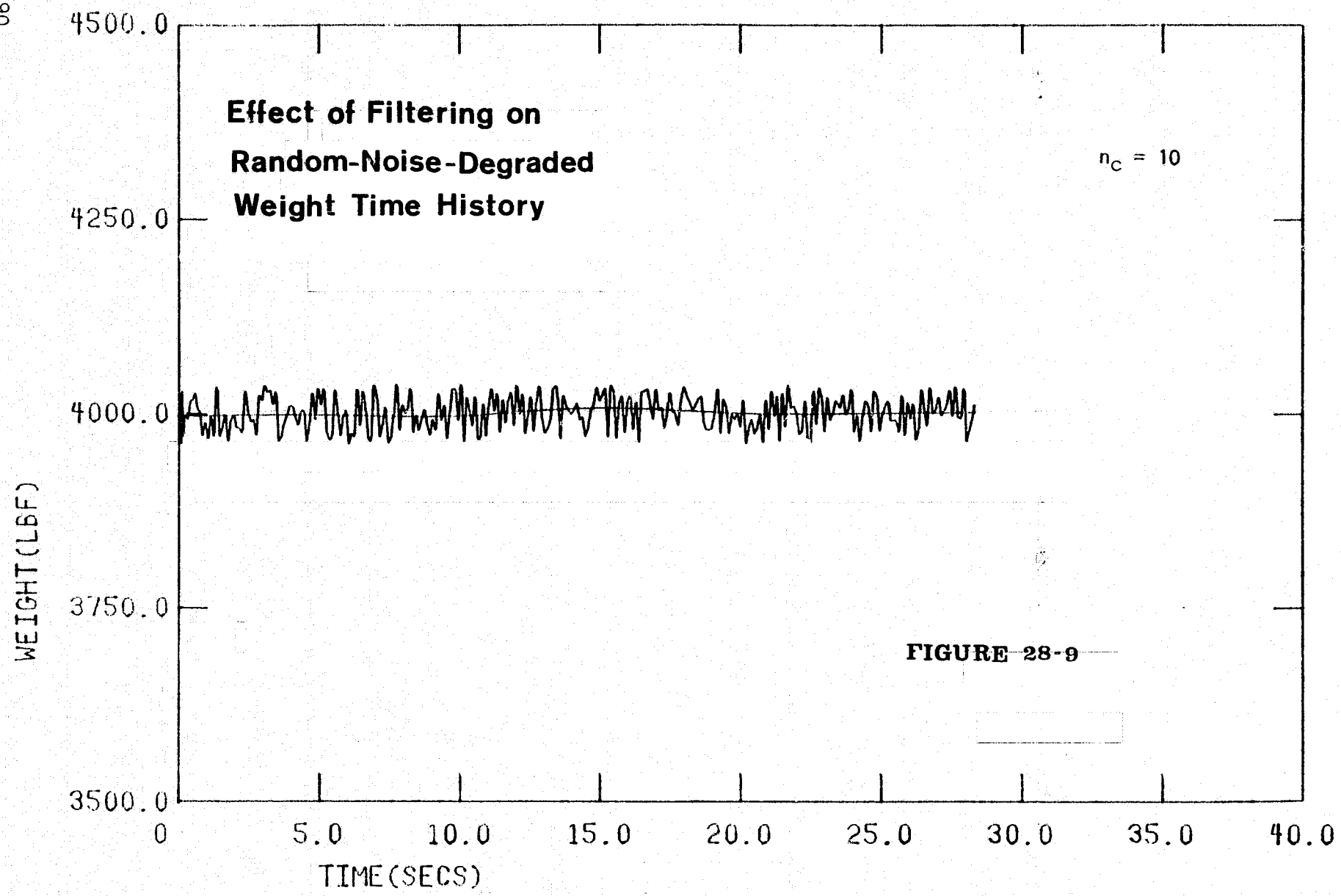
ANGLE-OF-ATTACK RATE (RAD/SEC) X 100



ACCELERATION(FT/SEC**2)

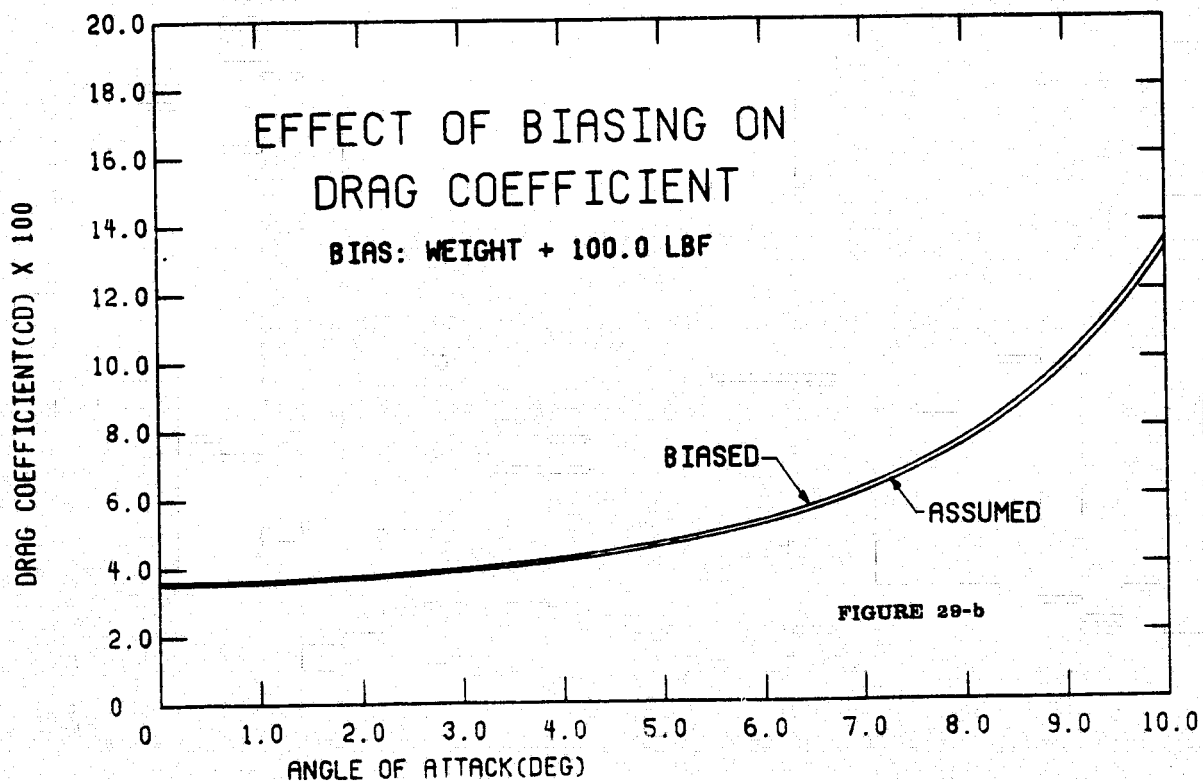
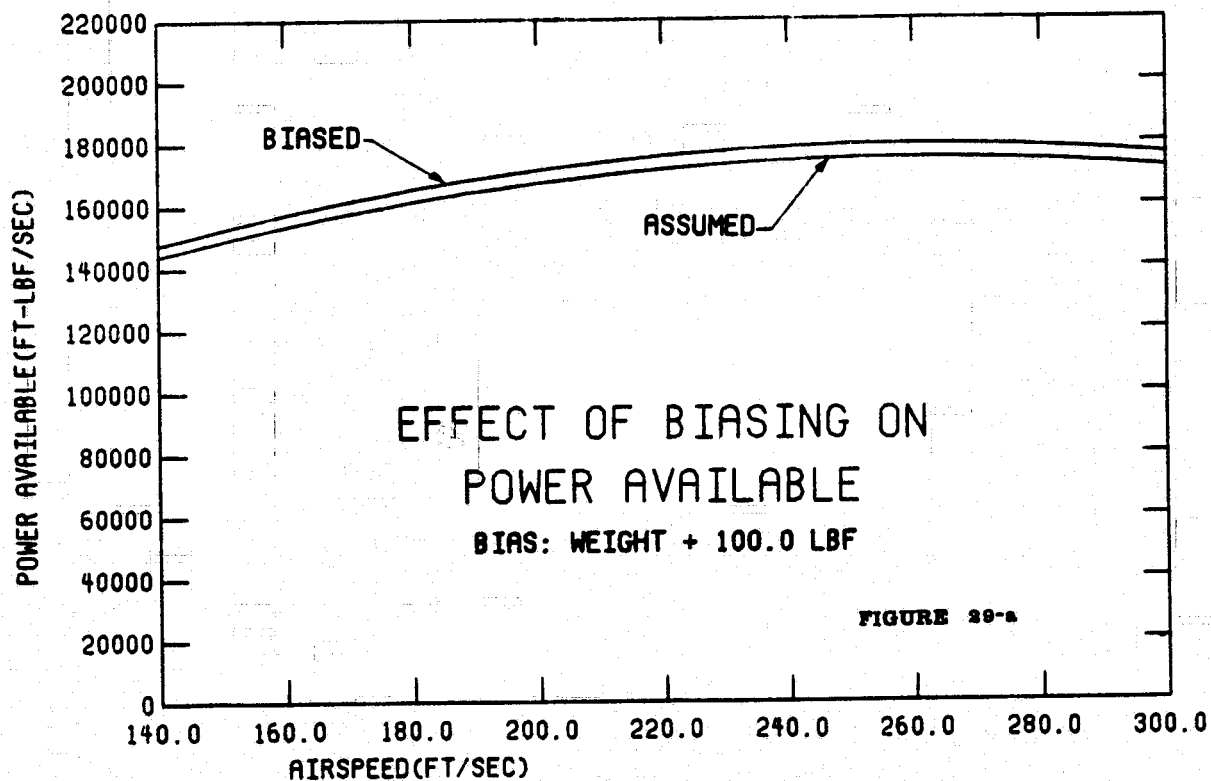


06

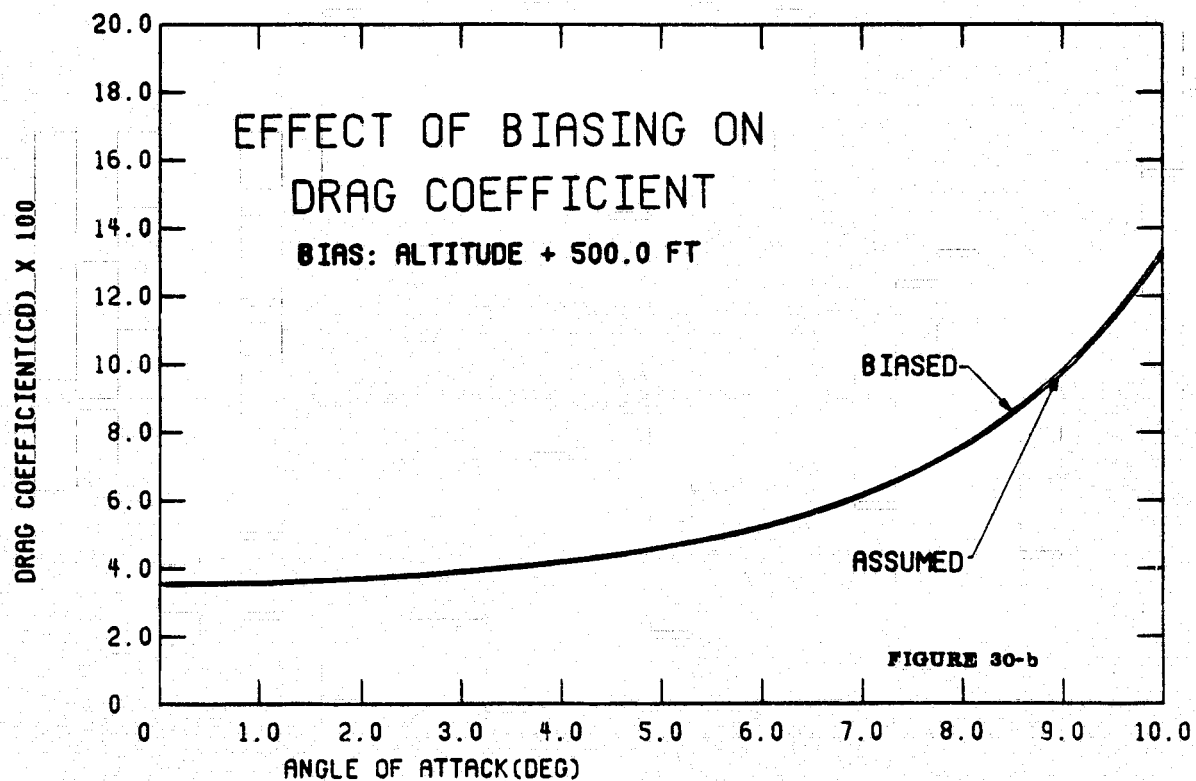
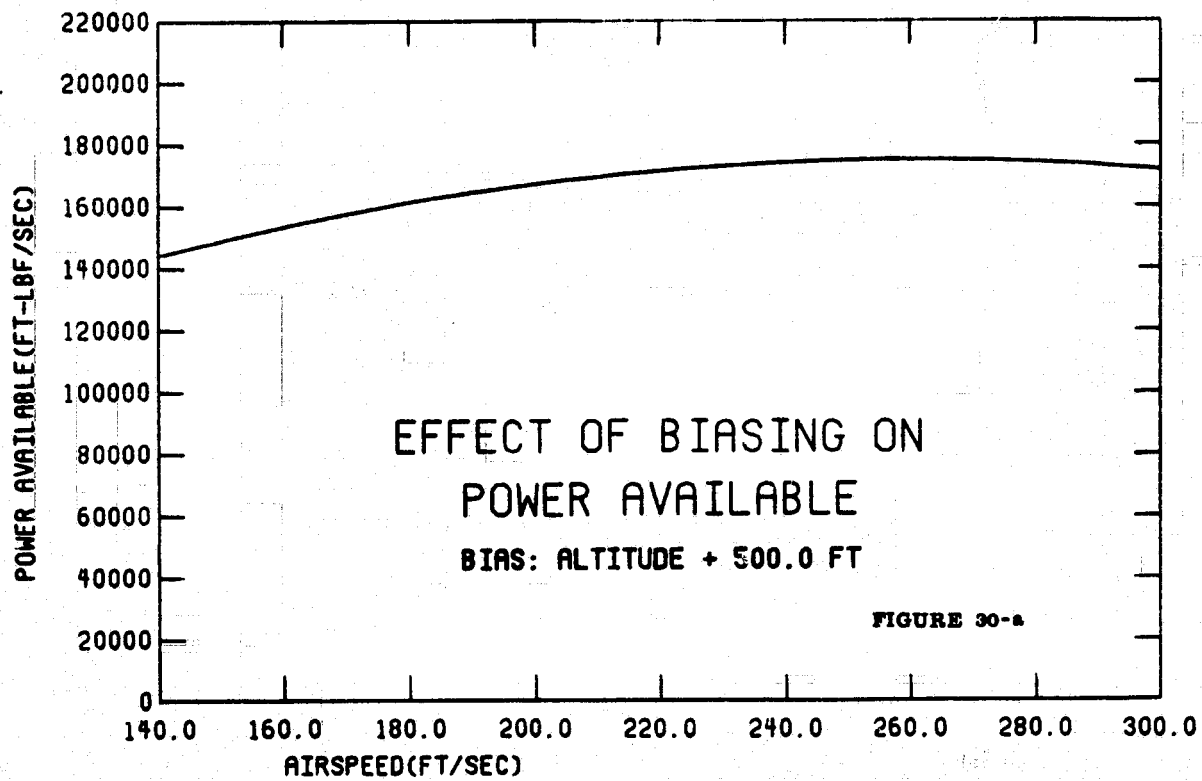


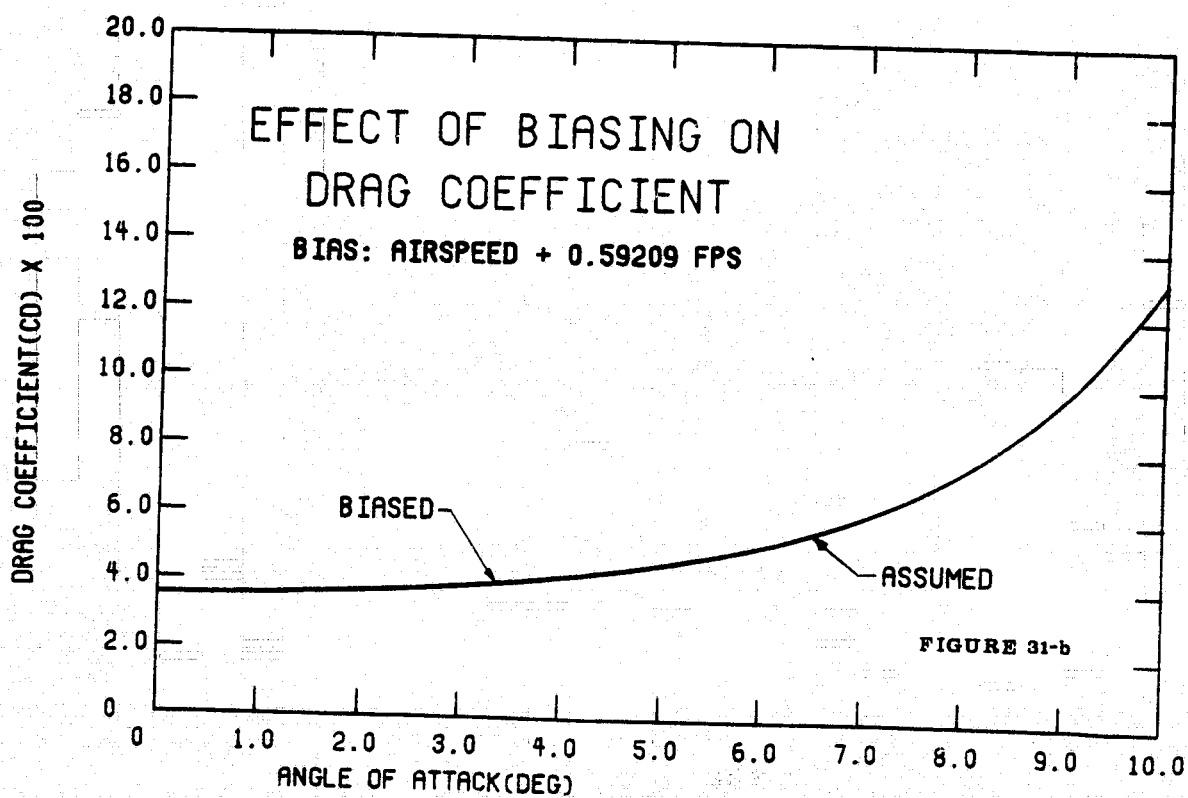
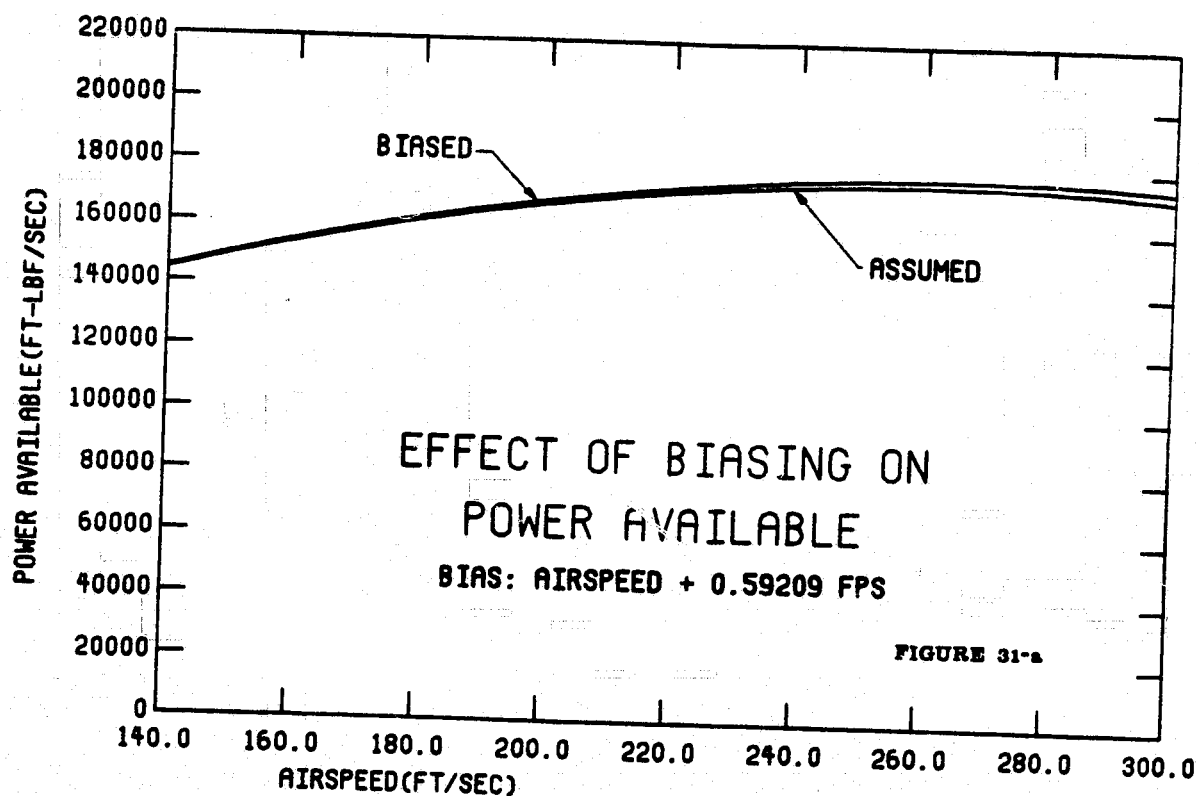
A second experiment degraded the data traces individually by a constant bias error. Reproduced as figures 29 through 38 are the recovered speed-power and drag-alpha characteristics for various bias errors compared with the undegraded characteristics used to generate the data traces. Generally, the characteristics for the largest bias error which can yield reasonable results are shown along with the characteristics for smaller bias errors so that the reader may assess the linearity of the change in characteristics with the change in bias error. Note that weight and altitude bias errors of the magnitude shown are not particularly serious. As might be expected, bias errors in airspeed affect the power determination primarily and have little influence on drag. The same is true with regard to bias errors in $\dot{V}$. Bias errors in θ and α , however, are extremely destructive. Even a 0.7° error in θ results in about a 10% error in C_{D0} while a -1.9° error in θ results in an error of about 37% in C_{D0} . The case for a bias error of $+1.9^\circ$ failed (i.e., gave a power exceeding the limit of 400 H.P.). An angle of attack bias error of as little as 0.1° is noticeable in the final result while an α bias error of 1.6° results in drag and power errors in the neighborhood of 30-40%. In addition, the shapes of the curves are altered drastically.

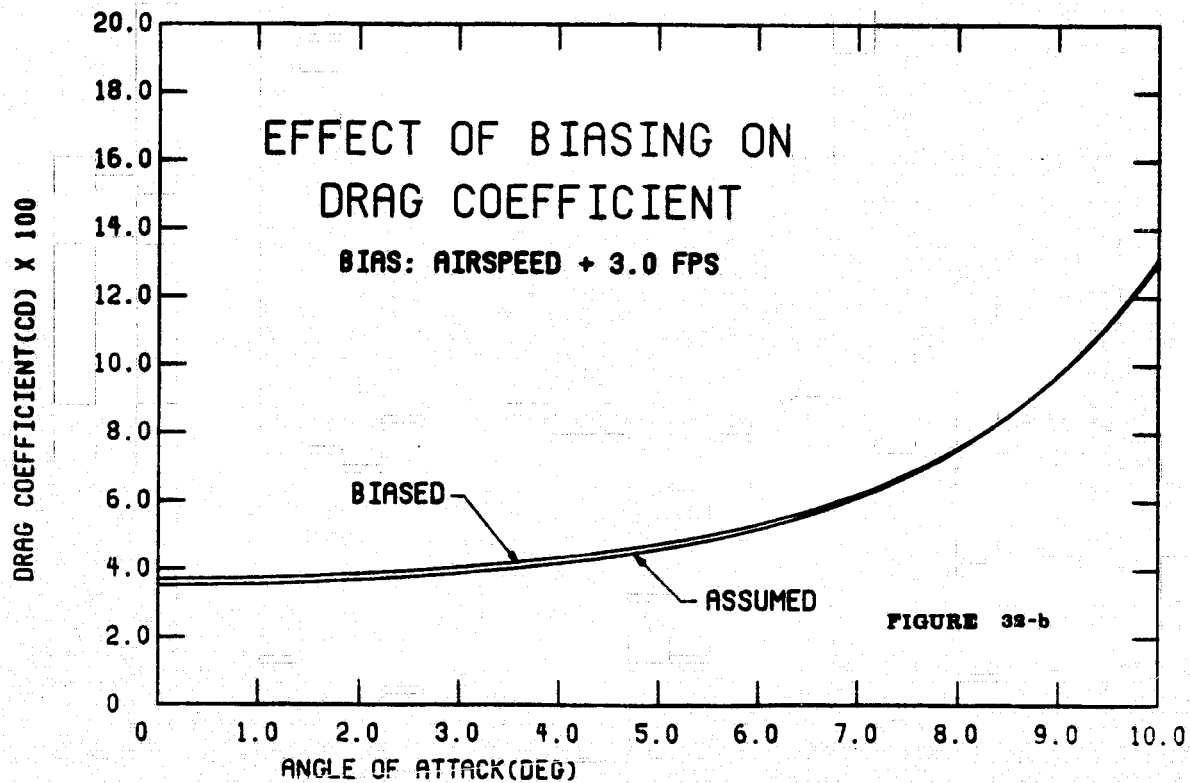
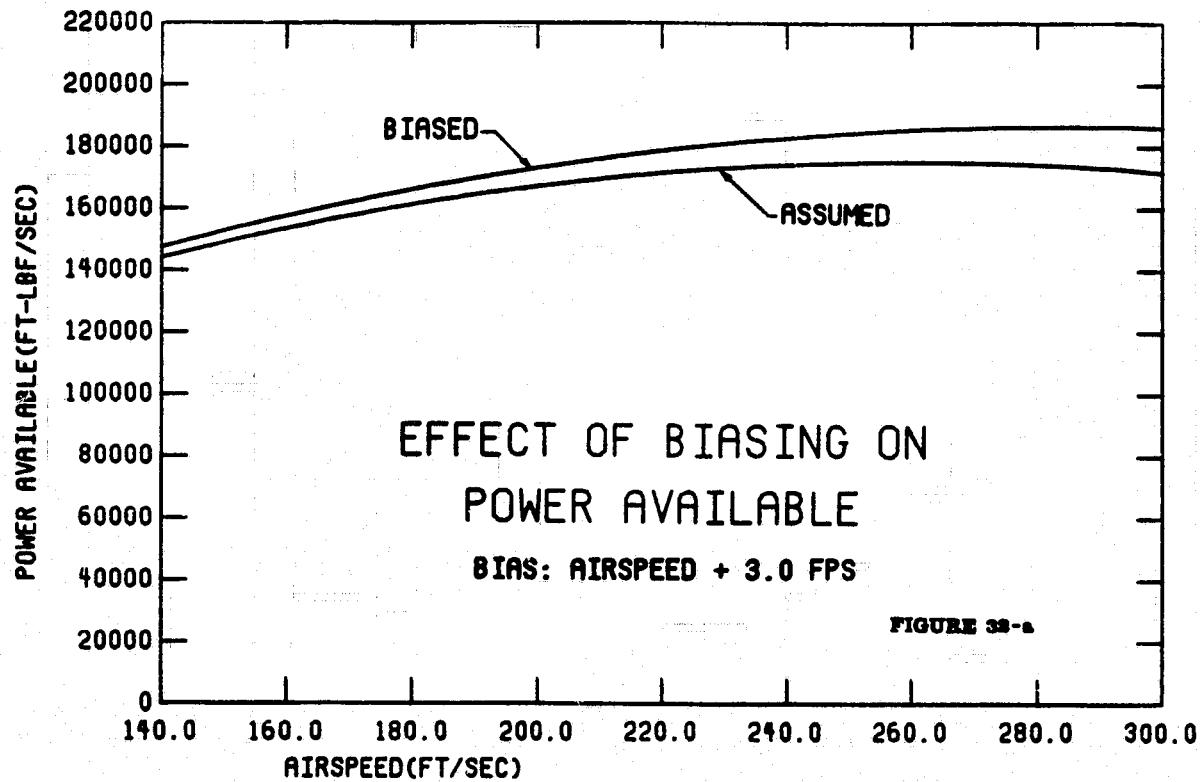
These results demonstrate the extreme sensitivity of the coefficient extraction procedure to typical noise and instrument errors encountered in flight test work. This is true even after the data have been filtered to remove the noise components which occur at frequencies above the usual aircraft responses to control deflections. Thus, to obtain accurate drag and power data using this procedure some means must be employed to reduce the noise components in the data at what might be termed signal frequencies.

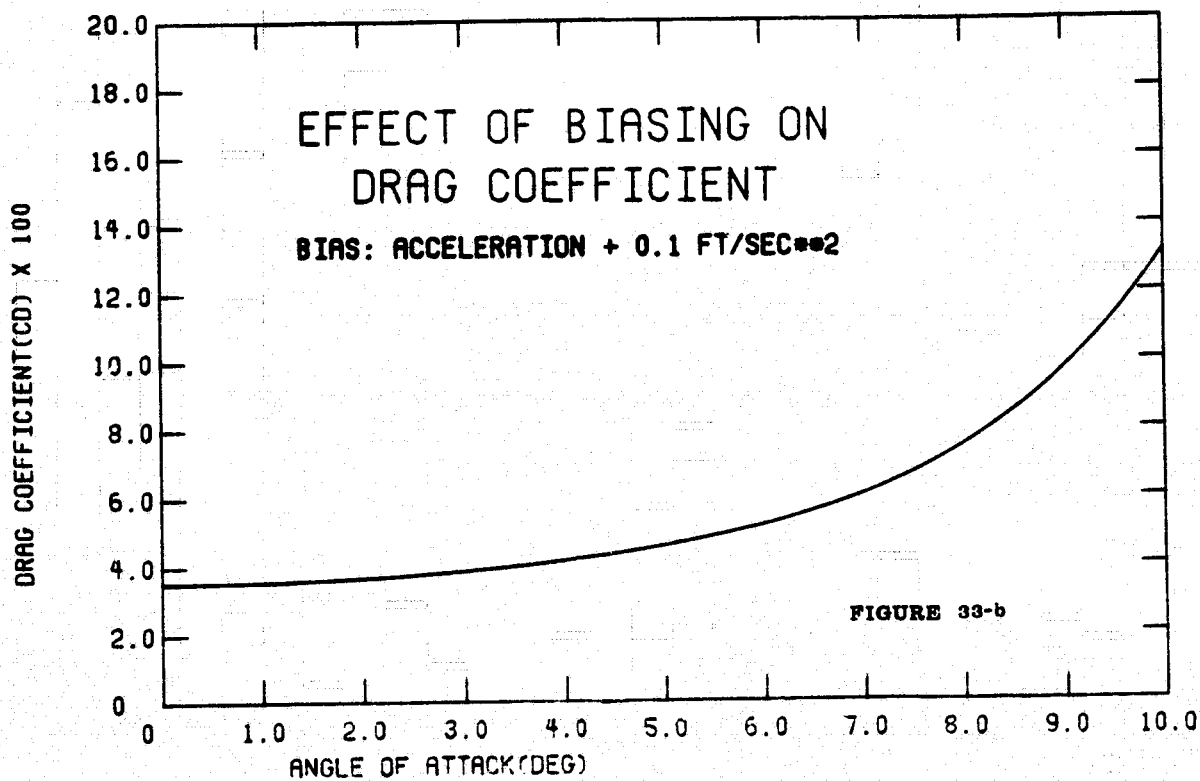
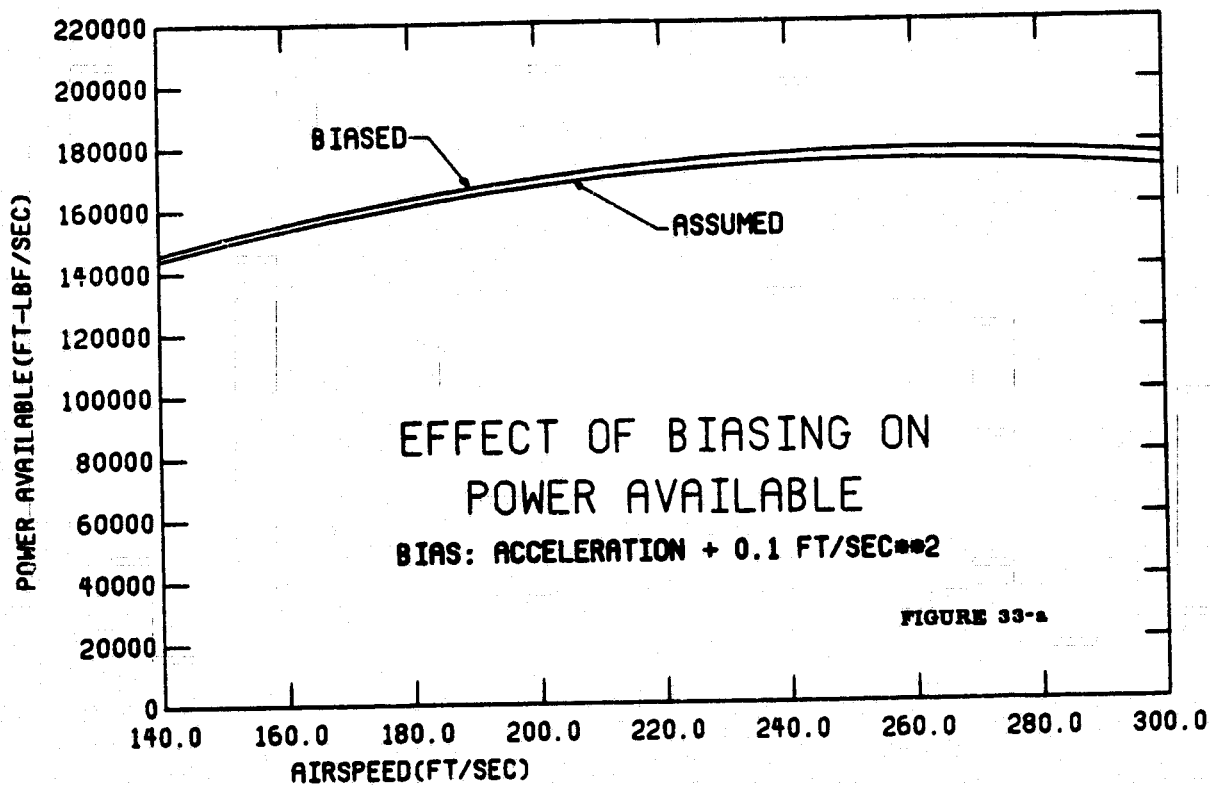


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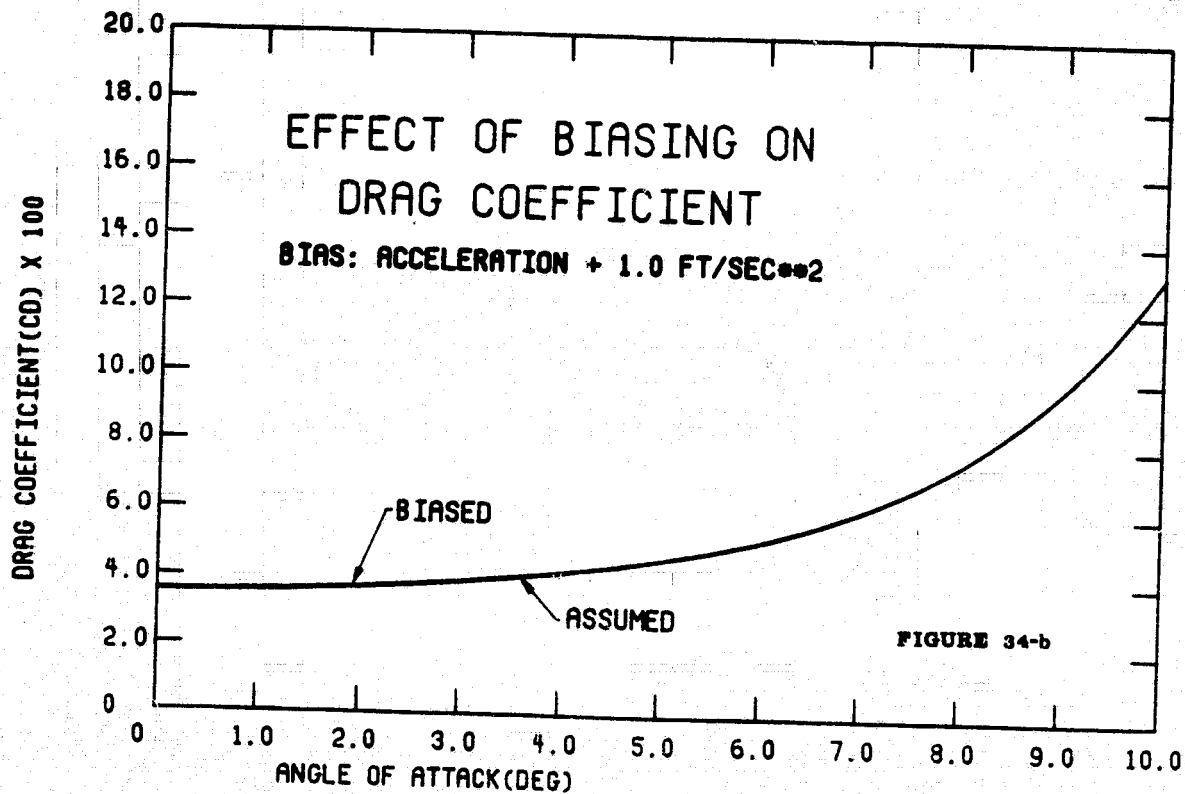
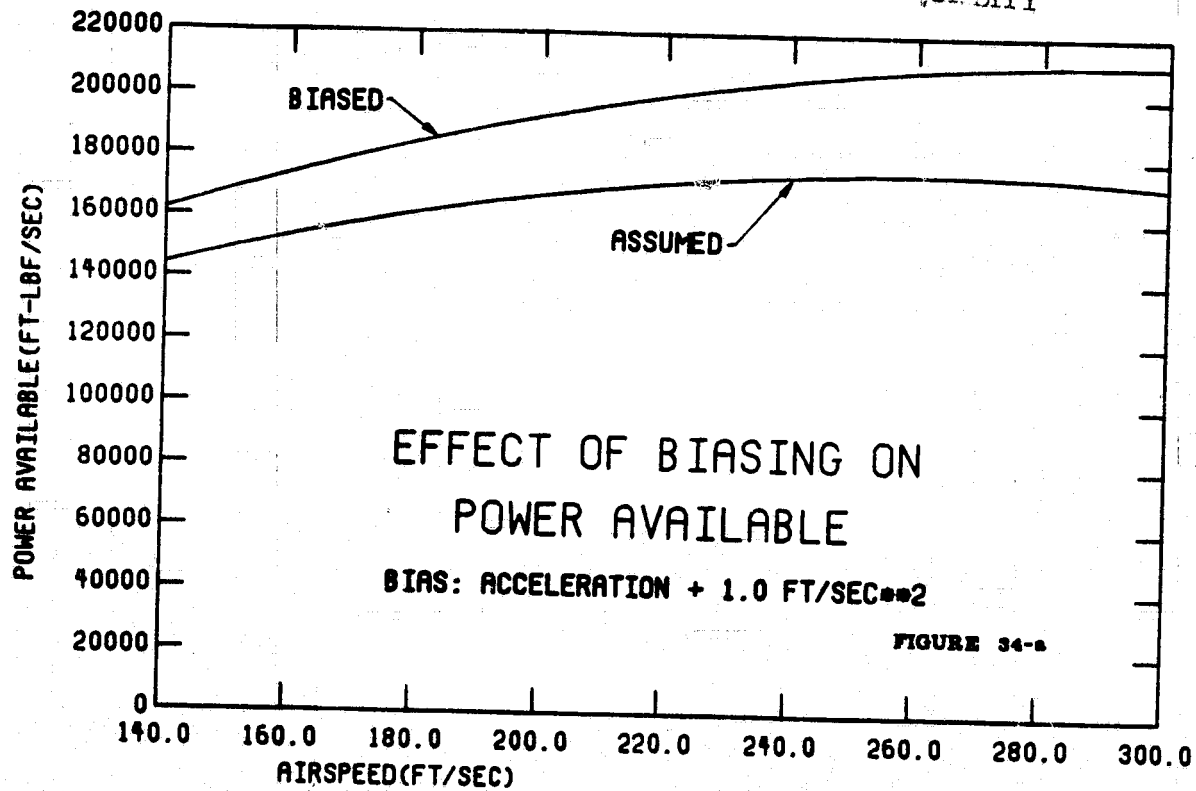


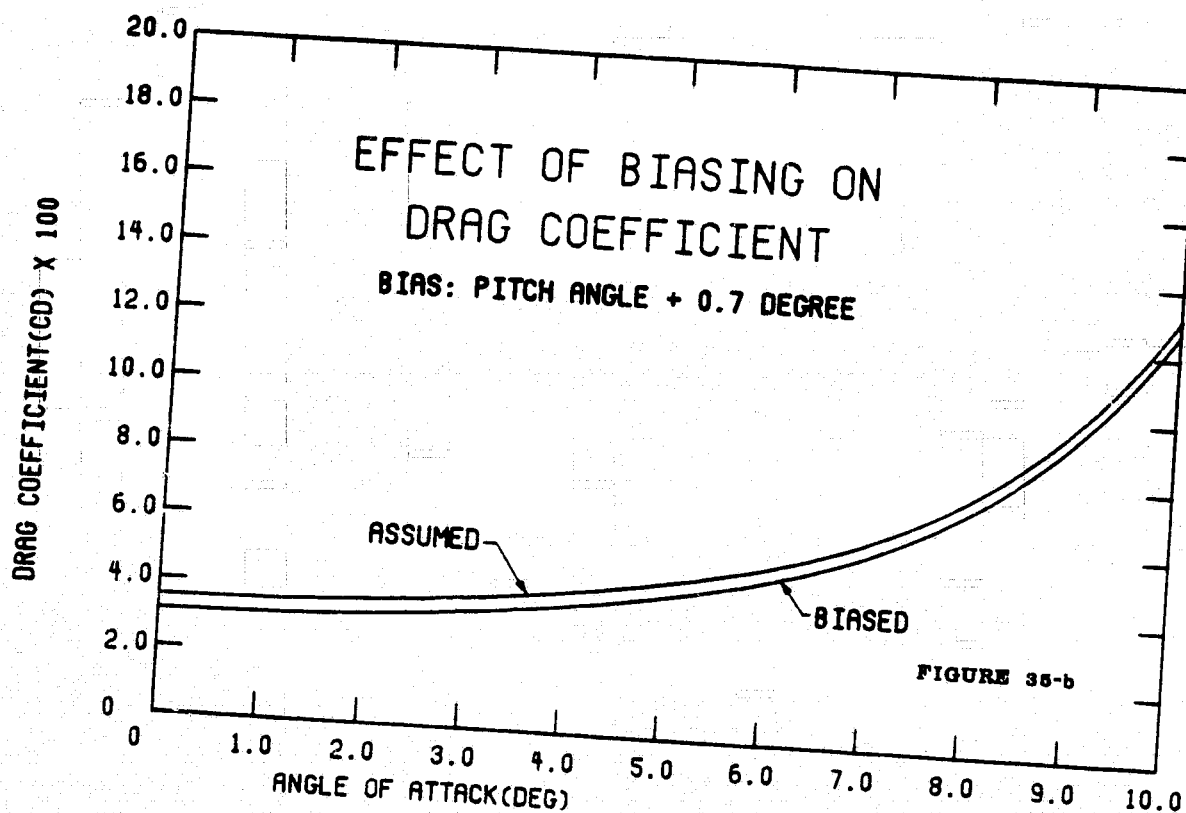
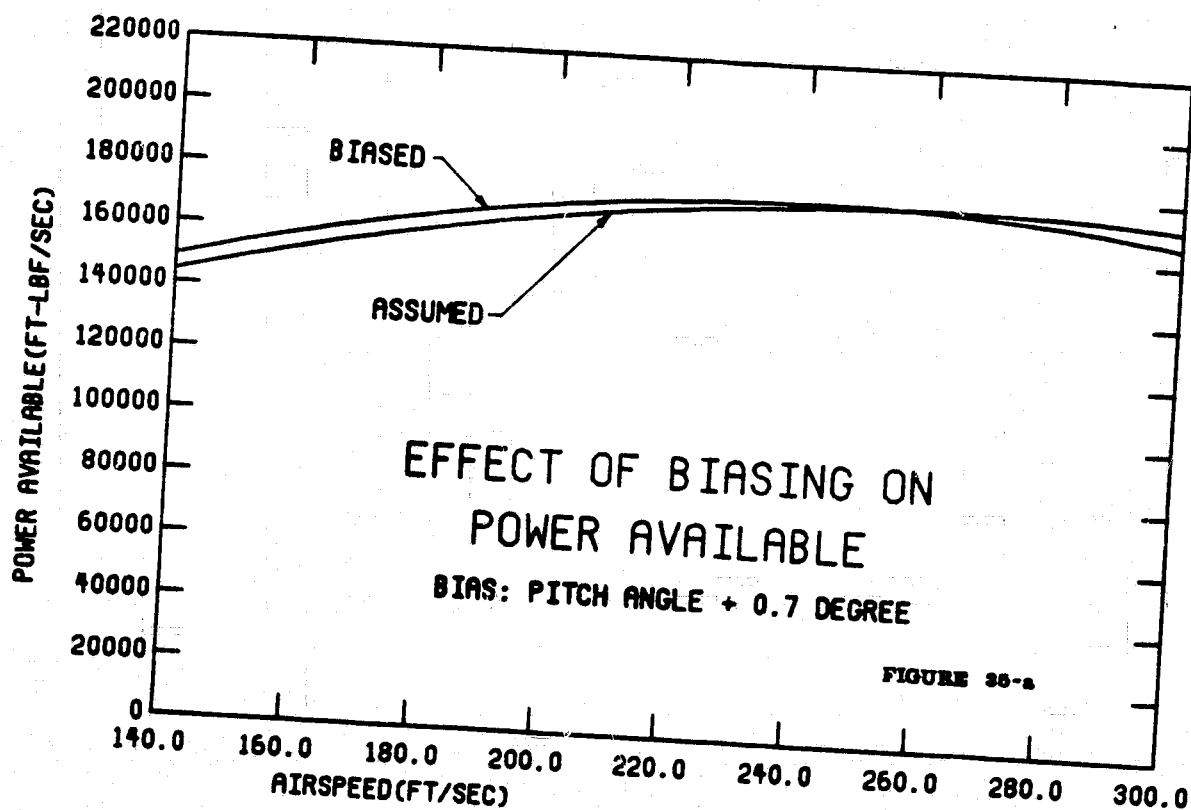




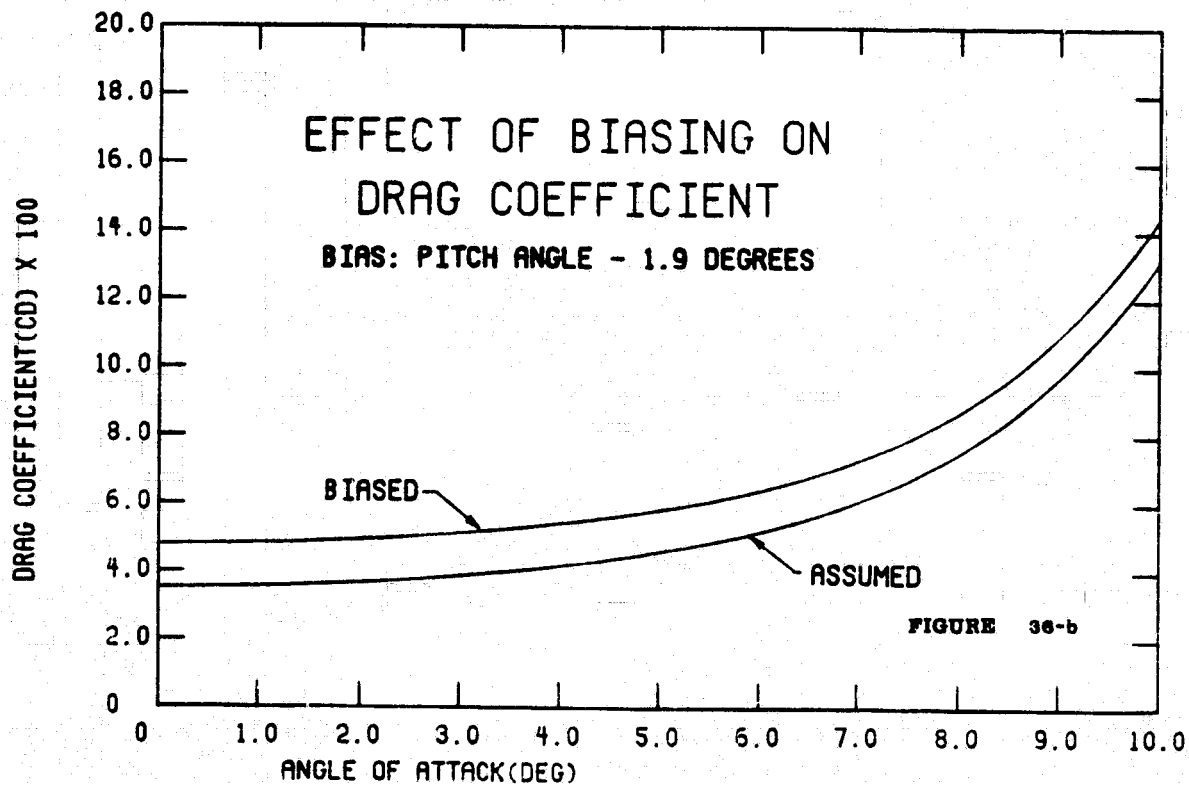
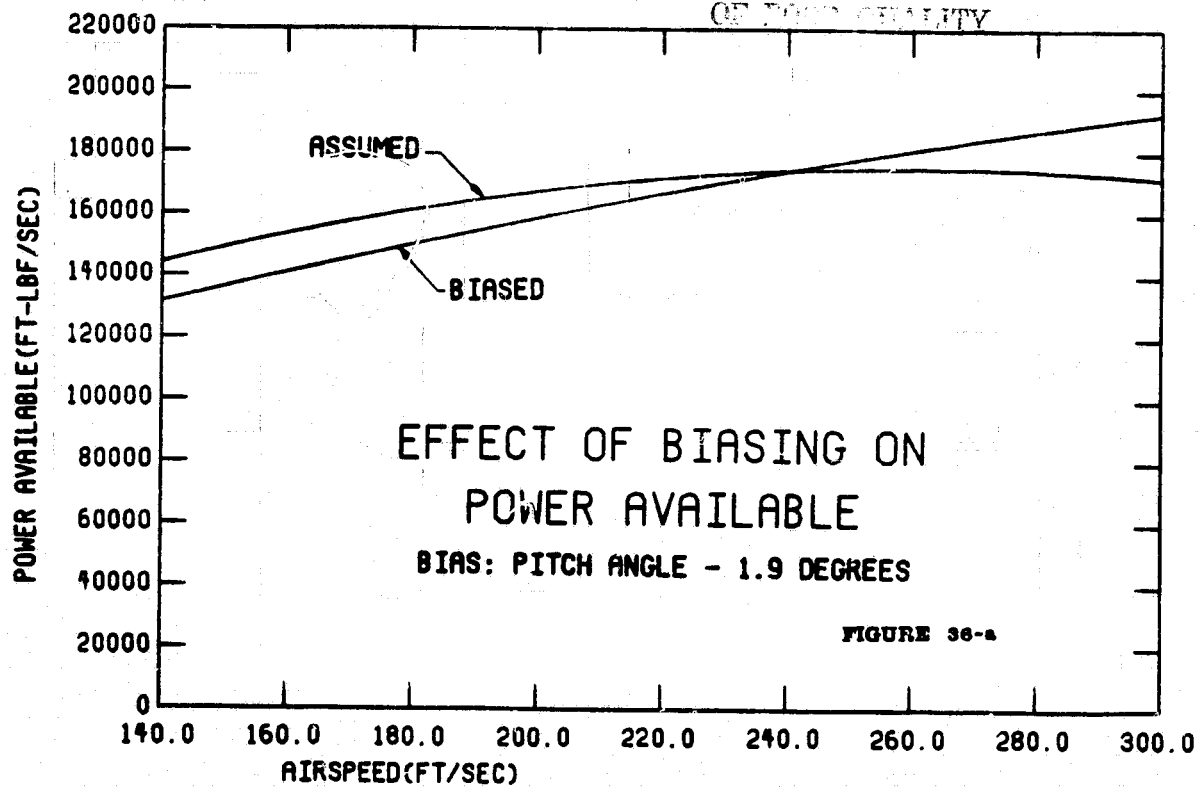


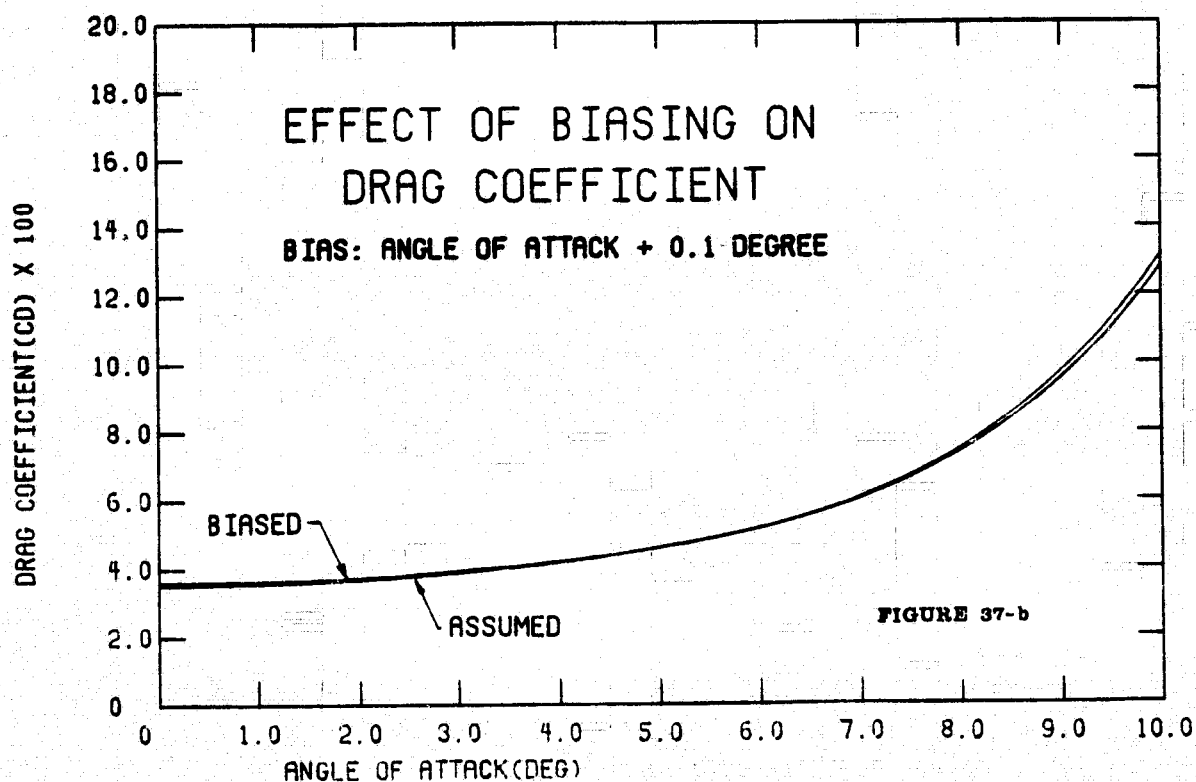
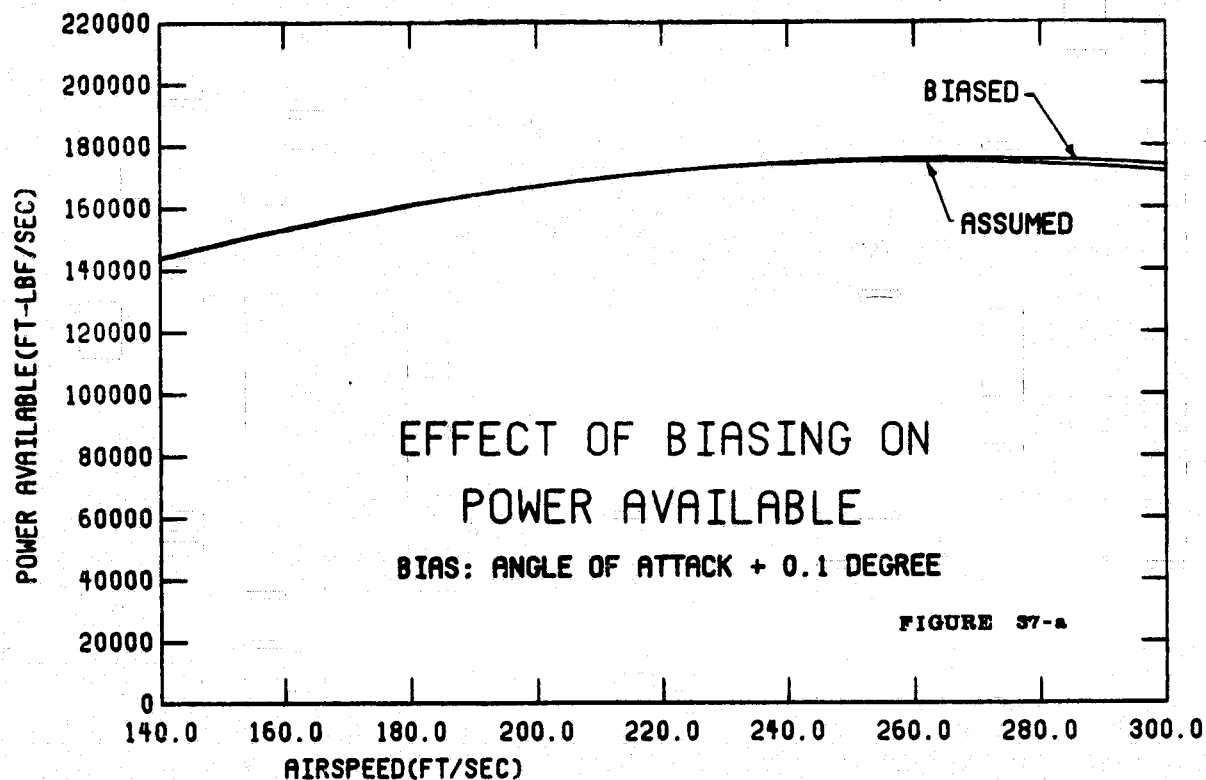
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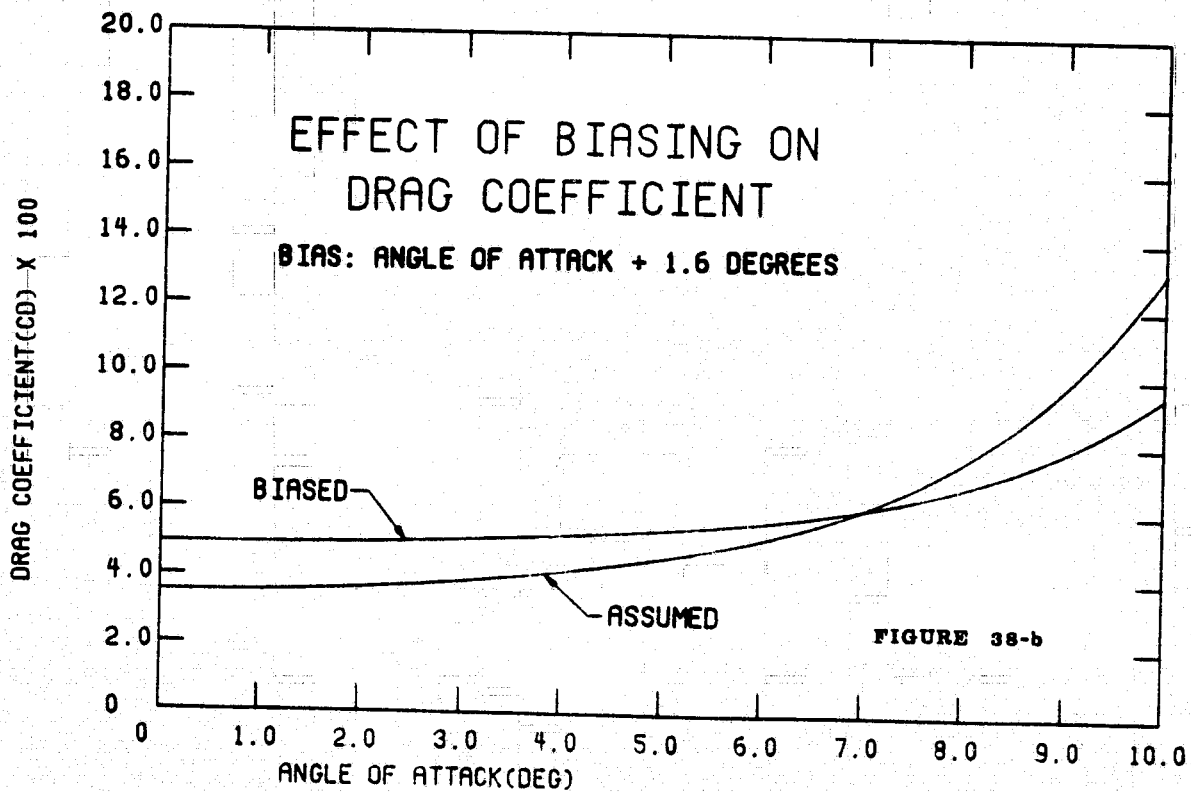
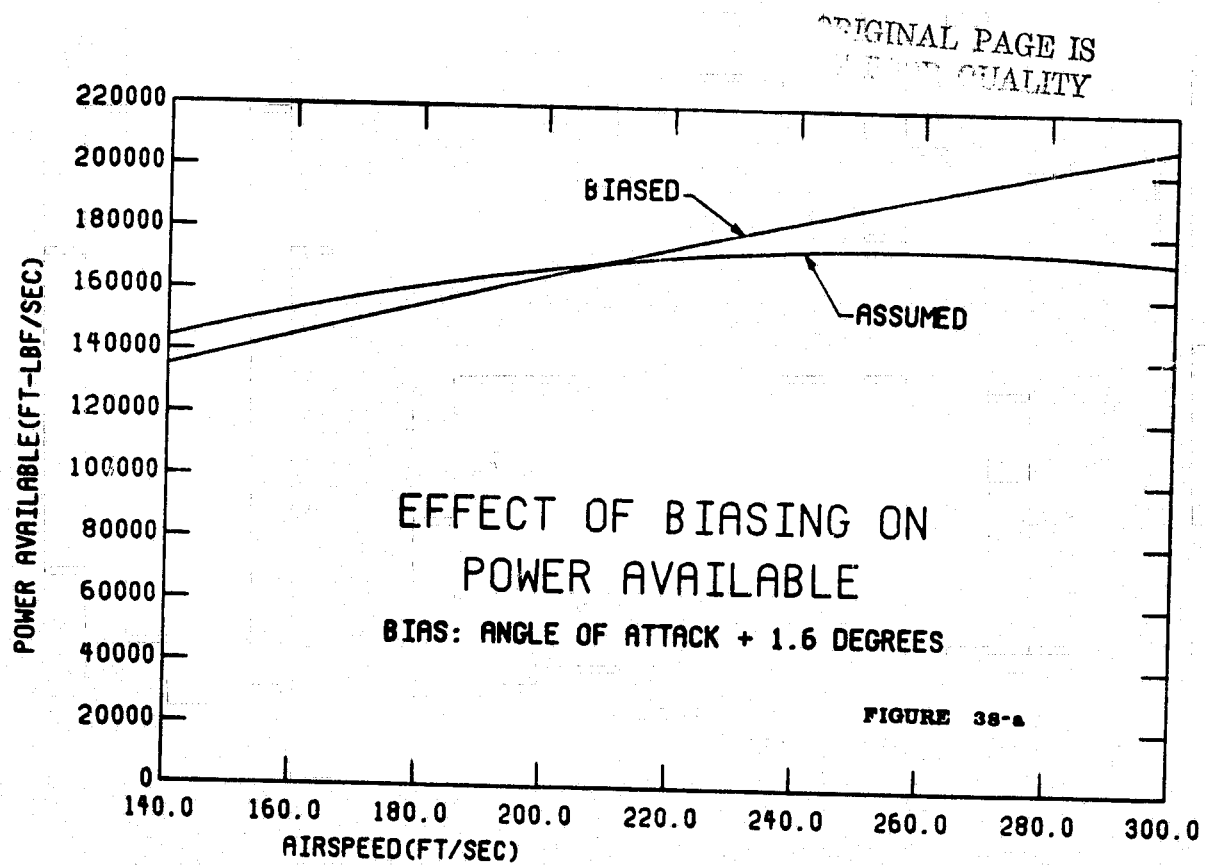




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Reduction of Noise at Signal Frequencies

The filtering technique discussed previously has been shown to be highly effective at suppressing noise components in the data at frequencies above the principal components of the aircraft response. There may, however, still be spurious contributions to the filtered signal from instrument biases, changes in instrument gains, and atmospheric turbulence at frequencies below this cutoff value. These contributions cannot be removed without employing additional information about the system. Since we do not know precisely the nature of these contributions, we will make some assumptions, based on our knowledge of the physics of the situation, to provide the required additional information. If we do this properly, we should be able to improve on the results produced by error-reduction techniques which assume the "noise" in each data channel to be "white" with a zero mean.

For reasons which will become evident later, we will assume that the filtered altitude and velocity data are correct as they stand. The other channels (α , θ , W , a_x , and $\dot{\theta}$), we can be reasonably confident, contain bias, gain, and various types of frequency-dependent errors to some degree.

In order to extract the coefficients of the power and drag models successfully, we have shown that we must have self-consistent data on which to operate. If any data channel contains spurious information, this severely limits our ability to extract the correct model with reasonable coefficient values. Thus, it is important that we take steps to assure, at the least, that our data set is self-consistent. We will therefore adopt a policy of modifying the filtered measured α , θ , and W data so that they form a consistent set with V and h . So long as these modifications are not excessive, say greater than 1% of the maximum data values, we can justify our changes by saying that the altered values still lie within the normal error bounds of the data*.

1. Reduction of Bias Error in α

We seek to modify α initially in order to remove significant bias errors. To this end we write equation (6) in the form

*

This is a somewhat different approach from those usually used to counter the extreme sensitivity of the least squares estimator to noisy data. Most investigators employ different, less sensitive identifiers (e.g., Newton-Raphson Maximum Likelihood, Gram, Kalman Filter, etc.) which may include provisions for treating certain types of random noise, but they do not modify the input data as such. According to a private communication from Dr. G. J. Dobeck of the Naval Coastal Systems Laboratory, Panama City, Florida, the best estimator for a particular problem depends upon the problem. Since the present problem is rather different from those usually described in the literature, it is not surprising that the more common procedures are not readily adapted to it. For the reader with a good mathematical background interested in a comparison of the characteristics of several of these identifiers, Dr. Dobeck's Ph.D. thesis at the University of South Florida, "System Identification and Application to Undersea Vehicles", is recommended.

$$S = \sum_{i=1}^N \left[\frac{W_i \dot{V}_i}{g} + W_i \sin(\theta_i - \alpha_i) - W_i \Delta\alpha \cos(\theta_i - \alpha_i) - \left(\frac{P_o}{V_i} + P_1 + P_2 V_i \right) \cos \alpha_i + \Delta\alpha \sin \alpha_i \left(\frac{P_o}{V_i} + P_1 + P_2 V_i \right) + \frac{\rho_i S V_i^2}{2} \left(C_{D_o} + C_{D_1} \alpha_i^2 + C_{D_2} \alpha_i^6 \right) + \frac{\rho_i S V_i^2}{2} \left(2\alpha_i \Delta\alpha C_{D_1} + 6\alpha_i^5 \Delta\alpha C_{D_2} \right) \right]^2 \quad (76)$$

where it has been assumed for the purposes of this analysis that $\cos \Delta\alpha = 1$, $\sin \Delta\alpha = \Delta\alpha$, and $(\alpha + \Delta\alpha)^6 = \alpha^6 + 6(\Delta\alpha)\alpha^5$. We then minimize S with respect to $\Delta\alpha$ to yield

$$\Delta\alpha = - \frac{\sum_{i=1}^N B_o B_1}{\sum_{i=1}^N B_o^2} \quad (77)$$

Here,

$$B_o = - W_i \cos(\theta_i - \alpha_i) + \sin \alpha_i \left(\frac{P_o}{V_i} + P_1 + P_2 V_i \right) + \frac{\rho_i S V_i^2}{2} \left[2\alpha_i C_{D_1} + 6\alpha_i^5 C_{D_2} \right] \quad (78)$$

and

$$B_1 = \frac{W_i \dot{V}_i}{g} + W_i \sin(\theta_i - \alpha_i) - \left[\frac{P_o}{V_i} + P_1 + P_2 V_i \right] \cos \alpha_i + \frac{\rho_i S V_i^2}{2} \left[C_{D_o} + C_{D_1} \alpha_i^2 + C_{D_2} \alpha_i^6 \right] \quad (79)$$

(This form will be the same for each of the 23 other models used to represent the data, only the values of B_0 and B_1 will be different.) The result of this computation is then the amount which must be added to α in order to minimize the fit error for the particular model employed. Since we are not certain that the model with the lowest fit error using degraded data is the best model when the data have been "treated", we will add only 2/3 of $\Delta\alpha$ to α , before we repeat the extraction process. The result, we then assume, is the smallest fit error which can be obtained by removing a bias from the α data.

2. Establishing the Probable Values of α and the Coefficients of the Lift Equation

Since the equation has been shown to be most sensitive to errors in α , we will endeavor to employ a procedure for establishing the proper range of α values which is not heavily dependent upon the value of α . We begin by choosing to fit the data in a least squares sense with the model

$$P = P_0 V^{1/3}$$

$$C_D = C_{D_0} + C_{D_1} \alpha + C_{D_2} \alpha^2 + C_{D_3} \alpha^3 + C_{D_4} \alpha^4. \quad (80)$$

This power model was selected on the basis of early full-scale wind tunnel test results as being a reasonably good representation of the actual power into the airstream. We recognize in addition that the equation relating forces and motions normal to the flight path can be written

$$\dot{\gamma} = \frac{gSV}{2W} C_L(\alpha) \rho(h) - \frac{g \cos \gamma}{V} + \frac{g P \sin \alpha}{WV^2}, \quad (81)$$

where $\rho(h) = \rho_0 (1 - 6.86 \times 10^{-6} h)^{4.26}, \quad (82)$

$$\gamma = \sin^{-1}(\dot{h}/V), \quad (83)$$

and
$$\dot{\gamma} = \frac{1}{\sqrt{1-(\dot{h}/V)^2}} \left[\frac{V\ddot{h} - \dot{h}\dot{V}}{V^2} \right]. \quad (84)$$

$\dot{h}$ is available as a consequence of the filtering operation and $\ddot{h}$ or, alternatively, $\dot{\gamma}$ can be obtained by spline fitting the $\dot{h}$ data or the computed values

of γ . Note that these equations involve only velocity and altitude (which we have already assumed to be noise-free) and their derivatives. In the interests of data consistency we have chosen to ignore the fact for the time being that γ is also $\theta - \alpha$.

Now (81) can be rearranged to represent C_L in the form

$$C_L = \frac{2W}{g \rho S V^2} \left[\dot{\gamma} + \frac{g \cos \gamma}{V} - \frac{g P \sin \alpha}{W V^2} \right]. \quad (85)$$

We know also that a reasonably accurate representation of the drag coefficient is

$$C_D = \bar{C}_{D_0} + \bar{C}_{D_1} C_L + \bar{C}_{D_2} C_L^2. \quad (86)$$

With this representation we will write equation (6) as

$$\frac{\dot{V}}{g} + \sin \gamma = \frac{\bar{P}_0 V^{1/3}}{W V} \cos \alpha - \frac{\rho S V^2}{2W} (\bar{C}_{D_1} + \bar{C}_{D_1} C_L + \bar{C}_{D_2} C_L^2). \quad (87)$$

With the power values obtained from (80) we solve for $C_L(t)$ from (85). Given these values, we find $\bar{P}_0$, $\bar{C}_{D_0}$, $\bar{C}_{D_1}$, and $\bar{C}_{D_2}$ from (87) in a least squares sense. Using the value of $\bar{P}_0$ found in this fashion, we reenter (85) and find a new value of $C_L(t)$. This is then used to extract new values of $\bar{P}_0$, $\bar{C}_{D_0}$, $\bar{C}_{D_1}$, and $\bar{C}_{D_2}$ from (87). The process is repeated until the change in the four coefficients from one iteration to the next is less than 0.001%.

As a result of the foregoing, we now have a reasonably reliable picture of $C_L(t)$. This we then fit to the bias-free α -data by a least-squares-distance routine (described in detail in NASA TN D-6374 and also in a later section of this report) using the following model:

$$\{C_{L_i} - CLQ[\dot{\theta}_i]\} = CLA_0 + CLA[\alpha_i] + CLAX[\alpha_i]^X. \quad (88)$$

Initially we assume $X = 2.0$ in order to solve for CLQ by a linear least squares method. With CLQ determined, we subtract the term $CLQ \cdot \dot{\theta}_i$ from C_{L_i} before we apply the least squares distance method to determine new values for the remaining coefficients*. We will assume that CLQ has this same value for the remainder of the data reduction procedures applied to a particular data set. The LSD routine determines the values of coefficients CLAO, CLA, CLAX, and X in this model which minimize the perpendicular distance from the curve represented by (88) to the data points.

We then adjust the values of α at every time point so that they satisfy (88) exactly. We employ for this purpose a second order Newton-Raphson procedure: If we call

$$f(\alpha_{i_k}) = (CLAX) \alpha_{i_k}^X + (CLA) \alpha_{i_k} + CLAO - \{C_{L_i} - CLQ[\dot{\theta}_i]\} \quad (89a)$$

$$f'(\alpha_{i_k}) = (X) \cdot (CLAX) \alpha_{i_k}^{X-1} + CLA \quad (89b)$$

$$f''(\alpha_{i_k}) = (X) \cdot (X-1) \cdot (CLAX) \alpha_{i_k}^{X-2}, \quad (89c)$$

where α_{i_k} is the bias-free value of the α -data at time point i , then the value of $\alpha_{i_{k+1}}$ closest to α_{i_k} which will make $f(\alpha_{i_{k+1}}) \rightarrow 0$ is given by

* We recognize that the values found for CLAO, CLA, CLAX, and X will vary somewhat as the center of gravity location - and to some extent the weight and altitude - is changed because they include a lift contribution arising from the elevator deflection required to attain trimmed flight. This lift contribution varies only with speed - hence α , if the weight and altitude are relatively constant. In maneuvering flight an additional elevator deflection (and thus an additional lift component) is necessary to induce rotation; this can be accounted for by a term proportional to $\dot{\theta}$ so that the α contribution found by the LSD method will then be virtually independent of rotational velocity. At a given c.g. location, initial weight, nominal altitude, and throttle position, the CLAO, CLA, CLAX, and X found by this approach should be the same whether the aircraft performs a level flight acceleration - deceleration or a pullup - pushover. The values of CLAO, CLA, CLAX, and X, however, may also depend upon throttle position because (a) the thrust axis may not intersect the c.g., (b) the lift distribution over the wing may be affected by the application of power, and (c) the flow field approaching the horizontal tail may be altered. For this reason the coefficient values should be determined at several different power settings, different altitudes, and different weights. One would also expect the drag coefficient values to be somewhat dependent upon power level.

$$\alpha_{i_{k+1}} = \alpha_{i_k} - \frac{f'(\alpha_{i_k})}{f''(\alpha_{i_k})} \pm \sqrt{\left[\frac{f'(\alpha_{i_k})}{f''(\alpha_{i_k})} \right]^2 - 2 \left[\frac{f(\alpha_{i_k})}{f''(\alpha_{i_k})} \right]} \quad (90)$$

The choice of signs on the radical is made according to the following rationale:

If $f'(\alpha_{i_k}) \cdot f''(\alpha_{i_k}) < 0$ use the negative sign on the radical.

If $f'(\alpha_{i_k}) \cdot f''(\alpha_{i_k}) > 0$ use the positive sign on the radical.

Occasionally,

$$\left[\frac{f'(\alpha_{i_k})}{f''(\alpha_{i_k})} \right]^2 - 2 \left[\frac{f(\alpha_{i_k})}{f''(\alpha_{i_k})} \right] < 0$$

because the radius of curvature of $f(\alpha_{i_k})$ at α_{i_k} no longer intersects the abscissa. When this happens, the computer cannot perform the operation. In such a circumstance the following procedure is suggested:

1. Choose as an initial estimate for $\alpha_{i_{k+1}}$

$$\alpha_{i_{k+1}} = \alpha_{i_k} - \frac{f'(\alpha_{i_k})}{f''(\alpha_{i_k})} \quad (91)$$

2. If $|f(\alpha_{i_{k+1}})| < |f(\alpha_{i_k})|$, then try (90) again.

3. If the radicand is again negative, try

$$\alpha_{i_{k+2}} = \alpha_{i_{k+1}} - \frac{f'(\alpha_{i_{k+1}})}{f''(\alpha_{i_{k+1}})} \quad (92)$$

and see if $|f(\alpha_{i_{k+2}})| < |f(\alpha_{i_{k+1}})|$. As long as

$|f(\alpha_{i_{k+n}})| < |f(\alpha_{i_{k+n-1}})|$, use either (90) or (91) as indicated.

4. Continue until either $|f(\alpha_{i_{k+n}})| < 10^{-15}$ or $|f'(\alpha_{i_{k+n}})| < 10^{-15}$.

In the former case the new root is found with sufficient accuracy. In the latter, a real root does not exist close to the starting point and we select the value of α for which $f(\alpha)$ approaches zero most closely. Note that the use of a least squares procedure does not guarantee that the coefficients chosen for any particular data point yield a root, only that the sum of $[f(\alpha_i)]^2$ is a minimum for the particular model used. Thus, an individual $f(\alpha_i)$ may be non-zero with no crossing of the abscissa for any α close to α_i .

With the revised set of α values given by the foregoing procedure, we now reenter the coefficient extraction routine, i.e., equation (6) or some alternate version thereof, with $\gamma = \theta - \alpha$ to find "updated" values of the P and C_D coefficients. We look, of course, for the model giving the lowest fit error. Its coefficients, along with the data, form the basis of our next step.

3. Modification of α -data to yield a more Consistent Data Set

In this step we seek to modify α slightly at each point in time by a different amount so as to (a) more nearly satisfy equation (81) at all times and (b) reduce the fit error obtained with equation (6). We begin by using the latest power data in (81) and solving for $C_i(t)$. With the least-squares-distance procedures we then update the values for $CLAO$, CLA , $CLAX$, and X . If we now substitute for α_i an "improved" value which is given by

$$\alpha_i + F \Delta \alpha_i,$$

where F is a factor permitting us to apply all or part of the correction during any particular iteration, and where $\Delta \alpha_i$ is defined* by

* $\Delta \alpha_i$ is the value by which α_i must be changed to satisfy (81) exactly. We could of course employ our Newton-Raphson procedure to determine it. We have chosen, however, to assume that $\Delta \alpha_i$ is very small and can be represented with satisfactory accuracy by one term in a binomial expansion.

$$\Delta \alpha_i = \frac{\dot{\gamma}_i + \frac{g}{V_i} \cos \gamma_i - \frac{g S p_i V_i}{2W_i} \left\{ \text{CLQ}(\dot{\theta}_i) + \text{CLAO} + \text{CLA}(\alpha_i) + \text{CLAX}(\alpha_i) \right\} - \frac{g P_i}{W_i V_i^2} \sin \alpha_i}{\frac{g S p_i V_i}{2W_i} \times \text{CLAX} \cdot \alpha_i + \text{CLA} + \frac{g P_i \cos \alpha_i}{W_i V_i^2}}, \quad (93)$$

Then the sum of the squares of the amount by which we fail to satisfy equation (81) at each time point (a quantity which we call S_2) should decrease.

We will usually take $F = 0.3$ on the first two iterations and 1.0 on subsequent iterations. Before we substitute $\alpha_i + F \Delta \alpha_i$ for α_i in equation

(6), however, we will update the θ -data so that it is more consistent with both γ and the revised α values. We assume for the present purpose that θ contains a gain error and a bias error which we will determine by fitting the θ -data with

$$\sin^{-1} \left[\frac{\dot{h}}{V} \right] + \alpha_i + F \Delta \alpha_i = A \theta_i + B \quad (94)$$

in order to determine A and B in a least squares sense. The new θ_i is simply $A \theta_{i \text{ old}} + B$. This value of θ plus the revised α value are then substituted into the appropriate version of equation (6) to extract the coefficient values. With new power coefficients from this extraction the cycle is repeated until the fit error, S , reaches a minimum, usually in two or three more iterations. This minimum is determined by comparing the fit error after each iteration with the fit error obtained for the previous iteration.

It will be observed that the power, computed using the coefficients obtained from the last extraction, is the principal mechanism by which $\Delta \alpha_i$ is modified in (93). It will also be observed that $\Delta \alpha_i$ is relatively

insensitive to very small changes in power. As a result, when the fit error for 300 points is less than about 10^{-10} , the $\Delta\alpha_i$ are generally 2×10^{-4} or less. These small modifications in α result in total power values which are very little different from those of the previous iteration. Hence, the reduction in fit error during the next iteration becomes miniscule. Some other means must therefore be employed to speed the reduction of the fit error to the desired range of 10^{-13} or less.

4. Modification of α -data by Trajectory Comparison

What we have as a result of the previous procedures is a set of lift, drag, and power coefficients obtained in a least squares manner from input V , h , and W data and modified α and θ data. We will now use the coefficient set and some assumptions regarding the accuracy of the input data to calculate the trajectory of the vehicle during the time in question. As the vehicle moves along its trajectory in the terrestrial X-Z plane, its position in space and its orientation may be described by a set of time histories. These time histories are the solutions of the system of equations (6), (81), (82), and (83) plus the relationship

$$\dot{W} = -cP \quad (95)$$

where c is the specific fuel consumption. Examination of the system will show that two of the 5 time histories must be specified a priori in order to obtain a unique solution. As we have indicated, we choose to assume that V and h and their derivatives may be considered to be accurate and noise-free. As a result we may readily develop the following time histories:

$$\begin{array}{lll} V(t) & h(t) & \rho(t) \\ \dot{V}(t) & \dot{h}(t) & \gamma(t) \\ \ddot{V}(t) & \ddot{h}(t) & \dot{\gamma}(t). \end{array} \quad (96)$$

If we now combine equations (6) and (81) to yield

$$\frac{\dot{\gamma}_i}{g} + \frac{\cos \gamma_i}{V_i} = \frac{\rho_i S V_i}{2W_i} C_{L_i} + \frac{\tan \alpha_i}{V_i} \left[\frac{\dot{V}_i}{g} + \sin \gamma_i + \frac{\rho_i S V_i^2}{2W_i} C_{D_i} \right] \quad (97)$$

we observe that as a consequence of (96) only $\alpha(t)$ and $W(t)$ are unknown in (97). But (95) can be written

$$\begin{aligned}
 W_{i+1} = W_i - c[P_0 + P_1 \dot{V}_i + P_2 \dot{V}_i^2] \Delta t - c \left(\frac{\Delta t}{2}\right)^2 [P_1 \ddot{V}_i + 2P_2 \dot{V}_i \ddot{V}_i] \\
 - c \left(\frac{\Delta t}{6}\right)^3 [P_1 \ddot{V}_i + 2P_2 (\dot{V}_i^2 + V_i \ddot{V}_i)] .
 \end{aligned} \tag{98}$$

This permits us to determine $W(t)$ given its initial value. With the results of (98) substituted into (97), we may solve (97) at each time point for α_i using the second order Newton-Raphson scheme. Thus, we can determine the $\alpha(t)$ which is compatible with any particular set of C_L , C_D , and P coefficients and the time histories given by (96).

$\alpha(t)$ found in this manner will not be the same as that found from step 3 above. We desire to modify the α -data resulting from step 3 so that it will be somewhat closer to that given by the trajectory computation. At the same time we wish to modify the C_L , C_D , and P coefficients so that they will yield an α -trajectory closer to the $\alpha(t)$ resulting from step 3. We begin as follows. If we call α_{m_i} the value of α_i resulting from step 3 and α_{t_i} the result of the trajectory calculation, then the result we seek is to minimize

$$J = \sum_{i=1}^N [(\alpha_{m_i} - \alpha_{t_i})^2] . \tag{99}$$

This will occur when $\frac{\partial J}{\partial C_{D_0}}, \frac{\partial J}{\partial C_{D_1}}, \frac{\partial J}{\partial C_{D_2}}, \dots, \frac{\partial J}{\partial CLAX} = 0$.

In order to minimize J with respect to all eight C_D and C_L coefficients simultaneously, we observe that a first order Taylor series expansion for $\frac{\partial J}{\partial C_{D_0}}$ in terms of the eight coefficients may be written

$$\begin{aligned}
 \left[\frac{\partial J}{\partial C_{D_0}} \right]_{k+1} &= \left[\frac{\partial J}{\partial C_{D_0}} \right]_k + \frac{\partial}{\partial C_{D_0}} \left[\frac{\partial J}{\partial C_{D_0}} \right] (C_{D_0_{k+1}} - C_{D_0_k}) + \frac{\partial}{\partial C_{D_1}} \left[\frac{\partial J}{\partial C_{D_0}} \right] (C_{D_1_{k+1}} - C_{D_1_k}) \\
 &\quad + \frac{\partial}{\partial C_{D_2}} \left[\frac{\partial J}{\partial C_{D_0}} \right] (C_{D_2_{k+1}} - C_{D_2_k}) + \dots \\
 \text{or } \left[\frac{\partial J}{\partial C_{D_0}} \right]_{k+1} &= \left[\frac{\partial J}{\partial C_{D_0}} \right]_k + \sum_{\ell=1}^8 \frac{\partial}{\partial C_{\ell}} \left[\frac{\partial J}{\partial C_{D_0}} \right] (C_{\ell_{k+1}} - C_{\ell_k})
 \end{aligned} \tag{100}$$

where $C_1 = C_{D_0}$, $C_2 = C_{D_1}$, $C_3 = C_{D_2}$, ...,

$$\frac{\partial J}{\partial C_{D_0}} = 2 \sum_{i=1}^N \left[(\alpha_{m_i} - \alpha_{+i}) \frac{\partial \alpha_{+i}}{\partial C_{D_0}} \right], \quad (101)$$

$$\text{and } \frac{\partial}{\partial C_\ell} \left(\frac{\partial J}{\partial C_{D_0}} \right) = 2 \sum_{i=1}^N \left[(\alpha_{m_i} - \alpha_{+i}) \frac{\partial^2 \alpha_{+i}}{\partial C_{D_0} \partial C_\ell} - \left(\frac{\partial \alpha_{+i}}{\partial C_{D_0}} \right) \left(\frac{\partial \alpha_{+i}}{\partial C_\ell} \right) \right]. \quad (102)$$

We will assume that we can neglect $(\alpha_{m_i} - \alpha_{+i}) \frac{\partial^2 \alpha_{+i}}{\partial C_{D_0} \partial C_\ell}$ in comparison to the other term in (102). Such a step will not affect the final answer, only the rate of convergence. In this particular instance the $\frac{\partial \alpha_{+i}}{\partial C_\ell}$ must be evaluated numerically although, where possible, it is desirable to do this analytically. The value of the derivative at a particular time point is found by determining the change in α_{+i} produced by small changes (1%) to either side of the original value of C_ℓ in (97). All other C_ℓ 's are held constant during the process.

When $C_{\ell_{k+1}}$ have the proper values, all the $\left(\frac{\partial J}{\partial C_\ell} \right)_{k+1} = 0$. This fact permits us to write a system of eight linear equations,

$$\left(\frac{\partial J}{\partial C_{D_0}} \right)_k + \sum_{\ell=1}^8 \left[\frac{\partial}{\partial C_\ell} \left(\frac{\partial J}{\partial C_{D_0}} \right)_k (C_{\ell_{k+1}} - C_{\ell_k}) \right] = 0, \quad (103)$$

$$\left(\frac{\partial J}{\partial CLAX} \right)_k + \sum_{\ell=1}^8 \left[\frac{\partial}{\partial C_\ell} \left(\frac{\partial J}{\partial CLAX} \right)_k (C_{\ell_{k+1}} - C_{\ell_k}) \right] = 0,$$

which we must solve for the eight new values of $C_{\ell_{k+1}}$. Although we may not actually wish to obtain the solutions in this fashion, we can find them from

$$C_{\ell_{k+1}} = C_{\ell_k} + \{A\}^{-1} \{B\}^* , \quad (104)$$

where $\{A\} =$

$$\begin{bmatrix} 2 \sum_{i=1}^N \frac{\partial \alpha_{+i}}{\partial C_{D_0}} \frac{\partial \alpha_{+i}}{\partial C_{D_0}} & \dots & 2 \sum_{i=1}^N \frac{\partial \alpha_{+i}}{\partial C_{D_0}} \frac{\partial \alpha_{+i}}{\partial CLAX} \\ \vdots & & \vdots \\ 2 \sum_{i=1}^N \frac{\partial \alpha_{+i}}{\partial CLAX} \frac{\partial \alpha_{+i}}{\partial C_{D_0}} & \dots & 2 \sum_{i=1}^N \frac{\partial \alpha_{+i}}{\partial CLAX} \frac{\partial \alpha_{+i}}{\partial CLAX} \end{bmatrix} \quad (105)$$

$$\{B\} = \begin{bmatrix} 2 \sum_{i=1}^N (\alpha_{m_i} - \alpha_{+i}) \frac{\partial \alpha_{+i}}{\partial C_{D_0}} \\ \vdots \\ 2 \sum_{i=1}^N (\alpha_{m_i} - \alpha_{+i}) \frac{\partial \alpha_{+i}}{\partial CLAX} \end{bmatrix} . \quad (106)$$

(104) is in effect a generalized first order Newton-Raphson procedure.

With the $C_{\ell_{k+1}}$ values substituted into (97) we determine a new trajectory. We call the α values for this new trajectory $\bar{\alpha}_{+i}$. We then define

$$\bar{\alpha}_{m_i} = \alpha_{m_i} + 0.5 (\bar{\alpha}_{+i} - \alpha_{m_i}) \quad (107)$$

* The A matrix in this formulation may, for some sets of physical data, be rather ill-conditioned. As a result, the values of $C_{\ell_{k+1}}$ obtained by various solution techniques may all be substantially in error as well as different. The user should therefore employ the actual technique presented in subsequent sections of this report with care until the reasonableness of the solutions is apparent.

and $\theta_i = \gamma_i + \bar{\alpha}_{m_i}$. With these values plus the measured values of V_i , $\dot{V}_i$, p_i , $\dot{\gamma}_i$, and W_i , we enter the coefficient extraction routine and the C_L vs. α curve fit procedure to obtain new power, drag, and lift coefficients and to check the resulting fit error.

Prior to beginning another iteration of this process with the latest C_L and C_D coefficients, we update our value for the specific fuel consumption, c , in the following fashion:

$$c = \frac{1}{N-1} \sum_{j=1}^{N-1} \left(\frac{W_{j+1} - W_j}{P_j} \right) \quad (108)$$

Here, W_j are the input values of the weight and P_j are the values of the power computed using the latest power coefficient.

By repeating the foregoing trajectory comparison with the updated value of $\bar{\alpha}_{m_i}$ two or three times, we arrive at a situation where both the α values and the fit errors have improved. By this time, however, $(\bar{\alpha}_{m_i} - \bar{\alpha}_{t_i}) \rightarrow 0$, so that no further improvement is possible with this approach.

It will be evident after a short reflection that if a negative C_{D1} is obtained during a coefficient extraction, the implication is that α for zero lift is positive. This is a condition the designer of the aircraft will usually avoid if he is aware of it because it leads inherently to high cruise drag with conventional quasi-symmetric fuselages. Thus, if the minimum fit error model contains a C_{D1} which, as a result of the least squares curve fit procedure, yields a negative value, one would appear to be justified on physical grounds in using as the basis for further operations the most similar model having C_{D1} and $C_{D3} \equiv 0$. This is a procedure we will usually follow in applying the foregoing trajectory comparison to reduce the noise in the α -channel.

It is necessary to point out, however, that light aircraft fuselages tend to be very non-symmetric about their x-y planes. It is possible, because of this asymmetry, that the minimum fuselage drag does not occur when the relative wind is parallel to the x-body axis. If the existence of this condition is suspected for the aircraft under test, the negative value for C_{D1} must be accepted.

The benefit obtained from the α -trajectory comparison described in this section and the preceding three noise-reduction steps has been to reduce the noise in the α and θ channels and improve the overall data consistency to the point that the extracted coefficients are usually sufficiently close to the "correct" values that they can form a useful starting set for the application of a Newton-Raphson identifier.

Application of Newton-Raphson Identifier

The Newton-Raphson Identifier as employed by Taylor and Iliff (Ref. 15) and others is a means of finding the values of unknown coefficients in the equations of motion which tend to minimize the squares of differences

between the measured time histories of aircraft state parameters and computed solutions to the equations of motion involving the same parameters. It is assumed that the solutions change linearly with a change in coefficient value. Furthermore, since the equations of motion used by Iliff and Taylor are linear first-order differential equations, the solutions are readily determined and the "cost function" minimization procedure can be joined with the solution procedure without undue difficulty. When forming the cost function it is desirable to include as many independent differences between measurement and computation as possible, since the more closely the number of differences approaches the number of unknowns in the problem, the more determinant it is, i.e., the more likely the procedure is to give reasonable coefficient values.

The present problem differs from that of Iliff and Taylor in that the equations of motion are non-linear. The solution procedure is therefore quite different, much more complex, and must be carried out independently of the minimization. The minimization yields a linearized approximation to the change in the coefficient values needed to minimize the difference between the flight time histories and the computed values of the same states. In the limit as the differences approach zero, the linearized approximations approach the exact values. Another significant difference from the Iliff and Taylor approach is that the present equations of motion have no specific forcing function(s). As noted above, any two states which are known a priori may serve this purpose. We have chosen to use the true airspeed along the flight path as the principle forcing function. Since the power into the airstream is specified as a function of true airspeed in our formulation of the problem, the power at any time is known if the coefficients in the power-velocity model are given. We use as initial coefficient values for this model those obtained from the previous noise-reduction procedure.[†] With the power and velocity specified as functions of time, it is then possible to determine a unique trajectory. The procedure is as follows:

1. Determine the weight at t_{j+1} from

$$\begin{aligned} W_{j+1} = & W_j - c\Delta t(P_0 + P_1 V_j + P_2 V_j^2) - c \frac{\Delta t^2}{2} (P_1 \dot{V}_j + 2P_2 V_j \dot{V}_j) \\ & - c \frac{\Delta t^3}{6} (P_1 \ddot{V}_j + 2P_2 \dot{V}_j^2 + 2P_2 V_j \ddot{V}_j) \\ & - c \frac{\Delta t^4}{24} (P_1 \dddot{V}_j + 6P_2 \dot{V}_j \ddot{V}_j + 2P_2 V_j \ddot{V}_j) \end{aligned} \quad (109)$$

$W_{j=1}$ = weight at beginning of maneuver (from test data)

V_j is specified

$\dot{V}_j, \ddot{V}_j, \ddot{V}_j$ are computed by the method of splines from $V_j, \dot{V}_j$, and $\ddot{V}_j$

[†] It is well known that the rate of convergence of the Newton-Raphson procedure decreases as the error in the estimated values of the coefficients increases. Thus it is desirable to begin the procedure with values as close to the "correct" values as one can reasonably manage.

2. $\gamma_{j=1}$ is determined from $\sin^{-1}(\dot{h}_1/V_1)$ since h_1 and $\dot{h}_1$ are available from the measured data. $\rho_{j=1}$ is determined from

$$\rho_{j=1} = \rho_0 (1 - 6.86 \times 10^{-6} h_{j=1})^{4.26} . \quad (110)$$

3. α_j is found from

$$\frac{\dot{\gamma}_j}{g} + \sin \gamma_j = \frac{(P_0 + P_1 V_j + P_2 V_j^2) \cos \alpha_j}{W_j V_j} - \frac{\rho_j S V_j^2}{2W_j} [C_{D_0} + C_{D_2} \alpha_j^2 + C_{D_4} \alpha_j^4] \quad (111)$$

by the second-order Newton-Raphson technique.

4. $\dot{\gamma}_j$ is given by

$$\dot{\gamma}_j = \frac{g \rho_j S V_j C_L(\alpha_j)}{2W_j} + \frac{g(P_0 + P_1 V_j + P_2 V_j^2) \sin \alpha_j}{W_j V_j^2} - \frac{g \cos \gamma_j}{V_j} . \quad (112)$$

5. γ_{j+1} is determined by forward integration of (112) using the following scheme:

- With the Runge-Kutta method, determine γ for the first 8 points of the data set.
- With γ , α , w , and ρ known at these points, one can then find $\dot{\gamma}$ at the eight points through (112).
- Represent $\dot{\gamma}(t)$ over the last six points of the interval by a fifth-order polynomial using Newton's interpolation formula:

$$\begin{aligned} \dot{\gamma}(t) = & a_0 + a_1(t - t_{j-5}) + a_2(t - t_{j-5})(t - t_{j-4}) + a_3(t - t_{j-5}) \\ & \cdot (t - t_{j-4})(t - t_{j-3}) + a_4(t - t_{j-5})(t - t_{j-4})(t - t_{j-3})(t - t_{j-2}) \\ & + a_5(t - t_{j-5})(t - t_{j-4})(t - t_{j-3})(t - t_{j-2})(t - t_{j-1}) , \end{aligned} \quad (113a)$$

where $a_0 = \dot{\gamma}_{j-5}$

$$a_1 = \frac{\dot{\gamma}_{j-4} - \dot{\gamma}_{j-5}}{t_{j-4} - t_{j-5}}$$

$$a_2 = [\dot{\gamma}_{j-3} - (a_0 + a_1 \{t_{j-3} - t_{j-5}\})] / [(t_{j-3} - t_{j-5})(t_{j-3} - t_{j-4})]$$

$$a_3 = [\dot{\gamma}_{j-2} - (a_0 + a_1 \{t_{j-2} - t_{j-5}\} + a_2 \{t_{j-2} - t_{j-5}\} \{t_{j-2} - t_{j-4}\})] \\ \div [(t_{j-2} - t_{j-5})(t_{j-2} - t_{j-4})(t_{j-2} - t_{j-3})]$$

$$a_4 = [\dot{\gamma}_{j-1} - (a_0 + a_1 \{t_{j-1} - t_{j-5}\} + a_2 \{t_{j-1} - t_{j-5}\} \{t_{j-1} - t_{j-4}\} \\ + a_3 \{t_{j-1} - t_{j-5}\} \{t_{j-1} - t_{j-4}\} \{t_{j-1} - t_{j-3}\})] / [(t_{j-1} - t_{j-5}) \\ \cdot (t_{j-1} - t_{j-4})(t_{j-1} - t_{j-3})(t_{j-1} - t_{j-2})]$$

$$a_5 = [\dot{\gamma}_j - (a_0 + a_1 \{t_j - t_{j-5}\} + a_2 \{t_j - t_{j-5}\} \{t_j - t_{j-4}\} \\ + a_3 \{t_j - t_{j-5}\} \{t_j - t_{j-4}\} \{t_j - t_{j-3}\} + a_4 \{t_j - t_{j-5}\} \{t_j - t_{j-4}\} \\ \cdot (t_j - t_{j-3})(t_j - t_{j-2})] / [(t_j - t_{j-5})(t_j - t_{j-4})(t_j - t_{j-3}) \\ \cdot (t_j - t_{j-2})(t_j - t_{j-1})].$$

- d. Extrapolate the formula to t_{j+1} . This is done simply by letting $t \leq t_{j+1}$.
- e. Integrate the extrapolated formula term-by-term analytically and evaluate the result between the limits t_{j-5} and t_{j+1} :

$$\hat{\gamma}_{j+1} = \gamma_{j-5} + \int_{t_{j-5}}^{t_{j+1}} \dot{\gamma} dt$$

$$\text{or } \hat{\gamma}_{j+1} = \gamma_{j-5} + \dot{\gamma}_{j-5} (t_{j+1} - t_{j-5}) + \frac{\ddot{\gamma}_{j-4} - \ddot{\gamma}_{j-5}}{t_{j-4} - t_{j-5}} \left[\frac{1}{2} (t_{j+1}^2 - t_{j-5}^2) - t_{j-5} (t_{j+1} - t_{j-5}) \right] + \dots \quad (113b)$$

At each step we then subtract t_{j-5} from all time values in order to extend the formula's range.

f. Estimate ρ_{j+1} from

$$\hat{\rho}_{j+1} = \rho_j + 4.26\rho_o (1 - 6.86 \times 10^{-6} h_j)^{3.26} (-6.86 \times 10^{-6}) v_j \sin \gamma_j \Delta t \quad (114a)$$

and α_{j+1} initially from

$$\hat{\alpha}_{j+1} = \alpha_j + 0.25 \left[\frac{\alpha_j - \alpha_{j-1}}{t_j - t_{j-1}} \right] \Delta t \quad (114b)$$

with corrections which are determined by comparing the value of γ_{j+1} from (113b) using the $\hat{\rho}_{j+1}$ and $\hat{\alpha}_{j+1}$ with the value of γ_{j+1} from (111) using the same ρ and α values. Then

$$(\hat{\alpha}_{j+1})_{k+1} = (\hat{\alpha}_{j+1})_k + \frac{(\Delta \gamma_{j+1})_k}{\left[\left(\frac{\partial \gamma}{\partial \alpha} \right)_{j+1} \right]_k}, \quad (115a)$$

$$\text{where } \frac{\partial \gamma}{\partial \alpha} = \frac{-(P \sin \hat{\alpha}/wv) - \frac{\rho s v^2}{2w} [2\hat{\alpha} C_{D_2} + 6C_{D_4} \hat{\alpha}^5]}{\sqrt{1 - \left(\frac{P \cos \hat{\alpha}}{wv} - \frac{\rho s v^2}{2w} C_D - \frac{\dot{v}}{g} \right)^2}} \quad (115b)$$

These k iterations are continued until $\Delta \gamma_{j+1} < 10^{-13}$. As a result, γ_{j+1} computed by the predictor equation (113b) is compatible with the other variable values to a high degree.

g. Determine $\hat{\gamma}_{j+1}$ from (112) using the latest predicted values of $\hat{\gamma}_{j+1}$, $\hat{\rho}_{j+1}$, and $\hat{\alpha}_{j+1}$. Calculate a corrected value for γ_{j+1} from

$$\gamma_{j+1} = \gamma_{j-5} + \int_{t_{j-5}}^{t_{j+1}} \dot{\gamma} dt \quad (116a)$$

where now

$$\begin{aligned} \dot{\gamma} = & -P(\gamma - \gamma_{j-5}) + A + B(t - t_{j-5}) + C(t - t_{j-5})^2 + D(t - t_{j-5})^3 \\ & + E(t - t_{j-5})^4 + F(t - t_{j-5})^5 \end{aligned} \quad (116b)$$

if $P > 10^{-2}$. In this equation, an extension of the procedure described by Smith in Ref. 2,

$$P = - \left[\frac{-\dot{\gamma}_{j+1} + 6\dot{\gamma}_j - 15\dot{\gamma}_{j-1} + 20\dot{\gamma}_{j-2} - 15\dot{\gamma}_{j-3} + 6\dot{\gamma}_{j-4} - \dot{\gamma}_{j-5}}{-\gamma_{j+1} + 6\gamma_j - 15\gamma_{j-1} + 20\gamma_{j-2} - 15\gamma_{j-3} + 6\gamma_{j-4} - \gamma_{j-5}} \right]$$

$$A = \dot{\gamma}_{j-5}$$

$$B = \left(\frac{12\dot{\gamma}_j - 75\dot{\gamma}_{j-1} + 200\dot{\gamma}_{j-2} - 300\dot{\gamma}_{j-3} + 300\dot{\gamma}_{j-4} - 137\dot{\gamma}_{j-5}}{60(t_{j-4} - t_{j-5})} \right)$$

$$+ P \left(\frac{12\gamma_j - 75\gamma_{j-1} + 200\gamma_{j-2} - 300\gamma_{j-3} + 300\gamma_{j-4} - 137\gamma_{j-5}}{60(t_{j-4} - t_{j-5})} \right)$$

$$C = \left(\frac{-10\dot{\gamma}_j + 61\dot{\gamma}_{j-1} - 156\dot{\gamma}_{j-2} + 214\dot{\gamma}_{j-3} - 154\dot{\gamma}_{j-4} + 45\dot{\gamma}_{j-5}}{24(t_{j-4} - t_{j-5})^2} \right)$$

$$+ P \left(\frac{-10\gamma_j + 61\gamma_{j-1} - 156\gamma_{j-2} + 214\gamma_{j-3} - 154\gamma_{j-4} + 45\gamma_{j-5}}{24(t_{j-4} - t_{j-5})^2} \right)$$

$$D = \left(\frac{7\dot{\gamma}_j - 41\dot{\gamma}_{j-1} + 98\dot{\gamma}_{j-2} - 118\dot{\gamma}_{j-3} + 71\dot{\gamma}_{j-4} - 17\dot{\gamma}_{j-5}}{24(t_{j-4} - t_{j-5})^3} \right)$$

$$+ P \left(\frac{7\gamma_j - 41\gamma_{j-1} + 98\gamma_{j-2} - 118\gamma_{j-3} + 71\gamma_{j-4} - 17\gamma_{j-5}}{24(t_{j-4} - t_{j-5})^3} \right)$$

$$\begin{aligned}
E &= \left(\frac{-2\dot{\gamma}_j + 11\dot{\gamma}_{j-1} - 24\dot{\gamma}_{j-2} + 26\dot{\gamma}_{j-3} - 14\dot{\gamma}_{j-4} + 3\dot{\gamma}_{j-5}}{24(\tau_{j-4} - \tau_{j-5})^4} \right) \\
&+ P \left(\frac{-2\gamma_j + 11\gamma_{j-1} - 24\gamma_{j-2} + 26\gamma_{j-3} - 14\gamma_{j-4} + 3\gamma_{j-5}}{24(\tau_{j-4} - \tau_{j-5})^4} \right) \\
F &= \left(\frac{\dot{\gamma}_j - 5\dot{\gamma}_{j-1} + 10\dot{\gamma}_{j-2} - 10\dot{\gamma}_{j-3} + 5\dot{\gamma}_{j-4} - \dot{\gamma}_{j-5}}{120(\tau_{j-4} - \tau_{j-5})^5} \right) \\
&+ P \left(\frac{\gamma_j - 5\gamma_{j-1} + 10\gamma_{j-2} - 10\gamma_{j-3} + 5\gamma_{j-4} - \gamma_{j-5}}{120(\tau_{j-4} - \tau_{j-5})^5} \right) \quad (116c)
\end{aligned}$$

for the case in which the time intervals are even. For uneven time intervals, the expressions are much more complex.

If $P \leq 10^{-2}$, we represent $\dot{\gamma}$ in (116a) by (113a) plus the term

$$a_6(\tau - \tau_{j-5})(\tau - \tau_{j-4})(\tau - \tau_{j-3})(\tau - \tau_{j-2})(\tau - \tau_{j-1})(\tau - \tau_j) \quad (116d)$$

$$\begin{aligned}
\text{where } a_6 &= [\hat{\gamma}_{j+1} - (a_0 + a_1\{\tau_{j+1} - \tau_{j-5}\} + a_2(\tau_{j+1} - \tau_{j-5})(\tau_{j+1} - \tau_{j-4}) \\
&+ a_3(\tau_{j+1} - \tau_{j-5})(\tau_{j+1} - \tau_{j-4})(\tau_{j+1} - \tau_{j-3}) + a_4(\tau_{j+1} - \tau_{j-5}) \\
&\cdot (\tau_{j+1} - \tau_{j-4})(\tau_{j+1} - \tau_{j-3})(\tau_{j+1} - \tau_{j-2}) + a_5(\tau_{j+1} - \tau_{j-5}) \\
&\cdot (\tau_{j+1} - \tau_{j-4})(\tau_{j+1} - \tau_{j-3})(\tau_{j+1} - \tau_{j-2}) \\
&\cdot (\tau_{j+1} - \tau_{j-1}))]/[(\tau_{j+1} - \tau_{j-5})(\tau_{j+1} - \tau_{j-4})(\tau_{j+1} - \tau_{j-3}) \\
&\cdot (\tau_{j+1} - \tau_{j-2})(\tau_{j+1} - \tau_{j-1})(\tau_{j+1} - \tau_j)] \quad (116e)
\end{aligned}$$

The $\dot{\gamma}_{j+1}$ in (116c) or (116e) is obtained from the predictor equation (113b). Its use in the corrector equation (116a) gives us the final, updated value of γ_{j+1} . Despite the attention to accuracy evidenced by the use of this procedure, the very "stiff" nature of (112), the fact that the Taylor expansion for h (see below) is truncated at four terms, and the fact that with any forward integration scheme the errors accumulate as one marches along, require that the step size be kept relatively small (0.01 sec. or less) if the desired accuracy (errors no larger than 1 part in 10^6 for a 30 second trajectory) is to be maintained. As a result, run times per iteration will be on the order of 4 minutes on an IBM 370/165.

6. h_{j+1} is found from

$$\begin{aligned} h_{j+1} = & h_j + (V_j \sin \gamma_j) \Delta t + (\dot{V}_j \sin \gamma_j + V_j \dot{\gamma}_j \cos \gamma_j) \frac{\Delta t^2}{2} \\ & + (\ddot{V}_j \sin \gamma_j + \dot{V}_j \dot{\gamma}_j \cos \gamma_j + V_j \ddot{\gamma}_j \cos \gamma_j - V_j \dot{\gamma}_j^2 \sin \gamma_j) \frac{\Delta t^3}{6} \\ & + \left[(\ddot{V}_j - 2\dot{V}_j \dot{\gamma}_j^2 - 3V_j \dot{\gamma}_j \ddot{\gamma}_j) \sin \gamma_j + (2\ddot{V}_j \dot{\gamma}_j + 2\dot{V}_j \ddot{\gamma}_j + V_j \ddot{\gamma}_j^2 - V_j \dot{\gamma}_j^3) \cos \gamma_j \right] \frac{\Delta t^4}{24}^* \end{aligned} \quad (117)$$

and ρ_{j+1} from h_{j+1} . $\ddot{\gamma}$ and $\ddot{\gamma}$ are found by differentiating (113a) and (116d) analytically. (118)

7. With ρ_{j+1} and γ_{j+1} known, α_{j+1} is determined by the Newton-Raphson technique from (111).

All of the variable values at t_{j+1} have now been determined. The process is then repeated to find the variable values at t_{j+2} and so on to t_N .

* A four term expansion is used because to employ additional terms would require data which are not readily available. High accuracy in the representation of the altitude can therefore be maintained only by using a relatively small step size.

The determination of $h(t)$, $\alpha(t)$, $p(t)$, $\gamma(t)$, $\dot{\gamma}(t)$, and $W(t)$ by this integration procedure provides the raw material from which one can form and evaluate a cost function. It will be recalled that we have assumed the measured values of V and h and their derivatives to be correct. We can, as a result, form the following "measured" variables:

$$h_{m_i},$$

$$\gamma_{m_i} = \sin^{-1} \left(\frac{\dot{h}_{m_i}}{V_{m_i}} \right),$$

$$\dot{\gamma}_{m_i} = \frac{1}{\sqrt{1 - \left(\frac{\dot{h}_{m_i}}{V_{m_i}} \right)^2}} \left[\frac{\ddot{h}_{m_i}}{V_{m_i}} - \frac{\dot{h}_{m_i} \dot{V}_{m_i}}{V_{m_i}^2} \right], \quad (119)$$

and

$$E_{m_i} = h_{m_i} + \frac{V_{m_i}^2}{2g},$$

all of which may be compared with values computed along the trajectory. Furthermore, the variation of each of these variables with each of the power, lift, and drag coefficients can be evaluated analytically* for each time point.

We can also develop two additional comparisons if we are willing to make some assumptions regarding the quality and character of the flight data. We will develop a "measured" weight time history by fitting a fourth-order polynomial to the computed values of W_i . At W_1 and W_N , however, the experimental values weighted by N^3 are used in the least squares curve fit routine. The partial derivatives of W_{+i} with respect to the power coefficients can, of course, be readily evaluated analytically.

If we now assume that the filtered value of $\dot{\theta}$ has an accuracy roughly comparable to that of V and h , then we can take as the "measured" value of α

* An analytical evaluation is both faster and more accurate than a numerical one.

$$\alpha_{m_i} = \int_{t_1}^{t_i} \dot{\theta}_{m_i} dt + \theta_1 - \sin^{-1} \left[\frac{\dot{h}_{m_i}}{V_{m_i}} \right] \quad (120)$$

In this case the partial derivatives of α_{t_i} with respect to the lift and drag coefficients must be evaluated numerically by the Newton-Raphson procedure. The partials of α_{t_i} with respect to the power coefficients are taken to be zero. Alternately, the measured values of α may be used in place of those computed by (120) if α is known to be accurate. These procedures permit us to form the following cost function:

$$J_2 = \sum_{i=1}^N \left[D_1 (h_{m_i} - h_{t_i})^2 + D_2 (\gamma_{m_i} - \gamma_{t_i})^2 + D_3 (\dot{\gamma}_{m_i} - \dot{\gamma}_{t_i})^2 + D_4 (w_{m_i} - w_{t_i})^2 + D_5 (E_{m_i} - E_{t_i})^2 + D_6 (\alpha_{m_i} - \alpha_{t_i})^2 \right], \quad (121)$$

where the D's are weights which may be applied to the various differences. If, for example, α_m is not regarded highly, its weight, D_6 , may be taken to be very small compared with the other weights. We may then proceed as before to determine the changes in the 13 (possible) coefficients which tend to minimize J_2 by minimizing $(h_{m_i} - h_{t_i})$, etc.* With the new coefficient values we then proceed to calculate a new trajectory, find a new value for the cost function, develop new coefficient values, and so on, until $J_2 < 10^{-13}$ or is as small as it will get.

In order to add the various constituent items of the cost function (121) properly, it is desirable that each item be dimensionless, else one is placed in the position of adding feet to pounds, a situation whose result is somewhat difficult to interpret. We choose, therefore, to expand our concept of weights in (121) and write

* Again, some care must be exercised in solving the system of 13 equations for the 13 new coefficient values because the state space, being nearly flat, leads inevitably to a relatively ill-conditioned matrix. The technique described with the program user instructions later in this report was found, after some experimentation, to be effective with a limited number of test cases. It may not be as effective in all cases, however.

$$D_1 = \frac{d_1}{h_{\max}^2}$$

$$D_4 = \frac{d_4}{W_{\max}^2}$$

$$D_2 = \frac{d_2}{\gamma_{\max}^2}$$

$$D_5 = \frac{d_5}{E_{\max}^2}$$

$$D_3 = \frac{d_3}{\gamma_{\max}^2}$$

$$D_6 = \frac{d_6}{\alpha_{\max}^2},$$

(122)

where the lower case d's are now dimensionless numbers which can serve the purpose of altering the importance of the variables with respect to one another. Normally, we take the d's = 1.0.

Additionally, we note the importance of updating, by (108), the specific fuel consumption, c , after each iteration. Given a set of power coefficients and the velocity time history, c uniquely determines W_i . The weight at each point has a relatively important effect on the values of α , γ , and p which are determined by the integration procedure.

One way to restrict the range of the individual coefficient values produced by the Newton-Raphson identifier to physically realizable values is to include a priori values of the coefficients in the cost function. These values, obtained from previous flight or wind tunnel tests, can be used to influence the values extracted from the current flight test data. Inclusion of these values is simply another way, as Iliff and Taylor (Ref. 15) point out, of "making use of all the information available to obtain the estimates and insuring that no change is made in the (coefficient value) unless there is sufficient information in the flight data." To effect this step, we add the terms

$$\frac{d_7}{P_{0m}^2} (P_{0m} - P_0)^2$$

$$\frac{d_8}{P_{1m}^2} (P_{1m} - P_1)^2$$

$\vdots$

$$\frac{d_{19}}{(CLAX_m)^2} (CLAX_m - CLAX)^2$$

(123)

to those inside the brackets of J_2 . Here, the subscript "m" refers to the a priori values. Then the additional partial derivatives are given by

$$\begin{array}{c} \frac{2d_7}{P_{0m}^2} (P_{0m} - P_0) \\ \vdots \\ \frac{2d_{19}}{(CLAX_m)^2} (CLAX_m - CLAX) \end{array} \quad (124)$$

and the additional second partial derivatives by

$$\begin{array}{c} \frac{2d_7}{P_{0m}^2} \\ \vdots \\ \frac{2d_{19}}{(CLAX_m)^2} \end{array} \quad (125)$$

The revised matrix equation for the coefficients is then obtained by adding (124) to the appropriate elements of the existing B matrix and (125) to the appropriate diagonal elements of the A matrix. As an initial estimate we take each lower case d, d_7 d_{19} , as ten times the coefficient value squared if we have a reasonable estimate of the correct coefficient values, and 0 if we do not.

Finally, for convenience of reference, the complete form of the matrix equation developed from (121), (124), and (125) is given below:

$$\begin{bmatrix} \Delta P_0 \\ \Delta P_1 \\ \Delta P_2 \\ \Delta P_3 \\ \Delta P_4 \\ \Delta C_{D_0} \\ \Delta C_{D_1} \\ \Delta C_{D_2} \\ \Delta C_{D_3} \\ \Delta C_{D_4} \\ \Delta C_{L_{A_0}} \\ \Delta C_{L_A} \\ \Delta C_{L_{A_X}} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & a_{15} & a_{16} & a_{17} & a_{18} & a_{19} & a_{110} & a_{111} & a_{112} & a_{113} \\ a_{21} & a_{22} & a_{23} & a_{24} & a_{25} & a_{26} & a_{27} & a_{28} & a_{29} & a_{210} & a_{211} & a_{212} & a_{213} \\ a_{31} & a_{32} & a_{33} & a_{34} & a_{35} & a_{36} & a_{37} & a_{38} & a_{39} & a_{310} & a_{311} & a_{312} & a_{313} \\ a_{41} & a_{42} & a_{43} & a_{44} & a_{45} & a_{46} & a_{47} & a_{48} & a_{49} & a_{410} & a_{411} & a_{412} & a_{413} \\ a_{51} & a_{52} & a_{53} & a_{54} & a_{55} & a_{56} & a_{57} & a_{58} & a_{59} & a_{510} & a_{511} & a_{512} & a_{513} \\ a_{61} & a_{62} & a_{63} & a_{64} & a_{65} & a_{66} & a_{67} & a_{68} & a_{69} & a_{610} & a_{611} & a_{612} & a_{613} \\ a_{71} & a_{72} & a_{73} & a_{74} & a_{75} & a_{76} & a_{77} & a_{78} & a_{79} & a_{710} & a_{711} & a_{712} & a_{713} \\ a_{81} & a_{82} & a_{83} & a_{84} & a_{85} & a_{86} & a_{87} & a_{88} & a_{89} & a_{810} & a_{811} & a_{812} & a_{813} \\ a_{91} & a_{92} & a_{93} & a_{94} & a_{95} & a_{96} & a_{97} & a_{98} & a_{99} & a_{910} & a_{911} & a_{912} & a_{913} \\ a_{101} & a_{102} & a_{103} & a_{104} & a_{105} & a_{106} & a_{107} & a_{108} & a_{109} & a_{1010} & a_{1011} & a_{1012} & a_{1013} \\ a_{111} & a_{112} & a_{113} & a_{114} & a_{115} & a_{116} & a_{117} & a_{118} & a_{119} & a_{1110} & a_{1111} & a_{1112} & a_{1113} \\ a_{121} & a_{122} & a_{123} & a_{124} & a_{125} & a_{126} & a_{127} & a_{128} & a_{129} & a_{1210} & a_{1211} & a_{1212} & a_{1213} \\ a_{131} & a_{132} & a_{133} & a_{134} & a_{135} & a_{136} & a_{137} & a_{138} & a_{139} & a_{1310} & a_{1311} & a_{1312} & a_{1313} \end{bmatrix}^{-1} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \\ b_5 \\ b_6 \\ b_7 \\ b_8 \\ b_9 \\ b_{10} \\ b_{11} \\ b_{12} \\ b_{13} \end{bmatrix}$$

(126)

where

$$\begin{aligned}
 a_{11} = & \frac{2d_1}{h_{\max}^2} \sum_{i=1}^N \frac{\partial h_{+i}}{\partial P_0} \frac{\partial h_{+i}}{\partial P_0} + \frac{2d_2}{\gamma_{\max}^2} \sum_{i=1}^N \frac{\partial \gamma_{+i}}{\partial P_0} \frac{\partial \gamma_{+i}}{\partial P_0} + \frac{2d_3}{\dot{\gamma}_{\max}^2} \sum_{i=1}^N \frac{\partial \dot{\gamma}_{+i}}{\partial P_0} \frac{\partial \dot{\gamma}_{+i}}{\partial P_0} \\
 & + \frac{2d_4}{w_{\max}^2} \sum_{i=1}^N \frac{\partial w_{+i}}{\partial P_0} \frac{\partial w_{+i}}{\partial P_0} + \frac{2d_5}{E_{\max}^2} \sum_{i=1}^N \frac{\partial E_{+i}}{\partial P_0} \frac{\partial E_{+i}}{\partial P_0} + \frac{2d_6}{\alpha_{\max}^2} \sum_{i=1}^N \frac{\partial \alpha_{+i}}{\partial P_0} \frac{\partial \alpha_{+i}}{\partial P_0} + \frac{2d_7}{P_{0m}^2} \\
 & + \frac{2d_2}{\gamma_{\max}^2} \sum_{i=1}^N (\gamma_{m_i} - \gamma_{+i}) \frac{\partial^2 \gamma_{+i}}{\partial P_0^2} + \frac{2d_3}{\dot{\gamma}_{\max}^2} \sum_{i=1}^N (\dot{\gamma}_{m_i} - \dot{\gamma}_{+i}) \frac{\partial^2 \dot{\gamma}_{+i}}{\partial P_0^2} \\
 & + \frac{2d_1}{h_{\max}^2} \sum_{i=1}^N (h_{m_i} - h_{+i}) \frac{\partial^2 h_{+i}}{\partial P_0^2}
 \end{aligned} \tag{127}$$

is a typical diagonal element and

$$\begin{aligned}
 a_{12} = & \frac{2d_1}{h_{\max}^2} \sum_{i=1}^N \frac{\partial h_{+i}}{\partial P_0} \frac{\partial h_{+i}}{\partial P_1} + \frac{2d_2}{\gamma_{\max}^2} \sum_{i=1}^N \frac{\partial \gamma_{+i}}{\partial P_0} \frac{\partial \gamma_{+i}}{\partial P_1} + \frac{2d_3}{\dot{\gamma}_{\max}^2} \sum_{i=1}^N \frac{\partial \dot{\gamma}_{+i}}{\partial P_0} \frac{\partial \dot{\gamma}_{+i}}{\partial P_1} \\
 & + \frac{2d_4}{w_{\max}^2} \sum_{i=1}^N \frac{\partial w_{+i}}{\partial P_0} \frac{\partial w_{+i}}{\partial P_1} + \frac{2d_5}{E_{\max}^2} \sum_{i=1}^N \frac{\partial E_{+i}}{\partial P_0} \frac{\partial E_{+i}}{\partial P_1} + \frac{2d_6}{\alpha_{\max}^2} \sum_{i=1}^N \frac{\partial \alpha_{+i}}{\partial P_0} \frac{\partial \alpha_{+i}}{\partial P_1} \\
 & + \frac{2d_2}{\gamma_{\max}^2} \sum_{i=1}^N (\gamma_{m_i} - \gamma_{+i}) \frac{\partial^2 \gamma_{+i}}{\partial P_0 \partial P_1} + \frac{2d_3}{\dot{\gamma}_{\max}^2} \sum_{i=1}^N (\dot{\gamma}_{m_i} - \dot{\gamma}_{+i}) \frac{\partial^2 \dot{\gamma}_{+i}}{\partial P_0 \partial P_1} \\
 & + \frac{2d_1}{h_{\max}^2} \sum_{i=1}^N (h_{m_i} - h_{+i}) \frac{\partial^2 h_{+i}}{\partial P_0 \partial P_1}
 \end{aligned} \tag{128}$$

is a typical off-diagonal element of the A matrix;

$$\begin{aligned}
 b_1 = & \frac{2d_1}{h_{\max}^2} \sum_{i=1}^N (h_{m_i} - h_{t_i}) \frac{\partial h_{t_i}}{\partial P_0} + \frac{2d_2}{\gamma_{\max}^2} \sum_{i=1}^N (\gamma_{m_i} - \gamma_{t_i}) \frac{\partial \gamma_{t_i}}{\partial P_0} \\
 & + \frac{2d_3}{\dot{\gamma}_{\max}^2} \sum_{i=1}^N (\dot{\gamma}_{m_i} - \dot{\gamma}_{t_i}) \frac{\partial \dot{\gamma}_{t_i}}{\partial P_0} + \frac{2d_4}{W_{\max}^2} \sum_{i=1}^N (W_{m_i} - W_{t_i}) \frac{\partial W_{t_i}}{\partial P_0} \\
 & + \frac{2d_5}{E_{\max}^2} \sum_{i=1}^N (E_{m_i} - E_{t_i}) \frac{\partial E_{t_i}}{\partial P_0} + \frac{2d_6}{\alpha_{\max}^2} \sum_{i=1}^N (\alpha_{m_i} - \alpha_{t_i}) \frac{\partial \alpha_{t_i}}{\partial P_0} + \frac{2d_7}{P_{0m}^2} (P_{0m} - P_0)
 \end{aligned} \tag{129}$$

is a typical element of the B matrix. Note that the number of elements depends upon the number of unknown coefficients. For example, for 9 unknown coefficients, the A matrix has 81 elements and the B matrix has 9 elements. Note also that some of the partials do not exist, i.e., $\frac{\partial \alpha}{\partial P}$, $\frac{\partial W}{\partial C_L}$, etc. Some of the second partial derivatives, e.g. those involving E and W, also do not exist. Second partial derivatives involving α are omitted; since the first partials must be evaluated numerically, there is no straightforward way to obtain the second partials at the same time. In addition, in an effort to speed convergence, tolerances are set on all differences, $(\alpha_{m_i} - \alpha_{t_i})$ etc.

When this difference is less than the established tolerance, the difference is set to zero. Since α_{m_i} for the test cases was known to contain some error, the tolerance for $(\alpha_{m_i} - \alpha_{t_i})$ was set at 6×10^{-5} radians. At this value the α -differences at each value of i became zero. No second partial derivative values are then necessary.

APPLICATION OF CONSTRAINTS TO MINIMIZATION OF COST FUNCTION

The parameter space described by these equations is nearly flat and has many local minima. As a result, repeated application of (126) usually leads to one of these local minima rather than to the global minimum. To find the global minimum two additional procedures are applied. The first is to constrain the recovered parameter values to lie between certain limits. For example, one would not expect an aircraft with a relatively low power

loading like the ATLIT to have a $C_{L\alpha}$ flaps up of more than 6.3. Similarly, the CLAX term, if it has a value, is not likely to be positive. The CLAO term will usually lie between -0.5 and +0.5. One can usually assign reasonable upper and lower limits to the other parameter values on the basis of wind tunnel tests, analysis, or previous experience. The parameter values can be constrained to lie within these limits by comparing the parameter values obtained after performing the operation described in (126) with the limits and adding a term

$$WGTU(P_0 - P_{0_{\text{lower limit}}}) \quad (130)$$

to the b_1 element and the term

$$WGTU \quad (131)$$

to the a_{11} element in (126) if $P_0 < P_{0_{\text{lower limit}}}$. Similarly if $P_0 > P_{0_{\text{upper limit}}}$ one adds

$$WGTU(P_0 - P_{0_{\text{upper limit}}}) \quad (132)$$

to the b_1 element and

$$WGTU \quad (133)$$

to the a_{11} element. The matrix manipulation is again carried out and the new parameter values are compared with the imposed limits. If any of the parameter values still does not lie within the limiting values, WGTU or WGTU, whichever is appropriate, is increased by a factor of 10 for that parameter and the matrix operation repeated.

While this operation will prevent parameter values from being grossly ridiculous in the physical sense, it does not insure convergence to a global minimum. There are two reasons:

1. The limits will almost always be chosen independently of one another and may in fact lie on different slopes of a local minima. Thus, the parameter values may not readily move off these limits if the weights, WGTU and WGTU, are reduced on subsequent iterations.

2. A number of the diagonal elements of the A matrix are much smaller than the off-diagonal elements in the same column or row. Such ill-conditioning can lead to relatively large excursions in some of the parameter values from iteration to iteration. These excursions may actually be large enough to cause the parameter value to move from one limit to the other in one iteration. Since the trajectory is very sensitive to the parameter values used to compute it, large changes in parameter values cannot be used to find the global minimum because the computed trajectory will cross the input trajectory on each iteration; the cost function increases very rapidly in these circumstances.

Two means have been found useful for conditioning the A matrix to alleviate this problem. The first method sets the off-diagonal elements, $a_{12}, a_{13}, \dots, a_{113}, a_{21}, a_{31}, \dots, a_{131}$, to zero and retains only a_{11} . This is equivalent to saying that any changes in P_0 do not depend upon the values of the other parameters nor do the other parameters depend upon P_0 ; changes in P_0 depend only on the agreement between the computed and measured trajectories. This is not as preposterous as it may at first appear. Consider the physical situation: All of the data on which the procedure operates is at a speed considerably above $V = 0$, the speed at which the power equals P_0 . P_0 , for the example cases at least, is much smaller (about a factor of 10) than the other terms in the power expression which also contributes to the ill-conditioning. Note, however, that the system can still converge to the global minimum when the off-diagonal elements are set to zero because $b_1 \rightarrow 0$ as the global minimum is approached.

The second method for improving the conditioning of the A matrix starts by extracting the power coefficients from both the drag and the lift equations. If the system has not converged to a global minimum and produced compatible data trajectories, the power coefficients extracted by fitting the two equations to the same data will be different. Then by imposing a priori power coefficients of the type

$$\frac{G P_0^2}{(G-1)P_{0\text{DRAG}} + P_{0\text{LIFT}}} \quad (134)$$

and supplying these with moderate weights, one can condition the system to converge reasonably rapidly to a new minimum. This will usually be much closer to the global minimum than the previous one. Then, by relaxing the weights on the a priori values somewhat, the system may adjust itself even closer to the global minimum. In (134) $P_{0\text{DRAG}}$ is the P_0 coefficient

extracted from the drag or $\dot{V}$ equation, $P_{0\text{LIFT}}$ is the P_0 coefficient extracted from the lift or $\dot{\gamma}$ equation, and G is an arbitrarily-selected constant. G should be about 10 for the higher order coefficients and about 100 for P_0 .

This is to account for the fact that because power is a small term in the $\dot{Y}$ equation, the parameter values from this equation will be more in error than those from the $\dot{V}$ equation. The correct a priori values should therefore lie closer to the parameter values derived from the $\dot{V}$ equation. The reason this procedure is effective is that when power is specified the system is actually determinant* at every speed; thus, specifying a priori values for the power coefficients will cause the system to converge fairly rapidly to some minimum. If the a priori values are exact, the lift and drag parameter values will be recovered with good accuracy but not exactly. The trick then is to choose G properly, use the first method, or develop some combination technique. Unfortunately, experience in working with the system is necessary in order to select the best approach. This situation, it may be mentioned, is not uncommon in parameter identification work at the present time.

If the a priori technique represented by equation (134) and its subsequent relaxations is permitted to go through a number of iterations one finds, not surprisingly, that the changes in the coefficient values get smaller and smaller each iteration. To permit this situation to continue beyond a certain point is (a) not cost-effective and (b) does not guarantee convergence of the coefficients to exact values. To aid computationally in the convergence to at least a local minimum those coefficients which do not change at least 1.5×10^{-6} times their value are "frozen" and the system reduced accordingly. CLA, however, is treated differently. When $\Delta CLA / CLA < 1.5 \times 10^{-6}$ but still positive, CLA is increased by 1.0×10^{-3} . This is done because it was found that CLA is the key parameter in determining which local minimum the system converges to. Near the correct value of CLA the state space must be very flat because the system will converge** to a very small cost function for any value of CLA. This value of the cost function will be very slightly greater than the global minimum so that the prospects for reaching the global minimum without some "nudging" of this kind are quite remote.

* That is to say the total lift or total drag are determinate. The individual coefficients in the polynomial expansions for lift and drag must still be found as before.

** By converge we mean reach a value from which it will not differ significantly despite numerous additional iterations.

EXAMPLE APPLICATION OF NOISE REDUCTION AND NEWTON-RAPHSON PROCEDURE

The efficacy of the foregoing procedures is indicated by the following example: If only the α -channel of the theoretical data set is degraded by 1% $\alpha_{\max}$ random noise and then filtered with $n_c = 10$, errors remaining in α are still on the order of 2×10^{-3} radians. When this computed data set is submitted to the least squares coefficient extraction procedure, the fit error obtained for the correct model is 0.294823×10^{-4} and the six coefficients are:

$$P_0 = 49398.169$$

$$C_{D_0} = .0440371829$$

$$P_2 = 857.520129$$

$$C_{D_2} = 1.390709638$$

$$P_3 = -1.005276788$$

$$C_{D_4} = 1947.263799$$

The α -bias error found ($-.111455 \times 10^{-8}$) is too small to justify a correction.

When the data are fit with a power model of $P_0 V^{1/3}$ and a five term drag model the fit error is $0.11828259 \times 10^{-3}$. When the drag model is changed to $C_D = C_{D_0} + C_{D_1} C_L^2$ the fit error becomes $0.30286167 \times 10^{-3}$ and the coefficients are

$$P_0 = 31825.6829$$

$$C_{D_0} = .036226989$$

$$C_{D_1} = .0932119$$

The program then uses a least-square distance routine to fit the α -data to the C_L values found from the $\dot{\gamma}$ -equation with the following result:

$$C_L = -0.002163327 + 6.35788976\alpha - 0.3823769\alpha^2$$

The individual α points are then moved to satisfy this equation.

When the coefficient extraction is repeated, the fit error for the correct model is now reduced to 0.1846867×10^{-6} and the coefficients are

$$P_0 = 25354.595$$

$$C_{D_0} = .03342$$

$$P_2 = 1173.542$$

$$C_{D_2} = 1.29939516$$

$$P_3 = 2.377407$$

$$C_{D_4} = 2005.55596$$

The C_L coefficients are then updated with the result that

$$C_L = -0.0017838557 + 6.34847\alpha - 0.310849\alpha^{2.0304627}$$

After 4 iterations of the α -modification procedure discussed in section 3 above, the minimum fit error for the correct model is 0.33751×10^{-7} and the coefficients are

$$P_0 = 26881.7756$$

$$C_{D_0} = .033792832$$

$$P_2 = 1156.25239$$

$$C_{D_2} = 1.2885474567$$

$$P_3 = -2.3179596$$

$$C_{D_4} = 2017.21169779$$

The lift coefficient equation has then become

$$C_L = -.001782573568 + 6.34888117\alpha - 0.3160536\alpha^{2.04393}$$

The trajectory comparison procedure yields a fit error of 0.15515×10^{-8} with the following coefficients:

$$P_0 = 28740.475$$

$$C_{D_0} = .03503665$$

$$P_2 = 1127.26152$$

$$C_{D_2} = 1.3017466$$

$$P_3 = -2.17339$$

$$C_{D_4} = 1991.91279$$

It is at this point that the Newton-Raphson Identifier is first applied. Using the foregoing coefficients and the latest value for the specific fuel consumption, we compute differences between the "measured" values and the latest calculated values of the variables along the flight trajectory as well as the values of the partial derivatives at each point. When these are properly summed and placed in the appropriate A and B matrices, we solve the system of equations to find the quantities by which the coefficients should be changed to reduce the difference between the "measured" trajectory and the computed trajectory. The new coefficients found by eight iterations of this procedure are then

$$P_0 = 28735.87794$$

$$C_{D_0} = .03510029979$$

$$CLA_0 = .254462293 \times 10^{-7}$$

$$P_2 = 1126.60939679$$

$$C_{D_2} = 1.28590$$

$$CLA = 6.29327993$$

$$P_3 = -2.1696485666$$

$$C_{D_4} = 2016.338978$$

$$CLAX = -.301975855 \times 10^{-8}$$

When these, along with a revised specific fuel consumption, are used in the subsequent trajectory computation, the fit error is less than 6×10^{-12} . Tables V and VI show the results achieved after 29 iterations. The fit error at this point is 1.3336×10^{-13} and the residual error in α averages about 1.2×10^{-5} radians. Additional iterations may be used until the final fit error of 6.553×10^{-14} — the value obtained with time histories computed from the correct theoretical coefficients — is approached. Note that in these circumstances the average residual error in α is less than 0.6928×10^{-5} radians, or about one part in 100,000. There is evidence to suggest, however, that most of this error is a result of the use of only 16 decimal digits in the integration routine. In that event, users with an extended precision capability should find the ultimate fit error to be somewhat lower ($\sim 10^{-22}$).

The example cited here shows that with flight data that are not excessively noisy or otherwise erroneous, the simple least squares procedure described earlier in this report can be extended and modified to accommodate such errors successfully and still produce reliable coefficient values. In the present case the reduction in fit error was more than eight orders of magnitude.

When this more powerful procedure was first applied to actual flight data, however, the initial fit error was about 10^{-1} (about 1000 times as large as for the test case) and no reduction could be obtained. Examination of the input data revealed that the α , θ , and $\sin^{-1}(h/V)$ data were very incompatible. It was immediately obvious that it would be necessary to reduce this incompatibility in some rational fashion before the procedure described above could begin to function effectively.

TABLE V. EFFECT OF NOISE REDUCTION EFFORTS ON RANDOM NOISE-CORRUPTED α -DATA
(OTHER CHANNELS NOISE FREE)

Pt.	α -values after smoothing by low- pass filter	α -values after application of noise- reduction program	Theoretical α -values
1	.1648561	.162610	.1625865
6	.1646336	.162650	.1626264
11	.1642220	.162726	.1627021
16	.1635306	.162858	.1628342
21	.1627125	.163017	.1629993
26	.1622586	.163060	.1630357
31	.1621283	.162896	.1628721
36	.1620319	.162473	.1624490
41	.1617028	.161753	.1617295
46	.1609460	.160710	.1606867
51	.1596614	.159317	.1592940
56	.1578413	.157549	.1572621
61	.1555447	.155404	.1553815
66	.1528620	.152898	.1528759
71	.1498808	.150048	.1500260
76	.1466639	.146872	.1468503
81	.1432434	.143406	.1433850
86	.1396289	.139697	.1396771
91	.1358230	.135794	.1357737
96	.1318381	.131741	.1317222
101	.1277057	.127589	.1275701
106	.1234775	.123383	.1233655
111	.1192182	.119174	.1191564
116	.1149943	.115007	.1149901
121	.1108633	.110919	.1109024
126	.1068668	.106936	.1069206
131	.1030291	.103087	.1030717
136	.0993605	.0993959	.0993814
141	.0958635	.0958769	.0958629
146	.0925384	.0925358	.0925223
151	.0896943	.0896856	.0896724
156	.0867033	.0866978	.0866851
161	.0838952	.0838976	.0838853
166	.0812729	.0812796	.0812676
171	.0788341	.0788380	.0788264
176	.0765706	.0765671	.0765559
181	.0744685	.0744597	.0744487
186	.0725120	.0725069	.0724962
191	.0706878	.0707004	.0706899
196	.0689884	.0690313	.0690211

TABLE V. (Continued)

Pt.	α -values after smoothing by low- pass filter	α -values after application of noise- reduction program	Theoretical α -values
201	.0674143	.0674917	.0674817
206	.0659714	.0660735	.0660637
211	.0646669	.0647690	.0647594
216	.0635016	.0635702	.0635607
221	.0624647	.0624701	.0624609
226	.0615312	.0614627	.0614536
231	.0606668	.0605417	.0605327
236	.0598368	.0597010	.0596921
241	.0590192	.0589354	.0589267
246	.0582159	.0582405	.0582318
251	.0574569	.0576115	.0576030
256	.0567929	.0570441	.0570357
261	.0562780	.0565344	.0565260
266	.0559444	.0560788	.0560705
271	.0557777	.0556742	.0556659
276	.0557012	.0553170	.0553088
281	.0555776	.0550045	.0549963
286	.0552280	.0547339	.0547258
291	.0544669	.0545027	.0544945
296	.0531435	.0543080	.0543000
298	.0524357	.0542399	.0542318

Fit error = 1.3336×10^{-13}

TABLE VI. COEFFICIENT VALUES OBTAINED WITH NOISE REDUCTION PROCEDURE

	Theoretical values used to generate data time histories	Values retrieved from noise reduction procedure
P_0	28,735.71427	28,738.72144
P_1	1,126.60714	1,126.5699
P_2	- 2.169642857	- 2.1694849
C_{D0}	0.035100000	0.03510121
C_{D1}	0	
C_{D2}	1.289155014	1.2887796
C_{D3}	0	
C_{D4}	2,030.800865	2,028.977898

A PRIORI IMPROVEMENT OF DATA COMPATIBILITY

A diligent investigation into the sources of α , θ , and γ incompatibility in the flight data revealed the possibility of at least the following sources of error in the individual data channels which had not been treated earlier:

1. alignment errors in the installation of the α and θ transducers
2. a bias error in the pitch rate gyro indication
3. a drift in the pitch angle indication
4. excessive lag or other dynamic effects in the pneumatic altitude and airspeed indications
5. gain and bias errors in the pressure instrument calibrations and in the position error calibrations
6. a phase lead in the θ and temperature indications relative to the other channels

It will be appreciated that many of these effects are not readily quantified in the usual calibration procedures. To make the flight data sufficiently self-compatible to be usable in the lift, drag, and power extraction routine, the filtered input measurements were altered as follows:

1. A bias, calculated from

$$\theta_b = \sin^{-1}\left(\frac{Ax_N}{g}\right) - \theta_N, \quad (135)$$

was added to the input θ data. The subscript N refers to the last data value in the set.

2. A bias, calculated from

$$\dot{\theta}_b = \frac{\theta_N - \int_1^T \dot{\theta} dt - \theta_1}{T}, \quad (136)$$

was added to the input $\dot{\theta}$ data. As a result of these steps the Ax , θ , and $\dot{\theta}$ traces were found to be quite self-consistent. If the time integral of $\dot{\theta}$ did not then match $\theta(t)$,

3. The phase lead of θ with respect to the other data channels was found by determining the value of τ which maximizes

$$\sum_{i=1}^N \left\{ \theta_i * \left[\int_1^i \dot{\theta}(i - \tau) d\tau + \theta_1 \right] \right\}. \quad (137)$$

The phase lead was eliminated by dropping τ data points from the beginning of each data trace except θ and temperature.

The opportunity to determine the compatibility of the pneumatic data (V and h) with the inertial data and the angle of attack follows from the kinematic equation for the longitudinal body axis acceleration and the definition of rate of climb:

$$A_x = \dot{V} \cos \alpha + V(\dot{\theta} - \dot{\alpha}) \sin \alpha + g \sin \theta - X_{ax} \dot{\theta}^2 \quad (138)$$

$$h_i = \int_1^i V \sin (\theta - \alpha) dt + h_1. \quad (139)$$

Examination of the first equation will show that if one assumes that as a result of 1, 2, and 3 above A_x , θ , and $\dot{\theta}$ are now correct and compatible among themselves, a compatible value for either V or α can be found by solving a differential equation assuming the other variable to be correct. If one assumes that α is correct then a compatible value of $V(t)$ is the solution of the equation

$$\dot{V}_j = \left[\frac{A_{x_j} - g \sin \theta_j + X_{ax} \dot{\theta}_j^2}{\cos \alpha_j} \right] - V_j (\dot{\theta}_j - \dot{\alpha}_j) \tan \alpha_j \quad (140)$$

with the initial condition $V_1 = V_1$ from pneumatic data at the first data point.

This solution is obtained quite readily by the technique described earlier to integrate the trajectory equations (112).

If, on the other hand, V is assumed to be the error-free variable, α can be determined by a slight variation of the same solution procedure. To obtain the proper form one first makes the substitution

$$u = \cos \alpha \quad (141)$$

whence (138) can be written

$$\dot{u}_j = \left[\frac{A_{x_j} - g \sin \theta_j + X_{ax} \dot{\theta}_j^2}{V_j} \right] - \left[\frac{\dot{V}_j}{V_j} \right] u_j - \dot{\theta}_j S_j \sqrt{1 - u_j^2} \quad (142)$$

Here S_j has the value ± 1.0 . The correct value is determined by the following logic:

a. choose as S_1 the value corresponding to the measured α_1 . This value of α is also used to begin the integration.

b. If $S_j > 0$, $u_j > 0.9999$, and $\{-u_j/[S_j(\sqrt{1-u_j^2} + 10^{-12})]\} < 0$,

then the sign of S_j is changed for the next value of j .

c. The same is true if $S_j < 0$, $u_j > 0.9999$, and $\{-u_j/[S_j(\sqrt{1-u_j^2} + 10^{-12})]\} > 0$.

The computed value of α at any point is then

$$\alpha_j = \sin^{-1} \{S_j \sqrt{1-u_j^2}\} . \quad (143)$$

An effort was made to calculate α in this manner but the solutions had ridiculously large magnitudes. Efforts were also made to apply gain and bias corrections to the velocity in an effort to improve the result. This too failed to produce physically reasonable results. The various lag constants were then varied over large ranges with the same end result. It was therefore concluded that the velocity and altitude data contained substantial errors, probably resulting from a combination of excessive lags, dynamic effects, and perhaps incorrect gains and biases. It was therefore necessary to assume that α was correct in order to solve for V .

The initial results were quite encouraging in that they were qualitatively similar to the input data but displayed quantitative differences of up to 20 ft/sec at certain times. It was found that this difference could be reduced significantly by assuming a drift in the pitch gyro indication of 8×10^{-4} rad/sec. Subtracting this "drift" from the input pitch angle indication led to a calculated velocity that usually differed from the input by less than 1.5 ft/sec. As a consequence of these findings

4. The input velocity was overwritten by the solution of (140) and

5. The input altitude was overwritten by

$$h(t) = \int_1^t V \sin(\theta - \alpha) dt + h_1 \quad (144)$$

where V is the result of the previous step. Comparisons of the calculated velocity and altitude with the input V and H data are shown for a typical pull-up-pushover in figure 39. Note that differences of this magnitude would make it impossible for the coefficient extraction procedure to operate successfully.

While the foregoing actions produce a reasonably compatible data set, they do not guarantee its accuracy. The reader is cautioned that while these data, when processed by the coefficient extraction program, will yield

physically reasonable numbers if the proper model is available, such results may not be the correct values for the particular aircraft under investigation. This could easily happen if errors in the α -channel, for example, are masked by the compatibility improvement scheme. Note also that the solution of (140) is not very sensitive to the exact value of gain and bias used for the α position error. Compare, for example, figure 39 with figure 40.

In an effort to fine-tune the data for improved compatibility before its submission to the coefficient extraction program, a number of other procedures were applied. The first represents γ by $\theta - \alpha$ and calculates $\dot{\gamma}$ from this by the method of splines. This value of $\dot{\gamma}$ is substituted into (138) now written as

$$A_x = \dot{V} \cos \alpha + V \dot{\gamma} \sin \alpha + g \sin \theta - X_{ax} \dot{\theta}^2. \quad (145)$$

Assuming that V , $\dot{V}$, θ , $\dot{\theta}$, $\dot{\gamma}$, and A_x are known, α is determined at each point by the second-order Newton-Raphson technique. The resulting α values are fit to the input α values using a second order polynomial:

$$\alpha_j = K_1 \alpha_{DATA_j}^2 + K_2 \alpha_{DATA_j} + K_3. \quad (146)$$

α_{DATA_j} is then replaced by values computed from this equation. K_1 , K_2 , and K_3 are found by the method of least squares. Since α may now be slightly different, new values of γ are computed and fit to the previous values by

$$\gamma_j = K_4 \gamma_{jOLD}^2 + K_5 \gamma_{jOLD} + K_6 \quad (147)$$

with K_4 , K_5 , and K_6 determined in a least squares sense. The new values of γ are replaced by those computed from the equation.

A new $\dot{\gamma}$, defined as $2K_4 \gamma_{jOLD} \dot{\gamma}_{jOLD} + K_5 \dot{\gamma}_{jOLD}$, is used to find new α 's. The cycle is repeated a number of times until K_1 and $K_3 \rightarrow 0$ and $K_2 \rightarrow 1.0$ as closely as possible.

The final "tuning" assumes that bias errors may still be present in α and θ and that there may be a small residual acceleration sensitivity in the static pressure indication. The latter is important primarily in those cases where V is assumed to be correct and a compatible α must be calculated. It serves principally as a check when α is taken to be correct and a compatible V is calculated. For this final tuning we construct the cost function

$$J_3 = \sum_{j=1}^N \left[\frac{d_{20}}{P_{m_1}^2} (P_{m_j} - P_{c_j})^2 + \frac{d_{21}}{A_{x_{\max}}^2} (A_{x_{m_j}} - A_{x_{c_j}})^2 + \frac{d_{22}}{A_m^2} (A_m - A)^2 \right. \\ \left. + \frac{d_{23}}{B_m^2} (B_m - B)^2 + \frac{d_{24}}{C_m^2} (C_m - C)^2 + \frac{d_{25}}{D_m^2} (D_m - D)^2 + \frac{d_{26}}{G_m^2} (G_m - G)^2 \right], \quad (148)$$

$$\text{where } P_{c_j} = \frac{P_0}{T_0} T_j \left\{ 1 - 6.86 \times 10^{-5} \left[\int_1^{t_j} V_j \sin(\theta_j - \alpha_j) dt_j \right. \right. \\ \left. \left. + G \int_1^{t_j} V_j \cos(\theta_j - \alpha_j) dt_j + h_1 \right] \right\}^{4.26} + A \dot{\theta}_j^2 + B A x_j + C g \sin \theta_j \quad (149)$$

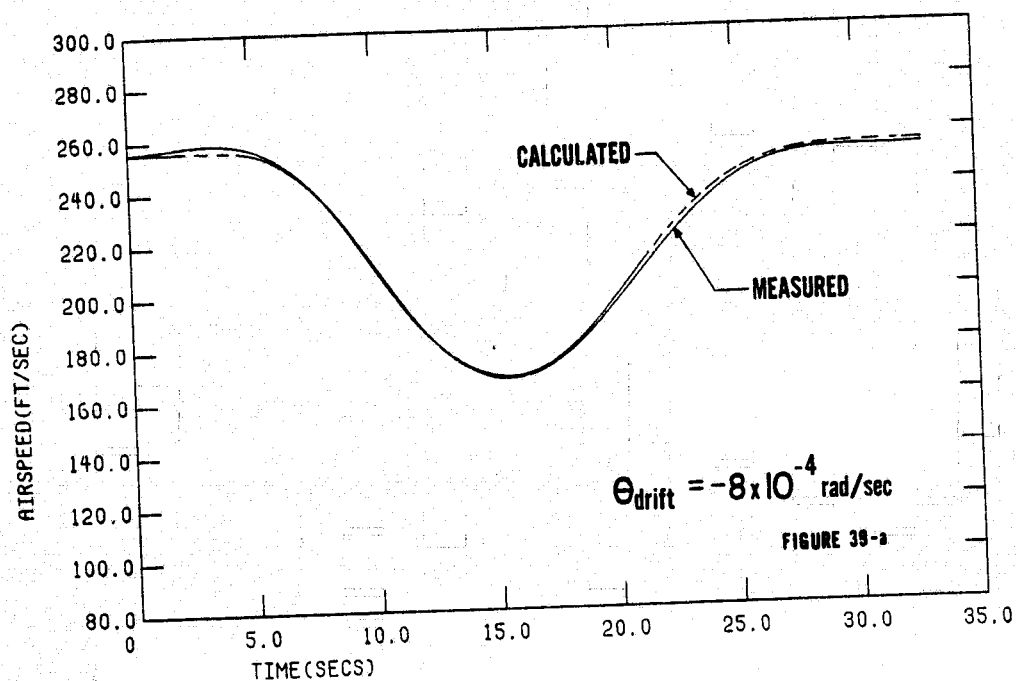
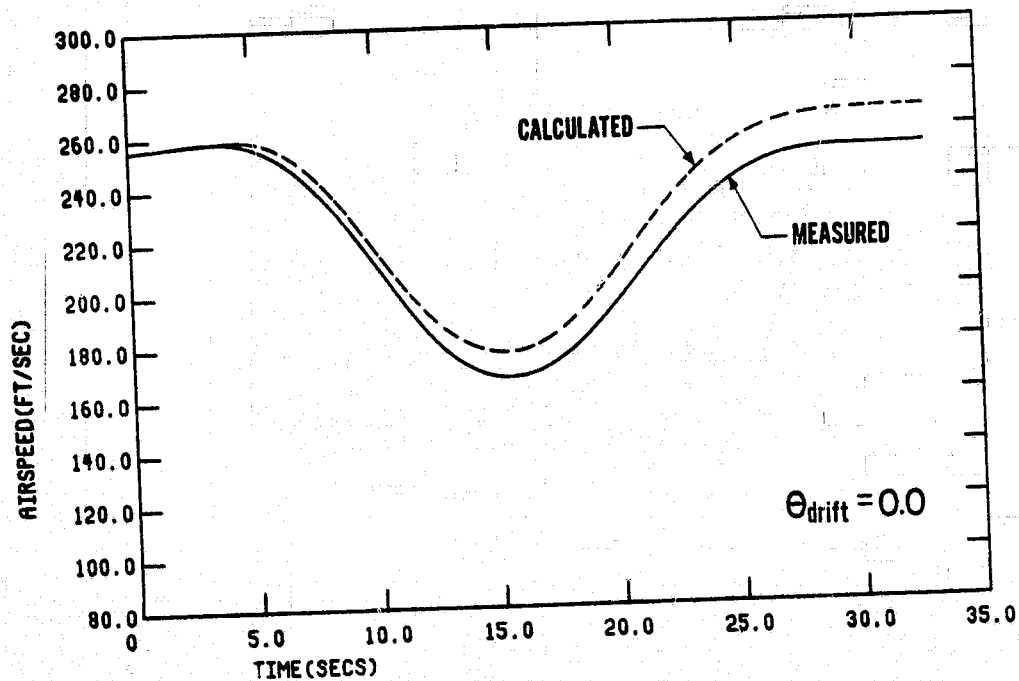
$$A_{x_{c_j}} = \dot{V}_j \cos \alpha_j + V_j (\dot{\theta}_j - \dot{\alpha}_j) \sin \alpha_j + X_{ax} \dot{\theta}_j^2 + D (V_j [\dot{\theta}_j - \dot{\alpha}_j] \cos \alpha_j \\ + g \cos \theta_j - \dot{V}_j \sin \alpha_j) + G (\dot{V}_j \sin \alpha_j - V_j (\dot{\theta}_j - \dot{\alpha}_j) \cos \alpha_j), \quad (150)$$

$$D = \theta_{\text{bias}},$$

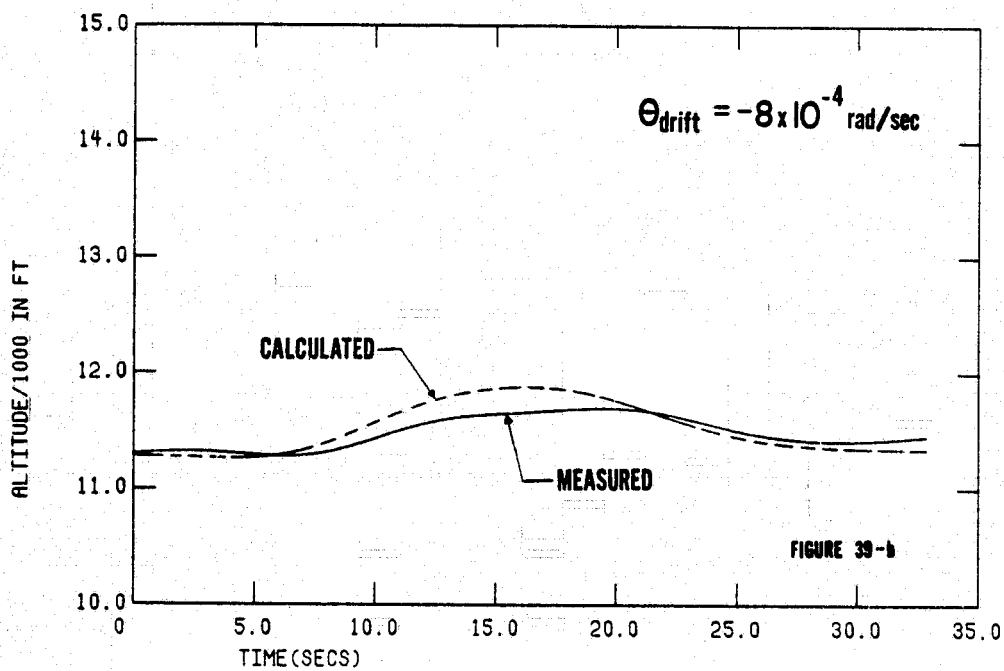
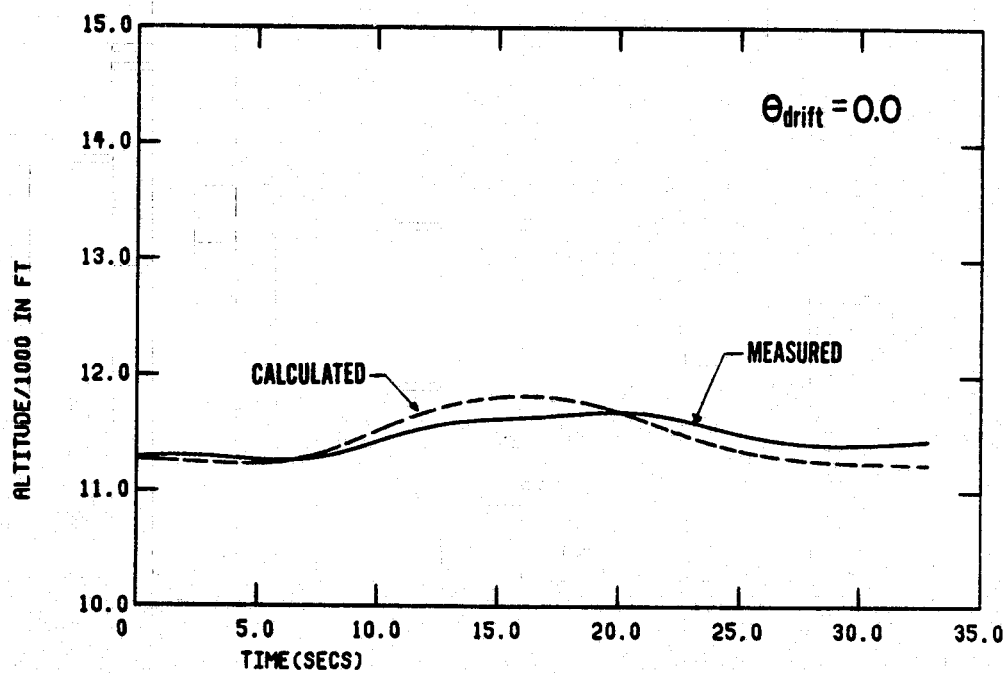
$$G = \gamma_{\text{bias}} \text{ or } (\theta_{\text{bias}} - \alpha_{\text{bias}}); \quad \alpha_{\text{bias}} = D - G, \quad (151)$$

and minimize J_3 with respect to A , B , C , D , and G , using the Newton-Raphson procedure. With these values we apply bias corrections to θ and α and an "acceleration correction" to P_{m_j} . We then return to the beginning of the

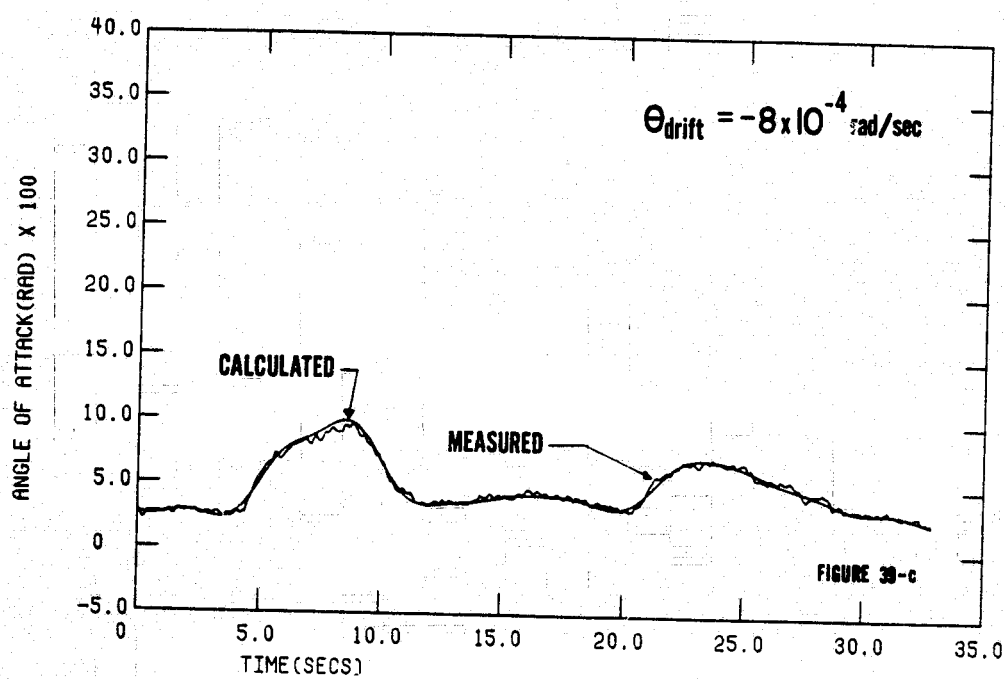
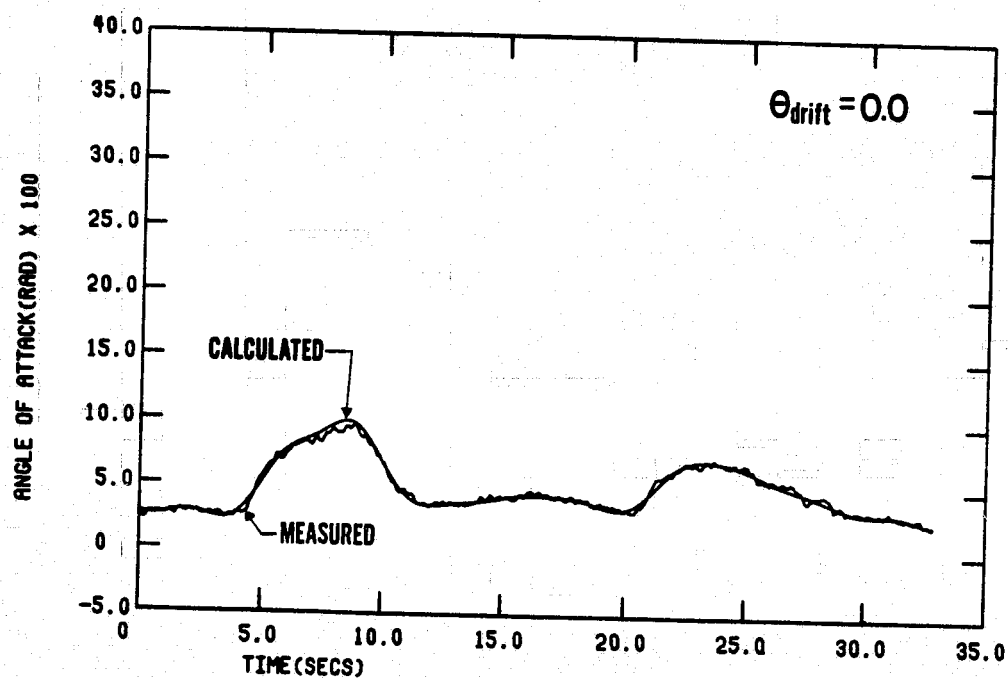
data processing activity, calculate new velocities, altitudes, and angles of attack, and again minimize J_3 with respect to A , B , C , D , and G . This procedure may be repeated until J_3 has in fact reached a minimum. A priori values may be included for the parameters if known. Even approximate a priori parameter values may be used to advantage during the processing of the first few data runs to insure reasonable results and easier detection of "bugs". Typical results for the ATLIT obtained by applying the entire calibration-filtering-compatibility improvement procedure (called FDR1) are shown in Appendix A.



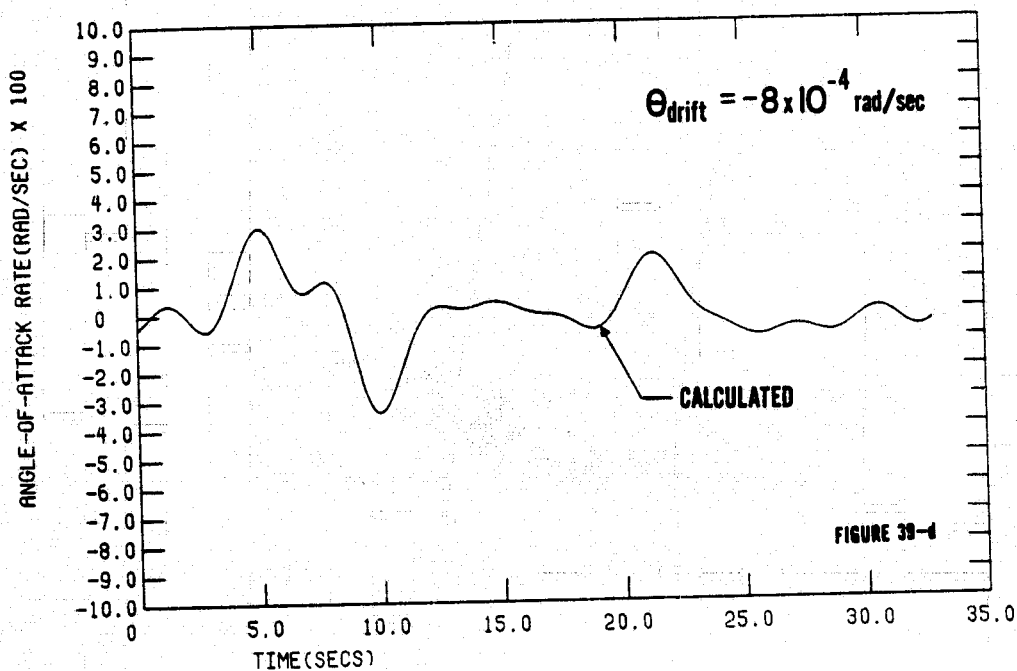
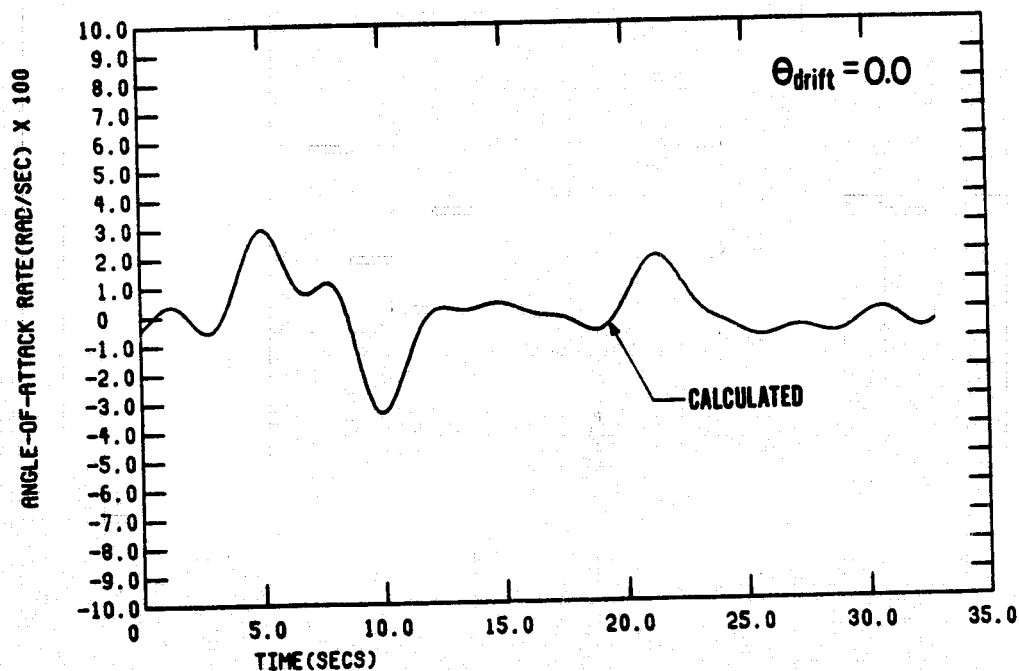
COMPARISON OF CALCULATED PULLUP-PUSHOVER
TRAJECTORY WITH MEASURED VALUES. ASSUMED
 $\propto$ POSITION ERROR CORRECTIONS: GAIN = 0.8667,
BIAS = 0.0047.



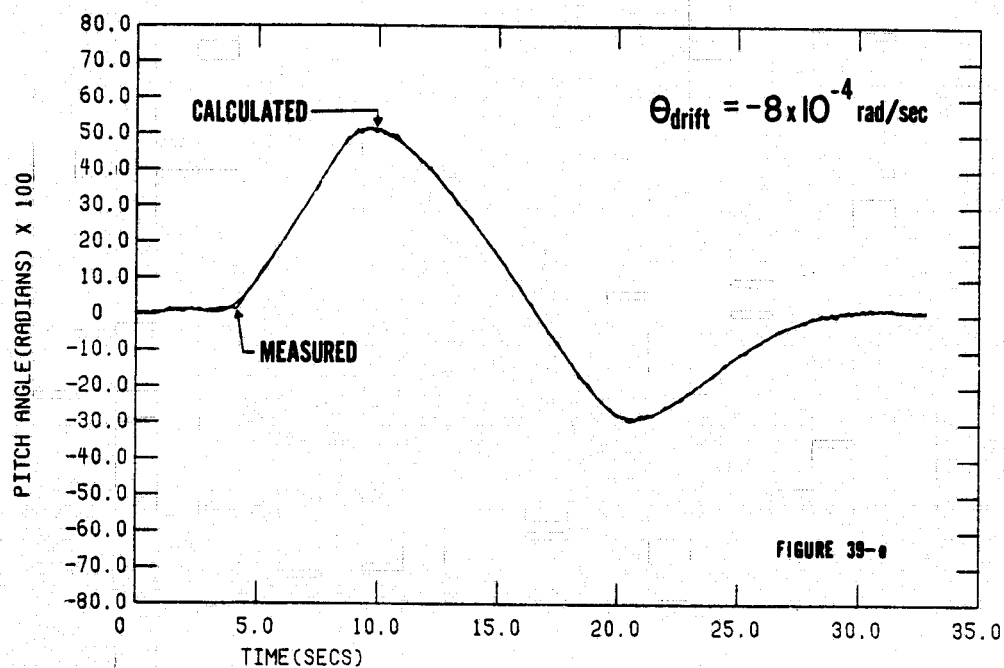
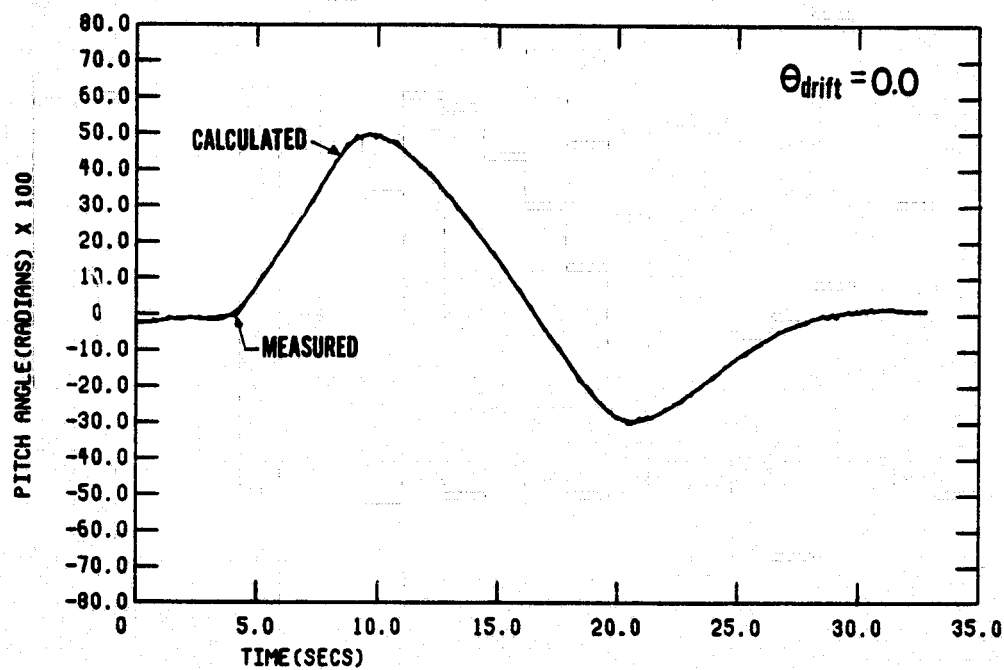
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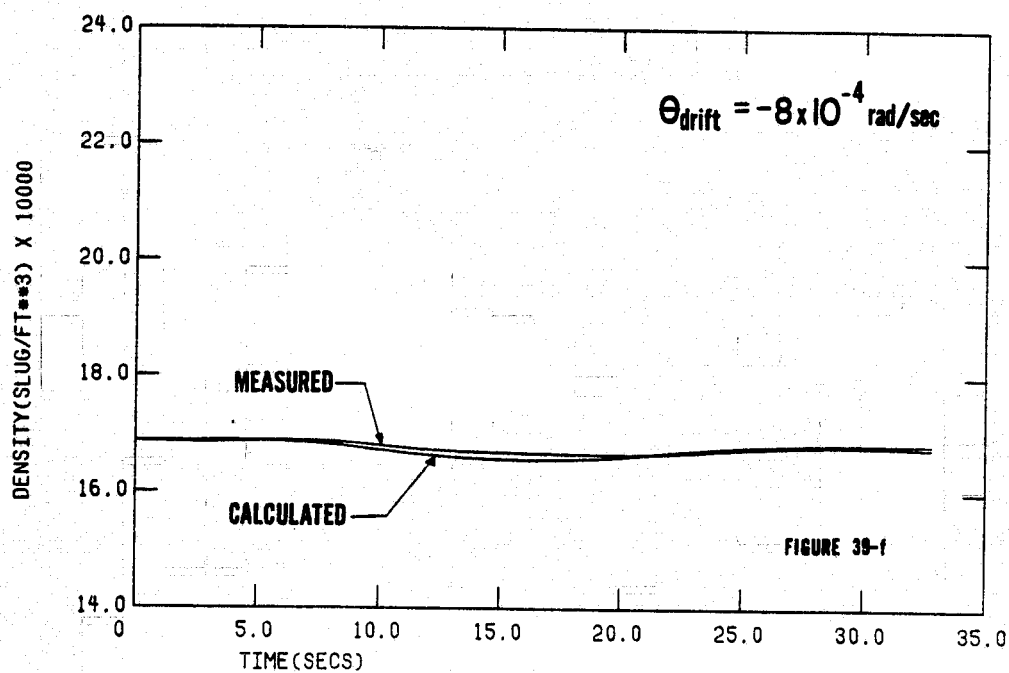
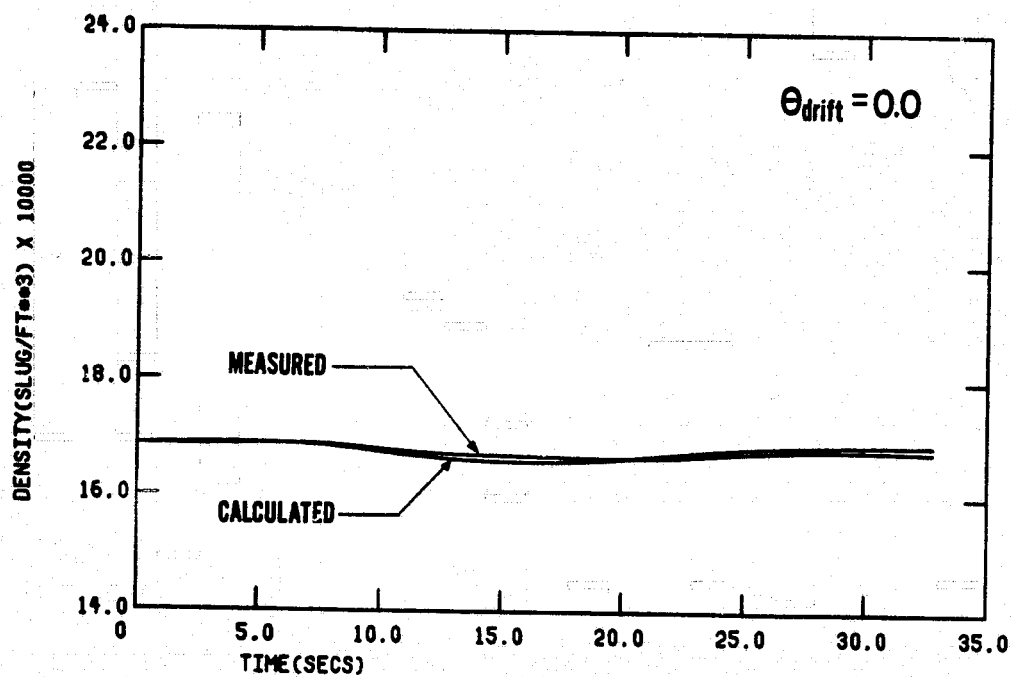
COMPARISON OF CALCULATED PULLUP-PUSHOVER TRAJECTORY WITH MEASURED VALUES. ASSUMED α POSITION ERROR CORRECTIONS: GAIN = 0.8667, BIAS = 0.0047.



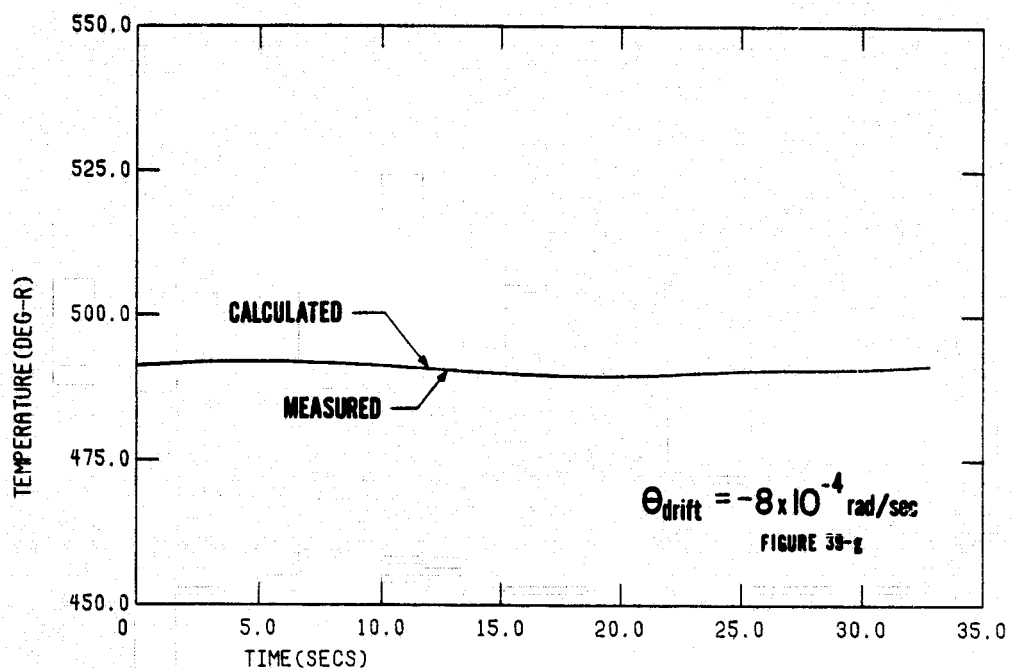
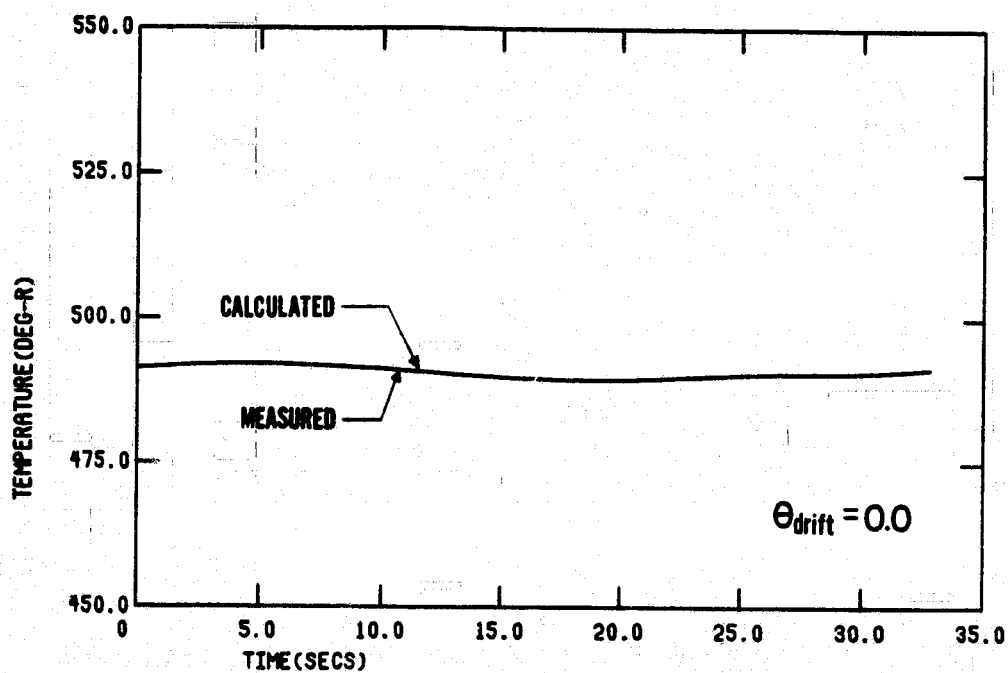
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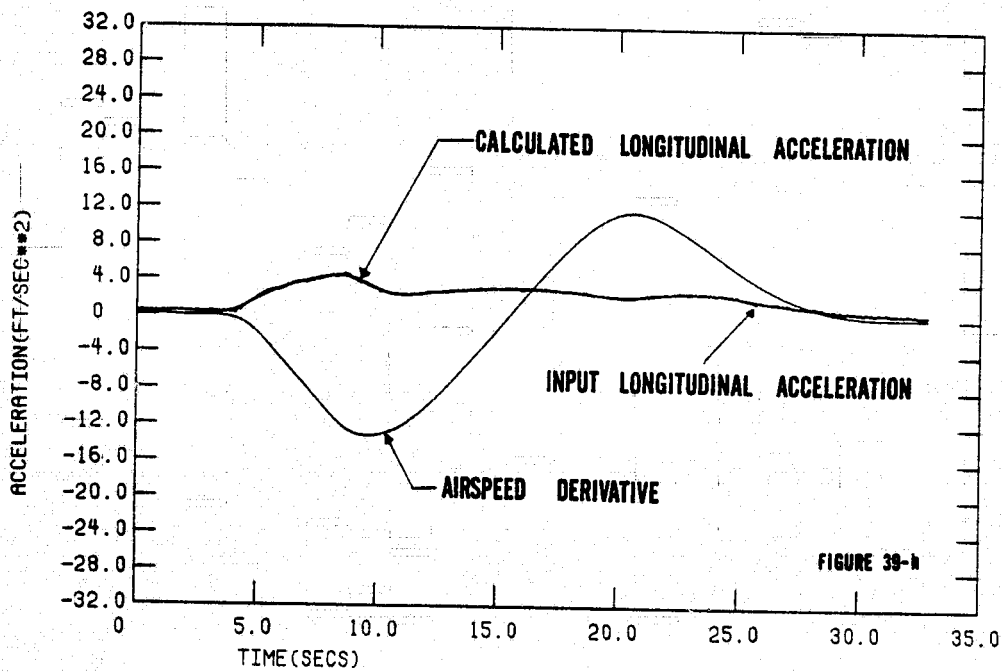
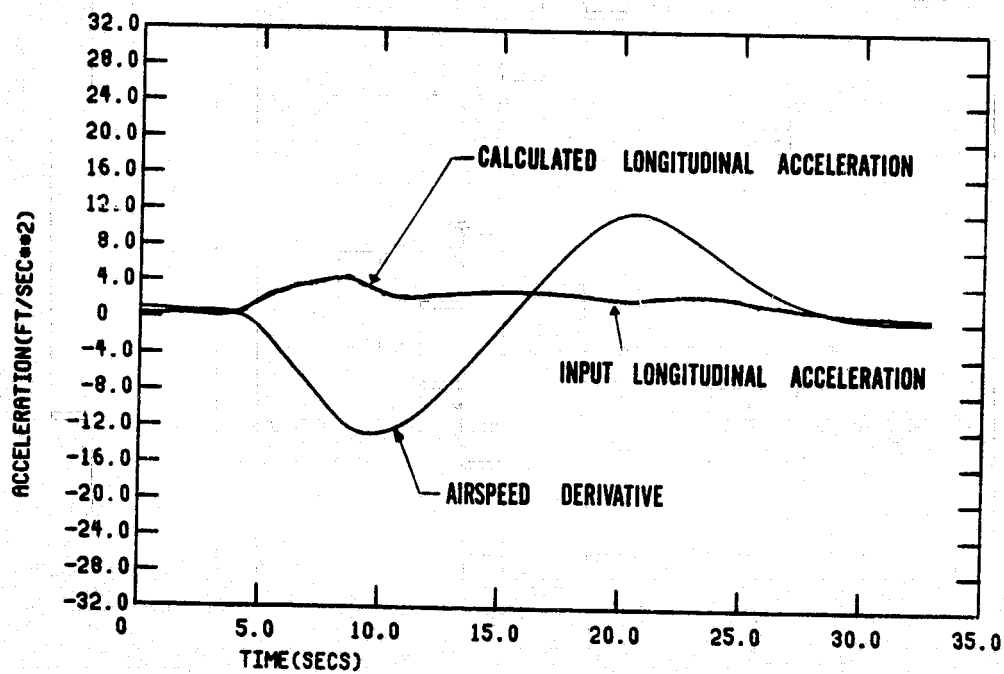
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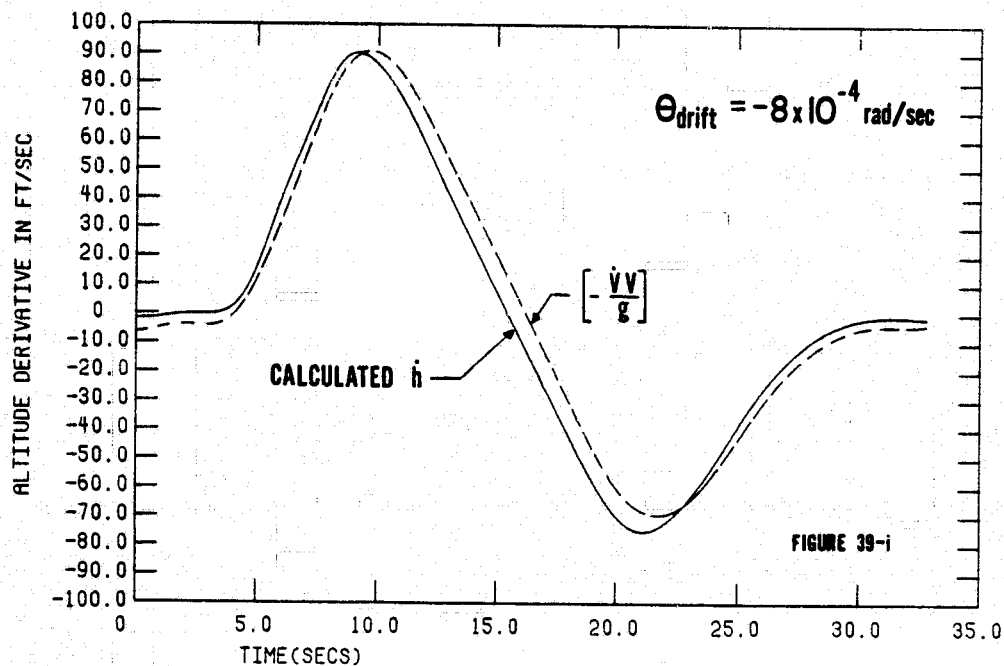
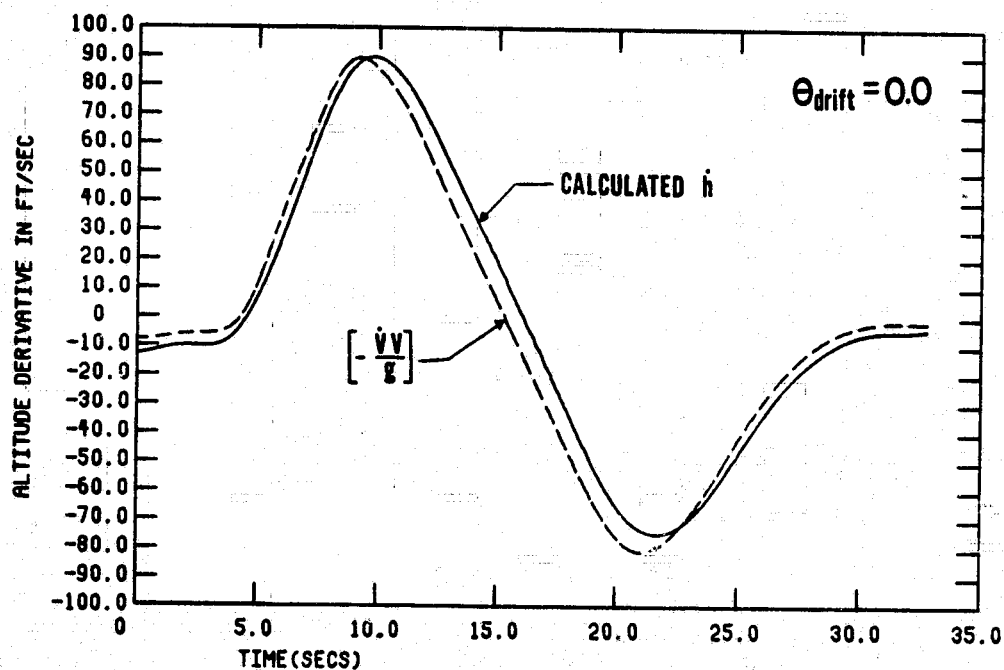
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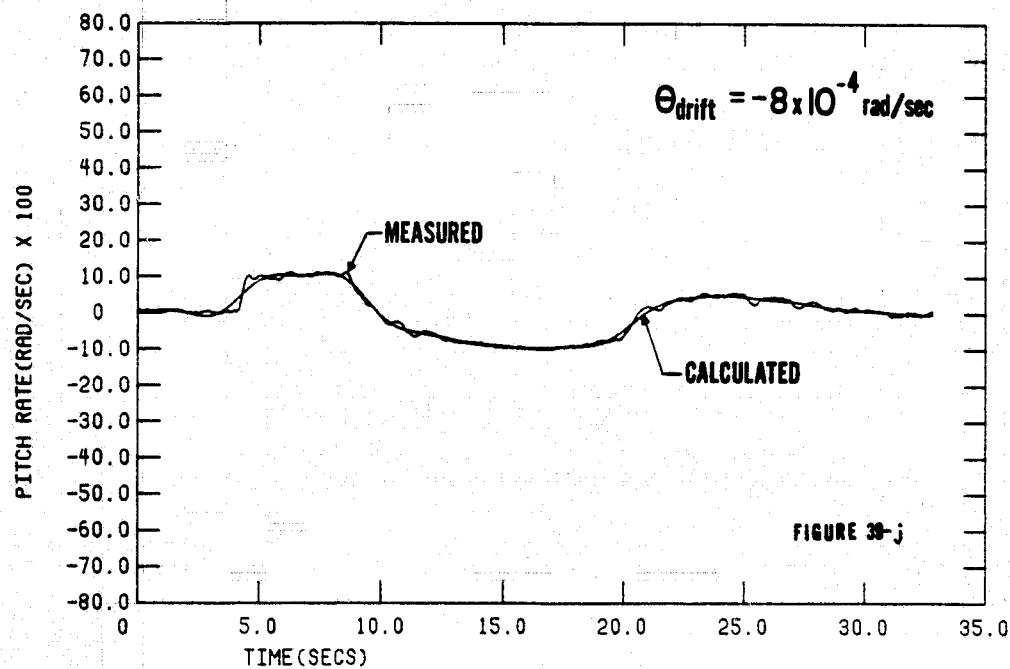
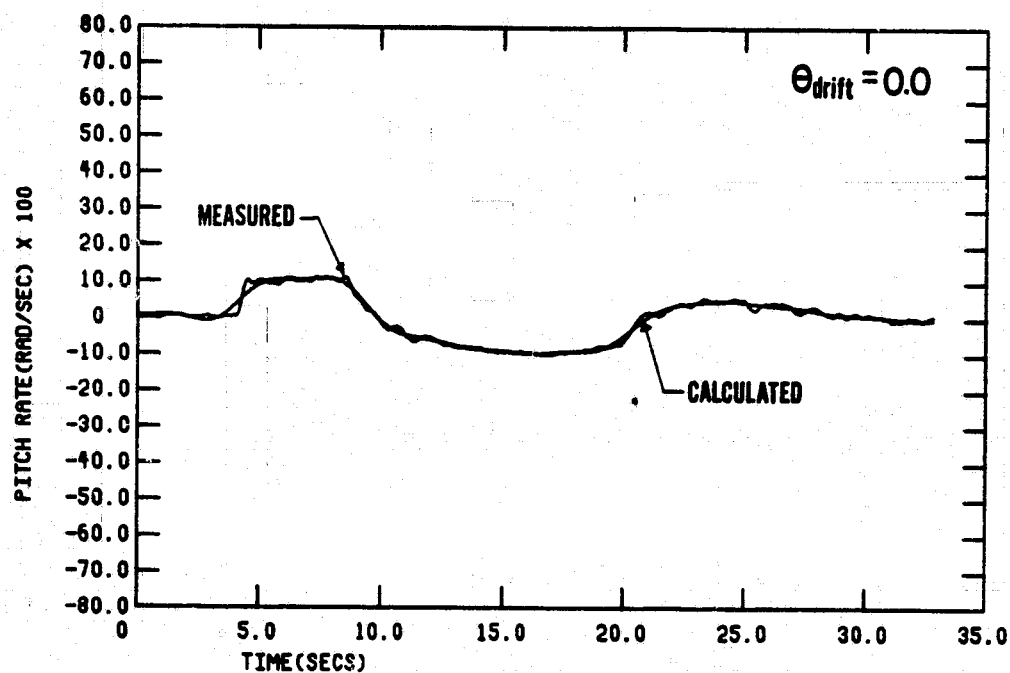
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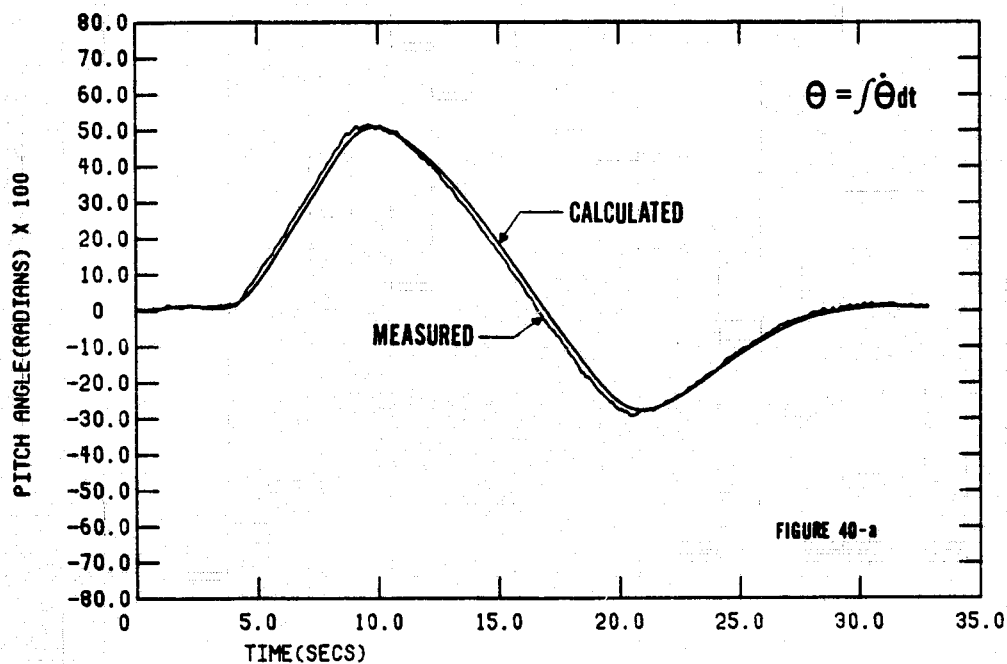
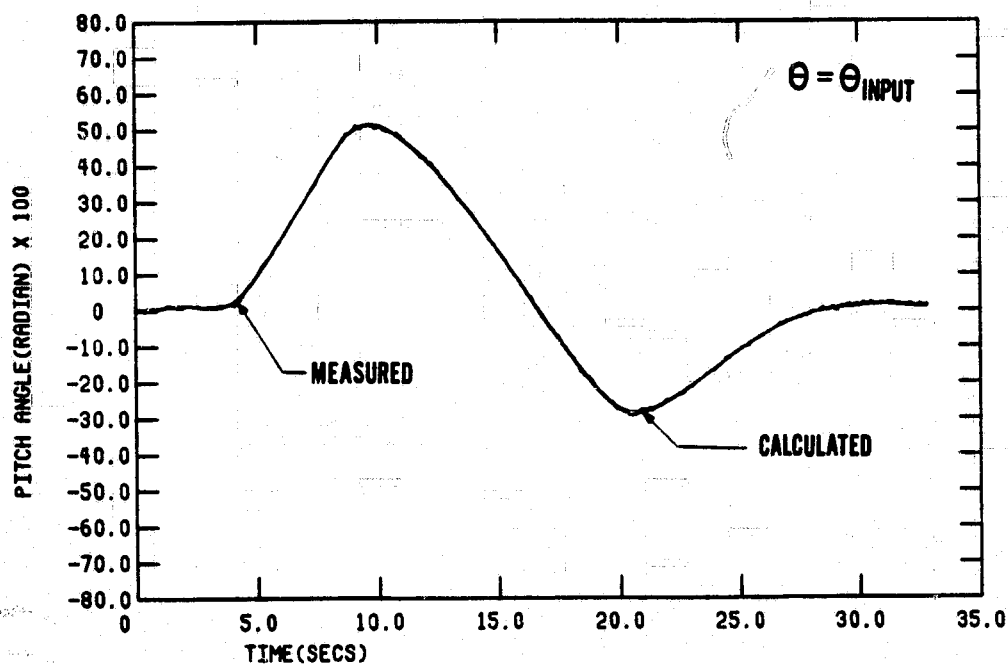
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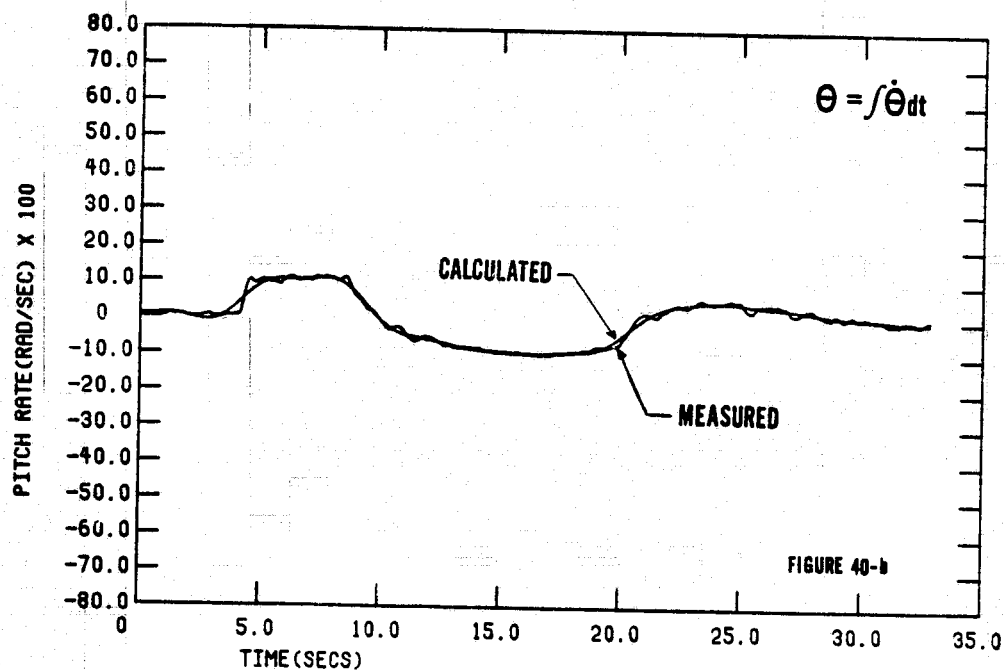
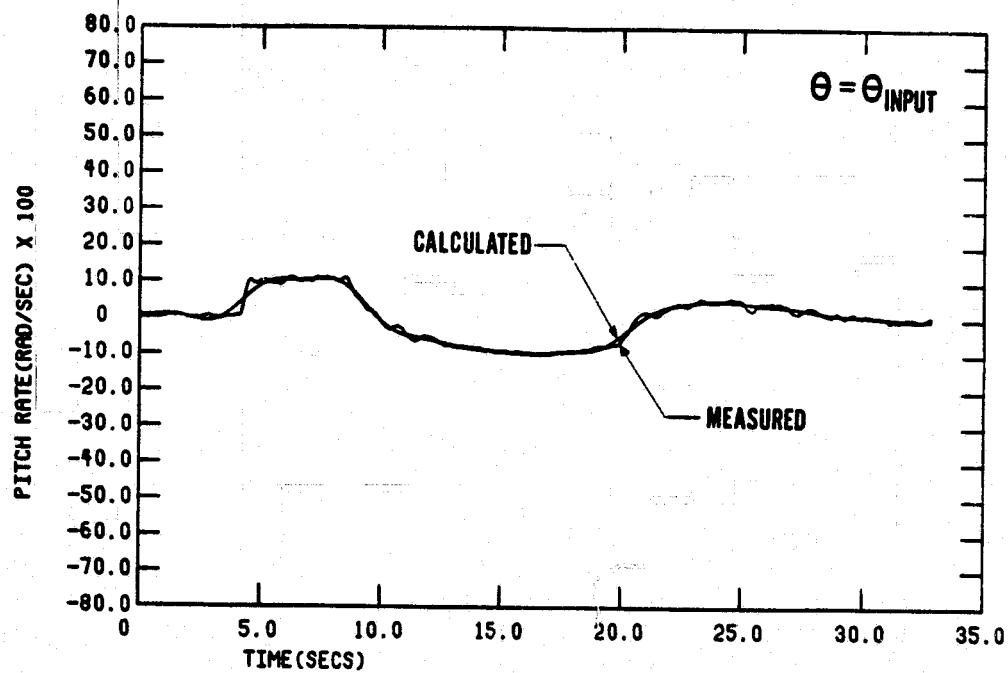
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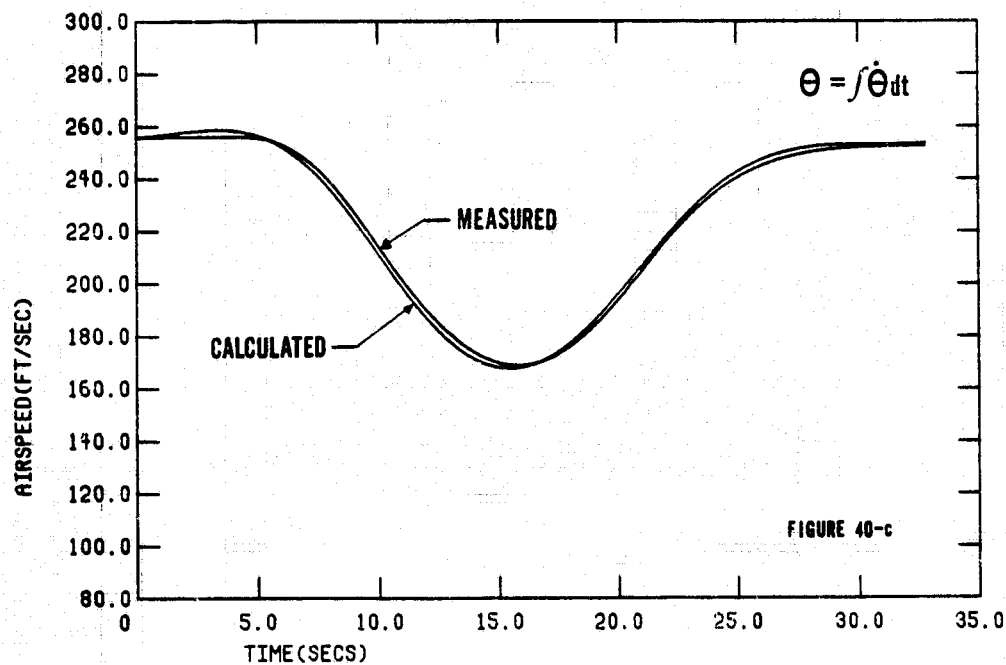
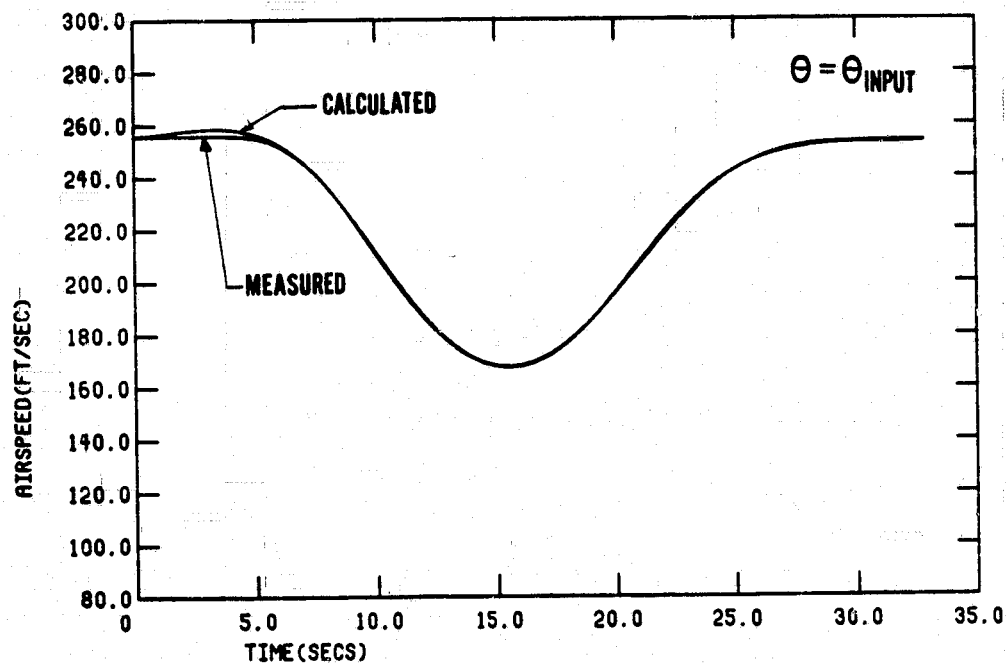
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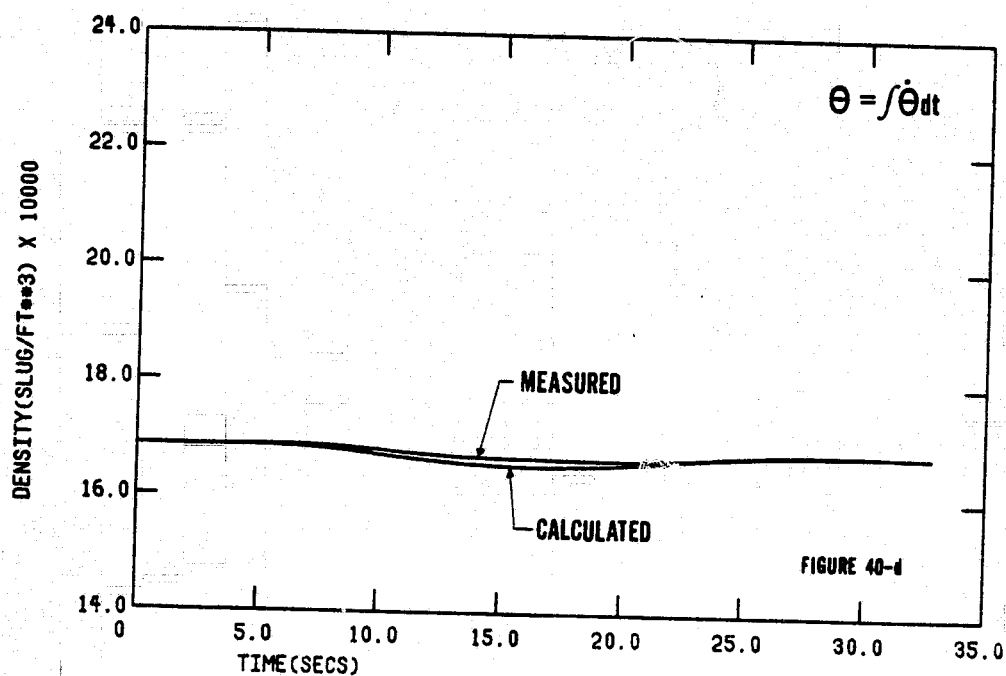
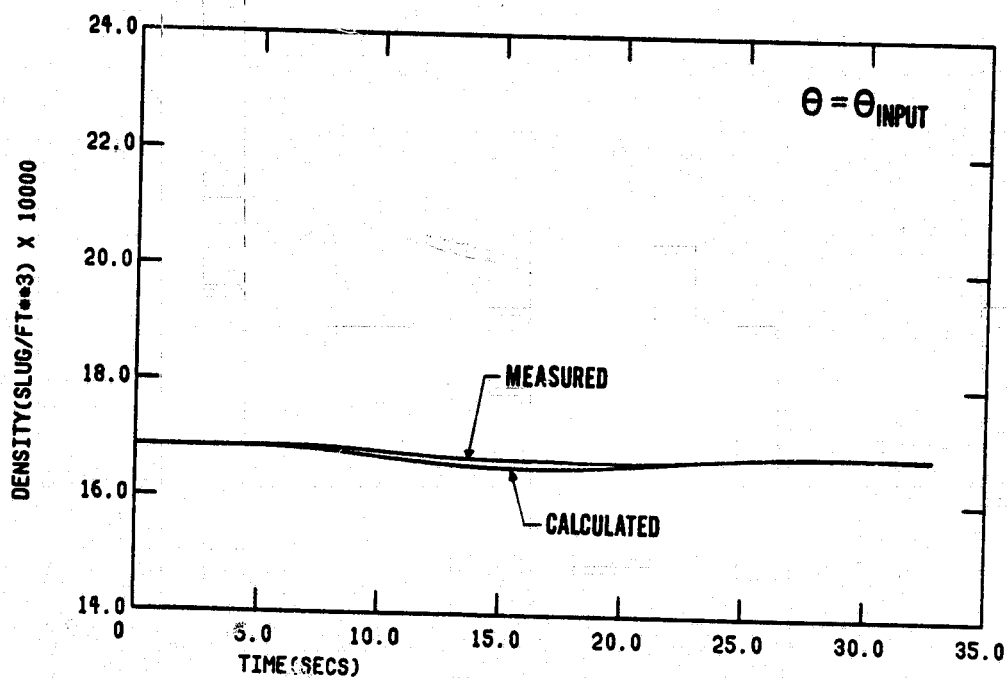
EFFECT OF USING $\int \dot{\theta} dt$ FOR θ IN CALCULATED SOLUTIONS. ASSUMED $\theta_{\text{drift}} = -0.025 \dot{\theta}/T$. ASSUMED $\propto$ POSITION ERROR CORRECTIONS GAIN 1.1538, BIAS -0.02 RADIANS.



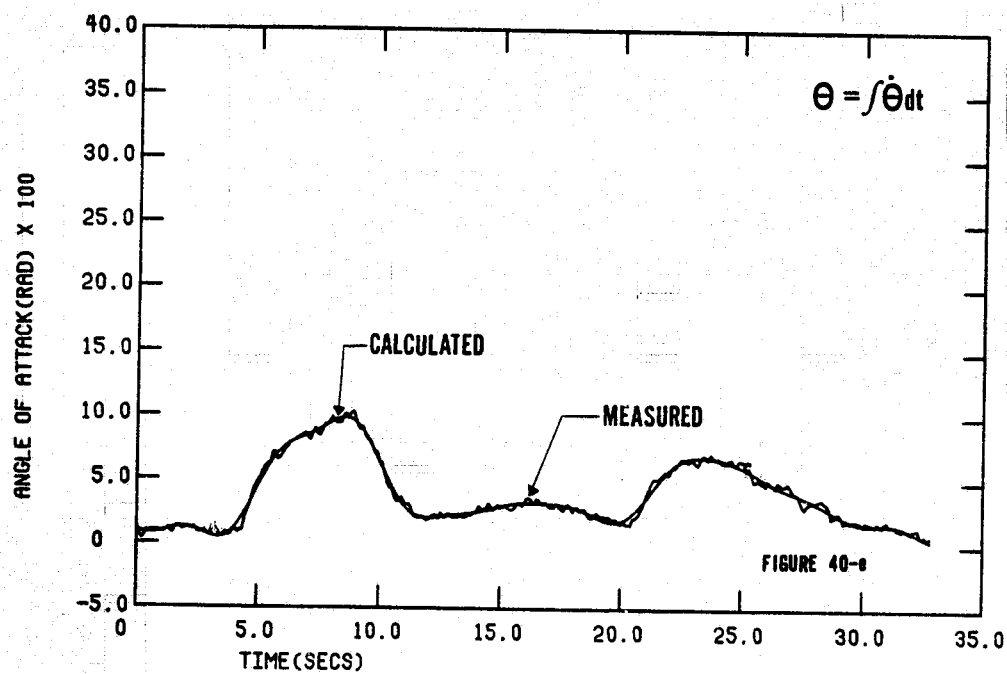
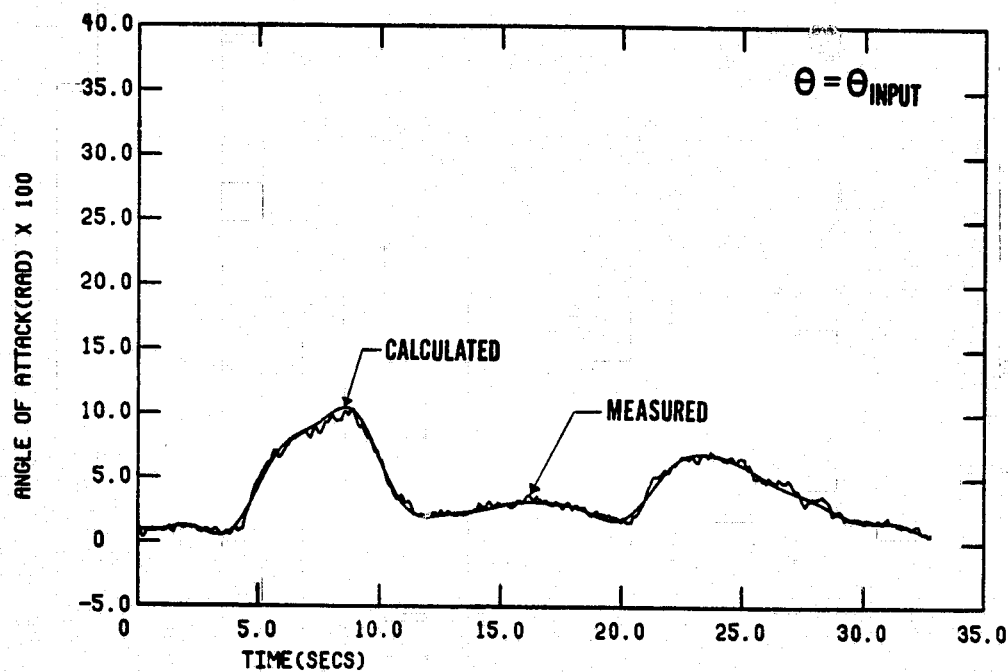
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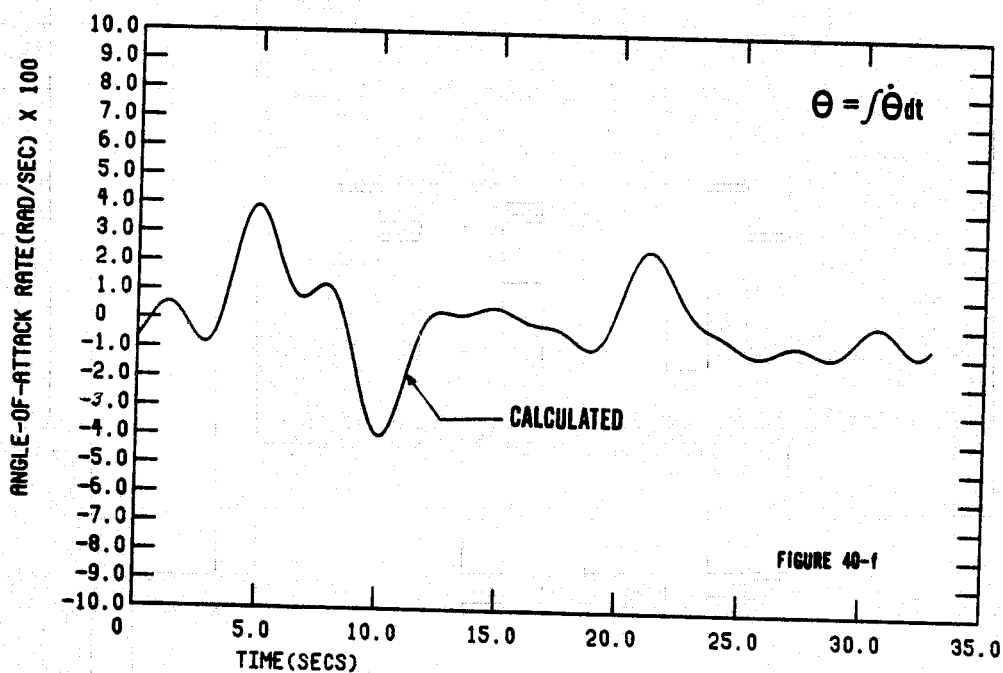
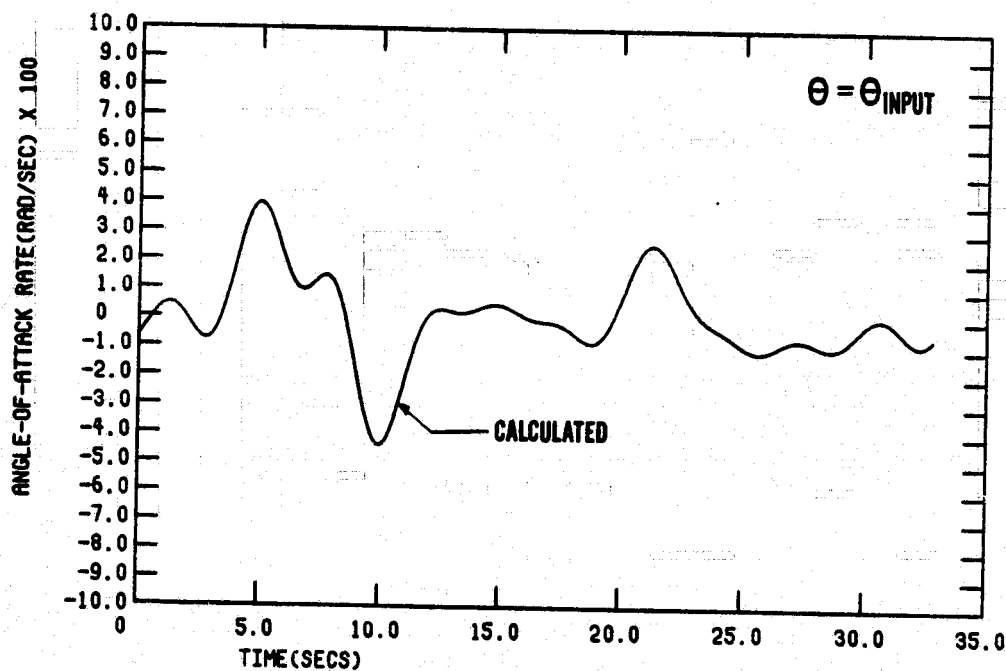
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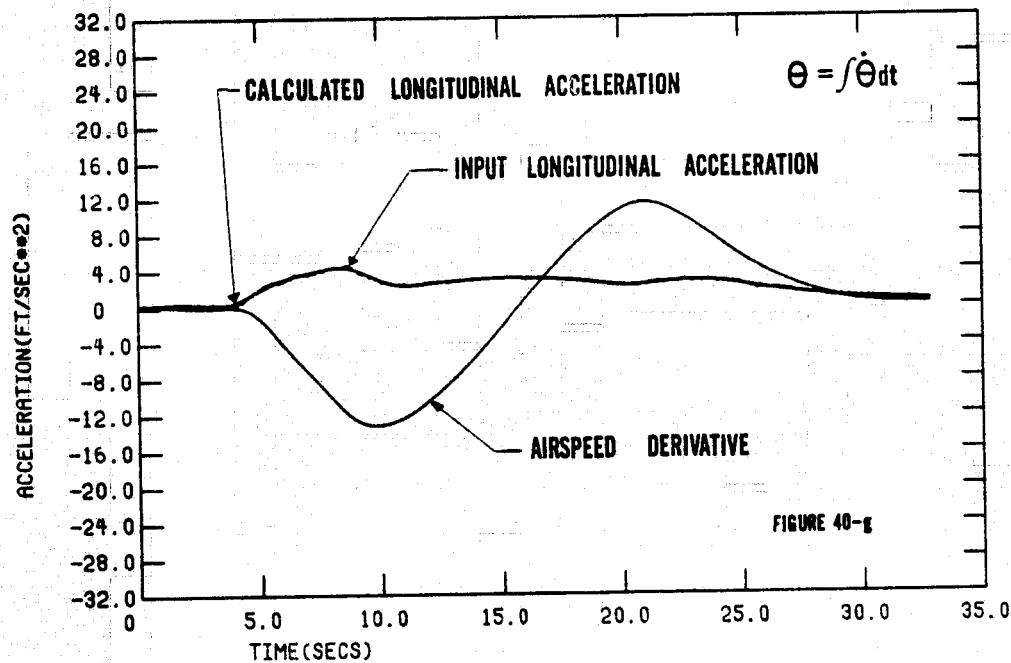
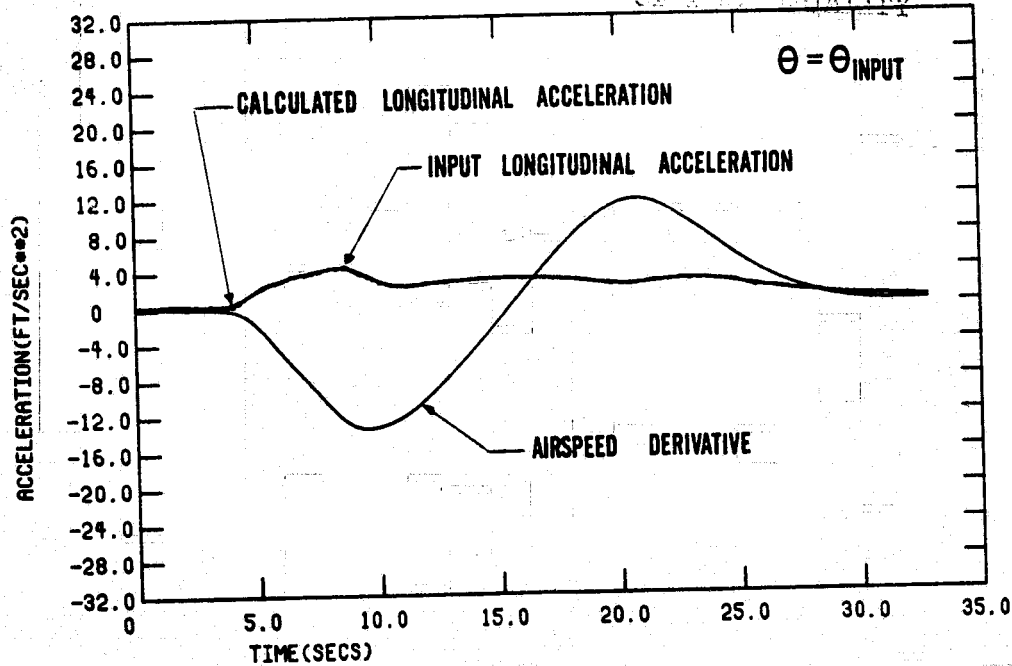


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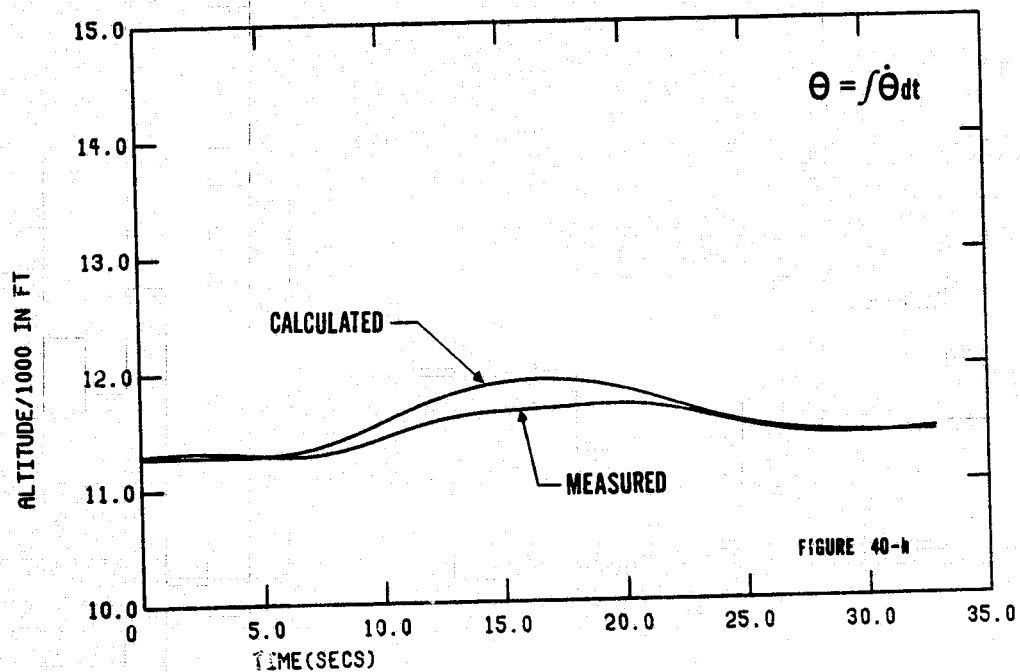
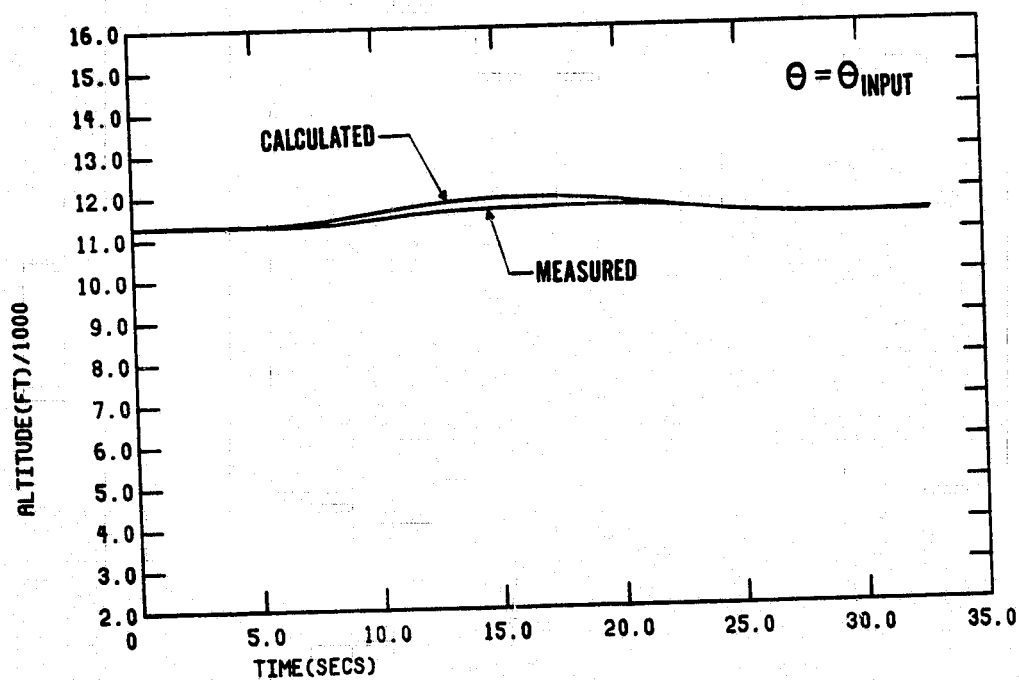


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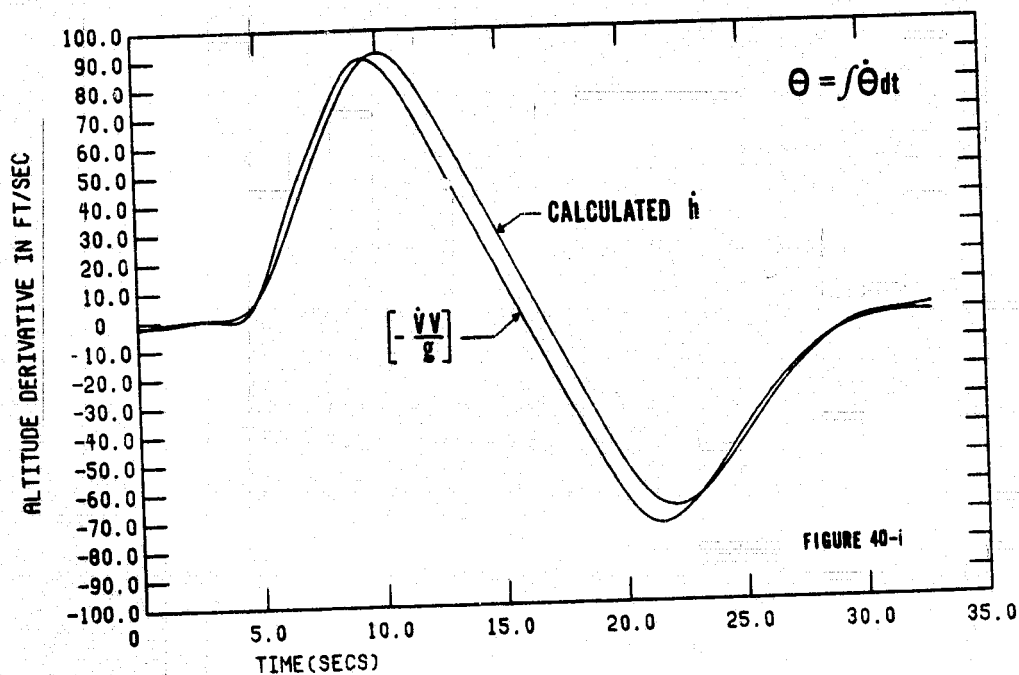
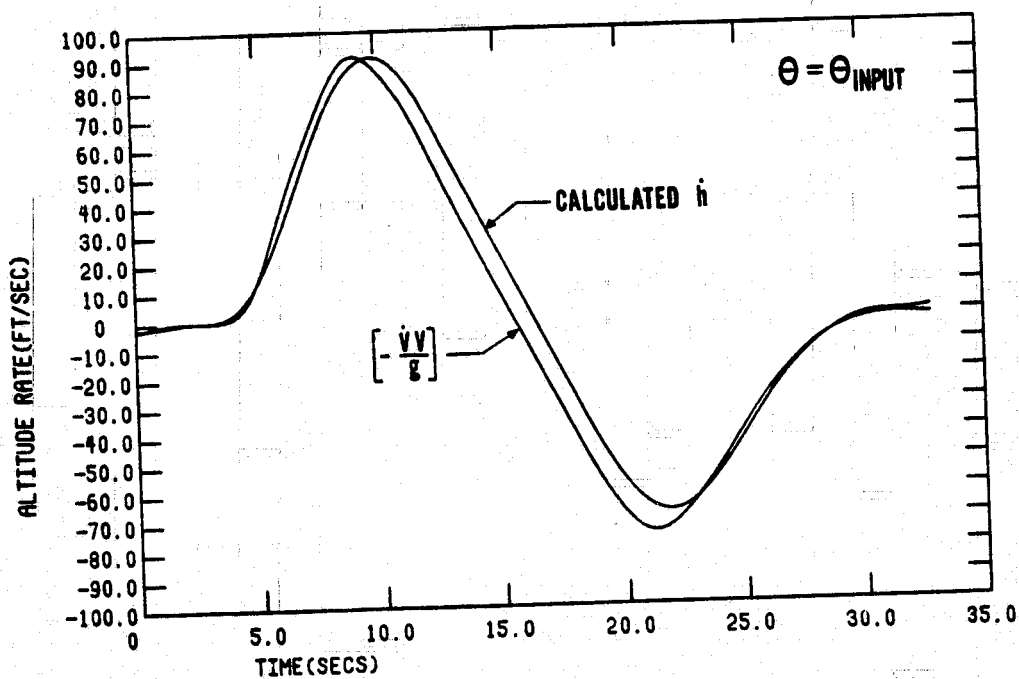
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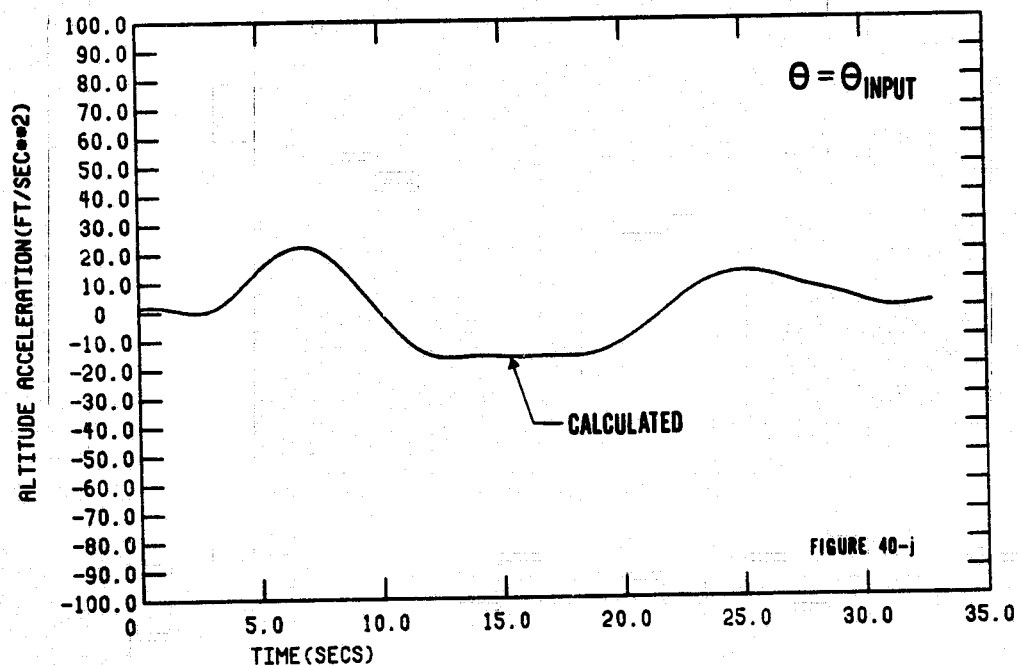
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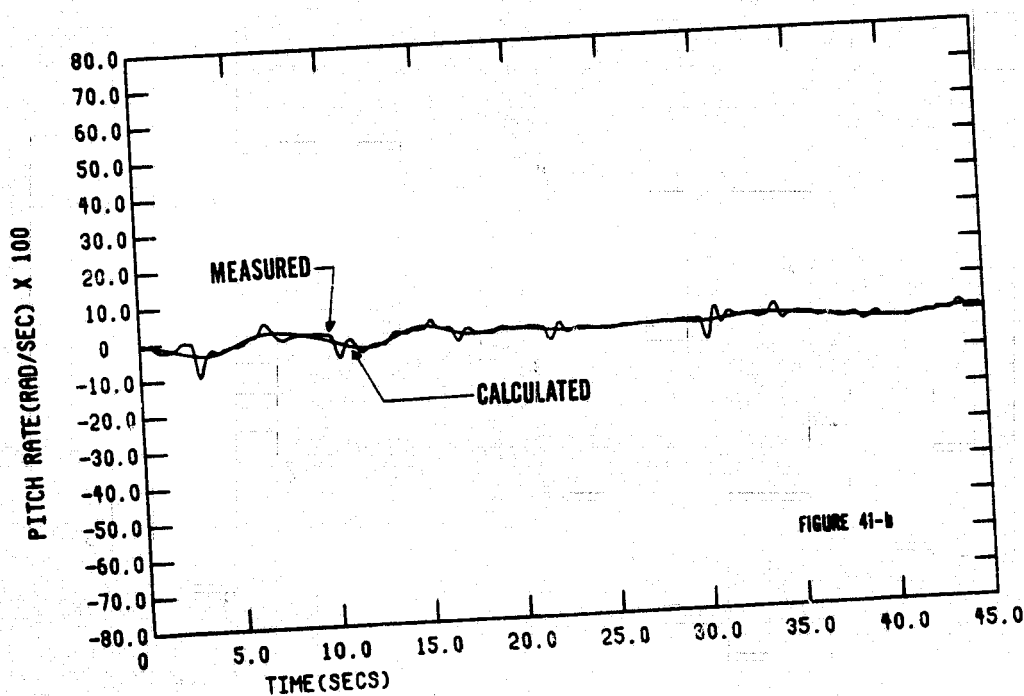
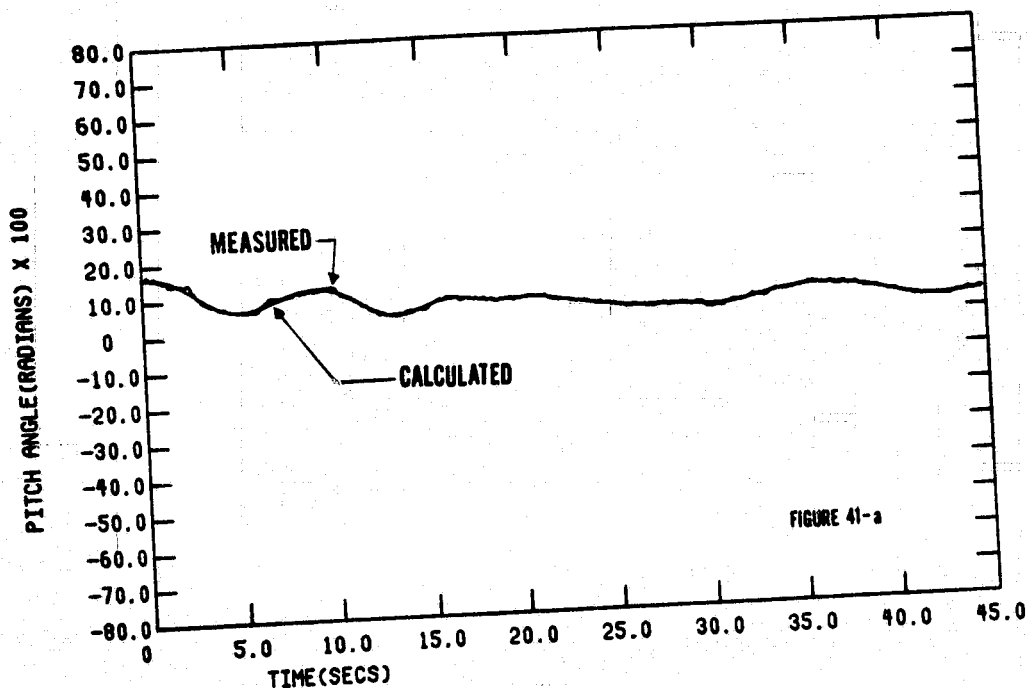
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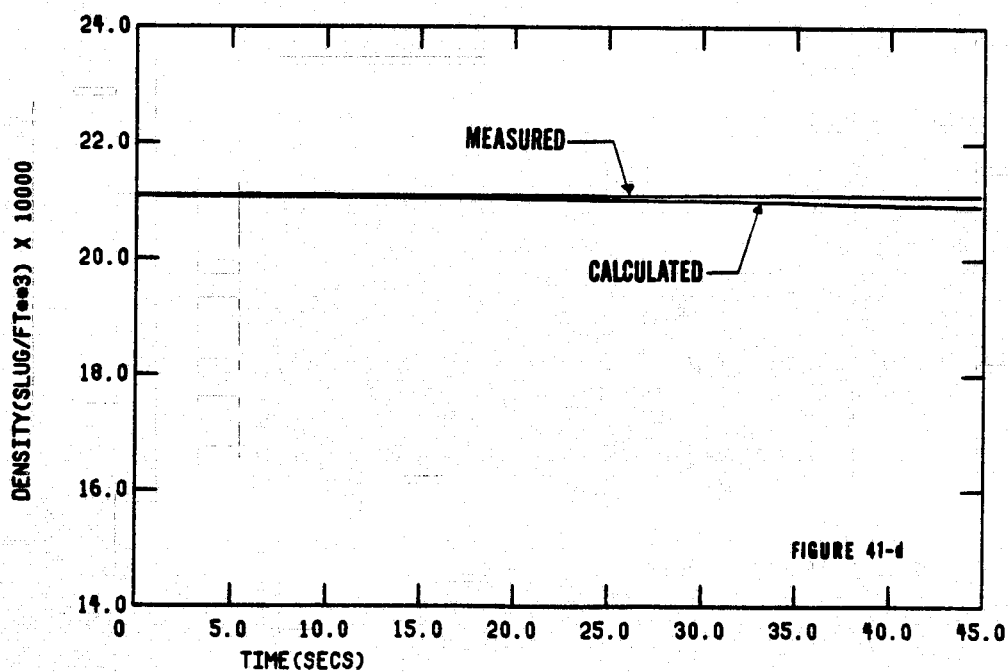
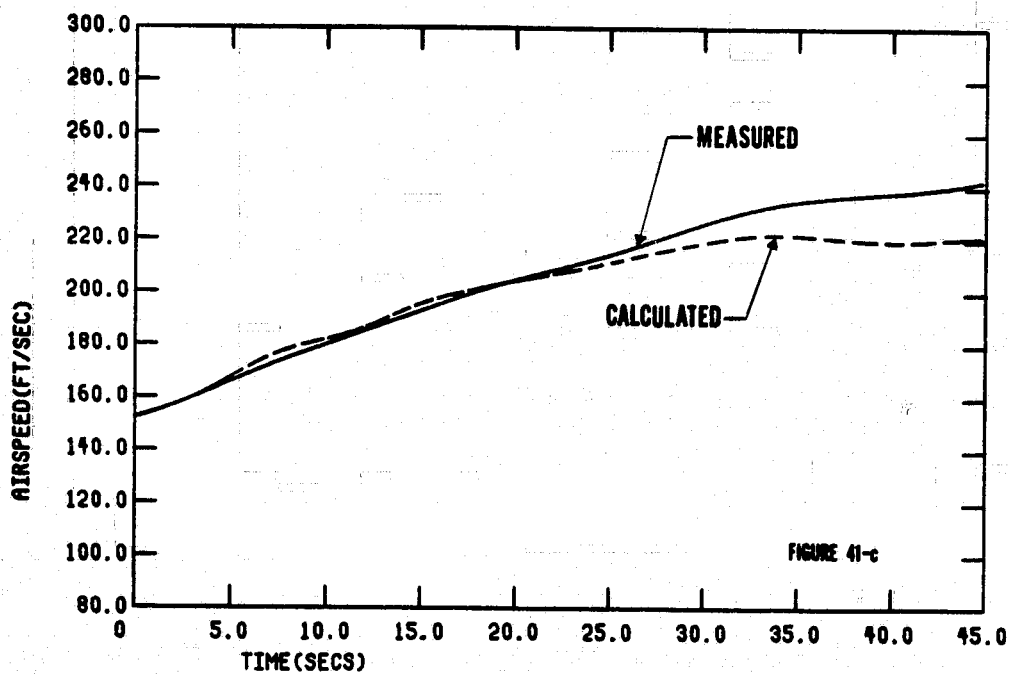
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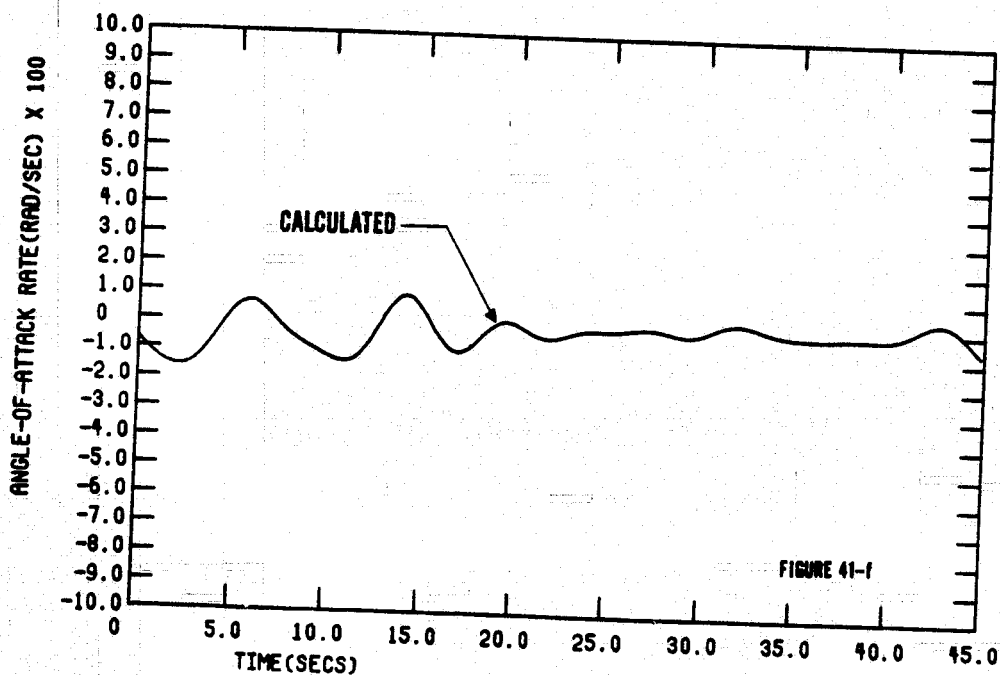
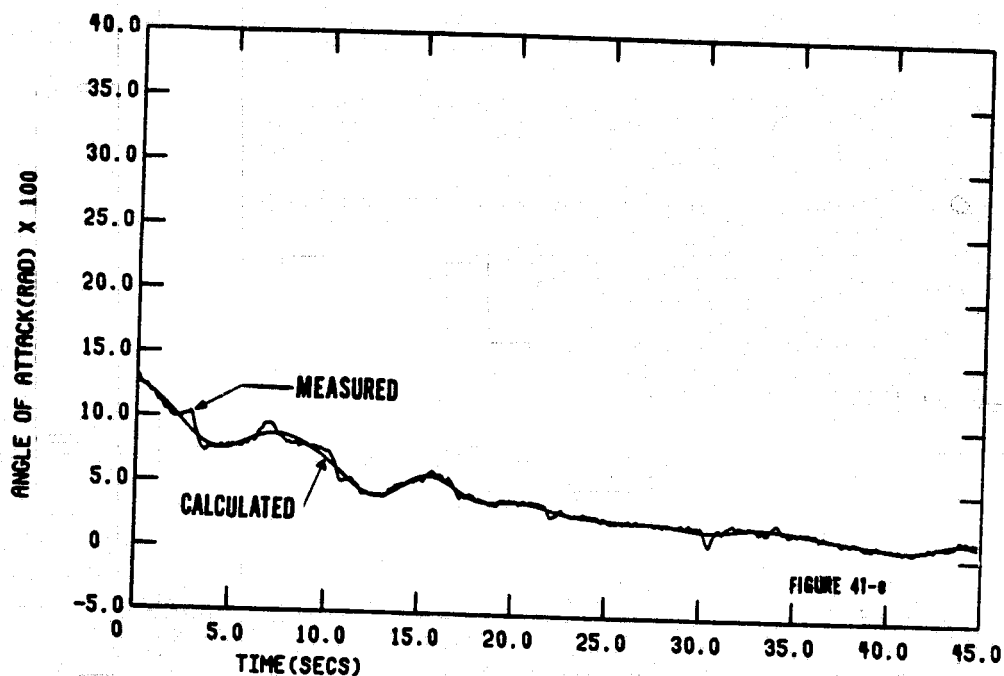
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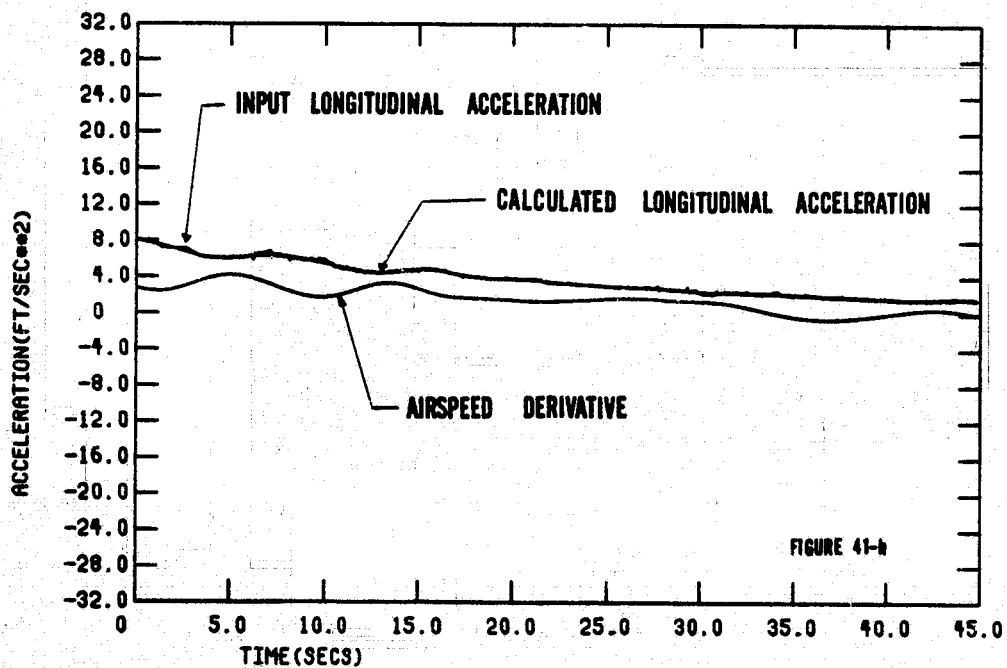
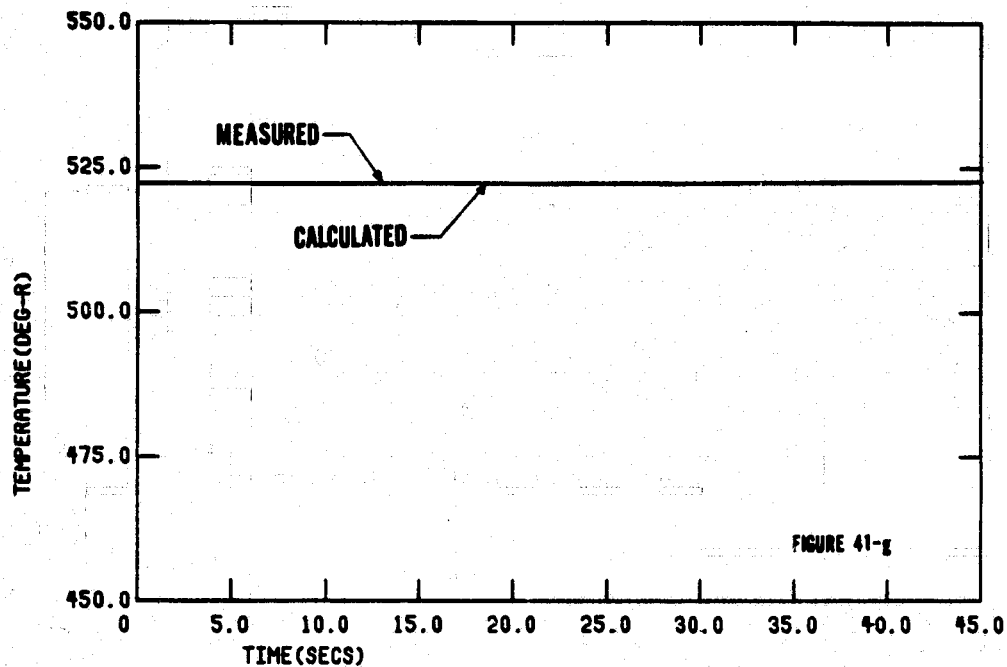
LEVEL FLIGHT ACCELERATION: COMPARISON OF
 MEASURED AND COMPUTED VALUES. NO θ
 DRIFT ASSUMED. $\propto$ POSITION ERROR CORRECTION:
 GAIN = 0.8667, BIAS = 0.0047.



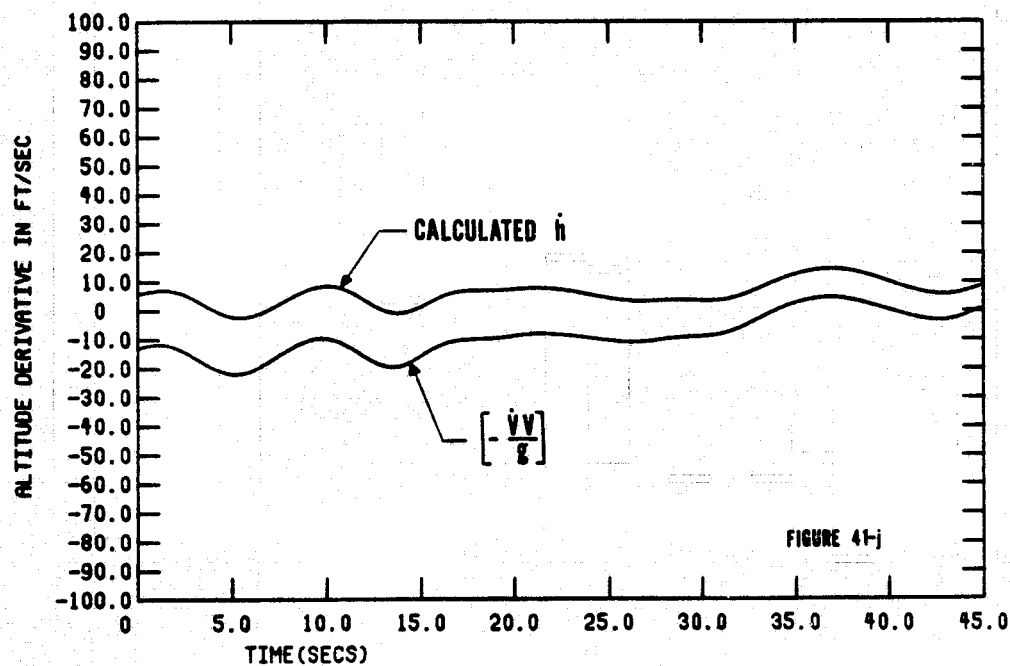
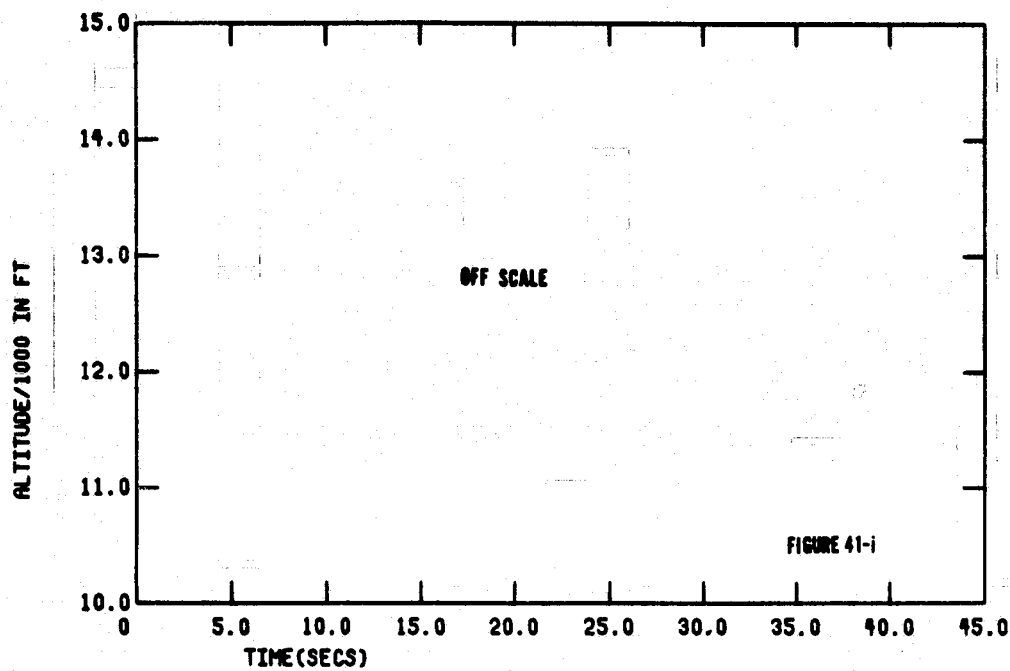
LEVEL FLIGHT ACCELERATION: COMPARISON OF MEASURED AND COMPUTED VALUES. NO θ DRIFT ASSUMED. $\propto$ POSITION ERROR CORRECTION: GAIN = 0.8667, BIAS = 0.0047.



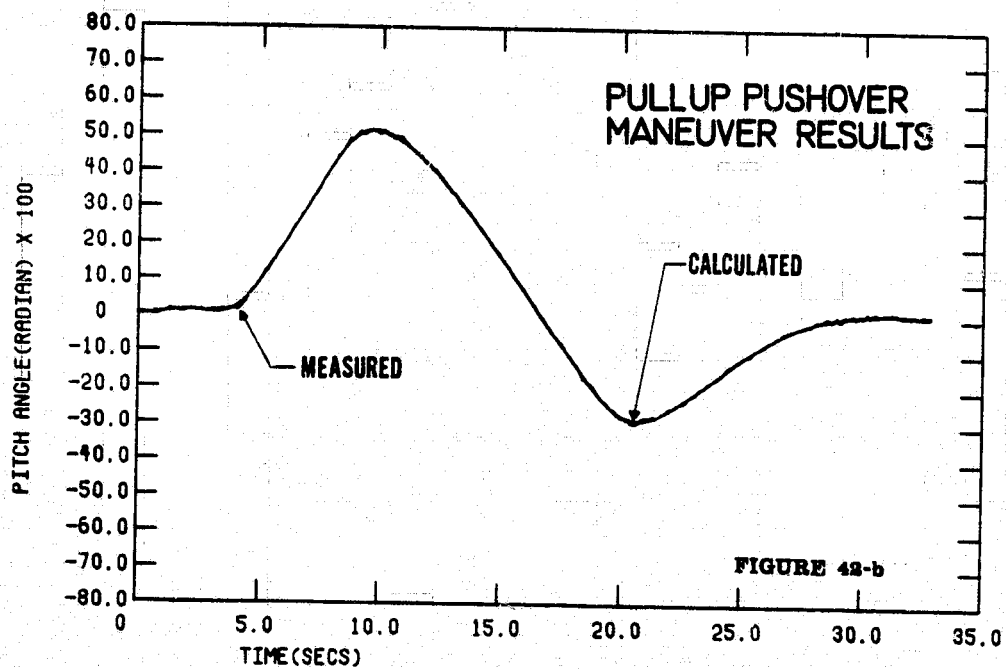
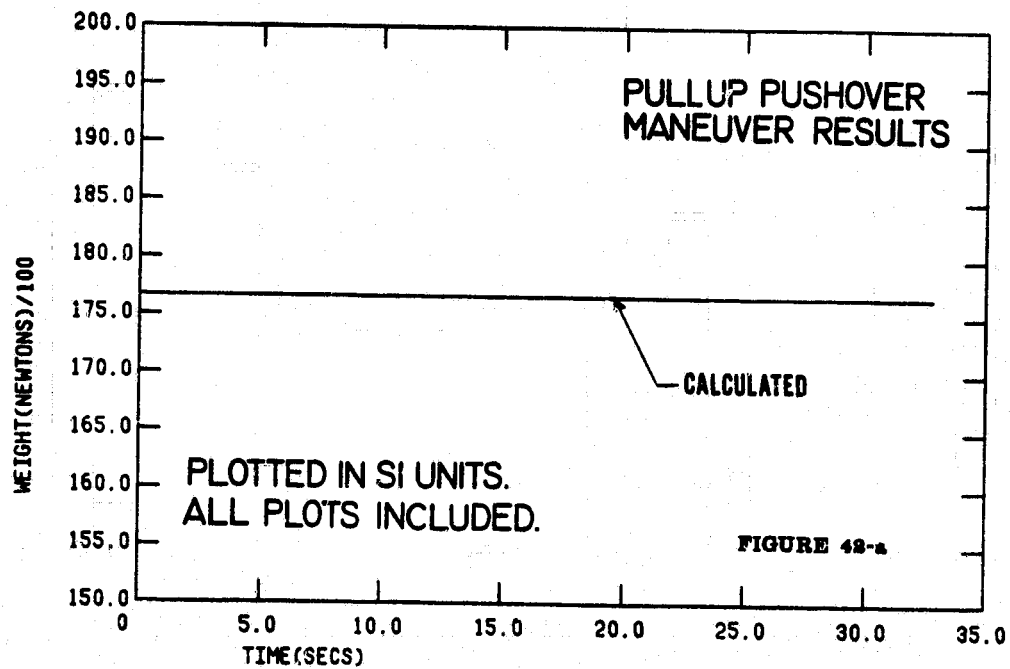
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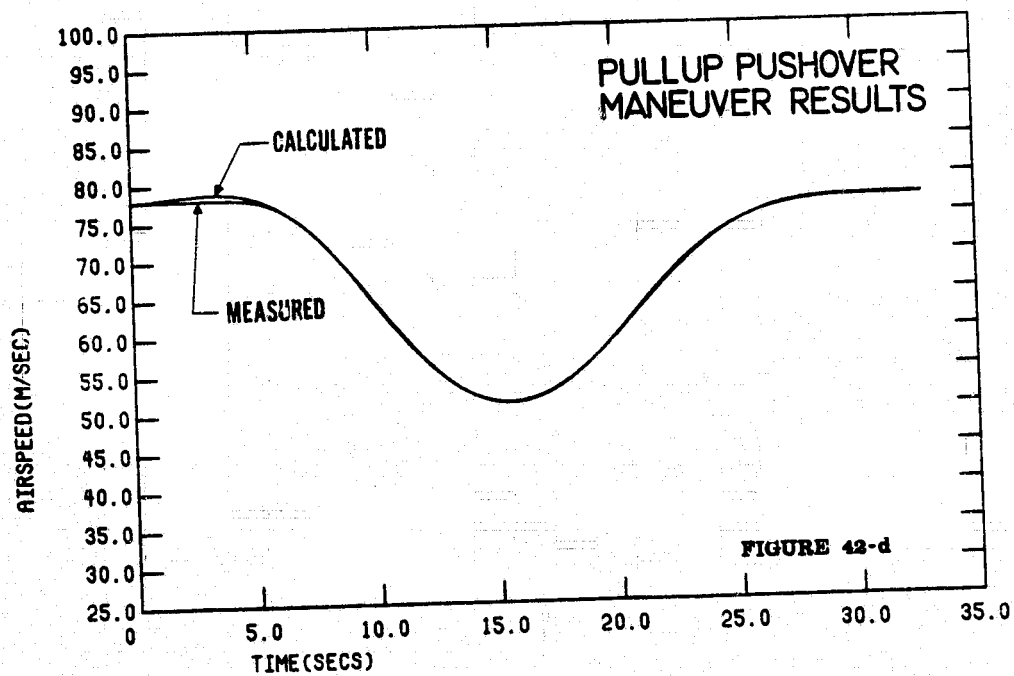
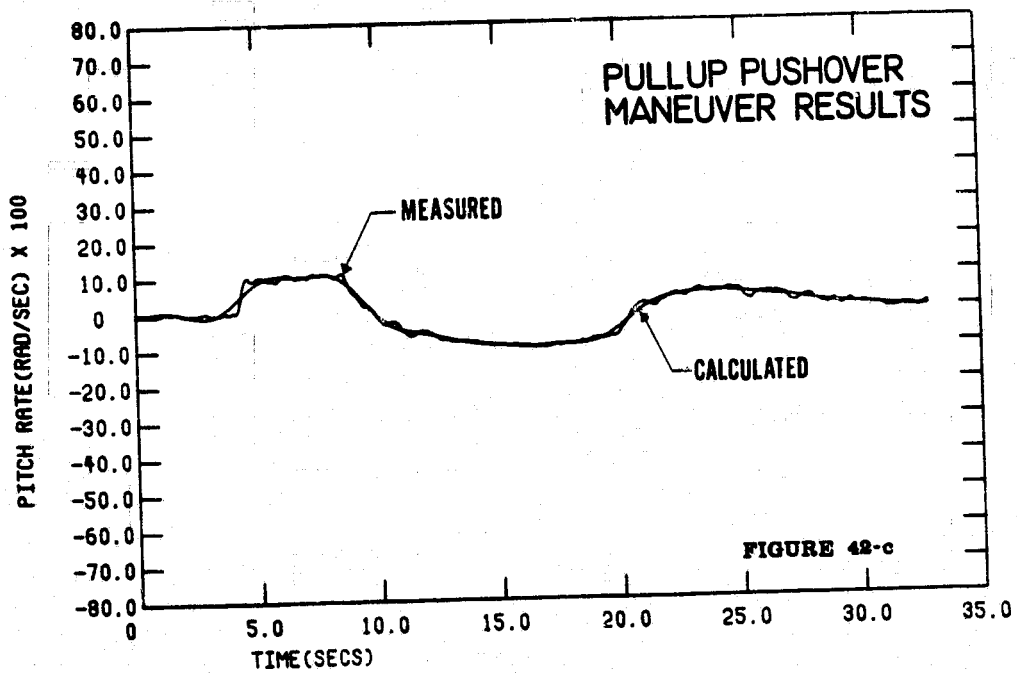


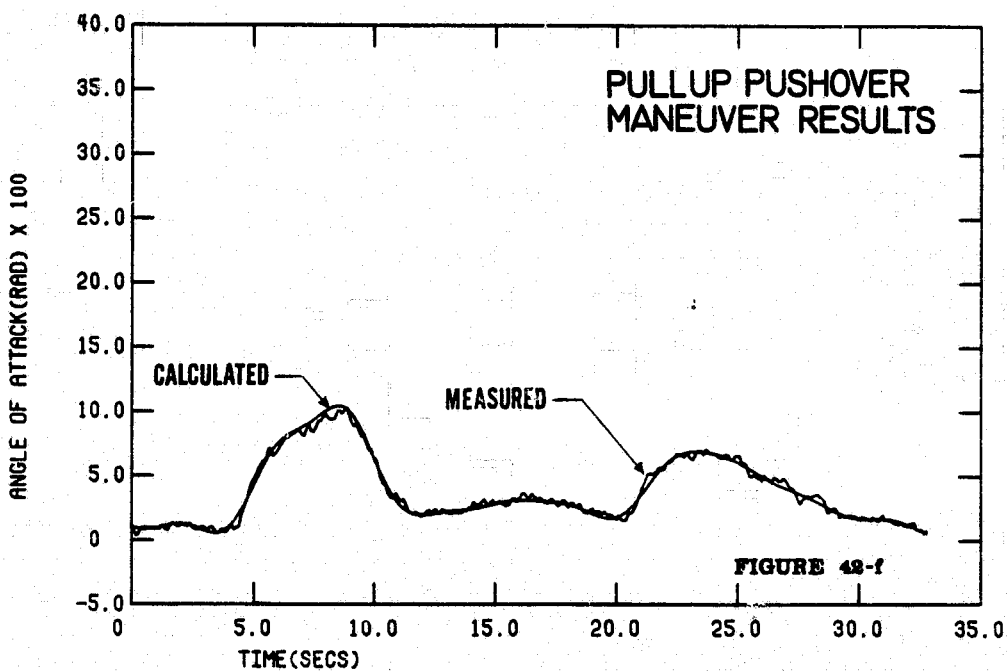
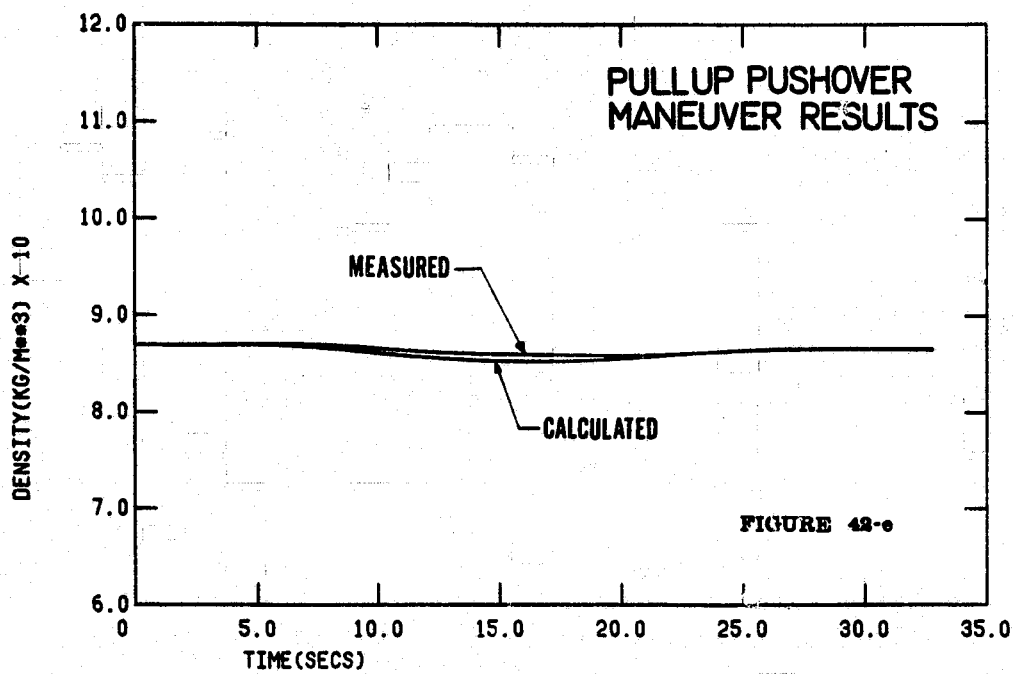
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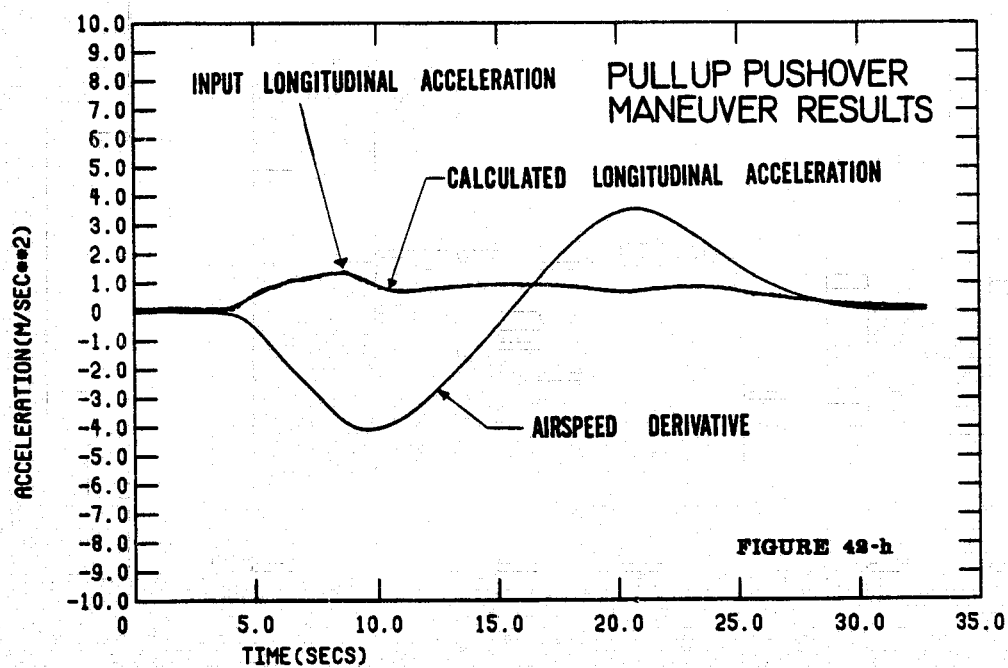
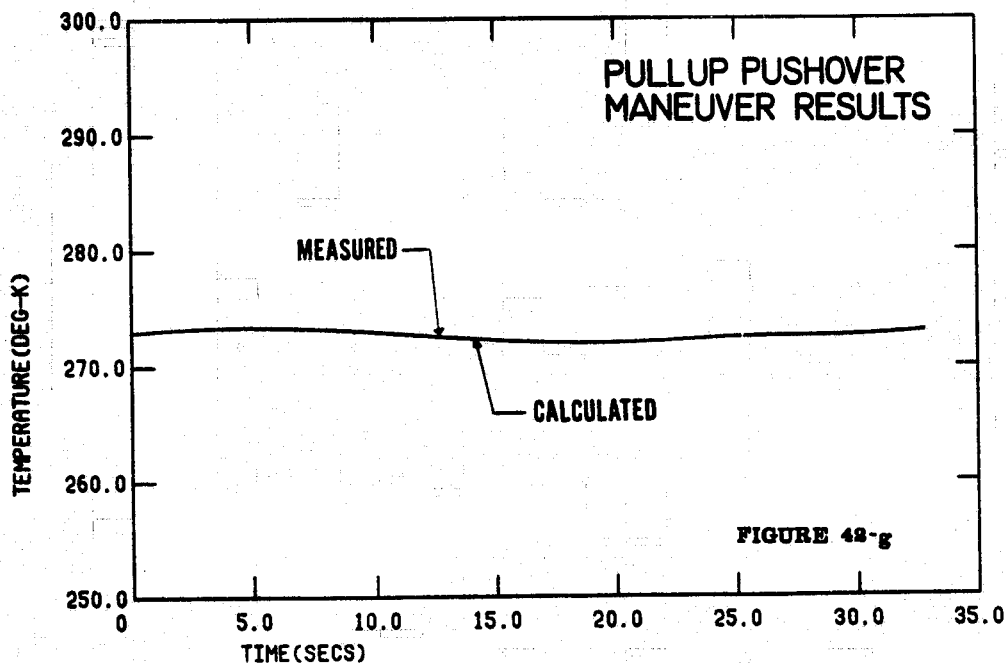


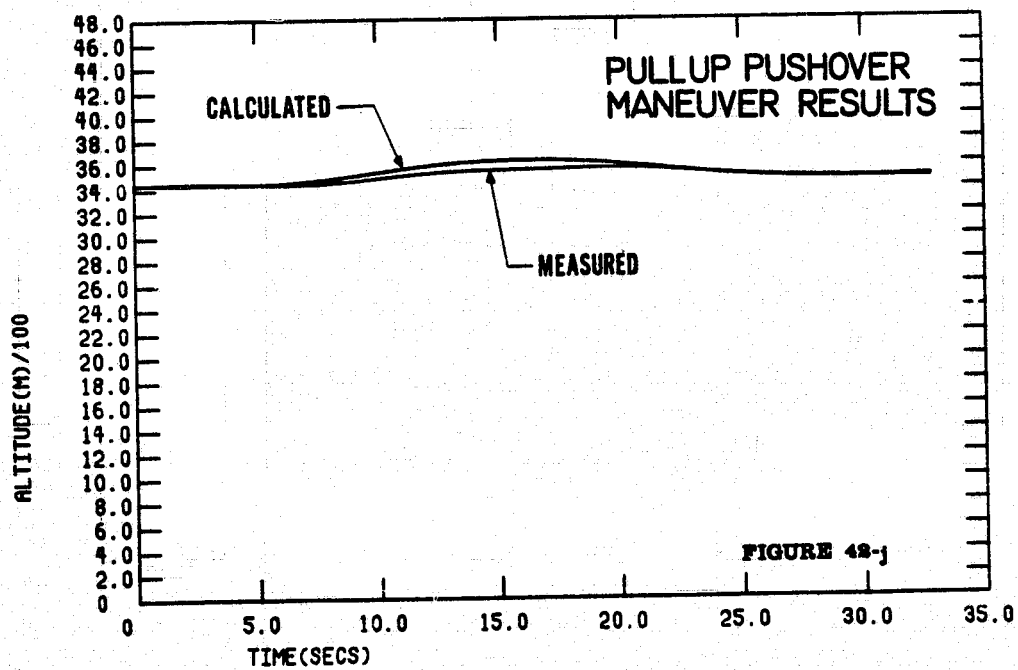
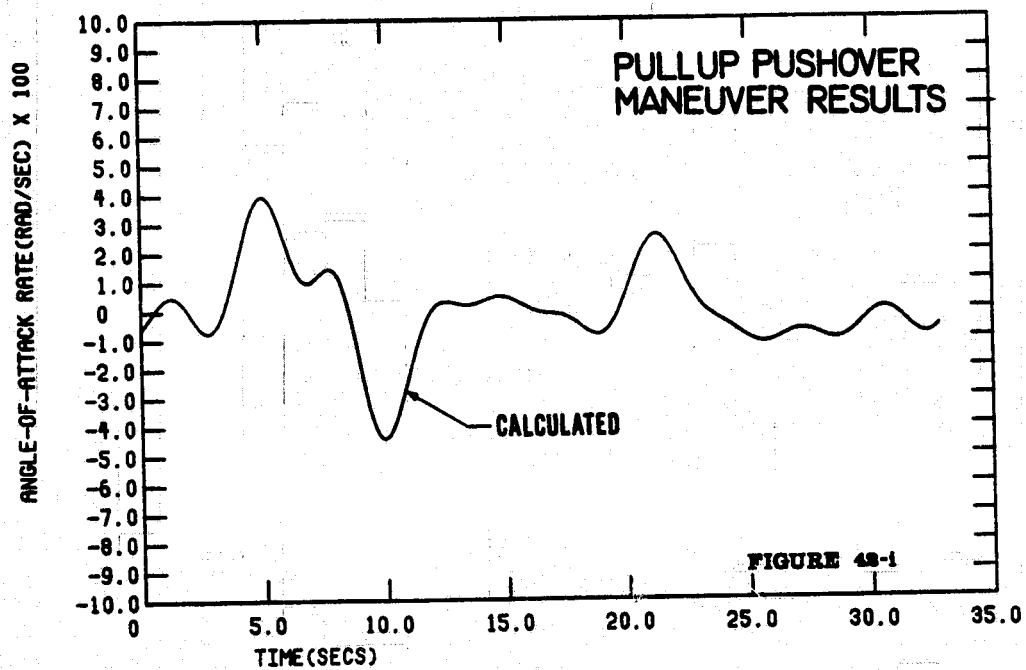
LEVEL FLIGHT ACCELERATION: COMPARISON OF
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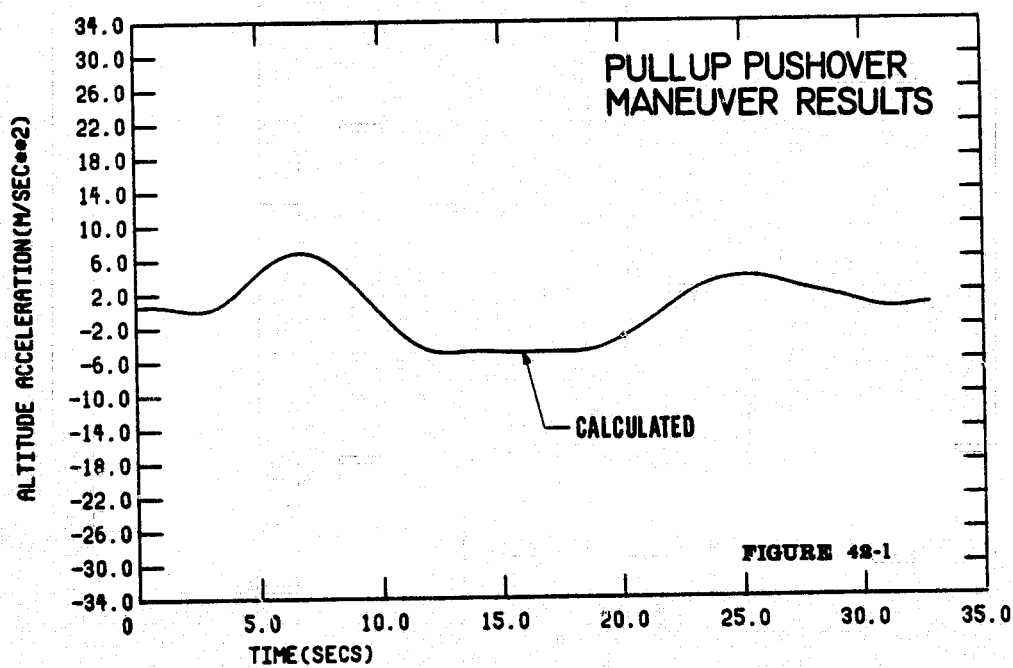
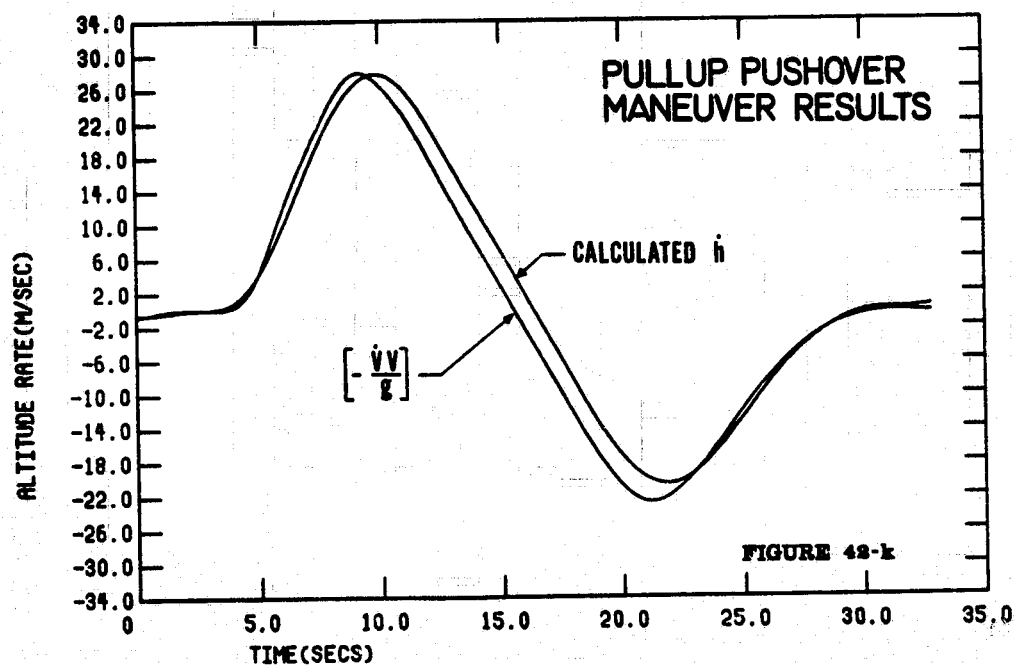


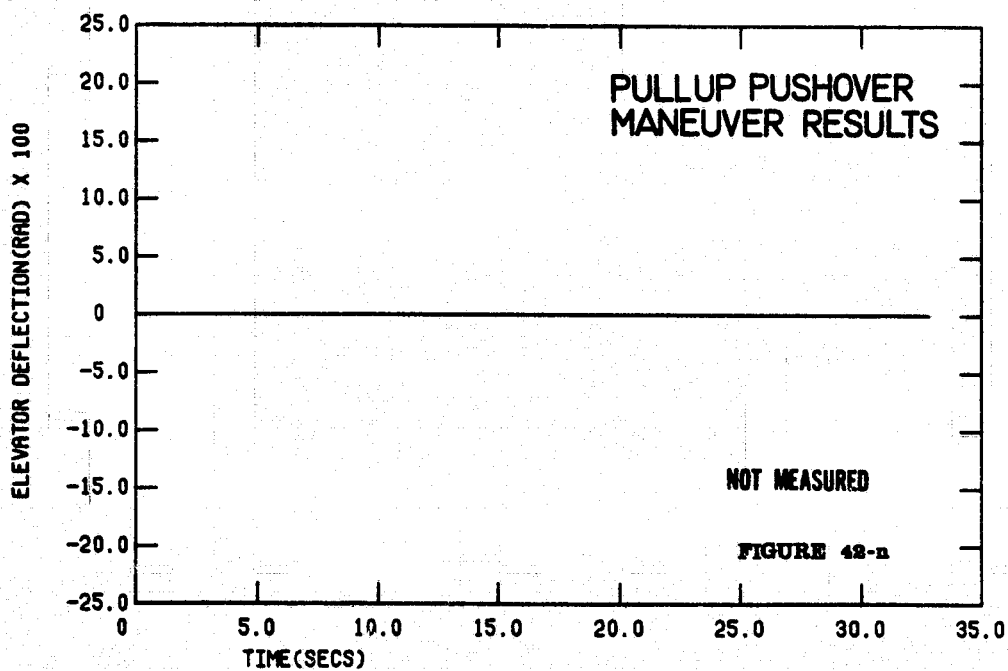
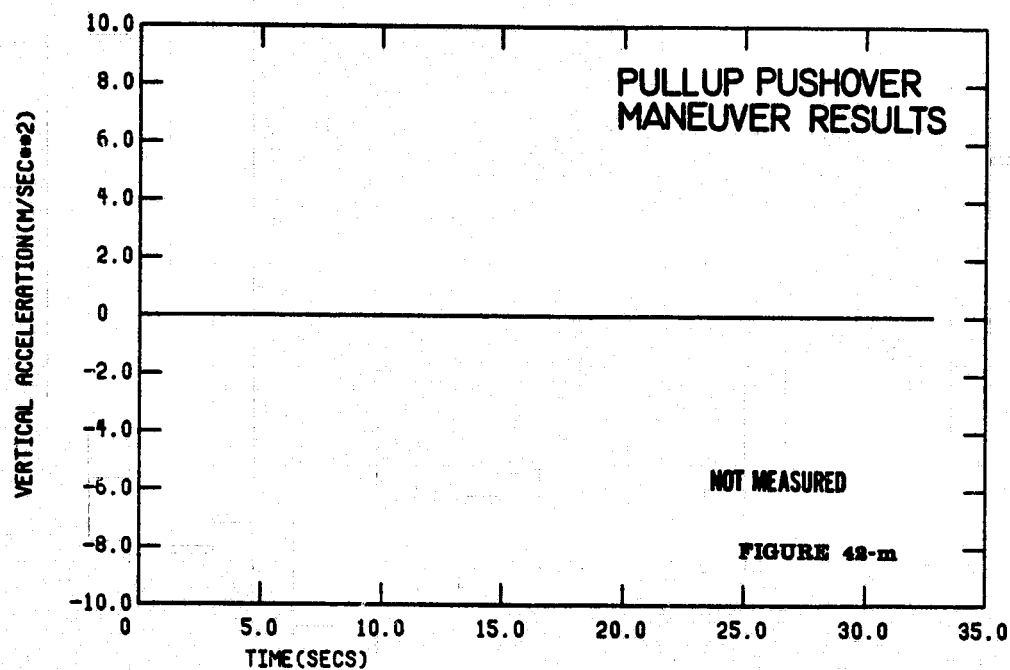












EXPERIENCE WITH FLIGHT DATA AFTER APPLICATION OF DATA COMPATIBILITY IMPROVEMENT PROCEDURE

Most of the problems encountered attempting to use actual flight data have been enumerated previously. As methods were developed to circumvent the gross inconsistencies present in the data, not surprisingly some smaller problems to the planned utilization of the data began to become apparent. These were of two types. The first is illustrated in figure 43. This shows θ corrected for bias error and drift plotted against the integral of $\dot{\theta}$ corrected for bias error for a pullup-pushover maneuver. Note that the functions begin and end near zero and the peaks lie on the 45° perfect correlation line. In between, however, there is a significant difference between the two measurements. Discussions with the flight crew revealed that it was extremely difficult to maintain a wing-level, yaw-rate-free attitude during the pullup-pushover maneuver. Since in three dimensions

$$\theta(t) = \int_0^t (g \cos \phi - r \sin \phi) dt + \theta_1,$$

it is quite apparent that a yaw rate (r) combined with a small bank angle (ϕ) can produce a significant departure in the integral of $\dot{\theta}$, i.e., q from that measured by a free gyro. Similarly, a reasonable bank angle alone can result in the integral of the rate trace being below the attitude gyro indication during pullups and above it during pushovers. This follows simply from the fact that the $\cos \phi$ term decreases the effective pitch rate. Note also that the effect is most pronounced when the pitch rate is greatest. Finally, there is a possibility that one of the gyros is mounted at a slight cant relative to the other, which would produce the same net effect.

The difference shown in figure 43 is sufficient to produce a rather significant difference in the extracted power and drag coefficients if one substitutes $\int \dot{\theta} dt$ for θ in the data submitted to the extraction procedure. For example, at maximum level flight speed the extracted thrust horsepower is about 22% greater if $\int \dot{\theta} dt$ is used than if θ is used. The lower figure is more consistent with that expected, given engine and propeller test data. The fit error with $\int \dot{\theta} dt$ is also about a factor of 2 greater than with θ . For these reasons it seems advisable to employ θ in place of $\int \dot{\theta} dt$.

The second type of problem which became apparent after some experience with the results of the data compatibility procedure is the extent to which one could specify a priori the correct form of the lift and drag models. It had been assumed initially that the maneuvers were sufficiently slow that contributions from terms such as C_{L_α} , C_{D_α} , $C_{D_\dot{\theta}}$, and $C_{L_\dot{\theta}}$ could be safely ignored. Inclusion of such terms in the model extractions lowered the fit errors by a factor of two or more. Further, the values of C_{L_α} , $C_{L_\dot{\theta}}$, etc,

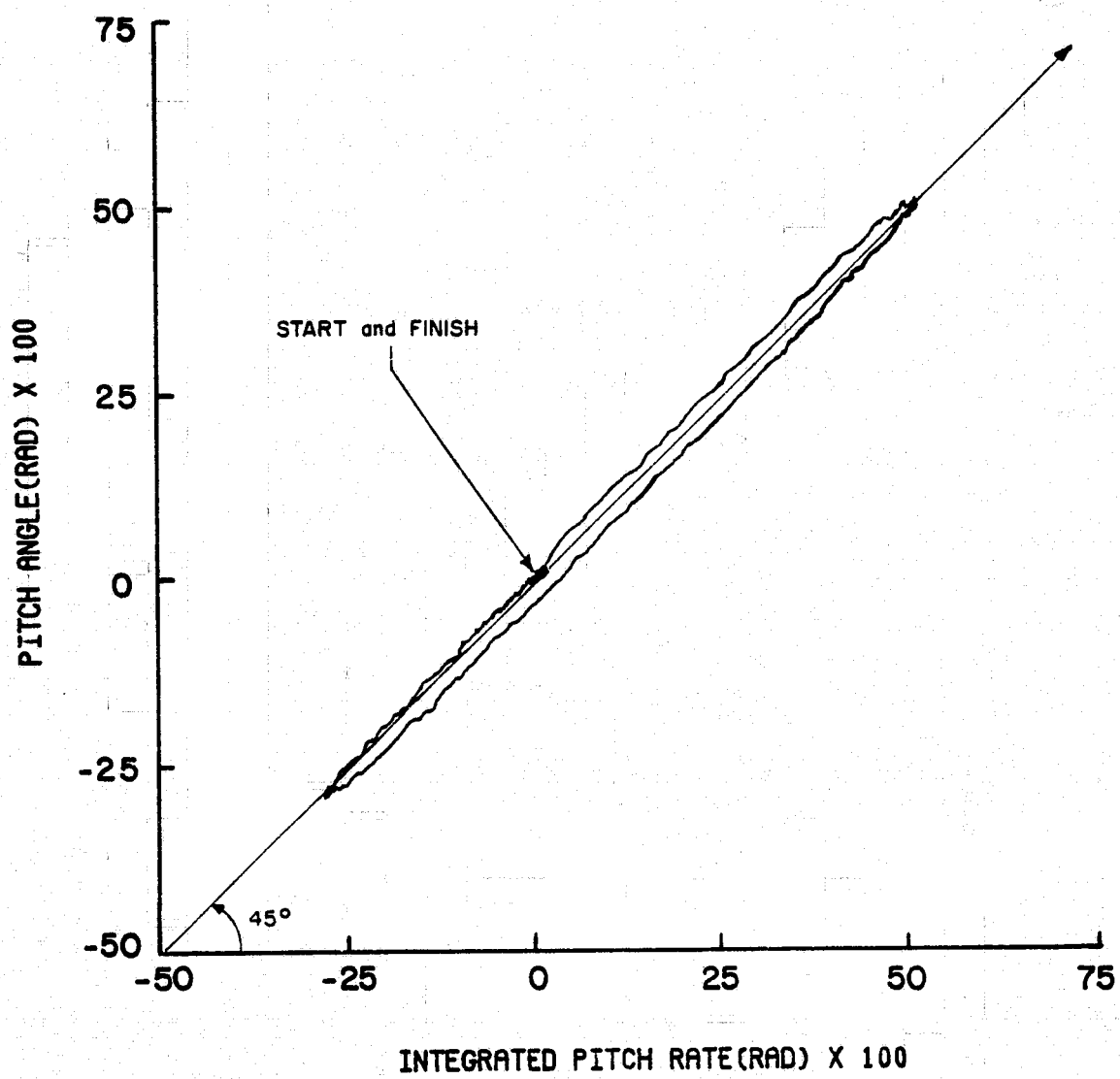


FIGURE 43

extracted indicated these terms could contribute as much as 10% to the overall C_L or C_D . Thus, it seems desirable to include these terms in the procedure whenever possible. That these terms would be important for the ATLIT airplane was not appreciated until the development work on the Noise Reduction -- Newton-Raphson procedure was almost complete and the end of the grant period was near at hand. Because of the very considerable time necessary to expand the computer program to accommodate these additional parameters, it was not possible to undertake this task for the present report. Instead, an expanded version of the initial least squares parameter extraction procedure was prepared. (MDLCK. See Appendix B for description). Most of the ATLIT results discussed in the next section were obtained using this limited procedure. An assessment of the validity of the parameter values obtained by this procedure can be obtained by comparing the fit error obtained with that found at various stages in the test case (random computation of the α -channel).

OTHER APPROACHES TO THE PROBLEM

Gerlach's Method

While the method described in the present report to find both the drag and the power from accelerated flight data was developed specifically for the ATLIT test program, it is similar in some respects to the scheme outlined by Gerlach (Ref. 9) in a 1970 SAE Business Aircraft Meeting paper. Subsequent results are discussed in Ref. 10. Gerlach assumes, for example, that while the engine brake horsepower is known a priori (as a function of manifold pressure and RPM), the actual power into the airstream is a quadratic function of this brake horsepower. His procedure is intended to yield the values of the three coefficients in this quadratic function. Similarly, he assumes a simple parabolic drag polar and a linear lift curve and the procedure is intended to yield values of $C_{D_{min}}$, span efficiency factor, $C_{L_{\alpha}}$, and $C_{L_{\alpha=0}}$.

The data time histories used in the extraction process are obtained as follows:

$$\alpha = \theta - \sin^{-1} \left[\frac{\Delta h_p - \int_0^{t_f} (Ax \sin \theta - Az \cos \theta - g) dt^2}{\frac{\Delta t}{V}} + \frac{\int_0^{t_f} (Ax \sin \theta - Az \cos \theta - g) dt}{V} \right] \quad (152)$$

$$\theta = - \tan^{-1} \frac{Ax}{Az} \Big|_{t=0} + \int_0^{t_f} \dot{\theta} dt \quad (153)$$

Here V is determined by the usual pressure and temperature instrumentation. Δh_p is the total change in altitude represented by the maneuver according to static pressure instrumentation, Δt is the total time of the maneuver, t_f the time at the end of the maneuver and Ax and Az are accelerometer indications along the body axes.

Gerlach indicates that the α , θ , and γ values obtained this way are inadequate because of slight inaccuracies in the determination of initial values and small zero shifts in Ax , Az , and $\dot{\theta}$. He then proceeds to find corrections for these errors by writing:

$$\Delta h(t) = \Delta h_0 + \Delta \theta_0 K_1(t) + \Delta \dot{h}_0 K_2(t) + \Delta A x_0 K_3(t) + A z_0 K_4(t) + \Delta \dot{\theta}_0 K_5(t) + \epsilon_h \quad (154)$$

where the $\Delta h(t)$ is the difference in the altitude obtained from pressure data and integration of the accelerometers; $\Delta \theta_0$, $\Delta A x_0$, $\Delta A z_0$, $\Delta \dot{\theta}_0$, $\Delta \dot{h}_0$ are initial bias errors, ϵ_h is the noise component of Δh , and Δh_0 is a remaining constant which should turn out to be zero. The variables $K_1 \dots K_5$ are said to be known functions of time but the method by which they are obtained is not given in the paper. Gerlach performs the same operation with regard to the difference in airspeed obtained from pressure data and accelerometer integrations. Using regression analysis, Gerlach finds corrections to his data. The corrected α , $\dot{\theta}$, h , and V data are then used in a system of equations

$$C_x = C_{x_0} + C_{x_{\Delta P+}} \left(\frac{\Delta P+}{\frac{1}{2} \rho V^2} \right) + C_{x_\alpha} \alpha + C_{x_{\alpha^2}} \alpha^2 + C_{x_{\dot{\alpha}}} \frac{\dot{\alpha}}{V} \quad (155)$$

$$C_z = C_{z_0} + C_{z_{\Delta P+}} \left(\frac{\Delta P+}{\frac{1}{2} \rho V^2} \right) + C_{z_\alpha} \alpha + C_{z_{\dot{\theta}}} \frac{\dot{\theta}}{V} + C_{z_{\delta_e}} \delta_e \quad (156)$$

$$C_m = C_{m_0} + C_{m_{\Delta P+}} \left(\frac{\Delta P+}{\frac{1}{2} \rho V^2} \right) + C_{m_\alpha} \alpha + C_{m_{\alpha^2}} \alpha^2 + C_{m_{\dot{\theta}}} \frac{\dot{\theta}}{V} + C_{m_{\delta_e}} \delta_e \quad (157)$$

$$\frac{\Delta P+}{\frac{1}{2} \rho V^2} = a + b \left[\frac{P}{\frac{1}{2} \rho V^3} \right] + c \left[\frac{P}{\frac{1}{2} \rho V^3} \right]^2 \quad (158)$$

Here P is the brake horsepower at a given manifold pressure and RPM, $\Delta P+$ is the change in total pressure at some point in the slipstream, δ_e is the elevator deflection, and a , b , and c are undetermined constants. This gives a total of 19 constants to be determined from four equations. Gerlach does not provide sufficient detail in the paper to identify the procedure by which he extracts these coefficient values but one could employ the least squares procedure by setting

$$C_x = \frac{w(Ax + g \sin \theta)}{g \frac{1}{2} \rho V^2 S}, \quad (159)$$

$$C_z = \frac{w(Az - g \cos \theta)}{g \frac{1}{2} \rho V^2 S}, \text{ and} \quad (160)$$

$$C_m = \frac{\ddot{\theta}_1}{\bar{C}_2^1 \bar{p} S V^2} \cdot \quad (161)$$

The reader will recognize several of these constant coefficients as familiar stability derivatives. Gerlach indicates further that by correcting the data to steady flight conditions by means of the chosen aerodynamic model, one can find the rate of climb as a function of speed, the elevator angle as a function of speed, and the drag polar. The details of the method are not supplied in the paper or the subsequent reference.

How does Gerlach's method compare with the method described in the present report? The latter does not include the pitching degree of freedom so that one cannot use it to extract longitudinal short period stability information as Gerlach does. On the other hand the flight maneuvers used in the present work are chosen so as to experience a large part of the aircraft's angle of attack and speed range rather than "small" perturbations about an equilibrium state from which one would normally extract short period information. Gerlach follows the latter approach. Gerlach apparently chooses integration of accelerations as his method of data smoothing, rather than filtering, and uses regression techniques for the removal of bias errors. A similar approach is followed in the present method to remove bias errors. The application of bias corrections is apparently the only device Gerlach uses to improve interparameter data consistency. He seems to have settled on a single, relatively simple aerodynamic model. The form of the equations to which the regression analysis is applied is also quite different from that employed herein since the equations serve a different purpose. The identification of thrust horsepower as a function of speed is not as evident in Gerlach's approach as in the present method. Finally, the philosophy adopted here is that by limiting one's consideration to motions of the center of gravity in the vertical plane and thus to performance problems alone, the consequent reduction in mathematical complexity should permit one to do a better job sorting out errors in the flight data and extracting thrust horsepower and drag.

Iliff's Method

Iliff (Ref. 12) employed a very interesting variant of his stability analysis procedure to determine lift and drag from pushover-pullup maneuver data. He did not attempt to determine thrust at the same time because "... an independent estimate of thrust is necessary". He assumes the following aerodynamic model

$$C_x = C_{x_0} + C_{x_\alpha} \alpha + C_{x_{\delta_e}} \delta_e + C_{x_{\alpha^2}} \alpha^2 + C_{x_{\alpha\delta_e}} \alpha \delta_e + C_{x_{\delta_e^2}} \delta_e^2 \quad (162)$$

$$C_z = C_{z_0} + C_{z_\alpha} \alpha + C_{z_{\delta_e}} \delta_e + C_{z_{\alpha^2}} \alpha^2 + C_{z_{\alpha\delta_e}} \alpha\delta_e + C_{z_{\delta_e^2}} \delta_e^2 \quad (163)$$

$$C_L = -C_z \cos \alpha + C_x \sin \alpha \quad (164)$$

$$C_D = -C_x \cos \alpha - C_z \sin \alpha \quad (165)$$

and writes the six equations

$$\dot{q} = M_V V + M_q q + M_\alpha \alpha + M_{\alpha^2} \alpha^2 + M_{\delta_e} \delta_e + M_{\delta_e^2} \delta_e^2 + M_{\alpha\delta_e} \alpha\delta_e + M_0 \quad (166)$$

$$\ddot{\alpha} = Z_V V + Z_\alpha \alpha + Z_{\alpha^2} \alpha^2 + Z_{\delta_e} \delta_e + Z_{\delta_e^2} \delta_e^2 + Z_{\alpha\delta_e} \alpha\delta_e + Z_0 + q + \frac{g}{V} \cos \theta_0 - \frac{g}{V} \theta \sin \theta_0 \quad (167)$$

$$\dot{V} = X_V V + X_\alpha \alpha + X_{\alpha^2} \alpha^2 + X_{\delta_e} \delta_e + X_{\delta_e^2} \delta_e^2 + X_0 + \frac{T}{W} g - g \sin \theta_0 - g \theta \cos \theta_0 \quad (168)$$

$$\dot{\theta} = q$$

$$A_z = -\frac{V}{g}(Z_V V + Z_\alpha \alpha + Z_{\alpha^2} \alpha^2 + Z_{\delta_e} \delta_e + Z_{\delta_e^2} \delta_e^2 + Z_{\alpha\delta_e} \alpha\delta_e + Z_0) \quad (169)$$

$$A_x = \frac{1}{g}(X_V V + X_\alpha \alpha + X_{\alpha^2} \alpha^2 + X_{\delta_e} \delta_e + X_{\delta_e^2} \delta_e^2 + X_{\alpha\delta_e} \alpha\delta_e + X_0 + \frac{T}{W} g) \quad (170)$$

δ_e , V , q , α , θ , $\dot{q}$, A_z , and A_x are available as measured functions of time and T , the net thrust, W , and θ_0 are taken as constants which are assumed known during a given maneuver. If one calls α^2 , $\alpha\delta_e$, and θ separate variables distinct from α and $\dot{\theta}$, then by specifying δ_e as a function of time, one has a system of six equations with constant coefficients which can be solved for

$q(t)$
 $\alpha(t)$
 $V(t)$
 $\theta(t)$
 $\alpha^2(t)$
 $\alpha\delta_e(t),$

provided values of the constant coefficients are supplied. Since the equations are linear, the general form of the solution may be written down immediately and the partial derivatives for the Newton-Raphson equations evaluated by substitution of these solutions in the analytical expressions or evaluated numerically by finite differences. The cost function to be minimized is constructed of differences squared between the measured and computed values of q , α , V , θ , $\dot{q}$, A_z , and A_x . The minimization is achieved when the constant coefficients, M_q , M_v , M_α , etc., assume those values which produce solutions to the system of six equations most nearly matching the measured data in a least squares sense.

In the form presented in the paper, Iliff solves for the values of 22 constants and 7 measurement biases. These include the 12 constants necessary to evaluate $C_x = x/(\frac{1}{2}\rho SV^2)$ and $C_z = Z/(\frac{1}{2}\rho SV^2)$. Note that the thrust must be known a priori in order to separate X_0 from the constant $\frac{1}{g}(X_0 + \frac{T}{W}g)$. X_0 , of course, is the major contributor to C_{D_0} . Iliff also assumes that the thrust axis is coincident with the x-body axis and his formulation is in terms of a body axis system rather than a wind axis system as used here.

The acceleration equations as written are for true accelerations; hence, the gravitational contributions to the usual instrument indications must first be removed before they are used in the minimization.

Iliff's model includes three non-linear terms which he is able to accommodate by writing three additional equations and calling these non-linear terms additional linear variables. Obviously, this process cannot be continued to a significant degree so that he must content himself with fairly simple lift and drag models if he is to avoid the non-linear solution techniques followed in the present work. This means that he must limit himself to maneuvers sufficiently restricted that the changes in all the variables are linear. He cannot evaluate the entire lift and drag curves in a single maneuver if the non-linearities of the complete curves extend beyond the form chosen. In the present work somewhat more complex models are investigated. In Iliff's formulation only small excursions in pitch angle about the initial value are permitted. That restriction does not exist in the present formulation. Iliff's as well as the present models do not include rate terms. One final difference is the inclusion of $C_{x_{\delta_e}}$, $C_{x_{\alpha\delta_e}}$, and $C_{x_{\delta_e}^2}$ terms in the drag expression; those

terms are not included explicitly in the present formulation. It was pointed out earlier, however, that for a given weight and c.g. location these effects would be included implicitly by the nature of the extraction process in the coefficients of the drag expression. The values of these coefficients in the present formulation would, therefore, be expected to change with changes in c.g. location or weight.

The Iliff paper illustrates very clearly the trade offs involved in activities of this type. If one is content with restricted aerodynamic models, evaluation over a limited speed range, and no thrust determination, then the trajectory computation is very much simpler. Since trajectory evaluation consumes at least 75% of the computational time and is responsible for much of the error in the present procedure, the time and accuracy advantage of the simpler procedure cannot be dismissed easily.

Some of Iliff's more recent studies in parameter estimation applied to stability and control problems are reported in references 13, 14, and 15. Other minimization algorithms are described in reference 16.

C-3

DISCUSSION OF RESULTS

Figure 44 presents the two data sets from which the lift, drag, and power data shown in figures 45, 46, and 47 were obtained. The drift value shown for the pullup-pushover maneuver was chosen after several trials to produce a good match between the measured velocity and the computed value. The α -gain and α -bias values used are those found by the flight calibration of the α -vane for the position error. The rough α -curve is the measured α values as modified by this calibration. The smooth α -curve is the filtered α data modified by the compatibility improvement scheme. The modification is responsible for the difference one sees between the peak measured values and the smooth values. The smooth curve on the θ plot is that produced from the input data by the filtering procedure. The $\dot{h}$ curve is obtained by differentiation of the fourier series representations of h .

To obtain the velocity match shown for the level flight acceleration it was necessary to employ a non-linear θ drift, one for which almost all the effect occurs in the last half of the maneuver. Note also that this drift has the opposite sign from that required with the pullup-pushover, an indication perhaps, of the random nature of the "drift". It would appear from the figure, however, that some further refinement of the non-linear drift function is necessary in order to achieve a really acceptable match.

Figure 46a shows the extracted drag coefficient values obtained with three different models for the pullup-pushover maneuver. Only the steady state components are plotted to facilitate comparison with the results of Holmes (Ref. 11) and the predictions. However, the complete drag coefficient expression obtained, including the rate terms, is shown on the figure. The power expressions associated with each of the extracted drag results are shown in figure 47a. It will be observed that the model giving the lowest fit error obviously is not an accurate representation of the aircraft's thrust horsepower. If one assumes that the drag found by Holmes is approximately correct, then it is seen that result (a) provides the best fit by best straddling the actual drag. The most reasonable power expression, (c), lies below both the expected power and the steady-state drag for all values and hence has the largest fit error. We may remark here that the fit error obtained by including the rate terms in the drag and power expressions is almost an order of magnitude smaller than the fit error for the same expressions without any of the rate terms.

A number of other power models, for example

$$P = P_0 \ln V_1$$

$$P = P_0 + P_2 V + P_3 V^2, \text{ and}$$

$$P = P_0 + P_1 V^x$$

where x has various values from 0.2 to 0.6, were investigated with no apparent improvement in the results.

The estimated power shown in figure 47a for 256 fps would appear to be consistent with the drag coefficient near $\alpha = 0$ shown in figure 46a, because the extracted power and drag values for model (c) -- which are related by an equation -- are both approximately the same as these values. At the low speed end of the data the estimated power is either a little low or the drag value derived from Ref. 11 is a little high or both. A power value of 103,000 ft-lbs/sec at 167 ft/sec is consistent with a drag coefficient value of about 0.98 at an $\alpha = 0.104$.

One explanation for the failure of the extracted values to agree better with what are probably reasonable power and drag is a possible error in the α position error calibration. The extraction process is, of course, more sensitive to the value of α than to the value of any other variable. As an experiment an extraction was performed on a data set with a larger value of α gain along with a negative bias value. The resulting α values were therefore centered about those used for the present extraction. Interestingly, the extracted power curve using model (c) had a considerably shallower slope than the result shown in figure 47a. Since the calculated flight velocity is not particularly sensitive to the values of α used in integrating the kinematic equation, it seems possible that an adjustment to α sufficient to bring the extracted results into much better agreement with the "accepted" values can be achieved while preserving the congruence between the calculated velocity and the measured value.

We may note in passing that the aircraft was flown in a rather "dirty" condition. This fact is no doubt primarily responsible for the measured drag being much greater ($\sim 25\%$) than the predicted value. When the aircraft was "cleaned up" for the full-scale wind tunnel tests the measured drag was found to be about 15% less* than the predicted value.

Figure 46b shows the extracted drag coefficients obtained from the level flight acceleration at 4000' depicted in figure 44. To obtain this result it was necessary to omit the rate terms from the drag model but retain them for the power expression. Note that the speed range and angle of attack range covered by the two data sets are approximately the same. The rates at which the variables change, of course, are much lower in the level flight acceleration. It would appear that the rates are below whatever threshold value is needed to give meaningful extractions. Also the fit error -- extrapolated to the same number of data points -- is about three times as large for the level flight acceleration as for the pullup-pushover. This would seem to indicate that maneuvers featuring more rapid parameter changes or larger parameter changes make possible more accurate coefficient extractions. They also aid in masking data measuring and acquisition defects. The ideal maneuvers, however, should not be so rapid as to excite more unsteady aerodynamic effects or so large as to uncover even more non-linearities.

* Private communication.

The value of C_{D_0} found from the level flight acceleration is 7.5% lower than that recovered from the pullup-pushover. Considering the fact that fit errors for both data sets are still excessive, this agreement is quite good. This value (0.0468) is about 13% below that given by Holmes. The uncharacteristic variation in the drag coefficient with angle of attack is indicative of a problem in the data submitted to the extraction routine. Note that in figure 44 the match between the measured and computed values of velocity is much poorer than for the pullup-pushover. In addition a much more unusual "drift" correction to θ was required to achieve even this level of congruence. One might suggest that perhaps a relatively low frequency gust to which the α vane responded more completely than did the aircraft (hence θ and $\dot{\theta}$) as a whole was responsible for spurious contributions to the computed aircraft velocity. Analysis of several more maneuvers would be required to determine the validity of this contention. In any event, the extracted variation of C_D with α for the level flight acceleration must, for the present, be regarded as having the correct order of magnitude and little more.

The failure of the extracted power values shown in figure 47b to agree more closely with those extrapolated from sea level full scale wind tunnel results is another indication of the higher level of error present in the level flight acceleration data set. Qualitatively, however, the power results are similar to those for the pullup-pushover, a favorable indication. There is some evidence also that the estimated power value for 4000' is perhaps just a little larger than is actually the case. Note the relatively good agreement obtained for $\alpha \rightarrow 0$ during the pullup-pushover. If the power and drag are in approximate equilibrium at $\alpha \approx 0.01$ and if the C_{D_0} value here is about 0.053, then one would expect a power into the airstream of about 149,000 ft-lbs/sec while the estimated value is about 153,000 ft-lbs/sec.

The differences between the extracted values and those determined from speed power measurements are about what one would expect, given the magnitude of the fit error. It was noted during the discussion of the computed theoretical case that a fit error of about 4×10^{-5} for 300 points (30 seconds of data) would be equivalent to an error of about 5% in drag or power. The fit error of 4×10^{-4} for 300 points in the pullup-pushover indicates a power or drag error of about 15%, which is about that found. A fit error of 2×10^{-3} for 450 points in the level flight acceleration indicates an error of about 30%. The extracted power values appear to differ by about 20% from the estimated values while the drag coefficient values are on the average about 40% below the values of Ref. 11.

Some 30 different aerodynamic models were investigated in an effort to reduce the fit error. None showed a significantly lower error while also yielding a reasonable C_{D_0} value. On the basis of these results one must conclude that the reason for the high fit error is more likely to be found in the lack of internal consistency in the data for this particular maneuver than it is in the failure to identify an appropriate aerodynamic model.

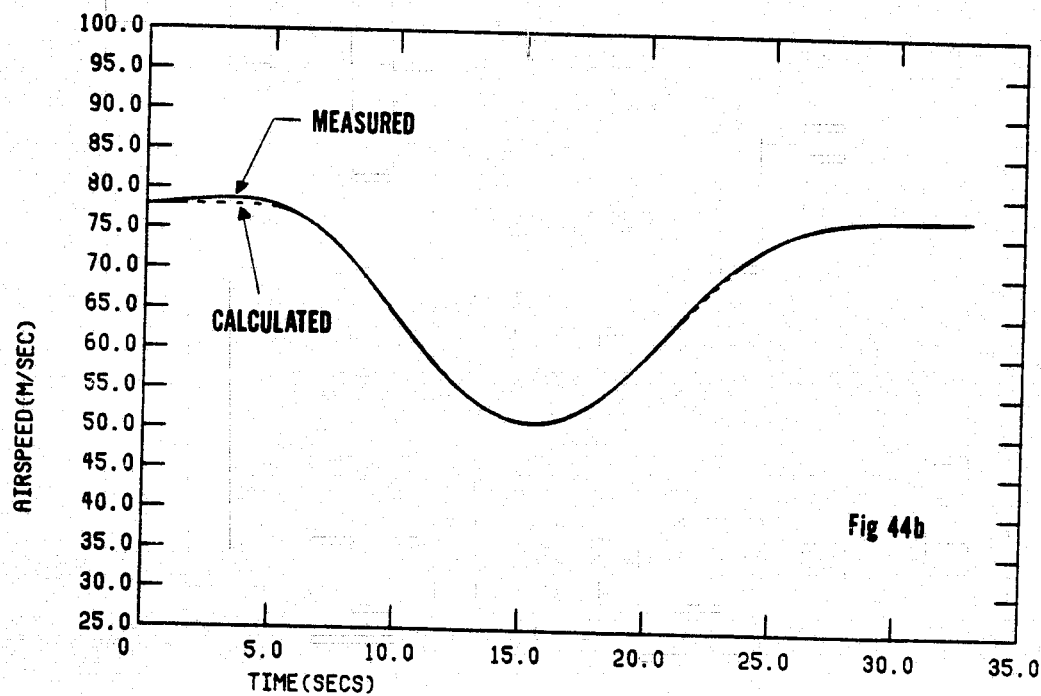
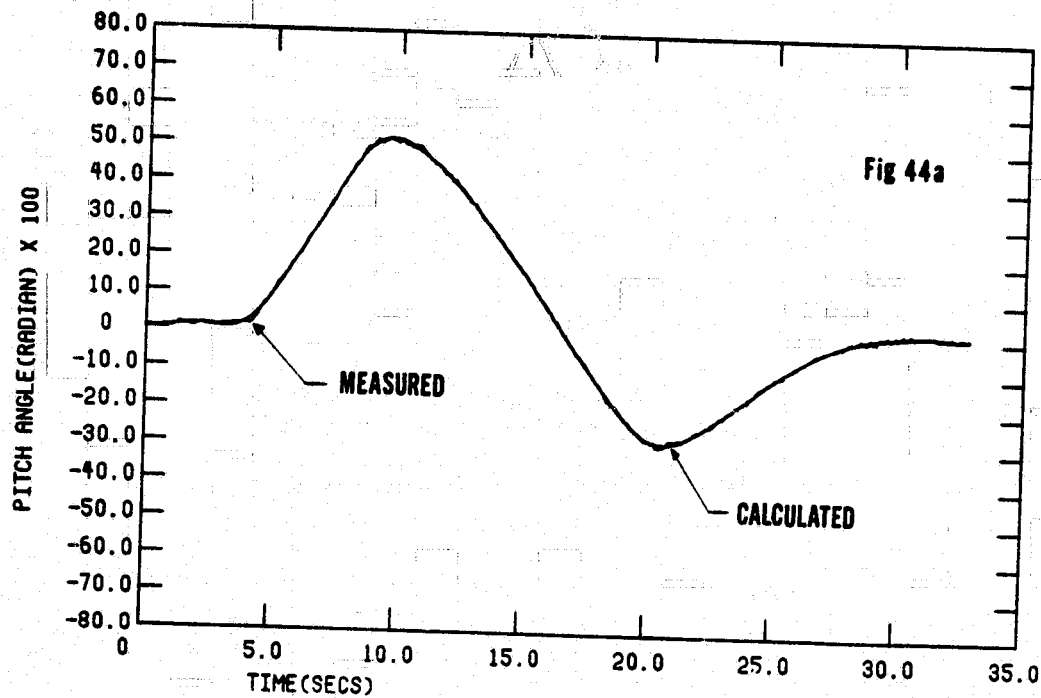
The importance of choosing a satisfactory model is illustrated by the results of an experiment using theoretical trajectory data. (Figure 22). The last term in the 5 term drag model was changed from α^6 to α^4 . This single change caused the fit error to increase fifteen orders of magnitude. The coefficients to the other terms in both the drag and power models also changed significantly. C_{D0} , for example, almost doubled. This extreme sensitivity to small changes in the model is a consequence of the ill-conditioned nature of the "A" matrix in the least squares procedure.

The extracted values of lift coefficient vs. α are shown in figure 45 along with the predicted values and the results of Holmes (Ref. 11). The extraction models used did not include rate terms. The values of $C_{L_{\alpha=0}}$ extracted from the pullup-pushover is about 7% higher than Holmes' result while that obtained from the level flight acceleration is about 10% high. Except for the upward curvature in the result extracted from the level flight acceleration the two maneuvers gave essentially the same lift result. The curvature in the level flight result is thought to be due to the failure of the "drift" model used to produce a better match between the measured and the computed flight velocities. (See figure 44).

The agreement between the extracted result and the steady state results of Holmes is good for $\alpha < 0.02$ radians, the highest speeds of the data sets. Elsewhere, the present results exhibit a lower lift slope. The extracted value of $C_{L_{\alpha}}$ is even smaller than predicted. The reason for this is uncertain but several possibilities come to mind: (a) the lift model does not account for the excess power available at the lower speeds in the form rate terms. (b) the excess power available may reduce the span efficiency by moving the load inboard. (c) the down thrust due to offset of the thrust axis may be greater than thought. Which, if any, of these is correct can be determined only after further study. Both the pullup-pushover maneuver and the steady speed-power data of Holmes indicate that the lift curve is essentially linear for $\alpha \leq 0.1$. This is fortunate since significant reductions in the complexity of subsequent calculations can be obtained by employing a linear lift curve model.

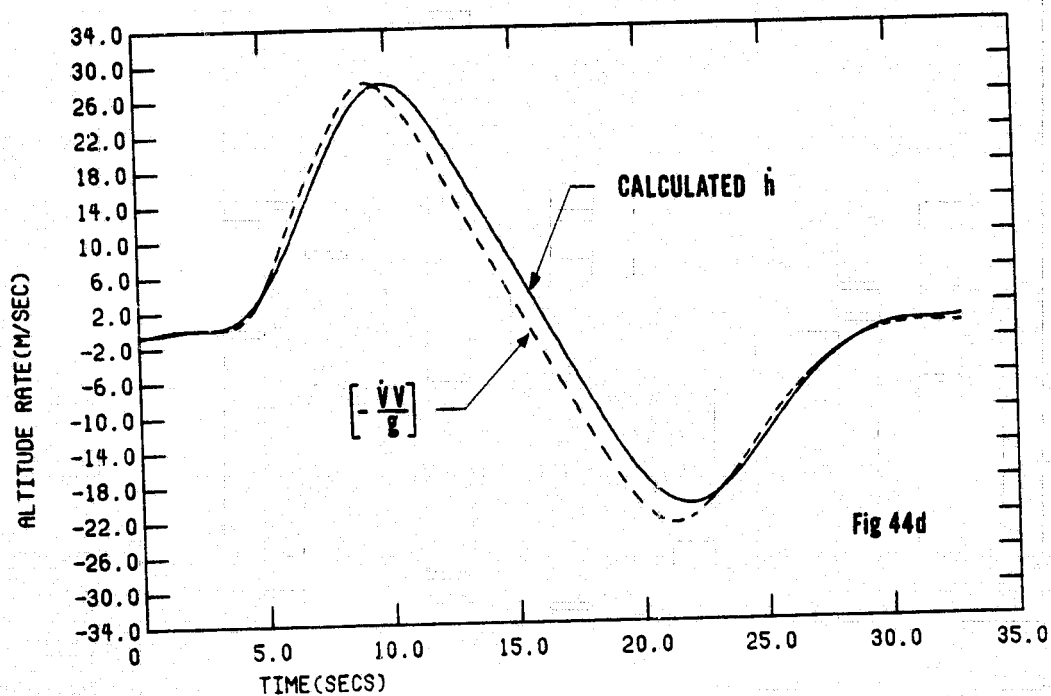
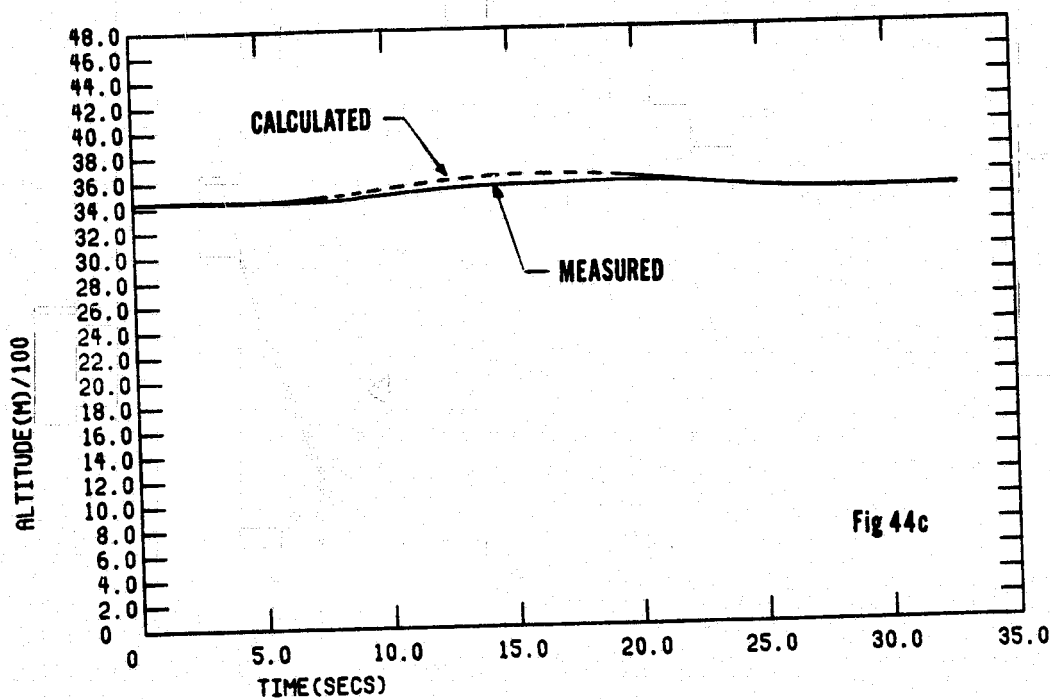
Obviously, the prediction for $C_{L_{\alpha=0}}$ is in error. This would seem to indicate that (a) the wing incidence angle is different from that assumed in developing the prediction, (b) the airfoil trailing edge shape is different from nominal, (c) the instrument reference line is different from that assumed to be the reference in developing the prediction, or (d) some combination of the above. Because, of the large difference which manifested itself in this case, $C_{L_{\alpha=0}}$ is a factor which should be checked closely when developing predictions.

The 13.5% increase in $C_{L_{\alpha}}$ over the predicted value would appear to be due the higher than nominal dynamic pressures over those areas of the wing swept by the propeller slipstream, an effect not included in the prediction. The area affected and the magnitude of the increase in dynamic pressure can probably be determined adequately by propeller momentum theory. These effects should be included in future predictions.

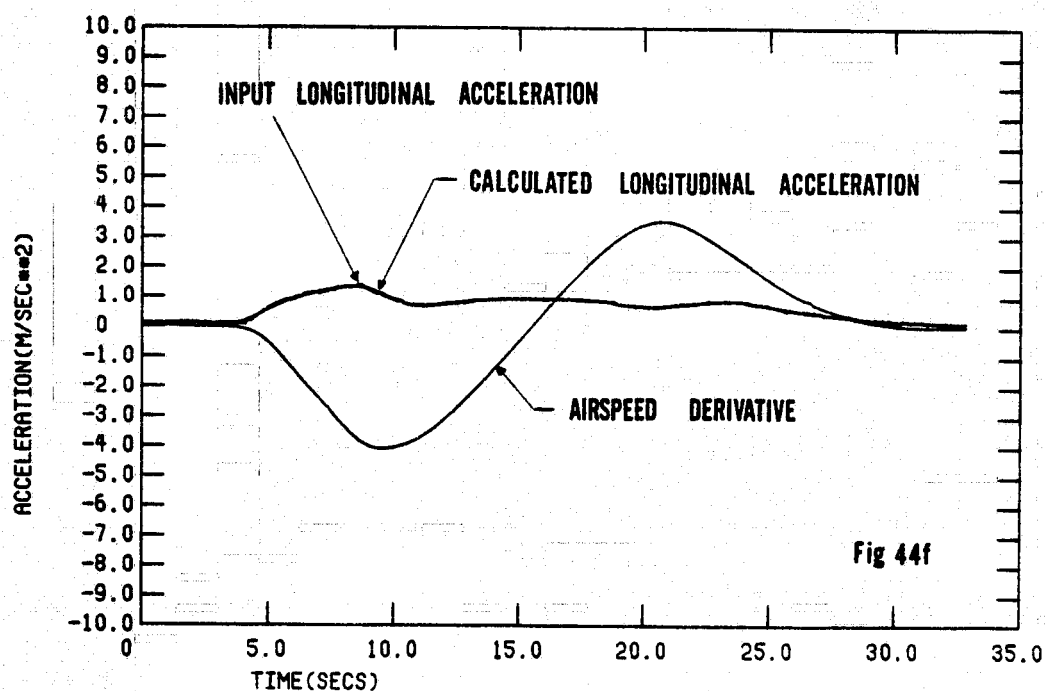
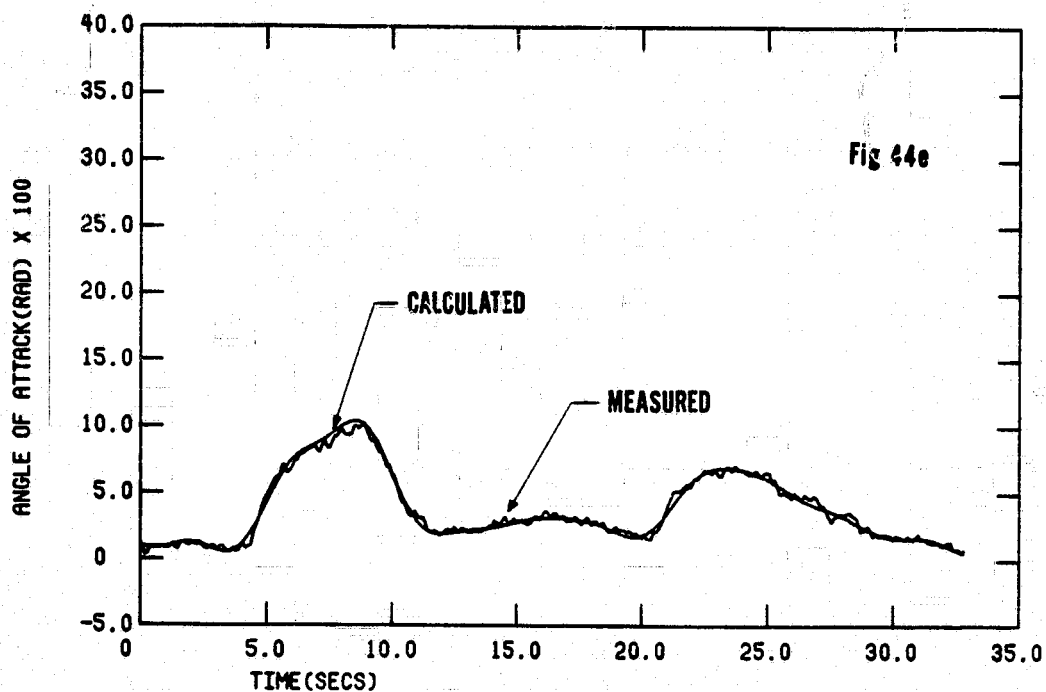


PULLUP-PUSHOVER MANEUVER ANALYZED FOR
LIFT, DRAG, AND POWER.

POSITION ERROR CORRECTION: GAIN = 0.8667,
BIAS = 0.01. $\theta_{\text{DRIFT}} = -0.028 \text{ RAD.}$

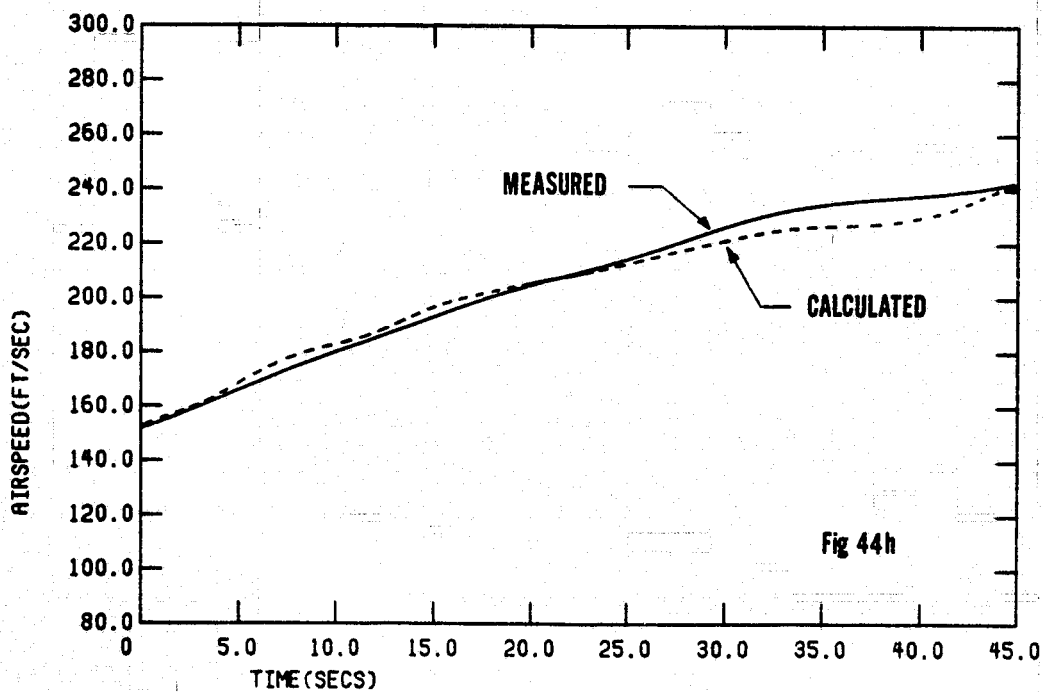
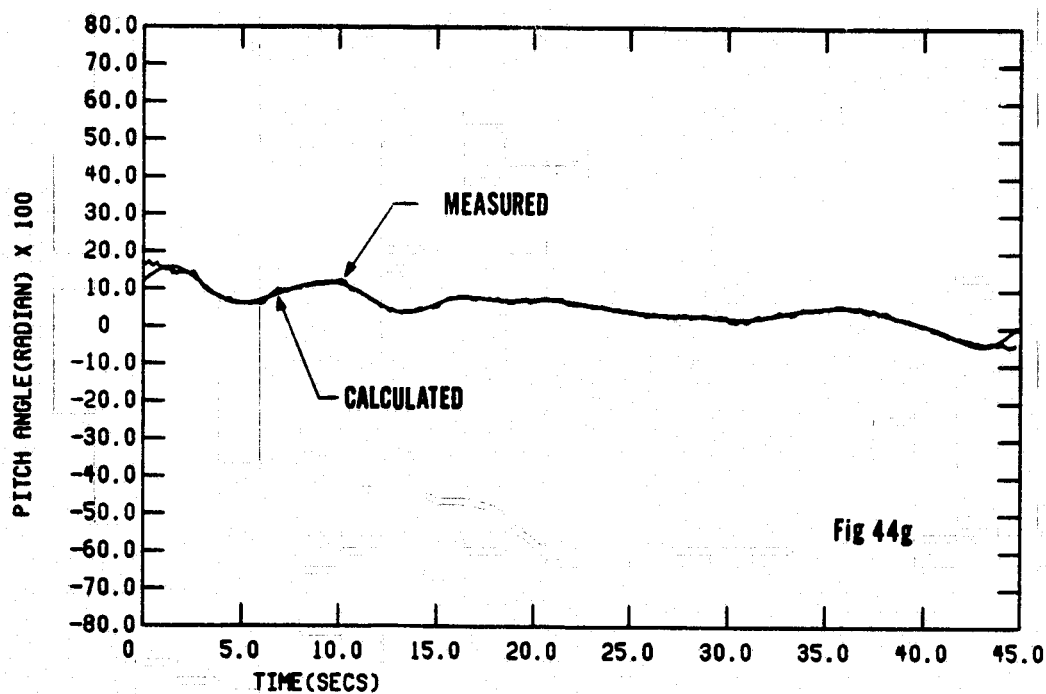


PULLUP-PUSHOVER MANEUVER ANALYZED FOR
LIFT, DRAG, AND POWER.
POSITION ERROR CORRECTION: GAIN = 0.8667,
BIAS = 0.01. $\theta_{\text{DRIFT}} = -0.028 \text{ RAD.}$

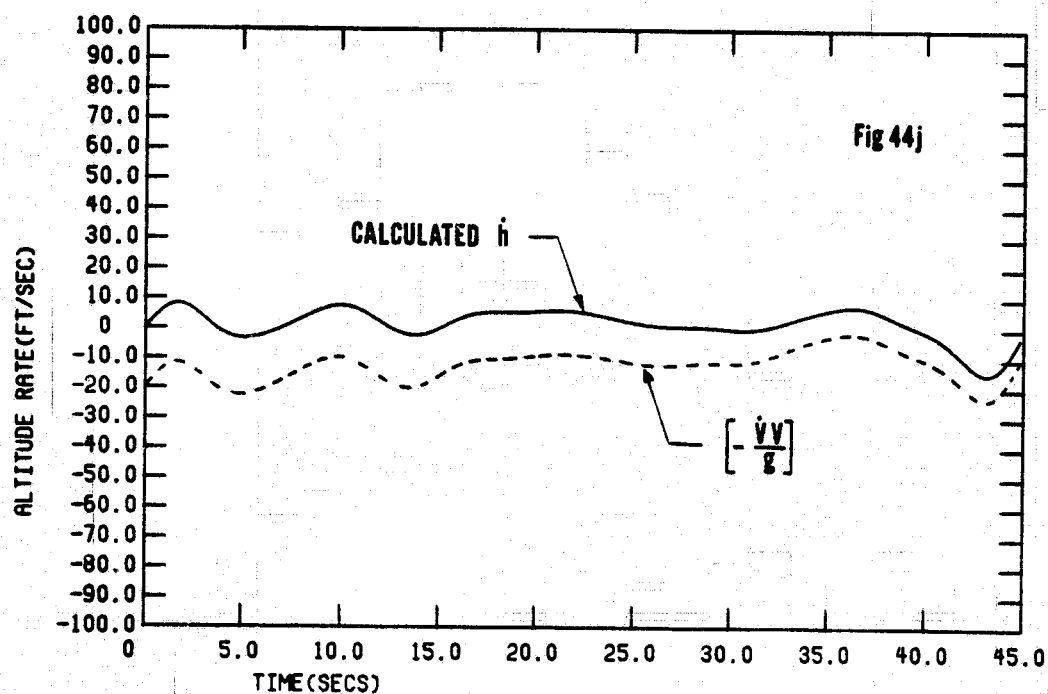
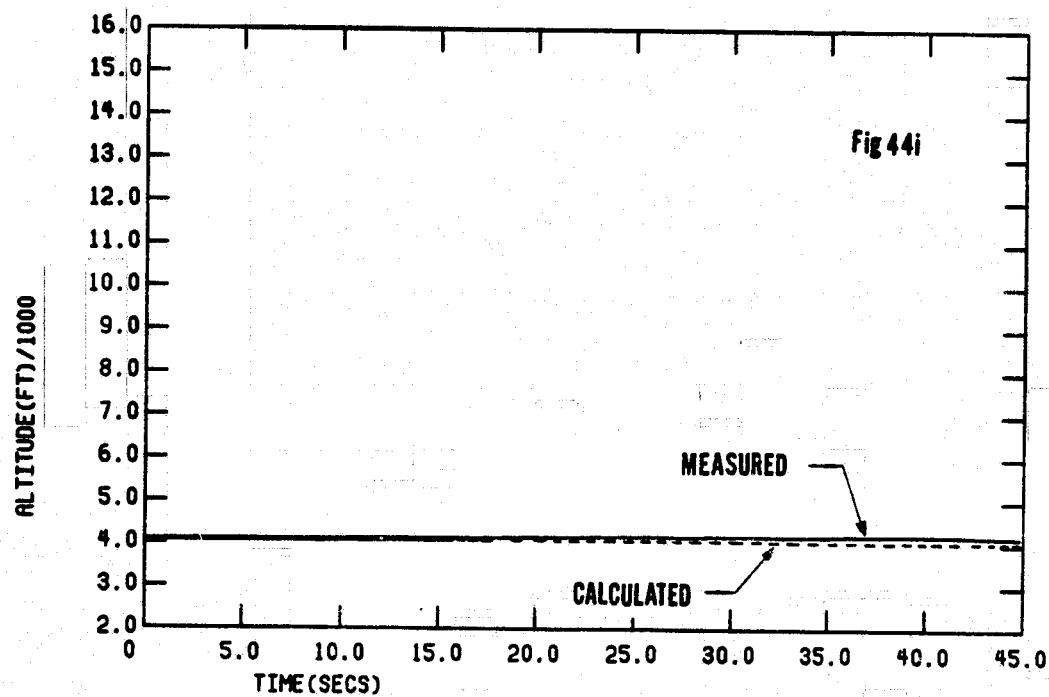


PULLUP-PUSHOVER MANEUVER ANALYZED FOR
LIFT, DRAG, AND POWER.

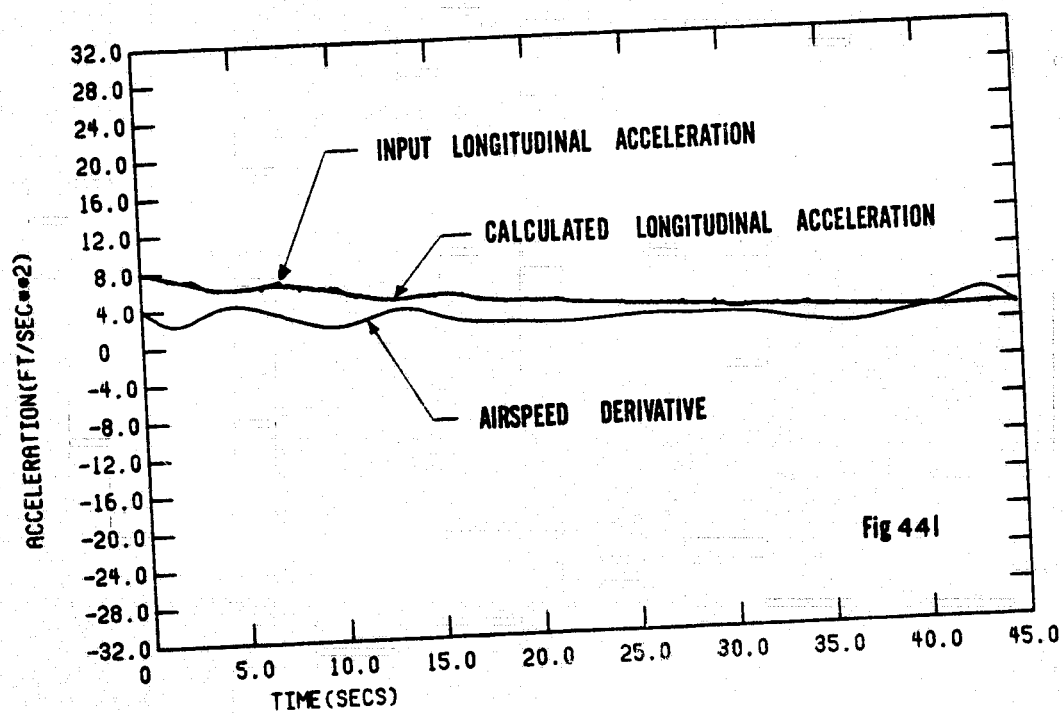
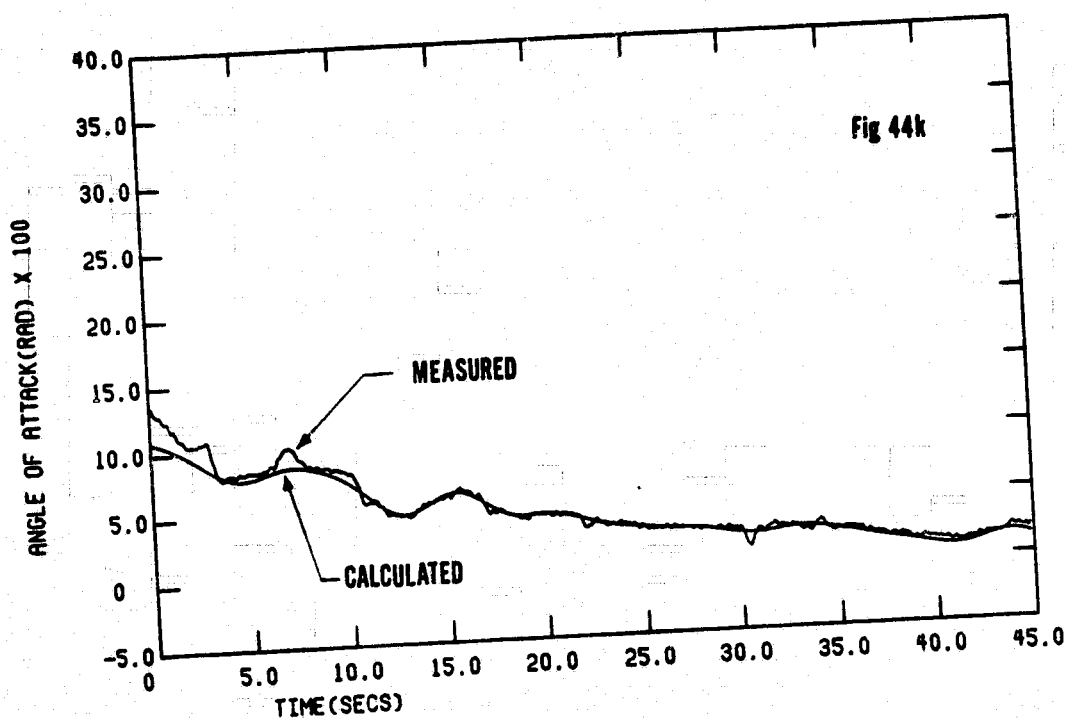
POSITION ERROR CORRECTION: GAIN = 0.8667,
BIAS = 0.01. $\theta_{\text{DRIFT}} = -0.028$ RAD.



LEVEL-FLIGHT-ACCELERATION MANEUVER
 ANALYZED FOR LIFT, DRAG, AND POWER.
 POSITION ERROR CORRECTION: GAIN = 0.8667,
 BIAS = 0.01, $\theta_{\text{DRIFT}} = .10$ RAD. (SEE TEXT)



LEVEL-FLIGHT-ACCELERATION MANEUVER
ANALYZED FOR LIFT, DRAG, AND POWER.
POSITION ERROR CORRECTION: GAIN = 0.8667,
BIAS = 0.01, $\theta_{\text{DRIFT}} = .10$ RAD. (SEE TEXT)



LEVEL-FLIGHT-ACCELERATION MANEUVER
 ANALYZED FOR LIFT, DRAG, AND POWER.
 POSITION ERROR CORRECTION: GAIN = 0.8667,
 BIAS = 0.01, $\theta_{\text{DRIFT}} = .10$ RAD. (SEE TEXT)

STEADY STATE LIFT COEFFICIENT EXTRACTED FROM MANEUVERING FLIGHT

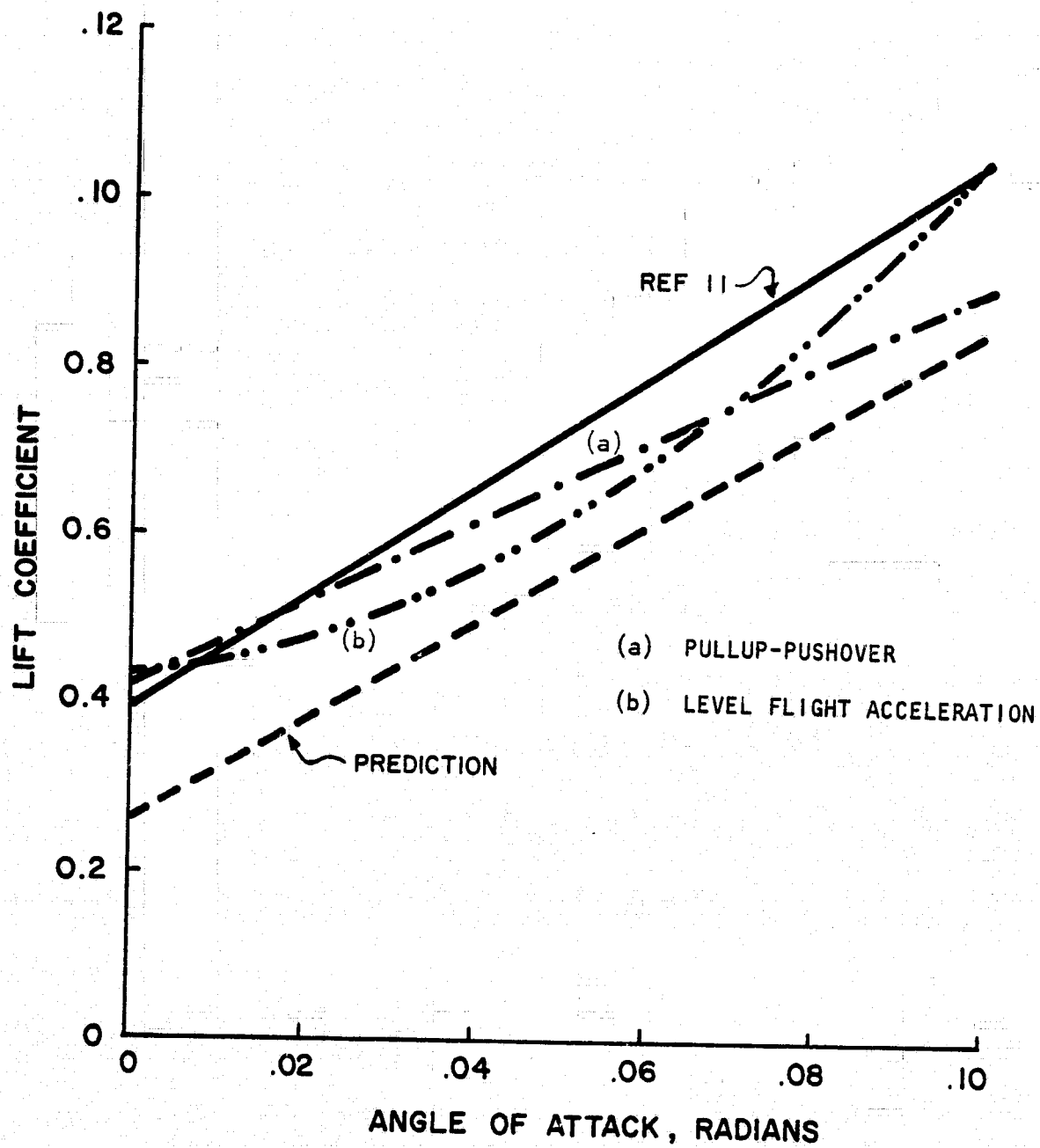


FIG 45

STEADY STATE DRAG COEFFICIENT EXTRACTED
FROM PULLUP - PUSHOVER AT 11,000'

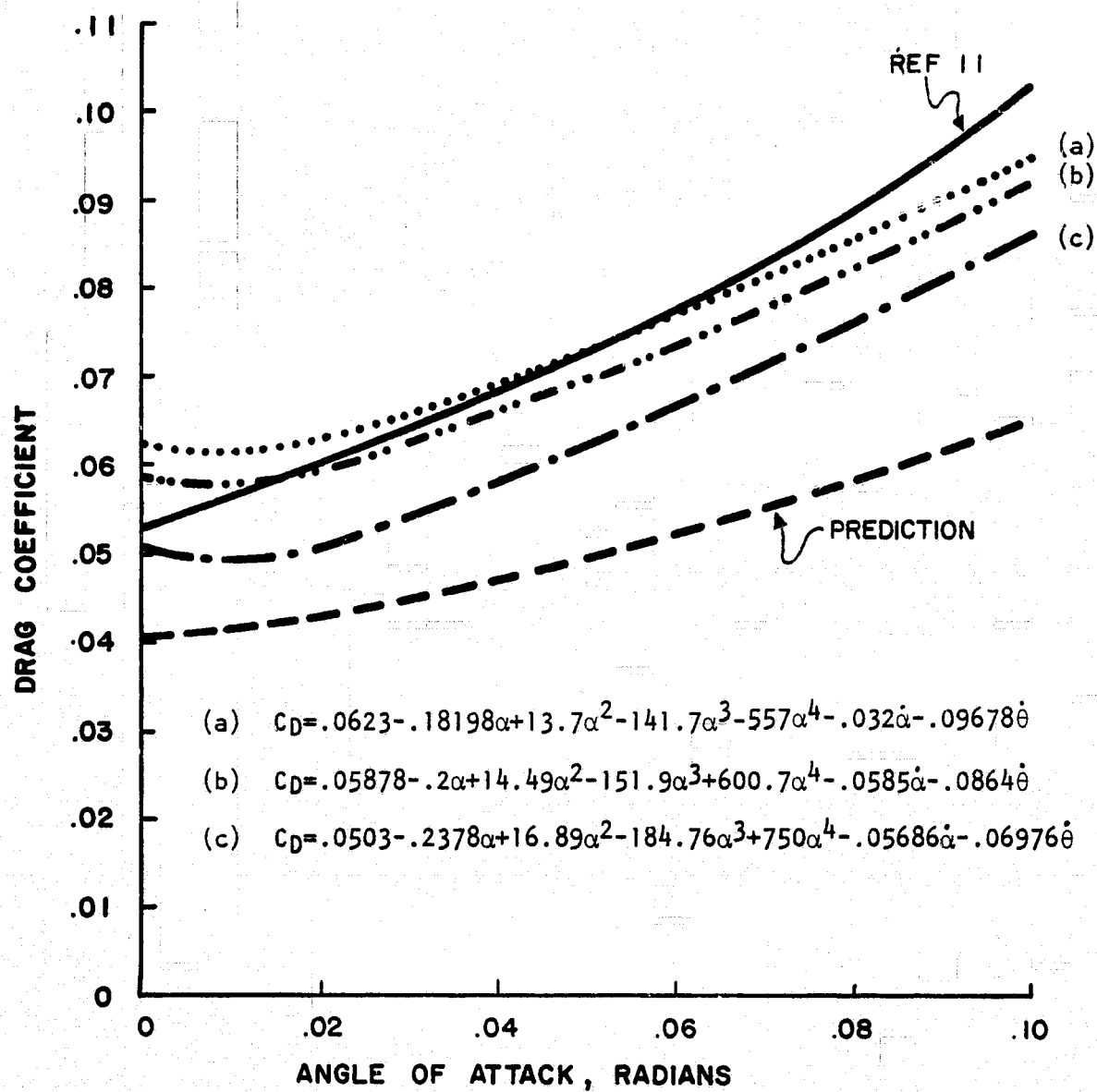
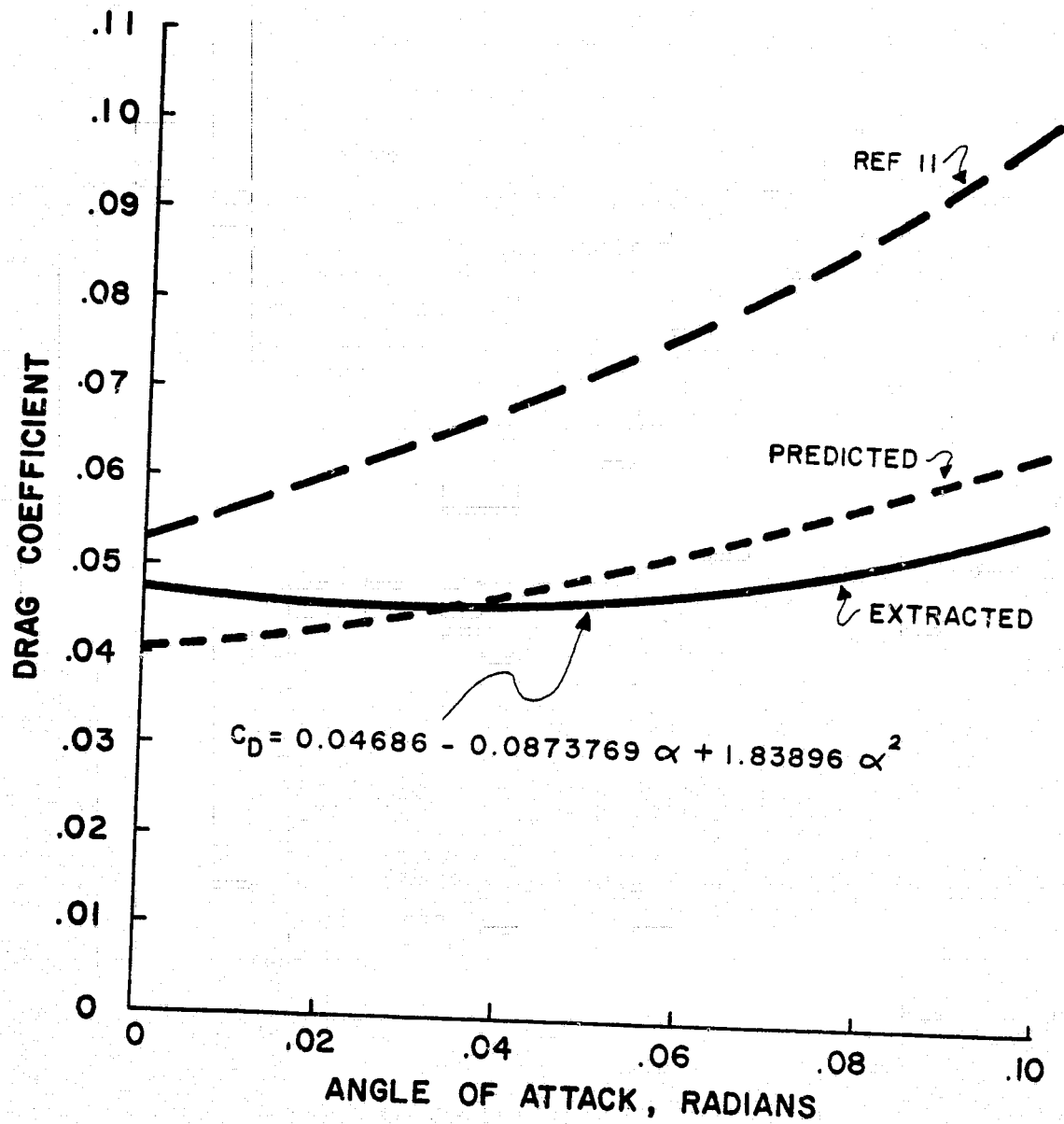
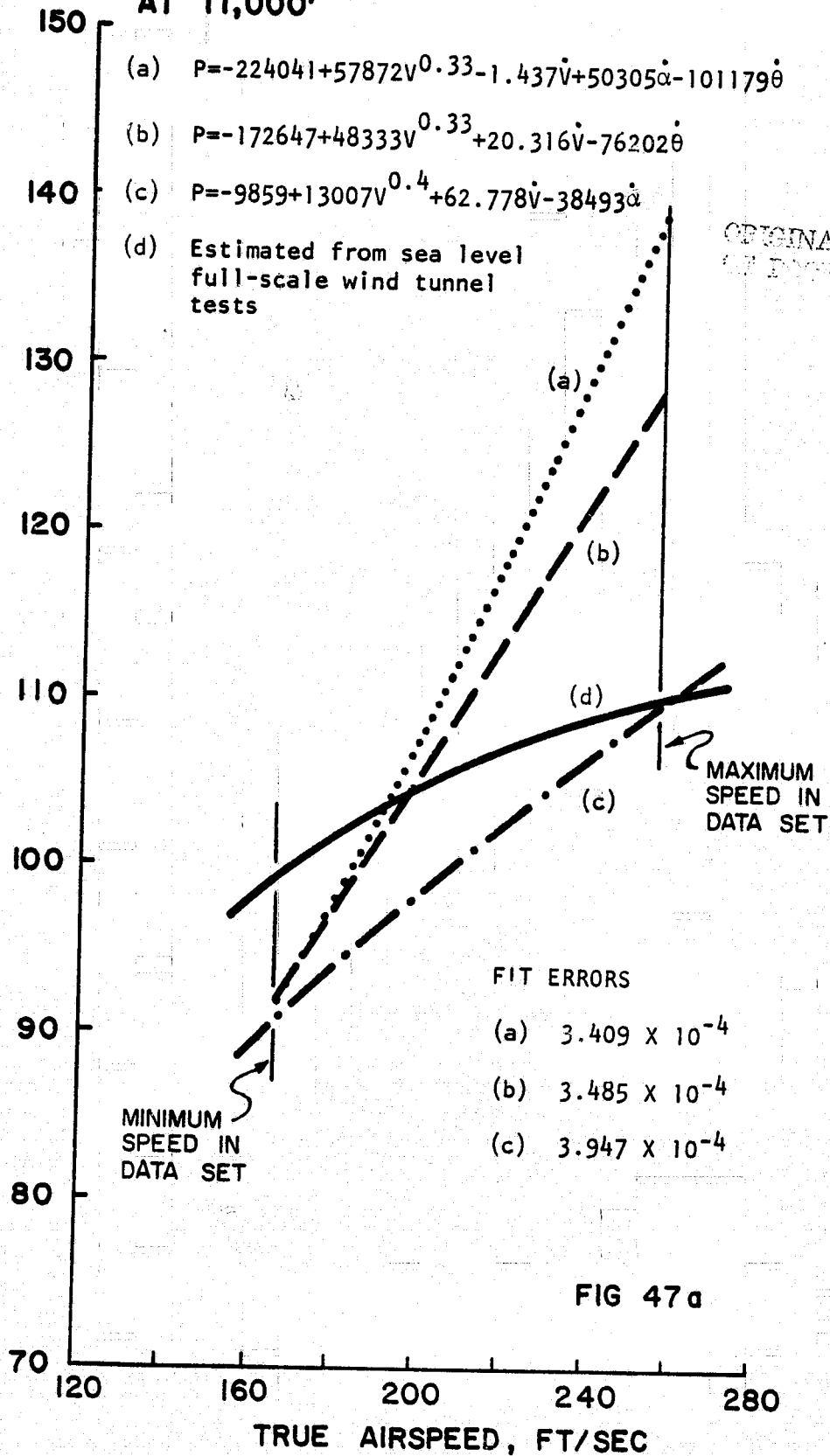


FIG 46a

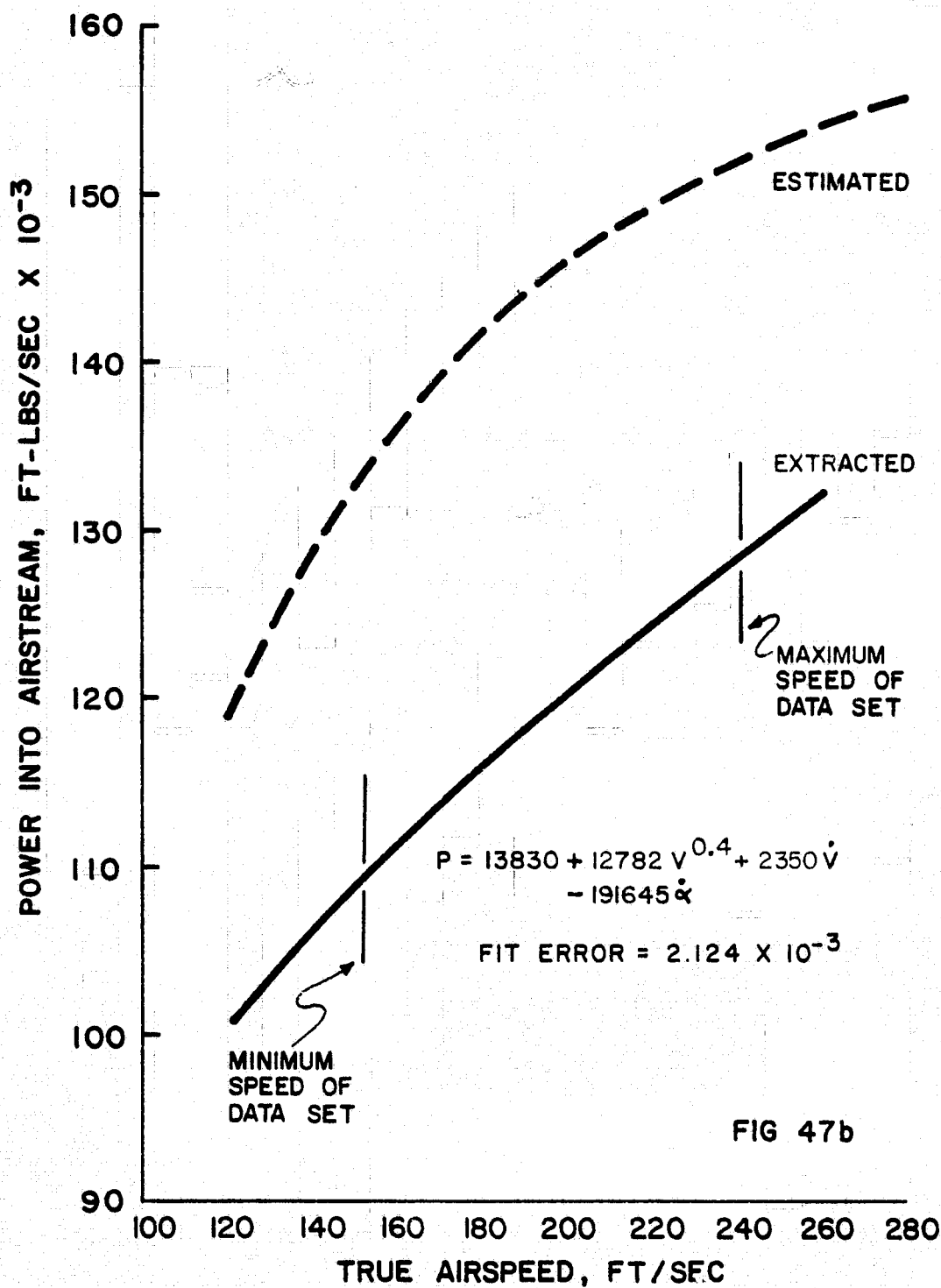
STEADY STATE DRAG COEFFICIENT EXTRACTED FROM LEVEL FLIGHT ACCELERATION AT 4000'



STEADY STATE POWER INTO AIRSTREAM EXTRACTED FROM PULLUP PUSHOVER AT 11,000'



STEADY STATE POWER INTO AIRSTREAM EXTRACTED FROM LEVEL FLIGHT ACCELERATION AT 4000'



A NOTE ON STABILITY AND PERFORMANCE EVALUATION

It had been planned to use the lift, drag, and power data extracted from typical maneuvers such as pullup-pushovers to evaluate the aircraft performance parameters. This procedure is analogous to that followed during prediction of the aircraft's performance except that one now substitutes the extracted or measured values of the lift, drag, and power for the estimated values. If extractions are carried out for several altitudes, several power settings, and several configurations, a rather complete picture of the aircraft's performance potential can be developed. However, because of the limited accuracy obtained thus far for the lift, drag, and power in flight as well as the limited number of maneuvers analyzed, this plan was not pursued.

It had also been planned to use the Iliff-Taylor program (Ref. 6) to extract stability derivative values from flight records. Some short stabilator, aileron, and rudder pulse maneuvers suitable for this purpose were flown. It was intended that at least the stabilator pulse records be processed through both FDR1 and FDR2 so as to make them as internally self-consistent as possible. FDR2 is, in fact, provided with a means of arranging the final version of the data in a form suitable for additional processing (punched cards or tape). Because of difficulties in defining adequate lift, drag, and power models and in lowering the fit errors, this plan was also aborted.

The reader interested in comparing the predicted with the measured performance and stability should be aware that full scale wind tunnel tests of the aircraft have been run at the Langley Research Center. Publication of the test results is expected in the near future. Researchers at the Langley Research Center have also been attempting to extract stability derivative values from the flight data by several techniques. It is understood they have also been stymied thus far by the problem of internally inconsistent data. The steady flight test results are available in Holmes (Ref. 11).

CONCLUSIONS

1. A technique has been developed which has demonstrated the ability to extract complete lift, drag, and thrust horsepower curves simultaneously from simulated time histories of a single aircraft maneuver covering the entire speed range.

2. The technique presently does not include rate terms in the model of the aircraft and these may be necessary in real world situations.

3. The technique requires rather accurate input data in order to yield acceptable results.

4. Some success has been achieved in developing an input data compatibility improvement routine.

5. The extraction technique is apparently quite sensitive to small computational errors and should therefore be run with the maximum precision available.

6. Preliminary results indicate reasonable agreement with other flight test techniques and extrapolations of full scale wind tunnel tests even though the trajectory matching features of the technique could not be used because these do not include rate terms in the model of the aircraft at the present time.

SUGGESTIONS FOR FUTURE WORK

It will be apparent to the careful reader that a proper understanding of the correct or best power model for this airplane has not yet been achieved. Until it is, FDR2 cannot hope to yield results with low fit errors. In this connection it would be desirable to employ a non-linear least squares technique -- one which calculates its own exponent values for at least the velocity dependence of the thrust horsepower -- to determine how the data can be fit more effectively. Note that an initial fit error about 10 times lower than that currently obtained will be necessary before FDR2 can proceed satisfactorily.

If, as now seems likely, the rate terms are sufficiently important as to require inclusion in the aircraft model, FDR2 will require substantial revision to provide for these terms in the various routines. Because of the complexity they will introduce in HPATH if included as variables it may be desirable to assume that the coefficients for the rate terms are "frozen" so far as HPATH (see Appendix C) is concerned.

Much of the difficulty encountered in obtaining convergence of the trajectory match procedure is thought to be related to the precision with which (a) the equations of motion can be integrated and (b) the "A" matrix in the Newton-Raphson coefficient modification equations can be inverted. It is highly desirable that the efficacy of doubling the number of decimal digits employed in these calculations be investigated. Currently 16 decimal digits are the maximum which can be used at the local computing facility.

Despite the fact that some success was achieved in improving the self-compatibility of the flight data this is really no substitute for flight data which is inherently more self-consistent. Accordingly, it would be desirable to try the entire procedure with data whose internal consistency is known to be superior to that used here.

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APPENDICES

PRECEDING PAGE PLAIN

APPENDIX A

FLIGHT DATA REDUCTION PROGRAM # 1

PRECEDING PAGE BEARING INFORMATION

User Instructions - FDRI

The program is written in FORTRAN IV and is designed to execute in double precision on an IBM 370/165 computer with an average execution time of 8 minutes 12 seconds for each maneuver data set. Execution requires approximately 724,000 bytes of core storage. The program is intended to handle data from only one flight during a given run. It is divided into two sections. The first section

- (a) adjusts the input data, if desired, for an assumed phase shift,
- (b) converts time, weight, pitch angle, pitch rate, airspeed, static pressure, angle of attack, total temperature, longitudinal acceleration, vertical acceleration, and elevator or stabilator deflection to compatible computational units,
- (c) calculates the lag corrections to the static and dynamic pressures,
- (d) applies the position-error correction ratio $\Delta p/q_c$,
- (e) applies the acceleration-dependent corrections to the static pressure,
- (f) converts total temperature to static temperature, static pressure to density, density to altitude, and indicated airspeed to true airspeed,
- (g) corrects the pitch angle indication for a known initial bias,
- (h) corrects the angle-of-attack indication for the instrument location, and
- (i) calibrates the angle-of-attack indication for a known or assumed bias and gain.

The second section

- (a) performs Fourier-series analysis and filtering on the weight, pitch angle, pitch rate, airspeed, density, angle of attack, static temperature, longitudinal acceleration, altitude, vertical acceleration, and elevator or stabilator time histories,
- (b) integrates the pitch rate indication to obtain the pitch angle indication,
- (c) calculates
 - (1) the acceleration from the airspeed,
 - (2) the angle-of-attack rate-of-change from the Fourier-series-and-filter modification of the angle of attack or from the differentiation of a cubic-spline fit of the input angles of attack,
 - (3) the density from altitude,
 - (4) the altitude's rate of change and acceleration from the Fourier-series-and-filter modification of the altitude or from the differentiations of a cubic-spline fit of the "input" altitude time history,
 - (5) the compatible angle-of-attack values from other time histories,

- (6) the compatible altitude and its rate-of-change values from the integration of the flight-path rate of change, and
- (7) the inertial-compatible airspeed,
- (d) performs a minimization technique with or without a priori values to make the data more consistent,
- (e) plots the time histories,
- (f) writes the results in English or SI units, and
- (g) produces punched output for the FLIGHT DATA REDUCTION #2 program.

The program requires the specification of the following input:

FDR1 Section 1

CARD 1:

- (a) The number of maneuvers NSETS in a single flight to be analyzed: NSETS is a right-adjusted integer number less than or equal to 10 and occupying columns 1-5. If NSETS is not an integer number between 0 and 10, the program will terminate prematurely.
- (b) The desired type of output units METRIC for all data sets (maneuvers):
 If METRIC = 0, the output will be in English units. If METRIC = 1, the output will be in SI units. METRIC is a right-adjusted integer number occupying columns 6-10. The specification of METRIC only affects the output listings. The punched output is in English units.

CARD 2:

The weight-time-history code ICODE for each of the NSETS maneuvers:
 If ICODE = 0, a continuous weight time history is produced from the first or preceding weight time history, assuming no elapsed time between the maneuvers. If ICODE = 1, a continuous weight time history is produced from the first or preceding weight time history with elapsed time considered between the maneuvers. The weight-time-history codes for the NSETS maneuvers are right-adjusted integer numbers with each maneuver's ICODE occupying 5 columns. (The ICODE parameter is used in conjunction with the ELAP parameter below.)

CARD 3:

- (a) The maximum number of minimization-improvement iterations NUMBER to be used for the maneuver:
 NUMBER is a right-adjusted integer number less than or equal to 10 and occupying columns 1-5. If NUMBER is less than zero, NUMBER will be set to zero. If NUMBER is greater than 10, logic errors will result beyond 10 iterations.

- (b) The elapsed time ELAP to the maneuver in seconds:
For the first maneuver, ELAP should be the elapsed time from takeoff or engine-start to the beginning of the first maneuver. For the successive maneuvers, ELAP should be the elapsed time from the end of the previous maneuver to the beginning of the next maneuver. ELAP may be set equal to zero for any of the successive maneuvers. ELAP is a floating-point number occupying columns 6-15. (The ELAP parameter is used in conjunction with the ICODE parameter above.)
- (c) The data set file number JFILE:
JFILE is a right-adjusted integer number occupying columns 16-20 and specifying that the data is to be read from cards, magnetic tape, disk, etc. The user must supply the suitable job control cards for the tape and/or disk reads. The JFILE parameter controls only the reading of CARDS (12 + MPTS + 1), ..., (12 + MPTS + 2K). All other data is expected to be in card form.
- (d) The variable location numbers IVL(I), I = 1-9:
The variable location number "names" the variable occupying a particular data field on the records containing the time histories. IVL(I) are right-adjusted integer numbers each occupying 5 columns beginning at column 21. The program assumes that for each recorded time point there are 10 variables: time, pitch angle, pitch rate, airspeed, static pressure, angle of attack, stagnation temperature, longitudinal acceleration, vertical acceleration, and elevator or stabilator deflection. The program also assumes that "time" will always occupy the first data field. For the variables in the second through the tenth data fields, the following IVL's must correspond to the variable name:

<u>Variable Name</u>	<u>IVL</u>
Pitch angle	2
Pitch rate	3
Airspeed	4
Static pressure	5
Angle of attack	6
Stagnation temperature	7
Longitudinal acceleration	8
Vertical acceleration	10
Elevator (Stabilator) deflection	11

For example: If the time history variables were ordered as "time", "longitudinal acceleration", "pitch angle", "airspeed", "pitch rate", "static pressure", "angle of attack", "vertical acceleration", "stagnation temperature", and "elevator deflection", the IVL's would correspondingly be IVL(1)=8, IVL(2)=2, IVL(3)=4, IVL(4)=3, IVL(5)=5, IVL(6)=6, IVL(7)=10, IVL(8)=7, and IVL(9)=11.

CARD 4:

The 80 characters of the array TITLE which are used as a header for identifying the output:

Since the program allows more than one flight maneuver to be analyzed in a given run, TITLE is used as a control variable to end execution. Termination of execution is achieved by following the last maneuver's data set to be analyzed by a title card having only the word END in the first three columns.

CARD 5:

- (a) The Fourier-series filter-cutoff harmonic NCH(1) for the lag corrections in the airspeed's static pressure system,
- (b) The Fourier-series filter-cutoff harmonic NCH(2) for the lag corrections in the altitude's static pressure system,
- (c) The Fourier-series filter-cutoff harmonic NCH(3) for the lag corrections in the altitude's and airspeed's stagnation pressure system,
- (d) The Fourier-series filter-cutoff harmonic NCH(4) for the lag corrections in the stagnation temperature system:
NCH(1), NCH(2), NCH(3), and NCH(4) must be right-adjusted integer numbers greater than 0 but less than 66. Each NCH(j) occupies 5 columns with NCH(1) beginning at column 1.
- (e) The lag time interval XLM(1)* in seconds for the stagnation pressure system,
- (f) The lag time interval XLM(2)* in seconds for the altitude's static pressure system,
- (g) The lag time interval XLM(3)* in seconds for the airspeed's static pressure system,
- (h) The lag time constant TAU(1)* in seconds for the stagnation pressure system,
- (i) The lag time constant TAU(2)* in seconds for the altitude's static pressure system,
- (j) The lag time constant TAU(3)* in seconds for the airspeed's static pressure system,
XLM(1), XLM(2), XLM(3), TAU(1), TAU(2), and TAU(3) are floating-point numbers each occupying 10 columns beginning at column 21.

CARD 6:

- (a) The assumed number of data points NSPTS to be indicative of a required phase shift:
If NSPTS is less than zero, NSPTS will be set to its absolute value. The value of (NSPTS x sampling rate) should not exceed

* These parameters are defined in the discussion accompanying equations.

unity; however, this suggestion is not mandatory. NSPTS is a right-adjusted integer number less than the total number of data points occupying columns 1-5.

- (b) The pitch angle linear drift DRIFT:

DRIFT is used by the equation:

$$(\text{pitch angle})_{\text{new}} = (\text{pitch angle})_{\text{old}} + \text{DRIFT}$$

$$\times (\text{point number} / \text{total number of points})$$

If DRIFT = 0.0, the application is bypassed. DRIFT is a floating-point number in radians/second occupying 15 columns beginning at column 6.

CARD 7:

- (a) The phase shift parameter LSP(1) for pitch angle,
- (b) the phase shift parameter LSP(2) for pitch rate,
- (c) the phase shift parameter LSP(3) for airspeed,
- (d) the phase shift parameter LSP(4) for static pressure,
- (e) the phase shift parameter LSP(5) for angle of attack,
- (f) the phase shift parameter LSP(6) for stagnation temperature,
- (g) the phase shift parameter LSP(7) for longitudinal acceleration,
- (h) the phase shift parameter LSP(8) for vertical acceleration, and
- (i) the phase shift parameter LSP(9) for the elevator or stabilator deflection:

If LSP(1) = 0, no phase shift is desired on variable "I" (or variable "I" was recorded by commutation). If LSP(1) = 1, a phase shift is desired on variable "I" (or variable "I" was recorded by frequency modulation). LSP(1) are right-adjusted integer numbers each occupying 5 columns beginning at column 1.

CARD 8:

- (a) The aircraft's wing area S in square feet,
- (b) the aircraft's gross takeoff weight GWT in pounds force,
- (c) the fuel consumption rate FCR1 in pounds force per second from takeoff or engine-start to the first maneuver,
- (d) the fuel consumption rate FCR2 in pounds force per second during the maneuvers,
- (e) the angle-of-attack-instrument location XACG in feet from the aircraft's center of gravity,
- (f) the pitch-angle-instrument-bias correction PCCG in radians,
- (g) the calibration factor CALP1 to the angle of attack, and
- (h) the calibration term CALP2 in radians to the angle of attack:

It should be noted that the program assumes FCR1 for the fuel consumption rate between maneuvers where the elapsed time ELAP is nonzero. XACG is a positive quantity if the instrument is ahead of the cg and negative if it is behind

the cg. S, GWT, FCR1, FCR2, XACG, PCCG, CALP1, and CALP2 are floating-point numbers each occupying 10 columns beginning at column 1.

CARDS 9, 10, 11:

- (a) The conversion factor CF(1) of time to seconds,
- (b) the conversion factor CF(2) of weight to pounds force,
- (c) the conversion factor CF(3) of pitch angle to radians,
- (d) the conversion factor CF(4) of pitch rate to radian per second,
- (e) the conversion factor CF(5) of airspeed to feet per second,
- (f) the conversion factor CF(6) of static pressure to pounds force per square foot,
- (g) the conversion factor CF(7) of angle of attack to radians,
- (h) the conversion factor CF(8) of stagnation temperature in the equation $T(^{\circ}R) = CF(8) \times T(^{\circ}X) + CF(9)$ for degrees Rankine,
- (i) the conversion term CF(9) of stagnation temperature in the equation $T(^{\circ}R) = CF(8) \times T(^{\circ}X) + CF(9)$ for degrees Rankine,
- (j) the conversion factor CF(10) of longitudinal acceleration to feet per squared second,
- (k) the conversion factor CF(11) of vertical acceleration to feet per squared second, and
- (l) the conversion factor CF(12) of elevator or stabilator deflection to radians:

If CF(8) = 0.0, CF(8) is set equal to 1.0. CF(1) through CF(12) are double-precision floating-point numbers occupying 20 card-columns each. CF(1) through CF(4) are contained on the ninth input-data card beginning with column 1, CF(5) through CF(8) are contained on the tenth input-data card, and CF(9) through CF(12) are contained on the eleventh input-data card beginning with column 1.

CARD 12:

The number of points MPTS on the (ratio-of-the-pressure-difference-to-the-dynamic-pressure versus the-indicated-airspeed) curve for the position-error pressure corrections:

MPTS must be greater than zero and no larger than 20. MPTS is a right-adjusted integer number occupying columns 1-2.

CARD 13,...,(12 + MPTS):

The measured values of the ratio of the pressure difference to the dynamic pressure DPQCP, and the measured values of the indicated airspeed VE in feet per second:

It is suggested that the values of DPQCP and VE span a sufficiently large region to include the input data's speed range. DPQCP and VE are floating-point numbers occupying columns 1-20 and columns 21-40, respectively, for each of the MPTS cards.

CARDS (12 + MPTS + 1), ..., (12 + MPTS + 2K):

The time histories of time TIME(K), pitch angle D(K,IVL=2), pitch rate D(K,IVL=3), airspeed D(K,IVL=4), static pressure D(K,IVL=5), angle of attack D(K,IVL=6), stagnation temperature D(K,IVL=7), longitudinal acceleration D(K,IVL=8), vertical acceleration D(K,IVL=10), and elevator or stabilator deflection D(K,IVL=11) for K=1 through K=450(maximum).

It should be noted that IVL parameters in D(K,IVL) correspond to the variable location numbers IVL(1) described on page 211. The duration of a maneuver is determined either by a maximum count of 450 data points and the perception of two(2) user-supplied blank or zero cards within the next 1000 counts or by the perception of two(2) user-supplied blank or zero cards.* TIME(K) and the D(K,IVL)'s are double-precision floating-point numbers. Two(2) cards describe a single data point with TIME(K) always occupying columns 1-15 on the first card. Each card contains five variables each occupying 15 columns beginning at column 1.

FDR1 Section 2

CARD (12 + MPTS + 2K + 1):

- (a) The Fourier-series analysis code IFS(1) for weight,
- (b) the Fourier-series analysis code IFS(2) for pitch angle,
- (c) the Fourier-series analysis code IFS(3) for pitch rate,
- (d) the Fourier-series analysis code IFS(4) for airspeed,
- (e) the Fourier-series analysis code IFS(5) for density,
- (f) the Fourier-series analysis code IFS(6) for angle of attack,
- (g) the Fourier-series analysis code IFS(7) for static temperature,
- (h) the Fourier-series analysis code IFS(8) for acceleration,
- (i) the Fourier-series analysis code IFS(9) for altitude,
- (j) the Fourier-series analysis code IFS(10) for vertical acceleration, and
- (k) the Fourier-series analysis code IFS(11) for elevator or stabilator deflection:
 - If IFS(1) = 0, analysis is performed on the "I"th time history.
 - If IFS(1) = 1, no analysis is performed on the "I"th time history.
 - IFS(1) are right-adjusted integer numbers each occupying 1 column beginning at column 1.

* In general, data sets will consist of more than 450 points. In order that the parameters of successive data sets are properly entered, all "extra" time-history data of the present maneuver must be ignored. The extra 1000-count specification "implies" that within 1000 data points beyond the maximum 450 data points the two(2) user-supplied blank or zero cards will be encountered.

CARD (12 + MPTS + 2K + 2):

- (a) The acceleration-determination code IPRC(1):
 If IPRC(1) = 0, the acceleration is calculated by the differentiation of the airspeed time history. If IPRC(1) = 1, the longitudinal acceleration is transformed into the rate-of-change of airspeed by the kinematic relationship between the aircraft's body axis and its flight path.
- (b) The degree of computation on the longitudinal acceleration IPRC(2):
 If IPRC(2) = 0, the longitudinal acceleration is transformed into the rate-of-change of airspeed by the kinematic relationship between the aircraft's body axis and its flight path and is smoothed by Fourier series and filtering. If IPRC(2) = 1, the longitudinal acceleration is only transformed into the rate-of-change of airspeed by the kinematic relationship between the aircraft's body axis and its flight path. If IPRC(2) = 2, the input values of longitudinal acceleration are retained. The following chart should be consulted in specifying IFS(4), IPRC(1), and IPRC(2) so that the program produces desired results:

Parameter Combinations	Results
IFS(4)=0, IPRC(1)=0, IPRC(2)=0	Result #1
IFS(4)=0, IPRC(1)=0, IPRC(2)=1	Result #1
IFS(4)=0, IPRC(1)=0, IPRC(2)=2	Result #1
IFS(4)=0, IPRC(1)=1, IPRC(2)=0	Result #2
IFS(4)=0, IPRC(1)=1, IPRC(2)=1	Result #3
IFS(4)=0, IPRC(1)=1, IPRC(2)=2	Illegal combination
IFS(4)=1, IPRC(1)=0, IPRC(2)=0	Result #4
IFS(4)=1, IPRC(1)=0, IPRC(2)=1	Result #4
IFS(4)=1, IPRC(1)=0, IPRC(2)=2	Illegal combination
IFS(4)=1, IPRC(1)=1, IPRC(2)=0	Result #4
IFS(4)=1, IPRC(1)=1, IPRC(2)=1	Result #4
IFS(4)=1, IPRC(1)=1, IPRC(2)=2	Illegal combination

- Result #1: Airspeed will be the smoothed input airspeed. Acceleration will be the differentiation of the smoothed airspeed.
- Result #2: Airspeed will be the smoothed input airspeed. Acceleration will be the Fourier-series-smoothed rate-of-change of airspeed transformation of the longitudinal acceleration.
- Result #3: Airspeed will be the smoothed input airspeed. Acceleration will be the unsmoothed rate-of-change of airspeed transformation of the longitudinal acceleration.
- Result #4: Airspeed will be the input airspeed. Acceleration will be the Fourier-series-smoothed rate-of-change of airspeed transformation of longitudinal acceleration.

- (c) The method of angle-of-attack rate computation IPRC(3):
If IPRC(3) = 0, the angle-of-attack rate will be calculated by the differentiation of the angle-of-attack's Fourier series. If IPRC(3) = 1, the angle-of-attack rate will be the differentiation of a cubic-spline fit of the angle of attack. It should be noted that if IFS(6) = 1 and IPRC(3) = 0, the program will set IPRC(3) = 1. IPRC(3) is a right-adjusted integer number occupying 1 column beginning at column 3.
- (d) The overall Fourier-series analysis code IPRC(4):
If IPRC(4) = 0, Fourier-series analysis will be performed on the time histories whose IFS(1) are zero. If IPRC(4) = 1, no Fourier-series analysis will be performed even if IFS(1) = 0. The specification of IPRC(4) = 1 provides a means to analyze "raw" data. IPRC(4) is a right-adjusted integer number occupying one column beginning at column 4.
- (e) The overall plotting code IPRC(5):
If IPRC(5) = 0, plots are requested. If IPRC(5) = 1, no plots are requested. IPRC(5) is a right-adjusted integer number occupying one column beginning at column 5.
- (f) The punch code IPRC(6):
If IPRC(6) = 0, punched output is requested. If IPRC(6) = 1, no punched output is requested. IPRC(6) is a right-adjusted integer number occupying one column beginning at column 6.
- (g) The pitch-angle determination code IPRC(7):
If IPRC(7) = 0, the pitch-angle time history will be the "modified" input pitch-angle time history. If IPRC(7) = 1, the pitch-angle time history will be the integrated pitch-rate time history. IPRC(7) is a right-adjusted integer number occupying one column beginning at column 7.
- (h) The compatibility check IPRC(8):
If IPRC(8) = 0, the compatibility check is bypassed. If IPRC(8) = 1, an angle-of-attack time history will be computed to be compatible with other time histories. If IPRC(8) = 2, an altitude time history will be computed to be pneumatically compatible with other time histories. It should be noted that the compatible altitude time history will exist only on the altitude-time-history plot whereas the compatible angle-of-attack time history will replace the existing angle-of-attack time history. Generally, IPRC(8) should be zero. IPRC(8) is a right-adjusted integer number occupying one column beginning at column 8.
- (i) The calculation code of the inertial-compatible altitude and airspeed IPRC(9):
If IPRC(9) = 0, the calculation of the inertial-compatible altitude and airspeed will be bypassed. If IPRC(9) = 1, the inertial-compatible altitude and airspeed will be computed. (If only the inertial-compatible airspeed is desired, see the discussion of FAC1 and FAC2 below.)

- (j) The distance XAX in feet of the longitudinal accelerometer from the aircraft's cg:
 XAX is a positive quantity if the accelerometer is ahead of the cg and a negative quantity if the accelerometer is behind the cg. Parameter XAX is a double-precision floating-point number occupying 15 columns beginning at column 11.
- (k) The fraction of the pneumatic-compatible altitude FAC1 and the fraction of the inertial-compatible altitude FAC2:
 The sum of FAC1 and FAC2 should be equal to 1.0; that is, $FAC1 + FAC2 = 1.0$. If only the inertial-compatible airspeed is desired, the user must specify $IPRC(9) = 1$, $FAC1 = 1.0$, and $FAC2 = 0.0$. Parameters FAC1 and FAC2 are double-precision floating-point numbers each occupying 15 columns beginning at column 26.
- (l) The data sampling rate DSPS per second:
 Parameter DSPS is a double-precision floating-point number occupying 15 columns beginning at column 56.

CARD (12 + MPTS + 2K + 3):

- (a) The plot code IP(1) for weight,
- (b) the plot code IP(2) for pitch angle,
- (c) the plot code IP(3) for pitch rate,
- (d) the plot code IP(4) for airspeed,
- (e) the plot code IP(5) for density,
- (f) the plot code IP(6) for angle of attack,
- (g) the plot code IP(7) for static temperature,
- (h) the plot code IP(8) for acceleration,
- (i) the plot code IP(9) for angle-of-attack rate,
- (j) the plot code IP(10) for altitude,
- (k) the plot code IP(11) for altitude rate of change,
- (l) the plot code IP(12) for altitude acceleration,
- (m) the plot code IP(13) for vertical acceleration, and
- (n) the plot code IP(14) for the elevator or stabilator deflection.
 If $IP(1)=0$, a plot is produced for the "I"th time history.
 If $IP(1)=1$, no plot is produced for the "I"th time history.
 IP(I) are right-adjusted integer numbers each occupying one column beginning at column 1.

CARD (12 + MPTS + 2K + 4):

- (a) The filter cutoff harmonic NC(1) for weight,
- (b) the filter cutoff harmonic NC(2) for pitch angle,
- (c) the filter cutoff harmonic NC(3) for pitch rate,
- (d) the filter cutoff harmonic NC(4) for airspeed,
- (e) the filter cutoff harmonic NC(5) for density,
- (f) the filter cutoff harmonic NC(6) for angle of attack,
- (g) the filter cutoff harmonic NC(7) for static temperature,
- (h) the filter cutoff harmonic NC(8) for acceleration,
- (i) the filter cutoff harmonic NC(9) for altitude,

- (j) the filter cutoff harmonic NC(10) for vertical, and
- (k) the filter cutoff harmonic NC(11) for the elevator or stabilator deflection.

All NC(I) are right-adjusted integer numbers each occupying 5 columns beginning at column 1. It is mandatory that $0 < NC(I) < 66$.

CARDS (12 + MPTS + 2K + 5), ..., (12 + MPTS + 2K + 10):

- (a) The a priori value AP(1) in feet per second squared and its weight W(1) for the first linear acceleration dependency,
- (b) the a priori value AP(2) in feet per second squared and its weight W(2) for the second linear acceleration dependency,
- (c) the a priori value AP(3) in feet per second squared and its weight W(3) for the third linear acceleration dependency,
- (d) the a priori value AP(4) in radians and its weight W(4) for the pitch angle bias,
- (e) the a priori value AP(5) and its weight W(5) for the phase shift, and
- (f) the a priori value AP(6) in radians and its weight W(6) for the flight-path-angle bias:

AP(I) and W(I) are double-precision floating-point numbers each occupying 20 columns beginning at column 1. Each of the six(6) input cards contains the AP(I) and W(I) that correspond to the dependency or bias under consideration.

CARDS (12 + MPTS + 2K + 11), ..., (12 + MPTS + 2K + 10 + NUMBER!/(NUMBER-1)!):

- (a) The code IR(1) for the calculation of the first linear acceleration dependency,
- (b) the code IR(2) for the calculation of the second linear acceleration dependency,
- (c) the code IR(3) for the calculation of the third linear acceleration dependency,
- (d) the code IR(4) for the calculation of the pitch-angle bias,
- (e) the code IR(5) for the calculation of the phase shift, and
- (f) the code IR(6) for the calculation of the flight-path-angle bias.

If IR(I) = 0, the calculation for the "I"th variable is excluded. If IR(I) = 1, the calculation for the "I"th variable is included. The calculation of at least one variable, preferably two, must be included. Failure to specify at least one variable will terminate the program prematurely. Parameters IR(I) are right-adjusted integer numbers each occupying one column beginning at column 1. It is necessary to provide [(NUMBER!)/(NUMBER-1)!] input cards containing the IR(I) codes.

For a given run consisting of one or more data sets (maneuvers), cards 1 and 2 need to be specified only once. Cards 3 through (12 + MPTS + 2K + 10 + NUMBER!/(NUMBER-1)!) need to be specified for each maneuver.

Program Listing - FDRI

PROGRAM: FLIGHT DATA REDUCTION #1 (FDRI) P.O. SMETANA/ S.R. FOX

* DATA REDUCTION SECTION NO. 1 *

GIVEN VALUES OF THE AIRCRAFT CHARACTERISTICS AND THE AIRCRAFT'S FLIGHT TIME HISTORIES OF PITCH ANGLE, PITCH RATE, AIRSPEED, STATIC PRESSURE, ANGLE OF ATTACK, TOTAL TEMPERATURE, LONGITUDINAL ACCELERATION, VERTICAL ACCELERATION, AND ELEVATOR (OR STABILATOR) DEFLECTION, THIS SECTION PERFORMS THE FOLLOWING:

- 1) ADJUSTS DATA, IF DESIRED, FOR AN ASSUMED PHASE SHIFT
- 2) CONVERTS TIME TO SECONDS
- 3) COMPUTES TOTAL MANEUVER EXECUTION TIME
- 4) COMPUTES AIRCRAFT'S WEIGHT TIME HISTORY
- 5) CONVERTS WEIGHT TO POUNDS FORCE
- 6) CONVERTS PITCH ANGLE TO RADIANS
- 7) CONVERTS PITCH RATE TO RADIANS PER SECOND
- 8) CONVERTS AIRSPEED TO FEET PER SECOND
- 9) CONVERTS STATIC PRESSURE TO POUNDS FORCE PER SQUARE FOOT
- 10) CONVERTS ANGLE OF ATTACK TO RADIANS
- 11) CONVERTS TOTAL TEMPERATURE TO DEGREES RANKINE
- 12) CONVERTS LONGITUDINAL ACCELERATION TO FEET PER SECOND SQUARED
- 13) CONVERTS VERTICAL ACCELERATION TO FEET PER SECOND SQUARED
- 14) CONVERTS ELEVATOR (OR STABILATOR) DEFLECTION TO RADIANS
- 15) CALCULATES LAG CORRECTIONS TO STATIC PRESSURE AND DYNAMIC PRESSURE
- 16) CALCULATES POSITION ERROR CORRECTION RATIO DP/QC
- 17) CALCULATES ACCELERATION-DEPENDENT CORRECTIONS TO STATIC PRESSURE
- 18) CONVERTS TOTAL TEMPERATURE TO STATIC TEMPERATURE
- 19) CONVERTS STATIC PRESSURE TO DENSITY
- 20) CONVERTS DENSITY TO ALTITUDE

21) CONVERTS INDICATED AIRSPEED TO TRUE AIRSPEED

22) CORRECTS PITCH ANGLE INDICATION FOR KNOWN INITIAL BIAS AND ANGLE OF ATTACK INDICATION FOR INSTRUMENT LOCATION

23) CALIBRATES ANGLE OF ATTACK INDICATION

24) PREPARES DATA FOR DATA REDUCTION SECTION NO. 2

THE FOLLOWING COMMENT CARDS DESCRIBE THE NECESSARY INPUT FOR DATA REDUCTION SECTION NO.1. FOR A MORE PRECISE DESCRIPTION, CONSULT THE USERS INSTRUCTIONS.

INPUT *** CARD 1

NSETS -> NUMBER OF DATA SETS TO BE ANALYZED
(-1 < NSETS < 11)

METRIC -> TYPE OF OUTPUT UNITS
METRIC=0 : ENGLISH UNITS
METRIC=1 : SI UNITS

INPUT *** CARD 2

ICODE -> ICODE=0 : CONTINUOUS WEIGHT TIME HISTORY
(CONTINUOUS FROM FIRST OR PRECEDING WEIGHT TIME HISTORY WITH NO ELAPSED TIME CONSIDERATIONS BETWEEN MANEUVERS)

ICODE=1 : DISCONTINUOUS WEIGHT TIME HISTORY
(CONTINUOUS FROM FIRST OR PRECEDING WEIGHT TIME HISTORY WITH ELAPSED TIME CONSIDERATIONS BETWEEN MANEUVERS)

INPUT *** CARD 3

NUMBER -> MAXIMUM NUMBER OF IMPROVEMENT ITERATIONS

ELAP -> ELAPSED TIME TO MANEUVER IN SECONDS

JFILE -> DATA SET FILE NUMBER

IVL (1) -> LOCATION NUMBER OF VARIABLE IN 2ND DATA FIELD
IVL (2) -> LOCATION NUMBER OF VARIABLE IN 3RD DATA FIELD
IVL (3) -> LOCATION NUMBER OF VARIABLE IN 4TH DATA FIELD
IVL (4) -> LOCATION NUMBER OF VARIABLE IN 5TH DATA FIELD
IVL (5) -> LOCATION NUMBER OF VARIABLE IN 6TH DATA FIELD
IVL (6) -> LOCATION NUMBER OF VARIABLE IN 7TH DATA FIELD
IVL (7) -> LOCATION NUMBER OF VARIABLE IN 8TH DATA FIELD
IVL (8) -> LOCATION NUMBER OF VARIABLE IN 9TH DATA FIELD
IVL (9) -> LOCATION NUMBER OF VARIABLE IN 10TH DATA FIELD

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C INPUT *** CARD 4 (FROM DATA SET JFILE)
C TITLE -> TITLE CARD FOR MANEUVER
C
C INPUT *** CARD 5
C NCH(1) -> FOURIER SERIES CUTOFF HARMONIC FOR AIRSPEED'S
C STATIC PRESSURE MEASUREMENTS 0<NCH(1)<66
C NCH(2) -> FOURIER SERIES CUTOFF HARMONIC FOR ALTITUDE'S
C STATIC PRESSURE MEASUREMENTS 0<NCH(2)<66
C NCH(3) -> FOURIER SERIES CUTOFF HARMONIC FOR AIRSPEED'S AND
C ALTITUDE'S STAGNATION PRESSURE 0<NCH(3)<66
C NCH(4) -> FOURIER SERIES CUTOFF HARMONIC FOR STAGNATION
C TEMPERATURE MEASUREMENTS 0<NCH(4)<66
C NIN(1) -> LAG TIME INTERVAL FOR STAGNATION PRESSURE SYSTEMS
C IN SECONDS
C NIN(2) -> LAG TIME INTERVAL FOR ALTITUDE'S STATIC PRESSURE
C SYSTEMS IN SECONDS
C NIN(3) -> LAG TIME INTERVAL FOR AIRSPEED'S STATIC PRESSURE
C SYSTEMS IN SECONDS
C TAU(1) -> LAG TIME CONSTANT FOR STAGNATION PRESSURE SYSTEMS
C IN SECONDS
C TAU(2) -> LAG TIME CONSTANT FOR ALTITUDE'S STATIC PRESSURE
C SYSTEMS IN SECONDS
C TAU(3) -> LAG TIME CONSTANT FOR AIRSPEED'S STATIC PRESSURE
C SYSTEMS IN SECONDS
C
C INPUT *** CARD 6
C NSPTS -> ASSURED NUMBER OF DATA POINTS TO BE INDICATIVE OF
C A REQUIRED PHASE SHIFT
C DRIFT -> PITCH ANGLE DRIFT (RADIAN/SEC) USED BY:
C PITCH ANGLE(NEW)-PITCH ANGLE(OLD)*DRIFT*(POINT
C NUMBER)/(TOTAL NUMBER OF POINTS)
C
C INPUT *** CARD 7
C LSP(1) -> PHASE SHIFT PARAMETER FOR PITCH ANGLE
C LSP(1)=0 : NO SHIFT (COMMUTATION)
C LSP(1)=1 : SHIFT (FREQUENCY MODULATION)
C LSP(2) -> PHASE SHIFT PARAMETER FOR PITCH RATE
C LSP(2)=0 : NO SHIFT (COMMUTATION)

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C LSP(2)=1 : SHIFT (FREQUENCY MODULATION)
C
C LSP(3) -> PHASE SHIFT PARAMETER FOR AIRSPEED
C LSP(3)=0 : NO SHIFT (COMMUTATION)
C LSP(3)=1 : SHIFT (FREQUENCY MODULATION)
C
C LSP(4) -> PHASE SHIFT PARAMETER FOR STATIC PRESSURE
C LSP(4)=0 : NO SHIFT (COMMUTATION)
C LSP(4)=1 : SHIFT (FREQUENCY MODULATION)
C
C LSP(5) -> PHASE SHIFT PARAMETER FOR ANGLE OF ATTACK
C LSP(5)=0 : NO SHIFT (COMMUTATION)
C LSP(5)=1 : SHIFT (FREQUENCY MODULATION)
C
C LSP(6) -> PHASE SHIFT PARAMETER FOR STAGNATION TEMPERATURE
C LSP(6)=0 : NO SHIFT (COMMUTATION)
C LSP(6)=1 : SHIFT (FREQUENCY MODULATION)
C
C LSP(7) -> PHASE SHIFT PARAMETER FOR LONGITUDINAL ACCELERATION
C LSP(7)=0 : NO SHIFT (COMMUTATION)
C LSP(7)=1 : SHIFT (FREQUENCY MODULATION)
C
C LSP(8) -> PHASE SHIFT PARAMETER FOR VERTICAL ACCELERATION
C LSP(8)=0 : NO SHIFT (COMMUTATION)
C LSP(8)=1 : SHIFT (FREQUENCY MODULATION)
C
C LSP(9) -> PHASE SHIFT PARAMETER FOR ELEVATOR DEFLECTION
C LSP(9)=0 : NO SHIFT (COMMUTATION)
C LSP(9)=1 : SHIFT (FREQUENCY MODULATION)
C
C INPUT *** CARD 8
C S -> WING AREA IN SQUARE FEET
C GWT -> GROSS TAKEOFF WEIGHT IN POUNDS FORCE
C FCR1 -> FUEL CONSUMPTION RATE IN POUNDS FORCE PER SECOND
C FROM TAKEOFF TO FIRST MANEUVER
C FCR2 -> FUEL CONSUMPTION RATE IN POUNDS FORCE PER SECOND
C DURING MANEUVERS
C XACG -> ANGLE-OF-ATTACK INSTRUMENT LOCATION FROM CENTER OF
C GRAVITY (POSITIVE IF XACG AHEAD CG, NEGATIVE IF
C XACG BEHIND CG) IN FEET
C FCCG -> KNOWN PITCH-ANGLE INSTRUMENT BIAS CORRECTION IN
C RADIANS
C CALF1 -> CALIBRATION FACTOR TO ANGLE OF ATTACK
C CALF2 -> CALIBRATION TERM TO ANGLE OF ATTACK IN RADIANS
C
C INPUT *** CARDS 9,10,11 CONVERSION FACTORS OR TERMS
C CP(1) -> TIME TO SECONDS

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C      CF(2)  ->  WEIGHT TO POUNDS FORCE          NL 241
C      CF(3)  ->  PITCH ANGLE TO RADIANS         NL 242
C      CF(4)  ->  PITCH RATE TO RADIANS PER SECOND NL 243
C      CF(5)  ->  AIRSPEED TO FEET PER SECOND    NL 244
C      CF(6)  ->  STATIC PRESSURE TO POUNDS FORCE PER SQUARE FOOT NL 245
C      CF(7)  ->  ANGLE OF ATTACK TO RADIANS     NL 246
C      CF(8)  ->  TEMPERATURE FACTOR FOR DEGREES RANKINE NL 247
C      CF(9)  ->  TEMPERATURE TERM FOR DEGREES RANKINE NL 248
C      CF(10) ->  LONGITUDINAL ACCELERATION TO FEET PER SQUARED SECOND NL 249
C      CF(11) ->  VERTICAL ACCELERATION TO FEET PER SQUARED SECONDS NL 250
C      CF(12) ->  ELEVATOR DEFLECTION TO RADIANS  NL 251
C
C INPUT *** CARD 12
C      NPTS ->  NUMBER OF POINTS ON DPQCP VS. VE CURVE <21 NL 252
C
C INPUT *** CARDS 13,....,(12*NPTS)
C      DPQCP ->  MEASURED POSITION ERROR CORRECTION RATIO NL 253
C      VE ->  MEASURED VALUES OF INDICATED AIRSPEED IN FEET PER SECOND NL 254
C
C INPUT *** 'CARDS' (12*NPTS+1),....,(12*NPTS+K1) (FROM DATA SET JPILE)
C      IDENTIFICATION OF NECESSARY INPUT TIME HISTORIES
C
C      TIME(1) ->  TIME NL 255
C      D(1,2) ->  PITCH ANGLE NL 256
C      D(1,3) ->  PITCH RATE NL 257
C      D(1,4) ->  AIRSPEED NL 258
C      D(1,5) ->  STATIC PRESSURE NL 259
C      D(1,6) ->  ANGLE OF ATTACK NL 260
C      D(1,7) ->  STAGNATION TEMPERATURE NL 261
C      D(1,8) ->  LONGITUDINAL ACCELERATION NL 262
C      D(1,10) ->  VERTICAL ACCELERATION NL 263
C      D(1,11) ->  ELEVATOR DEFLECTION NL 264
C
C      ***** NL 265

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* DATA REDUCTION SECTION NO. 2 *
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THE FOLLOWING PROGRAM CAPABILITIES ARE OPTIONAL. THE USER MUST SPECIFY THE DESIRED OPTIONS. THE USER SHOULD CONSULT THE USERS INSTRUCTIONS ('FORI', SECTION 2) FOR 'ILLEGAL' OPTION COMBINATIONS. GIVEN VALUES OF THE AIRCRAFT CHARACTERISTICS AND TIME HISTORIES OF WEIGHT, PITCH ANGLE, PITCH RATE, AIRSPEED, DENSITY, ANGLE-OF-ATTACK, STATIC TEMPERATURE, LONGITUDINAL ACCELERATION, ALTITUDE, VERTICAL ACCELERATION, AND ELEVATOR (OR STABILATOR) DEFLECTION, THIS SECTION PERFORMS THE FOLLOWING:

- 1) PERFORMS FOURIER ANALYSIS AND FILTERING ON WEIGHT TIME HISTORY
- 2) PERFORMS FOURIER ANALYSIS AND FILTERING ON PITCH ANGLE TIME HISTORY
- 3) PERFORMS FOURIER ANALYSIS AND FILTERING ON PITCH RATE TIME HISTORY
- 4) INTEGRATES PITCH RATE TO OBTAIN PITCH ANGLE, IF DESIRED
- 5) PERFORMS FOURIER ANALYSIS AND FILTERING ON AIRSPEED TIME HISTORY
- 6) CALCULATES ACCELERATION FROM AIRSPEED
- 7) PERFORMS FOURIER ANALYSIS AND FILTERING ON DENSITY TIME HISTORY
- 8) PERFORMS FOURIER ANALYSIS AND FILTERING ON ANGLE-OF-ATTACK TIME HISTORY
- 9) CALCULATES ANGLE-OF-ATTACK RATE FROM THE FOURIER-FILTER MODIFICATION OF ANGLE OF ATTACK OR FROM DIFFERENTIATION OF SPLINED-INPUT ANGLE OF ATTACK
- 10) PERFORMS FOURIER ANALYSIS AND FILTERING OF STATIC TEMPERATURE TIME HISTORY
- 11) CONVERTS LONGITUDINAL ACCELERATION INTO ACCELERATION COMPATIBLE WITH AIRSPEED
- 12) PERFORMS FOURIER ANALYSIS AND FILTERING OF LONGITUDINAL ACCELERATION TIME HISTORY
- 13) PERFORMS FOURIER ANALYSIS AND FILTERING OF ALTITUDE TIME HISTORY
- 14) CALCULATES DENSITY FROM ALTITUDE
- 15) CALCULATES ALTITUDE RATE OF CHANGE AND ACCELERATION FROM DIFFERENTIATIONS OF THE FOURIER-FILTER MODIFICATION OF ALTITUDE OR SPLINED-INPUT ALTITUDE

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- 16) CALCULATES COMPATIBLE ANGLE-OF-ATTACK VALUES FROM OTHER TIME HISTORIES
- 17) CALCULATES COMPATIBLE ALTITUDE AND ALTITUDE RATE FROM INTEGRAL OF DERIVATIVE OF FLIGHT-PATH ANGLE
- 18) PERFORMS FOURIER ANALYSIS AND FILTERING ON VERTICAL ACCELERATION TIME HISTORY
- 19) PERFORMS FOURIER ANALYSIS AND FILTERING ON ELEVATOR (OR STABILATOR) DEFLECTION TIME HISTORY
- 20) PERFORMS MINIMIZATION WITH OR WITHOUT A PRIORI VALUES FOR DATA COMPATIBILITY
- 21) PLOTS TIME HISTORIES
- 22) WRITES RESULTS IN ENGLISH OR SI UNITS
- 23) PUNCHES CARDS FOR USE IN PROGRAM 'PDR2'

THE FOLLOWING COMMENT CARDS DESCRIBE THE NECESSARY INPUT FOR DATA REDUCTION SECTION NO.2. FOR A MORE PRECISE DESCRIPTION, CONSULT THE USERS INSTRUCTIONS.

C INPUT *** CARD (12*NPTS*K+1)

- IFS(1) -> FOURIER ANALYSIS ON WEIGHT TIME HISTORY
IFS(1)=0 -> YES
IFS(1)=1 -> NO
- IFS(2) -> FOURIER ANALYSIS ON PITCH ANGLE TIME HISTORY
IFS(2)=0 -> YES
IFS(2)=1 -> NO
- IFS(3) -> FOURIER ANALYSIS ON PITCH RATE TIME HISTORY
IFS(3)=0 -> YES
IFS(3)=1 -> NO
- IFS(4) -> FOURIER ANALYSIS ON AIRSPEED TIME HISTORY
IFS(4)=0 -> YES
IFS(4)=1 -> NO
- IFS(5) -> FOURIER ANALYSIS ON DENSITY TIME HISTORY
IFS(5)=0 -> YES
IFS(5)=1 -> NO
- IFS(6) -> FOURIER ANALYSIS ON ANGLE OF ATTACK TIME HISTORY
IFS(6)=0 -> YES
IFS(6)=1 -> NO
- IFS(7) -> FOURIER ANALYSIS ON STATIC TEMPERATURE TIME HISTORY
IFS(7)=0 -> YES
IFS(7)=1 -> NO
- IFS(8) -> FOURIER ANALYSIS ON 'ACCELERATION' TIME HISTORY

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- IFS(9)=0 -> YES
IFS(9)=1 -> NO
- IFS(9) -> FOURIER ANALYSIS ON ALTITUDE TIME HISTORY
IFS(9)=0 -> YES
IFS(9)=1 -> NO
- IFS(10) -> FOURIER ANALYSIS ON VERTICAL ACCELERATION HISTORY
IFS(10)=0 -> YES
IFS(10)=1 -> NO
- IFS(11) -> FOURIER ANALYSIS ON (ELEVATOR/STABILATOR) HISTORY
IFS(11)=0 -> YES
IFS(11)=1 -> NO

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C INPUT *** CARD (12*NPTS*K+2)

- IPRC(1) -> METHOD OF ACCELERATION DETERMINATION
IPRC(1)=0 -> DERIVATIVE OF AIRSPEED TIME HISTORY
IPRC(1)=1 -> CONVERTED LONGITUDINAL ACCELERATION
- IPRC(2) -> DEGREE OF COMPUTATION ON LONGITUDINAL ACCELERATION
IPRC(2)=0 -> LONGITUDINAL ACCELERATION CONVERTED TO RATE-OF-CHANGE OF AIRSPEED BY TRANSFORMATION AND SMOOTHED BY FILTERING
IPRC(2)=1 -> LONGITUDINAL ACCELERATION CONVERTED TO RATE-OF-CHANGE OF AIRSPEED BY TRANSFORMATION
IPRC(2)=2 -> ORIGINAL LONGITUDINAL ACCELERATION
- IPRC(3) -> METHOD OF ANGLE-OF-ATTACK RATE COMPUTATION
IPRC(3)=0 -> DERIVATIVE OF ANGLE-OF-ATTACK HISTORY
IPRC(3)=1 -> DERIVATIVE OF SPLICED ANGLE OF ATTACK
- IPRC(4) -> OVERALL FOURIER ANALYSIS CODE
IPRC(4)=0 -> REQUEST FOURIER ANALYSIS
IPRC(4)=1 -> DECLINE FOURIER ANALYSIS
- IPRC(5) -> OVERALL PLOTTING CODE
IPRC(5)=0 -> REQUEST PLOTS
IPRC(5)=1 -> DECLINE PLOTS
- IPRC(6) -> PUNCH CODE
IPRC(6)=0 -> REQUEST PUNCHED CARDS
IPRC(6)=1 -> DECLINE PUNCHED CARDS
- IPRC(7) -> METHOD OF PITCH ANGLE DETERMINATION
IPRC(7)=0 -> ORIGINAL PITCH-ANGLE TIME HISTORY
IPRC(7)=1 -> INTEGRATION OF PITCH-RATE TIME HISTORY
- IPRC(8) -> COMPATIBILITY CHECK
IPRC(8)=0 -> BYPASS COMPATIBILITY CHECK
IPRC(8)=1 -> COMPUTE COMPATIBLE ANGLE OF ATTACK
IPRC(8)=2 -> COMPUTE COMPATIBLE ALTITUDE
- IPRC(9) -> CALCULATION OF INERTIAL-COMPATIBLE ALTITUDE
IPRC(9)=0 -> BYPASS ANALYSIS
IPRC(9)=1 -> PERFORM ANALYSIS

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C      AP(4), W(4) -> A PRIORI VALUE AND ITS WEIGHT FOR THE PITCH
C      ANGLE BIAS
C      AP(5), W(5) -> A PRIORI VALUE AND ITS WEIGHT FOR THE PHASE
C      SHIFT
C      AP(6), W(6) -> A PRIORI VALUE AND ITS WEIGHT FOR THE FLIGHT
C      PATH ANGLE BIAS
C INPUT *** CARDS (12*NPTS*K+1), ..., (12*NPTS*K+10+NUMBER1/(NUMBER-1) 1)
C *** CARDS:
C      IR(1) -> CODE FOR THE CALCULATION OF THE FIRST LINEAR
C      ACCELERATION DEPENDENCY
C      IR(1)=0 -> EXCLUDE
C      IR(1)=1 -> INCLUDE
C      IR(2) -> CODE FOR THE CALCULATION OF THE SECOND LINEAR
C      ACCELERATION DEPENDENCY
C      IR(2)=0 -> EXCLUDE
C      IR(2)=1 -> INCLUDE
C      IR(3) -> CODE FOR THE CALCULATION OF THE THIRD LINEAR
C      ACCELERATION DEPENDENCY
C      IR(3)=0 -> EXCLUDE
C      IR(3)=1 -> INCLUDE
C      IR(4) -> CODE FOR THE CALCULATION OF THE PITCH ANGLE BIAS
C      IR(4)=0 -> EXCLUDE
C      IR(4)=1 -> INCLUDE
C      IR(5) -> CODE FOR THE CALCULATION OF THE PHASE SHIFT
C      IR(5)=0 -> EXCLUDE
C      IR(5)=1 -> INCLUDE
C      IR(6) -> CODE FOR THE CALCULATION OF THE FLIGHT PATH ANGLE
C      BIAS
C      IR(6)=0 -> EXCLUDE
C      IR(6)=1 -> INCLUDE
C      IMPLICIT REAL*8(A-H,O-Z)
C      EXTERNAL PHIDEN
C      DIMENSION WNNH(10), CPQCP(20), VE(20), AA(4,20), ICODE(11), IN(450,1), C
C      IN(450,4), LSP(9), MCH(4), XLR(3), TAU(3), CP(12), PA(450), SVFC(10), NVFC(
C      110), IVL(9)
C      COMMON TITLE(20), D(450,11), TIME(450), A(100), W(100), P1(450), P2(450)
C      1, P3(450), ASD(450), F(450), PD(450), PS(450), PSD(450), TT, BNO, PI, G, JPL
C      10, BTRIC, JREAD, JWRITE, JPONCH, IERR
C      COMMON /TEMP1/ST(450,4), PAR(6), PSL, TSL, IPAN
C      DATA ZERO/4ZERO /
C *** SPECIFY CARRIAGE CONTROL FOR INSTALLATION
C      JREAD=1
C      JWRITE=3
C      JPONCH=2

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C *** INITIALIZE PARAMETERS
C      G=32.2DC
C      GAMMA=1.400
C      S=1716.161200
C      BNC=0.00237E0
C      TSL=518.7200
C      PSL=14.700+144.000
C      PI=3.14159265358979300
C      JFLOT=0
C      RJ=1
C
C      READ (JREAD,1) NSPTS,BTRIC
C      1 FORMAT (2I5)
C
C      IF (NSPTS.LE.0.OR.NSPTS.GT.10) GO TO 121
C
C      READ (JREAD,2) (ICODE(I),I=1,NSPTS)
C      2 FORMAT (10I5)
C
C      ICODE(NSPTS+1)=0
C
C      3 READ (JREAD,4) NUMBER,ELAP,JRILN,(IVL(I),I=1,9)
C      4 FORMAT (I5,F10.0,10I5)
C
C      5 READ (JFILL,6) (TITLE(I),I=1,20)
C      6 FORMAT (20A4)
C
C *** CHECK FOR EXECUTION TERMINATION
C      IF (TITLE(1).EQ.ZERO) GO TO 123
C *** INITIALIZE ERROR CODES
C      IERR=0
C      INC=0
C
C      READ (JREAD,7) MCH(1),MCH(2),MCH(3),MCH(4),XLR(1),XLR(2),XLR(3),TA
C      10(1),TAU(2),TAU(3)
C      7 FORMAT (4I5,6F10.0)
C
C      READ (JREAD,8) NSPTS,DRIFT
C      8 FORMAT (I5,F15.0)
C
C *** FORCE NSPTS TO BE POSITIVE
C      NSPTS=ABS(NSPTS)
C
C      READ (JREAD,9) (LSP(I),I=1,9)
C      9 FORMAT (9I5)
C
C      READ (JREAD,10) S,GWT,PCB1,PCB2,YACG,PCCG,CALP1,CALP2
C      10 FORMAT (8F10.0)
C
C      READ (JREAD,11) CP(1),CP(2),CP(3),CP(4),CP(5),CP(6),CP(7),CP(8),CP
C      1(9),CP(10),CP(11),CP(12)

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11 FORNAT (4D20.0/4D20.0/4D20.0)
C
C
C      WRITE (JREAD,12) NPYS
12 FORNAT (I2)
C
C      READ (JREAD,13) (VE(I),DPQCF(I),I=1,NPYS)
13 FORNAT (2F20.0)
C
C      K=1
C
14 READ (JFILE,15) TIME(K),D(K,IVL(1)),D(K,IVL(2)),D(K,IVL(3)),D(K,IV
  1L(4)),D(K,IVL(5)),D(K,IVL(6)),D(K,IVL(7)),D(K,IVL(8)),D(K,IVL(9))
15 FORNAT (5D15.8/5D15.8)
C*** CHECK FOR DATA SET END OF FILE
  IF (K.GE.450) GO TO 21
  IF (D(K,5).EQ.0.000) GO TO 20
  IF (K.GE.2) GO TO 16
  GO TO 17
C*** CHECK FOR EQUAL OR DECREASING TIME
  IF (TIME(K).LE.TIME(K-1)) GO TO 18
17 K=K+1
  GO TO 14
18 WRITE (JWRITE,19) K
19 FORNAT (1H1,///,11X,54H*** EQUAL OR DECREASING TIME ENCOUNTERED ON
  1 DATA CARD(13,42H). PROCEEDING WITH NEXT DATA SET, IF ANY.)
  ZERR=1
20 K=K-1
  IF (IERR.NE.0) GO TO 22
  GO TO 24
C*** SAFETY CHECK FOR ARRAY OVERFLOW
21 IF (D(K,5).EQ.0.000) GO TO 20
  K=K-1
22 J=1000
C*** THIS READ STATEMENT READS CARDS REMAINING AFTER MAXIMUM CARD
C*** COUNT INTO CUBBY VARIABLES
  DO 23 JP=1,JK
  READ (JFILE,15) D1,D2,D3,D4,D5,D6,D7,D8,D9,D10
  IF (D5.EQ.0.000) GO TO 24
23 CONTINUE
C*** CHECK ON TOTAL NUMBER OF POINTS
24 IF (K.LT.13) GO TO 25
  IF (IERR.NE.0) GO TO 117
  GO TO 27
25 WRITE (JWRITE,26)
26 FORNAT (1X,///,10X,79HNUMBER OF DATA POINTS IS LESS THAN 13 . PRO
  1CEEDING WITH NEXT DATA SET, IF ANY.)
  IERR=1
C*** CHECK FOR A NEW DATA SET
  GO TO 117
C*** CHECK FOR INCONSISTENCIES IN FOURIER SERIES SPECIFICATIONS
27 IF ((MCH(1).LE.0.OR.MCH(2).LE.0).OR.(MCH(3).LE.0.OR.MCH(4).LE.0))X
  1NC=1
  IF (INC.NE.0) WRITE (JWRITE,28)
28 FORNAT (1H1,///,1X,MCH(1),MCH(2),MCH(3),AND/OR MCH(4) HAVE(HAS
  1) BEEN SPECIFIED INCORRECTLY AS BEING LESS THAN OR EQUAL TO ZERO.
  1)
  IF (INC.NE.0) IERR=1

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C*** IF (IERR.NE.0) GO TO 117
C*** CCMOTE TOTAL TIME AND TIME POINTS IN CORRECT UNITS
  IF (CF(1).EQ.0.000) GO TO 29
  TT=(TIME(K)-TIME(1))*CF(1)
  TPT1=TIME(1)
  GO TO 30
29 TT=TIME(K)-TIME(1)
  TPT1=TIME(1)
30 DO 32 I=1,K
  IF (CF(1).EQ.0.000) GO TO 31
  TIME(I)=(TIME(I)-TPT1)*CF(1)
  GO TO 32
31 TIME(I)=TIME(I)-TPT1
32 CONTINUE
C*** WRITE TITLE, WING AREA, REFERENCE DENSITY, G, AND TOTAL TEST TIME
  WRITE (JWRITE,33) (TITLE(I),I=1,20)
  WRITE (JWRITE,33) (TIME(I),I=1,20)
33 FORNAT (1H1,///,23X,04('***',23X,'**',82X,'**',23X,'**',204X,2X,'
  1**',23X,'**',82X,'**',23X,04('***'))
C*** WRITE INPUT PARAMETERS
  WRITE (JWRITE,34) NSETS
34 FORNAT (1X,///,29X,71('***',29X,'1',69X,'1',29X,'1',39X,6HNSSETS
  1=1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,23,24,25,26,27,28,29,30,31,32,33,34,35,36,37,38,39,40,41,42,43,44,45,46,47,48,49,50,51,52,53,54,55,56,57,58,59,60,61,62,63,64,65,66,67,68,69,70,71,72,73,74,75,76,77,78,79,80,81,82,83,84,85,86,87,88,89,90,91,92,93,94,95,96,97,98,99,100))
  WRITE (JWRITE,35) (ICCODE(I),I=1,NSETS)
35 FORNAT (29X,'1',56X,11,12X,'1')
  WRITE (JWRITE,36)
36 FORNAT (29X,'1',69X,'1')
  WRITE (JWRITE,37) BETHIC,XLN(1),PCF1,CF(1),MCH(1),XLN(2),PCF2,CF(2)
  1),MCH(2),XLN(3),IACG,CF(3),MCH(3),TAU(1),PCG,CF(4),MCH(4),TAU(2),
  1),MCH(5),IACG,CF(5),MCH(6),PCF3,CF(6),MCH(7),PCF4,CF(7),LSP(1),LSP(2)
  1),LSP(3),LSP(4),CF(8),LSP(5),LSP(6),LSP(7),LSP(8),CF(9),LSP(9),BIA
  1),BSEFT,CF(10),CF(11),CF(12)
37 FORNAT (29X,'1',3X,BETHIC=' ',13,2X,XLN(1)=',P7.4,2X,PCF1=',P9
  1.6,2X,CF(1)=',D10.3,2X,'1',29X,'1',3X,MCH(1)=',13,2X,XLN(2)=
  1=',P7.4,2X,PCF2=',P9.6,2X,CF(2)=',D10.3,2X,'1',29X,'1',3X,
  1MCH(2)=',13,2X,XLN(3)=',P7.4,2X,IACG=',P9.6,2X,CF(3)=',D10.
  13,2X,'1',29X,'1',3X,MCH(3)=',13,2X,TAU(1)=',P7.4,2X,PCG=
  1,P9.6,2X,CF(4)=',D10.3,2X,'1',29X,'1',3X,MCH(4)=',13,2X,TAU
  1(2)=',P7.4,2X,PCF3=',P8.4,2X,CF(5)=',D10.3,2X,'1',29X,'1',3X
  13X,5=',P8.4,2X,TAU(3)=',P7.4,2X,PCF4=',P8.4,2X,CF(6)=',D1
  10.3,2X,'1',29X,'1',3X,MCH(5)=',13,4X,BSEFT=',P10.5,2X,BSEFT=
  1X3,7X,CF(7)=',D10.3,2X,'1',29X,'1',3X,LSP(1)=',11,2X,LSP(2)=
  1=',11,2X,LSP(3)=',11,2X,LSP(4)=',11,5X,CF(8)=',D10.3,2X,'1'
  1',29X,'1',3X,LSP(5)=',11,2X,LSP(6)=',11,2X,LSP(7)=',11,2X,
  1LSP(8)=',11,5X,CF(9)=',D10.3,2X,'1',29X,'1',3X,LSP(9)=',11,
  12X,BELAP=',P9.6,3X,BSEFT=',P9.2,2X,CF(10)=',D10.3,2X,'1',29X
  1,'1',50X,CF(11)=',D10.3,2X,'1',29X,'1',50X,CF(12)=',D10.3,2X,
  1,'1',29X,'1',69X,'1',29X,'1',20X,VE=9X,DPQCF=33X,'1',29X,
  1,'1',69X,'1')
  WRITE (JWRITE,38) (VE(I),DPQCF(I),I=1,NPYS)
38 FORNAT (29X,'1',17X,P9.4,3X,P9.6,31X,'1')
  WRITE (JWRITE,39)
39 FORNAT (29X,'1',69X,'1',1')
  IF (BETHIC.NE.0) GO TO 41
  WRITE (JWRITE,40) S,BNO,G,TT
40 FORNAT (1X,///,38X,51('***',38X,'**',49X,'**',38X,'**',13H WING ARE
  1A =',P10.5,6H PT**2,20X,'**',38X,'**',21H REFERENCE DENSITY =',P10
  1.0,11H SLUG/FT**3,7X,'**',38X,'**',31H ACCELERATION DUE TO GRAVITY
  1=',P7.4,10H FT/SEC**2,1X,'**',38X,'**',19H TOTAL TEST TIME =',P10
  1.4,8H SECONDS,12X,'**',38X,'**',49X,'**',38X,51('***'))

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70 PAB(I)=0.000
IPAB=0
IF (NUMBER.LT.0) NUMBER=0
NUN=NUMBER+1
C*** BEGIN IMPROVEMENT ITERATION
DO 119 JJJ=1,NUN
TD=TIME(K)-TIME(I)
DO 71 I=1,K
TX=TIME(I)-TIME(I)
P1(I)=D(I,7)-(D(I,7)+(D(K,7)-D(I,7))/TD*TX)
71 CONTINUE
C*** COMPUTE AND SMOOTH FOURIER COEFFICIENTS OF STAGNATION TEMPERATURE
CALL PARAF(P1,K,NPTP1,MCH(4))
C*** REGENERATE SMOOTHED STAGNATION TEMPERATURE
X1=A(I)
DO 73 I=1,K
TX=TIME(I)-TIME(I)
X2=D(I,7)+(D(K,7)-D(I,7))/TD*TX
X3=0.000
DO 72 N=2,NPTP1
X3=X3+A(N)*DCOS(2*(N-1)*PI*TIME(L)/TT)*B(N)*DSIN(2*(N-1)*PI*TIME(L)/TT)
72 CONTINUE
P1(I)=X1+X2+X3
73 CONTINUE
C*** DETERMINE FEASIBILITY OF STATIC PRESSURE BEHAVIOR AND MAKE ANY
C*** NECESSARY CORRECTIONS
KN1=N-1
DO 74 I=1,KN1
SN=1.000
C*** CALCULATE AN ALTITUDE BY ASSUMING CONSTANT TEMPERATURE
N=(1.000-(D(I,5)/PSI)**(1.000/4.2600))/0.860-6
C*** CALCULATE A LIMITING ALTITUDE DERIVATIVE MAGNITUDE
ND=DABS(D(I,4)*CSIN(1.200*(D(I,2)-D(I,6))))
C*** CALCULATE A LIMITING STATIC PRESSURE DERIVATIVE MAGNITUDE
PDPA=DABS(-6.860-6*4.2600*PSI*ND*(1.000-6.860-6*N)**3.2600)
C*** CALCULATE TWO-POINT STATIC PRESSURE DERIVATIVE OF INPUT DATA
PPI=(D(I,5)-D(I,5))/(TIME(I+1)-TIME(I))
C*** DETERMINE DIRECTION OF DERIVATIVE
IF (DABS(PPI).NE.PPI) SN=-1.000
C*** CHECK MAGNITUDES OF STATIC PRESSURE DERIVATIVES AND APPLY SMALLEST
IF (DABS(PPI).LE.DABS(PDPA)) ASLP=DABS(PPI)
IF (DABS(PPI).GT.DABS(PDPA)) ASLP=DABS(PDPA)
C*** COMPUTE 'NEW' STATIC PRESSURE
D(I,5)=D(I,5)+SN*ASLP*(TIME(I+1)-TIME(I))
74 CONTINUE
C*** DEFINE STATIC AND STAGNATION PRESSURES
DO 75 I=1,K
ASPD(I)=D(I,4)
D(I,7)=P1(I)
P(I)=D(I,5)
PA(I)=D(I,5)
PS(I)=P(I)+0.500*PSI/(N*TSI)*D(I,4)**2
75 CONTINUE
C*** COMPUTE LAG-CORRECTED STATIC PRESSURE AND QC
NP=(3*MCH(1))/2
NPA=(3*MCH(2))/2
NPS=(3*MCH(3))/2
NPTP=NP+1
NPAI=NPA+1

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NPSI=NPS+1
TD=TIME(K)-TIME(I)
C*** COMPUTE DEVIATIONS OF STATIC PRESSURES AND STAGNATION PRESSURE
DO 76 I=1,K
TX=TIME(I)-TIME(I)
P1(I)=P(I)-(P(I)+(P(K)-P(I))/TD*TX)
P2(I)=PA(I)-(PA(I)+(PA(K)-PA(I))/TD*TX)
76 P3(I)=PS(I)-(PS(I)+(PS(K)-PS(I))/TD*TX)
C*** SET TIME CONSTANTS AND TIME INTERVALS TO ZERO IF SPECIFIED
IF (JJJ.EQ.1) GC TC 78
DO 77 I=1,3
XLN(I)=0.000
77 TAU(I)=0.000
C*** COMPUTE AND SMOOTH FOURIER COEFFICIENTS OF AIRSPEED'S STATIC
C*** PRESSURE
78 CALL PARAF(P1,K,NPTP1,MCH(1))
C*** REGENERATE AIRSPEED'S SMOOTHED STATIC PRESSURE AT (TIME-LAMBDA)
X1=A(I)
DO 80 L=1,K
TX=TIME(L)-TIME(I)-XLN(3)
X2=P(I)+(P(K)-P(I))/TD*TX
X3=0.000
DO 79 N=2,NPTP1
X3=X3+A(N)*DCOS(2*(N-1)*PI*(TIME(L)-XLN(3))/TT)*B(N)*DSIN(2*(N-1)*PI*(TIME(L)-XLN(3))/TT)
79 CONTINUE
P1(L)=X1+X2+X3
80 CONTINUE
C*** COMPUTE DERIVATIVE OF AIRSPEED'S STATIC PRESSURE AT (TIME-LAMBDA)
XD1=(P(K)-P(I))/TD
DO 82 L=1,K
XD2=0.000
DO 81 N=1,NP
XD2=XD2+2*N*PI/TT*(-A(N+1)*CSIN(2*N*PI*(TIME(L)-XLN(3))/TT)*B(N+1)*DCOS(2*N*PI*(TIME(L)-XLN(3))/TT))
81 CONTINUE
PD(I)=XD1+XD2
82 CONTINUE
C*** COMPUTE FULLY LAG-CORRECTED STATIC PRESSURE FOR AIRSPEED
DO 83 L=1,K
P(L)=P1(L)+TAU(3)*PD(L)
IF (L.EC.K) P(L)=P(L-1)
83 CONTINUE
C*** COMPUTE AND SMOOTH FOURIER COEFFICIENTS OF ALTITUDE'S STATIC
C*** PRESSURE
CALL PARAF(P2,K,NPAI,MCH(2))
C*** REGENERATE ALTITUDE'S SMOOTHED STATIC PRESSURE AT (TIME-LAMBDA)
X1=A(I)
DO 85 L=1,K
TX=TIME(L)-TIME(I)-XLN(2)
X2=PA(I)+(PA(K)-PA(I))/TD*TX
X3=0.000
DO 84 N=2,NPAI
X3=X3+A(N)*DCOS(2*(N-1)*PI*(TIME(L)-XLN(2))/TT)*B(N)*DSIN(2*(N-1)*PI*(TIME(L)-XLN(2))/TT)
84 CONTINUE
P2(L)=X1+X2+X3
85 CONTINUE
C*** COMPUTE DERIVATIVE OF ALTITUDE'S STATIC PRESSURE AT (TIME-LAMBDA)
XD1=(PA(K)-PA(I))/TD

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1,6H (SECS), 71, '1', 31, 12H (SLUG/FT**3), 4X, '1', 4X, 9H (RADIAN), 6X, '1', 6
11, 7H (DEG-N), 6X, '1', 4X, 11H (FT/SEC**2), 4X, '1', 6X, '1', 19X, '1', 19X, '1'
'1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 6X, '1', 119 ('-', '1', '1')
DO 103 I=1,K
WRITE (JWRITE, 102) I, TIME(I), (D(I, J), J=5, 8)
102 FORMAT (6X, '1', 71, 13, 9X, '1', 61, F7.3, 6X, '1', 4X, F10.8, 5X, '1', 4X, F11.
17, 4X, '1', 4X, F11, F9.2, 6X, '1', 4X, F9.5, 6X, '1')
103 CONTINUE
WRITE (JWRITE, 104)
104 FORMAT (6X, '1', 119X, '1', 6X, 121 ('1', '1'))
WRITE (JWRITE, 105)
105 FORMAT (6X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 6X, '1', 4X
1, 10HDATA POINT, 5X, '1', 71, 4HTIME, 8X, '1', 5X, 8HALTITUDE, 6X, '1', 3X, 12H
1VERT. ACCEL., 4X, '1', 21, 14HEIVE. DEFLECT., 3X, '1', 6X, '1', 19X, '1', 6
1X, 6H (SECS), 71, '1', 6X, 6H (FEET), 7X, '1', 4X, 11H (FT/SEC**2), 4X, '1', 6X, 9
1H (RADIAN), 6X, '1', 6X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1'
1, 6X, '1', 99 ('-', '1', '1')
DO 107 I=1,K
WRITE (JWRITE, 106) I, TIME(I), (D(I, J), J=9, 11)
106 FORMAT (6X, '1', 71, 13, 9X, '1', 6X, F7.3, 6X, '1', 4X, F10.3, 5X, '1', 4X, F9.5
1, 6X, '1', 4X, F9.5, 6X, '1')
107 CONTINUE
WRITE (JWRITE, 108)
108 FORMAT (6X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 6X, 101 ('1'
'1'))
GO TO 116
C*** WRITE RESULTS IN SI UNITS
109 WRITE (JWRITE, 110)
110 FORMAT (1X, '1', 31, 6H ('1', '1', '1', '1', '1', '1'), '1', 31X, '1', 6X, 5X, 13HCONVER
1SI CH OF INPUT AND OUTPUT DATA TO COMPATIBLE UNITS, 7X, '1', 6X, '1', 31X, '1', 6
16X, '1', 31, 6H ('1', '1', '1', '1', '1', '1'), '1', 6X, '1', 19X, '1', 19X, '1', 19X, '1'
1, 19X, '1', 19X, '1', 19X, '1', 6X, '1', 4X, 10HDATA POINT, 5X, '1', 71, 4H1
11H, 8X, '1', 6X, 6HHEIGHT, 7X, '1', 3X, 11H1PITCH ANGLE, 5X, '1', 4X, 10H1PITCH
11RATE, 5X, '1', 5X, 8HALTITUDE, 6X, '1', 6X, '1', 19X, '1', 6X, 6H (SECS), 7X, '1'
151, 6H (NEWTONS), 5X, '1', 4X, 9H (RADIAN), 6X, '1', 3X, 12H (RADIAN/SEC)
116X, '1', 6X, 7H (M/SEC), 6X, '1', 6X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1'
1, 19X, '1', 19X, '1', 6X, '1', 119 ('-', '1', '1'))
DO 111 I=1,K
WS=D(I, 1)*4.448220
VS=D(I, 4)*0.304800
WRITE (JWRITE, 99) I, TIME(I), WS, D(I, 2), D(I, 3), VS
111 CONTINUE
WRITE (JWRITE, 112)
112 FORMAT (6X, '1', 119X, '1', 6X, 121 ('1', '1'), '1', 6X, '1', 19X, '1', 19X, '1', 19X
1, '1', 19X, '1', 19X, '1', 19X, '1', 6X, '1', 4X, 10HDATA POINT, 5X, '1', 71, 4X
11HTIME, 8X, '1', 5X, 7HDENSITY, 7X, '1', 2X, 15HANGLE OF ATTACK, 2X, '1', 4X, 1
11HTEMPERATURE, 4X, '1', 3X, 12H1ENG. ACCEL., 4X, '1', 6X, '1', 19X, '1', 6
1X, 6H (SECS), 71, '1', 4X, 9H (G/SEC**3), 6X, '1', 5X, 9H (RADIAN), 5X, '1', 6X, 7H
11 (DEG-N), 6X, '1', 4X, 10H (M/SEC**2), 5X, '1', 6X, '1', 19X, '1', 19X, '1', 19
1X, '1', 19X, '1', 19X, '1', 19X, '1', 6X, '1', 119 ('-', '1', '1'))
DO 113 I=1,K
DS=D(I, 5)*515.3800
AS=D(I, 8)*0.304800
TK=D(I, 7)*0.555555600
113 WRITE (JWRITE, 102) I, TIME(I), DS, D(I, 6), TK, AS
WRITE (JWRITE, 104)
WRITE (JWRITE, 114)
114 FORMAT (6X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 6X, '1', 4X
1, 10HDATA POINT, 5X, '1', 71, 4HTIME, 8X, '1', 5X, 8HALTITUDE, 6X, '1', 3X, 12H
1VERT. ACCEL., 4X, '1', 21, 14HEIVE. DEFLECT., 3X, '1', 6X, '1', 19X, '1', 6
1X, 6H (SECS), 71, '1', 6X, 6H (FEET), 7X, '1', 4X, 11H (FT/SEC**2), 4X, '1', 6X, 9
1H (RADIAN), 6X, '1', 6X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1', 19X, '1'
1, 6X, '1', 99 ('-', '1', '1'))
DO 115 I=1,K

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1X,6H(SECS),7I,11,5X,8H(METERS),6X,11,4X,10H(RC/SEC**2),5X,11,4X,
19H(RADIANS),6X,11,4X,6X,11,19X,11,19X,11,19X,11,19X,11,19X,11,
11,6X,11,99(11,11)
DC 115 I-1,R
HS=C(I,9)+0.3048D0
VAS=C(I,10)+0.3048D0
WRITE (JWRITE,106) I,TIME(I),HS,VAS,D(I,11)
115 CONTINUE
WRITE (JWRITE,108)
C*** CHECK FOURIER ANALYSIS AND FILTERING ROUTINE
116 CALL SEC2(K,JJJJ,MUR,LSF,ITEST,5)
117 IF (IERR.NE.0) WRITE (JWRITE,118)
118 FORMAT (1X,///,15X,'USER ERROR***CONSULT USER INSTRUCTIONS***TO W
TEXT DATA SET, 'I AM'//////
IF (IERR.NE.0.OR.ITEST.NE.0) GO TO 120
119 CONTINUE
120 KJ=KJ+1
C*** CHECK FOR PRESENCE OF ADDITIONAL DATA SETS
IF ((KJ-1).EQ.NSETS) GO TO 5
IF (KJ.LE.NSETS) GO TO 3
C*** TERMINATE PROGRAM EXECUTION
121 WRITE (JWRITE,122)
122 FORMAT (1X,///,15X,5HINPUT PARAMETER NSETS IS PROBABLY SPECIFIED
1 INCORRECTLY,//////)
C*** TERMINATE PLOT ROUTINES
123 IF (JPLCT.NE.0) CALL FICSIZ(0.0,0.0)
STOP
END

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	SUBROUTINE SEC2(K,JP,NUN,LSF,ITEST,S)	S2	1
		S2	2
C***	SUBROUTINE SEC2 IS A SUBROUTINE THAT PERFORMS FOURIER ANALYSIS AND	S2	3
C***	ATTEMPTS TO MAKE THE DATA NCRP COMPATIBLE	S2	4
C		S2	5
	IMPLICIT REAL*8 (A-H,O-Z)	S2	6
	DIMENSION TRG(21),IR(6),DY(450),DX(450),AX(450),FX(450),DV(450),HD	S2	7
	1(450),H(450),IFS(11),IPBC(9),IP(14),WC(11),SS(450,11),LSP(9),TST(4	S2	8
	150,16)	S2	9
	COMMON TITLE(20),D(450,11),TIME(450),A(100),B(100),F1(450),F2(450)	S2	10
	1,F3(450),F4(450),F5(450),F6(450),F7(450),F8(450),IT,RHO,PI,G,JKS,R	S2	11
	IBDC,JREAD,JWRITE,JPNCHN,TEER	S2	12
	COMMON /CABRY/F11(450),F12(450)	S2	13
	COMMON /TENE1/ST(450,4),PAR(6),PSL,TSL,IPAR	S2	14
	COMMON /TENE2/F9(450),F10(450),F13(450),F14(450),AP(6),N(6)	S2	15
	COMMON /NCW/INS(10,6)	S2	16
	DATA TRG,.000,5.000,10.000,15.000,20.000,25.000,30.000,35.000,40.0	S2	17
	10,45.000,50.000,55.000,60.000,65.000,70.000,75.000,80.000,85.000,	S2	18
	90.000,95.000,100.000/,NS/15/,NI/3/	S2	19
C		S2	20
C		S2	21
C		S2	22
C***	CHECK ON BYPASS	S2	23
	IF (JP.GT.1) GO TO 10	S2	24
C		S2	25
C		S2	26
	REAL (JREAD,1) (IFS(I),I=1,11)	S2	27
	1 FORMAT (11E1)	S2	28
C		S2	29

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C      READ (JREAD,2) (IPRC(I),I=1,9),XAX,FAC1,FAC2,DSFS
2  FORMAT (9I1,1X,4E15.0)
C
C*** CHECK FOR INPUT ERROR
IF (IFRC(1).NE.0.AND.IPRC(2).EQ.2) GO TO 64
C
C      READ (JREAD,3) (IP(I),I=1,14)
3  FORMAT (14I1)
C
C      READ (JREAD,4) (NC(I),I=1,11)
4  FORMAT (11I5)
C
C      READ (JREAD,5) (AP(I),N(I),I=1,6,
5  FORMAT (2D20.0)
C
C      NUNK=NUN-1
IF (NUNK.EQ.0) NUNK=1
DO 6 J=1,NUNK
  READ (JREAD,6) (IR(I),I=1,6)
6  FORMAT (6I1)
C
C
C      DO 7 JJ=1,6
7  IRS(J,J)=IR(JJ)
8  CONTINUE
C*** CHECK FOR ZERO CS MEAS-ZERO A PRIORI VALUE
DO 9 I=1,6
  IF (DABS(AP(I)).LT.1.0D-10) AF(I)=1.0D-10
9  CONTINUE
C*** ADJUST TO ODD NUMBER OF POINTS
10 IF ((N/2)*2).EQ.K) N=K-1
  N1=N
  IT=TIME(N)-TIME(1)
C*** DEFINE NEW ARRAYS
DO 11 I=1,K
  C*** DEFINE WEIGHT
  F1(I)=D(I,1)
C*** DEFINE PITCH ANGLE
  F2(I)=D(I,2)
C*** DEFINE PITCH RATE
  F3(I)=D(I,3)
C*** DEFINE AIRSPEED
  F4(I)=D(I,4)
C*** DEFINE DENSITY
  F5(I)=D(I,5)
C*** DEFINE ANGLE OF ATTACK
  F6(I)=D(I,6)
C*** DEFINE TEMPERATURE
  F7(I)=D(I,7)
C*** DEFINE LONGITUDINAL ACCELERATION
  F8(I)=D(I,8)
  AX(I)=D(I,8)
C*** DEFINE ALTITUDE
  FIC(I)=D(I,9)

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C*** INITIALIZE ALTITUDE DATA
F11(I)=C.000
C*** DEFINE VERTICAL ACCELERATION
F13(I)=D(I,10)
C*** DEFINE ELEVATOR (OR STABILATOR) DEFLECTION
F14(I)=D(I,11)
11 CONTINUE
C*** STORE INITIAL DATA FOR ELCTING
IF (IFRC(5).NE.0.OR.JP.NE.1) GO TO 13
DO 12 I=1,K
  DO 12 J=1,11
12 SS(I,J)=D(I,J)
C*** CHECK FOR OVERALL FOURIER SERIES ANALYSIS
13 IF (IFRC(4).NE.0) GO TO 92
C*** COMPUTE TERMINATION HARMONICS
N1=(3*NC(1))/2
N2=(3*NC(2))/2
N3=(3*NC(3))/2
N4=(3*NC(4))/2
N5=(3*NC(5))/2
N6=(3*NC(6))/2
N7=(3*NC(7))/2
N8=(3*NC(8))/2
N9=(3*NC(9))/2
N10=(3*NC(10))/2
N11=(3*NC(11))/2
C*** CHECK FOR INCORRECT INPUT
IF (((IFS(1).EQ.0.AND.N1.LE.0).OR.((IFS(2).EQ.0.AND.N2.LE.0).OR.
11FS(3).EQ.0.AND.N3.LE.0)).CF.((IFS(4).EQ.0.AND.N4.LE.0).OR.(IFS(
15).EQ.0.AND.N5.LE.0)).OR.((IFS(6).EQ.0.AND.N6.LE.0).OR.(IFS(7).EQ.
10.AND.N7.LE.0))) .OR.(((IFS(8).EQ.0.AND.N8.LE.0).OR.(IFS(9).EQ.0.
1.AND.N9.LE.0)).CF.((IFS(10).EQ.0.AND.N10.LE.0).OR.(IFS(11).EQ.0.AND
1.N11.LE.0)))) GO TO 126
C*** COMPUTE DEVIATIONS FOR TIME HISTORIES
TD=TIME(K)-TIME(1)
DO 23 I=1,K
  TX=TIME(I)-TIME(1)
  IF (IFS(I).NE.0) GO TO 14
  F1(I)=D(I,1)-(D(1,1)+(D(K,1)-D(1,1))/TD*TX)
14 IF (IFS(2).NE.0) GO TO 15
  F2(I)=D(I,2)-(D(1,2)+(D(K,2)-D(1,2))/TD*TX)
15 IF (IFS(3).NE.0) GO TO 16
  F3(I)=D(I,3)-(D(1,3)+(D(K,3)-D(1,3))/TD*TX)
16 IF (IFS(4).NE.0) GO TO 17
  F4(I)=D(I,4)-(D(1,4)+(D(K,4)-D(1,4))/TD*TX)
17 IF (IFS(5).NE.0) GO TO 18
  F5(I)=D(I,5)-(D(1,5)+(D(K,5)-D(1,5))/TD*TX)
18 IF (IFS(6).NE.0) GO TO 19
  F6(I)=D(I,6)-(D(1,6)+(D(K,6)-D(1,6))/TD*TX)
19 IF (IFS(7).NE.0) GO TO 20
  F7(I)=D(I,7)-(D(1,7)+(D(K,7)-D(1,7))/TD*TX)
20 IF (IFS(8).NE.0) GO TO 21
  F8(I)=D(I,8)-(D(1,8)+(D(K,8)-D(1,8))/TD*TX)
21 IF (IFS(9).NE.0) GO TO 22
  F9(I)=D(I,9)-(D(1,9)+(D(K,9)-D(1,9))/TD*TX)
22 IF (IFS(10).NE.0) GO TO 23
  F10(I)=D(I,10)-(D(1,10)+(D(K,10)-D(1,10))/TD*TX)
  F11(I)=D(I,11)-(D(1,11)+(D(K,11)-D(1,11))/TD*TX)
23 CONTINUE
  IF (IFS(I).NE.0) GO TO 26
C*** PERFORM FOURIER ANALYSIS ON WEIGHT TIME HISTORY

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 S2 149

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C*** N1P1=N1+1
C*** COMPUTE FOURIER SERIES COEFFICIENTS
CALL FAPAF(F1,K,N1P1,NC(1))
C*** REGENERATE WEIGHT TIME HISTORY (SMOOTHED)
X1=A(1)
DO 25 L=1,K
TX=TIME(L)-TIME(1)
X2=C(1,1)*D(K,1)-D(1,1))/TX*TX
X3=C.000
DO 24 M=2,N1P1
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)*B(M)*DSIN(2*(M-1)*PI*TIME(L)
1)/TT)
24 CONTINUE
25 F1(L)=X1*X2*X3
26 IF (IFS(2).NE.0) GO TO 29
C*** PERFORM FOURIER ANALYSIS ON PITCH ANGLE TIME HISTORY
N2F1=N2+1
C*** COMPUTE FOURIER SERIES COEFFICIENTS
CALL FAPAF(F2,K,N2P1,NC(2))
C*** REGENERATE PITCH ANGLE TIME HISTORY (SMOOTHED)
X1=A(1)
DO 28 L=1,K
TX=TIME(L)-TIME(1)
X2=D(1,2)*D(K,2)-D(1,2))/TX*TX
X3=C.000
DO 27 M=2,N2P1
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)*B(M)*DSIN(2*(M-1)*PI*TIME(L)
1)/TT)
27 CONTINUE
28 F2(L)=X1*X2*X3
29 IF (IFS(3).NE.0) GO TO 32
C*** PERFORM FOURIER ANALYSIS ON PITCH RATE TIME HISTORY
N3F1=N3+1
C*** COMPUTE FOURIER SERIES COEFFICIENTS
CALL FAPAF(F3,K,N3P1,NC(3))
C*** REGENERATE PITCH RATE TIME HISTORY (SMOOTHED)
X1=A(1)
DO 31 L=1,K
TX=TIME(L)-TIME(1)
X2=D(1,3)*D(K,3)-D(1,3))/TX*TX
X3=C.000
DO 30 M=2,N3P1
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)*B(M)*DSIN(2*(M-1)*PI*TIME(L)
1)/TT)
30 CONTINUE
31 F3(L)=X1*X2*X3
C*** INTEGRATE PITCH RATE TO OBTAIN PITCH ANGLE, IF DESIRED
PA1=F2(1)
IF (IPRC(7).NE.0) CALL TRAP(K,TIME,F3,F2,PA1)
32 IF (IFS(4).NE.0) GO TO 37
C*** PERFORM FOURIER ANALYSIS ON AIRSPEED TIME HISTORY
N4F1=N4+1
C*** COMPUTE FOURIER SERIES COEFFICIENTS
CALL FAPAF(F4,K,N4P1,NC(4))
C*** REGENERATE AIRSPEED TIME HISTORY (SMOOTHED)
X1=A(1)
DO 34 L=1,K
TX=TIME(L)-TIME(1)
X2=D(1,4)*D(K,4)-D(1,4))/TX*TX
X3=C.000

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DO 33 M=2,N4P1
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)*B(M)*DSIN(2*(M-1)*PI*TIME(L)
1)/TT)
33 CONTINUE
34 F4(L)=X1*X2*X3
IF (IPRC(1).NE.0) GO TO 37
C*** COMPUTE ACCELERATION (DERIVATIVE OF AIRSPEED) TIME HISTORY
X1=C(K,5)-D(1,4))/TD
DO 36 L=1,K
XD2=0.000
DO 35 M=1,N4
XD2=XD2+2*M*PI/TT*(-A(M+1)*DSIN(2*M*PI*TIME(L)/TT)*B(M+1)*DCOS(2*M
1*PI*TIME(L)/TT))
35 CONTINUE
36 F5(L)=X1*XD2
C*** CHECK FOR ACCELERATION-INPUT-OPTION COMPATIBILITY
37 IF (IFS(4).NE.0.AND.IPRC(1).EQ.0)IPRC(1)=1
IF (IFS(5).NE.0) GO TO 40
C*** PERFORM FOURIER ANALYSIS ON DENSITY TIME HISTORY
N5F1=N5+1
C*** COMPUTE FOURIER SERIES COEFFICIENTS
CALL FAPAF(F5,K,N5P1,NC(5))
C*** REGENERATE DENSITY TIME HISTORY (SMOOTHED)
X1=A(1)
DO 38 L=1,K
TX=TIME(L)-TIME(1)
X2=D(1,5)*D(K,5)-D(1,5))/TX*TX
X3=C.000
DO 38 M=2,N5P1
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)*B(M)*DSIN(2*(M-1)*PI*TIME(L)
1)/TT)
38 CONTINUE
39 F5(L)=X1*X2*X3
40 IF (IFS(6).NE.0) GO TO 45
C*** PERFORM FOURIER ANALYSIS ON ANGLE-OF-ATTACK TIME HISTORY
N6F1=N6+1
C*** COMPUTE FOURIER SERIES COEFFICIENTS
CALL FAPAF(F6,K,N6P1,NC(6))
C*** REGENERATE ANGLE-OF-ATTACK TIME HISTORY (SMOOTHED)
X1=A(1)
DO 42 L=1,K
TX=TIME(L)-TIME(1)
X2=D(1,6)*D(K,6)-D(1,6))/TX*TX
X3=C.000
DO 41 M=2,N6P1
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)*B(M)*DSIN(2*(M-1)*PI*TIME(L)
1)/TT)
41 CONTINUE
42 F6(L)=X1*X2*X3
IF (IPRC(3).NE.0) GO TO 45
C*** COMPUTE ANGLE-OF-ATTACK RATE TIME HISTORY
XD1=D(K,6)-D(1,6))/TD
DO 44 L=1,K
XD2=0.000
DO 43 M=1,N6
XD2=XD2+2*M*PI/TT*(-A(M+1)*DSIN(2*M*PI*TIME(L)/TT)*B(M+1)*DCOS(2*M
1*PI*TIME(L)/TT))
43 CONTINUE
44 F7(L)=XD1*XD2
IF (IFS(6).EQ.0.AND.IPRC(3).EQ.0) GO TO 47

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45 IPBC(3)=1 S2 270
IF (IPS(6).NE.0) WRITE (JWRITE,46) S2 271
46 FORMAT (1X,////,15X,9CHWARNING -> ANGLE-OF-ATTACK RATE HAS COMPUTE S2 272
10 USING UNSMOOTHED ANGLE-OF-ATTACK TIME HISTORY,////) S2 273
CALL FMI(K,F6,TIME,F9,DY,1,NS,NI) S2 274
47 IF (IPS(7).NE.0) GO TO 50 S2 275
C*** PERFORM FOURIER ANALYSIS ON TEMPERATURE TIME HISTORY S2 276
N7P1=N7+1 S2 277
C*** COMPUTE FOURIER SERIES COEFFICIENTS S2 278
CALL PARAF(F7,K,N7P1,NC(7)) S2 279
C*** REGENERATE TEMPERATURE TIME HISTORY (SMOOTHED) S2 280
X1=A(1) S2 281
DO 49 L=1,K S2 282
TX=TIME(L)-TIME(1) S2 283
X2=D(1,7)*(D(K,7)-D(1,7))/TD*TX S2 284
X3=0.000 S2 285
DO 48 M=2,N7P1 S2 286
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)+B(M)*DSIN(2*(M-1)*PI*TIME(L S2 287
1)/TT) S2 288
48 CONTINUE S2 289
49 F7(L)=X1+X2+X3 S2 290
C*** PERFORM FOURIER ANALYSIS ON LONGITUDINAL ACCELERATION TIME HISTORY S2 291
50 IIX=0 S2 292
GO TO 53 S2 293
51 IF (IPBC(2).LT.0.OR.IPBC(2).GE.2) GO TO 60 S2 294
IF (IPBC(2).NE.0.AND.IPBC(1).NE.0) IPBC(1)=0 S2 295
C*** CONVERT LONGITUDINAL ACCELERATION INTO 'COMPATIBLE' ACCELERATION S2 296
DO 52 JJ=1,K S2 297
D(JJ,8)=(AX(JJ)-G*DSIN(F2(JJ))+X1+F3(JJ)+F3(JJ))/DCOS(F6(JJ))+F4 S2 298
1JJ)*F9(JJ)-F3(JJ))*(DSIN(F6(JJ))/DCOS(F6(JJ))) S2 299
IF (IPBC(8).EQ.0) GO TO 52 S2 300
DV(JJ)=D(JJ,8) S2 301
D(JJ,8)=AX(JJ) S2 302
52 CONTINUE S2 303
IF (IPBC(8).NE.0) GO TO 53 S2 304
IF (IPBC(2).EQ.1) GO TO 60 S2 305
C*** COMPUTE DEVIATIONS FOR LONGITUDINAL ACCELERATION S2 306
53 DO 54 I=1,K S2 307
TX=TIME(I)-TIME(1) S2 308
F6(I)=D(I,8)-(D(1,8)+(D(K,8)-D(1,8))/TD*TX) S2 309
N8P1=N8+1 S2 310
C*** COMPUTE FOURIER SERIES COEFFICIENTS S2 311
CALL PARAF(FX,K,N8P1,NC(8)) S2 312
C*** REGENERATE ACCELERATION TIME HISTORY (SMOOTHED) S2 313
X1=A(1) S2 314
DO 56 L=1,K S2 315
TX=TIME(L)-TIME(1) S2 316
X2=D(1,8)*(D(K,8)-D(1,8))/TD*TX S2 317
X3=0.000 S2 318
DO 55 M=2,N8P1 S2 319
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)+B(M)*DSIN(2*(M-1)*PI*TIME(L S2 320
1)/TT) S2 321
55 CONTINUE S2 322
DV(L)=X1+X2+X3 S2 323
IF (IIX.EQ.0) S7(L,4)=DV(L) S2 324
56 CONTINUE S2 325
IF (IIX.NE.0) GO TO 57 S2 326
IIX=1 S2 327
GO TO 51 S2 328
57 DO 59 JJ=1,K S2 329

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IF (IPBC(8).EQ.0) GO TO 58 S2 330
D(JJ,8)=DV(JJ) S2 331
DV(JJ)=DY(JJ) S2 332
GO TO 59 S2 333
58 D(JJ,8)=DV(JJ) S2 334
59 CONTINUE S2 335
C*** ARRANGE FOR CORRECT LISTING S2 336
60 IF (IPBC(2).EQ.0.AND.IPBC(1).NE.0) GO TO 61 S2 337
GO TO 63 S2 338
61 DO 62 JJ=1,K S2 339
F8(JJ)=D(JJ,8) S2 340
62 D(JJ,8)=AX(JJ) S2 341
63 IF (IPBC(1).NE.0.AND.IPBC(2).EQ.2) GO TO 64 S2 342
GO TO 66 S2 343
64 WRITE (JWRITE,65) S2 344
65 FORMAT (1X,////,5X,'THE VALUES OF IPBC(1) AND IPBC(2) ARE NOT COMP S2 345
TIBLE. RETURNING TO NEXT DATA SET, IF ANY.',////) S2 346
IIFE=1 S2 347
RETURN S2 348
66 IF (IPS(9).NE.0) GO TO 71 S2 349
C*** PERFORM FOURIER ANALYSIS ON ALTITUDE TIME HISTORY S2 350
N9P1=N9+1 S2 351
C*** COMPUTE FOURIER SERIES COEFFICIENTS S2 352
CALL PARAF(F10,K,N9P1,NC(9)) S2 353
C*** REGENERATE ALTITUDE TIME HISTORY (SMOOTHED) S2 354
X1=A(1) S2 355
DO 68 L=1,K S2 356
TX=TIME(L)-TIME(1) S2 357
X2=D(1,9)*(D(K,9)-D(1,9))/TD*TX S2 358
X3=0.000 S2 359
DO 67 M=2,N9P1 S2 360
X3=X3+A(M)*DCOS(2*(M-1)*PI*TIME(L)/TT)+B(M)*DSIN(2*(M-1)*PI*TIME(L S2 361
1)/TT) S2 362
67 CONTINUE S2 363
F10(L)=X1+X2+X3 S2 364
C*** ADJUST DENSITY TO BE COMPATIBLE WITH ALTITUDE S2 365
IF (IPS(5).NE.0) F5(L)=RHO*(1.000-6.86D-06*F10(L))*4.26D0 S2 366
68 CONTINUE S2 367
C*** COMPUTE DERIVATIVE OF ALTITUDE TIME HISTORY S2 368
XD1=(D(K,9)-D(1,9))/TD S2 369
DO 70 L=1,K S2 370
XD3=0.000 S2 371
XD2=C.000 S2 372
DO 69 M=1,N9 S2 373
XD2=XD2+2*M*PI/TT*(-A(M+1)*DSIN(2*M*PI*TIME(L)/TT)+B(M+1)*DCOS(2*M S2 374
1*PI*TIME(L)/TT)) S2 375
XD3=XD3-(2*M*PI/TT)**2*(A(M+1)*DCOS(2*M*PI*TIME(L)/TT)+B(M+1)*DSIN S2 376
1(2*M*PI*TIME(L)/TT)) S2 377
69 CONTINUE S2 378
F12(L)=XD3 S2 379
70 F11(L)=XD1+XD2 S2 380
71 IF (IPS(3).EQ.0) GO TO 73 S2 381
WRITE (JWRITE,72) S2 382
72 FORMAT (1X,////,15X,8CHWARNING -> ALTITUDE DERIVATIVES WERE CORP S2 383
RECT USING UNSMOOTHED ALTITUDE TIME HISTORY,////) S2 384
CALL FMI(K,F10,TIME,F11,F12,2,NS,NI) S2 385
73 IF (IPBC(8).EQ.0) GO TO 83 S2 386
IF (IPBC(8).GE.2) GO TO 80 S2 387
C*** USING NEWTON-RAPHSON METHOD, FIND COMPATIBLE ANGLE OF ATTACK S2 388
ECUT=0 S2 389

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DO 78 L=1,K          S2 390
ITB=0                S2 391
ALP=F6(L)            S2 392
XP1=G*F1(L)/F4(L)*F8(L) S2 393
XP2=G*DSQRT(1.000-(F11(L)/F4(L))**2)+(F4(L)*F12(L)-F11(L)*F8(L))/( S2 394
F4(L)*DSQRT(1.000-(F11(L)/F4(L))**2)) S2 395
74 ITB=ITB+1          S2 396
FM=AL(L)-XP1*DCOS(ALP)-XP2*ESIN(ALP)*XAL*F3(L)*F3(L) S2 397
FMP=XP1*DSIN(ALP)-XP2*DCOS(ALP) S2 398
FMPF=XP1*DCOS(ALP)+XP2*DSIN(ALP) S2 399
NAC=(FMP/FMPF)*(FMP/FMPF)-2.000*(FM/FMPF) S2 400
ALF1=ALP             S2 401
IF (NAD.LT.0.000) GO TO 76 S2 402
IF ((FMP*FMPF).LT.0.010) GO TO 75 S2 403
ALP=ALP-FMP/FMPF*DSQRT(NAC) S2 404
GO TO 77              S2 405
75 ALP=ALP-FMP/FMPF*DSQRT(NAC) S2 406
GO TO 77              S2 407
76 ALP=ALP-FMP/FMPF    S2 408
LCMT=LCMT+1           S2 409
GO 78                 S2 410
77 IF (NADS(ALP1-ALP).LT.1.00-15.00.ITR.EQ.20) GO TO 78 S2 411
GO TO 74              S2 412
78 F6(L)=ALP          S2 413
IF (LCMT.NE.0) WRITE (JWRITE,79) LCMT S2 414
79 FCDEAT (11,/,10X,10H*** USING NEWTON-RAPHSON TO FIND COMPATIBLE S2 415
1 ANGLE OF ATTACK, THE ROUTINE WISHED TO SEEK COMPLEX ROOTS,13,7H S2 416
1 TIMES,/,) S2 417
GO TO 83              S2 418
C*** FIND COMPATIBLE DERIVATIVE OF FLIGHT-PATH ANGLE S2 419
80 DO 81 L=1,K        S2 420
81 DY(L)=(AL(L)-G*DSIN(F2(L))*XAL*F3(L)*F3(L)-F8(L)*DCOS(F6(L)))/(F4(L) S2 421
11)*DSIN(F6(L))) S2 422
GO=F2(L)-F6(L)        S2 423
C*** INTEGRATE DERIVATIVE OF FLIGHT-PATH ANGLE S2 424
CALL TRAP(K,TIME,DY,DX,GO) S2 425
C*** COMPUTE ALTITUDE RATE S2 426
DO 82 L=1,K          S2 427
82 HD(L)=F4(L)*DSIN(DX(L)) S2 428
HO=F10(L)             S2 429
C*** INTEGRATE ALTITUDE RATE S2 430
CALL TRAP(K,TIME,HO,H,HO) S2 431
83 IF (IPRC(9).EQ.0) GO TO 86 S2 432
C*** FIND AN INERTIAL-COMPATIBLE ALTITUDE AND DENSITY S2 433
HO=F10(L)             S2 434
DO 84 L=1,K          S2 435
CALL SECN(L,K,XAX) S2 436
84 DE(L)=F4(L)*DSIN(F2(L)-F6(L)) S2 437
CALL TRAP(K,TIME,DE,DY,HO) S2 438
DO 85 L=1,K          S2 439
F10(L)=FAC1*F10(L)+FAC2*DY(L) S2 440
F5(L)=RHO*(1.000-6.860-6*F10(L))**Z6D0 S2 441
CALL FHI(K,F10,T1R2,F11,F12,Z6S,WI) S2 442
86 IF (IPS(10).NE.0) GO TO 89 S2 443
C*** PERFORM FOURIER ANALYSIS ON VERTICAL ACCELERATION S2 444
N10E1=N10+1          S2 445
C*** COMPUTE FOURIER SERIES COEFFICIENTS S2 446
CALL PARAF(F13,K,N10P1,NC(10)) S2 447
C*** REGENERATE VERTICAL ACCELERATION TIME HISTORY (SMOOTHED) S2 448
X1=X(1)              S2 449

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DO 89 L=1,K          S2 450
TX=TIME(L)-TIME(1) S2 451
X2=C(1,10)*(D(K,10)-D(1,10))/TD*TX S2 452
X3=0.000             S2 453
DC 87 N=2,N10P1      S2 454
X3=X3+A(N)*DCOS(2*(N-1)*PI*TIME(L)/TI)+B(N)*DSIN(2*(N-1)*PI*TIME(L S2 455
1)/TI) S2 456
87 CONTINUE          S2 457
88 F13(L)=X1*X2*X3 S2 458
89 IF (IPS(11).NE.0) GO TO 92 S2 459
C*** PERFORM FOURIER ANALYSIS ON ELEVATOR (OR STABILATOR) DEFLECTION S2 460
N11E1=N11+1          S2 461
C*** COMPUTE FOURIER SERIES COEFFICIENTS S2 462
CALL PARAF(F14,K,N11P1,NC(11)) S2 463
C*** REGENERATE (ELEVATOR/STABILATOR) DEFLECTION TIME HISTORY (SMOOTHED) S2 464
X1=X(1)              S2 465
DO 91 L=1,K          S2 466
TX=TIME(L)-TIME(1) S2 467
X2=C(1,11)*(D(K,11)-D(1,11))/TD*TX S2 468
X3=0.000             S2 469
DO 90 N=2,N11P1      S2 470
X3=X3+A(N)*DCOS(2*(N-1)*PI*TIME(L)/TI)+B(N)*DSIN(2*(N-1)*PI*TIME(L S2 471
1)/TI) S2 472
90 CONTINUE          S2 473
91 F14(L)=X1*X2*X3 S2 474
C*** WRITE INPUT PARAMETERS S2 475
92 IF (JFE.NE.1) GO TO 96 S2 476
WRITE (JWRITE,93) IPS(1),NC(1),IP(1),IP(13),IPS(2),NC(2),IP(2),IP( S2 477
114),IPS(3),NC(3),IP(3),IPRC(1),IPS(4),NC(4),IP(4),IPRC(2),IPS(5),N S2 478
K(5),IP(5),IPRC(3),IPS(6),NC(6),IP(6),IPRC(4),IPS(7),NC(7),IP(7),I S2 479
IPRC(5),IPS(8),NC(8),IPRC(6),IPS(9),NC(9),IP(9),IPRC(7),IPS(1 S2 480
10),NC(10),IP(10),IPRC(8),IPS(11),NC(11),IP(11),IPRC(9),XAL,IP(12) S2 481
53 FCDEAT (1H1,/,42X,4H*,1/,42X,1H*,46X,1H*,42X,1H*,10X,26HSE S2 482
1CTION 2 INPUT PARAMETERS,10X,1H*,42X,1H*,46X,1H*,42X,1H*,2X,1 S2 483
IPS(1)=,12,2X,NC(1)=,13,2X,IP(1)=,12,2X,IP(13)=,12,3X,1H*, S2 484
142X,1H*,2X,IPS(2)=,12,2X,NC(2)=,13,2X,IP(2)=,12,2X,IP(14)= S2 485
1,12,3X,1H*,42X,1H*,2X,IPS(3)=,12,2X,NC(3)=,13,2X,IP(3)=,12 S2 486
1,2X,IPRC(1)=,12,2X,1H*,42X,1H*,2X,IPS(4)=,12,2X,NC(4)=,13, S2 487
12X,IP(4)=,12,2X,IPRC(2)=,12,2X,1H*,42X,1H*,2X,IPS(5)=,12,2 S2 488
1H,NC(5)=,13,2X,IP(5)=,12,2X,IPRC(3)=,12,2X,1H*,42X,1H*,2X, S2 489
1*IPS(6)=,12,2X,NC(6)=,13,2X,IP(6)=,12,2X,IPRC(4)=,12,2X,1H S2 490
1,42X,1H*,2X,IPS(7)=,12,2X,NC(7)=,13,2X,IP(7)=,12,2X,IPRC( S2 491
15)=,12,2X,1H*,42X,1H*,2X,IPS(8)=,12,2X,NC(8)=,13,2X,IP(8)= S2 492
1,12,2X,IPRC(6)=,12,2X,1H*,42X,1H*,2X,IPS(9)=,12,2X,NC(9)= S2 493
1,13,2X,IP(9)=,12,2X,IPRC(7)=,12,2X,1H*,42X,1H*,2X,IPS(10)= S2 494
1,11,2X,NC(10)=,12,2X,IP(10)=,11,2X,IPRC(8)=,12,2X,1H*,42X, S2 495
1H*,2X,IPS(11)=,11,2X,NC(11)=,12,2X,IP(11)=,11,2X,IPRC(9)= S2 496
1,12,2X,1H*,42X,1H*,2X,XAL=,F12,8,6X,IP(12)=,11,14X,1H*,16X S2 497
1,6H*,1H*,46X,1H*,6H*,1H*,36X,1H*,58X,1H*) S2 498
WRITE (JWRITE,94) (1,IP(1),1,W(I),I=1,6) S2 499
94 FORMAT (36X,1H*AP(1,1)=,1PD19,12,7X,W(1,1)=,1PD19,12,1H* S2 500
1) S2 501
WRITE (JWRITE,95) S2 502
95 FORMAT (36X,1H*58(1,1)=,1H*,1H*,1H*,1H*,1H*,1H*,1H*,1H*,1H*, S2 503
C*** TEMPORARILY STORE VALUES S2 504
DO 97 I=1,K          S2 505
TST(1,1)=D(1,1) S2 506
TST(1,2)=F2(I) S2 507
TST(1,3)=D(1,2) S2 508
TST(1,4)=F3(I) S2 509

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[illegible]

1.	F3(450),F4(450),F5(450),F6(450),F7(450),F8(450),TT,RMO,PI,G,JKS,R	PL	9
	12TRIC,JBADD,JWHITE,JPUNCH,IBRR	PL	9
	CORRCH,CASRT,F11(450),F12(450)	PL	10
	CORRCH /TENP1/SX(450,4),FAR(6),PSL,TSL,IPAR	PL	11
	CORRCH /TENP2/F9(450),F10(450),F13(450),F14(450),AP(6),W(6)	PL	12
	REAL44 TRD(4,450),XD(4,450),YRD(4,450),YD(4,450),TPTP	PL	13
		PL	14
		PL	15
	TIME=TIME	PL	16
	DO 1 I=1,K	PL	17
	IF (I.E.5) KD(I)=-1	PL	18
	DO 1 J=1,4	PL	19
1	KDD(J,I)=TIME(I)	PL	20
C***	PLOT WEIGHT TIME HISTCRY	PL	21
	IF (IP(1).NE.0) GO TO 4	PL	22
	N=1	PL	23
	IF (IFS(1).EQ.0) N=2	PL	24
	DO 2 I=1,K	PL	25
	YND(1,I)=D(1,1)	PL	26
	IF (IFS(1).EQ.0) YND(2,I)=F1(I)	PL	27
	IF (METRIC.NE.0) YND(1,I)=YBC(1,I)*.4482DG/100.ODG	PL	28
2	IF (METRIC.NE.0.AND.IFS(1).EQ.0) YND(2,I)=YBC(2,I)*.4482DG/100.ODG	PL	29
	CALL FICSI(10.0,10.0)	PL	30
	IF (METRIC.NE.0) GO TO 3	PL	31
	CALL GRAPP(2.0,0.0,TPTP,5.0,1,'TIME(SECS)',XND,XD,5.5,3500.0,4500	PL	32
	1.0,25C.0,1,'WEIGHT(LBF)',XND,YD,1,4,N,450,K,K,K,0,KD,1,'-')	PL	33
	GO TO 4	PL	34
3	CALL GRAPP(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XND,XD,5.5,150.0,200.0	PL	35
	1.5,C,1,'WEIGHT(NEWTONS)/100',YND,YD,1,4,N,450,K,K,K,0,KD,1,'-')	PL	36
1)		PL	37
C***	PLOT PITCH ANGLE TIME HISTCRY	PL	38
4	IF (IP(2).NE.0) GO TO 6	PL	39
	N=1	PL	40
	IF (IFS(2).EQ.0) N=2	PL	41
	DO 5 I=1,K	PL	42
	YND(1,I)=D(1,2)*100.ODG	PL	43
5	IF (IFS(2).EQ.0) YND(2,I)=F2(I)*100.ODG	PL	44
	CALL FICSI(10.0,10.0)	PL	45
	CALL GRAPP(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XND,XD,5.5,-80.0,80.0,	PL	46
	110.0,1,'PITCH ANGLE(RADIAN) X 100',YND,YD,1,4,N,450,K,K,K,0,KD,	PL	47
	11,'-')	PL	48
C***	PLOT PITCH RATE TIME HISTCRY	PL	49
6	IF (IP(3).NE.0) GO TO 8	PL	50
	N=1	PL	51
	IF (IFS(3).EQ.0) N=2	PL	52
	DO 7 I=1,K	PL	53
	YND(1,I)=D(1,3)*100.ODG	PL	54
7	IF (IFS(3).EQ.0) YND(2,I)=F3(I)*100.ODG	PL	55
	CALL FICSI(10.0,10.0)	PL	56
	CALL GRAPP(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XND,XD,5.5,-80.0,80.0,	PL	57
	110.0,1,'PITCH RATE(DMG/SEC) X 100',YND,YD,1,4,N,450,K,K,K,0,KD,	PL	58
	11,'-')	PL	59
C***	PLOT AIRSPEED TIME HISTCRY	PL	60
8	IF (IP(4).NE.0) GO TO 11	PL	61
	N=1	PL	62
	IF (IFS(4).EQ.0) N=2	PL	63
	DO 9 I=1,K	PL	64
	YND(1,I)=D(1,4)	PL	65
	IF (IFS(4).EQ.0) YND(2,I)=F4(I)	PL	66
	IF (METRIC.NE.0) YND(1,I)=YBC(1,I)*.3048DG	PL	67
9	IF (METRIC.NE.0.AND.IFS(4).EQ.0) YND(2,I)=YBC(2,I)*.3048DG	PL	67

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CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 10
CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,80.0,300.0,
120.0,1,'AIRSPEED(FT/SEC)',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
GO TO 11
10 CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,25.0,100.0,
15.0,1,'AIRSPEED(M/SEC)',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
C*** PLOT DENSITY TIME HISTORY
11 IF (IP(5).NE.0) GO TO 14
N=1
IF (IFS(5).EQ.0) N=2
DO 12 I=1,K
YRD(I,I)=D(I,5)*10000.000
IF (IFS(5).EQ.0) YRD(2,I)=F5(I)*10000.000
IF (METRIC.NE.0) YRD(1,I)=D(I,5)*5153.800
12 IF (METRIC.NE.0.AND.IFS(5).EQ.0) YRD(2,I)=F5(I)*5153.800
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 13
CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,14.0,24.0,2
1.0,1,'DENSITY(SIUG/FT**3) X 10000',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
GO TO 14
13 CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,6.0,12.0,1,
10.1,'DENSITY(KG/M**3) X 10',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
C*** PLOT ANGLE OF ATTACK TIME HISTORY
14 IF (IP(6).NE.0) GO TO 16
N=1
IF (IFS(6).EQ.0) N=2
DO 15 I=1,K
YRD(I,I)=D(I,6)*100.000
IF (IFS(6).EQ.0) YRD(2,I)=F6(I)*100.000
15 CALL PICSIZ(10.0,10.0)
CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-5.0,40.0,5
1.0,1,'ANGLE OF ATTACK(RAD) X 100',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
C*** PLOT TEMPERATURE TIME HISTORY
16 IF (IP(7).NE.0) GO TO 19
N=1
IF (IFS(7).EQ.0) N=2
DO 17 I=1,K
YRD(I,I)=D(I,7)
IF (IFS(7).EQ.0) YRD(2,I)=F7(I)
IF (METRIC.NE.0) YRD(1,I)=5.0/9.0*(D(I,7)-491.7200)*273.1800
17 IF (METRIC.NE.0.AND.IFS(7).EQ.0) YRD(2,I)=5.0/9.0*(F7(I)-491.72)*27
13.1800
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 18
CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,450.0,550.0
1.25.0,1,'TEMPERATURE(DEG-R)',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
GO TO 19
18 CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,250.0,300.0
1.10.0,1,'TEMPERATURE(DEG-F)',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
C*** PLOT ACCELERATION TIME HISTORY
19 IF (IP(8).NE.0) GO TO 22
N=2
IF (IFS(8).EQ.0) N=3
DO 20 I=1,K
YRD(I,I)=D(I,8)

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YRD(2,I)=F9(I)*DCOS(F6(I))*F8(I)*(F3(I)-F9(I))*DSIN(F6(I))-F8(I)*F3(I)
11)*2*G*DSIN(F2(I))*PAR(4)*G*DCOS(F2(I))*F4(I)*(F3(I)-F9(I))*DCOS
1(F6(I))-F8(I)*DSIN(F6(I))-2*G*DCOS(F2(I))*F4(I)*F3(I)-PAR(6)*F4(I)*
1(F3(I)-F9(I))*DCOS(F6(I))-F8(I)*DSIN(F6(I))
IF (IFS(8).EQ.0) YRD(3,I)=F8(I)
IF (METRIC.EQ.0) GO TO 20
YRD(1,I)=YRD(1,I)*0.304800
YRD(2,I)=YRD(2,I)*0.304800
IF (IFS(8).EQ.0) YRD(3,I)=YRD(3,I)*0.304800
20 CONTINUE
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 21
CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-32.0,32.0,
14.0,1,'ACCELERATION(FT/SEC**2)',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
GO TO 22
21 CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-10.0,10.0,
11.0,1,'ACCELERATION(M/SEC**2)',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
C*** PLOT ANGLE-OF-ATTACK RATE TIME HISTORY
22 IF (IP(9).NE.0) GO TO 24
N=1
DO 23 I=1,K
YRD(I,I)=D(I,9)*100.000
CALL PICSIZ(10.0,10.0)
CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-10.0,10.0,
11.0,1,'ANGLE-OF-ATTACK RATE(RAD/SEC) X 100',YRD,YD,1.4,N,450,K,K,K,1,' ')
16,K,K,KD,1,' ')
C*** PLOT ALTITUDE TIME HISTORY
24 IF (IP(10).NE.0) GO TO 30
N=1
IF (IFS(9).NE.0.AND.(IPRC(8).GE.2.AND.IPRC(9).EQ.0).OR.(IPRC(8).
1LT.2.AND.IPRC(9).NE.0)).OR.(IFS(9).EQ.0.AND.(IPRC(8).LT.2.AND.IPR
1C(9).EQ.0))) N=2
IF (IFS(9).NE.0.AND.(IPRC(8).GE.2.AND.IPRC(9).NE.0).OR.(IFS(9).E
10.0.AND.(IPRC(8).GE.2.AND.IPRC(9).EQ.0)).OR.(IFS(9).EQ.0.AND.(IPRC
1(8).LT.2.AND.IPRC(9).NE.0))) N=3
IF (IFS(9).EQ.0.AND.(IPRC(8).GE.2.AND.IPRC(9).NE.0)) N=4
DO 25 I=1,K
YRD(I,I)=D(I,9)/1000.000
IF (IFS(9).EQ.0) GO TO 25
IF (IPRC(8).GE.2) YRD(2,I)=H(I)/1000.000
IF (IPRC(8).GE.2.AND.IPRC(9).NE.0) YRD(3,I)=F10(I)/1000.000
IF (IPRC(8).LT.2) YRD(2,I)=F10(I)/1000.000
GO TO 26
25 YRD(2,I)=F10(I)/1000.000
IF (IPRC(8).GE.2) YRD(3,I)=H(I)/1000.000
IF (IPRC(8).GE.2.AND.IPRC(9).NE.0) YRD(4,I)=F10(I)/1000.000
IF (IPRC(8).LT.2.AND.IPRC(9).NE.0) YRD(3,I)=F10(I)/1000.000
26 IF (METRIC.EQ.0) GO TO 28
DO 27 J=1,N
YRD(J,I)=YRD(3,I)*0.304800*10.000
28 CONTINUE
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 29
CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,2.0,16.0,1,
10.1,'ALTITUDE(FT)/1000',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')
GO TO 30
29 CALL GRAFF(8.0,0.0,TPIP,5.0,1,'TIME(SECS)',XRD,XD,5.5,0.0,48.0,2,
10.1,'ALTITUDE(M)/100',YRD,YD,1.4,N,450,K,K,K,0,KD,1,' ')

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C*** PLOT ALTITUDE RATE TIME HISTORY
20 IF (IP(11).NE.0) GO TO 34
N=2
IF (IPRC(8).GE.2)N=3
DO 32 I=1,N
YRD(1,I)=F11(I)
YRD(2,I)=-P4(I)*F8(I)/G
IF (IPRC(8).GE.2)YRD(3,I)=HD(I)
IF (METRIC.EQ.0) GO TO 32
DO 31 J=1,N
31 YRD(J,I)=YRD(J,I)+0.3048D0
32 CONTINUE
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 33
CALL GRAFF(8.0,0.0,TPIP,5.0,1,*TIME(SECS)_,XRD,XD,5.5,-100.0,130.
10,10.0,1,*ALTITUDE RATE(FT/SEC)_,YRD,YD,1.4,N,450,K,K,K,0,KD,1,
1*,*)
GO TO 34
33 CALL GRAFF(8.0,0.0,TPIP,5.0,1,*TIME(SECS)_,XRD,XD,5.5,-14.0,34.0,
14.0,1,*ALTITUDE RATE(M/SEC)_,YRD,YD,1.4,N,450,K,K,K,0,KD,1,
1*,*)
C*** PLOT ALTITUDE ACCELERATION TIME HISTORY
34 IF (IP(12).NE.0) GO TO 37
DO 35 I=1,N
YRD(1,I)=F12(I)
35 IF (METRIC.NE.0)YRD(1,I)=F12(I)+0.3048D0
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 36
CALL GRAFF(8.0,0.0,TPIP,5.0,1,*TIME(SECS)_,XRD,XD,5.5,-100.0,100.
10,10.0,1,*ALTITUDE ACCELERATION(FT/SEC**2)_,YRD,YD,1.4,1,450,K,K,K,
1K,K,0,KC,1,*)
GO TO 37
36 CALL GRAFF(8.0,0.0,TPIP,5.0,1,*TIME(SECS)_,XRD,XD,5.5,-34.0,34.0,
14.0,1,*ALTITUDE ACCELERATION(M/SEC**2)_,YRD,YD,1.4,1,450,K,K,K,K,
10,KD,1,*)
C*** PLOT VERTICAL ACCELERATION TIME HISTORY
37 IF (IP(13).NE.0) GO TO 41
N=1
IF (IFS(10).EQ.C)N=2
DO 39 I=1,N
YRD(1,I)=D(1,10)
IF (IFS(10).EQ.0)YRD(2,I)=F13(I)
IF (METRIC.EQ.0) GO TO 39
DO 38 J=1,N
38 YRD(J,I)=YRD(J,I)+0.3048D0
39 CONTINUE
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 40
CALL GRAFF(8.0,0.0,TPIP,5.0,1,*TIME(SECS)_,XRD,XD,5.5,-32.0,32.0,
14.0,1,*VERTICAL ACCELERATION(FT/SEC**2)_,YRD,YD,1.4,N,450,K,K,K,K,
10,KC,1,*)
GO TO 41
40 CALL GRAFF(8.0,0.0,TPIP,5.0,1,*TIME(SECS)_,XRD,XD,5.5,-10.0,10.0,
12.0,1,*VERTICAL ACCELERATION(M/SEC**2)_,YRD,YD,1.4,N,450,K,K,K,K,
10,KC,1,*)
C*** PLOT ELEVATOR DEFLECTION TIME HISTORY
41 IF (IP(14).NE.0) GO TO 43
N=1
IF (IFS(11).EQ.0)N=2
DO 42 I=1,N

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YRD(1,I)=D(1,11)*100.0D0
42 IF (IFS(11).EQ.0)YRD(2,I)=F14(I)*100.0D0
CALL PICSIZ(10.0,10.0)
CALL GRAFF(8.0,0.0,TPIP,5.0,1,*TIME(SECS)_,XRD,XD,5.5,-25.0,25.0,
15.0,1,*ELEVATOR DEFLECTION(FA0) X 100_ ,YRD,YD,1.4,N,450,K,K,K,0
1,KD,1,*)
43 RETURN
END
SUBROUTINE SEC3(K,XAN,LSP,ITEST,LL,MUM,DSPPS)
C*** SUBROUTINE SEC3 CALCULATES PHASE SHIFT, AND OTHER DATA-
C*** DEPENDENT PARAMETERS BY A MINIMIZATION TECHNIQUE AND ADJUSTS THE
C*** DATA ACCORDINGLY
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION WK(2,6),DWK(2),F(3),X(3),TOL(2),TWK(21),TWJ(6),TWKK(36),
1WR(21),CC(6),C(6,6),Z(6,1),WR(100),LSP(9),RX(34),Dd(2),COST(10),SD
1V(10,6),ACOST(10),SL(450,3),SH(450,1),SMK(250),DPPA(450),PPA1(450)
1,PPA2(450),SA(450,2)
COMMON TITLE(20),D(450,11),TIME(450),A(100),W(100),F1(450),F2(450)
1,F3(450),P4(450),P5(450),P6(450),P7(450),P8(450),P9(450),P10(450),
1ETRIC,JREAD,JWRITE,JPUNCH,IEBR
COMMON /CARRY/F11(450),F12(450)
COMMON /TEMP1/ST(450,4),PAR(6),PSL,TSL,IPAR
COMMON /TEMP2/P9(450),F10(450),F13(450),F14(450),AP(6),V(6)
INTEGER LLSFN(10)/0,1,1,1,1,1,1,1,1,1/
C
C*** INITIALIZE PARAMETERS
LCNT=0
LMAX=10
ITEST=0
DO 1 J=1,6
IF (LL.GT.1)W(J)=W(J)/2.0D0
1 PAR(J)=0.0D0
X1=PSL/PSL
X2=F10(1)
C*** COMPUTE FLIGHT PATH ANGLE AND ITS DERIVATIVE
DO 2 I=1,N
PPA1(I)=DARSIN(F11(I)/P4(I))
PPA2(I)=PPA1(I)
DPPA(I)=(F4(I)*F12(I)-F11(I)*P8(I))/(P4(I)*DSQRT(1.0D0-(F11(I)/P4
1(I))**2)+P4(I))
2 CONTINUE
C*** FIND COMPATIBLE ANGLE OF ATTACK
3 RCNT=0
DO 9 L=1,K
C*** SOLVE FOR ANGLE OF ATTACK BY NEWTON RAPHSON
ITB=C
ALP=F6(I)
XP1=G*DSIN(PPA2(L))+P8(L)
IE2=G*DCOS(PPA2(L))*DPPA(L)*F4(L)
ITB=ITB+1
FW=ST(L,4)-XP1*DCOS(ALP)-IE2*DSIN(ALP)+XAN*P3(L)*F3(L)
FNE=XP1*DSIN(ALP)-IE2*DCOS(ALP)
FWPE=XP1*DCOS(ALP)+IE2*DSIN(ALP)
WAD=(FNE/FWEE)*(FNP/FWPP)-2.0D0*(FW/FWPP)
ALE1=ALE

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IF (RAD.LT.0.000) GO TO 6
IF ((PWP*PWP)-11.0.000) GO TO 5
ALP=ALP-PWP/PWPP*DSQRT(RAD)
GO TO 7
5 ALP=ALP-PWP/PWPP*DSQRT(RAD)
GO TO 7
6 ALP=ALP-PWP/PWPP
NCNT=NCNT+1
GO TO 8
7 IF (EARS(ALP-ALP)-11.00-15.00.1TH.20.20) GO TO 4
GO TO 4
C*** FORM COEFFICIENTS FOR LEAST SQUARES
8 SR(1,1)=ALP
SL(1,1)=1.000
SL(1,2)=P6(L)
SL(1,3)=P6(L)*P6(L)
9 CONTINUE
IF (NCNT.NE.0) WRITE (JURITE,10) NCNT
10 FORMAT (11,///,10X,10)*** DURING NEWTON-RAPHSON TO FIND COMPATIBLE
1 ANGLE OF ATTACK, THE ROUTINE WISHED TO SEEK COMPLEX ROOTS,13,7H
1 TIMES,///)
C*** EXACT LEAST SQUARES TO DETERMINE BIAS AND GAIN ESTIMATES
CALL LLSQAR(SL,SR,K,3,1,450,450,15,SWH,1TH,JURITE)
WRITE (JURITE,11) (SR(L,1),I=1,3)
11 FORMAT (31X,'COMPATIBILITY ESTIMATES OF THE 1 BIAS = ',1PD23.15,
1/31X,'BIAS AND GAINS BETWEEN INPUT 1-> FIRST-ORDER GAIN = ',1P
1D23.15,///,31X,'AND CALCULATED ANGLE OF ATTACK 1 SECOND-ORDER GAIN
1 = ',1PD23.15,/)
C*** COMPUTE AN ANGLE-OF-ATTACK VARIANCE INDICATION AND NEW VALUES OF
C*** ANGLE OF ATTACK
AVI=0.000
DO 12 I=1,K
SR(L,1)=P6(L)
OLD=P6(L)
P6(L)=SR(1,1)*P6(L)+(SR(2,1)*P6(L)+SR(3,1))
12 AVI=AVI+(P6(L)-OLD)*(SR(2,1)+P6(L)-CID)
WRITE (JURITE,13) AVI
13 FORMAT (31X,'ANGLE-OF-ATTACK VARIANCE INDICATION = ',1PD13.6,/)
C*** CHECK FOR INCREASING FIT ERROR
IF (ICHT.EQ.0) SAVI=AVI
IF (ICHT.EQ.0) GO TO 16
IF (AVI.GT.SAVI) GO TO 14
SAVI=AVI
GO TO 16
C*** RESET ANGLE OF ATTACK AND FLIGHT PATH ANGLE
DO 15 L=1,K
P6(L)=SA(L,1)
IF (ICHT.EQ.1) SA(L,2)=PPAT(L)
15 PPA2(L)=SA(L,2)
C*** BEGIN LOOP FOR SUCCESSIVE MINIMIZATIONS
16 CALL FNI(K,P6,TIME,P9,P14,1,15,3)
C*** TEST FOR MAXIMUM ITERATION OR INCREASING FIT ERROR
IF (ICHT.GE.10.OR.AVI.GT.SAVI) GO TO 19
C*** DETERMINE COMPATIBILITY ESTIMATES FOR FLIGHT PATH ANGLE
XGAP=P2(1)-P6(1)
IF (ICHT.NE.0) XGAP=PPA2(1)
C*** FORM THE COEFFICIENTS FOR LEAST SQUARES
SR(1,1)=XGAP
SL(1,1)=1.000
SL(1,2)=PPA2(1)

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S3 109

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SL(1,3)=PPA2(1)**2
DO 17 L=2,K
C*** INTEGRATE RATES FOR FLIGHT PATH ANGLE
XGAP=P2(L)-P6(L)
SR(1,1)=XGAP
SL(1,1)=1.000
SL(1,2)=PPA2(L)
17 SL(1,3)=PPA2(L)**2
C*** EXACT LEAST SQUARES FOR BIAS AND GAINS
CALL LLSQAR(SL,SR,K,3,1,450,450,15,SWH,1TH,JURITE)
C*** COMPUTE THE FITTED FLIGHT PATH ANGLE
DO 18 I=1,K
IF (ICHT.GT.0) SA(L,2)=PPA2(L)
18 PPA2(L)=SR(1,1)+SR(2,1)*PPA2(L)+SR(3,1)*PPA2(L)**2
C*** OBTAIN ITS DERIVATIVE
CALL FNI(K,PPA2,TIME,PPA,P14,1,15,3)
C*** RECOMPUTE COMPATIBLE ANGLE OF ATTACK
ICHT=ICHT+1
GO TO 3
C*** COMPUTE NEW ALTITUDE AND STATIC PRESSURE
19 NX=12
DO 21 I=1,K
IF (L.EQ.1) GO TO 20
NX=NX+0.500*(TIME(I)-TIME(L-1))*(P6(L)*DSIN(PPA2(L))+P6(L-1)*DSIN
20 PP2(L-1))
21 CONTINUE
XPA6=0.000
DO 46 I=1,LNAX
IF (LL.EQ.NUN) GO TO 25
WRITE (JURITE,22) LL,L
22 FORMAT (31X,'ITERATION',12,3X,'SUBITERATION',12,/)
C*** STORE DELTA VALUES
DO 23 I=1,6
DO 23 J=1,6
23 SDV(I,J)=PAR(I)
C*** INITIALIZE MATRICES
DO 24 J=1,21
DO 24 J=1,21
IF (J=1) GO TO 24
CC(J)=0.000
24 CONTINUE
C*** COMPUTE MAXIMUM PRESSURE AND ACCELERATION
25 MAX=DABS(ST(1,2))
THAX=DABS(ST(1,4))
DO 26 J=2,K
IF (DABS(ST(J,2))>.CT.THAX) THAX=DABS(ST(J,2))
IF (DABS(ST(J,4))>.CT.THAX) THAX=DABS(ST(J,4))
26 CONTINUE
C*** COMPUTE WEIGHT FACTORS
DN(1)=1.000/(THAX*THAX)
DN(2)=1.000/(THAX*THAX)
X(1)=0.000
X(2)=0.000
X(3)=0.000
TOL(1)=C.000
TOL(2)=C.000
C*** BEGIN COMPUTING PARAMETERS FOR PARTIAL DERIVATIVE EVALUATIONS
DO 35 I=1,K
X4=P3(2)-P9(I)
X5=P2(I)-P6(I)

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X6=P3(I)*P3(I)
X7=G*DSIN(P2(I))
X8=G*DCOS(P2(I))
X9=P3(I)*DCOS(P6(I))
X10=P3(I)*DSIN(P6(I))
X11=P4(I)*X4*DSIN(P6(I))
X12=P4(I)*X4*DCOS(P6(I))
X13=X12-X10
C*** CHECK FOR INITIAL POINT CALCULATION
IF (I.EQ.1) GO TO 27
X(1)=X2
X3=0.000
27 IF (I.EQ.1) GO TO 29
X3=(P7(I)-P7(I-1))/(TIME(I)-TIME(I-1))
C*** FIND POINT-TO-POINT INTEGRALS
P(1)=P4(I)*DSIN(X5)*P4(I-1)*DSIN(P2(I-1)-P6(I-1))
P(2)=P4(I)*DCOS(X5)*P4(I-1)*DCOS(P2(I-1)-P6(I-1))
P(3)=P3(I)*P4(I)*DCOS(X5)*P3(I-1)*P4(I-1)*DCOS(P2(I-1)-P6(I-1))
DO 28 J=1,3
28 X(J)=X(J)+0.500*(TIME(I)-TIME(I-1))*P(J)
29 X14=1.000-6.860-6*(X(1)*PAR(6)+X(2)*XPAR*X(J))
X15=X14*3.2600
IF (I.EQ.NUN) GO TO 30
C*** COMPUTE PARTIAL DERIVATIVES
WK(1,1)=X6
WK(2,1)=0.000
WK(1,2)=ST(I,4)
WK(2,2)=0.000
WK(1,3)=X7
WK(2,3)=0.000
WK(1,4)=0.000
WK(2,4)=X8*X13
WK(1,5)=X1*P7(I)*X15*(29.22360-6*(X(3)*(1.000-XPAR*X3/P7(I)))-X3*X
114/P7(I))
WK(2,5)=-P3(I)*X8
WK(1,6)=-29.22360-6*X1*P7(I)*(1.000-XPAR*X3/P7(I))*X15*X(2)
WK(2,6)=-X13
C*** COMPUTE STATIC PRESSURE AND LONGITUDINAL ACCELERATION
30 DWK(1)=X1*P7(I)*(1.000-XPAR*X3/P7(I))*X15*X14*PAR(1)*X6*PAR(2)*ST(I
IF(4)*PAR(3)*17
DWK(2)=X9*X11-X4*X6*X7*PAR(4)*(X8*X13)-XPAR*X6*P3(I)-PAR(6)*X13
C*** COMPUTE PRESSURE AND LONGITUDINAL ACCELERATION DIFFERENCES
DWK(1)=ST(I,2)-DWK(1)
DWK(2)=ST(I,4)-DWK(2)
IF (I.EQ.NUN) GO TO 33
C*** SUB MATRICES OF PARTIALS
JP=0
STWJ=0.000
DO 32 JJ=1,6
DO 31 J=1,2
JP=JP+1
TWJ(JP)=WK(J,JJ)*DSQRT(DW(J))
31 STWJ=STWJ+TWJ(JP)*DWK(J)*DSQRT(DW(J))
32 TWJ(JJ)=STWJ
HS=0
CALL HATA(TWJ,TWJ,2,6,HS)
CALL HATD(HR,TWJ,6,6,1)
CALL HATD(CC,TWJ,6,1,0)
C*** SUB DIFFERENCES SQUARED
33 DO 34 J=1,2

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34 TOL(J)=TOL(J)+CHK(J)*SUB(J)
35 CONTINUE
C*** COMPUTE COST FUNCTION AND TOLERANCES
PCF=0.000
IF (I.EQ.NUN) GO TO 37
DO 36 J=1,6
36 PCF=PCF+W(J)*(PAR(J)-AP(J))*2/(AP(J)*AP(J))
37 COST(L)=DW(1)*TOL(1)+DW(2)*TOL(2)+PCF
DO 38 I=1,2
38 TOL(I)=TOL(I)/N
WRITE (JWRITE,39) COST(L),(TOL(I),I=1,2)
39 FORMAT (31X,'COST FUNCTION (J) = ',1PD23.16,'/',31X,'WITH:',',',37X,'S
STATIC PRESSURE TOLERANCE = ',1PD23.16,'/',37X,'LONGITUDINAL ACCELE
TIC TOLERANCE = ',1PD23.16,'/')
C*** CHECK FOR INCREASE IN COST FUNCTION
IF (I.EQ.NUN) GO TO 56
IF (I.EQ.3) GO TO 40
IF (COST(L).GE.COST(L-1)) GO TO 47
C*** ADJUST MATRICES FOR LEAST SQUARES SOLUTION
40 CALL HSTR(HR,RI,6,1,0)
JP=0
DO 42 JJ=1,6
DO 41 J=1,6
IFAC=1.000
IF (JJ.EQ.J) IFAC=1.0000500
JP=JP+1
IC=IC(JP)
IF (J.EQ.JJ) IC=IC+2.000*W(JJ)/(AP(JJ)*AP(JJ))
C(J,JJ)=IC*IFAC
41 CONTINUE
Z(JJ,1)=CC(JJ)+2.000*W(JJ)*(AP(JJ)-PAR(JJ))/(AP(JJ)*AP(JJ))
42 CC=CONTINUE
N=6
C*** REDUCE MATRIX ORDER AS SPECIFIED BY USER
CALL REDUCR(C,Z,N,LI)
IF (N.EQ.0) ITEST=1
IF (ITEST.NE.0) GO TO 56
C*** EVALUATE LEAST SQUARES SOLUTION
CALL LLSQR(C,Z,N,N,1,6,6,15,VR,IR,JWRITE)
C*** TEST FOR ERROR
IF (IR.NE.129) IERR=1
IF (IERR.NE.0) RETURN
CALL RESET(Z,N)
C*** WRITE SOLUTION VALUES
WRITE (JWRITE,43) (Z(I,1),I=1,6)
43 FORMAT (30X,'1ST LINEAR ACCELERATION DEPENDENCY DELTA= ',D13.6,'/',3
10X,'2ND LINEAR ACCELERATION DEPENDENCY DELTA= ',D13.6,'/',30X,'3RD L
LINEAR ACCELERATION DEPENDENCY DELTA= ',D13.6,'/',30X,'PITCH ANGLE BI
IAS DELTA = ',D13.6,'/',30X,'PHASE SHIFT DELTA = ',D13.6,'/',30X,'FLIGH
1X PATH ANGLE DELTA= ',D13.6,'/')
C*** SUB DELTAS
DO 44 J=1,6
PAR(J)=SQR(I,J)*Z(J,1)
44 WRITE (JWRITE,45) (PAR(I),I=1,6)
45 FORMAT (42X,'UPDATED 1ST LINEAR ACCELERATION DEPENDENCY= ',D13.6,'/
1,2X,'UPDATED 2ND LINEAR ACCELERATION DEPENDENCY= ',D13.6,'/',42X,'UPD
ATED 3RD LINEAR ACCELERATION DEPENDENCY= ',D13.6,'/',42X,'UPDATED
PITCH ANGLE BIAS= ',D13.6,'/',42X,'UPDATED PHASE SHIFT= ',D13.6,'/',42
1X,'UPDATED FLIGHT PATH ANGLE BIAS= ',D13.6,'/')
IPAR=PAR(5)

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46 CONTINUE
ACOST(LL)=CCST(LL)
GO TO 45
C*** ADJUST COST FUNCTION AND DELTAS
47 ACOST(LL)=CCST(LL-1)
DO 48 J=1,6
48 PAR(J)=SDV(L-1,J)
C*** TEST FOR INCREASE IN COST FUNCTION
49 IF (LL.EQ.1) GO TO 50
IF (ACOST(LL).GE.ACOST(LL-1)) ITEST=1
50 IF (ITEST.EQ.1.CP.LL.EQ.NUN) GO TO 54
C*** WRITE BEST RESULTS
WRITE (JWRITE,51) L,ACOST(LL)
51 FORPAT (36X,13HOP THE ARCVE,12,44H ITERATIONS, THE BEST COST FUNC
ITION HAS BEEN,36X,22HCHOSEN TO BE EQUAL TO ,D.3.16,16H, AND THE
VALUES,36X,61HASSOCIATED WITH THIS COST FUNCTION (PHASE SHFT VA
LUE IS SUB-36X,62HJECT TO A MAGNITUDE AND SIGN RESTRICTION) WILL
BE USED TO MCC-36X,9HIFT DATA.//////)
C*** DETERMINE PHASE SHIFT
IF (PAR(5).GT.1.0D0) PAR(5)=1.0D0
IF (PAR(5).LT.0.0D0) IFAB=0
IF (IPAR.EQ.0) GO TO 52
PAR(5)=DSPS*PAR(5)
LP=PAR(5)
LFX=LP+1
LXP=LP
XLP1=LFX
IF ((PAR(5)-XLP).LT.0.5D0) IFAB=LP
IF ((XLPX-PAR(5)).LE.0.5D0) IPAR=LFX
PAR(5)=PAR(5)/DSPS
C*** ADJUST DATA WITH RESPECT TO DETERMINED DATA-DEPENDENT PARAMETERS
52 KN=R-IPAR
DO 53 I=1,KN
K=KN
D(I,1)=F1(I)
IF (LSP(1).NE.0) F2(I)=F2(I+IPAR)
F2(I)=F2(I)+PAR(4)
D(I,2)=F2(I)
IF (LSP(2).NE.0) F3(I)=F3(I+IPAR)
D(I,3)=F3(I)
IF (LSP(3).NE.0) F4(I)=F4(I+IPAR)
IF (LSP(4).NE.0) ST(I,2)=ST(I+IPAR,2)
D(I,5)=ST(I,2)
IF (LSP(5).NE.0) F6(I)=F6(I+IPAR)
F6(I)=F6(I)+PAR(4)-PAR(6)
D(I,6)=F6(I)
IF (LSP(5).NE.0) F9(I)=F9(I+IPAR)
IF (LSP(6).NE.0) ST(I,1)=ST(I+IPAR,1)
D(I,7)=ST(I,1)
IF (LSP(7).NE.0) ST(I,4)=ST(I+IPAR,4)
D(I,8)=ST(I,4)
IF (LSP(7).NE.0) F8(I)=F8(I+IPAR)
IF (LSP(8).NE.0) F13(I)=F13(I+IPAR)
IF (LSP(9).NE.0) F14(I)=F14(I+IPAR)
C*** CHECK FOR REDEFINING INPUT STATIC PRESSURE
IF (LLSPH(LL).EQ.0) GO TO 53
ST(I,2)=ST(I,2)-(PAR(1)*F3(I)+2*PAR(2)*ST(I,4)+PAR(3)*G*DSIN(F2(I
1)))

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53 CONTINUE
54 IF (ITEST.NE.C.AND.NE.O) WRITE (JWRITE,55)
55 FORPAT (36X,58HNO COST FUNCTION HAS BEEN DETERMINED TO BE BETTER T
HAN THE,36X,56HPREVIOUS BEST COST FUNCTION. THEREFORE, ITERATIO
INS HAVE,36X,15HBEEN CONCLUDED.//)
56 RETURN
END

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SUBROUTINE REDUCE(C,Z,N,LI)
C*** SUBROUTINE REDUCE DECREASES THE ORDER OF A SYMMETRIC MATRIX BY THE
ELIMINATION OF THE I-TH ROW AND COLUMN
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION C(6,6),Z(6,1),IR(6),R(6,6),S(6,1)
COMMON /ROW/IRS(10,6)
C
C*** INITIALIZE PARAMETERS
NR=N
DO 1 I=1,6
1 IR(I)=IRS(LL,I)
IJ=0
NR=N
IP=0
C*** DETERMINE FIRST ROW/COLUMN NOT ELIMINATED
DC 2 I=1,N
IF (IR(I).NE.0) IJ=I
IF (IR(I).NE.0) GO TO 3
2 CONTINUE
C*** IF IJ=0, USER SPECIFIED A NO MATRIX CONDITION
GO TO 6
C*** DEFINE NEW ELEMENTS IN TERMS OF OLD ELEMENTS
3 DC 5 I=1,N
IF (IR(I).EQ.0) GO TO 5
NR=NR+1
IF=IF+1
JP=0
DO 4 J=IJ,N
IF (IR(J).EQ.0) GO TO 4
JP=JP+1
R(I,JP)=C(I,J)
4 CONTINUE
S(IF,1)=Z(I,1)
5 CONTINUE
C*** DEFINE UPDATED ELEMENTS BY THE NEW ELEMENTS
NR=NR
DO 7 I=1,N
DO 6 J=1,N
C(I,J)=R(I,J)
6 CONTINUE
Z(I,1)=S(I,1)
7 CONTINUE
RETURN
C*** SET CODE FOR NO-MATRIX SPECIFICATION
8 N=0
RETURN
C
ENTRY RESET(Z,N)

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C***	ENTRY RESET ADJUSTS THE SOLUTION TO BE COMPATIBLE WITH THE	RD	51
C***	ORIGINAL RADIX	RD	52
C		RD	53
	MM=0	RD	55
	M=MM	AD	56
	DO 9 I=1,M	RD	57
	S(I,1)=6.000	AD	58
	IF (IB(I).EQ.0) GO TO 9	RD	59
	MM=MM+1	RD	60
	S(I,1)=Z(MM,1)	RD	61
9	CONTINUE	RD	62
	DO 10 I=1,M	RD	63
10	Z(I,1)=S(I,1)	RD	64
	RETURN	RD	65
	END	RD	66
	SUBROUTINE SHIFT(K,LSP,NSPTS)	SM	1
C		SM	2
C***	SUBROUTINE SHIFT ADJUSTS DATA FOR PHASE SHIFT	SM	3
C		SM	4
	IMPLICIT REAL*8(A-H,O-Z)	SM	5
	DIMENSION LSP(9)	SM	6
	COMMON TL(20),D(450,11),T(450),A(100),B(100),P1(450),P2(450),P3(450),	SM	7
	TS(450),AS(450),P(450),PD(450),PS(450),PSD(450),TT,MHC,PI,G,JP,R,JR,JW,	SM	8
	1JH	SH	9
C		SH	10
	L=1	SH	11
	KK=K-NSPTS	SH	12
	DO 2 I=1,9	SH	13
	IF (L.GT.7) I=2	SH	14
	IF (LSP(I).EQ.0) GO TO 2	SH	15
	DO 1 J=1,KK	SH	16
1	D(J,I+L)=D(J+NSPTS,I+L)	SH	17
2	CONTINUE	SH	18
	K=KK	SH	19
	RETURN	SH	20
	END	SH	21
	SUBROUTINE PARAF(ENT,K,NP1,NC)	PF	1
C		PF	2
C***	SUBROUTINE PARAF USES PARABOLIC INTEGRATION TO FORM FOURIER	PF	3
C***	SERIES COEFFICIENTS	PF	4
C		PF	5
	IMPLICIT REAL*8(A-H,O-Z)	PF	6
	DIMENSION FST(K),AA(100),BB(100),X(3593),P(3593),XY(3593),Y(3593)	PF	7
	COMMON TL(20),D(450,11),TH(450),A(100),B(100),P1(450),P2(450),P3(450),	PF	8
	TS(450),ASPD(450),P(450),PD(450),PS(450),PSD(450),TT,MHC,PI,G,JP,NC,JR	PF	9
	1,JV,JR	PF	10
	REAL*8 MM	PF	11
C		PF	12
C***	THE DIMENSION OF THE LARGE ARRAYS ARE DETERMINED BY:	PF	13
C***	(1) N1=450+(450-1)*(NIF=1)	PF	14
C***	(2) N2=N1*(N1-1)*(NIF=1)	PF	15
C***	(3) N3=N2*(N2-1)*(NIF=1) ----> N3=DIMENSION	PF	16
C***	INITIALIZE PARAMETERS	PF	17

	N0=2.000*PI/11	PP	19
	TOL=1.0E-10	PP	19
	KK=K	PP	20
	DC 1 I=1,K	PP	21
	I(I)=TR(I)	PP	22
	1 P(I)=INT(I)	PP	23
	KK=K	PP	24
C***	BEGIN IMPROVEMENT SCHEME	PP	25
	DO 5 JJR=1,3	PP	26
	KCHI=(KK-1)/2	PP	27
	L=1	PP	28
	IF=0	PP	29
C***	DETERMINE SLOPE DIFFERENCES	PP	30
	DC 4 J=1,KCHI	PP	31
	B=(X(L)-P(L*1))/(X(L)-X(L*1))-(P(L*1)-P(L*2))/(X(L*1)-X(L*2))/(X	PP	32
	1(L)-X(L*2))	PP	33
	S=(P(L)-P(L*1))/(X(L)-X(L*1))-(X(L)*X(L*1))*B	PP	34
	T=P(L)-X(L)*(R*X(L)+S)	PP	35
	S1=2.000*B*X(L)+S	PP	36
	S2=2.000*B*X(L*2)+S	PP	37
	IF (J.GT.1) GO TO 2	PP	38
	GC TO 3	PP	39
	2 IF (J.EQ.2) ANSD=DABS(S1-SX)	PP	40
	IF (DABS(S1-SX).GT.TOL) IP=IP+1	PP	41
	IF (DABS(S1-SX).GT.ANSD) ANSD=DABS(S1-SX)	PP	42
	3 SX=S2	PP	43
	4 L=L+2	PP	44
	IF (IP.NE.0) GO TO 5	PP	45
	GC TO 10	PP	46
C***	USE NEWTON'S INTERPOLATION FORMULA TO COMPUTE ADDITIONAL POINTS	PP	47
	5 NIP=1	PP	48
	DP=1.0D-12	PP	49
	N=0	PP	50
	L=1	PP	51
	J=6	PP	52
	XX=X(L)	PP	53
	XXN=X(K)	PP	54
	EC=C.000	PP	55
	6 B=B+1	PP	56
C***	DETERMINE ARGUMENT VALUES	PP	57
	XX=XX+EC	PP	58
	IF (DABS(XX-XXN).LT.DP) XX=XXN	PP	59
	IF (XX.GT.XXN) GO TO 7	PP	60
	IF (DABS(XX-X(L*1)).LT.DP) XX=X(L*1)	PP	61
	IF (XX.EQ.X(L*1).AND.XX.LT.XXN) J=J+1	PP	62
	IF (DABS(XX-X(J-2)).LT.DP) XX=X(J-2)	PP	63
	IF (XX.EQ.X(J-2).AND.XX.LT.XXN) J=J+1	PP	64
C***	COMPUTE THE NEWTONIAN COEFFICIENTS	PP	65
	A0=B(J-5)	PP	66
	A1=(P(J-4)-P(J-5))/(X(J-4)-X(J-5))	PP	67
	A2=(P(J-3)-(A0+A1*(X(J-3)-X(J-5))))/((X(J-3)-X(J-5))*(X(J-3)-X(J-4)	PP	68
	1))	PP	69
	A3=(P(J-2)-(A0+A1*(X(J-2)-X(J-5))+A2*(X(J-2)-X(J-5))*(X(J-2)-X(J-4)	PP	70
	1)))/((X(J-2)-X(J-5))*(X(J-2)-X(J-4))*(X(J-2)-X(J-3)))	PP	71
	A4=(P(J-1)-(A0+A1*(X(J-1)-X(J-5))+A2*(X(J-1)-X(J-5))*(X(J-1)-X(J-4)	PP	72
	1))+A3*(X(J-1)-X(J-5))*(X(J-1)-X(J-4))*(X(J-1)-X(J-3)))/((X(J-1)-X	PP	73
	1(J-5))*(X(J-1)-X(J-4))*(X(J-1)-X(J-3))*(X(J-1)-X(J-2)))	PP	74
	A5=(P(J)-(A0+A1*(X(J)-X(J-5))+A2*(X(J)-X(J-5))*(X(J)-X(J-4))+A3*(X	PP	75
	1(J)-X(J-5))*(X(J)-X(J-4))*(X(J)-X(J-3))+A4*(X(J)-X(J-5))*(X(J)-X	PP	76
	1(J)-X(J-5))*(X(J)-X(J-3))*(X(J)-X(J-2)))/((X(J)-X(J-5))*(X(J)-X(J-4))*(X	PP	77


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1(J)-X(J-3))*X(J)-X(J-2))*X(J)-X(J-1)) PF 78
C*** COMPUTE ADDITIONAL FUNCTION VALUES PF 79
Y(N)=A0+A1*(X-X(J-5))+A2*(X-X(J-5))*(X-X(J-4))+A3*(X-X(J-5))*( PF 80
X-X(J-4))*(X-X(J-3))+A4*(X-X(J-5))*(X-X(J-4))*(X-X(J-3))*(X- PF 81
X(J-2))+A5*(X-X(J-5))*(X-X(J-4))*(X-X(J-3))*(X-X(J-2))*(X-X(J PF 82
1-1)) PF 83
XY(N)=X PF 84
XC=(X(L+1)-X(L))/(NIP+1) PF 85
GO TO 6 PF 86
7 KB=R-1 PF 87
K=KB PF 88
DO 8 I=1,KN PF 89
X(I)=XY(I) PF 90
8 F(I)=Y(I) PF 91
9 CONTINUE PF 92
C*** DETERMINE NUMBER OF INTERVALS PF 93
10 KC=(K-1)/2 PF 94
L=1 PF 95
DO 17 J=1,KC PF 96
C*** SOLVE 3 EQUATIONS OVER INTERVAL PF 97
P=(F(L)-F(L+1))/(X(L)-X(L+1))-(F(L+1)-F(L+2))/(X(L+1)-X(L+2))/(X PF 98
1(L)-X(L+2)) PF 99
S=(X(L)-F(L+1))/(X(L)-X(L+1))-(X(L)+X(L+1))*P PF 100
T=F(L)-X(L)*(P+1) PF 101
C*** COMPUTE ZEROTH COEFFICIENTS FOR INTERVAL PF 102
AA(1)=(P*(X(L+2)+3-X(L)+3)/J.000+S*(X(L+2)+2-X(L)+2)/2.000+T PF 103
1X(L+2)-X(L+1))/(TT) PF 104
BB(1)=0.000 PF 105
DO 11 N=2,NP1 PF 106
NN=N-1 PF 107
C*** COMPUTE FIRST AND UPPER COEFFICIENTS FOR INTERVAL PF 108
AA(N)=P*(2.000*X(L+2)+DCOS(NN*W0*X(L+2))/(NN**2*W0**2)+(NN**2*W0** PF 109
12*X(L+2)+2-2.000)*DSIN(NN*W0*X(L+2))/(NN**3*W0**3))/(TT)*S*(DCOS( PF 110
1NN*W0*X(L+2))/(NN**2*W0**2)+X(L+2)*DSIN(NN*W0*X(L+2))/(NN*W0)/(TT PF 111
1)*T*DSIN(NN*W0*X(L+2))/(NN*W0)/(TT)-(P*(2.000*X(L+2)+DCOS(NN*W0*X( PF 112
1L))/(NN**2*W0**2)+(NN**2*W0**2*X(L+2)+2-2.000)*DSIN(NN*W0*X(L)/(NN PF 113
1003*W0**3))/(TT)*S*(DCOS(NN*W0*X(L)/(NN**2*W0**2)+X(L)*DCOS(NN*W0 PF 114
1*X(L))/(NN*W0)/(TT)+T*DSIN(NN*W0*X(L)/(NN*W0)/(TT)) PF 115
AA(N)=2.000*AA(N) PF 116
BB(N)=P*(2.000*X(L+2)+DCOS(NN*W0*X(L+2))/(NN**2*W0**2)-(NN**2*W0** PF 117
12*X(L+2)+2-2.000)*DCOS(NN*W0*X(L+2))/(NN**3*W0**3))/(TT)*S*(DSIN( PF 118
1NN*W0*X(L+2))/(NN**2*W0**2)-X(L+2)*DCOS(NN*W0*X(L+2))/(NN*W0)/(TT PF 119
1)-(P*DCOS(NN*W0*X(L+2))/(NN*W0)/(TT)-(P*(2.000*X(L+2)+DCOS(NN*W0*X( PF 120
1L))/(NN**2*W0**2)-(NN**2*W0**2*X(L+2)+2-2.000)*DCOS(NN*W0*X(L)/(NN PF 121
1003*W0**3))/(TT)*S*(DSIN(NN*W0*X(L)/(NN**2*W0**2)-X(L)*DCOS(NN*W0 PF 122
1*X(L))/(NN*W0)/(TT)-T*DCOS(NN*W0*X(L)/(NN*W0)/(TT)) PF 123
BB(N)=2.000*BB(N) PF 124
11 CONTINUE PF 125
IF (J.EQ.1) GO TO 12 PF 126
GO TO 10 PF 127
C*** SUM FOURIER SERIES COEFFICIENTS PF 128
12 DO 13 JJ=1,NP1 PF 129
A(JJ)=AA(JJ) PF 130
B(JJ)=BB(JJ) PF 131
13 CONTINUE PF 132
14 IF (J.GE.2) GO TO 15 PF 133
GO TO 17 PF 134
15 DO 16 JJ=1,NP1 PF 135
B(JJ)=B(JJ)+BB(JJ) PF 136
16 A(JJ)=A(JJ)+AA(JJ) PF 137

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17 L=L+2 PF 138
C*** FILTER FOURIER SERIES COEFFICIENTS TO REDUCE NOISE PF 139
CALL FILTER(A,B,NC,NP1) PF 140
K=KB PF 141
RETURN PF 142
END PF 143

SUBROUTINE TRAP(ND,X,CY,XO) TP 1
C TP 2
C*** SUBROUTINE TRAP INTEGRATES A FUNCTION BY TRAPEZOIDAL RULE TP 3
C TP 4
IMPLICIT REAL*8(A-H,O-Z) TP 5
DIMENSION X(ND),Y(ND) TP 6
C TP 7
C*** INITIALIZE PARAMETERS TP 8
S2=YC TP 9
IF (ND-1) 4,3,1 TP 10
C*** INTEGRATE OVER INTERVAL AND SUM TP 11
1 DO 2 I=2,ND TP 12
S1=S2 TP 13
S2=S2+0.5C0*(X(I)-X(I-1))*(CY(I)+CY(I-1)) TP 14
2 Y(I-1)=S1 TP 15
3 Y(ND)=S2 TP 16
4 RETURN TP 17
END TP 18

SUBROUTINE FNI(K,F,X,YP,PPP,ND,NS,NI) FN 1
C FN 2
C*** SUBROUTINE FNI USES NEWTON'S INTERPOLATION FORMULA TO COMPUTE FN 3
C*** ADDITIONAL POINTS FOR CUBIC SPLINE ANALYSIS FN 4
C FN 5
IMPLICIT REAL*8(A-H,O-Z) FN 6
DIMENSION P(K),X(K),FP(K),FEP(K),XY(1827),Y(1827),AA(4,1827),PPS(1 FN 7
1827) FN 8
C FN 9
C*** THE ARRAYS ARE PROTECTED AGAINST 'OVERFLOW' BY THE FOLLOWING CARDS FN 10
NB=K*(K-1)+NI+2*NS FN 11
IF (NB.LE.1827) GO TO 1 FN 12
NI=3 FN 13
NS=15 FN 14
NB=K*(K-1)+NI+2*NS FN 15
C*** INITIALIZE PARAMETERS FN 16
1 DF=1.0D-12 FN 17
N=X(4)-X(1) FN 18
XI=X FN 19
XC=DABS(XY/(NS+1)) FN 20
NN=DABS(XI)*X(N) FN 21
KCN=XC FN 22
N=0 FN 23
L=1 FN 24
J=6 FN 25
2 N=N+1 FN 26
C*** DETERMINE THE INTERVAL IN QUESTION FN 27
XI=X*XC FN 28
IF (DABS(XI-XN).LT.DF) XI=XN FN 29
IF (XI.GE.XN) GO TO 3 FN 30

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IF (DABS(XI-X(L)),LT.DP)XI=X(L)
IF (DABS(XI-X(L+1)),LT.DP)XI=X(L+1)
IF (XI.EQ.X(L+1).AND.XI.LT.X(L))L=L+1
IF (DABS(XI-X(J-2)),LT.DP)XI=X(J-2)
IF (XI.EQ.X(J-2).AND.J.LT.N)J=J+1
C*** COMPUTE THE NEWTONIAN COEFFICIENTS
A0=F(J-5)
A1=(F(J-4)-F(J-5))/(X(J-4)-X(J-5))
A2=(F(J-3)-(A0+A1*(X(J-3)-X(J-5))))/((X(J-3)-X(J-5))*(X(J-3)-X(J-4)))
A3=(F(J-2)-(A0+A1*(X(J-2)-X(J-5))+A2*(X(J-2)-X(J-5))*(X(J-2)-X(J-4))))/((X(J-2)-X(J-5))*(X(J-2)-X(J-4))*(X(J-2)-X(J-3)))
A4=(F(J-1)-(A0+A1*(X(J-1)-X(J-5))+A2*(X(J-1)-X(J-5))*(X(J-1)-X(J-4))+A3*(X(J-1)-X(J-5))*(X(J-1)-X(J-4))*(X(J-1)-X(J-3))))/((X(J-1)-X(J-5))*(X(J-1)-X(J-4))*(X(J-1)-X(J-3))*(X(J-1)-X(J-2)))
A5=(F(J)-(A0+A1*(X(J)-X(J-5))+A2*(X(J)-X(J-5))*(X(J)-X(J-4))+A3*(X(J)-X(J-5))*(X(J)-X(J-4))*(X(J)-X(J-3))+A4*(X(J)-X(J-5))*(X(J)-X(J-4))*(X(J)-X(J-3))*(X(J)-X(J-2))))/((X(J)-X(J-5))*(X(J)-X(J-4))*(X(J)-X(J-3))*(X(J)-X(J-2))*(X(J)-X(J-1)))
C*** COMPUTE ADDITIONAL POINTS BY INTERPOLATION
T(H)=A0+A1*(XI-X(J-5))+A2*(XI-X(J-5))*(XI-X(J-4))+A3*(XI-X(J-5))*(XI-X(J-4))*(XI-X(J-3))+A4*(XI-X(J-5))*(XI-X(J-4))*(XI-X(J-3))*(XI-X(J-2))+A5*(XI-X(J-5))*(XI-X(J-4))*(XI-X(J-3))*(XI-X(J-2))*(XI-X(J-1))
XI(H)=XI
C*** DETERMINE INTERVAL INCREMENTS
IF (XI.GE.X(1).AND.XI.LT.X(N))XC=(X(L+1)-X(L))/(NI+1)
IF (XI.GE.X(N))XC=XCB
GO TO 2
3 KN=N-1
C*** COMPUTE FIRST DERIVATIVE BY DIFFERENTIATION OF SPLINE FIT
CALL SPLINE(KN,XI,AA,
L1=NS+1
L2=KN-NS
L3=NI+1
II=0
DO 4 I=L1,L2,L3
II=II+1
J=I
IF (I.EQ.L2)J=J-1
FP(II)=3.000*AA(1,J)*XI(I)**2+2.000*AA(2,J)*XI(I)*AA(3,J)
4 CONTINUE
C*** CHECK FOR SECOND DERIVATIVE REQUEST
IF (ND.EQ.2) GO TO 5
GO TO 8
C*** COMPUTE ALL FIRST DERIVATIVES FOR SPLINE FIT
DO 6 I=1,KN
J=I
IF (I.EQ.KN)J=J-1
FPS(I)=3.000*AA(1,J)*XI(I)**2+2.000*AA(2,J)*XI(I)*AA(3,J)
C*** COMPUTE SECOND DERIVATIVE BY DIFFERENTIATION OF SPLICED FIRST DERIVATIVE
CALL SPLINE(KN,FPS,XI,AA)
II=0
DO 7 I=L1+2,L3
II=II+1
J=I
IF (I.EQ.L2)J=J-1
FP(II)=3.000*AA(1,J)*XI(I)**2+2.000*AA(2,J)*XI(I)*AA(3,J)
7 CONTINUE

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8 RETURN
END
SUBROUTINE SEC4(L,X,XAX)
C
C*** SUBROUTINE SEC4 CONTROLS THE ANGLE-OF-ATTACK CALCULATIONS BY THE
C*** DIFFERENTIAL EQUATION SOLUTION
C
IMPLICIT REAL*8(A-H,O-Z)
COMMON TL(20),D(450,11),TH(450),A(100),B(100),F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F7(450),F8(450),TT,RNO,PI,G,JKS,R,JR,J
IN,JF,INDB
CORRCH /TENP1/ST(450,4),PAR(6),PSL,TSL,IPAR
CORRCH /PARH/GR,DAX
CORRCH /BLK1/2(450,5)
CORRCH /LAB1/INB,IB
COMMON /TENP2/P9(450),F10(450),F13(450),F14(450),AP(6),U(6)
C
IF (L.GT.1) GO TO 2
C*** INITIALIZE PARAMETERS AT FIRST POINT FOR ALL POINTS
IS1=0
IWR=JW
IR=IERH
DAX=MAX
GR=G
DO 1 I=1,K
Z(L,1)=ST(L,4)
Z(L,2)=F2(L)
Z(L,3)=F3(L)
Z(L,4)=F9(L)
Z(L,5)=F6(L)
T=P4(L)
DY=(ST(L,4)-G*DSIN(Z(L,2))+RAX*Z(L,3)**2)/DCOS(Z(L,5))-Y*((Z(L,3)-Z(L,4))*DTAN(Z(L,5)))
GC TO 6
C*** COMPUTE TIME INCREMENT AND SET TIME TO PREVIOUS POINT
2 N=TH(L)-TH(L-1)
J=L-1
T=TH(J)
C*** EXACT PREDICTOR-CORRECTOR
CALL TREHOR(H,T,3,DI,J,IS1)
C*** CHECK FOR ERROR
IRGR=IR
IF (IRGR.NE.0) GO TO 4
GO TO 6
4 WRITE (JWRIT,5)
5 FORNAT (1X,/,10X,'AN ERROR OCCURRED IN THE PREDICTOR-CORRECTOR RUN')
ITIME',///)
5 RETURN
C*** DEFINE NEW AIRSPEED AND ACCELERATION
6 F4(I)=Y
F8(I)=DY
5 RETURN
END

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SUBROUTINE TREHOR(H,XI,XY,DYI,J,IS1)

FM 91
FM 92

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C
C*** SUBROUTINE TRENOB SOLVES A DIFFERENTIAL EQUATION BY PREDICTOR-
C*** CORRECTOR METHODS
C
      IMPLICIT REAL*8(A-H,O-Z)
      EXTERNAL FIDER
      COMMON /PARM/G,IXI
      COMMON /PCRD/DY(7),X(7),Y(7)
      COMMON /LAB1/JWRITE,IF
      COMMON /CRCOEF/P,LC,A1,A2,A3,A4,A5,HH
      COMMON /BLK1/2(450,5)
      COMMON /BLK2/PM(5)
C
C*** INITIALIZE PARAMETERS FOR FF
      DO 1 I=1,5
1    PM(I)=2(J,I)
C*** COMPUTE DERIVATIVE AT BEGINNING OF INTERVAL
      CALL FF(XI,YI,DYI)
      DY(7)=DYI
C*** TEST FOR INITIALIZATION
      IF (ISET) 2,2,4
C*** DEFINE VARIABLES INITIALLY
2    DO 3 I=1,7
      Y(I)=YI
      DY(I)=DYI
3    X(I)=XI
C*** BEGIN RUNGE KUTTA
      K=1
      LN=E
      ISET=1
      GO TO 5
4    IF (K-LN) K=K+1
      IF (K=7) 5,10,10
C*** DEFINE VARIABLES FOR FF
5    Y2=YI+0.5D0*H*DYI
      DO 6 I=1,5
6    PM(I)=(2(J,I)+2(J+1,I))/2.0D0
C*** COMPUTE DERIVATIVE AT INTERVAL MIDPOINT
      CALL FF(XI+C.5D0*H,Y2,DY2)
      Y3=YI+0.5D0*H*DY2
C*** UPDATE DERIVATIVE AT INTERVAL MIDPOINT
      CALL FF(XI+C.5D0*H,Y3,DY3)
C*** APPLY CORRECTIVE PROCEDURE FOR RUNGE KUTTA
      IF (DABS(DY2-DYI).LT.1.0D-15) GO TO 7
      P=-2.0D0*(DY3-DY2)/(DY2-DYI)/H
      IF ((P*H).LT.1.0D-04) GO TO 7
C*** COMPUTE 'STIFF-EQUATION' F COEFFICIENTS
      F0=0.0D0
      IF ((-P*H).LT.174.673D0.AND.(-P*H).GT.-180.218D0) F0=DEXP(-P*H)
      F1=(F0-1.0D0)/P/H
      F2=-(F1-1.0D0)/P/H
      F3=-(F2-0.5D0)/P/H
      Y4=YI+H*(2.0D0*DY3+F2*DYI*(F1-2.0D0*F2)+DY2*P*H*F2)
      AP=1.0D0
      IKP=0
      GO TO 8
C*** SET F COEFFICIENTS TO STANDARD ADAMS-BASHFORTH F COEFFICIENTS
7    F1=1.0D0
      F2=0.5D0
      F3=1.6666666666666667D-1

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      P=0.0D0
      Y4=YI+H*DY3
C*** DEFINE VARIABLES FOR FF
      DO 9 I=1,5
9    PM(I)=2(J+1,I)
C*** COMPUTE DERIVATIVE AT END OF INTERVAL
      CALL FF(XI+H,Y4,DY4)
      B=-3.0D0*(DYI+P*YI)+2.0D0*(DY2+P*Y2)+2.0D0*(DY3+P*Y3)-(DY4+P*Y4)
      C=4.0D0*((DYI+P*YI)-(DY2+P*Y2)-(DY3+P*Y3)+(DY4+P*Y4))
      Y5=YI+H*(DYI+P1+P2*P3)
C*** UPDATE DERIVATIVE AT END OF INTERVAL BY CORRECTION
      CALL FF(XI+H,Y5,DY5)
      GC TO 17
10    DO 11 I=1,6
      Y(I)=Y(I+1)
      DY(I)=DY(I+1)
11    X(I)=X(I+1)
      X(7)=X(6)+H
C*** CALL PREDICTOR TO PREDICT Y AT NEXT POINT
12    DO 13 I=1,6
13    CALL PHICP(I)
      K=7
      LK=IK+1
      PDCY=Y(1)+PHIDER(6,X(7),-1,1,0)-PHIDER(6,X(1),-1,1,0)
C*** DEFINE VARIABLE FOR FF
      DO 14 I=1,5
14    PM(I)=2(J+1,I)
C*** USING PREDICTED Y, COMPUTE ITS DERIVATIVE
      CALL FF(X(7),PDCY,DY(7))
      CALL PHICP(7)
C*** GENERATE COEFFICIENTS NECESSARY FOR 'STIFF-EQUATION' CORRECTOR
      CALL FCIP
C*** TEST FOR SUITABLE CORRECTOR
      IF ((P*H).LT.1.0D-02) GO TO 15
C*** CORRECT Y BY 'STIFF-EQUATION' CORRECTOR
      CALL FHETH
      GO TO 16
C*** CORRECT Y BY MODIFIED TRENOB CORRECTOR
15    Y(7)=Y(1)+PHIDER(7,X(7),-1,1,0)-PHIDER(7,X(1),-1,1,0)
16    Y5=Y(7)
C*** COMPUTE FUNCTION DERIVATIVE BY FF
      CALL FF(X(7),Y5,DY5)
      DY(7)=DY5
C*** TEST FOR POSSIBLE ERRORS
      IF (IK.EQ.0) RETURN
C*** UPDATE PARAMETERS
17    IF (LK.EQ.7) GO TO 20
      IF (LK.GT.7) GO TO 19
      DO 18 I=1,6
      Y(I)=Y(I+1)
      DY(I)=DY(I+1)
18    X(I)=X(I+1)
      X(7)=X(6)+H
19    Y(7)=Y5
      DY(7)=DY5
      IF (K.EQ.6) GO TO 12
20    YI=Y(7)
      DYI=DY(7)
      X=X(7)
      RETURN

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END                                TR 122

SUBROUTINE FF(Y,V,DV)              PP 1
C*** SUBROUTINE FF CALCULATES DERIVATIVES FOR ANGLE OF ATTACK PP 2
C*** PREDICTIONS                    PP 3
C                                   PP 4
IMPLICIT REAL*8(A-H,O-Z)          PP 5
COMMON /PARM/G,IAI                PP 6
COMMON /BLK2/X(5)                 PP 7
C                                   PP 8
DY=(X(1)-G*DSIN(X(2))-IAI*X(3)**2)/DCOS(X(5))-Y*(X(3)-X(4))*DTAN( PP 9
X(5)))                            PP 10
RETURN                             PP 11
END                                 PP 12
PP 13

SUBROUTINE PRICEF(I)               CP 1
C*** SUBROUTINE PRICEF COMPUTES COEFFICIENTS FOR NEWTON'S-FORWARD CP 2
C*** INTERPOLATION SCHEME FOR NON-EQUIDISTANT INTERVALS FOR THE CP 3
C*** FOLLOWING FUNCTION FHI:        CP 4
C*** FHI(X)=A(1)*X(2)*(X-X(1))*X(3)*(X-X(1))*(X-X(2))*... CP 5
C*** ...*X(I)*(X-X(1))*(X-X(2))*...*(X-X(I-1))*... CP 6
C*** ...*X(N)*(X-X(1))*(X-X(2))*...*(X-X(N-1)). CP 7
C*** BY USING A RECURSION FORMULA, PRICEF CAN BE USED TO COMPUTE BOTH CP 8
C*** DERIVATIVES AND ANTIDERIVATIVES OF FHI. PRICEF MUST BE CALLED IN CP 9
C*** CONSECUTIVELY-INCREASING VALUES OF I FOR THE RECURSION FORMULA TO CP 10
C*** BE CORRECT.                  CP 11
C                                   CP 12
IMPLICIT REAL*8(A-H,O-Z)          CP 13
COMMON /AMRK/A(7),C(7,8)         CP 14
COMMON /PCB/F(7),X(7),Y(7)       CP 15
COMMON /LAB1/JWRITE,IERR         CP 16
C                                   CP 17
IF (I.LT.1.CB.I.GT.7) GO TO 8    CP 18
C*** TRANSLATE                     CP 19
SVZ=X(1)                          CP 20
DO 1 J=1,I                        CP 21
1 X(J)=X(J)-SVZ                   CP 22
C*** CALCULATE THE C-COEFFICIENTS CP 23
J=1                               CP 24
C*** NOTE: C(I,1)=1 FOR ALL I     CP 25
C(I,J)=100                        CP 26
2 J=J+1                           CP 27
IF (J.GT.I) GO TO 3              CP 28
C(I,J)=X(I-1)*C(I-1,J-1)+C(I-1,J) CP 29
GO TO 2                           CP 30
C*** NOTE: C(I,I+1)=C FOR ALL I   CP 31
3 C(I,I+1)=000                   CP 32
C*** CALCULATE A(I)               CP 33
A(I)=000                          CP 34
DNN=100                           CP 35
J=1                               CP 36
4 IF (J.GT.I-1) GO TO 5           CP 37
A(I)=A(I)+A(J)*DNN                CP 38
DNN=DNN*(X(I)-X(J))               CP 39
CP 40

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J=J+1                             CP 41
GO TO 4                           CP 42
5 A(I)=(F(I)-A(I))/DNN            CP 43
C*** RESET                        CP 44
DO 6 J=1,I                        CP 45
6 X(J)=X(J)+SVZ                   CP 46
7 RETURN                           CP 47
8 IERR=1                           CP 48
WRITE (JWRITE,9) I               CP 49
9 FORNAT (1H, '***PRICEF ERROR: I=',I3, ' BUT 0<I<N IS REQUIRED****') CP 50
GO TO 7                           CP 51
END                                 CP 52

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SUBROUTINE LLSQAR(A,B,N,NA,NB,IA,IB,IDGT,WKAREA,IERR,JWRITE) LQ 1
C*** SUBROUTINE LLSQAR PERFORMS A LEAST SQUARES SOLUTION OF A OVER- LQ 2
C*** DETERMINED SYSTEM OF LINEAR EQUATIONS LQ 3
C                                   LQ 4
DIMENSION A(IA,1),B(IB,1),WKAREA(1) LQ 5
REAL*8 SUB                         LQ 6
REAL*8 A,B,WKAREA                  LQ 7
C                                   LQ 8
C*** INITIALIZE IERR               LQ 9
IERR=0                             LQ 10
C*** FIND THE PSEUDO-INVERSE OF MATRIX A LQ 11
CALL IPSDOR(A,N,NA,IA,A,IDGT,WKAREA,IERR,JWRITE) LQ 12
IF (IERR.NE.0) GO TO 5             LQ 13
C*** SOLVE THE EQUATION BY MULTIPLYING A-INVERSE AND B LQ 14
DO 4 I=1,NB                        LQ 15
4 I=1,NA                           LQ 16
DO 2 J=1,NA                        LQ 17
CALL VEPZRO                        LQ 18
DO 1 K=1,N                         LQ 19
CALL VEPHOL(A(K,J),B(K,I))         LQ 20
1 CONTINUE                         LQ 21
CALL VEPSTO(SUB)                   LQ 22
WKAREA(J)=SUB                      LQ 23
2 CONTINUE                         LQ 24
C*** MOVE THE RESULTS INTO MATRIX B LQ 25
DO 3 J=1,NA                        LQ 26
B(J,I)=WKAREA(J)                  LQ 27
3 CONTINUE                         LQ 28
4 CONTINUE                         LQ 29
GO TO 6                            LQ 30
5 IERR=129                         LQ 31
CALL UERTST(IERR,6,LLSQAR,JWRITE) LQ 32
6 RETURN                           LQ 33
END                                 LQ 34

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SUBROUTINE IPSDOR(A,N,N,IA,AINV,IDGT,WKAREA,IERR,JWRITE) PI 1
C*** SUBROUTINE IPSDOR FINDS THE PSEUDO-INVERSE OF A MATRIX PI 2
C                                   PI 3
DIMENSION A(IA,1),AINV(IA,1),WKAREA(N,1) PI 4
REAL*8 A,AINV,WKAREA,BIGA,ARN,ZERO,ETA PI 5
REAL*8 SUB,DETA                   PI 6
C                                   PI 7
PI 8

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IF (F.LI.O.CO) G=-G
N=F*G-S
NR=1.0/N
IF (I.LI.N) U(I,I+1)=F-G
IF (I.LI.N) GO TO 12
DO 11 J=L,N
11 WKAREA(J)=U(I,J)*NR
12 IF (I.LI.N) GO TO 16
DO 15 J=L,N
CALL VIP2RO
IF (I.LI.N) GO TO 15
DO 13 K=L,N
13 CALL VIPRUL(U(J,K),U(I,K))
CALL VIPSTO(S)
DO 14 K=L,N
14 U(J,K)=U(J,K)+S*WKAREA(K)
15 CONTINUE
16 Y=DABS(C(I))*DABS(WKAREA(I))
IF (Y.GT.X) X=Y
17 CONTINUE
C*** ACCUMULATION OF RIGHT HAND TRANSFORMATIONS
IF (ISW.EQ.O) GO TO 37
DO 25 I=1,N
II=N-I+1
IF (G.EQ.C.CO) GO TO 22
IF (I.LI.N) GO TO 24
N=U(II,II+1)*G
NR=1.0/N
DO 18 J=L,N
18 V(J,II)=U(II,J)*NR
DO 21 J=L,N
CALL VIP2RO
DO 19 K=L,N
19 CALL VIPRUL(U(II,K),V(K,II))
CALL VIPSTO(S)
DO 20 K=L,N
20 V(K,II)=V(K,II)+S*V(K,II)
21 CONTINUE
22 IF (I.LI.N) GO TO 24
DO 23 J=L,N
V(J,II)=0.00
23 V(II,II)=0.00
24 V(II,II)=1.000
G=WKAREA(II)
25 I=II
C*** ACCUMULATION OF LEFT HAND TRANSFORMATIONS
DO 36 I=1,N
II=N-I+1
LL=II+1
G=Q(II)
IF (LL.GT.N) GO TO 27
DO 26 J=LL,N
26 G(II,J)=0.00
27 IF (G.EQ.O.CO) GO TO 33
N=U(II,II)*G
NR=1.0/N
IF (I.LI.N) GO TO 31
DO 30 J=LL,N
CALL VIP2RO
DO 28 K=LL,N

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28 CALL VIPRUL(U(K,II),U(K,II))
CALL VIPSTO(S)
F=S*NR
DO 29 K=II,N
29 U(K,II)=U(K,II)+F*U(K,II)
30 CONTINUE
31 GR=1.0/G
DO 32 J=II,N
32 U(J,II)=U(J,II)*GR
GO TO 35
33 DO 34 J=II,N
34 U(J,II)=0.00
35 U(II,II)=U(II,II)+1.000
36 CONTINUE
C*** DIAGONALIZATION OF THE BIDIAGONAL FORM
37 EPS=EPS*Y
DO 57 K=1,N
NR=N-K+1
C*** TEST F SPLITTING
38 DO 39 I=1,NR
LI=NR-I+1
IF (DABS(WKAREA(LI)).LE.EPS) GO TO 45
IF (LL.EQ.1) GO TO 45
IF (DABS(Q(LL-1)).LE.EPS) GO TO 40
39 CONTINUE
C*** CANCELLATION OF WKAREA(L) IF LL.GT.1
40 C=0.00
S=1.000
LI=LI-1
IF (NR.LI.LL) GO TO 45
DO 44 I=LI,NR
F=S*WKAREA(I)
WKAREA(I)=C*WKAREA(I)
IF (DABS(F).LE.EPS) GO TO 45
G=Q(I)
Q(I)=DSQRT(F*F+G*G)
N=C(I)
IF (N.NE.ZERO) GO TO 41
C=ZERO
S=ONE
GO TO 42
41 C=C/N
S=-F/N
42 IF (ISW.EQ.O) GO TO 44
DO 43 J=1,N
Y=U(J,LI)
Z=U(J,LI)
U(J,LI)=Y*C+Z*S
43 U(J,LI)=Y*S+Z*C
44 CONTINUE
C*** TEST F CONVERGENCE
45 E=Q(NK)
IF (LL.EQ.NK) GO TO 55
C*** SHIFT FROM ECTICH 2X2 MINOR
K=Q(LL)
IF (NR.GT.1) Y=Q(NK-1)
IF (NR.GT.1) G=WKAREA(NK-1)
H=WKAREA(NK)
F=((I-2)*(Y+Z)+(G-H)*(G+H))/(2.00*H*Y)
G=DSQRT(F*F+ONE)

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0000 NEXT CP TRANSFORMATION

SV 177
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SV 179

SUBROUTINE DERTST (IER, NAME, JDATE)

SUBROUTINE VSCRTM(A,LA) VS 1

ORIGINAL, PAGE IS
OF POOR QUALITY

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      R=.375                                VS 20
      IF (I.EQ.J) GO TO 11                  VS 21
      IF (R.GT..5098437) GO TO 4           VS 22
      R=B*.90625E-2                         VS 23
      GO TO 5                               VS 24
      R=B-.21875                           VS 25
      R=1                                   VS 26
      C*** SELECT A CENTRAL ELEMENT OF THE ARRAY AND SAVE IT IN LOCATION T VS 27
      IJ=1+(J-1)*B                          VS 28
      T=A(IJ)                               VS 29
      C*** IF FIRST ELEMENT OF ARRAY IS GREATER THAN T, INTERCHANGE WITH T VS 30
      IF (A(I).LE.T) GO TO 6                VS 31
      A(IJ)=A(I)                            VS 32
      A(I)=T                                VS 33
      T=A(IJ)                               VS 34
      L=J                                    VS 35
      C*** IF LAST ELEMENT OF ARRAY IS LESS THAN T, INTERCHANGE WITH T VS 36
      IF (A(J).GE.T) GO TO 8                VS 37
      A(IJ)=A(J)                            VS 38
      A(J)=T                                VS 39
      T=A(IJ)                               VS 40
      C*** IF FIRST ELEMENT OF ARRAY IS GREATER THAN T, INTERCHANGE WITH T VS 41
      IF (A(I).LE.T) GO TO 8                VS 42
      A(IJ)=A(I)                            VS 43
      A(I)=T                                VS 44
      T=A(IJ)                               VS 45
      GO TO 8                               VS 46
      7 TT=A(I)                             VS 47
      A(L)=A(K)                             VS 48
      A(K)=TT                                VS 49
      C*** FIND AN ELEMENT IN SECOND HALF OF ARRAY WHICH IS SMALLER THAN T VS 50
      L=L+1                                 VS 51
      IF (A(L).GT.T) GO TO 8                VS 52
      C*** FIND AN ELEMENT IN FIRST HALF OF ARRAY WHICH IS GREATER THAN T VS 53
      K=K+1                                 VS 54
      IF (A(K).LT.T) GO TO 9                VS 55
      C*** INTERCHANGE THESE ELEMENTS VS 56
      IF (K.LE.L) GO TO 7                   VS 57
      C*** SAVE UPPER AND LOWER SUBSCRIPTS OF THE ARRAY YET TO BE SORTED VS 58
      IF (L-I.LE.J-K) GO TO 10              VS 59
      IL(N)=I                               VS 60
      IU(N)=L                               VS 61
      I=K                                    VS 62
      N=N+1                                 VS 63
      GO TO 12                              VS 64
      10 IL(N)=K                             VS 65
      IU(N)=J                               VS 66
      J=L                                    VS 67
      N=N+1                                 VS 68
      GO TO 12                              VS 69
      C*** BEGIN AGAIN ON ANOTHER PORTION OF UNSORTED ARRAY VS 70
      11 N=N-1                              VS 71
      IF (N.EQ.0) RETURN                   VS 72
      I=IL(N)                               VS 73
      J=IU(N)                               VS 74
      12 IF (J-I.GE.11) GO TO 5             VS 75
      IF (I.EQ.1) GO TO 2                  VS 76
      I=I+1                                 VS 77
      13 I=I+1                              VS 78
      IF (I.EQ.J) GO TO 11                  VS 79

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      T=A(I+1)                                VS 80
      IF (A(I).LE.T) GO TO 13              VS 81
      R=1                                    VS 82
      14 A(K+1)=A(K)                         VS 83
      K=K+1                                 VS 84
      IF (T.LT.A(K)) GO TO 14               VS 85
      A(K+1)=T                              VS 86
      GO TO 13                              VS 87
      END                                  VS 88

      SUBROUTINE HADD(A,B,M,N,NS)            NS 1
      C                                     NS 2
      C*** SUBROUTINE HADD ADDS TWO MATRICES NS 3
      C                                     NS 4
      IMPLICIT REAL*8 (A-H,O-Z)            NS 5
      DIMENSION A(1),B(1)                 NS 6
      C                                     NS 7
      NN=M*N                               NS 8
      C*** CHECK FOR UPPER TRIANGULAR STORAGE MODE NS 9
      IF (NS.EQ.1) NN=NN*(N+1)/2           NS 10
      C*** SUM THE MATRICES ELEMENT BY ELEMENT NS 11
      DO 1 I=1,NN                           NS 12
      1 A(I)=A(I)+B(I)                       NS 13
      RETURN                                NS 14
      END                                  NS 15

      SUBROUTINE HSTR(A,R,M,NSA,NSF)         NS 1
      C                                     NS 2
      C*** SUBROUTINE HSTR CHANGES THE STORAGE MODE OF THE MATRIX NS 3
      C                                     NS 4
      IMPLICIT REAL*8 (A-H,O-Z)            NS 5
      DIMENSION A(1),F(1)                 NS 6
      C                                     NS 7
      DO 5 I=1,M                           NS 8
      DO 5 J=1,M                           NS 9
      C*** IF MATRIX R IS GENERAL, FORM ELEMENT NS 10
      IF (NSR) 1,2,1                       NS 11
      C*** IF IN LOWER TRIANGLE OF SYMMETRIC OR DIAGONAL N, BYPASS NS 12
      1 IF (I-J) 2,2,5                     NS 13
      2 CALL ICC(I,J,IA,M,N,NSA)           NS 14
      C*** IF IN UPPER AND OFF-DIAGONAL OF DIAGONAL N, BYPASS NS 15
      IF (IR) 5,5,3                         NS 16
      C*** FORM R(I,J)                     NS 17
      3 R(IR)=0.0D0                         NS 18
      CALL ICC(I,J,IA,M,N,NSA)             NS 19
      C*** IF THERE IS NO A(I,J), LEAVE R(I,J) AT 0.0 NS 20
      IF (IA) 5,5,4                         NS 21
      4 R(IR)=A(IA)                         NS 22
      5 CONTINUE                           NS 23
      RETURN                                NS 24
      END                                  NS 25

      SUBROUTINE FILTER(A,B,NCUT,RFI)        PL 1
      C                                     PL 2

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C*** SUBROUTINE FILTER IS A LOW-PASS FILTER USED TO REDUCE HIGH NOISE
C
      IMPLICIT REAL*8(A-H,O-Z)
      DIMENSION A(NP1),B(NP1)
C
C*** INITIALIZE PARAMETERS
      PI=3.141592653589793D0
      I=NCUT
      IXI=3.0D0/2.0D0*X
      DO 4 N=1,NP1
C*** TEST FOR ARGUMENT RANGE FOR FILTERING
      II=I
      IF (IX.GE.X.AND.XX.LE.XIX) GC TO 1
      GO TO 2
1  A(N)=A(N)*(DCOS(PI*(XX-IX)/X))**2
      B(N)=B(N)*(DCOS(PI*(XX-IX)/X))**2
2  IF (XX.GT.XIX) GC TO 3
      GO TO 4
3  A(N)=0.0D0
      B(N)=C.CD0
4  CONTINUE
      RETURN
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      A=0.5D0-C
      F=A*(I-1)+1.0D0
      Q(I)=-C/P
      U(I)=(D-A*U(I-1))/P
      NN=NN
      YN=YY
2  YI=YY
C*** MODIFIED RIGHT-HAND END CONDITION THAT ALLEVIATES THE NEED TO
C*** SPECIFY THE X-DERIVATIVE OF Y AT POINT N
      A=31.0D0/32.0D0
      P=A*(N-1)+1.0D0
      H1=H(NN1)
      H2=H(NN1-1)
      H3=H(NN1-2)
      D=Y(N)*(32.0D0*H1+42.0D0*H2+21.0D0*H3)/(H1*H2)/(H1*H2*H3)-Y(NN1)*
      111.0D0*H1+42.0D0*H2+21.0D0*H3)/(H2*H3)/H2*(H1-1)*H1*(11.0D0*H1+2
      11.0D0*(H2*H3))/(H1*H2)/H2/H3-Y(NN1-2)*H1*(11.0D0*H1+21.0D0*H2)/H2
      1*H3)/(H1*H2*H3)/H3
      D=3.0D0*D/H1/16.0D0
      U(N)=(D-A*U(N-1))/P
C*** SOLVE FOR THE Spline COEFFICIENTS CORRESPONDING TO AHLBERG N(I) TO
C*** N(N) AND STORE THEM IN THE U(I)
      DO 3 J=1,NN1
      I=N-J
      U(I)=Q(I)*U(I+1)+U(I)
3  CONTINUE
C*** FORM THE Spline COEFFICIENTS FOR THE CONVENTIONAL FORM OF A Cubic
C*** POLYNOMIAL FROM THE U(I)
      UU=U(1)
      XI=X(1)
      YY=Y(1)
      DO 4 I=1,NN1
      UP=U(I+1)
      XP=X(I+1)
      YP=Y(I+1)
      HH=H(I)
      AA(1,I)=(UP-UU)/HH/6.0D0
      AA(2,I)=0.5D0*(XP*UU-XX*UP)/HH
      AA(3,I)=0.5D0*(UP*XP-XX*UU)/HH/6.0D0*(YP-YY)/HH
      AA(4,I)=(UU*XP*XP-XP*UP*XP)/HH/6.0D0*(UP*XP-UU*XP)/HH/6.0D0
      1*(YP*XP-YP*XX)/HH
      XX=XP
      UU=UP
      YY=YP
4  CONTINUE
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T(X)=X-X0
U(Y)=Y-Y0
V(DY)=DY-DY0
C*** CALCULATE X-DIFFERENCES
T0=T(X0)
T1=T(X1)
T2=T(X2)
T3=T(X3)
T4=T(X4)
T5=T(X5)
T6=T(X6)
C*** CALCULATE Y-DIFFERENCES RELATIVE TO Y0
U0=U(Y0)
U1=U(Y1)
U2=U(Y2)
U3=U(Y3)
U4=U(Y4)
U5=U(Y5)
U6=U(Y6)
C*** CALCULATE DY-DIFFERENCES RELATIVE TO DY0
V0=V(DY0)
V1=V(DY1)
V2=V(DY2)
V3=V(DY3)
V4=V(DY4)
V5=V(DY5)
V6=V(DY6)
C*** EQUATION 1
B0=U1/T1
B2=-T1
B3=B2+T1
B4=B3+T1
B5=B4+T1
B6=U1/T1
C*** EQUATION 2
C=T2*(B2+T2)/C
C3=-T2*(B3+T2+T2)/C
C4=-T2*(B4+T2+T2+T2)/C
C5=-T2*(B5+T2+T2+T2+T2)/C
C6=-T2*(B6+T2)/C
C*** UPDATE EQUATION 2
D0=B2+C0+B0
D3=B2+C3+B3
D4=B2+C4+B4
D5=B2+C5+B5
D6=B2+C6+B6
C*** EQUATION 3
E=T3*(D3+T3*(C3+T3))
E0=-T3*(T3*(D0+T3*(C0+T3)))/E
E4=-T3*(D4+T3*(C4+T3+T3))/E
E5=-T3*(D5+T3*(C5+T3+T3+T3))/E
E6=-T3*(D6+T3*(C6+T3+T3))/E
C*** UPDATE EQUATION 3
F0=D3+E0+D0
F4=D3+E4+D4
F5=D3+E5+D5
F6=D3+E6+D6
G0=C3+E0+C0
G4=C3+E4+C4

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G5=C3+E5+C5
G6=C3+E6+C6
C*** EQUATION 4
H=T4*(F4+T4*(G4+T4*(E4+T4)))
H0=(F4-(T4*(F0+T4*(G0+T4*(E0+T4))))/H
H5=(T4*(F5+T4*(G5+T4*(E5+T4+T4)))/H
H6=(F4-(T4*(F6+T4*(G6+T4*(E6+T4+T4))))/H
C*** UPDATE EQUATION 4
I0=F4+H0+G0
I5=F4+H5+G5
I6=F4+H6+G6
J0=G4+H0+G0
J5=G4+H5+G5
J6=G4+H6+G6
K0=F4+H0+G0
K5=F4+H5+G5
K6=F4+H6+G6
C*** EQUATION 5
L=T5*(I5+T5*(J5+T5*(K5+T5*(H5+T5))))
L0=(I5-(T5*(I0+T5*(J0+T5*(K0+T5*(H0+T5)))))/L
L6=(I5-(T5*(I6+T5*(J6+T5*(K6+T5*(H6+T5)))))/L
C*** UPDATE EQUATION 5
M0=I5+L0+I0
M6=I5+L6+I6
N0=J5+L0+J0
N6=J5+L6+J6
O0=K5+L0+K0
O6=K5+L6+K6
R0=H5+L0+H0
R6=H5+L6+H6
N=Y6-X0
P=(T6*(H6+T6*(H6+T6*(O6+T6*(R6+T6*(L6)))))-M6)
IF (DABS(P).LT.1.0D-33) P=1.0D-33
XNN=(T6*(M0+T6*(N0+T6*(O0+T6*(R0+T6*(L0)))))-T6)
IF (DABS(XNN).LT.1.0D-33) XNN=1.0D-33
C*** CHECK EXPONENTS TO PREVENT UNDERFLOWS AND OVERFLOWS
TEXT=DLOG(DABS(XNN))-DLOG(DABS(P))
IF (TEXT.LT.-77.0D0) GO TO 5
IF (TEXT.LE.74.0D0) GO TO 1
IX1=-1.0D0
IX2=-1.0D0
IF (DABS(XNN).EQ.XNN) IX1=1.0D0
IF (DABS(P).EQ.P) IX2=1.0D0
IXS=IX1*IX2
P=-1.0D+74
IF (IXS.GT.0.0D0) P=1.0D+74
IF (P.LT.0.0D0) GO TO 5
GO TO 2
C*** CALCULATE COEFFICIENTS
1 P=XNN/P
C*** TEST FOR MACHINE LIMIT
2 IF (P*P).LT.22.0D0) GO TO 3
P=22.0D0/H
3 IF (P.LT.101) GO TO 5
A0=DY0
A1=D0+P*H6
A2=D0+P*H6
A3=C0+P*O6
A4=D0+P*H6
A5=I0+P*L6

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PC 105
PC 106
PC 107
PC 108
PC 109
PC 110
PC 111
PC 112
PC 113
PC 114
PC 115
PC 116
PC 117
PC 118
PC 119
PC 120
PC 121
PC 122
PC 123
PC 124
PC 125
PC 126
PC 127
PC 128
PC 129
PC 130
PC 131
PC 132

```

```

GO TO 8
END
SUBROUTINE PRETH
C*** SUBROUTINE PRETH PRODUCES A CORRECTED VALUE OF Y(N+1)
C
      IMPLICIT REAL*8 (A-Z)
      COMMON /CBCGEP/P,A0,A1,A2,A3,A4,A5,W
      COMMON /PCN/DY0,EY1,DY2,DY3,EY4,DY5,DY6,X0,X1,X2,X3,X4,X5,X6,Y0,Y1
      Y1,Y2,Y3,Y4,Y5,Y6
C
      PH=F*H
      CCGEUTE THE TREANOR F-VALUES
      F0=0.000
      IF ((-PH).LT.174.67300.AND. (-PH).GT.-186.21800) F0=DEXP(-PH)
      F1=(F0-100)/(1-FH)
      F2=(F1-100)/(1-FH)
      F3=(F2-(100/200))/(1-FH)
      F4=(F3-(100/600))/(1-FH)
      F5=(F4-(100/2400))/(1-FH)
      F6=(F5-(100/12000))/(1-FH)
C*** CCGEUTE A CORRECTED VALUE OF Y(N+1)
      Y6=YC*H*(A0+F1*H*(A1+F2*H*(A2+F3*H*(A4*H*(A5*F4*H*(A6*H*(A7*F5*H*(A8*H*(A9*F6*H*(A10*H*(A11*F7*H*(A12*H*(A13*F8*H*(A14*F9*H*(A15*F10*H*(A16*H*(A17*F11*H*(A18*F12*H*(A19*F13*H*(A20*F14*H*(A21*F15*H*(A22*F16*H*(A23*F17*H*(A24*F18*H*(A25*F19*H*(A26*F20*H*(A27*F21*H*(A28*F22*H*(A29*F23*H*(A30*F24*H*(A31*F25*H*(A32*F26*H*(A33*F27*H*(A34*F28*H*(A35*F29*H*(A36*F30*H*(A37*F31*H*(A38*F32*H*(A39*F33*H*(A40*F34*H*(A41*F35*H*(A42*F36*H*(A43*F37*H*(A44*F38*H*(A45*F39*H*(A46*F40*H*(A47*F41*H*(A48*F42*H*(A49*F43*H*(A50*F44*H*(A51*F45*H*(A52*F46*H*(A53*F47*H*(A54*F48*H*(A55*F49*H*(A56*F50*H*(A57*F51*H*(A58*F52*H*(A59*F53*H*(A60*F54*H*(A61*F55*H*(A62*F56*H*(A63*F57*H*(A64*F58*H*(A65*F59*H*(A66*F60*H*(A67*F61*H*(A68*F62*H*(A69*F63*H*(A70*F64*H*(A71*F65*H*(A72*F66*H*(A73*F67*H*(A74*F68*H*(A75*F69*H*(A76*F70*H*(A77*F71*H*(A78*F72*H*(A79*F73*H*(A80*F74*H*(A81*F75*H*(A82*F76*H*(A83*F77*H*(A84*F78*H*(A85*F79*H*(A86*F80*H*(A87*F81*H*(A88*F82*H*(A89*F83*H*(A90*F84*H*(A91*F85*H*(A92*F86*H*(A93*F87*H*(A94*F88*H*(A95*F89*H*(A96*F90*H*(A97*F91*H*(A98*F92*H*(A99*F93*H*(A100*F94*H*(A101*F95*H*(A102*F96*H*(A103*F97*H*(A104*F98*H*(A105*F99*H*(A106*F100*H*(A107*F101*H*(A108*F102*H*(A109*F103*H*(A110*F104*H*(A111*F105*H*(A112*F106*H*(A113*F107*H*(A114*F108*H*(A115*F109*H*(A116*F110*H*(A117*F111*H*(A118*F112*H*(A119*F113*H*(A120*F114*H*(A121*F115*H*(A122*F116*H*(A123*F117*H*(A124*F118*H*(A125*F119*H*(A126*F120*H*(A127*F121*H*(A128*F122*H*(A129*F123*H*(A130*F124*H*(A131*F125*H*(A132*F126*H*(A133*F127*H*(A134*F128*H*(A135*F129*H*(A136*F130*H*(A137*F131*H*(A138*F132*H*(A139*F133*H*(A140*F134*H*(A141*F135*H*(A142*F136*H*(A143*F137*H*(A144*F138*H*(A145*F139*H*(A146*F140*H*(A147*F141*H*(A148*F142*H*(A149*F143*H*(A150*F144*H*(A151*F145*H*(A152*F146*H*(A153*F147*H*(A154*F148*H*(A155*F149*H*(A156*F150*H*(A157*F151*H*(A158*F152*H*(A159*F153*H*(A160*F154*H*(A161*F155*H*(A162*F156*H*(A163*F157*H*(A164*F158*H*(A165*F159*H*(A166*F160*H*(A167*F161*H*(A168*F162*H*(A169*F163*H*(A170*F164*H*(A171*F165*H*(A172*F166*H*(A173*F167*H*(A174*F168*H*(A175*F169*H*(A176*F170*H*(A177*F171*H*(A178*F172*H*(A179*F173*H*(A180*F174*H*(A181*F175*H*(A182*F176*H*(A183*F177*H*(A184*F178*H*(A185*F179*H*(A186*F180*H*(A187*F181*H*(A188*F182*H*(A189*F183*H*(A190*F184*H*(A191*F185*H*(A192*F186*H*(A193*F187*H*(A194*F188*H*(A195*F189*H*(A196*F190*H*(A197*F191*H*(A198*F192*H*(A199*F193*H*(A200*F194*H*(A201*F195*H*(A202*F196*H*(A203*F197*H*(A204*F198*H*(A205*F199*H*(A206*F200*H*(A207*F201*H*(A208*F202*H*(A209*F203*H*(A210*F204*H*(A211*F205*H*(A212*F206*H*(A213*F207*H*(A214*F208*H*(A215*F209*H*(A216*F210*H*(A217*F211*H*(A218*F212*H*(A219*F213*H*(A220*F214*H*(A221*F215*H*(A222*F216*H*(A223*F217*H*(A224*F218*H*(A225*F219*H*(A226*F220*H*(A227*F221*H*(A228*F222*H*(A229*F223*H*(A230*F224*H*(A231*F225*H*(A232*F226*H*(A233*F227*H*(A234*F228*H*(A235*F229*H*(A236*F230*H*(A237*F231*H*(A238*F232*H*(A239*F233*H*(A240*F234*H*(A241*F235*H*(A242*F236*H*(A243*F237*H*(A244*F238*H*(A245*F239*H*(A246*F240*H*(A247*F241*H*(A248*F242*H*(A249*F243*H*(A250*F244*H*(A251*F245*H*(A252*F246*H*(A253*F247*H*(A254*F248*H*(A255*F249*H*(A256*F250*H*(A257*F251*H*(A258*F252*H*(A259*F253*H*(A260*F254*H*(A261*F255*H*(A262*F256*H*(A263*F257*H*(A264*F258*H*(A265*F259*H*(A266*F260*H*(A267*F261*H*(A268*F262*H*(A269*F263*H*(A270*F264*H*(A271*F265*H*(A272*F266*H*(A273*F267*H*(A274*F268*H*(A275*F269*H*(A276*F270*H*(A277*F271*H*(A278*F272*H*(A279*F273*H*(A280*F274*H*(A281*F275*H*(A282*F276*H*(A283*F277*H*(A284*F278*H*(A285*F279*H*(A286*F280*H*(A287*F281*H*(A288*F282*H*(A289*F283*H*(A290*F284*H*(A291*F285*H*(A292*F286*H*(A293*F287*H*(A294*F288*H*(A295*F289*H*(A296*F290*H*(A297*F291*H*(A298*F292*H*(A299*F293*H*(A300*F294*H*(A301*F295*H*(A302*F296*H*(A303*F297*H*(A304*F298*H*(A305*F299*H*(A306*F300*H*(A307*F301*H*(A308*F302*H*(A309*F303*H*(A310*F304*H*(A311*F305*H*(A312*F306*H*(A313*F307*H*(A314*F308*H*(A315*F309*H*(A316*F310*H*(A317*F311*H*(A318*F312*H*(A319*F313*H*(A320*F314*H*(A321*F315*H*(A322*F316*H*(A323*F317*H*(A324*F318*H*(A325*F319*H*(A326*F320*H*(A327*F321*H*(A328*F322*H*(A329*F323*H*(A330*F324*H*(A331*F325*H*(A332*F326*H*(A333*F327*H*(A3
```

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C      IMPLICIT REAL*8 (A-H,O-Z)
C      DIMENSION A(1),R(1)

      DO 6 K=1,N
      KK=(K+N-K)/2
      DO 6 J=1,N
      IF (J-K) 1,1,6
1      IR=J+K
      R(IR)=0.0D0
      DO 6 I=1,N
      IF (HS) 2,4,2
2      CALL IOC(I,J,IA,N,N,HS)
      CALL IOC(I,K,IB,N,N,HS)
      IF (IA) 3,6,3
3      IF (IB) 5,6,5
4      IA=N*(J-1)+I
      IB=N*(K-1)+I
5      R(IR)=R(IR)+A(IA)*R(IB)
6      CONTINUE
      RETURN
      END

```

```

NT 5
NT 6
NT 7
NT 8
NT 9
NT 10
NT 11
NT 12
NT 13
NT 14
NT 15
NT 16
NT 17
NT 18
NT 19
NT 20
NT 21
NT 22
NT 23
NT 24
NT 25
NT 26

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Flowchart — FDR1

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*FDR1

PAGE 15

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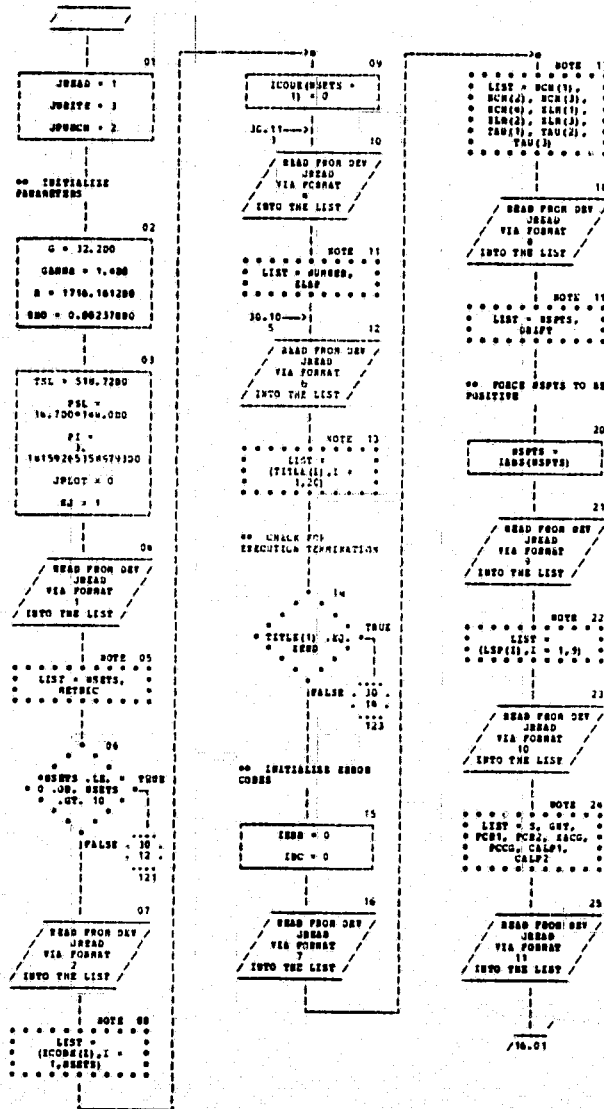


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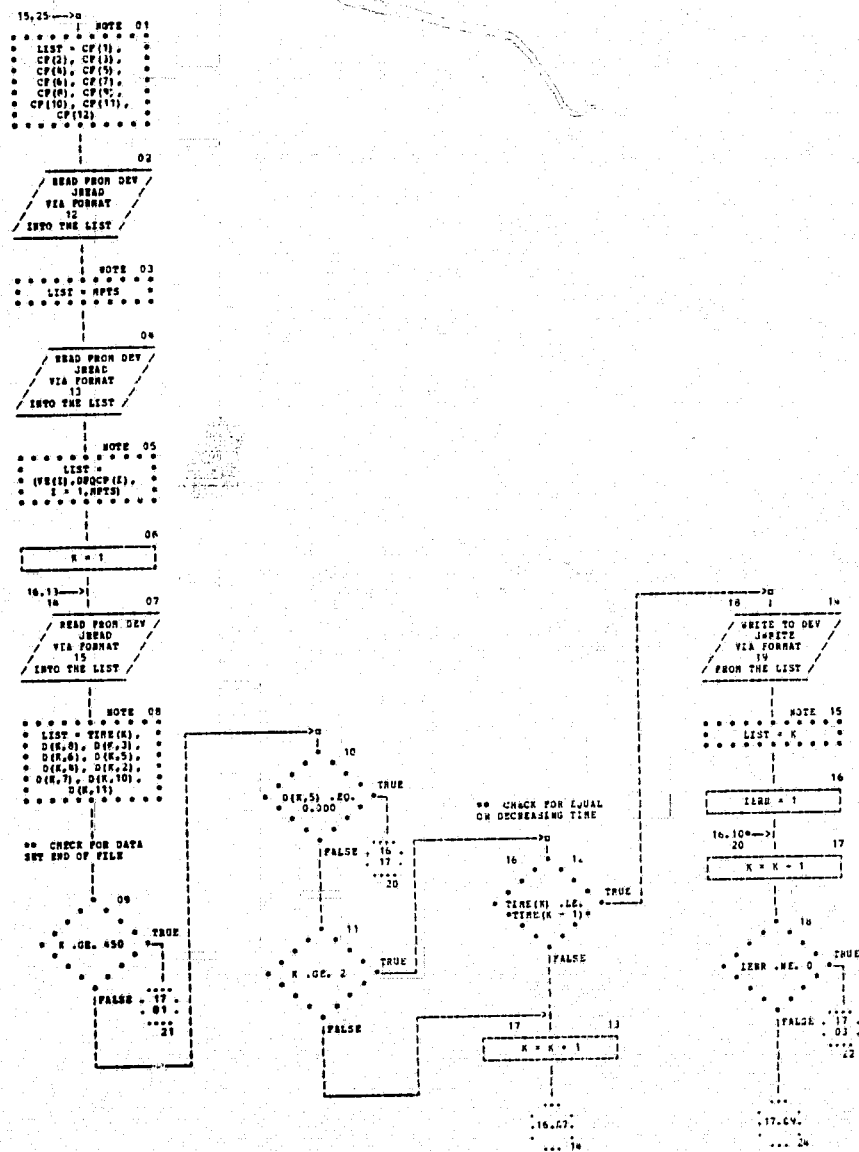


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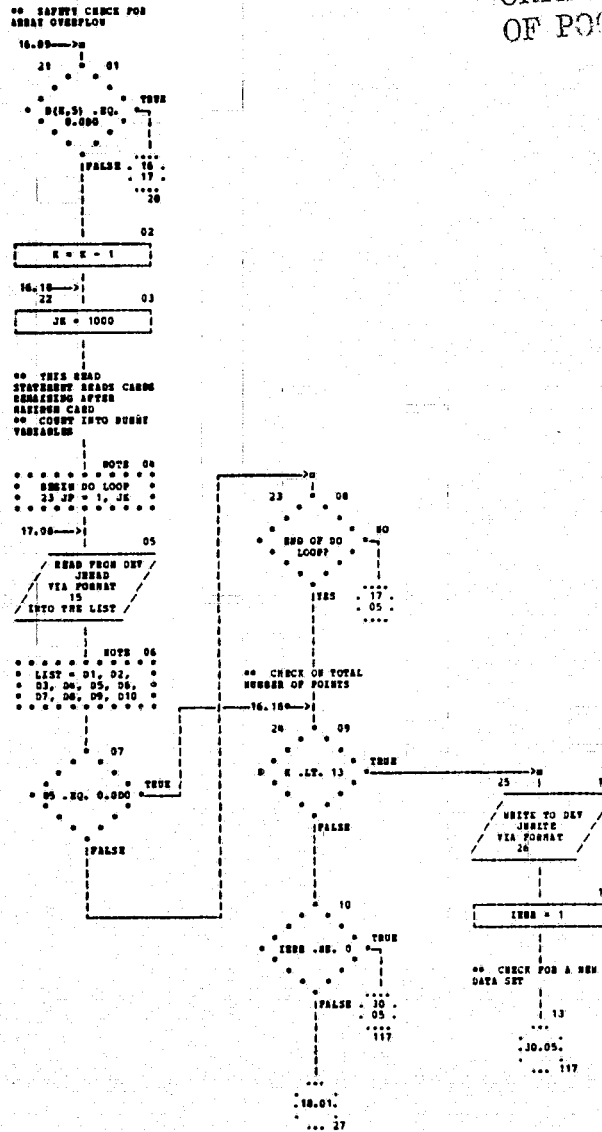


CHART TITLE - PROCEDURES

AUTOFLOW CHART SET -

PPRNT

PAGE 19

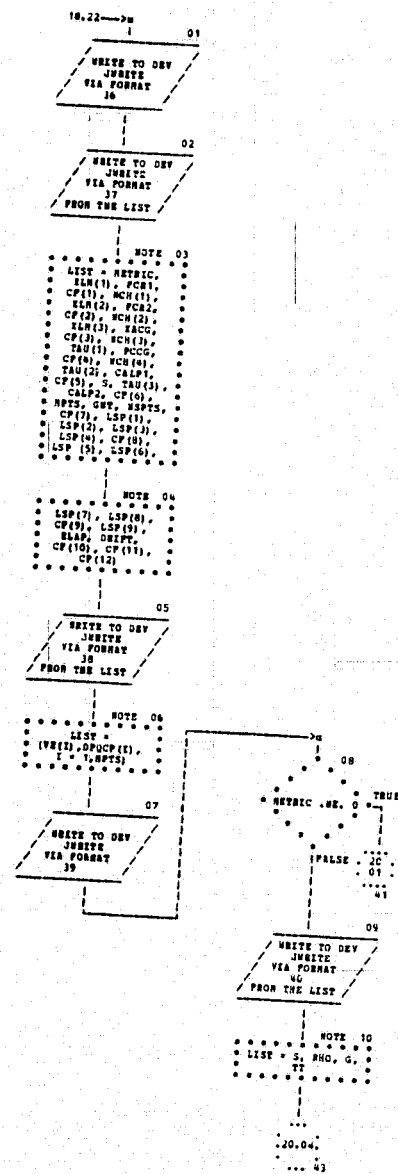
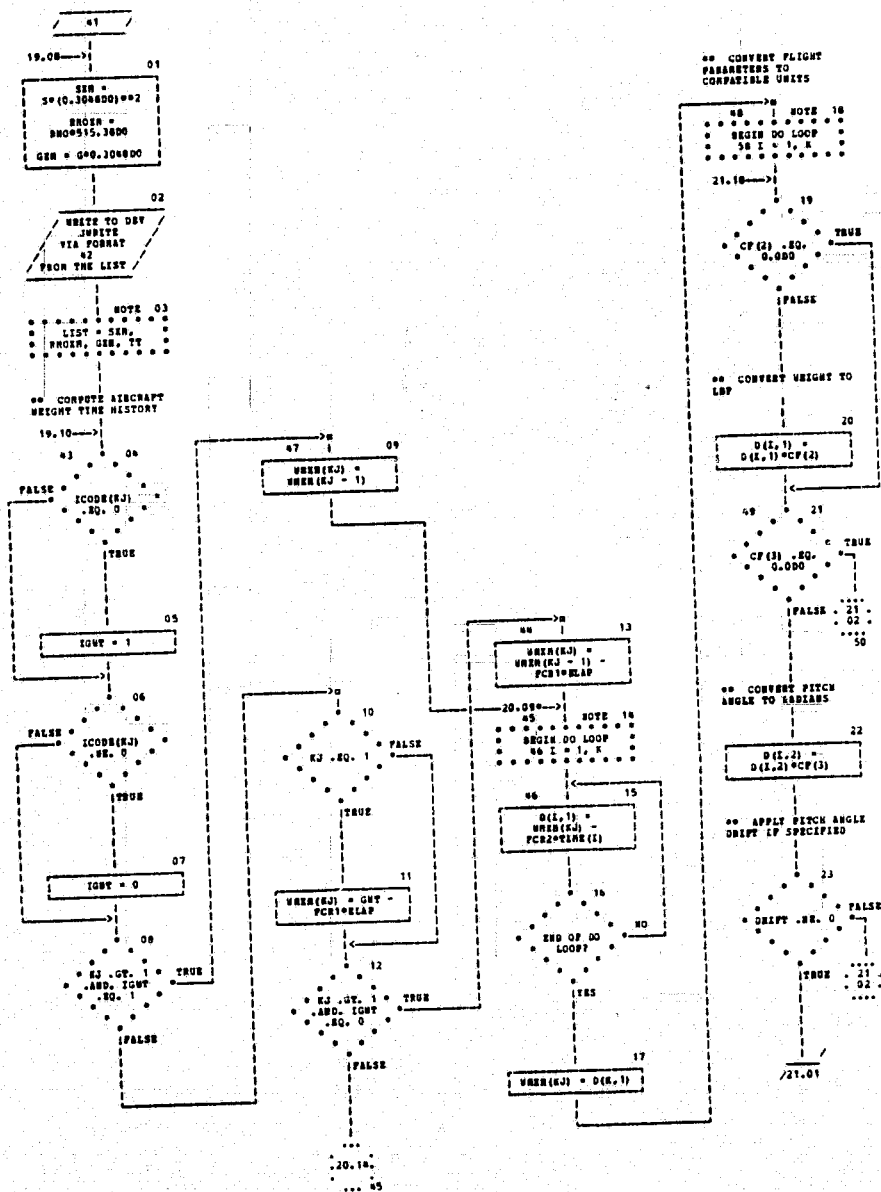


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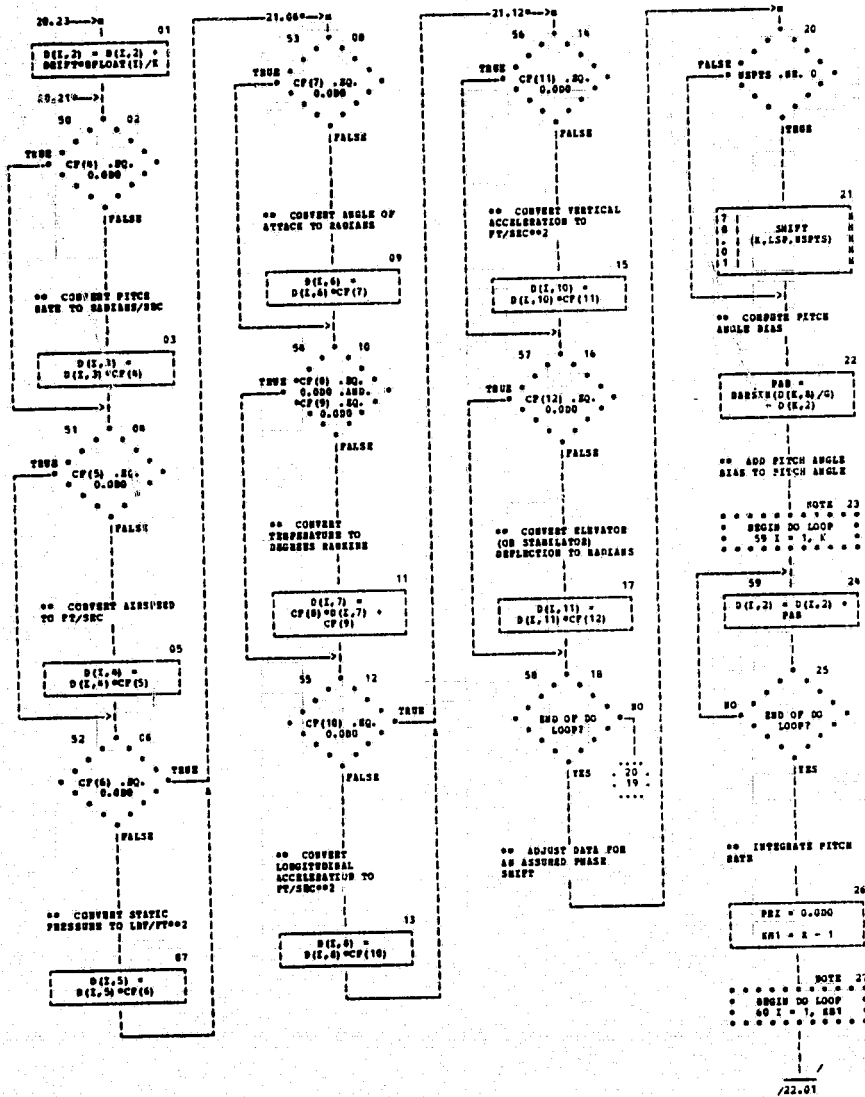
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07001

PAGE 21

CHART TITLE - PROCEDURE





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AUTOFLOW CHART SET -

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PAGE 23

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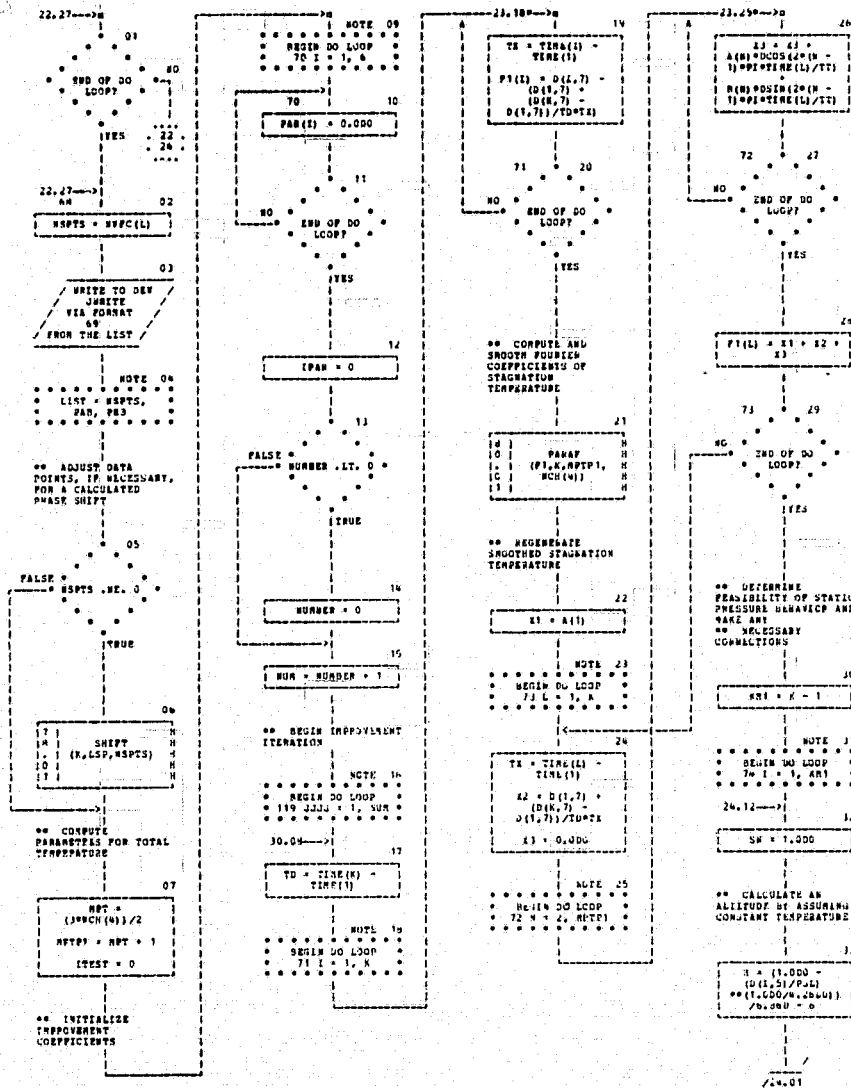


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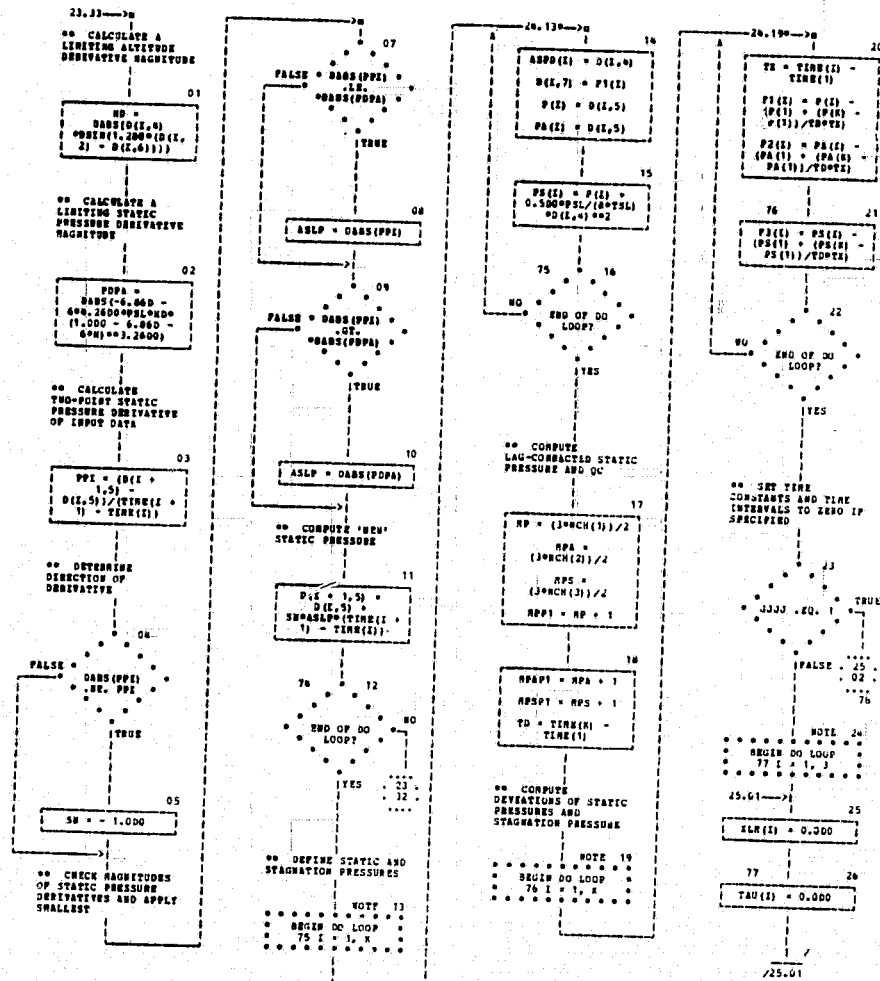


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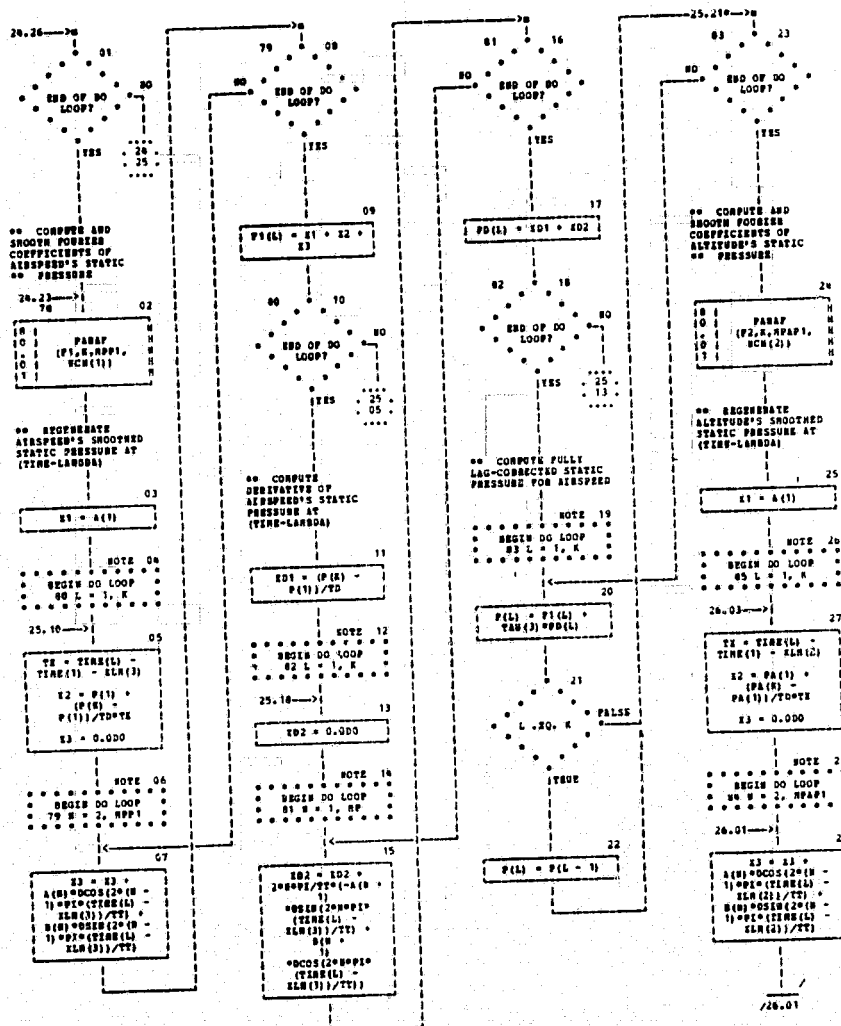
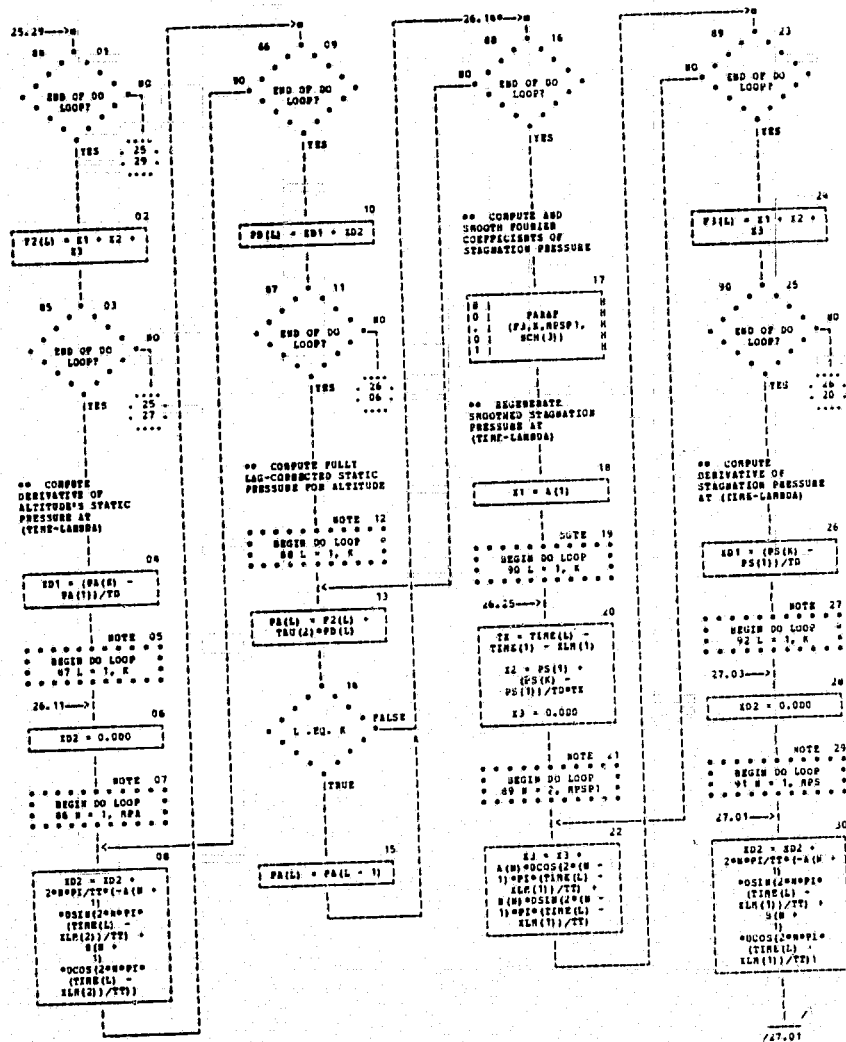


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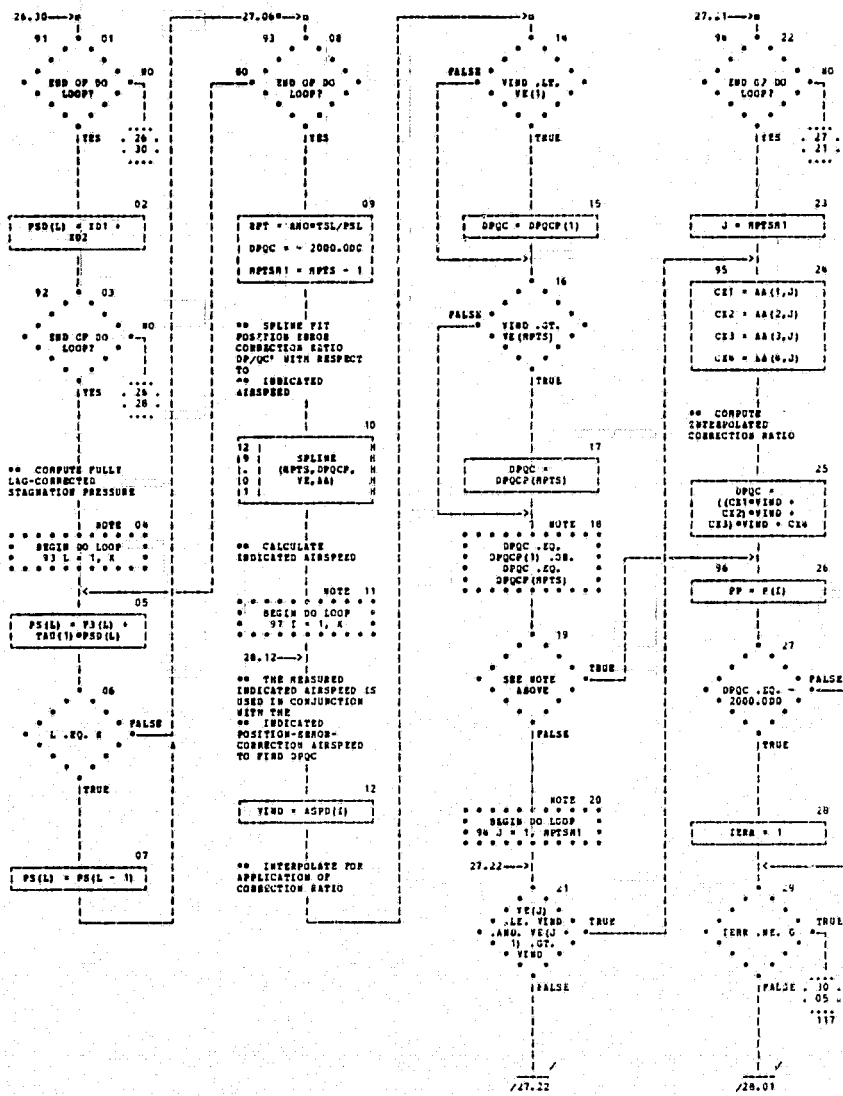


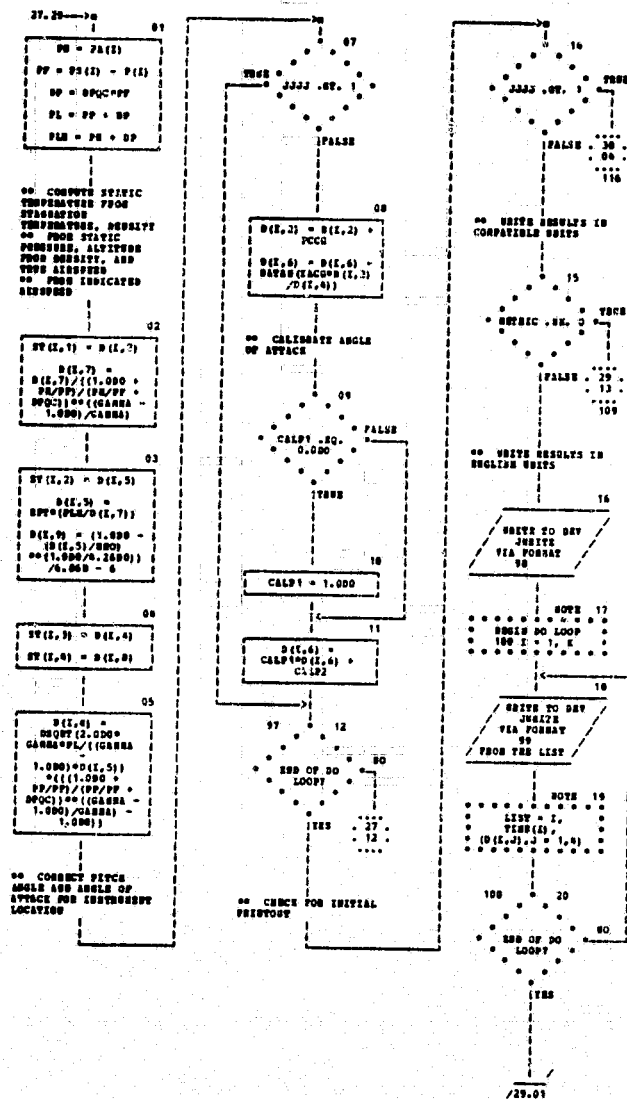
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• **PDH 1**

PAGE 27

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ADDITIONAL CHART SET -

70001

PAGE 29

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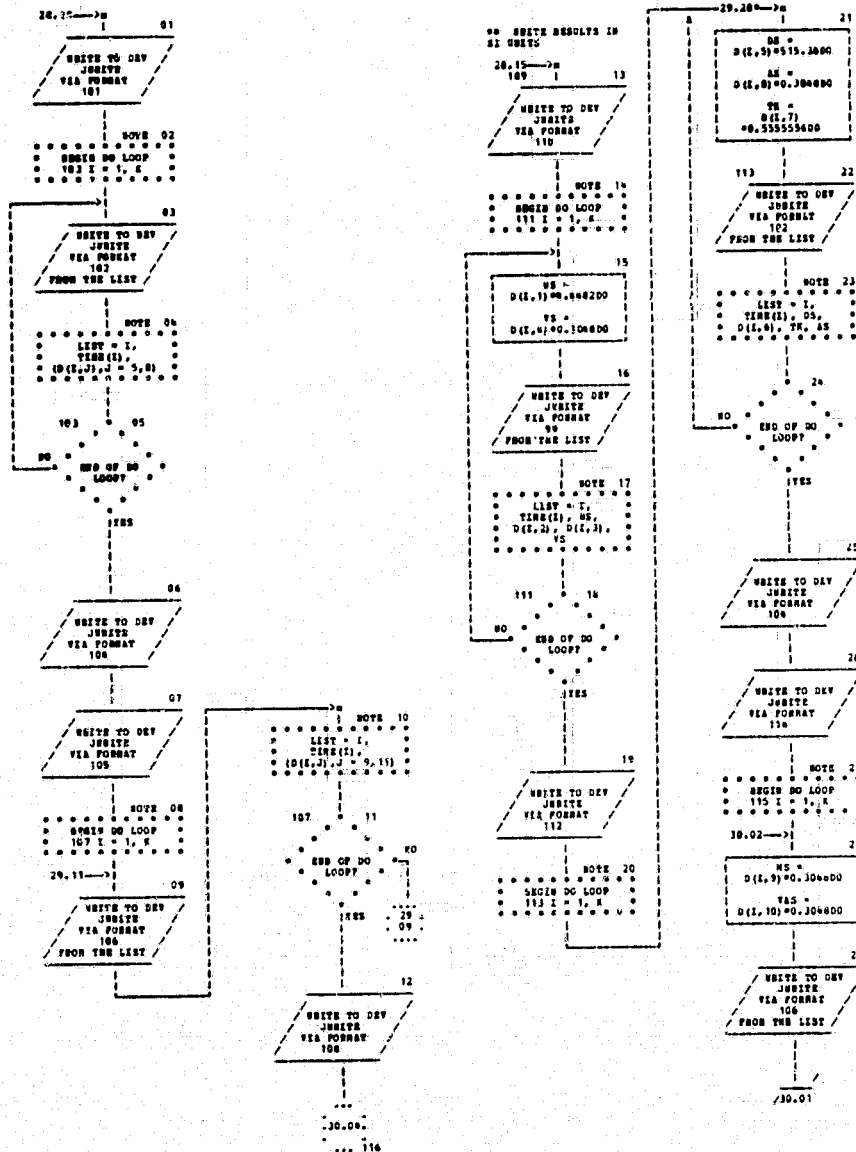


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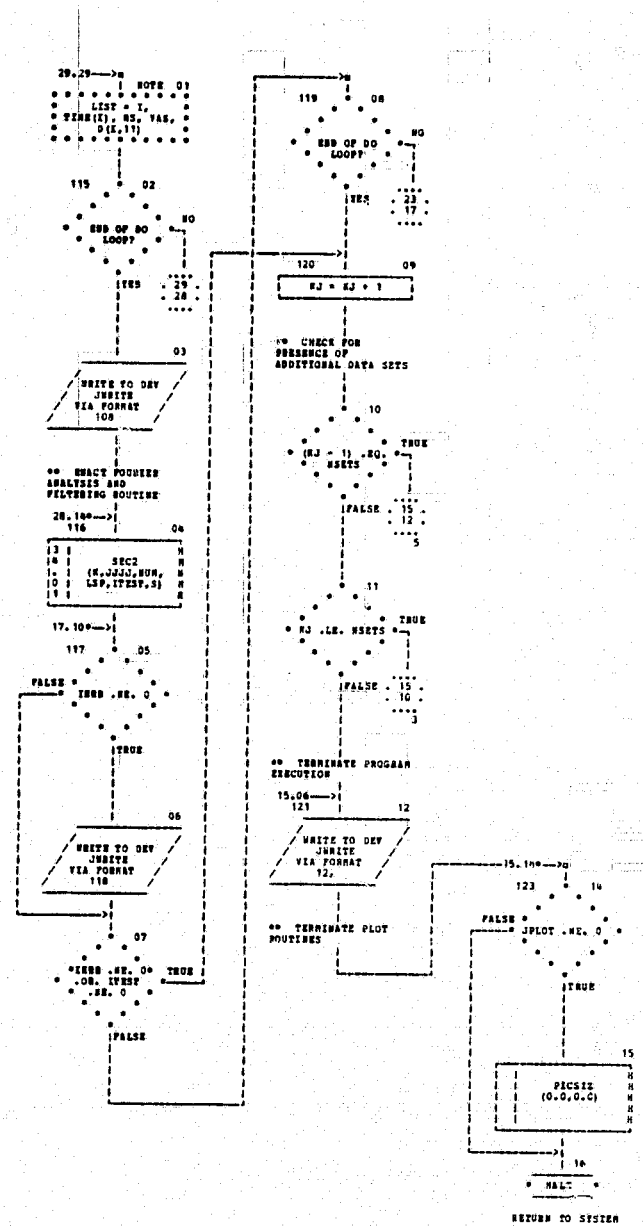
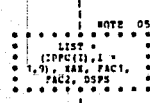
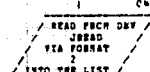
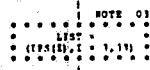
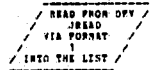
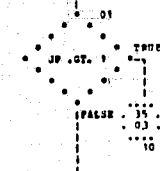


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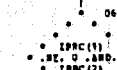
SEC2

30.00-->01
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ANALYSIS AND
** ATTEMPTS TO MAKE
THE DATA MORE
COMPATIBLE

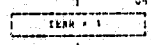
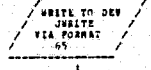
** CHECK OF BYPASS



** CHECK FOR INPUT ERROR



30.10



09
NEXT

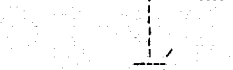
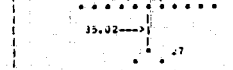
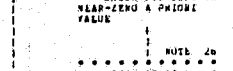
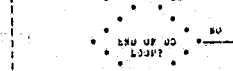
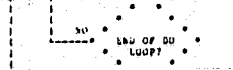
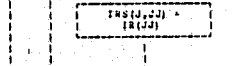
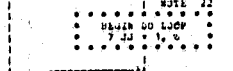
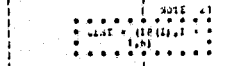
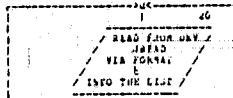
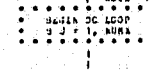
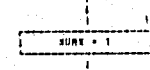
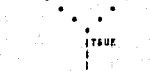
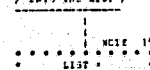
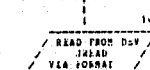
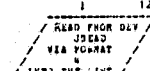
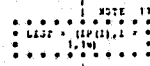
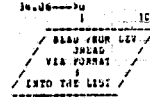
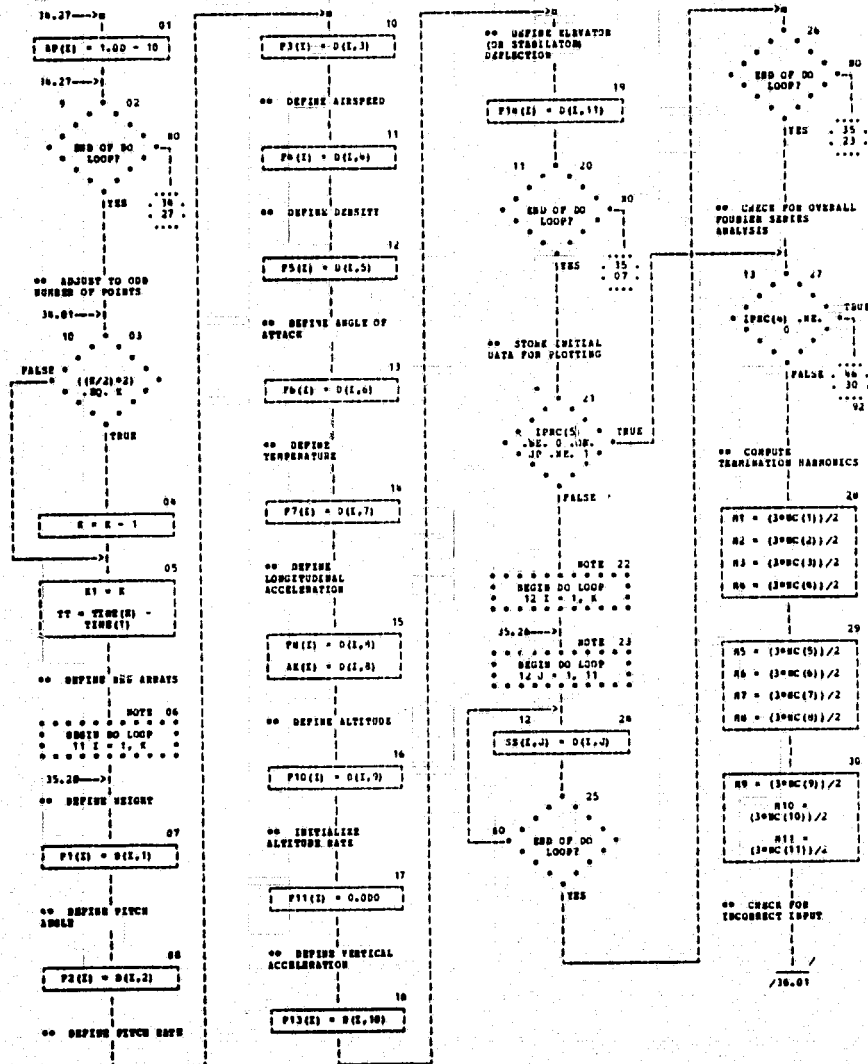


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PAGE 16

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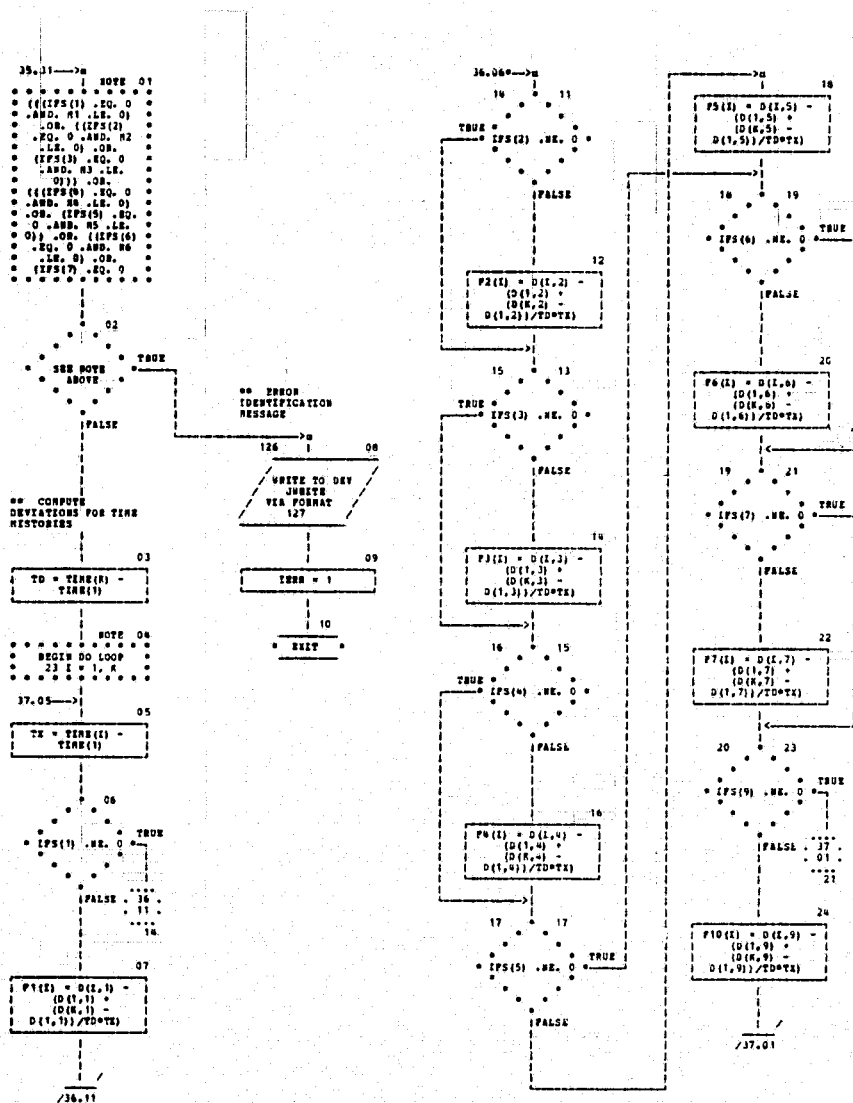
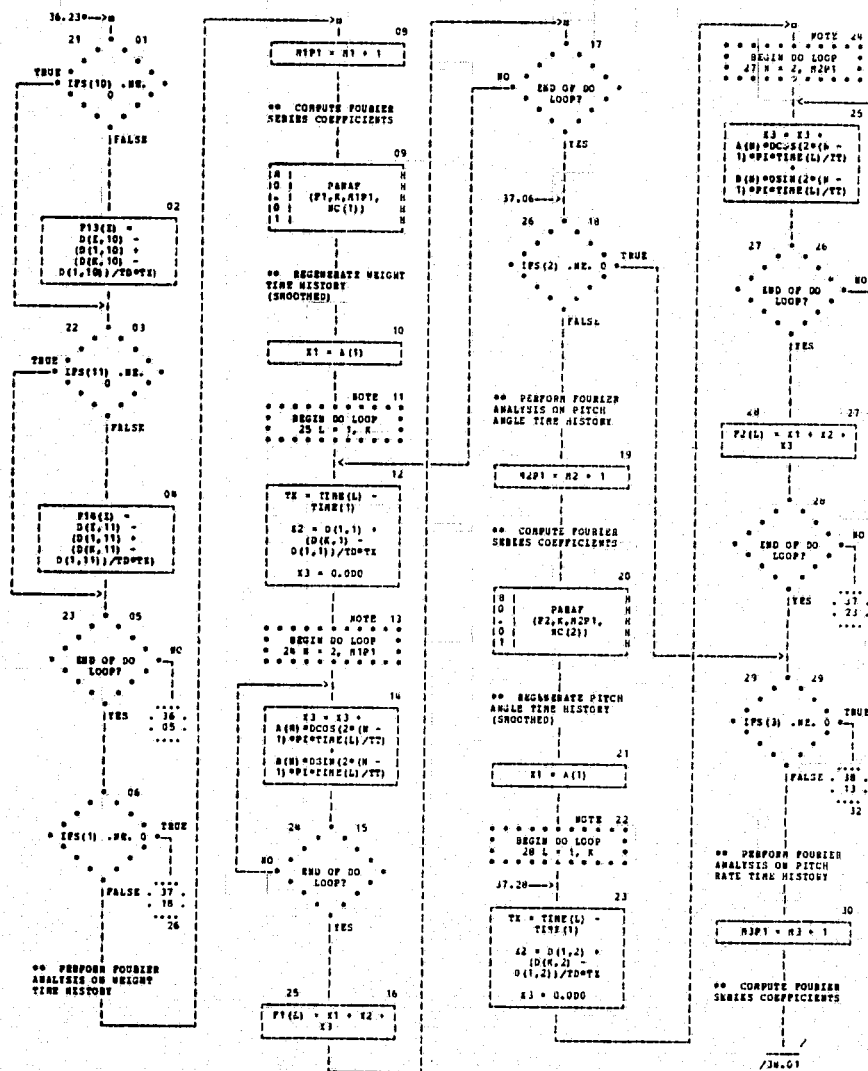


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PAGE 38

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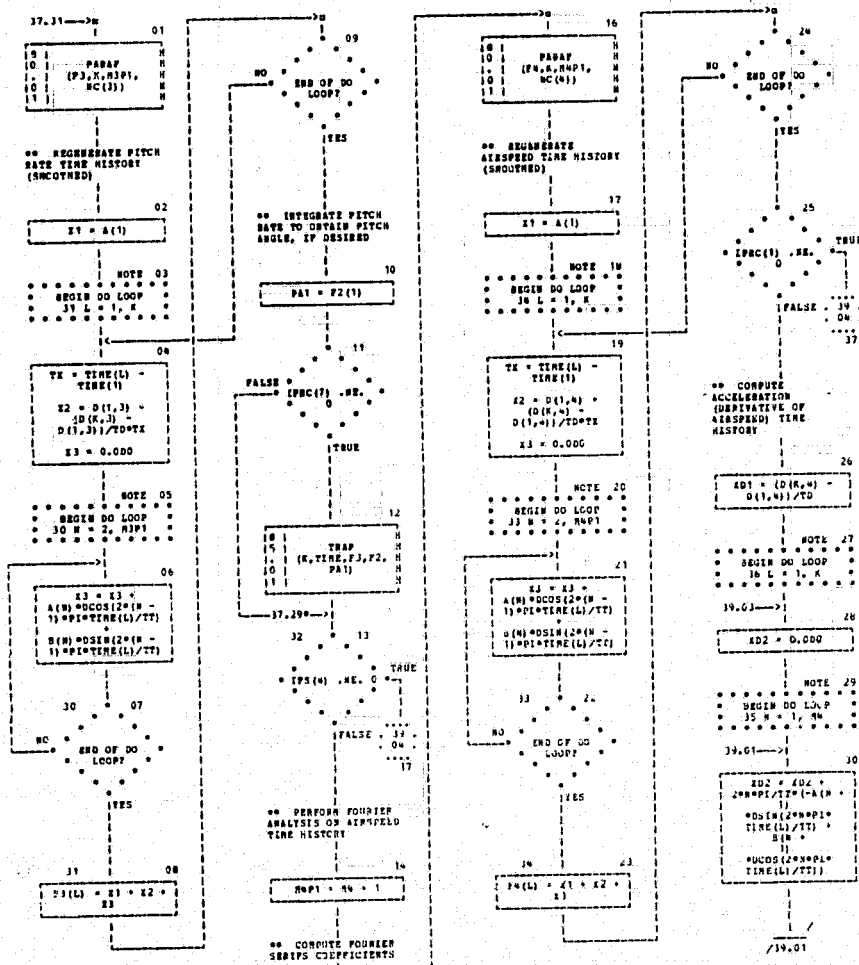
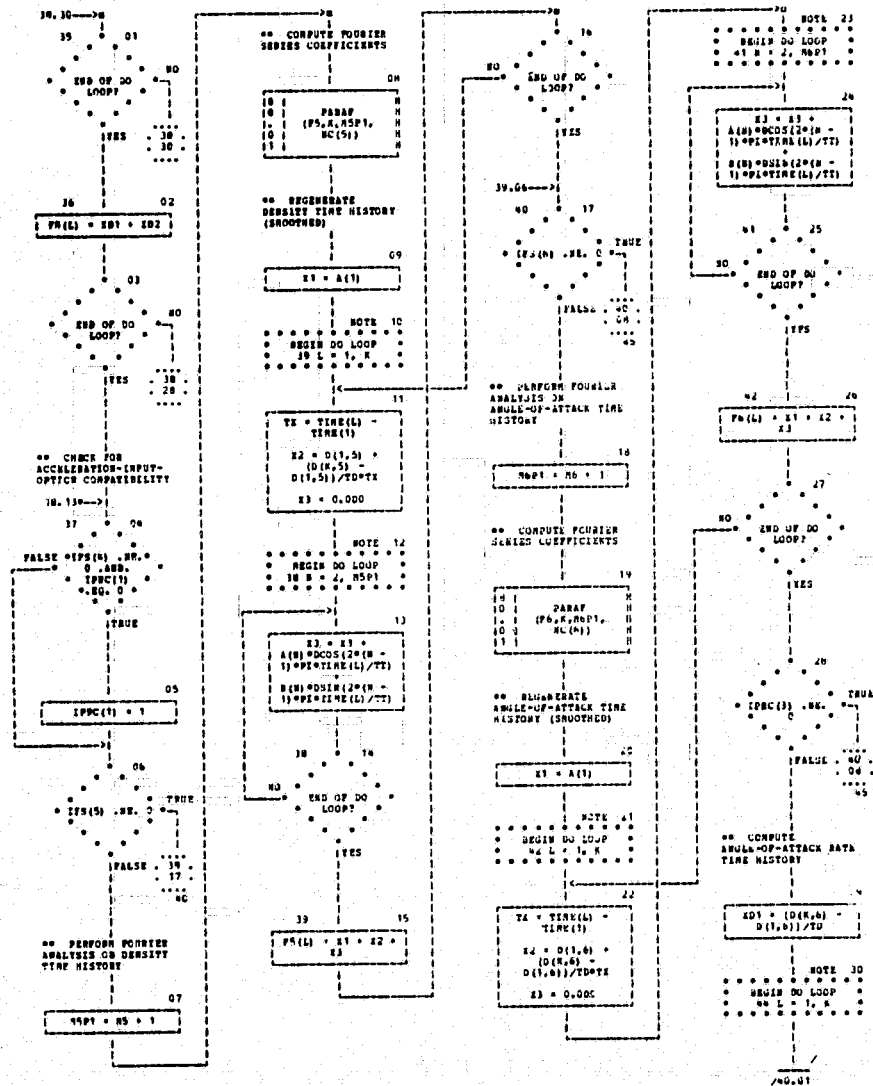


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PAGE 40

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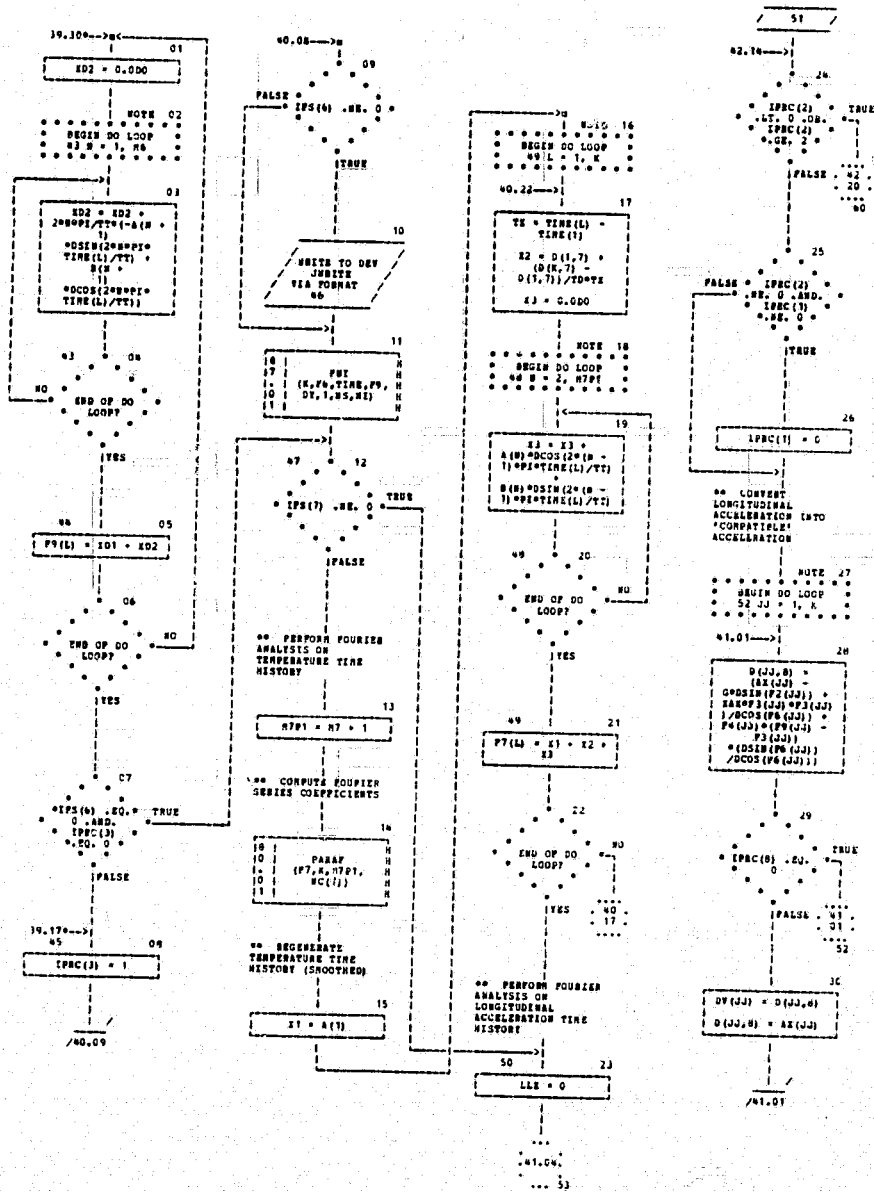


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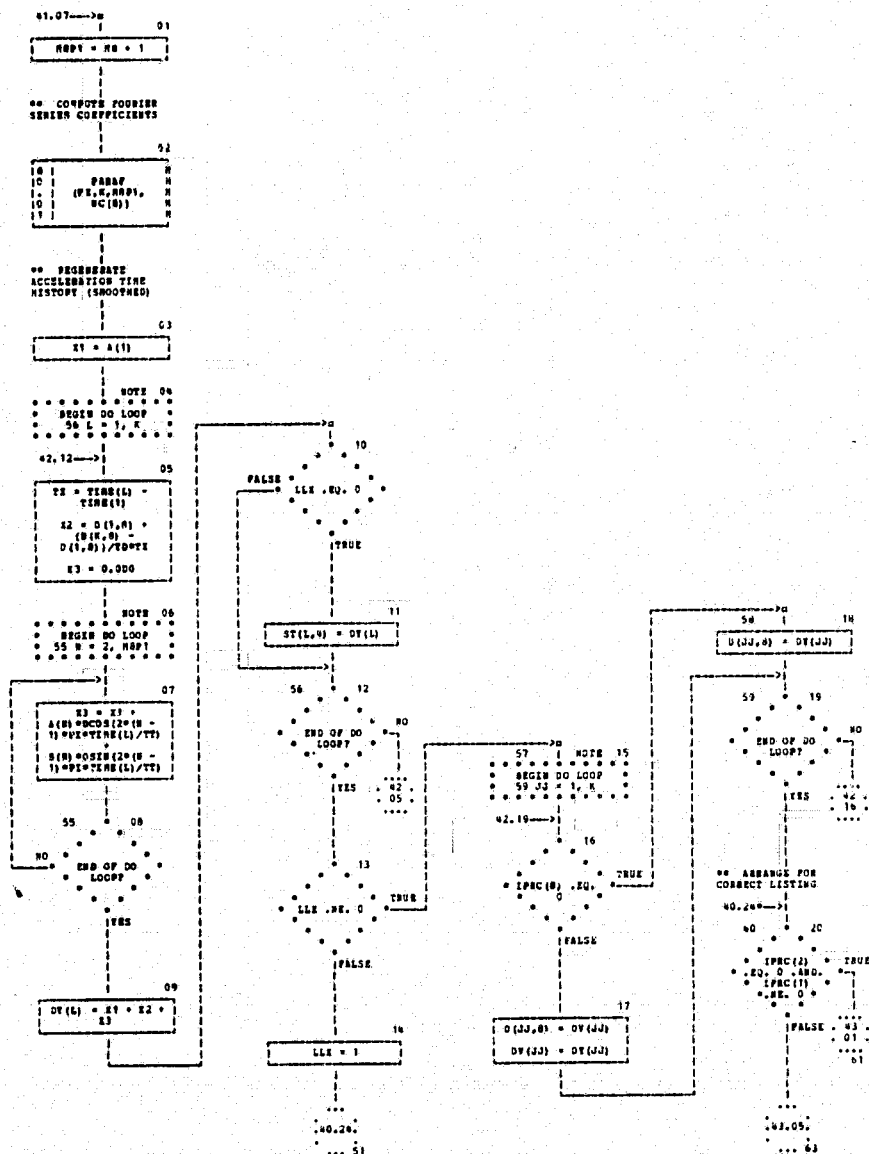
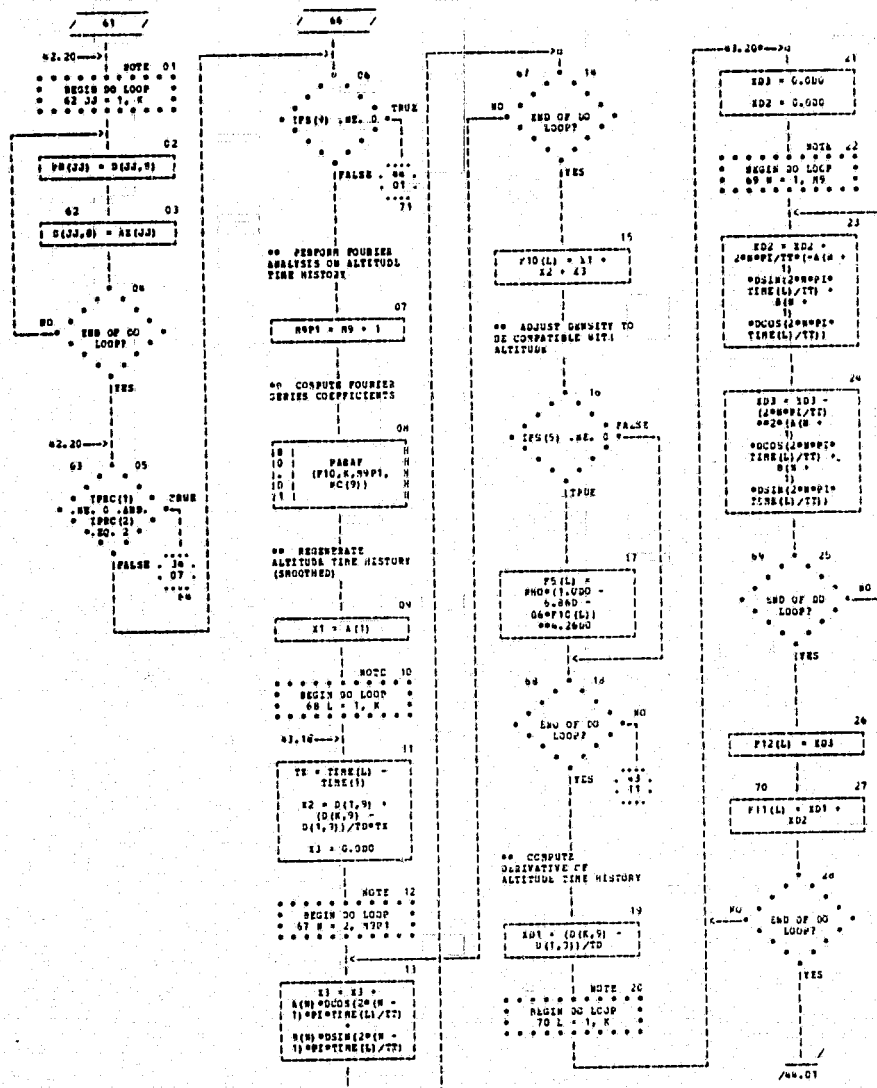


CHART TITLE - SUBROUTINE INC2(K,JF,SUN,SEP,TEST,3)

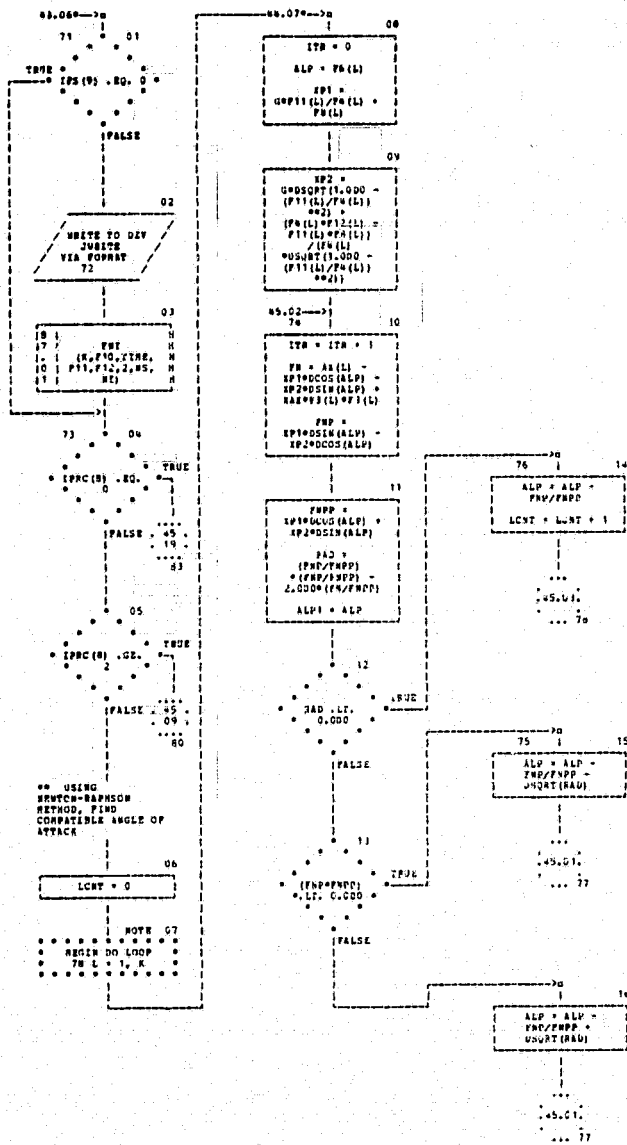


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PAGE 44

CHART TITLE - SUBROUTINE SEC2 (K,JP,HUN,LSP,ITEST,SI)

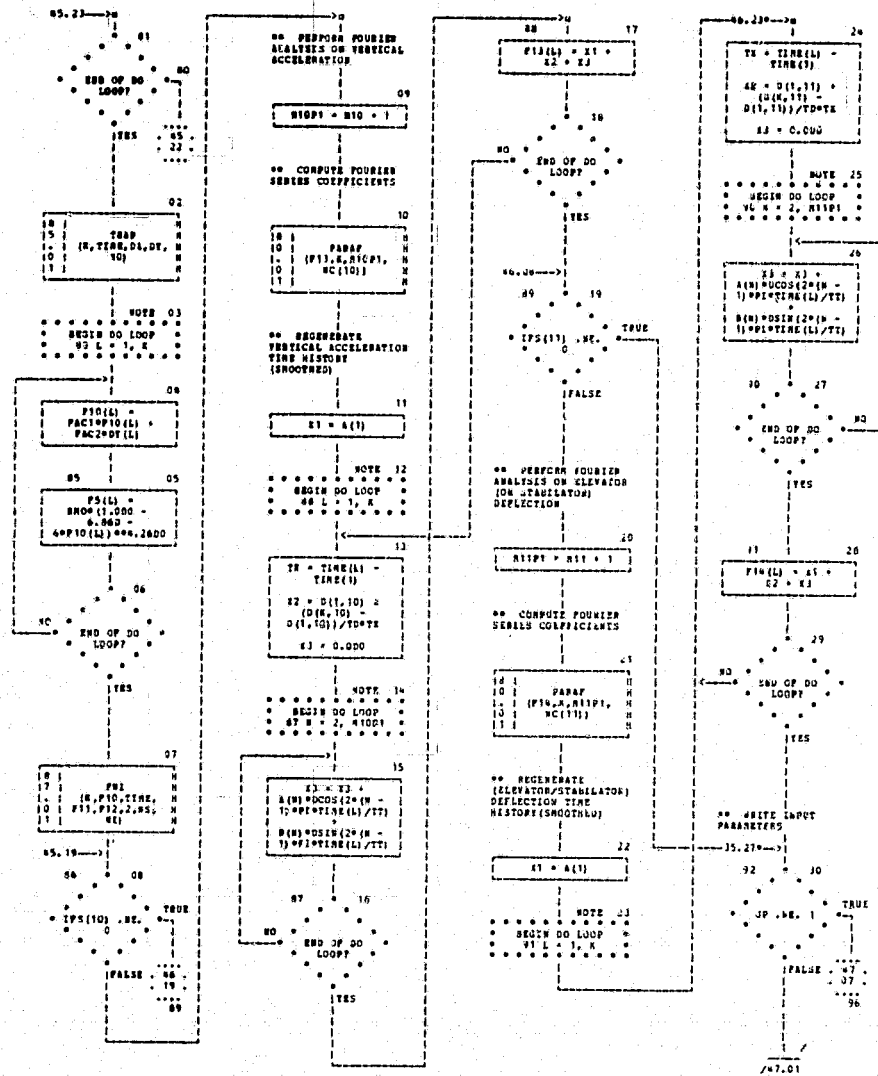


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PAGE 40

CHART TITLE - SUBROUTINE SOC2 (N,JP,MUM,LSO,ITEST,3)



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PAGE 47

CHART TITLE - SUBROUTINE SMC2(R,JP,SUB,LSP,ITERST,S)

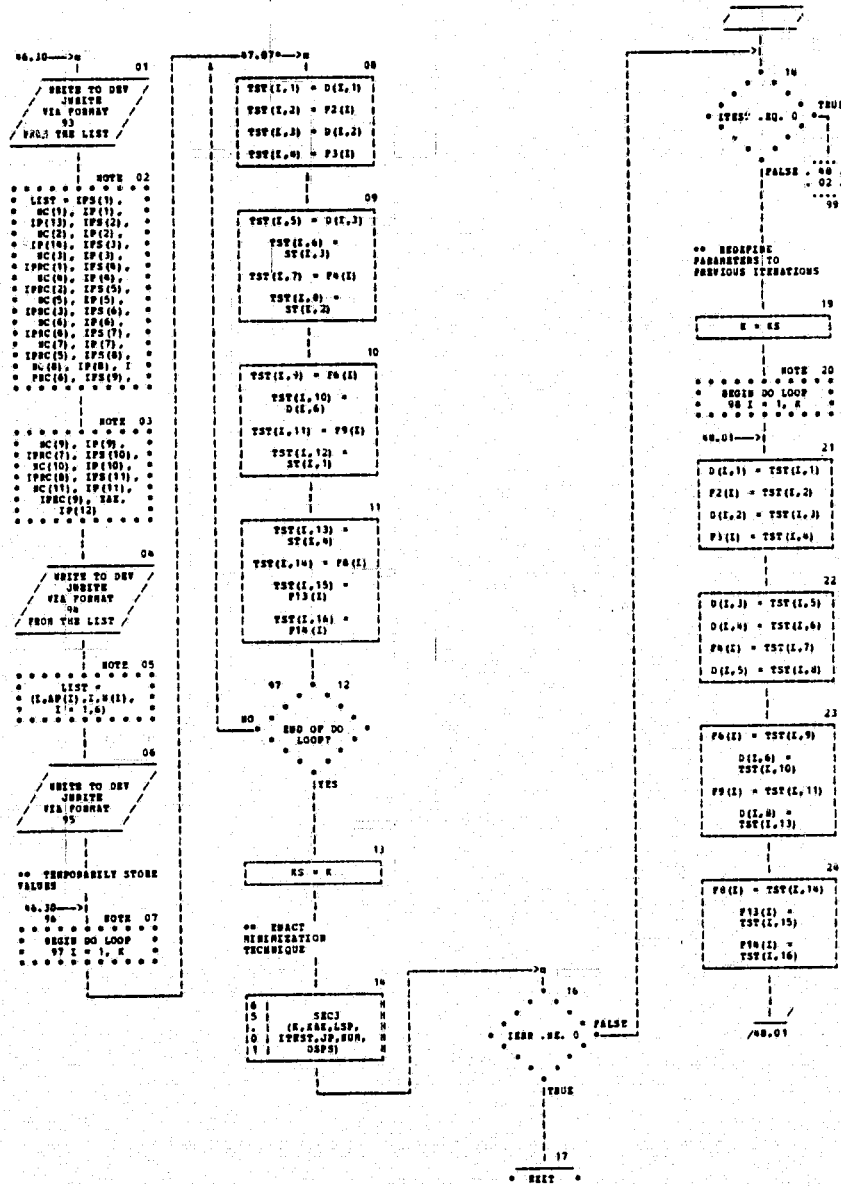


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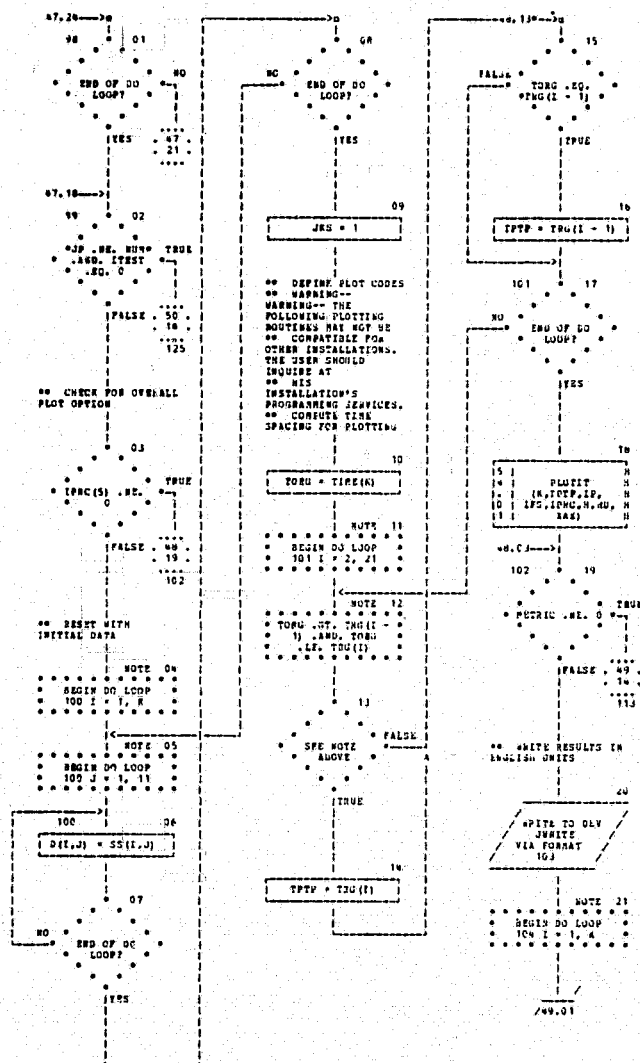
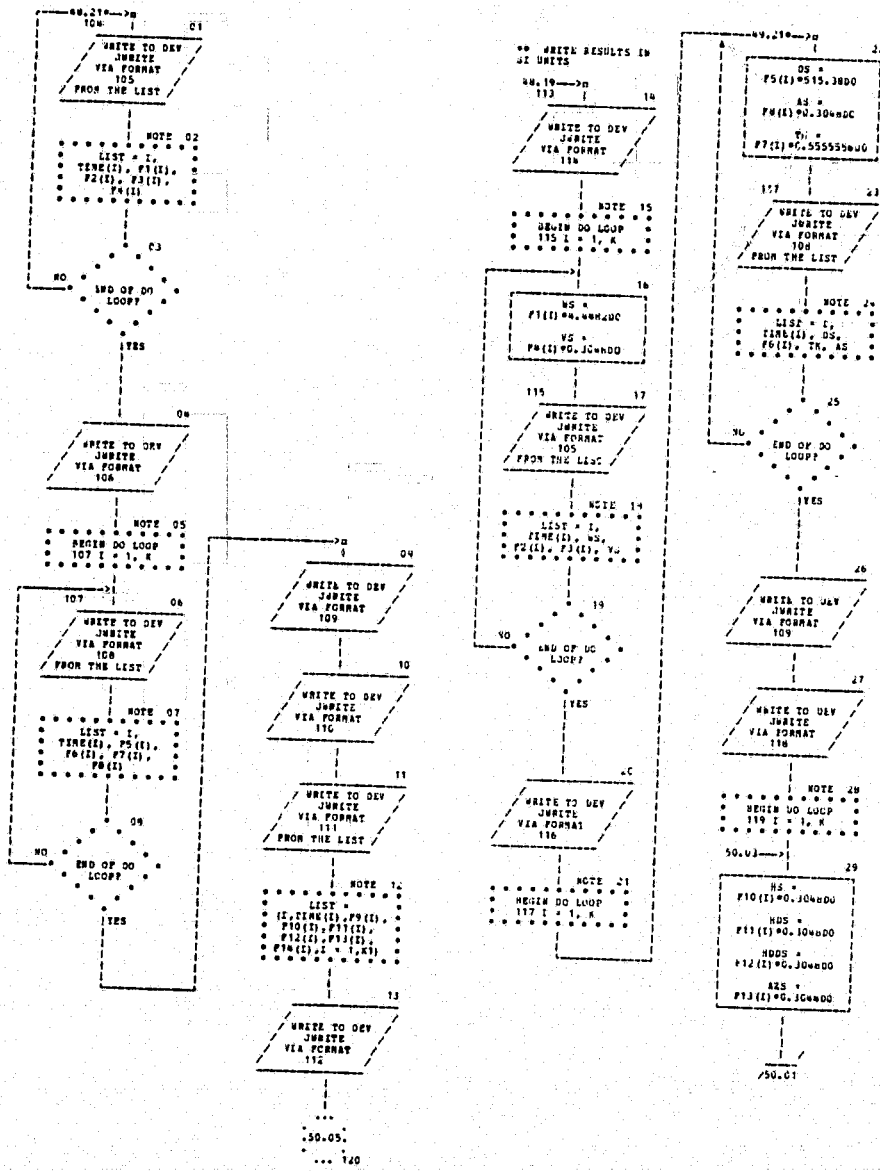


CHART TITLE - SUBROUTINE SRC2 (N,JP,NUN,LSP,ITEST,5)



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PAGE 50

CHART TITLE - SUBROUTINE SEC2(N,JP,MUR,LSP,TEST,3)

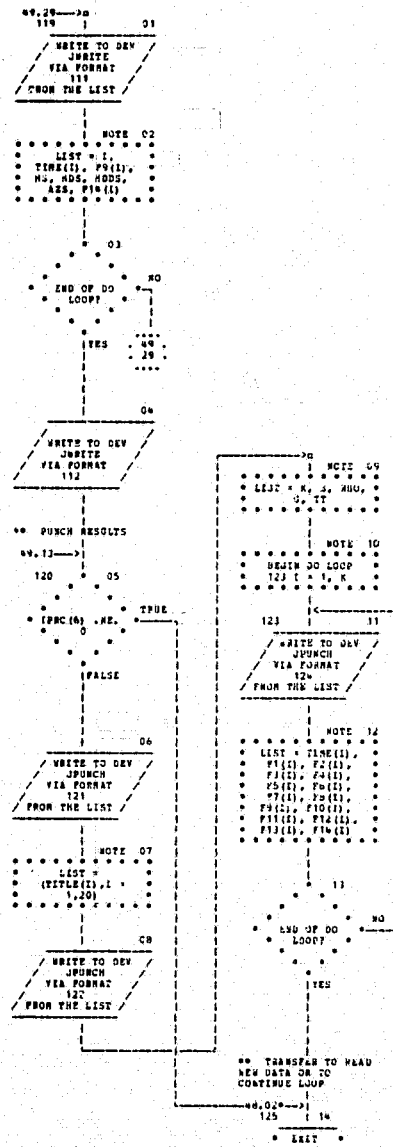
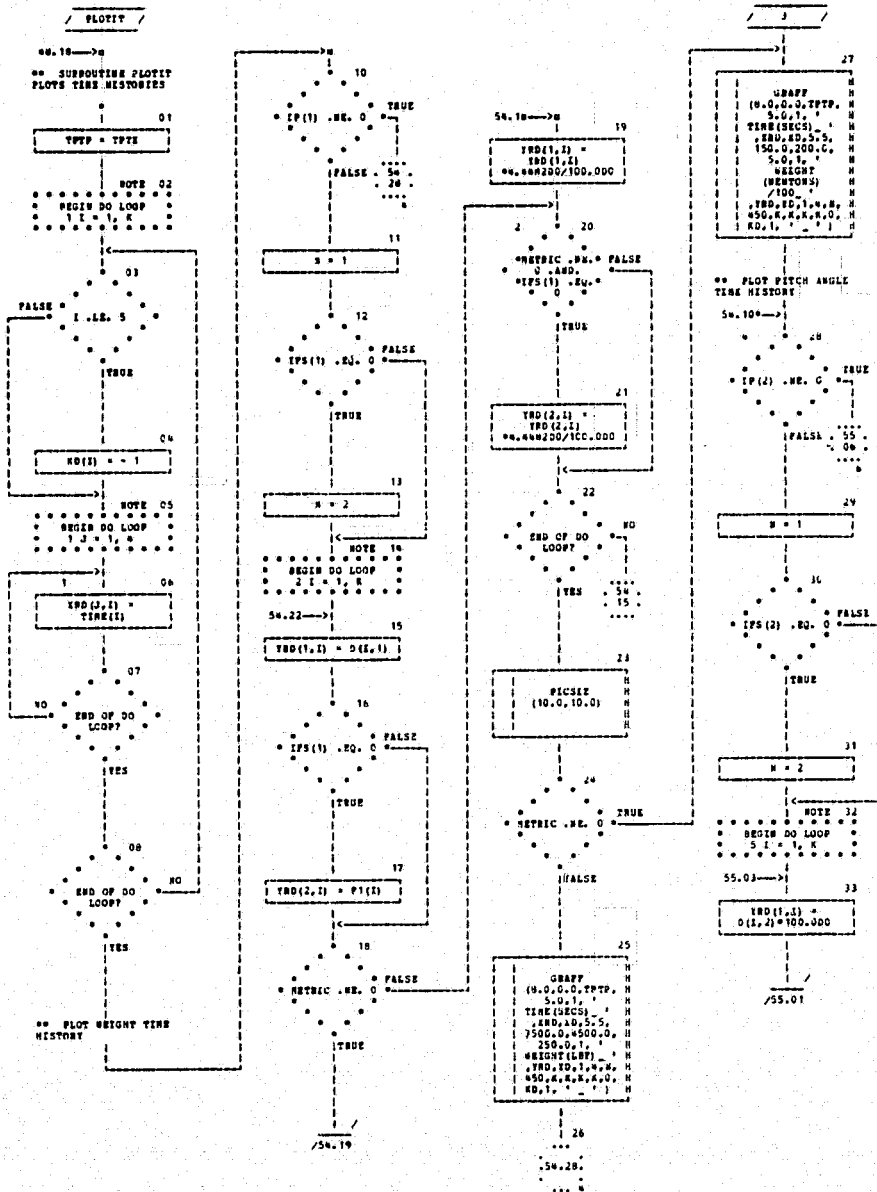


CHART TITLE - SUBROUTINE PLOTIT(N,TPTI,IP,IPS,IPRC,N,ND,KAE)



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PAGE 55

CHART TITLE - SUBROUTINE PLOTIT(E,TPTT,IP,IPS,IPRC,N,ND,EAS)

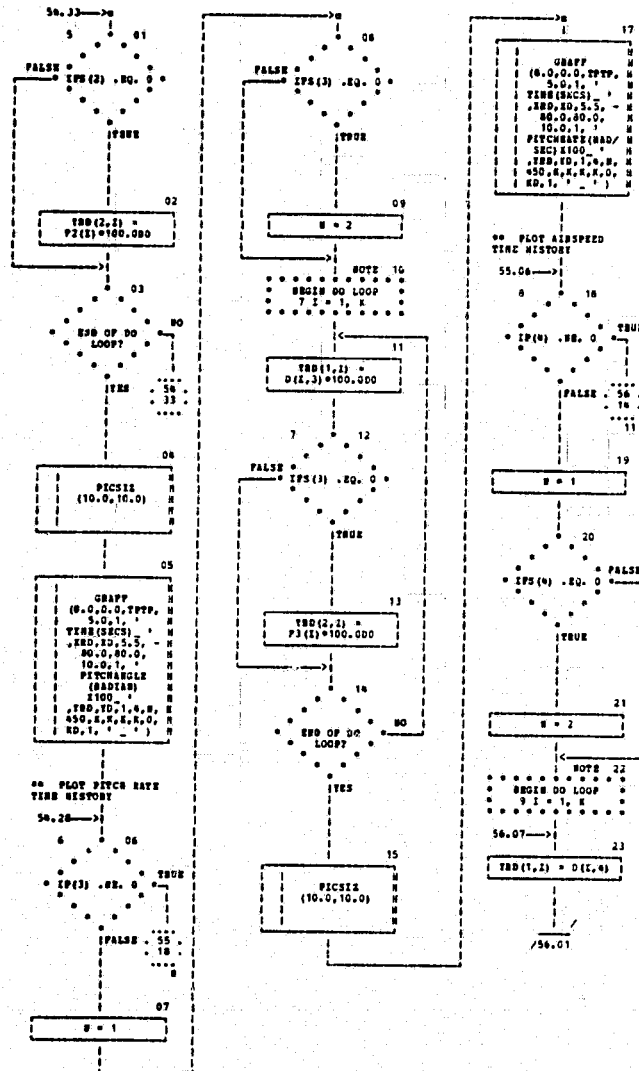
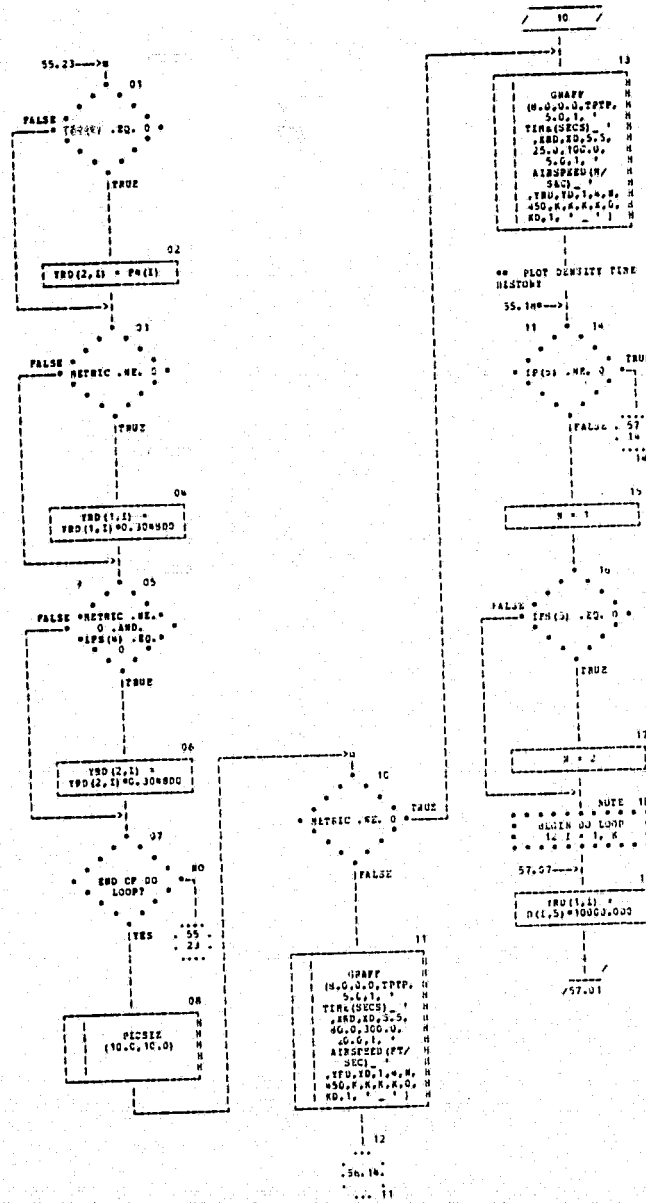


CHART TITLE - SUBROUTINE PLOTIT(N,TPTF,IP,LPS,IPRC,N,ND,XAS)

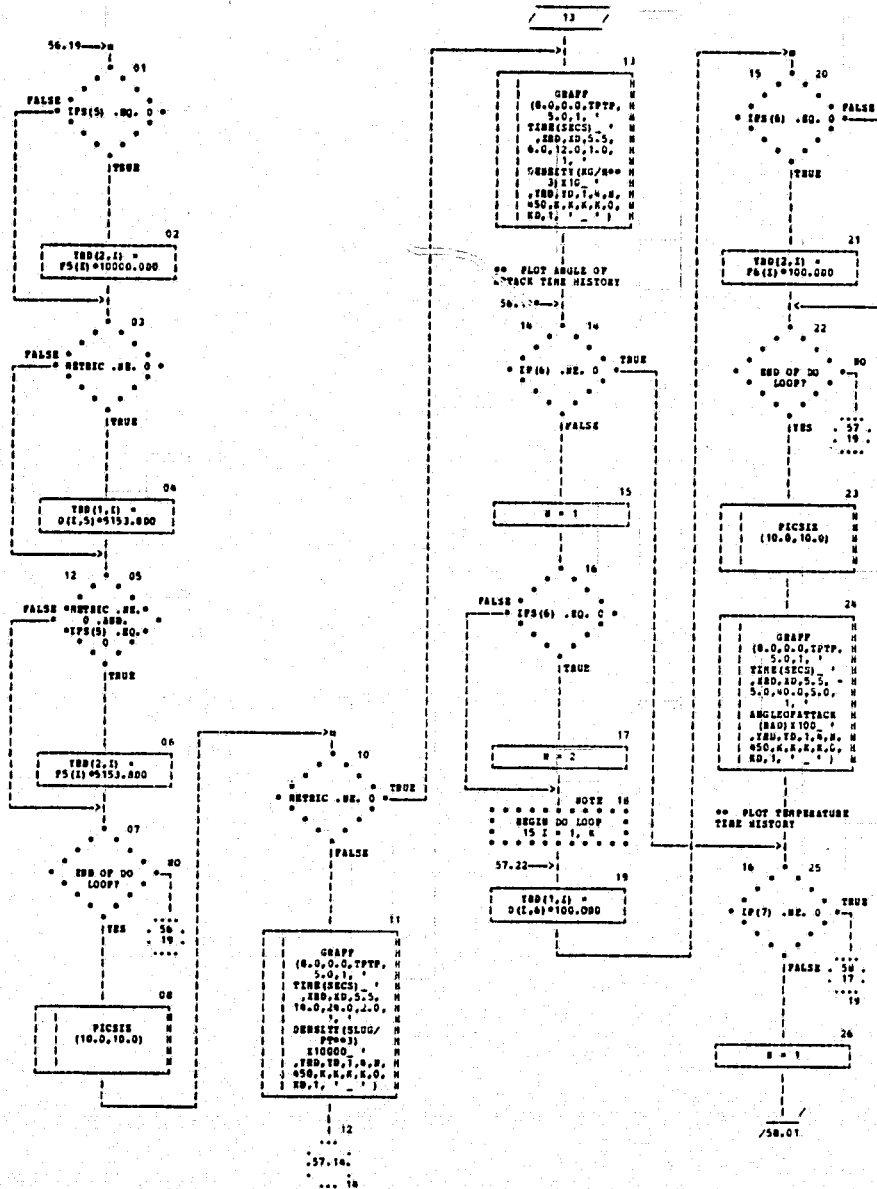


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PAGE 57

CHART TITLE - SUBROUTINE PLOTIT(N,TPH,IP,IPS,IPDC,N,NB,IAI)



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CHART TITLE - SUBSYSTEM FLOTIT(K,TYPE,IP,IPS,IPRC,M,NO,IAS)

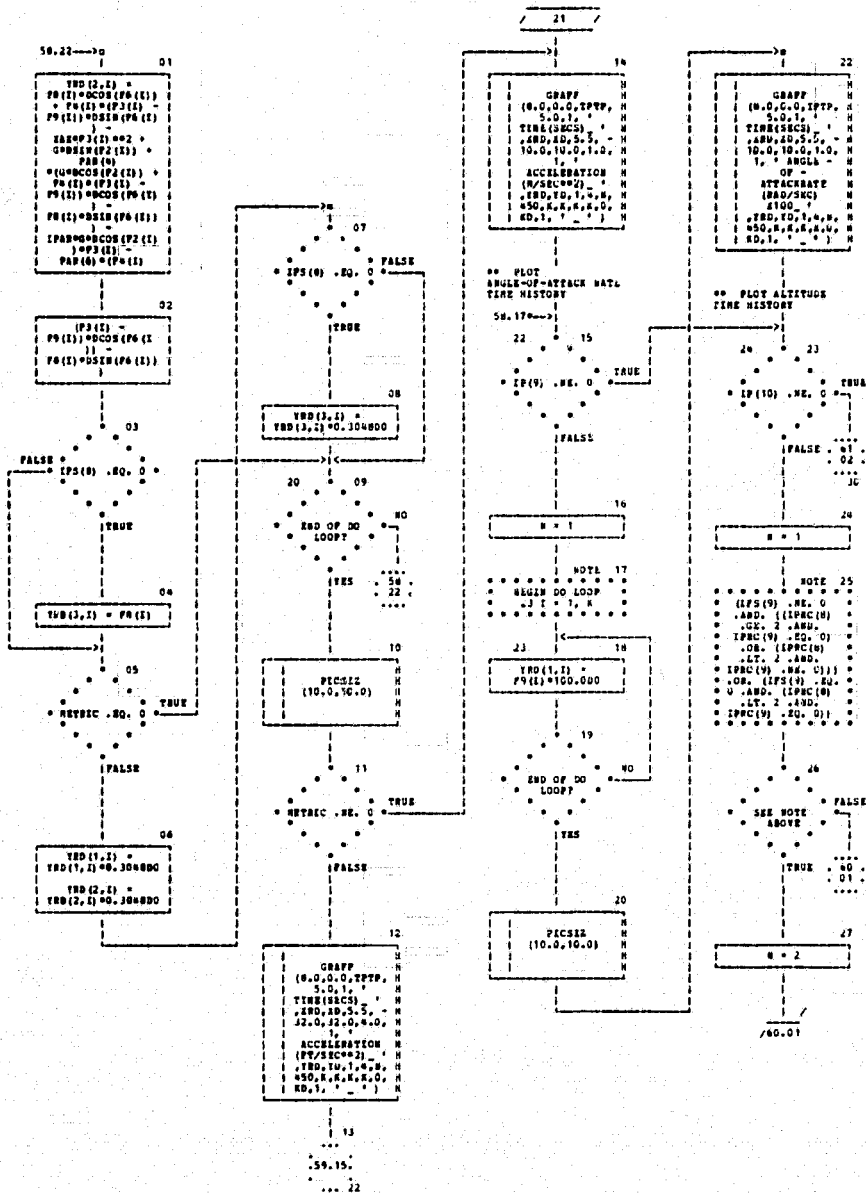
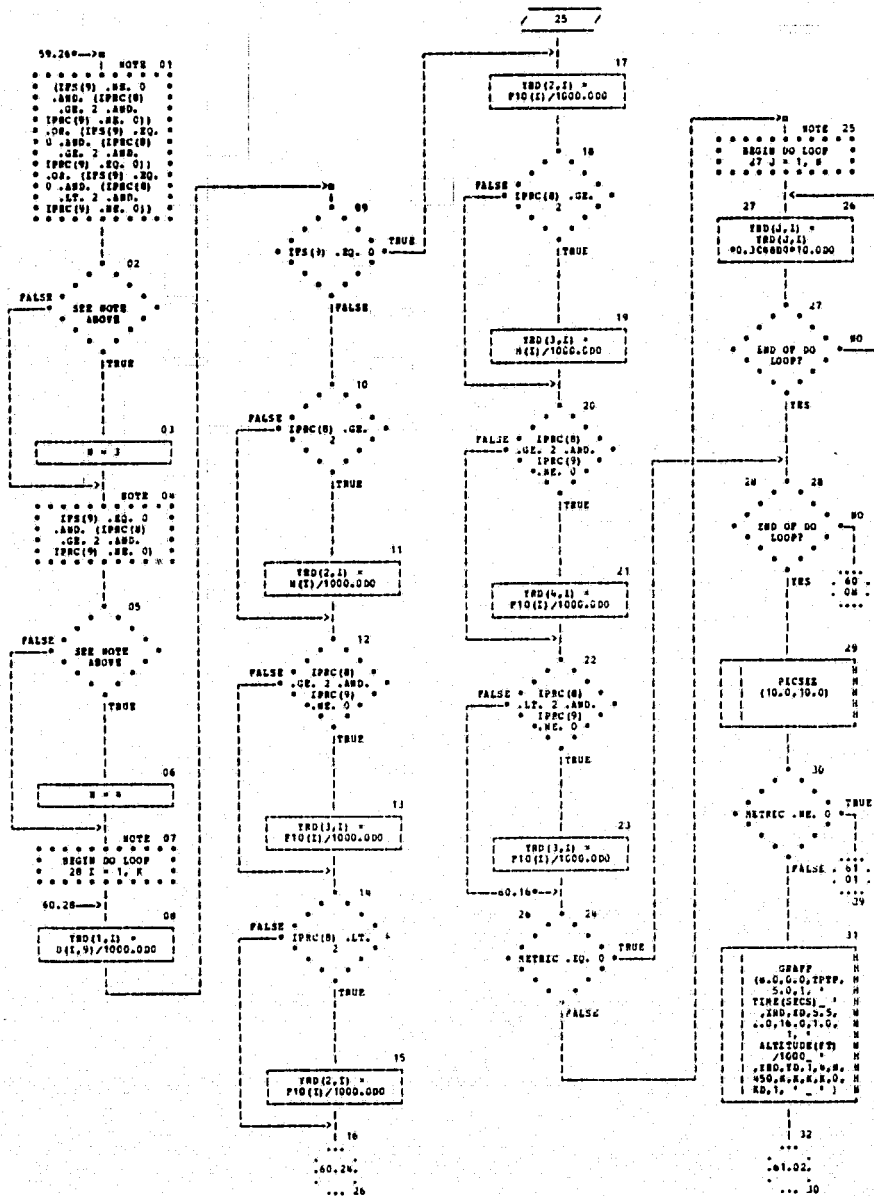


CHART TITLE - SUBROUTINE PLOTIT(R,TPTR,IP,IPS,IPRC,N,NO,IAK)



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CHART TITLE - SUBROUTINE PLOTIT (N,TPTR,IP,IPR,IPRC,N,NO,ZAS)

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PAGE 61

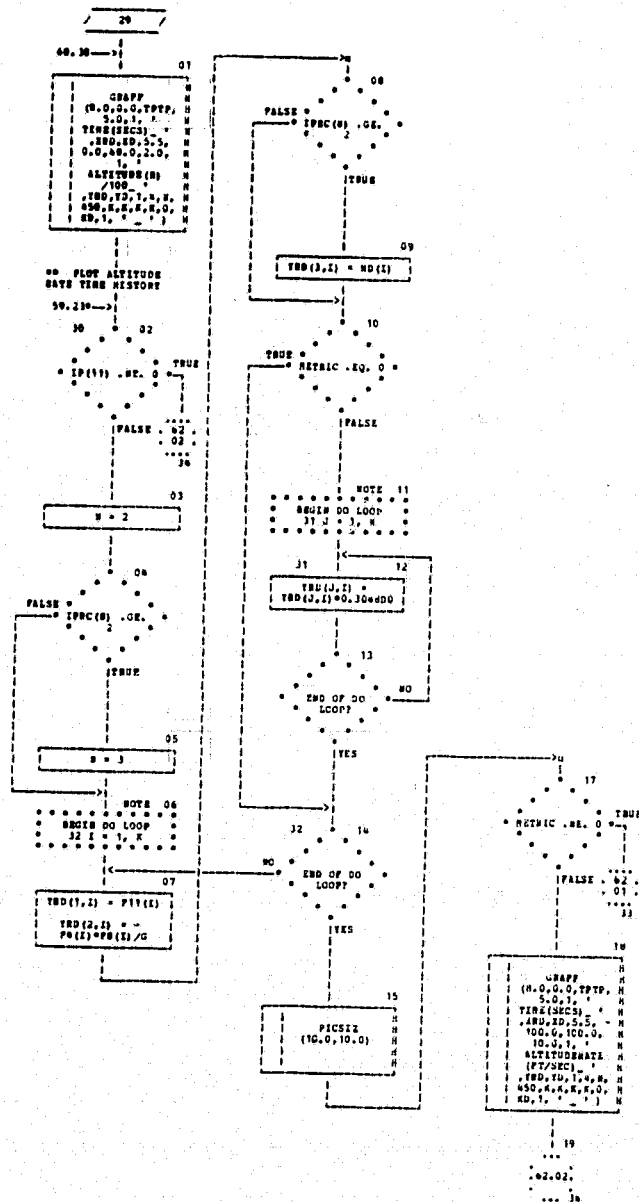
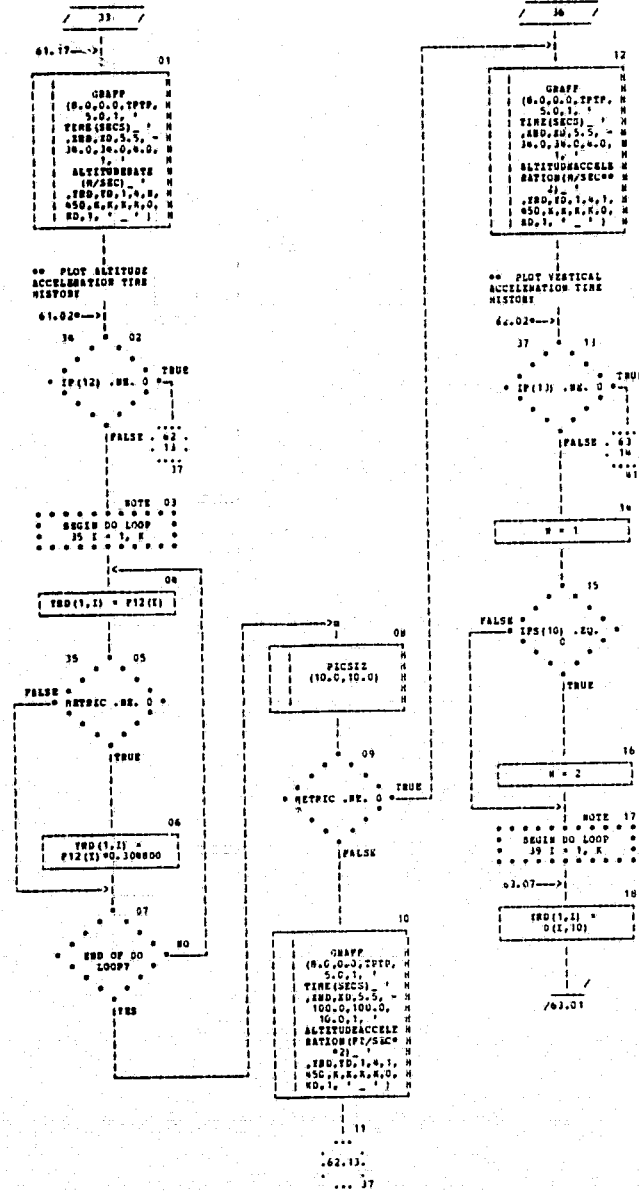


CHART TITLE - SUBROUTINE PLOT1(L,IP1,IP,IP3,IP3C,N,NO,IAS)



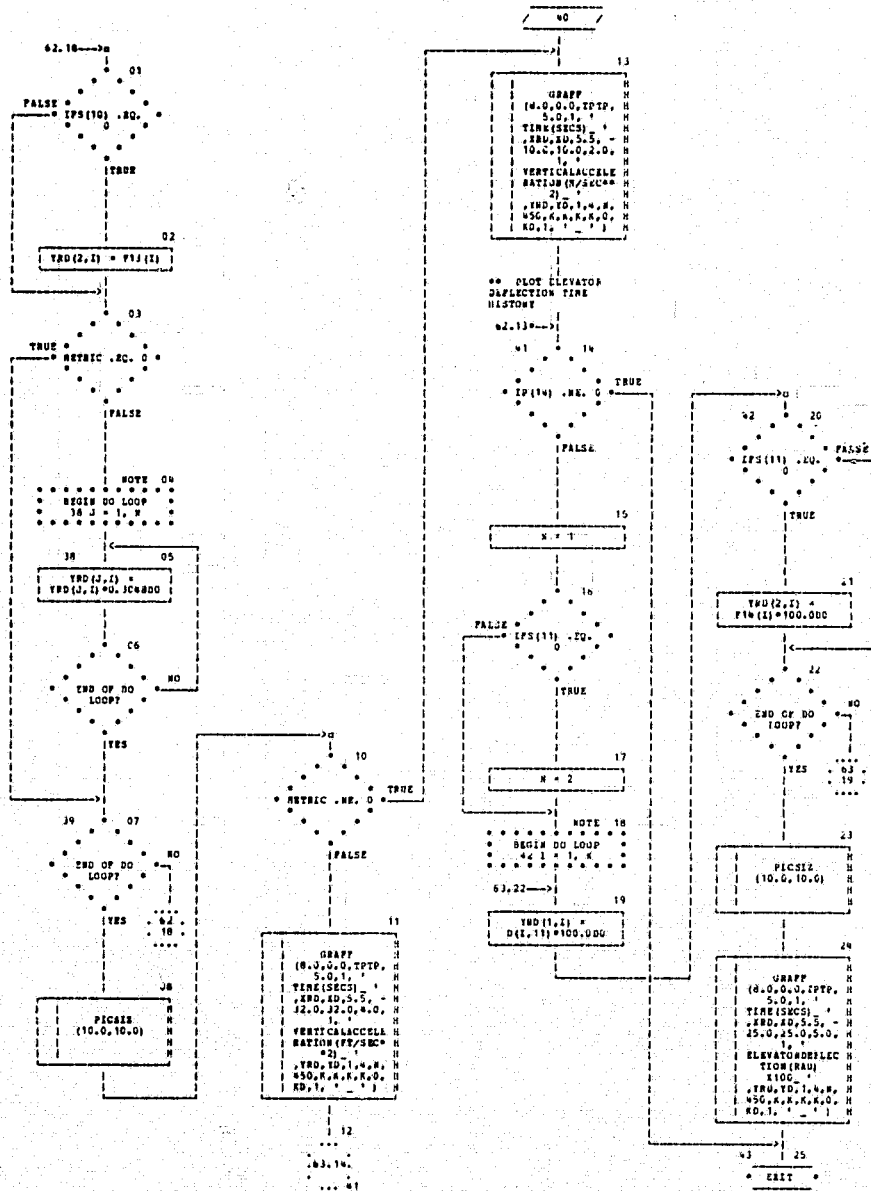
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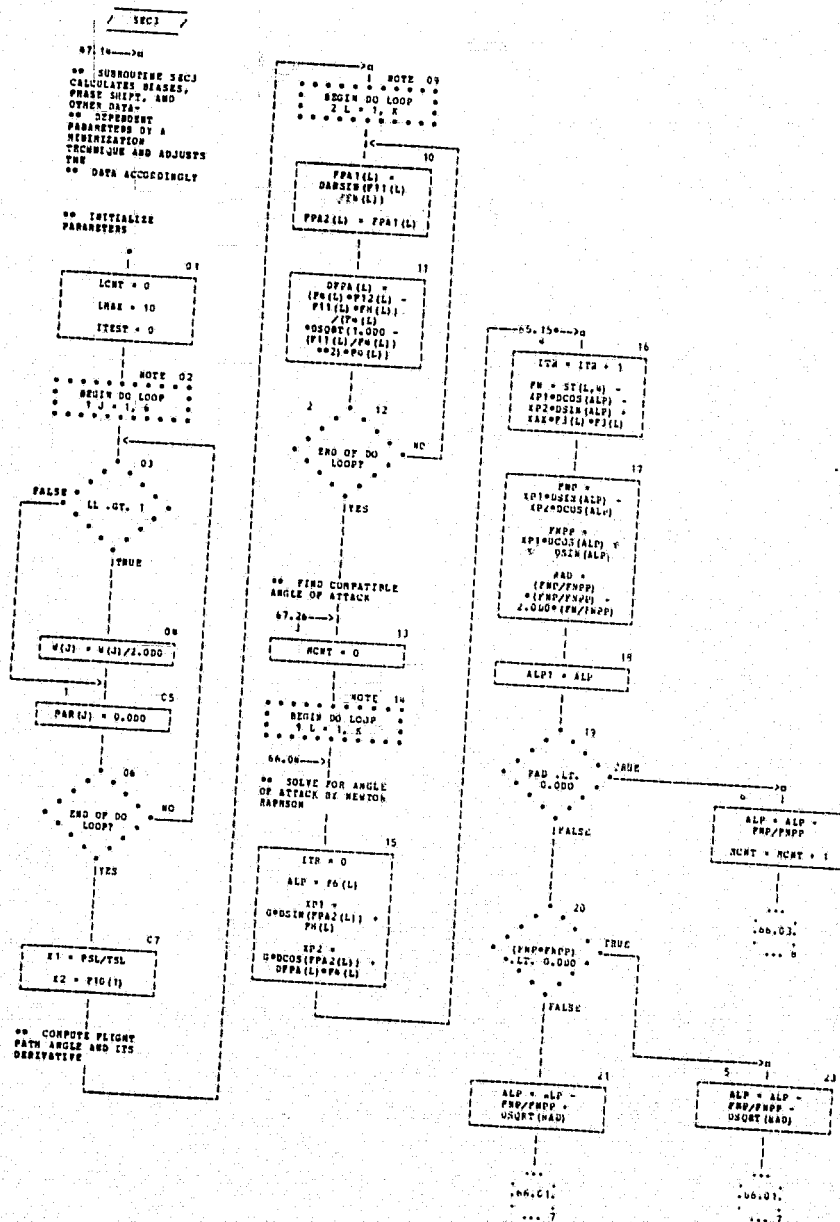
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PAGE 43

CHART TITLE - SUBROUTINE PLOTET(K,TPTX,IP,IFS,IPRC,H,NO,XAX)





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PAGE 66

CHART TITLE - SUBROUTINE SEC) (R,XAR,LSP,ITEST,LL,MUR,DSFS)

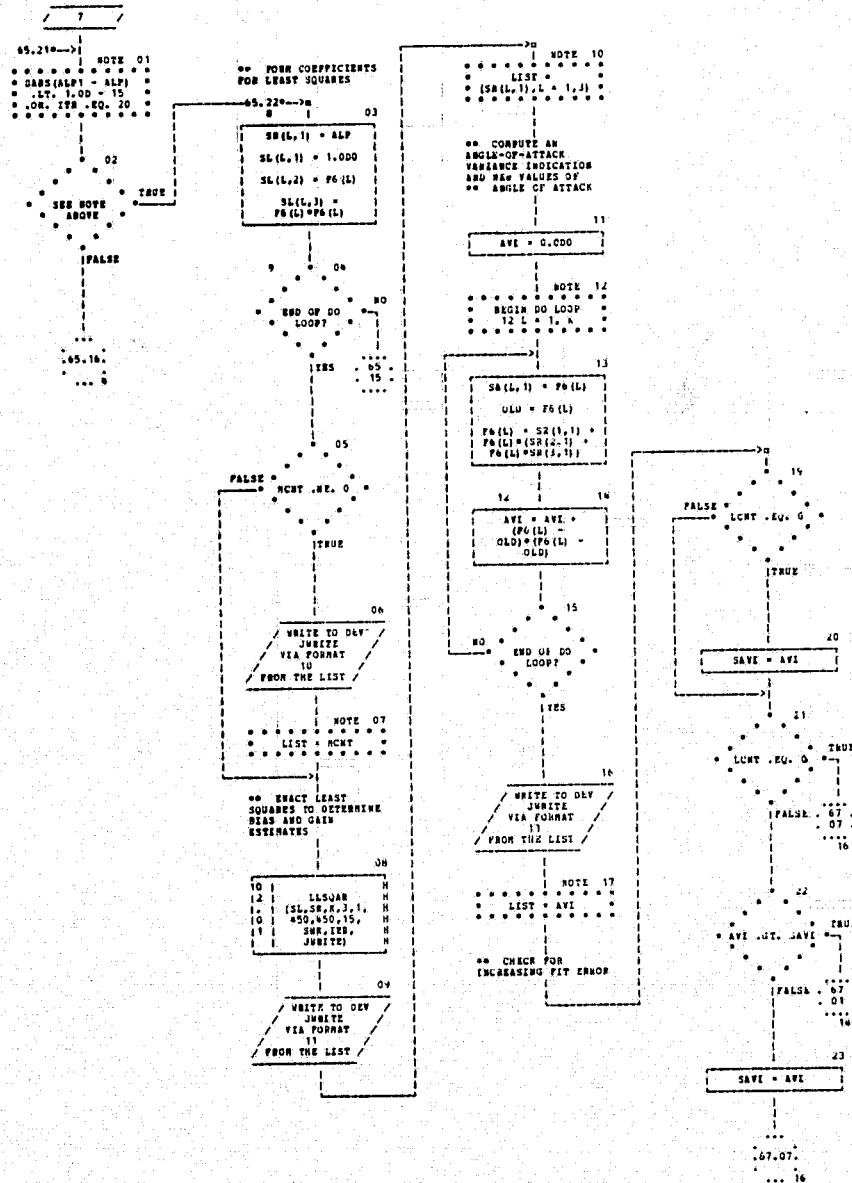
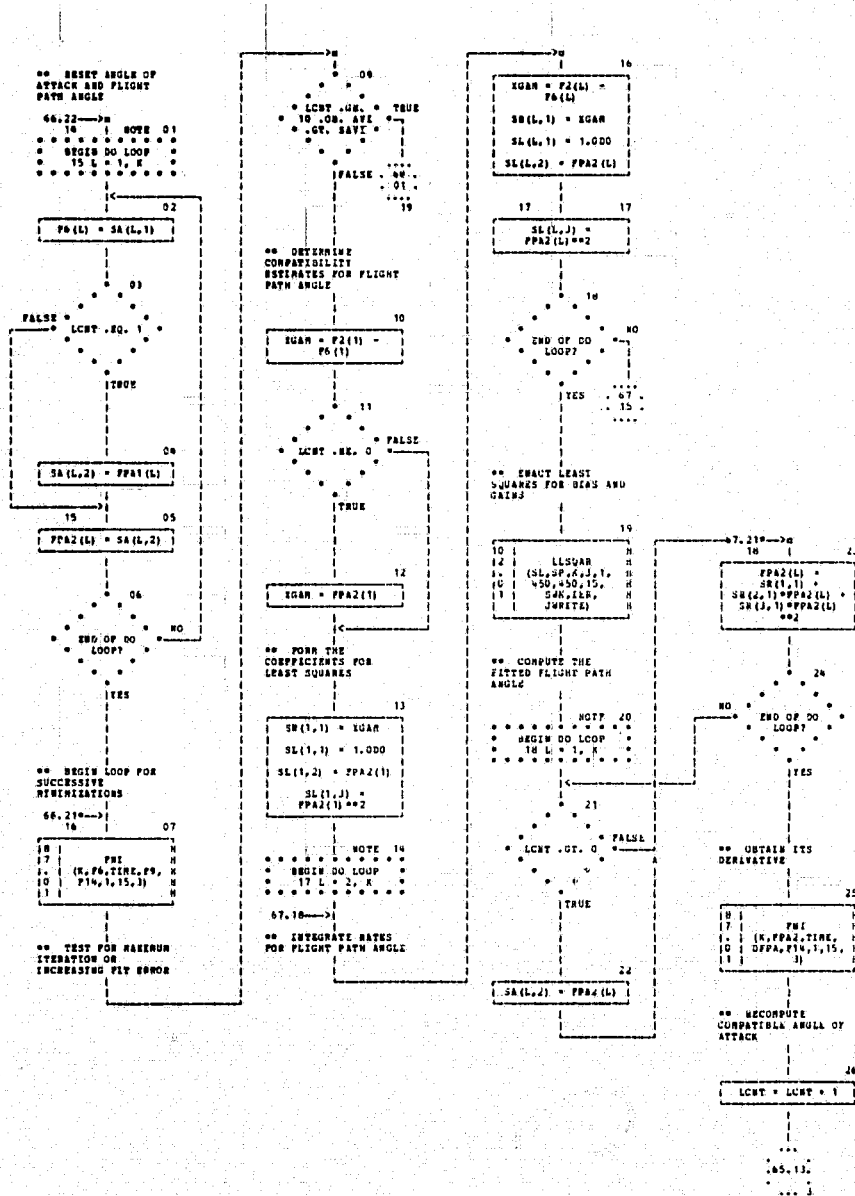


CHART TITLE - SUBROUTINE SMC3(K,SAR,LSP,ITEST,LL,NUN,OSP5)



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PAGE 68

CHART TITLE - SUBROUTINE SMC3(R,RR,LSP,ITEST,LL,MUR,DSFS)

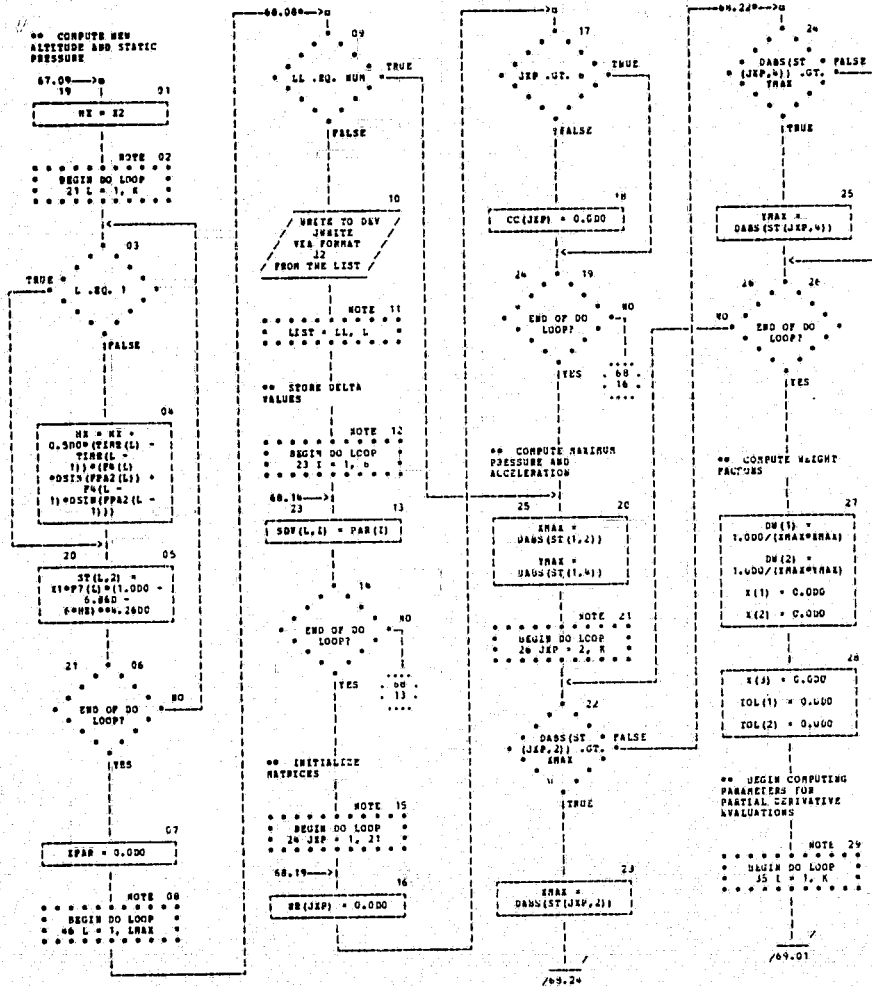
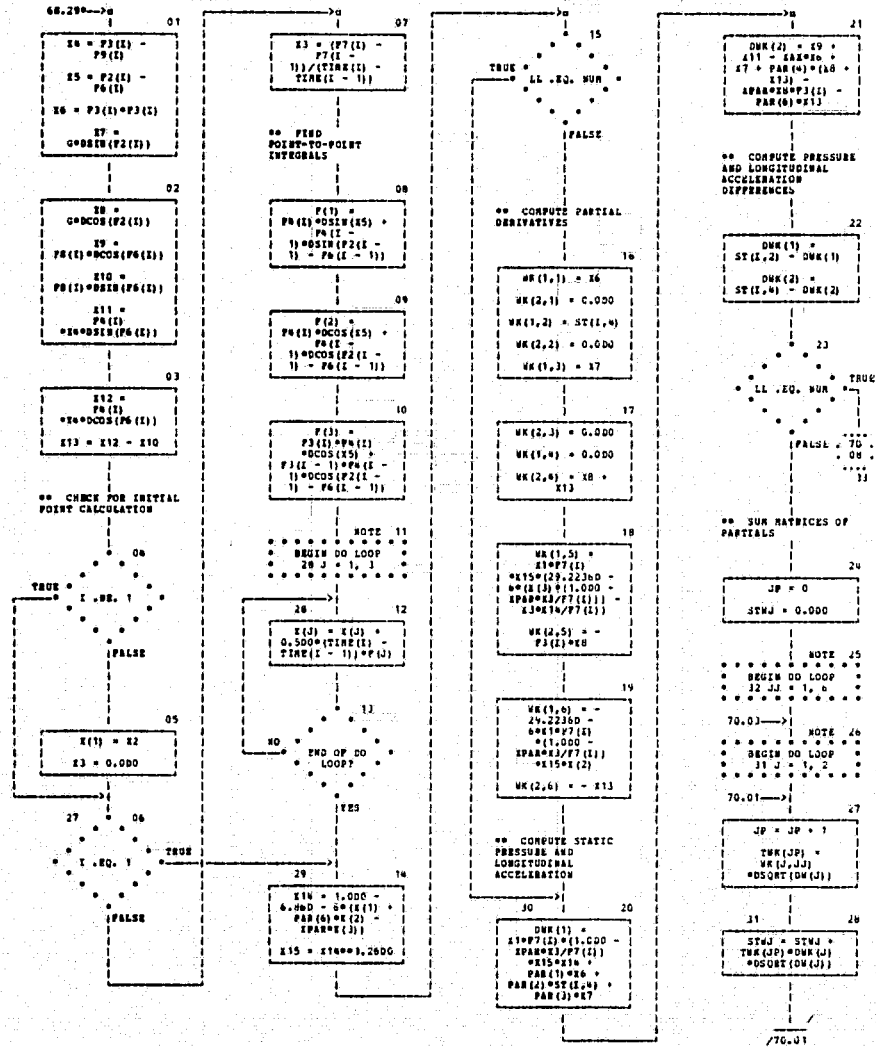


CHART TITLE - SUBROUTINE SEC3 (N, IAX, LSP, ITEST, LL, NUN, D5PS)



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PAGE 70

CHART TITLE - SUBROUTINE SECJ(K, IAE, LSP, ITEST, LL, NUN, DSP5)

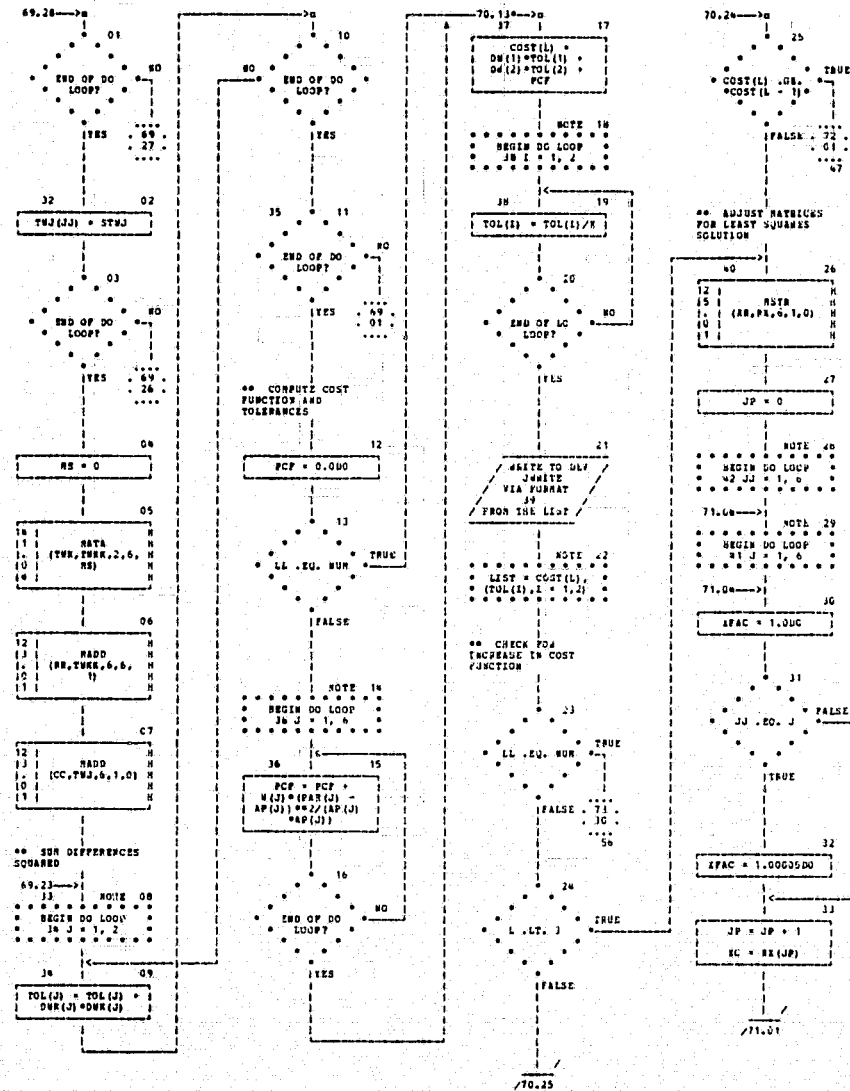
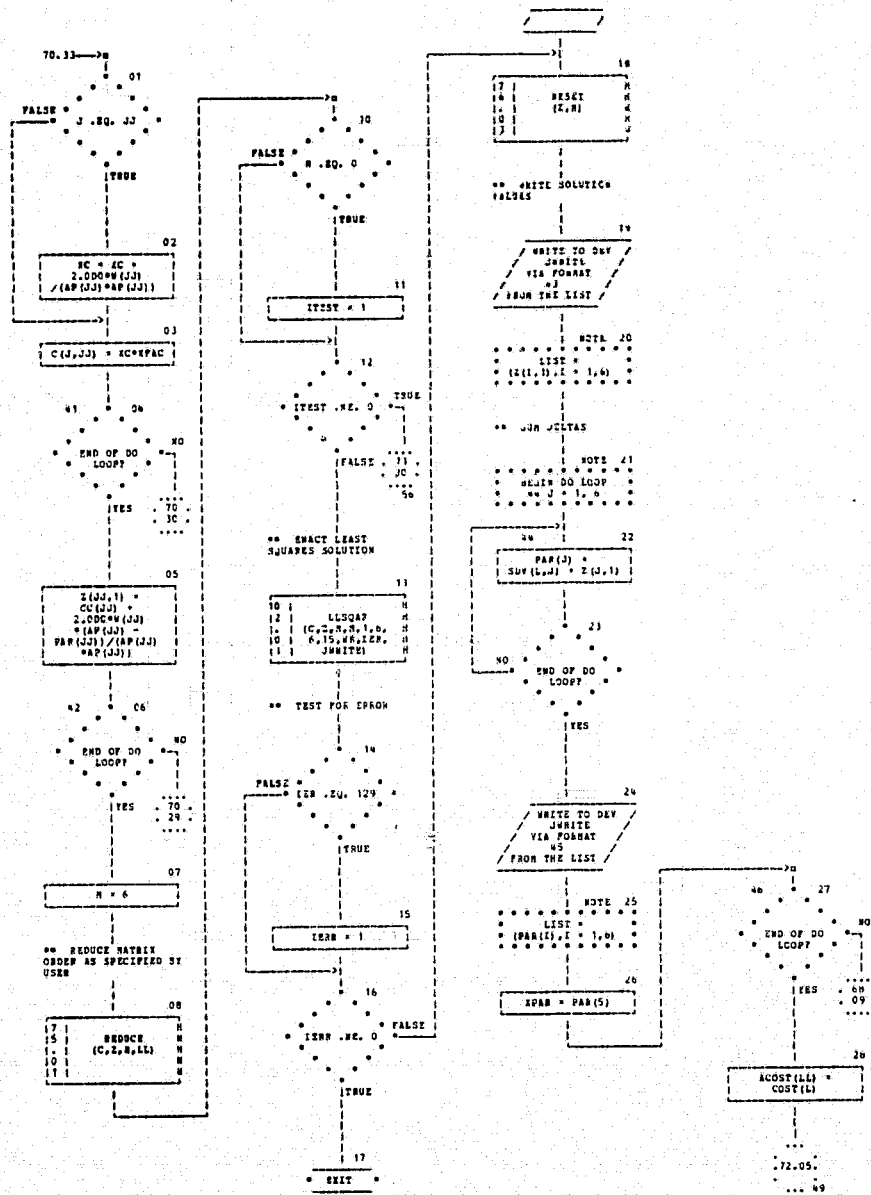


CHART TITLE - SUBROUTINE SMC3(N,NAR,LSP,ITEST,LL,NUN,DSPS)



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PAGE 72

CHART TITLE - SUBROUTINE SBC3(N,KAR,LSP,ITEST,LL,NUR,DSPPS)

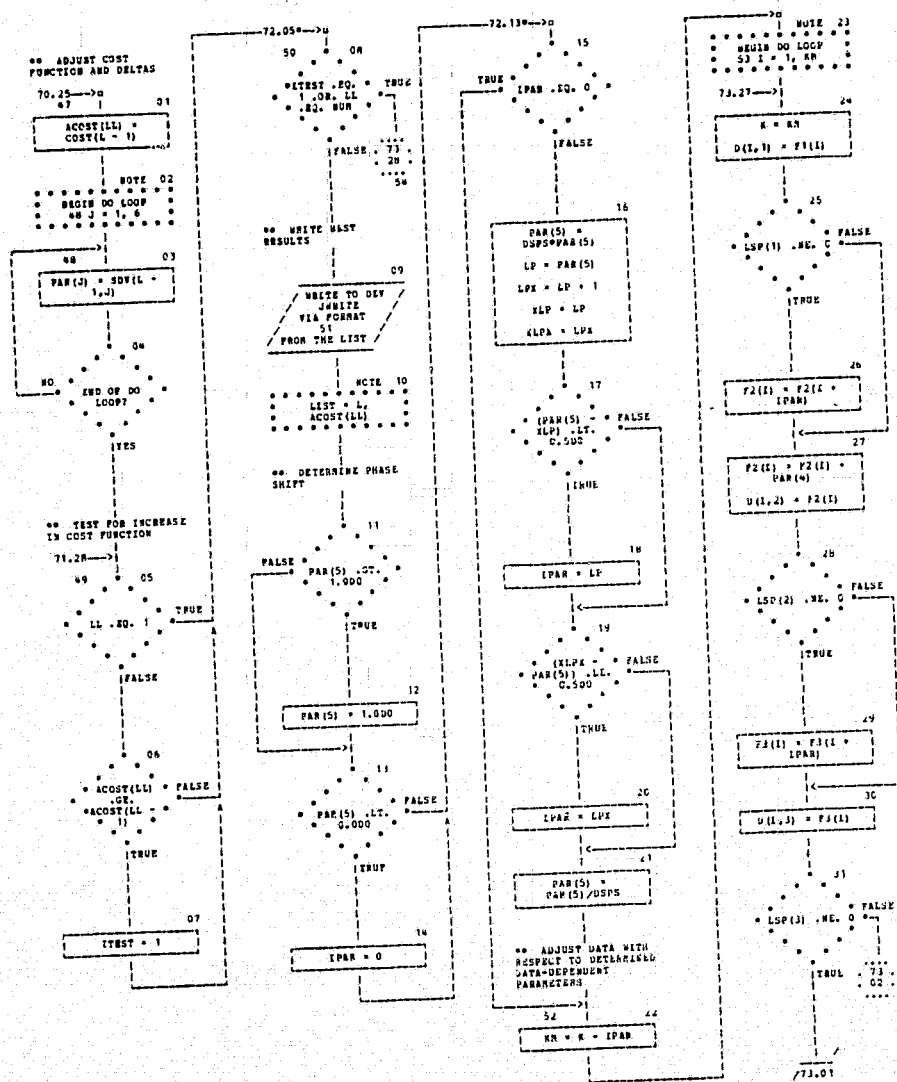
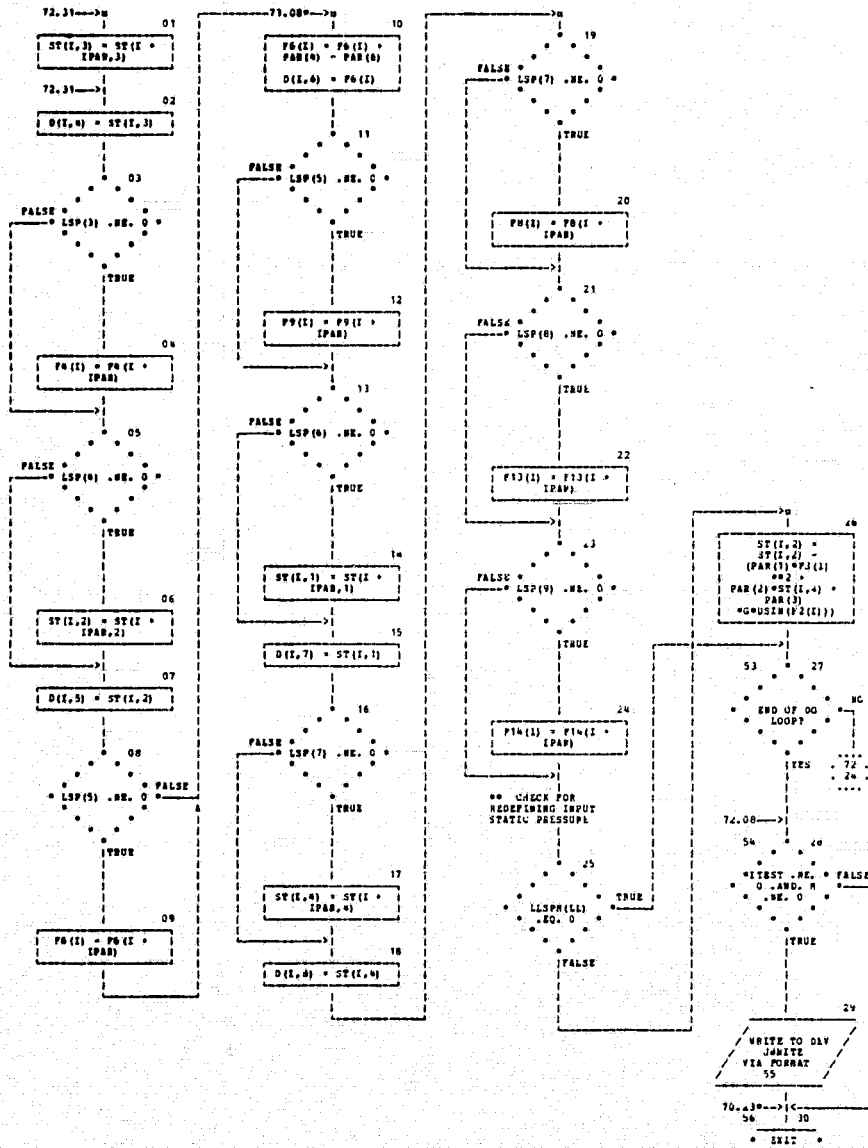


CHART TITLE - SUBROUTINE SEC3(X,MAX,LSP,ITEST,LL,NUN,DSPS)



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PAGE 75

CHART TITLE - SUBROUTINE REDUCE(C,S,R,LL)

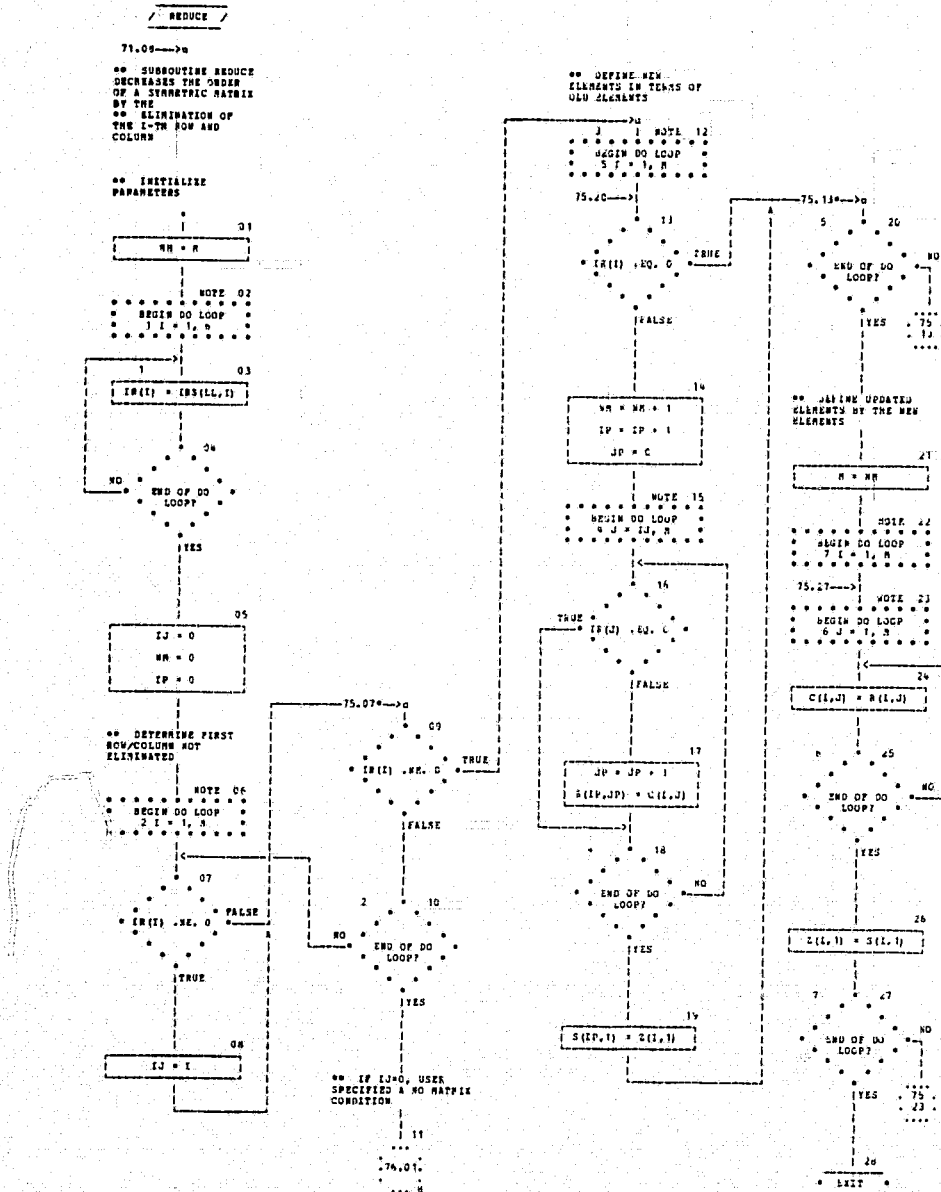
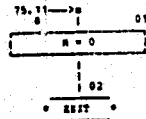


CHART TITLE - SUBROUTINE RESUCE(C,X,N,LL)

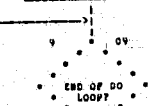
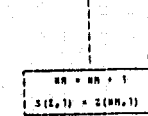
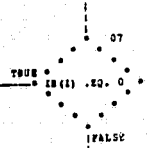
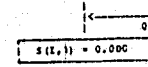
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SPECIFICATION



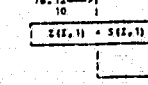
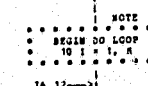
•• ENTRY RESET
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TO BE COMPATIBLE WITH
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•• ORIGINAL MATRIX



NOTE 05
•• BEGIN DO LOOP
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NOTE 10
•• BEGIN DO LOOP
•• 10 = 1, R



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PAGE 74

CHART TITLE - SUBROUTINE SHEPT (N, LSP, NSPTS)

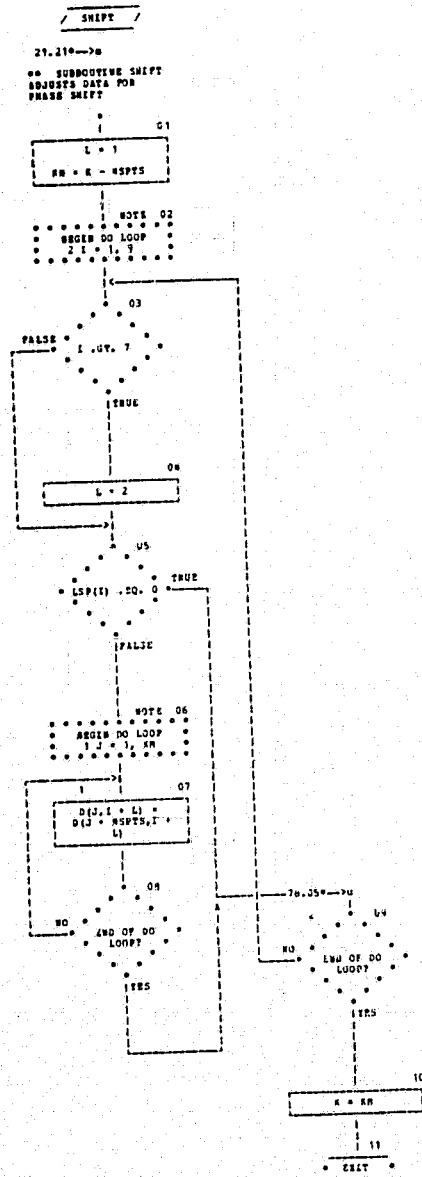
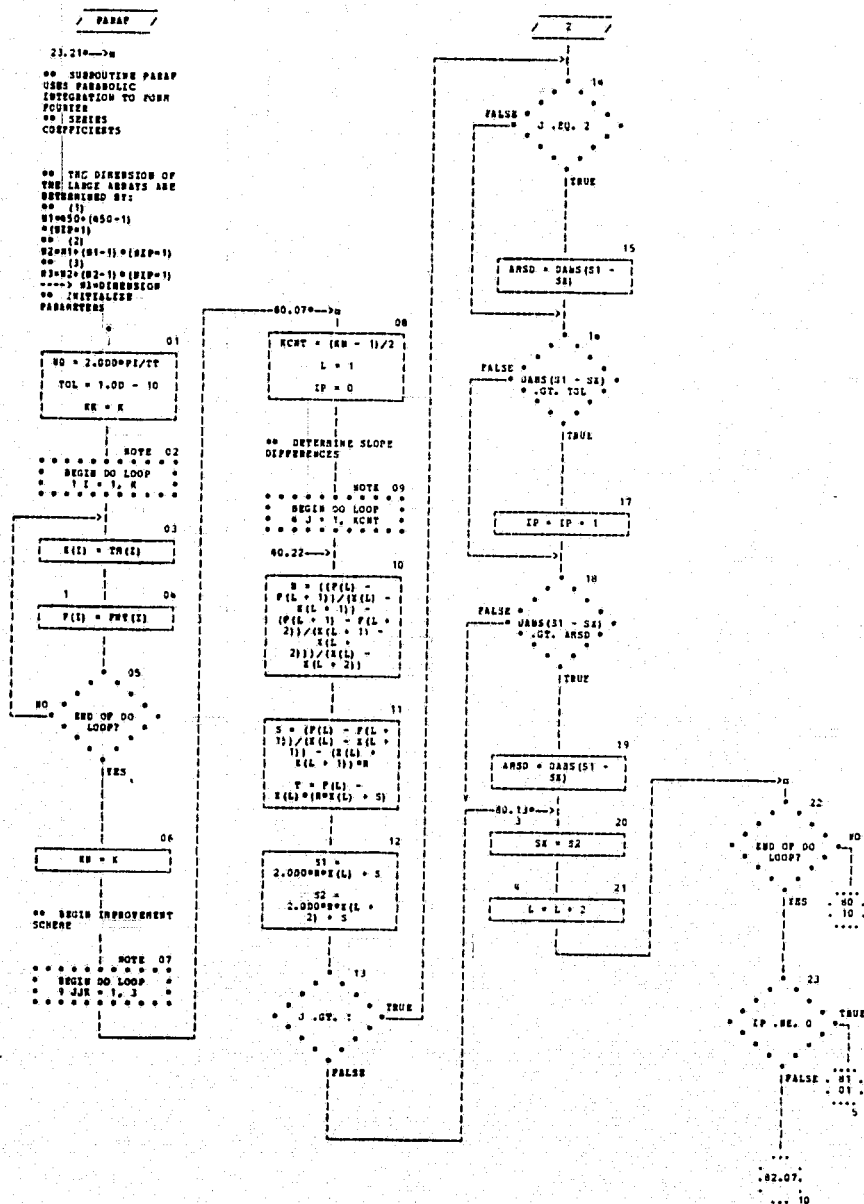


CHART TITLE - SUBROUTINE PARAP (PMT,K,RP1,UC)



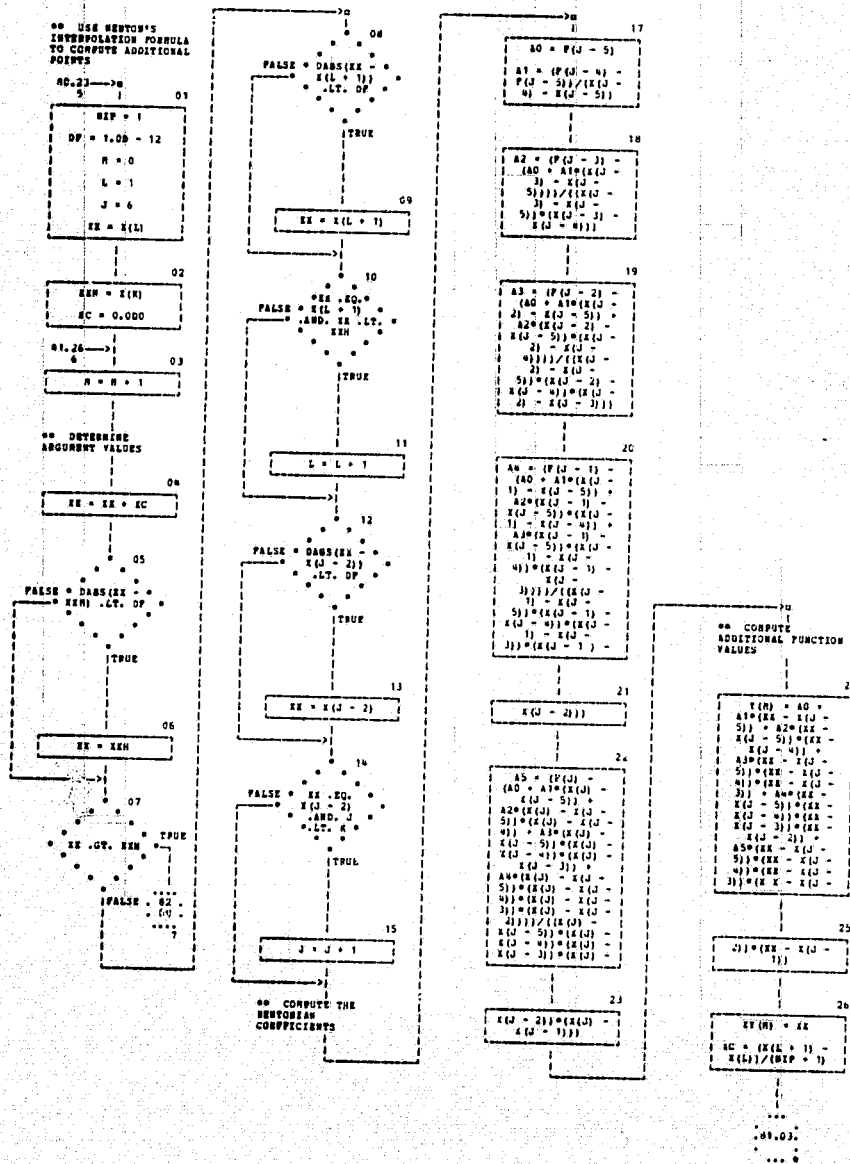
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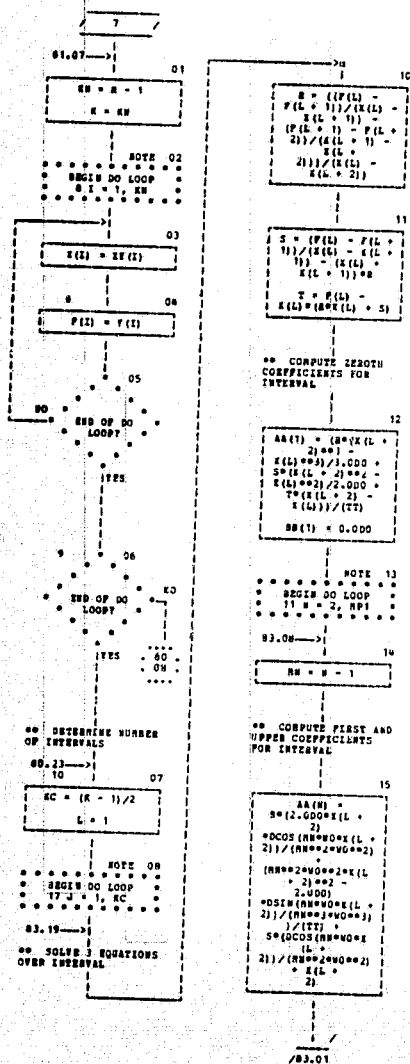
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PAGE 01

CHART TITLE - SUBROUTINE PARAP (PNT, X, NP1, NC)





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PAGE 43

CHART TITLE - SUBROUTINE PARAF(PNT,K,NP1,NC)

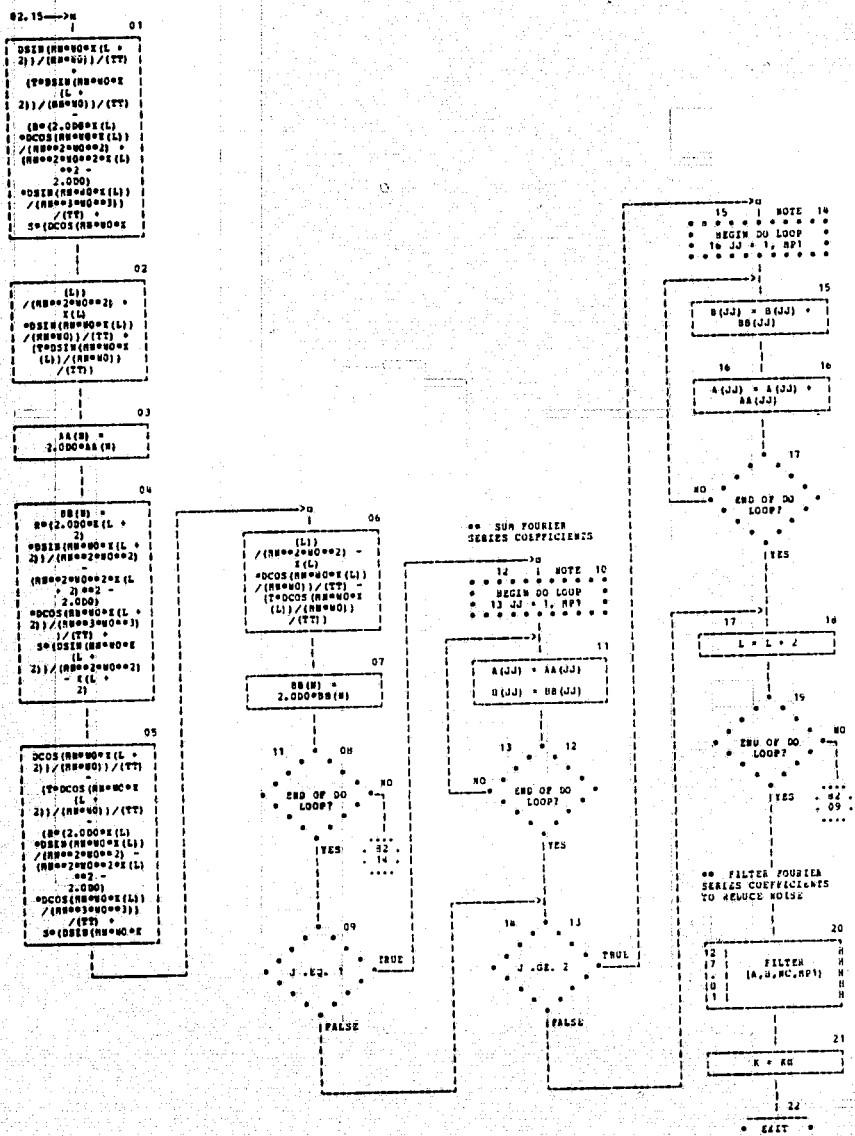
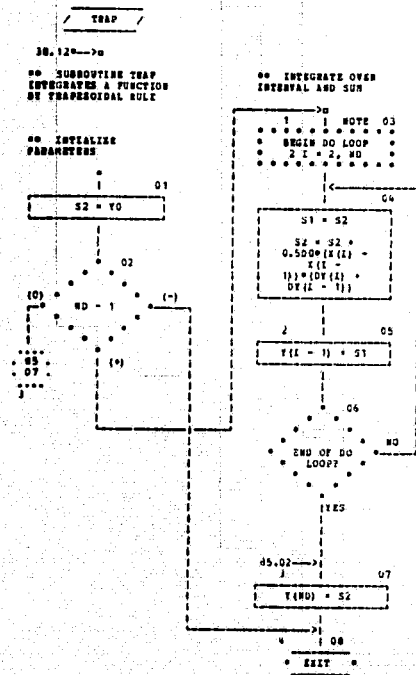


CHART TITLE - SUBROUTINE TRAP(SD,X,DT,T,TO)

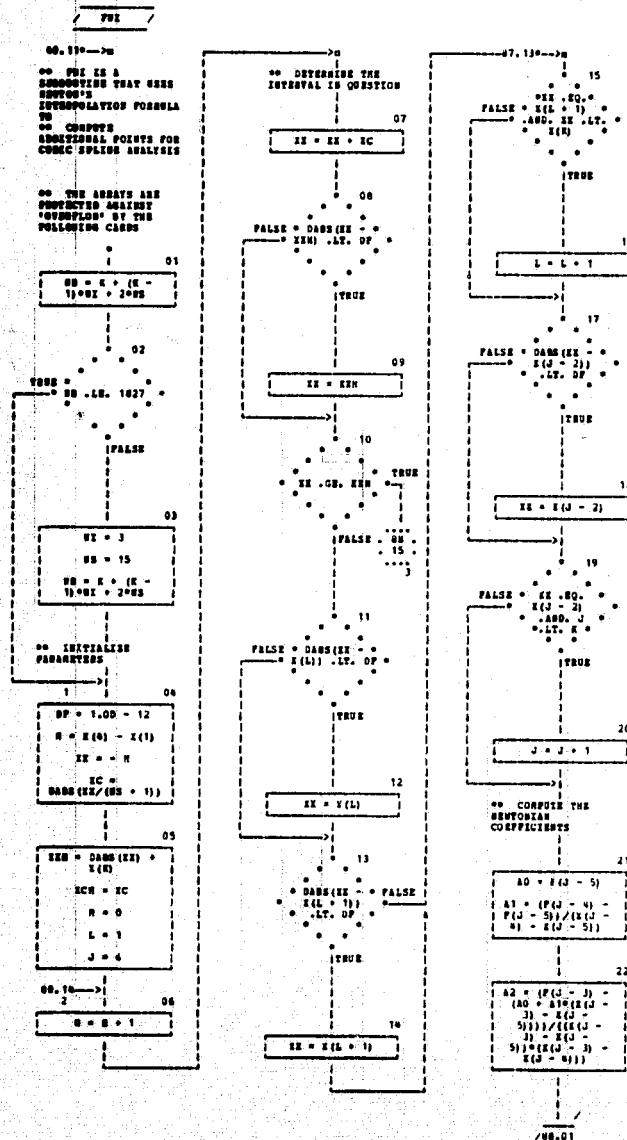


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PAGE 07

CHART TITLE - SUBROUTINE P01 (X,P,L,PP,PP,PP,PP,PP,PP)



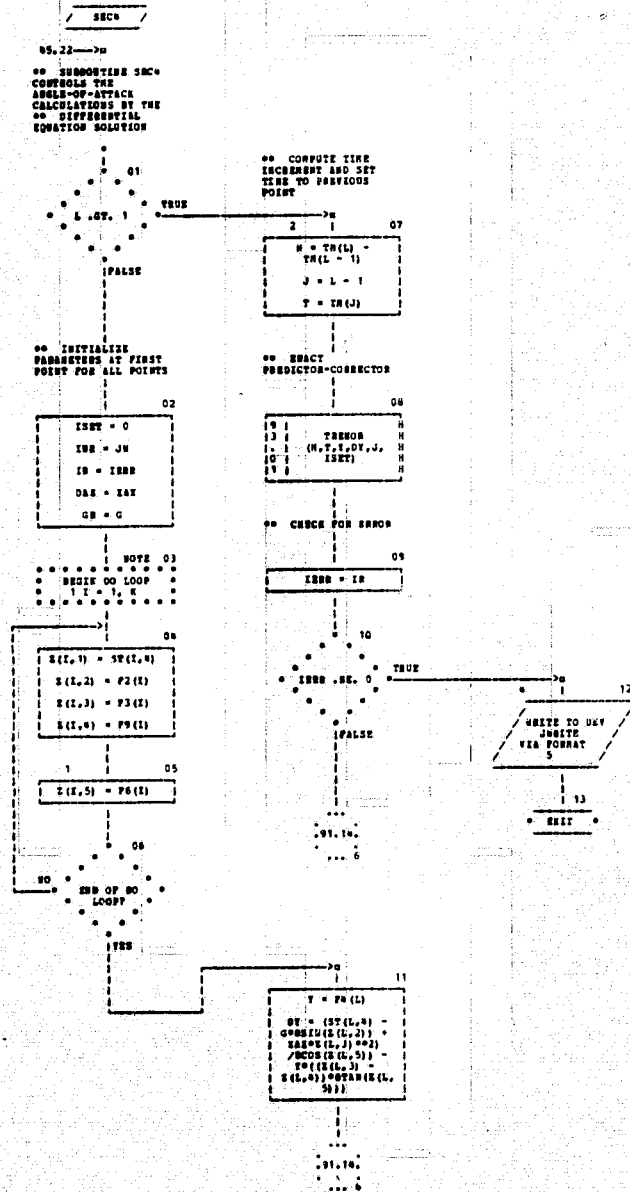
CARD TITLE - SUBTITLE FBI(U.S.I.F.P.P.D.,NO,US,MZ)

•FONTS

PAGE 49



CHART TITLE - SUBROUTINE SEC*(L,R,KX)



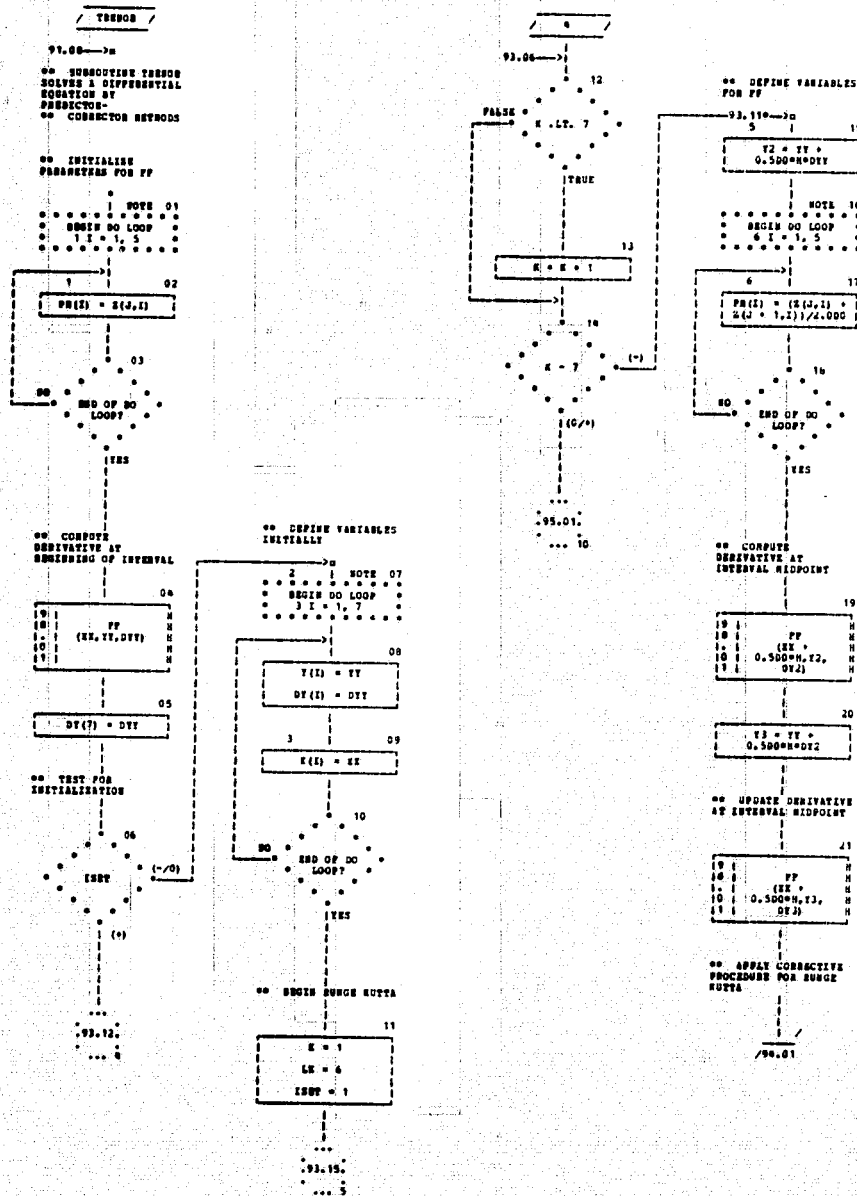
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PAGE 93

CHART TITLE - SUBROUTINE TRESOR (N, XE, YF, DTY, J, IZRT)



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PAGE 99

CHART TITLE - SUBROUTINE TRUNC(M, N, Y, DUT, J, ISPT)

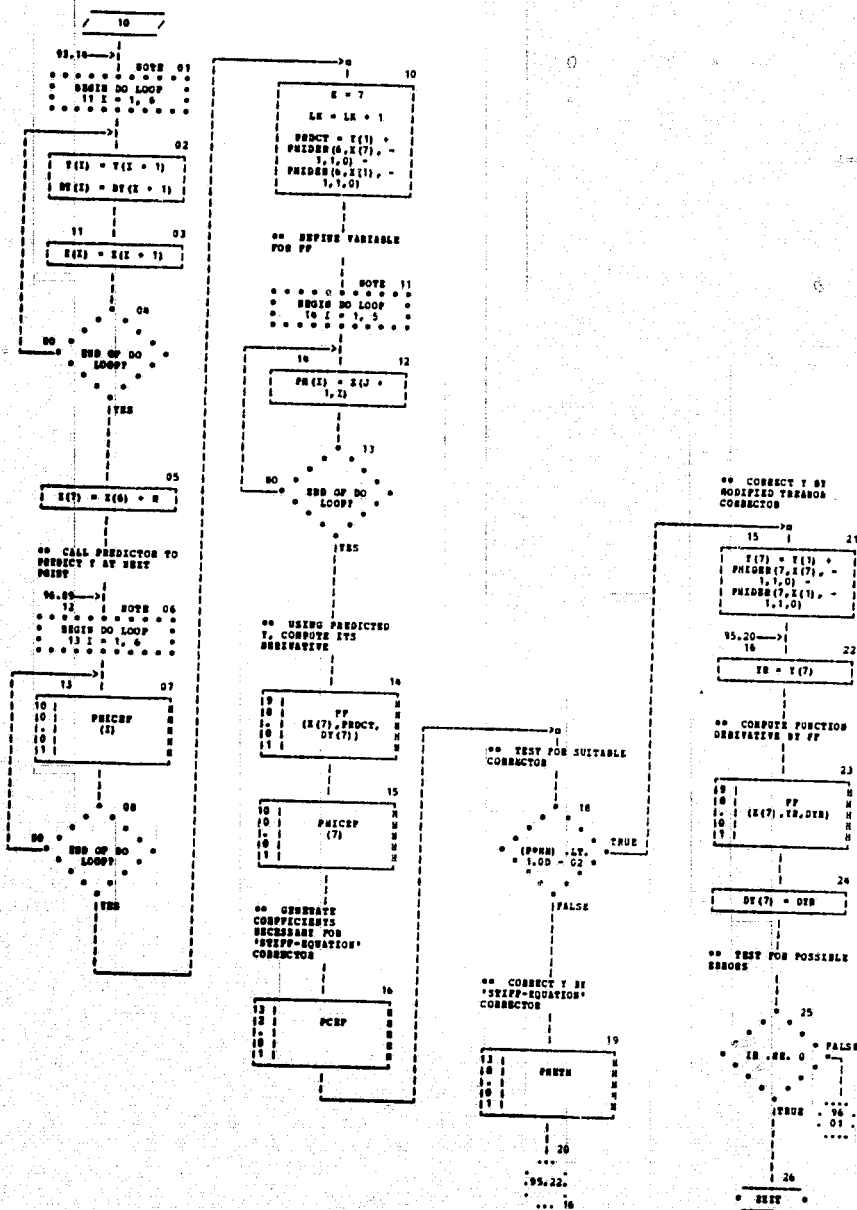
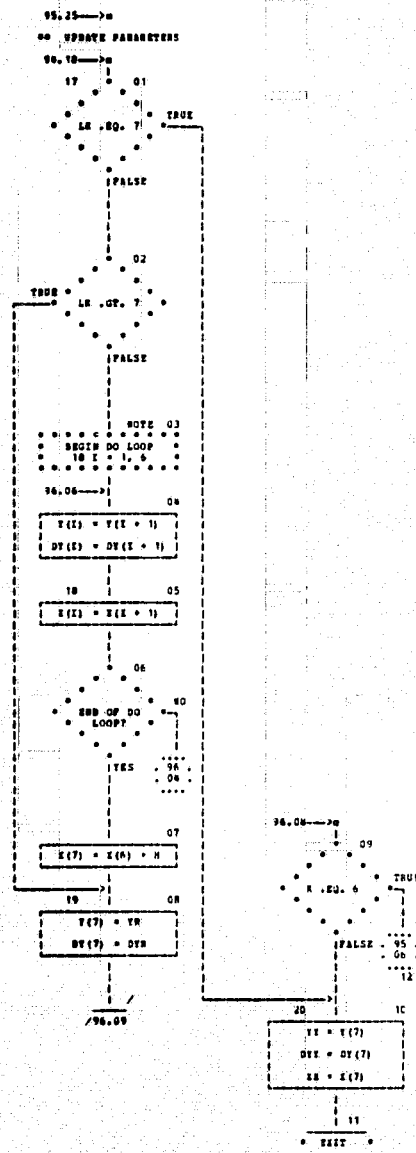


CHART TITLE - SUBROUTINE TREND00(M,EE,YY,DYY,J,ISZY)



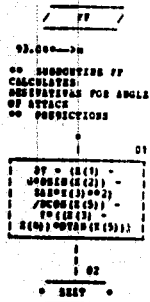
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CHART TITLE - SUBROUTINE PP(T,F,01)

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PAGE 08



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PAGE 102

CHART TITLE - SUBROUTINE LLQAR(A,B,N,NA,OB,IA,IB,IOGT,WRABA,IER,JWRITE)

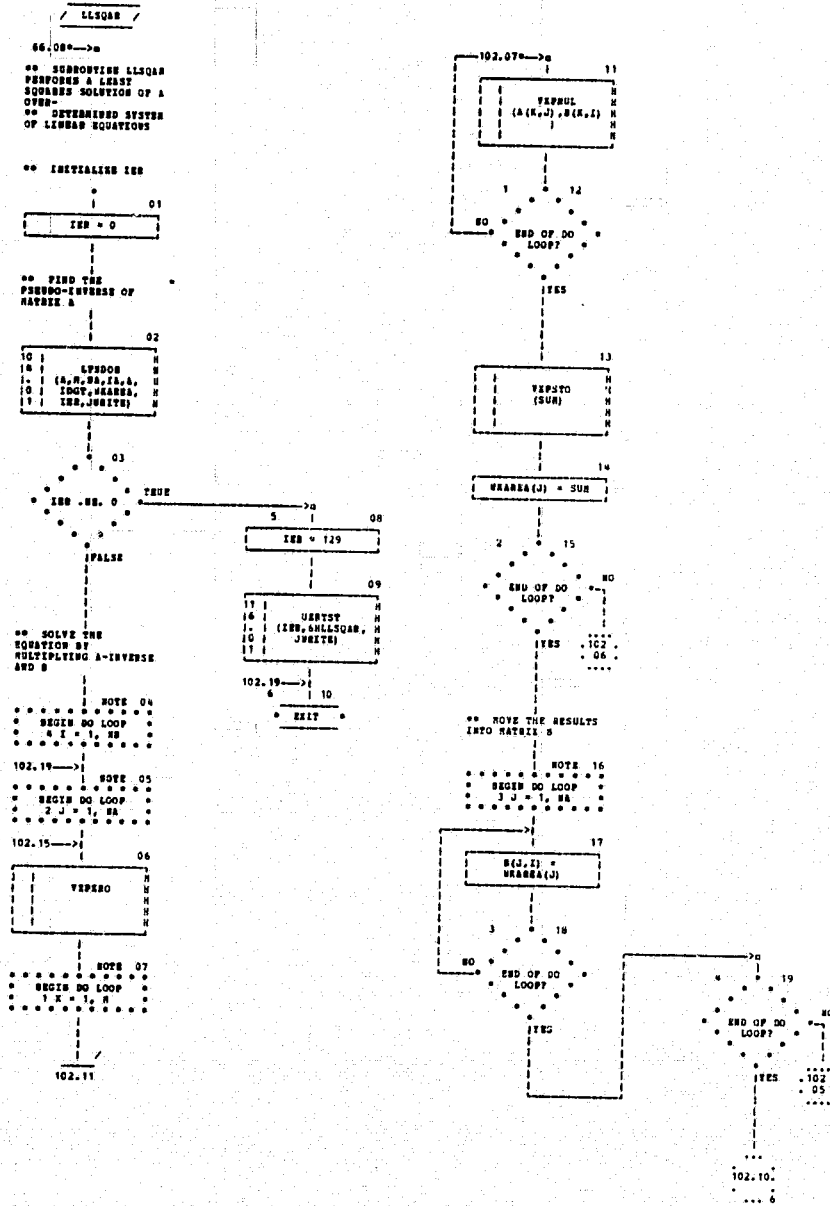
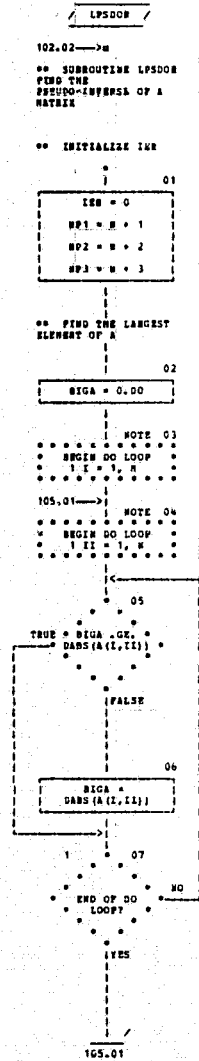


CHART TITLE - SUBROUTINE LPSDOR(A,N,M,IA,ALPH,IOPT,VRANKA,IER,JWRITE)



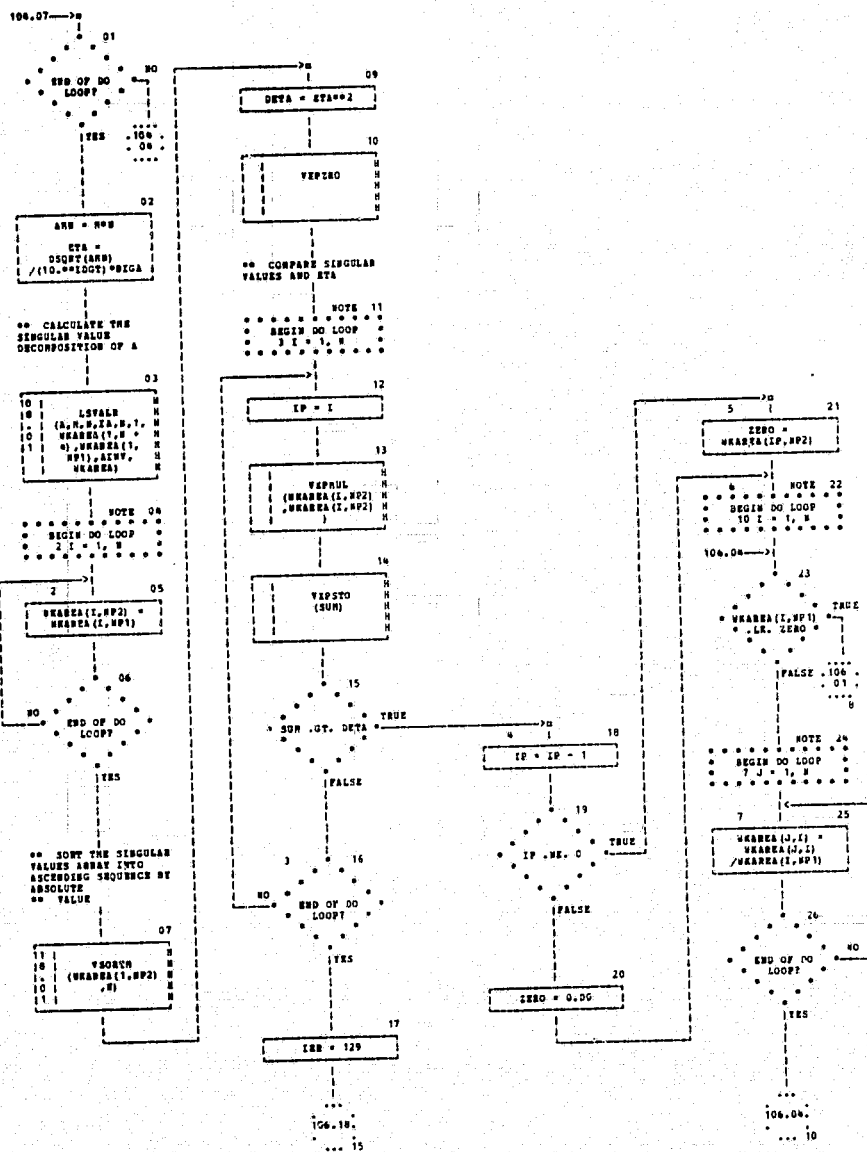
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PAGE 105

CHART TITLE - SUBROUTINE LPSUB(A,N,N,IA,AINV,IDOT,SHARRA,IER,JWSITE)



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OF POOR QUALITY

AUTOFLOW CHART SET -

*FDR1

PAGE 108

CHART TITLE - SUBROUTINE LSVALS(A,N,H,IA,IV,ISV,WRAREA,Q,U,V)

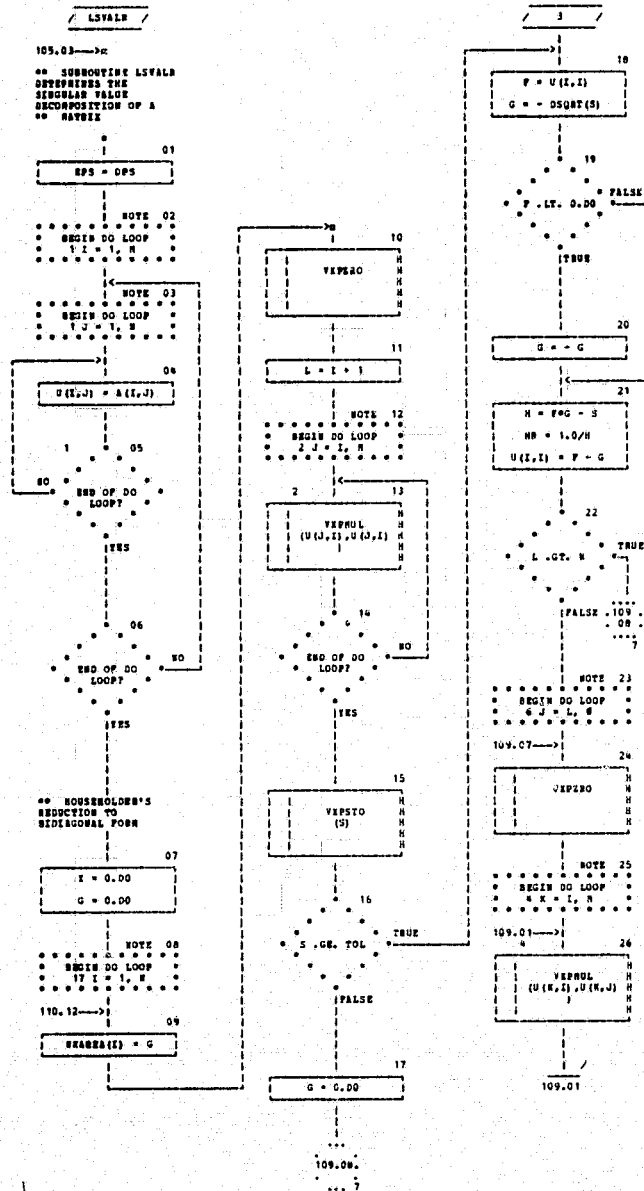
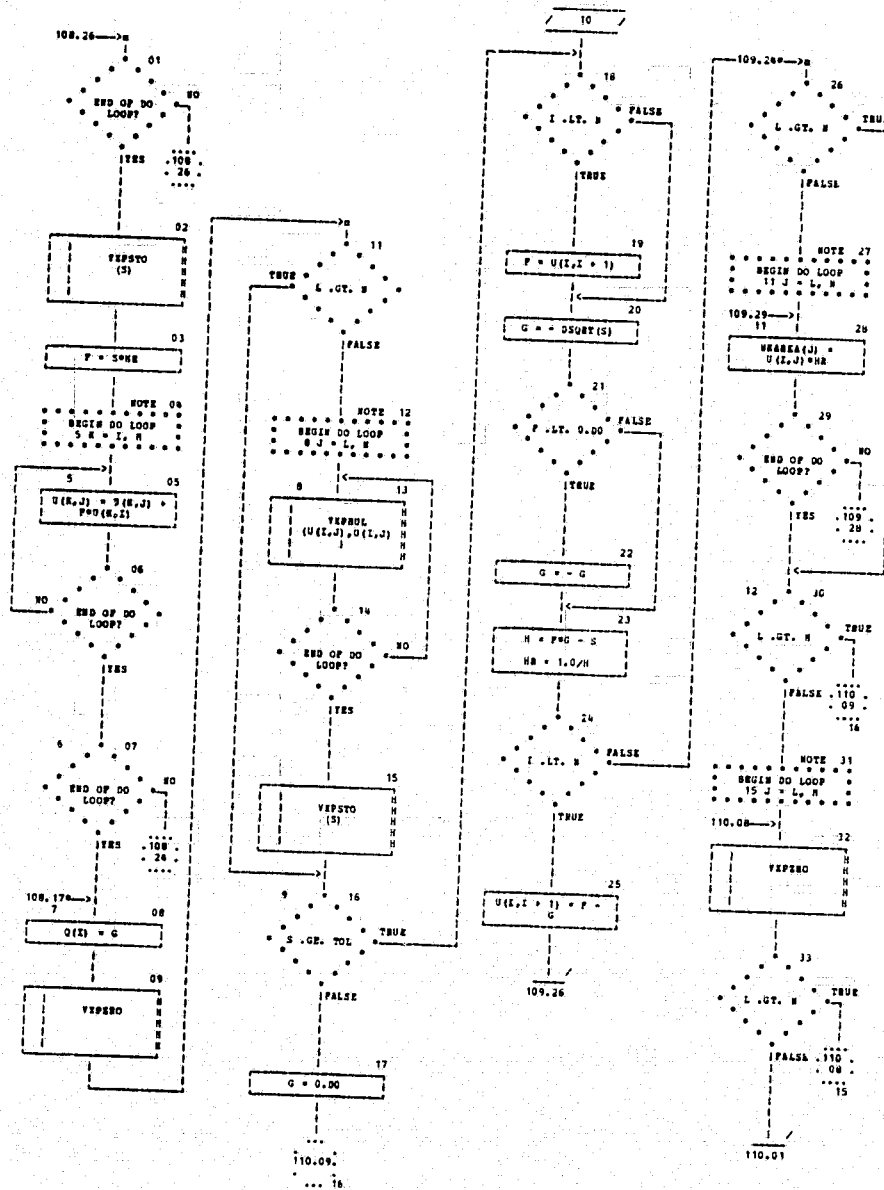


CHART TITLE - SUBROUTINE LSVAB(A,B,N,IA,IV,ISV,UBABR,Q,U,V)



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AUTOFLON CHART SET -

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PAGE 110

CHART TITLE - SUBROUTINE LVALN(A,N,M,I0,I1,ISU,VRARRA,Q,U,V)

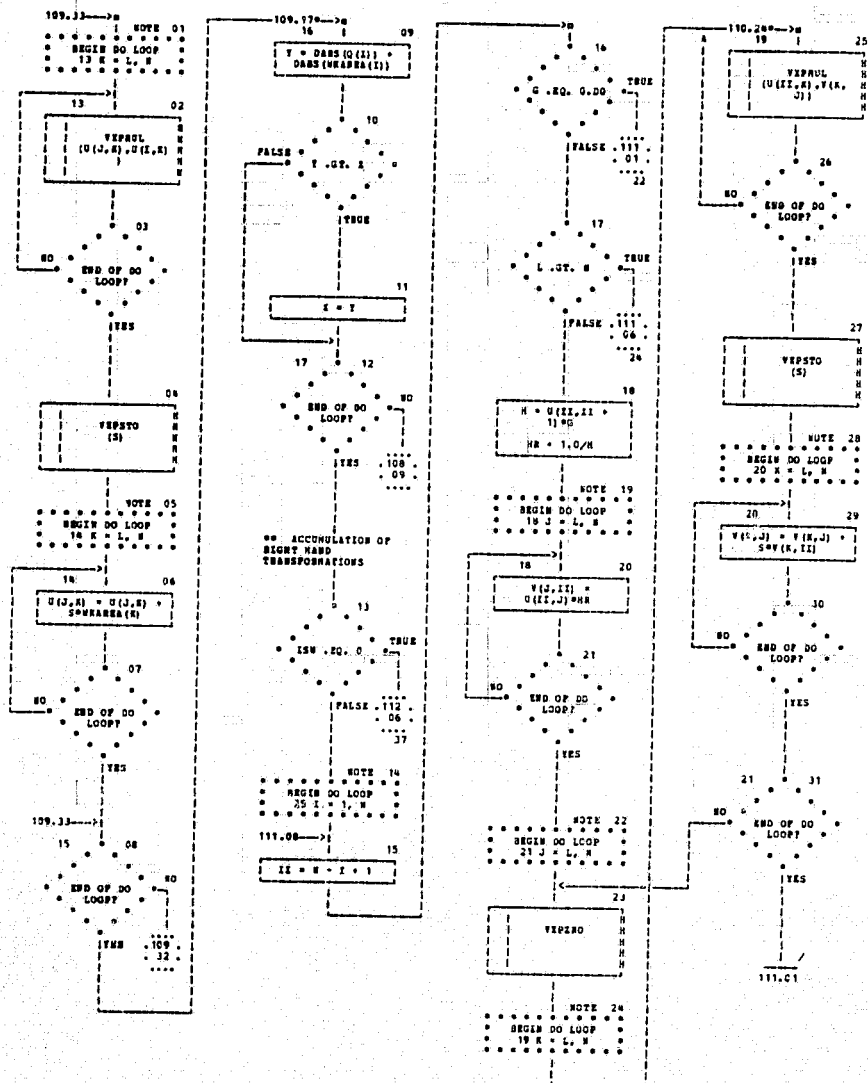
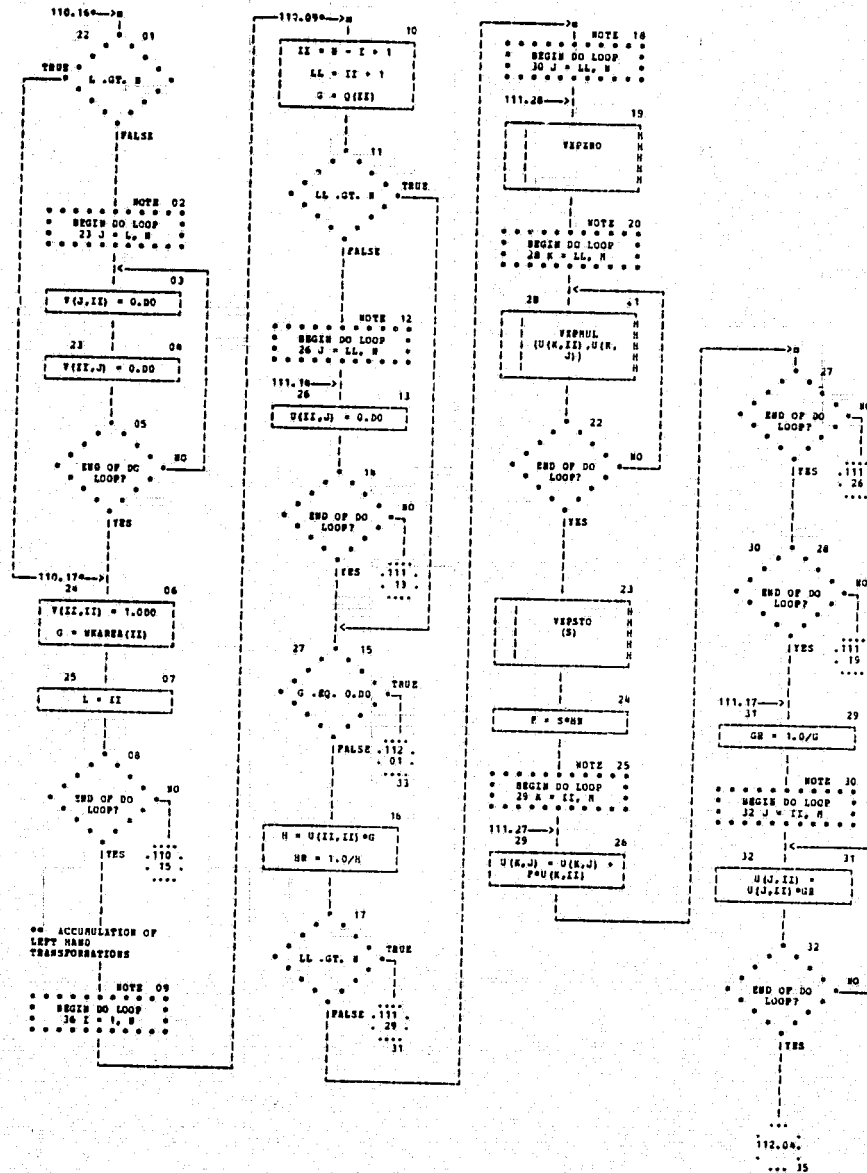


CHART TITLE - SUBROUTINE LEVALS(L, H, W, Z, IV, ISU, WKAREA, G, U, V)



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CHART TITLE - SUBROUTINE LVALN(A,B,N,LA,IV,ISD,WEARBA,Q,U,V)
AUTOFLOW CHART SET - *PDB1

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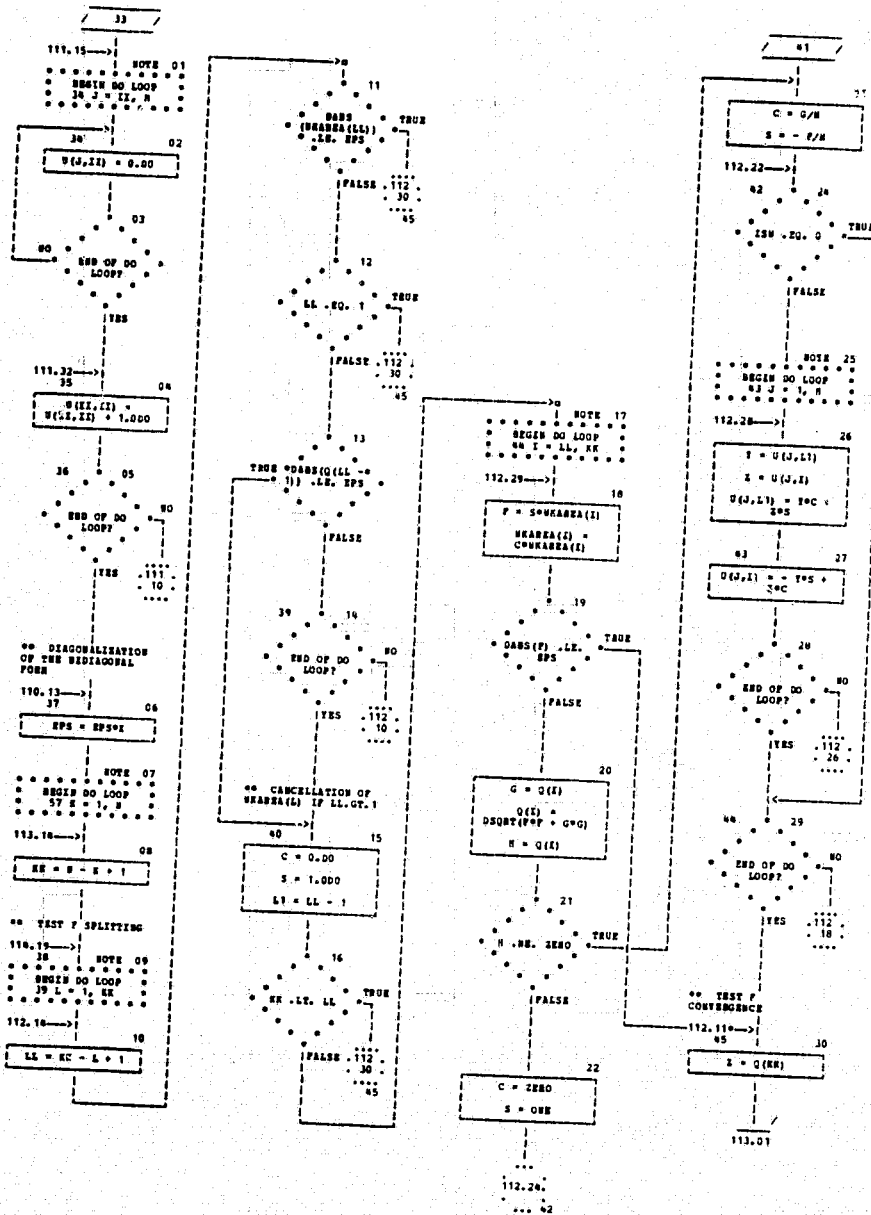
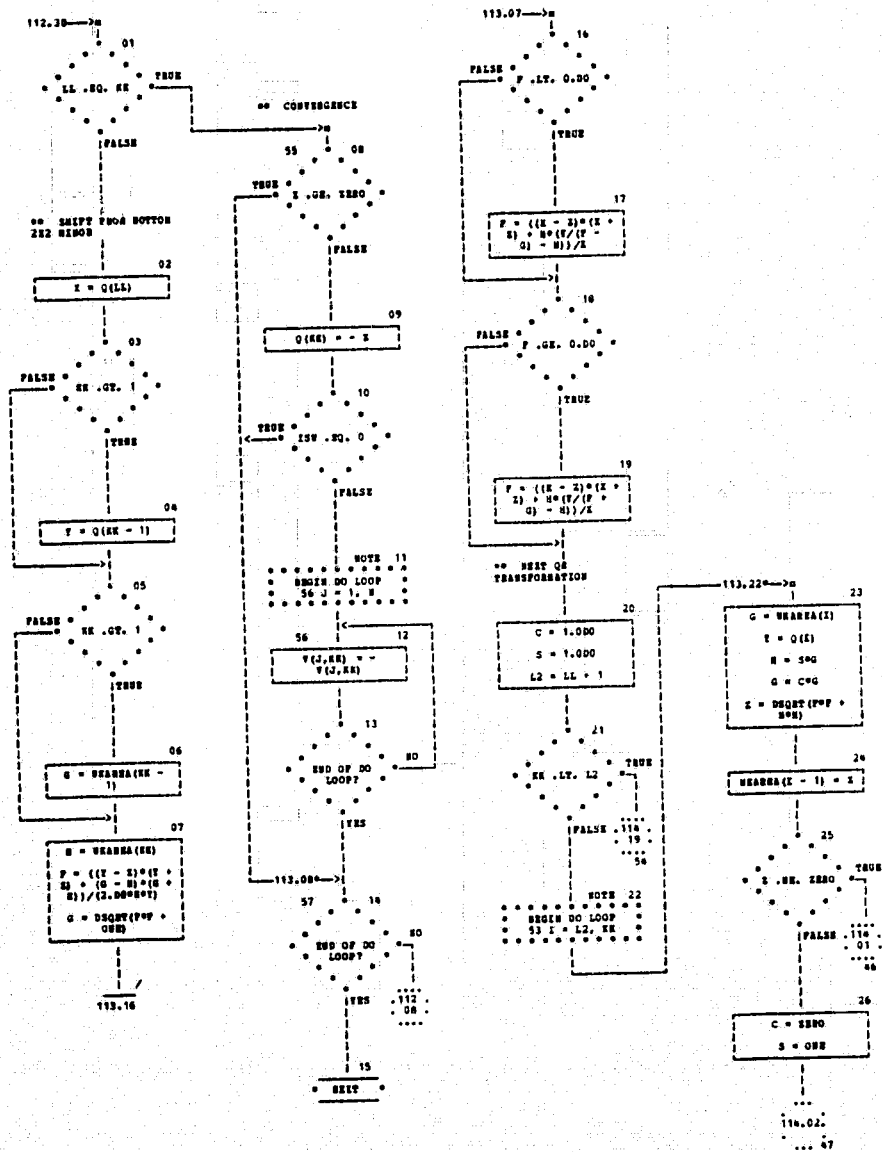


CHART TITLE - SUBROUTINE LEVAL3(I, J, K, L, M, N, O, P, Q, R, S, T, U, V, W, X, Y, Z)



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AUTOPLON CHART SET - *PDB1

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CHART TITLE - SUBROUTINE LEVALS(A,B,U,IA,IV,ISU,HEARDA,Q,U,V)

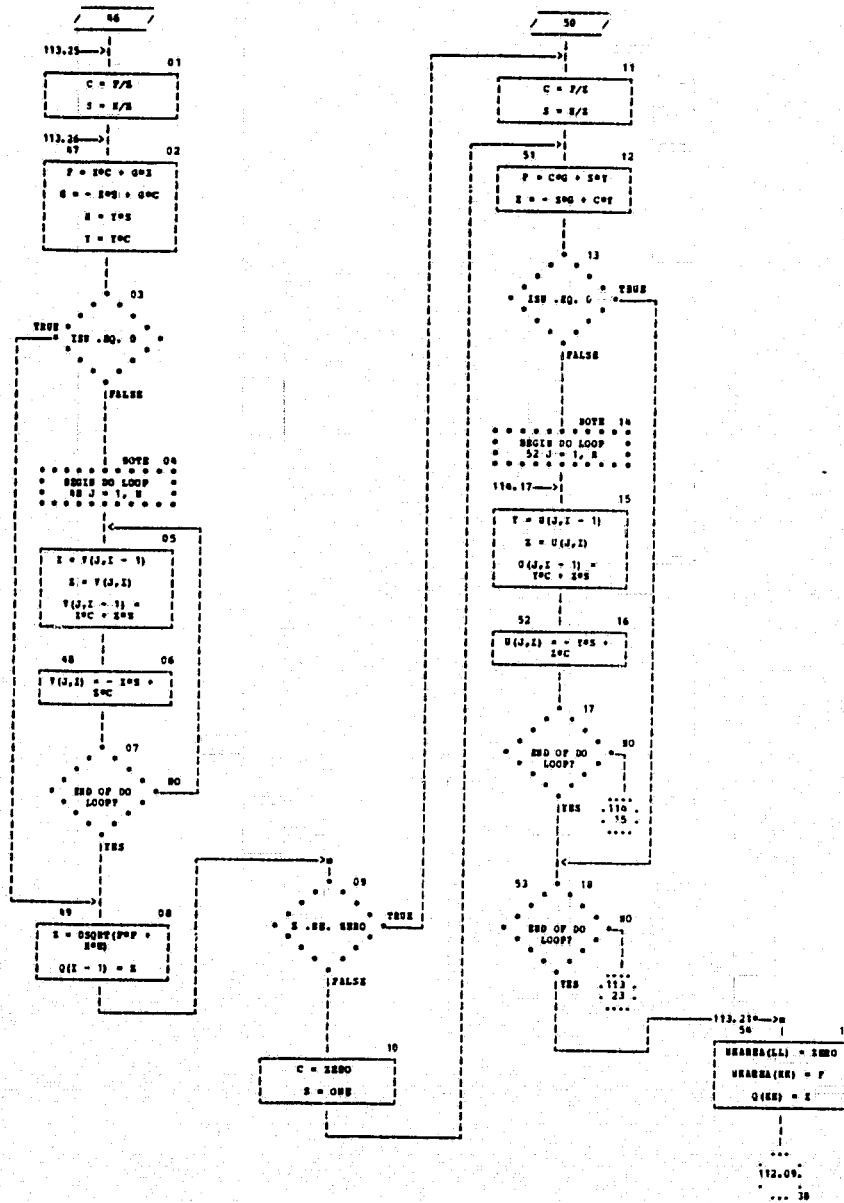


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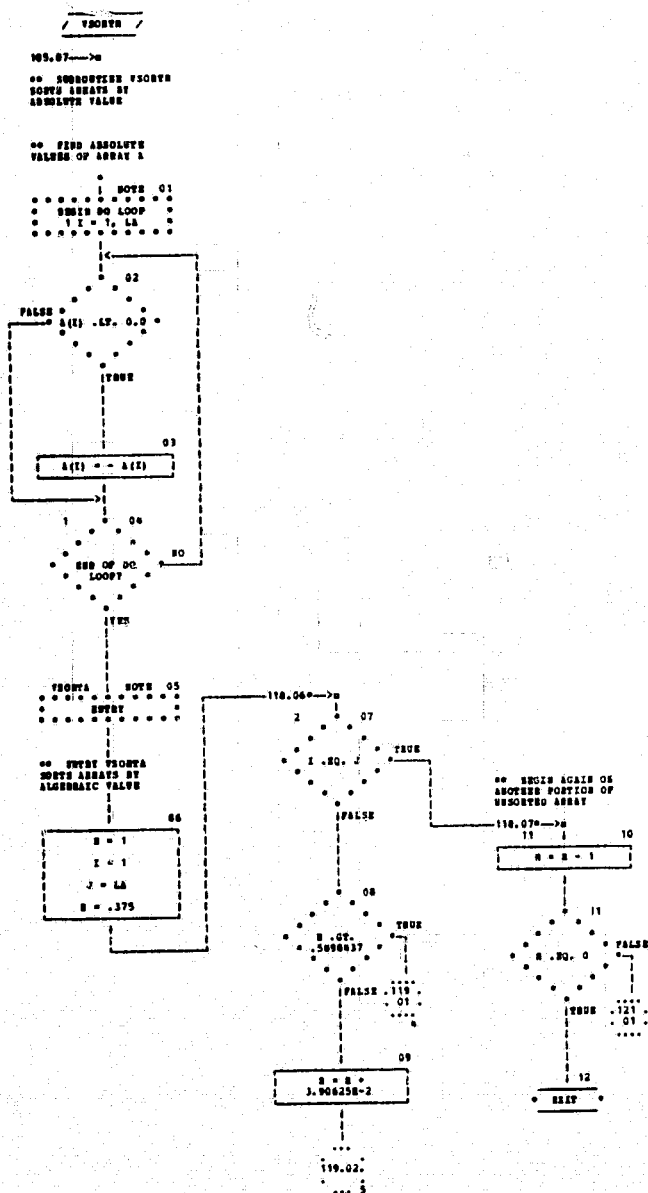


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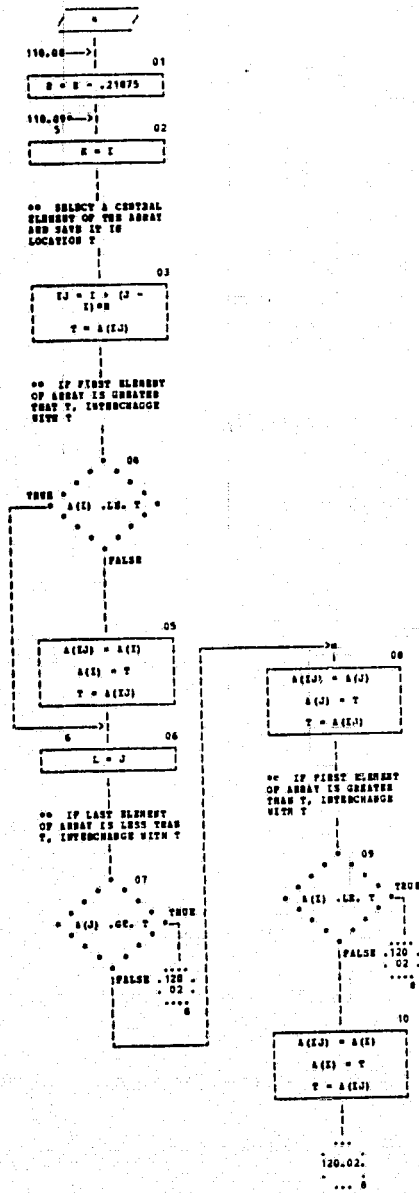


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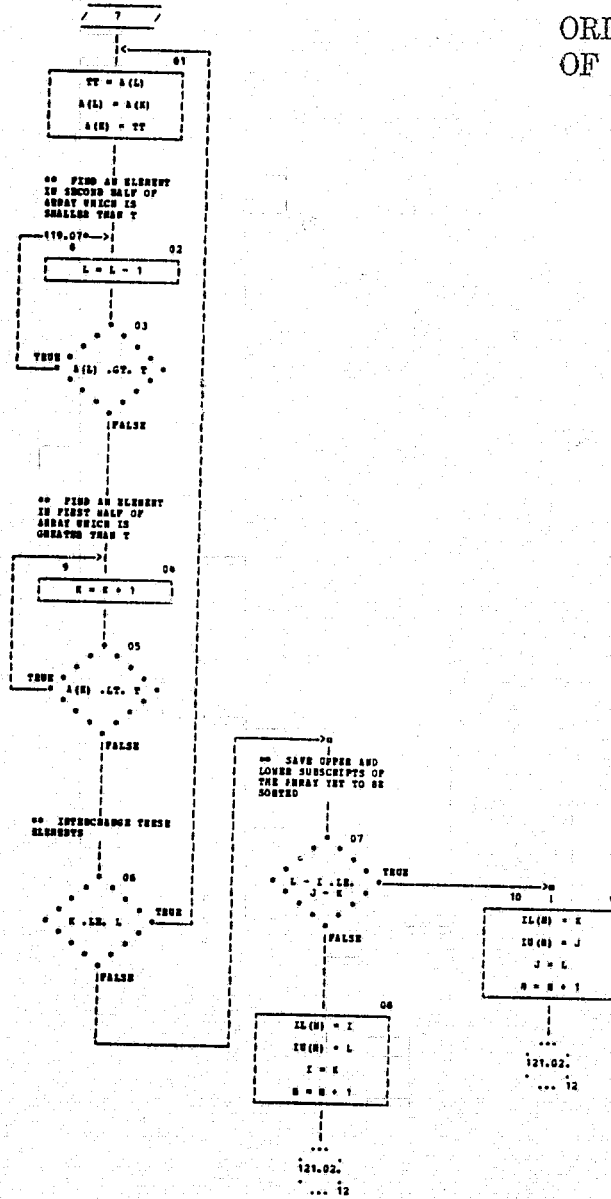
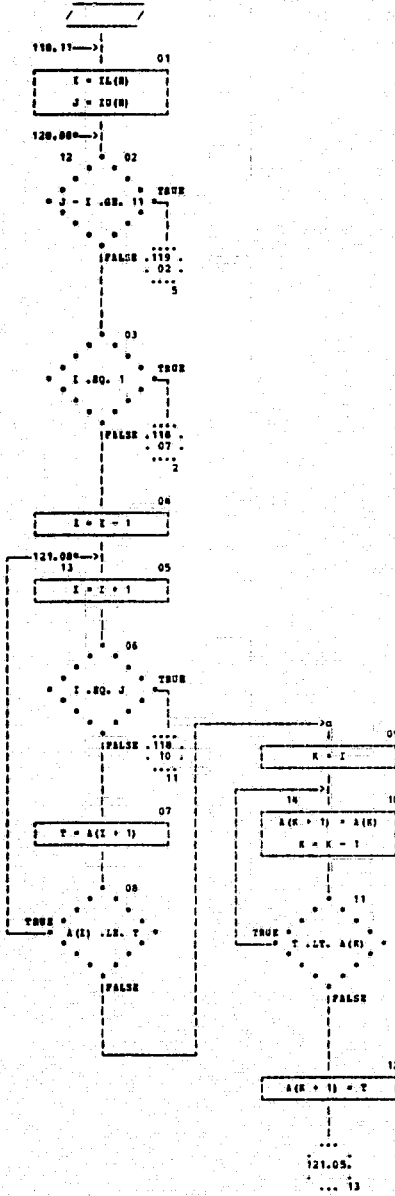


CHART TITLE - SUBROUTINE FIBON(FI,LI)



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AUTOPLOM CHART SET -

*PDR1

PAGE 123

CHART TITLE - SUBROUTINE HADD(A,B,C,R,NS)

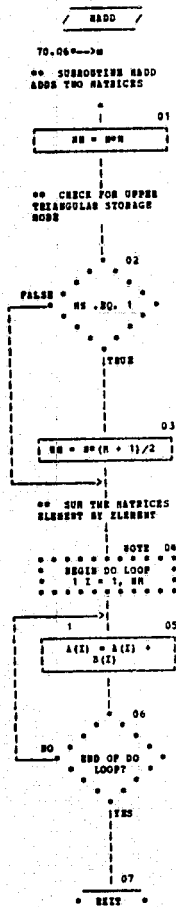
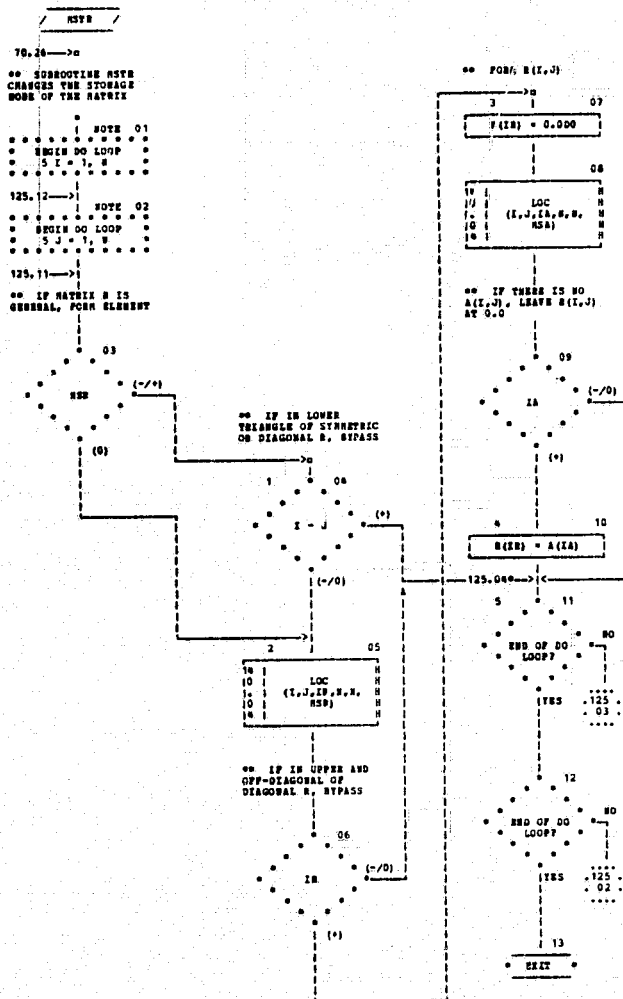


CHART TITLE - SUBROUTINE NSTR(A,N,N,NSA,NSR)



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AUTOPLOX CHART SET -

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PAGE 127

CHART TITLE - SUBROUTINE FILTER(A,S,NCOT,NPI)

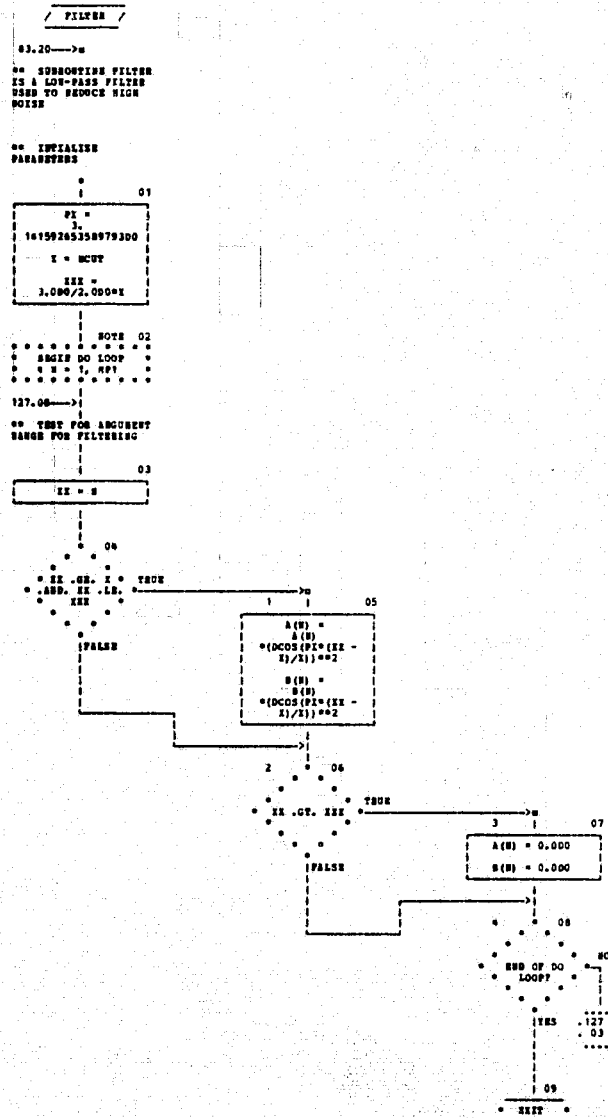
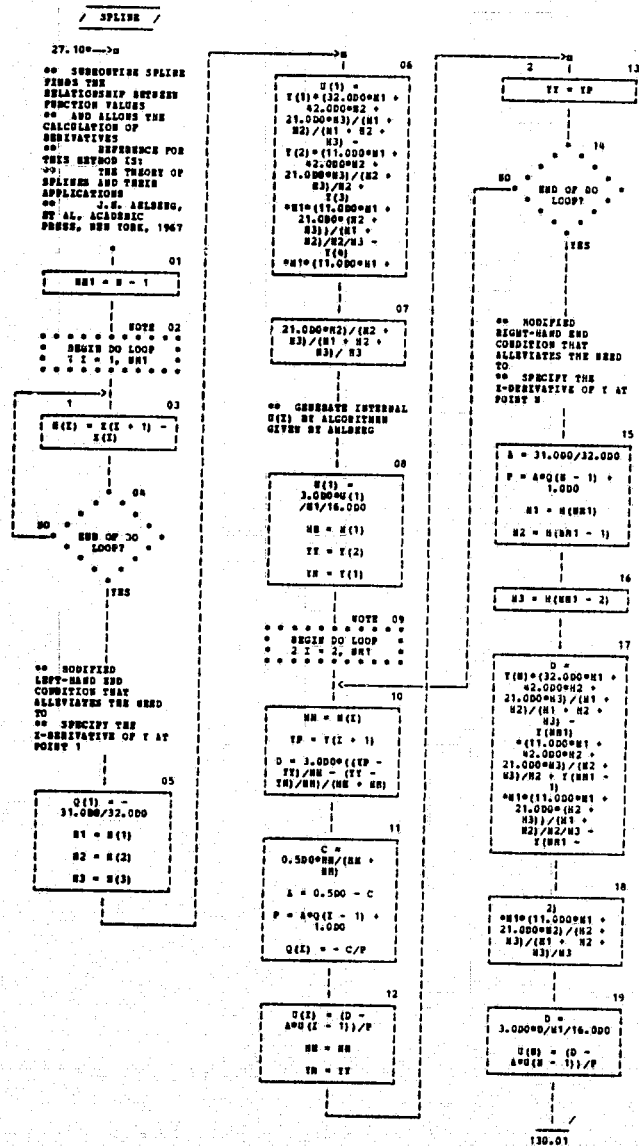


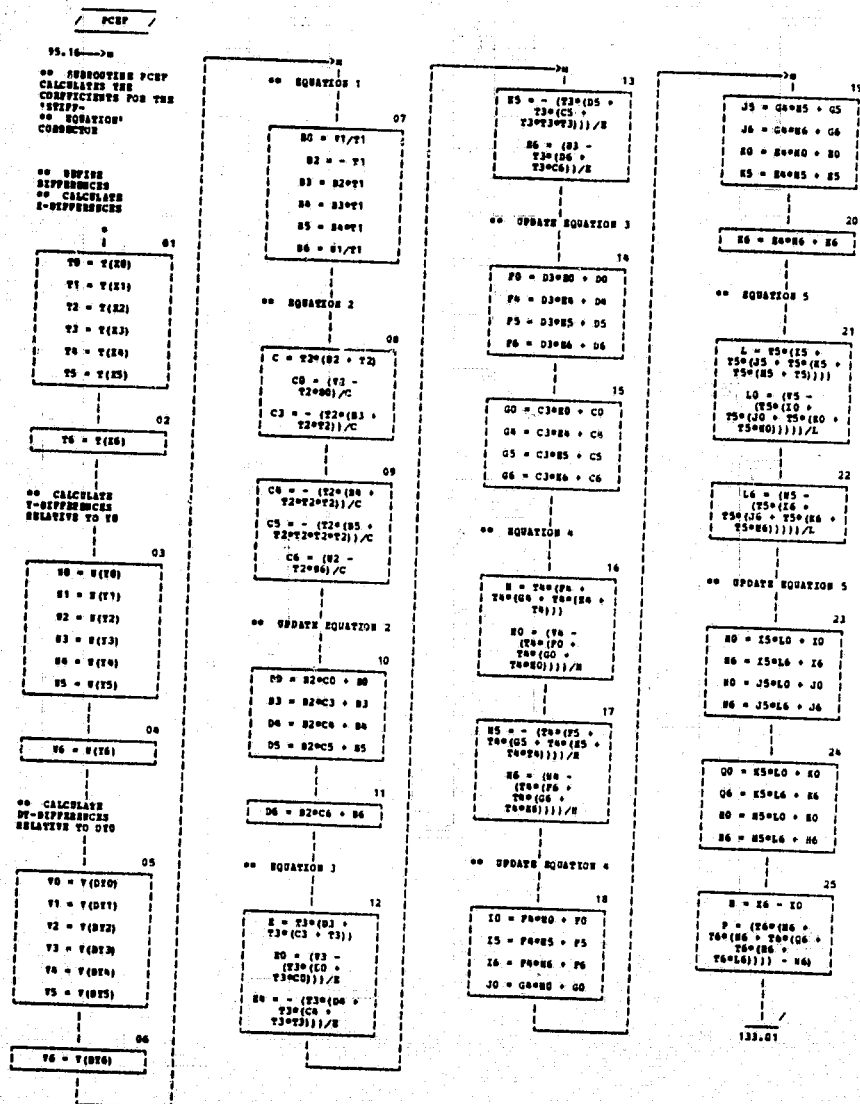
CHART TITLE - SUBROUTINE: SPLINE(U,Y,X,AA)



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Detailed description of Figure 1: The graph plots the rate of polymerization, R_p , against the concentration of the inhibitor, C_i . The y-axis (R_p) has major ticks at 0, 0.5, and 1.0. The x-axis (C_i) has major ticks at 0, 0.5, and 1.0. The curve is a smooth, decreasing curve that starts at $(0, 1.0)$ and approaches the x-axis as C_i increases. The curve is labeled with the equation $R_p = \frac{1}{1+C_i}$.





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CHART TITLE - SUBROUTINE PCRP

AUTOFLON CHART SET -

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PAGE 123

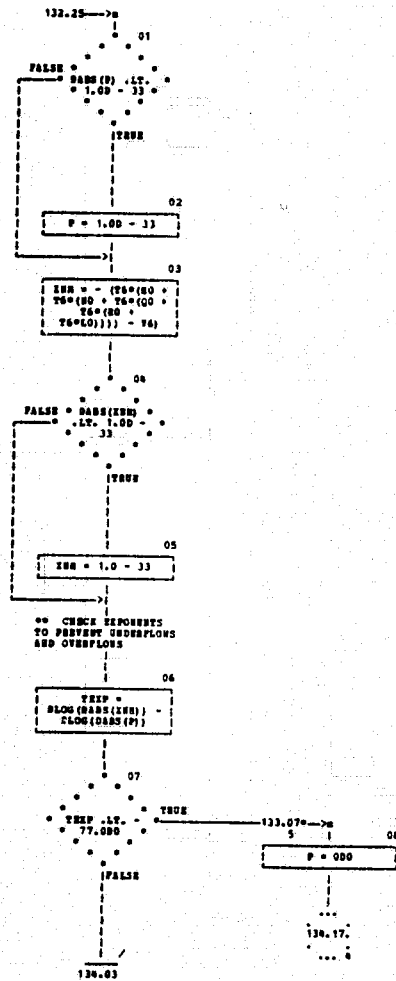
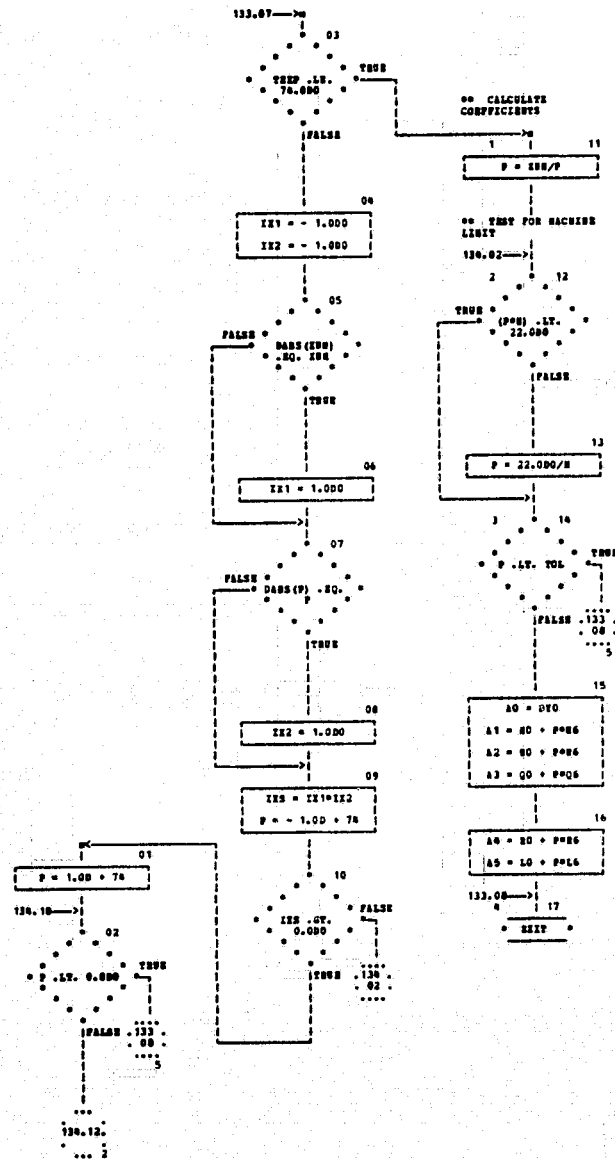
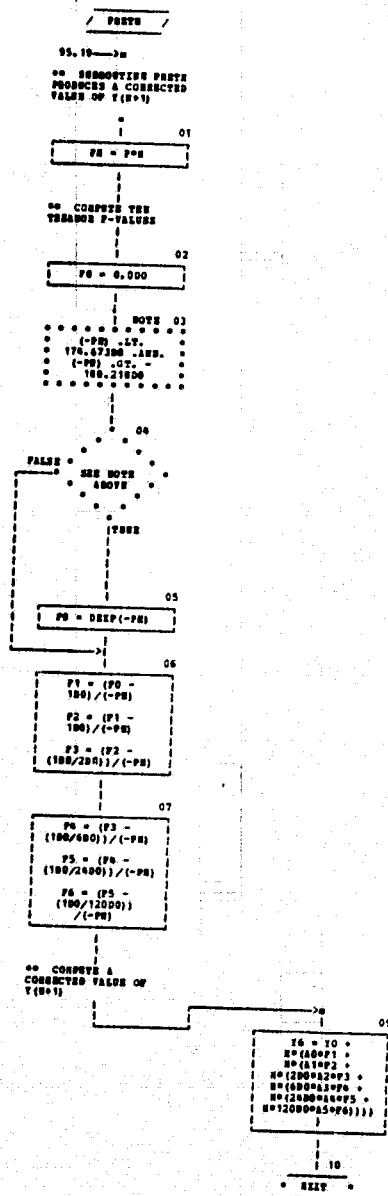


CHART TITLE - SUBOPTIM PCBP





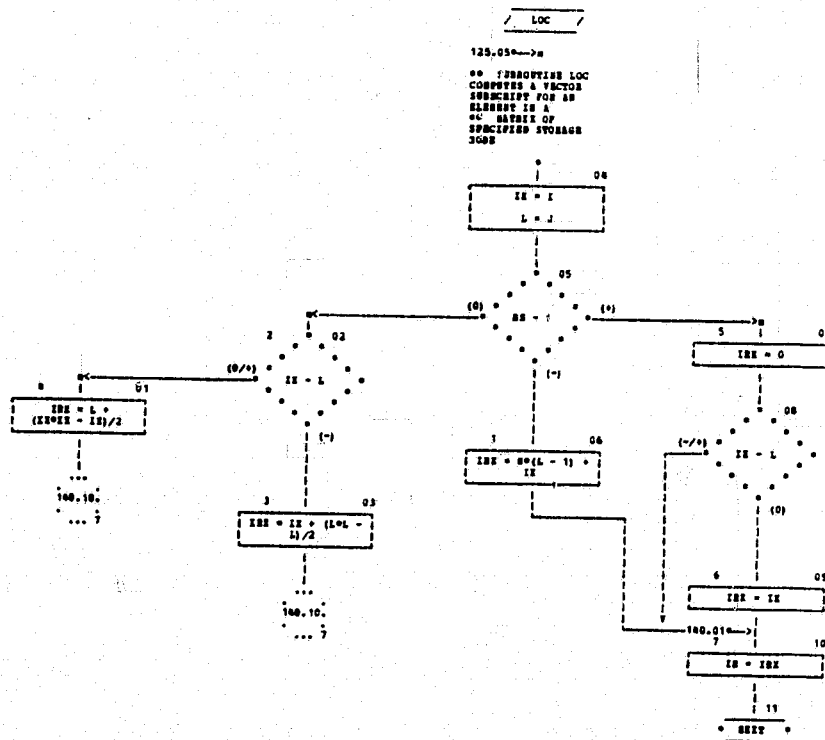
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CHART TITLE - SUBROUTINE LOC(I,J,LB,UB,UB)

APPROXIMATE CHART SET -

PF001

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Sample Input - FDR1

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4 4 4 4 0.025 0.033 0.025 0.040 0.30 0.040
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1.6889400 0.000 0.017453292500 1.000
459.7200 -32.174100

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132.0 -0.025
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161.333 -0.002
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7.361890100+04-2.254878960-02 7.443240560-01 1.937673180+00 1.419041560+03 646
1.27222350+02-8.119246610-01 3.618566850+01 646
7.361900100+04-2.905391660-02 9.643142040-01 1.938312140+00 1.421444140+03 647
1.27222350+02-6.494259260-01 3.648663770+01 647
7.361910100+04-2.180735120-02 1.117489690+00 2.001256450+00 1.419017040+03 648
1.272231800+02-4.006517620-01 3.628919330+01 648
7.361920100+04-2.471531840-02 8.338322770-01 1.969305080+00 1.419017040+03 649
1.272205360+02-8.730707330-01 3.667573920+01 649
7.361930100+04-2.628342640-02 5.533262610-01 1.937353700+00 1.419004790+03 650
1.276932410+02-7.390516730-01 3.606506640+01 650
7.361940100+04-1.867010300-02 5.845286120-01 1.904443900+00 1.417815750+03 651
1.275999330+02-4.140538170-01 3.666700600+01 651
7.361950100+04-2.516568990-02 5.867345910-01 1.779513710+00 1.420255100+03 652
1.276008750+02-7.021956670-01 3.621555260+01 652
7.361960100+04-1.698010690-02 8.042056290-01 1.937353710+00 1.421431880+03 653
1.276932410+02-5.748774150-01 3.656561560+01 653
7.361970100+04-2.086433370-02 7.096531570-01 1.905402330+00 1.417803500+03 654
1.276008750+02-1.024579890-01 3.640979480+01 654
7.361980100+04-2.520847250-02 6.154156240-01 1.873131480+00 1.419017040+03 655
1.276922570+02-5.799023100-01 3.648405340+01 655
7.361990100+04-2.086433370-02 5.517505640-01 1.809548210+00 1.419053810+03 656
1.275112610+02-4.229473400-01 3.630813210+01 656
7.362000100+04-2.515306900-02 4.278865750-01 1.779194230+00 1.422694460+03 657
1.280686650+02-2.623413730-02 3.646635970+01 657
7.362010100+04-1.533443370-02 5.205482130-01 1.904763380+00 1.422669340+03 658
1.276796450+02-5.438843870-01 3.624088810+01 658
7.362020100+04-2.084217230-02 4.263108800-01 1.809226740+00 1.420242850+03 659
1.276008750+02-3.596083030-01 3.635429630+01 659
7.362030100+04-2.300316100-02 3.635916370-01 1.747242850+00 1.420255100+03 660
1.276960660+02-3.060000000-01 3.638844920+01 660
7.362040100+04-1.972289540-02 3.301067090-01 1.874728870+00 1.421431880+03 661
1.276777630+02-2.364773240-01 3.647703250+01 661
7.362050100+04-2.084217230-02 1.083930380-01 1.967388220+00 1.417828010+03 662
1.274140530+02-2.900850520-01 3.632121140+01 662
7.362060100+04-2.299208040-02-2.638921300-01 1.745964950+00 1.421468650+03 663
1.276960660+02-3.060000000-01 3.628065490+01 663
7.362070100+04-1.855929590-02-1.384347030-01 1.745964950+00 1.421431880+03 664
1.276834150+02-1.049705880-01 3.610988190+01 664
7.362080100+04-1.422069710-02-4.630658870-02 1.745066520+00 1.417803500+03 665
1.27746350+02-2.507165460-01 3.665526590+01 665
7.362090100+04-1.911893430-02-1.708208380-01 1.649791350+00 1.419004790+03 666
1.271864790+02-1.099963320-01 3.690287330+01 666
7.362100100+04-1.531227220-02-1.692488740-01 1.817839980+00 1.417803500+03 667
1.276008750+02-3.746846580-01 3.676306130+01 667
7.362110100+04-1.858145730-02-1.140531250-02 1.586847030+00 1.419041560+03 668
1.276970060+02-5.388593080-01 3.687405690+01 668

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7.362120100+04-1.635398440-02 2.074342800-01 1.650110430+00 1.421456400+03 669
1.275746350+02-4.963783170-01 3.668728520+01 669
7.362130100+04-1.311804120-02 2.996131480-01 1.649152400+00 1.420218340+03 670
1.277817570+02-5.371840550-01 3.676199350+01 670
7.362140100+04-1.862023960-02 1.753660630-01 1.553937230+00 1.417791240+03 671
1.271285810+02-4.986535640-01 3.658589460+01 671
7.362150100+04-2.022713050-02 2.061802330-01 1.523263760+00 1.417815750+03 672
1.272241250+02-6.561264340-01 3.626571350+01 672
7.362160100+04-1.639276670-02 1.741044940-01 1.618478930+00 1.420255100+03 673
1.274140530+02-3.127016880-01 3.647596480+01 673
7.362170100+04-1.694686470-02 7.915084450-02 1.650110830+00 1.421456400+03 674
1.276865180+02-4.886013790-01 3.652932960+01 674
7.362180100+04-1.746218060-02-7.774953930-02 1.647235550+00 1.420255100+03 675
1.271323570+02-6.444000000-01 3.656988500+01 675
7.362190100+04-1.414867260-02-2.003774430-01 1.362548470+00 1.421480910+03 676
1.276018170+02-5.874416850-01 3.638631500+01 676
7.362200100+04-1.197660310-02-1.171971220-02 1.362867940+00 1.422657690+03 677
1.277864750+02-3.353172360-01 3.642366880+01 677
7.362210100+04-1.415975350-02 1.772551240-01 1.393221940+00 1.419029300+03 678
1.275989560+02-4.425322670-01 3.663712290+01 678
7.362220100+04-1.308479920-02 3.966842130-01 1.267652780+00 1.420267360+03 679
1.275074590+02-5.598000000-01 3.650371480+01 679
7.362230100+04-1.525686900-02 5.227541760-01 1.365104270+00 1.422694460+03 680
1.276960660+02-4.005532440-01 3.625317820+01 680
7.362240100+04-1.307371860-02 6.459879120-01 1.618478930+00 1.422657690+03 681
1.276758730+02-3.579325710-01 3.656988430+01 681

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THIS MUST BE A BLANK CARD
THIS MUST BE A BLANK CARD

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10000010011
010000001 -1.23897583300 0.000 1.000 10.000
0000000000000 PIOT CAND
-1 10 10 10 -1 10 10 -1 -1
0.000 0.000
0.000 0.000
0.000 0.000
0.000 0.000
0.000 0.000
0.000 0.000
000101
END

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Sample Output - FDR1

```

SECTION 1 INPUT PARAMETERS

                                NBETS= 1          ICODE
                                1
                                1

NETRIC= 1  XLML11= 0.0250  FCNRI= 0.022353  CP(1)= 0.0
NCMI12= 4  XLML12= 0.0250  XACGE= 1.023700  CP(2)= 0.0
NCMI13= 4  XLML13= 0.0250  PCORI= 0.022353  CP(3)= 0.1750-01
NCMI14= 4  YAU11= 0.0200  PCGCG= 8.0       CP(4)= 0.1750-01
NCMI15= 0  YAU12= 0.0200  PCGCG= 8.0       CP(5)= 0.1690-01
NCMI16= 0  YAU13= 0.0400  CALPE= -0.0200  CP(6)= 0.0
DE 190-0000  YAU14= 0.0400  CMSPZ= 0         CP(7)= 0.1700-01
OUTER 16  QUT= 7072.0000  LSP(1)= 1         CP(8)= 0.1000-01
LSP(2)= 0  LSP(3)= 1.612331  LSP(4)= 0       CP(9)= 0.0000-03
LSP(5)= 1  LSP(6)= 0  LSP(7)= 1  LSP(8)= 0   CP(10)= 0.2230-28
LSP(9)= 0  ELAM= 0.800000  ORNPT= -0.23     CP(11)= 0.0
                                           CP(12)= 0.0

VE          DPOCP

117.3330    -0.000000
120.0000    -0.000000
140.0070    -0.010000
101.3330    -0.002000
170.0000    0.003000
190.0070    0.107000
209.3330    0.010000
230.0000    0.013000
230.0070    0.013000
259.3330    0.013000
260.0000    0.013000
270.0070    0.010000

```

CALCULATED PHASE SHIFT COUNT = 0
CALCULATED PITCH ANGLE BIAS = 4.4310674201930-02 RADIAN
CALCULATED PITCH RATE BIAS = -2.6545965160010-03 RAD/SEC

[illegible]

59	5.820	17665.228	0.1821521	0.0001470	77.1876
60	5.800	17665.214	0.1800000	0.0078161	76.6685
61	5.800	17665.199	0.1780000	0.1532283	76.7799
62	5.800	17665.185	0.1760000	0.1306630	76.6045
63	5.800	17665.171	0.1740000	0.1066630	76.4205
64	5.800	17665.156	0.1720000	0.1066630	76.2320
65	5.800	17665.142	0.1700000	0.1066630	76.0425
66	5.800	17665.128	0.1680000	0.1066630	75.8502
67	5.800	17665.113	0.1660000	0.1066630	75.6577
68	5.800	17665.099	0.1640000	0.1066630	75.4652
69	5.800	17665.084	0.1620000	0.1066630	75.2727
70	5.800	17665.070	0.1600000	0.1066630	75.0802
71	5.800	17665.056	0.1580000	0.1066630	74.8877
72	5.800	17665.041	0.1560000	0.1066630	74.6952
73	5.800	17665.027	0.1540000	0.1066630	74.5027
74	5.800	17665.012	0.1520000	0.1066630	74.3102
75	5.800	17665.000	0.1500000	0.1066630	74.1177
76	5.800	17664.986	0.1480000	0.1066630	73.9252
77	5.800	17664.972	0.1460000	0.1066630	73.7327
78	5.800	17664.958	0.1440000	0.1066630	73.5402
79	5.800	17664.944	0.1420000	0.1066630	73.3477
80	5.800	17664.930	0.1400000	0.1066630	73.1552
81	5.800	17664.916	0.1380000	0.1066630	72.9627
82	5.800	17664.902	0.1360000	0.1066630	72.7702
83	5.800	17664.888	0.1340000	0.1066630	72.5777
84	5.800	17664.874	0.1320000	0.1066630	72.3852
85	5.800	17664.860	0.1300000	0.1066630	72.1927
86	5.800	17664.846	0.1280000	0.1066630	72.0002
87	5.800	17664.832	0.1260000	0.1066630	71.8077
88	5.800	17664.818	0.1240000	0.1066630	71.6152
89	5.800	17664.804	0.1220000	0.1066630	71.4227
90	5.800	17664.790	0.1200000	0.1066630	71.2302
91	5.800	17664.776	0.1180000	0.1066630	71.0377
92	5.800	17664.762	0.1160000	0.1066630	70.8452
93	5.800	17664.748	0.1140000	0.1066630	70.6527
94	5.800	17664.734	0.1120000	0.1066630	70.4602
95	5.800	17664.720	0.1100000	0.1066630	70.2677
96	5.800	17664.706	0.1080000	0.1066630	70.0752
97	5.800	17664.692	0.1060000	0.1066630	69.8827
98	5.800	17664.678	0.1040000	0.1066630	69.6902
99	5.800	17664.664	0.1020000	0.1066630	69.4977
100	5.800	17664.650	0.1000000	0.1066630	69.3052
101	5.800	17664.636	0.0980000	0.1066630	69.1127
102	5.800	17664.622	0.0960000	0.1066630	68.9202
103	5.800	17664.608	0.0940000	0.1066630	68.7277
104	5.800	17664.594	0.0920000	0.1066630	68.5352
105	5.800	17664.580	0.0900000	0.1066630	68.3427
106	5.800	17664.566	0.0880000	0.1066630	68.1502
107	5.800	17664.552	0.0860000	0.1066630	67.9577
108	5.800	17664.538	0.0840000	0.1066630	67.7652
109	5.800	17664.524	0.0820000	0.1066630	67.5727
110	5.800	17664.510	0.0800000	0.1066630	67.3802
111	5.800	17664.496	0.0780000	0.1066630	67.1877
112	5.800	17664.482	0.0760000	0.1066630	66.9952
113	5.800	17664.468	0.0740000	0.1066630	66.8027
114	5.800	17664.454	0.0720000	0.1066630	66.6102
115	5.800	17664.440	0.0700000	0.1066630	66.4177
116	5.800	17664.426	0.0680000	0.1066630	66.2252
117	5.800	17664.412	0.0660000	0.1066630	66.0327
118	5.800	17664.398	0.0640000	0.1066630	65.8402
119	5.800	17664.384	0.0620000	0.1066630	65.6477
120	5.800	17664.370	0.0600000	0.1066630	65.4552
121	5.800	17664.356	0.0580000	0.1066630	65.2627
122	5.800	17664.342	0.0560000	0.1066630	65.0702
123	5.800	17664.328	0.0540000	0.1066630	64.8777
124	5.800	17664.314	0.0520000	0.1066630	64.6852
125	5.800	17664.300	0.0500000	0.1066630	64.4927
126	5.800	17664.286	0.0480000	0.1066630	64.3002
127	5.800	17664.272	0.0460000	0.1066630	64.1077
128	5.800	17664.258	0.0440000	0.1066630	63.9152
129	5.800	17664.244	0.0420000	0.1066630	63.7227
130	5.800	17664.230	0.0400000	0.1066630	63.5302
131	5.800	17664.216	0.0380000	0.1066630	63.3377
132	5.800	17664.202	0.0360000	0.1066630	63.1452
133	5.800	17664.188	0.0340000	0.1066630	62.9527
134	5.800	17664.174	0.0320000	0.1066630	62.7602
135	5.800	17664.160	0.0300000	0.1066630	62.5677
136	5.800	17664.146	0.0280000	0.1066630	62.3752
137	5.800	17664.132	0.0260000	0.1066630	62.1827
138	5.800	17664.118	0.0240000	0.1066630	61.9902
139	5.800	17664.104	0.0220000	0.1066630	61.7977
140	5.800	17664.090	0.0200000	0.1066630	61.6052
141	5.800	17664.076	0.0180000	0.1066630	61.4127
142	5.800	17664.062	0.0160000	0.1066630	61.2202
143	5.800	17664.048	0.0140000	0.1066630	61.0277
144	5.800	17664.034	0.0120000	0.1066630	60.8352
145	5.800	17664.020	0.0100000	0.1066630	60.6427
146	5.800	17664.006	0.0080000	0.1066630	60.4502
147	5.800	17663.992	0.0060000	0.1066630	60.2577
148	5.800	17663.978	0.0040000	0.1066630	60.0652
149	5.800	17663.964	0.0020000	0.1066630	59.8727
150	5.800	17663.950	0.0000000	0.1066630	59.6802
151	5.800	17663.936	0.0000000	0.1066630	59.4877
152	5.800	17663.922	0.0000000	0.1066630	59.2952
153	5.800	17663.908	0.0000000	0.1066630	59.1027
154	5.800	17663.894	0.0000000	0.1066630	58.9102
155	5.800	17663.880	0.0000000	0.1066630	58.7177
156	5.800	17663.866	0.0000000	0.1066630	58.5252
157	5.800	17663.852	0.0000000	0.1066630	58.3327
158	5.800	17663.838	0.0000000	0.1066630	58.1402
159	5.800	17663.824	0.0000000	0.1066630	57.9477
160	5.800	17663.810	0.0000000	0.1066630	57.7552
161	5.800	17663.796	0.0000000	0.1066630	57.5627
162	5.800	17663.782	0.0000000	0.1066630	57.3702
163	5.800	17663.768	0.0000000	0.1066630	57.1777
164	5.800	17663.754	0.0000000	0.1066630	56.9852
165	5.800	17663.740	0.0000000	0.1066630	56.7927
166	5.800	17663.726	0.0000000	0.1066630	56.6002
167	5.800	17663.712	0.0000000	0.1066630	56.4077
168	5.800	17663.698	0.0000000	0.1066630	56.2152
169	5.800	17663.684	0.0000000	0.1066630	56.0227
170	5.800	17663.670	0.0000000	0.1066630	55.8302
171	5.800	17663.656	0.0000000	0.1066630	55.6377
172	5.800	17663.642	0.0000000	0.1066630	55.4452
173	5.800	17663.628	0.0000000	0.1066630	55.2527
174	5.800	17663.614	0.0000000	0.1066630	55.0602
175	5.800	17663.600	0.0000000	0.1066630	54.8677
176	5.800	17663.586	0.0000000	0.1066630	54.6752
177	5.800	17663.572	0.0000000	0.1066630	54.4827
178	5.800	17663.558	0.0000000	0.1066630	54.2902
179	5.800	17663.544	0.0000000	0.1066630	54.0977
180	5.800	17663.530	0.0000000	0.1066630	53.9052
181	5.800	17663.516	0.0000000	0.1066630	53.7127
182	5.800	17663.502	0.0000000	0.1066630	53.5202
183	5.800	17663.488	0.0000000	0.1066630	53.3277
184	5.800	17663.474	0.0000000	0.1066630	53.1352
185	5.800	17663.460	0.0000000	0.1066630	52.9427
186	5.800	17663.446	0.0000000	0.1066630	52.7502
187	5.800	17663.432	0.0000000	0.1066630	52.5577
188	5.800	17663.418	0.0000000	0.1066630	52.3652
189	5.800	17663.404	0.0000000	0.1066630	52.1727
190	5.800	17663.390	0.0000000	0.1066630	51.9802

ORIGINAL PAGE IS
OF POOR QUALITY

191	19.000	17603.276	-0.4181362	-0.0775211	56.9560
192	19.100	17603.216	-0.4239280	-0.0769776	56.9297
193	19.200	17603.260	-0.4231006	-0.0769680	57.1398
194	19.300	17603.299	-0.4237223	-0.0769600	57.4306
195	19.400	17603.271	-0.4244607	-0.0769600	57.7226
196	19.500	17603.257	-0.4251921	-0.0769601	58.0140
197	19.600	17603.242	-0.4259166	-0.0769772	58.3056
198	19.700	17603.228	-0.4266401	-0.0769700	58.5976
199	19.800	17603.213	-0.4273646	-0.0769600	58.8897
200	19.900	17603.199	-0.4280891	-0.0769600	59.1817
201	20.000	17603.185	-0.4288136	-0.0769600	59.4737
202	20.100	17603.170	-0.4295381	-0.0769600	59.7657
203	20.200	17603.156	-0.4302626	-0.0769600	60.0577
204	20.300	17603.142	-0.4309871	-0.0769600	60.3497
205	20.400	17603.127	-0.4317116	-0.0769600	60.6417
206	20.500	17603.113	-0.4324361	-0.0769600	60.9337
207	20.600	17603.098	-0.4331606	-0.0769600	61.2257
208	20.700	17603.084	-0.4338851	-0.0769600	61.5177
209	20.800	17603.070	-0.4346096	-0.0769600	61.8097
210	20.900	17603.055	-0.4353341	-0.0769600	62.1017
211	21.000	17603.041	-0.4360586	-0.0769600	62.3937
212	21.100	17603.026	-0.4367831	-0.0769600	62.6857
213	21.200	17603.012	-0.4375076	-0.0769600	62.9777
214	21.300	17602.998	-0.4382321	-0.0769600	63.2697
215	21.400	17602.983	-0.4389566	-0.0769600	63.5617
216	21.500	17602.969	-0.4396811	-0.0769600	63.8537
217	21.600	17602.954	-0.4404056	-0.0769600	64.1457
218	21.700	17602.940	-0.4411301	-0.0769600	64.4377
219	21.800	17602.926	-0.4418546	-0.0769600	64.7297
220	21.900	17602.911	-0.4425791	-0.0769600	65.0217
221	22.000	17602.897	-0.4433036	-0.0769600	65.3137
222	22.100	17602.882	-0.4440281	-0.0769600	65.6057
223	22.200	17602.868	-0.4447526	-0.0769600	65.8977
224	22.300	17602.853	-0.4454771	-0.0769600	66.1897
225	22.400	17602.839	-0.4462016	-0.0769600	66.4817
226	22.500	17602.825	-0.4469261	-0.0769600	66.7737
227	22.600	17602.811	-0.4476506	-0.0769600	67.0657
228	22.700	17602.796	-0.4483751	-0.0769600	67.3577
229	22.800	17602.782	-0.4491000	-0.0769600	67.6497
230	22.900	17602.767	-0.4498245	-0.0769600	67.9417
231	23.000	17602.753	-0.4505490	-0.0769600	68.2337
232	23.100	17602.739	-0.4512735	-0.0769600	68.5257
233	23.200	17602.724	-0.4520000	-0.0769600	68.8177
234	23.300	17602.710	-0.4527245	-0.0769600	69.1097
235	23.400	17602.695	-0.4534490	-0.0769600	69.4017
236	23.500	17602.681	-0.4541735	-0.0769600	69.6937
237	23.600	17602.667	-0.4548980	-0.0769600	69.9857
238	23.700	17602.652	-0.4556225	-0.0769600	70.2777
239	23.800	17602.638	-0.4563470	-0.0769600	70.5697
240	23.900	17602.624	-0.4570715	-0.0769600	70.8617
241	24.000	17602.609	-0.4577960	-0.0769600	71.1537
242	24.100	17602.595	-0.4585205	-0.0769600	71.4457
243	24.200	17602.581	-0.4592450	-0.0769600	71.7377
244	24.300	17602.566	-0.4599695	-0.0769600	72.0297
245	24.400	17602.552	-0.4606940	-0.0769600	72.3217
246	24.500	17602.537	-0.4614185	-0.0769600	72.6137
247	24.600	17602.523	-0.4621430	-0.0769600	72.9057
248	24.700	17602.509	-0.4628675	-0.0769600	73.1977
249	24.800	17602.494	-0.4635920	-0.0769600	73.4897
250	24.900	17602.480	-0.4643165	-0.0769600	73.7817
251	25.000	17602.465	-0.4650410	-0.0769600	74.0737
252	25.100	17602.451	-0.4657655	-0.0769600	74.3657
253	25.200	17602.436	-0.4664900	-0.0769600	74.6577
254	25.300	17602.422	-0.4672145	-0.0769600	74.9497
255	25.400	17602.408	-0.4679390	-0.0769600	75.2417
256	25.500	17602.393	-0.4686635	-0.0769600	75.5337
257	25.600	17602.379	-0.4693880	-0.0769600	75.8257
258	25.700	17602.364	-0.4701125	-0.0769600	76.1177
259	25.800	17602.350	-0.4708370	-0.0769600	76.4097
260	25.900	17602.336	-0.4715615	-0.0769600	76.7017
261	26.000	17602.321	-0.4722860	-0.0769600	76.9937
262	26.100	17602.307	-0.4730105	-0.0769600	77.2857
263	26.200	17602.292	-0.4737350	-0.0769600	77.5777
264	26.300	17602.278	-0.4744595	-0.0769600	77.8697
265	26.400	17602.264	-0.4751840	-0.0769600	78.1617
266	26.500	17602.249	-0.4759085	-0.0769600	78.4537
267	26.600	17602.235	-0.4766330	-0.0769600	78.7457
268	26.700	17602.220	-0.4773575	-0.0769600	79.0377
269	26.800	17602.206	-0.4780820	-0.0769600	79.3297
270	26.900	17602.192	-0.4788065	-0.0769600	79.6217
271	27.000	17602.177	-0.4795310	-0.0769600	79.9137
272	27.100	17602.163	-0.4802555	-0.0769600	80.2057
273	27.200	17602.148	-0.4809800	-0.0769600	80.4977
274	27.300	17602.134	-0.4817045	-0.0769600	80.7897
275	27.400	17602.119	-0.4824290	-0.0769600	81.0817
276	27.500	17602.105	-0.4831535	-0.0769600	81.3737
277	27.600	17602.091	-0.4838780	-0.0769600	81.6657
278	27.700	17602.077	-0.4846025	-0.0769600	81.9577
279	27.800	17602.062	-0.4853270	-0.0769600	82.2497
280	27.900	17602.048	-0.4860515	-0.0769600	82.5417
281	28.000	17602.033	-0.4867760	-0.0769600	82.8337
282	28.100	17602.019	-0.4875005	-0.0769600	83.1257
283	28.200	17601.999	-0.4882250	-0.0769600	83.4177
284	28.300	17601.980	-0.4889495	-0.0769600	83.7097
285	28.400	17601.960	-0.4896740	-0.0769600	84.0017
286	28.500	17601.941	-0.4903985	-0.0769600	84.2937
287	28.600	17601.921	-0.4911230	-0.0769600	84.5857
288	28.700	17601.902	-0.4918475	-0.0769600	84.8777
289	28.800	17601.883	-0.4925720	-0.0769600	85.1697
290	28.900	17601.863	-0.4932965	-0.0769600	85.4617
291	29.000	17601.844	-0.4940210	-0.0769600	85.7537
292	29.100	17601.825	-0.4947455	-0.0769600	86.0457
293	29.200	17601.805	-0.4954700	-0.0769600	86.3377
294	29.300	17601.786	-0.4961945	-0.0769600	86.6297
295	29.400	17601.767	-0.4969190	-0.0769600	86.9217
296	29.500	17601.747	-0.4976435	-0.0769600	87.2137
297	29.600	17601.728	-0.4983680	-0.0769600	87.5057
298	29.700	17601.709	-0.4990925	-0.0769600	87.7977
299	29.800	17601.689	-0.4998170	-0.0769600	88.0897
300	29.900	17601.670	-0.5005415	-0.0769600	88.3817
301	30.000	17601.651	-0.5012660	-0.0769600	88.6737
302	30.100	17601.631	-0.5019905	-0.0769600	88.9657
303	30.200	17601.612	-0.5027150	-0.0769600	89.2577
304	30.300	17601.593	-0.5034395	-0.0769600	89.5497
305	30.400	17601.573	-0.5041640	-0.0769600	89.8417
306	30.500	17601.554	-0.5048885	-0.0769600	90.1337
307	30.600	17601.535	-0.5056130	-0.0769600	90.4257
308	30.700	17601.515	-0.5063375	-0.0769600	90.7177
309	30.800	17601.496	-0.5070620	-0.0769600	91.0097
310	30.900	17601.477	-0.5077865	-0.0769600	91.3017
311	31.000	17601.457	-0.5085110	-0.0769600	91.5937
312	31.100	17601.438	-0.5092355	-0.0769600	91.8857
313	31.200	17601.419	-0.5099600	-0.0769600	92.1777
314	31.300	17601.399	-0.5106845	-0.0769600	92.4697
315	31.400	17601.380	-0.5114090	-0.0769600	92.7617
316	31.500	17601.361	-0.5121335	-0.0769600	93.0537
317	31.600	17601.341	-0.5128580	-0.0769600	93.3457
318	31.700	17601.322	-0.5135825	-0.0769600	93.6377
319	31.800	17601.303	-0.5143070	-0.0769600	93.9297
320	31.900	17601.283	-0.5150315	-0.0769600	94.2217
321	32.000	17601.264	-0.5157560	-0.0769600	94.5137
322	32.100	17601.244	-0.5164805	-0.0769600	94.8057

321	32.200	17681.429	0.0113133	-0.0012732	77.1786
322	32.200	17681.419	0.0088183	-0.0048118	77.1877
323	32.400	17681.400	0.0094367	-0.0061518	77.1979
324	32.600	17681.386	0.0137414	-0.0088991	77.2119
325	32.800	17681.371	0.0188163	0.0304391	77.2300
326	32.700	17681.357	0.0099018	0.0042680	77.2400
327	32.000	17681.243	0.0121095	0.0064492	77.2670
328	32.900	17681.320	0.0130630	0.0366220	77.2861

DATA POINT	TIME (SECS)	DENSITY (KG/M ³)	ANGLE OF ATTACK (RADIAN)	TEMPERATURE (DEG-K)	LONG. ACCEL. (M/SEC ²)
1	0.00	0.00027419	0.0104456	272.92	0.07961
2	0.100	0.00022597	0.0070670	272.96	0.01018
3	0.200	0.00017826	0.0027670	272.98	0.12250
4	0.300	0.00013124	0.0048381	272.97	0.10031
5	0.400	0.00008547	0.0086220	272.99	0.10086
6	0.500	0.00003967	0.0093663	272.90	0.09882
7	0.600	0.00009468	0.0098360	272.02	0.12776
8	0.700	0.00004948	0.0091347	272.03	0.09279
9	0.800	0.00001322	0.0097671	272.08	0.12786
10	0.900	0.00007528	0.0093002	272.06	0.07420
11	1.000	0.00003790	0.0086672	272.08	0.11723
12	1.100	0.00002317	0.0089070	272.09	0.11702
13	1.200	0.000077149	0.0096186	272.11	0.09672
14	1.300	0.000074081	0.0120980	272.12	0.11760
15	1.400	0.000071152	0.0083319	272.14	0.13296
16	1.500	0.000066730	0.0072132	272.15	0.13066
17	1.600	0.000066577	0.0121809	272.16	0.12805
18	1.700	0.000066327	0.0110433	272.16	0.12281
19	1.800	0.00002802	0.0122577	272.19	0.11768
20	1.900	0.00001460	0.0103317	272.20	0.13317
21	2.000	0.00003030	0.0112011	272.21	0.11783
22	2.100	0.00009538	0.0123630	272.22	0.11768
23	2.200	0.00006030	0.0113731	272.23	0.13315
24	2.300	0.00008099	0.0107943	272.24	0.09880
25	2.400	0.00009061	0.0115232	272.25	0.09893
26	2.500	0.00009550	0.0046006	272.26	0.13884
27	2.600	0.00003023	0.0080943	272.27	0.10037
28	2.700	0.00001482	0.0070670	272.28	0.10030
29	2.800	0.00002041	0.0091617	272.29	0.09930
30	2.900	0.000066468	0.0102643	272.30	0.09928
31	3.000	0.000066006	0.0091740	272.30	0.11832
32	3.100	0.000066820	0.0090940	272.31	0.13237
33	3.200	0.000071820	0.0090976	272.32	0.11718
34	3.300	0.000074908	0.0108071	272.32	0.11175
35	3.400	0.000077321	0.0075331	272.33	0.10668
36	3.500	0.00006637	0.0084513	272.33	0.09572
37	3.600	0.000066301	0.0090949	272.33	0.11718
38	3.700	0.00007532	0.0080943	272.34	0.11153
39	3.800	0.00001076	0.0089902	272.34	0.08489
40	3.900	0.00009075	0.0090949	272.35	0.10804
41	4.000	0.00009061	0.0080943	272.35	0.07306
42	4.100	0.000044495	0.0110306	272.35	0.06469
43	4.200	0.00008952	0.0080783	272.35	0.04991
44	4.300	0.00012047	0.0090949	272.35	0.17284
45	4.400	0.000018041	0.0102913	272.35	0.25917
46	4.500	0.000022599	0.0203641	272.35	0.32448
47	4.600	0.000070029	0.0120606	272.35	0.08828
48	4.700	0.000011809	0.0103640	272.35	0.09064
49	4.800	0.000035070	0.0333590	272.35	0.02467
50	4.900	0.000060303	0.0046006	272.35	0.06192
51	5.000	0.000066317	0.0046006	272.35	0.03280
52	5.100	0.000048321	0.0315034	272.35	0.03064
53	5.200	0.000092302	0.0061937	272.36	0.07313
54	5.300	0.000093026	0.0040931	272.36	0.07767
55	5.400	0.000090309	0.0022878	272.36	0.07070
56	5.500	0.000062251	0.0081025	272.36	0.03983
57	5.600	0.000066306	0.0119403	272.36	0.08001
58	5.700	0.000072687	0.0170900	272.35	0.08279
59	5.800	0.000091268	0.0082219	272.35	0.08486
60	5.900	0.000070300	0.0086829	272.32	0.08076
61	6.000	0.000072207	0.0170146	272.32	0.09087
62	6.100	0.000072646	0.0173820	272.31	0.04364
63	6.200	0.000073003	0.0175400	272.31	0.08003
64	6.300	0.000072646	0.0178267	272.30	0.09363
65	6.400	0.000071769	0.0170481	272.30	0.10861
66	6.500	0.000070300	0.0081190	272.30	0.10092
67	6.600	0.000068066	0.0084410	272.29	0.11138
68	6.700	0.000065632	0.0083399	272.28	0.12214
69	6.800	0.000062786	0.0080940	272.27	0.12226
70	6.900	0.000060868	0.0080863	272.27	0.12267
71	7.000	0.000064610	0.0082282	272.26	0.11808
72	7.100	0.000061997	0.0080470	272.25	0.14619
73	7.200	0.000063737	0.0086676	272.24	0.11709
74	7.300	0.000063708	0.0089773	272.24	0.11686
75	7.400	0.000062922	0.0086402	272.23	0.13060
76	7.500	0.000063108	0.0082761	272.22	0.12162
77	7.600	0.000061361	0.0087470	272.21	0.12583
78	7.700	0.000064515	0.0092917	272.20	0.12503
79	7.800	0.000064401	0.0092838	272.19	0.13060
80	7.900	0.000064094	0.0090949	272.18	0.12606
81	8.000	0.000073591	0.0092300	272.17	0.12873
82	8.100	0.000061811	0.0093163	272.16	0.13503
83	8.200	0.0000649637	0.0093506	272.15	0.13836
84	8.300	0.000063602	0.0090949	272.14	0.131261
85	8.400	0.000063672	0.0094048	272.13	0.13823
86	8.500	0.000060768	0.0104240	272.12	0.13804
87	8.600	0.000079435	0.0100488	272.11	0.14063
88	8.700	0.000077560	0.0098825	272.10	0.13826
89	8.800	0.000064440	0.0101573	272.09	0.136928
90	8.900	0.000064838	0.0102509	272.08	0.14202
91	9.000	0.0000721614	0.00968178	272.08	0.12027
92	9.100	0.000071680	0.0098000	272.05	0.10115
93	9.200	0.000077739	0.00968737	272.04	0.13704
94	9.300	0.000070724	0.00964401	272.03	0.09977
95	9.400	0.000061956	0.0082373	272.01	0.11096
96	9.500	0.000063525	0.0080941	272.00	0.06712
97	9.600	0.000062400	0.00788710	272.99	0.09728
98	9.700	0.000061199	0.00781713	272.98	0.08206
99	9.800	0.000060722	0.0094099	272.96	0.09286
100	9.900	0.0000608747	0.00705412	272.95	0.01566
101	10.000	0.000060991	0.0063894	272.93	0.00301
102	10.100	0.000061802	0.0062178	272.92	0.07670
103	10.200	0.000061808	0.0060561	272.91	0.05910
104	10.300	0.000061867	0.0048408	272.89	0.07664
105	10.400	0.000062319	0.0042877	272.88	0.076387
106	10.500	0.000060057	0.00414377	272.86	0.07680
107	10.600	0.000062498	0.0035276	272.85	0.07309
108	10.700	0.000061808	0.0032604	272.83	0.07200
109	10.800	0.000062970	0.0032330	272.82	0.07580
110	10.900	0.00006379110	0.0038880	272.80	0.07087
111	11.000	0.000063069	0.0031969	272.79	0.07567
112	11.100	0.000063492	0.0029300	272.77	0.07307
113	11.200	0.000063168	0.0025050	272.76	0.06384
114	11.300	0.000063078	0.0028189	272.74	0.07099
115	11.400	0.00006291197	0.0021480	272.72	0.07310
116	11.500	0.0000627878	0.0020000	272.71	0.07115
117	11.600	0.000062860	0.0196729	272.70	0.07363

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118	11.700	0.00028228	0.0211752	272.60	0.73568
119	11.800	0.00272280	0.0202836	272.60	0.74728
120	11.900	0.00222267	0.0170000	272.60	0.77468
121	12.000	0.00107872	0.0160700	272.60	0.78568
122	12.100	0.00193230	0.0201000	272.62	0.79087
123	12.200	0.00170246	0.0224107	272.60	0.79027
124	12.300	0.00150600	0.0221100	272.60	0.79036
125	12.400	0.00158123	0.0190022	272.60	0.80001
126	12.500	0.00137792	0.0201317	272.56	0.79573
127	12.600	0.00120339	0.0220700	272.64	0.81000
128	12.700	0.00109000	0.0202602	272.63	0.82110
129	12.800	0.00099562	0.0222300	272.61	0.79000
130	12.900	0.00087712	0.0222000	272.60	0.81021
131	13.000	0.00078001	0.0207230	272.62	0.82072
132	13.100	0.00069024	0.0207030	272.67	0.82904
133	13.200	0.00061412	0.0202300	272.65	0.80123
134	13.300	0.00054619	0.0221510	272.60	0.83000
135	13.400	0.00048604	0.0200110	272.62	0.80150
136	13.500	0.00042799	0.0200010	272.61	0.80000
137	13.600	0.00036170	0.0211441	272.56	0.82770
138	13.700	0.00029213	0.0220230	272.60	0.82230
139	13.800	0.00022747	0.0220700	272.57	0.80000
140	13.900	0.00016374	0.0201000	272.58	0.80000
141	14.000	0.00010000	0.0200000	272.56	0.80000
142	14.100	0.00003520	0.0207070	272.61	0.80000
143	14.200	0.00000100	0.0200000	272.60	0.80000
144	14.300	0.00000000	0.0200000	272.60	0.80000
145	14.400	0.00000000	0.0200000	272.60	0.80000
146	14.500	0.00000000	0.0200000	272.60	0.80000
147	14.600	0.00000000	0.0200000	272.60	0.80000
148	14.700	0.00000000	0.0200000	272.60	0.80000
149	14.800	0.00000000	0.0200000	272.60	0.80000
150	14.900	0.00000000	0.0200000	272.60	0.80000
151	15.000	0.00000000	0.0200000	272.60	0.80000
152	15.100	0.00000000	0.0200000	272.60	0.80000
153	15.200	0.00000000	0.0200000	272.60	0.80000
154	15.300	0.00000000	0.0200000	272.60	0.80000
155	15.400	0.00000000	0.0200000	272.60	0.80000
156	15.500	0.00000000	0.0200000	272.60	0.80000
157	15.600	0.00000000	0.0200000	272.60	0.80000
158	15.700	0.00000000	0.0200000	272.60	0.80000
159	15.800	0.00000000	0.0200000	272.60	0.80000
160	15.900	0.00000000	0.0200000	272.60	0.80000
161	16.000	0.00000000	0.0200000	272.60	0.80000
162	16.100	0.00000000	0.0200000	272.60	0.80000
163	16.200	0.00000000	0.0200000	272.60	0.80000
164	16.300	0.00000000	0.0200000	272.60	0.80000
165	16.400	0.00000000	0.0200000	272.60	0.80000
166	16.500	0.00000000	0.0200000	272.60	0.80000
167	16.600	0.00000000	0.0200000	272.60	0.80000
168	16.700	0.00000000	0.0200000	272.60	0.80000
169	16.800	0.00000000	0.0200000	272.60	0.80000
170	16.900	0.00000000	0.0200000	272.60	0.80000
171	17.000	0.00000000	0.0200000	272.60	0.80000
172	17.100	0.00000000	0.0200000	272.60	0.80000
173	17.200	0.00000000	0.0200000	272.60	0.80000
174	17.300	0.00000000	0.0200000	272.60	0.80000
175	17.400	0.00000000	0.0200000	272.60	0.80000
176	17.500	0.00000000	0.0200000	272.60	0.80000
177	17.600	0.00000000	0.0200000	272.60	0.80000
178	17.700	0.00000000	0.0200000	272.60	0.80000
179	17.800	0.00000000	0.0200000	272.60	0.80000
180	17.900	0.00000000	0.0200000	272.60	0.80000
181	18.000	0.00000000	0.0200000	272.60	0.80000
182	18.100	0.00000000	0.0200000	272.60	0.80000
183	18.200	0.00000000	0.0200000	272.60	0.80000
184	18.300	0.00000000	0.0200000	272.60	0.80000
185	18.400	0.00000000	0.0200000	272.60	0.80000
186	18.500	0.00000000	0.0200000	272.60	0.80000
187	18.600	0.00000000	0.0200000	272.60	0.80000
188	18.700	0.00000000	0.0200000	272.60	0.80000
189	18.800	0.00000000	0.0200000	272.60	0.80000
190	18.900	0.00000000	0.0200000	272.60	0.80000
191	19.000	0.00000000	0.0200000	272.60	0.80000
192	19.100	0.00000000	0.0200000	272.60	0.80000
193	19.200	0.00000000	0.0200000	272.60	0.80000
194	19.300	0.00000000	0.0200000	272.60	0.80000
195	19.400	0.00000000	0.0200000	272.60	0.80000
196	19.500	0.00000000	0.0200000	272.60	0.80000
197	19.600	0.00000000	0.0200000	272.60	0.80000
198	19.700	0.00000000	0.0200000	272.60	0.80000
199	19.800	0.00000000	0.0200000	272.60	0.80000
200	19.900	0.00000000	0.0200000	272.60	0.80000
201	20.000	0.00000000	0.0200000	272.60	0.80000
202	20.100	0.00000000	0.0200000	272.60	0.80000
203	20.200	0.00000000	0.0200000	272.60	0.80000
204	20.300	0.00000000	0.0200000	272.60	0.80000
205	20.400	0.00000000	0.0200000	272.60	0.80000
206	20.500	0.00000000	0.0200000	272.60	0.80000
207	20.600	0.00000000	0.0200000	272.60	0.80000
208	20.700	0.00000000	0.0200000	272.60	0.80000
209	20.800	0.00000000	0.0200000	272.60	0.80000
210	20.900	0.00000000	0.0200000	272.60	0.80000
211	21.000	0.00000000	0.0200000	272.60	0.80000
212	21.100	0.00000000	0.0200000	272.60	0.80000
213	21.200	0.00000000	0.0200000	272.60	0.80000
214	21.300	0.00000000	0.0200000	272.60	0.80000
215	21.400	0.00000000	0.0200000	272.60	0.80000
216	21.500	0.00000000	0.0200000	272.60	0.80000
217	21.600	0.00000000	0.0200000	272.60	0.80000
218	21.700	0.00000000	0.0200000	272.60	0.80000
219	21.800	0.00000000	0.0200000	272.60	0.80000
220	21.900	0.00000000	0.0200000	272.60	0.80000
221	22.000	0.00000000	0.0200000	272.60	0.80000
222	22.100	0.00000000	0.0200000	272.60	0.80000
223	22.200	0.00000000	0.0200000	272.60	0.80000
224	22.300	0.00000000	0.0200000	272.60	0.80000
225	22.400	0.00000000	0.0200000	272.60	0.80000
226	22.500	0.00000000	0.0200000	272.60	0.80000
227	22.600	0.00000000	0.0200000	272.60	0.80000
228	22.700	0.00000000	0.0200000	272.60	0.80000
229	22.800	0.00000000	0.0200000	272.60	0.80000
230	22.900	0.00000000	0.0200000	272.60	0.80000
231	23.000	0.00000000	0.0200000	272.60	0.80000
232	23.100	0.00000000	0.0200000	272.60	0.80000
233	23.200	0.00000000	0.0200000	272.60	0.80000
234	23.300	0.00000000	0.0200000	272.60	0.80000
235	23.400	0.00000000	0.0200000	272.60	0.80000
236	23.500	0.00000000	0.0200000	272.60	0.80000
237	23.600	0.00000000	0.0200000	272.60	0.80000
238	23.700	0.00000000	0.0200000	272.60	0.80000
239	23.800	0.00000000	0.0200000	272.60	0.80000
240	23.900	0.00000000	0.0200000	272.60	0.80000
241	24.000	0.00000000	0.0200000	272.60	0.80000
242	24.100	0.00000000	0.0200000	272.60	0.80000
243	24.200	0.00000000	0.0200000	272.60	0.80000
244	24.300	0.00000000	0.0200000	272.60	0.80000
245	24.400	0.00000000	0.0200000	272.60	0.80000
246	24.500	0.00000000	0.0200000	272.60	0.80000
247	24.600	0.00000000	0.0200000	272.60	0.80000
248	24.700	0.00000000	0.0200000	272.60	0.80000
249	24.800	0.00000000	0.0200000	272.60	0.80000
250	24.900	0.00000000	0.0200000	272.60	0.80000
251	25.000	0.00000000	0.0200000	272.60	0.80000

250	25.000	0.00230745	0.0000071	272.44	0.70303
251	25.000	0.00230745	0.0000071	272.44	0.70303
252	25.000	0.00230745	0.0000071	272.44	0.70303
253	25.000	0.00230745	0.0000071	272.44	0.70303
254	25.000	0.00230745	0.0000071	272.44	0.70303
255	25.000	0.00230745	0.0000071	272.44	0.70303
256	25.000	0.00230745	0.0000071	272.44	0.70303
257	25.000	0.00230745	0.0000071	272.44	0.70303
258	25.000	0.00230745	0.0000071	272.44	0.70303
259	25.000	0.00230745	0.0000071	272.44	0.70303
260	25.000	0.00230745	0.0000071	272.44	0.70303
261	25.000	0.00230745	0.0000071	272.44	0.70303
262	25.000	0.00230745	0.0000071	272.44	0.70303
263	25.000	0.00230745	0.0000071	272.44	0.70303
264	25.000	0.00230745	0.0000071	272.44	0.70303
265	25.000	0.00230745	0.0000071	272.44	0.70303
266	25.000	0.00230745	0.0000071	272.44	0.70303
267	25.000	0.00230745	0.0000071	272.44	0.70303
268	25.000	0.00230745	0.0000071	272.44	0.70303
269	25.000	0.00230745	0.0000071	272.44	0.70303
270	25.000	0.00230745	0.0000071	272.44	0.70303
271	25.000	0.00230745	0.0000071	272.44	0.70303
272	25.000	0.00230745	0.0000071	272.44	0.70303
273	25.000	0.00230745	0.0000071	272.44	0.70303
274	25.000	0.00230745	0.0000071	272.44	0.70303
275	25.000	0.00230745	0.0000071	272.44	0.70303
276	25.000	0.00230745	0.0000071	272.44	0.70303
277	25.000	0.00230745	0.0000071	272.44	0.70303
278	25.000	0.00230745	0.0000071	272.44	0.70303
279	25.000	0.00230745	0.0000071	272.44	0.70303
280	25.000	0.00230745	0.0000071	272.44	0.70303
281	25.000	0.00230745	0.0000071	272.44	0.70303
282	25.000	0.00230745	0.0000071	272.44	0.70303
283	25.000	0.00230745	0.0000071	272.44	0.70303
284	25.000	0.00230745	0.0000071	272.44	0.70303
285	25.000	0.00230745	0.0000071	272.44	0.70303
286	25.000	0.00230745	0.0000071	272.44	0.70303
287	25.000	0.00230745	0.0000071	272.44	0.70303
288	25.000	0.00230745	0.0000071	272.44	0.70303
289	25.000	0.00230745	0.0000071	272.44	0.70303
290	25.000	0.00230745	0.0000071	272.44	0.70303
291	25.000	0.00230745	0.0000071	272.44	0.70303
292	25.000	0.00230745	0.0000071	272.44	0.70303
293	25.000	0.00230745	0.0000071	272.44	0.70303
294	25.000	0.00230745	0.0000071	272.44	0.70303
295	25.000	0.00230745	0.0000071	272.44	0.70303
296	25.000	0.00230745	0.0000071	272.44	0.70303
297	25.000	0.00230745	0.0000071	272.44	0.70303
298	25.000	0.00230745	0.0000071	272.44	0.70303
299	25.000	0.00230745	0.0000071	272.44	0.70303
300	25.000	0.00230745	0.0000071	272.44	0.70303
301	25.000	0.00230745	0.0000071	272.44	0.70303
302	25.000	0.00230745	0.0000071	272.44	0.70303
303	25.000	0.00230745	0.0000071	272.44	0.70303
304	25.000	0.00230745	0.0000071	272.44	0.70303
305	25.000	0.00230745	0.0000071	272.44	0.70303
306	25.000	0.00230745	0.0000071	272.44	0.70303
307	25.000	0.00230745	0.0000071	272.44	0.70303
308	25.000	0.00230745	0.0000071	272.44	0.70303
309	25.000	0.00230745	0.0000071	272.44	0.70303
310	25.000	0.00230745	0.0000071	272.44	0.70303
311	25.000	0.00230745	0.0000071	272.44	0.70303
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313	25.000	0.00230745	0.0000071	272.44	0.70303
314	25.000	0.00230745	0.0000071	272.44	0.70303
315	25.000	0.00230745	0.0000071	272.44	0.70303
316	25.000	0.00230745	0.0000071	272.44	0.70303
317	25.000	0.00230745	0.0000071	272.44	0.70303
318	25.000	0.00230745	0.0000071	272.44	0.70303
319	25.000	0.00230745	0.0000071	272.44	0.70303
320	25.000	0.00230745	0.0000071	272.44	0.70303
321	25.000	0.00230745	0.0000071	272.44	0.70303
322	25.000	0.00230745	0.0000071	272.44	0.70303
323	25.000	0.00230745	0.0000071	272.44	0.70303
324	25.000	0.00230745	0.0000071	272.44	0.70303
325	25.000	0.00230745	0.0000071	272.44	0.70303
326	25.000	0.00230745	0.0000071	272.44	0.70303
327	25.000	0.00230745	0.0000071	272.44	0.70303
328	25.000	0.00230745	0.0000071	272.44	0.70303
329	25.000	0.00230745	0.0000071	272.44	0.70303
330	25.000	0.00230745	0.0000071	272.44	0.70303

DATA PCINT	TIME (SECS)	ALTITUDE (METERS)	VIRT. ACCEL (M/SEC^2)	ELEV. OFFSET (METERS)
1	0.0	3442.000	0.0	0.0
2	0.100	3442.032	0.0	0.0
3	0.200	3442.159	0.0	0.0
4	0.300	3442.480	0.0	0.0
5	0.400	3443.180	0.0	0.0
6	0.500	3444.093	0.0	0.0
7	0.600	3445.195	0.0	0.0
8	0.700	3446.437	0.0	0.0
9	0.800	3447.829	0.0	0.0
10	0.900	3449.381	0.0	0.0
11	1.000	3451.097	0.0	0.0
12	1.100	3452.987	0.0	0.0
13	1.200	3454.959	0.0	0.0
14	1.300	3457.023	0.0	0.0
15	1.400	3459.189	0.0	0.0
16	1.500	3461.467	0.0	0.0
17	1.600	3463.857	0.0	0.0
18	1.700	3466.359	0.0	0.0
19	1.800	3468.973	0.0	0.0
20	1.900	3471.700	0.0	0.0
21	2.000	3474.539	0.0	0.0
22	2.100	3477.490	0.0	0.0
23	2.200	3480.553	0.0	0.0
24	2.300	3483.728	0.0	0.0
25	2.400	3487.015	0.0	0.0
26	2.500	3490.414	0.0	0.0
27	2.600	3493.925	0.0	0.0
28	2.700	3497.548	0.0	0.0
29	2.800	3501.283	0.0	0.0
30	2.900	3505.130	0.0	0.0
31	3.000	3509.089	0.0	0.0
32	3.100	3513.160	0.0	0.0
33	3.200	3517.343	0.0	0.0
34	3.300	3521.638	0.0	0.0
35	3.400	3526.045	0.0	0.0
36	3.500	3530.564	0.0	0.0
37	3.600	3535.195	0.0	0.0
38	3.700	3539.938	0.0	0.0
39	3.800	3544.793	0.0	0.0
40	3.900	3549.760	0.0	0.0
41	4.000	3554.839	0.0	0.0
42	4.100	3559.930	0.0	0.0
43	4.200	3565.033	0.0	0.0
44	4.300	3570.148	0.0	0.0
45	4.400	3575.275	0.0	0.0
46	4.500	3580.414	0.0	0.0

ORIGINAL PAGE IS
OF POOR QUALITY

45	0.000	3442.129	0.0	0.0
46	0.000	3442.031	0.0	0.0
47	0.000	3442.140	0.0	0.0
48	0.000	3441.040	0.0	0.0
49	0.000	3441.151	0.0	0.0
50	0.000	3440.071	0.0	0.0
51	0.000	3440.216	0.0	0.0
52	0.150	3439.781	0.0	0.0
53	0.200	3439.230	0.0	0.0
54	0.300	3438.992	0.0	0.0
55	0.400	3438.091	0.0	0.0
56	0.500	3436.242	0.0	0.0
57	0.600	3437.930	0.0	0.0
58	0.700	3437.687	0.0	0.0
59	0.800	3437.406	0.0	0.0
60	0.900	3437.400	0.0	0.0
61	0.900	3437.143	0.0	0.0
62	0.100	3437.070	0.0	0.0
63	0.200	3437.023	0.0	0.0
64	0.300	3437.000	0.0	0.0
65	0.400	3437.100	0.0	0.0
66	0.500	3437.240	0.0	0.0
67	0.600	3437.560	0.0	0.0
68	0.700	3437.880	0.0	0.0
69	0.800	3438.102	0.0	0.0
70	0.900	3438.117	0.0	0.0
71	0.000	3438.136	0.0	0.0
72	0.100	3439.687	0.0	0.0
73	0.200	3440.001	0.0	0.0
74	0.300	3441.038	0.0	0.0
75	0.400	3441.064	0.0	0.0
76	0.500	3442.700	0.0	0.0
77	0.600	3442.600	0.0	0.0
78	0.700	3444.633	0.0	0.0
79	0.800	3445.786	0.0	0.0
80	0.900	3446.030	0.0	0.0
81	0.000	3446.880	0.0	0.0
82	0.100	3446.302	0.0	0.0
83	0.200	3446.710	0.0	0.0
84	0.300	3446.130	0.0	0.0
85	0.400	3446.886	0.0	0.0
86	0.500	3446.177	0.0	0.0
87	0.600	3446.036	0.0	0.0
88	0.700	3446.676	0.0	0.0
89	0.800	3446.146	0.0	0.0
90	0.900	3446.126	0.0	0.0
91	0.000	3446.612	0.0	0.0
92	0.100	3446.301	0.0	0.0
93	0.200	3447.044	0.0	0.0
94	0.300	3446.544	0.0	0.0
95	0.400	3471.560	0.0	0.0
96	0.500	3473.094	0.0	0.0
97	0.600	3475.025	0.0	0.0
98	0.700	3477.055	0.0	0.0
99	0.800	3479.708	0.0	0.0
100	0.900	3481.001	0.0	0.0
101	0.000	3482.949	0.0	0.0
102	0.100	3486.075	0.0	0.0
103	0.200	3486.209	0.0	0.0
104	0.300	3490.399	0.0	0.0
105	0.400	3492.462	0.0	0.0
106	0.500	3494.023	0.0	0.0
107	0.600	3496.723	0.0	0.0
108	0.700	3498.869	0.0	0.0
109	0.800	3499.866	0.0	0.0
110	0.900	3499.936	0.0	0.0
111	0.000	3500.001	0.0	0.0
112	0.100	3500.021	0.0	0.0
113	0.200	3500.080	0.0	0.0
114	0.300	3510.056	0.0	0.0
115	0.400	3512.710	0.0	0.0
116	0.500	3514.046	0.0	0.0
117	0.600	3516.366	0.0	0.0
118	0.700	3518.103	0.0	0.0
119	0.800	3519.026	0.0	0.0
120	0.900	3521.450	0.0	0.0
121	0.000	3523.111	0.0	0.0
122	0.100	3524.031	0.0	0.0
123	0.200	3526.189	0.0	0.0
124	0.300	3527.700	0.0	0.0
125	0.400	3528.902	0.0	0.0
126	0.500	3530.373	0.0	0.0
127	0.600	3531.751	0.0	0.0
128	0.700	3532.017	0.0	0.0
129	0.800	3539.068	0.0	0.0
130	0.900	3538.270	0.0	0.0
131	0.000	3536.263	0.0	0.0
132	0.100	3537.377	0.0	0.0
133	0.200	3538.322	0.0	0.0
134	0.300	3539.204	0.0	0.0
135	0.400	3540.153	0.0	0.0
136	0.500	3541.001	0.0	0.0
137	0.600	3541.808	0.0	0.0
138	0.700	3542.573	0.0	0.0
139	0.800	3543.227	0.0	0.0
140	0.900	3544.017	0.0	0.0
141	0.000	3544.496	0.0	0.0
142	0.100	3546.115	0.0	0.0
143	0.200	3545.700	0.0	0.0
144	0.300	3546.206	0.0	0.0
145	0.400	3546.309	0.0	0.0
146	0.500	3547.002	0.0	0.0
147	0.600	3547.026	0.0	0.0
148	0.700	3548.046	0.0	0.0
149	0.800	3548.269	0.0	0.0
150	0.900	3548.012	0.0	0.0
151	0.000	3549.102	0.0	0.0
152	0.100	3549.884	0.0	0.0
153	0.200	3549.921	0.0	0.0
154	0.300	3550.277	0.0	0.0
155	0.400	3550.578	0.0	0.0
156	0.500	3550.958	0.0	0.0
157	0.600	3551.223	0.0	0.0
158	0.700	3551.951	0.0	0.0
159	0.800	3551.968	0.0	0.0
160	0.900	3552.304	0.0	0.0
161	0.000	3552.580	0.0	0.0
162	0.100	3552.620	0.0	0.0
163	0.200	3552.217	0.0	0.0
164	0.300	3552.046	0.0	0.0
165	0.400	3552.022	0.0	0.0
166	0.500	3554.241	0.0	0.0
167	0.600	3554.686	0.0	0.0
168	0.700	3554.919	0.0	0.0
169	0.800	3555.309	0.0	0.0
170	0.900	3555.016	0.0	0.0
171	0.000	3556.150	0.0	0.0
172	0.100	3556.067	0.0	0.0
173	0.200	3556.979	0.0	0.0
174	0.300	3557.362	0.0	0.0
175	0.400	3557.630	0.0	0.0
176	0.500	3558.230	0.0	0.0

177	17.600	3550.700	0.0	0.0
178	17.700	3550.010	0.0	0.0
179	17.800	3549.511	0.0	0.0
180	17.900	3549.051	0.0	0.0
181	18.000	3548.217	0.0	0.0
182	18.100	3547.715	0.0	0.0
183	18.200	3547.107	0.0	0.0
184	18.300	3546.520	0.0	0.0
185	18.400	3545.951	0.0	0.0
186	18.500	3545.222	0.0	0.0
187	18.600	3544.600	0.0	0.0
188	18.700	3543.910	0.0	0.0
189	18.800	3543.176	0.0	0.0
190	18.900	3542.403	0.0	0.0
191	19.000	3541.703	0.0	0.0
192	19.100	3541.000	0.0	0.0
193	19.200	3540.295	0.0	0.0
194	19.300	3539.592	0.0	0.0
195	19.400	3538.891	0.0	0.0
196	19.500	3538.192	0.0	0.0
197	19.600	3537.495	0.0	0.0
198	19.700	3536.799	0.0	0.0
199	19.800	3536.105	0.0	0.0
200	19.900	3535.412	0.0	0.0
201	20.000	3534.720	0.0	0.0
202	20.100	3534.029	0.0	0.0
203	20.200	3533.339	0.0	0.0
204	20.300	3532.650	0.0	0.0
205	20.400	3531.961	0.0	0.0
206	20.500	3531.272	0.0	0.0
207	20.600	3530.583	0.0	0.0
208	20.700	3529.894	0.0	0.0
209	20.800	3529.205	0.0	0.0
210	20.900	3528.516	0.0	0.0
211	21.000	3527.827	0.0	0.0
212	21.100	3527.138	0.0	0.0
213	21.200	3526.448	0.0	0.0
214	21.300	3525.759	0.0	0.0
215	21.400	3525.070	0.0	0.0
216	21.500	3524.381	0.0	0.0
217	21.600	3523.692	0.0	0.0
218	21.700	3523.003	0.0	0.0
219	21.800	3522.314	0.0	0.0
220	21.900	3521.625	0.0	0.0
221	22.000	3520.936	0.0	0.0
222	22.100	3520.247	0.0	0.0
223	22.200	3519.558	0.0	0.0
224	22.300	3518.869	0.0	0.0
225	22.400	3518.180	0.0	0.0
226	22.500	3517.491	0.0	0.0
227	22.600	3516.802	0.0	0.0
228	22.700	3516.113	0.0	0.0
229	22.800	3515.424	0.0	0.0
230	22.900	3514.735	0.0	0.0
231	23.000	3514.046	0.0	0.0
232	23.100	3513.357	0.0	0.0
233	23.200	3512.668	0.0	0.0
234	23.300	3511.979	0.0	0.0
235	23.400	3511.290	0.0	0.0
236	23.500	3510.601	0.0	0.0
237	23.600	3509.912	0.0	0.0
238	23.700	3509.223	0.0	0.0
239	23.800	3508.534	0.0	0.0
240	23.900	3507.845	0.0	0.0
241	24.000	3507.156	0.0	0.0
242	24.100	3506.467	0.0	0.0
243	24.200	3505.778	0.0	0.0
244	24.300	3505.089	0.0	0.0
245	24.400	3504.400	0.0	0.0
246	24.500	3503.711	0.0	0.0
247	24.600	3503.022	0.0	0.0
248	24.700	3502.333	0.0	0.0
249	24.800	3501.644	0.0	0.0
250	24.900	3500.955	0.0	0.0
251	25.000	3500.266	0.0	0.0
252	25.100	3499.577	0.0	0.0
253	25.200	3498.888	0.0	0.0
254	25.300	3498.199	0.0	0.0
255	25.400	3497.510	0.0	0.0
256	25.500	3496.821	0.0	0.0
257	25.600	3496.132	0.0	0.0
258	25.700	3495.443	0.0	0.0
259	25.800	3494.754	0.0	0.0
260	25.900	3494.065	0.0	0.0
261	26.000	3493.376	0.0	0.0
262	26.100	3492.687	0.0	0.0
263	26.200	3491.998	0.0	0.0
264	26.300	3491.309	0.0	0.0
265	26.400	3490.620	0.0	0.0
266	26.500	3489.931	0.0	0.0
267	26.600	3489.242	0.0	0.0
268	26.700	3488.553	0.0	0.0
269	26.800	3487.864	0.0	0.0
270	26.900	3487.175	0.0	0.0
271	27.000	3486.486	0.0	0.0
272	27.100	3485.797	0.0	0.0
273	27.200	3485.108	0.0	0.0
274	27.300	3484.419	0.0	0.0
275	27.400	3483.730	0.0	0.0
276	27.500	3483.041	0.0	0.0
277	27.600	3482.352	0.0	0.0
278	27.700	3481.663	0.0	0.0
279	27.800	3480.974	0.0	0.0
280	27.900	3480.285	0.0	0.0
281	28.000	3479.596	0.0	0.0
282	28.100	3478.907	0.0	0.0
283	28.200	3478.218	0.0	0.0
284	28.300	3477.529	0.0	0.0
285	28.400	3476.840	0.0	0.0
286	28.500	3476.151	0.0	0.0
287	28.600	3475.462	0.0	0.0
288	28.700	3474.773	0.0	0.0
289	28.800	3474.084	0.0	0.0
290	28.900	3473.395	0.0	0.0
291	29.000	3472.706	0.0	0.0
292	29.100	3472.017	0.0	0.0
293	29.200	3471.328	0.0	0.0
294	29.300	3470.639	0.0	0.0
295	29.400	3469.950	0.0	0.0
296	29.500	3469.261	0.0	0.0
297	29.600	3468.572	0.0	0.0
298	29.700	3467.883	0.0	0.0
299	29.800	3467.194	0.0	0.0
300	29.900	3466.505	0.0	0.0
301	30.000	3465.816	0.0	0.0
302	30.100	3465.127	0.0	0.0
303	30.200	3464.438	0.0	0.0
304	30.300	3463.749	0.0	0.0
305	30.400	3463.060	0.0	0.0
306	30.500	3462.371	0.0	0.0
307	30.600	3461.682	0.0	0.0
308	30.700	3460.993	0.0	0.0

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309	30.900	3481.058	0.0	0.0
310	30.900	3481.424	0.0	0.0
311	31.000	3481.842	0.0	0.0
312	31.100	3482.229	0.0	0.0
313	31.200	3482.609	0.0	0.0
314	31.300	3482.970	0.0	0.0
315	31.400	3483.338	0.0	0.0
316	31.500	3483.696	0.0	0.0
317	31.600	3484.056	0.0	0.0
318	31.700	3484.404	0.0	0.0
319	31.800	3484.746	0.0	0.0
320	31.900	3485.088	0.0	0.0
321	32.000	3485.424	0.0	0.0
322	32.100	3485.757	0.0	0.0
323	32.200	3486.088	0.0	0.0
324	32.300	3486.417	0.0	0.0
325	32.400	3486.745	0.0	0.0
326	32.500	3487.069	0.0	0.0
327	32.600	3487.388	0.0	0.0
328	32.700	3487.704	0.0	0.0
329	32.800	3488.016	0.0	0.0
330	32.900	3488.324	0.0	0.0
331	33.000	3488.628	0.0	0.0

SECTION 2 INPUT PARAMETERS

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IP(1)=1 NC(1)=1 IP(1)=0 IP(1)=0
IP(2)=0 NC(2)=1 IP(2)=0 IP(2)=0
IP(3)=0 NC(3)=1 IP(3)=0 IP(3)=0
IP(4)=0 NC(4)=1 IP(4)=0 IP(4)=0
IP(5)=0 NC(5)=1 IP(5)=0 IP(5)=0
IP(6)=0 NC(6)=1 IP(6)=0 IP(6)=0
IP(7)=0 NC(7)=1 IP(7)=0 IP(7)=0
IP(8)=0 NC(8)=1 IP(8)=0 IP(8)=0
IP(9)=0 NC(9)=1 IP(9)=0 IP(9)=0
IP(10)=0 NC(10)=1 IP(10)=0 IP(10)=0
IP(11)=0 NC(11)=1 IP(11)=0 IP(11)=0
KARN = 0.12380758 IP(12)=0

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AP(1)=1.000000000000-10 W(1)=0.0
AP(2)=1.000000000000-10 W(2)=0.0
AP(3)=1.000000000000-10 W(3)=0.0
AP(4)=1.000000000000-10 W(4)=0.0
AP(5)=1.000000000000-10 W(5)=0.0
AP(6)=1.000000000000-10 W(6)=0.0

COMPATIBILITY ESTIMATES OF THE BIAS AND GAINS BETWEEN INPUT AND CALCULATED ANGLE OF ATTACK

BIAS = 0.34804441970200-04
FIRST-ORDER GAIN = 9.2715664960311070-01
SECOND-ORDER GAIN = 7.078123306740820-01
ANGLE-OF-ATTACK VARIANCE INDICATION = 2.1191300-04

COMPATIBILITY ESTIMATES OF THE BIAS AND GAINS BETWEEN INPUT AND CALCULATED ANGLE OF ATTACK

BIAS = 3.588501444127730-04
FIRST-ORDER GAIN = 9.0001267570596620-01
SECOND-ORDER GAIN = 3.9287257517269720-02
ANGLE-OF-ATTACK VARIANCE INDICATION = 1.7282340-05

COMPATIBILITY ESTIMATES OF THE BIAS AND GAINS BETWEEN INPUT AND CALCULATED ANGLE OF ATTACK

BIAS = 2.666739647282940-04
FIRST-ORDER GAIN = 1.3002990001402173-00
SECOND-ORDER GAIN = -2.2618519237684440-02
ANGLE-OF-ATTACK VARIANCE INDICATION = 2.1072080-05

ITERATION 1 SUBITERATION 1

COST FUNCTION (J) = 0.1895280996469300-03

WITH:

STATIC PRESSURE TOLERANCE = 0.0043110000000000-03
LONGITUDINAL ACCELERATION TOLERANCE = 0.7630390000000000-04

1ST LINEAR ACCELERATION DEPENDENCY DELTA = 3.0
2ND LINEAR ACCELERATION DEPENDENCY DELTA = 3.0
3RD LINEAR ACCELERATION DEPENDENCY DELTA = 3.0
PITCH ANGLE BIAS DELTA = -0.6642620-03

PHASE SHIFT DELTA = 0.0
 FLIGHT PATH ANGLE DELTA = -0.2339810-02
 UPDATED 1ST LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 2ND LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 3RD LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED PITCH ANGLE BIAS = -0.0002820-03
 UPDATED PHASE SHIFT = 0.0
 UPDATED FLIGHT PATH ANGLE BIAS = -8.2339810-02

ITERATION 1 SUBITERATION 2
 COST FUNCTION (J) = 2.267999281909700-02
 WITH:
 STATIC PRESSURE TOLERANCE = 2.3809088947578800-01
 LONGITUDINAL ACCELERATION TOLERANCE = 1.32253897279701680-03

1ST LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 2ND LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 3RD LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 PITCH ANGLE BIAS DELTA = 0.5338400-03
 PHASE SHIFT DELTA = 0.0
 FLIGHT PATH ANGLE DELTA = 0.3897260-02
 UPDATED 1ST LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 2ND LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 3RD LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED PITCH ANGLE BIAS = -0.1267320-03
 UPDATED PHASE SHIFT = 0.0
 UPDATED FLIGHT PATH ANGLE BIAS = 0.9582740-03

ITERATION 1 SUBITERATION 3
 COST FUNCTION (J) = 8.258768826345100-03
 WITH:
 STATIC PRESSURE TOLERANCE = 1.29081304781427600-02
 LONGITUDINAL ACCELERATION TOLERANCE = 3.62562189480056600-04

1ST LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 2ND LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 3RD LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 PITCH ANGLE BIAS DELTA = -0.8419670-04
 PHASE SHIFT DELTA = 0.0
 FLIGHT PATH ANGLE DELTA = -0.5208210-03
 UPDATED 1ST LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 2ND LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 3RD LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED PITCH ANGLE BIAS = -0.2181910-03
 UPDATED PHASE SHIFT = 0.0
 UPDATED FLIGHT PATH ANGLE BIAS = 0.4377530-03

ITERATION 1 SUBITERATION 4
 COST FUNCTION (J) = 5.8964186897586700-03
 WITH:
 STATIC PRESSURE TOLERANCE = 7.7408861946113730-04
 LONGITUDINAL ACCELERATION TOLERANCE = 3.44023687158641780-04

1ST LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 2ND LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 3RD LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 PITCH ANGLE BIAS DELTA = 0.1324210-04
 PHASE SHIFT DELTA = 0.0
 FLIGHT PATH ANGLE DELTA = 3.8188570-04
 UPDATED 1ST LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 2ND LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 3RD LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED PITCH ANGLE BIAS = -0.2018770-03
 UPDATED PHASE SHIFT = 0.0
 UPDATED FLIGHT PATH ANGLE BIAS = 0.3196190-03

ITERATION 1 SUBITERATION 5
 COST FUNCTION (J) = 5.8670436048491400-03
 WITH:
 STATIC PRESSURE TOLERANCE = 1.49819054754442100-03
 LONGITUDINAL ACCELERATION TOLERANCE = 3.42714113832319300-04

1ST LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 2ND LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 3RD LINEAR ACCELERATION DEPENDENCY DELTA = 0.0
 PITCH ANGLE BIAS DELTA = -0.2082840-03
 PHASE SHIFT DELTA = 0.0
 FLIGHT PATH ANGLE DELTA = -0.1287530-04
 UPDATED 1ST LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 2ND LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED 3RD LINEAR ACCELERATION DEPENDENCY = 0.0
 UPDATED PITCH ANGLE BIAS = -0.2037600-03
 UPDATED PHASE SHIFT = 0.0
 UPDATED FLIGHT PATH ANGLE BIAS = 0.3067630-03

ITERATION 1 SUBITERATION 6
 COST FUNCTION (J) = 5.86680289517105000-03
 WITH:
 STATIC PRESSURE TOLERANCE = 1.358014748942280000-03
 LONGITUDINAL ACCELERATION TOLERANCE = 3.4481388770118700-04

OF THE ABOVE 6 ITERATIONS, THE BEST COST FUNCTION HAS BEEN
 CHOSEN TO BE EQUAL TO 0.8670436048491400-03, AND THE VALUES
 ASSOCIATED WITH THIS COST FUNCTION (PHASE SHIFT VALUE IS SUB-
 JECT TO A MAGNITUDE AND SIGN RESTRICTION) WILL BE USED TO MOD-
 IFY DATA.

COMPATIBILITY ESTIMATES OF THE | BIAS = 0.7412954084448150-04
 BIAS AND GAINS BETWEEN INPUT 1-> FIRST-ORDER GAIN = 0.3185898682910430-01

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AND CALCULATED ANGLE OF ATTACK | SECOND-ORDER GAIN = 9.049492348968510-01
ANGLE-OF-ATTACK VARIANCE INDICATION = 2.060723D-06

COMPATIBILITY ESTIMATES OF THE | BIAS = 3.546362975537389D-04
BIAS AND GAINS BETWEEN INPUT -> FIRST-ORDER GAIN = 9.907789843720030D-01
AND CALCULATED ANGLE OF ATTACK | SECOND-ORDER GAIN = 9.697137767468000D-02
ANGLE-OF-ATTACK VARIANCE INDICATION = 1.705213D-05

COMPATIBILITY ESTIMATES OF THE | BIAS = 2.891961440536077D-04
BIAS AND GAINS BETWEEN INPUT -> FIRST-ORDER GAIN = 9.94610356572036D-01
AND CALCULATED ANGLE OF ATTACK | SECOND-ORDER GAIN = -1.503915194466186D-02
ANGLE-OF-ATTACK VARIANCE INDICATION = 2.022049D-05

COST FUNCTION (J) = 0.3822076277039400D-03
WITH:
STATIC PRESSURE TOLERANCE = 4.176208840448110D-03
LONGITUDINAL ACCELERATION TOLERANCE = 4.637635762958330D-04

FOURIER SERIES ANALYSIS WITH SPECIFIED HARMONICS

DATA POINT	TIME (SECS)	WEIGHT (NEWTONS)	PITCH ANGLE (RAUJANS)	PITCH RATE (RAUJ/SEC)	AIRSPEED (K/SEC)
1	0.0	17885.083	0.0007668	0.0008110	77.9111
2	0.100	17885.089	0.0002360	0.0013710	77.9177
3	0.200	17885.038	0.0004361	0.0020112	77.9266
4	0.300	17885.020	0.0007776	0.0033076	77.9311
5	0.400	17885.025	0.0012872	0.0042164	77.9377
6	0.500	17885.051	0.0018805	0.0051810	77.9463
7	0.600	17885.077	0.0024066	0.0060651	77.9506
8	0.700	17885.082	0.0034466	0.0069021	77.9567
9	0.800	17885.048	0.0043629	0.0076853	77.9625
10	0.900	17885.033	0.0051863	0.0082596	77.9680
11	1.000	17885.019	0.0064362	0.0087152	77.9731
12	1.100	17885.005	0.0074986	0.0090849	77.9778
13	1.200	17885.000	0.0083021	0.0093842	77.9820
14	1.300	17885.076	0.0093566	0.0096792	77.9858
15	1.400	17885.061	0.0103026	0.0098763	77.9890
16	1.500	17885.007	0.0111427	0.0100549	77.9918
17	1.600	17885.023	0.0120379	0.0102056	77.9941
18	1.700	17885.018	0.0126244	0.0103861	77.9959
19	1.800	17885.004	0.0132474	0.0104670	77.9973
20	1.900	17885.790	0.0138281	0.0105196	77.9983
21	2.000	17885.775	0.0143281	0.0105502	77.9990
22	2.100	17885.761	0.0148138	0.0105731	77.9996
23	2.200	17885.746	0.0152868	0.0105883	77.9998
24	2.300	17885.732	0.0157461	0.0105959	77.9999
25	2.400	17885.718	0.0161908	0.0105959	77.9999
26	2.500	17885.703	0.0166182	0.0105890	77.9998
27	2.600	17885.689	0.0170301	0.0105737	77.9997
28	2.700	17885.674	0.0174261	0.0105500	77.9993
29	2.800	17885.660	0.0178063	0.0105181	77.9986
30	2.900	17885.646	0.0181710	0.0104786	77.9976
31	3.000	17885.631	0.0185212	0.0104316	77.9963
32	3.100	17885.617	0.0188569	0.0103773	77.9948
33	3.200	17885.602	0.0191783	0.0103166	77.9931
34	3.300	17885.588	0.0194854	0.0102500	77.9912
35	3.400	17885.574	0.0197781	0.0101780	77.9892
36	3.500	17885.559	0.0200564	0.0101010	77.9869
37	3.600	17885.545	0.0203201	0.0100191	77.9843
38	3.700	17885.530	0.0205693	0.0099323	77.9815
39	3.800	17885.516	0.0208041	0.0098406	77.9785
40	3.900	17885.502	0.0210244	0.0097440	77.9753
41	4.000	17885.487	0.0212301	0.0096425	77.9718
42	4.100	17885.473	0.0214212	0.0095360	77.9681
43	4.200	17885.459	0.0215977	0.0094246	77.9642
44	4.300	17885.444	0.0217597	0.0093083	77.9599
45	4.400	17885.430	0.0219072	0.0091871	77.9553
46	4.500	17885.415	0.0220401	0.0090610	77.9504
47	4.600	17885.401	0.0221581	0.0089300	77.9452
48	4.700	17885.387	0.0222611	0.0087941	77.9397
49	4.800	17885.372	0.0223491	0.0086533	77.9340
50	4.900	17885.358	0.0224221	0.0085076	77.9280
51	5.000	17885.343	0.0224801	0.0083571	77.9218
52	5.100	17885.329	0.0225231	0.0082016	77.9153
53	5.200	17885.315	0.0225511	0.0080411	77.9086
54	5.300	17885.300	0.0225741	0.0078756	77.9017
55	5.400	17885.286	0.0225921	0.0077051	77.8946
56	5.500	17885.271	0.0226051	0.0075296	77.8873
57	5.600	17885.257	0.0226131	0.0073491	77.8798
58	5.700	17885.243	0.0226171	0.0071636	77.8721
59	5.800	17885.228	0.0226171	0.0069731	77.8642
60	5.900	17885.214	0.0226131	0.0067776	77.8561
61	6.000	17885.199	0.0226051	0.0065771	77.8478
62	6.100	17885.185	0.0225921	0.0063716	77.8393
63	6.200	17885.171	0.0225741	0.0061611	77.8306
64	6.300	17885.156	0.0225511	0.0059456	77.8217
65	6.400	17885.142	0.0225231	0.0057251	77.8126
66	6.500	17885.128	0.0224801	0.0055006	77.8033
67	6.600	17885.113	0.0224221	0.0052711	77.7938
68	6.700	17885.099	0.0223491	0.0050366	77.7841
69	6.800	17885.084	0.0222611	0.0047971	77.7742
70	6.900	17885.070	0.0221581	0.0045526	77.7641
71	7.000	17885.056	0.0220401	0.0043031	77.7538
72	7.100	17885.041	0.0219072	0.0040486	77.7433
73	7.200	17885.027	0.0217597	0.0037891	77.7326
74	7.300	17885.012	0.0215977	0.0035246	77.7217
75	7.400	17885.000	0.0214212	0.0032551	77.7106
76	7.500	17884.984	0.0212301	0.0029806	77.6993
77	7.600	17884.969	0.0210244	0.0027011	77.6878
78	7.700	17884.955	0.0208041	0.0024166	77.6761
79	7.800	17884.940	0.0205693	0.0021271	77.6642
80	7.900	17884.926	0.0203201	0.0018326	77.6521
81	8.000	17884.912	0.0200564	0.0015331	77.6398
82	8.100	17884.897	0.0197781	0.0012286	77.6273
83	8.200	17884.883	0.0194854	0.0009191	77.6146
84	8.300	17884.868	0.0191783	0.0006046	77.6017
85	8.400	17884.854	0.0188569	0.0002851	77.5886
86	8.500	17884.840	0.0185212	0.0000000	77.5753
87	8.600	17884.825	0.0181710	0.0000000	77.5618
88	8.700	17884.811	0.0178063	0.0000000	77.5481
89	8.800	17884.797	0.0174261	0.0000000	77.5342
90	8.900	17884.782	0.0170301	0.0000000	77.5201
91	9.000	17884.768	0.0166182	0.0000000	77.5058
92	9.100	17884.753	0.0161908	0.0000000	77.4913
93	9.200	17884.739	0.0157461	0.0000000	77.4766

94	9.300	17684.725	0.5103619	0.0416682	66.4899
95	9.400	17684.710	0.5113574	0.0135695	66.4715
96	9.500	17684.696	0.5123529	0.0263444	66.0614
97	9.600	17684.681	0.5133484	0.0116822	66.1812
98	9.700	17684.667	0.5143439	0.0114472	66.2412
99	9.800	17684.653	0.5153394	0.0082582	66.3212
100	9.900	17684.638	0.5163349	-0.0024259	66.4211
101	10.000	17684.624	0.5173304	-0.0216791	66.5177
102	10.100	17684.609	0.5183259	-0.0147193	62.6132
103	10.200	17684.595	0.5193214	-0.0201937	62.2109
104	10.300	17684.581	0.5203169	-0.0251921	62.0110
105	10.400	17684.566	0.5213124	-0.0296772	62.4137
106	10.500	17684.552	0.5223079	-0.0336838	62.0195
107	10.600	17684.537	0.5233034	-0.0372177	61.6254
108	10.700	17684.523	0.5242989	-0.0402051	61.2406
109	10.800	17684.508	0.5252944	-0.0429907	60.8670
110	10.900	17684.494	0.5262899	-0.0456286	60.4772
111	11.000	17684.480	0.5272854	-0.0472891	60.1017
112	11.100	17684.465	0.5282809	-0.0488979	59.7310
113	11.200	17684.451	0.5292764	-0.0504601	59.3850
114	11.300	17684.437	0.5302719	-0.0519792	59.0587
115	11.400	17684.422	0.5312674	-0.0534524	58.7499
116	11.500	17684.408	0.5322629	-0.0548821	58.4511
117	11.600	17684.394	0.5332584	-0.0562711	58.1605
118	11.700	17684.379	0.5342539	-0.0576254	57.8785
119	11.800	17684.365	0.5352494	-0.0589493	57.6037
120	11.900	17684.351	0.5362449	-0.0602369	57.3456
121	12.000	17684.336	0.5372404	-0.0614832	57.0939
122	12.100	17684.322	0.5382359	-0.0626840	56.8484
123	12.200	17684.307	0.5392314	-0.0638444	56.6096
124	12.300	17684.293	0.5402269	-0.0649600	56.3775
125	12.400	17684.278	0.5412224	-0.0660351	56.1525
126	12.500	17684.264	0.5422179	-0.0670644	55.9349
127	12.600	17684.250	0.5432134	-0.0680528	55.7241
128	12.700	17684.235	0.5442089	-0.0690050	55.5195
129	12.800	17684.221	0.5452044	-0.0700252	55.3216
130	12.900	17684.206	0.5462000	-0.0710080	55.1300
131	13.000	17684.192	0.5471955	-0.0720580	54.9452
132	13.100	17684.177	0.5481910	-0.0730796	54.7675
133	13.200	17684.163	0.5491865	-0.0740764	54.5965
134	13.300	17684.148	0.5501820	-0.0750440	54.4325
135	13.400	17684.134	0.5511775	-0.0760860	54.2750
136	13.500	17684.120	0.5521730	-0.0771060	54.1235
137	13.600	17684.105	0.5531685	-0.0781080	53.9775
138	13.700	17684.091	0.5541640	-0.0790860	53.8375
139	13.800	17684.077	0.5551595	-0.0800440	53.7025
140	13.900	17684.063	0.5561550	-0.0810760	53.5735
141	14.000	17684.048	0.5571505	-0.0820860	53.4500
142	14.100	17684.034	0.5581460	-0.0830760	53.3325
143	14.200	17684.019	0.5591415	-0.0840400	53.2215
144	14.300	17684.005	0.5601370	-0.0850740	53.1165
145	14.400	17683.991	0.5611325	-0.0860840	53.0175
146	14.500	17683.976	0.5621280	-0.0870660	52.9245
147	14.600	17683.962	0.5631235	-0.0880240	52.8375
148	14.700	17683.947	0.5641190	-0.0890620	52.7565
149	14.800	17683.933	0.5651145	-0.0900760	52.6815
150	14.900	17683.918	0.5661100	-0.0910700	52.6125
151	15.000	17683.904	0.5671055	-0.0920480	52.5495
152	15.100	17683.889	0.5681010	-0.0930060	52.4925
153	15.200	17683.875	0.5690965	-0.0939440	52.4415
154	15.300	17683.861	0.5700920	-0.0948580	52.3965
155	15.400	17683.846	0.5710875	-0.0957440	52.3575
156	15.500	17683.832	0.5720830	-0.0966060	52.3245
157	15.600	17683.818	0.5730785	-0.0974480	52.2975
158	15.700	17683.803	0.5740740	-0.0982660	52.2765
159	15.800	17683.789	0.5750695	-0.0990640	52.2615
160	15.900	17683.775	0.5760650	-0.0998380	52.2525
161	16.000	17683.760	0.5770605	-0.1005940	52.2495
162	16.100	17683.746	0.5780560	-0.1013280	52.2525
163	16.200	17683.732	0.5790515	-0.1020440	52.2615
164	16.300	17683.717	0.5800470	-0.1027360	52.2765
165	16.400	17683.703	0.5810425	-0.1034080	52.2975
166	16.500	17683.688	0.5820380	-0.1040640	52.3245
167	16.600	17683.674	0.5830335	-0.1047000	52.3575
168	16.700	17683.660	0.5840290	-0.1053200	52.3965
169	16.800	17683.645	0.5850245	-0.1059280	52.4415
170	16.900	17683.631	0.5860200	-0.1065200	52.4925
171	17.000	17683.616	0.5870155	-0.1070920	52.5495
172	17.100	17683.602	0.5880110	-0.1076480	52.6125
173	17.200	17683.587	0.5890065	-0.1081840	52.6815
174	17.300	17683.573	0.5900020	-0.1087040	52.7565
175	17.400	17683.558	0.5910000	-0.1092040	52.8375
176	17.500	17683.544	0.5920000	-0.1096800	52.9245
177	17.600	17683.530	0.5930000	-0.1101360	53.0175
178	17.700	17683.515	0.5940000	-0.1105760	53.1165
179	17.800	17683.501	0.5950000	-0.1110000	53.2215
180	17.900	17683.487	0.5960000	-0.1114080	53.3325
181	18.000	17683.472	0.5970000	-0.1118000	53.4495
182	18.100	17683.458	0.5980000	-0.1121760	53.5725
183	18.200	17683.444	0.5990000	-0.1125360	53.7015
184	18.300	17683.429	0.6000000	-0.1128800	53.8365
185	18.400	17683.415	0.6010000	-0.1132080	53.9775
186	18.500	17683.401	0.6020000	-0.1135200	54.1245
187	18.600	17683.386	0.6030000	-0.1138160	54.2775
188	18.700	17683.372	0.6040000	-0.1140960	54.4365
189	18.800	17683.357	0.6050000	-0.1143600	54.6015
190	18.900	17683.343	0.6060000	-0.1146080	54.7725
191	19.000	17683.329	0.6070000	-0.1148400	54.9495
192	19.100	17683.314	0.6080000	-0.1150560	55.1325
193	19.200	17683.300	0.6090000	-0.1152560	55.3215
194	19.300	17683.285	0.6100000	-0.1154400	55.5165
195	19.400	17683.271	0.6110000	-0.1156080	55.7175
196	19.500	17683.257	0.6120000	-0.1157600	55.9245
197	19.600	17683.242	0.6130000	-0.1158960	56.1375
198	19.700	17683.228	0.6140000	-0.1160160	56.3565
199	19.800	17683.213	0.6150000	-0.1161200	56.5815
200	19.900	17683.199	0.6160000	-0.1162080	56.8125
201	20.000	17683.185	0.6170000	-0.1162800	57.0495
202	20.100	17683.170	0.6180000	-0.1163360	57.2925
203	20.200	17683.156	0.6190000	-0.1163760	57.5415
204	20.300	17683.142	0.6200000	-0.1164000	57.7965
205	20.400	17683.127	0.6210000	-0.1164080	58.0575
206	20.500	17683.113	0.6220000	-0.1164000	58.3245
207	20.600	17683.098	0.6230000	-0.1163760	58.5975
208	20.700	17683.084	0.6240000	-0.1163360	58.8765
209	20.800	17683.070	0.6250000	-0.1162800	59.1615
210	20.900	17683.055	0.6260000	-0.1162080	59.4525
211	21.000	17683.041	0.6270000	-0.1161200	59.7495
212	21.100	17683.026	0.6280000	-0.1160080	60.0525
213	21.200	17683.012	0.6290000	-0.1158760	60.3615
214	21.300	17683.000	0.6300000	-0.1157200	60.6765
215	21.400	17682.983	0.6310000	-0.1155440	60.9975
216	21.500	17682.966	0.6320000	-0.1153480	61.3245
217	21.600	17682.954	0.6330000	-0.1151360	61.6575
218	21.700	17682.940	0.6340000	-0.1149000	61.9965
219	21.800	17682.926	0.6350000	-0.1146400	62.3415
220	21.900	17682.911	0.6360000	-0.1143600	62.6925
221	22.000	17682.897	0.6370000	-0.1140560	63.0495
222	22.100	17682.882	0.6380000	-0.1137280	63.4125
223	22.200	17682.868	0.6390000	-0.1133760	63.7815
224	22.300	17682.854	0.6400000	-0.1129960	64.1565
225	22.400	17682.839	0.6410000	-0.1125840	64.5375

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226	22.900	17662.625	-0.239926	0.0006727	68.2622
227	22.900	17662.611	-0.2398106	0.0006673	68.2601
228	22.900	17662.796	-0.2370268	0.0025021	68.0821
229	22.900	17662.762	-0.2225265	0.0033009	69.1398
230	22.900	17662.767	-0.2178446	0.0042712	69.4001
231	23.000	17662.763	-0.2122668	0.0043244	69.6999
232	23.100	17662.729	-0.2059060	0.0040981	69.9682
233	23.200	17662.724	-0.2037819	0.0040706	70.2309
234	23.300	17662.710	-0.1999089	0.0040603	70.4906
235	23.400	17662.498	-0.1929907	0.0041173	70.7434
236	23.500	17662.681	-0.1899203	0.0040795	70.9910
237	23.600	17662.667	-0.1868904	0.0040260	71.2329
238	23.700	17662.652	-0.1799268	0.0040719	71.4698
239	23.800	17662.628	-0.1738409	0.0040582	71.6992
240	23.900	17662.623	-0.1687181	0.0040285	71.9225
241	24.000	17662.609	-0.1636796	0.0040300	72.1418
242	24.100	17662.595	-0.1586465	0.0040281	72.3543
243	24.200	17662.580	-0.1542468	0.0040280	72.5608
244	24.300	17662.566	-0.1481762	0.0040094	72.7613
245	24.400	17662.551	-0.1420786	0.0040216	72.9559
246	24.500	17662.537	-0.1360200	0.0040128	73.1445
247	24.600	17662.523	-0.1320079	0.0040083	73.3273
248	24.700	17662.508	-0.1280110	0.0040077	73.5043
249	24.800	17662.494	-0.1241367	0.00401472	73.6754
250	24.900	17662.480	-0.1183214	0.0040309	73.8409
251	25.000	17662.465	-0.1135881	0.0040312	74.0008
252	25.100	17662.451	-0.1089067	0.0040464	74.1581
253	25.200	17662.436	-0.1042137	0.0040782	74.3041
254	25.300	17662.422	-0.0995060	0.0040926	74.4477
255	25.400	17662.408	-0.0952735	0.0040282	74.5861
256	25.500	17662.393	-0.0910264	0.00412789	74.7196
257	25.600	17662.379	-0.0867601	0.0040609	74.8486
258	25.700	17662.364	-0.0824871	0.0040787	74.9716
259	25.800	17662.350	-0.0782639	0.0040636	75.0902
260	25.900	17662.336	-0.0740268	0.00406103	75.2045
261	26.000	17662.321	-0.0697729	0.00407752	75.3145
262	26.100	17662.307	-0.0655063	0.00407074	75.4197
263	26.200	17662.292	-0.0612777	0.00406486	75.5208
264	26.300	17662.278	-0.0570041	0.00406953	75.6178
265	26.400	17662.264	-0.0527794	0.00405363	75.7109
266	26.500	17662.249	-0.0485769	0.00404720	75.7999
267	26.600	17662.235	-0.0443823	0.00404051	75.8850
268	26.700	17662.220	-0.0401876	0.00403367	75.9665
269	26.800	17662.206	-0.0359906	0.004031012	76.0442
270	26.900	17662.192	-0.0317915	0.00402867	76.1185
271	27.000	17662.177	-0.0275901	0.004016151	76.1892
272	27.100	17662.163	-0.0233823	0.00401823	76.2566
273	27.200	17662.149	-0.0191794	0.00400698	76.3200
274	27.300	17662.134	-0.0149726	0.00400351	76.3715
275	27.400	17662.120	-0.0107606	0.00400239	76.4192
276	27.500	17662.105	-0.0065486	0.00400019	76.4639
277	27.600	17662.091	-0.0023366	0.0040007570	76.5067
278	27.700	17662.077	-0.0018166	0.00400460	76.5467
279	27.800	17662.062	-0.0014131	0.004003589	76.5849
280	27.900	17662.048	-0.0010206	0.004002688	76.6204
281	28.000	17662.033	-0.0006281	0.004001810	76.6544
282	28.100	17662.019	-0.0002352	0.004000979	76.6860
283	28.200	17662.005	-0.0001427	0.004000164	76.7162
284	28.300	17661.990	-0.0000502	0.00400077501	76.7450
285	28.400	17661.976	-0.0000477	0.00400113	76.7724
286	28.500	17661.961	-0.0000501	0.00400157296	76.7987
287	28.600	17661.947	-0.0000741	0.0040018021	76.8235
288	28.700	17661.933	0.00004413	0.0040013686	76.8468
289	28.800	17661.918	0.0001315	0.00400131978	76.86737
290	28.900	17661.904	0.00027156	0.00400126268	76.88601
291	29.000	17661.889	0.0004717	0.00400117906	76.90172
292	29.100	17661.875	0.0007170	0.00400112044	76.91566
293	29.200	17661.861	0.0009642	0.00400106786	76.92804
294	29.300	17661.846	0.0012104	0.00400102056	76.93913
295	29.400	17661.832	0.0014566	0.00400097779	76.94887
296	29.500	17661.818	0.0017028	0.00400093866	76.95734
297	29.600	17661.803	0.0019490	0.00400090226	76.96457
298	29.700	17661.789	0.0021951	0.00400086763	76.97058
299	29.800	17661.774	0.0024413	0.00400083281	76.97537
300	29.900	17661.760	0.0026875	0.00400079887	76.97897
301	30.000	17661.746	0.0029337	0.00400076496	76.98145
302	30.100	17661.731	0.0031799	0.00400073107	76.98281
303	30.200	17661.717	0.0034261	0.00400069713	76.98307
304	30.300	17661.702	0.0036723	0.00400066321	76.98224
305	30.400	17661.688	0.0039185	0.00400062930	76.98033
306	30.500	17661.674	0.0041647	0.00400059538	76.97736
307	30.600	17661.659	0.0044109	0.00400056146	76.97333
308	30.700	17661.645	0.0046571	0.00400052754	76.96824
309	30.800	17661.630	0.0049033	0.00400049362	76.96210
310	30.900	17661.616	0.0051495	0.00400045970	76.95491
311	31.000	17661.602	0.0053957	0.00400042578	76.94668
312	31.100	17661.587	0.0056419	0.00400039186	76.93741
313	31.200	17661.573	0.0058881	0.00400035794	76.92710
314	31.300	17661.558	0.0061343	0.00400032402	76.91577
315	31.400	17661.544	0.0063805	0.00400029010	76.90342
316	31.500	17661.530	0.0066267	0.00400025618	76.89007
317	31.600	17661.516	0.0068729	0.00400022226	76.87572
318	31.700	17661.501	0.0071191	0.00400018834	76.86037
319	31.800	17661.487	0.0073653	0.00400015442	76.84402
320	31.900	17661.472	0.0076115	0.00400012050	76.82667
321	32.000	17661.458	0.0078577	0.00400008658	76.80832
322	32.100	17661.443	0.0081039	0.00400005266	76.78897
323	32.200	17661.429	0.0083501	0.00400001874	76.76862
324	32.300	17661.415	0.0085963	0.00400000000	76.74727
325	32.400	17661.400	0.0088425	0.00400000000	76.72492
326	32.500	17661.386	0.0090887	0.00400000000	76.70157
327	32.600	17661.371	0.0093349	0.00400000000	76.67722
328	32.700	17661.357	0.0095811	0.00400000000	76.65187
329	32.800	17661.343	0.0098273	0.00400000000	76.62552

DATA POINT	TIME (SECS)	DENSITY (G/CM ³)	ANGLE UP ATTACK (RADIANS)	TEMPERATURE (DEG-K)	ACCELERATION (M/SEC ²)
1	0.0	0.00000072	0.0102062	272.91	0.00614
2	0.100	0.00000719	0.0099809	272.92	0.00607
3	0.200	0.00000318	0.0097223	272.94	0.00610
4	0.300	0.00000566	0.0094637	272.96	0.00607
5	0.400	0.00000263	0.0092051	272.97	0.00607
6	0.500	0.00000609	0.0089465	272.99	0.00608
7	0.600	0.00000701	0.0086879	273.01	0.00602
8	0.700	0.00000763	0.0084293	273.02	0.00597
9	0.800	0.00000733	0.0081707	273.04	0.00587
10	0.900	0.00000876	0.0079121	273.05	0.00586
11	1.000	0.00000270	0.0076535	273.07	0.00489
12	1.100	0.00000421	0.0073949	273.08	0.00485
13	1.200	0.00000532	0.0071363	273.10	0.00495
14	1.300	0.00000608	0.0068777	273.11	0.00512
15	1.400	0.00000647	0.0066191	273.13	0.00502
16	1.500	0.00000660	0.0063605	273.14	0.00506
17	1.600	0.00000608	0.0061019	273.15	0.00501
18	1.700	0.00000617	0.0058433	273.17	0.00468
19	1.800	0.00000571	0.0055847	273.18	0.00418
20	1.900	0.00000519	0.0053261	273.19	0.00407
21	2.000	0.00000452	0.0050675	273.21	0.00472

22	2.100	0.00988306	0.0126187	273.22	0.00191
23	2.200	0.00988306	0.0126187	273.23	-0.00036
24	2.300	0.00988306	0.0126187	273.24	-0.00207
25	2.400	0.00988306	0.0126187	273.25	-0.00337
26	2.500	0.00988306	0.0126187	273.26	-0.00439
27	2.600	0.00988306	0.0126187	273.27	-0.00504
28	2.700	0.00988306	0.0126187	273.28	-0.00543
29	2.800	0.00988306	0.0126187	273.29	-0.00558
30	2.900	0.00988306	0.0126187	273.30	-0.00561
31	3.000	0.00988306	0.0126187	273.31	-0.00554
32	3.100	0.00988306	0.0126187	273.32	-0.00536
33	3.200	0.00988306	0.0126187	273.33	-0.00507
34	3.300	0.00988306	0.0126187	273.34	-0.00468
35	3.400	0.00988306	0.0126187	273.35	-0.00419
36	3.500	0.00988306	0.0126187	273.36	-0.00360
37	3.600	0.00988306	0.0126187	273.37	-0.00291
38	3.700	0.00988306	0.0126187	273.38	-0.00212
39	3.800	0.00988306	0.0126187	273.39	-0.00123
40	3.900	0.00988306	0.0126187	273.40	-0.00024
41	4.000	0.00988306	0.0126187	273.41	0.00075
42	4.100	0.00988306	0.0126187	273.42	0.00176
43	4.200	0.00988306	0.0126187	273.43	0.00277
44	4.300	0.00988306	0.0126187	273.44	0.00378
45	4.400	0.00988306	0.0126187	273.45	0.00479
46	4.500	0.00988306	0.0126187	273.46	0.00580
47	4.600	0.00988306	0.0126187	273.47	0.00681
48	4.700	0.00988306	0.0126187	273.48	0.00782
49	4.800	0.00988306	0.0126187	273.49	0.00883
50	4.900	0.00988306	0.0126187	273.50	0.00984
51	5.000	0.00988306	0.0126187	273.51	0.01085
52	5.100	0.00988306	0.0126187	273.52	0.01186
53	5.200	0.00988306	0.0126187	273.53	0.01287
54	5.300	0.00988306	0.0126187	273.54	0.01388
55	5.400	0.00988306	0.0126187	273.55	0.01489
56	5.500	0.00988306	0.0126187	273.56	0.01590
57	5.600	0.00988306	0.0126187	273.57	0.01691
58	5.700	0.00988306	0.0126187	273.58	0.01792
59	5.800	0.00988306	0.0126187	273.59	0.01893
60	5.900	0.00988306	0.0126187	273.60	0.01994
61	6.000	0.00988306	0.0126187	273.61	0.02095
62	6.100	0.00988306	0.0126187	273.62	0.02196
63	6.200	0.00988306	0.0126187	273.63	0.02297
64	6.300	0.00988306	0.0126187	273.64	0.02398
65	6.400	0.00988306	0.0126187	273.65	0.02499
66	6.500	0.00988306	0.0126187	273.66	0.02600
67	6.600	0.00988306	0.0126187	273.67	0.02701
68	6.700	0.00988306	0.0126187	273.68	0.02802
69	6.800	0.00988306	0.0126187	273.69	0.02903
70	6.900	0.00988306	0.0126187	273.70	0.03004
71	7.000	0.00988306	0.0126187	273.71	0.03105
72	7.100	0.00988306	0.0126187	273.72	0.03206
73	7.200	0.00988306	0.0126187	273.73	0.03307
74	7.300	0.00988306	0.0126187	273.74	0.03408
75	7.400	0.00988306	0.0126187	273.75	0.03509
76	7.500	0.00988306	0.0126187	273.76	0.03610
77	7.600	0.00988306	0.0126187	273.77	0.03711
78	7.700	0.00988306	0.0126187	273.78	0.03812
79	7.800	0.00988306	0.0126187	273.79	0.03913
80	7.900	0.00988306	0.0126187	273.80	0.04014
81	8.000	0.00988306	0.0126187	273.81	0.04115
82	8.100	0.00988306	0.0126187	273.82	0.04216
83	8.200	0.00988306	0.0126187	273.83	0.04317
84	8.300	0.00988306	0.0126187	273.84	0.04418
85	8.400	0.00988306	0.0126187	273.85	0.04519
86	8.500	0.00988306	0.0126187	273.86	0.04620
87	8.600	0.00988306	0.0126187	273.87	0.04721
88	8.700	0.00988306	0.0126187	273.88	0.04822
89	8.800	0.00988306	0.0126187	273.89	0.04923
90	8.900	0.00988306	0.0126187	273.90	0.05024
91	9.000	0.00988306	0.0126187	273.91	0.05125
92	9.100	0.00988306	0.0126187	273.92	0.05226
93	9.200	0.00988306	0.0126187	273.93	0.05327
94	9.300	0.00988306	0.0126187	273.94	0.05428
95	9.400	0.00988306	0.0126187	273.95	0.05529
96	9.500	0.00988306	0.0126187	273.96	0.05630
97	9.600	0.00988306	0.0126187	273.97	0.05731
98	9.700	0.00988306	0.0126187	273.98	0.05832
99	9.800	0.00988306	0.0126187	273.99	0.05933
100	9.900	0.00988306	0.0126187	274.00	0.06034
101	10.000	0.00988306	0.0126187	274.01	0.06135
102	10.100	0.00988306	0.0126187	274.02	0.06236
103	10.200	0.00988306	0.0126187	274.03	0.06337
104	10.300	0.00988306	0.0126187	274.04	0.06438
105	10.400	0.00988306	0.0126187	274.05	0.06539
106	10.500	0.00988306	0.0126187	274.06	0.06640
107	10.600	0.00988306	0.0126187	274.07	0.06741
108	10.700	0.00988306	0.0126187	274.08	0.06842
109	10.800	0.00988306	0.0126187	274.09	0.06943
110	10.900	0.00988306	0.0126187	274.10	0.07044
111	11.000	0.00988306	0.0126187	274.11	0.07145
112	11.100	0.00988306	0.0126187	274.12	0.07246
113	11.200	0.00988306	0.0126187	274.13	0.07347
114	11.300	0.00988306	0.0126187	274.14	0.07448
115	11.400	0.00988306	0.0126187	274.15	0.07549
116	11.500	0.00988306	0.0126187	274.16	0.07650
117	11.600	0.00988306	0.0126187	274.17	0.07751
118	11.700	0.00988306	0.0126187	274.18	0.07852
119	11.800	0.00988306	0.0126187	274.19	0.07953
120	11.900	0.00988306	0.0126187	274.20	0.08054
121	12.000	0.00988306	0.0126187	274.21	0.08155
122	12.100	0.00988306	0.0126187	274.22	0.08256
123	12.200	0.00988306	0.0126187	274.23	0.08357
124	12.300	0.00988306	0.0126187	274.24	0.08458
125	12.400	0.00988306	0.0126187	274.25	0.08559
126	12.500	0.00988306	0.0126187	274.26	0.08660
127	12.600	0.00988306	0.0126187	274.27	0.08761
128	12.700	0.00988306	0.0126187	274.28	0.08862
129	12.800	0.00988306	0.0126187	274.29	0.08963
130	12.900	0.00988306	0.0126187	274.30	0.09064
131	13.000	0.00988306	0.0126187	274.31	0.09165
132	13.100	0.00988306	0.0126187	274.32	0.09266
133	13.200	0.00988306	0.0126187	274.33	0.09367
134	13.300	0.00988306	0.0126187	274.34	0.09468
135	13.400	0.00988306	0.0126187	274.35	0.09569
136	13.500	0.00988306	0.0126187	274.36	0.09670
137	13.600	0.00988306	0.0126187	274.37	0.09771
138	13.700	0.00988306	0.0126187	274.38	0.09872
139	13.800	0.00988306	0.0126187	274.39	0.09973
140	13.900	0.00988306	0.0126187	274.40	0.10074
141	14.000	0.00988306	0.0126187	274.41	0.10175
142	14.100	0.00988306	0.0126187	274.42	0.10276
143	14.200	0.00988306	0.0126187	274.43	0.10377
144	14.300	0.00988306	0.0126187	274.44	0.10478
145	14.400	0.00988306	0.0126187	274.45	0.10579
146	14.500	0.00988306	0.0126187	274.46	0.10680
147	14.600	0.00988306	0.0126187	274.47	0.10781
148	14.700	0.00988306	0.0126187	274.48	0.10882
149	14.800	0.00988306	0.0126187	274.49	0.10983
150	14.900	0.00988306	0.0126187	274.50	0.11084
151	15.000	0.00988306	0.0126187	274.51	0.11185
152	15.100	0.00988306	0.0126187	274.52	0.11286
153	15.200	0.00988306	0.0126187	274.53	0.11387

ORIGINAL PAGE IS
OF POOR QUALITY

154	15.300	0.05282379	0.05282379	272.17	-0.19790
155	15.400	0.05282379	0.05282379	272.18	-0.09739
156	15.500	0.05282379	0.05282379	272.19	-0.00000
157	15.600	0.05282379	0.05282379	272.20	0.09739
158	15.700	0.05282379	0.05282379	272.21	0.19790
159	15.800	0.05282379	0.05282379	272.22	0.29841
160	15.900	0.05282379	0.05282379	272.23	0.39892
161	16.000	0.05282379	0.05282379	272.24	0.49943
162	16.100	0.05282379	0.05282379	272.25	0.59994
163	16.200	0.05282379	0.05282379	272.26	0.69945
164	16.300	0.05282379	0.05282379	272.27	0.79996
165	16.400	0.05282379	0.05282379	272.28	0.89947
166	16.500	0.05282379	0.05282379	272.29	0.99998
167	16.600	0.05282379	0.05282379	272.30	1.09949
168	16.700	0.05282379	0.05282379	272.31	1.19900
169	16.800	0.05282379	0.05282379	272.32	1.29851
170	16.900	0.05282379	0.05282379	272.33	1.39802
171	17.000	0.05282379	0.05282379	272.34	1.49753
172	17.100	0.05282379	0.05282379	272.35	1.59704
173	17.200	0.05282379	0.05282379	272.36	1.69655
174	17.300	0.05282379	0.05282379	272.37	1.79606
175	17.400	0.05282379	0.05282379	272.38	1.89557
176	17.500	0.05282379	0.05282379	272.39	1.99508
177	17.600	0.05282379	0.05282379	272.40	2.09459
178	17.700	0.05282379	0.05282379	272.41	2.19410
179	17.800	0.05282379	0.05282379	272.42	2.29361
180	17.900	0.05282379	0.05282379	272.43	2.39312
181	18.000	0.05282379	0.05282379	272.44	2.49263
182	18.100	0.05282379	0.05282379	272.45	2.59214
183	18.200	0.05282379	0.05282379	272.46	2.69165
184	18.300	0.05282379	0.05282379	272.47	2.79116
185	18.400	0.05282379	0.05282379	272.48	2.89067
186	18.500	0.05282379	0.05282379	272.49	2.99018
187	18.600	0.05282379	0.05282379	272.50	3.08969
188	18.700	0.05282379	0.05282379	272.51	3.18920
189	18.800	0.05282379	0.05282379	272.52	3.28871
190	18.900	0.05282379	0.05282379	272.53	3.38822
191	19.000	0.05282379	0.05282379	272.54	3.48773
192	19.100	0.05282379	0.05282379	272.55	3.58724
193	19.200	0.05282379	0.05282379	272.56	3.68675
194	19.300	0.05282379	0.05282379	272.57	3.78626
195	19.400	0.05282379	0.05282379	272.58	3.88577
196	19.500	0.05282379	0.05282379	272.59	3.98528
197	19.600	0.05282379	0.05282379	272.60	4.08479
198	19.700	0.05282379	0.05282379	272.61	4.18430
199	19.800	0.05282379	0.05282379	272.62	4.28381
200	19.900	0.05282379	0.05282379	272.63	4.38332
201	20.000	0.05282379	0.05282379	272.64	4.48283
202	20.100	0.05282379	0.05282379	272.65	4.58234
203	20.200	0.05282379	0.05282379	272.66	4.68185
204	20.300	0.05282379	0.05282379	272.67	4.78136
205	20.400	0.05282379	0.05282379	272.68	4.88087
206	20.500	0.05282379	0.05282379	272.69	4.98038
207	20.600	0.05282379	0.05282379	272.70	5.07989
208	20.700	0.05282379	0.05282379	272.71	5.17940
209	20.800	0.05282379	0.05282379	272.72	5.27891
210	20.900	0.05282379	0.05282379	272.73	5.37842
211	21.000	0.05282379	0.05282379	272.74	5.47793
212	21.100	0.05282379	0.05282379	272.75	5.57744
213	21.200	0.05282379	0.05282379	272.76	5.67695
214	21.300	0.05282379	0.05282379	272.77	5.77646
215	21.400	0.05282379	0.05282379	272.78	5.87597
216	21.500	0.05282379	0.05282379	272.79	5.97548
217	21.600	0.05282379	0.05282379	272.80	6.07499
218	21.700	0.05282379	0.05282379	272.81	6.17450
219	21.800	0.05282379	0.05282379	272.82	6.27401
220	21.900	0.05282379	0.05282379	272.83	6.37352
221	22.000	0.05282379	0.05282379	272.84	6.47303
222	22.100	0.05282379	0.05282379	272.85	6.57254
223	22.200	0.05282379	0.05282379	272.86	6.67205
224	22.300	0.05282379	0.05282379	272.87	6.77156
225	22.400	0.05282379	0.05282379	272.88	6.87107
226	22.500	0.05282379	0.05282379	272.89	6.97058
227	22.600	0.05282379	0.05282379	272.90	7.07009
228	22.700	0.05282379	0.05282379	272.91	7.16960
229	22.800	0.05282379	0.05282379	272.92	7.26911
230	22.900	0.05282379	0.05282379	272.93	7.36862
231	23.000	0.05282379	0.05282379	272.94	7.46813
232	23.100	0.05282379	0.05282379	272.95	7.56764
233	23.200	0.05282379	0.05282379	272.96	7.66715
234	23.300	0.05282379	0.05282379	272.97	7.76666
235	23.400	0.05282379	0.05282379	272.98	7.86617
236	23.500	0.05282379	0.05282379	272.99	7.96568
237	23.600	0.05282379	0.05282379	273.00	8.06519
238	23.700	0.05282379	0.05282379	273.01	8.16470
239	23.800	0.05282379	0.05282379	273.02	8.26421
240	23.900	0.05282379	0.05282379	273.03	8.36372
241	24.000	0.05282379	0.05282379	273.04	8.46323
242	24.100	0.05282379	0.05282379	273.05	8.56274
243	24.200	0.05282379	0.05282379	273.06	8.66225
244	24.300	0.05282379	0.05282379	273.07	8.76176
245	24.400	0.05282379	0.05282379	273.08	8.86127
246	24.500	0.05282379	0.05282379	273.09	8.96078
247	24.600	0.05282379	0.05282379	273.10	9.06029
248	24.700	0.05282379	0.05282379	273.11	9.15980
249	24.800	0.05282379	0.05282379	273.12	9.25931
250	24.900	0.05282379	0.05282379	273.13	9.35882
251	25.000	0.05282379	0.05282379	273.14	9.45833
252	25.100	0.05282379	0.05282379	273.15	9.55784
253	25.200	0.05282379	0.05282379	273.16	9.65735
254	25.300	0.05282379	0.05282379	273.17	9.75686
255	25.400	0.05282379	0.05282379	273.18	9.85637
256	25.500	0.05282379	0.05282379	273.19	9.95588
257	25.600	0.05282379	0.05282379	273.20	10.05539
258	25.700	0.05282379	0.05282379	273.21	10.15490
259	25.800	0.05282379	0.05282379	273.22	10.25441
260	25.900	0.05282379	0.05282379	273.23	10.35392
261	26.000	0.05282379	0.05282379	273.24	10.45343
262	26.100	0.05282379	0.05282379	273.25	10.55294
263	26.200	0.05282379	0.05282379	273.26	10.65245
264	26.300	0.05282379	0.05282379	273.27	10.75196
265	26.400	0.05282379	0.05282379	273.28	10.85147
266	26.500	0.05282379	0.05282379	273.29	10.95098
267	26.600	0.05282379	0.05282379	273.30	11.05049
268	26.700	0.05282379	0.05282379	273.31	11.14900
269	26.800	0.05282379	0.05282379	273.32	11.24851
270	26.900	0.05282379	0.05282379	273.33	11.34802
271	27.000	0.05282379	0.05282379	273.34	11.44753
272	27.100	0.05282379	0.05282379	273.35	11.54704
273	27.200	0.05282379	0.05282379	273.36	11.64655
274	27.300	0.05282379	0.05282379	273.37	11.74606
275	27.400	0.05282379	0.05282379	273.38	11.84557
276	27.500	0.05282379	0.05282379	273.39	11.94508
277	27.600	0.05282379	0.05282379	273.40	12.04459
278	27.700	0.05282379	0.05282379	273.41	12.14410
279	27.800	0.05282379	0.05282379	273.42	12.24361
280	27.900	0.05282379	0.05282379	273.43	12.34312
281	28.000	0.05282379	0.05282379	273.44	12.44263
282	28.100	0.05282379	0.05282379	273.45	12.54214
283	28.200	0.05282379	0.05282379	273.46	12.64165
284	28.300	0.05282379	0.05282379	273.47	12.74116
285	28.400	0.05282379	0.05282379	273.48	12.84067

286	28.500	0.00567122	0.0275112	272.57	0.28777
287	28.500	0.00567099	0.0264781	272.57	0.28678
288	28.500	0.00567076	0.0254450	272.58	0.28567
289	28.500	0.00567053	0.0244119	272.58	0.28456
290	28.500	0.00567030	0.0233788	272.58	0.28345
291	28.500	0.00567007	0.0223457	272.59	0.28234
292	28.500	0.00566984	0.0213126	272.59	0.28123
293	28.500	0.00566961	0.0202795	272.59	0.28012
294	28.500	0.00566938	0.0192464	272.59	0.27901
295	28.500	0.00566915	0.0182133	272.60	0.27790
296	28.500	0.00566892	0.0171802	272.60	0.27679
297	28.500	0.00566869	0.0161471	272.61	0.27568
298	28.500	0.00566846	0.0151140	272.61	0.27457
299	28.500	0.00566823	0.0140809	272.62	0.27346
300	28.500	0.00566800	0.0130478	272.62	0.27235
301	28.500	0.00566777	0.0120147	272.62	0.27124
302	28.500	0.00566754	0.0109816	272.63	0.27013
303	28.500	0.00566731	0.0099485	272.63	0.26902
304	28.500	0.00566708	0.0089154	272.64	0.26791
305	28.500	0.00566685	0.0078823	272.64	0.26680
306	28.500	0.00566662	0.0068492	272.65	0.26569
307	28.500	0.00566639	0.0058161	272.65	0.26458
308	28.500	0.00566616	0.0047830	272.66	0.26347
309	28.500	0.00566593	0.0037500	272.66	0.26236
310	28.500	0.00566570	0.0027169	272.67	0.26125
311	28.500	0.00566547	0.0016838	272.67	0.26014
312	28.500	0.00566524	0.0006507	272.68	0.25903
313	28.500	0.00566501	0.0000000	272.68	0.25792
314	28.500	0.00566478	0.0000000	272.69	0.25681
315	28.500	0.00566455	0.0000000	272.69	0.25570
316	28.500	0.00566432	0.0000000	272.70	0.25459
317	28.500	0.00566409	0.0000000	272.70	0.25348
318	28.500	0.00566386	0.0000000	272.71	0.25237
319	28.500	0.00566363	0.0000000	272.71	0.25126
320	28.500	0.00566340	0.0000000	272.72	0.25015
321	28.500	0.00566317	0.0000000	272.72	0.24904
322	28.500	0.00566294	0.0000000	272.73	0.24793
323	28.500	0.00566271	0.0000000	272.73	0.24682
324	28.500	0.00566248	0.0000000	272.74	0.24571
325	28.500	0.00566225	0.0000000	272.74	0.24460
326	28.500	0.00566202	0.0000000	272.75	0.24349
327	28.500	0.00566179	0.0000000	272.75	0.24238
328	28.500	0.00566156	0.0000000	272.76	0.24127
329	28.500	0.00566133	0.0000000	272.76	0.24016

DATA POINT	TIME (SECS)	ANGLE-OF-ATTACK RATE (RADIAN/SEC)	ALTITUDE (METERS)	ALTITUDE RATE (M/SEC)	ALT. ACCEL. (M/SEC^2)	VERT. ACCEL. (M/SEC^2)	ELEV. DEPLECT. (RADIAN)
1	0.100	-0.005218038	3435.19	-0.76	0.51	0.0	0.0
2	0.200	-0.005218038	3435.01	-0.68	0.58	0.0	0.0
3	0.300	-0.005218038	3434.83	-0.60	0.65	0.0	0.0
4	0.400	-0.005218038	3434.65	-0.52	0.72	0.0	0.0
5	0.500	-0.005218038	3434.47	-0.44	0.79	0.0	0.0
6	0.600	-0.005218038	3434.29	-0.36	0.86	0.0	0.0
7	0.700	-0.005218038	3434.11	-0.28	0.93	0.0	0.0
8	0.800	-0.005218038	3433.93	-0.20	1.00	0.0	0.0
9	0.900	-0.005218038	3433.75	-0.12	1.07	0.0	0.0
10	1.000	-0.005218038	3433.57	-0.04	1.14	0.0	0.0
11	1.100	-0.005218038	3433.39	0.04	1.21	0.0	0.0
12	1.200	-0.005218038	3433.21	0.12	1.28	0.0	0.0
13	1.300	-0.005218038	3433.03	0.20	1.35	0.0	0.0
14	1.400	-0.005218038	3432.85	0.28	1.42	0.0	0.0
15	1.500	-0.005218038	3432.67	0.36	1.49	0.0	0.0
16	1.600	-0.005218038	3432.49	0.44	1.56	0.0	0.0
17	1.700	-0.005218038	3432.31	0.52	1.63	0.0	0.0
18	1.800	-0.005218038	3432.13	0.60	1.70	0.0	0.0
19	1.900	-0.005218038	3431.95	0.68	1.77	0.0	0.0
20	2.000	-0.005218038	3431.77	0.76	1.84	0.0	0.0
21	2.100	-0.005218038	3431.59	0.84	1.91	0.0	0.0
22	2.200	-0.005218038	3431.41	0.92	1.98	0.0	0.0
23	2.300	-0.005218038	3431.23	1.00	2.05	0.0	0.0
24	2.400	-0.005218038	3431.05	1.08	2.12	0.0	0.0
25	2.500	-0.005218038	3430.87	1.16	2.19	0.0	0.0
26	2.600	-0.005218038	3430.69	1.24	2.26	0.0	0.0
27	2.700	-0.005218038	3430.51	1.32	2.33	0.0	0.0
28	2.800	-0.005218038	3430.33	1.40	2.40	0.0	0.0
29	2.900	-0.005218038	3430.15	1.48	2.47	0.0	0.0
30	3.000	-0.005218038	3429.97	1.56	2.54	0.0	0.0
31	3.100	-0.005218038	3429.79	1.64	2.61	0.0	0.0
32	3.200	-0.005218038	3429.61	1.72	2.68	0.0	0.0
33	3.300	-0.005218038	3429.43	1.80	2.75	0.0	0.0
34	3.400	-0.005218038	3429.25	1.88	2.82	0.0	0.0
35	3.500	-0.005218038	3429.07	1.96	2.89	0.0	0.0
36	3.600	-0.005218038	3428.89	2.04	2.96	0.0	0.0
37	3.700	-0.005218038	3428.71	2.12	3.03	0.0	0.0
38	3.800	-0.005218038	3428.53	2.20	3.10	0.0	0.0
39	3.900	-0.005218038	3428.35	2.28	3.17	0.0	0.0
40	4.000	-0.005218038	3428.17	2.36	3.24	0.0	0.0
41	4.100	-0.005218038	3427.99	2.44	3.31	0.0	0.0
42	4.200	-0.005218038	3427.81	2.52	3.38	0.0	0.0
43	4.300	-0.005218038	3427.63	2.60	3.45	0.0	0.0
44	4.400	-0.005218038	3427.45	2.68	3.52	0.0	0.0
45	4.500	-0.005218038	3427.27	2.76	3.59	0.0	0.0
46	4.600	-0.005218038	3427.09	2.84	3.66	0.0	0.0
47	4.700	-0.005218038	3426.91	2.92	3.73	0.0	0.0
48	4.800	-0.005218038	3426.73	3.00	3.80	0.0	0.0
49	4.900	-0.005218038	3426.55	3.08	3.87	0.0	0.0
50	5.000	-0.005218038	3426.37	3.16	3.94	0.0	0.0
51	5.100	-0.005218038	3426.19	3.24	4.01	0.0	0.0
52	5.200	-0.005218038	3426.01	3.32	4.08	0.0	0.0
53	5.300	-0.005218038	3425.83	3.40	4.15	0.0	0.0
54	5.400	-0.005218038	3425.65	3.48	4.22	0.0	0.0
55	5.500	-0.005218038	3425.47	3.56	4.29	0.0	0.0
56	5.600	-0.005218038	3425.29	3.64	4.36	0.0	0.0
57	5.700	-0.005218038	3425.11	3.72	4.43	0.0	0.0
58	5.800	-0.005218038	3424.93	3.80	4.50	0.0	0.0
59	5.900	-0.005218038	3424.75	3.88	4.57	0.0	0.0
60	6.000	-0.005218038	3424.57	3.96	4.64	0.0	0.0
61	6.100	-0.005218038	3424.39	4.04	4.71	0.0	0.0
62	6.200	-0.005218038	3424.21	4.12	4.78	0.0	0.0
63	6.300	-0.005218038	3424.03	4.20	4.85	0.0	0.0
64	6.400	-0.005218038	3423.85	4.28	4.92	0.0	0.0
65	6.500	-0.005218038	3423.67	4.36	4.99	0.0	0.0
66	6.600	-0.005218038	3423.49	4.44	5.06	0.0	0.0
67	6.700	-0.005218038	3423.31	4.52	5.13	0.0	0.0
68	6.800	-0.005218038	3423.13	4.60	5.20	0.0	0.0
69	6.900	-0.005218038	3422.95	4.68	5.27	0.0	0.0
70	7.000	-0.005218038	3422.77	4.76	5.34	0.0	0.0
71	7.100	-0.005218038	3422.59	4.84	5.41	0.0	0.0
72	7.200	-0.005218038	3422.41	4.92	5.48	0.0	0.0
73	7.300	-0.005218038	3422.23	5.00	5.55	0.0	0.0
74	7.400	-0.005218038	3422.05	5.08	5.62	0.0	0.0
75	7.500	-0.005218038	3421.87	5.16	5.69	0.0	0.0
76	7.600	-0.005218038	3421.69	5.24	5.76	0.0	0.0
77	7.700	-0.005218038	3421.51	5.32	5.83	0.0	0.0
78	7.800	-0.005218038	3421.33	5.40	5.90	0.0	0.0
79	7.900	-0.005218038	3421.15	5.48	5.97	0.0	0.0
80	8.000	-0.005218038	3420.97	5.56	6.04	0.0	0.0

ORIGINAL PAGE IS
OF POOR QUALITY

82	8.100	0.011447390	3483.44	23.17	9.09	0.0	0.0
83	8.200	0.009602612	3488.78	22.67	8.94	0.0	0.0
84	8.300	0.007170092	3488.17	22.16	8.99	0.0	0.0
85	8.400	0.004316795	3490.61	20.48	4.32	0.0	0.0
86	8.500	0.001018116	3493.09	20.00	4.05	0.0	0.0
87	8.600	-0.002660113	3495.61	19.10	3.77	0.0	0.0
88	8.700	-0.006656456	3498.17	17.75	3.46	0.0	0.0
89	8.800	-0.010869222	3500.76	16.09	3.19	0.0	0.0
90	8.900	-0.015207663	3503.38	14.39	2.89	0.0	0.0
91	9.000	-0.019588198	3506.04	12.67	2.58	0.0	0.0
92	9.100	-0.023844476	3508.72	10.91	2.29	0.0	0.0
93	9.200	-0.027921025	3511.42	9.13	1.98	0.0	0.0
94	9.300	-0.031730184	3514.14	7.31	1.68	0.0	0.0
95	9.400	-0.035310956	3516.88	5.46	1.37	0.0	0.0
96	9.500	-0.038682266	3519.64	3.58	1.07	0.0	0.0
97	9.600	-0.041855926	3522.40	1.68	0.76	0.0	0.0
98	9.700	-0.044832181	3525.17	-0.27	0.46	0.0	0.0
99	9.800	-0.047612458	3527.94	-2.27	0.16	0.0	0.0
100	9.900	-0.050200072	3530.72	-4.27	-0.14	0.0	0.0
101	10.000	-0.052602248	3533.49	-6.27	-0.44	0.0	0.0
102	10.100	-0.054827461	3536.26	-8.27	-0.74	0.0	0.0
103	10.200	-0.056872072	3539.03	-10.27	-1.03	0.0	0.0
104	10.300	-0.05873267	3541.78	-12.27	-1.32	0.0	0.0
105	10.400	-0.060412961	3544.52	-14.27	-1.61	0.0	0.0
106	10.500	-0.061916058	3547.25	-16.27	-1.90	0.0	0.0
107	10.600	-0.063246226	3549.98	-18.27	-2.19	0.0	0.0
108	10.700	-0.064406222	3552.62	-20.27	-2.48	0.0	0.0
109	10.800	-0.065406008	3555.25	-22.27	-2.77	0.0	0.0
110	10.900	-0.066254880	3557.88	-24.27	-3.06	0.0	0.0
111	11.000	-0.066953773	3560.43	-26.27	-3.35	0.0	0.0
112	11.100	-0.067503193	3562.98	-28.27	-3.64	0.0	0.0
113	11.200	-0.067903993	3565.53	-30.27	-3.93	0.0	0.0
114	11.300	-0.068155457	3568.08	-32.27	-4.22	0.0	0.0
115	11.400	-0.068268103	3570.60	-34.27	-4.51	0.0	0.0
116	11.500	-0.068242187	3573.13	-36.27	-4.80	0.0	0.0
117	11.600	-0.068076714	3575.64	-38.27	-5.09	0.0	0.0
118	11.700	-0.067776976	3578.15	-40.27	-5.38	0.0	0.0
119	11.800	-0.067347902	3580.66	-42.27	-5.67	0.0	0.0
120	11.900	-0.066783653	3583.15	-44.27	-5.96	0.0	0.0
121	12.000	-0.066070272	3585.64	-46.27	-6.25	0.0	0.0
122	12.100	-0.065214800	3588.11	-48.27	-6.54	0.0	0.0
123	12.200	-0.064224796	3590.58	-50.27	-6.83	0.0	0.0
124	12.300	-0.063106814	3593.03	-52.27	-7.12	0.0	0.0
125	12.400	-0.061866398	3595.48	-54.27	-7.41	0.0	0.0
126	12.500	-0.060509455	3597.91	-56.27	-7.70	0.0	0.0
127	12.600	-0.059032088	3600.34	-58.27	-8.00	0.0	0.0
128	12.700	-0.057439281	3602.75	-60.27	-8.29	0.0	0.0
129	12.800	-0.055726118	3605.15	-62.27	-8.58	0.0	0.0
130	12.900	-0.053898615	3607.54	-64.27	-8.87	0.0	0.0
131	13.000	-0.051951835	3609.91	-66.27	-9.16	0.0	0.0
132	13.100	-0.049891023	3612.27	-68.27	-9.45	0.0	0.0
133	13.200	-0.047711118	3614.61	-70.27	-9.74	0.0	0.0
134	13.300	-0.045418135	3616.94	-72.27	-10.03	0.0	0.0
135	13.400	-0.042916263	3619.25	-74.27	-10.32	0.0	0.0
136	13.500	-0.040209701	3621.55	-76.27	-10.61	0.0	0.0
137	13.600	-0.037293237	3623.84	-78.27	-10.90	0.0	0.0
138	13.700	-0.034162481	3626.11	-80.27	-11.19	0.0	0.0
139	13.800	-0.030823933	3628.37	-82.27	-11.48	0.0	0.0
140	13.900	-0.027274321	3630.61	-84.27	-11.77	0.0	0.0
141	14.000	-0.023506876	3632.84	-86.27	-12.06	0.0	0.0
142	14.100	-0.019526096	3635.05	-88.27	-12.35	0.0	0.0
143	14.200	-0.015336611	3637.25	-90.27	-12.64	0.0	0.0
144	14.300	-0.010936404	3639.44	-92.27	-12.93	0.0	0.0
145	14.400	-0.006326105	3641.61	-94.27	-13.22	0.0	0.0
146	14.500	-0.001495963	3643.75	-96.27	-13.51	0.0	0.0
147	14.600	0.003536437	3645.88	-98.27	-13.80	0.0	0.0
148	14.700	0.008477561	3647.99	-100.27	-14.09	0.0	0.0
149	14.800	0.013326086	3650.08	-102.27	-14.38	0.0	0.0
150	14.900	0.018081295	3652.15	-104.27	-14.67	0.0	0.0
151	15.000	0.022742508	3654.20	-106.27	-14.96	0.0	0.0
152	15.100	0.027309663	3656.24	-108.27	-15.25	0.0	0.0
153	15.200	0.031782232	3658.27	-110.27	-15.54	0.0	0.0
154	15.300	0.036067429	3660.28	-112.27	-15.83	0.0	0.0
155	15.400	0.040162521	3662.27	-114.27	-16.12	0.0	0.0
156	15.500	0.044073192	3664.24	-116.27	-16.41	0.0	0.0
157	15.600	0.047803646	3666.19	-118.27	-16.70	0.0	0.0
158	15.700	0.051359555	3668.12	-120.27	-16.99	0.0	0.0
159	15.800	0.054736461	3670.03	-122.27	-17.28	0.0	0.0
160	15.900	0.057939661	3671.91	-124.27	-17.57	0.0	0.0
161	16.000	0.060964091	3673.77	-126.27	-17.86	0.0	0.0
162	16.100	0.063805165	3675.61	-128.27	-18.15	0.0	0.0
163	16.200	0.066458902	3677.43	-130.27	-18.44	0.0	0.0
164	16.300	0.068931666	3679.23	-132.27	-18.73	0.0	0.0
165	16.400	0.071229111	3681.01	-134.27	-19.02	0.0	0.0
166	16.500	0.073356140	3682.77	-136.27	-19.31	0.0	0.0
167	16.600	0.075308740	3684.51	-138.27	-19.60	0.0	0.0
168	16.700	0.077082011	3686.23	-140.27	-19.89	0.0	0.0
169	16.800	0.078681962	3687.93	-142.27	-20.18	0.0	0.0
170	16.900	0.080113574	3689.61	-144.27	-20.47	0.0	0.0
171	17.000	0.081382796	3691.27	-146.27	-20.76	0.0	0.0
172	17.100	0.082495190	3692.91	-148.27	-21.05	0.0	0.0
173	17.200	0.083457466	3694.53	-150.27	-21.34	0.0	0.0
174	17.300	0.084275379	3696.13	-152.27	-21.63	0.0	0.0
175	17.400	0.084954134	3697.71	-154.27	-21.92	0.0	0.0
176	17.500	0.085498192	3699.27	-156.27	-22.21	0.0	0.0
177	17.600	0.085912630	3700.81	-158.27	-22.50	0.0	0.0
178	17.700	0.086194159	3702.33	-160.27	-22.79	0.0	0.0
179	17.800	0.086348357	3703.84	-162.27	-23.08	0.0	0.0
180	17.900	0.086380304	3705.33	-164.27	-23.37	0.0	0.0
181	18.000	0.086295627	3706.80	-166.27	-23.66	0.0	0.0
182	18.100	0.086099600	3708.25	-168.27	-23.95	0.0	0.0
183	18.200	0.085797346	3709.68	-170.27	-24.24	0.0	0.0
184	18.300	0.085385037	3711.09	-172.27	-24.53	0.0	0.0
185	18.400	0.084868660	3712.48	-174.27	-24.82	0.0	0.0
186	18.500	0.084253493	3713.85	-176.27	-25.11	0.0	0.0
187	18.600	0.083535600	3715.20	-178.27	-25.40	0.0	0.0
188	18.700	0.082719963	3716.53	-180.27	-25.69	0.0	0.0
189	18.800	0.081812381	3717.84	-182.27	-25.98	0.0	0.0
190	18.900	0.080819008	3719.13	-184.27	-26.27	0.0	0.0
191	19.000	0.079746993	3720.41	-186.27	-26.56	0.0	0.0
192	19.100	0.078591500	3721.67	-188.27	-26.85	0.0	0.0
193	19.200	0.077348666	3722.91	-190.27	-27.14	0.0	0.0
194	19.300	0.076014500	3724.13	-192.27	-27.43	0.0	0.0
195	19.400	0.074595066	3725.33	-194.27	-27.72	0.0	0.0
196	19.500	0.073095346	3726.51	-196.27	-28.01	0.0	0.0
197	19.600	0.071520368	3727.67	-198.27	-28.30	0.0	0.0
198	19.700	0.069875117	3728.81	-200.27	-28.59	0.0	0.0
199	19.800	0.068155681	3729.93	-202.27	-28.88	0.0	0.0
200	19.900	0.066366422	3731.03	-204.27	-29.17	0.0	0.0
201	20.000	0.064512447	3732.11	-206.27	-29.46	0.0	0.0
202	20.100	0.062599326	3733.17	-208.27	-29.75	0.0	0.0
203	20.200	0.060632000	3734.21	-210.27	-30.04	0.0	0.0
204	20.300	0.058615576	3735.23	-212.27	-30.33	0.0	0.0
205	20.400	0.056555066	3736.23	-214.27	-30.62	0.0	0.0
206	20.500	0.054455476	3737.21	-216.27	-30.91	0.0	0.0
207	20.600	0.052322714	3738.17	-218.27	-31.20	0.0	0.0
208	20.700	0.050162000	3739.11	-220.27	-31.49	0.0	0.0
209	20.800	0.047979244	3740.03	-222.27	-31.78	0.0	0.0
210	20.900	0.045779011	3740.93	-224.27	-32.07	0.0	0.0
211	21.000	0.043565758	3741.81	-226.27	-32.36	0.0	0.0
212	21.100	0.041344026	3742.67	-228.27	-32.65	0.0	0.0
213	21.200	0.039117610	3743.51	-230.27	-32.94	0.0	0.0

APPENDIX B

MODEL CHECK PROGRAM

User Instructions — MDLCK

The program is written in FORTRAN IV and is designed to run in double precision on an IBM 370/165 computer with an average execution time of 20 seconds per case. Execution requires approximately 146,000 bytes of core storage. Given the output of the FDR1 program (Appendix A), this program provides a quick means of determining feasible power-drag model forms and initial estimates of the power and drag coefficients which would shorten the execution time of the FDR2 program (see Appendix C).* The program requires the specification of the following input data:

CARD 1:

The read unit number IDS:

IDS is a right-adjusted integer number occupying columns 1-5 and specifying that the data is to be read from cards, magnetic tape, disk, etc. The user must supply the suitable job control cards for the tape and/or disk reads. The IDS parameter controls only the reading of CARDS 2, 3, and (4,...,3 + 5K). All other data is expected in CARD form.

CARD 2:

The title array TITLE1:

The 80 characters of the array TITLE1 are used for identifying output. TITLE1 is provided by the first card of the punched output of the FDR1 program.

CARD 3:

- (a) The total number of points K in the data set,
- (b) The aircraft's wing area S in square feet,
- (c) The sea-level atmospheric density ρ_0 in slug/ft³,
- (d) The acceleration due to gravity G in ft/sec², and
- (e) The total elapsed time for the maneuver TT in seconds:
K is a right-adjusted integer number occupying columns 1-10.
S, ρ_0 , G, and TT are double-precision floating-point numbers each occupying 15 columns beginning at column 11. These values are provided by the second card of the punched output of the FDR1 program.

* It must be emphasized that this program allows greater freedom in the specification of the power-drag model forms than does the FDR2 program. This program allows the inclusion of term for the rates of other independent variables, while the FDR2 program allows only "steady-state" conditions.

CARDS 4,...,(3 + 5K):

The time histories of time T, weight F1, pitch angle F2, pitch rate F3, airspeed F4, density F5, angle of attack F6, static temperature X1, acceleration F8, angle-of-attack rate F9, altitude X2, altitude rate X3, altitude acceleration X4, vertical acceleration X5, and elevator deflection X6:

The variables T, F1, F2, F3, F4, F5, F6, X1, F8, F9, X2, X3, X4, X5, and X6 are double-precision floating-point numbers each occupying 25 columns. These variables are provided by the remaining punched output of the FDR1 program.

CARD (3 + 5K + 1):

The title array TITLE:

The 80 characters of the array TITLE are used for additional data set identification. Since this program allows more than one power-drag model form to be analyzed in a given run, TITLE is also used as a control variable to end execution. Termination of execution is achieved by following the last model-form data cards by a title card having only the word END in the first three card columns.

CARD (3 + 5K + 2):

(a) The power-drag model form parameters LOC(I):

The LOC(I), I = 1,...,15 parameters determine the specific model form to be used. The general form of the power and drag-coefficient equations are

$$\text{Power} = P_0 + P_1 V^{\text{EX1}} + P_2 V^{\text{EX2}} + P_3 V^{\text{EX3}} + P_4 V^{\text{EX4}} + P_5 \dot{V} + P_6 \dot{\alpha} + P_7 \dot{\theta}$$

$$C_D = C_{D0} + C_{D1} \alpha^{\text{EX1}} + C_{D2} \alpha^{\text{EX2}} + C_{D3} \alpha^{\text{EX3}} + C_{D4} \alpha^{\text{EX4}} + C_{D5} \dot{\alpha} + C_{D6} \dot{\theta}$$

Through the use of the LOC(I) parameters, the user may include or exclude as many terms as desired. It is mandatory that at least one power term and at least one drag-coefficient term is included; otherwise, the program will terminate prematurely. The following chart should be used in the specification of the desired model(s):

LOC parameter	Corresponding Coefficient
LOC(1)	P_0
LOC(2)	P_1
LOC(3)	P_2
LOC(4)	P_3
LOC(5)	P_4
LOC(6)	P_5
LOC(7)	P_6
LOC(8)	P_7
LOC(9)	C_{D0}
LOC(10)	C_{D1}
LOC(11)	C_{D2}
LOC(12)	C_{D3}
LOC(13)	C_{D4}
LOC(14)	C_{D5}
LOC(15)	C_{D6}

If LOC(1) = 0, the corresponding coefficient term will be excluded from the analysis. If LOC(1) = 1, the corresponding coefficient term will be included in the analysis. These parameters are right-adjusted integer numbers each occupying 1 column beginning at column 1.

- (b) The desired type of output units METRIC:
 If METRIC = 0, the output will be in English units. If METRIC = 1, the output will be in SI units. METRIC is a right-adjusted integer number occupying column 16.

C-5

CARD (3 + 5K + 3):

- (a) The exponent EX1 on the second power-coefficient term,
- (b) The exponent EX2 on the third power-coefficient term,
- (c) The exponent EX3 on the fourth power-coefficient term,
- (d) The exponent EX4 on the fifth power-coefficient term,
- (e) The exponent IEX1 on the second drag-coefficient term,
- (f) The exponent IEX2 on the third drag-coefficient term,
- (g) The exponent IEX3 on the fourth drag-coefficient term, and
- (h) The exponent IEX4 on the fifth drag-coefficient term:
EX1, EX2, EX3, and EX4 are floating-point numbers each occupying 10 columns beginning at column 1. No two of these exponents may have the same value; otherwise, a singular matrix will terminate execution. IEX1, IEX2, IEX3, and IEX4 are right-adjusted integer numbers each occupying 5 columns beginning at column 41. No two of these exponents may have the same value; otherwise, a singular matrix will terminate execution.

CARD (3 + 5K + 4):

- (a) The lower allowable limit PLOW of the power available in foot-pounds per second,
- (b) The upper allowable limit PHIGH of the power available in foot-pounds per second,
- (c) The lower allowable limit CDLOW of the drag coefficient,
- (d) The upper allowable limit CDHIGH of the drag coefficient, and
- (e) The thrust incidence angle TIA in radians:
PLOW, PHIGH, CDLOW, CDHIGH, and TIA are floating-point numbers each occupying 10 columns beginning at column 1.

For a given run consisting of more than one power-drag model form, cards (3 + 5K + 1) through (3 + 5K + 4) must be repeated for each model form.

Program Listing – MDLCK

```

C PROGRAM: MODEL FORMS CHECK (MDLCK)          F.O. SNETANA & S.R. FOX  NL 1
C
C ***** NL 2
C * NL 3
C * MODEL FORMS CHECK * NL 4
C * NL 5
C ***** NL 6
C
C GIVEN THE OUTPUT OF FLIGHT DATA REDUCTION PROGRAM #1, THIS PROGRAM NL 7
C ALLOWS THE USER TO DETERMINE THE MODEL FORM(S) FOR THE POWER AND NL 8
C DRAG COEFFICIENTS FOR FLIGHT DATA REDUCTION PROGRAM #2. IT SHOULD NL 9
C BE EMPHASIZED THAT THIS PROGRAM ALLOWS GREATER FREEDOM THAN FLIGHT NL 10
C DATA REDUCTION PROGRAM #2 IN THE REPRESENTATION OF THE POWER AND NL 11
C DRAG FUNCTIONS. NL 12
C
C THE FOLLOWING COMMENT CARDS DESCRIBE THE NECESSARY INPUT FOR THIS NL 13
C PROGRAM. FOR A MORE PRECISE DESCRIPTION, CONSULT THE USERS IN- NL 14
C STRUCTIONS. NL 15
C
C INPUT *** CARD 1 NL 16
C
C IDS -> READ UNIT NUMBER (ALLOWS READING OF CARDS, DISK, NL 17
C TAPE, ETC OF THE OUTPUT OF FLIGHT DATA REDUCTION NL 18
C PROGRAM #1) NL 19
C
C INPUT *** CARD 2 (OUTPUT OF FLIGHT DATA REDUCTION PROGRAM #1) NL 20
C
C TITLE1 -> TITLE CARD FOR MANEUVER NL 21
C
C INPUT *** CARD 3 (OUTPUT OF FLIGHT DATA REDUCTION PROGRAM #1) NL 22
C
C K -> NUMBER OF POINTS IN DATA SET NL 23
C
C S -> AIRCRAFT'S WING AREA IN SQUARE FEET NL 24
C
C RHO -> SEA-LEVEL ATMOSPHERIC DENSITY IN SLUG/FT**3 NL 25
C
C G -> ACCELERATION DUE TO GRAVITY IN FT/SEC**2 NL 26
C
C TT -> TOTAL ELAPSED TIME FOR MANEUVER IN SECONDS NL 27
C
C INPUT *** CARDS 4.....(3*5K) (OUTPUT FROM 'FOR1') NL 28
C
C IDENTIFICATION OF NECESSARY INPUT TIME HISTORIES NL 29
C
C T -> TIME (DUMMY VARIABLE) NL 30
C F1(1) -> WEIGHT NL 31
C F2(1) -> PITCH ANGLE NL 32
C
C F3(1) -> PITCH RATE NL 33
C F4(1) -> AIRSPEED NL 34
C F5(1) -> DENSITY NL 35
C F6(1) -> ANGLE OF ATTACK NL 36
C X1 -> STATIC TEMPERATURE (DUMMY VARIABLE) NL 37
C F8(1) -> ACCELERATION NL 38
C F9(1) -> ANGLE OF ATTACK RATE NL 39
C X2 -> ALTITUDE (DUMMY VARIABLE) NL 40
C X3 -> ALTITUDE RATE (DUMMY VARIABLE) NL 41
C X4 -> ALTITUDE ACCELERATION (DUMMY VARIABLE) NL 42
C X5 -> VERTICAL ACCELERATION (DUMMY VARIABLE) NL 43
C X6 -> ELEVATOR/STABILATOR DEFLECTION (DUMMY VARIABLE) NL 44
C
C INPUT *** CARD (3*5K+1) NL 45
C
C TITLE -> TITLE CARD FOR ADDITIONAL LABELING OR PROGRAM NL 46
C TERMINATION NL 47
C
C INPUT *** CARD (3*5K+2) (CONSULT USERS INSTRUCTIONS) NL 48
C
C LOC(1) -> MODEL SOLUTION FORM (CHOSEN BY CARD COLUMN NUMBER) NL 49
C LOC(1)=0 -> SKIP COEFFICIENT NL 50
C LOC(1)=1 -> INCLUDE COEFFICIENT NL 51
C
C METRIC -> OUTPUT PRINT CODE NL 52
C METRIC=0 -> OUTPUT PRINTED IN ENGLISH UNITS NL 53
C METRIC=1 -> OUTPUT PRINTED IN SI UNITS NL 54
C
C INPUT *** CARD (3*5K+3) (CONSULT USERS INSTRUCTIONS) NL 55
C
C EX1 -> EXPONENT ON SECOND POWER-COEFFICIENT TERM NL 56
C
C EX2 -> EXPONENT ON THIRD POWER-COEFFICIENT TERM NL 57
C
C EX3 -> EXPONENT ON FOURTH POWER-COEFFICIENT TERM NL 58
C
C EX4 -> EXPONENT ON FIFTH POWER-COEFFICIENT TERM NL 59
C
C IEX1 -> EXPONENT ON SECOND DRAG-COEFFICIENT TERM (INTEGER) NL 60
C
C IEX2 -> EXPONENT ON THIRD DRAG-COEFFICIENT TERM (INTEGER) NL 61
C
C IEX3 -> EXPONENT ON FOURTH DRAG-COEFFICIENT TERM (INTEGER) NL 62
C
C IEX4 -> EXPONENT ON FIFTH DRAG-COEFFICIENT TERM (INTEGER) NL 63
C
C INPUT *** CARD (3*5K+4) NL 64
C
C PLOW -> LOWER LIMIT OF ALLOWABLE POWER AVAILABLE (FT-LB/SEC) NL 65
C
C PHIGH -> UPPER LIMIT OF ALLOWABLE POWER AVAILABLE (FT-LB/SEC) NL 66

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C COLOR -> LOWER LIMIT OF ALLOWABLE DRAG COEFFICIENT NL 17
C COMHIGH -> UPPER LIMIT OF ALLOWABLE DRAG COEFFICIENT NL 18
C TIA -> THRUST INCIDENCE ANGLE IN RADIANS NL 19
C *** ADDITIONAL MODEL FORMS MAY BE SPECIFIED BY *REPEATING* PROCESS FROM CARD(3+5K+1) THROUGH CARD(3+5K+4). THE PROGRAM IS TERMINATED WHEN CARD(3+5K+1) CONTAINS THE WORD *END* IN THE FIRST THREE CARD COLUMNS. NL 20
C IMPLICIT REAL*(A-H,O-Z) NL 21
C DIMENSION LOC(15),TITLE(20),TITELI(20) NL 22
C COMMON F(1450),F2(450),F3(450),F4(450),F5(450),F6(450),F8(450),F9(1450),C(450,15),X(450,1),WKAR(450),CPM(15),SGN(4),EX1,EX2,EX3,EX4,G1,S,RHO,TIA,PLOW,PHIGH,COLOR,CDHIGH,JREAD,JWRITE,IEX1,IEX2,IEX3,IEX4,METRIC NL 23
C DATA XEND/HEND / NL 24
C READ JREAD, I IDS NL 25
C 1 FORMAT (15) NL 26
C*** CHECK IDS FOR ERROR NL 27
C IF (IDS.EQ.JPUNCH.OR.IDS.EQ.JWRITE) GO TO 11 NL 28
C READ (IDS,2) (TITELI(I),I=1,20) NL 29
C 2 FORMAT (20A4) NL 30
C READ (IDS,3) K,S,RHO,G NL 31
C 3 FORMAT (I10,4D15.8) NL 32
C DO 5 I=1,K NL 33
C READ (IDS,4) T,F1(I),F2(I),F3(I),F4(I),F5(I),F6(I),X1,F8(I),F9(I),IX2,XJ,X4,X5,X6 NL 34
C 4 FORMAT (3D25,16) NL 35
C 5 CONTINUE NL 36
C*** SET CASE COUNTER NL 37
C ICASE=0 NL 38
C 6 HEAD (JREAD,2) (TITLE(I),I=1,20) NL 39
C*** CHECK FOR PROGRAM TERMINATION NL 40
C IF (TITLE(1).EQ.XEND) GO TO 13 NL 41
C READ (JREAD,7) (LOC(I),I=1,15),METRIC NL 42
C 7 FCMAT (1611) NL 43
C READ (JREAD,8) EX1,EX2,EX3,EX4,IEX1,IEX2,IEX3,IEX4 NL 44
C 8 FORMAT (4F10.0,4I5) NL 45
C READ (JREAD,9) PLOW,PHIGH,COLOR,CDHIGH,TIA NL 46
C 9 FORMAT (SF10.0) NL 47
C WRITE (JWRITE,10) (TITELI(I),I=1,20),(TITLE(I),I=1,20),IDS,LOC(1),LOC(7),LOC(13),EX1,PLOW,K,LOC(2),LOC(8),LOC(14),EX2,PHIGH,IEX1,LOC NL 48
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113) LOC(9)*LOC(15)*EX3*COLOW*IEK2*LOC(4)*LOC(10)*5*EX0*CONIGH*IEK3 ML 101
114) LOC(5)*LOC(11)*G*METRIC*IEK4*LOC(4)*LOC(12)*TIA*RHQ ML 102
10 FORMAT (1H1,////20X,8H(---),,20X,|,|,82X,|,|,20X,|,|,20X,|,| ML 103
1X,|,|,20X,|,|,1X,20A4,1X,|,|,20X,|,|,82X,|,|,20X,|,|,1X,|,|,MP ML 104
1UT PARAMETERS=.64X,|,|,20X,|,|,82X,|,|,20X,|,|,2X,10S=.14, ML 105
1 LOC(1)*=.13, LOC(7)*=.13, LOC(13)*=.12,2X,*EX1*=F10.6,2X,*PLOW ML 106
14*F11,2,5X,|,|,20X,|,|,2X,*K*=.15, LOC(2)*=.13, LOC(8)*=.13, ML 107
1 LOC(14)*=.12,2X,*EX2*=F10.6,2X,*PHIGH*=F11.2,4X,|,|,20X,|,|, ML 108
12X,*EX1*=.13, LOC(13)*=.13, LOC(9)*=.13, LOC(15)*=.12,2X,*EX3*= ML 109
1,F10.6,2X,*COLOW*=F11.8,4X,|,|,20X,|,|,2X,*IEK2*=.13, LOC(4)*= ML 110
1,13, LOC(10)*=.72, 5X,*F,3,2X,*EX4*=F10.6,2X,*CONIGH*=F10.6, ML 101
1X,|,|,20X,|,|,2X,*IEK3*=.13, LOC(5)*=.13, LOC(11)*=.12, G*F ML 102
10.5,2X,*METRIC*=.13,27X,|,|,20X,|,|,2X,*IEK4*=.13, LOC(16)*=.13, ML 103
18 LOC(12)*=.12, TIA*=F6.0,2X,*RHQ*=.1P015.0,18X,|,|,20X,|,|,82 ML 104
1X,|,|,20X,8H(---)) ML 105
**** UPDATE CASE COUNTER AND ENACT MODEL SOLUTION ML 106
ICASE=ICASE1 ML 106
CALL MODEL(K,ICASE,LOC) ML 107
**** CONTINUE TO NEXT CASE IF ANY ML 108
GO TO 6 ML 109
**** WRITE ERROR MESSAGE ML 200
11 WRITE (JWRITE,12) ML 201
12 FORMAT (1X,////20X,*INPUT ERROR *** IDS IS INCORRECT*) ML 202
13 STOP ML 203
END ML 204

```

```

C SUBROUTINE MODEL(K,CASE,Z)
C*** SUBROUTINE MODEL CALCULATES THE POWER AND DRAG COEFFICIENTS OF THE
C*** USER-SPECIFIED MODEL FROM THE EQUATION OF MOTION TANGENT TO THE
C*** FLIGHT PATH
C
C IMPLICIT REAL*8(A-M,D-Z)
C DIMENSION TS(15),LOC(15),LLOC(15),H(8)
C COMMON F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F8(450),F9(
C 1450),C(450,15),X(450,1),WKAR(450),CPM(15),SGN(4),EX1,EX2,EX3,EX4,G
C 15,RMD,TIA,PLOW,PHIGH,CLOW,CDHIGH,JREAD,JWRITE,IEK1,IEK2,IEK3,IEK
C 14,METRIC
C DATA FAIL,4HNOGO/
C
C WRITE(JWRITE,1)
C 1 FORMAT(1X,////,50X,27HM O D E L S O L U T I O N,/)
C*** DETERMINE NUMBER OF UNKNOWN S
C NUM=15
C ICK1=0
C ICK2=0
C JC=0
C DO 6 I=1,15
C IF (LOC(I)) 21,2,3
C 2 NUM=NUM+1
C GO TO 6
C 3 JC=JC+1
C LLOC(JC)=I
C IF (I=8) 4,4,5
C 4 ICK1=ICK1+1
C GO TO 6
C 5 ICK2=ICK2+1
C 6 CONTINUE

```

```

10 SSX=SSX+SS+SSX NO 93
C*** WRITE MODEL VALUES NO 94
IF (METRIC.NE.0) GO TO 18 NO 95
IF (NFL.GT.0) GO TO 16 NO 96
WRITE (JWRITE,15) ICASE,CFM(1),CFM(9),CFM(2),CFM(10),CFM(3),CFM(11) NO 97
1),CFM(4),CFM(12),NFL,CFM(5),CFM(13),CFM(6),CFM(14),CFM(7),CFM(15), NO 98
1CFM(8),SSX NO 99
15 FORMAT (28X,76(' '),/28X,'*',74X,'*',/28X,'*',2X,'CASE',12,4X,'P NO 100
10 = ',IPD23,16,3X,'C00 = ',IPD23,16,2X,'*',/28X,'*',12X,'P1 = ',IPD 101
1IPD23,16,3X,'C01 = ',IPD23,16,2X,'*',/28X,'*',1X,'POINT',6X,'P2 = NO 102
1',IPD23,16,3X,'C02 = ',IPD23,16,2X,'*',/28X,'*',1X,'FAILURES',3X, NO 103
1P3 = ',IPD23,16,3X,'C03 = ',IPD23,16,2X,'*',/28X,'*',1X,'=',14,6 NO 104
1X,'P4 = ',IPD23,16,3X,'C06 = ',IPD23,16,2X,'*',/28X,'*',12X,'P5 = NO 105
1',IPD23,16,3X,'C05 = ',IPD23,16,2X,'*',/28X,'*',12X,'P6 = ',IPD2 NO 106
13,16,3X,'C06 = ',IPD23,16,2X,'*',/28X,'*',12X,'P7 = ',IPD23,16,34 NO 107
1X,'*',/28X,'*',74X,'*',/28X,'*',1X,'FIT ERROR= ',D23,16,39X,'*', NO 108
1/,28X,'*',74X,'*',/28X,76(' ')) NO 109
RETURN NO 110
16 WRITE (JWRITE,17) ICASE,CFM(1),CFM(9),CFM(2),CFM(10),CFM(3),CFM(11 NO 111
1),CFM(4),CFM(12),NFL,CFM(5),CFM(13),CFM(6),CFM(14),CFM(7),CFM(15), NO 112
1CFM(8),F NO 113
17 FORMAT (28X,76(' '),/28X,'*',74X,'*',/28X,'*',2X,'CASE',12,4X,'P NO 114
10 = ',IPD23,16,3X,'C00 = ',IPD23,16,2X,'*',/28X,'*',12X,'P1 = ',IP 115
1IPD23,16,3X,'C01 = ',IPD23,16,2X,'*',/28X,'*',1X,'POINT',6X,'P2 = NO 116
1',IPD23,16,3X,'C02 = ',IPD23,16,2X,'*',/28X,'*',1X,'FAILURES',3X, NO 117
1P3 = ',IPD23,16,3X,'C03 = ',IPD23,16,2X,'*',/28X,'*',1X,'=',14,6 NO 118
1X,'P4 = ',IPD23,16,3X,'C06 = ',IPD23,16,2X,'*',/28X,'*',12X,'P5 = NO 119
1',IPD23,16,3X,'C05 = ',IPD23,16,2X,'*',/28X,'*',12X,'P6 = ',IPD2 NO 120
13,16,3X,'C06 = ',IPD23,16,2X,'*',/28X,'*',12X,'P7 = ',IPD23,16,34 NO 121
1X,'*',/28X,'*',74X,'*',/28X,'*',1X,'FIT ERROR= ',A,58X,'*',/28 NO 122
1X,'*',74X,'*',/28X,76(' ')) NO 123
RETURN NO 124
88 DO 19 L=1,8 NO 125
19 H(L)=CFM(L)*1.355818D-3 NO 126
IF (NFL.GT.0) GO TO 20 NO 127
WRITE (JWRITE,15) ICASE,H(1),CFM(9),H(2),CFM(10),H(3),CFM(11),H(4) NO 128
1,CFM(12),NFL,H(5),CFM(13),H(6),CFM(14),H(7),CFM(15),H(8),SSX NO 129
RETURN NO 130
20 WRITE (JWRITE,17) ICASE,H(1),CFM(9),H(2),CFM(10),H(3),CFM(11),H(4) NO 131
1,CFM(12),NFL,H(5),CFM(13),H(6),CFM(14),H(7),CFM(15),H(8),FAIL NO 132
RETURN NO 133
21 WRITE (JWRITE,22) NO 134
22 FORMAT (1X,////,20X,'INPUT ERROR *** USER SPECIFIED AT LEAST ONE L NO 135
1QC PARAMETER INCORRECTLY.**) NO 136
RETURN NO 137
END NO 138

```

	SUBROUTINE SIGNS(Y,X1,X2,X3,X4)	SN	1
C		SN	2
C***	SUBROUTINE SIGNS DETERMINES THE CORRECT SIGN ON TERMS IN	SN	3
C***	COMPUTING THE DRAG COEFFICIENT EXPRESSION OR ITS DERIVATIVES IN	SN	4
C***	RELATION TO ARGUMENT AND EXPONENTS	SN	5
C		SN	6
	IMPLICIT REAL*8(A-H,O-Z)	SN	7
	INTEGER*4 X1,X2,X3,X4	SN	8
	DIMENSION Y(4),L(4)	SN	9
C		SN	10
	DO 1 I=1,4	SN	11

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1 Y(1)=1.000
  L(1)=X1
  L(2)=X2
  L(3)=X3
  L(4)=X4
  DO 2 I=1,4
    IF (((L(1)/2)*2).NE.L(1))Y(1)=1.000
2 CONTINUE
  RETURN
  ENTRY CHNGE(Y)
  DO 3 I=1,4
3 Y(1)=1.000
  RETURN
  END

SUBROUTINE LLSQAR(A,B,M,NA,NB,IA,IB,IDGT,WKAREA,IER,JWRITE)
C
C*** SUBROUTINE LLSQAR PERFORMS A LEAST SQUARES SOLUTION OF A OVER-
C*** DETERMINED SYSTEM OF LINEAR EQUATIONS
C
  DIMENSION A(IA,1),B(IB,1),WKAREA(1)
  REAL*8 SUM
  REAL*8 A,B,WKAREA
C
C*** INITIALIZE IER
  IER=0
C*** FIND THE PSEUDO-INVERSE OF MATRIX A
  CALL LPSDOR(A,M,NA,IA,A,IDGT,WKAREA,IER,JWRITE)
  IF (IER.NE.0) GO TO 5
C*** SOLVE THE EQUATION BY MULTIPLYING A-INVERSE AND B
  DO 4 I=1,NB
  DO 2 J=1,NA
  CALL VXPZRO
  DO 1 K=1,M
  CALL VXPWUL(A(K,J),B(K,1))
1 CONTINUE
  CALL VXPSTO(SUM)
  WKAREA(J)=SUM
2 CONTINUE
C*** MOVE THE RESULTS INTO MATRIX B
  DO 3 J=1,NA
  B(J,1)=WKAREA(J)
3 CONTINUE
4 CONTINUE
  GO TO 6
5 IER=129
  CALL UERTST(IER,6,LLSQAR,JWRITE)
6 RETURN
  END

SUBROUTINE LPSDOR(A,M,N,IA,AINV,IDGT,WKAREA,IER,JWRITE)
C
C*** SUBROUTINE LPSDOR FIND THE PSEUDO-INVERSE OF A MATRIX
C
  DIMENSION A(IA,1),AINV(IA,1),WKAREA(N,1)
  REAL*8 A,AINV,WKAREA,BIGA,AMN,ZERO,ETA

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SN 12
SN 13
SN 14
SN 15
SN 16
SN 17
SN 18
SN 19
SN 20
SN 21
SN 22
SN 23
SN 24
SN 25
LQ 1
LQ 2
LQ 3
LQ 4
LQ 5
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LQ 18
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LQ 22
LQ 23
LQ 24
LQ 25
LQ 26
LQ 27
LQ 28
LQ 29
LQ 30
LQ 31
LQ 32
LQ 33
LQ 34

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REAL*8 SUM,DETA
C
C*** INITIALIZE IER
  IER=0
  NP1=N+1
  NP2=N+2
  NP3=N+3
C*** FIND THE LARGEST ELEMENT OF A
  BIGA=0.00
  DO 1 I=1,M
  DO 1 II=1,N
  IF (BIGA.GE.DABS(A(1,II))) GO TO 1
  BIGA=DABS(A(1,II))
1 CONTINUE
  AMN=0.00
  ETA=DSORT(AMN)/((10.**IDGT)*BIGA)
C*** CALCULATE THE SINGULAR VALUE DECOMPOSITION OF A
  CALL LSYALR(A,M,N,IA,N,1,WKAREA(1,N+4),WKAREA(1,NP1),AINV,WKAREA)
  DO 2 I=1,N
2 WKAREA(1,NP2)=WKAREA(1,NP1)
C*** SORT THE SINGULAR VALUES ARRAY INTO ASCENDING SEQUENCE BY ABSOLUTE
C*** VALUE
  CALL VSORTM(WKAREA(1,NP2),N)
  DETA=ETA**2
  CALL VXPZRO
C*** COMPARE SINGULAR VALUES AND ETA
  DO 3 I=1,M
  IP=I
  CALL VXPWUL(WKAREA(1,NP2),WKAREA(1,NP2))
  CALL VXPSTO(SUM)
  IF (SUM.GT.DETA) GO TO 4
3 CONTINUE
  IER=129
  GO TO 15
4 IP=IP-1
  IF (IP.NE.0) GO TO 5
  ZERO=0.00
  GO TO 6
5 ZERO=WKAREA(IP,NP2)
  DO 10 I=1,M
  IF (WKAREA(I,NP1).LE.ZERO) GO TO 6
  DO 7 J=1,N
7 WKAREA(J,1)=WKAREA(J,1)/WKAREA(I,NP1)
  GO TO 10
C*** SET WKAREA(J,1)=0.0, FOR J=1,...,N, IF WKAREA(I,NP1).LE.ZERO
  DO 9 J=1,N
9 WKAREA(J,1)=0.0
10 CONTINUE
  DO 14 I=1,M
  DO 12 J=1,N
  CALL VXPZRO
  DO 11 K=1,M
11 CALL VXPWUL(WKAREA(J,K),AINV(I,K))
  CALL VXPSTO(SUM)
12 WKAREA(J,NP3)=SUM
C*** MOVE THE RESULTS INTO MATRIX AINV
  DO 13 J=1,N
13 AINV(I,J)=WKAREA(J,NP3)
14 CONTINUE
  GO TO 16

```

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PI 7
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PI 9
PI 10
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PI 62
PI 63
PI 64
PI 65
PI 66

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18 CALL UERTST(IER,6MLPSDOR,JWRITE)
16 RETURN
END

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PI 67
PI 68
PI 69

```

```

C SUBROUTINE LSVLR(A,M,N,IA,IV,ISW,WKAREA,Q,U,V)
C*** SUBROUTINE LSVLR DETERMINES THE SINGULAR VALUE DECOMPOSITION OF A
C*** MATRIX
C
DIMENSION A(IA,1),U(IA,1),V(IV,1),Q(1),WKAREA(1)
REAL*8A,WKAREA,Q,U,V,EPS,TOL
REAL*8F,G,H,X,Y,Z,C,S,HR,GR,DPS,ONE,ZERO
DATA TOL/Z0010000000000000/DPS/Z3410000000000000/
DATA ONE/1.0D0/,ZERO/0.000/

```

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C
EPS=DPS
DO 1 I=1,M
DO 1 J=1,N
U(I,J)=A(I,J)
1 CONTINUE
C*** HOUSEHOLDER'S REDUCTION TO BIDIAGONAL FORM
X=0.0D0
G=0.0D0
DO 17 I=1,N
WKAREA(I)=G
CALL VXPZRO
L=I+1
DO 2 J=L,M

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```

2 CALL VXPML(U(J,I),U(J,I))
CALL VXPSTQ(S)
IF (S.GE.TOL) GO TO 3
G=0.0D0
GO TO 7
3 F=U(I,I)
G=-DSQRT(S)
IF (F.LT.0.0D0)G=-G
H=F*G-S
H=1.0/H
U(I,I)=F-G
IF (L.GT.N) GO TO 7
DO 6 J=L,N
CALL VXPZRO
DO 4 K=L,M

```

```

4 CALL VXPML(U(K,I),U(K,J))
CALL VXPSTQ(S)
F=S*HR
DO 5 K=L,M
U(K,J)=U(K,J)+F*U(K,I)
5 CONTINUE
7 Q(I)=G
CALL VXPZRO
IF (L.GT.N) GO TO 9
DO 8 J=L,N

```

```

8 CALL VXPML(U(I,J),U(I,J))
CALL VXPSTQ(S)
9 IF (S.GE.TOL) GO TO 10
G=0.0D0
GO TO 16

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```

10 IF (L.GT.N) GO TO 12
DO 11 J=L,N
CALL VXPZRO
DO 13 K=L,M

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```

13 CALL VXPML(U(K,I),U(K,J))
CALL VXPSTQ(S)
F=S*HR
DO 14 K=L,M
U(K,J)=U(K,J)+F*U(K,I)
14 CONTINUE
11 CONTINUE
12 IF (L.GT.N) GO TO 24
DO 23 J=L,N
V(J,I)=0.0D0
V(I,I)=1.0D0
G=WKAREA(I)

```

```

25 L=I
C*** ACCUMULATION OF LEFT HAND TRANSFORMATIONS
DO 36 I=1,N
LL=I+1
G=0.0D0
IF (LL.GT.N) GO TO 27
DO 26 J=LL,N
U(I,I)=0.0D0
27 IF (G.EQ.0.0D0) GO TO 33
H=U(I,I)*G
H=1.0/H
IF (LL.GT.N) GO TO 31
DO 30 J=LL,N

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30 V(J,I)=U(J,I)+V(J,I)*H
31 V(I,I)=U(I,I)+V(I,I)*H
32 V(I,I)=U(I,I)+V(I,I)*H
33 V(I,I)=U(I,I)+V(I,I)*H
34 V(I,I)=U(I,I)+V(I,I)*H
35 V(I,I)=U(I,I)+V(I,I)*H
36 V(I,I)=U(I,I)+V(I,I)*H
37 V(I,I)=U(I,I)+V(I,I)*H
38 V(I,I)=U(I,I)+V(I,I)*H
39 V(I,I)=U(I,I)+V(I,I)*H
40 V(I,I)=U(I,I)+V(I,I)*H
41 V(I,I)=U(I,I)+V(I,I)*H
42 V(I,I)=U(I,I)+V(I,I)*H
43 V(I,I)=U(I,I)+V(I,I)*H
44 V(I,I)=U(I,I)+V(I,I)*H
45 V(I,I)=U(I,I)+V(I,I)*H
46 V(I,I)=U(I,I)+V(I,I)*H
47 V(I,I)=U(I,I)+V(I,I)*H
48 V(I,I)=U(I,I)+V(I,I)*H
49 V(I,I)=U(I,I)+V(I,I)*H
50 V(I,I)=U(I,I)+V(I,I)*H
51 V(I,I)=U(I,I)+V(I,I)*H
52 V(I,I)=U(I,I)+V(I,I)*H
53 V(I,I)=U(I,I)+V(I,I)*H
54 V(I,I)=U(I,I)+V(I,I)*H

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10 IF (I.LT.N)F=U(I,I+1)
G=-DSQRT(S)
IF (F.LT.0.0D0)G=-G
H=F*G-S
H=1.0/H
IF (I.LT.N)U(I,I+1)=F-G
IF (L.GT.N) GO TO 12
DO 11 J=L,N
11 WKAREA(J)=U(I,J)*HR
12 IF (L.GT.N) GO TO 16
DO 15 J=L,N
CALL VXPZRO
IF (L.GT.N) GO TO 15
DO 13 K=L,N
13 CALL VXPML(U(J,K),U(I,K))
CALL VXPSTQ(S)
DO 14 K=L,N
14 U(J,K)=U(J,K)+S*WKAREA(K)
15 CONTINUE
16 Y=DABS(Q(I))+DABS(WKAREA(I))
IF (Y.GT.X)X=Y
17 CONTINUE
C*** ACCUMULATION OF RIGHT HAND TRANSFORMATIONS
IF (ISW.EQ.0) GO TO 37
DO 25 I=1,N
II=N-I+1
IF (G.EQ.0.0D0) GO TO 22
IF (L.GT.N) GO TO 24
H=U(II,II)*G
H=1.0/H
DO 18 J=L,N
18 V(J,II)=U(II,J)*HR
DO 21 J=L,N
CALL VXPZRO
DO 19 K=L,N
19 CALL VXPML(U(II,K),V(K,II))
CALL VXPSTQ(S)
DO 20 K=L,N
20 V(K,II)=V(K,II)+S*V(K,II)
21 CONTINUE
22 IF (L.GT.N) GO TO 24
DO 23 J=L,N
V(J,II)=0.0D0
23 V(II,II)=0.0D0
24 V(II,II)=1.0D0
G=WKAREA(II)

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25 L=II
C*** ACCUMULATION OF LEFT HAND TRANSFORMATIONS
DO 36 I=1,N
II=N-I+1
LL=II+1
G=0.0D0
IF (LL.GT.N) GO TO 27
DO 26 J=LL,N
U(II,II)=0.0D0
27 IF (G.EQ.0.0D0) GO TO 33
H=U(II,II)*G
H=1.0/H
IF (LL.GT.N) GO TO 31
DO 30 J=LL,N

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```

30 V(J,II)=U(J,II)+V(J,II)*H
31 V(II,II)=U(II,II)+V(II,II)*H
32 V(II,II)=U(II,II)+V(II,II)*H
33 V(II,II)=U(II,II)+V(II,II)*H
34 V(II,II)=U(II,II)+V(II,II)*H
35 V(II,II)=U(II,II)+V(II,II)*H
36 V(II,II)=U(II,II)+V(II,II)*H
37 V(II,II)=U(II,II)+V(II,II)*H
38 V(II,II)=U(II,II)+V(II,II)*H
39 V(II,II)=U(II,II)+V(II,II)*H
40 V(II,II)=U(II,II)+V(II,II)*H
41 V(II,II)=U(II,II)+V(II,II)*H
42 V(II,II)=U(II,II)+V(II,II)*H
43 V(II,II)=U(II,II)+V(II,II)*H
44 V(II,II)=U(II,II)+V(II,II)*H
45 V(II,II)=U(II,II)+V(II,II)*H
46 V(II,II)=U(II,II)+V(II,II)*H
47 V(II,II)=U(II,II)+V(II,II)*H
48 V(II,II)=U(II,II)+V(II,II)*H
49 V(II,II)=U(II,II)+V(II,II)*H
50 V(II,II)=U(II,II)+V(II,II)*H
51 V(II,II)=U(II,II)+V(II,II)*H
52 V(II,II)=U(II,II)+V(II,II)*H
53 V(II,II)=U(II,II)+V(II,II)*H
54 V(II,II)=U(II,II)+V(II,II)*H

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55 V(II,II)=U(II,II)+V(II,II)*H
56 V(II,II)=U(II,II)+V(II,II)*H
57 V(II,II)=U(II,II)+V(II,II)*H
58 V(II,II)=U(II,II)+V(II,II)*H
59 V(II,II)=U(II,II)+V(II,II)*H
60 V(II,II)=U(II,II)+V(II,II)*H
61 V(II,II)=U(II,II)+V(II,II)*H
62 V(II,II)=U(II,II)+V(II,II)*H
63 V(II,II)=U(II,II)+V(II,II)*H
64 V(II,II)=U(II,II)+V(II,II)*H
65 V(II,II)=U(II,II)+V(II,II)*H
66 V(II,II)=U(II,II)+V(II,II)*H
67 V(II,II)=U(II,II)+V(II,II)*H
68 V(II,II)=U(II,II)+V(II,II)*H
69 V(II,II)=U(II,II)+V(II,II)*H
70 V(II,II)=U(II,II)+V(II,II)*H
71 V(II,II)=U(II,II)+V(II,II)*H
72 V(II,II)=U(II,II)+V(II,II)*H
73 V(II,II)=U(II,II)+V(II,II)*H
74 V(II,II)=U(II,II)+V(II,II)*H
75 V(II,II)=U(II,II)+V(II,II)*H
76 V(II,II)=U(II,II)+V(II,II)*H
77 V(II,II)=U(II,II)+V(II,II)*H
78 V(II,II)=U(II,II)+V(II,II)*H
79 V(II,II)=U(II,II)+V(II,II)*H
80 V(II,II)=U(II,II)+V(II,II)*H
81 V(II,II)=U(II,II)+V(II,II)*H
82 V(II,II)=U(II,II)+V(II,II)*H
83 V(II,II)=U(II,II)+V(II,II)*H
84 V(II,II)=U(II,II)+V(II,II)*H
85 V(II,II)=U(II,II)+V(II,II)*H
86 V(II,II)=U(II,II)+V(II,II)*H
87 V(II,II)=U(II,II)+V(II,II)*H
88 V(II,II)=U(II,II)+V(II,II)*H
89 V(II,II)=U(II,II)+V(II,II)*H
90 V(II,II)=U(II,II)+V(II,II)*H
91 V(II,II)=U(II,II)+V(II,II)*H
92 V(II,II)=U(II,II)+V(II,II)*H
93 V(II,II)=U(II,II)+V(II,II)*H
94 V(II,II)=U(II,II)+V(II,II)*H
95 V(II,II)=U(II,II)+V(II,II)*H
96 V(II,II)=U(II,II)+V(II,II)*H
97 V(II,II)=U(II,II)+V(II,II)*H
98 V(II,II)=U(II,II)+V(II,II)*H
99 V(II,II)=U(II,II)+V(II,II)*H
100 V(II,II)=U(II,II)+V(II,II)*H
101 V(II,II)=U(II,II)+V(II,II)*H
102 V(II,II)=U(II,II)+V(II,II)*H
103 V(II,II)=U(II,II)+V(II,II)*H
104 V(II,II)=U(II,II)+V(II,II)*H
105 V(II,II)=U(II,II)+V(II,II)*H
106 V(II,II)=U(II,II)+V(II,II)*H
107 V(II,II)=U(II,II)+V(II,II)*H
108 V(II,II)=U(II,II)+V(II,II)*H
109 V(II,II)=U(II,II)+V(II,II)*H
110 V(II,II)=U(II,II)+V(II,II)*H
111 V(II,II)=U(II,II)+V(II,II)*H
112 V(II,II)=U(II,II)+V(II,II)*H
113 V(II,II)=U(II,II)+V(II,II)*H
114 V(II,II)=U(II,II)+V(II,II)*H

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CALL VXPZRO
DO 28 K=LL,M
28 CALL VXPMLT(U(K,I),U(K,J))
CALL VXPSTG(S)
F=S*HR
DO 29 K=II,M
29 U(K,J)=U(K,J)+F*U(K,I)
30 CONTINUE
31 GR=1.0/G
DO 32 J=II,M
32 U(J,I)=U(J,I)*GR
GO TO 35
33 DO 34 J=II,M
34 U(J,I)=0.00
35 U(II,I)=U(II,I)+1.000
36 CONTINUE
C*** DIAGONALIZATION OF THE BIDIAGONAL FORM
37 EPS=EPS*X
DO 37 K=1,N
KK=N-K+1
C*** TEST F SPLITTING
38 DO 39 L=1,KK
LL=KK-L+1
IF (DABS(WKAREA(LL)).LE.EPS) GO TO 45
IF (LL.EQ.1) GO TO 45
IF (DABS(Q(LL-1)).LE.EPS) GO TO 40
39 CONTINUE
C*** CANCELLATION OF WKAREA(L) IF LL.GT.1
40 C=0.00
S=1.000
L1=LL-1
IF (KK.LT.LL) GO TO 45
DO 44 I=LL,KK
F=S*WKAREA(I)
WKAREA(I)=C*WKAREA(I)
IF (DABS(F).LE.EPS) GO TO 45
G=Q(I)
QL=DOSQRT(F*F+G*G)
H=Q(I)
IF (H.NE.ZERO) GO TO 41
C=ZERO
S=GNE
GO TO 42
41 C=G/H
S=-F/H
42 IF (ISW.EQ.0) GO TO 44
DO 43 J=1,M
V=U(J,L1)
Z=U(J,I)
U(J,L1)=V+C*Z+S
U(J,I)=V-S*Z+C
43 CONTINUE
C*** TEST F CONVERGENCE
45 Z=Q(KK)
IF (LL.EQ.KK) GO TO 55
C*** SHIFT FROM BOTTOM 2X2 MINOR
X=Q(LL)
IF (KK.GT.1) V=Q(KK-1)
IF (KK.GT.1) G=WKAREA(KK-1)
H=WKAREA(KK)

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SV 174

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F=((Y-Z)*(V+Z)*(G-H)*(G+H))/(2.D0RHOV)
G=DSQRT(F*F+ONE)
IF (F.LT.0.00) F=((X-Z)*(X+Z)+H*(Y/(F-G)-H))/X
IF (F.GE.0.00) F=((X-Z)*(X+Z)+H*(Y/(F+G)-H))/X
C*** NEXT QR TRANSFORMATION
C=1.000
S=1.000
L2=LL+1
IF (KK.LT.L2) GO TO 54
DO 53 I=L2,KK
G=WKAREA(I)
Y=Q(I)
H=S*G
G=C*G
Z=DSQRT(F*F+H*H)
WKAREA(I-1)=Z
IF (Z.NE.ZERO) GO TO 46
C=ZERO
S=GNE
GO TO 47
46 C=F/Z
S=H/Z
47 F=X*C+G*S
G=-X*S+G*C
H=Y*S
V=Y*C
IF (ISW.EQ.0) GO TO 49
DO 48 J=1,N
X=Y*(J,I-1)
Z=V*(J,I)
V(J,I-1)=X+C*Z+S
48 V(J,I)=-X*S+Z*C
49 Z=DSQRT(F*F+H*H)
Q(I-1)=Z
IF (Z.NE.ZERO) GO TO 50
C=ZERO
S=GNE
GO TO 51
50 C=F/Z
S=H/Z
51 F=C*G+S*Y
X=-S*G+C*Y
IF (ISW.EQ.0) GO TO 53
DO 52 J=1,M
V=U(J,I-1)
Z=U(J,I)
U(J,I-1)=V+C*Z+S
52 U(J,I)=-V*S+Z*C
53 CONTINUE
54 WKAREA(LL)=ZERO
WKAREA(KK)=F
Q(KK)=X
GO TO 38
C*** CONVERGENCE
55 IF (Z.GE.ZERO) GO TO 57
Q(KK)=-Z
IF (ISW.EQ.0) GO TO 57
DO 56 J=1,N
56 V(J,KK)=-V(J,KK)
57 CONTINUE

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RETURN	SV	235
END	SV	236
SUBROUTINE UERTST(IER,NAME,JWRITE)	UR	1
C*** SUBROUTINE UERTST GENERATES ERROR MESSAGES	UR	2
C	UR	3
DIMENSION ITP(5),IBIT(4)	UR	4
INTEGER*2 NAME(3)	UR	5
INTEGER WARN,WARF,TERM,JWRITE	UR	6
EQUIVALENCE (IBIT(1),WARN),(IBIT(2),WARF),(IBIT(3),TERM)	UR	7
DATA ITP/'WARN','ING',' ',' ',' ',' ',' ',' ',' ',' ',' ',' '	UR	8
1* FIX*,' ',"TERM","INAL"," '"," '"," '","NON","DEFI","NE	UR	9
10 ' ',' ',"/IBIT/32.64,128.0/	UR	10
C	UR	11
IER2=IER	UR	12
IF (IER2.GE.WARN) GO TO 1	UR	13
C*** UNDEFINED	UR	14
IER1=4	UR	15
GO TO 4	UR	16
1 IF (IER2.LT.TERM) GO TO 2	UR	17
C*** TERMINAL	UR	18
IER1=3	UR	19
GO TO 4	UR	20
2 IF (IER2.LT.WARF) GO TO 3	UR	21
C*** WARNING (WITH FIX)	UR	22
IER1=2	UR	23
GO TO 4	UR	24
C*** WARNING	UR	25
3 IER1=1	UR	26
C*** EXTRACT 'N'	UR	27
4 IER2=IER2-IBIT(IER1)	UR	28
C*** PRINT ERROR MESSAGE	UR	29
WRITE (JWRITE,5) (ITP(I,IER1),I=1,5),NAME,IER2,IER	UR	30
5 FORMAT (1X,/,1X,"ERROR MESSAGE FROM UERTST",2X,5A4,4X,3A2,4X,12,2X	UR	31
1,"IER=",13)	UR	32
RETURN	UR	33
END	UR	34
END	UR	35
SUBROUTINE VSORTM(A,LA)	VS	1
C	VS	2
C*** SUBROUTINE VSORTM SORTS ARRAYS BY ABSOLUTE VALUE	VS	3
C	VS	4
DIMENSION A(1),IU(21),IL(21)	VS	5
REAL*8A,T,TT	VS	6
C	VS	7
C*** FIND ABSOLUTE VALUES OF ARRAY A	VS	8
DO 1 I=1,LA	VS	9
IF (A(I).LT.0.0)A(I)=-A(I)	VS	10
1 CONTINUE	VS	11
C	VS	12
ENTRY VSORTA(A,LA)	VS	13
C	VS	14
C*** ENTRY VSORTA SORTS ARRAYS BY ALGEBRAIC VALUE	VS	15
C	VS	16
N=1	VS	17

I=1	VS	18
J=LA	VS	19
R=.375	VS	20
2 IF (I.EQ.J) GO TO 11	VS	21
IF (R.GT..5898437) GO TO 4	VS	22
R=R+.90625E-2	VS	23
GO TO 5	VS	24
4 R=R-.21875	VS	25
5 K=I	VS	26
C*** SELECT A CENTRAL ELEMENT OF THE ARRAY AND SAVE IT IN LOCATION T	VS	27
IJ=I+(J-I)*R	VS	28
T=A(IJ)	VS	29
C*** IF FIRST ELEMENT OF ARRAY IS GREATER THAN T, INTERCHANGE WITH T	VS	30
IF (A(I).LE.T) GO TO 6	VS	31
A(IJ)=A(I)	VS	32
A(I)=T	VS	33
T=A(IJ)	VS	34
6 L=J	VS	35
C*** IF LAST ELEMENT OF ARRAY IS LESS THAN T, INTERCHANGE WITH T	VS	36
IF (A(L).GE.T) GO TO 8	VS	37
A(IJ)=A(L)	VS	38
A(L)=T	VS	39
T=A(IJ)	VS	40
C*** IF FIRST ELEMENT OF ARRAY IS GREATER THAN T, INTERCHANGE WITH T	VS	41
IF (A(I).LE.T) GO TO 8	VS	42
A(IJ)=A(I)	VS	43
A(I)=T	VS	44
T=A(IJ)	VS	45
GO TO 8	VS	46
7 TT=A(L)	VS	47
A(L)=A(K)	VS	48
A(K)=TT	VS	49
C*** FIND AN ELEMENT IN SECOND HALF OF ARRAY WHICH IS SMALLER THAN T	VS	50
8 L=L-1	VS	51
IF (A(L).GT.T) GO TO 8	VS	52
C*** FIND AN ELEMENT IN FIRST HALF OF ARRAY WHICH IS GREATER THAN T	VS	53
9 K=K+1	VS	54
IF (A(K).LT.T) GO TO 9	VS	55
C*** INTERCHANGE THESE ELEMENTS	VS	56
IF (K.LE.L) GO TO 7	VS	57
C*** SAVE UPPER AND LOWER SUBSCRIPTS OF THE ARRAY YET TO BE SORTED	VS	58
IF (L-1.LE.J-K) GO TO 10	VS	59
IL(N)=I	VS	60
IU(N)=L	VS	61
I=K	VS	62
N=N+1	VS	63
GO TO 12	VS	64
10 IL(N)=K	VS	65
IU(N)=J	VS	66
J=L	VS	67
N=N+1	VS	68
GO TO 12	VS	69
C*** BEGIN AGAIN ON ANOTHER PORTION OF UNSORTED ARRAY	VS	70
11 N=N-1	VS	71
IF (N.EQ.0) RETURN	VS	72
I=IL(N)	VS	73
J=IU(N)	VS	74
12 IF (J-I.EQ.1) GO TO 5	VS	75
IF (I.EQ.1) GO TO 2	VS	76
I=I-1	VS	77

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```
13 I=I+1  
IF (I.EQ.J) GO TO 11  
T=A(I+1)  
IF (A(I).LE.T) GO TO 13  
K=I  
14 A(K+1)=A(K)  
K=K-1  
IF (I.LT.A(K)) GO TO 14  
A(K+1)=T  
GO TO 13  
END
```

```
VS 78  
VS 79  
VS 80  
VS 81  
VS 82  
VS 83  
VS 84  
VS 85  
VS 86  
VS 87  
VS 88
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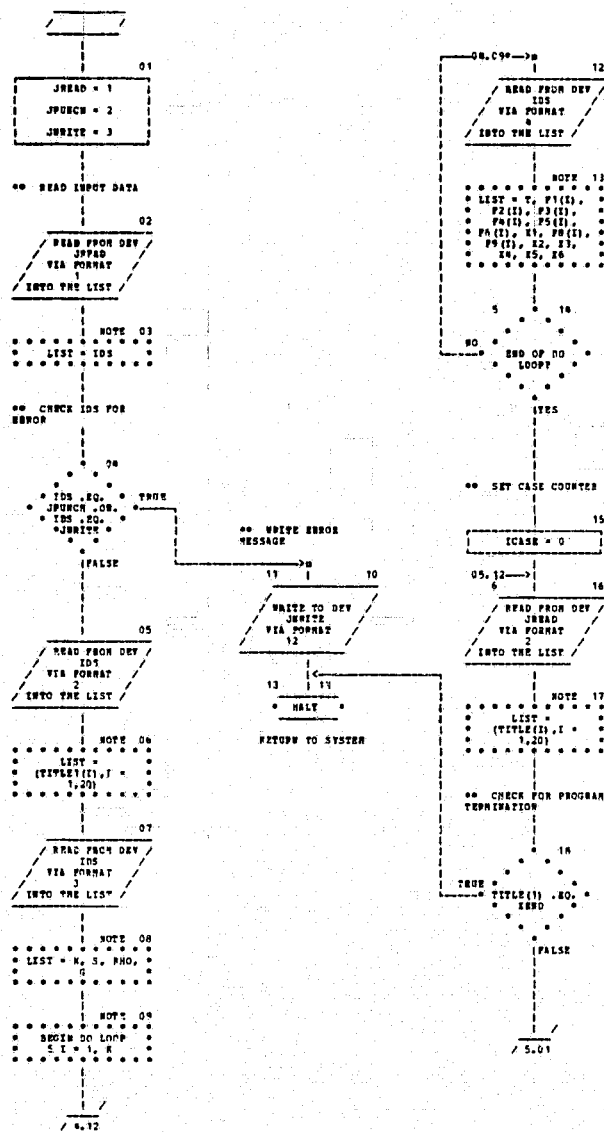
Flowchart - MDLCK

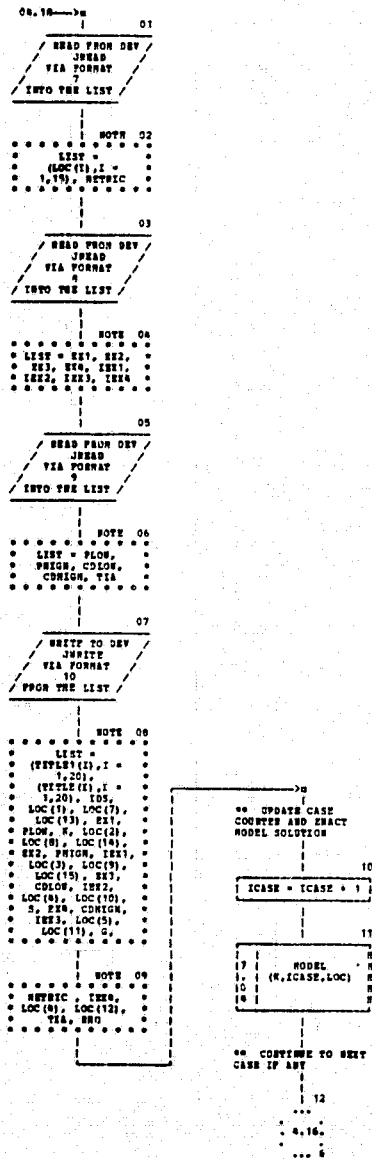
CHART TITLE - PROCEDURES

AUTOFLOW CHART SET -

MDLCK

PAGE 04



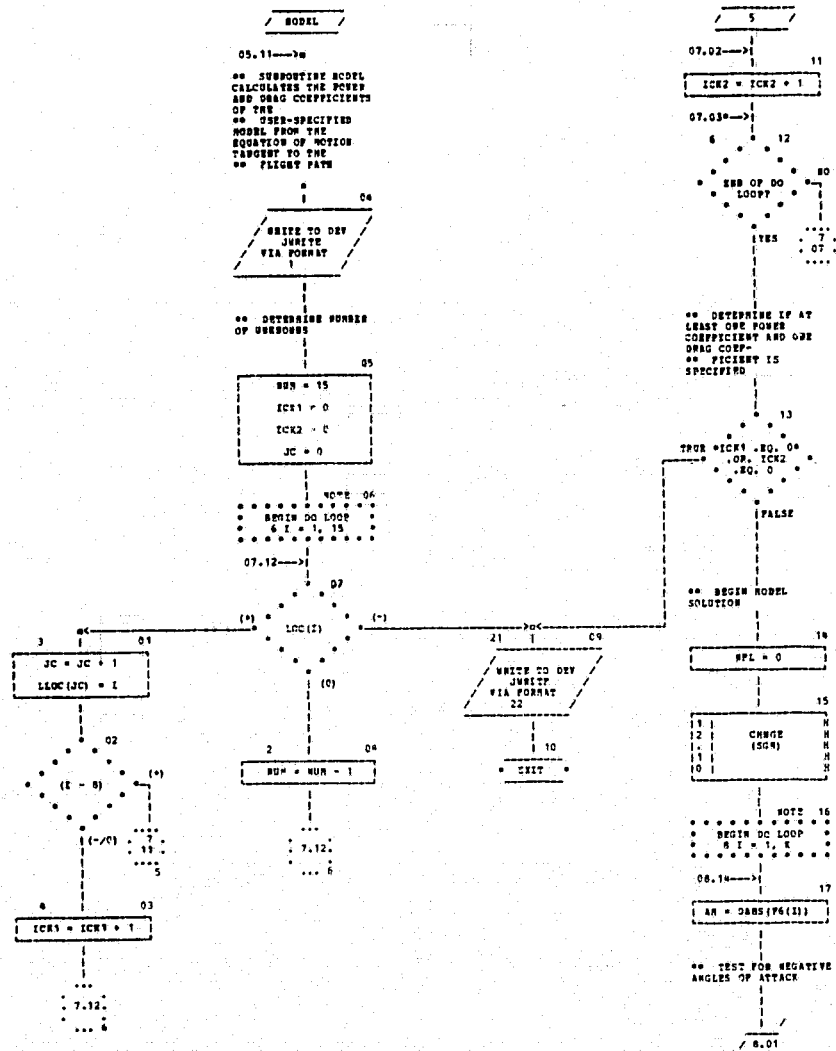


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PAGE 07

CHART TITLE - SUBSTITUTED NOVEL(R, ICASE, LOC)



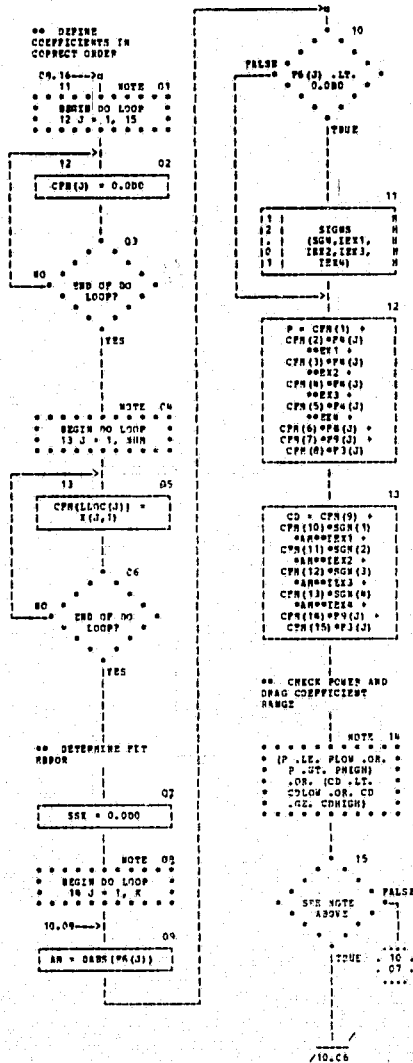
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AUTOFLOW CHART KEY -

PROLOG

PAGE 05

CHART TITLE - SUBROUTINE NODR(N,ICASE,LOC)



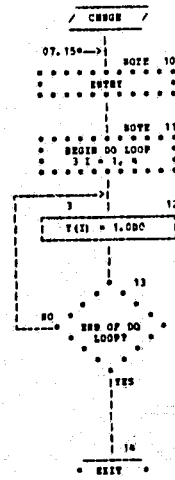
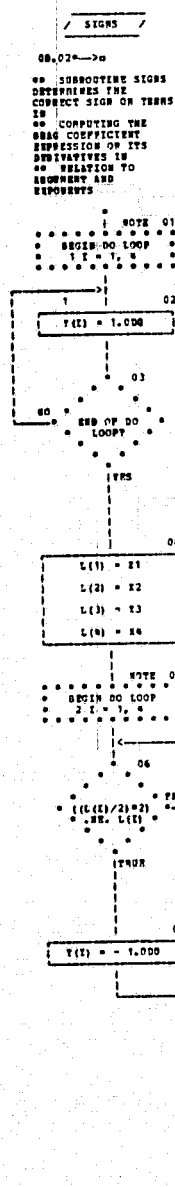
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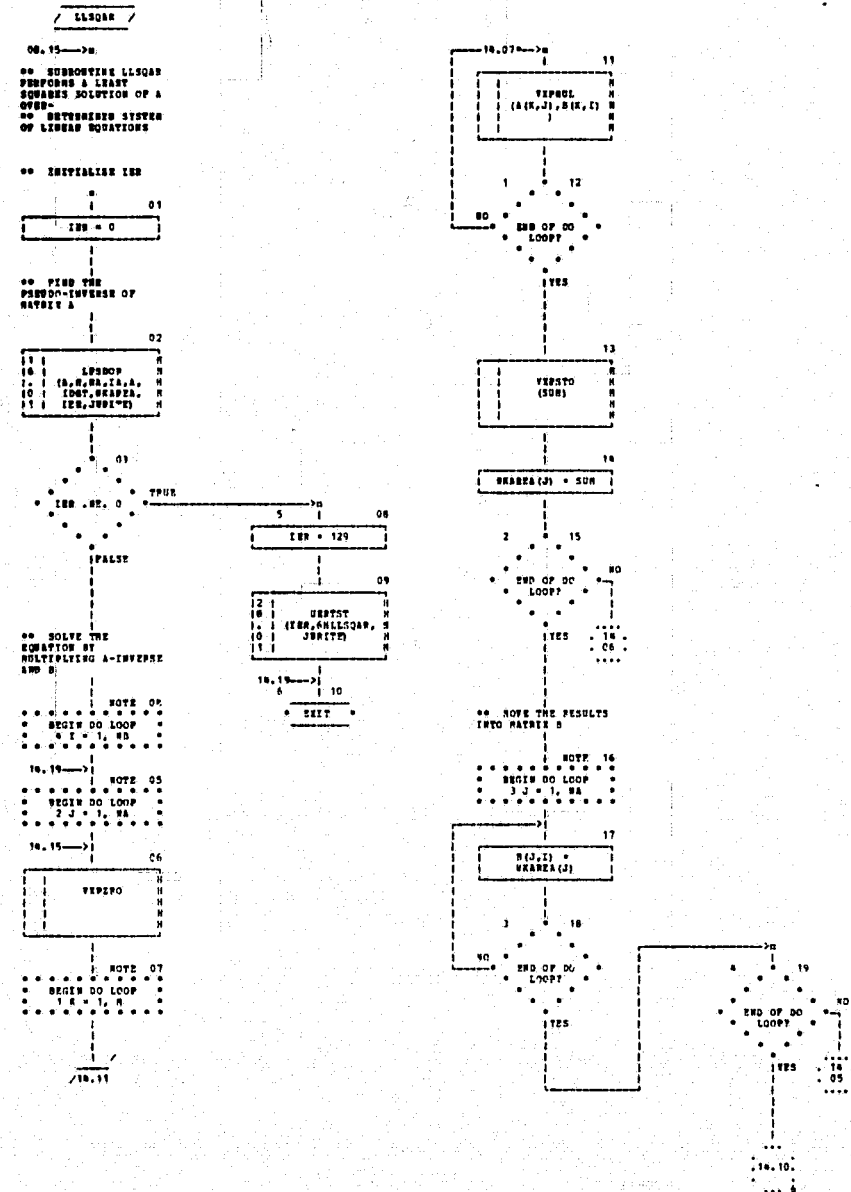
ASTROFLOW CHART SET -

•R0LCE

PAGE 12

CHART TITLE - SUBROUTINE SIGNS(X1,X2,X3,X4)





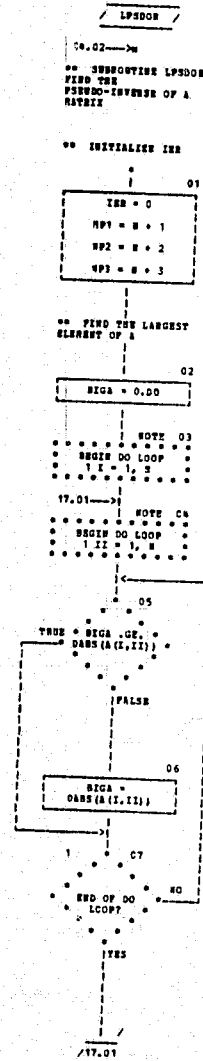
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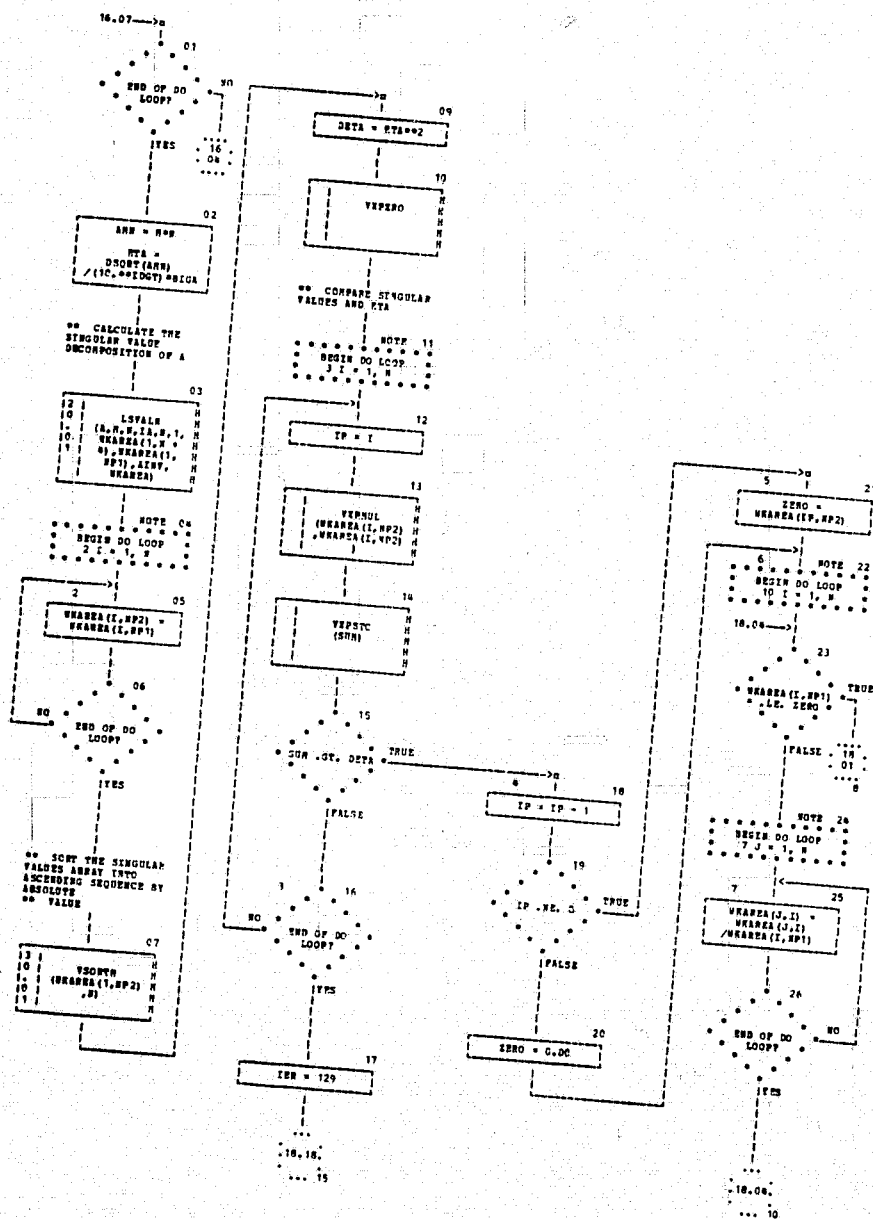
CHART TITLE - SUBROUTINE LPSDOR(A,B,N,IA,ANV,INDV,NEARS,INB,JUSTH)

AUTOFLOW CHART SET -

*NOICE

PAGE 16





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AUTOPLOW CHART SET -

*MOLCE

PAGE 10

CHART TITLE - SUBROUTINE LPMDCR(A,N,M,IA,AP1,IPCT,APRPA,IPR,WRITE)

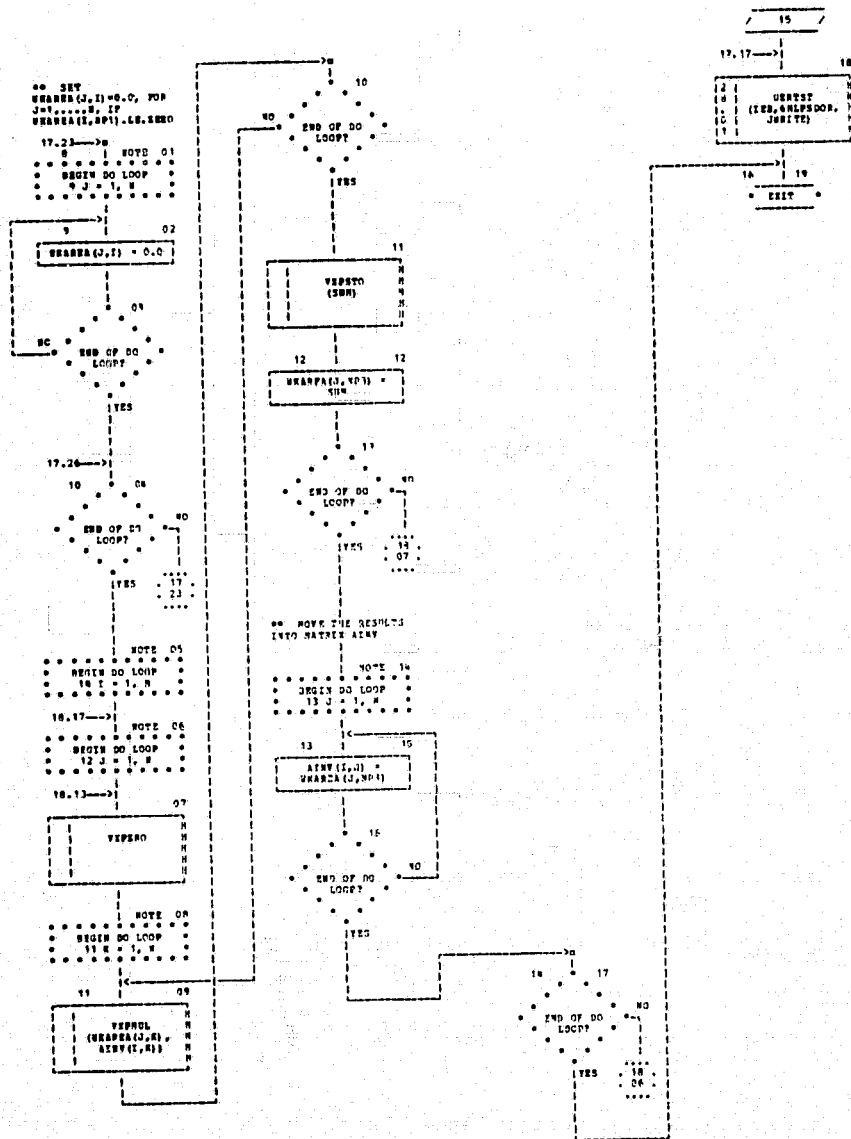
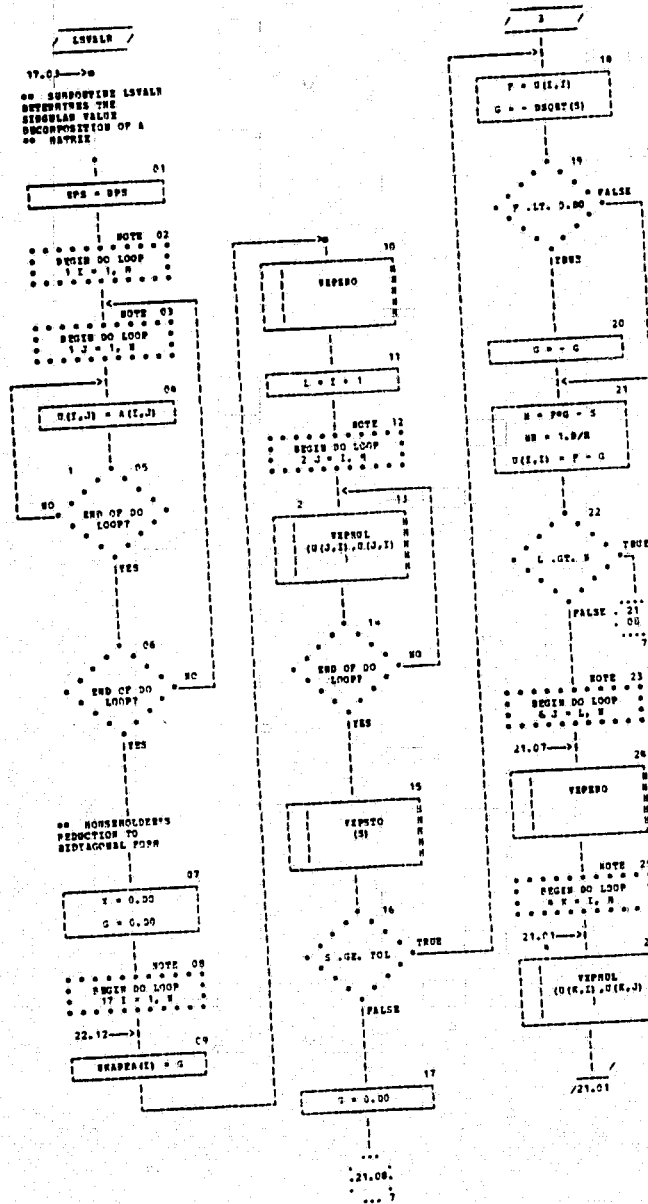


CHART TITLE - SUBROUTINE LEVEL(R,N,R,IA,IV,ISU,WEAVER,Q,U,V)



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AUTOFLOW CHART SET -

•BOLCE

PAGE 21

CHART TITLE - SUBROUTINE LEVALR (A, N, U, TA, IV, IER, VERRA, Q, R, T)

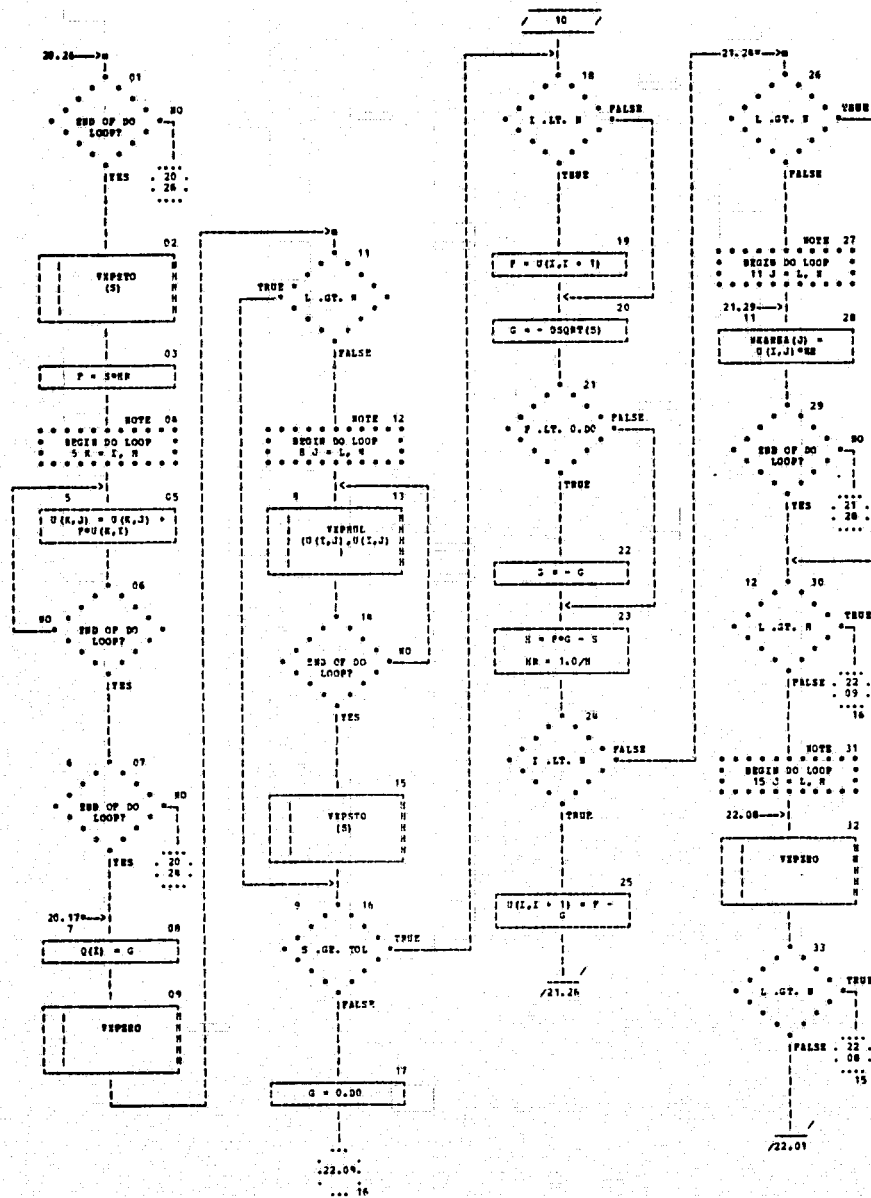
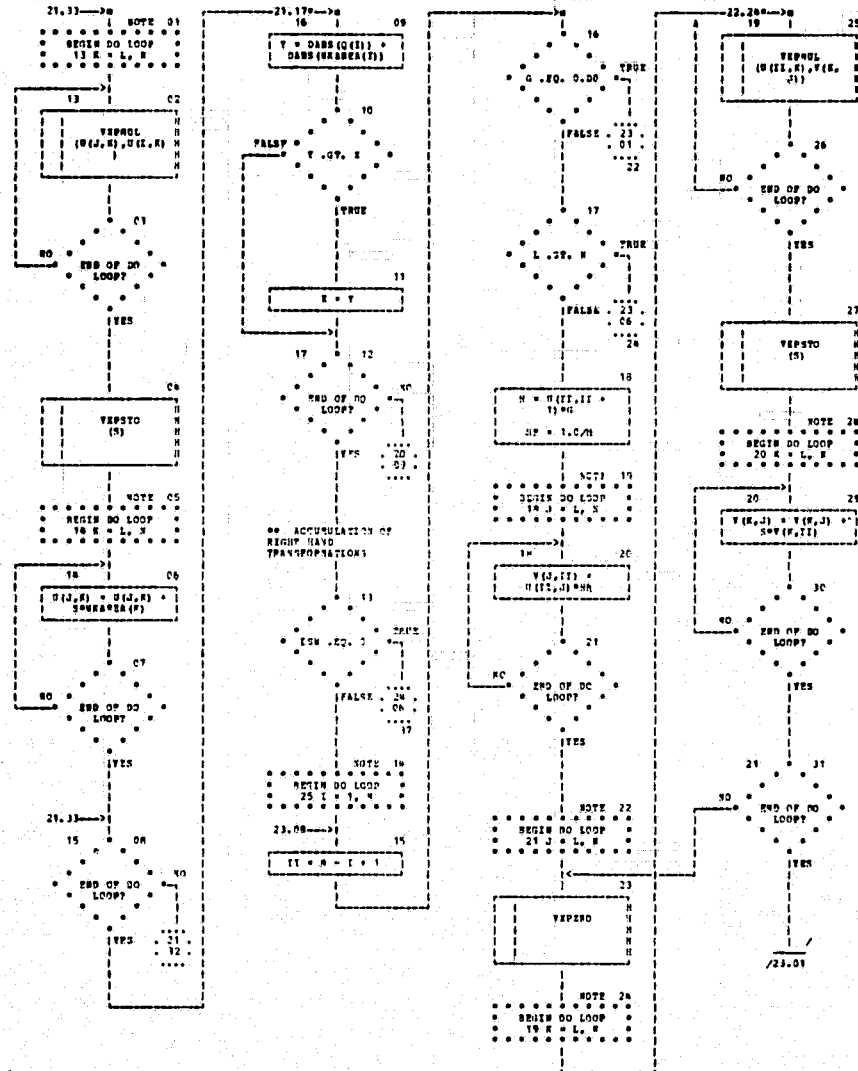


CHART TITLE - SUBROUTINE LVALRIA, N, M, L, IV, ISM, HAREA, Q, U, V)



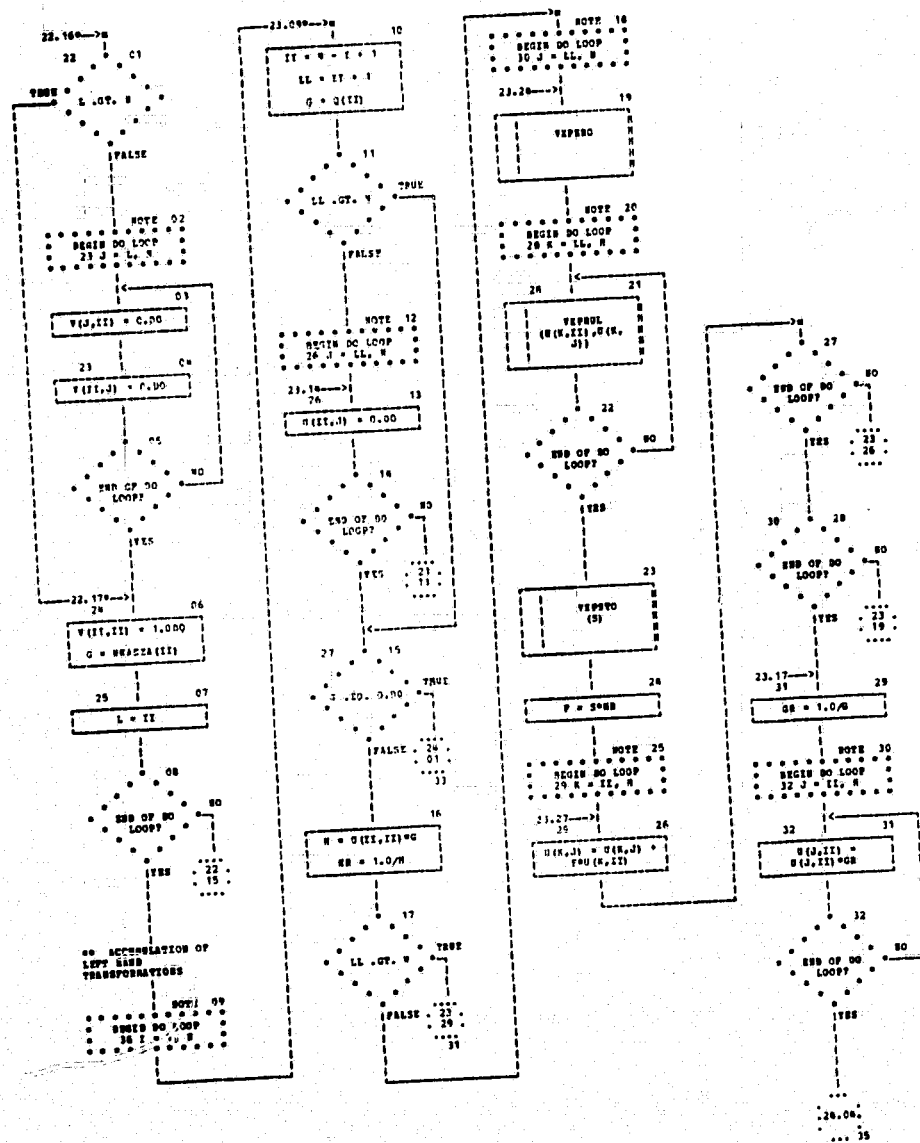
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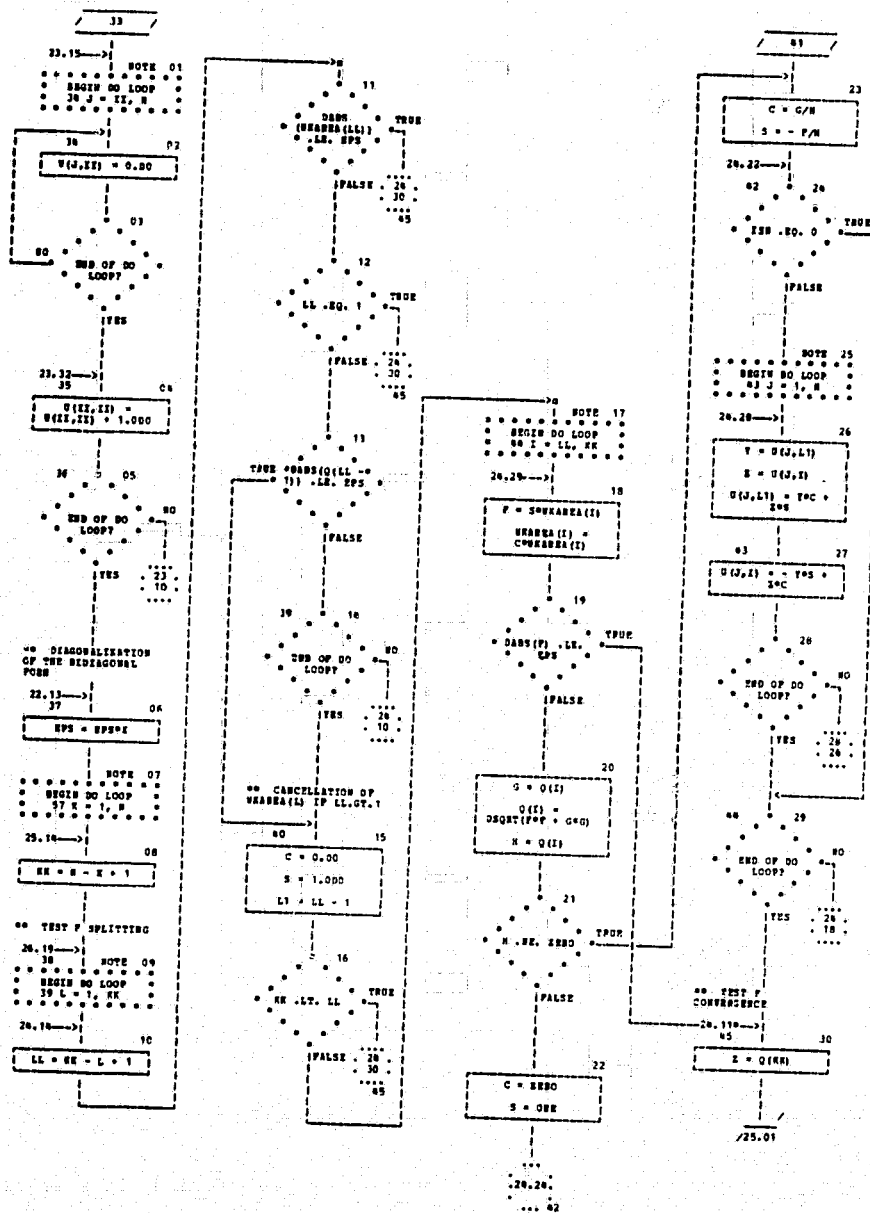
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*NDLCK

PAGE 23

CHART TITLE - SUBROUTINE LVALS(N,M,IA,IV,ISW,WRAPER,O,D,V)





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ASTROFLOW CHART SET -

INDEX

PAGE 25

CHART TITLE - SUBROUTINE LVALS(A,B,C,X,Z,ISQ,SHABRA,Q,P,T)

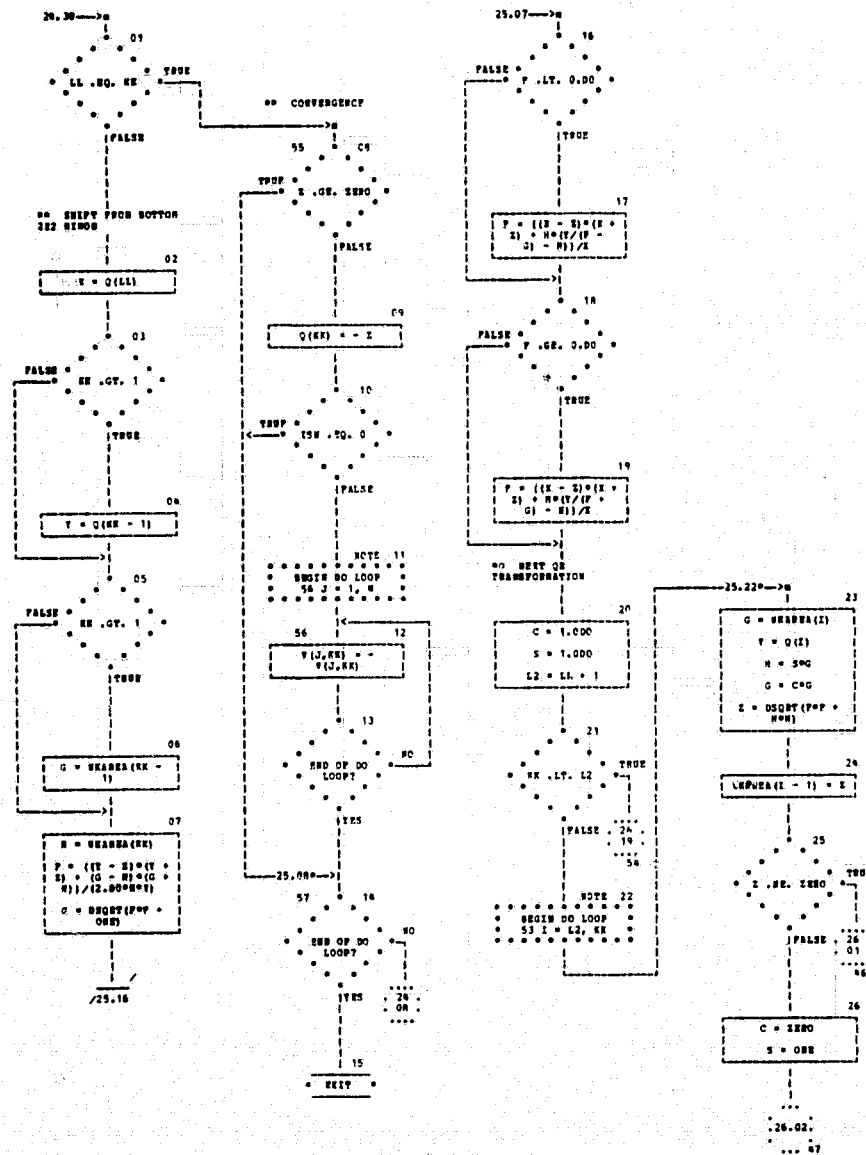


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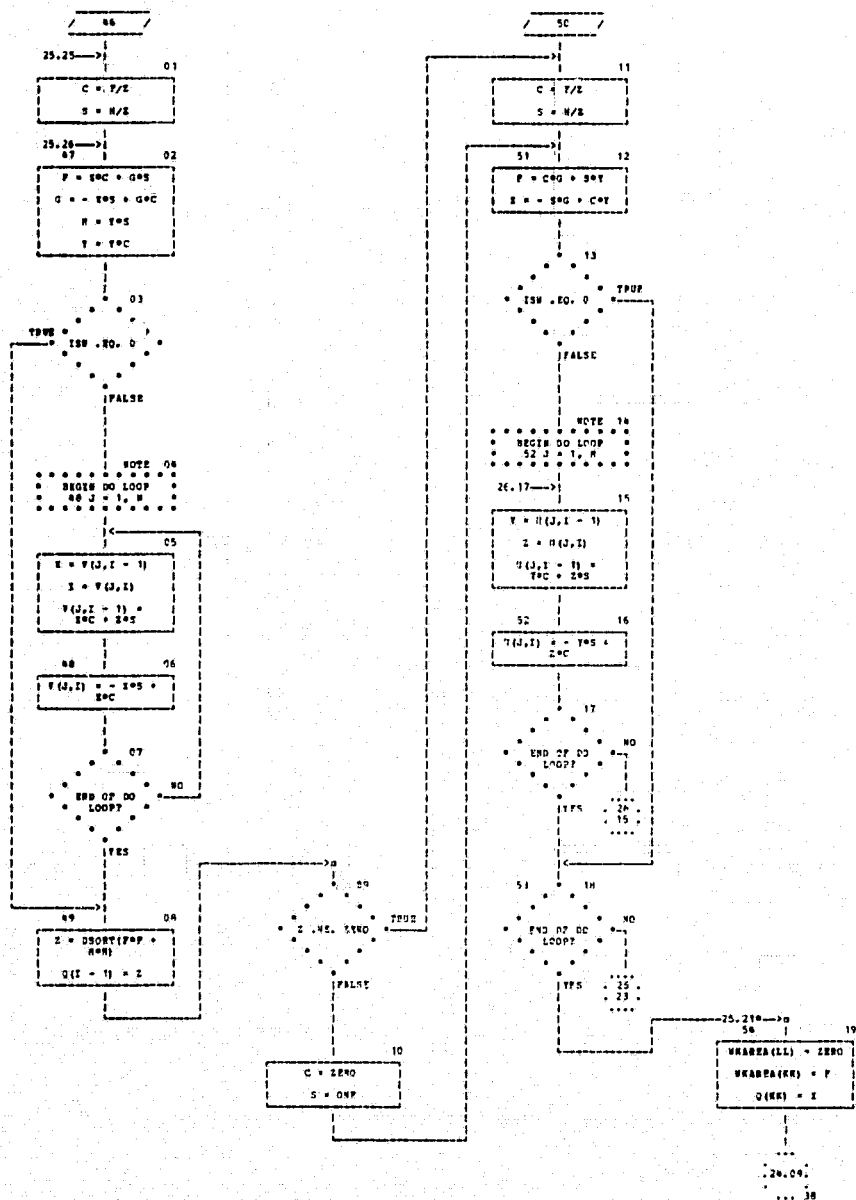


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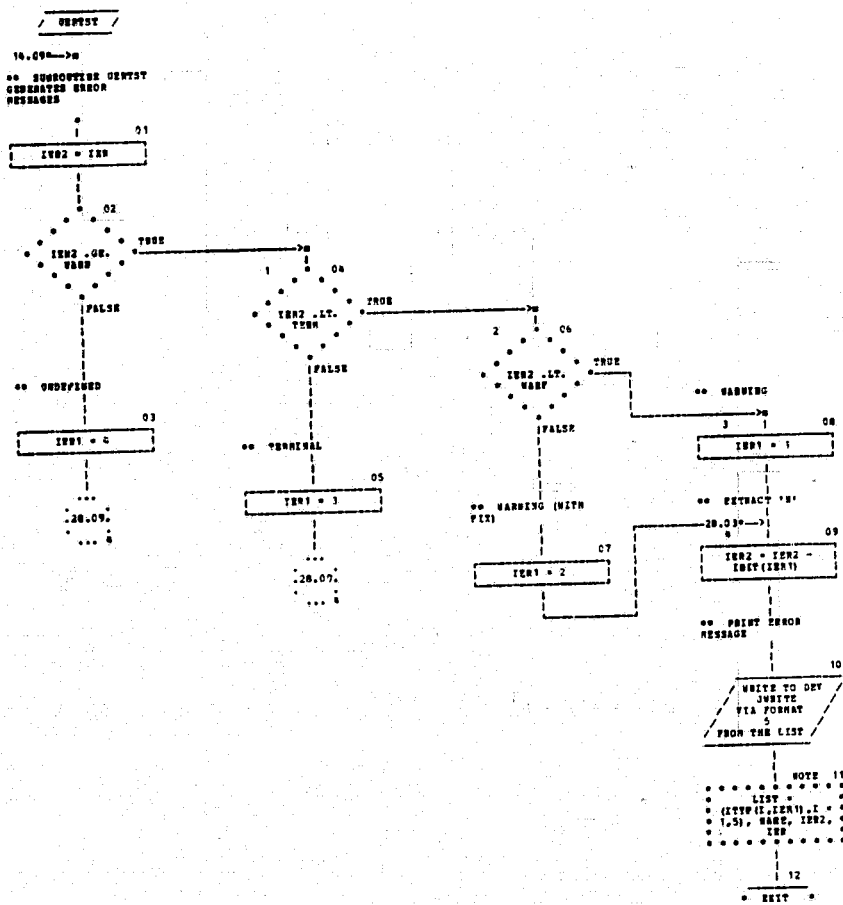
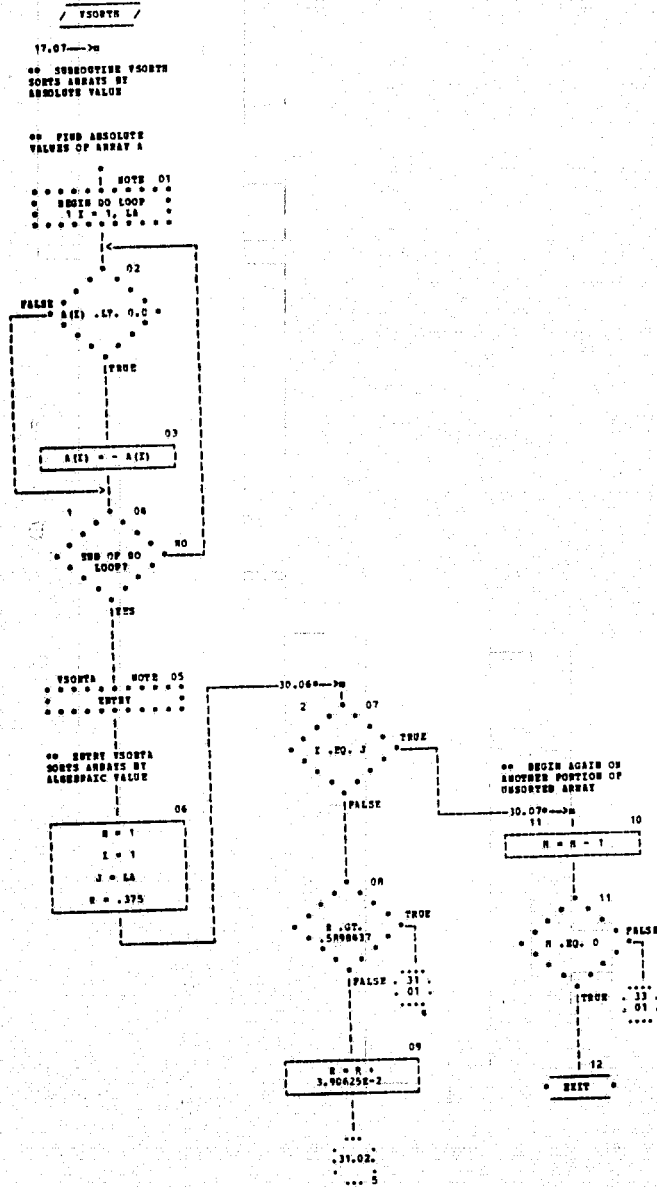


CHART TITLE - SUBROUTINE VSORTN(LA)



Question	Answer
1. What is the main purpose of the study?	To investigate the effect of the new curriculum on the learning outcomes of the students.
2. What are the research objectives?	To compare the learning outcomes of the students who were taught using the new curriculum with those who were taught using the old curriculum.
3. What is the research hypothesis?	The students who were taught using the new curriculum will have higher learning outcomes than those who were taught using the old curriculum.
4. What is the significance of the study?	The study is significant because it will help to determine whether the new curriculum is effective in improving the learning outcomes of the students.
5. What are the limitations of the study?	The study is limited to the students who were taught using the new curriculum and the old curriculum.
6. What are the conclusions of the study?	The study concludes that the new curriculum is effective in improving the learning outcomes of the students.

•NDLCK

CHART TITLE - SUBROUTINE VSORT4(A,LA)



CHART TITLE - SUBROUTINE VSORTN(A,L)

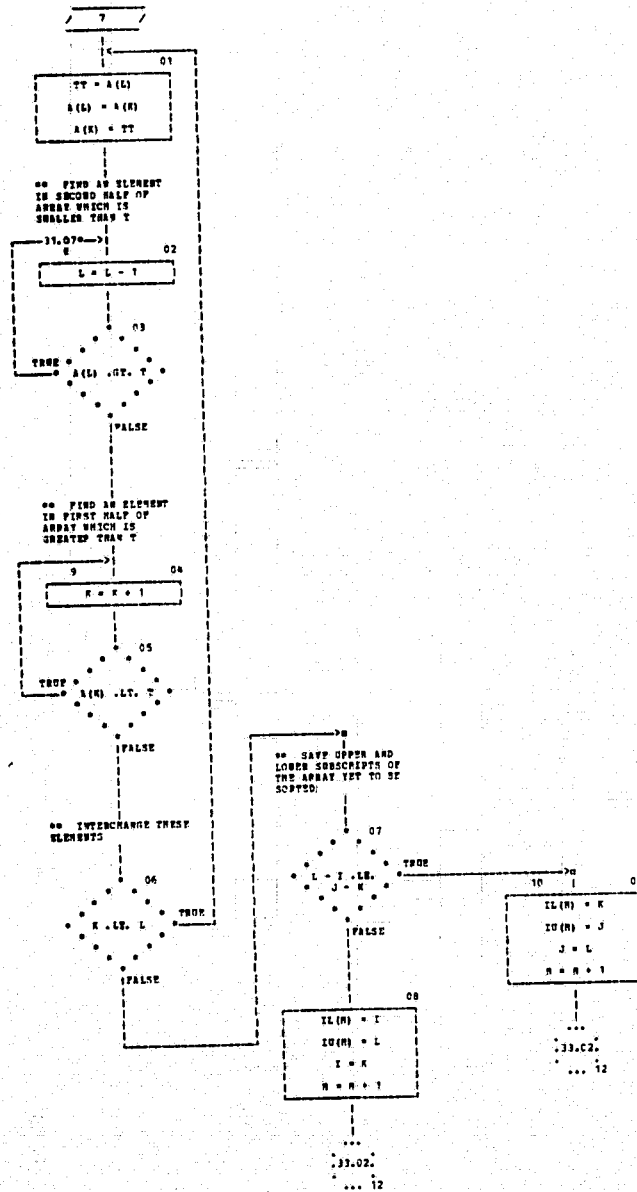
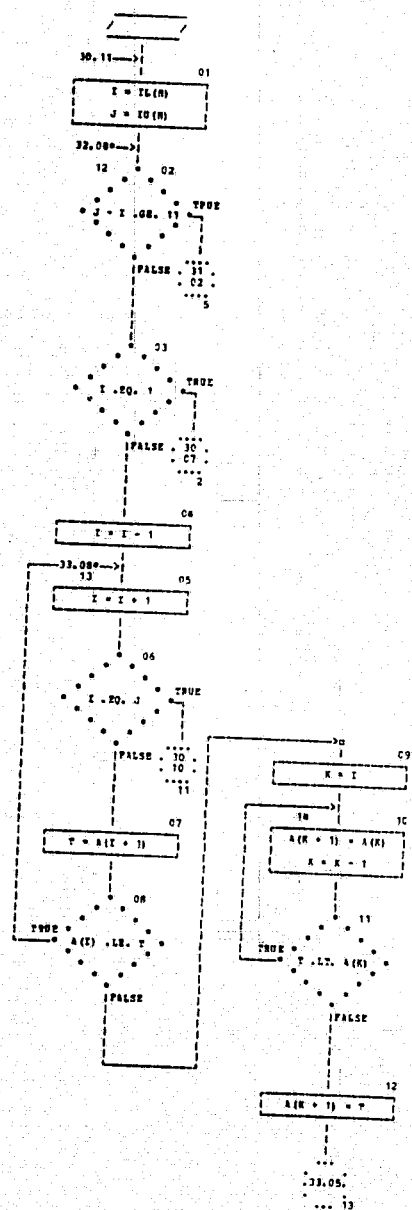


CHART TITLE - SUBROUTINE VSORTH(4,LA)



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 N2 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78
 1100010111111110
 0.33 1.0 2.0 3.0 1 2 3 4
 0.0 220000.0 0.03 0.2 0.0
 N2 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78
 1103011111111110
 0.33 1.0 2.0 3.0 1 2 3 4
 0.0 220000.0 0.03 0.2 0.0
 N2 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78
 1100010011111110
 0.33 1.0 2.0 3.0 1 2 3 4
 0.0 220000.0 0.03 0.2 0.0
 N2 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78
 1100010111111110
 0.33 1.0 2.0 3.0 1 2 3 4
 0.0 220000.0 0.03 0.2 0.0
 END

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 OF POOR QUALITY

Sample Output - MDLCK

ATLIT 2ND MANEUVER-FLAPS UP- PULL UP/PUSH OVER -FLIGHT RECORD 40 / TAPE 33
N2 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78

INPUT PARAMETERS:

```
IDS= 1 LOC(1)= 1 LOC(7)= 0 LOC(13)= 1 EX1= 0.330000 PLOW= 0.0
K = 329 LOC(2)= 1 LOC(8)= 0 LOC(14)= 0 EX2= 1.000000 PHIGH= 220000.00
IEX1= 1 LOC(3)= 0 LOC(9)= 1 LOC(15)= 0 EX3= 2.000000 CDLOW= 0.03000000
IEX2= 2 LOC(4)= 0 LOC(10)= 1 S= 155.000 EX4= 3.000000 CDHIGH= 0.200000
IEX3= 3 LOC(5)= 0 LOC(11)= 1 G=32.20000 METRIC= 0
IEX4= 4 LOC(6)= 0 LOC(12)= 1 TIA=0.0 RHO= 2.37800000D-03
```

MODEL SOLUTION

```
*****
* CASE 1 P0 = -1.9075427295846290D 04 CD0 = 9.7858791559805700D-02 *
* P1 = 1.8783283564491880D 04 CD1 = -3.1127814633765940D 00 *
* POINT P2 = 0.0 CD2 = 7.5219254076526670D 01 *
* FAILURES P3 = 0.0 CD3 = -7.1776141411864490D 02 *
* = 0 P4 = 0.0 CD4 = 2.5315192305099640D 03 *
* P5 = 0.0 CD5 = 0.0 *
* P6 = 0.0 CD6 = 0.0 *
* P7 = 0.0 *
* FIT ERROR= 1.2678382163476900D-03 *
*****
```

ATLIT 2ND MANEUVER-FLAPS UP- PULL UP/PUSH OVER -FLIGHT RECORD 40 / TAPE 33
N2 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78

INPUT PARAMETERS:

```
IDS= 1 LOC(1)= 1 LOC(7)= 0 LOC(13)= 1 EX1= 0.330000 PLOW= 0.0
K = 329 LOC(2)= 0 LOC(8)= 0 LOC(14)= 0 EX2= 1.000000 PHIGH= 220000.00
IEX1= 1 LOC(3)= 1 LOC(9)= 1 LOC(15)= 0 EX3= 2.000000 CDLOW= 0.03000000
IEX2= 2 LOC(4)= 1 LOC(10)= 0 S= 155.000 EX4= 3.000000 CDHIGH= 0.200000
IEX3= 3 LOC(5)= 0 LOC(11)= 1 G=32.20000 METRIC= 0
IEX4= 4 LOC(6)= 1 LOC(12)= 0 TIA=0.0 RHO= 2.37800000D-03
```

MODEL SOLUTION

```
*****
* CASE 2 P0 = 1.2572089673847120D 05 CD0 = 1.1397611529792790D-01 *
* P1 = 0.0 CD1 = 0.0 *
* POINT P2 = -8.8305471163788170D 02 CD2 = 2.2892197472198560D 00 *
* FAILURES P3 = 5.1177917963706350D 00 CD3 = 0.0 *
* = 139 P4 = 0.0 CD4 = 4.9463660472275040D-01 *
* P5 = 0.0 CD5 = 0.0 *
* P6 = 0.0 CD6 = 0.0 *
* P7 = 0.0 *
* FIT ERROR= NOGO *
*****
```

ORIGINAL PAGE IS
OF POOR QUALITY

ATLIT 2ND MANEUVER-FLAPS UP- PULL UP/PUSH OVER -FLIGHT RECORD 40 / TAPE 33
R2 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78

INPUT PARAMETERS:

IDS= 1 LOC(1)= 1 LOC(7)= 1 LOC(13)= 1 EX1= 0.330000 PLOW= 0.0
K = 329 LOC(2)= 1 LOC(8)= 1 LOC(14)= 1 EX2= 1.000000 PHIGH= 220000.00
TEX1= 1 LOC(3)= 0 LOC(9)= 1 LOC(15)= 1 EX3= 2.000000 CDLOW= 0.03000000
TEX2= 2 LOC(4)= 0 LOC(10)= 1 S= 155.000 EX4= 3.000000 CDHIGH= 0.200000
TEX3= 3 LOC(5)= 0 LOC(11)= 1 G=32.20000 METRIC= 0
TEX4= 4 LOC(6)= 0 LOC(12)= 1 TIA=0.0 RHO= 2.378000000D-03

MODEL SOLUTION

* CASE 3 P0 = -1.6727993236693100D 05 CD0 = 1.0578236177750270D-01 *
* P1 = 4.6225563944157660D 04 CD1 = -2.9522029821300210D 00 *
* POINT P2 = 0.0 CD2 = 7.1582277591681330D 01 *
* FAILURES P3 = 0.0 CD3 = -6.7968774725152030D 02 *
* = 0 P4 = 0.0 CD4 = 2.3604573381351100D 03 *
* P5 = 1.0251808370680070D 02 CD5 = -3.7985910360145450D-02 *
* P6 = 3.8167648764190490D 04 CD6 = -3.0345692924638160D-02 *
* P7 = -7.5874764891120240D 04 *
* FIT ERROR= 4.0330476066782180D-04 *

ATLIT 2ND MANEUVER-FLAPS UP- PULL UP/PUSH OVER -FLIGHT RECORD 40 / TAPE 33
R2 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78

INPUT PARAMETERS:

IDS= 1 LOC(1)= 1 LOC(7)= 0 LOC(13)= 1 EX1= 0.330000 PLOW= 0.0
K = 329 LOC(2)= 1 LOC(8)= 0 LOC(14)= 1 EX2= 1.000000 PHIGH= 220000.00
TEX1= 1 LOC(3)= 0 LOC(9)= 1 LOC(15)= 1 EX3= 2.000000 CDLOW= 0.03000000
TEX2= 2 LOC(4)= 0 LOC(10)= 1 S= 155.000 EX4= 3.000000 CDHIGH= 0.200000
TEX3= 3 LOC(5)= 0 LOC(11)= 1 G=32.20000 METRIC= 0
TEX4= 4 LOC(6)= 0 LOC(12)= 1 TIA=0.0 RHO= 2.378000000D-03

MODEL SOLUTION

* CASE 4 P0 = -2.7421717821759680D 04 CD0 = 1.0170408476488630D-01 *
* P1 = 2.0739496227345200D 04 CD1 = -3.3236150323255800D 00 *
* POINT P2 = 0.0 CD2 = 8.1810452665467010D 01 *
* FAILURES P3 = 0.0 CD3 = -7.8777244545713970D 02 *
* = 0 P4 = 0.0 CD4 = 2.7685680185972090D 03 *
* P5 = 1.5325397679C23000D 02 CD5 = -2.9569289621422700D-02 *
* P6 = 0.0 CD6 = -1.3805895088386370D-02 *
* P7 = 0.0 *
* FIT ERROR= 4.4129020022670690D-04 *

ATLIT 2ND MANEUVER-FLAPS UP- PULL UP/PUSH OVER -FLIGHT RECORD 40 / TAPE 33
 82 CALP1=0.8667,CALP2=0.01,DRIFT=-0.0247,INPUT THETA,ATLIT PU/PO 11/16/78

INPUT PARAMETERS:

IDS= 1 LOC(1)= 1 LOC(7)= 0 LOC(13)= 1 EX1= 0.330000 PLOW= 0.0
 K = 329 LOC(2)= 1 LOC(8)= 1 LOC(14)= 1 EX2= 1.000000 PHIGH= 220000.00
 IEX1= 1 LOC(3)= 0 LOC(9)= 1 LOC(15)= 1 EX3= 2.000000 CDLOW= 0.03000000
 IEX2= 2 LOC(4)= 0 LOC(10)= 1 S= 155.000 EX4= 3.000000 CDHIGH= 0.200000
 IEX3= 3 LOC(5)= 0 LOC(11)= 1 G=32.20000 NETRIC= 0
 IEX4= 4 LOC(6)= 0 LOC(12)= 1 TIA=0.0 RHO= 2.37800000D-03

MODEL SOLUTION

```
*****
* CASE 5      P0 = -1.3766976406211250D 05    CD0 = 1.0459972275408370D-01 *
*             P1 = 4.0706173894969020D 04    CD1 = -3.0241526545201370D 00 *
* POINT       P2 = 0.0                        CD2 = 7.3345800606244400D 01 *
* FAILURES    P3 = 0.0                        CD3 = -6.9741647600744210D 02 *
*             P4 = 0.0                        CD4 = 2.4235066074519010D 03 *
*             P5 = 1.1585437965626160D 02    CD5 = -5.9431180733862110D-02 *
*             P6 = 0.0                        CD6 = -2.3753420317233120D-02 *
*             P7 = -6.2007517024450910D 04
*
* FIT ERROR= 4.0574138034874030D-04
*****
```

APPENDIX C

FLIGHT DATA REDUCTION PROGRAM # 2

User Instructions - FDR2

The program is written in FORTRAN IV and is designed to execute in double-precision on an IBM 370/165 computer with an average execution time of 60 minutes for each maneuver data set. Execution requires approximately 936,000 bytes of core storage. Given the output of the FDR1 program (Appendix A), this program

- (a) prints the input data in English or SI units,
- (b) solves as many as 18 different model sets of power and drag coefficients,
- (c) updates all rates for compatibility,
- (d) calculates
 - (1) a bias for the angle of attack values,
 - (2) a 1/3-power model and iterates for initial convergence of the coefficients in the lift expression,
 - (3) the coefficient values in the lift expression,
 - (4) new values of angle of attack from the expression of the lift function, and
 - (5) the frequency-dependent corrections to the angle-of-attack values,
- (e) integrates the aircraft's equations of motion in the x-z plane to obtain time histories of both aircraft and flight path parameters, assuming airspeed and altitude are correct,
- (f) estimates a specific fuel consumption,
- (g) modifies the angle-of-attack values to obtain a better match with the aircraft's trajectory,
- (h) predicts the flight path trajectory in an iterative procedure to attempt an improvement in the power, lift, and drag coefficients,
- (i) computes the confidence levels for the angle-of-attack values and the pitch-angle values,
- (j) prints the output results in English or SI units, and
- (k) punches cards for stability analysis.

The program requires the specification of the following input:

CARD 1:

The title array TITLE.

The 80 characters of the array TITLE are used as control variables to end execution. Execution termination is achieved by following the last data card with a title card having only the word END in the first three card columns. It should be observed that on all other occasions this card behaves simply as a dummy card. Therefore, the user may wish to use this card to supply additional data set labeling.

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CARD 2:

- (a) The read unit number IDS:
IDS is a right-adjusted integer number occupying columns 1-5 and specifying that the data is to be read from cards, magnetic tape, disk, etc. The user must supply the suitable job control cards for the tape and/or disk reads. The IDS parameter controls only the reading of CARDS 33, 34, and (35,...,34 + 5K). All other data is expected in card form.
- (b) The input-data print code INPUT:
INPUT is a right-adjusted integer number occupying columns 6-10. If INPUT = 0, the input time histories are printed. If INPUT = 1, the input time histories are not printed.
- (c) The plot code IPLOT:
IPLOT is a right-adjusted integer number occupying columns 11-15. If IPLOT = 0, plots will be allowed. If IPLOT = 1, no plots will be allowed.
- (d) The punch code IPUNCH:
IPUNCH is a right-adjusted integer number occupying columns 16-20. If IPUNCH = 0, no cards will be punched. If IPUNCH = 1, cards will be punched.
- (e) The desired type of input and output units METRIC:
If METRIC = 0, the input and output will be in English units. If METRIC = 1, the input and output will be in SI units. METRIC is a right-adjusted integer number occupying columns 21-25. The specification of METRIC only affects the listings. The punched output is in English units.
- (f) The lift function code MTH:
MTH is a right-adjusted integer number, occupying columns 26-30, specifying the form of lift-coefficient equation. The following chart indicates the available forms:

MTH	FORM
0	$C_L = x_0 + x_1 \alpha$
1	$C_L = x_0 + x_1 \alpha + x_2 \dot{\theta}$
2	$C_L = x_0 + x_1 \alpha + x_2 \alpha^3$
3	$C_L = x_0 + x_1 \alpha + x_2 \alpha^3 + x_4 \dot{\theta}$
4	$C_L = x_0 + x_1 \alpha^2$
5	$C_L = x_0 + x_1 \alpha^2 + x_3 \dot{\theta}$

If MTH > 5 or MTH < 0, the program sets MTH = 0.

- (g) The method by which the coefficients in the lift expression are determined, MCLCC:

MCLCC is a right-adjusted integer number occupying columns 31-35. If MCLCC = 0, the lift coefficients (x_i 's) are calculated by a linear-least-squares procedure. If MCLCC = 1, the lift coefficients (x_i 's) are calculated by a least-square-distance procedure. If the user specifies MCLCC = 1 and the procedure is not capable of converging, the program defaults to MCLCC = 0.

- (h) The maximum number MAXHPI of iterative attempts to improve the power, lift, and drag coefficients by trajectory predictions: MAXHPI is a right-adjusted integer number, occupying columns 36-40, with a maximum permissible value of 5. MAXHPI does not control the preset number of sub-iterations between the power-drag model solutions.

CARD 3:

- (a) The exponent EX1 on the second power-coefficient term,
 (b) The exponent EX2 on the third power-coefficient term,
 (c) The exponent EX3 on the fourth power-coefficient term,
 (d) The exponent EX4 on the fifth power-coefficient term,
 (e) The exponent IEX1 on the second drag-coefficient term,
 (f) The exponent IEX2 on the third drag-coefficient term,
 (g) The exponent IEX3 on the fourth drag-coefficient term, and
 (h) The exponent IEX4 on the fifth drag-coefficient term:
 EX1, EX2, EX3, and EX4 are floating-point numbers each occupying 10 columns beginning at column 1. It should be noted that no two of these exponents must have the same value; otherwise, execution will terminate. IEX1, IEX2, IEX3, IEX4 are right-adjusted integer numbers each occupying 5 columns beginning at column 41. It should be noted that no two of these exponents must have the same value; otherwise, execution will terminate.

CARD 4:

The power-drag model solution forms IMODEL(I), I=1,...,18:
 IMODEL(I) are right-adjusted integer numbers, each occupying 1 column beginning at column 1, specifying the model(s) to be used for the determination of the power and drag coefficients. The general power and drag coefficient equations are

$$P = P_0 + P_1 V^{EX1} + P_2 V^{EX2} + P_3 V^{EX3} + P_4 V^{EX4} \quad \text{and}$$

$$C_D = C_{D0} + C_{D1} \alpha^{IEX1} + C_{D2} \alpha^{IEX2} + C_{D3} \alpha^{IEX3} + C_{D4} \alpha^{IEX4}$$

Through the use of IMODEL(I), various combinations of the coefficients can be specified*. If IMODEL(I) = 0, the model will be bypassed. If IMODEL(I) = 1, the model solution will be performed. It is mandatory that at least one model is specified; otherwise, the program will terminate prematurely. The following chart should be used for the specification of the desired model(s):

IMODEL(I)	Coefficients Determined by Analysis
I = 1	P_0, C_{D0}, C_{D2}
I = 2	P_0, P_1, C_{D0}, C_{D2}
I = 3	$P_0, P_1, C_{D0}, C_{D2}, C_{D4}$
I = 4	$P_0, P_1, C_{D0}, C_{D1}, C_{D2}, C_{D3}, C_{D4}$
I = 5	P_0, P_2, C_{D0}, C_{D2}
I = 6	$P_0, P_2, C_{D0}, C_{D2}, C_{D4}$
I = 7	$P_0, P_2, C_{D0}, C_{D1}, C_{D2}, C_{D3}, C_{D4}$
I = 8	$P_0, P_1, P_2, C_{D0}, C_{D2}$
I = 9	$P_0, P_1, P_2, C_{D0}, C_{D2}, C_{D4}$
I = 10	$P_0, P_1, P_2, C_{D0}, C_{D1}, C_{D2}, C_{D3}, C_{D4}$
I = 11	$P_0, P_2, P_3, C_{D0}, C_{D2}$
I = 12	$P_0, P_2, P_3, C_{D0}, C_{D2}, C_{D4}$
I = 13	$P_0, P_2, P_3, C_{D0}, C_{D1}, C_{D2}, C_{D3}, C_{D4}$

*The user may wish to specify different models than those models provided. In order for this to be accomplished, the users must change the DATA statement and the INTEGER statement in Subroutine MODEL. The DATA statement assumes that 18 "different" models, each with a maximum of 10 coefficients for the power-drag model, will be specified. The INTEGER statement indicates the numbers of unknowns in the models of the DATA statement.

Chart (Continued)

IMODEL(I)	Coefficients Determined by Analysis
I = 14	$P_0, C_{D0}, C_{D1}, C_{D2}$
I = 15	$P_0, P_1, C_{D0}, C_{D1}, C_{D2}$
I = 16	$P_0, P_2, C_{D0}, C_{D1}, C_{D2}$
I = 17	$P_0, P_1, P_2, C_{D0}, C_{D1}, C_{D2}$
I = 18	$P_0, P_2, P_3, C_{D0}, C_{D1}, C_{D2}$

CARD 5:

- (a) The lower allowable limit PLOW of the power available in foot-pounds per second,
 - (b) The upper allowable limit PHIGH of the power available in foot-pounds per second,
 - (c) The lower allowable limit CDLOW of the drag coefficient,
 - (d) The upper allowable limit CDHIGH of the drag coefficient,
 - (e) The thrust incidence angle TIA in radians,
 - (f) The estimated initial flight-path-angle bias TARE in radians, and
 - (g) The estimated initial altitude bias HTARE in feet:
- PLOW, PHIGH, CDLOW, CDHIGH, and TIA are floating-point numbers each occupying 10 columns beginning at column 1. TARE and HTARE are double-precision floating-point numbers each occupying 15 columns beginning at column 51.

CARDS 6,...,18:

- (a) The a priori value AP(1) in $\text{ft-lb}_f/\text{sec}$ and its weight WGT(1) for the first power coefficient P_0 ,
- (b) The a priori value AP(2) in suitable power units* and its weight WGT(2) for the second power coefficient P_1 ,
- (c) The a priori value AP(3) in suitable power units* and its weight WGT(3) for the third power coefficient P_2 ,
- (d) The a priori value AP(4) in suitable power units* and its weight WGT(4) for the fourth power coefficient P_3 ,
- (e) The a priori value AP(5) in suitable power units* and its weight WGT(5) for the fifth power coefficient P_4 ,

* Since the "coefficients" of the power and drag coefficients' equations, given in the discussion of CARD 4, and the lift coefficients' equation, given in the discussion of CARD 2(f), are user-dependent, the user must specify the a priori values in suitable units.

- (f) The a priori value AP(6) and its weight WGT(6) for the first drag coefficient C_{D_0} ,
- (g) The a priori value AP(7) in suitable drag units* and its weight WGT(7) for the second drag coefficient C_{D_1} ,
- (h) The a priori value AP(8) in suitable drag units* and its weight WGT(8) for the third drag coefficient C_{D_2} ,
- (i) The a priori value AP(9) in suitable drag units* and its weight WGT(9) for the fourth drag coefficient C_{D_3} ,
- (j) The a priori value AP(10) in suitable drag units* and its weight WGT(10) for the fifth drag coefficient C_{D_4} ,
- (k) The a priori value AP(11) and its weight WGT(11) for the lift coefficient $C_{L_{\alpha_0}}$,
- (l) The a priori value AP(12) in per radian and its weight WGT(12) for the lift coefficient $C_{L_{\alpha}}$, and
- (m) The a priori value AP(13) in suitable lift units* and its weight WGT(13) for the lift coefficient $C_{L_{\alpha x}}$:

AP(1) and WGT(1) are double-precision floating-point numbers each occupying 20 columns beginning at column 1. Each of the thirteen (13) input cards contains the AP(1) and WGT(1) that correspond to the coefficient under consideration. A zero weight on any of the a priori values prevents the application of an a priori value to that coefficient.

CARD 19:

- (a) The plot code IP(1) for weight,
- (b) The plot code IP(2) for pitch angle,
- (c) The plot code IP(3) for pitch rate,
- (d) The plot code IP(4) for airspeed,
- (e) The plot code IP(5) for density,
- (f) The plot code IP(6) for angle of attack,
- (g) The plot code IP(7) for static temperature,
- (h) The plot code IP(8) for acceleration,
- (i) The plot code IP(9) for angle-of-attack rate,
- (j) The plot code IP(10) for altitude,
- (k) The plot code IP(11) for altitude rate,
- (l) The plot code IP(12) for altitude acceleration,
- (m) The plot code IP(13) for vertical acceleration,

*
(See previous note).

- (n) The plot code IP(14) for elevator or stabilator deflection,
- (o) The plot code IP(15) for lift coefficient versus angle of attack,
- (p) The Plot code IP(16) for drag coefficient versus angle of attack,
- (q) The plot code IP(17) for lift coefficient versus drag coefficient, and
- (r) The plot code IP(18) for power available versus airspeed:
 If IP(1) = 0, a plot is produced for the "1"th time history.
 If IP(1) = 1, no plot is produced for the "1"th time history.
 IP(1) are right-adjusted integer numbers each occupying one column beginning at column 1.

CARDS 20,...,32:

- (a) The minimal allowable constraint CRMIN(1) and the maximal allowable constraint CRMAX(1) for the power coefficient P_0^* ,
- (b) The minimal allowable constraint CRMIN(2) and the maximal allowable constraint CRMAX(2) for the power coefficient P_1^* ,
- (c) The minimal allowable constraint CRMIN(3) and the maximal allowable constraint CRMAX(3) for the power coefficient P_2^* ,
- (d) The minimal allowable constraint CRMIN(4) and the maximal allowable constraint CRMAX(4) for the power coefficient P_3^* ,
- (e) The minimal allowable constraint CRMIN(5) and the maximal allowable constraint CRMAX(5) for the power coefficient P_4^* ,
- (f) The minimal allowable constraint CRMIN(6) and the maximal allowable constraint CRMAX(6) for the drag coefficient C_{D0}^* ,
- (g) The minimal allowable constraint CRMIN(7) and the maximal allowable constraint CRMAX(7) for the drag coefficient C_{D1}^* ,
- (h) The minimal allowable constraint CRMIN(8) and the maximal allowable constraint CRMAX(8) for the drag coefficient C_{D2}^* ,
- (i) The minimal allowable constraint CRMIN(9) and the maximal allowable constraint CRMAX(9) for the drag coefficient C_{D3}^* ,
- (j) The minimal allowable constraint CRMIN(10) and the maximal allowable constraint CRMAX(10) for the drag coefficient C_{D4}^* ,
- (k) The minimal allowable constraint CRMIN(11) and the maximal allowable constraint CRMAX(11) for the lift coefficient $C_{L\alpha 0}^*$,
- (l) The minimal allowable constraint CRMIN(12) and the maximal allowable constraint CRMAX(12) for the lift coefficient $C_{L\alpha}^*$, and
- (m) The minimal allowable constraint CRMIN(13) and the maximal allowable constraint CRMAX(13) for the lift coefficient $C_{L\alpha x}^*$:

* Since the "coefficients" of the power, drag and lift coefficients' equations are user-dependent, the user must specify the values of CRMIN(1) and CRMAX(1) in suitable units.

CRMIN(I) and CRMAX(I) are double-precision floating-point numbers each occupying 20 columns beginning at column 1. Each of the thirteen (13) input cards contains the CRMIN(I) and CRMAX(I) that correspond to the coefficient under consideration.

CARD 33:

The title array TITLE:

The 80 characters of the array TITLE are used for identifying output. TITLE is provided by the first card of the punched output of the FDR1 program.

CARD 34:

- (a) The total number of points K in the data set,
 - (b) The aircraft's wing area S in square feet,
 - (c) The sea-level atmospheric density RHO in slug/ft³,
 - (d) The acceleration due to gravity G in ft/sec², and
 - (e) The total elapsed time for the maneuver TT in seconds:
- K is a right-adjusted integer number occupying columns 1-10. S, RHO, G, and TT are double-precision floating-point numbers each occupying 15 columns beginning at column 11. These values are provided by the second card of the punched output of the FDR1 program.

CARD 35,...,(34 + 5K):

The time histories of time TIME(I), weight F1(I), pitch angle F2(I), pitch rate F3(I), airspeed F4(I), density F5(I), angle of attack F6(I), static temperature F7(I), acceleration F8(I), angle-of-attack rate F9(I), altitude F10(I), altitude rate F11(I), altitude acceleration F12(I), vertical acceleration F13(I), and elevator or stabilator deflection F14(I):

The variables TIME(I) and F1(I) through F14(I) are double-precision floating-point numbers each occupying 25 columns. These variables are provided by the remaining punched output of the FDR1 program.

For a given run consisting of more than one data set, cards 1 through (34 + 5K) must be specified for each data set.

Program Listing - FDR2

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C PROGRAM: FLIGHT DATA REDUCTION #2 ( FDR2 ) - P.O. SHETANA & S.M. FOX NL 1
C
C ***** NL 2
C * FLIGHT DATA REDUCTION 2 * NL 3
C * NL 4
C ***** NL 5
C
C GIVEN VALUES OF THE AIRCRAFT CHARACTERISTICS AND THE AIRCRAFT'S NL 6
C FLIGHT TIME HISTORIES OF WEIGHT, PITCH ANGLE, PITCH RATE, AIRSPEED NL 7
C DENSITY, ANGLE OF ATTACK, STATIC TEMPERATURE, ACCELERATION, ANGLE- NL 8
C OF-ATTACK RATE, ALTITUDE, ALTITUDE RATE, ALTITUDE ACCELERATION, NL 9
C VERTICAL ACCELERATION, AND ELEVATOR (OR STABILATOR) DEFLECTION, NL 10
C THIS PROGRAM PERFORMS THE FOLLOWING: NL 11
C
C 1) PRINTS INPUT DATA IN ENGLISH OR SI UNITS NL 12
C
C 2) SOLVES UP THROUGH 18 DIFFERENT MODEL SOLUTIONS FOR POWER NL 13
C AND DRAG COEFFICIENTS NL 14
C
C 3) CALCULATES A BIAS FOR THE ANGLE-OF-ATTACK VALUES NL 15
C
C 4) UPDATES ALL RATES FOR COMPATIBILITY NL 16
C
C 5) COMPUTES A 1/3-POWER MODEL ITERATION FOR INITIAL CONVERGENCE NL 17
C
C 6) COMPUTES THE LIFT COEFFICIENTS NL 18
C
C 7) INSPECTS THE ANGLE-OF-ATTACK VALUES DUE TO THE LIFT COEF- NL 19
C FICIENTS NL 20
C
C 8) CALCULATES FREQUENCY-DEPENDENT CORRECTIONS TO ANGLE-OF- NL 21
C ATTACK VALUES NL 22
C
C 9) INTEGRATES THE AIRCRAFT'S EQUATIONS OF MOTION TO OBTAIN TIME NL 23
C HISTORIES OF BOTH AIRCRAFT AND FLIGHT PATH PARAMETERS ASSUM- NL 24
C ING AIRSPEED AND ALTITUDE ARE CORRECT NL 25
C
C 10) CALCULATES A SPECIFIC FUEL CONSUMPTION NL 26
C
C 11) MODIFIES ANGLE-OF-ATTACK VALUES DUE TO THE INTEGRATION OF NL 27
C AIRCRAFT'S EQUATION OF MOTION NL 28
C
C 12) PREDICTS THE FLIGHT PATH TRAJECTORY IN AN ITERATIVE PROCE- NL 29
C DURE TO ATTEMPT AN IMPROVEMENT IN THE POWER, LIFT, AND DRAG NL 30
C COEFFICIENTS NL 31
C
C 13) COMPUTES CONFIDENCE LEVELS FOR ANGLE-OF-ATTACK VALUES AND NL 32
C PITCH-ANGLE VALUES NL 33
C
C 14) PRINTS OUTPUT RESULTS IN ENGLISH OR SI UNITS NL 34
C
C 15) PUNCHES CARDS FOR STABILITY ANALYSIS NL 35
C

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C
C THE FOLLOWING COMMENT CARDS DESCRIBE THE NECESSARY INPUT FOR THIS NL 58
C PROGRAM. FOR A MORE PRECISE DESCRIPTION, CONSULT THE USERS IN- NL 59
C STRUCTIONS. NL 60
C
C INPUT *** CARD 1 NL 61
C
C TITLE -> FIRST TITLE CARD (DUMMY CARD, EXCEPT FOR PROGRAM NL 62
C TERMINATION) NL 63
C
C INPUT *** CARD 2 NL 64
C
C IDS -> READ UNIT NUMBER (ALLOWS READING OF CARDS, DISK, NL 65
C TAPE, ETC OF PUNCHED CARDS FROM 'FDR1') NL 66
C
C INPUT -> CODE FOR INPUT DATA PRINT NL 67
C INPUT=0 -> PRINT INPUT DATA NL 68
C INPUT=1 -> NO PRINT NL 69
C
C IPLOT -> PLOT CODE NL 70
C IPLOT=0 -> PLOT NL 71
C IPLOT=1 -> NO PLOT NL 72
C
C IPUNCH -> PUNCH CODE NL 73
C IPUNCH=0 -> NO PUNCH NL 74
C IPUNCH=1 -> PUNCH CARDS NL 75
C
C METRIC -> INPUT/OUTPUT PRINT CODE NL 76
C METRIC=0 -> INPUT & OUTPUT PRINTED IN ENGLISH UNITS NL 77
C METRIC=1 -> INPUT & OUTPUT PRINTED IN SI UNITS NL 78
C
C NTH -> LIFT FUNCTION FORM CODE NL 79
C NTH=0 ->  $CL=X0+X1*A$  NL 80
C NTH=1 ->  $CL=X0+X1*A+X2*B$  NL 81
C NTH=2 ->  $CL=X0+X1*A+X2*A**X3$  NL 82
C NTH=3 ->  $CL=X0+X1*A+X2*A**X3+X4*B$  NL 83
C NTH=4 ->  $CL=X0+X1*A**X3$  NL 84
C NTH=5 ->  $CL=X0+X1*A**X3+X4*B$  NL 85
C WHERE: A=ANGLE OF ATTACK NL 86
C B=PITCH RATE NL 87
C
C MCLOC -> METHOD OF LIFT COEFFICIENT CALCULATION NL 88
C MCLOC=0 -> LINEAR LEAST SQUARES NL 89
C MCLOC=1 -> LEAST SQUARE DISTANCE NL 90
C
C MAXHPI -> MAXIMUM NUMBER OF ITERATIVE ATTEMPTS TO IMPROVE THE NL 91
C POWER, LIFT, AND DRAG COEFFICIENTS BY TRAJECTORY NL 92
C PREDICTIONS (-1<MAXHPI<6) NL 93
C
C INPUT *** CARD 3 (CONSULT USERS INSTRUCTIONS) NL 94
C
C EXP1 -> EXPONENT ON SECOND POWER-COEFFICIENT TERM NL 95
C

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C      EX2  -> EXPONENT ON THIRD POWER-COEFFICIENT TERM      NL 118
C      EX3  -> EXPONENT ON FOURTH POWER-COEFFICIENT TERM      NL 119
C      EX4  -> EXPONENT ON FIFTH POWER-COEFFICIENT TERM      NL 120
C      IEX1  -> EXPONENT ON SECOND DRAG-COEFFICIENT TERM (INTEGER) NL 121
C      IEX2  -> EXPONENT ON THIRD DRAG-COEFFICIENT TERM (INTEGER) NL 122
C      IEX3  -> EXPONENT ON FOURTH DRAG-COEFFICIENT TERM (INTEGER) NL 123
C      IEX4  -> EXPONENT ON FIFTH DRAG-COEFFICIENT TERM (INTEGER) NL 124
C
C INPUT *** CARD 4 (CONSULT USERS INSTRUCTIONS)
C      INODEL -> MODEL SOLUTION FORM (CHOSEN BY CARD COLUMN NUMBER) NL 125
C      INODEL=0 -> SKIP MODEL NL 126
C      INODEL=1 -> SOLVE MODEL NL 127
C
C INPUT *** CARD 5
C      PLOW -> LOWER LIMIT OF ALLOWABLE POWER AVAILABLE (FT-LB/SEC) NL 128
C      PHIGH -> UPPER LIMIT OF ALLOWABLE POWER AVAILABLE (FT-LB/SEC) NL 129
C      CDLOW -> LOWER LIMIT OF ALLOWABLE DRAG COEFFICIENT NL 130
C      CDHIGH -> UPPER LIMIT OF ALLOWABLE DRAG COEFFICIENT NL 131
C      TIA -> THRUST INCIDENCE ANGLE IN RADIAN NL 132
C      TANR -> ESTIMATED INITIAL FLIGHT-PATH-ANGLE BIAS IN RADIAN NL 133
C      HTANG -> ESTIMATED INITIAL ALTITUDE BIAS IN FEET NL 134
C
C INPUT *** CARDS 6, ..., 18
C      AP(1), WGT(1) -> A PRIORI VALUE AND WEIGHT FOR P0 NL 135
C      AP(2), WGT(2) -> A PRIORI VALUE AND WEIGHT FOR P1 NL 136
C      AP(3), WGT(3) -> A PRIORI VALUE AND WEIGHT FOR P2 NL 137
C      AP(4), WGT(4) -> A PRIORI VALUE AND WEIGHT FOR P3 NL 138
C      AP(5), WGT(5) -> A PRIORI VALUE AND WEIGHT FOR P4 NL 139
C      AP(6), WGT(6) -> A PRIORI VALUE AND WEIGHT FOR CD0 NL 140
C      AP(7), WGT(7) -> A PRIORI VALUE AND WEIGHT FOR CD1 NL 141
C      AP(8), WGT(8) -> A PRIORI VALUE AND WEIGHT FOR CD2 NL 142
C      AP(9), WGT(9) -> A PRIORI VALUE AND WEIGHT FOR CD3 NL 143
C      AP(10), WGT(10) -> A PRIORI VALUE AND WEIGHT FOR CD4 NL 144
C      AP(11), WGT(11) -> A PRIORI VALUE AND WEIGHT FOR CLAG NL 145
C      AP(12), WGT(12) -> A PRIORI VALUE AND WEIGHT FOR CLA NL 146
C      AP(13), WGT(13) -> A PRIORI VALUE AND WEIGHT FOR CLAX NL 147

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C INPUT *** CARD 19
C      IP(1) -> PLOT CODE FOR WEIGHT TIME HISTORY NL 178
C      IP(1)=0 -> REQUESTED NL 179
C      IP(1)=1 -> NOT REQUESTED NL 180
C      IP(2) -> PLOT CODE FOR PITCH ANGLE TIME HISTORY NL 181
C      IP(2)=0 -> REQUESTED NL 182
C      IP(2)=1 -> NOT REQUESTED NL 183
C      IP(3) -> PLOT CODE FOR PITCH RATE TIME HISTORY NL 184
C      IP(3)=0 -> REQUESTED NL 185
C      IP(3)=1 -> NOT REQUESTED NL 186
C      IP(4) -> PLOT CODE FOR AIRSPEED TIME HISTORY NL 187
C      IP(4)=0 -> REQUESTED NL 188
C      IP(4)=1 -> NOT REQUESTED NL 189
C      IP(5) -> PLOT CODE FOR DENSITY TIME HISTORY NL 190
C      IP(5)=0 -> REQUESTED NL 191
C      IP(5)=1 -> NOT REQUESTED NL 192
C      IP(6) -> PLOT CODE FOR ANGLE OF ATTACK TIME HISTORY NL 193
C      IP(6)=0 -> REQUESTED NL 194
C      IP(6)=1 -> NOT REQUESTED NL 195
C      IP(7) -> PLOT CODE FOR TEMPERATURE TIME HISTORY NL 196
C      IP(7)=0 -> REQUESTED NL 197
C      IP(7)=1 -> NOT REQUESTED NL 198
C      IP(8) -> PLOT CODE FOR ACCELERATION TIME HISTORY NL 199
C      IP(8)=0 -> REQUESTED NL 200
C      IP(8)=1 -> NOT REQUESTED NL 201
C      IP(9) -> PLOT CODE FOR ANGLE-OF-ATTACK RATE TIME HISTORY NL 202
C      IP(9)=0 -> REQUESTED NL 203
C      IP(9)=1 -> NOT REQUESTED NL 204
C      IP(10) -> PLOT CODE FOR ALTITUDE TIME HISTORY NL 205
C      IP(10)=0 -> REQUESTED NL 206
C      IP(10)=1 -> NOT REQUESTED NL 207
C      IP(11) -> PLOT CODE FOR ALTITUDE RATE TIME HISTORY NL 208
C      IP(11)=0 -> REQUESTED NL 209
C      IP(11)=1 -> NOT REQUESTED NL 210
C      IP(12) -> PLOT CODE FOR ALTITUDE ACCELERATION TIME HISTORY NL 211
C      IP(12)=0 -> REQUESTED NL 212
C      IP(12)=1 -> NOT REQUESTED NL 213
C      IP(13) -> PLOT CODE FOR VERTICAL ACCELERATION TIME HISTORY NL 214
C      IP(13)=0 -> REQUESTED NL 215
C      IP(13)=1 -> NOT REQUESTED NL 216
C      IP(14) -> PLOT CODE FOR ELEVATOR/STABILATOR TIME HISTORY NL 217
C      IP(14)=0 -> REQUESTED NL 218
C      IP(14)=1 -> NOT REQUESTED NL 219
C      IP(15) -> PLOT CODE FOR LIFT COEFFICIENT VS ANGLE OF ATTACK NL 220
C      IP(15)=0 -> REQUESTED NL 221
C      IP(15)=1 -> NOT REQUESTED NL 222
C      IP(16) -> PLOT CODE FOR LIFT COEFFICIENT VS ANGLE OF ATTACK NL 223
C      IP(16)=0 -> REQUESTED NL 224
C      IP(16)=1 -> NOT REQUESTED NL 225
C      IP(17) -> PLOT CODE FOR LIFT COEFFICIENT VS ANGLE OF ATTACK NL 226
C      IP(17)=0 -> REQUESTED NL 227
C      IP(17)=1 -> NOT REQUESTED NL 228
C      IP(18) -> PLOT CODE FOR LIFT COEFFICIENT VS ANGLE OF ATTACK NL 229
C      IP(18)=0 -> REQUESTED NL 230
C      IP(18)=1 -> NOT REQUESTED NL 231
C      IP(19) -> PLOT CODE FOR LIFT COEFFICIENT VS ANGLE OF ATTACK NL 232
C      IP(19)=0 -> REQUESTED NL 233
C      IP(19)=1 -> NOT REQUESTED NL 234
C      IP(20) -> PLOT CODE FOR LIFT COEFFICIENT VS ANGLE OF ATTACK NL 235
C      IP(20)=0 -> REQUESTED NL 236
C      IP(20)=1 -> NOT REQUESTED NL 237

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C          IP(15)=1 -> NOT REQUESTED          NL 238
C          IP(16) -> PLOT CODE FOR DRAG COEFFICIENT VS ANGLE OF ATTACK NL 239
C          IP(16)=0 -> REQUESTED                NL 240
C          IP(16)=1 -> NOT REQUESTED            NL 241
C          IP(17) -> PLOT CODE FOR LIFT COEFFICIENT VS DRAG COEFFICIENT NL 242
C          IP(17)=0 -> REQUESTED                NL 243
C          IP(17)=1 -> NOT REQUESTED            NL 244
C          IP(18) -> PLOT CODE FOR POWER AVAILABLE VS AIRSPEED          NL 245
C          IP(18)=0 -> REQUESTED                NL 246
C          IP(18)=1 -> NOT REQUESTED            NL 247
C          NL 248
C          NL 249
C          NL 250
C          NL 251
C          NL 252
C          NL 253
C INPUT *** CARDS 20, ..., 32                NL 254
C          NL 255
C          CRMIN(1), CRMAX(1) -> MINIMUM & MAXIMUM CONSTRAINTS FOR P0 NL 256
C          CRMIN(2), CRMAX(2) -> MINIMUM & MAXIMUM CONSTRAINTS FOR P1 NL 257
C          CRMIN(3), CRMAX(3) -> MINIMUM & MAXIMUM CONSTRAINTS FOR P2 NL 258
C          CRMIN(4), CRMAX(4) -> MINIMUM & MAXIMUM CONSTRAINTS FOR P3 NL 259
C          CRMIN(5), CRMAX(5) -> MINIMUM & MAXIMUM CONSTRAINTS FOR P4 NL 260
C          CRMIN(6), CRMAX(6) -> MINIMUM & MAXIMUM CONSTRAINTS FOR C00 NL 261
C          CRMIN(7), CRMAX(7) -> MINIMUM & MAXIMUM CONSTRAINTS FOR C01 NL 262
C          CRMIN(8), CRMAX(8) -> MINIMUM & MAXIMUM CONSTRAINTS FOR C02 NL 263
C          CRMIN(9), CRMAX(9) -> MINIMUM & MAXIMUM CONSTRAINTS FOR C03 NL 264
C          CRMIN(10), CRMAX(10) -> MINIMUM & MAXIMUM CONSTRAINTS FOR C04 NL 265
C          CRMIN(11), CRMAX(11) -> MINIMUM & MAXIMUM CONSTRAINTS FOR CLA0 NL 266
C          CRMIN(12), CRMAX(12) -> MINIMUM & MAXIMUM CONSTRAINTS FOR CLA1 NL 267
C          CRMIN(13), CRMAX(13) -> MINIMUM & MAXIMUM CONSTRAINTS FOR CLA2 NL 268
C          NL 269
C          NL 270
C          NL 271
C INPUT *** CARD 33                          NL 272
C          TITLE -> TITLE CARD FOR MANEUVER (PUNCHED CARD FROM 'PDR1') NL 273
C          NL 274
C          NL 275
C          NL 276
C          NL 277
C INPUT *** CARD 34 (PUNCHED CARD FROM 'PDR1') NL 278
C          NL 279
C          K -> NUMBER OF POINTS IN DATA SET NL 280
C          NL 281
C          S -> AIRCRAFT'S WING AREA IN SQUARE FEET NL 282
C          NL 283
C          RHO -> SEA-LEVEL ATMOSPHERIC DENSITY IN SLUG/FT**3 NL 284
C          NL 285
C          G -> ACCELERATION DUE TO GRAVITY IN FT/SEC**2 NL 286
C          NL 287
C          TT -> TOTAL ELAPSED TIME FOR MANEUVER IN SECONDS NL 288
C          NL 289
C          NL 290
C          NL 291
C INPUT *** CARDS 35, ..., (34+5K) (PUNCHED CARDS FROM 'PDR1') NL 292
C          NL 293
C          IDENTIFICATION OF NECESSARY INPUT TIME HISTORIES NL 294
C          NL 295
C          TIME(I) -> TIME NL 296
C          P1(I) -> WEIGHT NL 297

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C          F2(I) -> PITCH ANGLE NL 298
C          F3(I) -> PITCH RATE NL 299
C          F4(I) -> AIRSPEED NL 300
C          F5(I) -> DENSITY NL 301
C          F6(I) -> ANGLE OF ATTACK NL 302
C          F7(I) -> STATIC TEMPERATURE NL 303
C          F8(I) -> ACCELERATION NL 304
C          F9(I) -> ANGLE-OF-ATTACK RATE NL 305
C          F10(I) -> ALTITUDE NL 306
C          F11(I) -> ALTITUDE RATE NL 307
C          F12(I) -> ALTITUDE ACCELERATION NL 308
C          F13(I) -> VERTICAL ACCELERATION NL 309
C          F14(I) -> ELEVATOR (OR STABILATOR) DEFLECTION NL 310
C          NL 311
C          NL 312
C          NL 313
C          IMPLICIT REAL*8(A-H,O-Z) NL 314
C          EXTERNAL VL,DDV,DDDV,ALP,DVA,PHIDER NL 315
C          DIMENSION TITLE(20),IMODEL(18),FIT(2),ALPHA(450),THETA(450),DUN(45 NL 316
C          10),AL(4),WRK(1367),IP(18),TRG(21),NHPI(5),INPATH(5) NL 317
C          COMMON TIME(450),F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F NL 318
C          17(450),F8(450),F9(450),F10(450),F11(450),F12(450),F13(450),F14(450) NL 319
C          1),C(450,11),X(450,1),WKAR(250),CPR(14),SGN(4),SGD(4),PT1(450),PT2( NL 320
C          1450),PMRA(450),CL(450),CD(450),X1(450),X2(450),EX1,EX2,EX3,EX4,G,S NL 321
C          1,RHO,TIA,EXPI,FLOW,PHIGH,CDLOW,CDHIGH,JREAD,JWRITE,JPUNCH,IX1,IX NL 322
C          12,IEK3,IEK4,METRIC,L1,L2,IEQNR(18),IERR NL 323
C          COMMON /LAB2/ICPT,ICD,MTH,MCLCC NL 324
C          COMMON /LAB8/ALPHA1,P1,PAC(8),Z1,Z2 NL 325
C          COMMON /LAB9/ADF(450) NL 326
C          COMMON /LAB1/AP(13),UGT(13),CRMIN(13),CRMAX(13) NL 327
C          INTEGER NLLS(6)/2,3,3,4,2,3/,NLSO(6)/2,2,4,4,3,3/ NL 328
C          DATA TRG/0.000,5.000,10.000,15.000,20.000,25.000,30.000,35.000,40. NL 329
C          1000,45.000,50.000,55.000,60.000,65.000,70.000,75.000,80.000,85.000 NL 330
C          1,90.000,95.000,100.000/,INPATH/6,5,5,5,8/,IEND/4HEND / NL 331
C          NL 332
C          C*** SPECIFIC CARRIAGE CONTROL FOR INSTALLATION NL 333
C          JREAD=1 NL 334
C          JWRITE=3 NL 335
C          JPUNCH=2 NL 336
C          JFLOT=0 NL 337
C          NL 338
C          NL 339
C          1 READ (JREAD,2) (TITLE(I),I=1,20) NL 340
C          2 FORHAT (20A4) NL 341
C          NL 342
C          C*** CHECK FOR PROGRAM TERMINATION NL 343
C          IF (TITLE(1).EQ.XEND) GO TO 200 NL 344
C          C*** INITIALIZE CODES NL 345
C          LPRG=1 NL 346
C          ISPT=0 NL 347
C          LPSS=0 NL 348
C          IERR=0 NL 349
C          IUP=0 NL 350
C          ISW=0 NL 351
C          IEN=0 NL 352
C          IPATH=0 NL 353
C          PITOK=1.0D-13 NL 354
C          LPRGM=1 NL 355
C          ITRN=0 NL 356
C          NL 357

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C
C
C   READ (JREAD,3) IDS,INPUT,IPLOT,IPUNCH,METRIC,ETH,MCCLC,MAXMPI
3   FORMAT (8I5)
C
C*** CHECK FOR ERROR IN IDS
C   IF (IDS.LE.3) IDS=JREAD
C
C
C   READ (JREAD,4) EX1,EX2,EX3,EX4,IEK1,IEK2,IEK3,IEK4
4   FORMAT (4F10.0,4I5)
C
C
C   READ (JREAD,5) (INODEL(I),I=1,18)
5   FORMAT (18I1)
C
C
C   READ (JREAD,6) PLOW,PHIGH,CDLOW,CDHIGH,TIA,TARE,HTARE
6   FORMAT (5F10.0,2D15.0)
C
C
C   READ (JREAD,7) (AP(I),MGT(I),I=1,13)
7   FORMAT (2D20.0)
C
C
C   READ (JREAD,8) (IP(I),I=1,18)
8   FORMAT (18I1)
C
C
C   READ (JREAD,9) (CRMIN(I),CRMAX(I),I=1,13)
9   FORMAT (2D20.0)
C
C
C   READ (IDS,10) (TITLE(I),I=1,20)
10  FORMAT (20A4)
C
C
C   READ (IDS,11) E,S,RHO,G,TT
11  FORMAT (I10,4D15.8)
C
C   DO 14 I=1,K
C
C   READ (IDS,12) TIME(I),P1(I),P2(I),P3(I),P4(I),P5(I),P6(I),P7(I),P8
12  FORMAT (3D25.16)
C
C
C
C
C*** TEST FOR INCREASING TIME
C   IF (I.EQ.1) GO TO 14
C   IF (TIME(I).GT.TIME(I-1)) GO TO 14
C   WRITE (JWRITE,13) I
13  FORMAT (1X,/,10X,'PROGRAM FOUND TIME VALUE = OR < TIME OF PREVIOUS
14  GO TO 1
14  CONTINUE
C*** THESE TWO COMMENT CARDS ARE SUPPLIED SOLELY FOR THE USER TO USE
C*** AT HIS CONVENIENCE

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NL 358
NL 359
NL 360
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NL 417

C*** CHECK FOR ETH OR MAXMPI ERRORS
IF (ETH.LT.0.OR.ETH.GT.5) ETH=0
MAXMPI=IAPS(MAXMPI)
IF (MAXMPI.GT.5) MAXMPI=5
C*** DETERMINE MODEL NUMBERS
IKN=0
DO 15 IL=1,18
IF (INODEL(IL).EQ.0) GO TO 15
IKN=IKN+1
IEQNM(IKN)=IL
15 CONTINUE
C*** CHECK FOR MODEL ERROR
IF (IKN.EQ.0) WRITE (JWRITE,16)
16  FORMAT (1X,/,10X,'ERROR DETECTED IN MODEL CODE. TO NEXT DATA SET
1, IF ANY.')
IF (IKN.EQ.0) GO TO 1
L1=1
L2=IKN
C*** PRINT TITLE
WRITE (JWRITE,17) (TITLE(I),I=1,20)
17  FORMAT (18I,/,21X,84(' '),23X,84(' '),23X,84(' '),20A4,2X,
18  FORMAT (1X,/,18X,95(' '),19X,'INPUT PARAMETERS:',27X,IDS
C*** WRITE INPUT PARAMETERS
WRITE (JWRITE,18) IDS,EX1,PLOW,TIA,INPUT,EX2,PHIGH,TARE,IPLOT,EX3,
1CDLOW,HTARE,IPUNCH,EX4,CDHIGH,G,METRIC,E,S,RHO,TT,ETH,IEK1,IEK2,IE
1K3,IEK4,(INODEL(I),I=1,18), (IP(I),I=1,18)
18  FORMAT (1X,/,18X,95(' '),19X,'INPUT PARAMETERS:',27X,IDS
1=,12,2X,EX1=,F10.7,2X,PLOW=,D16.9,2X,TIA=,D16.9,2X,INPUT=
1T=,12,2X,EX2=,F10.7,2X,PHIGH=,D15.8,2X,TARE=,D15.8,2X,IPLOT=,1
1X,IPUNCH=,11,2X,EX3=,F10.7,2X,CDLOW=,D15.8,2X,HTARE=,D14.7,2X,
127X,METRIC=,11,2X,E=,F10.7,2X,CDHIGH=,D14.7,2X,G=,F10.7,2X,
1,P9.6,2X,RHO=,12,2X,IEK1=,13,2X,IEK2=,13,2X,IEK3=,13,
12X,IEK4=,13,2X,INODEL(1)=,12,2X,INODEL(2)=,12,2X,INODEL(
13)=,12,2X,INODEL(4)=,12,2X,INODEL(5)=,12,2X,INODEL(6)=,12,
1,27X,INODEL(7)=,12,2X,INODEL(8)=,12,2X,INODEL(9)=,12,2X,INO
1DEL(10)=,11,2X,INODEL(11)=,11,2X,INODEL(12)=,11,2X,INODEL(16)=
1,11,2X,INODEL(17)=,11,2X,INODEL(18)=,11,2X,INODEL(16)=
1IP(2)=,12,2X,IP(3)=,12,2X,IP(4)=,12,2X,IP(5)=,12,2X,IP(
16)=,12,2X,IP(7)=,12,2X,IP(8)=,12,2X,IP(9)=,12,2X,IP(10)=,
11,2X,IP(11)=,11,2X,IP(12)=,11,2X,IP(13)=,11,2X,IP(14)=,
1,11,2X,IP(15)=,11,2X,IP(16)=,11,2X,IP(17)=,11,2X,IP(18)=,1
11)
WRITE (JWRITE,19) (I,AP(I),I,MGT(I),I,CRMIN(I),I,CRMAX(I),I=1,13)
19  FORMAT (19X,AP(' ',I2,')=,1PD14.7,2X,MGT(' ',I2,')=,1PD11.4,2X,CR
1MIN(' ',I2,')=,1PD13.6,2X,CRMAX(' ',I2,')=,1PD13.6)
WRITE (JWRITE,20)
20  FORMAT (1X,/,18X,95(' '),
IF (METRIC.NE.0) GO TO 22
WRITE (JWRITE,21) S,RHO,G,TT
21  FORMAT (1X,/,38X,51(' '),38X,84(' '),38X,84(' '),13H MING ARE
1A =,F10.5,6H FT**2,20X,84(' '),38X,84(' '),21H REFERENCE DENSITY =,F10
1.8,11H SLUG/FT**3,7X,84(' '),38X,84(' '),31H ACCELERATION DUE TO GRAVITY
1 =,F7.4,10H FT/SEC**2,1X,84(' '),38X,84(' '),19H TOTAL TEST TIME =,F10
1.4,8H SECONDS,12X,84(' '),38X,84(' '),38X,51(' '),
GO TO 24
22  SIN=S*0.3048D0**2
RHO=RHO*0.515,38D0
G=G*0.3048D0

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WRITE (JWRITE,23) SYN,ENOR,GMM,TT NL 478
23 FORMAT (1X,/,38X,51(' '),/38X,/,49X,/,38X,/,13H WING ARE NL 479
1A = ,P11.5,5H M**2,20X,/,38X,/,21H REFERENCE DENSITY = ,P12. NL 480
10,8H KG/M**3,8X,/,38X,/,31H ACCELERATION DUE TO GRAVITY = ,P NL 481
10,4,9H M/SEC**2,1X,/,38X,/,19H TOTAL TEST TIME = ,P10.4,8H S NL 482
1ECCNDS,12X,/,38X,/,49X,/,38X,51(' ')) NL 483
C*** CHECK FOR INITIAL INPUT AND MODIFIED INPUT PRINTOUT NL 484
24 IF (IMPUT.NE.0) GO TO 47 NL 485
25 IF (METRIC.NE.0) GO TO 28 NL 486
IF (ISW.NE.0) WRITE (JWRITE,26) LPRG NL 487
IF (ISW.NE.0) WRITE (JWRITE,27) LPRG NL 488
26 FORMAT (1X,/,31X,68(' '),/31X,/,66X,/,31X,/,12X,INITIAL NL 489
1 INPUT DATA (FOR PROGRAM LOOP*,12,*) ,14X,/,31X,/,66X,/, NL 490
1,31X,68(' '),/6X,121(' '),/6X,/,19X,/,1,19X,/,1,19X,/,1 NL 491
1,19X,/,1,19X,/,6X,/,4X,10HDATA POINT,5X,/,1,7X,4HTIME,8X,/,1 NL 492
1,6X,6HWEIGHT,7X,/,1,3X,11HPITCH ANGLE,5X,/,1,4X,10HPITCH RATE,5X, NL 493
1,1,5X,8HAIRSPEED,6X,/,6X,/,19X,/,1,6X,6H(SECS),7X,/,1,7X,5H NL 494
1(LBP),7X,/,1,4X,9H(RADIANS),6X,/,1,3X,12H(RADIAM/SEC),4X,/,1,5X,8H NL 495
1(PT/SEC),6X,/,6X,/,19X,/,1,19X,/,1,19X,/,1,19X,/,1,1 NL 496
19X,/,6X,/,119(' '),/31X,/,66X,/,31X,/,14X,MODIFIED NL 497
27 FORMAT (1X,/,31X,68(' '),/31X,/,66X,/,31X,/,14X,MODIFIED NL 498
10 DATA (FOR PROGRAM LOOP*,12,*) ,17X,/,31X,/,66X,/,31X,/, NL 499
168(' '),/6X,121(' '),/6X,/,19X,/,1,19X,/,1,19X,/,1,19X,/,1 NL 500
1,1,19X,/,6X,/,4X,10HDATA POINT,5X,/,1,7X,4HTIME,8X,/,1,6X, NL 501
1,1,19X,/,6X,/,4X,10HDATA POINT,5X,/,1,4X,10HPITCH RATE,5X,/,1,5 NL 502
16HWEIGHT,7X,/,1,3X,11HPITCH ANGLE,5X,/,1,4X,10HPITCH RATE,5X, NL 503
1X,8HAIRSPEED,6X,/,6X,/,19X,/,1,6X,6H(SECS),7X,/,1,7X,5H(LBP) NL 504
1,7X,/,1,4X,9H(RADIANS),6X,/,1,3X,12H(RADIAM/SEC),4X,/,1,5X,8H(PT/ NL 505
1SEC),6X,/,6X,/,19X,/,1,19X,/,1,19X,/,1,19X,/,1,19X,/,1 NL 506
1,/,6X,/,119(' '),/31X,/,66X,/,31X,/,14X,MODIFIED NL 507
GO TO 31 NL 508
28 IF (ISW.EQ.0) WRITE (JWRITE,29) LPRG NL 509
IF (ISW.NE.0) WRITE (JWRITE,30) LPRG NL 510
29 FORMAT (1X,/,31X,68(' '),/31X,/,66X,/,31X,/,12X,INITIAL NL 511
1 INPUT DATA (FOR PROGRAM LOOP*,12,*) ,14X,/,31X,/,66X,/, NL 512
1,31X,68(' '),/6X,121(' '),/6X,/,19X,/,1,19X,/,1,19X,/,1,19X,/,1 NL 513
1,19X,/,1,19X,/,6X,/,4X,10HDATA POINT,5X,/,1,7X,4HTIME,8X,/,1 NL 514
1,6X,6HWEIGHT,7X,/,1,3X,11HPITCH ANGLE,5X,/,1,4X,10HPITCH RATE,5X, NL 515
1,1,5X,8HAIRSPEED,6X,/,6X,/,19X,/,1,6X,6H(SECS),7X,/,1,5X,9H NL 516
1(MEWT),5X,/,1,4X,9H(RADIANS),6X,/,1,3X,12H(RADIAM/SEC),4X,/,1,19X,/,1 NL 517
1X,7H(M/SEC),6X,/,6X,/,19X,/,1,19X,/,1,19X,/,1,19X,/,1,19X,/,1 NL 518
1,19X,/,6X,/,119(' '),/31X,/,66X,/,31X,/,14X,MODIFIED NL 519
30 FORMAT (1X,/,31X,68(' '),/31X,/,66X,/,31X,/,14X,MODIFIED NL 520
10 DATA (FOR PROGRAM LOOP*,12,*) ,17X,/,31X,/,66X,/,31X,/, NL 521
168(' '),/6X,121(' '),/6X,/,19X,/,1,19X,/,1,19X,/,1,19X,/,1 NL 522
1,1,19X,/,6X,/,4X,10HDATA POINT,5X,/,1,7X,4HTIME,8X,/,1,6X, NL 523
16HWEIGHT,7X,/,1,3X,11HPITCH ANGLE,5X,/,1,4X,10HPITCH RATE,5X,/,1,5 NL 524
1X,8HAIRSPEED,6X,/,6X,/,19X,/,1,6X,6H(SECS),7X,/,1,5X,9H(MEWT) NL 525
1(ONS),5X,/,1,4X,9H(RADIANS),6X,/,1,3X,12H(RADIAM/SEC),4X,/,1,6X,7H( NL 526
1M/SEC),6X,/,6X,/,19X,/,1,19X,/,1,19X,/,1,19X,/,1,19X,/,1 NL 527
1,/,6X,/,119(' '),/31X,/,66X,/,31X,/,14X,MODIFIED NL 528
31 IF (METRIC.NE.0) GO TO 41 NL 529
C*** WRITE INPUT IN ENGLISH UNITS NL 530
DO 32 I=1,K NL 531
32 WRITE (JWRITE,33) I,TIME(I),P1(I),P2(I),P3(I),P4(I) NL 532
33 FORMAT (6X,/,7X,13,9X,/,1,6X,F7.3,6X,/,1,4X,F10.4,5X,/,1,3X,F11. NL 533
17,5X,/,1,4X,F10.7,5X,/,1,5X,F8.4,6X,/) NL 534
WRITE (JWRITE,34) NL 535
34 FORMAT (6X,/,119X,/,6X,121(' '),/6X,/,19X,/,1,19X,/,1,19X,/,1 NL 536
1,1,19X,/,1,19X,/,6X,/,19X,/,6X,/,4X,10HDATA POINT,5X,/,1,7X,4 NL 537
1HTIME,8X,/,1,5X,7HDENSITY,7X,/,1,2X,15HANGLE OF ATTACK,2X,/,1,4X,1

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11TEMPERATURE,4X,/,1,3X,12MACCELERATION,4X,/,6X,/,19X,/,1,6X NL 538
1,6H(SECS),7X,/,1,3X,12H(SLOG/PT**3),4X,/,1,4X,9H(RADIANS),6X,/,1,6 NL 539
1X,7H( DEG-R),6X,/,1,4X,11H(PT/SEC**2),4X,/,5X,/,1,19X,/,1,19X,/,1 NL 540
1,19X,/,1,19X,/,1,19X,/,1,19X,/,6X,/,119(' '),/ NL 541
DO 35 I=1,K NL 542
35 WRITE (JWRITE,36) I,TIME(I),P5(I),P6(I),P7(I),P8(I) NL 543
36 FORMAT (6X,/,7X,13,9X,/,1,6X,F7.3,6X,/,1,4X,F10.8,5X,/,1,4X,F11. NL 544
17,4X,/,1,7X,F6.2,6X,/,1,4X,F9.5,6X,/) NL 545
WRITE (JWRITE,37) NL 546
37 FORMAT (6X,/,119X,/,6X,121(' '),/6X,121(' '),/ NL 547
WRITE (JWRITE,38) NL 548
38 FORMAT (6X,/,12X,/,1,10X,/,1,22X,/,1,10X,/,1,15X,/,1,13X,/,1,14X NL 549
1,/,1,16X,/,6X,/,1X,10HDATA POINT,1X,/,1,3X,4HTIME,3X,/,1,1X, NL 550
120HANGLE-OF-ATTACK RATE,1X,/,1,1X,8HALTITUDE,1X,/,1,1X,13HALTITUDE NL 551
1 RATE,1X,/,1,1X,11HALT. ACCEL,1X,/,1,1X,12HVERT. ACCEL,1X,/,1,1X NL 552
1,14HELEV. DEPLECT,1X,/,6X,/,12X,/,1,2X,6H(SECS),2X,/,1,5X,1 NL 553
12H(RADIAM/SEC),5X,/,1,3X,4H(PT/SEC),4X,8H(PT/SEC),3X,/,1,1X,11H NL 554
1(PT/SEC**2),1X,/,1,2X,11H(PT/SEC**2),1X,/,1,3X,9H(RADIANS),4X,/,1 NL 555
1,6X,/,12X,/,1,10X,/,1,22X,/,1,10X,/,1,15X,/,1,13X,/,1,14X,/,1 NL 556
16X,/,6X,/,119(' '),/ NL 557
WRITE (JWRITE,39) (I,TIME(I),P9(I),P10(I),P11(I),P12(I),P13(I),P14 NL 558
(I),I=1,K) NL 559
39 FORMAT (6X,/,4X,14,4X,/,1,2X,F6.2,2X,/,1,5X,F12.9,5X,/,1,1X,F8.2 NL 560
1,1X,/,1,4X,F7.2,4X,/,1,2X,F6.2,3X,/,1,4X,F6.2,4X,/,1,4X,F6.5,4X,/, NL 561
1) NL 562
WRITE (JWRITE,40) NL 563
40 FORMAT (6X,/,12X,/,1,10X,/,1,22X,/,1,10X,/,1,15X,/,1,13X,/,1,14X NL 564
1,/,1,16X,/,6X,121(' '),/ NL 565
IF (IPATH.NE.0) GO TO 174 NL 566
IF (ISW.NE.0) GO TO 150 NL 567
GO TO 47 NL 568
C*** WRITE INPUT IN SI UNITS NL 569
41 DO 42 I=1,K NL 570
NS=P1(I)*4.448200 NL 571
VS=P4(I)*0.304800 NL 572
42 WRITE (JWRITE,33) I,TIME(I),NS,P2(I),P3(I),VS NL 573
WRITE (JWRITE,43) NL 574
43 FORMAT (6X,/,119X,/,6X,121(' '),/6X,/,19X,/,1,19X,/,1,19X,/,1,19X,/,1 NL 575
1,1,19X,/,1,19X,/,6X,/,4X,10HDATA POINT,5X,/,1,7X,4 NL 576
1HTIME,8X,/,1,5X,7HDENSITY,7X,/,1,2X,15HANGLE OF ATTACK,2X,/,1,4X,1 NL 577
11TEMPERATURE,4X,/,1,3X,12MACCELERATION,4X,/,6X,/,19X,/,1,6X NL 578
1,6H(SECS),7X,/,1,4X,9H(KG/M**3),6X,/,1,4X,9H(RADIANS),6X,/,1,6X,7H NL 579
1( DEG-R),6X,/,1,4X,10H(M/SEC**2),5X,/,6X,/,19X,/,1,19X,/,1,19 NL 580
1X,/,1,19X,/,1,19X,/,1,19X,/,6X,/,119(' '),/ NL 581
DO 44 I=1,K NL 582
DS=P5(I)*515.3800 NL 583
AS=P8(I)*0.304800 NL 584
TK=5.000/9.000*(P7(I)-491.7200)+273.1800 NL 585
44 WRITE (JWRITE,36) I,TIME(I),DS,P6(I),TK,AS NL 586
WRITE (JWRITE,37) NL 587
WRITE (JWRITE,45) NL 588
45 FORMAT (6X,/,12X,/,1,10X,/,1,22X,/,1,10X,/,1,15X,/,1,13X,/,1,14X NL 589
1,/,1,16X,/,6X,/,1X,10HDATA POINT,1X,/,1,3X,4HTIME,3X,/,1,1X, NL 590
120HANGLE-OF-ATTACK RATE,1X,/,1,1X,8HALTITUDE,1X,/,1,1X,13HALTITUDE NL 591
1 RATE,1X,/,1,1X,11HALT. ACCEL,1X,/,1,1X,12HVERT. ACCEL,1X,/,1,1X NL 592
1,14HELEV. DEPLECT,1X,/,6X,/,12X,/,1,2X,6H(SECS),2X,/,1,5X,1 NL 593
12H(RADIAM/SEC),5X,/,1,1X,8H(METERS),1X,/,1,4X,7H(M/SEC),4X,/,1,2X, NL 594
110H(M/SEC**2),1X,/,1,2X,10H(M/SEC**2),2X,/,1,3X,9H(RADIANS),4X,/,1 NL 595
1,/,6X,/,12X,/,1,10X,/,1,22X,/,1,10X,/,1,15X,/,1,13X,/,1,14X,/,1 NL 596
116X,/,6X,/,119(' '),/ NL 597

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DO 46 I=1,K
  NS=F10(I)*0.3048DD
  HDS=F11(I)*0.3048DD
  HDS=F12(I)*0.3048DD
  AZS=F13(I)*0.3048DD
46 WRITE (JWRITE,39) I,TIME(I),F9(I),NS,HDS,HDS,AZS,F10(I)
  WRITE (JWRITE,40)
C*** CHECK FOR PROGRAM DIRECTION
  IF (IPATH.NE.0) GO TO 174
  IF (ISU.NE.0) GO TO 150
C*** CALL MODEL EXTRACTION
47 CALL MODEL(K,LPRG,FIT,MNB)
  IF (IERR.NE.0) GO TO 1
C*** CHECK FIT ERROR
  IF (LPRG.EQ.1.AND.FIT(LPRG).EQ.1.0D+60) GO TO 1
  IJKL=1
  IF (LPRG.GT.1) IJKL=2
C*** STORE BEST MODEL COEFFICIENTS
  CALL FITERR(FIT,IJKL,CFM)
  IF (LPRG.NE.1) GO TO 49
C*** DETERMINE MAXIMUM PITCH ANGLE AND ANGLE OF ATTACK
  ANAX=F6(1)
  THAX=F2(1)
  DO 48 I=1,K
    ALPHA(I)=F6(I)
    THETA(I)=F2(I)
    IF (DABS(F6(I)).GT.DABS(ANAX)) ANAX=F6(I)
48 IF (DABS(F2(I)).GT.DABS(THAX)) THAX=F2(I)
C*** CHECK FIT ERROR
49 IF (FIT(LPRG).LT.FITOK) GO TO 50
C*** CALCULATE BIAS IN ANGLE OF ATTACK
  CALL ABIAS(K,LPRG,FIT,MNB)
  IF (IERR.NE.0) GO TO 1
C*** UPDATE RATES FOR COMPATIBILITY
50 IF (IUP.EQ.0) GO TO 51
  CALL FMI(K,F2,TIME,F3,DUR,1,15,3,0)
  CALL FMI(K,F6,TIME,F9,DUR,1,15,3,0)
C*** CALCULATE POWER, DRAG COEFFICIENT AND LIFT COEFFICIENT
51 SD2=5/2.0D0
  CALL CHNGE(SGN)
  DO 52 I=1,K
    PWRA(I)=CFM(1)*CFM(2)*F4(I)**EX1*CFM(3)*F4(I)**EX2*CFM(4)*F4(I)**EX
    IEX=CFM(5)*F4(I)**EX4
    AN=F6(I)
    IF (F6(I).LT.0.0D0) CALL SIGNS(SGN,IEX1,IEX2,IEX3,IEX4)
    CD(I)=CFM(6)*CFM(7)*SGM(1)*AN**IEX1*CFM(8)*SGM(2)*AN**IEX2*CFM(9)*
    1SGM(3)*AN**IEX3*CFM(10)*SGM(4)*AN**IEX4
    CL(I)=F1(I)/(SD2*F5(I)*F4(I)**2)*(DCOS(F2(I)-F6(I))*F4(I)*(F3(I)-F
    19(I))/G-DSIN(F6(I)+TIA)*PWRA(I)/(F4(I)*F1(I)))
    IF (F6(I).LT.0.0D0) CALL CHNGE(SGN)
    IF (FIT(LPRG).LT.FITOK.AND.IUP.EQ.0) FT1(I)=DARSIN(F11(I)/F4(I))
52 CONTINUE
C*** CHECK FIT ERROR AND BYPASS CODES
  IF (IERR.NE.0) GO TO 187
  IF (FIT(LPRG).LT.FITOK.AND.IUP.EQ.0) GO TO 70
  IF (FIT(LPRG).LT.FITOK.AND.IUP.NE.0) GO TO 178
  IF (LPSS.NE.0) GO TO 180
  LPSS=1
C*** CALCULATE FLIGHT-PATH ANGLE
  DO 53 I=1,K
    53 FT1(I)=DARSIN(F11(I)/F4(I))
C*** CALCULATE FLIGHT-PATH-ANGLE RATE OF CHANGE
  CALL FMI(K,FT1,TIME,FT2,DUR,1,15,3,0)
C*** SET UP LEAST-SQUARES COEFFICIENTS FOR 1/3 POWER TERM
  DO 54 I=1,K
    C(I,1)=DCOS(F6(I)+TIA)/(F1(I)*F4(I))*F4(I)**0.33333DD
    C(I,2)=-F5(I)*S*F4(I)**2/(2.0D0*F1(I))
    C(I,3)=C(I,2)*F6(I)
    C(I,4)=C(I,3)*F6(I)
    C(I,5)=C(I,4)*F6(I)
    C(I,6)=C(I,5)*F6(I)
54 X(I,1)=F6(I)/G+DSIN(F2(I)-F6(I))
C*** PERFORM LEAST SQUARES
  CALL LLSQAR(C,X,K,6,1,450,450,15,MKAB,IEB,JWRITE)
  IF (IERR.EQ.129) WRITE (JWRITE,55)
55 FORMAT (1X,/,10X,'ZERO MATRIX ENCOUNTERED IN LEAST SQUARES. TO M
  EXIT DATA SET, IF ANY.')
  IF (IERR.EQ.129) GO TO 1
C*** DETERMINE FIT ERROR
  TMF=0.0D0
  DO 56 I=1,K
    TMF=DCOS(F6(I)+TIA)*(X(I,1)*F4(I)**0.33333DD)/(F1(I)*F4(I))-
    1*(F5(I)*F4(I)**2/(2.0D0*F1(I)))+(X(I,2)*X(I,3)*F6(I)+X(I,4)*F6(I)*
    1X(I,5)*F6(I)*F6(I)+X(I,6)*F6(I)*F6(I)*F6(I)*F6(I)*F6(I))/G+D
    1SIN(F2(I)-F6(I))
56 TMF=TMF+TMF*TMF
C*** WRITE COEFFICIENTS AND FIT ERROR
  IF (IERR.NE.0) GO TO 58
  WRITE (JWRITE,57) (X(I,1),I=1-6),TMF
57 FORMAT (1X,/,13X,106(' '),13X,' ',104X,' ',13X,' ',18X,'IMITI
  1ALIZATION OF COEFFICIENT CONVERGENCE SCHEME BY 1/3 POWER MODEL',19
  1X,' ',13X,' ',104X,' ',13X,' ',1X,'FORM:',2X,'P = ',1PD12.5,'
  1V**1/3',73X,' ',13X,' ',104X,' ',13X,' ',8X,'CD = ',1PD12.5,'
  1 ',1PD12.5,'*A + ',1PD12.5,'*A**2 + ',1PD12.5,'*A**3 + ',1PD12.5,'
  1A**4',3X,' ',13X,' ',104X,' ',13X,' ',10X,'WHERE: V = AIRSPE
  1ED(FT/SEC)',66X,' ',13X,' ',18X,'A = ANGLE OF ATTACK(RADIAN)',59
  1X,' ',13X,' ',104X,' ',13X,' ',10X,'FIT ERROR = ',D16.9,75X,' ',13
  1X,' ',104X,' ',13X,106(' '))
  GO TO 60
58 CF1=X(1,1)*1.355818D-3
  WRITE (JWRITE,59) CF1,(X(I,1),I=2-6),TMF
59 FORMAT (1X,/,13X,106(' '),13X,' ',104X,' ',13X,' ',18X,'IMITI
  1ALIZATION OF COEFFICIENT CONVERGENCE SCHEME BY 1/3 POWER MODEL',19
  1X,' ',13X,' ',104X,' ',13X,' ',1X,'FORM:',2X,'P = ',1PD12.5,'
  1V**1/3',73X,' ',13X,' ',104X,' ',13X,' ',8X,'CD = ',1PD12.5,'
  1 ',1PD12.5,'*A + ',1PD12.5,'*A**2 + ',1PD12.5,'*A**3 + ',1PD12.5,'
  1A**4',3X,' ',13X,' ',104X,' ',13X,' ',10X,'WHERE: V = AIRSPE
  1ED(FT/SEC)',66X,' ',13X,' ',18X,'A = ANGLE OF ATTACK(RADIAN)',59
  1X,' ',13X,' ',104X,' ',13X,' ',10X,'FIT ERROR = ',D16.9,75X,' ',13
  1X,' ',104X,' ',13X,106(' '))
60 CF1=X(1,1)
C*** CHECK FOR FURTHER IMPROVEMENT
  IF (TMF.GT.(5*FIT(LPRG))) GO TO 72
C*** COMPUTE LIFT COEFFICIENT BASED ON 1/3 POWER MODEL AND EXTRACT NEW
C*** COEFFICIENTS UNTIL CONVERGENCE
  ITER=0
61 DO 62 I=1,K
    W=F1(I)
    V=F4(I)
    R=F5(I)

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C**=X(4,1)
WRITE (JWRITE,69)
69 FORMAT (77X,'.',/,77X,'.',/,75X,5('.',/,76X,'.',/,77X,'.',)
GO TO 61
70 IF (X1(LPRG).LT.PITOK) GO TO 72
DO 71 I=1,K
71 CL(I)=DUM(I)
C*** OBTAIN INITIAL ESTIMATES ON LIFT COEFFICIENTS
72 INTST=0
EFX=2.000
GO TO 86
73 INTST=1
CALL LLSQAR(C,I,K,N,1,450,450,15,NKAR,IER,JWRITE)
IF (IER.EQ.129) WRITE (JWRITE,55)
IF (IER.EQ.129) GO TO 1
C*** INITIALIZE LEAST-SQUARE-DISTANCE COEFFICIENTS
INTST=0
GO TO 104
74 INTST=1
AL(1)=CFN(11)
AL(2)=CFN(12)
AL(3)=CFN(13)
AL(4)=2.000
HCLQ=CFN(14)
C*** PRINT OUT ESTIMATES
WRITE (JWRITE,75) (AL(I),I=1,4),CFN(14)
75 FORMAT (1X,///,48X,'INITIAL ESTIMATES OF LIFT COEFFICIENTS',///,53X
1,'CLAO=',D23.16,///,53X,'CLIA =',D23.16,///,53X,'CLAX=',D23.16,///,53X,'
1PXI=',D23.16,///,53X,'CLQ =',D23.16,/)
C*** CHECK LIFT FUNCTION CODE FOR DETERMINATION OF NUMBER OF UNKNOWN
N=NLS(NTH+1)
IF (HCLCC.NE.0)N=NLSD(NTH+1)
IF (HCLCC.EQ.0) GO TO 87
C*** ADJUST CL'S, IF NECESSARY, FOR PITCH RATE DEPENDENCY
76 IF ((NTH.EQ.0.OR.NTH.EQ.2).OR.NTH.EQ.4) GO TO 78
DO 77 I=1,K
77 CL(I)=CL(I)-CFN(14)*F3(I)
C*** ORDER DATA FOR DETERMINING LIFT COEFFICIENTS
78 CALL ASCEN(K,CL,F6,X1,X2)
C*** CHECK FOR NEGATIVE OR ZERO X2'S
JJ=0
DO 79 I=1,K
IF (X2(I).GT.0.000) GO TO 80
79 JJ=JJ+1
80 KN=K-JJ
IF (KN.EQ.K) GO TO 83
C*** STORE VALUES FOR LATTER COMPUTATION
DO 81 I=1,JJ
NKAR(I)=X2(I)
81 NKAR(I+JJ)=X1(I)
C*** ADJUST REMAINING POINTS FOR LEAST-SQUARE DISTANCE
DO 82 I=1,KN
X1(I)=X1(JJ+I)
82 X2(I)=X2(JJ+I)
83 LN=0
C*** PERFORM LEAST-SQUARE-DISTANCE FIT
CALL LSD(X2,X1,KN,AL,N,NHS,LN,IER,JWRITE,NTH)
IF (LN.NE.0) GO TO 84
ICD=1
CFN(11)=AL(1)

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      CFM(12)=AL(2)
      CFM(13)=AL(3)
      EXPX=AL(4)
C*** COMPUTE INTERCEPT
      IF (JJ.EQ.0) GO TO 114
      YCEPT=MKAR(JJ+JJ)-CFM(12)*MKAR(JJ)
      GO TO 114
C*** DEFAULT TO LINEAR LEAST-SQUARES FIT
      IF ((MTH.EQ.0.OR.MTH.EQ.2).OR.MTH.EQ.4) GO TO 86
      DO 85 I=1,K
      85 CL(I)=CL(I)+CFM(14)*F3(I)
      86 N=MLLS(MTH+1)
C*** PERFORM LINEAR LEAST-SQUARES FIT
      87 MTHP1=MTH+1
      DO 94 I=1,K
      IF (F6(I).LE.0.0.AND.MTH.GE.2) GO TO 95
      C(I,1)=1.000
      GO TO (88,89,90,91,92,93),MTHP1
      88 C(I,2)=F6(I)
      GO TO 94
      89 C(I,2)=F6(I)
      C(I,3)=F3(I)
      GO TO 94
      90 C(I,2)=F6(I)
      C(I,3)=F6(I)*EXPX
      GO TO 94
      91 C(I,2)=F6(I)
      C(I,3)=F6(I)*EXPX
      C(I,4)=F3(I)
      GO TO 94
      92 C(I,2)=F6(I)*EXPX
      GO TO 94
      93 C(I,2)=F6(I)*EXPX
      C(I,3)=F3(I)
      GO TO 94
      94 X(I,1)=CL(I)
      IF (INTST.EQ.0) GO TO 73
      ICD=2
      GO TO 103
      95 EXPX=2.000
      DO 102 I=1,K
      C(I,1)=1.000
      GO TO (96,97,98,99,100,101),MTHP1
      96 C(I,2)=F6(I)
      GO TO 102
      97 C(I,2)=F6(I)
      C(I,3)=F3(I)
      GO TO 102
      98 C(I,2)=F6(I)
      C(I,3)=F6(I)*F6(I)
      GO TO 102
      99 C(I,2)=F6(I)
      C(I,3)=F6(I)*F6(I)
      C(I,4)=F3(I)
      GO TO 102
      100 C(I,2)=F6(I)*F6(I)
      GO TO 102
      101 C(I,2)=F6(I)*F6(I)
      C(I,3)=F3(I)
      GO TO 102
      102 X(I,1)=CL(I)
      IF (INTST.EQ.0) GO TO 73

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      ICD=3
      103 CALL LLSQAR(C,X,K,N,1,450,450,15,MKAR,IER,JWRITE)
      IF (IER.EQ.129) WRITE (JWRITE,55)
      IF (IER.EQ.129) GO TO 1
      104 CFM(11)=X(1,1)
      DO 105 I=12,14
      105 CFM(I)=0.000
      GO TO (106,107,108,109,110,111),MTHP1
      106 CFM(12)=X(2,1)
      GO TO 112
      107 CFM(12)=X(2,1)
      CFM(14)=X(3,1)
      GO TO 112
      108 CFM(12)=X(2,1)
      CFM(13)=X(3,1)
      GO TO 112
      109 CFM(14)=X(2,1)
      CFM(13)=X(3,1)
      CFM(14)=X(4,1)
      GO TO 112
      110 CFM(13)=X(2,1)
      GO TO 112
      111 CFM(13)=X(2,1)
      CFM(14)=X(3,1)
      112 LN=0
      IF (INTST.EQ.0) GO TO 74
C*** WRITE OUT LIFT COEFFICIENTS
      WRITE (JWRITE,113)
      113 FORMAT (1X,/,48X,'LIFT COEFFICIENTS: BY LINEAR LEAST SQUARES',/)
      GO TO 116
      114 WRITE (JWRITE,115)
      115 FORMAT (1X,/,48X,'LIFT COEFFICIENTS: BY LEAST SQUARE DISTANCE',/)
      116 WRITE (JWRITE,117) CFM(11),CFM(12),CFM(13),EXPX,CFM(14)
      117 FORMAT (53X,'CLAO=',D23.16,/,53X,'CLA =',D23.16,/,53X,'CLAX=',D23.16,/,53X,'EXPX=',D23.16,/,53X,'CLQ=',D23.16,/)
C*** CHECK PROGRAM DIRECTION
      IF (IPATH.NE.0) GO TO 150
C*** CHECK FIT ERROR
      TFX=0.000
      DO 123 I=1,K
      GO TO (118,120,121),ICD
      118 IF (F6(I).GT.0.000) GO TO 119
      CLX=CFM(12)*F6(I)+YCEPT+HCLQ*F3(I)
      CL(I)=CL(I)+HCLQ*F3(I)
      GO TO 122
      119 CLX=CFM(11)+CFM(12)*F6(I)+CFM(13)*F6(I)*EXPX+HCLQ*F3(I)
      CL(I)=CL(I)+HCLQ*F3(I)
      GO TO 122
      120 CLX=CFM(11)+CFM(12)*F6(I)+CFM(13)*F6(I)*EXPX+CFM(14)*F3(I)
      GO TO 122
      121 CLX=CFM(11)+CFM(12)*F6(I)+CFM(13)*F6(I)*F6(I)+CFM(14)*F3(I)
      122 XFX=CL(I)-CLX
      123 TFX=TFX+XFX*XFX
      WRITE (JWRITE,124) TFX
      124 FORMAT (53X,'LIFT COEFFICIENT FIT ERROR= ',D23.16,/)
C*** CHECK FOR A BYPASS
      IF (FIT(LPRG).LT.FITOK) GO TO 178
      IF (TNF.GT.(5*FIT(LPRG))) GO TO 140
C*** READJUST ANGLE OF ATTACK BY NEWTON-RAPHSON ON LIFT EXPRESSION
      NCNT=0

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NL 898
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152 FORMAT (1X,////,27X,38H) ESTIMATED SPECIFIC FUEL CONSUMPTION = ,1PD2 NL 1078
10.13,21H LBF/(FT-LBF/SEC)/SEC,/) NL 1079
GO TO 155 NL 1080
153 SCSPC=CSFC*4448.200/1.355800 NL 1081
WRITE (JWRITE,154) SCSPC NL 1082
154 FORMAT (1X,////,27X,38H) ESTIMATED SPECIFIC FUEL CONSUMPTION = ,1PD2 NL 1083
10.13,9H W/KW-SEC) NL 1084
155 IF (CSFC.LE.0.000) WRITE (JWRITE,156) NL 1085
156 FORMAT (1X,/,27X,'SPECIFIC FUEL CONSUMPTION IS NEGATIVE OR ZERO. T NL 1086
TO NEXT DATA SET, IF ANY.') NL 1087
C*** TEST MAGNITUDE OF CSFC NL 1088
IF (CSFC.LE.0.000) GO TO 1 NL 1089
IF (CSFC.GT.0.40-06) CSFC=0.40-06 NL 1090
IF (CSFC.LT.0.40-07) CSFC=0.40-07 NL 1091
IF (METRIC.NE.0) GO TO 157 NL 1092
IF (CSFC.EQ.0.40-06.OR.CSFC.EQ.0.40-07) WRITE (JWRITE,152) CSFC NL 1093
GO TO 158 NL 1094
157 SCSPC=CSFC*4448.200/1.355800 NL 1095
IF (CSFC.EQ.0.40-06.OR.CSFC.EQ.0.40-07) WRITE (JWRITE,154) SCSPC NL 1096
C*** STORE PARAMETERS NL 1097
158 IF (IPATH.EQ.1) GO TO 159 NL 1098
IF (FIT(LPRG).GT.WRK(1)) GO TO 162 NL 1099
159 WRK(1)=FIT(LPRG) NL 1100
WRK(2)=CSFC NL 1101
WRK(3)=EXPK NL 1102
DO 160 I=1,14 NL 1103
WRK(I+3)=CFM(I) NL 1104
DO 161 I=1,K NL 1105
WRK(I+17)=F1(I) NL 1106
WRK(I+17+K)=F2(I) NL 1107
WRK(I+17+K+K)=F6(I) NL 1108
161 WRK(I+17+K+K)=F6(I) NL 1109
C*** CHECK FOR MAXIMUM ITERATION NL 1110
162 IF (IPATH.GE.7) GO TO 168 NL 1111
C*** ENACT PATH PERFORMANCE ROUTINE NL 1112
CALL PATH(K,CSFC,IPATH) NL 1113
IF (IERR.NE.0) GO TO 1 NL 1114
C*** CHECK FOR PITCH ANGLE MODIFICATION NL 1115
IF (IPATH.GE.2) ISPT=1 NL 1116
C*** ADJUST ANGLE OF ATTACK AND PITCH ANGLE NL 1117
PAC=0.500 NL 1118
DO 165 I=1,K NL 1119
IF (IPATH.GE.3) PAC=-0.500 NL 1120
F6(I)=F6(I)+PAC*ADF(I) NL 1121
IF (ISPT.NE.0) F2(I)=F6(I)+FT1(I) NL 1122
IF (I.EQ.1) GO TO 165 NL 1123
DW=F1(I)-F1(I-1) NL 1124
IF (DABS(DW).LT.0.0001DC) GO TO 163 NL 1125
GO TO 165 NL 1126
163 WRITE (JWRITE,164) NL 1127
164 FORMAT (1X,////,10X,'CONSECUTIVE WEIGHT POINTS FAILED TO CHANGE BY NL 1128
MINIMUM ALLOWANCE. TO NEXT DATA SET, IF ANY.') NL 1129
GO TO 1 NL 1130
165 CONTINUE NL 1131
C*** ADJUST PITCH ANGLE NL 1132
CALL GAM(K) NL 1133
C*** PERFORM MODEL EXTRACTION NL 1134
CALL MODEL(K,LPRG,FIT,RNB) NL 1135
C*** CHECK FOR APPROACHING MAXIMUM ITERATION NL 1136
IF (IPATH.LE.5) GO TO 166 NL 1137
IPATH=IPATH+1 NL 1137

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C*** UPDATE LIFT COEFFICIENTS NL 1138
166 DO 167 I=1,K NL 1139
V=FM(I) NL 1140
F1=CFM(I)+CFM(2)*V**EX1+CFM(3)*V**EX2+CFM(4)*V**EX3+CFM(5)*V**EX4 NL 1141
167 CL(I)=(2.000*F1(I)/(F5(I)*S*V*G))* (F2(I)*G*DCOS(F1(I))/V-G*PI*DS NL 1142
1X(F6(I)+TIA)/(F1(I)*V*G)) NL 1143
GO TO 168 NL 1144
C*** DEFINE BEST PARAMETERS NL 1145
168 FIT(LPRG)=WRK(1) NL 1146
CSFC=WRK(2) NL 1147
EXPK=WRK(3) NL 1148
DO 169 I=1,14 NL 1149
CFM(I)=WRK(I+3) NL 1150
DO 170 I=1,K NL 1151
F1(I)=WRK(I+17) NL 1152
F2(I)=WRK(I+17+K) NL 1153
170 F6(I)=WRK(I+17+K+K) NL 1154
C*** WRITE PARAMETERS NL 1155
IF (METRIC.NE.0) GO TO 172 NL 1156
WRITE (JWRITE,171) FIT(LPRG),CSFC NL 1157
171 FORMAT (1X,////,15X,25H'BEST' MODEL FIT ERROR = ,1PD23.16,/,15X,35H NL 1158
1'BEST' SPECIFIC FUEL CONSUMPTION = ,1PD20.13,21H LBF/(FT-LBF/SEC)/ NL 1159
1SEC) NL 1160
GO TO 141 NL 1161
172 SCSPC=CSFC*4448.200/1.355800 NL 1162
WRITE (JWRITE,173) FIT(LPRG),SCSPC NL 1163
173 FORMAT (1X,////,15X,25H'BEST' MODEL FIT ERROR = ,1PD23.16,/,15X,35H NL 1164
1'BEST' SPECIFIC FUEL CONSUMPTION = ,1PD20.13,9H W/KW-SEC) NL 1165
GO TO 141 NL 1166
C*** ENACT TRAJECTORY PREDICTION ROUTINE NL 1167
174 IF (RAIHPI.EQ.0) GO TO 177 NL 1168
C*** DO NOT ALLOW AP(I)'S TO BE EQUAL TO ZERO NL 1169
DO 175 I=1,13 NL 1170
175 IF (DABS(AP(I)).LT.1.0D-16) AP(I)=1.0D-10 NL 1171
DO 176 I=1,MAXINT NL 1172
WHPI(I)=IUPATH(I) NL 1173
C*** DETERMINE POWER AND LIFT COEFFICIENTS FROM EQUATION OF MOTION NL 1174
C*** NORMAL TO FLIGHT PATH OR ADJUST A PRIORI WEIGHTS NL 1175
CALL GDEQN(K,RNB,I) NL 1176
CALL HPATH(K,CSFC,RNB,LPRG,FIT,TARE,HTARE,WHPI(I)) NL 1177
176 CONTINUE NL 1178
C*** CALL MODEL EXTRACTION ROUTINE NL 1179
177 CALL MODEL(K,LPRG,FIT,RNB) NL 1180
C*** DETERMINE CONFIDENCE MAGNITUDES FOR ANGLE OF ATTACK AND PITCH NL 1181
C*** ANGLE NL 1182
178 XALP=0.000 NL 1183
XTHE=0.000 NL 1184
DO 179 I=1,K NL 1185
XALP=XALP+(DABS((ALPHA(I)-F6(I))/ANAXI))**2 NL 1186
XTHE=XTHE+(DABS((THETA(I)-F2(I))/THAXI))**2 NL 1187
XALP=XALP/K NL 1188
XTHE=XTHE/K NL 1189
WRITE (JWRITE,180) XALP,XTHE NL 1190
180 FORMAT (1X,////,43X,'ANGLE-OF-ATTACK CONFIDENCE = ,D20.13,/,43X,'P NL 1191
ITCH ANGLE CONFIDENCE = ,D20.13,/) NL 1192
C*** CHECK FIT ERROR FOR POSSIBLE ANALYSIS TERMINATION NL 1193
IF (FIT(LPRG).LE.PITOK) GO TO 181 NL 1194
C*** PROCEED WITH NEXT PROGRAM LOOP (LPRG+1) NL 1195
LPRG=LPRG+1 NL 1196
C*** TEST FOR SPECIFIED LOOP MAXIMUM NL 1197

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C*** CHECK FOR NEW DATA SET
199 GO TO 1
C*** TERMINATE PLOT ROUTINES AND PROGRAM
200 IF (JPLOT.NE.0) CALL PICSIZ(0.0,0.0)
STOP
END

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NL 1318
NL 1319
NL 1320
NL 1321
NL 1322
NL 1323

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SUBROUTINE PLOTIT(K,TPTX,IP)
C
C*** SUBROUTINE PLOTIT PLOTS TIME HISTORIES, CL VS ALPHA, CD VS ALPHA,
C*** CL VS CD, AND POWER VS AIRSPEED
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION KD(5),DUR(450),IP(18)
COMMON TIME(450),F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F
17(450),F8(450),F9(450),F10(450),F11(450),F12(450),F13(450),F14(450)
1),C(450,11),X(450,1),XKAR(250),CFM(14),SGM(4),SGD(4),PT1(450),PT2(
1450),PWAA(450),CL(450),CD(450),K1(450),K2(450),EX1,EX2,EX3,EX4,G,S
1,RHO,TIA,EXPX,PLOW,PHIGH,CDLOW,CDHIGH,JREAD,JWRITE,JPUNCH,TEXT,TEX
12,TEX1,TEX4,METRIC,L1,L2,IZQNM(18),IERR
COMMON /LAB2/VCEPT,ICD,ITH,NCLCC
REAL*4 XRD(2,450),KD(2,450),YRD(2,450),YD(2,450),TPTP
C
TPTP=TPTX
DO 1 I=1,K
IF (I.LE.5) KD(I)=1
1 XRD(1,I)=TIME(I)
C*** PLOT WEIGHT TIME HISTORY
IF (IP(1).NE.0) GO TO 4
DO 2 I=1,K
YRD(1,I)=F1(I)
2 IF (METRIC.NE.0) YRD(1,I)=YRD(1,I)+.4444444/100.000
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 3
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,3500.0,4500
1,0,250.0,1,'WEIGHT(LBF)',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
GO TO 4
3 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,150.0,200.0
1,5.0,1,'WEIGHT(NEWTONS)/100',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
C*** PLOT PITCH ANGLE TIME HISTORY
4 IF (IP(2).NE.0) GO TO 6
DO 5 I=1,K
YRD(1,I)=F2(I)+100.000
CALL PICSIZ(10.0,10.0)
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,-80.0,80.0,
110.0,1,'PITCH ANGLE(RADIAN) X 100',YRD,YD,1,2,1,450,K,0,0,0,KD,
11,' ')
C*** PLOT PITCH RATE TIME HISTORY
6 IF (IP(3).NE.0) GO TO 8
DO 7 I=1,K
YRD(1,I)=F3(I)+100.000
CALL PICSIZ(10.0,10.0)
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,-80.0,80.0,
110.0,1,'PITCH RATE(RAD/SEC) X 100',YRD,YD,1,2,1,450,K,0,0,0,KD,
11,' ')
C*** PLOT AIRSPEED TIME HISTORY
8 IF (IP(4).NE.0) GO TO 11

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DO 9 I=1,K
YRD(1,I)=F4(I)
9 IF (METRIC.NE.0) YRD(1,I)=YRD(1,I)+0.304800
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 10
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,80.0,300.0,
120.0,1,'AIRSPEED(FT/SEC)',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
GO TO 11
10 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,25.0,100.0,
15.0,1,'AIRSPEED(M/SEC)',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
C*** PLOT DENSITY TIME HISTORY
11 IF (IP(5).NE.0) GO TO 14
DO 12 I=1,K
YRD(1,I)=F5(I)+10000.000
12 IF (METRIC.NE.0) YRD(1,I)=F5(I)+5153.800
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 13
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,10.0,20.0,2
1,0,1,'DENSITY(SLUG/FT**3) X 10000',YRD,YD,1,2,1,450,K,0,0,0,KD,
11,' ')
GO TO 14
13 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,6.0,12.0,1,
10,1,'DENSITY(KG/M**3) X 10',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
C*** PLOT ANGLE OF ATTACK TIME HISTORY
14 IF (IP(6).NE.0) GO TO 16
DO 15 I=1,K
YRD(1,I)=F6(I)+100.000
CALL PICSIZ(10.0,10.0)
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,-5.0,40.0,5
1,0,1,'ANGLE OF ATTACK(RAD) X 100',YRD,YD,1,2,1,450,K,0,0,0,KD,1,
1,' ')
C*** PLOT TEMPERATURE TIME HISTORY
16 IF (IP(7).NE.0) GO TO 19
DO 17 I=1,K
YRD(1,I)=F7(I)
17 IF (METRIC.NE.0) YRD(1,I)=5.000/9.000*(F7(I)-491.7200)+273.1800
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 18
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,450.0,550.0
1,25.0,1,'TEMPERATURE(DEG-R)',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
GO TO 19
18 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,250.0,300.0
1,10.0,1,'TEMPERATURE(DEG-K)',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
C*** PLOT ACCELERATION TIME HISTORY
19 IF (IP(8).NE.0) GO TO 22
DO 20 I=1,K
YRD(1,I)=F8(I)
20 IF (METRIC.NE.0) YRD(1,I)=F8(I)+0.304800
CALL PICSIZ(10.0,10.0)
IF (METRIC.NE.0) GO TO 21
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,-32.0,32.0,
14.0,1,'ACCELERATION(FT/SEC**2)',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
GO TO 22
21 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,KD,5.5,-10.0,10.0,
11.0,1,'ACCELERATION(M/SEC**2)',YRD,YD,1,2,1,450,K,0,0,0,KD,1,' ')
C*** PLOT ANGLE-OF-ATTACK RATE TIME HISTORY

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22 IF (IP(9).NE.0) GO TO 24 PL 112
DO 23 I=1,K PL 113
23 YRD(1,I)=P9(I)*100.000 PL 114
CALL PICSIZ(10.0,10.0) PL 115
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-10.0,10.0, PL 116
11.0,1,'ANGLE OF ATTACK RATE(RAD/SEC) X 100',YRD,YD,1.2,1,450,K,0, PL 117
10.0,0,KD,1,' ') PL 118
C*** PLOT ALTITUDE TIME HISTORY PL 119
24 IF (IP(10).NE.0) GO TO 27 PL 120
DO 25 I=1,K PL 121
YRD(1,I)=P10(I)/1000.000 PL 122
25 IF (METRIC.NE.0) YRD(1,I)=P10(I)/100.000*0.304800 PL 123
CALL PICSIZ(10.0,10.0) PL 124
IF (METRIC.NE.0) GO TO 26 PL 125
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,4.0,16.0,1. PL 126
10.0,1,'ALTITUDE RATE(FT/SEC)',YRD,YD,1.2,1,450,K,0,0,0,KD,1,' ') PL 127
GO TO 27 PL 128
26 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,6.0,48.0,2. PL 129
10.0,1,'ALTITUDE (M)/100',YRD,YD,1.2,1,450,K,0,0,0,KD,1,' ') PL 130
C*** PLOT ALTITUDE RATE TIME HISTORY PL 131
27 IF (IP(11).NE.0) GO TO 30 PL 132
DO 28 I=1,K PL 133
YRD(1,I)=P11(I) PL 134
28 IF (METRIC.NE.0) YRD(1,I)=P11(I)*0.304800 PL 135
CALL PICSIZ(10.0,10.0) PL 136
IF (METRIC.NE.0) GO TO 29 PL 137
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-100.0,100. PL 138
10.0,1,'ALTITUDE RATE(FT/SEC)',YRD,YD,1.2,1,450,K,0,0,0,KD,1, PL 139
1' ') PL 140
GO TO 30 PL 141
29 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-34.0,34.0, PL 142
10.0,1,'ALTITUDE RATE(M/SEC)',YRD,YD,1.2,1,450,K,0,0,0,KD,1,' ') PL 143
C*** PLOT ALTITUDE ACCELERATION TIME HISTORY PL 144
30 IF (IP(12).NE.0) GO TO 33 PL 145
DO 31 I=1,K PL 146
YRD(1,I)=P12(I) PL 147
31 IF (METRIC.NE.0) YRD(1,I)=P12(I)*0.304800 PL 148
CALL PICSIZ(10.0,10.0) PL 149
IF (METRIC.NE.0) GO TO 32 PL 150
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-100.0,100. PL 151
10.0,1,'ALTITUDE ACCELERATION(FT/SEC**2)',YRD,YD,1.2,1,450,K,0, PL 152
10.0,0,KD,1,' ') PL 153
GO TO 33 PL 154
32 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-34.0,34.0, PL 155
10.0,1,'ALTITUDE ACCELERATION(M/SEC**2)',YRD,YD,1.2,1,450,K,0,0,0, PL 156
10.0,0,KD,1,' ') PL 157
C*** PLOT VERTICAL ACCELERATION TIME HISTORY PL 158
33 IF (IP(13).NE.0) GO TO 36 PL 159
DO 34 I=1,K PL 160
YRD(1,I)=P13(I) PL 161
34 IF (METRIC.NE.0) YRD(1,I)=P13(I)*0.304800 PL 162
CALL PICSIZ(10.0,10.0) PL 163
IF (METRIC.NE.0) GO TO 35 PL 164
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-32.0,32.0, PL 165
10.0,1,'VERTICAL ACCELERATION(FT/SEC**2)',YRD,YD,1.2,1,450,K,0,0,0, PL 166
10.0,0,KD,1,' ') PL 167
GO TO 36 PL 168
35 CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-10.0,10.0, PL 169
12.0,1,'VERTICAL ACCELERATION(M/SEC**2)',YRD,YD,1.2,1,450,K,0,0,0, PL 170
12.0,0,KD,1,' ') PL 171

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10.0,0,KD,1,' ') PL 172
C*** PLOT ELEVATOR DEFLECTION TIME HISTORY PL 173
36 IF (IP(14).NE.0) GO TO 38 PL 174
DO 37 I=1,K PL 175
YRD(1,I)=P14(I)*100.000 PL 176
CALL PICSIZ(10.0,10.0) PL 177
CALL GRAFF(8.0,0.0,TPTP,5.0,1,'TIME(SECS)',XRD,XD,5.5,-25.0,25.0, PL 178
15.0,1,'ELEVATOR DEFLECTION(RAD) X 100',YRD,YD,1.2,1,450,K,0,0,0, PL 179
10.0,0,KD,1,' ') PL 180
C*** PLOT LIFT COEFFICIENT VS ANGLE OF ATTACK PL 181
38 IF (IP(15).NE.0) GO TO 44 PL 182
KD(2)=0 PL 183
CALL ASCEN(K,CL,P6,X1,X2) PL 184
DO 42 I=1,K PL 185
XRD(1,I)=X2(I)*100.000 PL 186
YRD(1,I)=X1(I)*10.000 PL 187
XRD(2,I)=XRD(1,I) PL 188
GO TO (39,40,41),ICD PL 189
39 IF (P6(I).GT.0.000) GO TO 40 PL 190
DUN(I)=CFN(12)*P6(I)*CEPT*CFN(14)*P3(I) PL 191
GO TO 42 PL 192
40 DUN(I)=CFN(11)*CFN(12)*P6(I)*CFN(13)*P6(I)**EXP*CFN(14)*P3(I) PL 193
GO TO 42 PL 194
41 DUN(I)=CFN(11)*CFN(12)*P6(I)*CFN(13)*P6(I)**2*CFN(14)*P3(I) PL 195
42 CONTINUE PL 196
CALL ASCEN(K,DUN,P6,X1,X2) PL 197
DO 43 I=1,K PL 198
YRD(2,I)=X1(I)*10.000 PL 199
CALL PICSIZ(10.0,10.0) PL 200
CALL GRAFF(8.0,-5.0,40.0,5.0,1,'ANGLE OF ATTACK(RAD) X 100',XRD,X PL 201
10.5,0,0,20.0,2.0,1,'LIFT COEFFICIENT X 10',XRD,YD,1.2,2,450,K, PL 202
10.0,0,KD,1,' ') PL 203
C*** PLOT DRAG COEFFICIENT VS ANGLE OF ATTACK PL 204
44 IF (IP(16).NE.0) GO TO 46 PL 205
CALL ASCEN(K,CD,P6,X1,X2) PL 206
DO 45 I=1,K PL 207
XRD(1,I)=X2(I)*100.000 PL 208
YRD(1,I)=X1(I)*100.000 PL 209
CALL PICSIZ(10.0,10.0) PL 210
CALL GRAFF(8.0,-5.0,40.0,5.0,1,'ANGLE OF ATTACK(RAD) X 100',XRD,X PL 211
10.5,0,0,15.0,1.0,1,'DRAG COEFFICIENT X 100',YRD,YD,1.2,1,450,K, PL 212
10.0,0,KD,1,' ') PL 213
C*** PLOT LIFT COEFFICIENT VS DRAG COEFFICIENT PL 214
46 IF ((IP(17).NE.0.OR.IP(15).NE.0).OR.IP(16).NE.0) GO TO 49 PL 215
CALL ASCEN(K,CL,CD,X1,X2) PL 216
DO 47 I=1,K PL 217
XRD(1,I)=X2(I)*100.000 PL 218
XRD(2,I)=XRD(1,I) PL 219
47 YRD(1,I)=X1(I)*100.000 PL 220
CALL ASCEN(K,DUN,CD,X1,X2) PL 221
DO 48 I=1,K PL 222
YRD(2,I)=X1(I)*100.000 PL 223
CALL PICSIZ(10.0,10.0) PL 224
CALL GRAFF(8.0,0.0,15.0,1.0,1,'DRAG COEFFICIENT (CD) X 100',XRD,X PL 225
10.5,0,0,200.0,20.0,1,'LIFT COEFFICIENT (CL) X 100',YRD,YD,1.2,2 PL 226
10.5,0,K,0,0,0,KD,1,' ') PL 227
C*** PLOT POWER AVAILABLE VS AIRSPEED PL 228
49 IF (IP(18).NE.0) GO TO 52 PL 229
CALL ASCEN(K,PWR,P6,X1,X2) PL 230
DO 50 I=1,K PL 231

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XRD(1,1)=X2(I)
YRD(1,1)=X1(I)/1000.000
IF (METRIC.EQ.0) GO TO 50
XRD(1,1)=XRD(1,1)*0.304800
YRD(1,1)=X1(I)*1.355800/1000.0
50 CONTINUE
CALL PICSI(10.0,10.0)
IF (METRIC.NE.0) GO TO 51
CALL GRAFF(8.0,80.0,300.0,20.0,1,'AIRSPEED (FT/SEC)',XRD,XD,5.5,20
1.0,220.0,20.0,1,'POWER AVAILABLE (FT-LBF/SEC)/1000',YRD,YD,1,2,1,4
150,X,0.0,0.0,XD,1,' ')
GO TO 52
51 CALL GRAFF(8.0,25.0,100.0,5.0,1,'AIRSPEED (M/SEC)',XRD,XD,5.5,30.0
1,300.0,10.0,1,'POWER AVAILABLE (KILOWATTS)',YRD,YD,1,2,1,450,X,0.0
1,0.0,XD,1,' ')
52 RETURN
END

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SUBROUTINE ARIAS(K,LPRG,FIT,MNB) AB 1

C*** SUBROUTINE ARIAS CALCULATES A CONSTANT BIAS IN ANGLE OF ATTACK AB 2

C AB 3

IMPLICIT REAL*8(A-H,O-Z) AB 4

DIMENSION FIT(2),ST(10) AB 5

COMMON TIME(450),P1(450),P2(450),P3(450),P4(450),P5(450),P6(450),P AB 6

17(450),P8(450),P9(450),P10(450),P11(450),P12(450),P13(450),P14(450) AB 7

1),C(450,11),X(450,1),WKAR(250),CFR(14),SGM(4),SGD(4),PT1(450),PT2(AB 8

1450),PWRA(450),CL(450),IX(450),X1(450),X2(450),EX1,EX2,EX3,EX4,G,S AB 9

1,RHO,TIA,EXPI,PLOW,PHIGH,CDLOW,CDHIGH,JHEAD,JWRITE,JPUNCH,IX1,IX AB 10

12,IX3,IX4,METRIC,L1,L2,IROHM(10),IERR AB 11

C AB 12

C*** INITIALIZE PARAMETERS AB 13

IF=0 AB 14

BF=0.666700 AB 15

C*** STORE PERTINENT INFORMATION AB 16

1 SM1=FIT(LPRG) AB 17

DO 2 I=1,10 AB 18

2 ST(I)=CFR(I) AB 19

C*** STEP AND CHECK COUNTER AB 20

IT=IT+1 AB 21

IF (IT.GE.2) GO TO 12 AB 22

C*** SET LOOP PARAMETERS AB 23

CALL CHNGE(SGM) AB 24

CALL CHNGE(SGD) AB 25

IX1=IX1-1 AB 26

IX2=IX2-1 AB 27

IX3=IX3-1 AB 28

IX4=IX4-1 AB 29

BB=0.000 AB 30

BBB=0.000 AB 31

C*** CALCULATE THE BIAS SUMS AB 32

DO 4 I=1,K AB 33

M=P1(I) AB 34

T=P2(I) AB 35

V=P4(I) AB 36

R=P5(I) AB 37

A=P6(I) AB 38

AM=DABS(A) AB 39

AB 40

```

IF (A.GE.0.000) GO TO 3
CALL SIGNS(SGM,IX1,IX2,IX3,IX4)
CALL SIGNS(SGD,IX1,IX2,IX3,IX4)
3 P=CFR(1)*CFR(2)+V*EX1*CFR(3)+V*EX2*CFR(4)+V*EX3*CFR(5)+V*EX4
CD=CFR(6)*CFR(7)+SGM(1)*AM*IX1*CFR(8)+SGM(2)*AM*IX2*CFR(9)+SGM
1(3)*AM*IX3*CFR(10)+SGM(4)*AM*IX4
BO=G*DSIN(A*TIA)/(M*V)*P*G*S*R*V/(2.000*M)*SGD(1)*IX1*AM*IX1*
1CFR(7)+SGD(2)*IX2*AM*IX2*CFR(8)+SGD(3)*IX3*AM*IX3*CFR(9)+SGD(4
1)*IX4*AM*IX4*CFR(10))
B1=P8(I)-G*DCOS(A*TIA)/(M*V)*P*G*S*R*V/(2.000*M)*CD*G*DSIN(T-A)
BB=BB+B1
BBB=BBB+B1
IF (A.GE.0.000) GO TO 4
CALL CHNGE(SGM)
CALL CHNGE(SGD)
4 CONTINUE
C*** CALCULATE THE BIAS
ABS=-BB/BBB
WRITE (JWRITE,5) ABS
5 FORMAT (1X,/,30X,70(' '),/,30X,/,',',68X,/,',',/,30X,/,',',3X,46NCALCULA
1TED CONSTANT BIAS IN ANGLE OF ATTACK = ,1PD16.9,3X,/,')
IF (DABS(ABS).LT.5.0D-07) GO TO 7
WRITE (JWRITE,6)
6 FORMAT (30X,/,',',68X,/,',',/,30X,70(' '),/)
GO TO 9
7 WRITE (JWRITE,8)
8 FORMAT (30X,/,',',3X,ANGLE-OF-ATTACK BIAS < 5.0D-07. BYPASSING ABA
1YSIS,/,13X,/,',',/,30X,/,',',68X,/,',',/,30X,70(' '),/)
RETURN
C*** CORRECT ANGLE OF ATTACK
9 DO 10 I=1,K
10 P6(I)=P6(I)+ABS*BF
C*** PERFORM MODEL EXTRACTION
CALL MODEL(K,LPRG,FIT,MNB)
IF (IERR.NE.0) RETURN
SM2=FIT(LPRG)
C*** CHECK FIT ERROR
IF (SM2.LT.SM1) GO TO 1
FIT(LPRG)=SM1
C*** READJUST ANGLE OF ATTACK
DO 11 I=1,K
11 P6(I)=P6(I)-ABS*BF
12 DO 13 I=1,10
13 CFR(I)=ST(I)
RETURN
END

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SUBROUTINE ALPDEL(K,LPRG,MNB,FIT) AD 1

C AD 2

C*** SUBROUTINE ALPDEL PERFORMS FREQUENCY-DEPENDENT CORRECTIONS TO THE AD 3

C*** VALUES OF ANGLE OF ATTACK AD 4

C AD 5

IMPLICIT REAL*8(A-H,O-Z) AD 6

DIMENSION FIT(2),ST(4,450),SA(4,450),FC(4,11),AL(4) AD 7

COMMON TIME(450),P1(450),P2(450),P3(450),P4(450),P5(450),P6(450),P AD 8

17(450),P8(450),P9(450),P10(450),P11(450),P12(450),P13(450),P14(450) AD 9

1),C(450,11),X(450,1),WKAR(250),CFR(14),SGM(4),SGD(4),PT1(450),PT2(AD 10

1450),PWRA(450),CL(450),CD(450),X1(450),X2(450),EX1,EX2,EX3,EX4,G,S AD 11

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1,RHO,TIA,EXPI,PLOW,PHIGH,CLOW,CDHIGH,JREAD,JWRITE,JPUCH,IEK1,IEK AD 12
12,IEK3,IEK4,METRIC,L1,L2,IEQNM(10),IERR AD 13
COMMON /LAB2/ICEPT,ICD,NTH,NCLCC AD 14
INTEGER NLLS(6)/2,3,3,4,2,3/,NLSO(6)/2,2,4,4,3,3/ AD 15
C AD 16
C*** INITIALIZE PARAMETERS AD 17
BS3=0.300 AD 18
IUP=0 AD 19
IT=0 AD 20
WRITE (JWRITE,1) AD 21
1 FORMAT (6X,120(' '),/,6X,6(' '),1X,46HBEGIN FREQUENCY CORRECTIONS AD 22
ITO ANGLE OF ATTACK,1X,6(' ')) AD 23
C*** STORE PERTINENT INFORMATION AD 24
DO 2 I=1,K AD 25
ST(I,I)=F2(I) AD 26
2 SA(I,I)=F6(I) AD 27
DO 3 I=1,10 AD 28
3 FC(I,I)=CFN(I) AD 29
FC(I,1)=FIT(LPRG) AD 30
C*** CHECK AND STEP COUNTER AD 31
4 IF (IT.GE.3) GO TO 59 AD 32
IT=IT+1 AD 33
WRITE (JWRITE,5) IT AD 34
5 FORMAT (1X,/,6X,'ITERATIONS',12,/) AD 35
IF (IT.GT.2)BS3=1.000 AD 36
C*** COMPUTE POWER AVAILABLE AND LIFT COEFFICIENT AD 37
DO 7 I=1,K AD 38
PWRA(I)=CFN(1)*CFN(2)*F4(I)**EX1*CFN(3)*F4(I)**EX2*CFN(4)*F4(I)**X AD 39
IX3*CFN(5)*F4(I)**EX4 AD 40
7 CL(I)=(2.000*F1(I)/(F5(I)*F4(I)*G*S))* (PT2(I)+G*DCOS(PT1(I)))/F4(I) AD 41
1-G*PWRA(I)*DSIN(F6(I)*TIA)/(F1(I)*F4(I)**2) AD 42
C*** CHECK LIFT FUNCTION CODE FOR DETERMINATION OF NUMBER OF UNKNOWNNS AD 43
N=NLLS(NTH+1) AD 44
IF (NCLCC.NE.0)N=NLSO(NTH+1) AD 45
IF (NCLCC.EQ.0) GO TO 20 AD 46
C*** ADJUST CL'S, IF NECESSARY, FOR PITCH RATE DEPENDENCY AD 47
IF ((NTH.EQ.0.OR.NTH.EQ.2).OR.NTH.EQ.4) GO TO 10 AD 48
DO 9 I=1,K AD 49
9 CL(I)=CL(I)-CFN(14)*F3(I) AD 50
C*** ORDER DATA FOR DETERMINING LIFT COEFFICIENTS AD 51
10 CALL ASCEN(K,CL,F6,X1,X2) AD 52
C*** CHECK FOR NEGATIVE OR ZERO X2'S AD 53
JJ=0 AD 54
DO 11 I=1,K AD 55
IF (X2(I).GT.0.000) GO TO 12 AD 56
11 JJ=JJ+1 AD 57
12 KM=K-JJ AD 58
IF (KM.EQ.K) GO TO 15 AD 59
C*** STORE VALUES FOR LATER COMPUTATION AD 60
DO 13 I=1,JJ AD 61
WKAB(I)=X2(I) AD 62
13 WKAR(I+JJ)=X1(I) AD 63
C*** ADJUST REMAINING POINTS FOR LEAST-SQUARE DISTANCE AD 64
DO 14 I=1,KM AD 65
X1(I)=X1(JJ+I) AD 66
X2(I)=X2(JJ+I) AD 67
14 X2(I)=X2(JJ+I) AD 68
C*** INITIALIZE LEAST-SQUARE-DISTANCE COEFFICIENTS AD 69
15 AL(1)=CFN(11) AD 70
AL(2)=CFN(12) AD 71
AL(3)=CFN(13) AD 71

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AL(4)=EXPI AD 72
LN=0 AD 73
C*** PERFORM LEAST-SQUARE-DISTANCE FIT AD 74
CALL LSD(X2,X1,KM,AL,N,NRS,LN,IERR,JWRITE,NTH) AD 75
IF (LN.NE.0) GO TO 17 AD 76
WRITE (JWRITE,16) AD 77
16 FORMAT (1X,/,45X,42HIFT COEFFICIENTS BY LEAST-SQUARE DISTANCE,/) AD 78
C*** DEFINE CODE AND LIFT COEFFICIENTS AD 79
ICD=1 AD 80
CFN(11)=AL(1) AD 81
CFN(12)=AL(2) AD 82
CFN(13)=AL(3) AD 83
EXPI=AL(4) AD 84
C*** COMPUTE INTERCEPT AD 85
IF (JJ.EQ.0) GO TO 47 AD 86
ICEPT=WKAR(JJ+JJ)-CFN(12)*WKAB(JJ) AD 87
GO TO 47 AD 88
C*** DEFAULT TO LINEAR LEAST-SQUARES FIT AD 89
17 IF ((NTH.EQ.0.OR.NTH.EQ.2).OR.NTH.EQ.4) GO TO 19 AD 90
DO 18 I=1,K AD 91
18 CL(I)=CL(I)*CFN(14)*F3(I) AD 92
19 N=NLLS(NTH+1) AD 93
C*** PERFORM LINEAR LEAST-SQUARES FIT AD 94
20 NTHP1=NTH+1 AD 95
DO 27 I=1,K AD 96
IF (F6(I).LE.0.0.AND.NTH.GE.2) GO TO 28 AD 97
C(I,1)=1.000 AD 98
GO TO (21,22,23,24,25,26),NTHP1 AD 99
21 C(I,2)=F6(I) AD 100
GO TO 27 AD 101
22 C(I,2)=F6(I) AD 102
C(I,3)=F3(I) AD 103
GO TO 27 AD 104
23 C(I,2)=F6(I) AD 105
C(I,3)=F6(I)**EXPI AD 106
GO TO 27 AD 107
24 C(I,2)=F6(I) AD 108
C(I,3)=F6(I)**EXPI AD 109
C(I,4)=F3(I) AD 110
GO TO 27 AD 111
25 C(I,2)=F6(I)**EXPI AD 112
GO TO 27 AD 113
26 C(I,2)=F6(I)**EXPI AD 114
C(I,3)=F3(I) AD 115
27 X(I,1)=CL(I) AD 116
ICD=2 AD 117
GO TO 36 AD 118
28 EXPK=2.000 AD 119
DO 35 I=1,K AD 120
C(I,1)=1.000 AD 121
GO TO (29,30,31,32,33,34),NTHP1 AD 122
29 C(I,2)=F6(I) AD 123
GO TO 35 AD 124
30 C(I,2)=F6(I) AD 125
C(I,3)=F3(I) AD 126
GO TO 35 AD 127
31 C(I,2)=F6(I) AD 128
C(I,3)=F6(I)*F6(I) AD 129
GO TO 35 AD 130
32 C(I,2)=F6(I) AD 131

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      C(I,3)=F6(I)*F6(I)
      C(I,4)=F3(I)
      GO TO 35
33  C(I,2)=F6(I)*F6(I)
      GO TO 35
34  C(I,2)=F6(I)*F6(I)
      C(I,3)=F3(I)
35  X(I,1)=CL(I)
      ICD=3
36  CALL LLSQAR(C,X,K,N,1,450,450,15,UNAR,IER,JWRITE)
      IF (IER.EQ.129) WRITE (JWRITE,37)
37  FORMAT (1X,/,10X,'ZERO MATRIX ENCOUNTERED. LOCATION:ALPDEL. TO
      INEXT DATA SET. IF ANY.',/)
      IF (IER.EQ.129) IERR=1
      IF (IER.EQ.0) RETURN
      CFM(1)=X(1,1)
      DO 38 I=12,14
38  CFM(I)=0.000
      GO TO (39,40,41,42,43,44),NTHP1
39  CFM(14)=X(2,1)
      GO TO 45
40  CFM(12)=X(2,1)
      CFM(14)=X(3,1)
      GO TO 45
41  CFM(12)=X(2,1)
      CFM(13)=X(3,1)
      GO TO 45
42  CFM(12)=X(2,1)
      CFM(13)=X(3,1)
      CFM(14)=X(4,1)
      GO TO 45
43  CFM(13)=X(2,1)
      GO TO 45
44  CFM(13)=X(2,1)
      CFM(14)=X(3,1)
45  WRITE (JWRITE,46)
46  FORMAT (1X,/,45X,41H LIFT COEFFICIENTS BY LINEAR LEAST SQUARES,/)
      LM=0
47  WRITE (JWRITE,48) CFM(11),CFM(12),CFM(13),EXPX,CFM(14)
48  FORMAT (52X,7HCLAO = ,D23.16,/,52X,7HCLB = ,D23.16,/,52X,7HCLC =
      ,D23.16,/,52X,7HCLD = ,D23.16,/,52X,7HCLQ = ,D23.16,/)
C*** CHECK ON UPDATE CODE
      IF (IUP.EQ.0) WRITE (JWRITE,49)
49  FORMAT (6X,6(' '),1X,46H END FREQUENCY CORRECTIONS TO ANGLE OF AT
      TACK,1X,6(' '),/,6X,12G(' '))
      IF (IUP.EQ.0) GO TO 64
C*** INITIALIZE FIT ERROR SUM
      TSX=0.000
C*** SOLVE FOR ANGLE OF ATTACK BY NEWTON-RAPHSON
      NCNT=0
      DO 54 I=1,K
      CALL NEWTON(I,A,NCNT)
      ALP=A-F6(I)
C*** COMPUTE FREQUENCY-DEPENDENT ANGLE-OF-ATTACK CORRECTIONS
      F6(I)=F6(I)+BSJ*ALP
C*** COMPUTE FIT ERROR
      GO TO (50,51,52),ICD
50  IF (F6(I).GT.0.000) GO TO 51
      CLX=CFM(12)*F6(I)+CEPT*CFM(14)*F3(I)
      GO TO 53

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51  CLX=CFM(11)*CFM(12)*F6(I)+CFM(13)*F6(I)+EXPX*CFM(14)*F3(I)
      GO TO 53
52  CLX=CFM(11)*CFM(12)*F6(I)+CFM(13)*F6(I)+F6(I)*CFM(14)*F3(I)
53  SX=(FT2(I)-G*S*F5(I)*F4(I)+CLX/(2.000*F1(I)))*G*DCOS(PT1(I))/F4(I)-
      1G*P4RA(I)*DSIN(P6(I)*TIA)/(F1(I)*F4(I)+2)
      TSX=TSX+SX*SX
54  CONTINUE
      IF (NCNT.EQ.0) WRITE (JWRITE,55) NCNT
55  FORMAT (1X,/,4X,94H*** DURING NEWTON-RAPHSON FOR ANGLE OF ATTACK
      IN NEWTON, ROUTINE WISHED TO SEEK COMPLEX ROOTS ,13,7H TIMES.)
      WRITE (JWRITE,56) TSX
56  FORMAT (1X,/,30X,52H FREQUENCY-DEPENDENT FIT ERROR FOR ANGLE OF AT
      TACK = ,D20.13,/)
C*** COMPUTE PITCH ANGLE CORRECTION DUE TO CORRECTIONS IN ANGLE OF
C*** ATTACK
      CALL GANK(K)
C*** PERFORM NOGEL EXTRACTIONS
      CALL NOGEL(K,LPRG,FIT,NB)
      IF (IERH.EQ.0) RETURN
C*** STORE UPDATED VALUES
      DO 57 I=1,10
57  FC(IT+1,1)=CFM(I)
      FC(IT+1,11)=FIT(LPRG)
      DO 58 I=1,K
      ST(IT+1,1)=F2(I)
58  SA(IT+1,1)=F6(I)
      GO TO 4
C*** TEST FIT ERROR
59  IPL=IT+1
      FIT(LPRG)=FC(1,11)
      DO 60 J=1,IPL
60  IF (FC(J,11).LT.FIT(LPRG)) FIT(LPRG)=FC(J,11)
      DO 61 J=1,IPL
61  IF (FC(J,11).EQ.FIT(LPRG)) NFIT=J
C*** REDEFINE COEFFICIENTS
      DO 62 I=1,10
62  CFM(I)=FC(NFIT,I)
C*** RESET PITCH ANGLE AND ANGLE OF ATTACK
      DO 63 I=1,K
      F2(I)=ST(NFIT,I)
      F6(I)=SA(NFIT,I)
      IUP=1
      GO TO 6
64  RETURN
      END

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      SUBROUTINE NEWTON(I,ALP,NCNT)
C
C*** SUBROUTINE NEWTON USES A MODIFIED SECOND-ORDER NEWTON-RAPHSON
C*** METHOD TO ADJUST THE VALUES OF ANGLE OF ATTACK
C
      IMPLICIT REAL*8(A-H,O-Z)
      COMMON TIME(450),F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F
      17(450),F8(450),F9(450),F10(450),F11(450),F12(450),F13(450),F14(450)
      1),C(450,11),X(450,1),UNAR(250),CFM(14),SGM(4),SGD(4),FT1(450),FT2(
      1450),P4RA(450),XX(450),YY(450),X1(450),X2(450),EX1,EX2,EX3,EX4,G,S
      1),RHO,TIA,EXPX,BLOW,PHIGH,CDLOW,CDHIGH,JREAD,JWRITE,JPUNCH,IEX1,IE
      12,IEK3,IEK4,METRIC,L1,L2,IEQW(18),IERR

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      NW 1
      NW 2
      NW 3
      NW 4
      NW 5
      NW 6
      NW 7
      NW 8
      NW 9
      NW 10
      NW 11
      NW 12

```

```

COMMON /LAB2/YCPT,ICD,MTH,NCLCC
C
C*** INITIALIZE PARAMETERS
ISZ=0
N=P1(I)
V=P4(I)
W=P5(I)
GD=PT2(I)
ND=P11(I)
P=PWRA(I)
GAB=DABSIN(HD/V)
1 A=V6(I)
C*** BEGIN ITERATION
ICK=0
2 A0=A
C*** COMPUTE LIFT COEFFICIENT AND DERIVATIVES
GO TO (3,4,5),ICD
3 IF (A.GT.0.000) GO TO 4
CL=CFM(12)*A*ICRPT
DCL=CFM(12)
DDCL=0.000
GO TO 6
4 CL=CFM(11)*CFM(12)*A*CFM(13)*A**EXPI*CFM(14)*P3(I)
DCL=CFM(12)*EXPI*CFM(13)*A**EXPI-1.000
DDCL=EXPI*(EXPI-1.000)*CFM(13)*A**EXPI-2.000
GO TO 6
5 CL=CFM(11)*CFM(12)*A*CFM(13)*A**A*CFM(14)*P3(I)
DCL=CFM(12)*2.000*CFM(13)*A
DDCL=2.000*CFM(13)
C*** FORM NEWTON-RAPHSON EQUATION
6 H=GD-(G*S*W*V*CL/(2.000*W)*G*DSIN(A*TIA)*P/(W*V*V))*G*DCOS(GAM)/V
HP=-((G*S*W*V)/(2.000*W)*DCL*G*P*DCOS(A*TIA)/(W*V*V))
X=DABS((P*H*W*V)/(DSIN(A*TIA)+1.00-6))/P
C*** CHECK FOR NEAR-ZERO SLOPE
IF (DABS(HP).LT.1.0D-15.AND.ISZ.EQ.4) GO TO 11
IF (DABS(HP).GE.1.0D-15) GO TO 7
ISZ=ISZ+1
C*** MODIFY POWER AND START ITERATION AGAIN
P=P*12
GO TO 1
7 HPP=G*P*DSIN(A*TIA)/(W*V*V)-G*S*W*V*DDCL/(2.000*W)
RAD=(HP/HPP)*(HP/HPP)-2.000*(H/HPP)
C*** ADJUST VALUES OF ANGLE OF ATTACK
IF (RAD.LT.0.000) GO TO 9
IF ((HP/HPP).LT.0.000) GO TO 8
A=A-HP/HPP*DSQRT(RAD)
GO TO 10
8 A=A-HP/HPP*DSQRT(RAD)
GO TO 10
9 A=A-HP/HPP
HCMT=HCMT+1
GO TO 11
10 ICK=ICK+1
IF (DABS(A-A0).LE.1.0D-15.OR.ICK.GE.20) GO TO 11
GO TO 2
11 ALP=A
RETURN
END

```

NM 13
 NM 14
 NM 15
 NM 16
 NM 17
 NM 18
 NM 19
 NM 20
 NM 21
 NM 22
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 NM 24
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 NM 67
 NM 68
 NM 69
 NM 70
 NM 71

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SUBROUTINE MODEL(X,LPRG,PIT,NBD)
C
C*** SUBROUTINE MODEL CALCULATES THE POWER AND DRAG COEFFICIENTS OF THE
C*** SPECIFIED MODELS FROM THE EQUATION OF MOTION TANGENT TO THE FLIGHT
C*** PATH
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION PIT(2),ST(18,1),TS(10),LOC(10,18)
COMMON TIME(N50),P1(N50),P2(N50),P3(N50),P4(N50),P5(N50),P6(N50),P
17(N50),P8(N50),P9(N50),P10(N50),P11(N50),P12(N50),P13(N50),P14(N50)
1,C(N50,11),X(N50,1),WKAR(250),CFM(14),SGM(4),SGD(4),PT1(450),PT2(
1450),PWRA(450),CL(450),IX(450),X1(450),X2(450),IX1,IX2,IX3,IX4,G,S
1,RMO,TIA,EXPI,PLOW,PHIGH,CDLOW,CDHIGH,JWRITE,JWRITE,JWRITE,JWRITE,J
12,IX13,IX14,HEMIC,L1,L2,IEQNM(18),IERN
INTEGER IEQNM(18)/3,4,5,7,4,5,7,5,6,8,5,6,8,4,5,5,6,6,6/
DATA LOC/1,6,8,0,0,0,0,0,0,0,1,2,6,8,0,0,0,0,0,1,2,6,8,10,0,0,0,0,
10,0,1,2,6,7,8,9,10,0,0,0,1,3,6,8,0,0,0,0,0,1,3,6,8,10,0,0,0,0,0,
11,3,6,7,8,9,10,0,0,0,1,2,3,6,8,0,0,0,0,0,1,2,3,6,8,10,0,0,0,0,1,2,
13,6,7,8,9,10,0,0,0,1,3,4,6,8,0,0,0,0,0,1,3,4,6,8,10,0,0,0,0,1,3,4,6,
17,8,9,10,0,0,0,1,6,7,8,0,0,0,0,0,0,1,2,6,7,8,0,0,0,0,0,1,3,6,7,8,0,0,
1,0,0,0,1,2,3,6,7,8,0,0,0,0,0,1,3,4,6,7,8,0,0,0,0,0/
C
WRITE(JWRITE,1)
1 FORMAT(1X,////,50X,29HM O D E L S O L U T I O N S,/)
WRITE(JWRITE,2)
2 FORMAT(28X,76(' '),/,28X,*,*,7X,*,*)
C*** BEGIN ANALYSIS ON SPECIFIED MODELS
DO 14 LKRM=L1,L2
C*** DETERMINE SPECIFIC MODEL AND NUMBER OF UNKNOWNNS
JCMT=IEQNM(LKRM)
NUM=IEQNM(JCMT)
NPL=0
CALL CHNGE(SGM)
DO 4 I=1,K
AM=DABS(P6(I))
C*** TEST FOR NEGATIVE ANGLES OF ATTACK
IF (P6(I).LT.0.000) CALL SIGNS(SGM,IX1,IX2,IX3,IX4)
C*** DETERMINE GENERAL TERMS FOR MATRIX FORMULATION
TS(1)=DCOS(P6(I)+TIA)/(P1(I)*P4(I))
TS(2)=TS(1)*P4(I)**EX1
TS(3)=TS(1)*P4(I)**EX2
TS(4)=TS(1)*P4(I)**EX3
TS(5)=TS(1)*P4(I)**EX4
TS(6)=TS(5)*P4(I)**2/(2.000*P1(I))
TS(7)=TS(6)*SGM(1)*AM**IX1
TS(8)=TS(6)*SGM(2)*AM**IX2
TS(9)=TS(6)*SGM(3)*AM**IX3
TS(10)=TS(6)*SGM(4)*AM**IX4
IF (P6(I).LT.0.000) CALL CHNGE(SGM)
C*** FORM COEFFICIENTS FOR LEAST SQUARES
DO 3 J=1,NUM
3 C(I,J)=TS(LOC(J,JCMT))
4 X(I,1)=P8(I)/G*DSIN(P2(I)-P6(I))
C*** ENACT LEAST SQUARES
CALL LLSQAR(C,X,K,IEQNM(JCMT),1,450,450,16,WKAR,IER,JWRITE)
C*** CHECK FOR ERROR
IF (IER.EQ.129) GO TO 5
GO TO 7

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5 WRITE (JWRITE,6) ND 59
6 FORMAT (1X,/,10X,'ZERO-MATRIX ENCOUNTERED IN MODEL. TO NEXT DATA ND 60
1 SET, IF ANY,./) ND 61
IERR=1 ND 62
RETURN ND 63
C*** STORE VALUES FOR COMPARISON ND 64
7 DO 8 J=1,10 ND 65
8 ST(JCNT,J)=X(J,1) ND 66
C*** DEFINE COEFFICIENTS IN CORRECT ORDER ND 67
DO 9 J=1,10 ND 68
9 CPH(J)=0.000 ND 69
DO 10 J=1,NUM ND 70
10 CPH(LOC(J,JCNT))=X(J,1) ND 71
C*** DETERMINE FIT ERROR ND 72
SSX=0.000 ND 73
DO 11 J=1,K ND 74
AM=DABS(P6(J)) ND 75
IF (P6(J)-LY.0.000) CALL SIGNS(SGN,IX1,IX2,IX3,IX4) ND 76
P=CPH(1)*CPH(2)*P4(J)**IX1*CPH(3)*P4(J)**IX2*CPH(4)*P4(J)**IX3*CPH ND 77
1(5)*P4(J)**IX4 ND 78
CD=CPH(6)*CPH(7)*SGN(1)*AB**IX1*CPH(8)*SGN(2)*AB**IX2*CPH(9)*SGN ND 79
1(3)*AB**IX3*CPH(10)*SGN(4)*AB**IX4 ND 80
C*** CHECK POWER AND DRAG COEFFICIENT RANGE ND 81
IF ((P.LC.PLOW.OR.P.GT.PHIGH).OR.(CD.LC.CDLOW.OR.CD.GE.CDHIGH)) NPL ND 82
1=NPL+1 ND 83
SS=DCOS(P6(J)+TIA)*P/(P1(J)*P4(J))- (P5(J)*S*P4(J)**2/(2.000*P1(J)) ND 84
1*CD*P8(J)/G*DSIN(P2(J)-P6(J)) ND 85
11 SSX=SSX+SS ND 86
C*** WRITE MODEL VALUES ND 87
IF (NPL.GT.0) SSX=1.00+60 ND 88
WRITE (JWRITE,12) JCNT,CPH(1),CPH(6),CPH(2),CPH(7),CPH(3),CPH(8),C ND 89
1PH(4),CPH(9),NPL,CPH(5),CPH(10),SSX ND 90
12 FORMAT (20X,/,1X,'MODEL ',I2,3X,'P0 = ',1PD23.16,3X,'CD0 = ',1PD ND 91
123.16,2X,/,20X,/,1X,'POINT',6X,'P2 = ',1PD23.16,3X,'CD1 = ',1PD23.16,2 ND 92
1X,/,20X,/,1X,'FAILURES',3X,'P3 = ',1PD23.16,3X,'CD2 = ',1PD23.16 ND 93
16,2X,/,20X,/,1X,'P4',6X,'P4 = ',1PD23.16,3X,'CD3 = ',1 ND 94
1PD23.16,2X,/,20X,/,1X,'I4',6X,'P4 = ',1PD23.16,3X,'CD4 = ', ND 95
1PD23.16,2X,/,20X,/,1X,'FIT ERROR= ',D23. ND 96
116,39X,/,20X,/,1X,'74X,/,20X,/,1X,'74X,/,20X,/,1X,'74X, ND 97
100 ND 98
GO TO 14 ND 99
13 P0=CPH(1)*1.355818D-3 ND 100
P1=CPH(2)*1.355818D-3 ND 101
P2=CPH(3)*1.355818D-3 ND 102
P3=CPH(4)*1.355818D-3 ND 103
P4=CPH(5)*1.355818D-3 ND 104
WRITE (JWRITE,12) JCNT,P0,CPH(6),P1,CPH(7),P2,CPH(8),P3,CPH(9),NPL ND 105
1,P4,CPH(10),SSX ND 106
14 ST(JCNT,11)=SSX ND 107
C*** DETERMINE BEST MODEL BY FIT ERROR ND 108
ICC=IEQUH(1) ND 109
FIT(LPRG)=ST(ICC,11) ND 110
DO 15 J=L1,L2 ND 111
ICC=IEQUH(J) ND 112
IF (ST(ICC,11).LT.FIT(LPRG)) FIT(LPRG)=ST(ICC,11) ND 113
DO 16 J=L1,L2 ND 114
ICC=IEQUH(J) ND 115
16 IF (ST(ICC,11).EQ.FIT(LPRG)) NNB=ICC ND 116
WRITE (JWRITE,2) ND 117
ND 118

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IF (FIT(LPRG).EQ.1.0D+60) GO TO 18 ND 119
WRITE (JWRITE,17) NNB ND 120
17 FORMAT (20X,/,1X,'MODEL ',I2,' FOUND TO BE BEST FIT',22X,/, ND 121
1/,20X,/,1X,/,20X,/,20X,76(' '),/ ND 122
GO TO 20 ND 123
18 WRITE (JWRITE,19) ND 124
19 FORMAT (20X,/,1X,'NO MODEL FOUND TO BE ADEQUATE',22X,/,20 ND 125
1X,/,1X,74X,/,20X,76(' '),/ ND 126
C*** UPDATE COEFFICIENT VALUES ND 127
20 DO 21 J=1,10 ND 128
21 CPH(J)=0.000 ND 129
NNB=INQN(NNB) ND 130
DO 22 J=1,NUM ND 131
22 CPH(LOC(J,NNB))=ST(NNB,J) ND 132
RETURN ND 133
END ND 134

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SUBROUTINE F(T,Y,DI,C,KJK,J,IPATH,MCST,UCST) PP 1
C*** SUBROUTINE F USES THE HORIZONTAL- AND VERTICAL-PLANE EQUATIONS OF PP 2
C*** MOTION TO COMPUTE COMPATIBLE FLIGHT PATH PARAMETERS PP 3
C PP 4
IMPLICIT REAL*8(A-H,O-Z) PP 5
EXTERNAL VA,DDV,DDDV,ALP,DVA,PHIDER PP 6
DIMENSION Y(4),DY(4),CX(6) PP 7
COMMON TH(450),F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F7( PP 8
1450),F8(450),F9(450),F10(450),F11(450),F12(450),F13(450),F14(450), PP 9
1X(450,11),X(450,1),WKAR(250),CPH(14),SGR(4),SGD(4),PFI(450),PT2(45 PP 10
10),PVRA(450),XI(450),YI(450),X1(450),X2(450),X11,IX2,IX3,IX4,G,S,R PP 11
1MO,TIA,EXPI,PLOW,PHIGH,CDLOW,CDHIGH,JREAD,JWRITE,JPOUNCH,IX1,IX2, PP 12
1IX3,IX4,NRTIC,L1,L2,IEQUH(18),IERR PP 13
COMMON /LAB8/ALP1,P1,PAC(8),CL,CD PP 14
C PP 15
C*** CALCULATE AIRCRAFT HEIGHT PP 16
IF (J.NE.1) GO TO 1 PP 17
Y(1)=F1(J) GO TO 1 PP 18
GO TO 2 PP 19
1 Y(1)=Y(1)+DY(1)*(Y-TN(J-1))+DIY*(Y-TN(J-1))**2/2.000+DDIY*(Y-TN(J- PP 20
11))**3/6.000 PP 21
C*** COMPUTE DENSITY FACTOR PP 22
2 PE=(1.000-6.86D-6*Y(2))**4.2600 PP 23
C*** INITIALIZE PARAMETERS PP 24
ICHT=0 PP 25
A=P6(J) PP 26
TD=P3(J) PP 27
C1=(2.000*Y(1)/(G*S*RH0*PH*Y(3)))+(DY(4)*G*DCOS(Y(4))/Y(3)) PP 28
C2=2.000*Y(1)/(G*S*RH0*PH*Y(3)*Y(3)) PP 29
C3=C2*(DI(3)*COSIN(Y(4))) PP 30
C*** START NEWTON-RAPHSON ITERATION PP 31
JB=0 PP 32
3 ICHT=ICHT+1 PP 33
C*** CALCULATE CL, CD, AND THEIR DERIVATIVES PP 34
CALL CLCD(JB,A,TD,CPH,IX1,IX2,IX3,IX4,EXPI,CX) PP 35
C*** CALCULATE NEWTON-RAPHSON EQUATIONS PP 36
FI=CX(1)*DTAN(A)+(C3+CX(2))-C1 PP 37
FIP=CX(3)+(C3+CX(2))/(DCOS(A)*DCOS(A))+DTAN(A)*CX(5) PP 38
FIPP=CX(4)+(2.000*CX(5)+2.000*(C3+CX(2))*DTAN(A))/DCOS(A)**2+CX(6) PP 39
1*DTAN(A) PP 40
PP 41

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C*** SOLVE FOR ANGLE OF ATTACK
RAD=(PI/PIPP)*(PI/PIPP)-2.000*(PI/PIPP)
A1=A
IF (RAD.LT.0.000) GO TO 5
IF ((PI/PIPP).LT.0.000) GO TO 4
A=A-PI/PIPP+DSQRT(RAD)
GO TO 6
4 A=A-PI/PIPP-DSQRT(RAD)
GO TO 6
5 A=A-PI/PIPP
NCMT=NCMT+1
GO TO 7
C*** TEST FOR CONVERGENCE OR MAXIMUM ITERATION
6 IF (DABS(A1-A).LT.1.0D-15.OR.ICMT.EQ.20) GO TO 7
GO TO 3
C*** UPDATE CL, CD, POWER, AND WEIGHT DERIVATIVES
7 JR=1
ALP1=A
CALL CLCD(JR,A,TD,CFN,IEK1,IEK2,IEK3,IEK4,EXPI,CK)
CL=CK(1)
CD=CK(2)
PI=Y(1)*Y(3)/(G*DCOS(ALP1+TIA))*DY(3)*G*S*RHOPH*Y(3)**2*CK(2)/(2
1.000*Y(1))*G*DSIN(T(4)))
IF (PI.LT.0.000) IERR=1
IF (IERR.NE.0) RETURN
DY(1)=-C*PI
DIW=-C*DY(3)*(EX1*CFN(2)*Y(3)**(EX1-1.000)+EX2*CFN(3)*Y(3)**(EX2-1
1.000)+EX3*CFN(4)*Y(3)**(EX3-1.000)+EX4*CFN(5)*Y(3)**(EX4-1.000))
DDF=DDY(1)
DDIW=-C*(EX1*CFN(2)*Y(3)**(EX1-1.000)+EX2*CFN(3)*Y(3)**(EX2-1.000)+
EX3*CFN(4)*Y(3)**(EX3-1.000)+EX4*CFN(5)*Y(3)**(EX4-1.000))
DDI=DDY(1)*DDIW
C*** COMPUTE PARTIAL DERIVATIVES OF EQUATION OF MOTION
IF (KJK.EQ.2) GO TO 8
R1=RHOPH
CALL PARTIAL(J,Y(1),R1,ALP1,Y(3),DY(3),DY(2),Y(4),DY(4),PAC,NCMT)
8 RETURN
END

```

```

SUBROUTINE PATH(M,C,IPATH)
C
C*** SUBROUTINE PATH INTEGRATES THE VEHICLE EQUATIONS OF MOTION TO
C*** OBTAIN TIME HISTORIES OF BOTH VEHICLE AND FLIGHT PATH PARAMETERS
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION DY(4),Y(4),SC(450,8)
COMMON TIME(450),P1(450),P2(450),P3(450),P4(450),P5(450),P6(450),P
17(450),P8(450),P9(450),P10(450),P11(450),P12(450),P13(450),P14(450)
18,2(450,11),X(450,1),MAAB(250),CFN(14),SGN(4),SGD(4),FT1(450),FT2(
1450),PWA(450),XI(450),YI(450),X2(450),X1(450),EX1,EX2,EX3,EX4,G,S
1,RHO,TIA,EXPI,RLOW,PHIGH,CDLOW,CDHIGH,JREAD,JWRITE,JPUNCH,IEK1,IEK
12,IEK3,IEK4,METRIC,L1,L2,IQNH(18),IERR
COMMON /LAB9/ALP1,P1,PAC(8),CL,CD
COMMON /LAB9/ARF(450)
C
C*** INITIALIZE PARAMETERS

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GANNAX=1.000
VNIW=80.000
CALL CHNGE(SGN)
C*** WRITE HEADER TITLE
WRITE (JWRITE,1) IPATH
1 FORMAT (1X,///,43X,07(' '),//,43X,00,45X,00,///,43X,00,2X,'PATH DE
INFORMANCE ANALYSIS ITERATION NO.',12,2X,' ',//,43X,00,3X,' (ALTITUD
1E AND AIRSPEED ASSUMED CORRECT)',3X,00,///,43X,00,45X,00,///,43X,07
1(' '),//)
C*** COMPUTE ACCELERATION DERIVATIVE
IF (IPATH.NE.1) GO TO 2
CALL PHI(M,P8,TIME,PT1,PT2,0.15,3,2)
C*** COMPUTE MINIMUM WEIGHT
2 WZMPTY=PT1(M)-1.000
C*** BEGIN LOOP FOR CORRECTIONS
DO 16 KJK=1,2
C*** WRITE LABELS IN ENGLISH OR SI UNITS
IF (METRIC.EQ.0) WRITE (JWRITE,3) KJK
IF (METRIC.NE.0) WRITE (JWRITE,4) KJK
3 FORMAT (1X,///,51X,'PATH PERFORMANCE SUBITERATION',12,///,13X,'TIME',
17X,'ALTITUDE',5X,'AIRSPEED',6X,'GANNAX',7X,'ALPHA',10X,'CL',11X,'CD'
1,9X,'WEIGHT',9X,'POWER',//,12X,' (SECS)',8X,' (FT)',7X,' (FT/SEC)',6X
1,' (RAD)',7X,' (RAD)',35X,' (LBF)',6X,' (FT-LBF/SEC)',//)
4 FORMAT (1X,///,51X,'PATH PERFORMANCE SUBITERATION',12,///,13X,'TIME',
17X,'ALTITUDE',5X,'AIRSPEED',6X,'GANNAX',7X,'ALPHA',10X,'CL',11X,'CD'
1,9X,'WEIGHT',9X,'POWER',//,12X,' (SECS)',8X,' (FT)',7X,' (FT/SEC)',
1,6X,' (RAD)',7X,' (RAD)',33X,' (NEWTONS)',2X,' (KW)',//)
C*** BEGIN INTEGRATION
I=1
T=TIME(I)
Y(1)=F1(I)
Y(2)=F10(I)
Y(3)=P4(I)
Y(4)=PT1(I)
DY(2)=F11(I)
DY(3)=F8(I)
DY(4)=PT2(I)
NCMT=0
C*** EXACT SOLUTION ROUTINE
CALL F(T,Y,DY,C,KJK,I,IPATH,NCMT,NCMT)
C*** CHECK FOR ERROR
IF (IERR.NE.0) RETURN
C*** WRITE RESULTS
IF (METRIC.NE.0) GO TO 6
WRITE (JWRITE,5) T,Y(2),Y(3),Y(4),ALP1,CL,CD,Y(1),P1
5 FORMAT (9X,9(1PD12.5,1X))
GO TO 7
6 WS=Y(1)*4.44820D
HS=Y(2)*0.3048D
VS=Y(3)*0.3048D
PIS=P1*1.3558D/1000.0D
WRITE (JWRITE,5) T,HS,VS,Y(4),ALP1,CL,CD,WS,PIS
C*** STORE ANGLE OF ATTACK DIFFERENCE AND PARTIAL DERIVATIVES
7 ADY(I)=ALP1-P6(I)
IF (KJK.EQ.2) GO TO 9
DO 8 L=1,8
8 SC(L,L)=PAC(L)
C*** CONTINUE INTEGRATION
9 DO 13 I=2,M

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T=TIME(I)
T(1)=F1(I)
T(2)=F10(I)
T(3)=F4(I)
T(4)=F11(I)
DT(2)=F11(I)
DT(3)=F8(I)
DT(4)=F12(I)
C*** EXACT SOLUTION ROUTINE
CALL F(T,Y,DT,C,KJK,I,IPATH,NCNT,NCNT)
C*** CHECK FOR ERROR
IF (IERR.NE.0) RETURN
C*** CHECK FOR TOLERANCE LIMITS
IF (T(1).LT.WERTV) GO TO 17
IF (T(2).LT.0.000) GO TO 19
IF (DABS(T(4)).GT.GAMMA) GO TO 21
IF (T(3).LT.VMIN) GO TO 23
C*** WRITE RESULTS
IF (IERR.NE.0) GO TO 10
WRITE (JWRITE,5) T,Y(2),Y(3),Y(4),ALP1,CL,CD,Y(1),P1
GO TO 11
10 WS=Y(1)+.448200
HS=Y(2)+.304800
VS=Y(3)+.304800
PIS=P1+1.355800/1000.000
WRITE (JWRITE,5) T,HS,VS,Y(4),ALP1,CL,CD,WS,PIS
C*** STORE ANGLE OF ATTACK
11 ADP(I)=ALP1-F6(I)
IF (KJK.EQ.2) GO TO 13
DO 12 L=1,8
12 SC(L,L)=PAC(L)
13 CONTINUE
IF (NCNT.NE.0) WRITE (JWRITE,14) NCNT
14 FORMAT (1X,///,9I,94H*** DURING NEWTON-RAPHSON FOR ANGLE OF ATTACK
1IN F , ROUTINE WISHED TO SEEK COMPLEX ROOTS ,13,7H TIMES.)
IF (KJK.EQ.2) GO TO 16
IF (NCNT.NE.0) WRITE (JWRITE,15) NCNT
15 FORMAT (1X,///,9I,94H*** DURING NEWTON-RAPHSON FOR ANGLE OF ATTACK
1IN PARTIAL, ROUTINE WISHED TO SEEK COMPLEX ROOTS ,13,7H TIMES.)
C*** CALL DELTA CORRECTION ROUTINE
CALL DCR(M,ADP,SC,CFN,JWRITE)
16 CONTINUE
RETURN
C*** ERROR MESSAGES (TERMINATING)
17 WRITE (JWRITE,18)
18 FORMAT (1X,///,10I,'AIRCRAFT WEIGHT MINIMUM DECREASED BY 1 LBF OR 4
1.482 NEWTONS. DATA REJECTED.')
GO TO 25
19 WRITE (JWRITE,20)
20 FORMAT (1X,///,10I,'ALTITUDE BECAME LESS THAN ZERO. DATA REJECTED.'
1)
GO TO 25
21 WRITE (JWRITE,22)
22 FORMAT (1X,///,10I,'ABSOLUTE VALUE OF FLIGHT PATH ANGLE EXCEEDED 1
1RADIAN. DATA REJECTED.')
GO TO 25
23 WRITE (JWRITE,24)
24 FORMAT (1X,///,10I,'AIRSPEED BECAME LESS THAN THE MINIMUM SPEED. DA
1TA REJECTED.')
25 IERR=1

```

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PH 78
PH 79
PH 80
PH 81
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PH 85
PH 86
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PH 112
PH 113
PH 114
PH 115
PH 116
PH 117
PH 118
PH 119
PH 120
PH 121
PH 122
PH 123
PH 124
PH 125
PH 126
PH 127
PH 128
PH 129
PH 130
PH 131
PH 132
PH 133
PH 134
PH 135
PH 136
PH 137

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```

RETURN
END
PH 138
PH 139

SUBROUTINE PARTIAL(J,V,H,ALP,V,DU,DM,FPA,DPPA,PAC,NCNT)
PH 1
C
C*** SUBROUTINE PARTIAL COMPUTES NUMERICALLY THE PARTIAL DERIVATIVES OF
PH 2
C*** THE LIFT AND DRAG COEFFICIENTS
PH 3
C
PH 4
PH 5
IMPLICIT REAL*8(A-H,O-Z)
PH 6
DIMENSION CX(8),PAC(8),FX(2),CXI(6)
PH 7
COMMON TIME(450),F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F
PH 8
17(450),F8(450),F9(450),F10(450),F11(450),F12(450),F13(450),F14(450)
PH 9
1),C(450,11),X(450,1),UKAN(250),CFN(14),SGN(4),SGD(4),PT1(450),PT2(
PH 10
450),PWBA(450),CL(450),CD(450),X1(450),X2(450),X3(450),X4(450),C,S
PH 11
1,RHO,TIA,XIPI,DLOW,PHIGH,CDLOW,CDHIGH,JREAD,JWRITE,JFUNCH,IX1,IX
PH 12
12,IX3,IX4,METRIC,L1,L2,IEQW(18),IERR
PH 13
C
C*** INITIALIZE FACTORS AND PARAMETERS
PH 14
FX(1)=0.9900
PH 15
FX(2)=1.0100
PH 16
TD=F3(J)
PH 17
IN=0
PH 18
JC=1
PH 19
C*** STORE LIFT AND DRAG COEFFICIENTS
PH 20
DO 1 I=1,8
PH 21
1 CX(I)=CFN(I+5)
PH 22
C*** COMPUTE COEFFICIENTS FOR EQUATION OF MOTION
PH 23
C1=(2.000*W/(G*S*R*V))*(DPPA+G*DCOS(FPA)/V)
PH 24
C2=2.000*W/(G*S*R*V)
PH 25
C3=C2*(DV*S*DSIN(FPA))
PH 26
C*** BEGIN COMPUTATION OF PARTIAL DERIVATIVES
PH 27
DO 9 JX=1,16
PH 28
9 JX=1,16
PH 29
A=ALP
PH 30
IF (IN.EQ.2) JC=JC+1
PH 31
IN=1
PH 32
IF (((JX/2)*2).EQ.JX)IN=2
PH 33
TEST FOR ZERO COEFFICIENT
PH 34
IF (CX(JC).NE.0.000) GO TO 2
PH 35
PAC(JC)=0.000
PH 36
GO TO 9
PH 37
C*** MODIFY COEFFICIENT
PH 38
2 CFN(JC+5)=CX(JC)*FX(IN)
PH 39
ICNT=0
PH 40
3 ICNT=ICNT+1
PH 41
JB=0
PH 42
C*** COMPUTE CL, CD, AND THEIR DERIVATIVES
PH 43
CALL CLCD(JR,A,TD,CFN,IX1,IX2,IX3,IX4,EXPI,CXI)
PH 44
FORM NEWTON-RAPHSON EQUATIONS
PH 45
F1=CXI(1)+DTAN(A)*(C3+CXI(2))-C1
PH 46
F1P=CXI(3)+(C3+CXI(2))/(DCOS(A)*DCOS(A))+DTAN(A)*CXI(5)
PH 47
F1PP=CXI(4)+(2.000*CXI(5)+2.000*(C3+CXI(2))*DTAN(A))/(DCOS(A)*DCOS
PH 48
1(A))*CXI(6)+DTAN(A)
PH 49
C*** SOLVE FOR ANGLE OF ATTACK
PH 50
RAD=(F1P/F1PP)*(F1P/F1PP)-2.000*(F1/F1PP)
PH 51
AS=A
PH 52
IF (RAD.LT.0.000) GO TO 5
PH 53
IF ((F1P/F1PP).LT.0.000) GO TO 4
PH 54
A=A-F1P/F1PP+DSQRT(RAD)
PH 55

```



```

      GO TO 6
4 A=A-FIP/FIPP-DSQRT(RAD)
      GO TO 6
5 A=A-FIP/FIPP
      MCNT=MCNT+1
      GO TO 7
6 IF (DABS(AS-A)-LT.1.0D-15.OR.ICNT.GE.20) GO TO 7
      GO TO 3
7 IF (((JX/2)*2).NE.JX) A1=A
      IF (((JX/2)*2).EQ.JX) A2=A
      IF (((JX/2)*2).EQ.JX) GO TO 8
      GO TO 9
C*** COMPUTE PARTIAL DERIVATIVES AND RESET COEFFICIENTS
8 PAC(JC)=(A2-A1)/(FX(2)-FX(1))/CX(JC)
      CFH(JC+5)=CX(JC)
9 CONTINUE
      RETURN
      END

```

```

PR 56
PR 57
PR 58
PR 59
PR 60
PR 61
PR 62
PR 63
PR 64
PR 65
PR 66
PR 67
PR 68
PR 69
PR 70
PR 71
PR 72
PR 73

```

```

C SUBROUTINE FITERR(P,I,X)
C*** SUBROUTINE FITERR CHECKS FIT ERRORS AND STORES
C*** *BEST* MODEL EXTRACTION COEFFICIENTS
C
      IMPLICIT REAL*8(A-H,O-Z)
      DIMENSION I(14),IX(14)
C
      IF (I.NE.1) GO TO 3
1 F1=F
      DO 2 J=1,14
2 IX(J)=I(J)
      RETURN
3 F2=F
      IF (F2.LT.F1) GO TO 1
      F=F1
      DO 4 J=1,14
4 I(J)=IX(J)
      RETURN
      END

```

```

PR 1
PR 2
PR 3
PR 4
PR 5
PR 6
PR 7
PR 8
PR 9
PR 10
PR 11
PR 12
PR 13
PR 14
PR 15
PR 16
PR 17
PR 18
PR 19
PR 20

```

```

C SUBROUTINE ASCEN(N,I,X,YY,IX)
C*** SUBROUTINE ASCEN ORDERS DATA OF X VS. Y BY ASCENDING X
C
      IMPLICIT REAL*8(A-H,O-Z)
      DIMENSION I(N),Y(N),X(N),IX(N)
C
      STORE INPUT VALUES
      DO 1 J=1,N
1 YY(J)=Y(J)
      IX(J)=I(J)
      NN=N-1
C*** ARRANGE IN ASCENDING ORDER
      DO 3 J=1,NN
      M=J
      NP1=J+1

```

```

AS 1
AS 2
AS 3
AS 4
AS 5
AS 6
AS 7
AS 8
AS 9
AS 10
AS 11
AS 12
AS 13
AS 14
AS 15
AS 16

```

```

      DO 2 I=NP1,N
2 IF (IX(I).LT.IX(N)) M=I
      I1=IX(J)
      T2=YY(J)
      IX(J)=IX(M)
      YY(J)=YY(M)
      IX(M)=T1
      YY(M)=T2
3 YY(N)=T2
      RETURN
      END

```

```

AS 17
AS 18
AS 19
AS 20
AS 21
AS 22
AS 23
AS 24
AS 25
AS 26

```

```

C SUBROUTINE CLCD(L,A,PR,C,IEK1,IEK2,IEK3,IEK4,IX,N)
C*** SUBROUTINE CLCD CALCULATES LIFT AND DRAG COEFFICIENTS AND THEIR
C*** DERIVATIVES WHEN NEEDED
C
      IMPLICIT REAL*8(A-H,O-Z)
      DIMENSION C(14),B(6),S(4)
      COMMON /LAB2/ICDPT,ICD,ATH,HCICC
C
C*** COMPUTE DRAG COEFFICIENTS AND DERIVATIVES
      CALL CHNGE(S)
      IF (A.LT.0.0D0) CALL SIGNS(S,IEK1,IEK2,IEK3,IEK4)
      AN=DABS(A)
      B(2)=C(6)*S(1)*C(7)*AN**IEK1+S(2)*C(8)*AN**IEK2+S(3)*C(9)*AN**IEK3
      S(4)*C(10)*AN**IEK4
      IF (A.LT.0.0D0) CALL CHNGE(S)
      IF (L.NE.0) GO TO 1
      L1=IEK1-1
      L2=IEK2-1
      L3=IEK3-1
      L4=IEK4-1
      L5=L1-1
      L6=L2-1
      L7=L3-1
      L8=L4-1
      IF (A.LT.0.0D0) CALL SIGNS(S,L1,L2,L3,L4)
      B(5)=S(1)*IEK1*C(7)*AN**L1+S(2)*IEK2*C(8)*AN**L2+S(3)*IEK3*C(9)*AN**L3
      S(4)*IEK4*C(10)*AN**L4
      IF (A.LT.0.0D0) CALL SIGNS(S,L5,L6,L7,L8)
      B(6)=S(1)*IEK1*L1*C(7)*AN**L5+S(2)*IEK2*L2*C(8)*AN**L6+S(3)*IEK3*L3
      C(9)*AN**L7+S(4)*IEK4*L4*C(10)*AN**L8
      IF (A.LT.0.0D0) CALL CHNGE(S)
C*** CHECK FORM FOR LIFT COEFFICIENT EXPRESSION
1 GO TO (2,3,4),ICD
C*** COMPUTE LIFT COEFFICIENT AND DERIVATIVES
2 IF (A.GT.0.0D0) GO TO 3
      B(1)=C(12)*A+Y*C(14)*PR
      IF (L.NE.0) GO TO 5
      B(3)=C(12)
      B(4)=0.0D0
      GO TO 5
3 B(1)=C(11)*C(12)*A+C(13)*A**EX*C(14)*PR
      IF (L.NE.0) GO TO 5
      B(3)=C(12)*EX*C(13)*A**EX-1.0D0
      B(4)=EX*(EX-1.0D0)*C(13)*A**EX-2.0D0
      GO TO 5
4 B(1)=C(11)*C(12)*A+C(13)*A**A+C(14)*PR

```

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CD 46
CD 47

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IF (L.NE.0) GO TO 5
B(3)=C(12)+2.000*C(13)*A
B(4)=2.000*C(13)
5 RETURN
END
CD 48
CD 49
CD 50
CD 51
CD 52

SUBROUTINE DCR(N,AD,P,C,JWRITE)
C
C*** SUBROUTINE DCR SOLVES FOR DELTA CORRECTIONS TO BE APPLIED TO LIFT
C*** AND DRAG COEFFICIENTS
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION AD(450),P(450,8),C(14),F(8),A(8,2),B(8)
C
C*** INITIALIZE FACTORS AND COEFFICIENTS
DO 1 J=1,8
F(J)=1.000
IF (C(J+5)-EQ.0.000) F(J)=0.000
A(J,1)=0.000
1 A(J,2)=0.000
C*** SUM PRODUCTS OF PARTIALS
DO 2 J=1,8
DO 2 L=1,8
A(L,1)=A(L,1)+P(J,L)*F(J)*F(L)
2 A(L,2)=A(L,2)+P(J,L)*AD(J)*F(L)
C*** INITIALIZE DELTA CORRECTIONS
DO 3 L=1,8
B(L)=0.000
C*** CALCULATE CORRECTIONS
DO 4 L=1,8
IF (A(L,1)-EQ.0.000) GO TO 4
B(L)=A(L,2)/A(L,1)
4 CONTINUE
C*** APPLY CORRECTIONS
DO 5 L=1,8
F(L)=C(L+5)
5 C(L+5)=C(L+5)+B(L)
C*** WRITE OLD AND NEW DRAG AND LIFT COEFFICIENTS AND DELTAS
WRITE (JWRITE,6) (F(L),B(L),C(L+5),L=1,8)
6 FORMAT (1X,///,42X,'PATH PERFORMANCE DRAG AND LIFT COEFFICIENT UPD.
1 1ATE',///,42X,'OLD',22X,'DELTA',22X,'NEW',///,26X,'CD0 : ',D23.16,' +
1 1,D23.16,' = ',D23.16,/,26X,'CD1 : ',D23.16,' + ',D23.16,' = ',D2
13.16,/,26X,'CD2 : ',D23.16,' + ',D23.16,' = ',D23.16,/,26X,'CD3 :
1,D23.16,' + ',D23.16,' = ',D23.16,/,26X,'CD4 : ',D23.16,' + ',D23
1.16,' = ',D23.16,/,26X,'CLA0 : ',D23.16,' + ',D23.16,' = ',D23.16,
1,26X,'CLA : ',D23.16,' + ',D23.16,' = ',D23.16,/,26X,'CLAX : ',D23.
116,' + ',D23.16,' = ',D23.16,///)
RETURN
END
CD 1
CD 2
CD 3
CD 4
CD 5
CD 6
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CD 43

SUBROUTINE SPLINE(W,Y,X,AA,IC)
C
C*** SUBROUTINE SPLINE FINDS THE RELATIONSHIP BETWEEN FUNCTION VALUES
C*** AND ALLOWS THE CALCULATION OF DERIVATIVES
C*** REFERENCE FOR THIS METHOD IS:
C*** THE THEORY OF SPLINES AND THEIR APPLICATIONS
SP 1
SP 2
SP 3
SP 4
SP 5
SP 6

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C*** J.H. AHLBERG, ET AL, ACADEMIC PRESS, NEW YORK, 1967
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION X(N),Y(N),AA(4,N),BB(4,1827),CC(4,1827),DD(4,1827),H(182
17),Q(1827),U(1827),EE(4,1827)
C
N=1-N-1
DO 1 I=1,NH1
1 H(I)=4(I+1)-I(I)
C*** MODIFIED LEFT-HAND END CONDITION THAT ALLEVIATES THE NEED TO
C*** SPECIFY THE X-DERIVATIVE OF Y AT POINT 1
Q(1)=-31.000/32.000
H1=H(1)
H2=H(2)
H3=H(3)
U(1)=Y(1)*(32.000*H1+42.000*H2+21.000*H3)/(H1*H2)/(H1*H2+H3)-Y(2)*
1(11.000*H1+42.000*H2+21.000*H3)/(H2*H3)/H2+Y(3)*H1*(11.000*H1+21.0
100*(H2+H3))/(H1*H2)/H2/H3-Y(4)*H1*(11.000*H1+21.000*H2)/(H2*H3)/(H
11*H2+H3)/H3
C*** GENERATE INTERNAL U(I) BY ALGORITHM GIVEN BY AHLBERG
U(1)=3.000*U(1)/H1/16.000
HH=H(1)
YY=Y(2)
YH=Y(1)
DO 2 I=2,NH1
HH=H(I)
YH=Y(I+1)
YP=Y(I+1)
D=3.000*((YH-YP)/HH-(YP-YH)/HH)/(HH*HH)
C=C.500*HH/(HH*HH)
A=0.500-C
P=A*Q(I-1)+1.000
Q(I)=-C/P
U(I)=(D-A*U(I-1))/P
HH=HH
YH=YH
2 YH=YP
C*** MODIFIED RIGHT-HAND END CONDITION THAT ALLEVIATES THE NEED TO
C*** SPECIFY THE X-DERIVATIVE OF Y AT POINT N
P=A*Q(N-1)+1.000
H1=H(NH1)
H2=H(NH1-1)
H3=H(NH1-2)
D=Y(N)*(32.000*H1+42.000*H2+21.000*H3)/(H1*H2)/(H1*H2+H3)-Y(NH1)*
11.000*H1+42.000*H2+21.000*H3)/(H2*H3)/H2+Y(NH1-1)*H1*(11.000*H1+2
11.000*(H2+H3))/(H1*H2)/H2/H3-Y(NH1-2)*H1*(11.000*H1+21.000*H2)/H2
1*H3)/(H1*H2+H3)/H3
D=3.000*D/H1/16.000
U(N)=(D-A*U(N-1))/P
C*** SOLVE FOR THE SPLINE COEFFICIENTS CORRESPONDING TO AHLBERG N(0) TO
C*** N(N) AND STORE THEM IN THE U(I)
DO 3 J=1,NH1
I=N-J
3 U(I)=Q(I)*U(I+1)+U(I)
C*** FORM THE SPLINE COEFFICIENTS FOR THE CONVENTIONAL FORM OF A CUBIC
C*** POLYNOMIAL FROM THE U(I)
UU=U(1)
XX=Y(1)
YY=Y(1)
DO 4 I=1,NH1
SP 7
SP 8
SP 9
SP 10
SP 11
SP 12
SP 13
SP 14
SP 15
SP 16
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SP 64
SP 65
SP 66

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UP=U(I+1) SP 67
XP=X(I+1) SP 68
YP=Y(I+1) SP 69
HH=H(I) SP 70
AA(1,I)=(UP-U)/HH/6.000 SP 71
AA(2,I)=0.500*(XP-UU-XX*UP)/HH SP 72
AA(3,I)=0.500*(UP*XX-XX*UP-XP*XP)/HH+(UU-UP)*HH/6.000*(YP-Y)/HH SP 73
AA(4,I)=(UU*XP*XP-UP*UP*XX*XX)/HH/6.000*(UP*XX-UP*XP)*HH/6.000 SP 74
I(YI*XP-YP*XI)/HH SP 75
XX=XP SP 76
UU=UP SP 77
YY=YP SP 78
IF (IC.EQ.0) GO TO 13 SP 79
C*** STORE COEFFICIENTS FOR LATTER USE SP 80
GO TO (5,7,9,11),IC SP 81
DO 6 I=1,NN1 SP 82
DO 6 J1=1,4 SP 83
6 BB(J1,I)=AA(J1,I) SP 84
GO TO 13 SP 85
7 DO 8 I=1,NN1 SP 86
DO 8 J1=1,4 SP 87
8 CC(J1,I)=AA(J1,I) SP 88
GO TO 13 SP 89
9 DO 10 I=1,NN1 SP 90
DO 10 J1=1,4 SP 91
10 DD(J1,I)=AA(J1,I) SP 92
GO TO 13 SP 93
11 DO 12 I=1,NN1 SP 94
DO 12 J1=1,4 SP 95
12 EE(J1,I)=AA(J1,I) SP 96
13 RETURN SP 97
C SP 98
ENTRY VIX(T,Z) SP 99
C*** DETERMINE AIRSPEED AT TIME T SP 100
IF (T.GT.X(1)) GO TO 14 SP 101
I=1 SP 102
GO TO 16 SP 103
14 DO 15 I=1,NN1 SP 104
IF (X(I).LE.T.AND.X(I+1).GT.T) GO TO 16 SP 105
15 CONTINUE SP 106
I=NN1 SP 107
16 Z=((BB(1,I)*T+BB(2,I)*T+BB(3,I)*T+BB(4,I) SP 108
RETURN SP 109
C SP 110
ENTRY DVX(T,Z) SP 111
C*** DETERMINE ACCELERATION AT TIME T SP 112
IF (T.GT.X(1)) GO TO 17 SP 113
I=1 SP 114
GO TO 19 SP 115
17 DO 18 I=1,NN1 SP 116
IF (X(I).LE.T.AND.X(I+1).GT.T) GO TO 19 SP 117
18 CONTINUE SP 118
I=NN1 SP 119
19 Z=((CC(1,I)*T+CC(2,I)*T+CC(3,I)*T+CC(4,I) SP 120
RETURN SP 121
C SP 122
ENTRY DOVXX(T,Z) SP 123
C*** DETERMINE 2ND AIRSPEED DERIVATIVE AT TIME T SP 124
IF (T.GT.X(1)) GO TO 20 SP 125
I=1 SP 126

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GO TO 22 SP 127
20 DO 21 I=1,NN1 SP 128
IF (X(I).LE.T.AND.X(I+1).GT.T) GO TO 22 SP 129
21 CONTINUE SP 130
I=NN1 SP 131
22 Z=3.000*CC(1,I)*T+2.000*CC(2,I)*T+CC(3,I) SP 132
RETURN SP 133
C SP 134
ENTRY AXI(T,Z) SP 135
C*** DETERMINE ANGLE OF ATTACK AT TIME T SP 136
IF (T.GT.X(1)) GO TO 23 SP 137
I=1 SP 138
GO TO 25 SP 139
23 DO 24 I=1,NN1 SP 140
IF (X(I).LE.T.AND.X(I+1).GT.T) GO TO 25 SP 141
24 CONTINUE SP 142
I=NN1 SP 143
25 Z=((DD(1,I)*T+DD(2,I)*T+DD(3,I)*T+DD(4,I) SP 144
RETURN SP 145
C SP 146
ENTRY DDDVX(T,Z) SP 147
C*** DETERMINE 3RD AIRSPEED DERIVATIVE SP 148
IF (T.GT.X(1)) GO TO 26 SP 149
I=1 SP 150
GO TO 28 SP 151
26 DO 27 I=1,NN1 SP 152
IF (X(I).LE.T.AND.X(I+1).GT.T) GO TO 28 SP 153
27 CONTINUE SP 154
I=NN1 SP 155
28 Z=3.000*EE(1,I)*T+2.000*EE(2,I)*T+EE(3,I) SP 156
RETURN SP 157
END SP 158

SUBROUTINE FNI(K,F,X,PP,PPP,ND,NS,NI,IC) PN 1
PN 2
C*** SUBROUTINE FNI USES NEWTON'S INTERPOLATION FORMULA TO COMPUTE PN 3
C*** ADDITIONAL POINTS FOR CUBIC SPLINE ANALYSIS PN 4
C PN 5
IMPLICIT REAL*8(A-H,O-Z) PN 6
DIMENSION F(K),X(K),PP(K),PPP(K),XY(1827),Y(1827),AA(4,1827),FPS(1 PN 7
1827) PN 8
C PN 9
C*** THE ARRAYS ARE PROTECTED AGAINST "OVERFLOW" BY THE FOLLOWING CARDS PN 10
NB=K*(K-1)*NI*2*NS PN 11
IF (NB.EQ.K) GO TO 4 PN 12
IF (NB.LE.1827) GO TO 1 PN 13
NI=3 PN 14
NS=15 PN 15
NB=K*(K-1)*NI*2*NS PN 16
C*** INITIALIZE PARAMETERS PN 17
1 OF=1.0D-12 PN 18
N=X(2)-X(1) PN 19
XX=-N PN 20
XC=QABS(XX/(NS+1)) PN 21
XN=QABS(XX)*X(K) PN 22
ACH=XC PN 23
R=C PN 24
I=1 PN 25

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J=6
2 N=N+1
C*** DETERMINE THE INTERVAL IN QUESTION
IX=XX*XC
IF (DABS(XX-XXH).LT.DF) XX=XXH
IF (XX.GE.XXH) GO TO 3
IF (DABS(XX-X(L)).LT.DF) XX=X(L)
IF (DABS(XX-X(L+1)).LT.DF) XX=X(L+1)
IF (XX.EQ.X(L+1).AND.XX.LT.X(K)) L=L+1
IF (DABS(XX-X(J-2)).LT.DF) XX=X(J-2)
IF (XX.EQ.X(J-2).AND.J.LT.N) J=J+1
C*** COMPUTE THE NEWTONIAN COEFFICIENTS
A0=F(J-5)
A1=(F(J-4)-F(J-5))/(X(J-4)-X(J-5))
A2=(F(J-3)-(A0+A1*(X(J-3)-X(J-5))))/((X(J-3)-X(J-5))*(X(J-3)-X(J-4)
1)))
A3=(F(J-2)-(A0+A1*(X(J-2)-X(J-5))+A2*(X(J-2)-X(J-5))*(X(J-2)-X(J-4)
1)))/((X(J-2)-X(J-5))*(X(J-2)-X(J-4))+(X(J-2)-X(J-3)))
A4=(F(J-1)-(A0+A1*(X(J-1)-X(J-5))+A2*(X(J-1)-X(J-5))*(X(J-1)-X(J-4)
1))+A3*(X(J-1)-X(J-5))*(X(J-1)-X(J-3)))/((X(J-1)-X(J-4)
1)*(X(J-1)-X(J-3)))+(X(J-1)-X(J-2)))
A5=(F(J)-(A0+A1*(X(J)-X(J-5))+A2*(X(J)-X(J-5))*(X(J)-X(J-4)
1)+A3*(X(J)-X(J-5))*(X(J)-X(J-3))+A4*(X(J)-X(J-5))*(X(J)-X(J-2)
1-4)))/(X(J)-X(J-3))*(X(J)-X(J-2)))/((X(J)-X(J-5))*(X(J)-X(J-4))*(X(J)-X(J-3))*(X(J)-X(J-2)))+(X(J)-X(J-3))*(X(J)-X(J-2)))+(X(J)-X(J-1)))
C*** COMPUTE ADDITIONAL POINTS BY INTERPOLATION
X(H)=A0+A1*(XX-X(J-5))+A2*(XX-X(J-5))*(XX-X(J-4))+A3*(XX-X(J-5))*
1XX-X(J-4))*(XX-X(J-3))+A4*(XX-X(J-5))*(XX-X(J-3))*(XX-X(J-2))+
1X(J-2))+A5*(XX-X(J-5))*(XX-X(J-4))*(XX-X(J-3))*(XX-X(J-2))*(XX-X(J
1-1))
XY(H)=XX
C*** DETERMINE INTERVAL INCREMENT
IF (XX.GE.X(1).AND.XX.LT.X(K)) XC=(X(L+1)-X(L))/(N1+1)
IF (XX.GE.X(K)) XC=XCH
GO TO 2
3 KN=N-1
4 IF (N0.EQ.K) KN=K
C*** COMPUTE SPLINE COEFFICIENTS
CALL SPLINE(KN,Y,XY,AA,IC)
IF (IC.NE.0) GO TO 9
C*** COMPUTE FIRST DERIVATIVE BY DIFFERENTIATION OF SPLINE FIT
L1=NS+1
L2=KN-NS
L3=N1+1
II=0
DO 5 I=L1,L2,L3
II=II+1
J=I
IF (I.EQ.L2) J=J-1
FP(II)=3.000*AA(1,J)*XY(I)**2+2.000*AA(2,J)*XY(I)+AA(3,J)
5 CONTINUE
C*** CHECK FOR SECOND DERIVATIVE REQUEST
IF (N0.EQ.2) GO TO 6
GO TO 9
C*** COMPUTE ALL FIRST DERIVATIVES FOR SPLINE FIT
6 DO 7 I=1,KN
J=I
IF (I.EQ.KN) J=J-1
7 FPS(I)=3.000*AA(1,J)*XY(I)**2+2.000*AA(2,J)*XY(I)+AA(3,J)
C*** COMPUTE SECOND DERIVATIVE BY DIFFERENTIATION OF SPLINED FIRST

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C*** DERIVATIVE
CALL SPLINE(KN,FPS,XY,AA,IC)
II=0
DO 8 I=L1,L2,L3
II=II+1
J=I
2F (I.EQ.L2) J=J-1
FPP(II)=3.000*AA(1,J)*XY(I)**2+2.000*AA(2,J)*XY(I)+AA(3,J)
8 CONTINUE
9 RETURN
END

FUNCTION VA(T)
C
C*** FUNCTION VA (WITH SPLINE) DETERMINES THE AIRSPEED AT TIME T
C
C IMPLICIT REAL*8(A-H,O-Z)
CALL VEX(T,X)
VA=X
RETURN
END

FUNCTION DDV(T)
C
C*** FUNCTION DDV (WITH SPLINE) DETERMINES THE SECOND DERIVATIVE OF
C AIRSPEED AT TIME T
C
C IMPLICIT REAL*8(A-H,O-Z)
CALL DDVX(T,X)
DDV=X
RETURN
END

FUNCTION DDDV(T)
C
C*** FUNCTION DDDV (WITH SPLINE) DETERMINES THE THIRD DERIVATIVE OF
C AIRSPEED AT TIME T
C
C IMPLICIT REAL*8(A-H,O-Z)
CALL DDDVX(T,X)
DDD=X
RETURN
END

FUNCTION ALP(T)
C
C*** FUNCTION ALP (WITH SPLINE) DETERMINES THE ANGLE OF ATTACK AT
C TIME T

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C*** DETERMINE DIFFERENCE IN 'PREDICTED' AND ABOVE ESTIMATION OF FLIGHT FF 98
C*** PATH ANGLE FF 99
      DGAN=VY-GAM1 FF 100
C*** DETERMINE A CORRECTION TO ANGLE OF ATTACK THRU DERIVATIVES OF FF 101
C*** EQUATION OF MOTION FF 102
      IF (IKP.EQ.0) GO TO 3 FF 103
      ADEL=DGAN/DGDA FF 104
      CDL=CDL*ADEL FF 105
C*** COMPUTE DERIVATIVE OF FLIGHT PATH ANGLE FF 106
      DYT=G*S*H*Y*(CFM(11)+CFM(12)*A+CFM(13)*A**2)*XPK/(2.000*H)+G*P*DSIN FF 107
      1 (A)/(H*Y*X)-G*DCOS(YE)/Y FF 108
      XRH0=H FF 109
      A=AXX FF 110
      W=XXX FF 111
      R=XXX FF 112
      RETURN FF 113
      END FF 114

      SUBROUTINE TREWOR(H,IX,YY,D2Y,D3Y,D4Y,ISET,F,IPRN,KK,IK) TR 1
C C*** SUBROUTINE TREWOR PREDICTS A FLIGHT PATH TRAJECTORY TR 2
C TR 3
      IMPLICIT REAL*8(A-H,O-Z) TR 4
      EXTERNAL VA,DDV,DDDV,ALP,DVA,PHIDER TR 5
      COMMON /TEST/ICKP TR 6
      COMMON /LAB3/DGAN TR 7
      COMMON /LAB6/Y1,ADT TR 8
      COMMON /PCR/DY(7),X(7),Y(7) TR 9
      COMMON /LAB1/JWRITE,IR TR 10
      COMMON /CRCOEF/P,A0,A1,A2,A3,A4,A5,HH TR 11
C TR 12
C*** INITIALIZE PARAMETERS TR 13
      AF=0.000 TR 14
      IKP=0 TR 15
C*** COMPUTE DERIVATIVE AT BEGINNING OF INTERVAL TR 16
      CALL FF(IX,YY,D2Y,F,IPRN,DGAN,AF,IKP) TR 17
      DY(7)=D2Y TR 18
      T1=XX TR 19
C*** TEST FOR INITIALIZATION TR 20
      IF (ISET) 1,1,3 TR 21
C*** INITIALIZE PARAMETERS TR 22
      1 DO 2 I=1,7 TR 23
        Y(I)=YY TR 24
        DY(I)=D2Y TR 25
      2 X(I)=XX TR 26
C*** BEGIN RUNGE KUTTA TR 27
      LK=6 TR 28
      K=1 TR 29
      ISET=1 TR 30
      GO TO 4 TR 31
      3 IF (K.LT.7) K=K+1 TR 32
      IF (K=7) 4,7,7 TR 33
C*** DEFINE VARIABLES FOR FF TR 34
      Y2=YY+0.500*H*D2Y TR 35
      AF=0.500 TR 36
      IKP=0 TR 37
C*** COMPUTE DERIVATIVE AT INTERVAL MIDPOINT TR 38
      CALL FF(IX+0.500*H,Y2,DY2,F,IPRN,DGAN,AF,IKP) TR 39

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      Y3=YY+0.500*H*D2Y TR 41
C*** UPDATE DERIVATIVE AT INTERVAL MIDPOINT TR 42
      CALL FF(IX+0.500*H,Y3,DY3,F,IPRN,DGAN,AF,IKP) TR 43
C*** APPLY CORRECTIVE PROCEDURE FOR RUNGE KUTTA TR 44
      IF (DABS(DY2-DY1).LT.1.0D-15) GO TO 5 TR 45
      P=-2.000*(DY3-DY2)/(DY2-DY1)/H TR 46
      IF ((P*H).LT.1.0D-04) GO TO 5 TR 47
C*** COMPUTE 'STIFF-EQUATION' F COEFFICIENTS TR 48
      F0=0.000 TR 49
      IF ((1-P*H).LT.174.67300.AND.(-P*H).GT.-180.21800) F0=DEXP(-P*H) TR 50
      F1=-(F0-1.000)/P/H TR 51
      F2=-(F1-1.000)/P/H TR 52
      F3=-(F2-0.500)/P/H TR 53
      Y4=YY+H*(2.000*DY3+F2*D2Y*(F1-2.000*F2)+DY2*P*H*F2) TR 54
      AF=1.000 TR 55
      IKP=0 TR 56
      GO TO 6 TR 57
C*** SET F COEFFICIENTS TO STANDARD ADAMS-BASHFORTH F COEFFICIENTS TR 58
      5 F1=1.000 TR 59
      F2=0.500 TR 60
      F3=1.6666666666666667D-1 TR 61
      P=0.000 TR 62
      Y4=YY+H*DY3 TR 63
      AF=1.000 TR 64
      IKF=0 TR 65
C*** COMPUTE DERIVATIVE AT END OF INTERVAL TR 66
      6 CALL FF(IX+H,Y4,DY4,F,IPRN,DGAN,AF,IKP) TR 67
      B=-3.000*(DY4+P*Y1)+2.000*(DY2+P*Y2)+2.000*(DY3+P*Y3)-(DY4+P*Y4) TR 68
      C=4.000*((DY4+P*Y1)-(DY2+P*Y2)-(DY3+P*Y3)+(DY4+P*Y4)) TR 69
      YR=YY+H*(DY4+F1*B+F2*C+F3) TR 70
      IKF=1 TR 71
C*** UPDATE DERIVATIVE AT END OF INTERVAL BY CORRECTOR TR 72
      CALL FF(IX+H,YR,DYR,F,IPRN,DGAN,AF,IKP) TR 73
      IKP=0 TR 74
      GO TO 14 TR 75
      7 IF (IPRN.NE.0) GO TO 9 TR 76
      DO 8 I=1,6 TR 77
        Y(I)=Y(I+1) TR 78
        DY(I)=DY(I+1) TR 79
      8 X(I)=X(I+1) TR 80
      X(7)=X(6)*H TR 81
C*** CALL PREDICTOR TO PREDICT Y AT NEXT POINT TR 82
      9 DO 10 I=1,6 TR 83
        10 CALL PHICEF(I) TR 84
      K=7 TR 85
      LK=LK+1 TR 86
      PRDCT=Y(1)+PHIDER(6,X(7),-1,1,0)-PHIDER(6,X(1),-1,1,0) TR 87
C*** USING PREDICTED Y, COMPUTE ITS DERIVATIVE TR 88
      AF=1.000 TR 89
      IKP=0 TR 90
      CALL FF(X(7),PRDCT,DYP,F,IPRN,DGAN,AF,IKP) TR 91
      DY(7)=DYP TR 92
      CALL PHICEF(7) TR 93
C*** GENERATE COEFFICIENTS NECESSARY FOR 'STIFF-EQUATION' CORRECTOR TR 94
      CALL PCF TR 95
C*** TEST FOR SUITABLE CORRECTOR TR 96
      IF ((P*H).LT.1.0D-02) GO TO 12 TR 97
      IF ((P*H).GT.22.000) ICKP=ICKP+1 TR 98
      IF ((P*H).GT.22.000) WRITE (JWRITE,11) TR 99
      11 FORMAT (2X,20(' '),P*H > 22.0') TR 100

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C*** CORRECT Y BY 'STIFF-EQUATION' CORRECTOR
CALL PMETH
GO TO 13
C*** CORRECT Y BY MODIFIED TREANOR CORRECTOR
12 Y(7)=Y(1)+PHIDER(7,X(7),-1,1,0)-PHIDER(7,X(1),-1,1,0)
13 YR=Y(7)
C*** COMPUTE 1ST DERIVATIVE OF FLIGHT PATH ANGLE
AP=1.000
IKP=1
CALL PP(X(7),YR,DYR,F,IPRH,DGAM,AP,IKP)
DY(7)=DYR
C*** COMPUTE 2ND DERIVATIVE OF FLIGHT PATH ANGLE
D3Y=PHIDER(7,X(7),1,1,0)
C*** COMPUTE 3RD DERIVATIVE OF FLIGHT PATH ANGLE
D4Y=PHIDER(7,X(7),2,1,0)
C*** TEST FOR POSSIBLE ERRORS
IF (IR.RE.0) RETURN
14 IF (DABS(DGAM).LT.1.0D-16) KK=1
IF (IPRH.NE.IK.AND.KK.EQ.0) GO TO 18
IF (LK.EQ.7) GO TO 17
IF (LK.GT.7) GO TO 16
DO 15 I=1,6
Y(I)=Y(I+1)
DI(I)=DI(I+1)
15 X(I)=X(I+1)
X(7)=X(6)+H
16 Y(7)=YR
DI(7)=DYR
IF (K.EQ.6) GO TO 9
17 YI=Y(7)
D2Y=DI(7)
XI=X(7)
18 RETURN
END

```

```

SUBROUTINE WSUB(N,P,TH,WM,JWRITE)
C
C*** SUBROUTINE WSUB FITS THE WEIGHT TIME HISTORY WITH A TRIGONOMETRIC
C*** POLYNOMIAL AND CHECKS ITS DERIVATIVE FOR DECREASING WEIGHT
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION P(N),TH(N),WM(N),C(450,9),X(450,1),WK(250)
C
C*** INITIALIZE PARAMETERS
PI=3.141592653589793D0
TT=TH(N)
IT=PI/TT
C*** FORM LEAST-SQUARES COEFFICIENTS
DO 1 J=1,N
TEMP=P(J)-P(1)
WT=1.000
IF (J.EQ.1.OR.J.EQ.N) WT=N*N*N
T=TH(J)
TX=T/TT*PI
C(J,1)=WT*Y
C(J,2)=WT*DCOS(TX)
C(J,3)=WT*DSIN(TX)
C(J,4)=WT*DCOS(2.0*TX)

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TR 101
TR 102
TR 103
TR 104
TR 105
TR 106
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TR 131
TR 132
TR 133
TR 134

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WS 1
WS 2
WS 3
WS 4
WS 5
WS 6
WS 7
WS 8
WS 9
WS 10
WS 11
WS 12
WS 13
WS 14
WS 15
WS 16
WS 17
WS 18
WS 19
WS 20
WS 21
WS 22
WS 23

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C(J,5)=WT*DSIN(2.0*TX)
C(J,6)=WT*DCOS(3.0*TX)
C(J,7)=WT*DSIN(3.0*TX)
C(J,8)=WT*DCOS(4.0*TX)
C(J,9)=WT*DSIN(4.0*TX)
1 X(J,1)=WT*TEMP
C*** ENACT LEAST SQUARES
CALL LLSQAR(C,X,N,9,1,450,450,15,WK,IER,JWRITE)
DO 2 J=1,N
T=TH(J)
TX=T/TT*PI
C*** COMPUTE AND CHECK WEIGHT DERIVATIVE
WD=X(1,1)-X(2,1)*XT*DSIN(TX)+X(3,1)*XT*DCOS(TX)-X(4,1)*2.0*XT*DSIN(TX)
1(2.0*TX)+X(5,1)*2.0*XT*DCOS(2.0*TX)-X(6,1)*3.0*XT*DSIN(3.0*TX)+X(7,1)*3.0*XT*DCOS(3.0*TX)-X(8,1)*4.0*XT*DSIN(4.0*TX)+X(9,1)*4.0*XT*DCOS(4.0*TX)
1COS(4.0*TX)
IF (WD.GE.0.0D0) GO TO 3
C*** COMPUTE FITTED WEIGHT
WT=X(1,1)+X(2,1)*DCOS(TX)+X(3,1)*DSIN(TX)+X(4,1)*DCOS(2.0*TX)+X(5,1)*DSIN(2.0*TX)+X(6,1)*DCOS(3.0*TX)+X(7,1)*DSIN(3.0*TX)+X(8,1)*DCOS(4.0*TX)+X(9,1)*DSIN(4.0*TX)
WM(J)=WT*P(1)
2 CC=WT*WT
GO TO 7
3 WRITE(JWRITE,4)
4 FORMAT(1X,/,10X,'WEIGHT DERIVATIVE FOUND TO BE > OR = ZERO.',/)
C*** REDUCE POLYNOMIAL TO FIRST ORDER IF WEIGHT DERIVATIVE IS FOUND POSITIVE
DO 5 J=1,N
TEMP=P(J)-P(1)
WT=1.000
IF (J.EQ.1.OR.J.EQ.N) WT=N*N*N
C(J,1)=WT*TH(J)
C(J,2)=WT
5 X(J,1)=WT*TEMP
CALL LLSQAR(C,X,2,1,450,450,15,WK,IER,JWRITE)
DO 6 J=1,N
WM(J)=X(1,1)*TH(J)+X(2,1)*P(1)
7 RETURN
END

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```

SUBROUTINE ADJUST(C,CC,CX,X,DSCALE,LLOC,NLOC,IP,NEQ)
C
C*** SUBROUTINE ADJUST ADJUSTS MATRICES DUE TO SUBROUTINE HPATH'S
C*** COEFFICIENT FREEZING
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION C(13,13),CC(13,1),CX(14),X(13),LLOC(13),NLOC(13),LOC(13)
1,D(13,13),DSCALE(13)
C
C*** MODIFY CC-MATRIX AND DETERMINE LOCATIONS OF FROZEN COEFFICIENTS
N=0
DO 2 JXP=1,NEQ
IF (CX(JXP).EQ.0.000D0.OR.LLOC(JXP).NE.0) GO TO 2
N=N+1
LOC(N)=0
IF (NLOC(JXP).EQ.0) GO TO 2
LOC(N)=1

```

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WS 24
WS 25
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WS 58
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WS 60
WS 61
WS 62
WS 63
AT 1
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AT 17

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DO 1 L=1,IP
1 CC(L,1)=CC(L,1)-C(H,L)*X(H)*DSCLB(H)
2 CONTINUE
C*** UPDATE MATRICES
LI=0
DO 4 I=1,IP
IF (LOC(I).EQ.1) GO TO 4
LI=LI+1
LN=0
DO 3 J=1,IP
IF (LOC(J).EQ.1) GO TO 3
LN=LN+1
D(LY,LI)=C(I,J)
3 CONTINUE
4 CC(LI,1)=CC(LI,1)
C*** DEFINE NEW UPDATED MATRIX
IP=LI
DO 5 I=1,IP
DO 5 J=1,IP
5 C(J,I)=D(J,I)
RETURN
END

```

```

SUBROUTINE PCRF
C
C*** SUBROUTINE PCRF CALCULATES THE COEFFICIENTS FOR THE 'STIFF-
EQUATION' CORRECTOR
C
IMPLICIT REAL*8(A-Z)
REAL*8 TOL/1.0D-2/
COMMON /PCRF/DY0,DY1,DY2,DY3,DY4,DY5,DY6,X0,X1,X2,X3,X4,X5,X6,Y0,Y1
1,Y2,Y3,Y4,Y5,Y6
COMMON /CRCORF/P,A0,A1,A2,A3,A4,A5,H
C
C*** DEFINE DIFFERENCES
T(X)=X-X0
W(X)=Y-Y0
V(DY)=DY-DY0
C*** CALCULATE X-DIFFERENCES
X0=T(X0)
X1=T(X1)
X2=T(X2)
X3=T(X3)
X4=T(X4)
X5=T(X5)
X6=T(X6)
C*** CALCULATE Y-DIFFERENCES RELATIVE TO Y0
Y0=W(Y0)
Y1=W(Y1)
Y2=W(Y2)
Y3=W(Y3)
Y4=W(Y4)
Y5=W(Y5)
Y6=W(Y6)
C*** CALCULATE DY-DIFFERENCES RELATIVE TO DY0
DY0=V(DY0)
DY1=V(DY1)

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AT 38
AT 39
AT 40

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V2=V(DY2)
V3=V(DY3)
V4=V(DY4)
V5=V(DY5)
V6=V(DY6)
C*** EQUATION 1
H0=V1/T1
H2=-T1
H3=H2*T1
H4=H3*T1
H5=H4*T1
H6=H5/T1
C*** EQUATION 2
C0=(V2-T2*H0)/C
C3=-(T2*(H3+T2*T2))/C
C4=-(T2*(H4+T2*T2))/C
C5=-(T2*(H5+T2*T2))/C
C6=-(T2*(H6+T2*T2))/C
C*** UPDATE EQUATION 2
D0=H2*C0+H0
D3=H2*C3+H3
D4=H2*C4+H4
D5=H2*C5+H5
D6=H2*C6+H6
C*** EQUATION 3
E0=(V3-(T3*(D0+T3*C0)))/E
E4=-(T3*(D4+T3*(C4+T3*T3)))/E
E5=-(T3*(D5+T3*(C5+T3*T3)))/E
E6=(V3-T3*(D6+T3*C6))/E
C*** UPDATE EQUATION 3
F0=D3+E0+D0
F4=D3+E4+D4
F5=D3+E5+D5
F6=D3+E6+D6
G0=C3+E0+C0
G4=C3+E4+C4
G5=C3+E5+C5
G6=C3+E6+C6
C*** EQUATION 4
H=T4*(F4+T4*(G4+T4*(E4+T4)))
H0=(V4-(T4*(F0+T4*(G0+T4*E0)))/H
H5=-(T4*(F5+T4*(G5+T4*(E5+T4*E4)))/H
H6=(V4-(T4*(F6+T4*(G6+T4*E6)))/H
C*** UPDATE EQUATION 4
I0=F4+H0+F0
I5=F4+H5+F5
I6=F4+H6+F6
J0=G4+H0+G0
J5=G4+H5+G5
J6=G4+H6+G6
K0=H4+H0+E0
K5=H4+H5+E5
K6=H4+H6+E6
C*** EQUATION 5
L=T5*(I5+T5*(J5+T5*(K5+T5*(H5+T5))))
L0=(V5-(T5*(I0+T5*(J0+T5*(K0+T5*E0)))/L
L6=(V5-(T5*(I6+T5*(J6+T5*(K6+T5*E6)))/L
C*** UPDATE EQUATION 5

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PC 94

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C      IF (N.LT.1.OR.N.GT.7) GO TO 9
C***  TRANSLATE
      SVE=X(1)
      DO 1 I=1,N
1     X(I)=X(I)-SVE
      XX=XX-SVE
2     IF (ICF1.GT.ICF2) GO TO 3
      CALL PHICF1(ICF1)
      ICF1=ICF1+1
      GO TO 2
3     PHIDER=0D0
      I=I+1
      IF (I.LT.1) I=1
4     IF (I.GT.N) GO TO 6
      S=1D0
      CFT=0D0
      J2=I-K
      IF (J2.GT.1) J2=1
      DO 5 J=1,J2
      CFT=CFT+S*DFACT(I-J+1)/DFACT(I-J-K+1)*C(I,J)*(XX*(I-J-K))
5     S=-S
      PHIDER=PHIDER+A(I)*CFT
      I=I+1
      GO TO 4
C***  RESET
6     XX=XX+SVE
      DO 7 I=1,N
7     X(I)=X(I)+SVE
8     RETURN
9     IERR=1
      WRITE (JWRITE,10) N
10    FORMAT (1H '*** PHIDER ERROR: N=',I11, ' BUT 1<=N<=7 REQUIRED')
      GO TO 8
      END

```

```

SUBROUTINE PRETH
C***  SUBROUTINE PRETH PRODUCES A CORRECTED VALUE OF Y(N+1)
C      IMPLICIT REAL*8(A-Z)
      COMMON /CRCOEP/8,A0,A1,A2,A3,A4,A5,H
      COMMON /PCR/DY0,DY1,DY2,DY3,DY4,DY5,DY6,X0,X1,X2,X3,X4,X5,X6,Y0,Y1,
1,Y2,Y3,Y4,Y5,Y6
C      PH=P*H
C***  COMPUTE THE TREANOR F-VALUES
      F0=0.0D0
      IF ((-PH).LT.174.673D0.AND.(-PH).GT.-1D0.21D0) F6=DEXP(-PH)
      F1=(F0-1D0)/(-PH)
      F2=(F1-1D0)/(-PH)
      F3=(F2-(1D0/2D0))/(-PH)
      F4=(F3-(1D0/6D0))/(-PH)
      F5=(F4-(1D0/24D0))/(-PH)
      F6=(F5-(1D0/120D0))/(-PH)
C***  COMPUTE A CORRECTED VALUE OF Y(N+1)
      Y6=Y0+H*(A0+F1*H*(A1+F2*H*(2D0+A2*F3+H*(6D0+A3*F4+H*(24D0+A4*F5+H*
1120D0+A5*F6))))

```

```

RETURN
END

```

```

SUBROUTINE LOC(I,J,IX,IN,N,NS)
C***  SUBROUTINE LOC COMPUTES A VECTOR SUBSCRIPT FOR AN ELEMENT IN A
C***  MATRIX OF SPECIFIED STORAGE MODE
C      IX=I
      L=J
      IF (NS-1) 1,2,5
1     IX=IX*(L-1)+IX
      GO TO 7
2     IF (IX-L) 3,4,4
3     IX=IX+(L*L-L)/2
      GO TO 7
4     IX=L+(IX*IX-IX)/2
      GO TO 7
5     IX=0
      IF (IX-L) 7,6,7
6     IX=IX
7     IN=IX
      RETURN
      END

```

```

SUBROUTINE NATA(A,R,N,N,NS)
C***  SUBROUTINE NATA PREMULTIPLIES A MATRIX BY ITS TRANSPOSE TO FORM
C***  A SYMMETRIC MATRIX
C      IMPLICIT REAL*8(A-H,O-Z)
      DIMENSION A(1),R(1)
C      DO 6 K=1,N
      NX=(K*K-K)/2
      DO 6 J=1,N
      IF (J-K) 1,1,6
1     IX=J+KX
      R(IX)=0.0D0
      DO 6 I=1,N
      IF (NS) 2,4,2
2     CALL LOC(I,J,IA,N,N,NS)
      CALL LOC(I,K,IB,N,N,NS)
      IF (IA) 3,6,3
3     IF (IB) 5,6,5
4     IX=NX*(J-1)+I
      IX=NX*(K-1)+I
5     R(IX)=R(IX)+A(IA)*A(IB)
6     CONTINUE
      RETURN
      END

```

```

SUBROUTINE NADD(A,B,R,N,N,NSA,NSB)
C

```

C*** SUBROUTINE MADE ADDS TWO MATRICES ELEMENT BY ELEMENT TO FORM
C*** RESULTANT MATRIX

C
IMPLICIT REAL*8(A-N,O-Z)
DIMENSION A(1),B(1),R(1)

C*** DETERMINE STORAGE MODE OF OUTPUT MATRIX
IF (NSA-NSB) 2,1,2

1 CALL LOC(N,M,NS,M,N,NSA)

GO TO 13

2 MTEST=NSA*NSB

NSR=0

IF (MTEST) 4,4,3

3 NSR=1

4 IF (MTEST-2) 6,6,5

5 NSR=2

C*** LOCATE ELEMENTS AND PERFORM ADDITIONS

6 DO 12 J=1,M

DO 12 I=1,N

CALL LOC(I,J,IJB,N,M,NSB)

IF (IJB) 7,12,7

7 CALL LOC(I,J,IJA,N,M,NSA)

REL=0.0

IF (IJA) 8,9,8

8 REL=A(IJA)

9 CALL LOC(I,J,IJB,N,M,NSB)

REL=0.0

IF (IJB) 10,11,10

10 REL=B(IJB)

11 R(IJB)=REL+REL

12 CONTINUE

RETURN

C*** ADD MATRICES OF LIKE-STORAGE MODE

13 DO 14 I=1,M

14 R(I)=A(I)+B(I)

RETURN

END

SUBROUTINE GANK(K)

C*** SUBROUTINE GANK CALCULATES A BIAS AND GAIN CORRECTION FOR VALUES
C*** OF PITCH ANGLE

C
IMPLICIT REAL*8(A-N,O-Z)

COMMON TIRE(450),F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F

17(450),F8(450),F9(450),F10(450),F11(450),F12(450),F13(450),F14(450)

1),C(450,11),X(450,1),WKAR(250),CFH(10),SGN(4),SGD(4),FT1(450),FT2(

450),PWR(450),CL(450),XX(450),X1(450),X2(450),EXT,EX2,EX3,EX4,C,S

1,RHO,TIA,EXPX,PLOW,PHIGH,CDLOW,CDHIGH,JREAD,JWRITE,JPUNCH,IEK1,IEK

2,IEK3,IEK4,METRIC,L1,L2,IEQNM(18),IERR

C*** FORM COEFFICIENTS FOR LEAST SQUARES

DO 1 I=1,K

C(I,1)=1.000

C(I,2)=F2(I)

1 X(I,1)=F6(I)+FT1(I)

C*** PERFORM LEAST SQUARES FOR GAIN AND BIAS

CALL LLSQAR(C,I,K,2,1,450,450,16,WKAR,IERR,JWRITE)

NA 3
NA 4
NA 5
NA 6
NA 7
NA 8
NA 9
NA 10
NA 11
NA 12
NA 13
NA 14
NA 15
NA 16
NA 17
NA 18
NA 19
NA 20
NA 21
NA 22
NA 23
NA 24
NA 25
NA 26
NA 27
NA 28
NA 29
NA 30
NA 31
NA 32
NA 33
NA 34
NA 35
NA 36
NA 37
NA 38
NA 39

IF (IERR.EQ.129) GO TO 2

GO TO 4

2 WRITE (JWRITE,3)

3 FORMAT (1X,////,10X,'ZERO MATRIX ENCOUNTERED IN SUBROUTINE GANK.

4 TO NEXT DATA SET. IF ANY.'//)

IERR=1

RETURN

4 WRITE (JWRITE,5) X(2,1),X(1,1)

5 FORMAT (1X,//,42X,50('-'//,42X,'1',48X,'1',42X,'1',42X,'1' PITCH-ANGLE G

1AIN = ',1PD18.11,9X,'1',42X,'1' PITCH-ANGLE BIAS = ',1PD18.11,'

IRADIAN 1',42X,'1',48X,'1',42X,50('-'//)

C*** PERFORM CORRECTIONS TO PITCH ANGLE VALUES

DO 6 I=1,K

6 F2(I)=X(2,1)*F2(I)+X(1,1)

RETURN

C ENTRY NPITCH(K)

C*** ENTRY NPITCH SOLVES FOR PITCH ANGLE BY NEWTON-RAPHSON

C INITIALIZE PARAMETERS

C CALL CHNGE(SGN)

C*** BEGIN SOLUTION LOOP

DO 9 I=1,K

IT=0

TS=F2(I)

T=TS

AN=DABS(F6(I))

C*** IF (F6(I).LT.0.000) CALL SIGNS(SGN,IEK1,IEK2,IEK3,IEK4)

COMPUTE POWER AND DRAG COEFFICIENT

PWR=CFH(1)*CFH(2)*F4(I)*EX1*CFH(3)*F4(I)*EX2*CFH(4)*F4(I)*EX3+C

1PH(5)*F4(I)*EX4

CD=CFH(6)*SGN(1)*CFH(7)*AN*EX1*SGN(2)*CFH(8)*AN*EX2*SGN(3)*CFH

1(9)*AN*EX3*SGN(4)*CFH(10)*AN*EX4

C*** IF (F6(I).LT.0.000) CALL CHNGE(SGN)

FORM NEWTON-RAPHSON EQUATIONS

7 TT=DCOS(F6(I)+TIA)*PWR/(F1(I)*F4(I))-(DSIN(T-F6(I))*F8(I)/G+F5(I)*

15*F4(I)*2*CD/(2.000*F1(I)))

TFE=-DCOS(T-F6(I))

IF (DABS(TFE).LT.1.0D-10) GO TO 8

IT=IT+1

TT=T+TFE/TFP

IF (DABS(TT-T).LT.1.0D-16.OR.IT.GE.40) GO TO 8

T=TT

GO TO 7

C*** ADJUST PITCH ANGLE

8 F2(I)=TS+0.333333D*(TS-T)

9 CONTINUE

RETURN

END

C SUBROUTINE LSD(X,Y,M,AL,N,BNS,LNET,IERR,JWRITE,RTN)

C*** SUBROUTINE LSD IS A MODIFICATION OF THE GENERAL LEAST-SQUARE-

C*** DISTANCE CURVE FITTING PROGRAM GIVEN IN THE FOLLOWING REFERENCE:

C*** A LEAST-SQUARE-DISTANCE CURVE-FITTING TECHNIQUE

C*** JOHN Q. HOWELL, NASA TN D-6374, JULY 1971

GP 21
GP 22
GP 23
GP 24
GP 25
GP 26
GP 27
GP 28
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GP 31
GP 32
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GP 67
GP 68
GP 69
GP 70

LD 1
LD 2
LD 3
LD 4
LD 5
LD 6
LD 7

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      IMPLICIT REAL*8(A-H,O-Z)
      DIMENSION A(4,4),AL(4),B(4,1),DIS(450),DYDAL(4,450),I(450),X(450),XX(450)
      1(450),Y(450),YI(450),SAL(4),NBAR(32),IPT(450)
      LD 8
C*** SET INITIAL PARAMETERS
      RANGE=0.0100
      NI=100
      RNSOLD=0.0500
      RNSOLD=0.000
      NTHP1=NTHP
      LD 9
C*** START ITERATION
      DO 30 ITER=1,NI
      LD 10
C*** FIND CLOSEST POINTS ON CURVE
      IFAIL=0
      DO 12 I=1,8
      LD 11
      W(I)=1.000
      LD 12
C*** OBTAIN INITIAL GUESS AT X-COORDINATE OF CLOSEST POINT
      (XI(I),YI(I)) ON CURVE TO DATA POINT (I(I),Y(I)), FROM THE
      LD 13
C*** INTERSECTION OF A PERPENDICULAR FROM THE DATA POINT WITH
      LD 14
C*** THE TANGENT TO THE CURVE AT THE POINT (X(I),Y(I)) WHERE
      LD 15
C*** THE CURVE EQUATION IS Y = F(X)
      CALL FUNCTHA(AL,X(I),F,DFDX,NTHP1)
      LD 16
      XI(I)=X(I)-(F-Y(I))*DFDX/(1.000+DFDX*DFDX)
      LD 17
C*** SEARCH ABOUT THIS POINT XI(I) FOR A SIGN CHANGE IN THE
      LD 18
C*** FUNCTION (F(X)-Y(I))*DFDX + (X-X(I))
      LD 19
      IF (XI(I).NE.0.000) GO TO 1
      LD 20
      YI(I)=F
      LD 21
      XI(I)=X(I)
      LD 22
      GO TO 11
      LD 23
      1 IF (I.NE.1) GO TO 2
      LD 24
      DXUPR=RANGE*(X(I+1)-X(I))
      LD 25
      DXLWR=RANGE*(X(I)-X(I-1))
      LD 26
      GO TO 3
      LD 27
      2 DXLWR=RANGE*(X(I)-X(I-1))
      LD 28
      DXUPR=DXLWR
      LD 29
      IF (I.NE.N) DXUPR=RANGE*(X(I+1)-X(I))
      LD 30
      3 XLWR=XI(I)
      LD 31
      XLUPR=XI(I)
      LD 32
      DO 5 J=1,100
      LD 33
      CALL FUNCTHA(AL,XLWR,FLWR,DPLWR,NTHP1)
      LD 34
      CALL FUNCTHA(AL,XUPR,FUPR,DFUPR,NTHP1)
      LD 35
      FUNLWR=(FLWR-Y(I))*DFLWR*(XLWR-X(I))
      LD 36
      FUNUPR=(FUPR-Y(I))*DFUPR*(XUPR-X(I))
      LD 37
      IF (FUNLWR*FUNUPR) 6,4,4
      LD 38
      4 XLWR=XLWR-DXUPR
      LD 39
      XUPR=XUPR+DXUPR
      LD 40
      IF (XLWR.LT.0.000) XLWR=0.000
      LD 41
      5 CONTINUE
      LD 42
      DIS(I)=0.000
      LD 43
      IFAIL=IFAIL+1
      LD 44
      IPT(IPAIL)=I
      LD 45
      W(I)=0.000
      LD 46
      GO TO 12
      LD 47
C*** SIGN CHANGE HAS BEEN FOUND. FIND ROOT BY METHOD OF FALSE
      LD 48
C*** POSITION.
      LD 49
      KOLD=0.000
      LD 50
      DO 9 J=1,100
      LD 51
      XROOT=(XLWR*FUNUPR-XUPR*FUNLWR)/(FUNUPR-FUNLWR)
      LD 52
      IF (DABS(1.000-XOLD/XROOT).LT.1.00-03) GO TO 10
      LD 53
      XOLD=XROOT
      LD 54
      LD 55
      LD 56
      LD 57
      LD 58
      LD 59
      LD 60
      LD 61
      LD 62
      LD 63
      LD 64
      LD 65
      LD 66
      LD 67

```

```

      CALL FUNCTHA(AL,XROOT,FROOT,DFROOT,NTHP1)
      LD 68
      FUNRT=(FROOT-Y(I))*DFROOT*(XROOT-X(I))
      LD 69
      IF (FUNLWR*FUNRT) 7,10,8
      LD 70
      7 FUNUPR=FUNRT
      LD 71
      XUPR=XROOT
      LD 72
      GO TO 9
      LD 73
      8 FUNLWR=FUNRT
      LD 74
      XLWR=XROOT
      LD 75
      9 CONTINUE
      LD 76
      DIS(I)=0.000
      LD 77
      IFAIL=IFAIL+1
      LD 78
      IPT(IPAIL)=I
      LD 79
      W(I)=0.000
      LD 80
      GO TO 12
      LD 81
C*** CLOSEST POINT FOUND, NOW FIND DISTANCE
      LD 82
      10 XI(I)=XROOT
      LD 83
      YI(I)=FROOT
      LD 84
      11 DX=XI(I)-X(I)
      LD 85
      DY=YI(I)-Y(I)
      LD 86
      DIS(I)=DSQRT(DX*DX+DY*DY)
      LD 87
      12 CONTINUE
      LD 88
      IF (IFAIL.NE.0) WRITE (JWRITE,13) ITER
      LD 89
      13 FORMAT (1X,/,24X,79HTHE SHORTEST DISTANCE COULD NOT BE FOUND FOR
      LD 90
      LD 91
      LD 92
      LD 93
      LD 94
      LD 95
      LD 96
      LD 97
      LD 98
      LD 99
      LD 100
      LD 101
      LD 102
      LD 103
      LD 104
      LD 105
      LD 106
      LD 107
      LD 108
      LD 109
      LD 110
      LD 111
      LD 112
      LD 113
      LD 114
      LD 115
      LD 116
      LD 117
      LD 118
      LD 119
      LD 120
      LD 121
      LD 122
      LD 123
      LD 124
      LD 125
      LD 126
      LD 127

```

```

19 CALL FUNCTNA(AL,IX(I),F,DF,HTMP1)
IF (DF.EQ.0.000) GO TO 20
DYDAL(K,I)=DSQRT(1.000/(1.000+1.000/DF/DF))*DYDAL(K,I)
GO TO 21
20 DYDAL(K,I)=0.000
21 CONTINUE
DO 24 K=1,N
DO 23 J=K,N
A(K,J)=0.000
DO 22 I=1,N
22 A(K,J)=A(K,J)+DYDAL(K,I)*DYDAL(J,I)
23 A(J,K)=A(K,J)
24 CONTINUE
C*** INCREASE STABILITY WITH DAMPING TECHNIQUE
T=0.000
DO 25 I=1,N
25 T=T+B(I,1)*B(I,1)
W=0.500*SQRT(1/T)
DO 26 I=1,N
26 A(I,I)=A(I,I)+0.500/W
C*** SOLVE THE LINEAR SIMULTANEOUS EQUATION FOR CORRECTIONS TO
C*** THE AL(I) AND GENERATE NEW AL(I)
CALL LLSQAB(A,B,N,N,1,4,4,16,NKAR,INR,JWRITE)
IF (INR.EQ.129) IERR=1
IF (IERR.NE.0) GO TO 32
AL(1)=AL(1)+B(1,1)
GO TO (27,28,29,29),HTMP1
27 AL(2)=AL(2)+B(2,1)
GO TO 30
28 AL(2)=AL(2)+B(2,1)
AL(3)=AL(3)+B(3,1)
AL(4)=AL(4)+B(4,1)
GO TO 30
29 AL(3)=AL(3)+B(3,1)
AL(4)=AL(4)+B(4,1)
30 CONTINUE
WRITE (JWRITE,31) B1,ERR
31 FORMAT (1X,9(' '),*AFTER*,14,' ITERATIONS (1.0 - RMS/RESOLD), THE
RELATIVE ERROR BETWEEN',1X,11,' TWO SUCCESSIVE VALUES OF RMS, STILL
1L EXCEEDS THE SPECIFIED ERROR PARAMETER =',D10.3)
RETURN
32 RMS=ERRS
DO 33 I=1,4
33 AL(I)=SAL(I)
34 RETURN
END
LD 128
LD 129
LD 130
LD 131
LD 132
LD 133
LD 134
LD 135
LD 136
LD 137
LD 138
LD 139
LD 140
LD 141
LD 142
LD 143
LD 144
LD 145
LD 146
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LD 158
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LD 162
LD 163
LD 164
LD 165
LD 166
LD 167
LD 168
LD 169
LD 170
LD 171
LD 172
LD 173

```

```

SUBROUTINE FUNCTNA(A,X,I,DYDI,HTMP1)
C
C*** SUBROUTINE FUNCTNA COMPUTES THE VALUE OF THE FITTED FUNCTION AND
C*** ITS X-DERIVATIVE
C
IMPLICIT REAL*8 (A-H,O-Z)
DIMENSION A(4),DYDA(4,N),X(N),Y(N)
C
GO TO (1,2,3,4),HTMP1
C*** CALCULATE FUNCTION VALUE AND ITS DERIVATIVE VALUE
1 Y=A(1)+A(2)*X

```

```

DYDI=A(2)
RETURN
C*** CHECK ARGUMENT FOR ERROR
2 IF (X.LE.0.000) GO TO 3
C*** CALCULATE FUNCTION VALUE AND ITS DERIVATIVE VALUE
Y=A(1)+A(2)*X+A(3)*X**A(4)
DYDI=A(2)+A(3)*A(4)*X**(A(4)-1.000)
RETURN
C*** SET FUNCTION VALUE AND ITS DERIVATIVE VALUE
3 Y=A(1)
DYDI=0.000
RETURN
C*** CHECK ARGUMENT FOR ERROR
4 IF (X.LE.0.000) GO TO 5
C*** CALCULATE FUNCTION VALUE AND ITS DERIVATIVE VALUE
Y=A(1)+A(3)*X**A(4)
DYDI=A(3)*A(4)*X**(A(4)-1.000)
RETURN
C*** SET FUNCTION VALUE AND ITS DERIVATIVE VALUE
5 Y=A(1)
DYDI=0.000
RETURN
END
FA 12
FA 13
FA 14
FA 15
FA 16
FA 17
FA 18
FA 19
FA 20
FA 21
FA 22
FA 23
FA 24
FA 25
FA 26
FA 27
FA 28
FA 29
FA 30
FA 31
FA 32
FA 33
FA 34

```

```

SUBROUTINE FUNCTNB(A,N,X,I,DYDA,HTMP1)
C
C*** SUBROUTINE FUNCTNB COMPUTES THE VALUE OF THE FITTED FUNCTION
C*** AND ITS PARTIAL DERIVATIVES WITH RESPECT TO THE COEFFICIENTS
C
IMPLICIT REAL*8 (A-H,O-Z)
DIMENSION A(4),DYDA(4,N),X(N),Y(N)
C
GO TO (1,3,3,6,6),HTMP1
C*** FOR NTH=0,1
1 DO 2 I=1,N
C*** CALCULATE PARTIAL DERIVATIVES
DYDA(1,I)=1.000
DYDA(2,I)=X(I)
2 Y(I)=A(1)+A(2)*X(I)
RETURN
C*** FOR NTH=2,3
3 DO 5 I=1,N
C*** CALCULATE PARTIAL DERIVATIVES
DYDA(1,I)=1.000
DYDA(2,I)=X(I)
C*** TEST ARGUMENT
IF (X(I).LE.0.000) GO TO 4
DYDA(3,I)=X(I)**A(4)
DYDA(4,I)=A(3)*X(I)**A(4)*DLOG(X(I))
C*** CALCULATE FUNCTION VALUE
Y(I)=A(1)+A(2)*X(I)+A(3)*X(I)**A(4)
GO TO 5
C*** SET PARTIAL DERIVATIVES AND FUNCTION TO SPECIFIED VARIABLES
4 DYDA(3,I)=0.000
DYDA(4,I)=0.000
Y(I)=A(1)
5 CONTINUE
RETURN
FA 1
FA 2
FA 3
FA 4
FA 5
FA 6
FA 7
FA 8
FA 9
FA 10
FA 11
FA 12
FA 13
FA 14
FA 15
FA 16
FA 17
FA 18
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FA 32
FA 33
FA 34

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C***	FOR BTH=4,5	PB	35
6	DO 8 I=1,N	PB	36
	DTDA(I,I)=1.000	PB	37
C***	TEST ARGUMENT	PB	38
	IF (I(I),LE,0.000) GO TO 7	PB	39
	DTDA(2,I)=X(I)**A(8)	PB	40
	DTDA(3,I)=A(3)*X(I)**A(4)*DLOG(I(I))	PB	41
C***	CALCULATE FUNCTION VALUE	PB	42
	Y(I)=A(1)+A(3)*X(I)**A(4)	PB	43
	GO TO 8	PB	44
7	DTDA(2,I)=0.000	PB	45
	DTDA(3,I)=0.000	PB	46
	Y(I)=A(1)	PB	47
8	CONTINUE	PB	48
	RETURN	PB	49
	END	PB	50

```

SUBROUTINE GDEQN(K,NHB,ICK)
C
C*** SUBROUTINE GDEQN SOLVES FOR POWER AND LIFT COEFFICIENTS BY USING
C*** EQUATION OF MOTION NORMAL TO FLIGHT PATH AND MODIFIES THE A PRIORI
C*** VALUES AND THEIR WEIGHTS, IF NEEDED
C
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION TS(8),LOC(8,10),COP(8),APWF(13,5)
COMMON TIME(450),F1(450),F2(450),F3(450),F4(450),F5(450),F6(450),F
17(450),F8(450),F9(450),F10(450),F11(450),F12(450),F13(450),F14(450)
19,C(450,1),X(450,1),WAKR(450),CFM(14),SGW(4),SGD(4),FTI(450),FT2(
1450),PURA(450),XI(450),CO(450),XI(450),X2(450),EX1,EX2,EX3,EX4,G,S
1,WHO,TIA,EXPF,FLOW,PHIGH,CLOW,CDHIGH,JBREAD,JWRITE,JPUNCH,IEX1,IEX
12,IEK3,IEK4,METRIC,1,1,L2,IECROW(10),IEER
COMMON /LABI/AP(13),WGT(13),CRMW(13),CRMV(13)
INTEGER IEQM(10)/4,5,5,5,5,5,6,6,6,6,6,6,5,5,6,6/
DATA LOC/1,6,7,8,0,0,0,0,1,2,6,7,8,0,0,0,1,2,6,7,8,0,0,0,1,2,6,7,8
1,0,0,0,1,3,6,7,8,0,0,0,1,3,6,7,8,0,0,0,1,3,6,7,8,0,0,0,1,2,3,6,7,8
1,0,0,1,2,3,6,7,8,0,0,1,2,3,6,7,8,0,0,1,3,4,6,7,8,0,0,0,1,3,4,6,7,8,0
1,0,1,3,4,6,7,8,0,0,1,6,7,8,0,0,0,1,2,6,7,8,0,0,0,1,3,6,7,8,0,0,0
1,1,2,3,6,7,8,0,0,1,3,4,6,7,8,0,0,0,0,APWF/1.000,1.000,1.000,1.000,1.0
100,1.000,1.000,1.000,1.000,1.000,1.000,1.000,2.00,2.1,0.00+0,2
1.00,1.2,00+4,1.00+0,1.00+0,1.00+0,1.00+0,1.00+0,1.00+0,1.00+0,1.00
1+0,1.00+3,2.00+3,1.00+0,2.00+2,2.00+3,1.00+0,1.00+0,1.00+0,1.00+0
11.00+0,1.00+0,1.00+0,1.00+0,1.00+3,2.00+4,1.00+0,2.00+3,2.00+2,1.0
10+0,1.00+0,1.00+0,1.00+0,1.00+0,1.00+0,1.00+0,1.00+0,1.00+4,2.00+5
1,1.00+0,2.00+3,2.00+1,1.00+0,1.00+0,1.00+0,1.00+0,1.00+0,1.00+0,1.
100+0,1.00+0,1.00+4/
C
IF (ICK.GT.1) GO TO 17
WRITE (JWRITE,1)
1 FORMAT (1X,///,51X,30HNORMAL-TO-FLIGHT-PATH SOLUTION,/)
WRITE (JWRITE,2)
2 FORMAT (28X,76('**'),/28X,'**',74X,'**')
C*** DETERMINE NUMBER OF UNKNOWNNS
NUN=IEQM(NHB)
DO 5 I=1,K
C*** DETERMINE GENERAL TERMS FOR MATRIX FORMULATION
TS(1)=DSIN(F6(I)*TIA)
TS(2)=TS(1)*F4(I)**EX1
TS(3)=TS(1)*F4(I)**EX2

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[illegible]

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C*** MODIFICATION TO THIRD-POWER-COEFFICIENT A PRIORI      GD 102
AP(3)=127.000*CFH(3)**2/(126.00*CFH(3)*COF(3))             GD 103
WGT(3)=AP(3)*AP(3)*200.000                                  GD 104
C*** MODIFICATION TO FOURTH-POWER-COEFFICIENT A PRIORI      GD 105
AP(4)=34.300*CFH(4)**2/(33.300*CFH(4)*COF(4))              GD 106
WGT(4)=AP(4)*AP(4)*2.00*07                                  GD 107
C*** MODIFICATION TO FIFTH-POWER-COEFFICIENT A PRIORI       GD 108
AP(5)=AP(5)                                                   GD 109
WGT(5)=WGT(5)                                                 GD 110
16 RETURN                                                     GD 111
C*** MODIFY A PRIORI WEIGHTS DUE TO TRAJECTORY PREDICTION ROUTINE'S GD 112
C*** ITERATION NUMBER                                         GD 113
17 DO 18 I=1,13                                               GD 114
IF (WGT(I).EQ.0.000) GO TO 18                                  GD 115
WGT(I)=AP(I)*AP(I)*APWF(I,ICK)                                GD 116
18 CONTINUE                                                    GD 117
RETURN                                                         GD 118
END                                                            GD 119

SUBROUTINE SIGNS(Y,X1,X2,X3,X4)                                SM 1
C                                                            SM 2
C*** SUBROUTINE SIGNS DETERMINES THE CORRECT SIGN ON TERMS IN SM 3
C*** COMPUTING THE DRAG COEFFICIENT EXPRESSION OR ITS DERIVATIVES IN SM 4
C*** RELATION TO ARGUMENT AND EXPONENTS                       SM 5
C                                                            SM 6
IMPLICIT REAL*8(A-H,O-Z)                                       SM 7
INTEGER*4 I1,X2,X3,X4                                          SM 8
DIMENSION Y(4),L(4)                                            SM 9
C                                                            SM 10
DO 1 I=1,4                                                      SM 11
1 Y(I)=1.000                                                    SM 12
L(I)=X1                                                         SM 13
L(2)=X2                                                         SM 14
L(3)=X3                                                         SM 15
L(4)=X4                                                         SM 16
DO 2 I=1,4                                                      SM 17
IF (((L(I)/2)*2).NE.L(I))Y(I)=-1.000                          SM 18
2 CONTINUE                                                       SM 19
RETURN                                                           SM 20
ENTRY CHNGE(Y)                                                  SM 21
DO 3 I=1,4                                                      SM 22
3 Y(I)=1.000                                                    SM 23
RETURN                                                           SM 24
END                                                            SM 25

SUBROUTINE LLSQAR(A,B,M,NA,NB,IA,IB,IDGT,WKAREA,IER,JWRITE)    LQ 1
C                                                            LQ 2
C*** SUBROUTINE LLSQAR PERFORMS A LEAST SQUARES SOLUTION OF A OVER- LQ 3
C*** DETERMINED SYSTEM OF LINEAR EQUATIONS                    LQ 4
C                                                            LQ 5
DIMENSION A(IA,1),B(IB,1),WKAREA(1)                           LQ 6
REAL*8 SUM                                                       LQ 7
REAL*8 A,B,WKAREA                                                LQ 8
C                                                            LQ 9
C*** INITIALIZE IER                                           LQ 10
IER=0                                                            LQ 11

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C*** FIND THE PSEUDO-INVERSE OF MATRIX A                     LQ 12
CALL LPSDOR(A,M,NA,IA,A,IDGT,WKAREA,IER,JWRITE)               LQ 13
IF (IER.NE.0) GO TO 5                                           LQ 14
C*** SOLVE THE EQUATION BY MULTIPLYING A-INVERSE AND B        LQ 15
DO 4 I=1,NB                                                      LQ 16
DO 2 J=1,NA                                                       LQ 17
CALL VIP2RO                                                      LQ 18
DO 1 K=1,M                                                         LQ 19
CALL VIPHUL(A(S,J),B(K,I))                                       LQ 20
1 CONTINUE                                                       LQ 21
CALL VIPSTO(SUM)                                                  LQ 22
WKAREA(J)=SUM                                                     LQ 23
2 CONTINUE                                                       LQ 24
C*** MOVE THE RESULTS INTO MATRIX B                            LQ 25
DO 3 J=1,NA                                                       LQ 26
B(J,I)=WKAREA(J)                                                  LQ 27
3 CONTINUE                                                       LQ 28
GO TO 6                                                           LQ 29
5 IER=129                                                         LQ 30
CALL UERTST(IER,SHLLSQAR,JWRITE)                                LQ 31
6 RETURN                                                         LQ 32
END                                                            LQ 33

SUBROUTINE LPSDOR(A,M,N,IA,AINV,IDGT,WKAREA,IER,JWRITE)        PI 1
C                                                            PI 2
C*** SUBROUTINE LPSDOR FIND THE PSEUDO-INVERSE OF A MATRIX   PI 3
C                                                            PI 4
DIMENSION A(IA,1),AINV(IA,1),WKAREA(M,1)                     PI 5
REAL*8 A,AINV,WKAREA,BIGA,ANN,ZERO,ETA                       PI 6
REAL*8 SUM,DETA                                                 PI 7
C                                                            PI 8
C*** INITIALIZE IER                                           PI 9
IER=0                                                            PI 10
NP1=N+1                                                         PI 11
NP2=N+2                                                         PI 12
NP3=N+3                                                         PI 13
C*** FIND THE LARGEST ELEMENT OF A                            PI 14
BIGA=0.00                                                       PI 15
DO 1 I=1,N                                                       PI 16
DO 1 II=1,N                                                       PI 17
IF (BIGA.GE.DABS(A(I,II))) GO TO 1                               PI 18
BIGA=DABS(A(I,II))                                               PI 19
1 CONTINUE                                                       PI 20
ANN=N*N                                                         PI 21
ETA=DSQRT(ANN)/(10.**IDGT)*BIGA                                  PI 22
C*** CALCULATE THE SINGULAR VALUE DECOMPOSITION OF A          PI 23
CALL LSVLDB(A,M,N,IA,N,1,WKAREA(1,N+4),WKAREA(1,NP1),AINV,WKAREA) PI 24
DO 2 I=1,N                                                       PI 25
2 WKAREA(I,NP2)=WKAREA(I,NP1)                                    PI 26
C*** SORT THE SINGULAR VALUES ARRAY INTO ASCENDING SEQUENCE BY ABSOLUTE PI 27
C*** VALUE                                                    PI 28
CALL VSORTH(WKAREA(1,NP2),N)                                     PI 29
DETA=ETA**2                                                      PI 30
CALL VIP2RO                                                       PI 31
C*** COMPARE SINGULAR VALUES AND ETA                         PI 32
DO 3 I=1,N                                                       PI 33
IP=I                                                             PI 34

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CALL VAPNUL(WKAREA(I,WP2),WKAREA(I,WP2))
CALL XFPSTO(SUN)
IF (SUN.GT.DETA) GO TO 4
3 CONTINUE
IER=129
GO TO 15
4 IP=IP-1
IF (IP.LE.0) GO TO 5
ZERO=0.D0
GO TO 6
5 ZERO=WKAREA(IP,WP2)
6 DO 10 I=1,N
  IF (WKAREA(I,WP1).LE.ZERO) GO TO 8
  DO 7 J=1,M
7 WKAREA(J,I)=WKAREA(J,I)/WKAREA(I,WP1)
  GO TO 10
C*** SET WKAREA(J,I)=0.0, FOR J=1,...,M, IF WKAREA(I,WP1).LE.ZERO
8 DO 9 J=1,M
9 WKAREA(J,I)=0.0
10 CONTINUE
DO 14 I=1,M
DO 12 J=1,M
CALL VXPZRO
DO 11 K=1,M
11 CALL VAPNUL(WKAREA(J,K),AINV(I,K))
CALL XFPSTO(SUN)
12 WKAREA(J,WP3)=SUN
C*** SOLVE THE RESULTS INTO MATRIX AINV
DO 13 J=1,M
13 AINV(I,J)=WKAREA(J,WP3)
14 CONTINUE
GO TO 16
15 CALL UERTST(IER,6HLPSSDOR,WRITE)
16 RETURN
END

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PI	69

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C      SUBROUTINE LSWALR(A,G,H,N,IA,IV,ISW,WKAREA,Q,U,V)
C***
C*** SUBROUTINE LSWALR DETERMINES THE SINGULAR VALUE DECOMPOSITION OF A
C*** MATRIX
C
C      DIMENSION A(IA,1),U(IA,1),V(IV,1),Q(1),WKAREA(1)
C      REAL*8A,WKAREA,Q,U,V,EPS,TOL
C      REAL*8F,G,H,X,Y,Z,C,S,BR,GR,DPS,OME,ZERO
C      DATA TOL/20D1000000000000000.,DPS/234100000000000000/,
C      DATA OME/1.0D0/,ZERO/0.0D0/
C
C      EPS=DPS
C      DO 1 I=1,M
C      DO 1 J=1,N
C      U(I,J)=A(I,J)
C      1 CONTINUE
C*** HOUSEHOLDER'S REDUCTION TO BIDIAGONAL FORM
C      X=0.0D0
C      G=0.0D0
C      DO 17 I=1,M
C      WKAREA(I)=G
C      CALL XYP2RQ

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SV	20
SV	21
SV	22

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L=I+1
DO 2 J=I,N
2 CALL VXPUL(U(J,I),U(J,I))
CALL VXPSTO(S)
IF (S.GE.TOL) GO TO 3
G=0.00
GO TO 7
3 F=U(I,I)
G=-DSQRT(S)
IF (F.LT.0.00) G=-G
H=F*G-S
HR=1.0/H
U(I,I)=F-G
IF (L.GT.N) GO TO 7
DO 6 J=L,N
CALL VXPZRO
DO 4 K=I,N
4 CALL VXPUL(U(K,I),U(K,I))
CALL VXPSTO(S)
F=S*HR
DO 5 K=I,N
5 U(K,I)=U(K,I)+F*U(K,I)
6 CONTINUE
7 Q(I)=G
CALL VXPZRO
IF (L.GT.N) GO TO 9
DO 8 J=L,N
8 CALL VXPUL(U(J,I),U(J,I))
CALL VXPSTO(S)
9 IF (S.GE.TOL) GO TO 10
G=0.00
GO TO 16
10 IF (I.LT.1) F=U(I,I+1)
G=-DSQRT(S)
IF (F.LT.0.00) G=-G
H=F*G-S
HR=1.0/H
IF (I.LT.N) U(I,I+1)=F-G
IF (L.GT.N) GO TO 12
DO 11 J=L,N
11 WKAREA(J)=U(I,J)*HR
12 IF (L.GT.N) GO TO 16
DO 15 J=L,N
CALL VXPZRO
IF (L.GT.N) GO TO 15
DO 13 K=L,N
13 CALL VXPUL(U(J,K),U(I,K))
CALL VXPSTO(S)
DO 14 K=L,N
14 U(J,K)=U(J,K)+S*WKAREA(K)
15 Y=DABS(Q(I))+DABS(WKAREA(I))
16 Y=GTAB(Q(I),Y)
17 IF (Y.GT.X) Y=X
17 CONTINUE
C*** ACCUMULATION OF RIGHT HAND T
IF (ISW.EQ.0) GO TO 37
DO 25 I=1,N
II=N-I+1
IF (G.EQ.0.00) GO TO 22
IF (L.GT.N) GO TO 24

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H=U(II,II+1)*G
NR=1.0/H
DO 18 J=L,N
18 V(J,II)=U(II,J)*NR
DO 21 J=L,N
CALL VXPZRO
DO 19 K=L,N
19 CALL VXPUL(U(II,K),V(K,J))
CALL VXPSTO(S)
DO 20 K=L,N
20 V(K,J)=V(K,J)+S*V(K,II)
21 CCNTINUE
22 IF (L.GT.N) GO TO 24
DO 23 J=L,N
V(J,II)=0.00
23 V(II,J)=0.00
24 V(II,II)=1.000
G=WKAREA(II)
25 L=II
C*** ACCUMULATION OF LEFT HAND TRANSFORMATIONS
DO 26 I=1,N
II=II+1
LL=II+1
G=Q(II)
IF (LL.GT.N) GO TO 27
DO 26 J=LL,N
26 U(II,J)=0.00
27 IF (G.EQ.0.00) GO TO 33
H=U(II,II)*G
NR=1.0/H
IF (LL.GT.N) GO TO 31
DO 30 J=LL,N
CALL VXPZRO
DO 28 K=LL,N
28 CALL VXPUL(U(K,II),U(K,J))
CALL VXPSTO(S)
F=S*NR
DO 29 K=II,H
29 U(K,J)=U(K,J)+F*U(K,II)
30 CCNTINUE
31 GR=1.0/G
DO 32 J=II,H
32 U(J,II)=U(J,II)*GR
GO TO 35
33 DO 34 J=II,H
34 U(J,II)=0.00
35 U(II,II)=U(II,II)+1.000
36 CCNTINUE
C*** DIAGONALIZATION OF THE BIDIAGONAL FORM
37 EPS=EPS*X
DO 57 K=1,N
KK=N-K+1
C*** TEST F SPLITTING
38 DO 39 L=1,KK
LL=KK-L+1
IF (DABS(WKAREA(LL)).LE.EPS) GO TO 45
IF (LL.EQ.1) GO TO 45
IF (DABS(Q(LL-1)).LE.EPS) GO TO 40
39 CONTINUE
C*** CANCELLATION OF WKAREA(L) IF LL.GT.1

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40 C=0.00
S=1.000
LI=LL-1
IF (KK.LT.LI) GO TO 45
DO 44 I=LI,KK
F=S*WKAREA(I)
WKAREA(I)=C*WKAREA(I)
IF (DABS(F).LE.EPS) GO TO 45
G=C(I)
Q(I)=DSQRT(F*F*G*G)
H=Q(I)
IF (H.NE.ZERO) GO TO 41
C=ZERO
S=ONE
GO TO 42
41 C=G/H
S=-F/H
42 IF (ISW.EQ.0) GO TO 44
DO 43 J=1,N
Y=U(J,LI)
Z=U(J,I)
U(J,LI)=Y*C+Z*S
43 U(J,I)=-Y*S+Z*C
44 CONTINUE
C*** TEST F CONVERGENCE
45 Z=Q(KK)
IF (LL.EQ.KK) GO TO 55
C*** SHIFT FROM BOTTOM 2X2 MINOR
X=Q(LL)
IF (KK.GT.1) Y=Q(KK-1)
IF (KK.GT.1) G=WKAREA(KK-1)
H=WKAREA(KK)
F=((Y-Z)*(Y+Z)+(G-H)*(G+H))/(2.00*H*Y)
G=DSQRT(F*F*ONE)
IF (F.LT.0.00) F=-((X-Z)*(X+Z)+H*(Y/(F-G)-H))/X
IF (F.GE.0.00) F=((X-Z)*(X+Z)+H*(Y/(F+G)-H))/X
C*** NEXT QR TRANSFORMATION
C=1.000
S=1.000
L2=LL+1
IF (KK.LT.L2) GO TO 54
DO 53 I=L2,KK
G=WKAREA(I)
Y=G(I)
H=S*G
G=C*G
Z=DSQRT(F*F*H*H)
WKAREA(I-1)=Z
IF (Z.NE.ZERO) GO TO 46
C=ZERO
S=ONE
GO TO 47
46 C=F/Z
S=H/Z
47 F=X*C*G*S
G=X*S*G*C
H=Y*G
Y=Y*G
IF (ISW.EQ.0) GO TO 49
DO 48 J=1,N

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	X=V(J,I-1)	SV	203
	Z=V(J,I)	SV	204
	V(J,I)=X+C+Z*S	SV	205
48	V(J,I)=X+S+Z*C	SV	206
49	Z=DSQRT(F*F+H*H)	SV	207
	Q(I-1)=Z	SV	208
	IF (Z.NE.ZERO) GO TO 50	SV	209
	C=ZERO	SV	210
	S=GNE	SV	211
	GO TO 51	SV	212
50	C=F/Z	SV	213
	S=H/Z	SV	214
51	F=C*G+S*Y	SV	215
	I=-S*G+C*Y	SV	216
	IF (ISW.EQ.O) GO TO 53	SV	217
	DO 52 J=1,N	SV	218
	Y=U(J,I-1)	SV	219
	Z=U(J,I)	SV	220
	U(J,I-1)=Y+C+Z*S	SV	221
52	U(J,I)=Y+S+Z*C	SV	222
53	CONTINUE	SV	223
54	WKAREA(LL)=ZERO	SV	224
	WKAREA(KK)=F	SV	225
	Q(KK)=I	SV	226
	GO TO 38	SV	227
C***	CONVERGENCE	SV	228
55	IF (Z.GE.ZERO) GO TO 57	SV	229
	Q(KK)=-Z	SV	230
	IF (ISW.EQ.O) GO TO 57	SV	231
	DO 56 J=1,M	SV	232
56	V(J,KK)=-V(J,KK)	SV	233
57	CONTINUE	SV	234
	RETURN	SV	235
	END	SV	236
	SUBROUTINE UERTST(IER,NAME,JWRITE)	UR	1
C		UR	2
C***	SUBROUTINE UERTST GENERATES ERROR MESSAGES	UR	3
C		UR	4
	DIMENSION ITRY(5,C),IBIT(4)	UR	5
	INTEGER*2 NAME(3)	UR	6
	COMMON WARN,WARN,TERR,JWRITE	UR	7
	EQUIVALENCE (IBIT(1),WARN),(IBIT(2),WARN),(IBIT(3),TERR)	UR	8
	DATA ITRY,'WARN','ING ',' ',' ',' ','WARN','ING(','WITH'	UR	9
	' FJL',')','TERR','INAL',' ',' ',' ','MON','DEFT','NE	UR	10
	ID ',' ',' ','/,IBIT/32,64,128,0/	UR	11
C		UR	12
	IER2=IER	UR	13
	IF (IER2.GE.WARN) GO TO 1	UR	14
C***	UNDEFINED	UR	15
	IER1=4	UR	16
	GO TO 4	UR	17
1	IF (IER2.LT.TERR) GO TO 2	UR	18
C***	TERMINAL	UR	19
	IER1=J	UR	20
	GO TO 4	UR	21
2	IF (IER2.LT.WARN) GO TO 3	UR	22
C***	WARNING (WITH FIX)	UR	23

	IER1=2	UN	24
	GO TO 4	UN	25
C***	WARNING	UN	26
3	IER1=1	UN	27
C***	EXTRACT 'M'	UN	28
4	IER2=IER2-1BIT(IER1)	UN	29
C***	PRINT ERROR MESSAGE	UN	30
	WRITE (JWRITE,5) ((ITUP(I,IER1),I=1,5),NAME,IER2,IER	UN	31
5	FORMAT (1X,/,1X,'ERROR MESSAGE FROM DERTST',2X,5A4,4X,3A2,4X,I2,2X	UN	32
	1,'IER= ',I3)	UN	33
	RETURN	UN	34
	END	UN	35
	SUBROUTINE VSORTA(A,LA)	VS	1
C		VS	2
C***	SUBROUTINE VSORTA SORTS ARRAYS BY ABSOLUTE VALUE	VS	3
C		VS	4
	DIMENSION A(1),IU(21),IL(21)	VS	5
	REAL*8A,T,II	VS	6
C		VS	7
C***	FIND ABSOLUTE VALUES OF ARRAY A	VS	8
	DO I=1,LA	VS	9
	IF (A(I)-LT.0.0)A(I)=-A(I)	VS	10
1	CONTINUE	VS	11
C		VS	12
	ENTRY VSORTA(A,LA)	VS	13
C		VS	14
C***	ENTRY VSORTA SORTS ARRAYS BY ALGEBRAIC VALUE	VS	15
C		VS	16
	M=1	VS	17
	I=1	VS	18
	J=LA	VS	19
	R=-.375	VS	20
2	IF (I.EQ.J) GO TO 11	VS	21
	IF (R.GT..5898437) GO TO 4	VS	22
	R=R+3.90625E-2	VS	23
	GO TO 5	VS	24
4	R=R-.21875	VS	25
5	K=I	VS	26
C***	SELECT A CENTRAL ELEMENT OF THE ARRAY AND SAVE IT IN LOCATION T	VS	27
	IJ=I+(J-I)*R	VS	28
	T=A(IJ)	VS	29
C***	IF FIRST ELEMENT OF ARRAY IS GREATER THAN T, INTERCHANGE WITH T	VS	30
	IF (A(I)-LT.T) GO TO 6	VS	31
	A(IJ)=A(I)	VS	32
	A(I)=T	VS	33
	T=A(IJ)	VS	34
6	L=J	VS	35
C***	IF LAST ELEMENT OF ARRAY IS LESS THAN T, INTERCHANGE WITH T	VS	36
	IF (A(J)-GT.T) GO TO 8	VS	37
	A(IJ)=A(J)	VS	38
	A(J)=T	VS	39
	T=A(IJ)	VS	40
C***	IF FIRST ELEMENT OF ARRAY IS GREATER THAN T, INTERCHANGE WITH T	VS	41
	IF (A(I)-LT.T) GO TO 8	VS	42
	A(IJ)=A(I)	VS	43
	A(I)=T	VS	44
	T=A(IJ)	VS	45


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IF (JX.GT.WMPI.OB-LEK.GT.WMPI) GO TO 133
IF (LEK.EQ.1) GO TO 5
DO 4 LL=1,NEQ
  CRRN(LL)=CRRN(LL)+1.0000018D0
  CRRN(LL)=CRRN(LL)/1.0000018D0
  4 WRITE (JWRITE,6) IXX
  6 FORMAT (1X,///,33X,65MF LIGHT PATH TRAJECTORY
  1 P R E D I C T I O N,///,59X,11METERATION 0,12,///,5X,TIME,7X,AL
  ITITUDE,5X,AIRSPED,4X,FLIGHT PATH,3X,ANGLE OF,7X,LIFT,9X,
  1'DRAG,8X,WEIGHT,8X,POWER,5X,ACCELERATION,///,44X,ANGLE,7X,
  1ATTACK,5X,CORFFICIENT,2X,CORFFICIENT,16X,AVAILABLE)
  IF (METRIC.NE.0) GO TO 8
  8 WRITE (JWRITE,7)
  7 FORMAT (4X,(SEC),5X,(FT),7X,(FT/SEC),5X,(RADIAN),5X,(RADI
  AN),33X,(LBF),5X,(FT-LBF/SEC),3X,(FT/SEC),/)
  GO TO 10
  8 WRITE (JWRITE,9)
  9 FORMAT (4X,(SEC),5X,(H),5X,(H/SEC),5X,(RADIAN),5X,(RADIAN
  1),32X,(NEWTONS),5X,(KW),5X,(H/SEC),/)
C*** INITIALIZE PARAMETERS
10 DO 11 LL=1,3
11 RRRR(LL)=0.0D0
  RCL=0
  LCR=0
  IPTS=99
  N=N+(N-1)*IPTS
  ICRP=0
  ADT=0.0D0
  DO 12 LL=1,13
  RNT(LL,1)=0.0D0
  RNT(LL,2)=0.0D0
  12 RR(5,LL)=0.0D0
  RPRINT=0
C*** CALCULATE MAXIMUMS FOR WEIGHTS
  IX(1)=F10(1)
  IX(2)=DABS(DARSIN(F11(1)/F4(1)))
  IX(3)=DABS(PT2(1))
  IX(4)=F1(1)
  IX(5)=F4(1)**2/(2.0D0*G)+F10(1)
  IX(6)=DABS(F6(1))
  DO 13 JXP=2,N
  IF (F10(JXP).GT.IX(1)) IX(1)=F10(JXP)
  IF (DABS(DARSIN(F11(JXP)/F4(JXP)).GT.IX(2)) IX(2)=DABS(DARSIN(F11
  1JXP)/F4(JXP))
  IF (DABS(PT2(JXP)).GT.IX(3)) IX(3)=DABS(PT2(JXP))
  IF (F1(JXP).GT.IX(4)) IX(4)=F1(JXP)
  IF ((F4(JXP)**2/(2.0D0*G)+F10(JXP)).GT.IX(5)) IX(5)=F4(JXP)**2/(2.0
  1D0*G)+F10(JXP)
  13 IF (DABS(F6(JXP)).GT.IX(6)) IX(6)=DABS(F6(JXP))
C*** CALCULATE WEIGHTS FOR LEAST SQUARES SOLUTION
DO 14 I=1,6
  14 D(I)=DF(I)/IX(I)**2
C*** EXACT SPLINE ON ANGLE OF ATTACK FOR ROOT ESTIMATIONS
CALL SPLINE(N,F6,TIME,AA,3)
C*** EXACT POLYNOMIAL FIT ROUTINE ON WEIGHT
CALL WSUB(N,F1,TIME,WB)
C*** SET INITIAL VALUES
TH(1)=TIME(1)
L=1
LC=1

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HP 75
HP 76
HP 77
HP 78
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HP 92
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HP 120
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HP 126
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HP 128
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HP 130
HP 131
HP 132
HP 133
HP 134

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I1=L
IIS=I1
J=0
ISHT=0
DO 15 JXP=1,6
  15 TOL(JXP)=0.0D0
C*** BEGIN ANALYSIS ON SET OF POINTS
DO 88 IPT=2,N
  IPTS=9
  IF (IPT.EQ.2) IPTS=32
  IF (ICRP.NE.0) IPTS=19
  N=1
  IF (IPTS.EQ.0) N=0
  ICRP=0
  IPTSP1=IPTS+1
  N=N-(99-IPTS)
  IF (IPT.LE.2) GO TO 16
  TS=TH(L-1)
  TTPT=TH(1)
  TH(1)=TH
  L=1
  I1=IIS
  16 DELT=(TIME(IPT)-TIME(IPT-1))/IPTSP1
C*** COMPUTE TIME POINTS BETWEEN INPUT TIME POINTS
DO 17 JX=1,IPTSP1
  L=L+1
  LC=LC+1
  17 TH(L)=TH(L-1)+DELT
  TH(L)=TIME(IPT)
  TTH=TH(L)
C*** DETERMINE INTERVAL RANGE
  I2=LC
  IIS=I2
  I4=I2-1
  IF (I2.EQ.N) I4=I2
C*** BEGIN ANALYSIS ON INTERVAL RANGE
DO 87 I=I1,I4
  IF (I.NE.1) AS=AF
  T=TH(I-1)+1
  V=VA(I)
  DV=DVA(I)
  IF (I.NE.1.AND.NPRINT.EQ.N) AT=A
  A=ALP(I)
  IF (I.NE.1) GO TO 18
C*** DETERMINE PARAMETERS FOR FIRST POINT
  N=F1(I)
  R=F5(I)
  GFPA=DARSIN(F11(I)/F4(I))
  GFPA=GFPA+TARE
  N=F10(I)+HTARE
  T1=0.0D0
  R1=R
  THT1=T-T1
  GO TO 20
C*** DETERMINE PREVIOUS TIME POINT VALUE
  18 IF (I.EQ.I1) T1=TS
  IF (I.NE.I1) T1=TH(I-1)
C*** DETERMINE VALUES AT PREVIOUS TIME POINT
  Z=T1
  V=VA(I)

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HP 135
HP 136
HP 137
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HP 193
HP 194

C-16

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DV=DVA(2) HP 195
V2=DDV(2) HP 196
V3=DDDV(2) HP 197
P=CFH(1)*CFH(2)*V**EX1*CFH(3)*V**EX2*CFH(4)*V**EX3*CFH(5)*V**EX4 HP 198
C*** COMPUTE WEIGHT DERIVATIVES HP 199
DU=-P*P HP 200
D2H=-P*DV*(EX1*CFH(2)*V**EX1-1.000)+EX2*CFH(3)*V**EX2-1.000)*EX3 HP 201
1*CFH(4)*V**EX3-1.000)+EX4*CFH(5)*V**EX4-1.000)) HP 202
D3H=-P*(DV**2*(EX1*CFH(2)*V**EX1-1.000)+EX2*CFH(3)*V**EX2-1.000)*V**EX3-1.000)+EX3*CFH(4)*V**EX3-1.000)+EX4*CFH(5)*V**EX4-1.000)+V2*(EX1*CFH(2)*V**EX1-1.000)+EX2*CFH(3)*V**EX2-1.000)+EX3*CFH(4)*V**EX3-1.000)+EX4*CFH(5)*V**EX4-1.000)) HP 203
D4H=-P*((EX1*CFH(2)*V**EX1-1.000)+EX2*CFH(3)*V**EX2-1.000)+EX3*CFH(4)*V**EX3-1.000)+EX4*CFH(5)*V**EX4-1.000)+V2*(EX1*CFH(2)*V**EX1-1.000)+EX3*CFH(4)*V**EX3-1.000)+EX4*CFH(5)*V**EX4-1.000)+V3*(EX1*CFH(2)*V**EX1-1.000)+EX2*CFH(3)*V**EX2-1.000)+EX3*CFH(4)*V**EX3-1.000)+EX4*CFH(5)*V**EX4-1.000)) HP 204
C*** TEST FOR PARAMETERS' UPDATE HP 205
THT1=T-T HP 206
IF (KPRINT.NE.N) GO TO 19 HP 207
HT=H HP 208
HT=H HP 209
FPA=GNX HP 210
DPCA=GNX HP 211
C*** ESTIMATE WEIGHT, ALTITUDE, AND DENSITY AT NEXT POINT HP 212
19 W=H*THT1*(DH*THT1*(D2H/2.000*THT1*(D3H/6.000*THT1*(D4H/24.000))) HP 213
DU=V*DSIN(GNX) HP 214
D2H=V*DSIN(GNX)*DCOS(GNX) HP 215
D3H=(V2-V*DGX*DGX)*DSIN(GNX)*(2.000*V*DGX*V*D2G)*DCOS(GNX) HP 216
D4H=(V3-3.000*V*DGX*D2G-3.000*V*DGX**2)*DSIN(GNX)*(3.000*V2*DG HP 217
THT1=V*DGX*(3.000*V*D2G+V*D3G)*DCOS(GNX) HP 218
IF (I.LE.7) D4H=0.000 HP 219
H=H*THT1*(DH*THT1*(D2H/2.000*THT1*(D3H/6.000*THT1*(D4H/24.000))) HP 220
R1=R HP 221
R=BHO*(1.000-6.86D-6)*.26D0 HP 222
V=VA(T) HP 223
DV=DVA(T) HP 224
C*** COMPUTE POWER HP 225
20 P=CFH(1)*CFH(2)*V**EX1*CFH(3)*V**EX2*CFH(4)*V**EX3*CFH(5)*V**EX4 HP 226
ICK=0 HP 227
C*** COMPUTE DRAG COEFFICIENT AND DERIVATIVES WRT ANGLE OF ATTACK HP 228
AH=DABS(A) HP 229
IF (A.GE.0.000) GO TO 22 HP 230
CALL SIGNS(SMN,IX1,IX2,IX3,IX4) HP 231
CALL SIGNS(SGD,IX1,IX2,IX3,IX4) HP 232
22 CD=CFH(6)*SMN(1)*CFH(7)*AH**IX1*SMN(2)*CFH(8)*AH**IX2*SMN(3)*CFH HP 233
1(9)*AH**IX3*SMN(4)*CFH(10)*AH**IX4 HP 234
CDP=SGM(1)*IX1*CFH(7)*AH**IX1*SGM(2)*IX2*CFH(8)*AH**IX2*SGM(3)*I HP 235
1EX3*CFH(9)*AH**IX3*SGM(4)*IX4*CFH(10)*AH**IX4 HP 236
CDGP=SGD(1)*IX1*IX3*CFH(7)*AH**IX1*SGD(2)*IX2*IX2*CFH(8)*AH**IX HP 237
1EX2*SGD(3)*IX3*IX3*CFH(9)*AH**IX3*SGD(4)*IX4*IX4*CFH(10)*AH**IX HP 238
IF (A.GE.0.000) GO TO 23 HP 239
CALL CHNGE(SMN) HP 240

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CALL CHNGE(SGD) HP 241
C*** PERFORM NEWTON-RAPHSON TO DETERMINE 'ESTIMATED' ANGLE OF ATTACK HP 242
23 FA=DCOS(A*TIA)*P/(H*V)*(H*S*V*V*CD/(2.000*H)+DV/G*DSIN(GFPA)) HP 243
FAP=-DSIN(A*TIA)*P/(H*V)*(H*S*V*V*CDP/(2.000*H)) HP 244
FAPP=-DCOS(A*TIA)*P/(H*V)*(H*S*V*V*CDGP/(2.000*H)) HP 245
RAD=(FAP/FAPP)*(FAP/FAPP)-2.000*(FA/FAPP) HP 246
A1=A HP 247
IF (RAD.LT.0.000) GO TO 25 HP 248
IF ((FAP/FAPP).LT.0.000) GO TO 24 HP 249
A=A-FAP/FAPP*DSQRT(RAD) HP 250
GO TO 26 HP 251
24 A=A-FAP/FAPP*DSQRT(RAD) HP 252
GO TO 26 HP 253
25 A=AS+0.2600*ADT*THT1 HP 254
ICH=ICH+1 HP 255
GO TO 27 HP 256
26 IF (DABS(A1-A).LT.1.0D-15.OR.ICK.EQ.20) GO TO 27 HP 257
GO TO 21 HP 258
C*** COMPUTE LIFT COEFFICIENT FOR 'ESTIMATED' ANGLE OF ATTACK HP 259
27 TDAPX=((I-I1)*F3(IPT)*(I-I1)*F3(IPT-1))/(I-I1) HP 260
GO TO (29,29,30),ICD HP 261
28 IF (A.GT.0.000) GO TO 29 HP 262
CL=CFH(12)*A*YCF*CFH(14)*TDAPX HP 263
GO TO 31 HP 264
29 CL=CFH(11)*CFH(12)*A*CFH(13)*A**EXPI*CFH(14)*TDAPX HP 265
GO TO 31 HP 266
30 CL=CFH(11)*CFH(12)*A*CFH(13)*A*A*CFH(14)*TDAPX HP 267
31 IF=1 HP 268
C*** WRITE OUT RESULTS HP 269
IF (KPRINT.NE.0) GO TO 34 HP 270
IF (METRIC.NE.0) GO TO 33 HP 271
WRITE (JWRITE,32) T,H,V,GFPA,A,CL,CD,W,P,DV HP 272
32 FORMAT (1X,10(1PD12.5,1X)) HP 273
GO TO 34 HP 274
33 ALT=H*0.3048D0 HP 275
VX=V*0.3048D0 HP 276
WY=W*4.4482D0 HP 277
PX=P*1.355818D-3 HP 278
DVH=DV*0.3048D0 HP 279
WRITE (JWRITE,32) T,ALT,VX,GFPA,A,CL,CD,WX,PX,DVH HP 280
C*** CALCULATE TIME INCREMENT HP 281
34 IF (I.LT.K) TDRL=TH*(I-I1+1)-TH*(I-I1+1) HP 282
C*** SET FLIGHT PATH ANGLE HP 283
GNX=GFPA HP 284
IF (I.NE.1) GO TO 35 HP 285
C*** SET FLIGHT-PATH-ANGLE DERIVATIVE FOR FIRST POINT HP 286
DGPPA=G*S*R*V*CL/(2.000*H)-G*DCOS(GNX)/V*G*DSIN(A*TIA)*P/(H*V*V) HP 287
D2G=0.000 HP 288
D3G=0.000 HP 289
C*** SET OR DETERMINE PARAMETERS FOR TRAJECTORY PREDICTION HP 290
35 IF (I.NE.1) DGMT=DGNX HP 291
DGNX=DGPPA HP 292
D2GN=D2G HP 293
D3GN=D3G HP 294
ADT=0.000 HP 295
IF (I.NE.1) ADT=(AF-AS)/THT1 HP 296
IPRM=0 HP 297
KK=0 HP 298
HGAN=GFPA HP 299

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NDGNN=DGPPA      MP 315
JL=0              MP 316
IK=10             MP 317
ST1=T1           MP 318
IJPL=0           MP 319
IF (I.LT.7) IK=0  MP 320
C*** CALL TRAJECTORY PREDICTION ROUTINE MP 321
IF (I.LT.K) CALL TRXNR(TDEL,T,GPPA,DGPPA,D2G,D3G,ISST,F,IPRN,KK,I MP 322
1K)              MP 323
IERN=IERN        MP 324
IF (IERN.NE.0) RETURN MP 325
T=TH(I-1)+1      MP 326
T1=ST1           MP 327
IF (I.EQ.6) IK=10 MP 328
IF (I.LT.6) GO TO 37 MP 329
C*** ITERATE TRAJECTORY PREDICTION FOR BETTER ESTIMATION MP 330
DO 36 JPL=1,IK   MP 331
IPRN=IPRN+1      MP 332
IJPL=JPL         MP 333
GPPA=HGAP        MP 334
IF (I.LT.K) CALL TRXNR(TDEL,T,GPPA,DGPPA,D2G,D3G,ISST,F,IPRN,KK,I MP 335
1K)              MP 336
IERN=IERN        MP 337
IF (IERN.NE.0) RETURN MP 338
T=TH(I-1)+1      MP 339
T1=ST1           MP 340
IF (KK.EQ.1) GO TO 37 MP 341
36 CONTINUE      MP 342
37 KPRINT=KPRINT+1 MP 343
C*** TEST FOR INTERVAL RANGE END MP 344
IF (IPTS.NE.0.AND.KPRINT.EQ.IPTS) KPRINT=0 MP 345
C*** DEFINE VALUES FOR PARTIAL DERIVATIVE EVALUATIONS MP 346
T=TH(I-1)+1      MP 347
IF (I.EQ.7) GO TO 38 MP 348
D2GN=0.000       MP 349
IF (I.NE.1) D2GN=(DGNX-DGNY)/(T-T1) MP 350
D2G=D2GN         MP 351
38 ATX=A          MP 352
NTX=N            MP 353
BTX=B            MP 354
IF (I.NE.1) GO TO 41 MP 355
C*** INITIALIZE MATRICES MP 356
DO 39 JXP=1,NXD  MP 357
NR(JXP)=0.000    MP 358
NP(JXP)=0.000    MP 359
NQ(JXP)=0.000    MP 360
39 RS(JXP)=0.000  MP 361
DO 40 JXP=1,NXH  MP 362
CC(JXP)=0.000    MP 363
C*** TEST FOR FIRST POINT DIRECTION MP 364
41 IF (I.EQ.1) GO TO 71 MP 365
C*** TEST FOR PARTIAL DERIVATIVE DETERMINATION MP 366
IF (KPRINT.NE.1) GO TO 87 MP 367
C*** DEFINE SCALAR VALUES AT PRESENT AND PREVIOUS POINTS MP 368
J=J+1            MP 369
T1=TTT           MP 370
IF (I.EQ.K) T1=TH(1) MP 371
V=VA(T)          MP 372
V=VA(T1)         MP 373
DV=DVA(T1)       MP 374

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P=CFN(1)+CFN(2)*V**EX1+CFN(3)*V**EX2+CFN(4)*V**EX3+CFN(5)*V**EX4 MP 375
A=AT             MP 376
AN=DABS(A)       MP 377
TDAPX=((I-I3)*P3(IPT)+(I4-I)*P3(IPT-1))/(I4-I1) MP 378
GO TO (42,43,44),ICD MP 379
42 IF (A.GT.0.000) GO TO 43 MP 380
CL=CFN(12)*A+ICPT*CFN(14)*TDAPX MP 381
GO TO 45         MP 382
43 CL=CFN(11)+CFN(12)*A+CFN(13)*A**EXPC*CFN(14)*TDAPX MP 383
GO TO 45         MP 384
44 CL=CFN(11)+CFN(12)*A+CFN(13)*A**CFN(14)*TDAPX MP 385
45 IF (A.LT.0.000) CALL SIGNS(SNN,IE1,IE2,IE3,IE4) MP 386
CD=CFN(6)*SNN(1)+CFN(7)*A**IE1+SNN(2)*CFN(8)*A**IE2+SNN(3)*CFN MP 387
1(9)*A**IE3+SNN(4)*CFN(10)*A**IE4 MP 388
IF (A.LT.0.000) CALL CHNGE(SNN) MP 389
W=WT             MP 390
B=BT             MP 391
HDM=V*DSIN(FPA) MP 392
C*** FIND PARTIAL DERIVATIVES WRT ANGLE OF ATTACK MP 393
CALL PARTIAL(J,W,B,A,V,CV,HDM,FPA,DGPPA,PAC,RCH) MP 394
C*** COMPUTE NECESSARY FACTORS AND TERMS FOR DERIVATIVE EVALUATIONS MP 395
TBT1=T-T1        MP 396
X1=V**EX1        MP 397
X2=V**EX2        MP 398
X3=V**EX3        MP 399
X4=V**EX4        MP 400
X5=A**IE1        MP 401
X6=A**IE2        MP 402
X7=A**IE3        MP 403
X8=A**IE4        MP 404
X9=DCOS(A*TIA)/(W*V) MP 405
X10=D*V**V/(2.000*W) MP 406
X11=DV/G         MP 407
X12=X9*P-(X10*CD+X11) MP 408
X13=DSQRT(1.000-X12*X12) MP 409
X14=G*TBT1**2*X10/2.000 MP 410
X15=TBT1*DCOS(A*TIA)/W MP 411
X16=TBT1**2*D*V*X9/2.000 MP 412
X17=TBT1**2*G*DSIN(A*TIA)/(2.0*W*V) MP 413
X18=TBT1**2*G/4.000 MP 414
X19=-TBT1*V*X10  MP 415
X20=-TBT1**2*D*V*X10/2.000 MP 416
X21=G*DSIN(A*TIA)/(W*V*V) MP 417
X22=D*V*DDV(T1)/TBT1/3.000 MP 418
X23=D*V*DDV(T1)/3.000 MP 419
X24=-X13*X14     MP 420
X25=G*S*V*V/(2.000*W) MP 421
X26=X9*X9*X12/X13**3 MP 422
X27=X10*X10*X12/X13**3 MP 423
X28=X9*X10*X12/X13**3 MP 424
X29=-X14*X12/X13 MP 425
C*** INITIALIZE PARAMETERS MP 426
DO 46 JXP=1,10   MP 427
PS(JXP)=0.000   MP 428
JXX=0           MP 429
C*** COMPUTE PARTIAL DERIVATIVES MP 430
CTP(1)=-(X15*X16+(X13*X17+4.000*X18*X12*X9)-(X17*2)/X13*X12*X9) MP 431
CTP(2)=X9/X13   MP 432
CTP(3)=X21*G/V*X12*X9/X13 MP 433
CTP(4)=-(X19*X20-4.000*X18*X12*X10-2.000*X18*X10**2*CL*X12/X13*X17 MP 434

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10X12=X10*P/X13
CTP(5)=-X10/X13
CTP(6)=-G/V*X12*X10/X13
CTP(7)=0.000
DO 70 JPK=1,NEQ
IF (CFH(JPK).EQ.0.000.OR.JLOC(JPK).NE.0) GO TO 70
JJK=JJK+1
WK(2,JJK)=0.000
WK(4,JJK)=0.000
WK(6,JJK)=0.000
GO TO (47,49,51,53,55,57,59,61,63,65,67,69),JPK
C*** COMPUTE PARTIALS WRT FIRST POWER COEFFICIENT
47 DO 48 JXP=1,3
48 WK(JXP,JJK)=CTP(JXP)
WK(4,JJK)=P*TRT1
WK(5,JJK)=WK(5,JJK)+0.500*TRT1*(DCOS(ATX*TIA)/WTX+DCOS(A*TIA)/W)
PS(1)=CFH(1)*WK(5,JJK)
GO TO 70
C*** COMPUTE PARTIALS WRT SECOND POWER COEFFICIENT
49 DO 50 JL=1,3
50 WK(JL,JJK)=CTP(JL)*K1
WK(4,JJK)=P*(V*EX1*TRT1+TRT1**2/2.000*EX1*(X22*V***(EX1-1.000)+(EX1-1.000)*X23*V***(EX1-2.000)))
WK(5,JJK)=WK(5,JJK)+0.500*TRT1*(DCOS(ATX*TIA)*V*EX1/WTX+DCOS(A*TIA)*V*EX1/W)
PS(2)=CFH(2)*WK(5,JJK)
GO TO 70
C*** COMPUTE PARTIALS WRT THIRD POWER COEFFICIENT
51 DO 52 JL=1,3
52 WK(JL,JJK)=CTP(JL)*K2
WK(4,JJK)=P*(V*EX2*TRT1+TRT1**2/2.000*EX2*(X22*V***(EX2-1.000)+(EX2-1.000)*X23*V***(EX2-2.000)))
WK(5,JJK)=WK(5,JJK)+0.500*TRT1*(DCOS(ATX*TIA)*V*EX2/WTX+DCOS(A*TIA)*V*EX2/W)
PS(3)=CFH(3)*WK(5,JJK)
GO TO 70
C*** COMPUTE PARTIALS WRT FOURTH POWER COEFFICIENT
53 DO 54 JL=1,3
54 WK(JL,JJK)=CTP(JL)*K3
WK(4,JJK)=P*(V*EX3*TRT1+TRT1**2/2.000*EX3*(X22*V***(EX3-1.000)+(EX3-1.000)*X23*V***(EX3-2.000)))
WK(5,JJK)=WK(5,JJK)+0.500*TRT1*(DCOS(ATX*TIA)*V*EX3/WTX+DCOS(A*TIA)*V*EX3/W)
PS(4)=CFH(4)*WK(5,JJK)
GO TO 70
C*** COMPUTE PARTIALS WRT FIFTH POWER COEFFICIENT
55 DO 56 JL=1,3
56 WK(JL,JJK)=CTP(JL)*K4
WK(4,JJK)=P*(V*EX4*TRT1+TRT1**2/2.000*EX4*(X22*V***(EX4-1.000)+(EX4-1.000)*X23*V***(EX4-2.000)))
WK(5,JJK)=WK(5,JJK)+0.500*TRT1*(DCOS(ATX*TIA)*V*EX4/WTX+DCOS(A*TIA)*V*EX4/W)
PS(5)=CFH(5)*WK(5,JJK)
GO TO 70
C*** COMPUTE PARTIALS WRT FIRST DRAG COEFFICIENT
57 DO 58 JXP=1,4
58 WK(JXP,JJK)=CTP(JXP)*3
WK(5,JJK)=WK(5,JJK)-0.2500*TRT1*S*(RTX*V*P**3/WTX+R*V**3/W)
PS(6)=CFH(6)*WK(5,JJK)
WK(6,JJK)=PAC(1)

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GO TO 70
C*** COMPUTE PARTIALS WRT SECOND DRAG COEFFICIENT
59 DO 60 JL=1,4
60 WK(JL,JJK)=CTP(JL)*K5
WK(5,JJK)=WK(5,JJK)-0.2500*TRT1*S*(RTX*V*P**3*ATX*EX1/WTX+R*V**3*1A*EX1/W)
PS(7)=CFH(7)*WK(5,JJK)
WK(6,JJK)=PAC(2)
GO TO 70
C*** COMPUTE PARTIALS WRT THIRD DRAG COEFFICIENT
61 DO 62 JL=1,4
62 WK(JL,JJK)=CTP(JL)*K6
WK(5,JJK)=WK(5,JJK)-0.2500*TRT1*S*(RTX*V*P**3*ATX*EX2/WTX+R*V**3*1A*EX2/W)
PS(8)=CFH(8)*WK(5,JJK)
WK(6,JJK)=PAC(3)
GO TO 70
C*** COMPUTE PARTIALS WRT FOURTH DRAG COEFFICIENT
63 DO 64 JL=1,4
64 WK(JL,JJK)=CTP(JL)*K7
WK(5,JJK)=WK(5,JJK)-0.2500*TRT1*S*(RTX*V*P**3*ATX*EX3/WTX+R*V**3*1A*EX3/W)
PS(9)=CFH(9)*WK(5,JJK)
WK(6,JJK)=PAC(4)
GO TO 70
C*** COMPUTE PARTIALS WRT FIFTH DRAG COEFFICIENT
65 DO 66 JL=1,4
66 WK(JL,JJK)=CTP(JL)*K8
WK(5,JJK)=WK(5,JJK)-0.2500*TRT1*S*(RTX*V*P**3*ATX*EX4/WTX+R*V**3*1A*EX4/W)
PS(10)=CFH(10)*WK(5,JJK)
WK(6,JJK)=PAC(5)
GO TO 70
C*** COMPUTE PARTIALS WRT FIRST LIFT COEFFICIENT
67 WK(1,JJK)=X24
WK(3,JJK)=X25
WK(6,JJK)=PAC(6)
GO TO 70
C*** COMPUTE PARTIALS WRT SECOND LIFT COEFFICIENT
68 WK(1,JJK)=X24*A
WK(3,JJK)=X25*A
WK(6,JJK)=PAC(7)
GO TO 70
C*** COMPUTE PARTIALS WRT THIRD LIFT COEFFICIENT
69 WK(1,JJK)=X24*A**EXPI
WK(3,JJK)=X25*A**EXPI
WK(6,JJK)=PAC(8)
70 CONTINUE
C*** COMPUTE DIFFERENCES FOR ALL POINTS
71 CK(1)=H-F10(J*1)
IF (DABS(CK(1)).LT.4.0D-06) CK(1)=0.000
CK(2)=HGAM-DARSIN(F11(J*1)/P4(J*1))
IF (DABS(HGAM).LT.6.0D-03) ICKP=1
IF (DABS(CK(2)).LT.1.0D-08) CK(2)=0.000
CK(3)=HDGRH-PT2(J*1)
IF (DABS(CK(3)).LT.3.0D-07) CK(3)=0.000
IF ((J+1).EQ.1) GO TO 77
C*** ZERO OUT SECOND-PARTIAL-DERIVATIVE ARRAYS
DO 72 JPK=1,NEQ
DO 72 JL=1,NEQ

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      ZH(JL,JPK)=0.000
      ZL(JL,JPK)=0.000
72  ZK(JL,JPK)=0.000
C*** STORE FACTORS FOR 2ND PARTIAL DERIVATIVES
      FS(1)=1.000
      FS(2)=X1
      FS(3)=X2
      FS(4)=X3
      FS(5)=X4
      FS(6)=1.000
      FS(7)=X5
      FS(8)=X6
      FS(9)=X7
      FS(10)=X8
      FS(11)=1.000
      FS(12)=A
      FS(13)=A**EXPK
C*** COMPUTE SECOND PARTIALS OF FLIGHT PATH ANGLE, ITS RATE, AND
C*** ALTITUDE
      ZAP1=-CK(2)*X26
      ZAP2=-CK(2)*X28
      ZAP3=-CK(3)*G*X9*X10/(V*X13)*(1.000*(X12/X13)**2)
      ZAP4=-CK(3)*G*X9*X10/(V*X13)*(1.000*(X12/X13)**2)
      ZAP5=-CK(1)*(X12*X9/X13*(2.000*X17*G*TH1**2*X12*X9/X13)+2.000*X1
      18*X9*X13**2-(X14*CL*X17*P-2.000*X18*X13)*((X9*X12)**2/X13**3*X9
      10/X13))
      ZAP6=-CK(1)*(X12/X13*X10*(X17*2.000*X18*X12*X9/X13)-2.000*X18*X10*
      1X9*(X14*CL*X17*P-2.000*X18*X13)*(X9*X10*X12**2/X13**3*X9*X10/X13))
      DO 73 JL=1,5
      DO 73 JH=1,5
      ZK(JH,JL)=ZAP1*FS(JH)*FS(JL)
      ZK(JH+5,JL)=ZAP2*FS(JH+5)*FS(JL)
      ZL(JH,JL)=ZAP3*FS(JH)*FS(JL)
      ZL(JH+5,JL)=ZAP4*FS(JH+5)*FS(JL)
      ZH(JH,JL)=ZAP5*FS(JH)*FS(JL)
      ZH(JH+5,JL)=ZAP6*FS(JH+5)*FS(JL)
73  ZH(JH+5,JL)=ZAP6*FS(JH+5)*FS(JL)
      ZAP1=-CK(2)*X28
      ZAP2=-CK(2)*X27
      ZAP3=-CK(3)*G*X9*X10/(V*X13)*(1.000*(X12/X13)**2)
      ZAP4=-CK(3)*G*X10*X10/(V*X13)*(1.000*(X12/X13)**2)
      ZAP5=-CK(1)*(X12/X13*X10*(X17*2.000*X18*X12*X9/X13)-2.000*X18*X10*
      1X9*(X14*CL*X17*P-2.000*X18*X13)*(X9*X10*X12**2/X13**3*X9*X10/X13))
      ZAP6=-CK(1)*(X10**2*(2.000*X18*(1.000-X12**2/X13**2)-(X14*CL*X17*P
      1-2.000*X18*X13)*(X12**2/X13**3+1.000/X13)))
      DO 74 JL=6,10
      DO 74 JH=1,5
      ZK(JH,JL)=ZAP1*FS(JH)*FS(JL)
      ZK(JH+5,JL)=ZAP2*FS(JH+5)*FS(JL)
      ZL(JH,JL)=ZAP3*FS(JH)*FS(JL)
      ZL(JH+5,JL)=ZAP4*FS(JH+5)*FS(JL)
      ZH(JH,JL)=ZAP5*FS(JH)*FS(JL)
      ZH(JH+5,JL)=ZAP6*FS(JH+5)*FS(JL)
74  ZH(JH+5,JL)=ZAP6*FS(JH+5)*FS(JL)
      ZAP7=-CK(1)*X29*X19
      ZAP8=-CK(1)*X29*X10
C*** STORE PARTIALS OF LIFT COEFFICIENTS
      DO 75 JH=1,13
      DO 75 JL=1,5
      ZH(JH,JL)=ZAP7*FS(JL)*FS(JH)
      ZH(JH,JL+5)=ZAP8*FS(JL+5)*FS(JH)
      ZH(JL,JH)=ZH(JH,JL)

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75  ZH(JL+5,JH)=ZH(JH,JL+5)
C*** COMPUTE MATRIX OF 2ND PARTIALS OF J WRT MODEL COEFFICIENTS
      JJ=0
      JJJ=0
      DO 76 JPK=1,NEQ
      IF (CFH(JPK).EQ.0.000.OR.JLOC(JPK).NE.0) GO TO 76
      JJJ=JJJ+1
      DO 76 JPY=1,NEQ
      IF (CFH(JPY).EQ.0.000.OR.JLOC(JPY).NE.0) GO TO 76
      JJJ=JJJ+1
      TWK(JJJ)=ZK(JPY,JPY)*D(2)
      TWK(JJJ)*ZL(JPY,JPY)*D(3)
      TWK(JJJ)=ZH(JPK,JPY)*D(1)
76  CONTINUE
C*** SUM MATRICES OF SECOND PARTIALS
      CALL HADD(PP,TWK,PP,JJ,JJ,0,0)
      CALL HADD(RQ,TWK,RQ,JJ,JJ,0,0)
      CALL HADD(RS,TWK,RS,JJ,JJ,0,0)
77  CK(4)=WTK-WK(J+1)
      IF (DABS(CK(4)).GT.1.0D-04) GO TO 78
      WTK=WK(J+1)
      CK(4)=0.000
78  ENER(1)=ENER(2)
      ENER(2)=ENER(3)
      P=CFH(1)*CFH(2)*F4(J+1)**EX1*CFH(3)*F4(J+1)**EX2*CFH(4)*F4(J+1)**EX
      1X3*CFH(5)*F4(J+1)**EX4
      IF (ATX.LT.0.000) CALL SIGMS(SUM,IEK1,IEK2,IEK3,IEK4)
      AM=DABS(ATX)
      CD=CFH(6)*CFH(7)*SUM(1)*AM**IEK1*CFH(8)*SUM(2)*AM**IEK2*CFH(9)*SUM
      1(3)*AM**IEK3*CFH(10)*SUM(4)*AM**IEK4
      IF (ATX.LT.0.000) CALL CHNGE(SUM)
      ENER(3)=P*DCOS(ATX+TIA)/WTK-RTX*F4(J+1)**3/(2.000*WTK)*CD
      IF ((J+1).EQ.1) ENERGT=F4(1)**2/(2.000*G)*F10(1)
      IF ((J+1).GT.2) GO TO 79
      IF ((J+1).EQ.1) GO TO 80
      ENERGT=ENERGT*PS(1)*PS(2)*PS(3)*PS(4)*PS(5)*PS(6)*PS(7)*PS(8)*PS(9)
      1)*PS(10)
      GO TO 80
79  TA1=TIME(IPT-3)-TIME(IPT-2)
      TA2=0.000
      TA3=TIME(IPT-1)-TIME(IPT-2)
      C1=(ENER(1)-ENER(2))/(TA1-TA2)-(ENER(2)-ENER(3))/(TA2-TA3)/(TA1-
      1TA3)
      C2=(ENER(1)-ENER(2))/(TA1-TA2)-C1*(TA1+TA2)
      C3=ENER(1)-TA1*(C1+TA1*C2)
      ENERGT=ENERGT+C1/3.000*(TA3**3-TA2**3)+C2/2.000*(TA3**2-TA2**2)+C3
      1*(TA3-TA2)
80  CK(5)=ENERGT*F4(J+1)**2/(2.000*G)*F10(J+1)
      IF ((J+1).EQ.2) ENERGT=ENERGT-CK(5)
      IF ((J+1).EQ.2) CK(5)=0.000
      IF (DABS(CK(5)).LT.3.0D-05) CK(5)=0.000
      CK(6)=ATX*F6(J+1)
      IF (DABS(CK(6)).LT.1.0D-03) CK(6)=0.000
      IF ((J+1).EQ.1) GO TO 83
C*** SUM MATRICES OF PARTIALS
      IP=0
      JJ=0
      DO 82 JXP=1,NEQ
      IF (CFH(JXP).EQ.0.000.OR.JLOC(JXP).NE.0) GO TO 82
      IP=IP+1

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      STWJ=0.000
      DO 81 JP=1,6
      JJ=JJ+1
      TWK(JJ)=WK(JP,IP)*DSQRT(D(JP))
81  STWJ=STWJ+TWK(JJ)*CK(JP)*DSQRT(D(JP))
      TWJ(IP)=STWJ
82  CONTINUE
      NS=0
      CALL DATA(TWK,TWK,6,IP,NS)
      CALL HADD(RR,TWK,RR,IP,IP,0,1)
      CALL HADD(CC,TWJ,CC,IP,1,0,0)
C*** COMPUTE SUM OF SQUARED RESIDUALS
83  DO 84 JXP=1,6
84  TOL(JXP)=TOL(JXP)+CK(JXP)*CK(JXP)
C*** STORE AND DEFINE PARAMETERS
      A=ATI
      M=MTI
      R=RTI
      IF (LKK.EQ.1) GO TO 86
      DO 85 JJP=1,3
85  HLD(JJP,J+1)=HLD(JJP,J+1)
86  HLD(1,J+1)=F1(J+1)
      HLD(2,J+1)=F5(J+1)
      HLD(3,J+1)=F6(J+1)
      F1(J+1)=M
      F5(J+1)=R
      F6(J+1)=A
87  IF (IPTS.EQ.0.AND.KPRINT.EQ.IPTSPI) KPRINT=0
C*** PROCEED WITH NEXT POINT
88  CONTINUE
      IF (LCH.NE.0) WRITE (JWRITE,89) LCH
89  FORMAT (1X,/,9I,94H*** DURING NEWTON-RAPHSON FOR ANGLE OF ATTACK
118  HPATH, ROUTINE WISHED TO SEEK COMPLEX ROOTS ,13,7H TIMES.)
      IF (HCH.NE.0) WRITE (JWRITE,90) HCH
90  FORMAT (1X,/,9I,94H*** DURING NEWTON-RAPHSON FOR ANGLE OF ATTACK
118  PARTIAL, ROUTINE WISHED TO SEEK COMPLEX ROOTS ,13,7H TIMES.)
C*** DETERMINE APPROPRIATE A PRIORI VALUE APPLICATION
      IJX=0
      DO 91 JXP=1,NEQ
      SP(JXP)=1.000
      IF (CFN(JXP).EQ.0.000.OR.JLOC(JXP).NE.0) GO TO 91
      IJX=IJX+1
      ILOC(IJX)=JXP
      DSL(IJX)=SCALE(JXP)
91  CONTINUE
C*** COMPUTE THE COST FUNCTION
      PCF=0.000
      PPCF=0.000
      DO 92 JXP=1,IP
C*** SET A PRIORI VALUE AS MODEL COEFFICIENT IF CONDITION IS MET
      IF (JLOC(ILOC(JXP)).NE.0) AP(ILOC(JXP))=CFN(ILOC(JXP))
92  PPCF=PCCF+WGT(ILOC(JXP))*CFN(ILOC(JXP))-AP(ILOC(JXP))*2/(AP(ILOC(JXP))+AP(ILOC(JXP)))
      DO 93 JJP=1,6
93  PCF=PCF+D(JJP)*TOL(JXP)
      IF (IPS.NE.0) JK=1
      COST(JK)=PCF+PPCF
      WRITE (JWRITE,94) COST(JK)
94  FORMAT (1X,/,33X,'COST FUNCTION (J) = ',1PD23.16,/,33X,'WITH:')
      DO 95 JJP=1,6

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95  TOL(JXP)=TOL(JXP)/N
      WRITE (JWRITE,96) (TOL(JXP),JJP=1,6)
96  FORMAT (39I,'ALTITUDE TOLERANCE = ',D20.13,/,39I,'FLIGHT-PATH-ANGLE
118  TOLERANCE = ',D20.13,/,39I,'FLIGHT-PATH-ANGLE-DERIVATIVE TOLERAN
118  ICE = ',D20.13,/,39I,'WEIGHT TOLERANCE = ',D20.13,/,39I,'ENERGY TOL
118  TERENCE = ',D20.13,/,39I,'ANGLE-OF-ATTACK TOLERANCE = ',D20.13,/,39I)
C*** UPDATE COST FUNCTION
C*** CHECK COST FUNCTION WITH TOLERANCE FOR ITERATION TERMINATION
      IF (COST(JK).LT.1.0D-10) GO TO 133
      IF (JK.EQ.1) HCOST=COST(1)
C*** TEST FOR INCREASE IN COST FUNCTION
      IF (JK.GT.1.AND.COST(JK).GT.HCOST) GO TO 130
      NCOST=COST(JK)
C*** ADJUST MATRICES FOR LEAST SQUARES SOLUTION
      CALL HADD(RR,RR,RR,IP,IP,0,0)
      CALL HADD(RR,RQ,RR,IP,IP,0,0)
      CALL HADD(RR,RS,RS,IP,IP,0,0)
      HADD=IP*IP
      IPS=0
      IPSH=0
      DO 97 JL=1,HADD
97  RYS(JL)=RYS(JL)
      DO 98 JL=1,IP
98  CCX(JL)=CC(JL)
99  IC=0
      IPSH=IPSH+1
      IF (IPS.EQ.0) GO TO 101
C*** APPLY CONSTRAINTS AND SIGN FACTOR, IF NEEDED
      JJ=0
      DO 100 JXP=1,NEQ
      IF (CFN(JXP).EQ.0.000.OR.JLOC(JXP).NE.0) GO TO 100
      JJ=JJ+1
      IF ((CFN(JXP)*FIX*(JJ,1)*SCALE(JXP)).GT.CRNIN(JXP).AND.(CFN(JXP)*
118  FIX*(JJ,1)*SCALE(JXP)).LT.CRNAX(JXP)) GO TO 100
      IF (IPSH.GT.2.AND.RNT(JXP,1).NE.0.000) RNT(JXP,1)=RNT(JXP,1)+10.0D
118  10
      IF (IPSH.GT.2.AND.RNT(JXP,2).NE.0.000) RNT(JXP,2)=RNT(JXP,2)+10.0D
118  10
      IF (IPSH.GT.2.AND.(RNT(JXP,1).NE.0.000.OR.RNT(JXP,2).NE.0.000)) G
118  10 TO 100
      IF ((CFN(JXP)*FIX*(JJ,1)*SCALE(JXP)).LT.CRNIN(JXP)) RNT(JXP,1)=WGT
118  1L(JXP)
      IF ((CFN(JXP)*FIX*(JJ,1)*SCALE(JXP)).GT.CRNAX(JXP)) RNT(JXP,2)=WGT
118  1U(JXP)
      IF (CFN(JXP).GT.CRNIN(JXP).AND.RNT(JXP,1).NE.0.000) SF(JXP)=-0.500
      IF (CFN(JXP).LT.CRNAX(JXP).AND.RNT(JXP,2).NE.0.000) SF(JXP)=-0.500
      IF ((JXP.EQ.8.AND.(FIX*(JJ,1)*SCALE(JXP)).LT.6.000).AND.(CFN(JXP)
118  1+FIX*(JJ,1)*SCALE(JXP)).LT.CRNIN(JXP)) CRNIN(JXP)=CRNIN(JXP)-FIX*(J
118  1(JJ,1)*SCALE(JXP)
100 CONTINUE
C*** FORM MATRIX FOR LEAST-SQUARES SOLUTION
101  DO 103 JKP=1,IP
      IF (DABS(CFN(ILOC(JKP)))) .LT.1.0D-03.AND.ILOC(JKP).EQ.11) AP(ILOC(
118  1(JKP)))=1.0D-10
      IF (DABS(CFN(ILOC(JKP)))) .LT.1.0D-03.AND.ILOC(JKP).EQ.11) WGT(ILOC
118  1(JKP))=1.0D-17
      IF (LKK.GT.4.AND.(WGT(ILOC(JKP)).GT.6.000.AND.ILOC(JKP).EQ.11)) W
118  1GT(ILOC(JKP))=2.500*WGT(ILOC(JKP))
      DO 102 JXP=1,IP
      IFAC=1.000

```

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```

IF (JXP1.EQ.JXP2) KPAC=1.0000500*DSL(JXP1)      HP 795
IC=IC+1      HP 796
KC=KC(IC)    HP 797
IF (JXP1.EQ.JXP2) KC=KC+2.000*WGT(ILOC(JXP1))/(AP(ILOC(JXP1))*AP(IL HP 798
LOC(JXP1)))  HP 799
IF (JXP1.EQ.JXP2.AND.IPS.NE.0) KC=KC+2.000*WGT(ILOC(JXP1),1)*2.000* HP 800
WGT(ILOC(JXP1),2) HP 801
U(JXP2,JXP1)=KC*KPAC HP 802
102 ZH(JXP2,JXP1)=U(JXP2,JXP1) HP 803
Y(JXP1,1)=CC(JXP1)*2.000*WGT(ILOC(JXP1))*(AP(ILOC(JXP1))-CFH(ILOC HP 804
(JXP1)))/(AP(ILOC(JXP1))*AP(ILOC(JXP1))) HP 805
IF (IPS.NE.0) Y(JXP1,1)=Y(JXP1,1)-2.000*SF(ILOC(JXP1))*WGT(ILOC(JXP HP 806
1),1)*CFH(ILOC(JXP1))-CRHIN(ILOC(JXP1))*2.000*SF(ILOC(JXP1))*WGT HP 807
(ILOC(JXP1),2)*(CRHAX(ILOC(JXP1))-CFH(ILOC(JXP1))) HP 808
103 YS(JXP1,1)=Y(JXP1,1) HP 809
C*** BHACT LEAST SQUARES SOLUTION HP 810
CALL LLSQAR(U,Y,IP,IP,1,13,13,15,UKAR,IER,JWRITE) HP 811
C*** TEST FOR ERROR HP 812
IF (IER.EQ.129) IERR=1 HP 813
IF (IERR.NE.0) RETURN HP 814
IF (IPSHI.GE.3) GO TO 107 HP 815
C*** TEST FOR APPLICATION OF CONSTRAINTS HP 816
IFIX=0 HP 817
JJ=0 HP 818
DO 104 JXP=1,NEQ HP 819
IF (CFH(JXP).EQ.0.000.OR.JLOC(JXP).NE.0) GO TO 104 HP 820
JJ=JJ+1 HP 821
IF ((CFH(JXP)*FIX*(JJ,1)*SCALE(JXP)).LT.CRHIN(JXP).OR.(CFH(JXP)*F HP 822
IX*(JJ,1)*SCALE(JXP)).GT.CRHAX(JXP)) IFIX=1 HP 823
IPS=IFIX HP 824
104 CONTINUE HP 825
C*** RESET MATRICES HP 826
IF (IFIX.EQ.0) GO TO 107 HP 827
DO 105 JL=1,NXDD HP 828
105 RX(JL)=RIS(JL) HP 829
DO 106 JL=1,IP HP 830
106 CC(JL)=CCX(JL) HP 831
GO TO 99 HP 832
C*** APPLY DELTAS TO POWER, DRAG, AND LIFT COEFFICIENTS HP 833
107 WRITE (JWRITE,108) FIX HP 834
108 FORMAT (1X,///,3X,'PREVIOUS COEFFICIENT',8X,F4.2,'*DELTA',9X,'NEW HP 835
ICOEFFICIENT',//) HP 836
JJ=0 HP 837
NLCX=0 HP 838
DO 119 JXP=1,NEQ HP 839
LLCC(JXP)=JLOC(JXP) HP 840
NLOC(JXP)=0 HP 841
IX=0.000 HP 842
NS(JXP)=0.000 HP 843
ICK=1 HP 844
IF (CFH(JXP).EQ.0.000.OR.JLOC(JXP).NE.0) GO TO 115 HP 845
ICK=0 HP 846
JJ=JJ+1 HP 847
IX=Y(JJ,1)*DSL(JJ) HP 848
IF (JXP.EQ.12) IC12=IX HP 849
IF (DABS(IX/CFH(JXP)).LT.1.5D-06.OR.DABS(CFH(JXP)*FIX*IX).LT.3.0D- HP 850
108) IX=0.000 HP 851
IF (JXP.EQ.12.AND.DABS(Y(JJ,1)*DSL(JJ)/CFH(JXP)).LT.1.5D-06) IX=1.0 HP 852
ID=03 HP 853
IF (IX.NE.0.000) GO TO 109 HP 854

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ICK=1      HP 855
NLOC(JXP)=1 HP 856
JLOC(JXP)=1 HP 857
NLCX=NLCX+1 HP 858
IX=Y(JJ,1)*DSL(JJ) HP 859
109 NS(JXP)=FIX*IX HP 860
CHLD=CFH(JXP) HP 861
CFH(JXP)=CFH(JXP)+NS(JXP) HP 862
IF (METRIC.NE.0) GO TO 112 HP 863
IF (ICK.EQ.0) WRITE (JWRITE,110) CHLD,FX,IX,CFH(JXP) HP 864
IF (ICK.NE.0) WRITE (JWRITE,111) CHLD,FX,IX,CFH(JXP) HP 865
110 FORMAT (3X,D20.13,' * ',F4.2,'**',D15.8,' * ',D20.13) HP 866
111 FORMAT (3X,D20.13,' * ',F4.2,'**',D15.8,' * ',D20.13,3X,' (PROZEN)' HP 867
1) HP 868
GO TO 119 HP 869
112 IF (JXP.GT.5) GO TO 113 HP 870
CXH=CHLD*1.355818D-3 HP 871
IX=IX*1.355818D-3 HP 872
CXI=CFH(JXP)*1.355818D-3 HP 873
GO TO 114 HP 874
113 CXH=CHLD HP 875
CXI=CFH(JXP) HP 876
114 IF (ICK.EQ.0) WRITE (JWRITE,110) CXH,FX,IX,CXI HP 877
IF (ICK.NE.0) WRITE (JWRITE,111) CXH,FX,IX,CXI HP 878
GO TO 119 HP 879
115 IF (METRIC.NE.0) GO TO 116 HP 880
WRITE (JWRITE,111) CFH(JXP),FX,IX,CFH(JXP) HP 881
GO TO 119 HP 882
116 IF (JXP.GT.5) GO TO 117 HP 883
CXH=CFH(JXP)*1.355818D-3 HP 884
CXI=CFH(JXP)*1.355818D-3 HP 885
GO TO 118 HP 886
117 CXH=CFH(JXP) HP 887
CXI=CXH HP 888
118 WRITE (JWRITE,111) CXH,FX,IX,CXI HP 889
119 CONTINUE HP 890
C*** CHECK FOR ADJUSTMENT TO MATRICES DUE TO COEFFICIENT FREEZING HP 891
IF (NLCX.EQ.0.OR.NLCX.GT.(JJ-2)) GO TO 128 HP 892
DO 120 JXP=1,NEQ HP 893
IF (JXP.EQ.12.AND.RS(JXP).EQ.1.0D-03) CFH(12)=CFH(12)+1.0D-03 HP 894
IF (JXP.EQ.12.AND.(CFH(JXP).GT.6.296D0.AND.TC12.GT.0.000)) CFH(JXP) HP 895
=CFH(JXP)+3.0D-03 HP 896
120 CFH(JXP)=CFH(JXP)-RS(JXP)*(1-NLOC(JXP)) HP 897
DO 121 IX=1,10 HP 898
121 IF (CFH(12).GT.CRHAX(12)) CFH(12)=CFH(12)-1.0D-03 HP 899
C*** ADJUST MATRICES HP 900
CALL ADJUST(ZH,YS,CFH,Y,DSL,LLCC,NLOC,IP,NEQ) HP 901
WRITE (JWRITE,108) FIX HP 902
C*** COMPUTE NEW ADJUSTED DELTAS HP 903
CALL LLSQAR(ZH,YS,IP,IP,1,13,13,15,UKAR,IER,JWRITE) HP 904
C*** TEST FOR ERROR HP 905
IF (IER.EQ.129) IERR=1 HP 906
IF (IERR.NE.0) RETURN HP 907
C*** APPLY DELTAS HP 908
JJ=0 HP 909
DO 127 JXP=1,NEQ HP 910
IX=0.000 HP 911
ICK=1 HP 912
IF (CFH(JXP).EQ.0.000.OR.(((JLOC(JXP).EQ.LLOC(JXP)).AND.JLOC(JXP). HP 913
NE.0).OR.NLOC(JXP).NE.0)) GO TO 122 HP 914

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ICK=0	NP 915
JJ=JJ+1	NP 916
IX=FXI*YS(JJ,1)*SCALE(JXP)	NP 917
CHLD=CFN(JXP)	NP 918
122 CFX(JXP)=CFN(JXP)*IX	NP 919
IF (METRIC.NE.0) GO TO 123	NP 920
IF (ICK.EQ.0) WRITE (JWRITE,110) CHLD,FXI,IX,CFN(JXP)	NP 921
IF (ICK.NE.0) WRITE (JWRITE,111) CFX(JXP),FXI,IX,CFN(JXP)	NP 922
GO TO 127	NP 923
123 IF (JXP.GT.5) GO TO 125	NP 924
CIM=CHLD*1.355818D-3	NP 925
IX=IX*1.355818D-3	NP 926
CFI=CFN(JXP)*1.355818D-3	NP 927
GO TO 126	NP 928
125 CIM=CHLD	NP 929
CFI=CFN(JXP)	NP 930
126 IF (ICK.EQ.0) WRITE (JWRITE,110) CIM,FXI,IX,CFI	NP 931
IF (ICK.NE.0) WRITE (JWRITE,111) CFI,FXI,IX,CFI	NP 932
127 CONTINUE	NP 933
C*** START NEW ITERATION OR CONTINUE	NP 934
128 ICNT=0	NP 935
DO 129 JXP=1,NEQ	NP 936
HCFN(LKK+1,JXP)=CFN(JXP)	NP 937
129 IF (CFN(JXP).NE.0.0D0.AND.JLOC(JXP).NE.0) ICNT=ICNT+1	NP 938
IF ((MUN-ICNT).LE.2) GO TO 133	NP 939
GO TO 3	NP 940
C*** READJUST COEFFICIENTS DUE TO TOLERANCE INCREASE	NP 941
130 DO 131 JXP=1,NEQ	NP 942
131 CFX(JXP)=HCFN(LKK-2,JXP)	NP 943
C*** RESET PARAMETERS WITH RESPECT TO BEST TOLERANCE	NP 944
DO 132 IG=1,N	NP 945
F1(IG)=XHLD(1,IG)	NP 946
F5(IG)=XHLD(2,IG)	NP 947
132 F6(IG)=XHLD(3,IG)	NP 948
C*** MAKE ADJUSTMENT TO PITCH ANGLE	NP 949
133 DO 134 I=1,N	NP 950
134 F2(I)=F6(I)*DARSIN(F11(I)/F4(I))	NP 951
RETURN	NP 952
END	NP 953

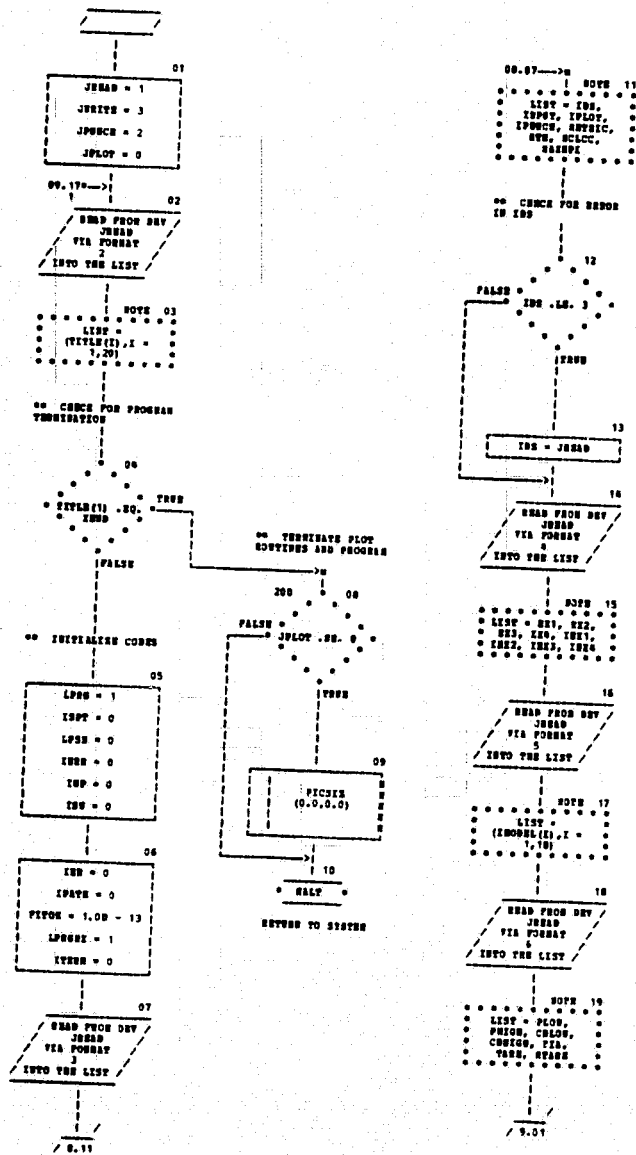
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Flowchart - FDR2

CHART TITLE - PROCEDURE**ASTROLOG CHART SET -**

• 2002

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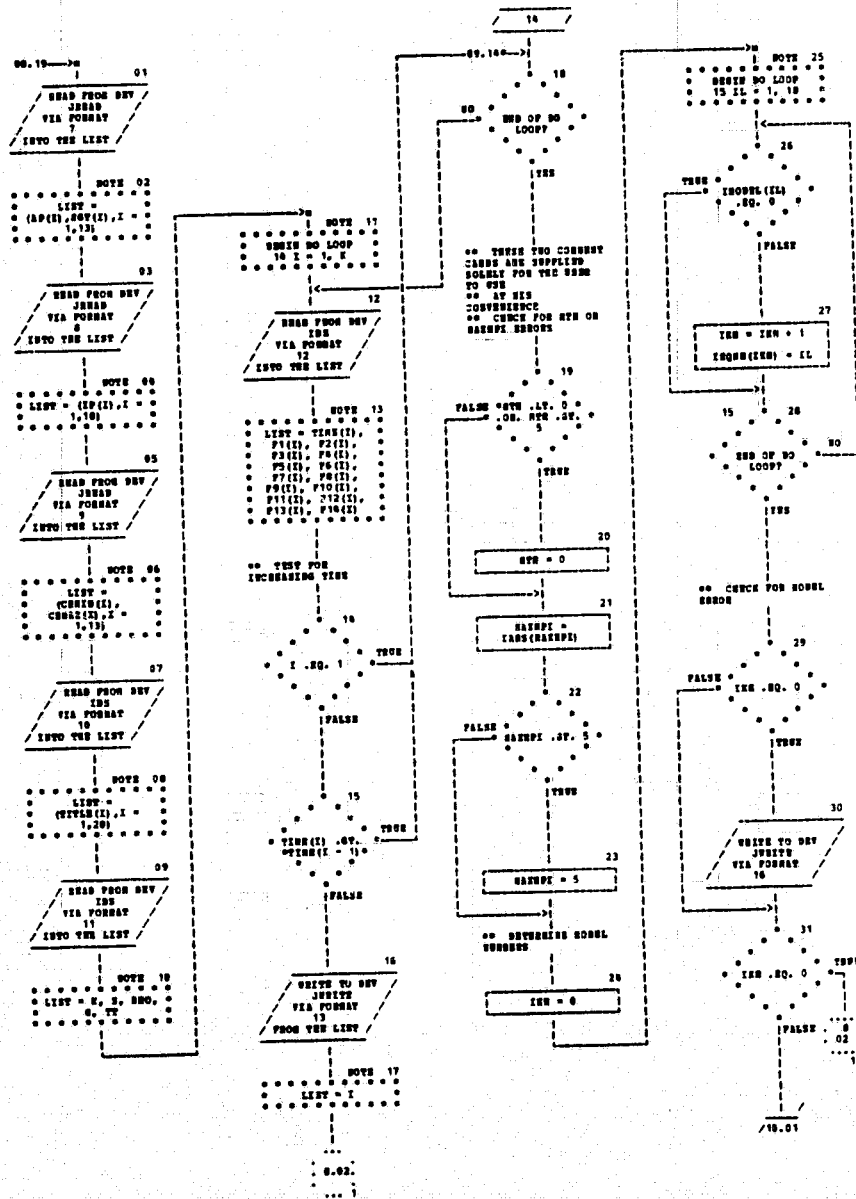
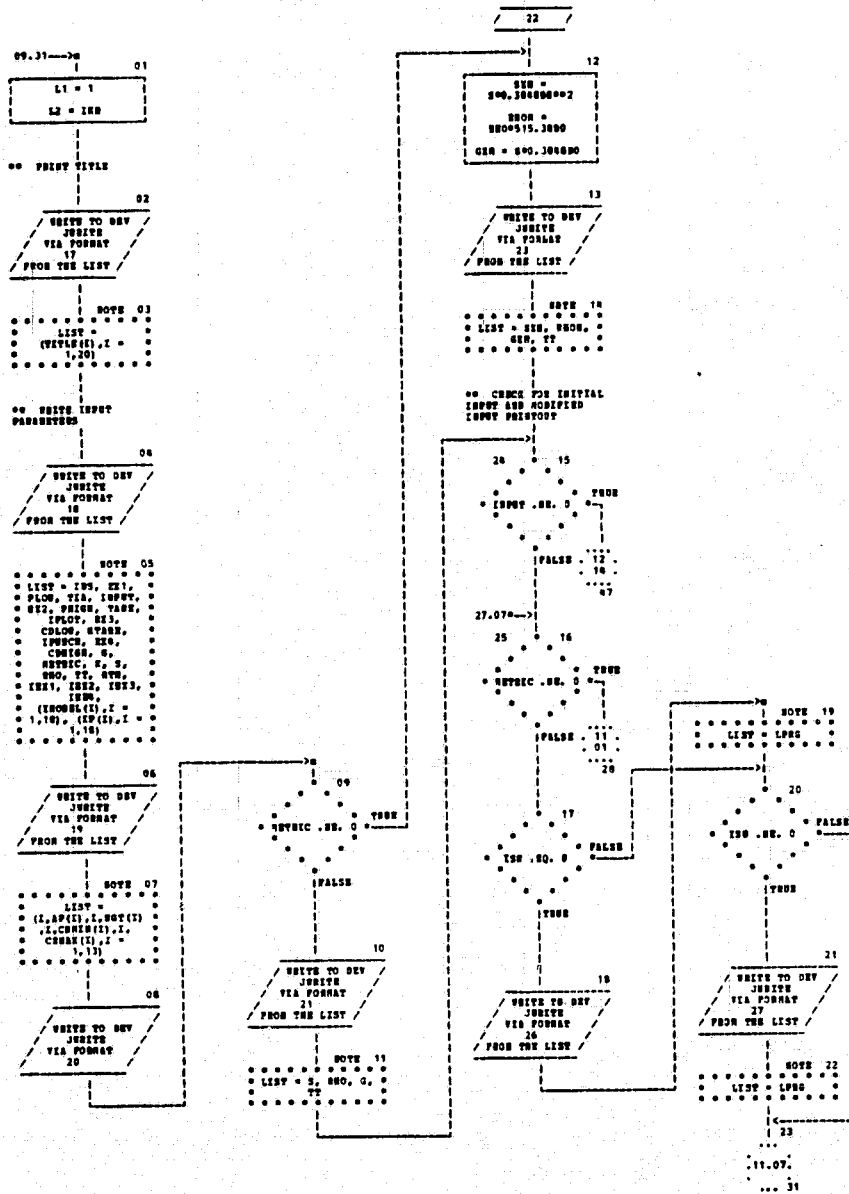
CASEY TITLE - PROCEDURES

CHART TYPE - PROCEDURES



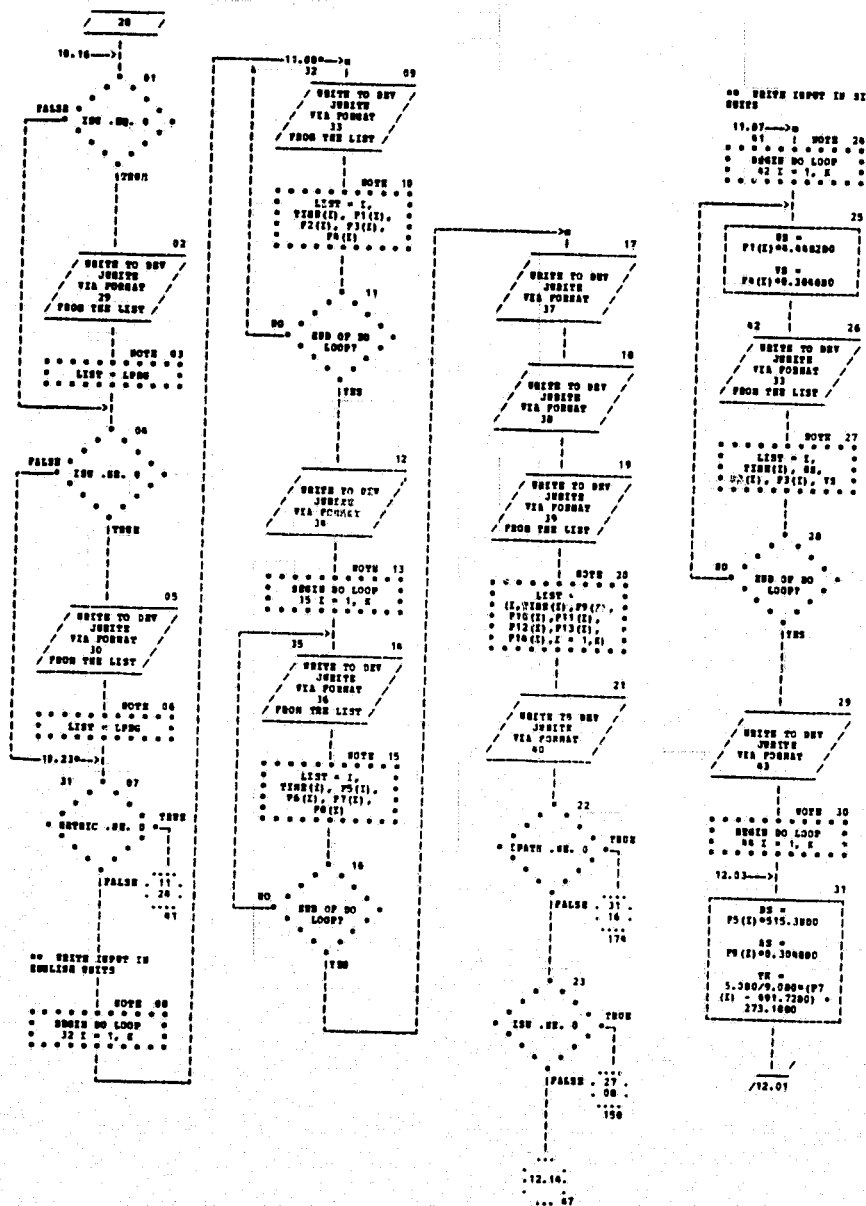
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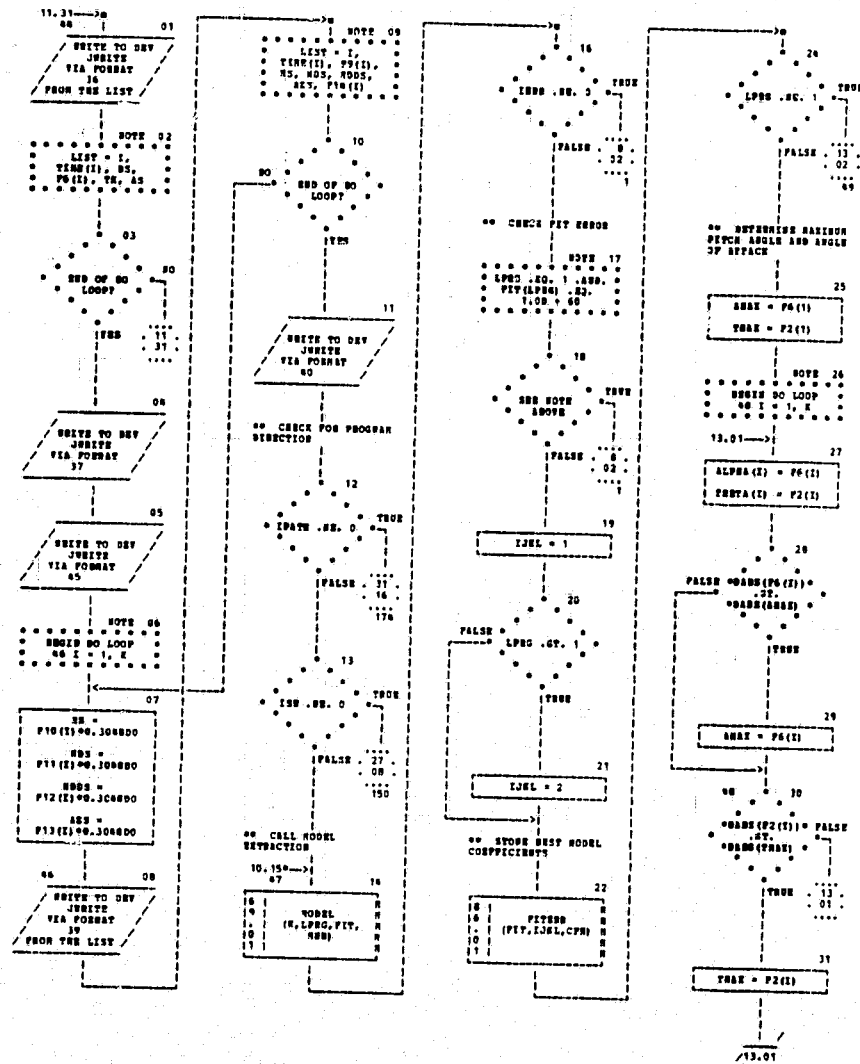
CREAT TITAN - PARACHUTER

AUTOFLOW CRAFT SW -

0002

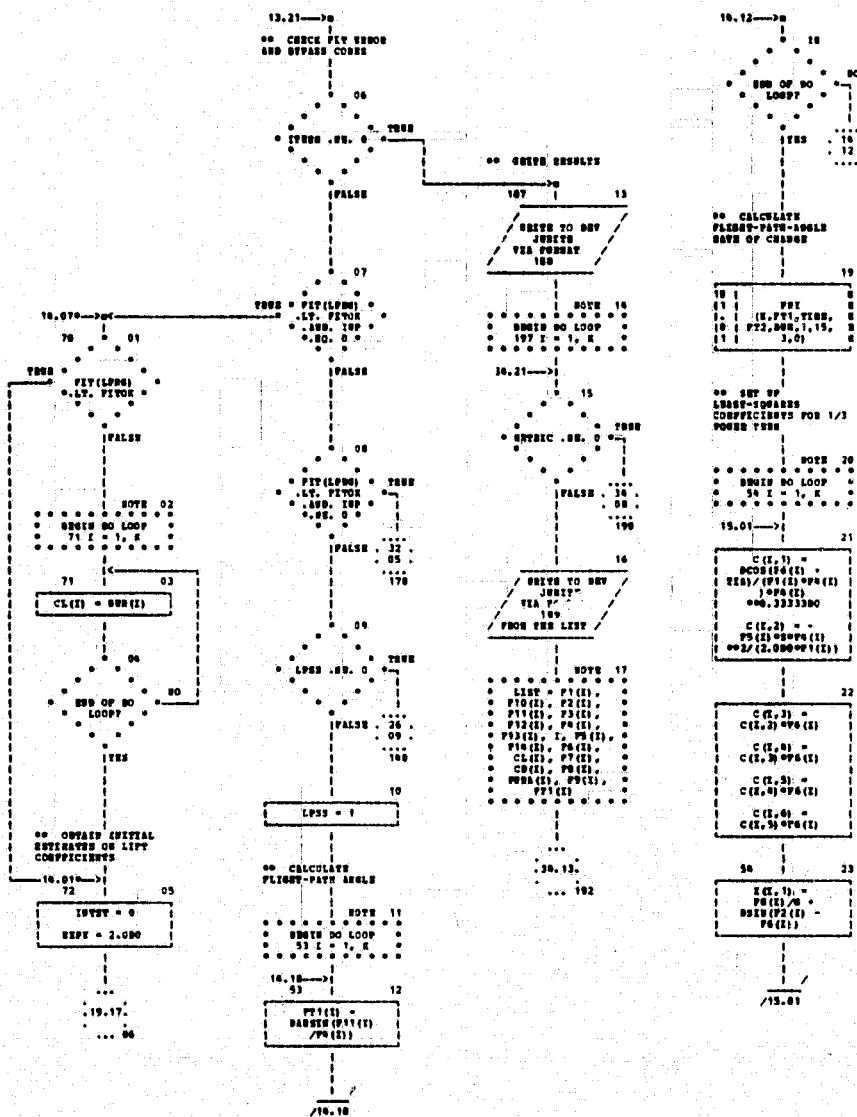
PAGE 11

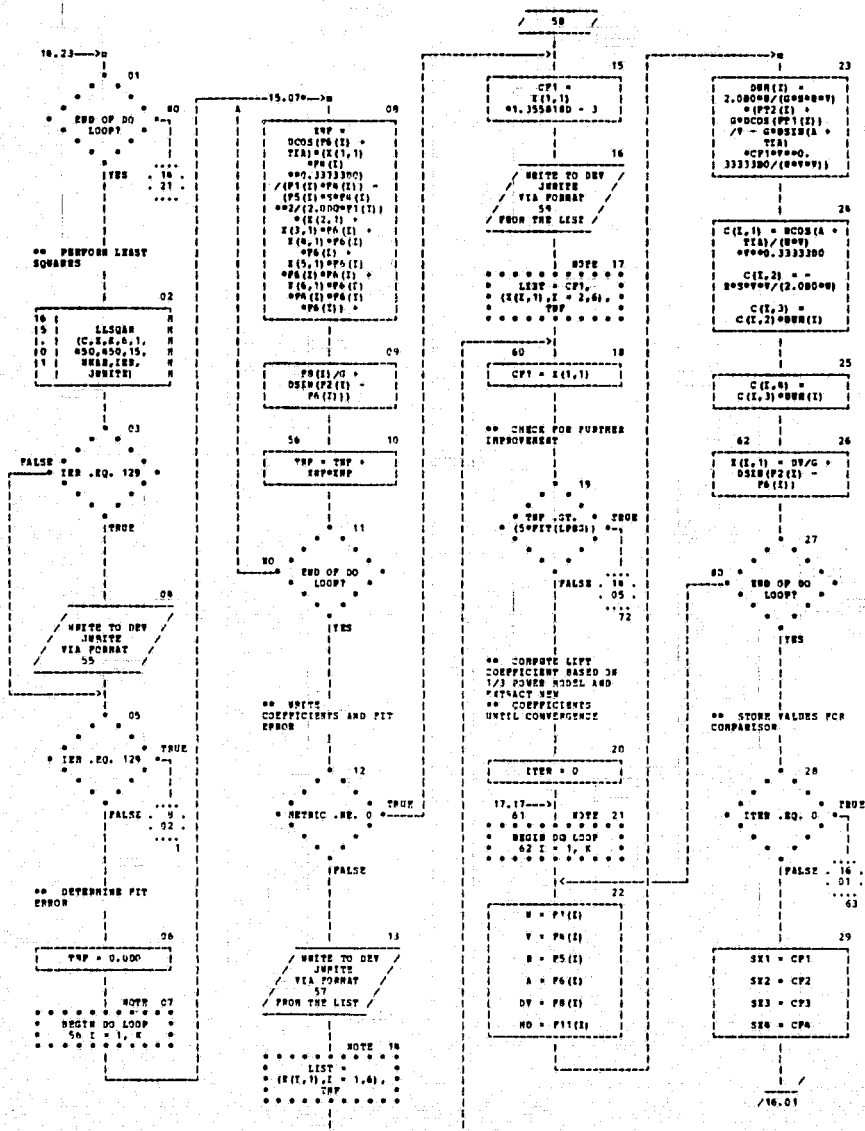




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CHART TITLE - FRODO BAGGINS

CRANT TITLE - PROGRAMMES

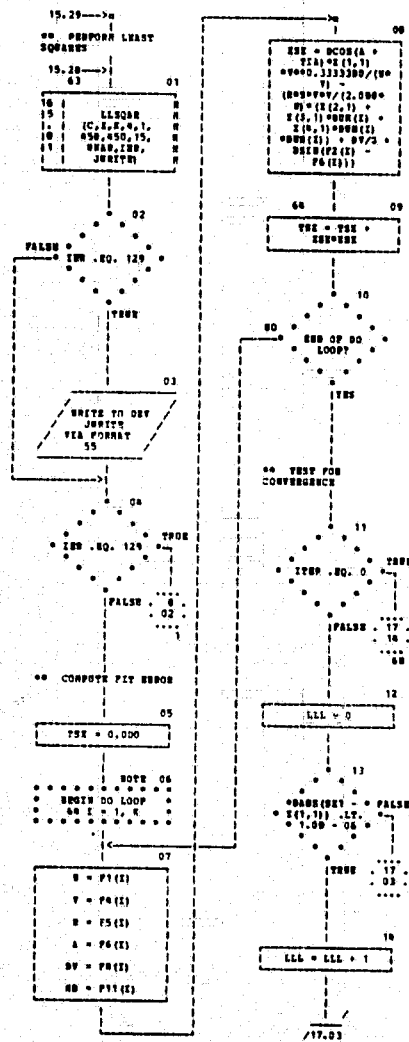


CHART TITLE - PROGRAM

AUTOPLOE CHART 800 -

*P002

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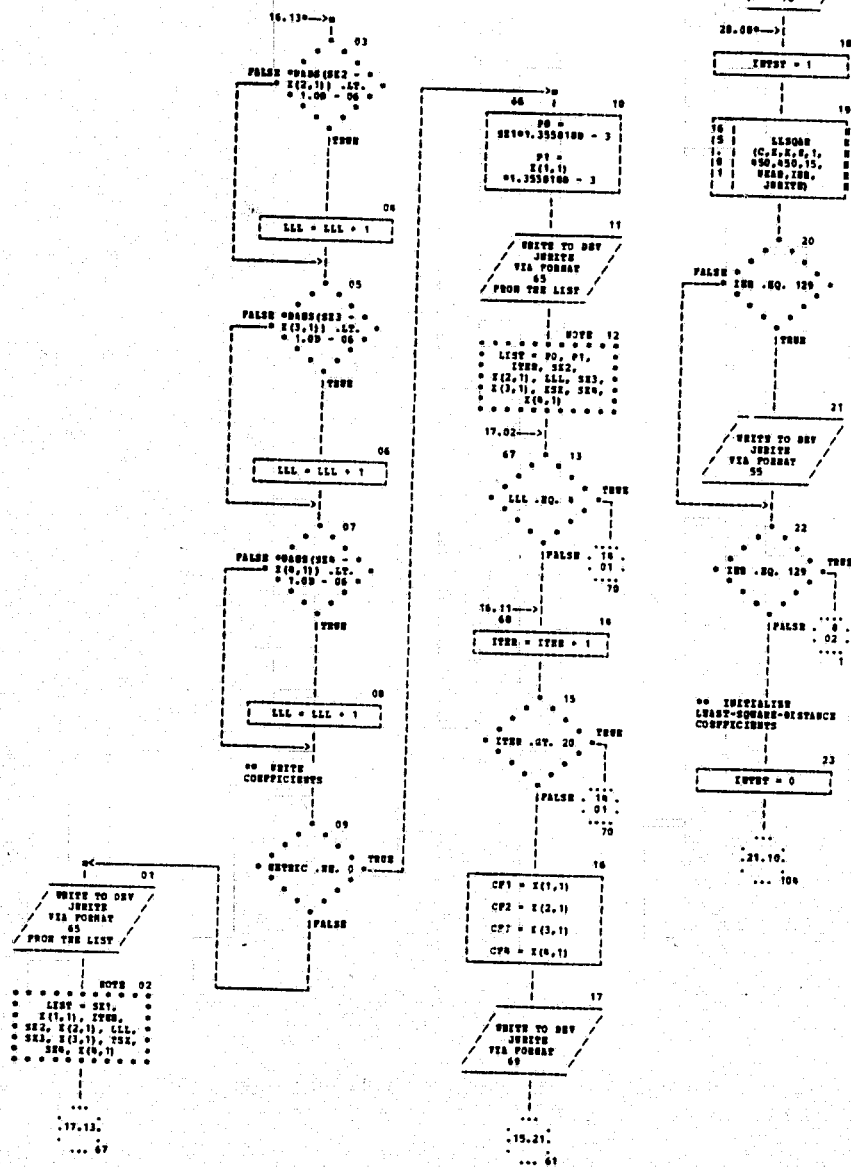


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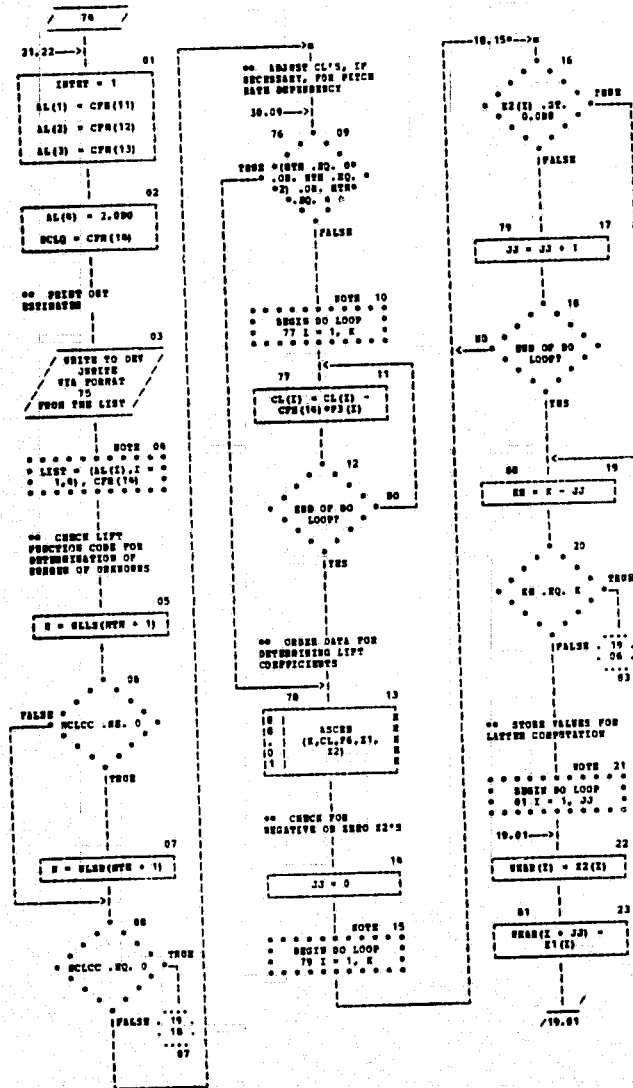




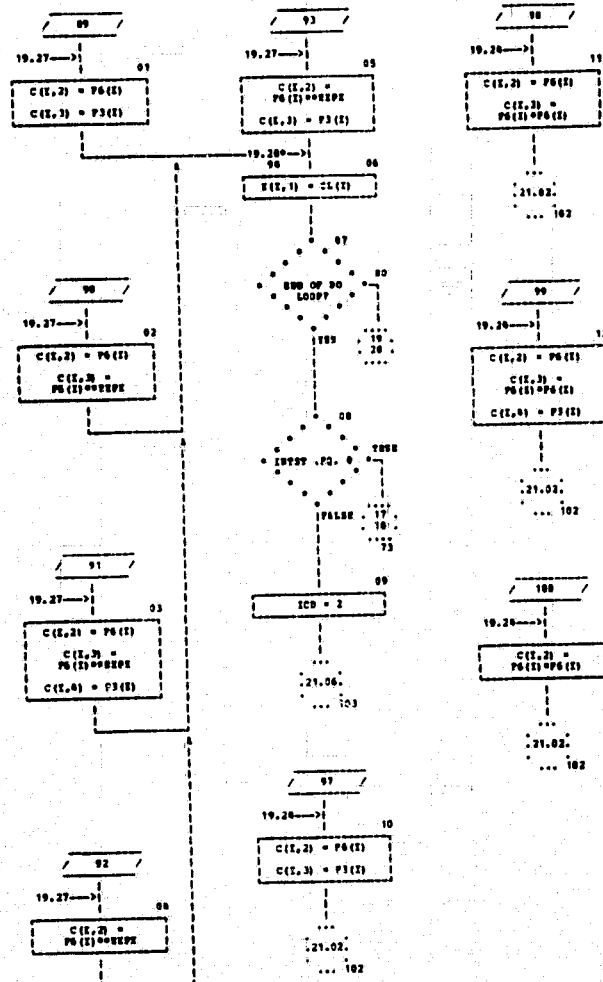
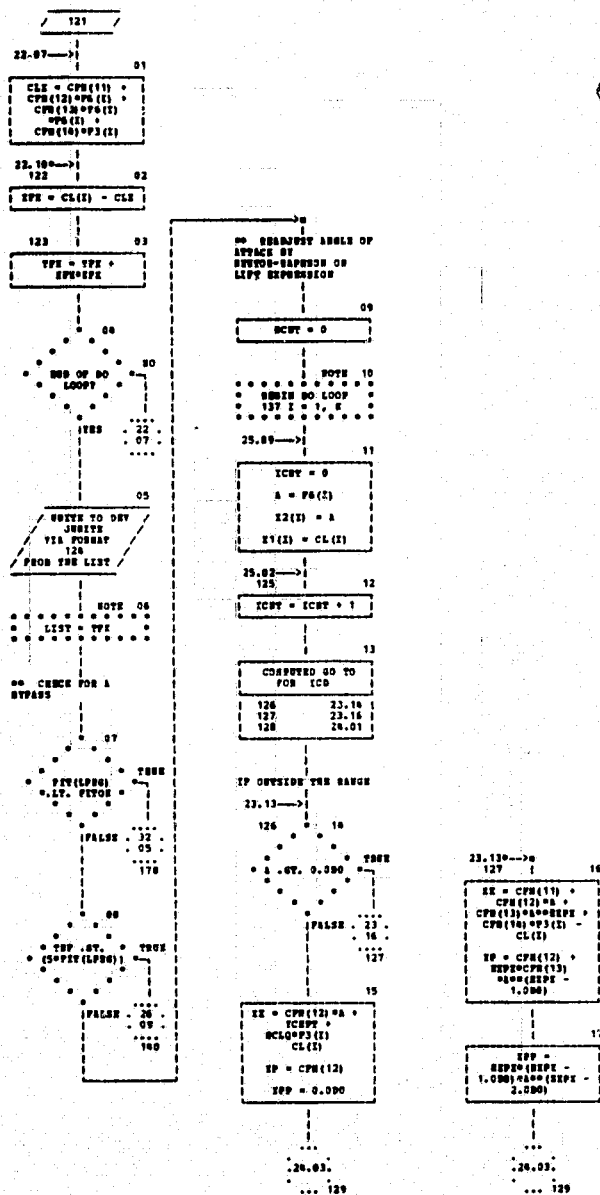
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CHART TITLE - PROCEDURES

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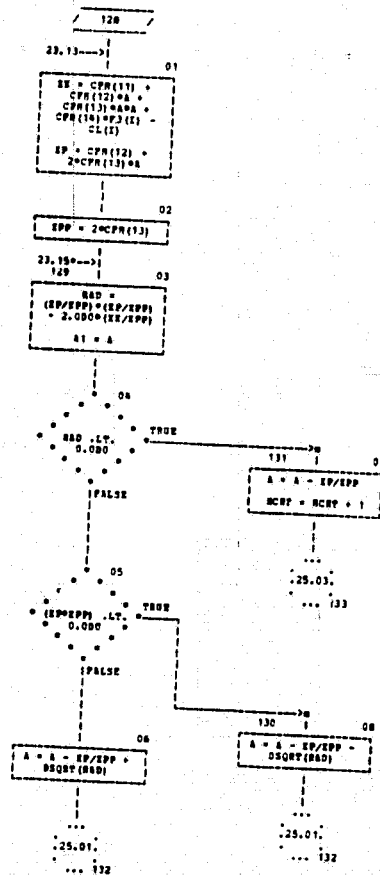


CHART TITLE - PROCEDURES

ANTHONY CHART 187 -

• 2002

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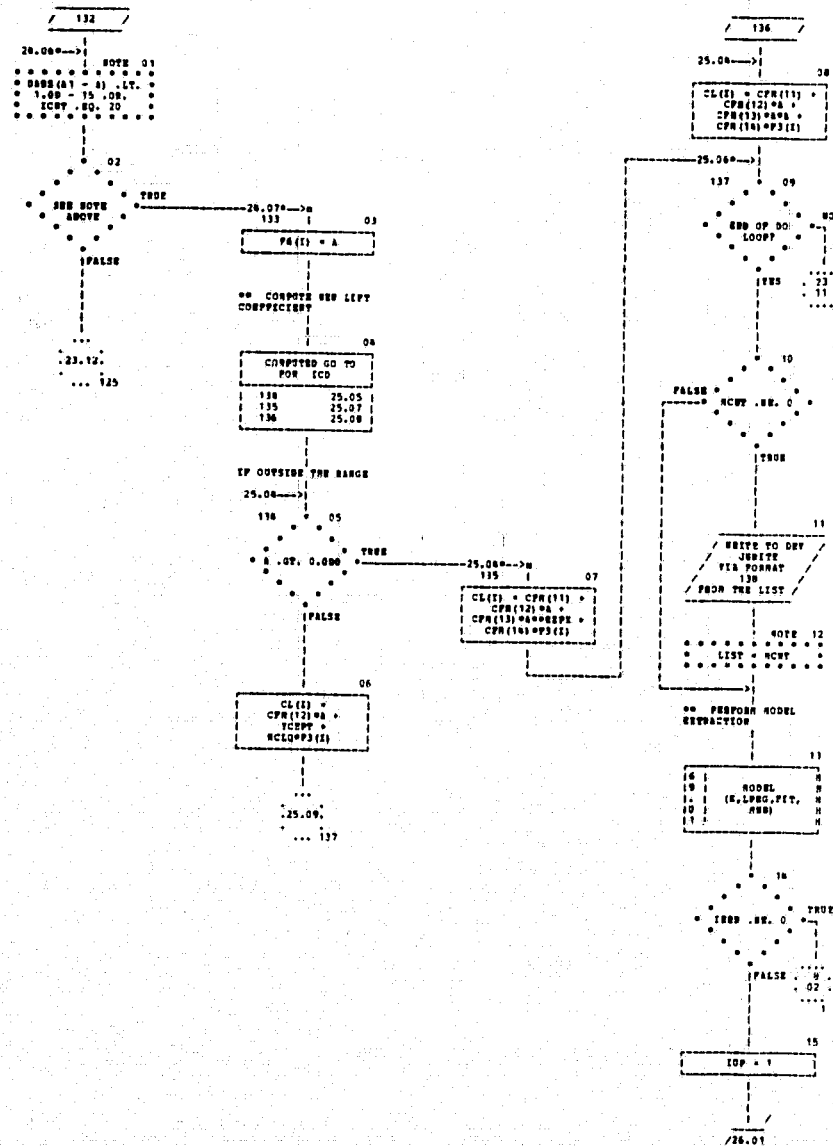
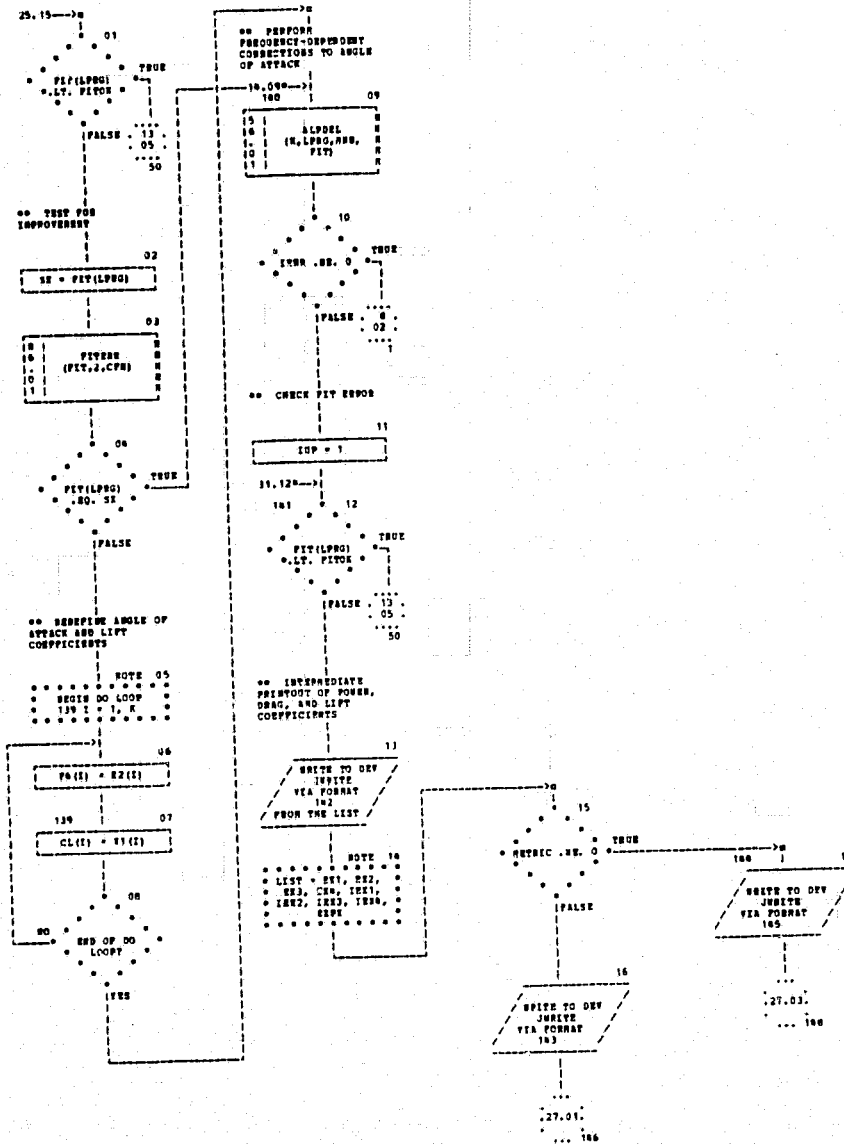


CHART TITLE - PROCEDURES



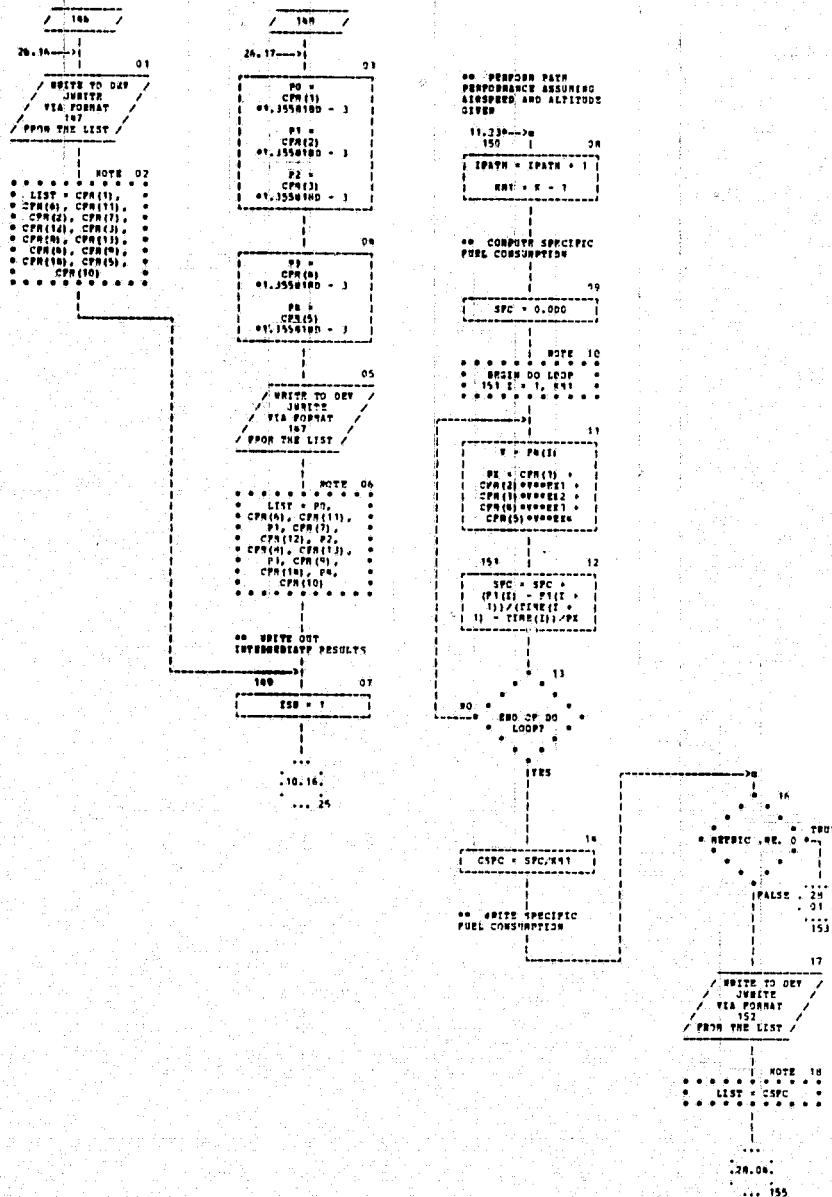
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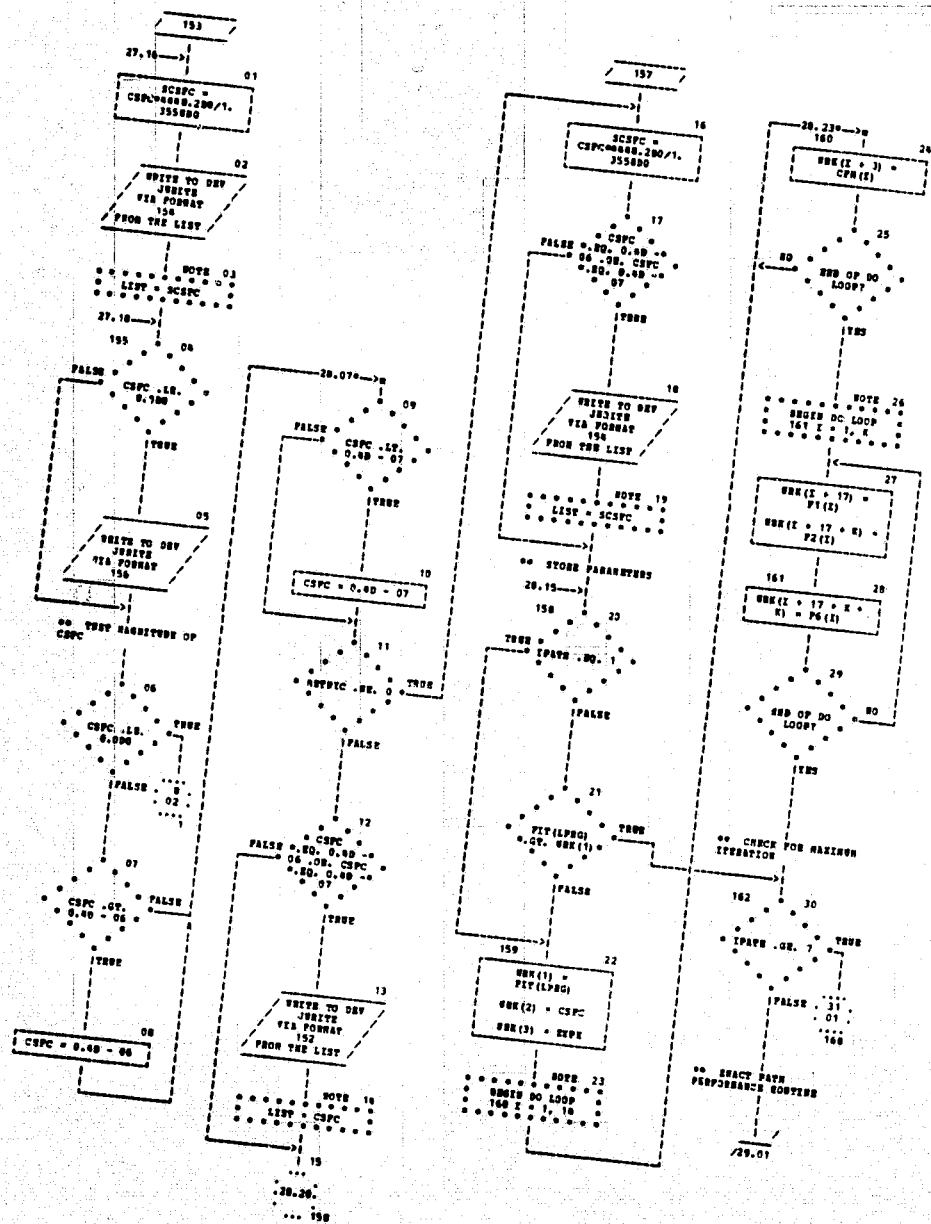
AUTOFLOW CHART SET

00002

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CHART TITLE - PROCEDURES



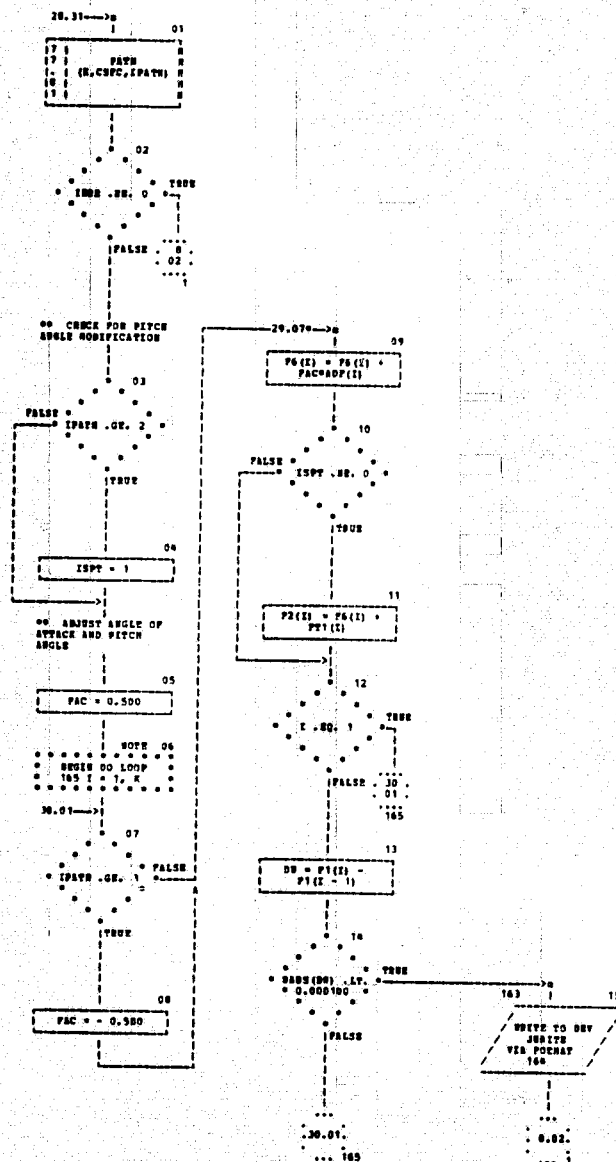


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AUTOFLOW CHART SET -

07922

PAGE 29

CHART TITLE - PROCEDURES

00 DEFINE BEST
PARAMETERS

20.30—>α
198 01

```

1  FIT(LPRG) =
2  USR (1)
3
4  CSFC = USR (2)
5
6  EXPE = USR (3)

```

```

      1  SOTB 02
      2  BEGIN DO LOOP
      3  T&9 I = 1, 10
      4  C C C

```

169 03
CPA (I) = FRK (I +
3)

NO • END OF DO •
• LOOP? •

1783

```

      * * * * *
      * BEGIN DO LOOP *
      * 170 I = 1, K *
      * * * * *

```

$$\begin{aligned} P_1(X) &= \text{WRK}(X + 17) \\ P_2(X) &= \text{WRK}(X + 17 + K) \end{aligned}$$

170 1 07

76(I) = SUR(I +
17 + R + N)

08
END OF DO

YES

•• WRITE PARAGRAPHS

00. EVACT TRAJECTORY
PREDICTION ROUTINE

11.220—>B

174 16
• •
• •
• •
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FALSE . 3
0
1

NOTE 1

LT. 1.00
10

1

YES

```

      * * * * * NOTE 2
      * * * * *
      * BEGIN DO LOOP
      * 175 * * * * *

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12.03-->|
|
-----
|      NUPH(I) =
|      INPATH(I)

```

•• DETERMINE POWER
AND LIFT COEFFICIENTS
FROM EQUATION OF

132.01

511



CHART TITLE - PROCEDURE

AUTOPLAN CHART SET -

07992

PAGE 32

31.23-->
** NORMAL TO FLIGHT
PATH OR ADJUST A
FLIGHT HEIGHTS

01

15: GDROR
16: (R,RRD,I)
17:

02

18: HPAER
19: (R,CSPC,RRD,
20: LPRG,PIT,PAER,
21: HPAER,RRD(I))

176

03

END OF DO
LOOP?
YES 31
22

** CALL MODEL
EXTRACTION ROUTINE

31.16-->
177

04

18: MODEL
19: (R,LPRG,PIT,
20: RRD)
21:

** DETERMINE
CONFIDENCE MAGNITUDES
FOR ANGLE OF ATTACK
AND PITCH
** ANGLE

18.00-->
178

05

HALP = 0.000
XVNE = 0.000

NOTE 06

BEGIN DO LOOP
179 I = 1, R
DO

33.05-->

07

HALP = HALP
(DAMP (CALPHA (I) -
76(I)) / ANGLE) **2

/33.04

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CHART TITLE - PROCEDURE

ASTROLOG CHART SET -

07002

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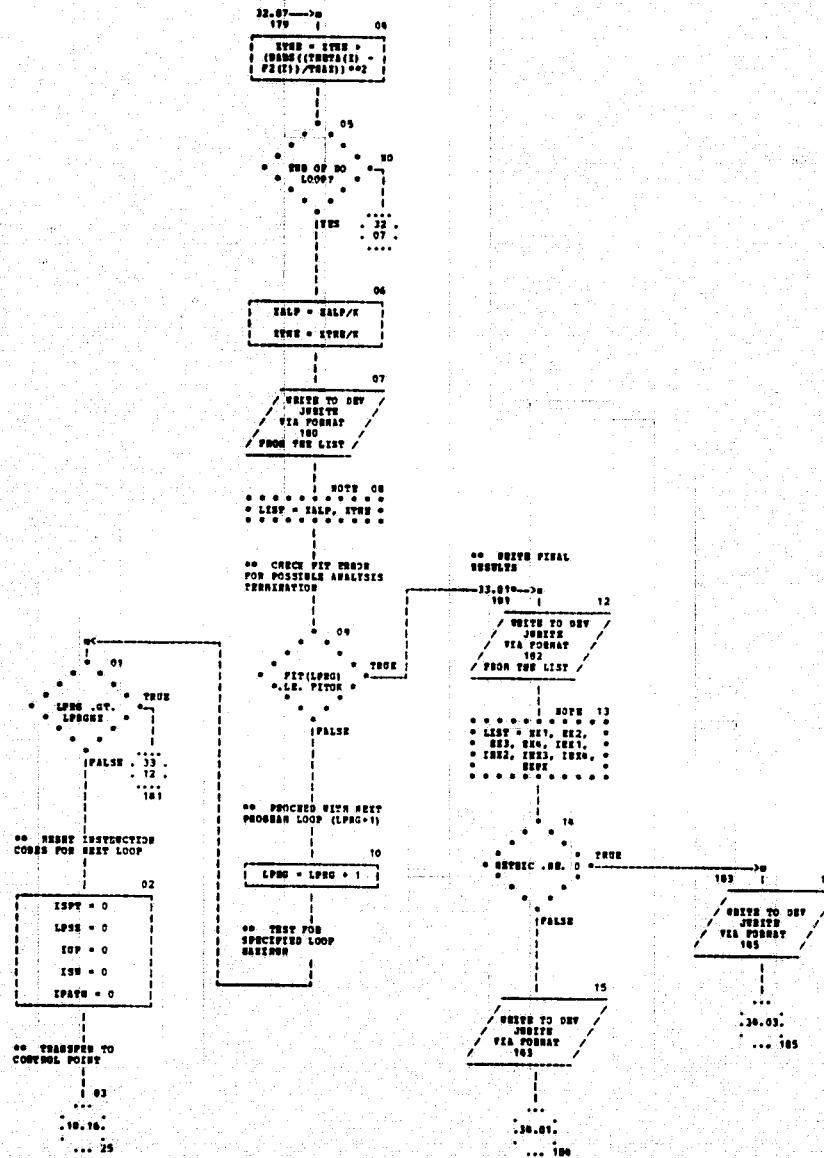
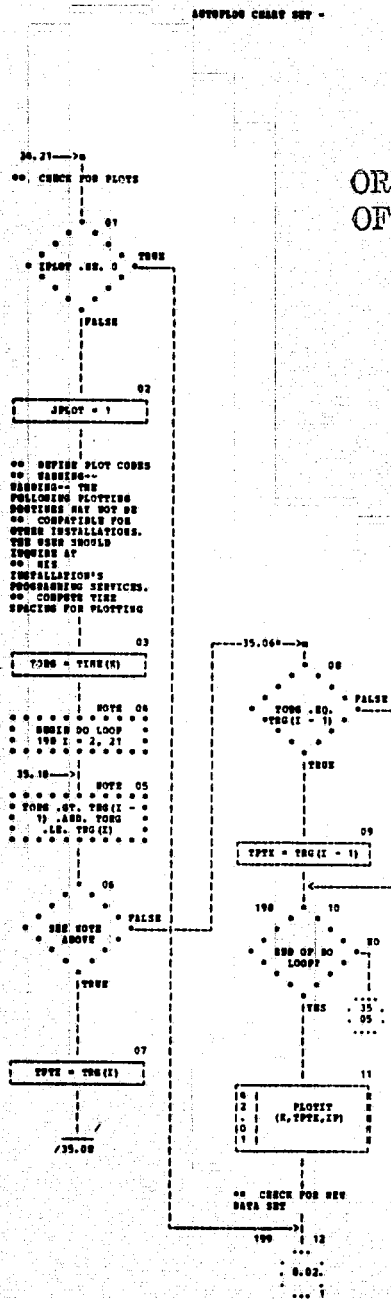


CHART TITLE - PROCEDURE

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CHART TITLE - SMOOTHS PLATE (R. 0578.10)

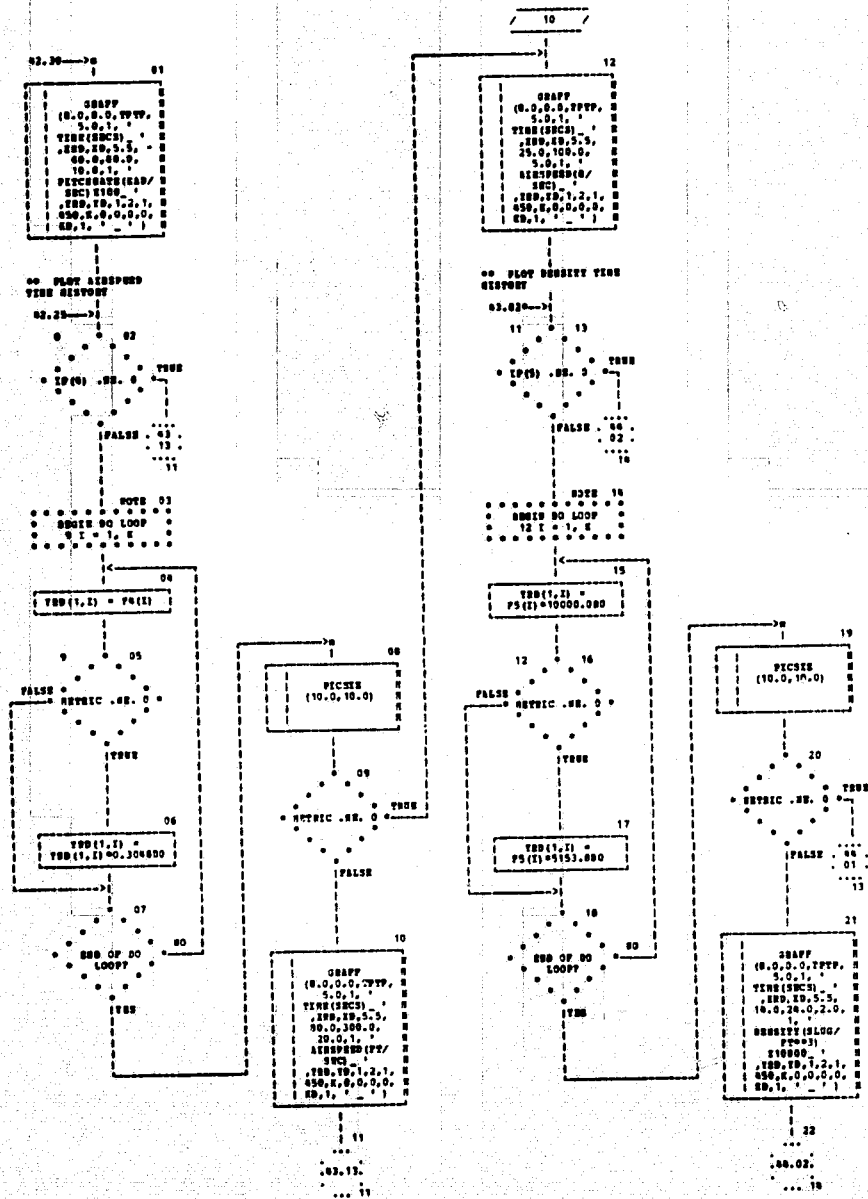
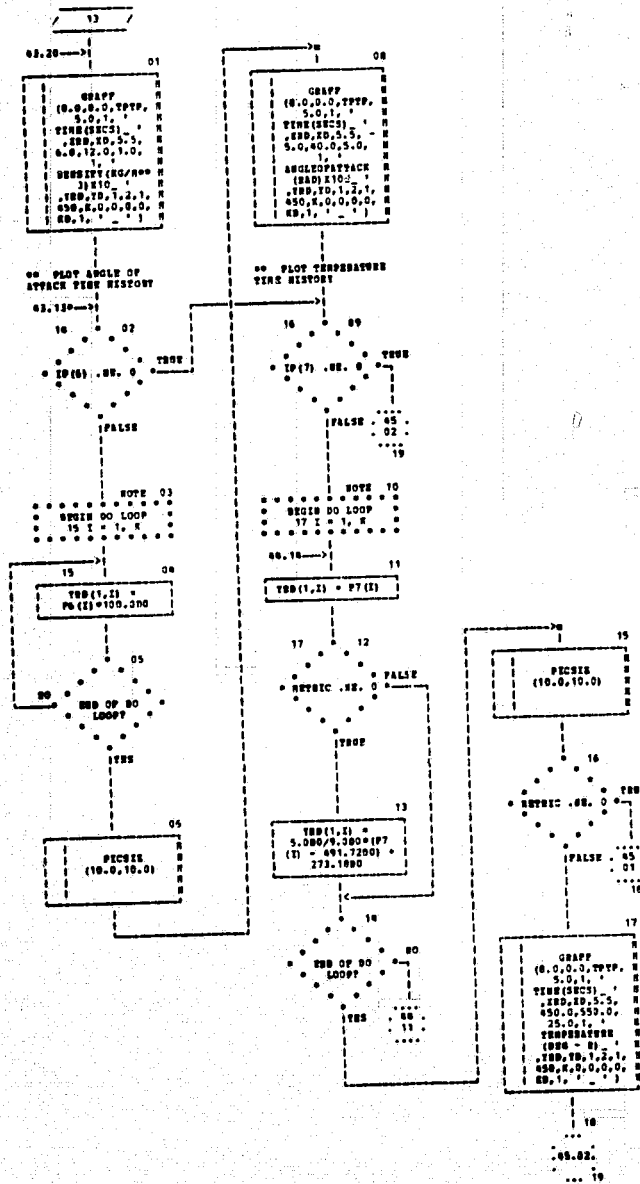


CHART TITLE - SUBROUTINE PLOTVIEW(TYPE,IP)

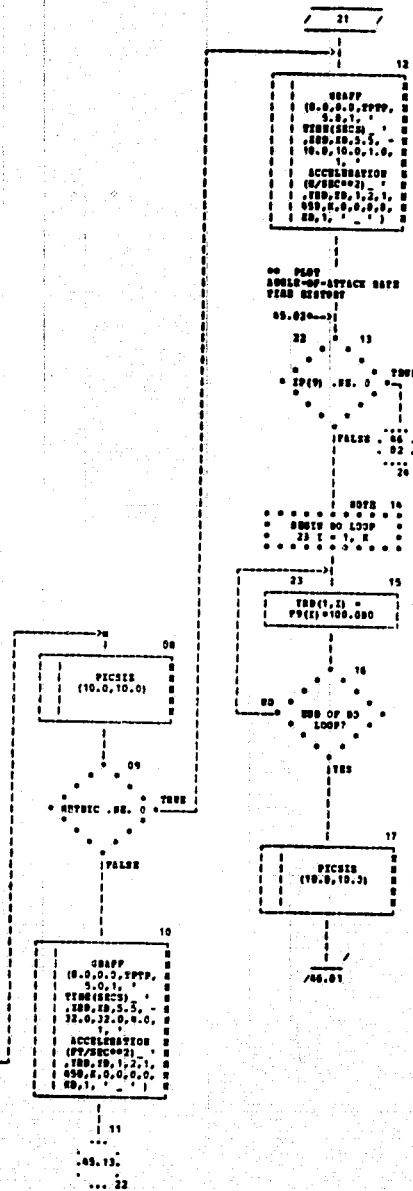


• P002

PAGE 09

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PAGE 27

CHART TITLE - SUBROUTINE PLOT12 (K,PT2,IP)





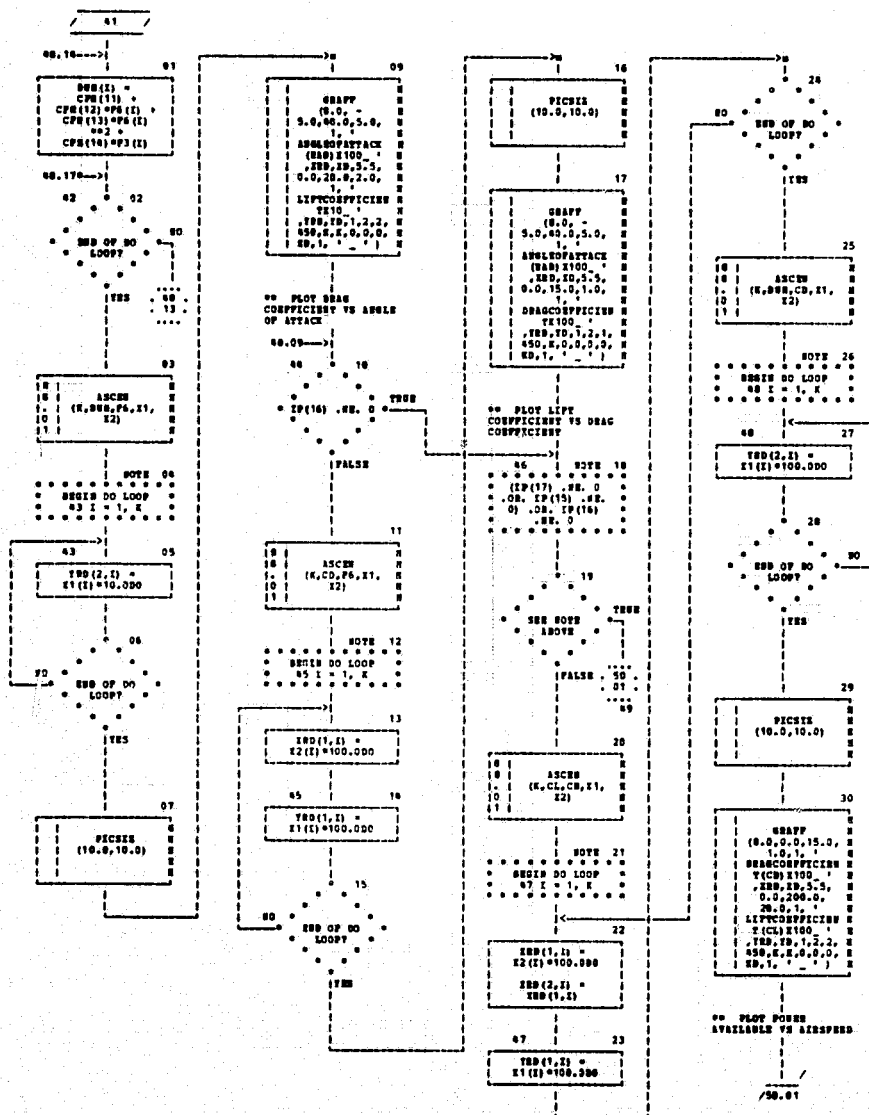
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AUTOFLOW CHART SET -

*T002

PAGE 49

CHART TITLE - SUBROUTINE PLOTIS(K,TYPE,IP)



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OF POOR QUALITY

AUTOFLOW CHART SET -

• **FD-202**

PAGE 52

CHART TITLE - SUBROUTINE AUTOS (N, LOG, FIT, END)

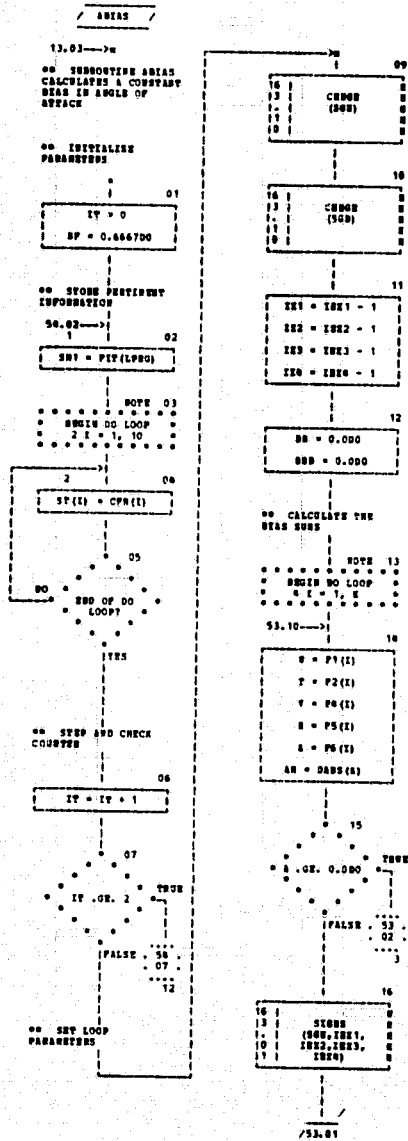
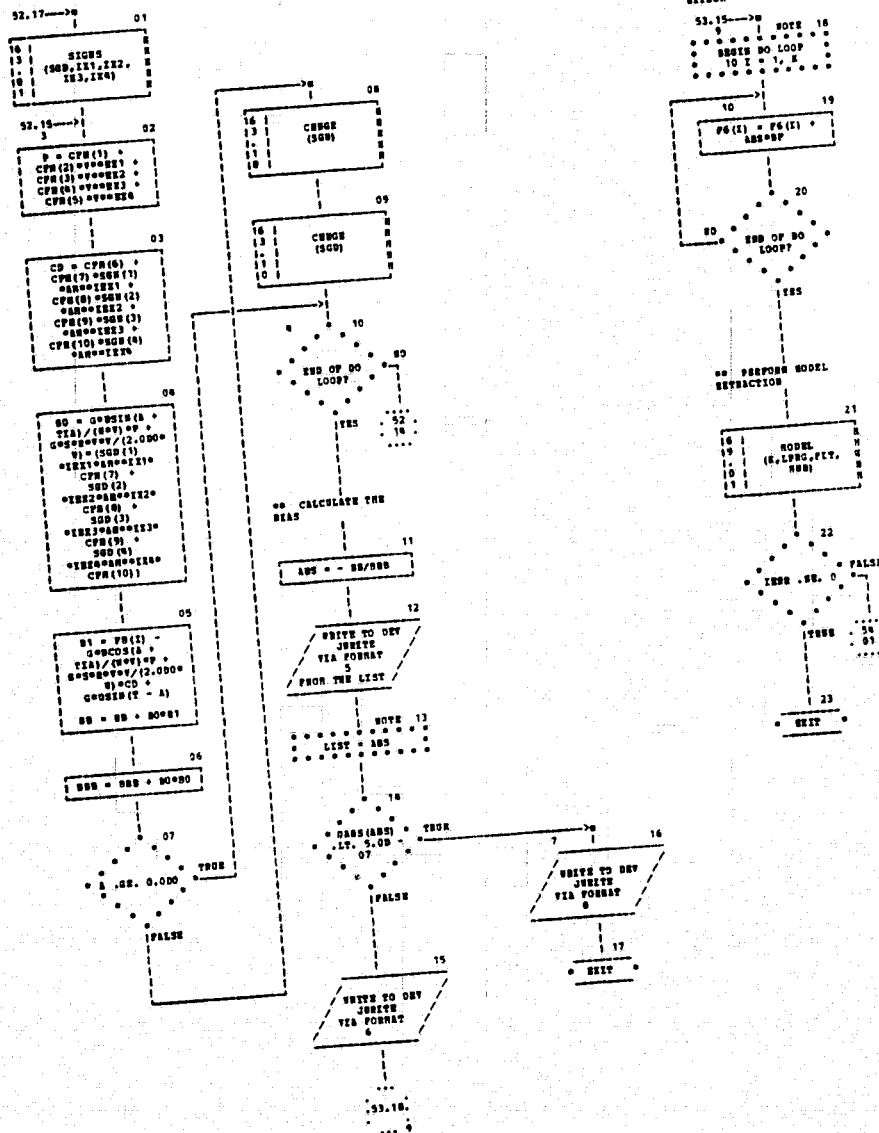


CHART TITLE - SUBROUTINE ASTRAR(E,LPHO,PIV,NOO)



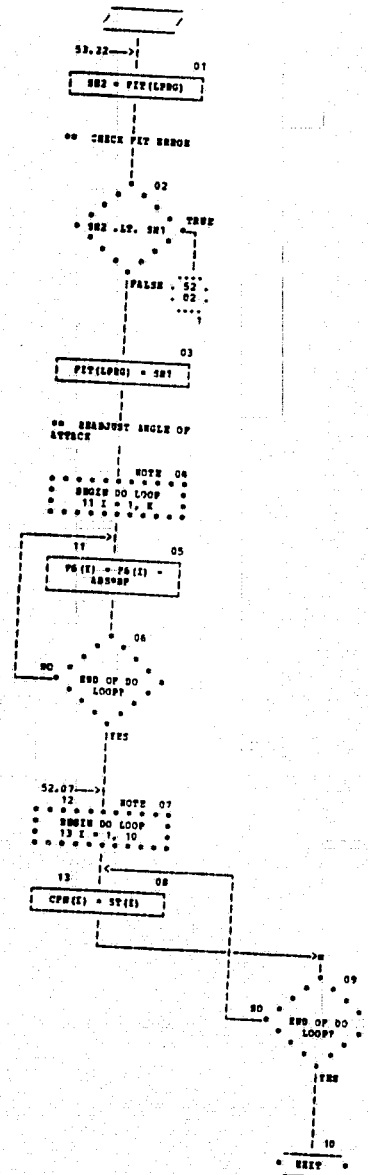
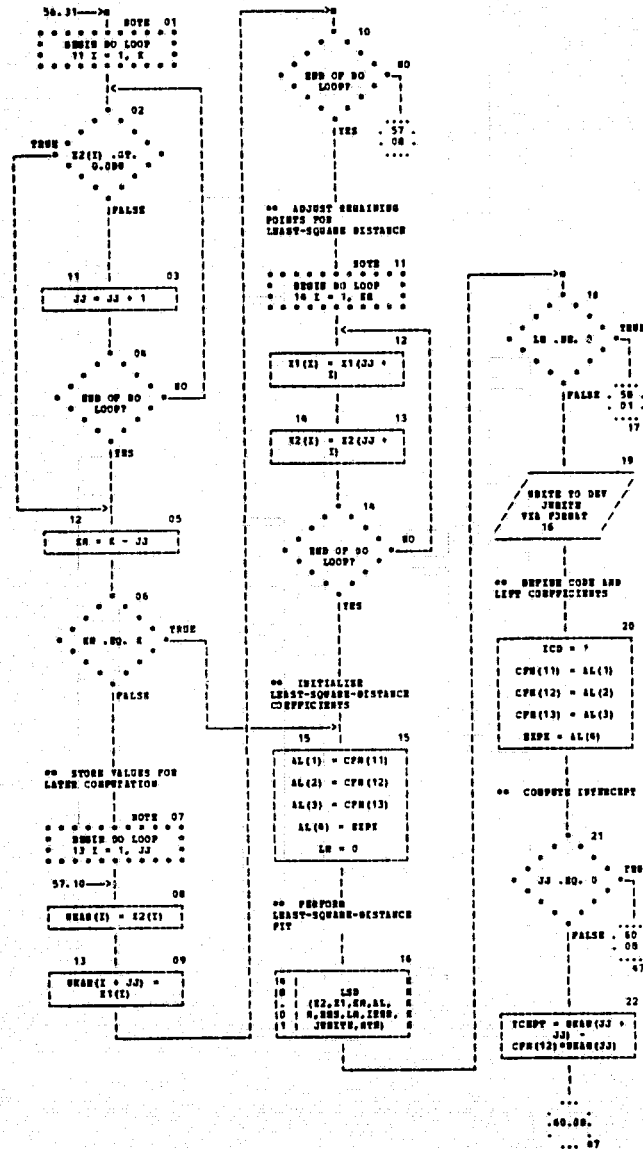


CHART TITLE - SMOGOUTLINE ALPHEL(K,LPRO,RUB,FIT)



CREDIT TITLE - SUBROUTINE ALP000(X,LP00,000,FTY)

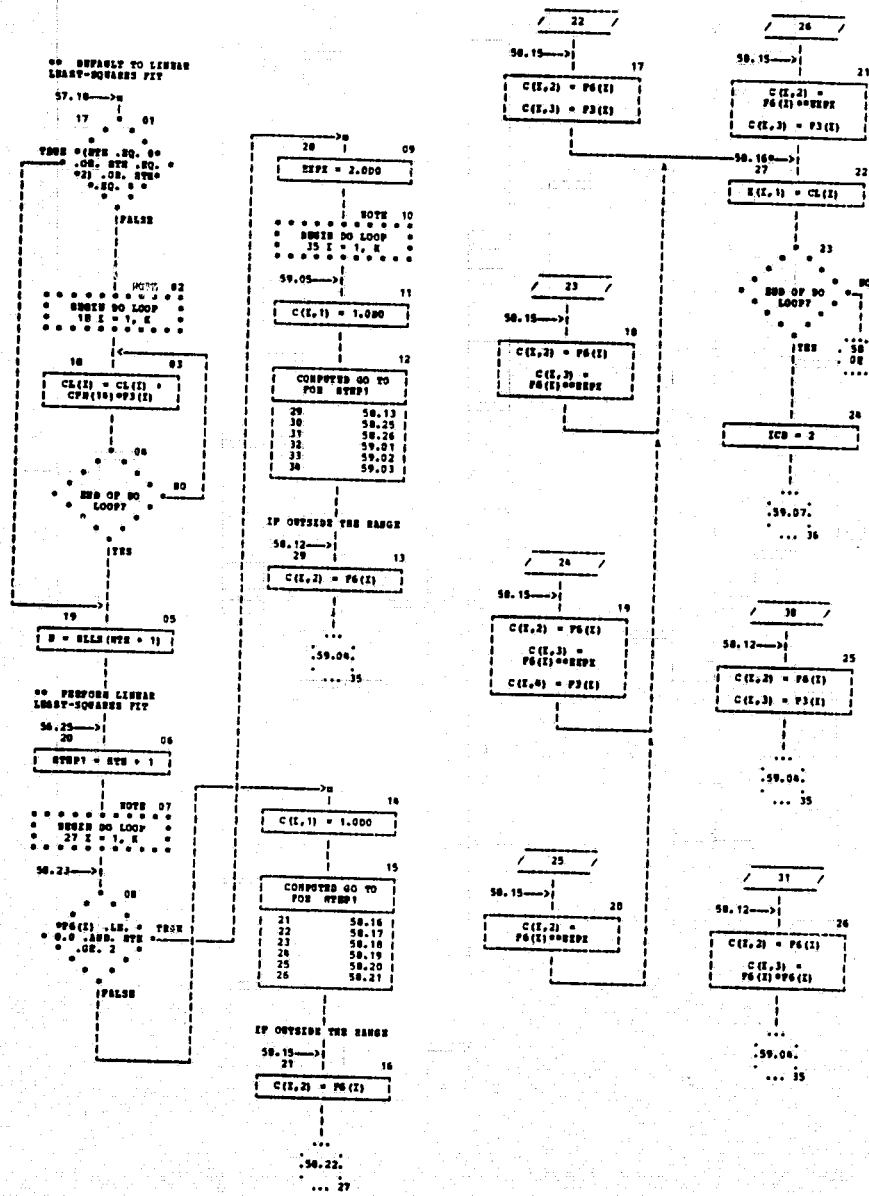
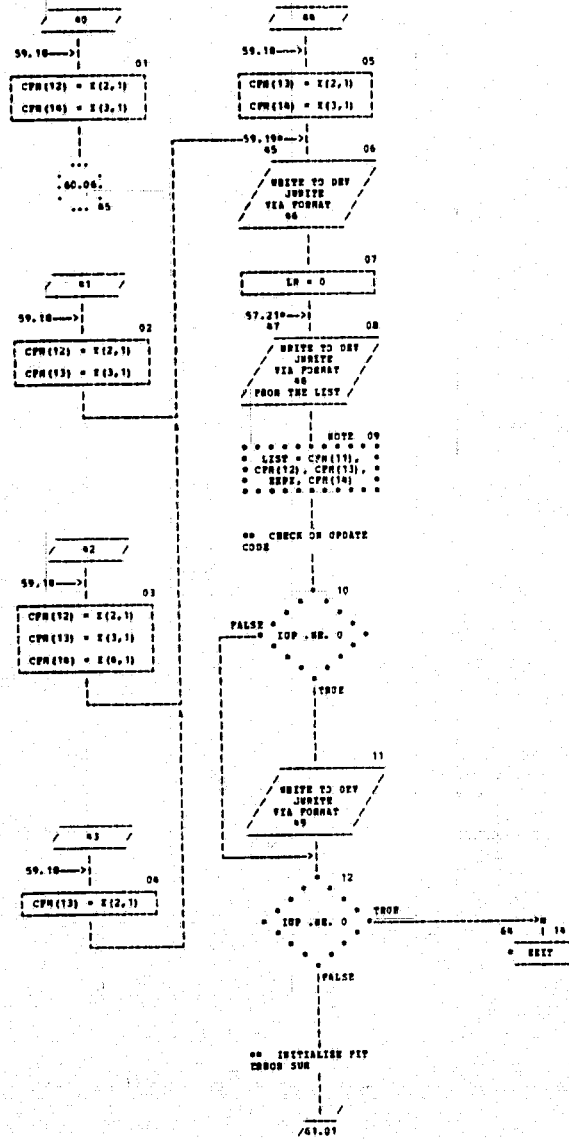


CHART TITLE - SUBROUTINE ALPDEL(X,LPNO,NOO,PIV)

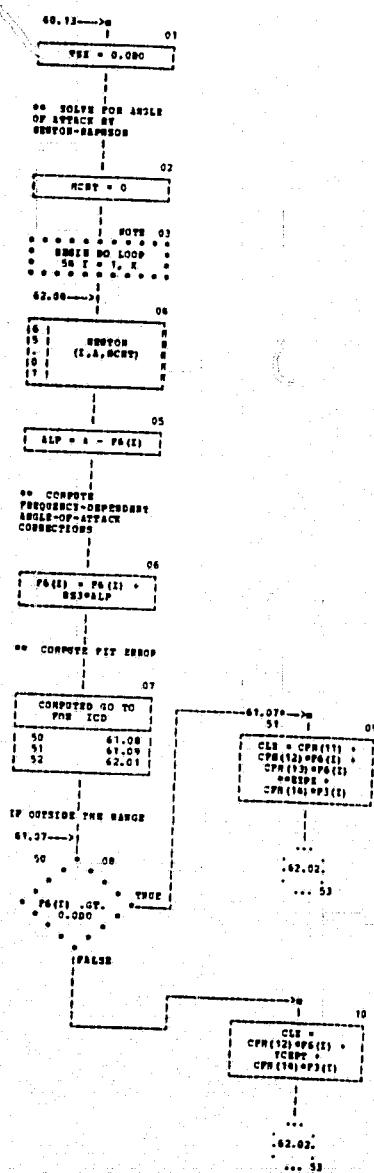


AUTOPLOD CRANT SET -

• PDB 2

PAGE 67

CHART TITLE - SUBROUTINE ALPHAL(R,LONG,ANG,PET)





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OF POOR QUALITY

AUTOFLOW CHART SET -

•P002

PAGE 03

CHART TITLE - SUBROUTINE ALPHAL(I, LOG, RHO, FIT)

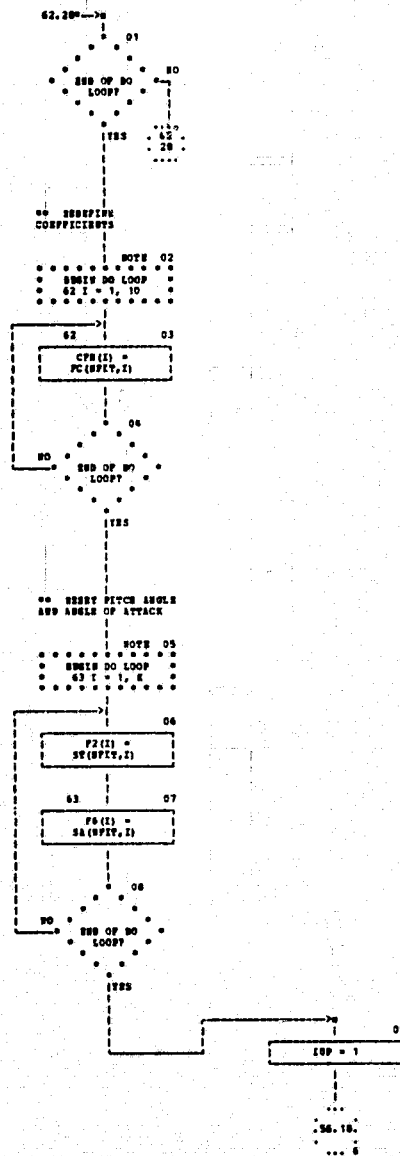
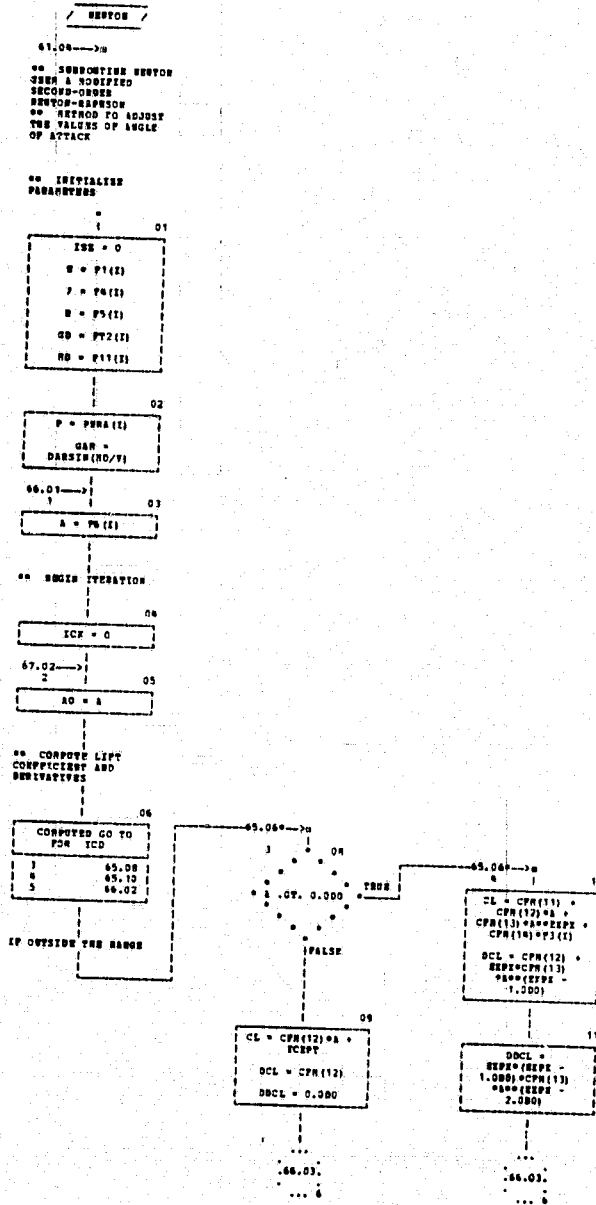
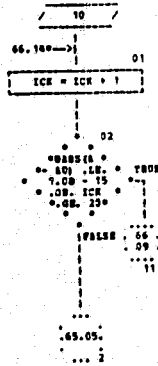


CHART TITLE - SUBROUTINE SECTOR(L,ALP,RCNT)



PAGE 46

CHART TITLE - SUBROUTINE NEWTON(X,ALP,NCN)



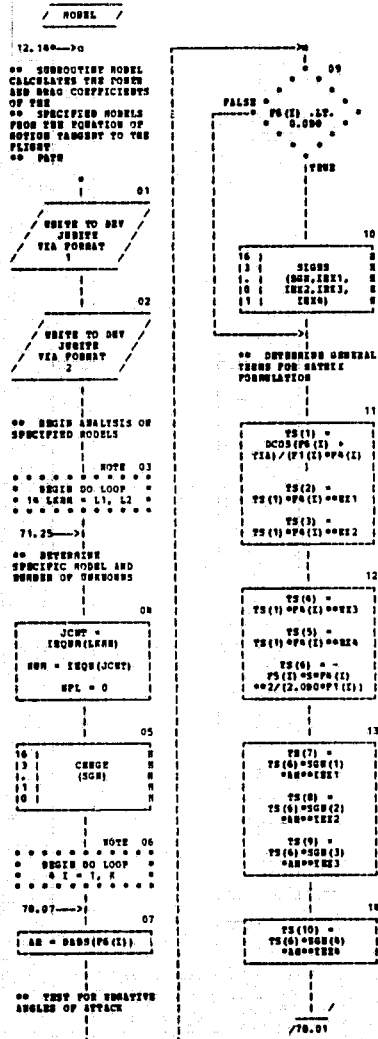
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ADTOP130 CRASH SET -

#P002

PAGE 69

CRASH TITLE - SUBROUTINE MODEL(LPM,PTZ,ABO)



540

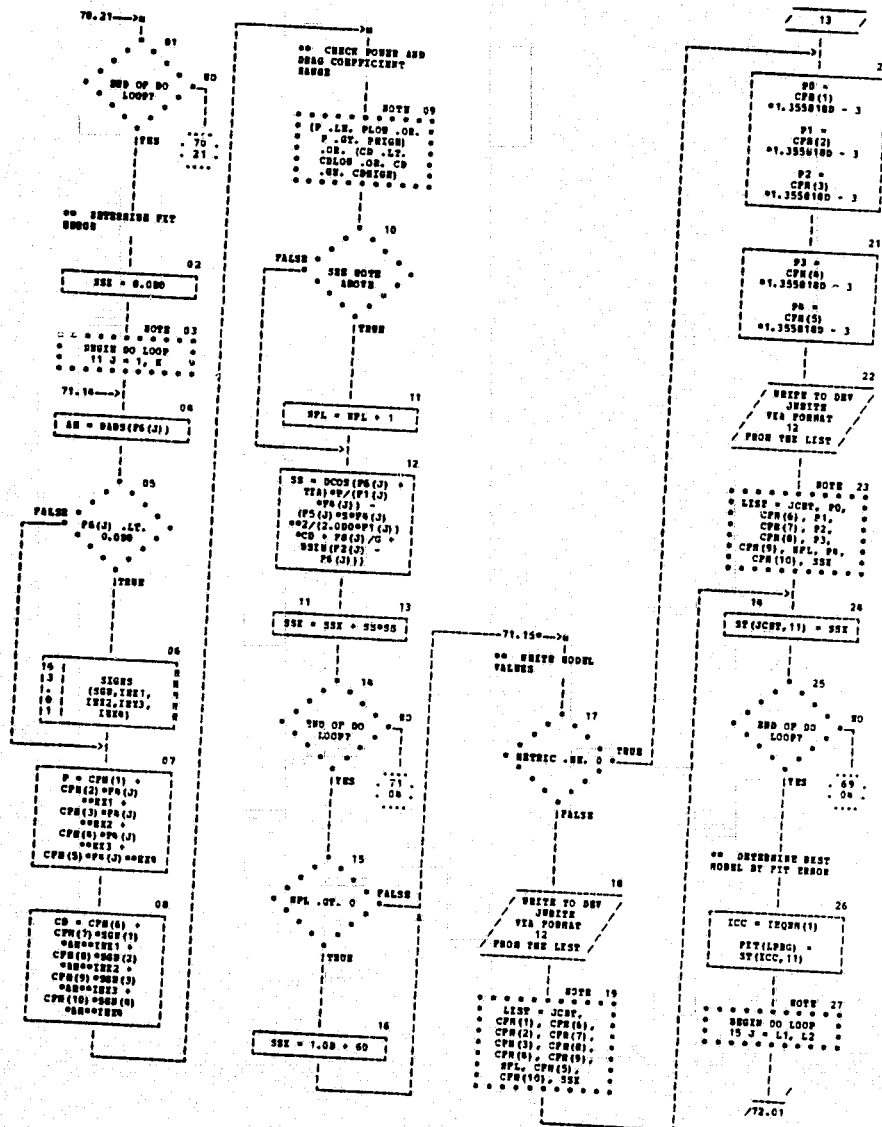
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OF POOR QUALITY

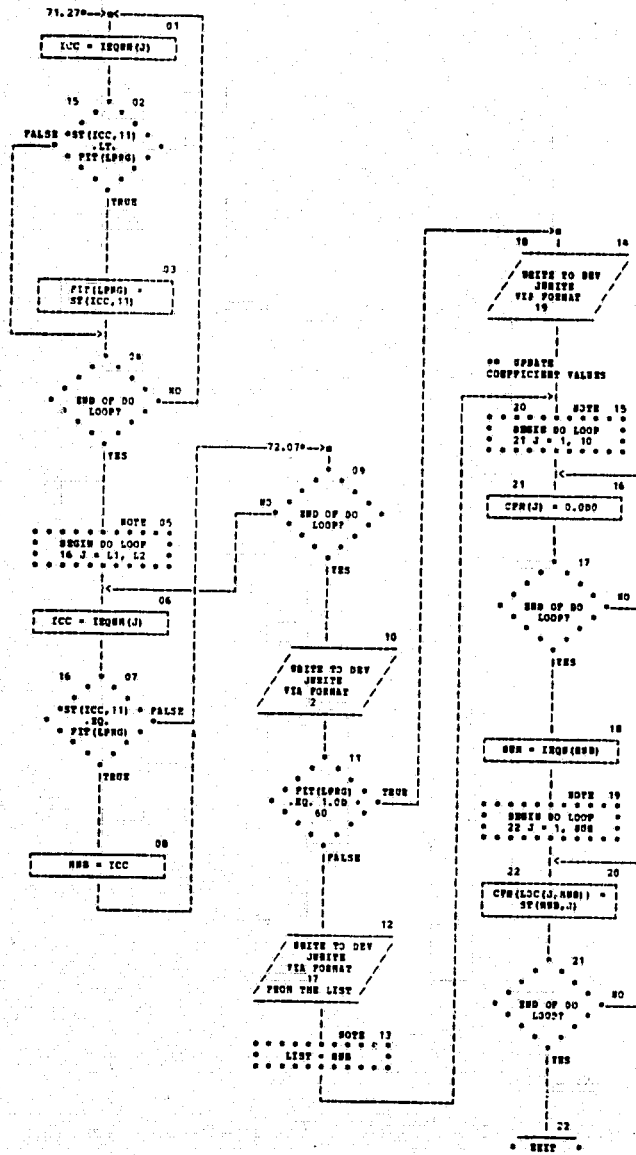
CRASH STYLE - SUBROUTINE MODEL(C, L, P, F, R, S)

APPROX CRASH SET -

CPH2

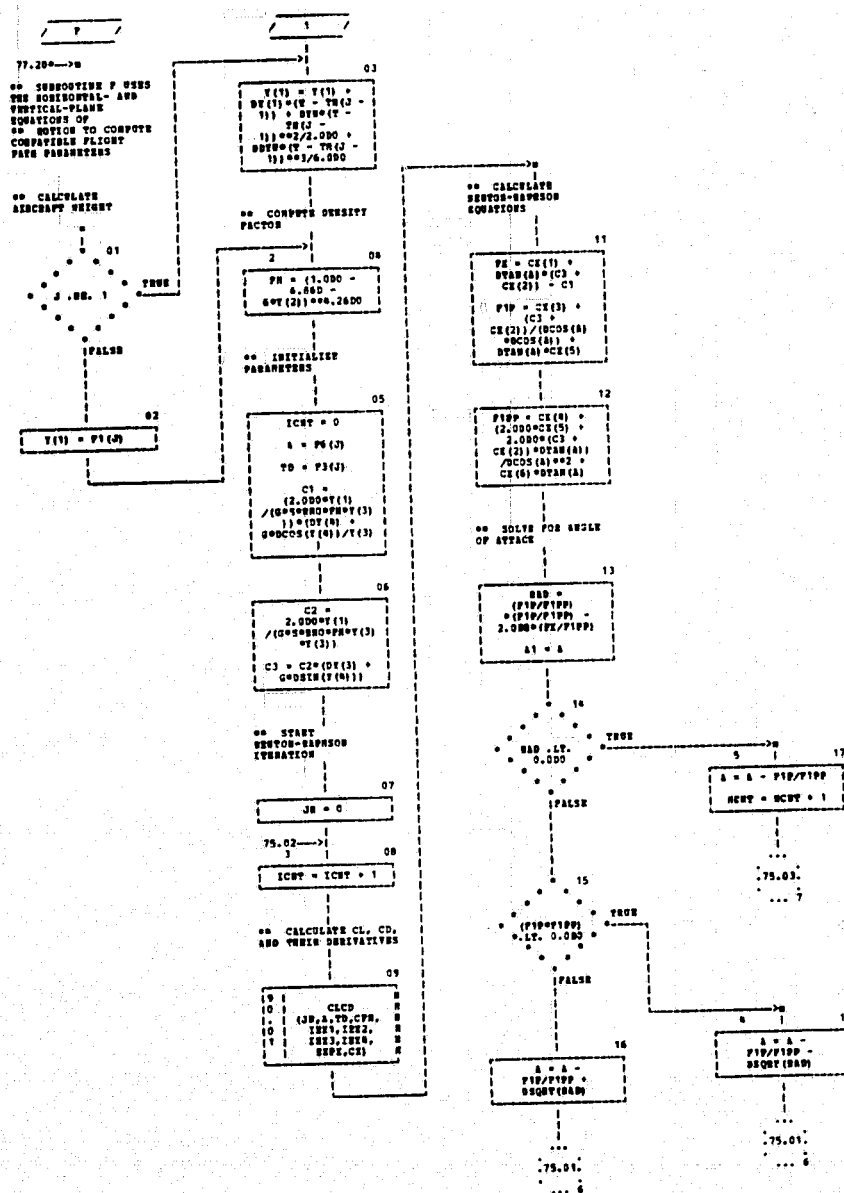
PAGE 71





PAGE 70

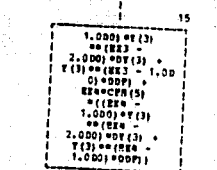
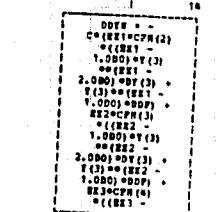
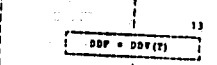
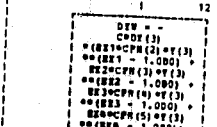
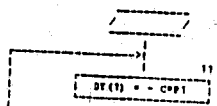
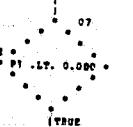
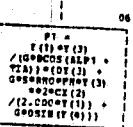
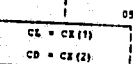
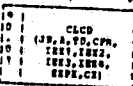
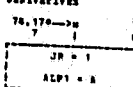
CHART TITLE - SUBROUTINE P(P,T,BY,C,KJE,J,IPATH,NCST,NCST)



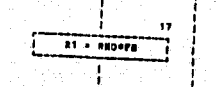
00 TEST FOR
CONVERGENCE ON
MAXIMUM ITERATION



00 UPDATE CL, CD,
PODS, AND WEIGHT
DERIVATIVES



00 COMPUTE PARTIAL
DERIVATIVES OF
FUNCTION OF REGION

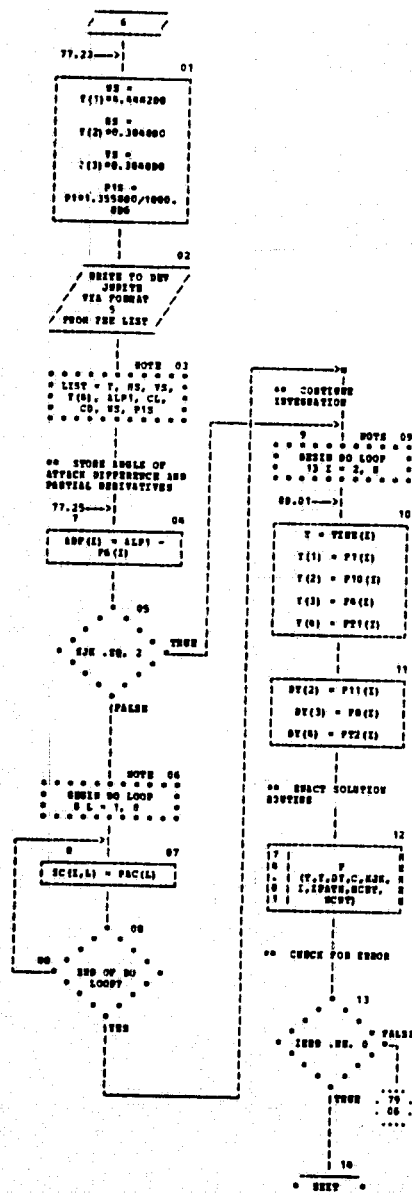


PAGE 77

CHART TITLE - SUBROUTINE PATH(D,C,IPATH)



CHART TITLE - SUBROUTINE PDPH(U,C,IVATH)



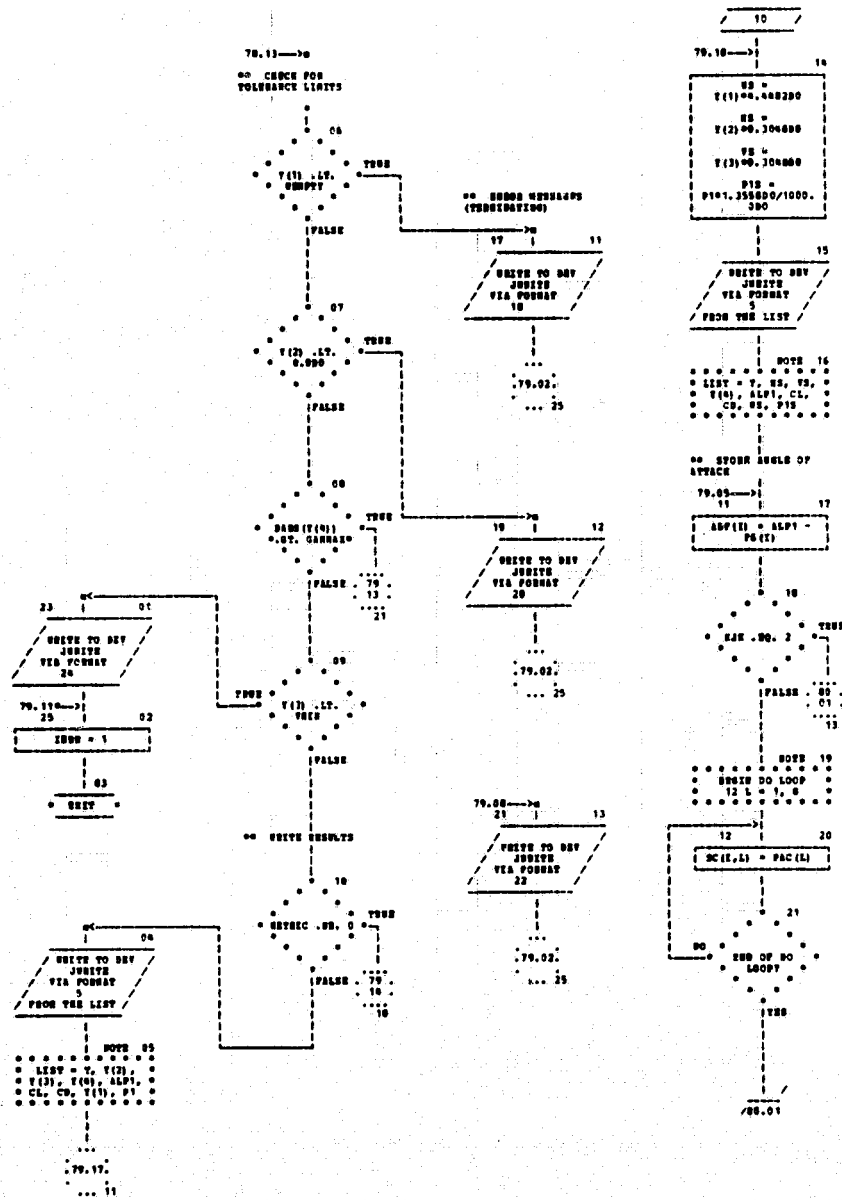
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AUTOPLOM CREDIT REV -

0002

PAGE 79

CREDIT TITLE - AUTOPLOM CREDIT REV (C, 10/1/70)



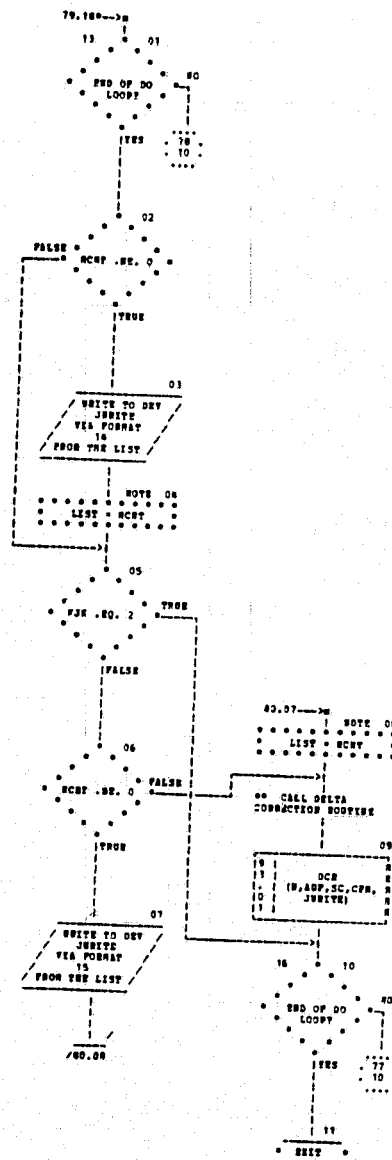
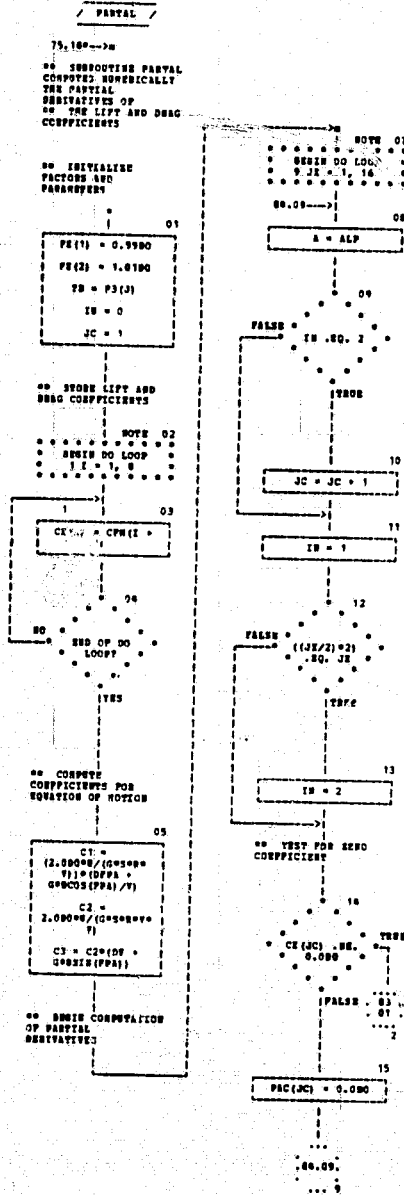
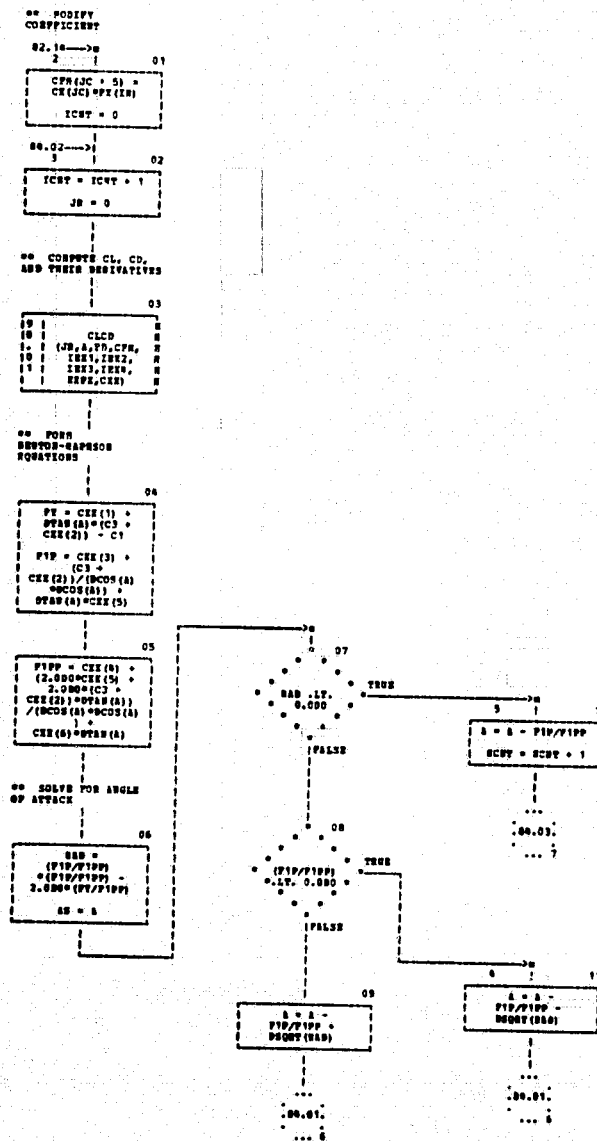


CHART TITLE - SUBROUTINE PARTIAL(J, U, D, ALP, T, DF, DN, PPA, OPFA, PAC, SCUT)



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OF POOR QUALITY



51.090--> NOTE 01
 DARS (AS - A) .LT.
 1.50 - 15.00.
 ICNT .05. 20



CHART TITLE - SUBROUTINE FITERR(P,I,J)

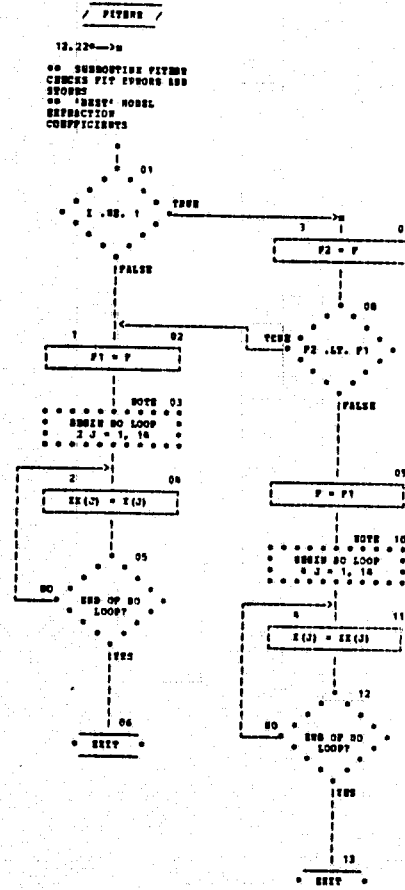
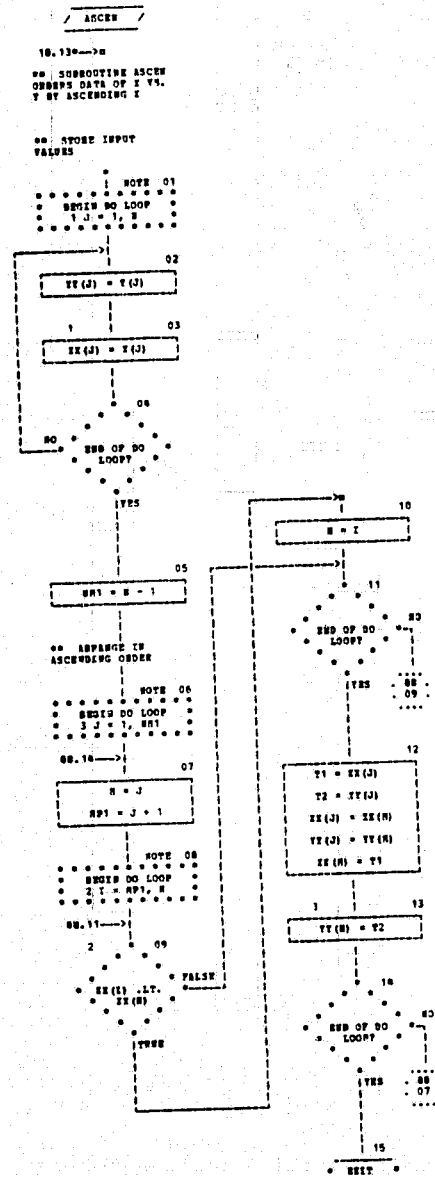
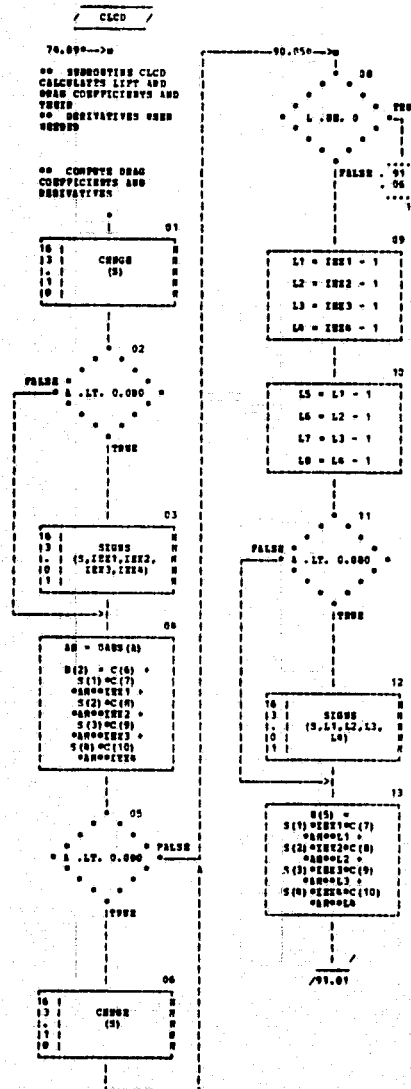


CHART TITLE - SUBROUTINE ASCEN(U,V,X,Y,XI)



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CHART TITLE - SUBROUTINE CLCD(L,PH,C,ISE1,ISE2,ISE3,ISE4,IE,0)



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CARDY TITLE - SUBROUTINE CLCD(L,A,PH,C,IX1,IX2,IX3,IX4,OX,B)

```

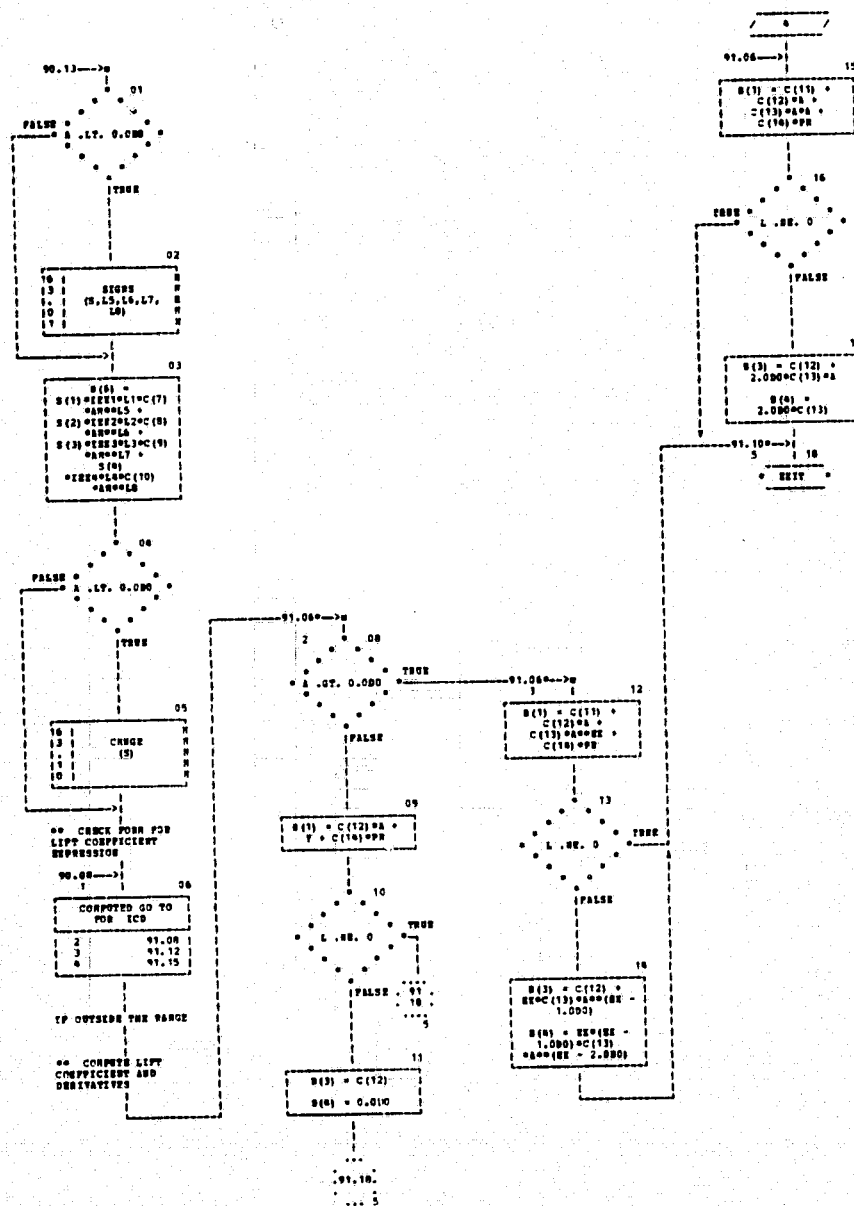
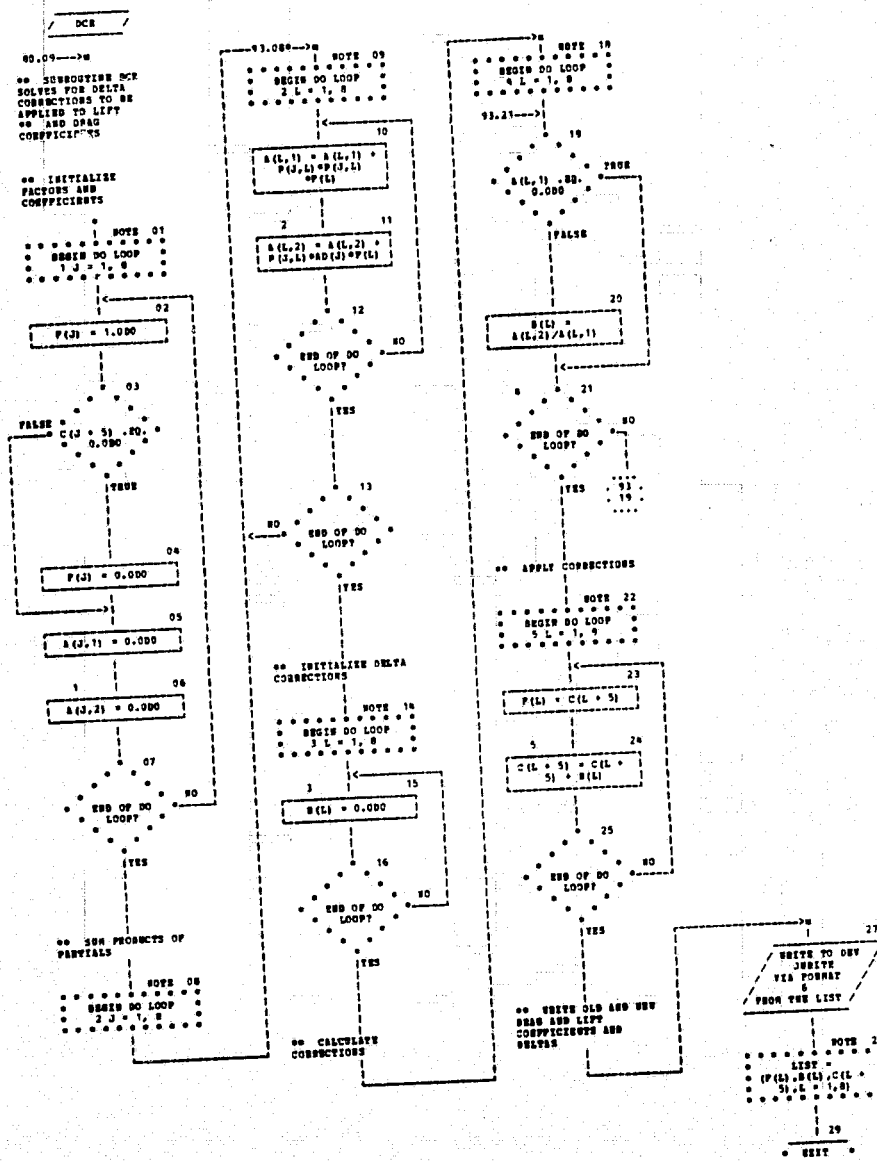


CHART TITLE - SUBROUTINE DCR (H,AB,P,C,JEUNITS)



OPTION /

CHART TITLE - SUBROUTINE SPGLINE(N,T,X,AA,IC)

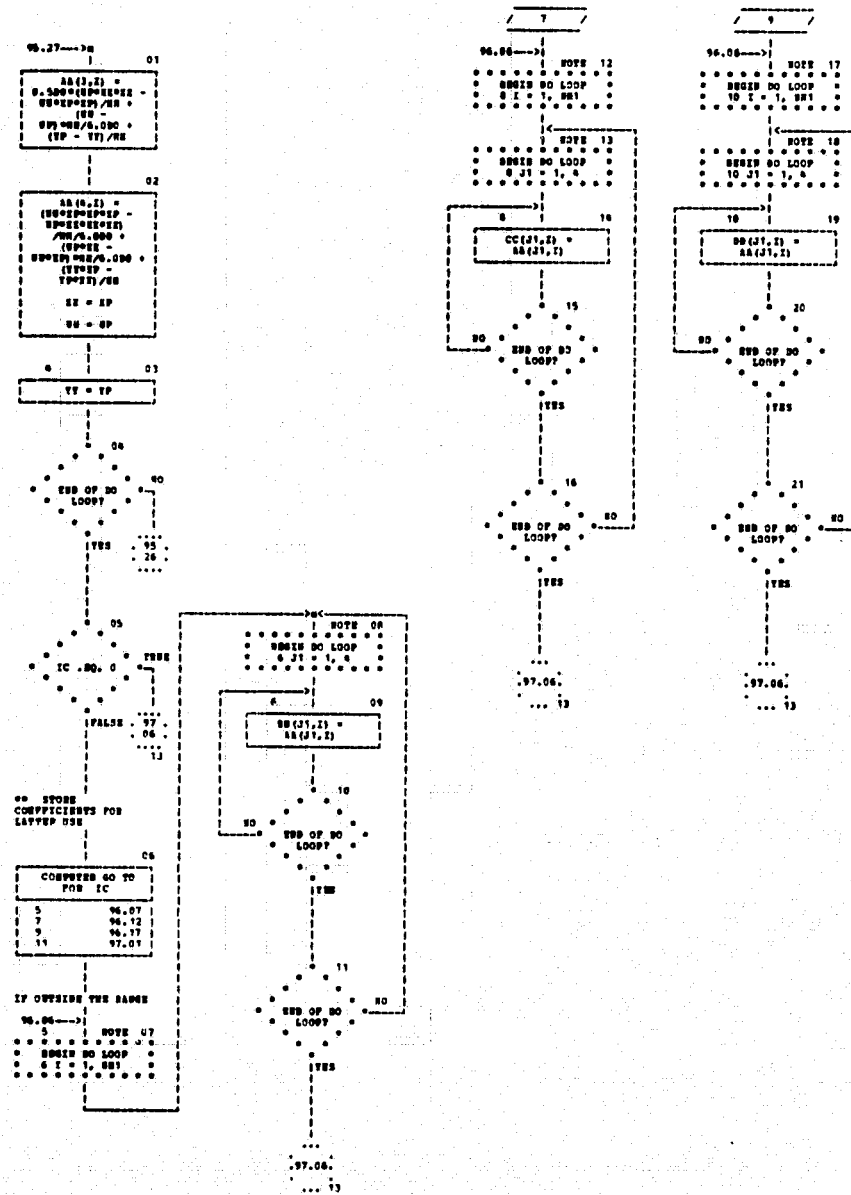
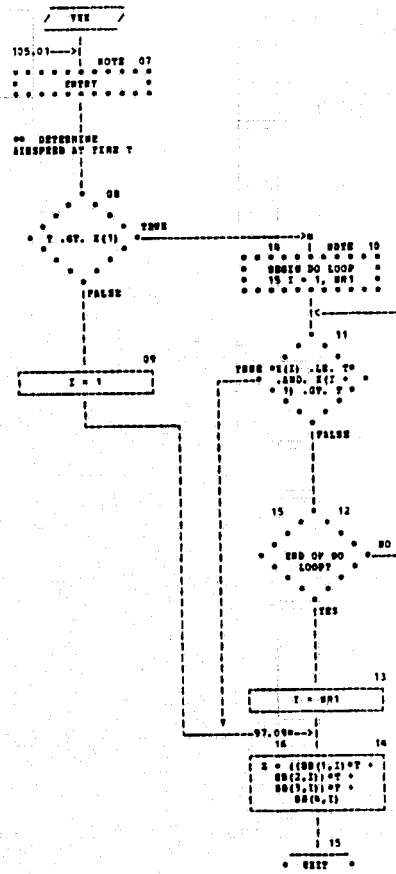
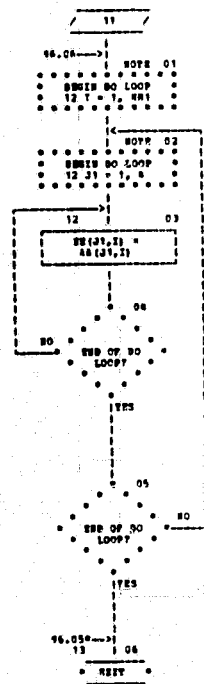
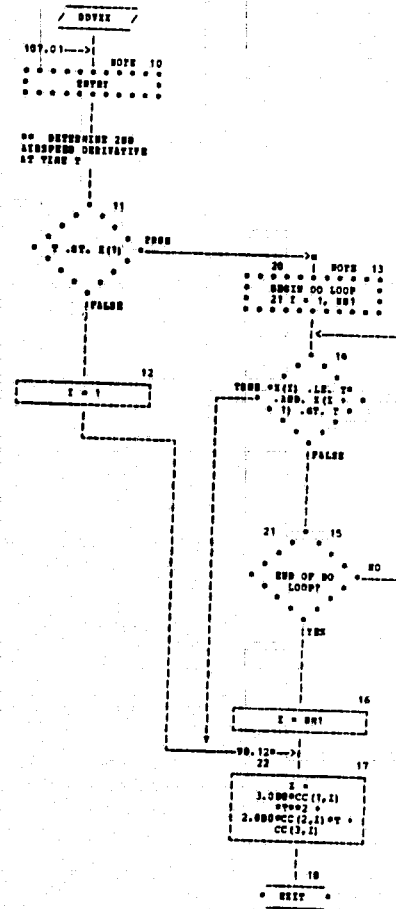
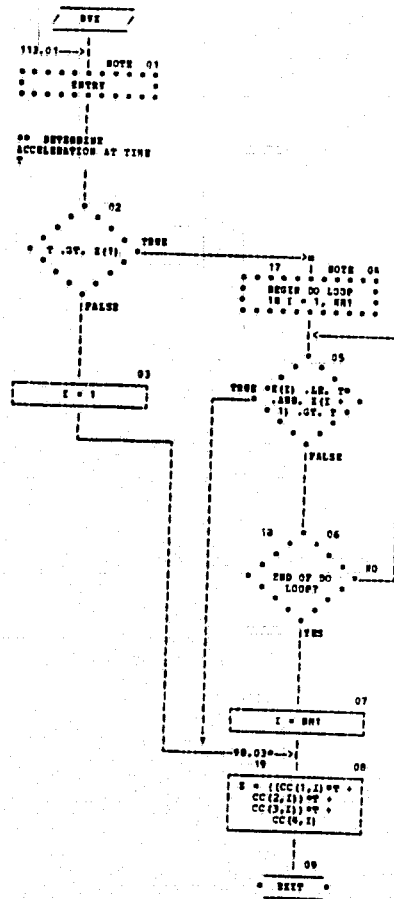


CHART TITLE - SUBROUTINE SPLIST(M,I,X,AA,IC)



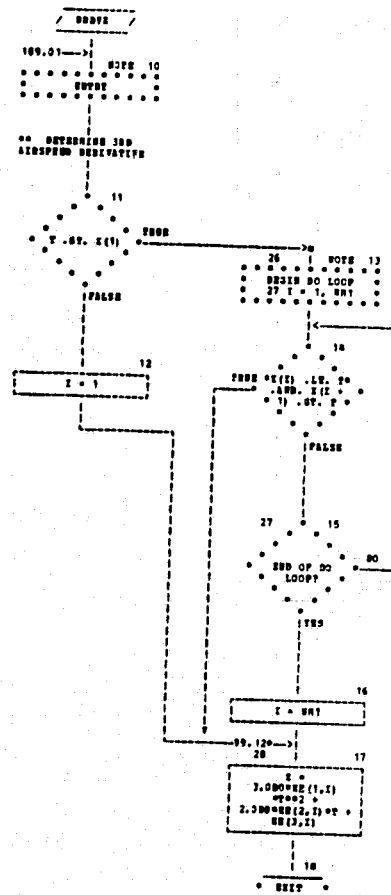


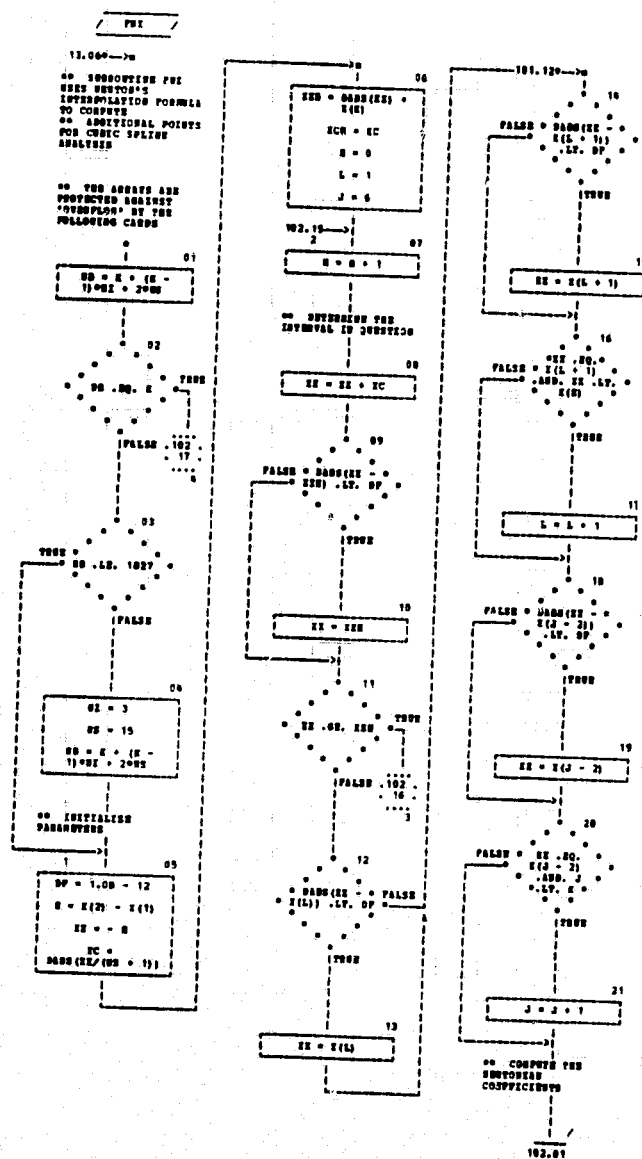
一、
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 三、
 四、
 五、
 六、
 七、
 八、
 九、
 十、

• 4982

PAGE 99

CRABT TITLE - SUBROUTINE SPLINE(U,V,Z,AA,IC)





PAGE 102

CHART TITLE - SUBROUTINE FBI (E,F,I,PP,PPP,NO,NS,NI,IC)



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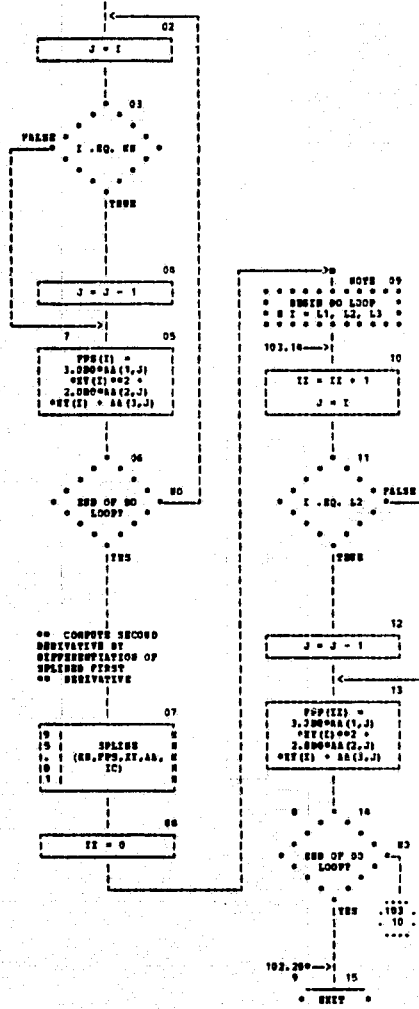
00 COMPUTE ALL FIRST
DERIVATIVES FOR
SPLINE FIT

```

```

102.28-->
      6      1      NOTE 01
* * * * *
*   BEGIN DO LOOP   *
*   7 I = 1, KN     *
* * * * *

```



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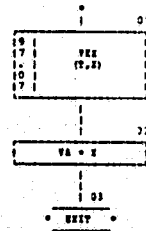
AUTOFLOR CHART SET -

*P002

PAGE 105

CHART TITLE - FUNCTION VA(T)

** FUNCTION VA (RPM
SPLINE DETERMINES
THE AIRSPEED AT TIME
T



AUTOFLOR CHART SET -

*P002

PAGE 107

CHART TITLE - FUNCTION DDV(T)

** FUNCTION DDV
(RPM SPLINE)
DETERMINES THE SECOND
DERIVATIVE OF
** AIRSPEED AT TIME
T

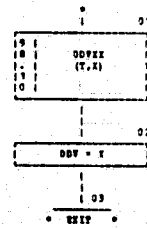


CHART TITLE - FUNCTION DOBV(T)

** FUNCTION DOBV
 (WITH SPLINE)
 DETERMINES THE THIRD
 DERIVATIVE OF
 ** ADOBV AT TIME
 T

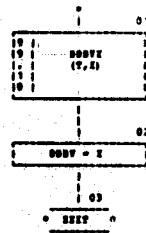
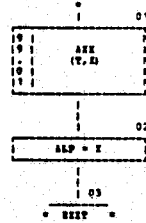


CHART TITLE - FUNCTION ALP(T)

** FUNCTION ALP
 (WITH SPLINE)
 DETERMINES THE ANGLE
 OF ATTACK AT
 ** TIME T



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OF POOR QUALITY

NOTOPUS CHART SET -

07002

PAGE 113

CHART TITLE - FUNCTION DVA(7)

00 FUNCTION DVA
(WITH SPLINE)
OUTLINES THE PULSE
SEQUENCE OF
00 RESUME

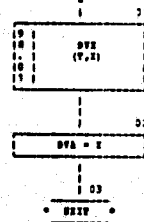
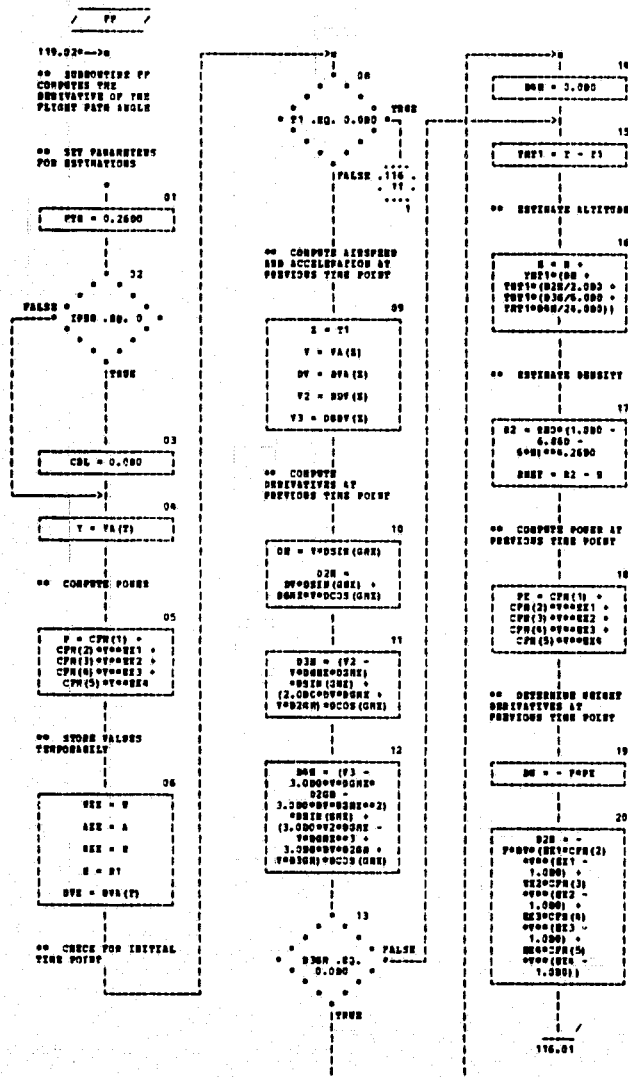


CHART TITLE - SHOOTDOWN PP (U, V, DTY, P, IPRN, OBAR, AV, IEP)



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OF POOR QUALITY

•FBI

PAGE 116

CHART TITLE - SUBROUTINE FFT(T,IT,BUT,P,IPRQ,OSAN,AP,IEP)

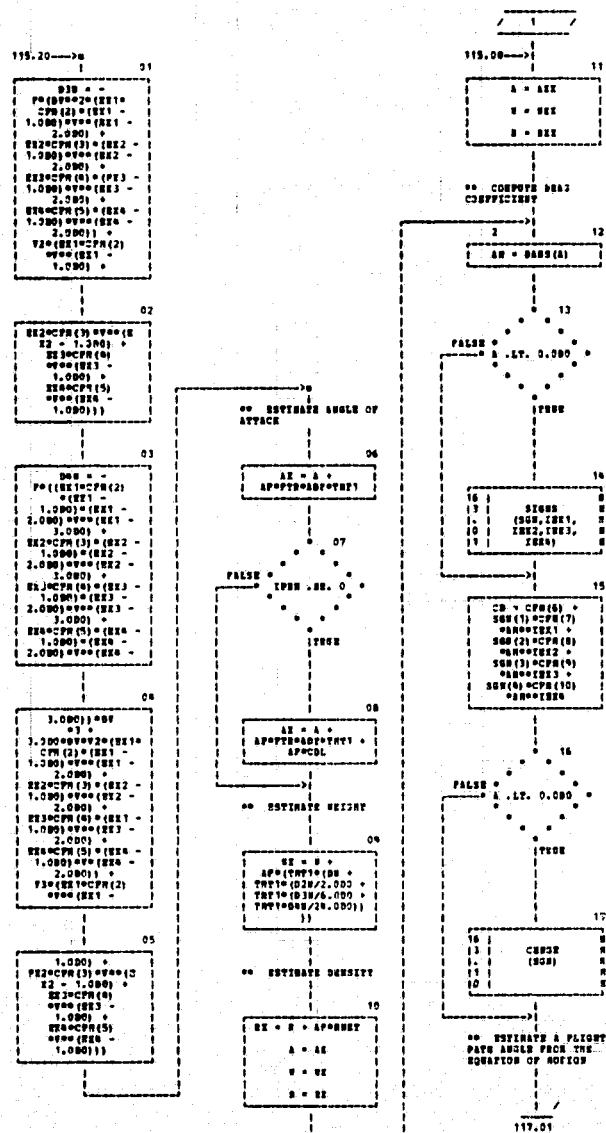
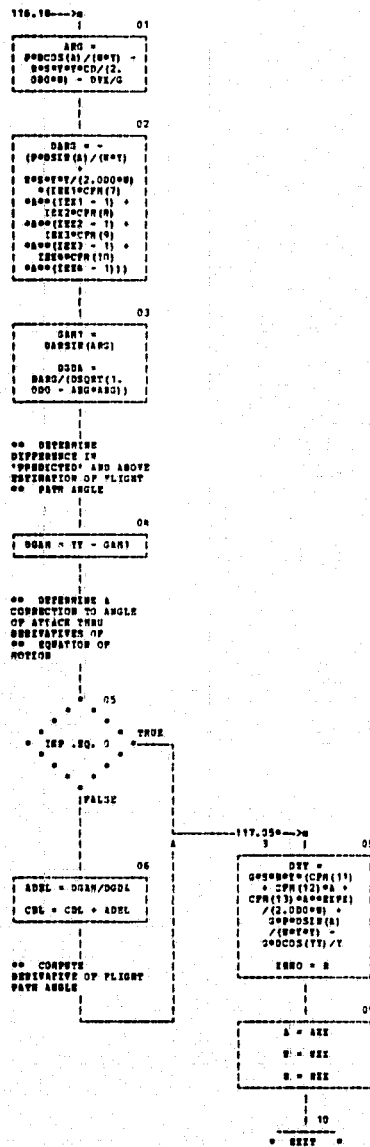


CHART TITLE - SUBROUTINE PP(T,TE,DT,F,IPR,DCAN,AF,INP)



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OF POOR QUALITY

AUTOFLOW CHART SUB -

*P002

PAGE 119

CHART TITLE - SUBROUTINE TRENOR(N,IX,IV,D2Y,D3Y,D4Y,ISBT,P,IPR0,EX,IN)

TRENOR
193.200-->M
** SUBROUTINE TRENOR
PREDICTS A FLIGHT
PATH TRAJECTORY

** INITIALIZE
PARAMETERS

01
AP = 0.000
IMP = 0

** COMPUTE
DERIVATIVE AT
BEGINNING OF INTERVAL

02
11 PP
15 (EX,IV,D2Y,P,
10 IPR0,D2AR,AP,
17 IMP)

03
D2(7) = D2Y
IV = EX

** TEST FOR
INITIALIZATION

04
ISBT
119.10.
... 3

** INITIALIZE
PARAMETERS

05
1. NOTE 05
2. WHEN DO LOOP
3. 2 I = 1, 7

06
Y(I) = IV
D2(I) = D2Y

07
2
X(I) = EX

08
END OF DO
LOOP

YES

** BEGIN RANGE KOTPA

09
LE = 6
K = 1
ISBT = 1

120.01.
... 6

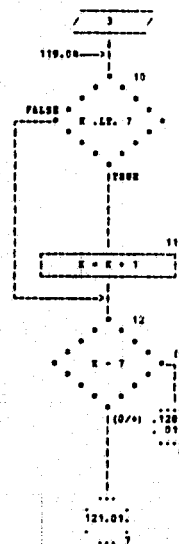


CHART TITLE - SUBROUTINE TRENDS (R, X, Y, DZ, DZT, DZT, DZT, P, IPRN, AN, IS)

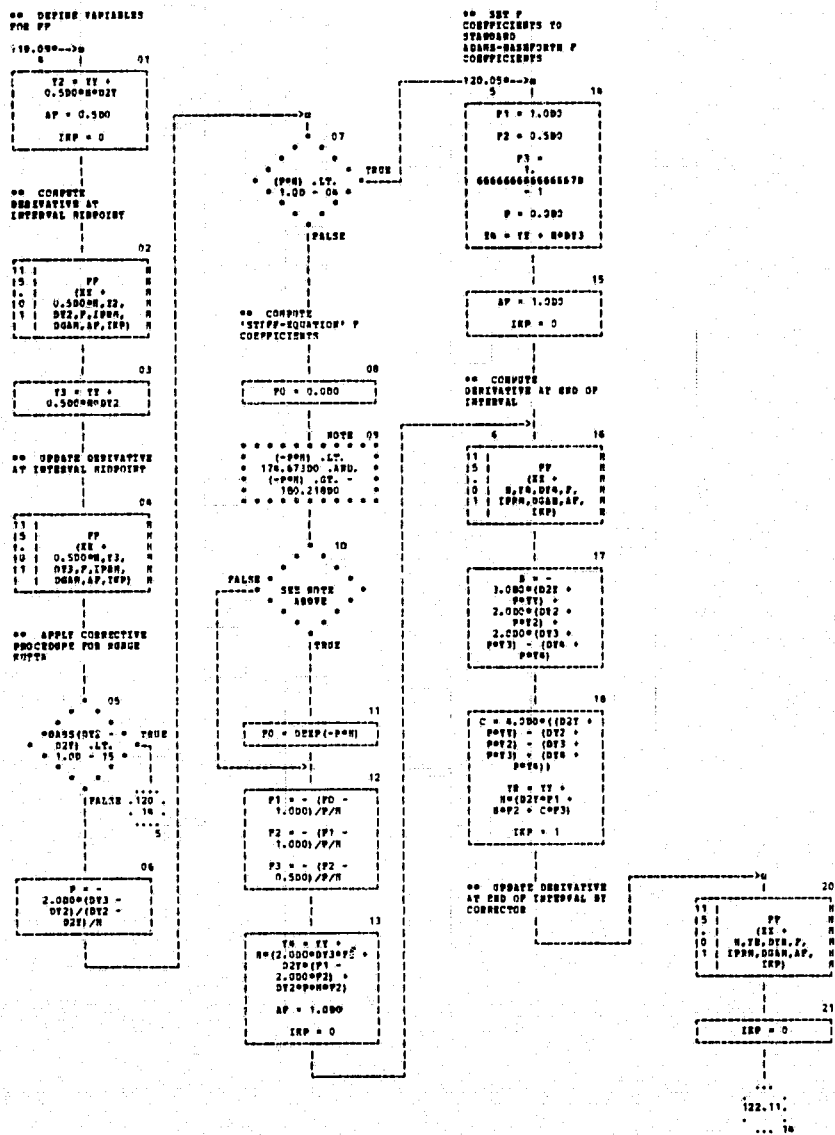
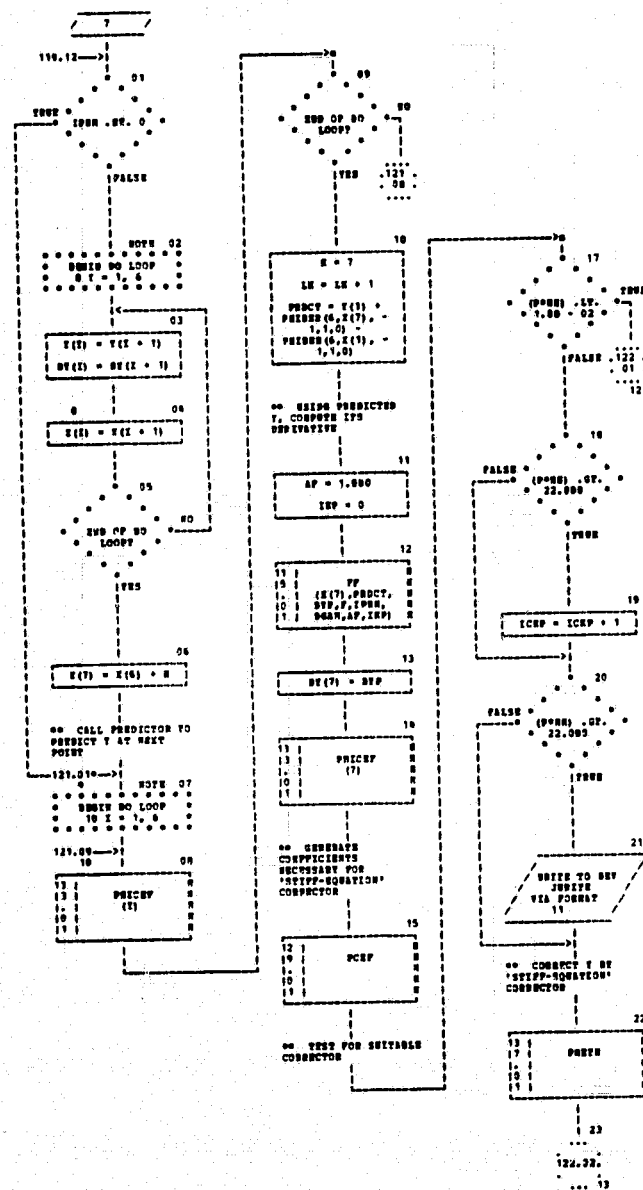
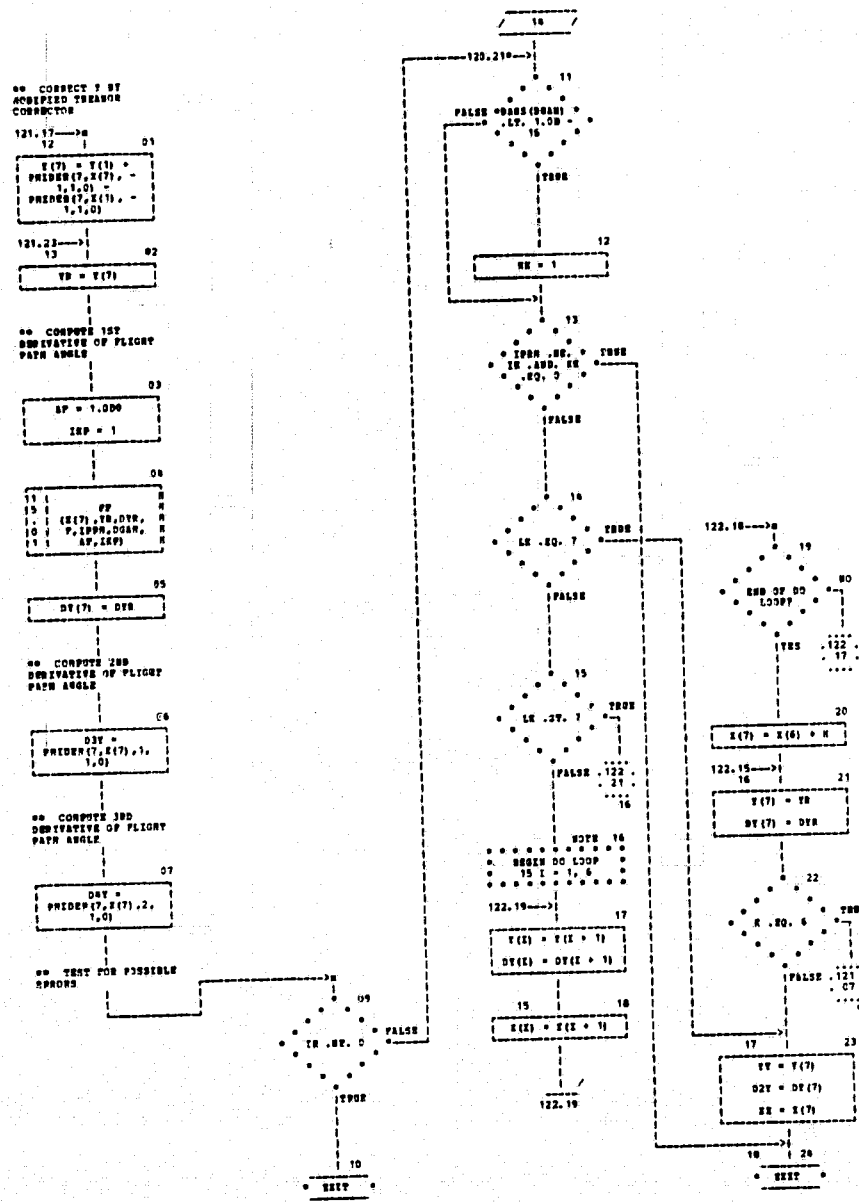


CHART TITLE - SUBROGATION THEWOB(U,II,IV,DIV,DIV,ISST,P,IPAN,OR,IR)





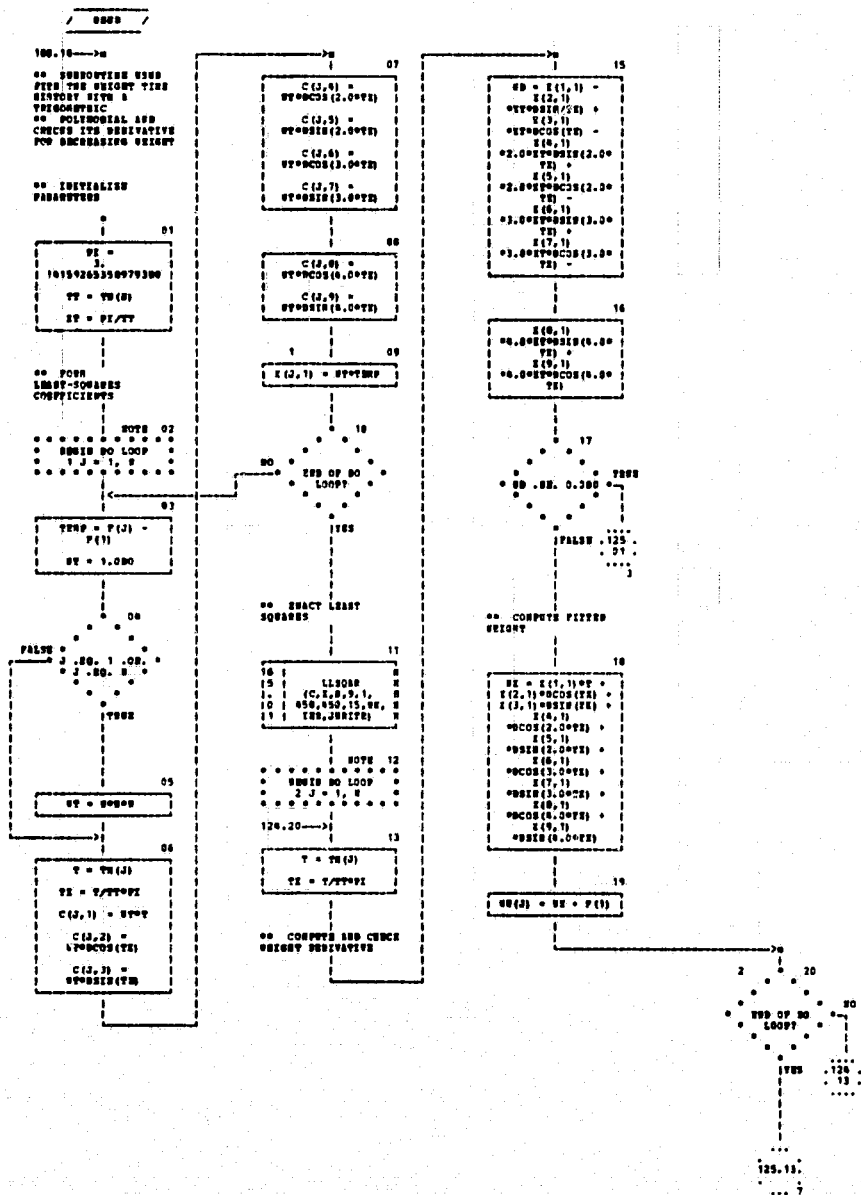
ORIGINAL PAGE IS
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AUTOPLOM CHART 107 -

*P002

PAGE 120

CHART TITLE - SUBROUTINE TSPH(0,P,TH,00,JOINTS)



C-7

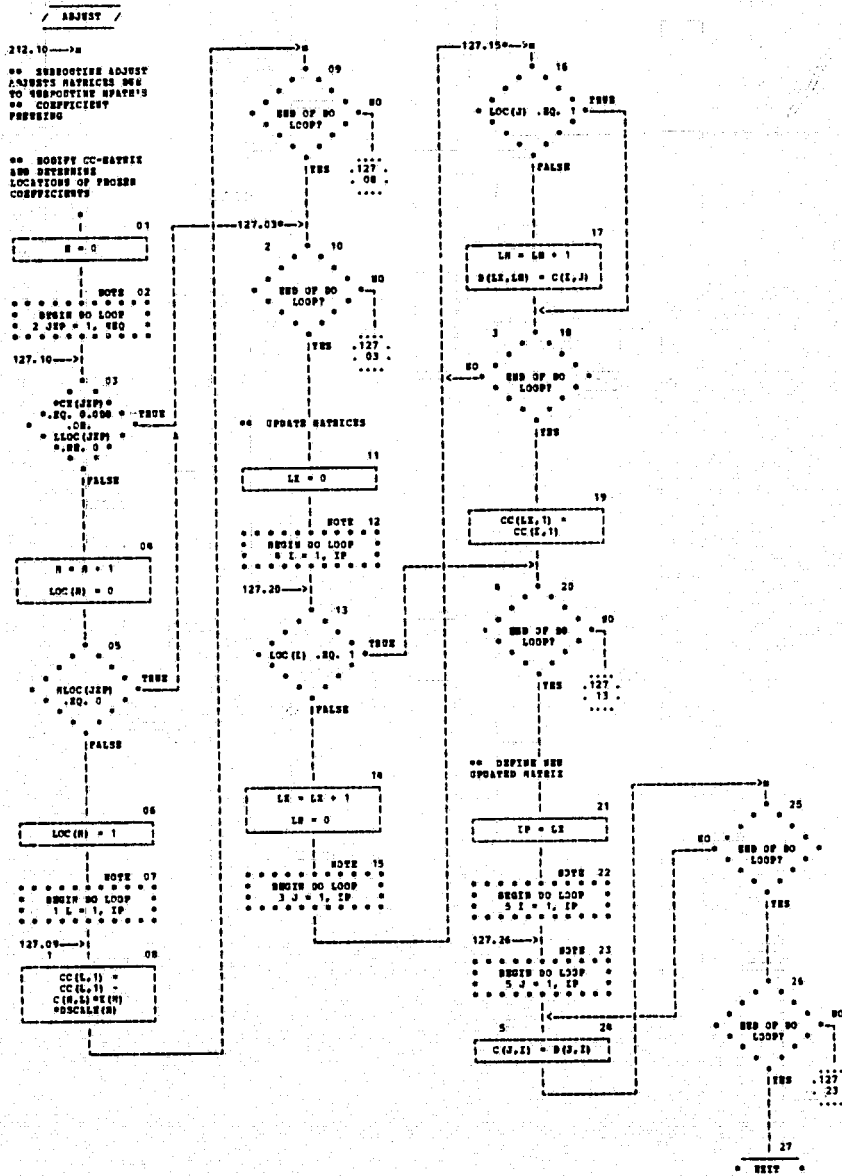
ORIGINAL PAGE IS
OF POOR QUALITY

AUTOFLOW CHART REV -

7082

PAGE 127

CHART TITLE - SUBROUTINE ADJUST(C,CC,CH,S,SCALE,LOC,LOC,IP,NOQ)



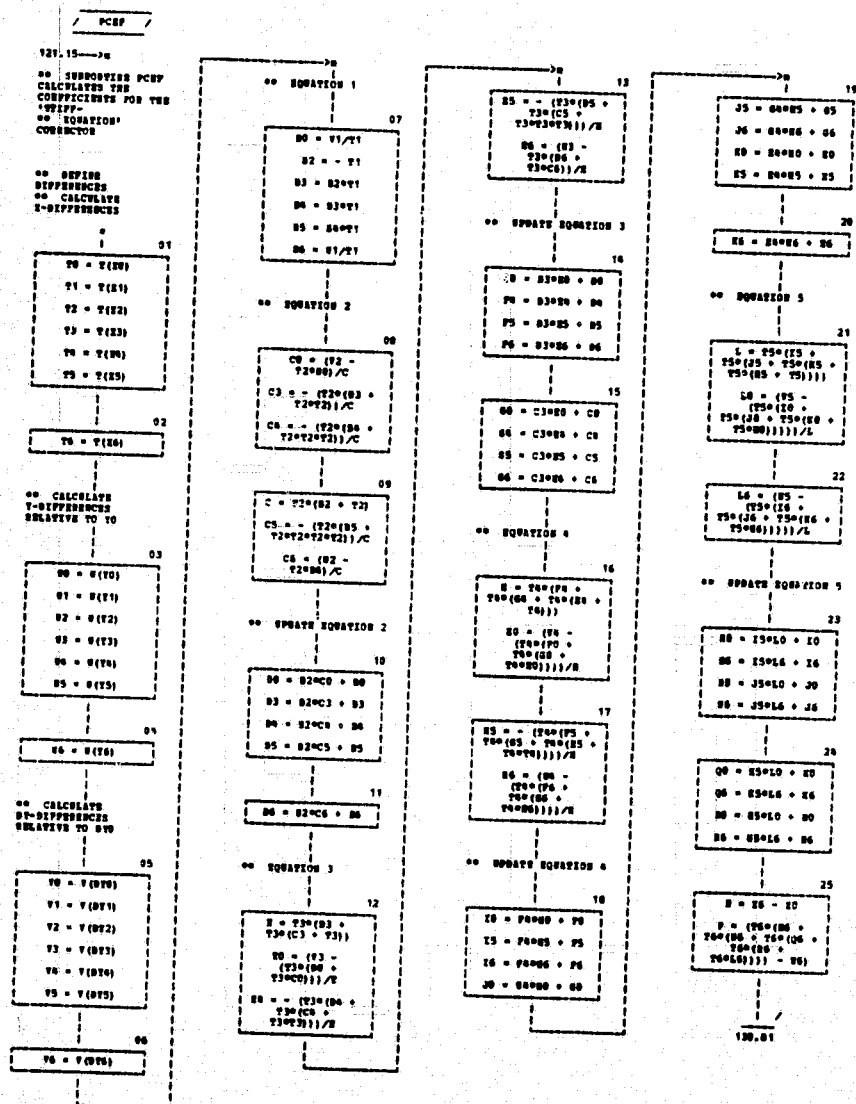


CHART TITLE - SUPPORTING PCRP

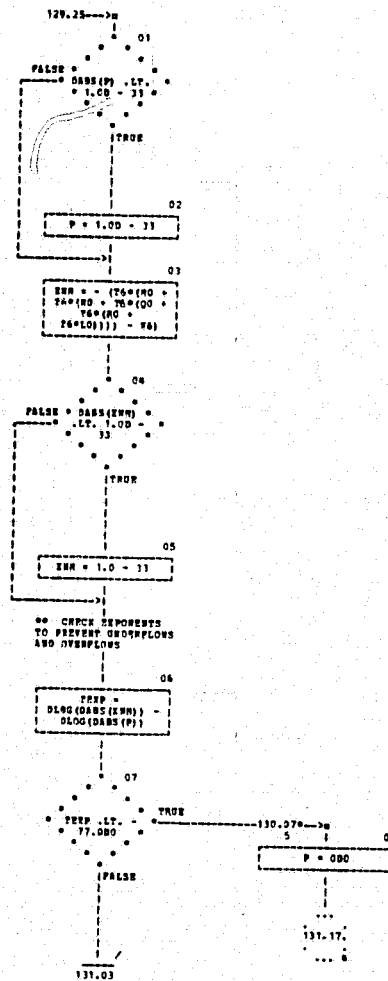
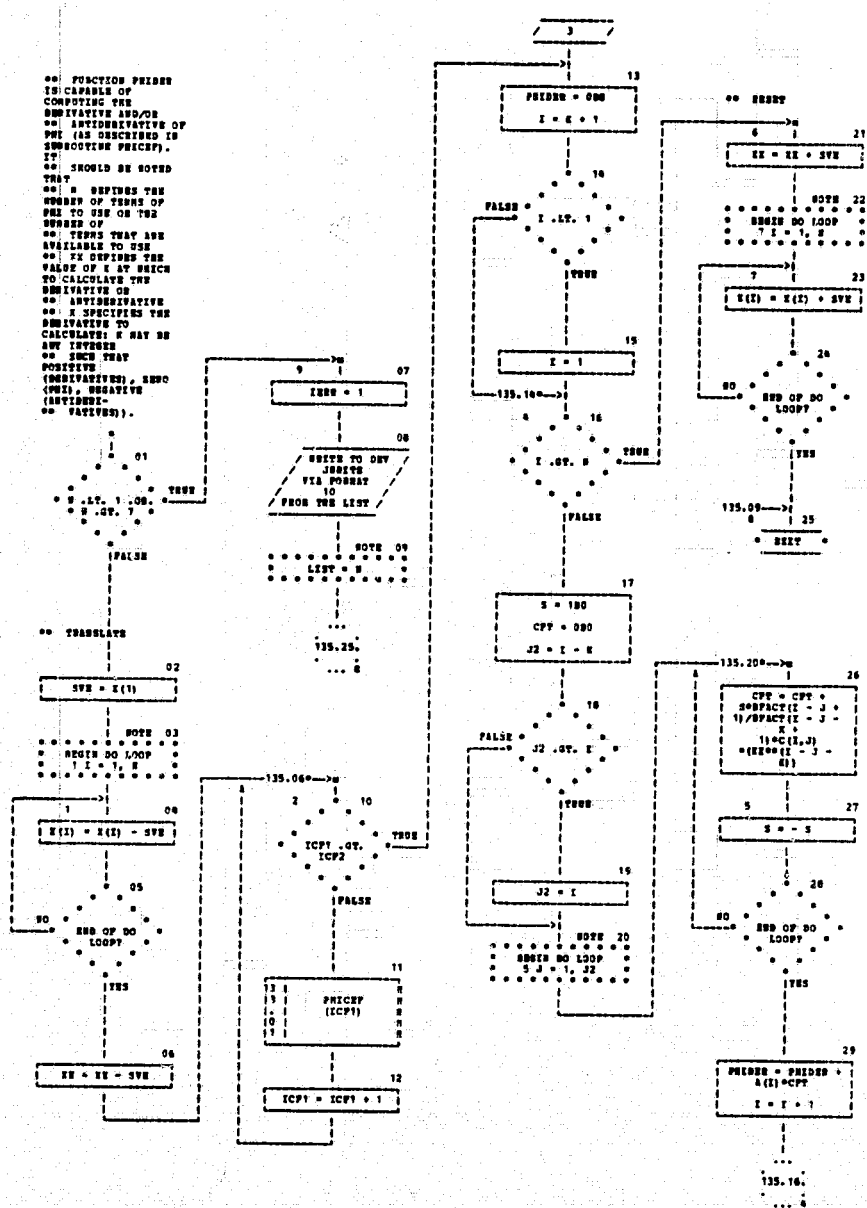


CHART TITLE - SUBROUTINE PWCHP(E)



CHART TITLE - FUNCTION PRINTER (U, IR, R, XCF1, ICF2)



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AUTOPLOE CHART SUB -

00002

PAGE 137

CHART TITLE - SUBROUTINE PRTE

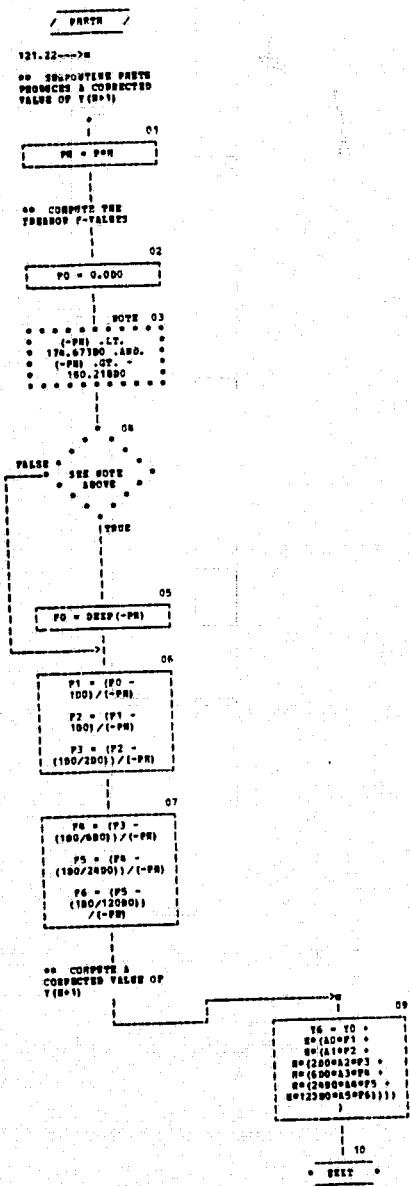
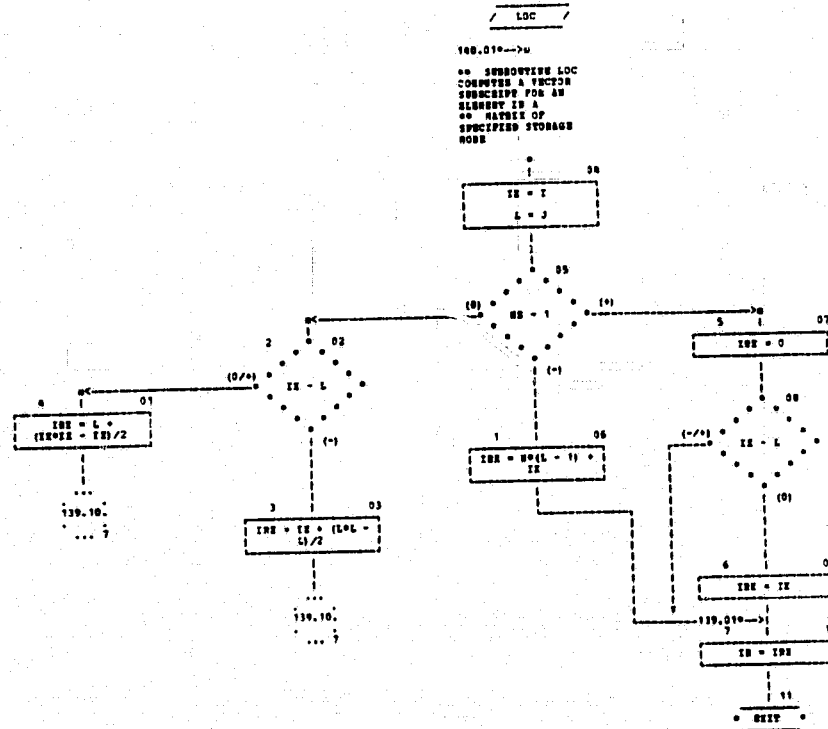


CHART TITLE - SUBROUTINE LOC(I,J,IB,B,R,R)



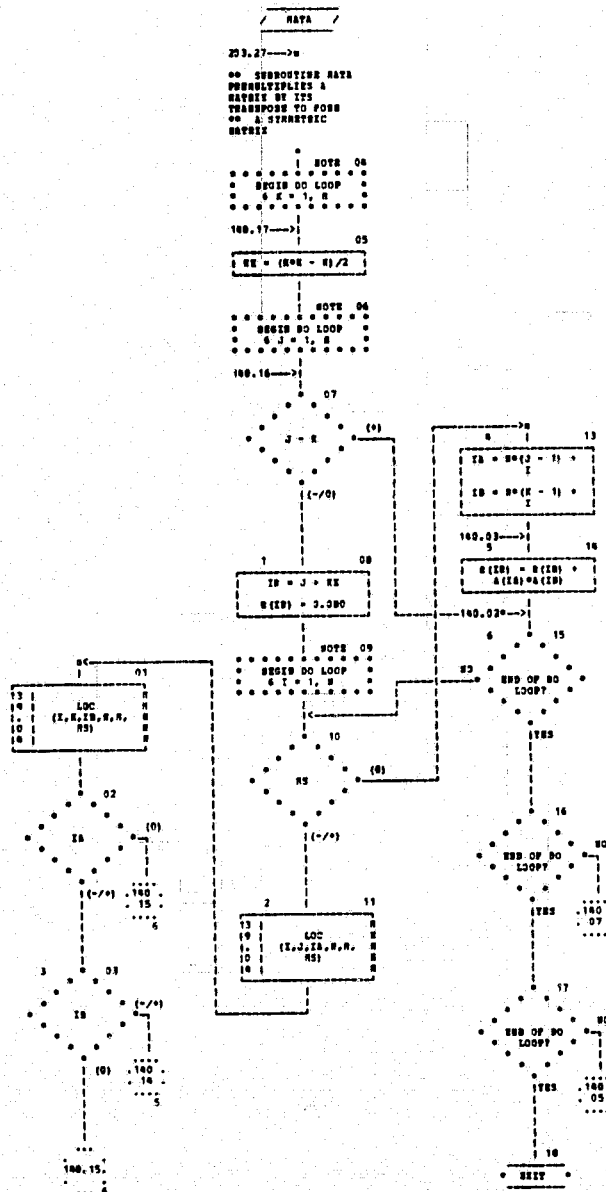
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ALTOPLOC CHART 30T -

*P002

PAGE 100

CHART TITLE - SUBROUTINE DATA(0,0,0,0,0)



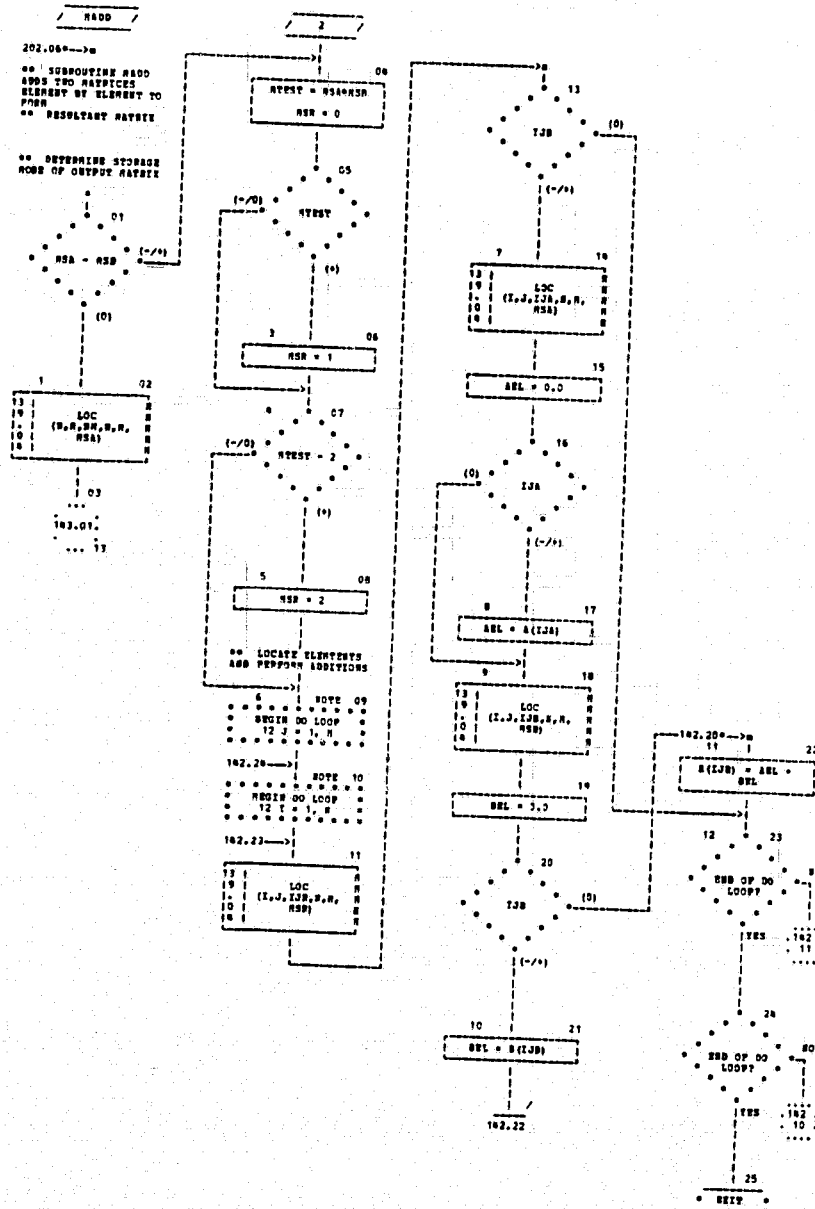
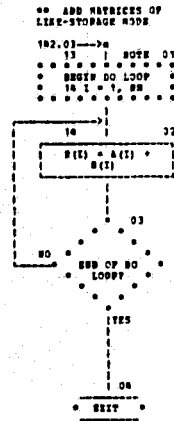


CHART TITLE - SUBROUTINE READ(A,B,C,D,R,NSA,NSB)



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CHART TITLE - SUBROUTINE GARE(D)

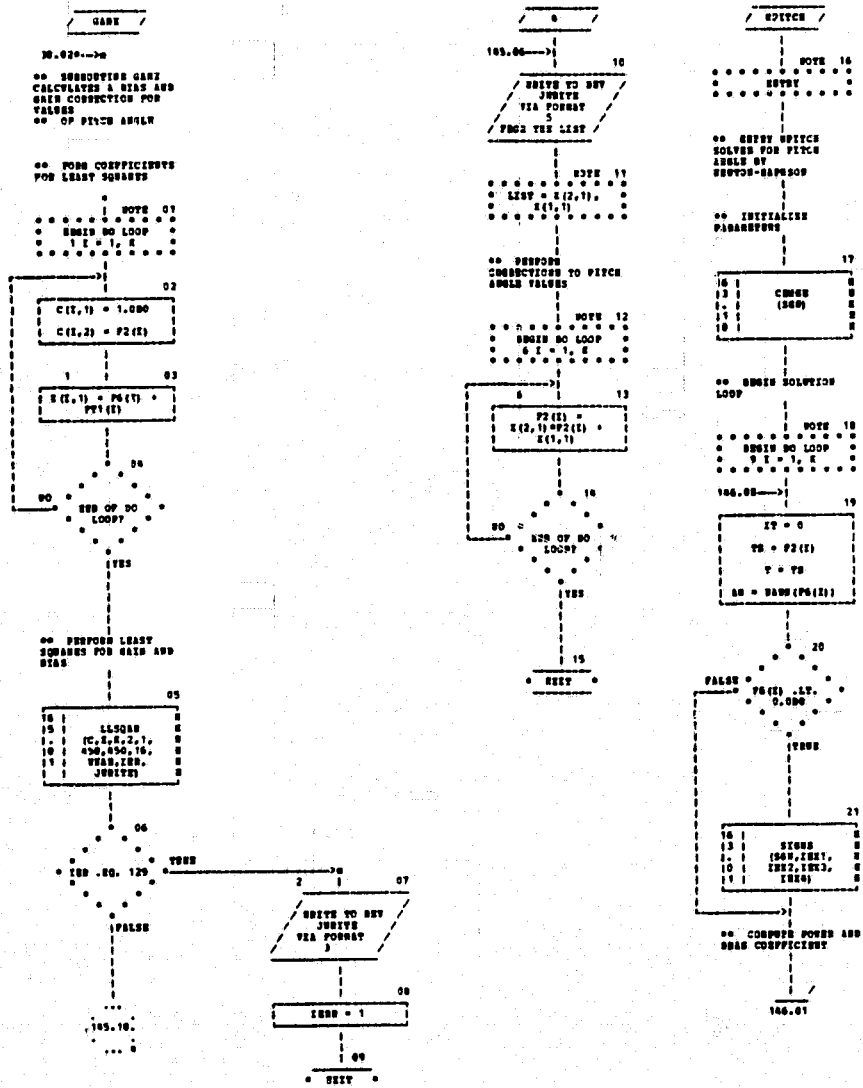
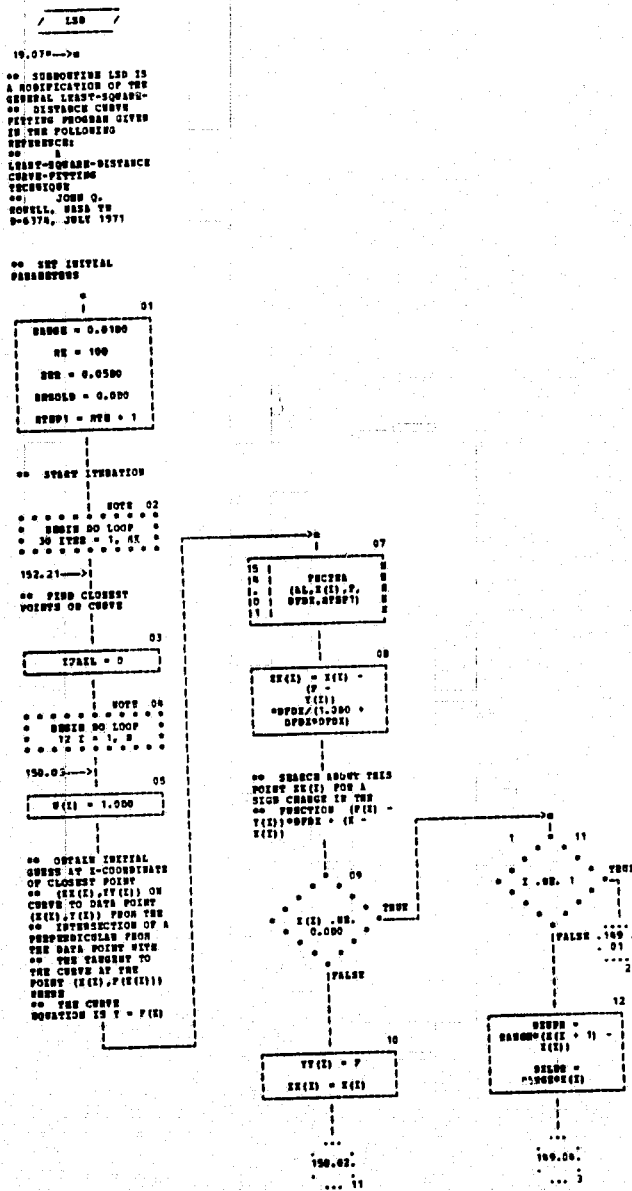


CHART TITLE - SUBROUTINE LSD (N,Y,S,AL,R,HHH,LAST,ICOR,JUSTE,STP)



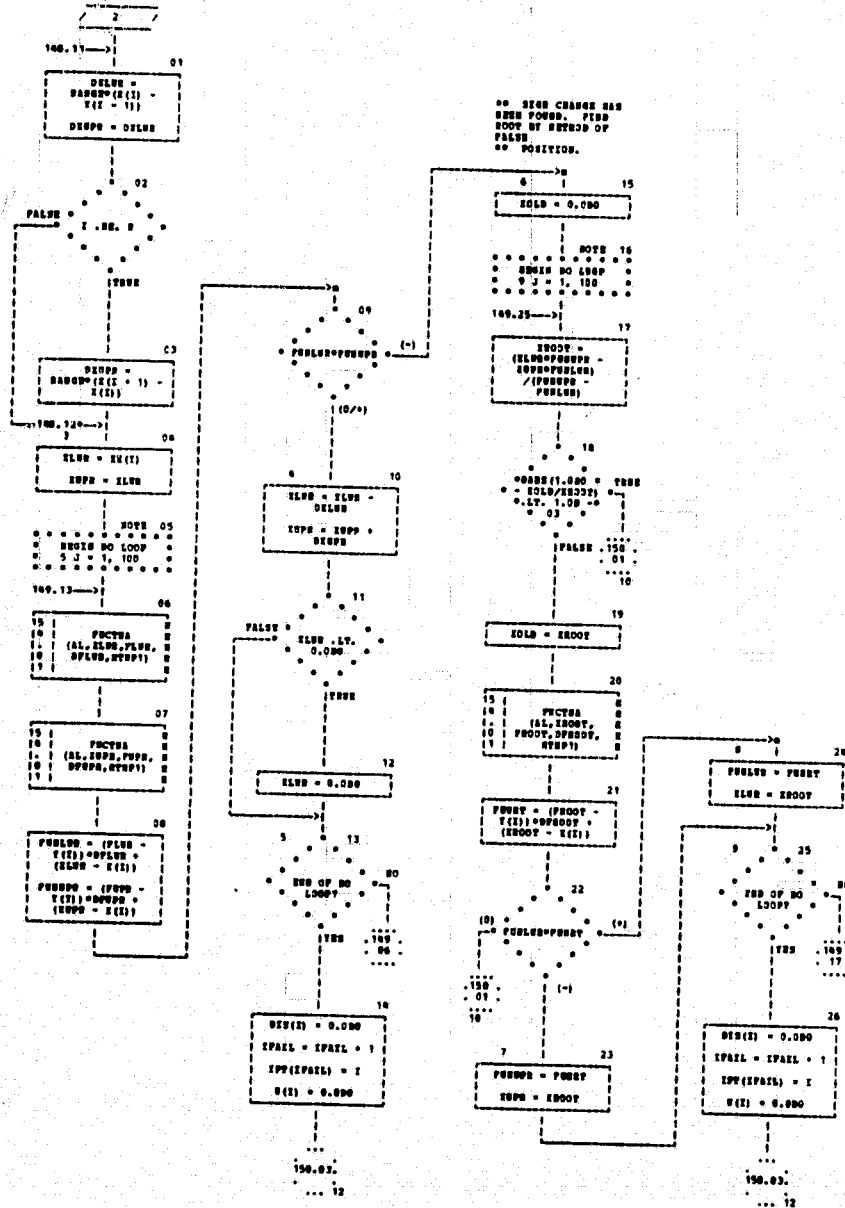
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ADTOPLES CHART 507 -

*P002

PAGE 100

CHART TITLE - SUBROUTINE LSP(X,Y,Z,AL,N,NS,LOUT,TIME,JOINTS,RTS)

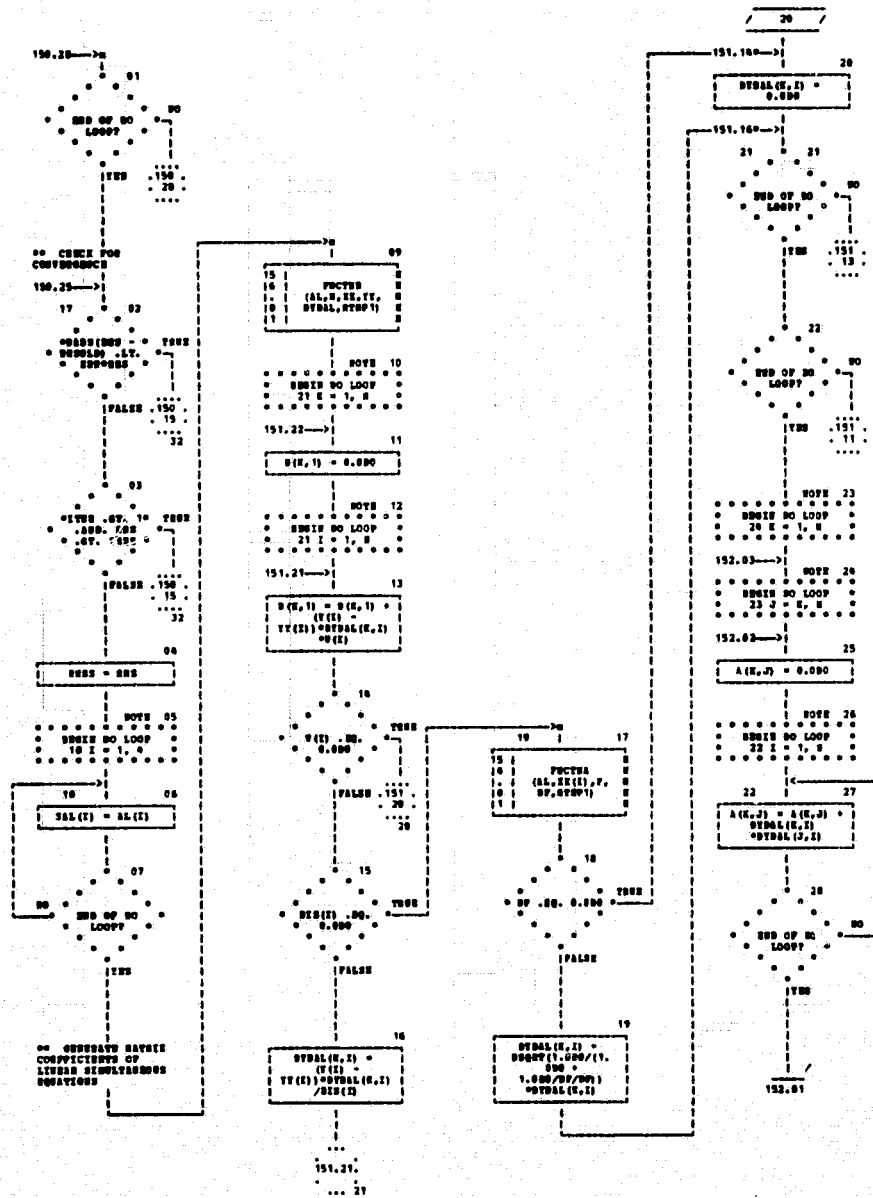


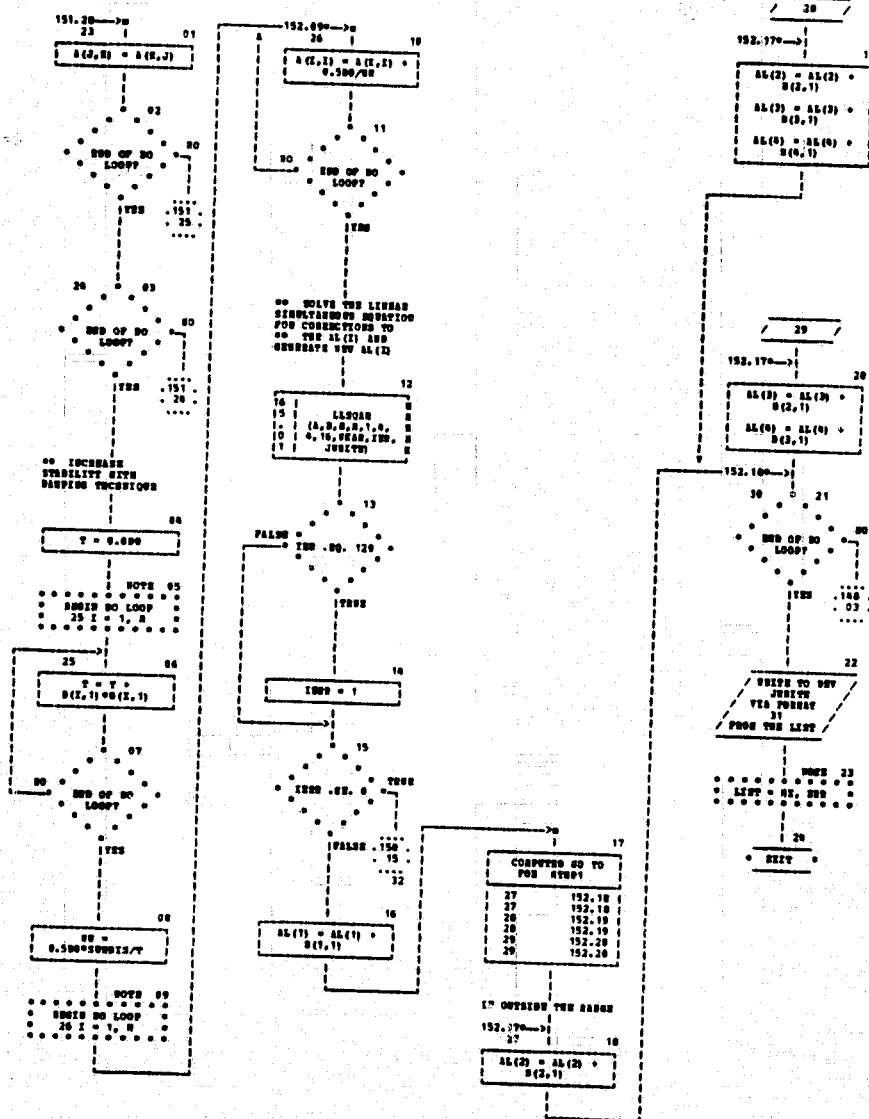
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• 17-22

PAGE 151

CHART TITLE - SUBROUTINE L00(N,T,U,AL,N,000,LEVT,TURN,JOINTS,OTM)





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OF POOR QUALITY

•FDB2

PAGE 154

CHART TITLE - SUBROUTINE FACTUA(A,B,C,D,E,F,G,H,I,J,K,L,M,N,O,P,Q,R,S,T,U,V,W,X,Y,Z)

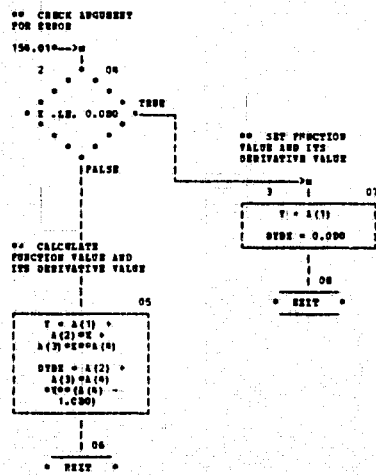
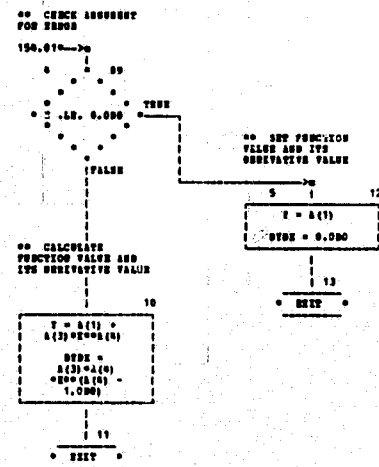
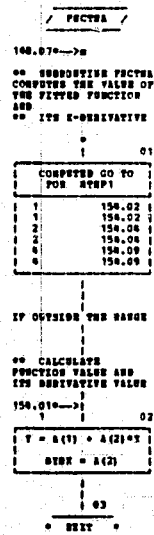
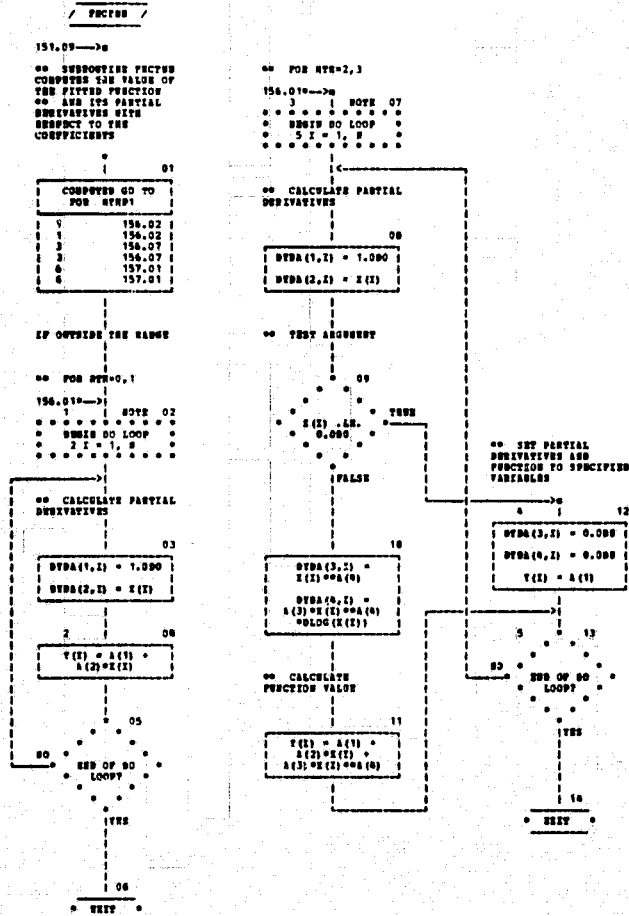


CHART TITLE - SUBROUTINE FACTOR(A,X,Z,T,DTM,STDP)

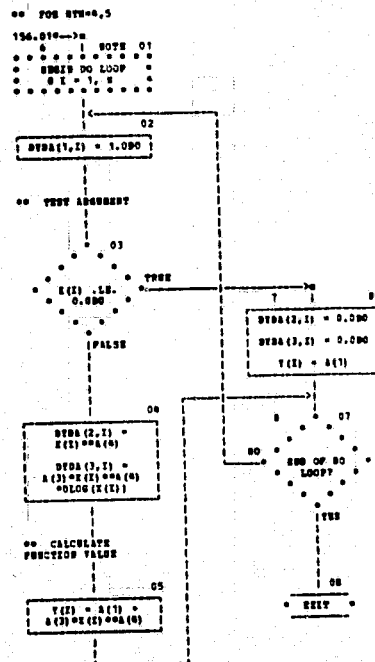


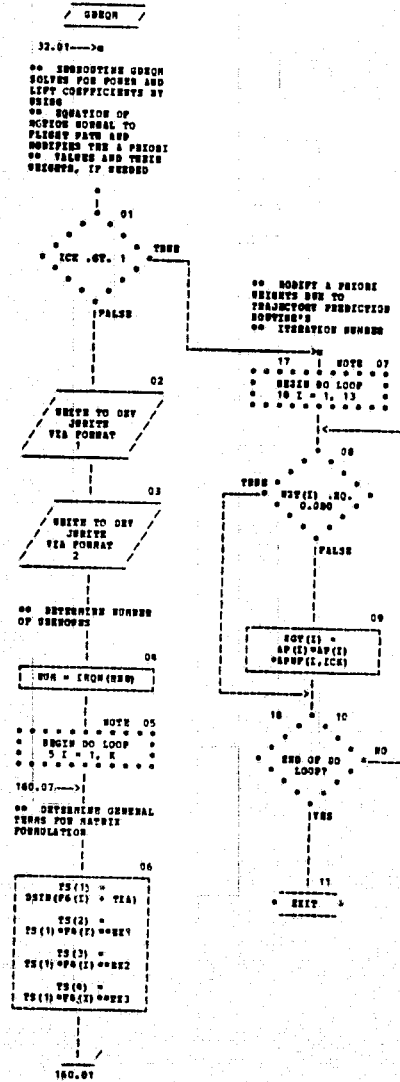
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• 87012

PAGE 297

CHART TITLE - SUBROUTINE FACTOR(A,B,E,Y,DTDA,DTDF)





PAGE 140



```

100.210--> 01
  P = COP(1) +
  COP(2)*PP(2)
  **E11
  COP(3)*PP(2)
  **E12
  COP(4)*PP(2)
  **E13
  COP(5)*PP(2)**E14

02
  CL = COP(6) +
  COP(7)*PP(2) +
  COP(8)*PP(2)
  **E15

03
  SS = BAKEN(2) +
  T21*PP +
  PS(2)*PP(2)
  **2/2.880*CL -
  (PP(2)**2)*PP(2)
  **PP(2) +
  6.00000(PS(2))
  /PP(2))

11
  SSX = SSX + SS*PP

04
  END OF DO
  LOOP?

05
  YES
  ** SITES MODEL
  VALUES

06
  ** SITES .BX.
  ** VALUE .101.
  ** .09.

13
  WRITE TO REV
  JOURNAL
  VIA FORMAT
  12
  FROM THE LIST

07
  ** NOTE 08
  ** LIST = SSX, PS,
  ** COP(1), COP(6),
  ** COP(2), COP(7),
  ** COP(3), COP(8),
  ** COP(4), COP(5),
  ** SSX

161.04--> 09
  P0 =
  COP(1)
  01.3550100 - 3

  P1 =
  COP(2)
  01.3550100 - 3

  P2 =
  COP(3)
  01.3550100 - 3

10
  P3 =
  COP(4)
  01.3550100 - 3

  P4 =
  COP(5)
  01.3550100 - 3

11
  WRITE TO REV
  JOURNAL
  VIA FORMAT
  12
  FROM THE LIST

12
  ** NOTE 12
  ** LIST = SSX, PS,
  ** COP(6), P1,
  ** COP(7), P2,
  ** COP(8), P3, P4,
  ** SSX

13
  WRITE TO REV
  JOURNAL
  VIA FORMAT
  15

14
  ** MODIFY A PRIORIE
  VALUES AND WEIGHTS IF
  SUCCESSFUL

  16
  ** MODIFICATION TO
  SECOND-POWER
  COEFFICIENT A PRIORIE

  AP(2) = AP(2)
  WGT(2) = WGT(2)

17
  ** MODIFICATION TO
  THIRD-POWER
  COEFFICIENT A PRIORIE

  AP(3) =
  127.9700*CPH(3)
  **2/(12.00*CPH
  (3) + COP(3))
  WGT(3) =
  AP(3)*AP(3)
  **288.000

18
  ** MODIFICATION TO
  FOURTH-POWER
  COEFFICIENT A PRIORIE

  AP(4) =
  34.24600*CPH(4)
  **2/(13.300*CPH
  (4) + COP(4))
  WGT(4) =
  AP(4)*AP(4)
  **6.00 + 27

19
  ** MODIFICATION TO
  FIFTH-POWER
  COEFFICIENT A PRIORIE

  AP(5) = AP(5)
  WGT(5) = WGT(5)

20
  ** SITES

```

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CHART TITLE - SUBROUTINE SIGN (Y,X1,X2,X3,X4)

AUTOPLOE CHART SET -

07002

PAGE 163

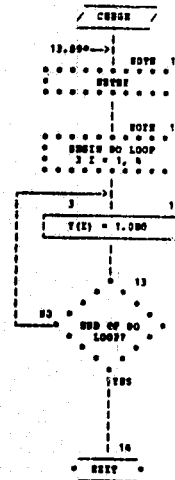
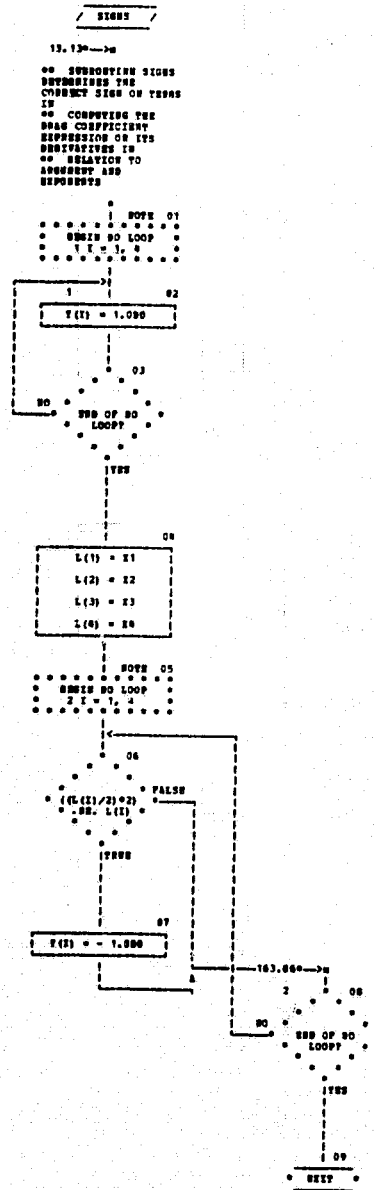
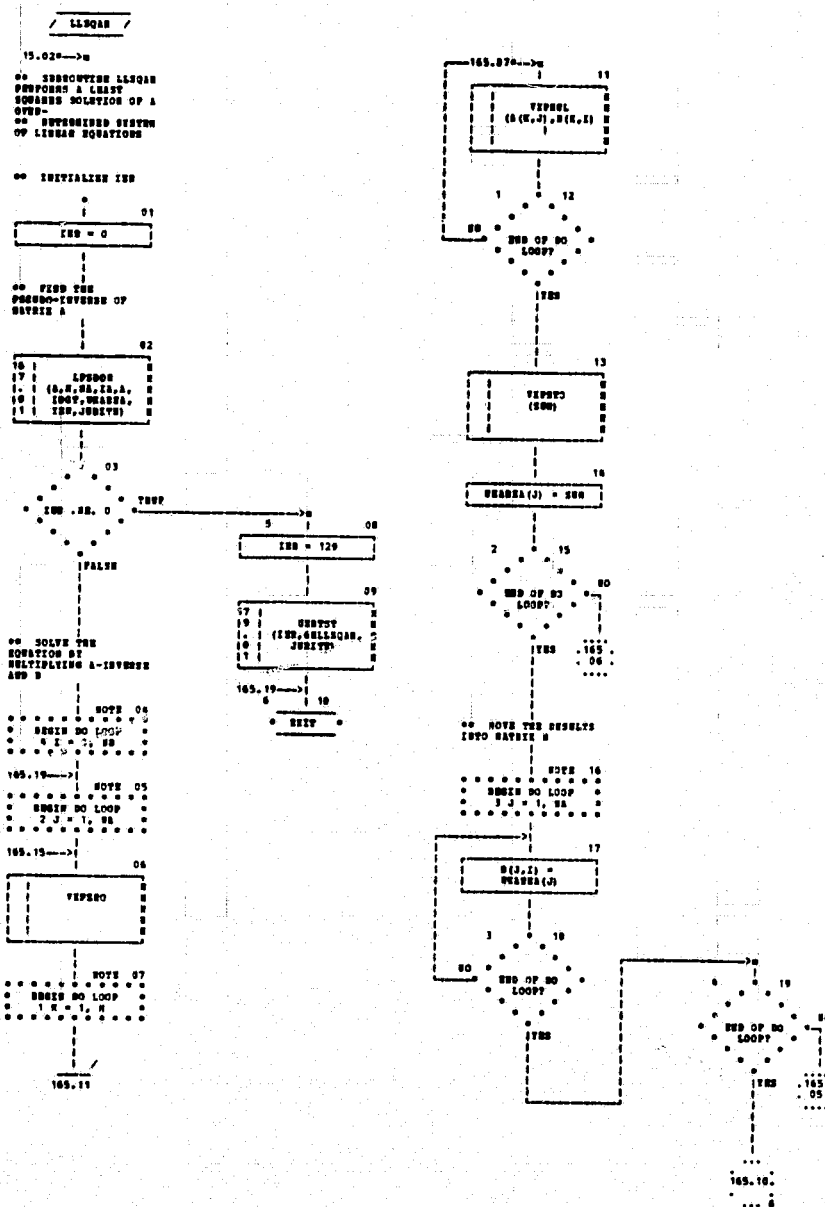


CHART TITLE - SUBROUTINE LLSQAR2(0,0,0,0,00,10,10,1007,00000,100,100000)



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AUTOFLUO CHART SET -

*7002

PAGE 167

CHART TITLE - SUBROUTINE LPSBOR(S,N,W,IA,ATOT,ISOT,DEADBE,IER,JOBTOT)

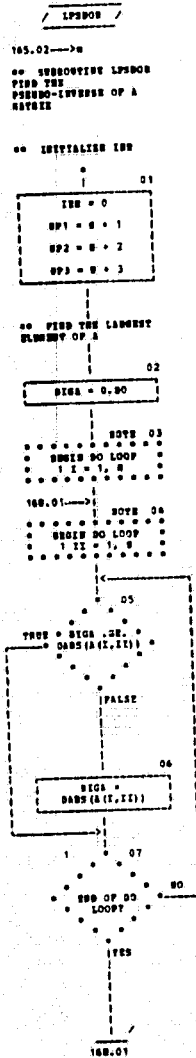
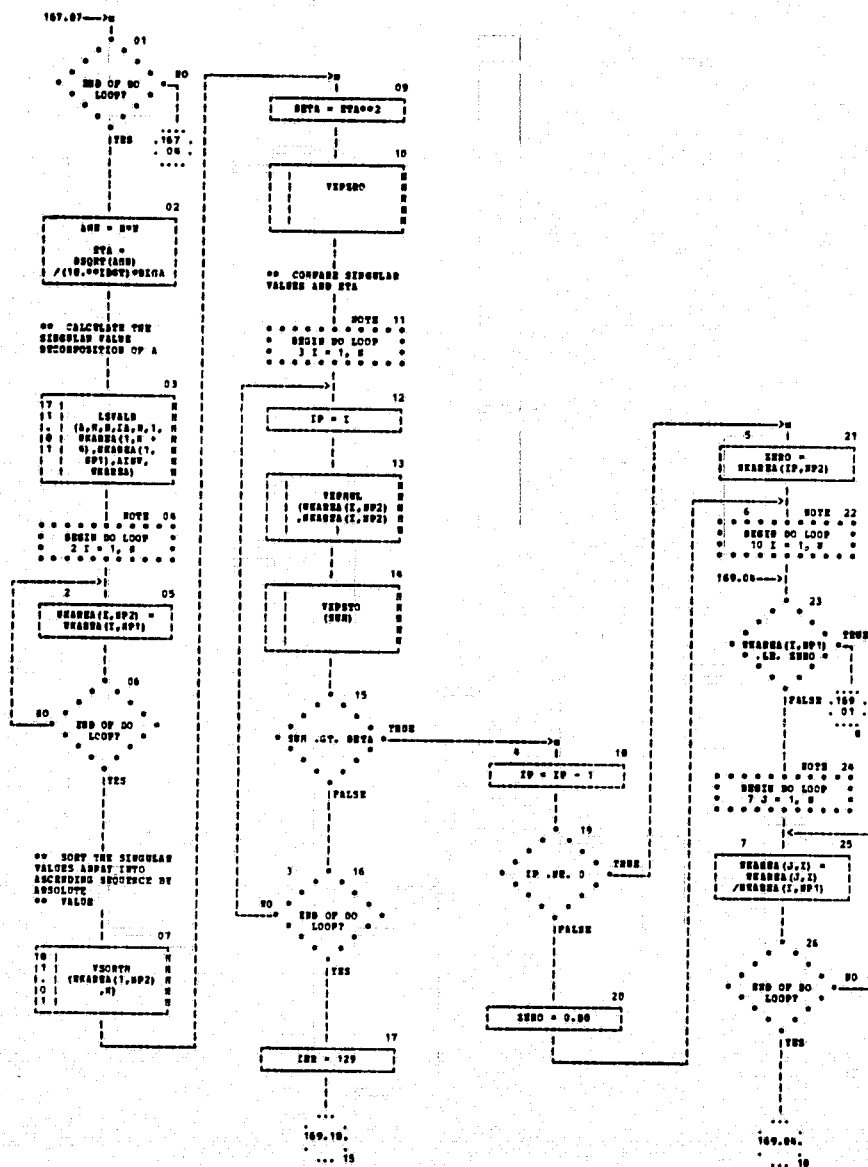


CHART TITLE - SUBROUTINE LPSOON(A,B,C,IA,IBV,ICST,WHASHO,IBR,JUGSTO)



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• FMS2

PAGE 169

CHART TITLE - SUBROSTINE LPSOR(A, N, S, I, A, A, I, V, I, D, T, U, K, I, A, N, A, I, S, U, J, U, R, E, T, M)

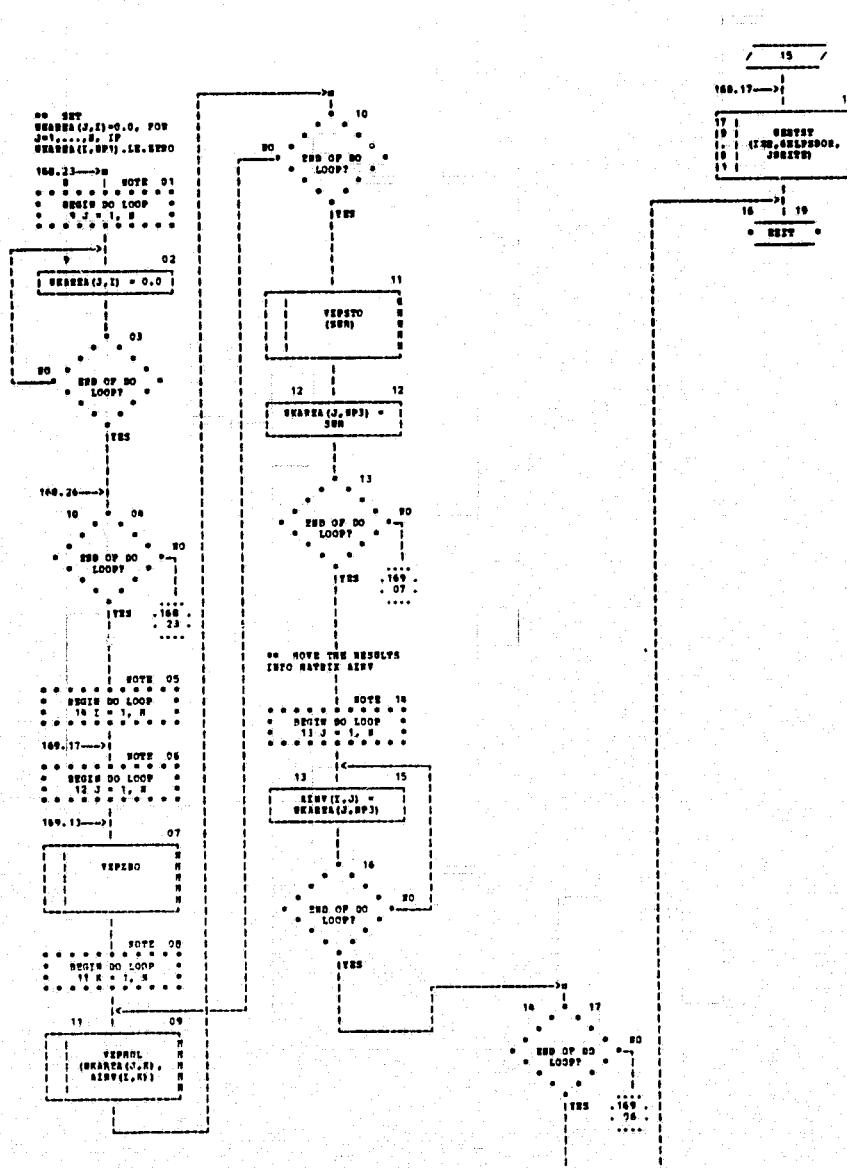
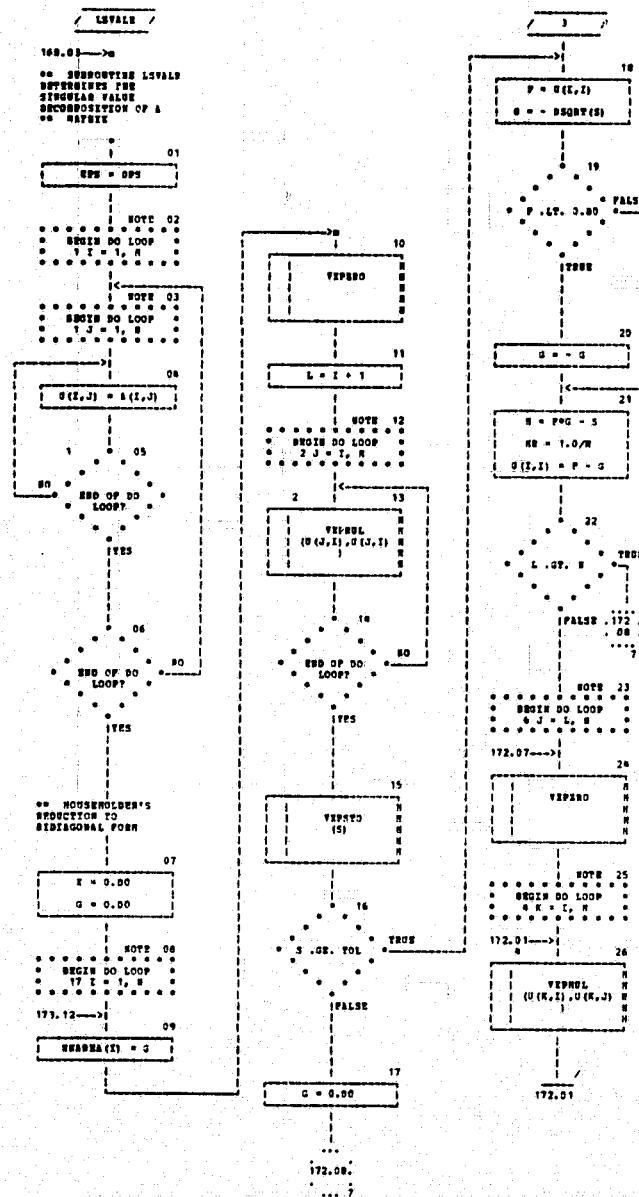


CHART TITLE - SUBROUTINE LSVALS(L,N,N,IA,IV,IS,UNRES,0,0,0)



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• Free!

PAGE 172

CHART TITLE - SUBROUTINE LEVEL(I,II,III,IV,V,VI,VII,VIII,IX,X,XI,XII)

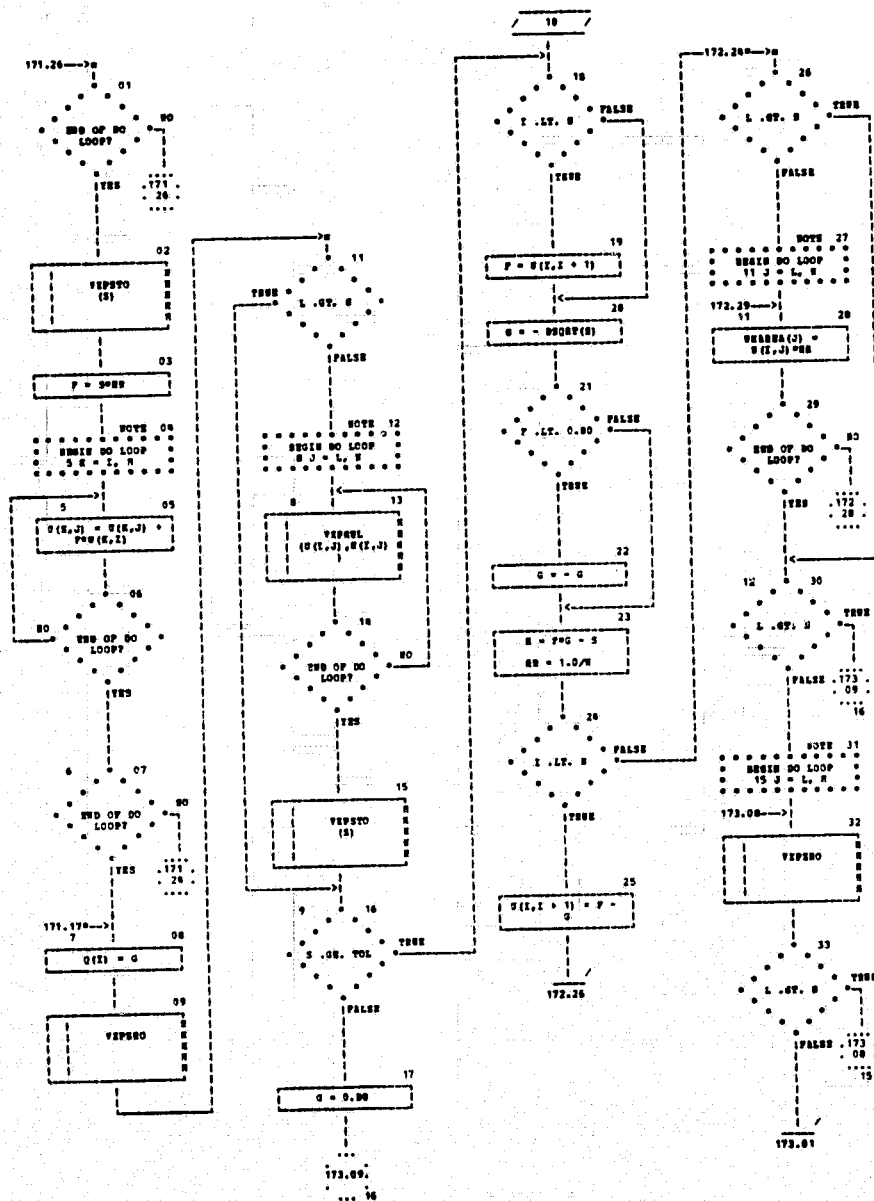
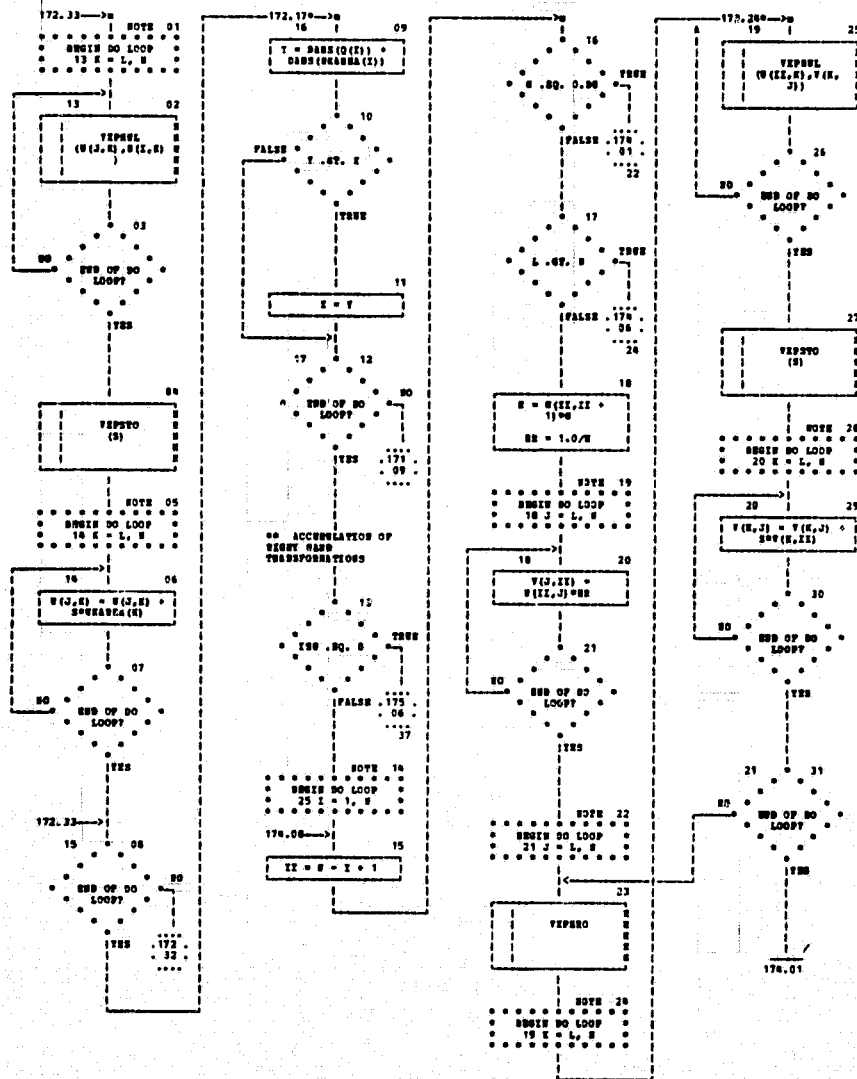


CHART TITLE - SUBROUTINE LSVAR(S,R,H,X,I,TSR,SEARSA,Q,U,V)



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AUTOFLOW CHART SET -

*P082

PAGE 178

CHART TITLE - SUBROUTINE LSWAL(A,B,C,IA,IB,IC,IBASE,Q,R,V)

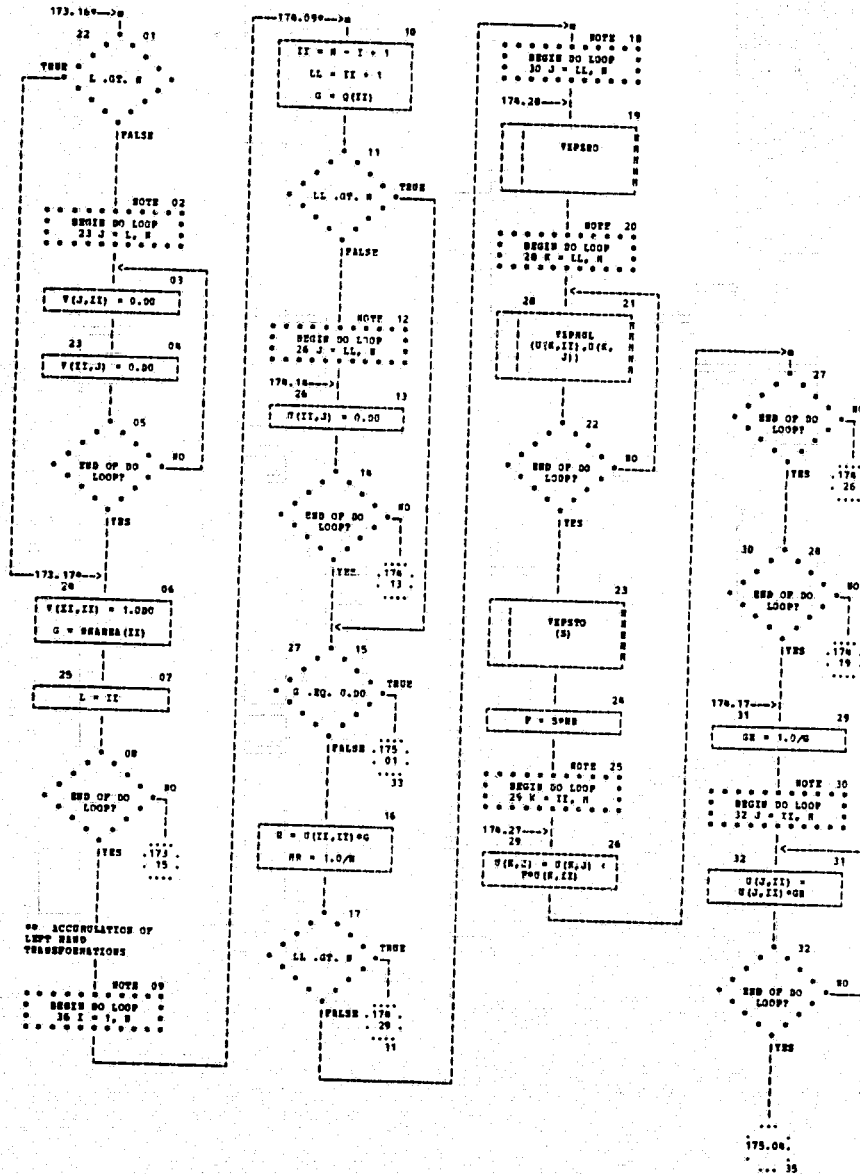


CHART TITLE - SUBROUTINE LEVELS (A,N,B,IA,IP,ISU,SHARPA,Q,U,V)

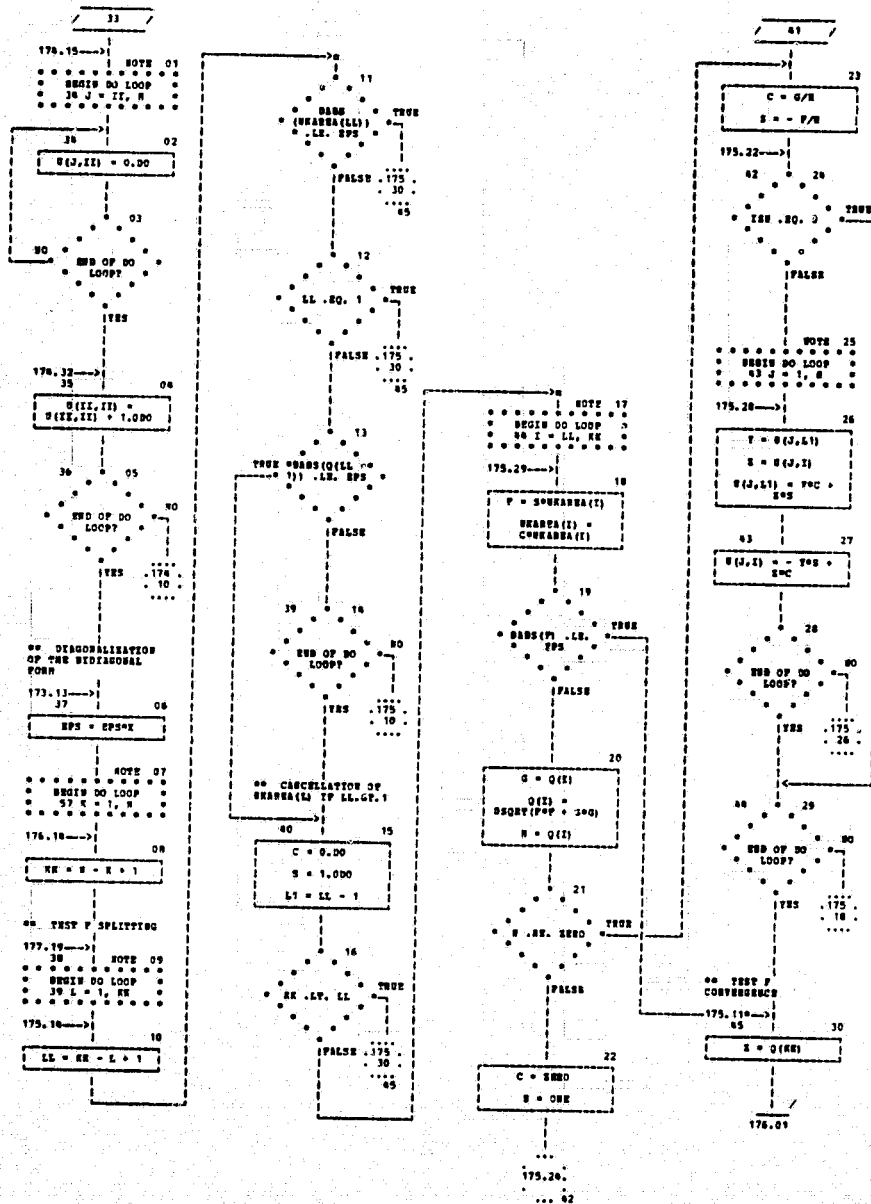


CHART TITLE - SUBROUTINE LEVAL(A,B,H,X,IV,ISV,UNARRA,Q,P,V)

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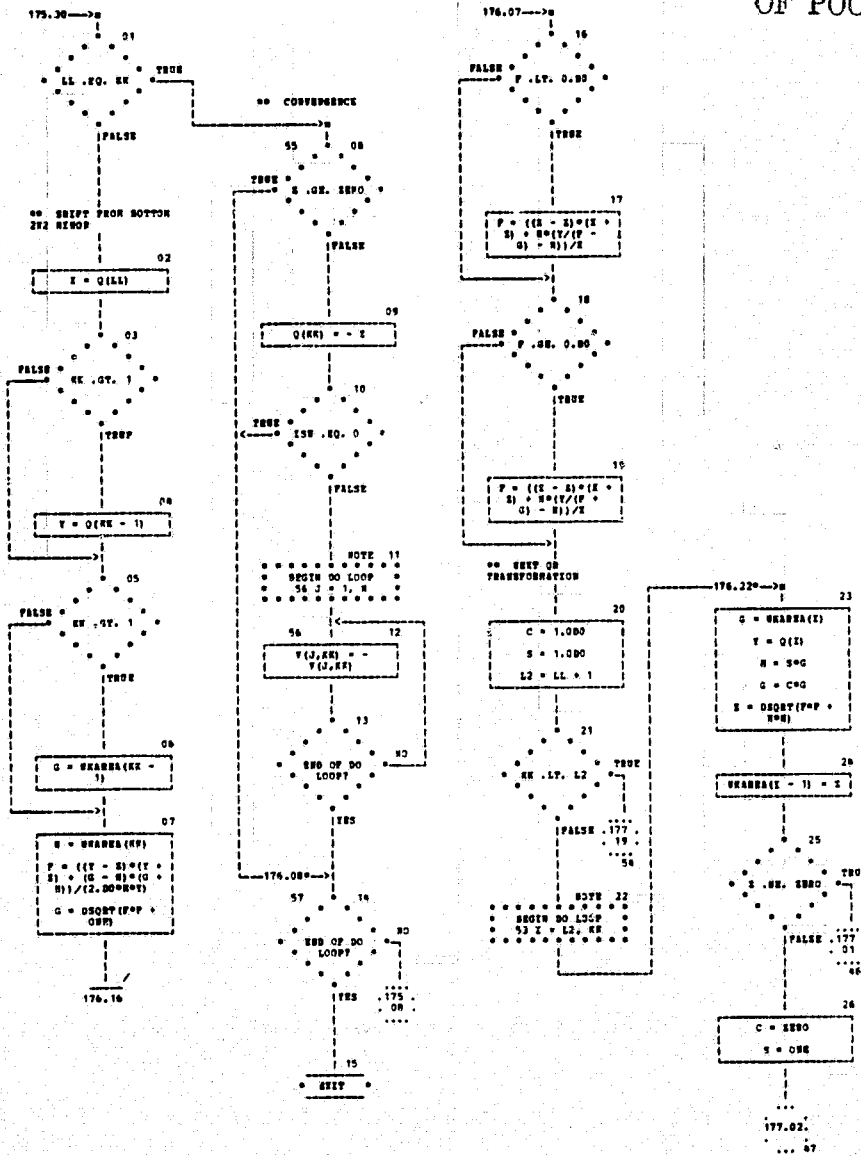


CHART TYPE - SUBROUTINE L5VALS(A,B,C,X,Z,TSV,SEADR,Q,U,V)

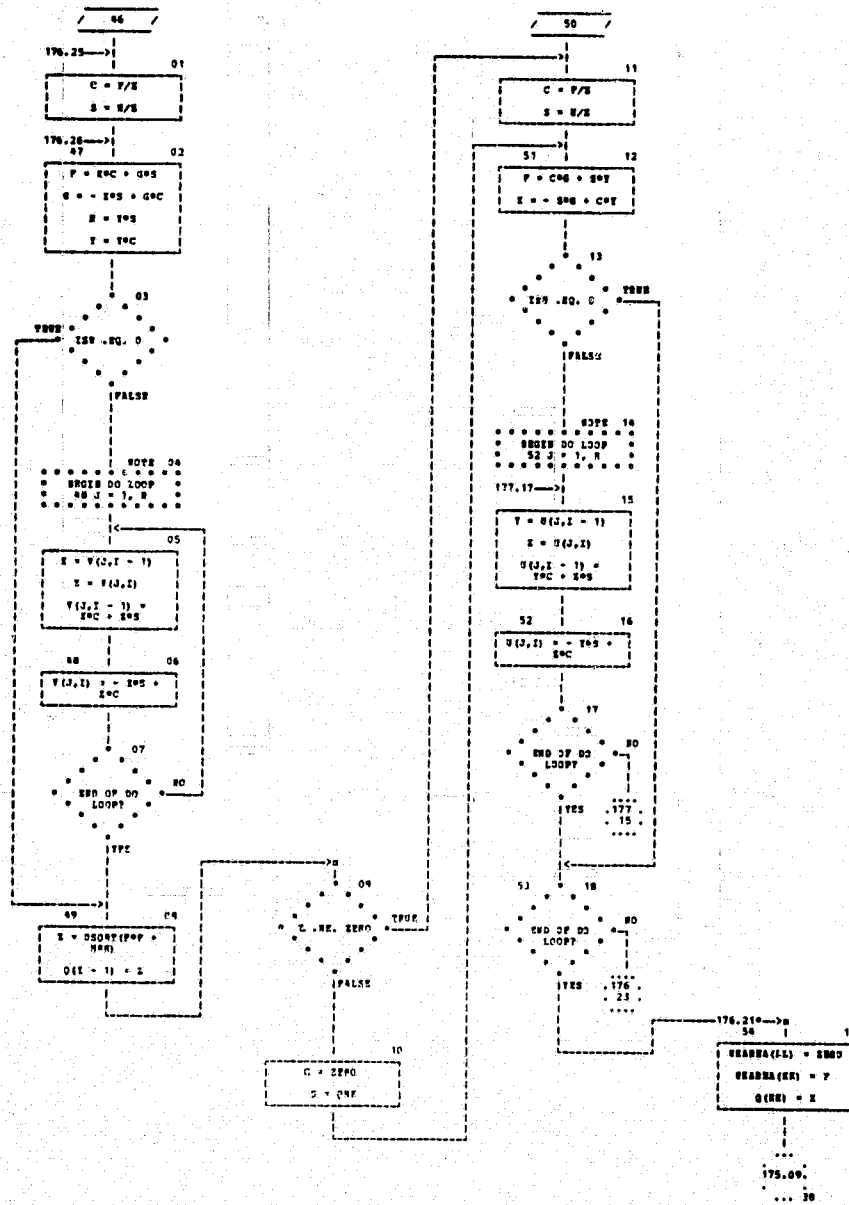


CHART TITLE - SUBOPTIMIZ UNITST (IEN, HANS, JUSTIN)

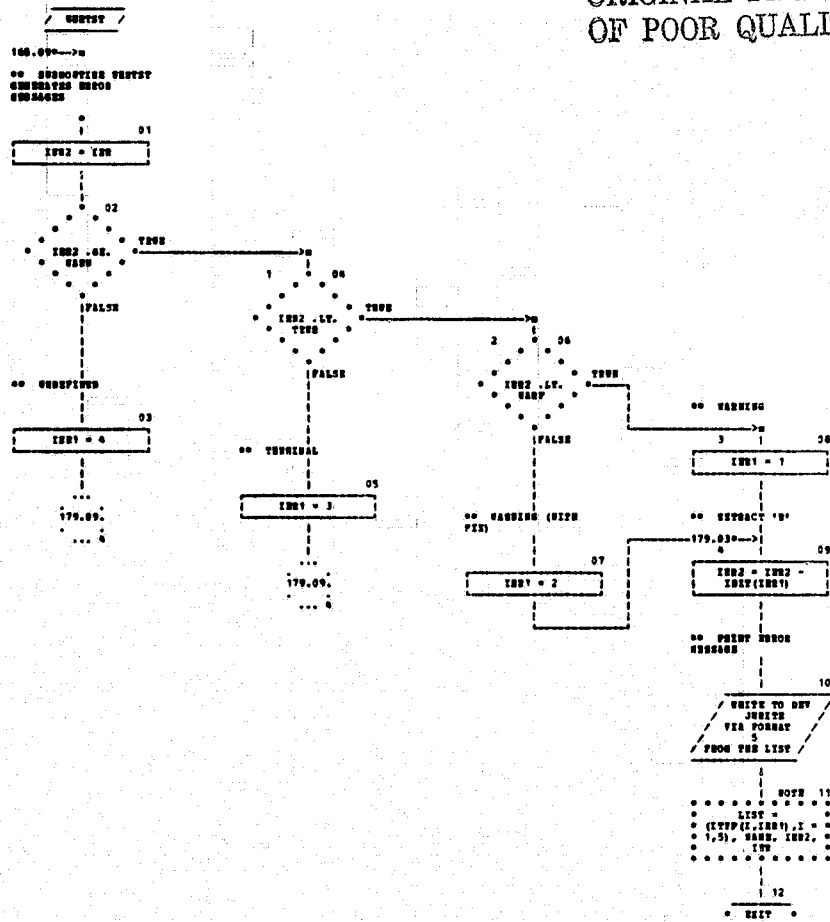
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CHART TITLE - SUBROUTINE TSORT(LA)

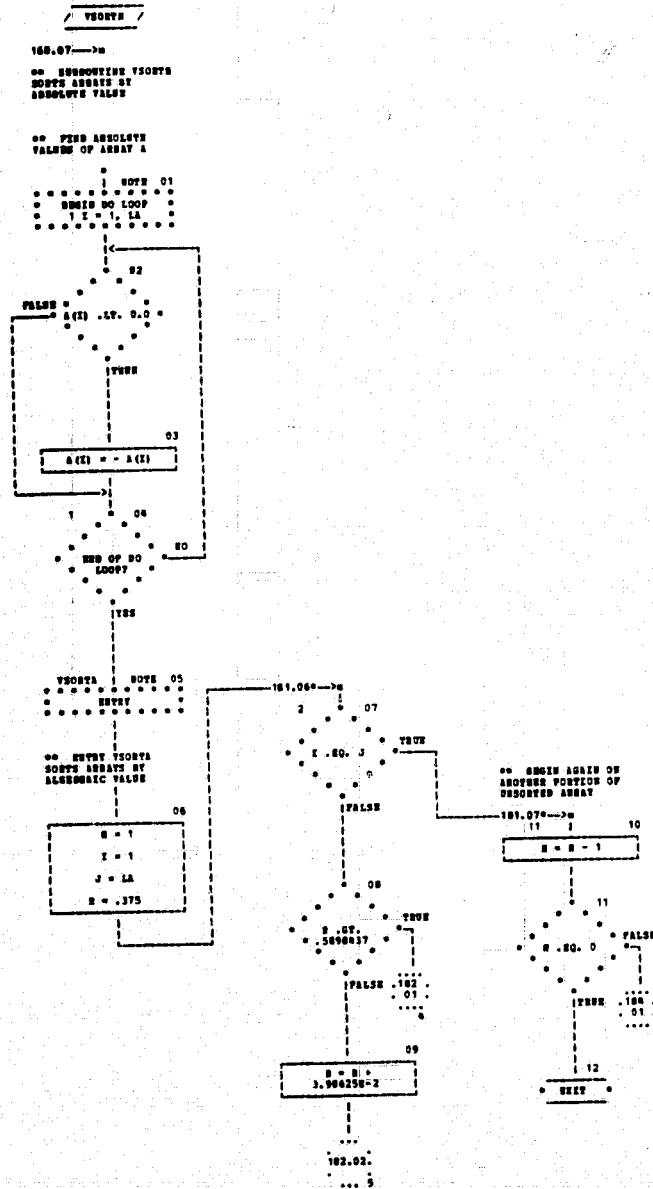
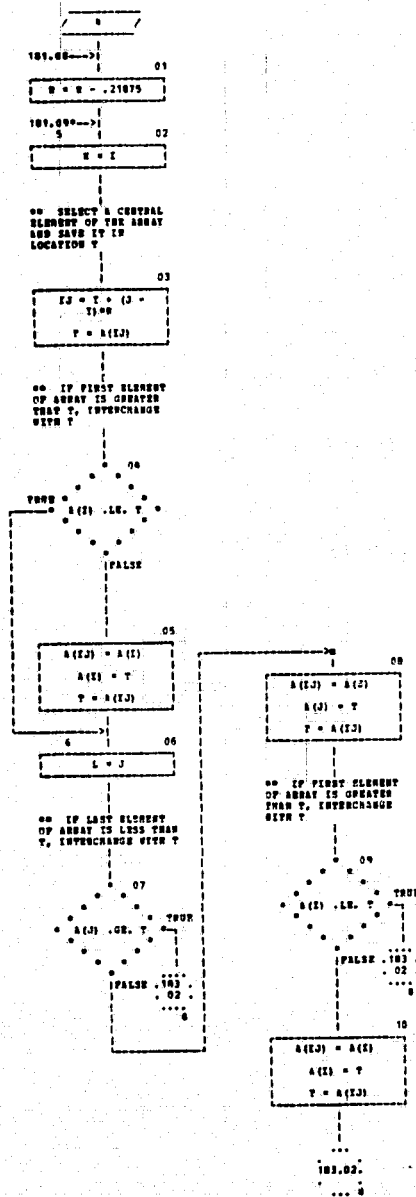
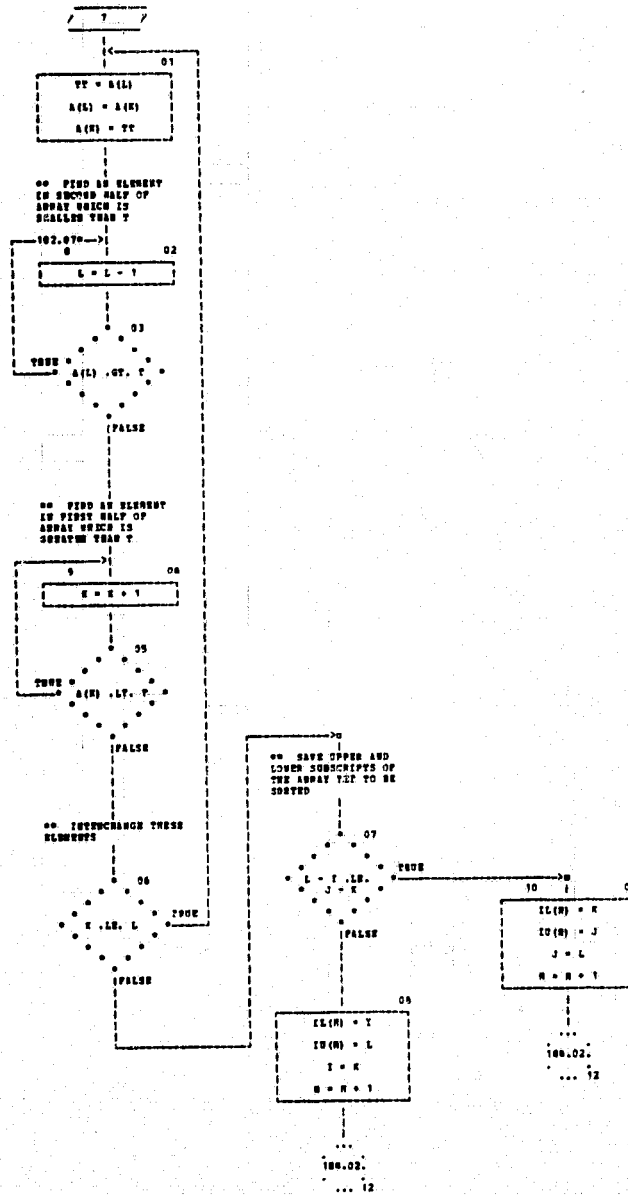


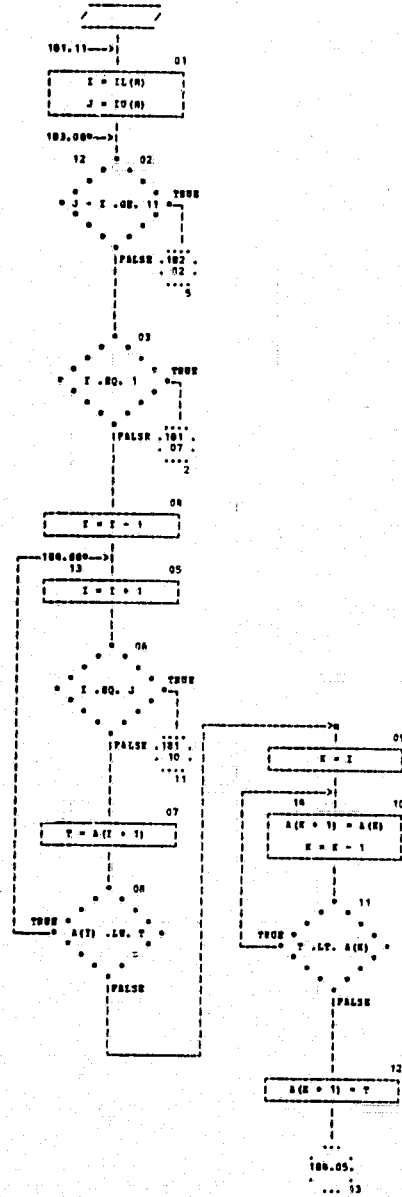
CHART TITLE - SUBROUTINE VACUUM(A,LA)



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CHART TITLE - JOSSONINE 93070(1,2)





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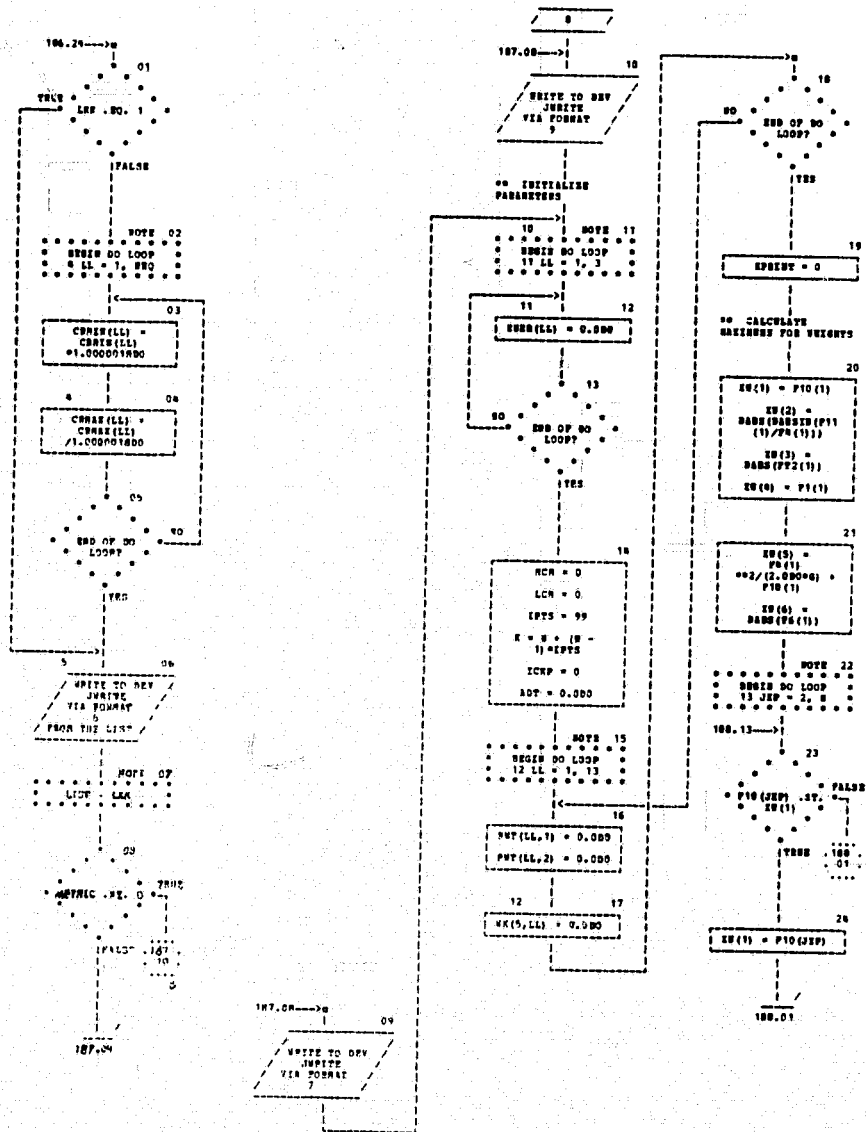
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AUTOFLIGHT CHART SET -

•PDR2

PAGE 107

CHART TITLE - SUBROUTINE SPATN (U.F.,GND,LONG,FIT,TARE,WTARE,HUPE)



```

187.230-->#
      1  NOTE 01
      *
      *  DASH(DASHIN(P11
      *  (JEP)/P8(JEP))
      *  .GT. IN(2)
      *

```

FALSE
SEE NOTE
ABOVE
TRUE

IN(2) =
DARS(DARSIN(F17
(JX9)/P0(JX9))

FALSE • SANS (PT2
• (JEP) • CT.
• EX(3)

ITRE

XU(3) =
0000(PT2(JXP))

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07
XU(8) - P1(JED)

```

-188.060-->M      1  NOTE ON
* . . . . .
* (P4 (JEP)
* 002/(2.0800G) *
* P10(JEP) .UT.
* 20(5)
* . . . . .

```

FALSE **SEE NOTE**
ABOVE

IV(5) =
P6 (JXP)
=2/(2.00000) *
P10 (JXP)

~~FALSE~~ • DDBS (PG (JEP)) •
• CT. EN (6) •

12

KU(6) =
DAGE(PG(JKP))

END OF DO
LOOP

88. CALCULATE WEIGHTS
FOR LEAST SQUARES
SOLUTION

18 15
D(I) =
DP(I)/XU(I)*100

NO
END OF DO
LOOP
YES

TO EXACT SPLINE ON
ANGLE OF ATTACK FOR
ROOT ESTIMATIONS

EXACT POLYMER

0900Z
FM
TO
INFO

USCIB
(N, P1, TIME, NO)

19
TH(1) = TIME(1)

112 = 11
J = 0

```

      1  NOTE 21
      * * * * *
      BEGIN DO LOOP
      15 JIP = 1, 6
      * * * * *

```

END OF DO
LOOP?

00 BEGIN ANALYSIS
SET OF POINTS

ITEM = 9

197 . 00 . 2

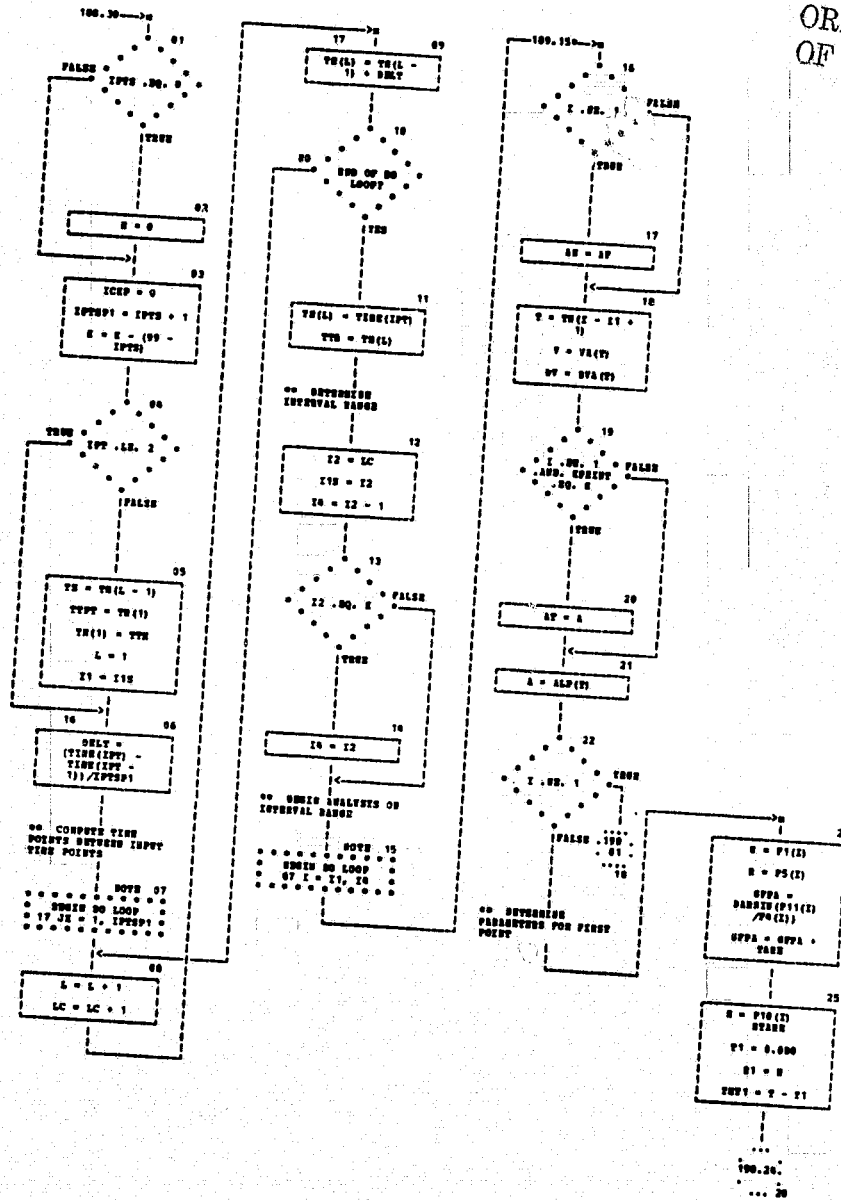
IPTS - 32

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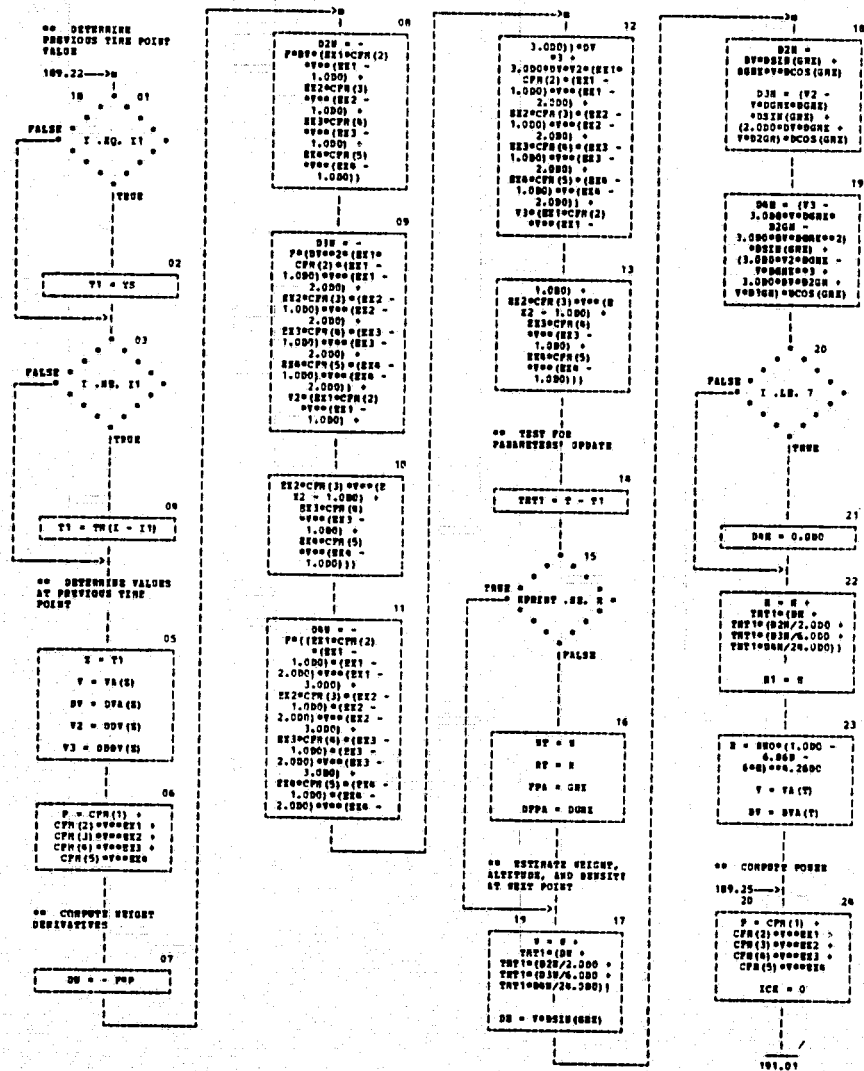


CHART TITLE - SUBROUTINE RPATH(U,P,GRS,LPGR,VIT,TAKE,WTARE,SEPI)

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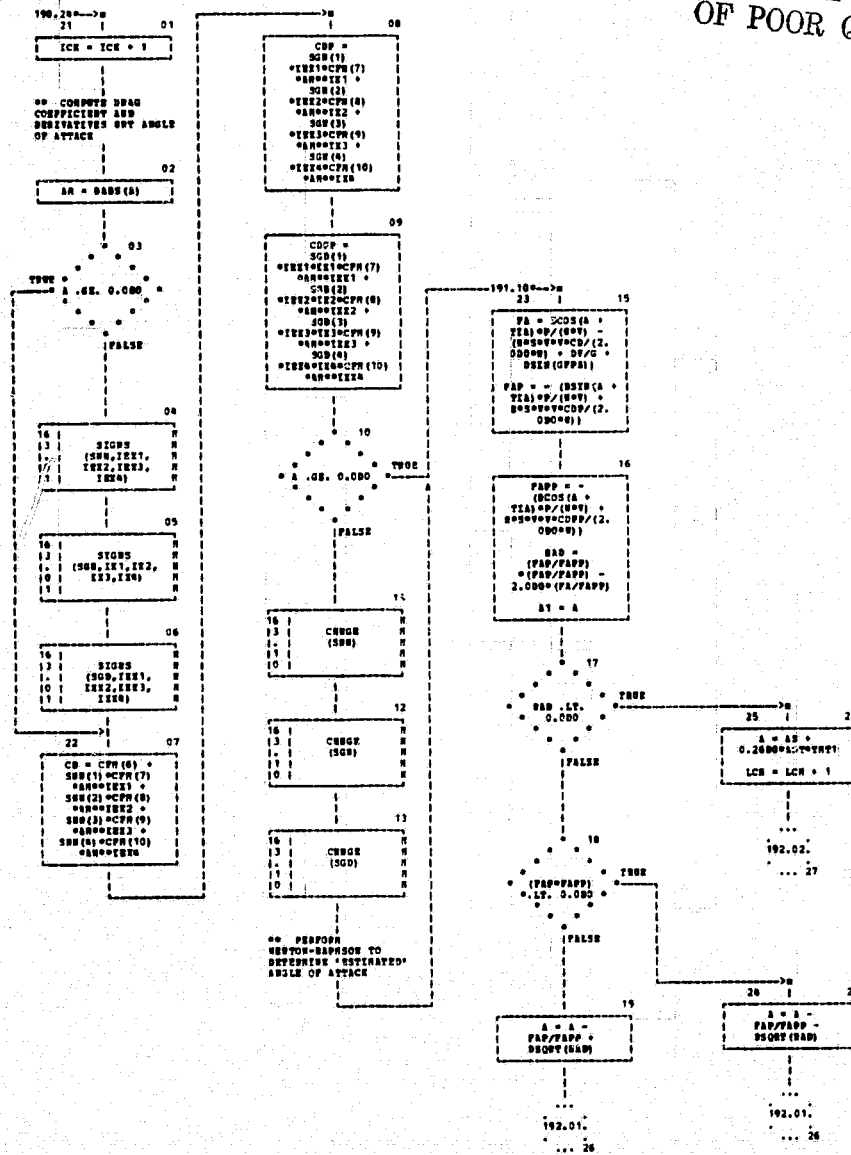
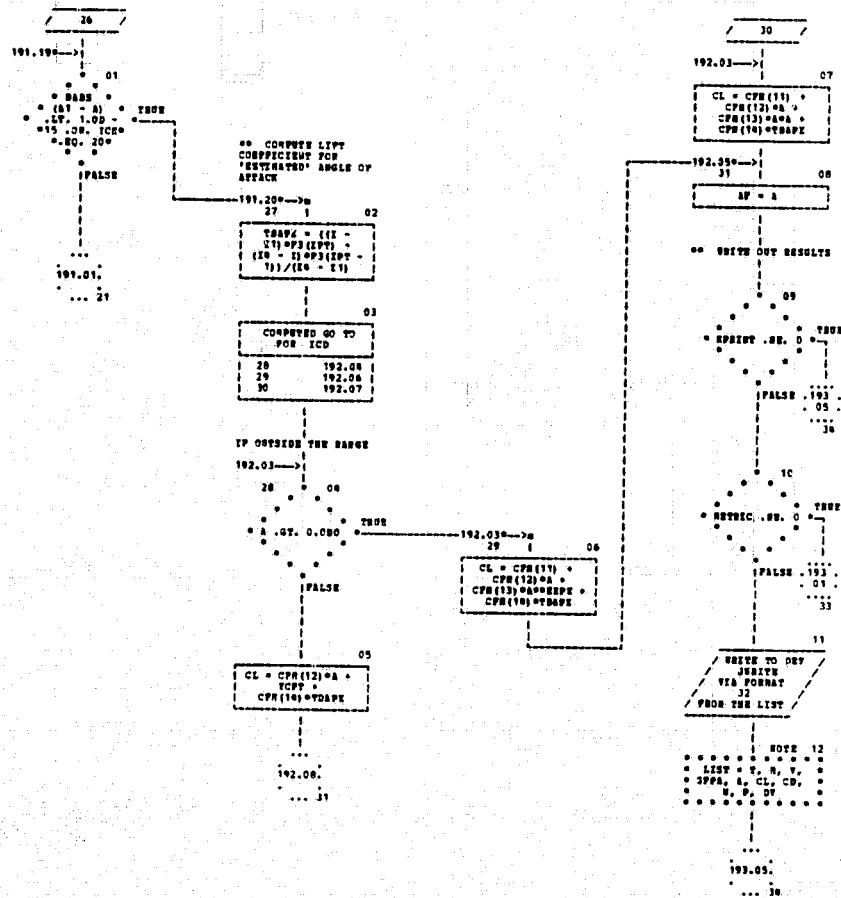
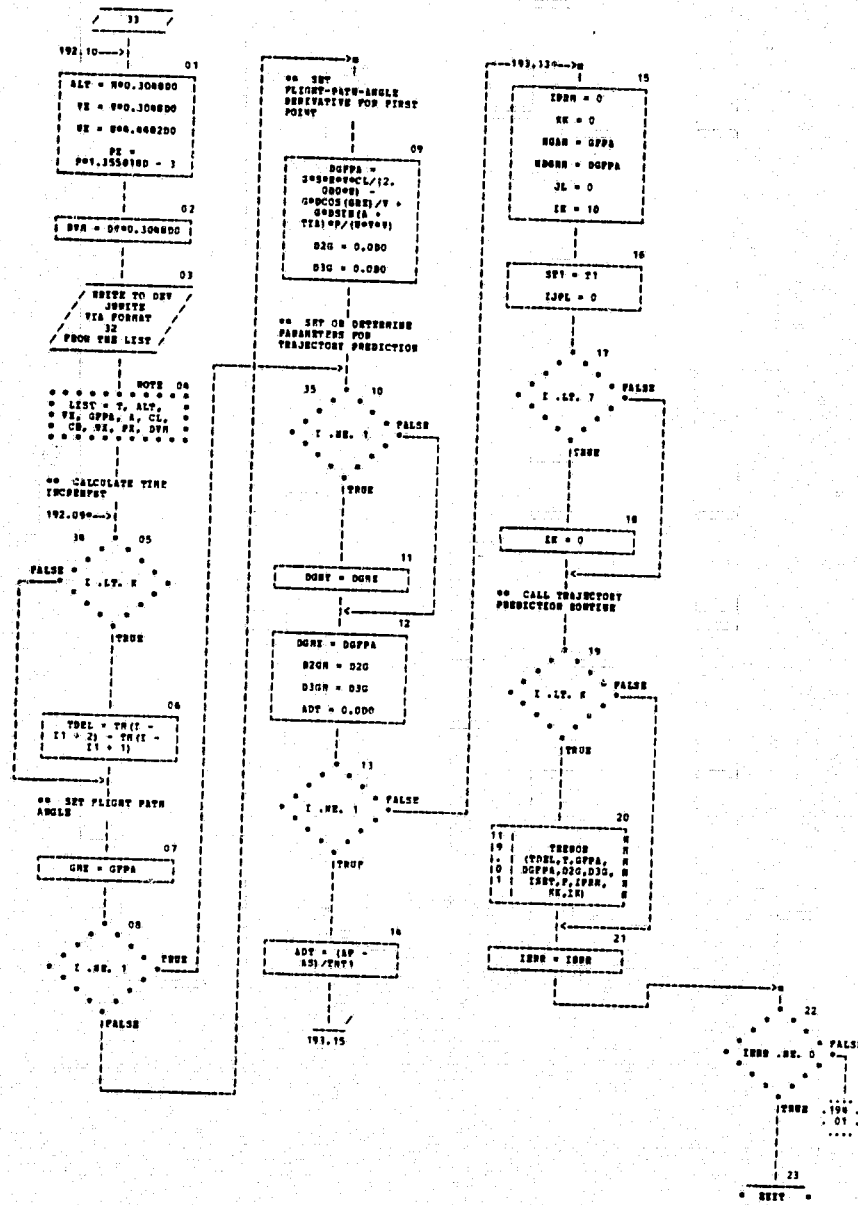


CHART TITLE - SUBROUTINE WPAW(R,P,MR,LPRG,PIV,TABR,WTABR,WRPI)



AUTOFLOW CHART REV - 00002
CHART TITLE - SUBROUTINE HPATH(U,V,W,LPG,PET,TARE,WTARE,HWPE)

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AUTOFLOW CHART 807 -

*0002

PAGE 105

CHART TITLE - CUBIC SPHERE SPHERE(S,P,ABD,LPM,FIV,TAKR,UTADR,GRPE)

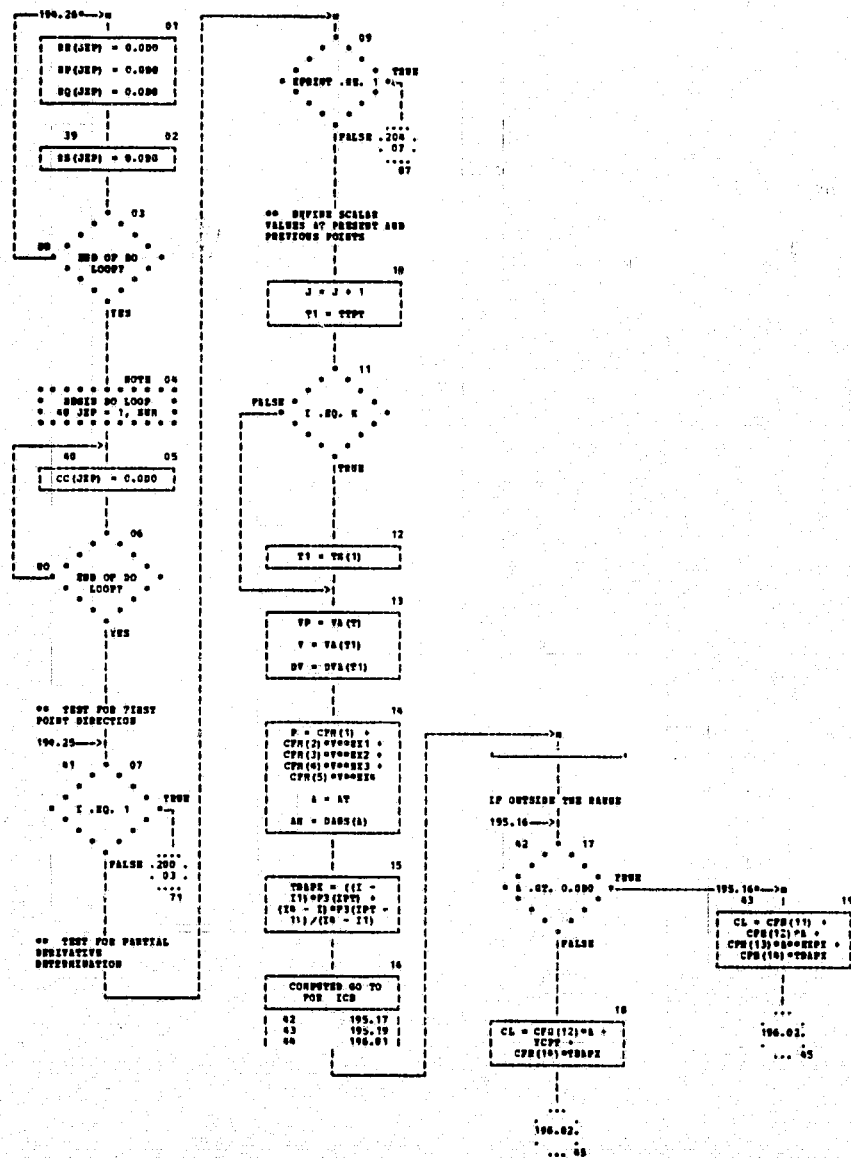


CHART TITLE - SUBROSTION SPATH(U,F,HHH,LPHG,FIT,TADE,STAHU,HHPI)

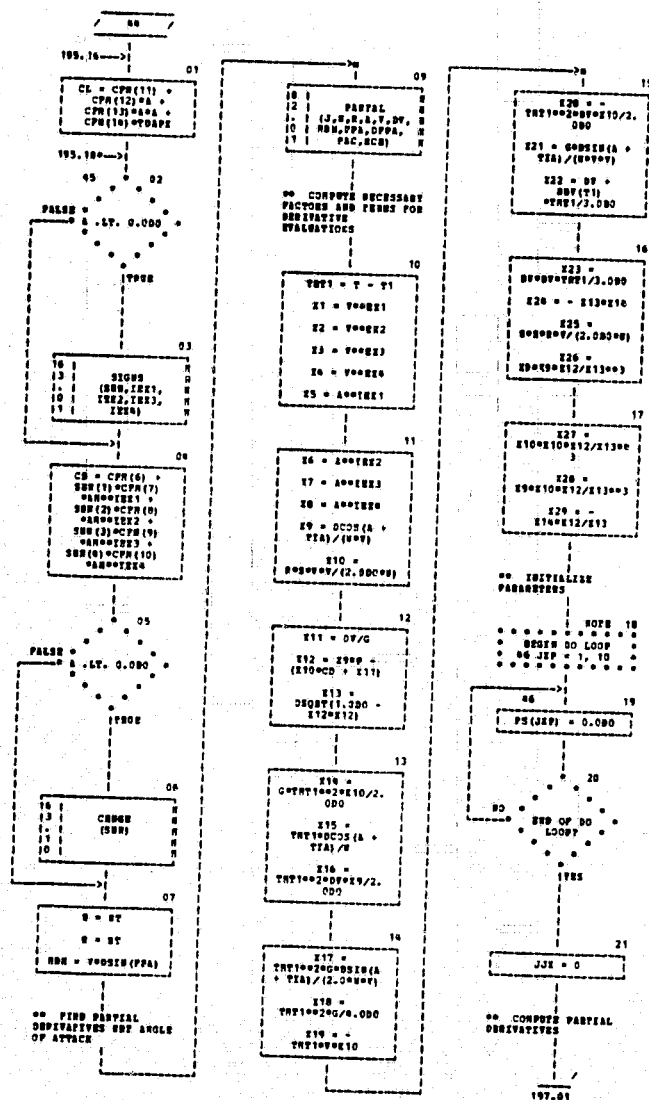


CHART TITLE - SUBROUTERS HPATH (H, F, QUB, LPNG, PIT, TAGE, STAGE, UNDI)

CHART TITLE - SUBROUTINE HPAIR(R,V,SDR,LPOD,PIT,TAGE,HTAGE,ENPI)

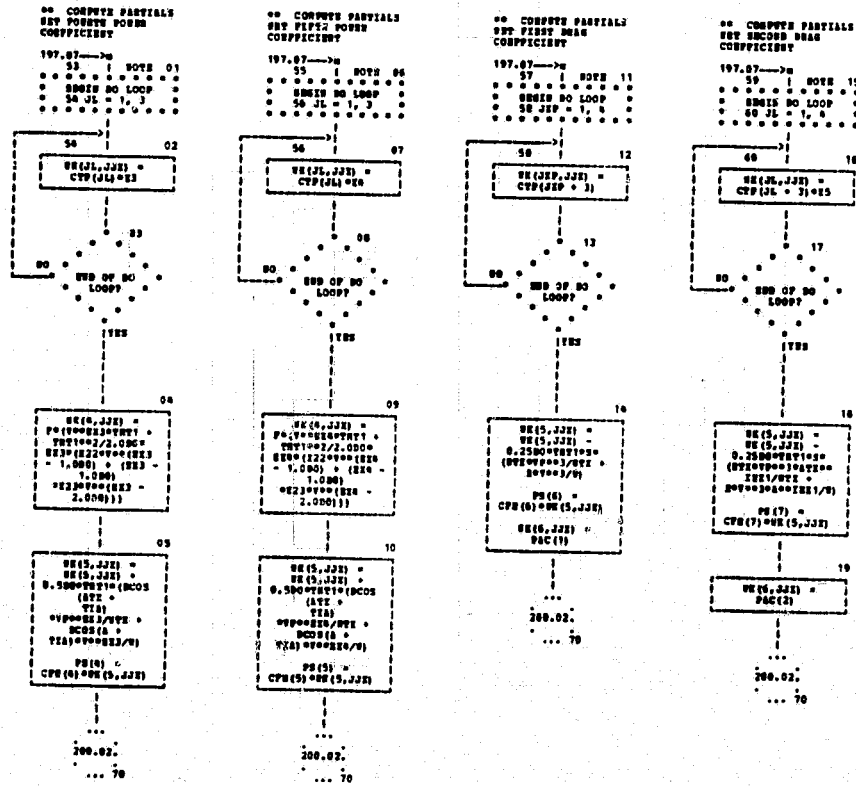


CHART TITLE - SUBROUTINE MPATH(S,P,AND,LPOS,PLT,TIME,UTIME,NMPI

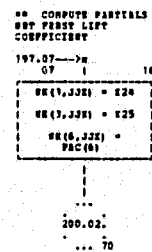
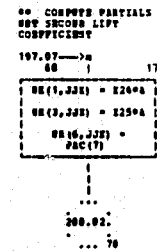
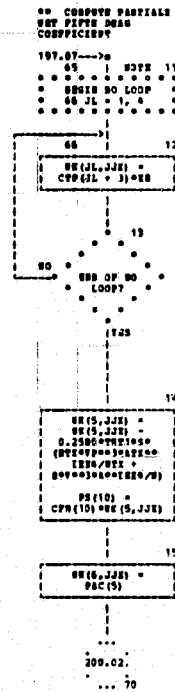
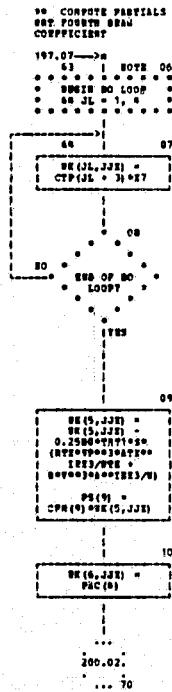
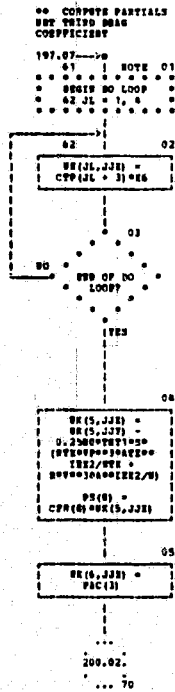


CHART TITLE - SUBROUTINE SPATZ(S,P,RRR,LPPM,PTT,TARR,RYARR,SRPT)

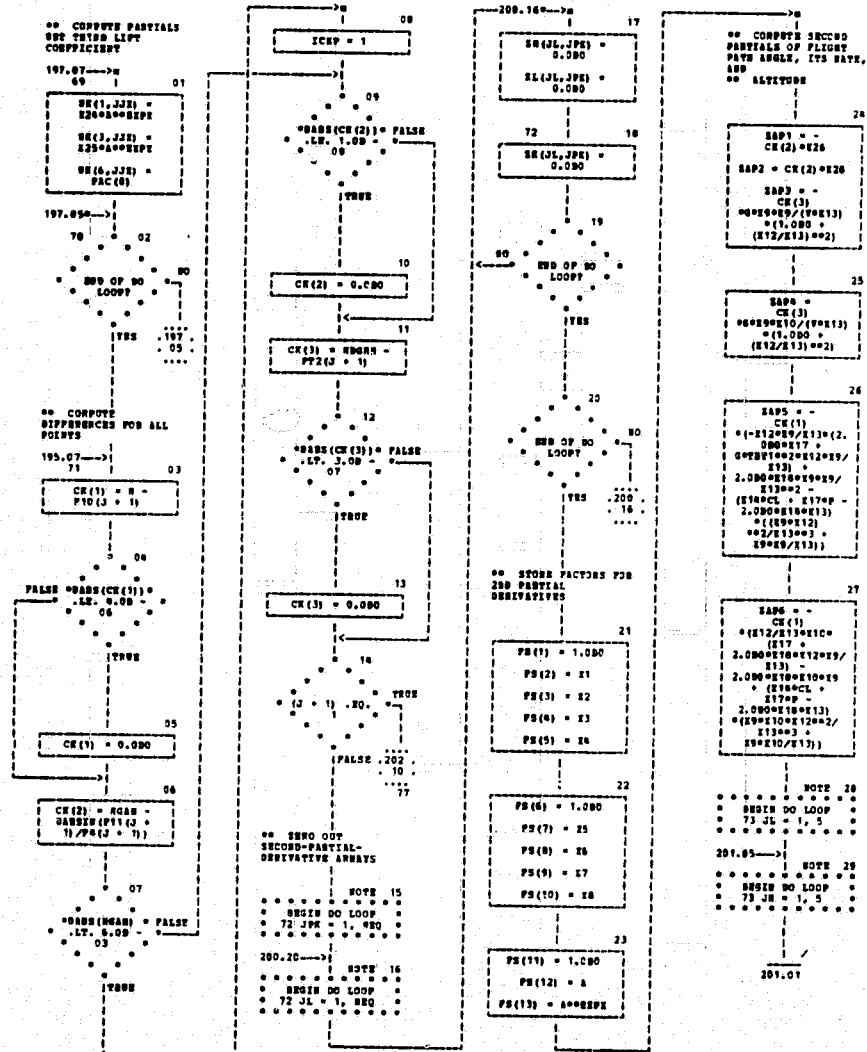
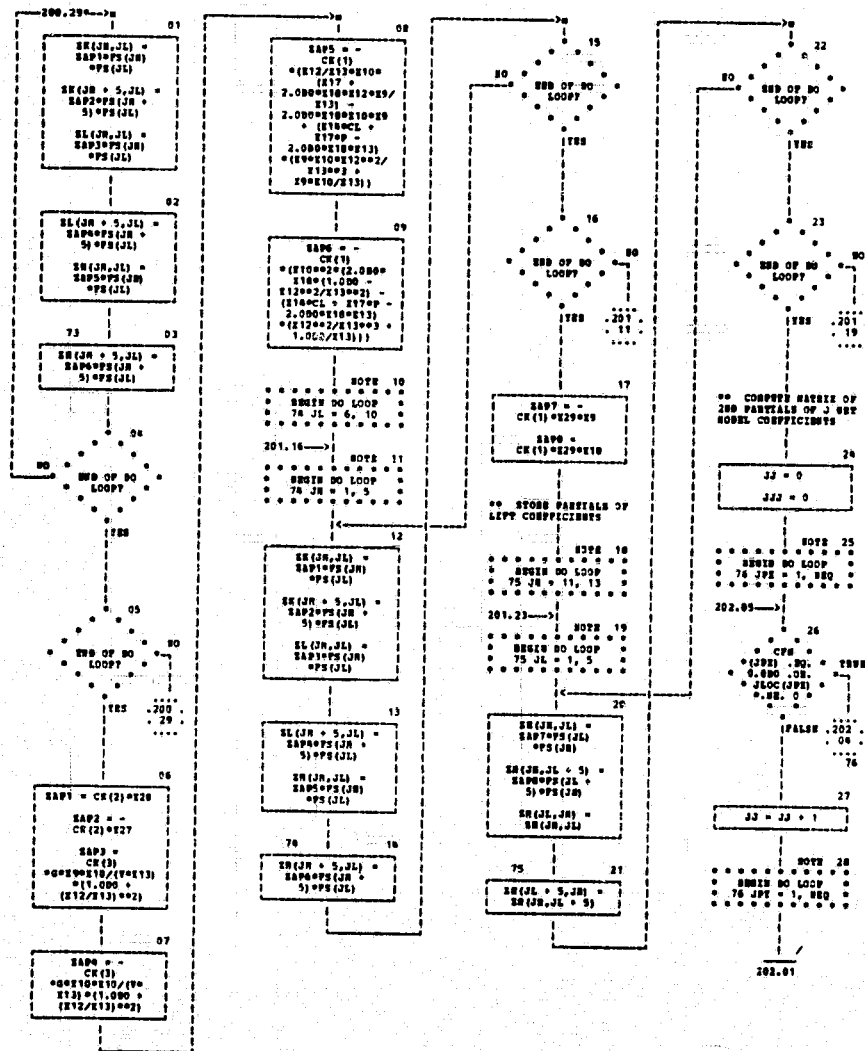


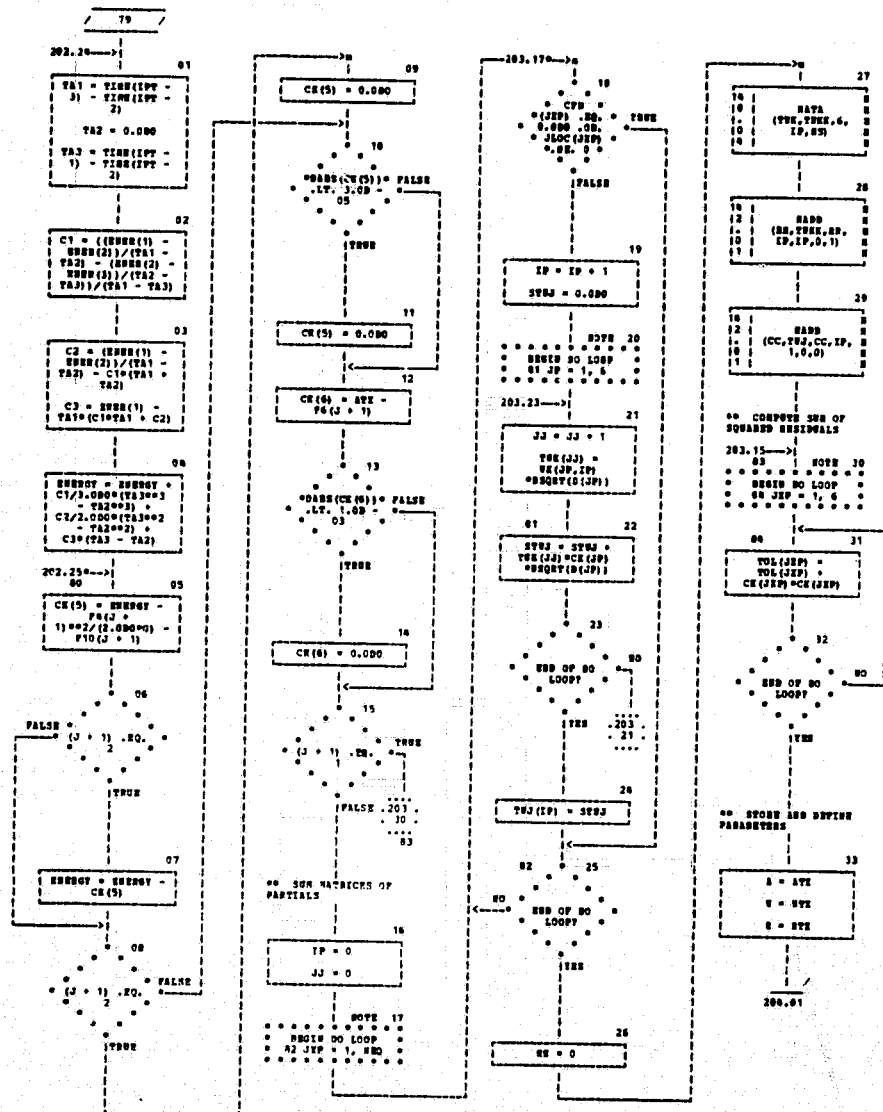
CHART TITLE - SUBROUTINE SPATH(S,F,SUB,LUNG,PIT,TARE,WTARE,SHPIX)





PAGE 203

CHART TITLE - SUBROUTINE ROUTE(U,F,AND,LPDC,FIT,TARE,HTAB,STEP)



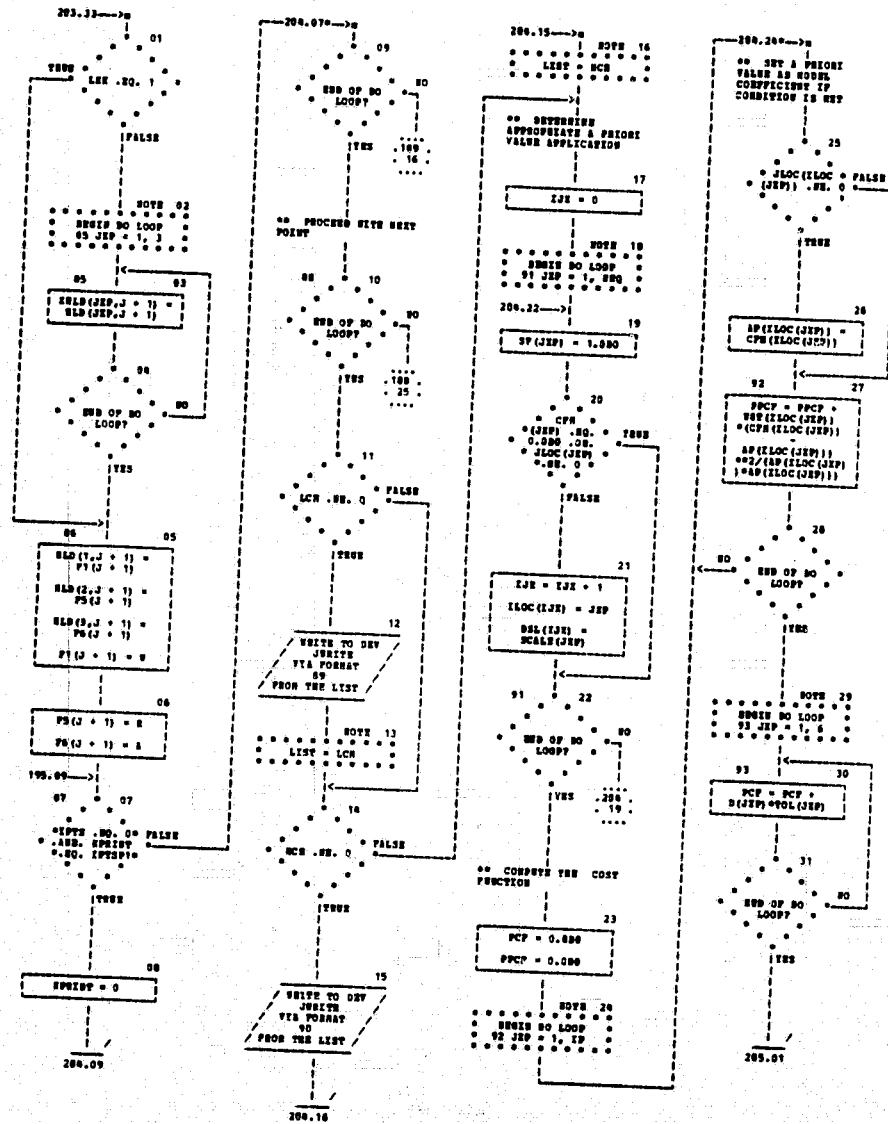
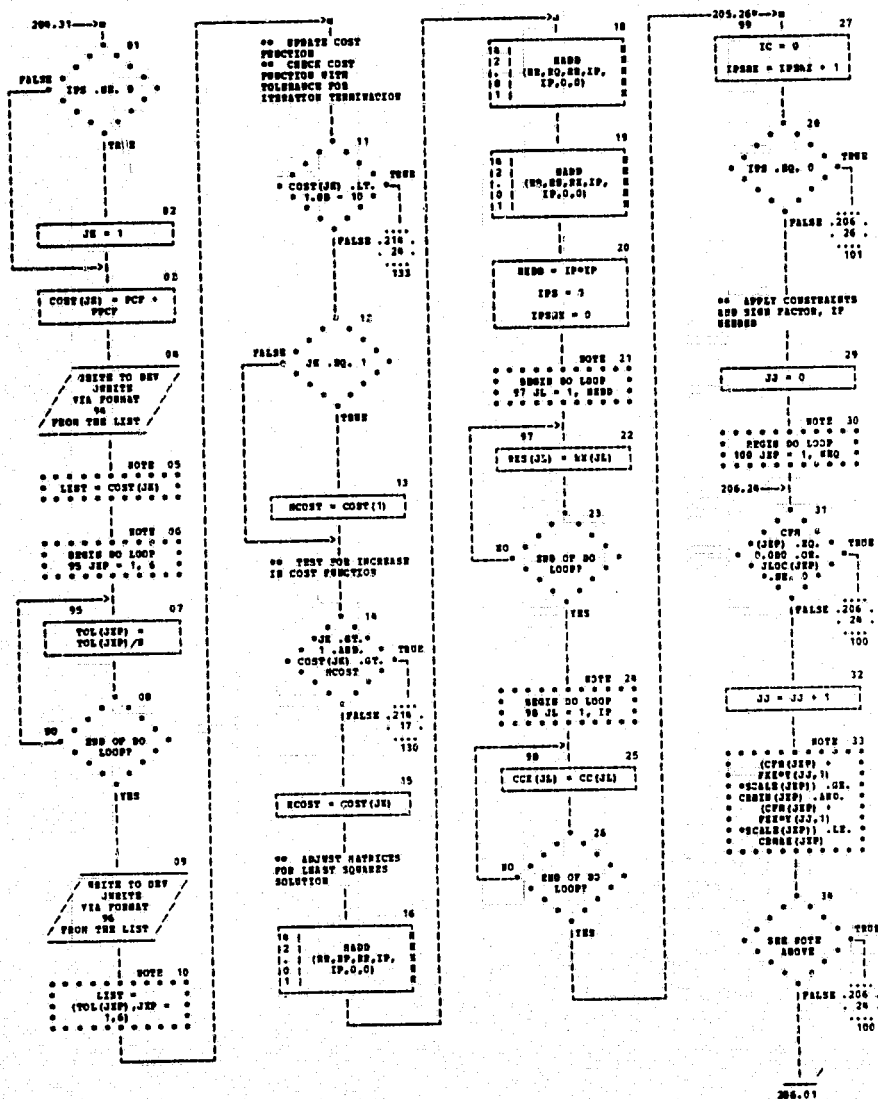
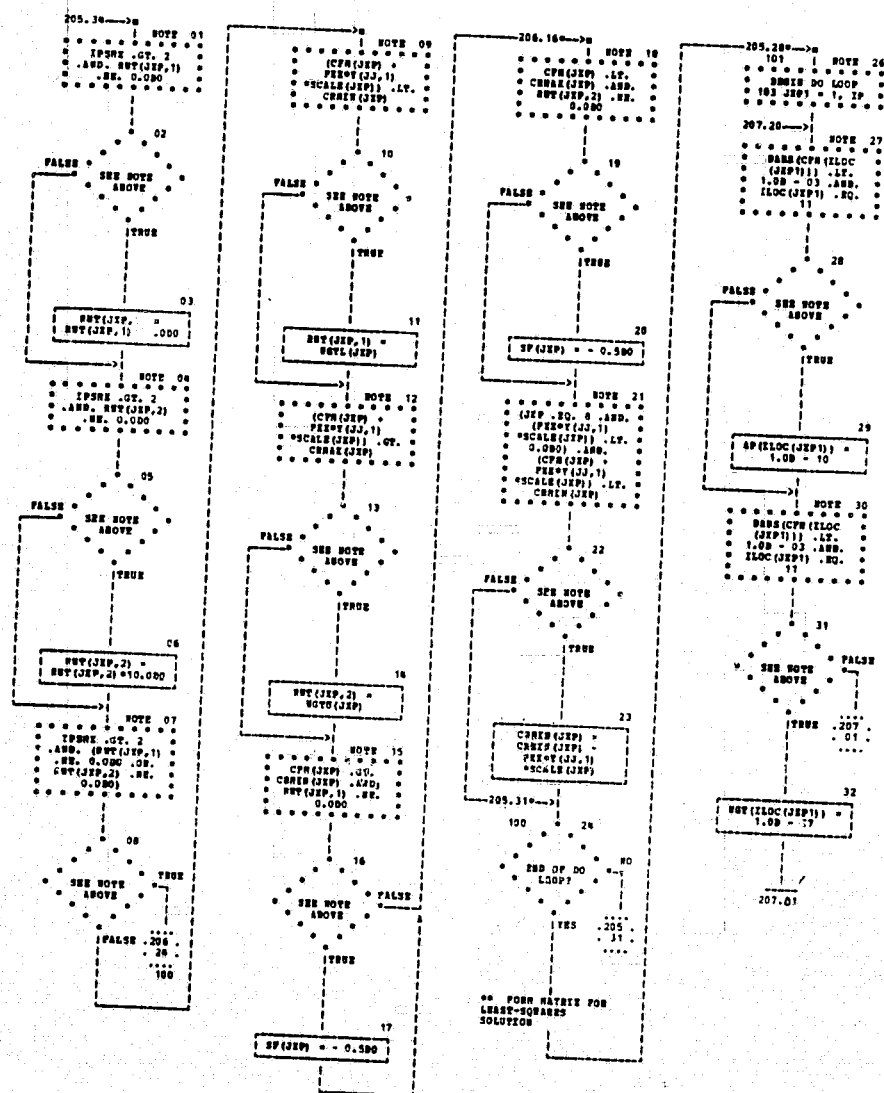


CHART TITLE - SUBROUTINE DEATH(S,F,HUB,LPHG,FIT,TAXI,STARS,NOPI)



CRABT TITLE - SHROTYING SPITH (S, F, HND, LPHG, FIT, TANG, HTARE, DAPY)



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AUTOPLON CHART 207 -

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PAGE 207

CHART TITLE - SUBROUTINE SPACE(S,P,REQ,LONG,PIV,TAB,STARS,SEPI)

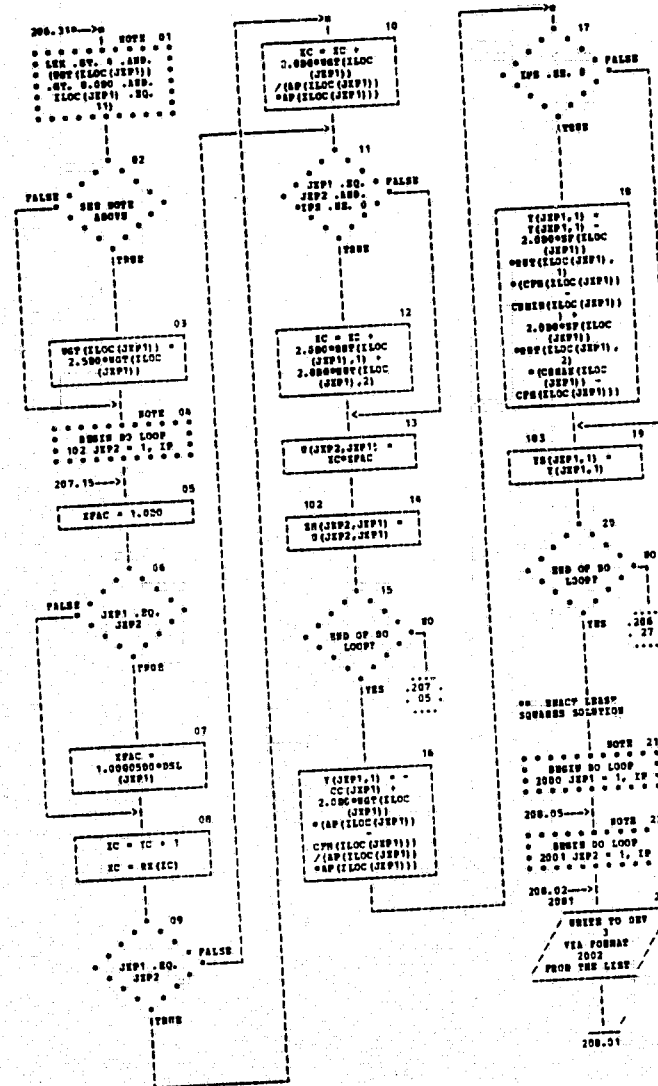
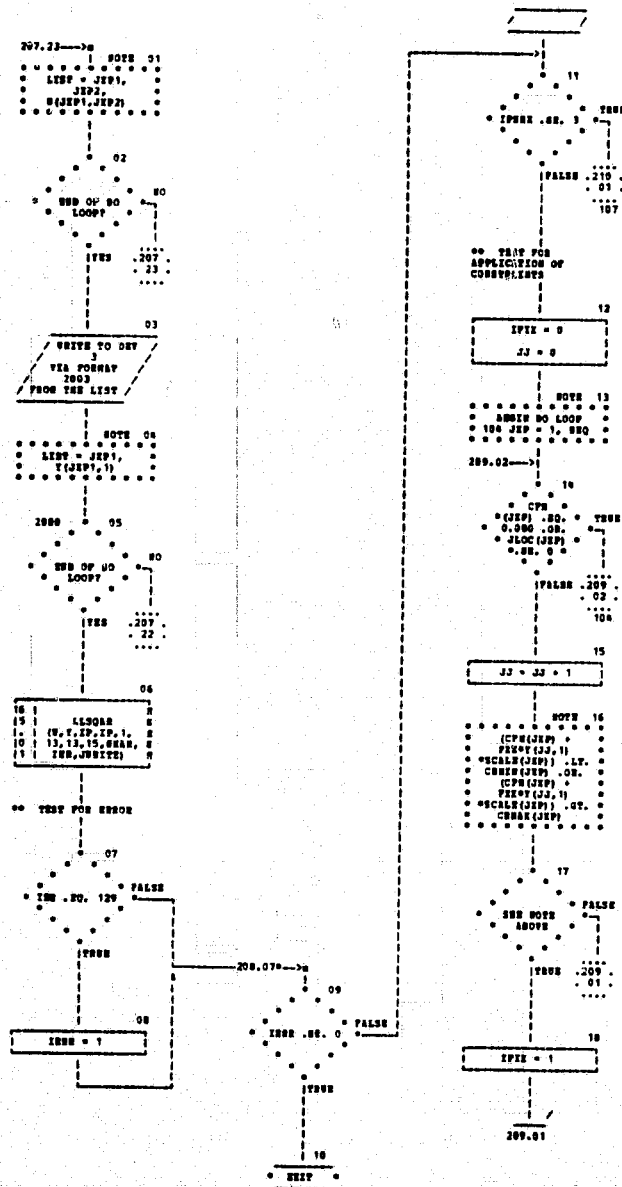


CHART TITLE - SUBROUTINE SPATN (U,V,HNS,LPG,PIT,TARE,RTARE,ENFT)



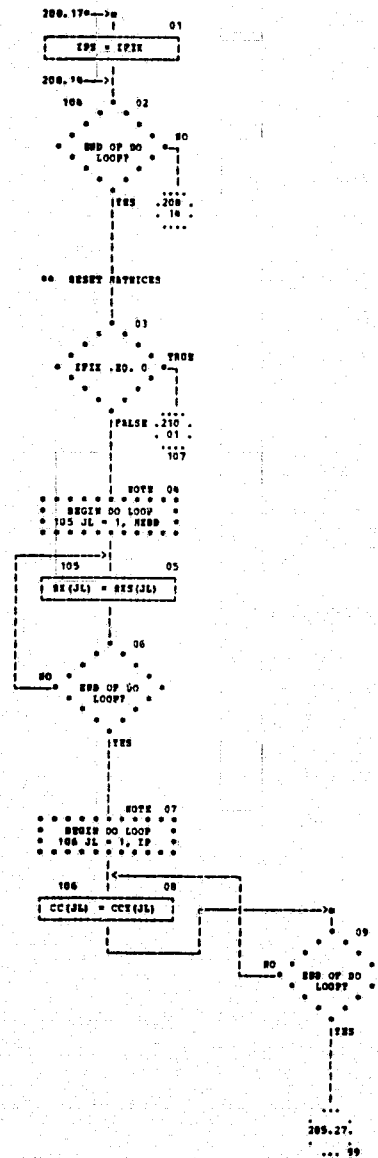
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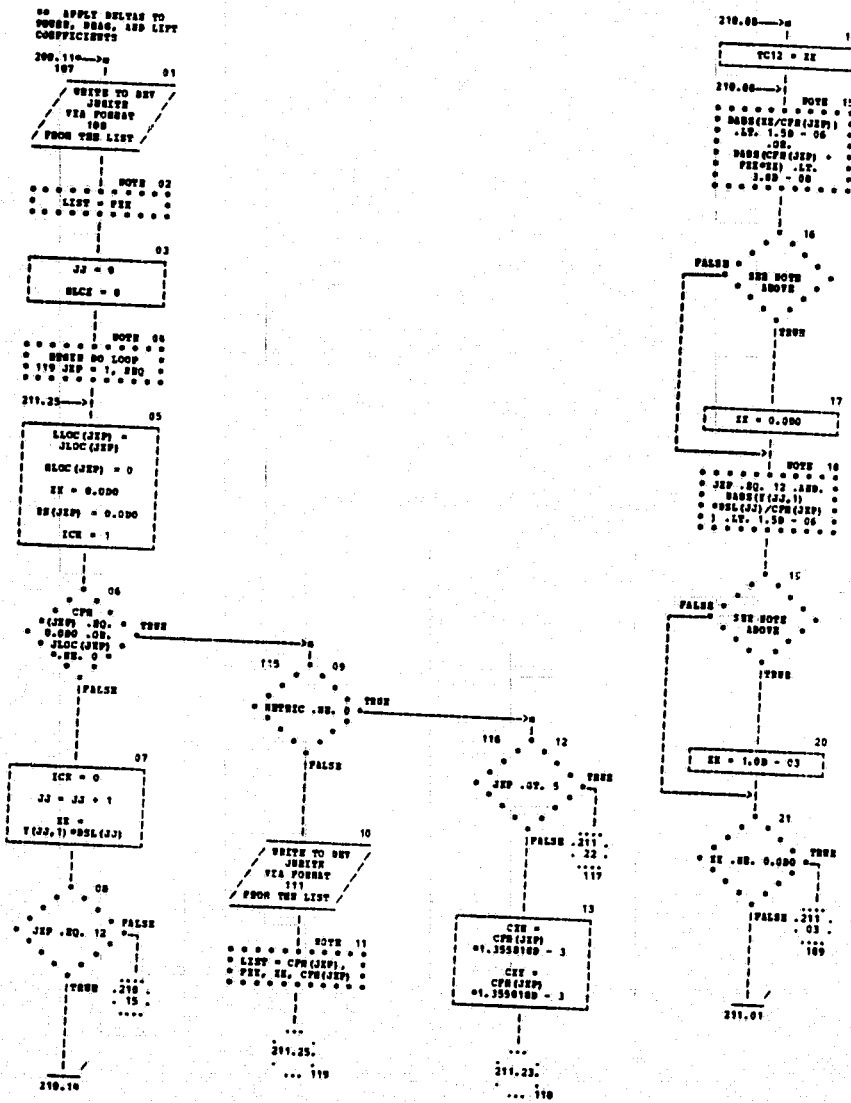
ARTOPLOW CHART 500 -

*P002

PAGE 209

CHART TITLE - SUBROUTINE SPATH(P,P,END,LPG,PT,TAB,STARS,SOPT)





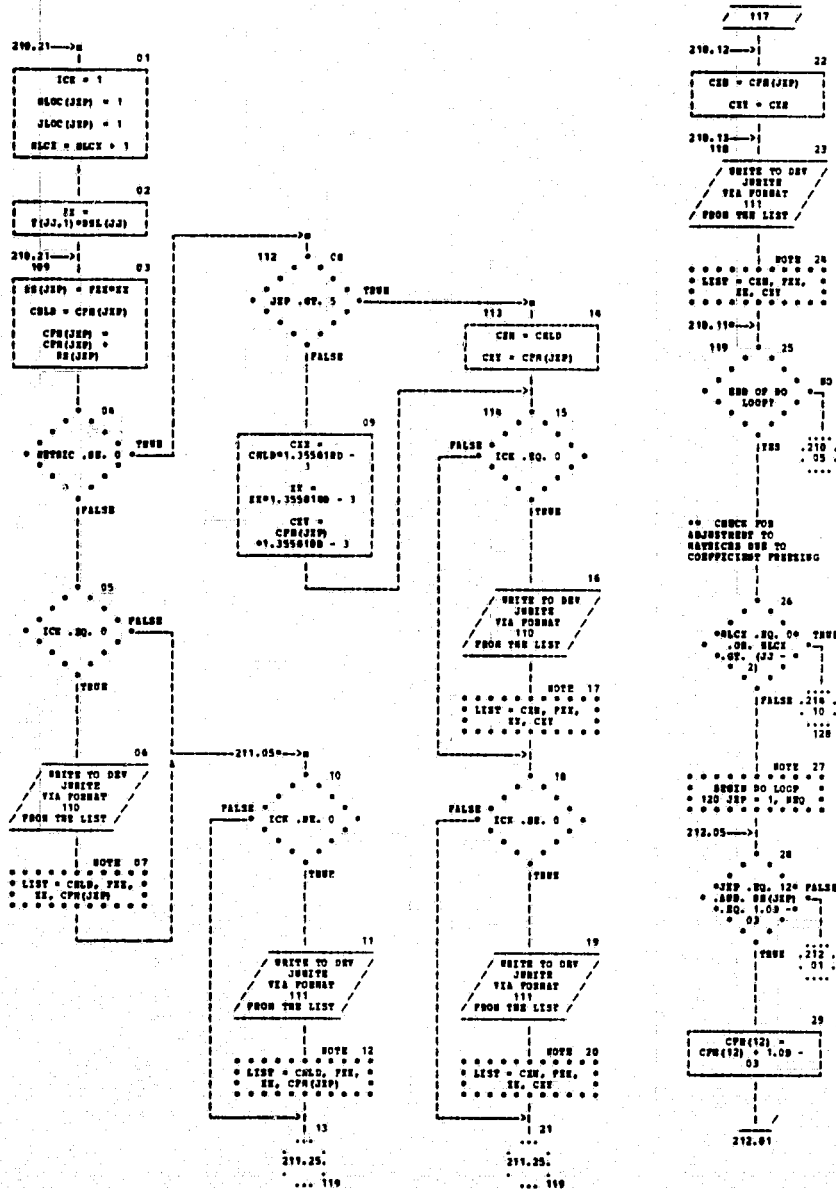
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AUTOLOG CHART 807 -

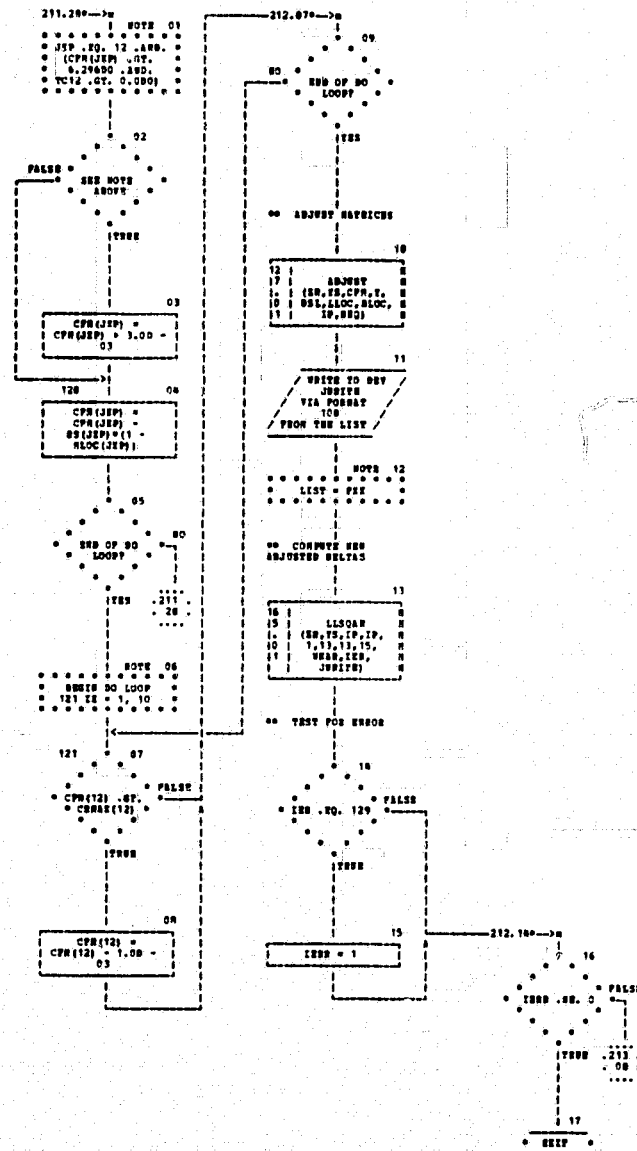
07002

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CHART TITLE - SUBROUTINE 807 (D, F, 800, LPH, P17, 7400, 7400, 8001)

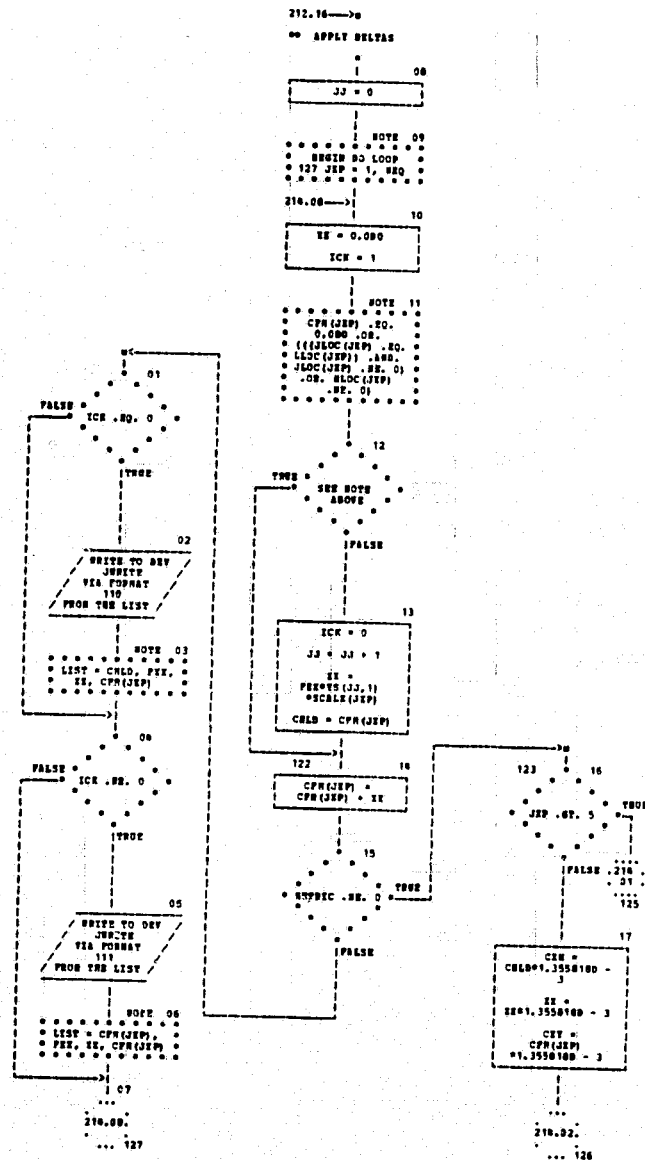


CHAPT TITLE - SUBSECTION NPATH (B, P, RND, LPRG, FIT, TACH, WTDR, NHPF)



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CHART TITLE - SUBROUTINE RPAH(N,P,NOB,LPG,PIT,TIME,STAND,NOPI)
AUTOPAGE CHART SET - *P002
PAGE 313





Sample Input - FDR2

1234567890123456789012345678901234567890123456789012345678901234567890

PATH PERFORMANCE CORRUPTED THEORETICAL DATA

1	0	0	0	2	0	2	1	1	1	2	3	6
0.3333	1.0	2.0	3.0	1	1	2	3	6	MODEL CARD	1.05D-08		
0.0000000000000000	0.0000000000000000	0.0000000000000000	0.0000000000000000	0.0000000000000000	0.0000000000000000	0.0000000000000000	0.0000000000000000	0.0000000000000000	9.90D-03			
0.0	220000.0	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
28735.7142700	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
1126.60714300	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
-2.16964285700	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.035100	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
1.28915501400	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
2030.80086500	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
6.300	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
000000000000000000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
28730.000	28740.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
1125.000	1128.200	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
-2.172900	-2.166500	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.0347500	0.0354500	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
1.287400	1.30000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
2010.000	2050.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
-0.500	0.500	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
6.2500	6.300	0.000	0.000	0.000	0.000	0.000	0.000	0.000				
-0.500	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000				

NEW CORRUPTED THEORETICAL FDR2 MC=10 ON 1/10 OF 1% IN TEST DATA

298	0.15500000	0.3	0.23780000	0.02	0.32200000	0.2	0.28490000	0.2
0.0	0.3999999999999999	0.4	0.1626379051266506	0.0	0.2309777539610616	0.0	0.46640041953812637D	0.1
0.6746509799602561D-02	0.1467390249070915D	0.3	0.46640041953812637D	0.1	0.1626379051266506	0.0	0.2309777539610616	0.0
0.1648560765425594D	0.5200000000000000	0.3	0.46640041953812637D	0.1	0.1626379051266506	0.0	0.2309777539610616	0.0
-0.3801820452064249D-02	0.1000000040672511D	0.4	0.7545954040176251D-02	0.0	0.1626379051266506	0.0	0.2309777539610616	0.0
0.8907990471548577D	0.0	0.0	0.0	0.0	0.1626379051266506	0.0	0.2309777539610616	0.0
0.9999999999999999	0.3999999291529504D	0.4	0.1627060695994274D	0.0	0.2309777539610616	0.0	0.46640041953812637D	0.1
0.68863717154536199D-02	0.14678564653614200D	0.3	0.2309777539610616	0.0	0.1627060695994274D	0.0	0.2309777539610616	0.0
0.1648182138234927D	0.5200000000000000	0.3	0.46640041953812637D	0.1	0.1627060695994274D	0.0	0.2309777539610616	0.0
-0.3770723355296413D-02	0.1000000161032975D	0.4	0.1656222059396401D-01	0.0	0.2309777539610616	0.0	0.46640041953812637D	0.1
0.9124496576312505D	0.0	0.0	0.0	0.0	0.2309777539610616	0.0	0.46640041953812637D	0.1
0.1999999999999999	0.3999998919383835D	0.4	0.1627756309188572D	0.0	0.2309777539610616	0.0	0.46640041953812637D	0.1
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0.1647806620676928D	0.5200000000000000	0.3	0.46640041953812637D	0.1	0.1627756309188572D	0.0	0.2309777539610616	0.0
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* WING AREA = 155.00000 FT**2
* REFERENCE DENSITY = 0.00237800 SLUGS/FT**3
* ACCELERATION DUE TO GRAVITY = 32.2000 FT/SEC**2
* TOTAL TEST TIME = 28.4900 SECONDS

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INITIAL INPUT DATA (PCF PROGRAM LCCP) IN

N	CATA POINT	TIME (SECS)	HEIGHT (LMT)	PITCH ANGLE (RADIANS)	PITCH RATE (RADIANS/SEC)	AIR SPEED (FT/SEC)
1	0	3.60	3595.9557	0.1626370	0.0267668	1467.7390
2	0.010	3595.9560	0.1627081	0.0266863	1467.7656	
3	0.020	3595.9563	0.1627796	0.0267088	1467.8322	
4	0.030	3595.9565	0.1628480	0.0267181	1467.8737	
5	0.040	3595.9567	0.1629168	0.0267304	1467.9251	
6	0.050	3595.9574	0.1630078	0.0267584	1467.9178	
7	0.060	3595.9577	0.1630222	0.0267722	1467.9116	
8	0.100	3595.9595	0.1633921	0.0268131	1467.2025	
9	0.125	3595.9592	0.1633574	0.0268043	1467.2045	
10	0.140	3595.9584	0.1633710	0.0268177	1467.2660	
11	0.180	3595.9530	0.1630762	0.0269127	1467.6269	
12	0.220	3595.9515	0.1624557	0.0269566	1467.7508	
13	0.260	3595.9500	0.1618552	0.0269287	1467.7517	
14	0.300	3595.9488	0.1612770	0.0269191	1467.7508	
15	0.340	3595.9470	0.1607124	0.0269132	1467.8880	
16	0.380	3595.9452	0.1601605	0.0269139	1467.8880	
17	0.500	3595.9410	0.1576562	0.0269326	1469.0011	
18	0.580	3595.9370	0.1548007	0.0269426	1469.3346	
19	0.660	3595.9350	0.1519692	0.0269350	1469.3737	
20	0.740	3595.9320	0.1491257	0.0269377	1469.4007	
21	0.840	3595.9260	0.1457250	0.0269358	1469.4168	
22	0.940	3595.9184	0.1417420	0.0269319	1469.4168	
23	1.040	3595.9107	0.1376542	0.0269313	1469.4168	
24	1.140	3595.9030	0.1334760	0.0269344	1469.4168	
25	1.240	3595.8953	0.1293076	0.0269361	1469.4168	
26	1.340	3595.8876	0.1251392	0.0269361	1469.4168	
27	1.440	3595.8800	0.1210007	0.0269361	1469.4168	
28	1.540	3595.8723	0.1168923	0.0269361	1469.4168	
29	1.640	3595.8647	0.1128039	0.0269361	1469.4168	
30	1.740	3595.8570	0.1087355	0.0269361	1469.4168	
31	1.840	3595.8494	0.1046871	0.0269361	1469.4168	
32	1.940	3595.8417	0.1006587	0.0269361	1469.4168	
33	2.040	3595.8341	0.0966403	0.0269361	1469.4168	
34	2.140	3595.8264	0.0926419	0.0269361	1469.4168	
35	2.240	3595.8188	0.0886635	0.0269361	1469.4168	
36	2.340	3595.8111	0.0847051	0.0269361	1469.4168	
37	2.440	3595.8035	0.0807667	0.0269361	1469.4168	
38	2.540	3595.7958	0.0768483	0.0269361	1469.4168	
39	2.640	3595.7882	0.0729499	0.0269361	1469.4168	
40	2.740	3595.7805	0.0690715	0.0269361	1469.4168	
41	2.840	3595.7729	0.0652131	0.0269361	1469.4168	
42	2.940	3595.7652	0.0613747	0.0269361	1469.4168	
43	3.040	3595.7576	0.0575563	0.0269361	1469.4168	
44	3.140	3595.7500	0.0537579	0.0269361	1469.4168	
45	3.240	3595.7423	0.0499795	0.0269361	1469.4168	
46	3.340	3595.7347	0.0462211	0.0269361	1469.4168	
47	3.440	3595.7270	0.0424827	0.0269361	1469.4168	
48	3.540	3595.7194	0.0387643	0.0269361	1469.4168	
49	3.640	3595.7117	0.0350659	0.0269361	1469.4168	
50	3.740	3595.7041	0.0313875	0.0269361	1469.4168	
51	3.840	3595.6964	0.0277291	0.0269361	1469.4168	
52	3.940	3595.6888	0.0240907	0.0269361	1469.4168	
53	4.040	3595.6811	0.0204723	0.0269361	1469.4168	
54	4.140	3595.6735	0.0168739	0.0269361	1469.4168	
55	4.240	3595.6658	0.0132955	0.0269361	1469.4168	
56	4.340	3595.6582	0.0097371	0.0269361	1469.4168	
57	4.440	3595.6505	0.0061987	0.0269361	1469.4168	
58	4.540	3595.6429	0.0026803	0.0269361	1469.4168	
59	4.640	3595.6352	0.0001819	0.0269361	1469.4168	
60	4.740	3595.6276	0.0000000	0.0269361	1469.4168	
61	4.840	3595.6200	0.0000000	0.0269361	1469.4168	
62	4.940	3595.6124	0.0000000	0.0269361	1469.4168	
63	5.040	3595.6048	0.0000000	0.0269361	1469.4168	
64	5.140	3595.5972	0.0000000	0.0269361	1469.4168	
65	5.240	3595.5896	0.0000000	0.0269361	1469.4168	
66	5.340	3595.5820	0.0000000	0.0269361	1469.4168	
67	5.440	3595.5744	0.0000000	0.0269361	1469.4168	

200	18e990	3999.2655	-0.115621	-0.0208180	211.8283
201	18e991	3999.2656	-0.117691	-0.0208250	212.8034
202	18e992	3999.2657	-0.1199572	-0.0192307	213.6736
203	18e993	3999.2658	-0.121741	-0.0184413	214.4447
204	18e994	3999.2659	-0.1235476	-0.0176491	215.2164
205	18e995	3999.2660	-0.1254755	-0.0168403	215.9889
206	18e996	3999.2661	-0.1274228	-0.0160113	216.7627
207	18e997	3999.2662	-0.1294897	-0.0151642	217.5388
208	18e998	3999.2663	-0.1316773	-0.0143073	218.3164
209	18e999	3999.2664	-0.1339857	-0.0134360	219.0954
210	19e000	3999.2665	-0.1364143	-0.0125549	219.8768
211	19e001	3999.2666	-0.1389633	-0.0116687	220.6606
212	19e002	3999.2667	-0.1416329	-0.0107724	221.4468
213	19e003	3999.2668	-0.1444233	-0.0098709	222.2354
214	19e004	3999.2669	-0.1473347	-0.0089594	223.0264
215	19e005	3999.2670	-0.1503673	-0.0080330	223.8198
216	19e006	3999.2671	-0.1535222	-0.0070967	224.6156
217	19e007	3999.2672	-0.1567997	-0.0061556	225.4138
218	19e008	3999.2673	-0.1601999	-0.0052047	226.2144
219	19e009	3999.2674	-0.1637231	-0.0042490	227.0174
220	19e010	3999.2675	-0.1673697	-0.0032835	227.8228
221	19e011	3999.2676	-0.1711401	-0.0023032	228.6306
222	19e012	3999.2677	-0.1750347	-0.0013032	229.4408
223	19e013	3999.2678	-0.1790539	-0.0002785	230.2534
224	19e014	3999.2679	-0.1831981	0.0007664	231.0684
225	19e015	3999.2680	-0.1874679	0.0018734	231.8858
226	19e016	3999.2681	-0.1918641	0.0030044	232.7056
227	19e017	3999.2682	-0.1963875	0.0041644	233.5278
228	19e018	3999.2683	-0.2010391	0.0053584	234.3524
229	19e019	3999.2684	-0.2058199	0.0065914	235.1794
230	19e020	3999.2685	-0.2107309	0.0078684	236.0088
231	19e021	3999.2686	-0.2157731	0.0091944	236.8406
232	19e022	3999.2687	-0.2209475	0.0105744	237.6748
233	19e023	3999.2688	-0.2262541	0.0120144	238.5214
234	19e024	3999.2689	-0.2316929	0.0135194	239.3804
235	19e025	3999.2690	-0.2372649	0.0150944	240.2518
236	19e026	3999.2691	-0.2429701	0.0167444	241.1356
237	19e027	3999.2692	-0.2488095	0.0184744	242.0318
238	19e028	3999.2693	-0.2547841	0.0202894	242.9414
239	19e029	3999.2694	-0.2608949	0.0221944	243.8644
240	19e030	3999.2695	-0.2671429	0.0241944	244.8008
241	19e031	3999.2696	-0.2735281	0.0262944	245.7506
242	19e032	3999.2697	-0.2800515	0.0284944	246.7138
243	19e033	3999.2698	-0.2867141	0.0307944	247.6904
244	19e034	3999.2699	-0.2935169	0.0331944	248.6804
245	19e035	3999.2700	-0.3004609	0.0356944	249.6838
246	19e036	3999.2701	-0.3075471	0.0382944	250.7006
247	19e037	3999.2702	-0.3147765	0.0409944	251.7308
248	19e038	3999.2703	-0.3221501	0.0437944	252.7744
249	19e039	3999.2704	-0.3296689	0.0466944	253.8314
250	19e040	3999.2705	-0.3373329	0.0496944	254.9018
251	19e041	3999.2706	-0.3451431	0.0527944	255.9856
252	19e042	3999.2707	-0.3530995	0.0559944	257.0828
253	19e043	3999.2708	-0.3612021	0.0592944	258.1934
254	19e044	3999.2709	-0.3694509	0.0626944	259.3174
255	19e045	3999.2710	-0.3778459	0.0661944	260.4548
256	19e046	3999.2711	-0.3863871	0.0697944	261.6056
257	19e047	3999.2712	-0.3950745	0.0734944	262.7708
258	19e048	3999.2713	-0.4039081	0.0772944	263.9504
259	19e049	3999.2714	-0.4128879	0.0811944	265.1444
260	19e050	3999.2715	-0.4219139	0.0851944	266.3528
261	19e051	3999.2716	-0.4310861	0.0892944	267.5756
262	19e052	3999.2717	-0.4404045	0.0934944	268.8128
263	19e053	3999.2718	-0.4498691	0.0977944	270.0644
264	19e054	3999.2719	-0.4594799	0.1021944	271.3304
265	19e055	3999.2720	-0.4692369	0.1066944	272.6108
266	19e056	3999.2721	-0.4791401	0.1112944	273.9056
267	19e057	3999.2722	-0.4891895	0.1159944	275.2158
268	19e058	3999.2723	-0.4993851	0.1207944	276.5414
269	19e059	3999.2724	-0.5097269	0.1256944	277.8824
270	19e060	3999.2725	-0.5202149	0.1306944	279.2388
271	19e061	3999.2726	-0.5308491	0.1357944	280.6106
272	19e062	3999.2727	-0.5416295	0.1409944	282.0078
273	19e063	3999.2728	-0.5525561	0.1462944	283.4304
274	19e064	3999.2729	-0.5636289	0.1516944	284.8784
275	19e065	3999.2730	-0.5748479	0.1571944	286.3518
276	19e066	3999.2731	-0.5862131	0.1627944	287.8506
277	19e067	3999.2732	-0.5977245	0.1684944	289.3748
278	19e068	3999.2733	-0.6093821	0.1742944	290.9244
279	19e069	3999.2734	-0.6211859	0.1801944	292.4994
280	19e070	3999.2735	-0.6331359	0.1861944	294.0998
281	19e071	3999.2736	-0.6452321	0.1922944	295.7256
282	19e072	3999.2737	-0.6574745	0.1984944	297.3768
283	19e073	3999.2738	-0.6698631	0.2047944	299.0534
284	19e074	3999.2739	-0.6823979	0.2111944	300.7556
285	19e075	3999.2740	-0.6950789	0.2176944	302.4834
286	19e076	3999.2741	-0.7079061	0.2242944	304.2368
287	19e077	3999.2742	-0.7208795	0.2309944	306.0158
288	19e078	3999.2743	-0.7339991	0.2377944	307.8204
289	19e079	3999.2744	-0.7472649	0.2446944	309.6506
290	19e080	3999.2745	-0.7606769	0.2516944	311.5064
291	19e081	3999.2746	-0.7742351	0.2587944	313.3878
292	19e082	3999.2747	-0.7879495	0.2659944	315.2948
293	19e083	3999.2748	-0.8018201	0.2732944	317.2274
294	19e084	3999.2749	-0.8158469	0.2806944	319.1856
295	19e085	3999.2750	-0.8300299	0.2881944	321.1694
296	19e086	3999.2751	-0.8443691	0.2957944	323.1788
297	19e087	3999.2752	-0.8588645	0.3034944	325.2138
298	19e088	3999.2753	-0.8735161	0.3112944	327.2744
299	19e089	3999.2754	-0.8883239	0.3191944	329.3606
300	19e090	3999.2755	-0.9032879	0.3271944	331.4724

DATA POINT	TIME (SECS)	DENSITY (SLUG/FT**3)	ANGLE OF ATTACK (RADIAN)	TEMPERATURE (DEG-R)	ACCELERATION (FT/SEC**2)
1	0.00	0.00230976	0.1848561	520.00	4.68606
2	0.010	0.00230976	0.1848182	520.00	4.68628
3	0.020	0.00230976	0.1847807	520.00	4.68647
4	0.030	0.00230976	0.1847434	520.00	4.68663
5	0.040	0.00230976	0.1847060	520.00	4.68677
6	0.050	0.00230976	0.1846686	520.00	4.68688
7	0.060	0.00230976	0.1846311	520.00	4.68697
8	0.070	0.00230976	0.1845936	520.00	4.68704
9	0.080	0.00230976	0.1845561	520.00	4.68709
10	0.090	0.00230976	0.1845186	520.00	4.68712
11	0.100	0.00230976	0.1844811	520.00	4.68714
12	0.110	0.00230976	0.1844436	520.00	4.68715
13	0.120	0.00230976	0.1844061	520.00	4.68715
14	0.130	0.00230976	0.1843686	520.00	4.68714
15	0.140	0.00230976	0.1843311	520.00	4.68712
16	0.150	0.00230976	0.1842936	520.00	4.68709
17	0.160	0.00230976	0.1842561	520.00	4.68704
18	0.170	0.00230976	0.1842186	520.00	4.68697
19	0.180	0.00230976	0.1841811	520.00	4.68688
20	0.190	0.00230976	0.1841436	520.00	4.68677
21	0.200	0.00230976	0.1841061	520.00	4.68663
22	0.210	0.00230976	0.1840686	520.00	4.68647
23	0.220	0.00230976	0.1840311	520.00	4.68628
24	0.230	0.00230976	0.1839936	520.00	4.68606
25	0.240	0.00230976	0.1839561	520.00	4.68582
26	0.250	0.00230976	0.1839186	520.00	4.68556

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OF POOR QUALITY

27	14840	00023062	00042188	520000	3460728
28	14840	00023062	00042187	520000	3460728
29	14840	00023065	00042180	520000	3462314
30	14840	00023065	00042182	520000	3471688
31	14840	00023065	00042183	520000	3470728
32	14840	00023065	00042115	520000	3469675
33	14840	00023064	00042107	520000	3469675
34	14840	00023064	00042086	520000	3470728
35	14840	00023063	00042080	520000	3469675
36	14840	00023062	00042039	520000	3469675
37	14840	00023062	00042037	520000	3469675
38	14840	00023062	00042036	520000	3469675
39	14840	00023061	00041879	520000	3469675
40	14840	00023061	00041797	520000	3469675
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142	14840	00023061	00040610	520000	3469675
143	14840	00023061	00040610	520000	3469675
144	14840	00023061	00040610	520000	3469675
145	14840	00023061	00040610	520000	3469675
146	14840	00023061	00040610	520000	3469675
147	14840	00023061	00040610	520000	3469675
148	14840	00023061	00040610	520000	3469675
149	14840	00023061	00040610	520000	3469675
150	14840	00023061	00040610	520000	3469675
151	14840	00023061	00040610	520000	3469675
152	14840	00023061	00040610	520000	3469675
153	14840	00023061	00040610	520000	3469675
154	14840	00023061	00040610	520000	3469675
155	14840	00023061	00040610	520000	3469675
156	14840	00023061	00040610	520000	3469675
157	14840	00023061	00040610	520000	3469675
158	14840	00023061	00040610	520000	3469675
159	14840	00023061	00040610	520000	3469675
160	14840	00023061	00040610	520000	3469675
161	14840	00023061	00040610	520000	3469675
162	14840	00023061	00040610	520000	3469675
163	14840	00023061	00040610	520000	3469675
164	14840	00023061	00040610	520000	3469675
165	14840	00023061	00040610	520000	3469675
166	14840	00023061	00040610	520000	3469675
167	14840	00023061	00040610	520000	3469675
168	14840	00023061	00040610	520000	3469675
169	14840	00023061	00040610	520000	3469675
170	14840	00023061	00040610	520000	3469675
171	14840	00023061	00040610	520000	3469675
172	14840	00023061	00040610	520000	3469675
173	14840	00023061	00040610	520000	3469675
174	14840	00023061	00040610	520000	3469675
175	14840	00023061	00040610	520000	3469675
176	14840	00023061	00040610	520000	3469675
177	14840	00023061	00040610	520000	3469675
178	14840	00023061	00040610	520000	3469675
179	14840	00023061	00040610	520000	3469675
180	14840	00023061	00040610	520000	3469675
181	14840	00023061	00040610	520000	3469675
182	14840	00023061	00040610	520000	3469675
183	14840	00023061	00040610	520000	3469675
184	14840	00023061	00040610	520000	3469675
185	14840	00023061	00040610	520000	3469675
186	14840	00023061	00040610	520000	3469675
187	14840	00023061	00040610	520000	3469675
188	14840	00023061	00040610	520000	3469675
189	14840	00023061	00040610	520000	3469675
190	14840	00023061	00040610	520000	3469675
191	14840	00023061	00040610	520000	3469675
192	14840	00023061	00040610	520000	3469675
193	14840	00023061	00040610	520000	3469675
194	14840	00023061	00040610	520000	3469675
195	14840	00023061	00040610	520000	3469675
196	14840	00023061	00040610	520000	3469675
197	14840	00023061	00040610	520000	3469675
198	14840	00023061	00040610	520000	3469675
199	14840	00023061	00040610	520000	3469675
200	14840	00023061	00040610	520000	3469675

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ORIGINAL PAGE IS
OF POOR QUALITY

DATA POINT	TIME (SECS)	ANGLE-UP-ATTACH RATE (RADIAN/SEC)	ALTITUDE (FT)	ALTITUDE RATE (FT/SEC)	ALT. ACCEL. (FT/SEC**2)	VEL. ACCEL. (FT/SEC**2)	ELV. DEFLECT. (RADIAN)
1	0.00	-3.003801921	1000.00	0.00	0.00	0.00	0.00
2	0.010	-3.003770743	1000.00	0.00	0.00	0.00	0.00
3	0.020	-3.003739565	1000.00	0.00	0.00	0.00	0.00
4	0.030	-3.003708387	1000.00	0.00	0.00	0.00	0.00
5	0.040	-3.003677209	1000.00	0.00	0.00	0.00	0.00
6	0.050	-3.003646031	1000.00	0.00	0.00	0.00	0.00
7	0.060	-3.003614853	1000.00	0.00	0.00	0.00	0.00
8	0.070	-3.003583675	1000.00	0.00	0.00	0.00	0.00
9	0.080	-3.003552497	1000.00	0.00	0.00	0.00	0.00
10	0.090	-3.003521319	1000.00	0.00	0.00	0.00	0.00
11	0.100	-3.003490141	1000.00	0.00	0.00	0.00	0.00
12	0.110	-3.003458963	1000.00	0.00	0.00	0.00	0.00
13	0.120	-3.003427785	1000.00	0.00	0.00	0.00	0.00
14	0.130	-3.003396607	1000.00	0.00	0.00	0.00	0.00
15	0.140	-3.003365429	1000.00	0.00	0.00	0.00	0.00
16	0.150	-3.003334251	1000.00	0.00	0.00	0.00	0.00
17	0.160	-3.003303073	1000.00	0.00	0.00	0.00	0.00
18	0.170	-3.003271895	1000.00	0.00	0.00	0.00	0.00
19	0.180	-3.003240717	1000.00	0.00	0.00	0.00	0.00
20	0.190	-3.003209539	1000.00	0.00	0.00	0.00	0.00
21	0.200	-3.003178361	1000.00	0.00	0.00	0.00	0.00
22	0.210	-3.003147183	1000.00	0.00	0.00	0.00	0.00
23	0.220	-3.003116005	1000.00	0.00	0.00	0.00	0.00
24	0.230	-3.003084827	1000.00	0.00	0.00	0.00	0.00
25	0.240	-3.003053649	1000.00	0.00	0.00	0.00	0.00
26	0.250	-3.003022471	1000.00	0.00	0.00	0.00	0.00
27	0.260	-3.002991293	1000.00	0.00	0.00	0.00	0.00
28	0.270	-3.002960115	1000.00	0.00	0.00	0.00	0.00
29	0.280	-3.002928937	1000.00	0.00	0.00	0.00	0.00
30	0.290	-3.002897759	1000.00	0.00	0.00	0.00	0.00
31	0.300	-3.002866581	1000.00	0.00	0.00	0.00	0.00
32	0.310	-3.002835403	1000.00	0.00	0.00	0.00	0.00
33	0.320	-3.002804225	1000.00	0.00	0.00	0.00	0.00
34	0.330	-3.002773047	1000.00	0.00	0.00	0.00	0.00
35	0.340	-3.002741869	1000.00	0.00	0.00	0.00	0.00
36	0.350	-3.002710691	1000.00	0.00	0.00	0.00	0.00
37	0.360	-3.002679513	1000.00	0.00	0.00	0.00	0.00
38	0.370	-3.002648335	1000.00	0.00	0.00	0.00	0.00
39	0.380	-3.002617157	1000.00	0.00	0.00	0.00	0.00
40	0.390	-3.002585979	1000.00	0.00	0.00	0.00	0.00
41	0.400	-3.002554801	1000.00	0.00	0.00	0.00	0.00
42	0.410	-3.002523623	1000.00	0.00	0.00	0.00	0.00
43	0.420	-3.002492445	1000.00	0.00	0.00	0.00	0.00
44	0.430	-3.002461267	1000.00	0.00	0.00	0.00	0.00
45	0.440	-3.002430089	1000.00	0.00	0.00	0.00	0.00
46	0.450	-3.002398911	1000.00	0.00	0.00	0.00	0.00
47	0.460	-3.002367733	1000.00	0.00	0.00	0.00	0.00
48	0.470	-3.002336555	1000.00	0.00	0.00	0.00	0.00
49	0.480	-3.002305377	1000.00	0.00	0.00	0.00	0.00
50	0.490	-3.002274199	1000.00	0.00	0.00	0.00	0.00
51	0.500	-3.002243021	1000.00	0.00	0.00	0.00	0.00
52	0.510	-3.002211843	1000.00	0.00	0.00	0.00	0.00
53	0.520	-3.002180665	1000.00	0.00	0.00	0.00	0.00
54	0.530	-3.002149487	1000.00	0.00	0.00	0.00	0.00
55	0.540	-3.002118309	1000.00	0.00	0.00	0.00	0.00
56	0.550	-3.002087131	1000.00	0.00	0.00	0.00	0.00
57	0.560	-3.002055953	1000.00	0.00	0.00	0.00	0.00
58	0.570	-3.002024775	1000.00	0.00	0.00	0.00	0.00
59	0.580	-3.001993597	1000.00	0.00	0.00	0.00	0.00
60	0.590	-3.001962419	1000.00	0.00	0.00	0.00	0.00
61	0.600	-3.001931241	1000.00	0.00	0.00	0.00	0.00
62	0.610	-3.001899963	1000.00	0.00	0.00	0.00	0.00
63	0.620	-3.001868785	1000.00	0.00	0.00	0.00	0.00
64	0.630	-3.001837607	1000.00	0.00	0.00	0.00	0.00
65	0.640	-3.001806429	1000.00	0.00	0.00	0.00	0.00
66	0.650	-3.001775251	1000.00	0.00	0.00	0.00	0.00
67	0.660	-3.001744073	1000.00	0.00	0.00	0.00	0.00
68	0.670	-3.001712895	1000.00	0.00	0.00	0.00	0.00
69	0.680	-3.001681717	1000.00	0.00	0.00	0.00	0.00
70	0.690	-3.001650539	1000.00	0.00	0.00	0.00	0.00
71	0.700	-3.001619361	1000.00	0.00	0.00	0.00	0.00
72	0.710	-3.001588183	1000.00	0.00	0.00	0.00	0.00
73	0.720	-3.001557005	1000.00	0.00	0.00	0.00	0.00
74	0.730	-3.001525827	1000.00	0.00	0.00	0.00	0.00
75	0.740	-3.001494649	1000.00	0.00	0.00	0.00	0.00
76	0.750	-3.001463471	1000.00	0.00	0.00	0.00	0.00
77	0.760	-3.001432293	1000.00	0.00	0.00	0.00	0.00
78	0.770	-3.001401115	1000.00	0.00	0.00	0.00	0.00
79	0.780	-3.001369937	1000.00	0.00	0.00	0.00	0.00
80	0.790	-3.001338759	1000.00	0.00	0.00	0.00	0.00
81	0.800	-3.001307581	1000.00	0.00	0.00	0.00	0.00
82	0.810	-3.001276403	1000.00	0.00	0.00	0.00	0.00
83	0.820	-3.001245225	1000.00	0.00	0.00	0.00	0.00
84	0.830	-3.001214047	1000.00	0.00	0.00	0.00	0.00
85	0.840	-3.001182869	1000.00	0.00	0.00	0.00	0.00
86	0.850	-3.001151691	1000.00	0.00	0.00	0.00	0.00
87	0.860	-3.001120513	1000.00	0.00	0.00	0.00	0.00
88	0.870	-3.001089335	1000.00	0.00	0.00	0.00	0.00
89	0.880	-3.001058157	1000.00	0.00	0.00	0.00	0.00
90	0.890	-3.001026979	1000.00	0.00	0.00	0.00	0.00
91	0.900	-3.001000000	1000.00	0.00	0.00	0.00	0.00
92	0.910	-3.000968822	1000.00	0.00	0.00	0.00	0.00
93	0.920	-3.000937644	1000.00	0.00	0.00	0.00	0.00
94	0.930	-3.000906466	1000.00	0.00	0.00	0.00	0.00
95	0.940	-3.000875288	1000.00	0.00	0.00	0.00	0.00
96	0.950	-3.000844110	1000.00	0.00	0.00	0.00	0.00
97	0.960	-3.000812932	1000.00	0.00	0.00	0.00	0.00
98	0.970	-3.000781754	1000.00	0.00	0.00	0.00	0.00
99	0.980	-3.000750576	1000.00	0.00	0.00	0.00	0.00
100	0.990	-3.000719398	1000.00	0.00	0.00	0.00	0.00
101	1.000	-3.000688220	1000.00	0.00	0.00	0.00	0.00
102	1.010	-3.000657042	1000.00	0.00	0.00	0.00	0.00
103	1.020	-3.000625864	1000.00	0.00	0.00	0.00	0.00
104	1.030	-3.000594686	1000.00	0.00	0.00	0.00	0.00
105	1.040	-3.000563508	1000.00	0.00	0.00	0.00	0.00
106	1.050	-3.000532330	1000.00	0.00	0.00	0.00	0.00
107	1.060	-3.000501152	1000.00	0.00	0.00	0.00	0.00
108	1.070	-3.000469974	1000.00	0.00	0.00	0.00	0.00
109	1.080	-3.000438796	1000.00	0.00	0.00	0.00	0.00
110	1.090	-3.000407618	1000.00	0.00	0.00	0.00	0.00
111	1.100	-3.000376440	1000.00	0.00	0.00	0.00	0.00
112	1.110	-3.000345262	1000.00	0.00	0.00	0.00	0.00
113	1.120	-3.000314084	1000.00	0.00	0.00	0.00	0.00
114	1.130	-3.000282906	1000.00	0.00	0.00	0.00	0.00
115	1.140	-3.000251728	1000.00	0.00	0.00	0.00	0.00
116	1.150	-3.000220550	1000.00	0.00	0.00	0.00	0.00
117	1.160	-3.000189372	1000.00	0.00	0.00	0.00	0.00

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ORIGINAL PAGE IS
OF POOR QUALITY

250	230.000	-0.001477646	870.10	-48.21	1.99	0.0	0.0
251	230.750	-0.001477646	880.00	-48.30	2.00	0.0	0.0
252	231.500	-0.001477646	890.00	-48.39	2.01	0.0	0.0
253	232.250	-0.001477646	900.00	-48.48	2.02	0.0	0.0
254	233.000	-0.001477646	910.00	-48.57	2.03	0.0	0.0
255	233.750	-0.001477646	920.00	-48.66	2.04	0.0	0.0
256	234.500	-0.001477646	930.00	-48.75	2.05	0.0	0.0
257	235.250	-0.001477646	940.00	-48.84	2.06	0.0	0.0
258	236.000	-0.001477646	950.00	-48.93	2.07	0.0	0.0
259	236.750	-0.001477646	960.00	-49.02	2.08	0.0	0.0
260	237.500	-0.001477646	970.00	-49.11	2.09	0.0	0.0
261	238.250	-0.001477646	980.00	-49.20	2.10	0.0	0.0
262	239.000	-0.001477646	990.00	-49.29	2.11	0.0	0.0
263	239.750	-0.001477646	1000.00	-49.38	2.12	0.0	0.0
264	240.500	-0.001477646	1010.00	-49.47	2.13	0.0	0.0
265	241.250	-0.001477646	1020.00	-49.56	2.14	0.0	0.0
266	242.000	-0.001477646	1030.00	-49.65	2.15	0.0	0.0
267	242.750	-0.001477646	1040.00	-49.74	2.16	0.0	0.0
268	243.500	-0.001477646	1050.00	-49.83	2.17	0.0	0.0
269	244.250	-0.001477646	1060.00	-49.92	2.18	0.0	0.0
270	245.000	-0.001477646	1070.00	-50.01	2.19	0.0	0.0
271	245.750	-0.001477646	1080.00	-50.10	2.20	0.0	0.0
272	246.500	-0.001477646	1090.00	-50.19	2.21	0.0	0.0
273	247.250	-0.001477646	1100.00	-50.28	2.22	0.0	0.0
274	248.000	-0.001477646	1110.00	-50.37	2.23	0.0	0.0
275	248.750	-0.001477646	1120.00	-50.46	2.24	0.0	0.0
276	249.500	-0.001477646	1130.00	-50.55	2.25	0.0	0.0
277	250.250	-0.001477646	1140.00	-50.64	2.26	0.0	0.0
278	251.000	-0.001477646	1150.00	-50.73	2.27	0.0	0.0
279	251.750	-0.001477646	1160.00	-50.82	2.28	0.0	0.0
280	252.500	-0.001477646	1170.00	-50.91	2.29	0.0	0.0
281	253.250	-0.001477646	1180.00	-51.00	2.30	0.0	0.0
282	254.000	-0.001477646	1190.00	-51.09	2.31	0.0	0.0
283	254.750	-0.001477646	1200.00	-51.18	2.32	0.0	0.0
284	255.500	-0.001477646	1210.00	-51.27	2.33	0.0	0.0
285	256.250	-0.001477646	1220.00	-51.36	2.34	0.0	0.0
286	257.000	-0.001477646	1230.00	-51.45	2.35	0.0	0.0
287	257.750	-0.001477646	1240.00	-51.54	2.36	0.0	0.0
288	258.500	-0.001477646	1250.00	-51.63	2.37	0.0	0.0
289	259.250	-0.001477646	1260.00	-51.72	2.38	0.0	0.0
290	260.000	-0.001477646	1270.00	-51.81	2.39	0.0	0.0
291	260.750	-0.001477646	1280.00	-51.90	2.40	0.0	0.0
292	261.500	-0.001477646	1290.00	-51.99	2.41	0.0	0.0
293	262.250	-0.001477646	1300.00	-52.08	2.42	0.0	0.0
294	263.000	-0.001477646	1310.00	-52.17	2.43	0.0	0.0
295	263.750	-0.001477646	1320.00	-52.26	2.44	0.0	0.0
296	264.500	-0.001477646	1330.00	-52.35	2.45	0.0	0.0
297	265.250	-0.001477646	1340.00	-52.44	2.46	0.0	0.0
298	266.000	-0.001477646	1350.00	-52.53	2.47	0.0	0.0
299	266.750	-0.001477646	1360.00	-52.62	2.48	0.0	0.0
300	267.500	-0.001477646	1370.00	-52.71	2.49	0.0	0.0

MODEL SOLUTIONS

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*****
*
* MODEL 12  P0 = 4.934814337822700 04  C00 = 4.40711221010133000-02
*          P1 = 3.0  C01 = 0.0
* PCINT  P2 = 4.5752012971043800 02  C02 = 1.39070963827348000 00
*          P3 = -1.0002707644448400 00  C03 = 0.0
*          P4 = 0.0  C04 = 1.04726379909510000 03
*
* FIT ERROR = 2.9482340264673200-05
*
*****
```

MODEL 12 FOUND TO BE BEST FIT

CALCULATED CONSTANT BIAS IN ANGLE OF ATTACK = -1.3788531000-07
ANGLE-OF-ATTACK BIAS < 5.00-07. BYPASSING ANALYSIS

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*****
*
* INITIALIZATION OF COEFFICIENT CONVERGENCE SCHEME BY 1/3 POWER MODEL
* FORM: P = 2.823900 040001/3
* C0 = 1.444880-01 + -4.367200 000A + 4.475830 010002 + -4.073130 020003 + 1.020040 030004
*
* WHERE: V = AIRSPEED (FT/SEC)
*          A = ANGLE OF ATTACK (RADIAN)
*
* FIT ERROR = 8.7314186320-05
*
*****
```

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*****
*
* COEFFICIENT CONVERGENCE ITERATION # 1
* NUMBER OF COEFFICIENTS PASSED = 3
* FIT ERROR = 7.35100301740540-05
*
*****
```

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*****
*
* COEFFICIENT CONVERGENCE ITERATION # 2
* NUMBER OF COEFFICIENTS PASSED = 3
* FIT ERROR = 7.34425132217070-05
*
*****
```

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*****
*****                                PAST                                PRESENT
*****                                *****                                *****
COEFFICIENT CONVERGENCE ITERATION # D 1.07881117120E-01 1.07881117120E-01
NUMBER OF COEFFICIENTS PASSED # D -3.03924155228E-01 -3.03924155228E-01
RT ENGRG = 7.33300000000E-05 2.37894790670E-01
*****

```

CLAQ=J.70577921627205530-02
CLA = J.046504438120331J 01
CLAX=-0.047987432350UJH1D 00
EAPX=0.200000000003J00000 01
CLQ = 3.0

CLAU-0.70577921627205533-02
CLA = J.0465044361203310 01
CLAU-0.04798763735603010 00
EXPK= J.200000000000000000 01
CLC= 0-0

LIFT COEFFICIENT FIT ERROR= 0.2656704779175000=02

[illegible]

***** BEGIN FREQUENCY CORRECTIONS TO ANGLE OF ATTACK *****

ITERATION 1

LIFT COEFFICIENTS BY LEAST-SQUARE DISTANCE

CLAO = -0.34147935610469070-02
CLA = 0.63832043140372410 01
CLAM = -0.51321504977005010 00
EAPK = 0.20617551464802930 01
CLQ = 0.0

FREQUENCY-DEPENDENT FIT ERROR FOR ANGLE OF ATTACK = 0.9209099248022D-07

PITCH-ANGLE GAIN = 1.00042646660 00
PITCH-ANGLE BIAS = 3.617408316140-05 RADIANS

MODEL SOLUTIONS

100

ORIGINAL PAGE IS
OF POOR QUALITY

```

* MODEL 12 P0 = 1.7C32228791009400 04 C00 = 3.37898822900030600-02
* P1 = 0.0 C01 = 0.0
* POINT P2 = 1.0188081000773200 03 C02 = 1.29913774809112000 00
* FAILURES P3 = -2.0158585790000000 00 C03 = 0.0
* U P4 = 2.0 C04 = 2.0074003376003200 03
* FIT ERROR= 7.6242337488300000-08
*
*****
* MODEL 12 FOUND TO BE BEST FIT
*
*****

```

ITERATION# 2

LIFT COEFFICIENTS BY LEAST-SQUARE DISTANCE

```

CLAO = -0.328870300012750-02
CLA = 0.003790030223007300 01
CLAR = -0.0000077421235000 00
EMPE = 0.2099877200900000 01
CLO = 0.0

```

FREQUENCY-DEPENDENT FIT ERROR FOR ANGLE OF ATTACK = 0.003120816741320-07

```

PITCH-ANGLE GAIN = 1.000032670700 00
PITCH-ANGLE DIAS = -1.010001789750-07 RADIAN

```

MODEL SOLUTIONS

```

*****
* MODEL 12 P0 = 2.0087571500745200 04 C00 = 3.37102002701516300-02
* P1 = 0.0 C01 = 0.0
* POINT P2 = 1.018758720000373100 03 C02 = 1.29825017305102100 00
* FAILURES P3 = -2.03251017100141700 00 C03 = 0.0
* U P4 = 0.0 C04 = 2.00010000077397000 03
* FIT ERROR= 0.00002217400007000-08
*
*****
* MODEL 12 FOUND TO BE BEST FIT
*
*****

```

ITERATION# 3

LIFT COEFFICIENTS BY LEAST-SQUARE DISTANCE

```

CLAO = -0.328870009722153010-02
CLA = 0.0037900302230077900 01
CLAR = -0.0000077421235000 00
EMPE = 0.2099877200900000 01
CLO = 0.0

```

FREQUENCY-DEPENDENT FIT ERROR FOR ANGLE OF ATTACK = 0.00319728030000-08

```

PITCH-ANGLE GAIN = 1.000030258000 00
PITCH-ANGLE DIAS = -1.0000039010300-07 RADIAN

```

MODEL SOLUTIONS

```

*****
* MODEL 12 P0 = 2.00815607000150000 04 C00 = 3.3500010220100000-02
* P1 = 0.0 C01 = 0.0
* POINT P2 = 1.01802303000000000 03 C02 = 1.29002115001503000 00
* FAILURES P3 = -2.0300074007000000 00 C03 = 0.0
* U P4 = 0.0 C04 = 2.0100100000770000 03
* FIT ERROR= 0.00000339001300000-08
*
*****
* MODEL 12 FOUND TO BE BEST FIT
*
*****

```

CLAU # -0032915861184529310-02
CLA # 0003802093758433810 01
CLAR # -00042408762355713760 00
EAPR # 0000086358702090390 01
CLD # 000

***** RAD FREQUENCY CORRECTIONS TO ANGLE OF ATTACK *****

[illegible]

MODIFIED DATA (PER PROGRAM LOOPS)

	CATA POINT	TIME (SECS)	WEIGHT (LBP)	PITCH ANGLE (VAL/ANS)	PITCH RATE (RAD/ANG/SEC)	AIRSPD (FT/SEC)
1	0+0.0	3894.9557	0+1627443	0+00L77403	146.7350	146.7350
4	0+0.0	3894.9593	0+1628125	0+00R6903	146.7850	146.7850
5	0+0.0	3894.9585	0+1628021	0+00J0750	146.8322	146.8322
6	0+0.0	3894.9576	0+1628211	0+00L1740	146.8774	146.8774
7	0+0.0	3894.9565	0+1630255	0+00J7304	146.9251	146.9251
8	0+0.0	3894.9557	0+1631744	0+00J7542	147.0178	147.0178
9	0+0.0	3894.9549	0+1632609	0+00J4500	147.0705	147.0705
10	0+0.0	3894.9539	0+1633116	0+00J1112	147.1025	147.1025
11	0+0.0	3894.9532	0+1633543	0+00R0853	147.2505	147.2505
12	0+0.0	3894.9524	0+1634285	0+00R6777	147.3862	147.3862
13	0+0.0	3894.9516	0+1641433	0+00R9187	147.5468	147.5468
14	0+0.0	3894.9509	0+1642026	0+00J7348	147.7505	147.7505
15	0+0.0	3894.9501	0+1642626	0+00J1280	147.9311	147.9311
16	0+0.0	3894.9493	0+1643461	0+00L4819	148.1119	148.1119
17	0+0.0	3894.9485	0+1649252	0+00J1322	148.2880	148.2880
18	0+0.0	3894.9477	0+1650774	0+00J1256	148.4626	148.4626
19	0+0.0	3894.9469	0+1651604	0+00J1328	148.6311	148.6311
20	0+0.0	3894.9461	0+1651954	0+00J1308	148.7369	148.7369
21	0+0.0	3894.9453	0+1651926	0+00J1306	148.7673	148.7673
22	0+0.0	3894.9445	0+1651926	0+00J1306	148.7673	148.7673
23	0+0.0	3894.9437	0+1651926	0+00J1306	148.7673	148.7673
24	0+0.0	3894.9429	0+1651926	0+00J1306	148.7673	148.7673
25	0+0.0	3894.9421	0+1651926	0+00J1306	148.7673	148.7673
26	0+0.0	3894.9413	0+1651926	0+00J1306	148.7673	148.7673
27	0+0.0	3894.9405	0+1651926	0+00J1306	148.7673	148.7673
28	0+0.0	3894.9397	0+1651926	0+00J1306	148.7673	148.7673
29	0+0.0	3894.9389	0+1651926	0+00J1306	148.7673	148.7673
30	0+0.0	3894.9381	0+1651926	0+00J1306	148.7673	148.7673
31	0+0.0	3894.9373	0+1651926	0+00J1306	148.7673	148.7673
32	0+0.0	3894.9365	0+1651926	0+00J1306	148.7673	148.7673
33	0+0.0	3894.9357	0+1651926	0+00J1306	148.7673	148.7673
34	0+0.0	3894.9349	0+1651926	0+00J1306	148.7673	148.7673
35	0+0.0	3894.9341	0+1651926	0+00J1306	148.7673	148.7673
36	0+0.0	3894.9333	0+1651926	0+00J1306	148.7673	148.7673
37	0+0.0	3894.9325	0+1651926	0+00J1306	148.7673	148.7673
38	0+0.0	3894.9317	0+1651926	0+00J1306	148.7673	148.7673
39	0+0.0	3894.9309	0+1651926	0+00J1306	148.7673	148.7673
40	0+0.0	3894.9301	0+1651926	0+00J1306	148.7673	148.7673
41	0+0.0	3894.9293	0+1651926	0+00J1306	148.7673	148.7673
42	0+0.0	3894.9285	0+1651926	0+00J1306	148.7673	148.7673
43	0+0.0	3894.9277	0+1651926	0+00J1306	148.7673	148.7673
44	0+0.0	3894.9269	0+1651926	0+00J1306	148.7673	148.7673
45	0+0.0	3894.9261	0+1651926	0+00J1306	148.7673	148.7673
46	0+0.0	3894.9253	0+1651926	0+00J1306	148.7673	148.7673
47	0+0.0	3894.9245	0+1651926	0+00J1306	148.7673	148.7673
48	0+0.0	3894.9237	0+1651926	0+00J1306	148.7673	148.7673
49	0+0.0	3894.9229	0+1651926	0+00J1306	148.7673	148.7673
50	0+0.0	3894.9221	0+1651926	0+00J1306	148.7673	148.7673
51	0+0.0	3894.9213	0+1651926	0+00J1306	148.7673	148.7673
52	0+0.0	3894.9205	0+1651926	0+00J1306	148.7673	148.7673
53	0+0.0	3894.9197	0+1651926	0+00J1306	148.7673	148.7673
54	0+0.0	3894.9189	0+1651926	0+00J1306	148.7673	148.7673
55	0+0.0	3894.9181	0+1651926	0+00J1306	148.7673	148.7673
56	0+0.0	3894.9173	0+1651926	0+00J1306	148.7673	148.7673
57	0+0.0	3894.9165	0+1651926	0+00J1306	148.7673	148.7673
58	0+0.0	3894.9157	0+1651926	0+00J1306	148.7673	148.7673
59	0+0.0	3894.9149	0+1651926	0+00J1306	148.7673	148.7673
60	0+0.0	3894.9141	0+1651926	0+00J1306	148.7673	148.7673
61	0+0.0	3894.9133	0+1651926	0+00J1306	148.7673	148.7673
62	0+0.0	3894.9125	0+1651926	0+00J1306	148.7673	148.7673
63	0+0.0	3894.9117	0+1651926	0+00J1306	148.7673	148.7673
64	0+0.0	3894.9109	0+1651926	0+00J1306	148.7673	148.7673
65	0+0.0	3894.9101	0+1651926	0+00J1306	148.7673	148.7673
66	0+0.0	3894.9093	0+1651926	0+00J1306	148.7673	148.7673
67	0+0.0	3894.9085	0+1651926	0+00J1306	148.7673	148.7673
68	0+0.0	3894.9077	0+1651926	0+00J1306	148.7673	148.7673
69	0+0.0	3894.9069	0+1651926	0+00J1306	148.7673	148.7673
70	0+0.0	3894.9061	0+1651926	0+00J1306	148.7673	148.7673
71	0+0.0	3894.9053	0+1651926	0+00J1306	148.7673	148.7673
72	0+0.0	3894.9045	0+1651926	0+00J1306	148.7673	148.7673
73	0+0.0	3894.9037	0+1651926	0+00J1306	148.7673	148.7673
74	0+0.0	3894.9029	0+1651926	0+00J1306	148.7673	148.7673
75	0+0.0	3894.9021	0+1651926	0+00J1306	148.7673	148.7673

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76	04340	3990.7572	043090071	040000000	158.1461
77	04440	3990.7536	043100372	040007019	158.0010
78	04540	3990.7499	043117040	040070046	158.0262
79	04640	3990.7467	043120032	040080197	157.9702
80	04740	3990.7418	043123194	040085001	157.9213
81	04840	3990.7380	043126617	040087810	157.8829
82	04940	3990.7341	043131775	040094000	157.8400
83	74400	3990.7303	043135999	040110040	157.8002
84	74500	3990.7266	043140126	040121291	157.7608
85	74600	3990.7228	043144333	040130033	157.7218
86	74700	3990.7187	043148511	040137001	157.6833
87	74800	3990.7149	043152702	040144002	157.6453
88	74900	3990.7110	043156866	040151002	157.6078
89	75000	3990.7072	043161027	040158002	157.5708
90	75100	3990.7033	043165186	040165002	157.5343
91	75200	3990.6995	043169321	040172002	157.4983
92	75300	3990.6956	043173457	040179002	157.4628
93	75400	3990.6918	043177583	040186002	157.4278
94	75500	3990.6879	043181709	040193002	157.3933
95	75600	3990.6840	043185835	040200002	157.3593
96	75700	3990.6801	043190000	040207002	157.3258
97	75800	3990.6762	043194126	040214002	157.2928
98	75900	3990.6723	043198252	040221002	157.2598
99	76000	3990.6684	043202378	040228002	157.2273
100	76100	3990.6645	043206504	040235002	157.1953
101	76200	3990.6606	043210630	040242002	157.1638
102	76300	3990.6567	043214756	040249002	157.1323
103	76400	3990.6528	043218882	040256002	157.1013
104	76500	3990.6489	043223008	040263002	157.0708
105	76600	3990.6450	043227134	040270002	157.0408
106	76700	3990.6411	043231260	040277002	157.0113
107	76800	3990.6372	043235386	040284002	156.9823
108	76900	3990.6333	043239512	040291002	156.9538
109	77000	3990.6294	043243638	040298002	156.9258
110	77100	3990.6255	043247764	040305002	156.8983
111	77200	3990.6216	043251890	040312002	156.8713
112	77300	3990.6177	043256016	040319002	156.8448
113	77400	3990.6138	043260142	040326002	156.8188
114	77500	3990.6099	043264268	040333002	156.7933
115	77600	3990.6060	043268394	040340002	156.7683
116	77700	3990.6021	043272520	040347002	156.7438
117	77800	3990.5982	043276646	040354002	156.7198
118	77900	3990.5943	043280772	040361002	156.6963
119	78000	3990.5904	043284898	040368002	156.6733
120	78100	3990.5865	043289024	040375002	156.6508
121	78200	3990.5826	043293150	040382002	156.6288
122	78300	3990.5787	043297276	040389002	156.6073
123	78400	3990.5748	043301402	040396002	156.5863
124	78500	3990.5709	043305528	040403002	156.5663
125	78600	3990.5670	043309654	040410002	156.5473
126	78700	3990.5631	043313780	040417002	156.5293
127	78800	3990.5592	043317906	040424002	156.5123
128	78900	3990.5553	043322032	040431002	156.4963
129	79000	3990.5514	043326158	040438002	156.4813
130	79100	3990.5475	043330284	040445002	156.4673
131	79200	3990.5436	043334410	040452002	156.4543
132	79300	3990.5397	043338536	040459002	156.4423
133	79400	3990.5358	043342662	040466002	156.4313
134	79500	3990.5319	043346788	040473002	156.4213
135	79600	3990.5280	043350914	040480002	156.4123
136	79700	3990.5241	043355040	040487002	156.4043
137	79800	3990.5202	043359166	040494002	156.3973
138	79900	3990.5163	043363292	040501002	156.3913
139	80000	3990.5124	043367418	040508002	156.3863
140	80100	3990.5085	043371544	040515002	156.3823
141	80200	3990.5046	043375670	040522002	156.3793
142	80300	3990.5007	043379796	040529002	156.3773
143	80400	3990.4968	043383922	040536002	156.3763
144	80500	3990.4929	043388048	040543002	156.3763
145	80600	3990.4890	043392174	040550002	156.3773
146	80700	3990.4851	043396300	040557002	156.3793
147	80800	3990.4812	043400426	040564002	156.3823
148	80900	3990.4773	043404552	040571002	156.3863
149	81000	3990.4734	043408678	040578002	156.3913
150	81100	3990.4695	043412804	040585002	156.3973
151	81200	3990.4656	043416930	040592002	156.4043
152	81300	3990.4617	043421056	040599002	156.4123
153	81400	3990.4578	043425182	040606002	156.4213
154	81500	3990.4539	043429308	040613002	156.4313
155	81600	3990.4500	043433434	040620002	156.4423
156	81700	3990.4461	043437560	040627002	156.4543
157	81800	3990.4422	043441686	040634002	156.4673
158	81900	3990.4383	043445812	040641002	156.4813
159	82000	3990.4344	043449938	040648002	156.4963
160	82100	3990.4305	043454064	040655002	156.5123
161	82200	3990.4266	043458190	040662002	156.5293
162	82300	3990.4227	043462316	040669002	156.5473
163	82400	3990.4188	043466442	040676002	156.5663
164	82500	3990.4149	043470568	040683002	156.5863
165	82600	3990.4110	043474694	040690002	156.6073
166	82700	3990.4071	043478820	040697002	156.6293
167	82800	3990.4032	043482946	040704002	156.6523
168	82900	3990.3993	043487072	040711002	156.6773
169	83000	3990.3954	043491198	040718002	156.7033
170	83100	3990.3915	043495324	040725002	156.7303
171	83200	3990.3876	043499450	040732002	156.7583
172	83300	3990.3837	043503576	040739002	156.7873
173	83400	3990.3798	043507702	040746002	156.8173
174	83500	3990.3759	043511828	040753002	156.8483
175	83600	3990.3720	043515954	040760002	156.8803
176	83700	3990.3681	043520080	040767002	156.9133
177	83800	3990.3642	043524206	040774002	156.9473
178	83900	3990.3603	043528332	040781002	156.9823
179	84000	3990.3564	043532458	040788002	157.0183
180	84100	3990.3525	043536584	040795002	157.0553
181	84200	3990.3486	043540710	040802002	157.0933
182	84300	3990.3447	043544836	040809002	157.1323
183	84400	3990.3408	043548962	040816002	157.1723
184	84500	3990.3369	043553088	040823002	157.2133
185	84600	3990.3330	043557214	040830002	157.2553
186	84700	3990.3291	043561340	040837002	157.2983
187	84800	3990.3252	043565466	040844002	157.3423
188	84900	3990.3213	043569592	040851002	157.3873
189	85000	3990.3174	043573718	040858002	157.4333
190	85100	3990.3135	043577844	040865002	157.4803
191	85200	3990.3096	043581970	040872002	157.5283
192	85300	3990.3057	043586096	040879002	157.5773
193	85400	3990.3018	043590222	040886002	157.6273
194	85500	3990.2979	043594348	040893002	157.6783
195	85600	3990.2940	043598474	040900002	157.7303
196	85700	3990.2901	043602600	040907002	157.7833
197	85800	3990.2862	043606726	040914002	157.8373
198	85900	3990.2823	043610852	040921002	157.8923
199	86000	3990.2784	043614978	040928002	157.9483
200	86100	3990.2745	043619104	040935002	158.0053
201	86200	3990.2706	043623230	040942002	158.0633
202	86300	3990.2667	043627356	040949002	158.1223
203	86400	3990.2628	043631482	040956002	158.1823
204	86500	3990.2589	043635608	040963002	158.2433
205	86600	3990.2550	043639734	040970002	158.3053
206	86700	3990.2511	043643860	040977002	158.3683
207	86800	3990.2472	043647986	040984002	158.4323
208	86900	3990.2433	043652112	040991002	158.4973
209	87000	3990.2394	043656238	041000000	158.5633
210	87100	3990.2355	043660364	041007000	158.6303
211	87200	3990.2316	043664490	041014000	158.6983
212	87300	3990.2277	043668616	041021000	158.7673
213	87400	3990.2238	043672742	041028000	158.8373
214	87500	3990.2199	043676868	041035000	158.9083
215	87600	3990.2160	043680994	041042000	158.9803
216	87700	3990.2121	043685120	041049000	159.0533
217	87800	3990.2082	043689246	041056000	159.1273
218	87900	3990.2043	043693372	041063000	159.2023
219	88000	3990.2004	043697498	041070000	159.2783
220	88100	3990.1965	043701624	041077000	159.3553
221	88200	3990.1926	043705750	041084000	159.4333
222	88300	3990.1887	043709876	041091000	159.5123
223	88400	3990.1848	043714002	041098000	159.5923
224	88500	3990.1809	043718128	041105000	159.6733
225	88600	3990.1770	043722254	041112000	159.7553
226	88700	3990.1731	043726380	041119000	159.8383
227	88800	3990.1692	043730506	041126000	159.9223
228	88900	3990.1653	043734632	041133000	160.0073
229	89000	3990.1614	043738758	041140000	160.0933
230	89100	3990.1575	043742884	041147000	160.1803
231	89200	3990.1536	043747010	041154000	160.2683
232	89300	3990.1497	043751136	041161000	160.3573
233	89400	3990.1458	043755262	041168000	160.4473
234	89500	3990.1419	043759388	041175000	160.5383
235	89600	3990.1380	043763514	041182000	160.6303
236	89700				

208	19.800	3000.2310	-0.1300180	-0.0145773	219.3046
209	19.800	3000.2310	-0.1316331	-0.0138169	218.2788
210	19.800	3000.2223	-0.1327802	-0.0130670	221.2462
211	19.800	3000.2188	-0.1340400	-0.0123061	222.2156
212	19.800	3000.2118	-0.1352882	-0.0115861	223.1827
213	19.800	3000.2063	-0.1365612	-0.0108136	224.1503
214	19.800	3000.2009	-0.1378481	-0.0100761	225.1152
215	19.800	3000.1960	-0.1391374	-0.0093442	226.0781
216	19.800	3000.1902	-0.1404279	-0.0086179	227.0400
217	19.800	3000.1819	-0.1417120	-0.0078973	227.9973
218	19.800	3000.1875	-0.1430002	-0.0071825	228.9531
219	19.800	3000.1821	-0.1442903	-0.0064736	229.9081
220	19.800	3000.1788	-0.1455817	-0.0057707	230.8641
221	19.800	3000.1744	-0.1468742	-0.0050740	231.8209
222	19.800	3000.1700	-0.1481678	-0.0043836	232.7762
223	19.800	3000.1656	-0.1494626	-0.0036993	233.7301
224	19.800	3000.1612	-0.1507584	-0.0030214	234.6826
225	19.800	3000.1568	-0.1520552	-0.0023499	235.6340
226	19.800	3000.1524	-0.1533530	-0.0016845	236.5845
227	19.800	3000.1481	-0.1546517	-0.0010254	237.5342
228	19.800	3000.1437	-0.1559513	-0.0003726	238.4830
229	19.800	3000.1393	-0.1572518	0.0002800	239.4311
230	19.800	3000.1350	-0.1585532	0.0009364	240.3787
231	19.800	3000.1306	-0.1598555	0.0015976	241.3259
232	19.800	3000.1263	-0.1611586	0.0022636	242.2727
233	19.800	3000.1219	-0.1624625	0.0029344	243.2192
234	19.800	3000.1175	-0.1637672	0.0036099	244.1654
235	19.800	3000.1132	-0.1650727	0.0042901	245.1113
236	19.800	3000.1088	-0.1663790	0.0049750	246.0569
237	19.800	3000.1044	-0.1676860	0.0056646	247.0022
238	19.800	3000.1000	-0.1689937	0.0063589	247.9472
239	19.800	3000.0956	-0.1703021	0.0070580	248.8919
240	19.800	3000.0912	-0.1716112	0.0077619	249.8363
241	19.800	3000.0868	-0.1729210	0.0084706	250.7804
242	19.800	3000.0824	-0.1742314	0.0091841	251.7242
243	19.800	3000.0780	-0.1755424	0.0099024	252.6677
244	19.800	3000.0736	-0.1768540	0.0106255	253.6109
245	19.800	3000.0692	-0.1781661	0.0113534	254.5538
246	19.800	3000.0648	-0.1794787	0.0120861	255.4964
247	19.800	3000.0604	-0.1807918	0.0128236	256.4387
248	19.800	3000.0560	-0.1821053	0.0135659	257.3807
249	19.800	3000.0516	-0.1834192	0.0143130	258.3224
250	19.800	3000.0472	-0.1847335	0.0150649	259.2638
251	19.800	3000.0428	-0.1860482	0.0158216	260.2049
252	19.800	3000.0384	-0.1873632	0.0165831	261.1457
253	19.800	3000.0340	-0.1886785	0.0173494	262.0862
254	19.800	3000.0296	-0.1899941	0.0181205	263.0264
255	19.800	3000.0252	-0.1913099	0.0188964	263.9663
256	19.800	3000.0208	-0.1926259	0.0196771	264.9059
257	19.800	3000.0164	-0.1939421	0.0204626	265.8452
258	19.800	3000.0120	-0.1952584	0.0212529	266.7842
259	19.800	3000.0076	-0.1965748	0.0220480	267.7229
260	19.800	3000.0032	-0.1978913	0.0228479	268.6613
261	19.800	3000.0000	-0.1992078	0.0236526	269.5994
262	19.800	3000.0000	-0.2005243	0.0244621	270.5372
263	19.800	3000.0000	-0.2018407	0.0252764	271.4747
264	19.800	3000.0000	-0.2031570	0.0260946	272.4119
265	19.800	3000.0000	-0.2044732	0.0269166	273.3488
266	19.800	3000.0000	-0.2057893	0.0277424	274.2854
267	19.800	3000.0000	-0.2071053	0.0285720	275.2217
268	19.800	3000.0000	-0.2084212	0.0294054	276.1577
269	19.800	3000.0000	-0.2097370	0.0302426	277.0934
270	19.800	3000.0000	-0.2110527	0.0310836	278.0288
271	19.800	3000.0000	-0.2123683	0.0319284	278.9639
272	19.800	3000.0000	-0.2136838	0.0327770	279.8987
273	19.800	3000.0000	-0.2150000	0.0336294	280.8332
274	19.800	3000.0000	-0.2163161	0.0344856	281.7674
275	19.800	3000.0000	-0.2176321	0.0353456	282.7013
276	19.800	3000.0000	-0.2189480	0.0362094	283.6349
277	19.800	3000.0000	-0.2202638	0.0370770	284.5682
278	19.800	3000.0000	-0.2215795	0.0379484	285.5012
279	19.800	3000.0000	-0.2228951	0.0388236	286.4339
280	19.800	3000.0000	-0.2242106	0.0397026	287.3663
281	19.800	3000.0000	-0.2255260	0.0405854	288.2984
282	19.800	3000.0000	-0.2268413	0.0414720	289.2302
283	19.800	3000.0000	-0.2281565	0.0423624	290.1617
284	19.800	3000.0000	-0.2294716	0.0432566	291.0929
285	19.800	3000.0000	-0.2307866	0.0441546	292.0238
286	19.800	3000.0000	-0.2321015	0.0450564	292.9544
287	19.800	3000.0000	-0.2334163	0.0459620	293.8847
288	19.800	3000.0000	-0.2347310	0.0468714	294.8147
289	19.800	3000.0000	-0.2360456	0.0477846	295.7444
290	19.800	3000.0000	-0.2373601	0.0487016	296.6738
291	19.800	3000.0000	-0.2386745	0.0496224	297.6029
292	19.800	3000.0000	-0.2399888	0.0505470	298.5317
293	19.800	3000.0000	-0.2413030	0.0514754	299.4602
294	19.800	3000.0000	-0.2426171	0.0524076	300.3884
295	19.800	3000.0000	-0.2439311	0.0533436	301.3163
296	19.800	3000.0000	-0.2452451	0.0542834	302.2439
297	19.800	3000.0000	-0.2465590	0.0552270	303.1712
298	19.800	3000.0000	-0.2478728	0.0561744	304.0982
299	19.800	3000.0000	-0.2491865	0.0571256	305.0249
300	19.800	3000.0000	-0.2505001	0.0580806	305.9513

DATA POINT	TIME (SECS)	DENSITY (SLUG/FT**3)	ANGLE OF ATTACK (RADIAN)	TEMPERATURE (DEG-F)	ACCELERATION (FT/SEC**2)
1	0.010	0.0023078	0.1629030	520.00	0.00000
2	0.010	0.0023078	0.1625095	520.00	0.00000
3	0.010	0.0023078	0.1621167	520.00	0.00000
4	0.010	0.0023078	0.1617236	520.00	0.00000
5	0.010	0.0023078	0.1613302	520.00	0.00000
6	0.010	0.0023078	0.1609365	520.00	0.00000
7	0.010	0.0023078	0.1605425	520.00	0.00000
8	0.010	0.0023078	0.1601482	520.00	0.00000
9	0.010	0.0023078	0.1597536	520.00	0.00000
10	0.010	0.0023078	0.1593587	520.00	0.00000
11	0.010	0.0023078	0.1589635	520.00	0.00000
12	0.010	0.0023078	0.1585680	520.00	0.00000
13	0.010	0.0023078	0.1581722	520.00	0.00000
14	0.010	0.0023078	0.1577761	520.00	0.00000
15	0.010	0.0023078	0.1573797	520.00	0.00000
16	0.010	0.0023078	0.1569830	520.00	0.00000
17	0.010	0.0023078	0.1565860	520.00	0.00000
18	0.010	0.0023078	0.1561887	520.00	0.00000
19	0.010	0.0023078	0.1557911	520.00	0.00000
20	0.010	0.0023078	0.1553932	520.00	0.00000
21	0.010	0.0023078	0.1549950	520.00	0.00000
22	0.010	0.0023078	0.1545965	520.00	0.00000
23	0.010	0.0023078	0.1541977	520.00	0.00000
24	0.010	0.0023078	0.1537986	520.00	0.00000
25	0.010	0.0023078	0.1533992	520.00	0.00000
26	0.010	0.0023078	0.1529995	520.00	0.00000
27	0.010	0.0023078	0.1525995	520.00	0.00000
28	0.010	0.0023078	0.1521992	520.00	0.00000
29	0.010	0.0023078	0.1517986	520.00	0.00000
30	0.010	0.0023078	0.1513977	520.00	0.00000
31	0.010	0.0023078	0.1509965	520.00	0.00000
32	0.010	0.0023078	0.1505950	520.00	0.00000
33	0.010	0.0023078	0.1501932	520.00	0.00000
34	0.010	0.0023078	0.1497911	520.00	0.00000

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167	180.280	0.00228031	0.00270236	520.00	7.000235
168	180.280	0.00228042	0.00270285	520.00	7.000237
169	180.280	0.00228053	0.00270334	520.00	7.000239
170	180.280	0.00228064	0.00270383	520.00	7.000241
171	180.280	0.00228075	0.00270432	520.00	7.000243
172	180.280	0.00228086	0.00270481	520.00	7.000245
173	180.280	0.00228097	0.00270530	520.00	7.000247
174	180.280	0.00228108	0.00270579	520.00	7.000249
175	180.280	0.00228119	0.00270628	520.00	7.000251
176	180.280	0.00228130	0.00270677	520.00	7.000253
177	180.280	0.00228141	0.00270726	520.00	7.000255
178	180.280	0.00228152	0.00270775	520.00	7.000257
179	180.280	0.00228163	0.00270824	520.00	7.000259
180	180.280	0.00228174	0.00270873	520.00	7.000261
181	180.280	0.00228185	0.00270922	520.00	7.000263
182	180.280	0.00228196	0.00270971	520.00	7.000265
183	180.280	0.00228207	0.00271020	520.00	7.000267
184	180.280	0.00228218	0.00271069	520.00	7.000269
185	180.280	0.00228229	0.00271118	520.00	7.000271
186	180.280	0.00228240	0.00271167	520.00	7.000273
187	180.280	0.00228251	0.00271216	520.00	7.000275
188	180.280	0.00228262	0.00271265	520.00	7.000277
189	180.280	0.00228273	0.00271314	520.00	7.000279
190	180.280	0.00228284	0.00271363	520.00	7.000281
191	180.280	0.00228295	0.00271412	520.00	7.000283
192	180.280	0.00228306	0.00271461	520.00	7.000285
193	180.280	0.00228317	0.00271510	520.00	7.000287
194	180.280	0.00228328	0.00271559	520.00	7.000289
195	180.280	0.00228339	0.00271608	520.00	7.000291
196	180.280	0.00228350	0.00271657	520.00	7.000293
197	180.280	0.00228361	0.00271706	520.00	7.000295
198	180.280	0.00228372	0.00271755	520.00	7.000297
199	180.280	0.00228383	0.00271804	520.00	7.000299
200	180.280	0.00228394	0.00271853	520.00	7.000301
201	180.280	0.00228405	0.00271902	520.00	7.000303
202	180.280	0.00228416	0.00271951	520.00	7.000305
203	180.280	0.00228427	0.00272000	520.00	7.000307
204	180.280	0.00228438	0.00272049	520.00	7.000309
205	180.280	0.00228449	0.00272098	520.00	7.000311
206	180.280	0.00228460	0.00272147	520.00	7.000313
207	180.280	0.00228471	0.00272196	520.00	7.000315
208	180.280	0.00228482	0.00272245	520.00	7.000317
209	180.280	0.00228493	0.00272294	520.00	7.000319
210	180.280	0.00228504	0.00272343	520.00	7.000321
211	180.280	0.00228515	0.00272392	520.00	7.000323
212	180.280	0.00228526	0.00272441	520.00	7.000325
213	180.280	0.00228537	0.00272490	520.00	7.000327
214	180.280	0.00228548	0.00272539	520.00	7.000329
215	180.280	0.00228559	0.00272588	520.00	7.000331
216	180.280	0.00228570	0.00272637	520.00	7.000333
217	180.280	0.00228581	0.00272686	520.00	7.000335
218	180.280	0.00228592	0.00272735	520.00	7.000337
219	180.280	0.00228603	0.00272784	520.00	7.000339
220	180.280	0.00228614	0.00272833	520.00	7.000341
221	180.280	0.00228625	0.00272882	520.00	7.000343
222	180.280	0.00228636	0.00272931	520.00	7.000345
223	180.280	0.00228647	0.00272980	520.00	7.000347
224	180.280	0.00228658	0.00273029	520.00	7.000349
225	180.280	0.00228669	0.00273078	520.00	7.000351
226	180.280	0.00228680	0.00273127	520.00	7.000353
227	180.280	0.00228691	0.00273176	520.00	7.000355
228	180.280	0.00228702	0.00273225	520.00	7.000357
229	180.280	0.00228713	0.00273274	520.00	7.000359
230	180.280	0.00228724	0.00273323	520.00	7.000361
231	180.280	0.00228735	0.00273372	520.00	7.000363
232	180.280	0.00228746	0.00273421	520.00	7.000365
233	180.280	0.00228757	0.00273470	520.00	7.000367
234	180.280	0.00228768	0.00273519	520.00	7.000369
235	180.280	0.00228779	0.00273568	520.00	7.000371
236	180.280	0.00228790	0.00273617	520.00	7.000373
237	180.280	0.00228801	0.00273666	520.00	7.000375
238	180.280	0.00228812	0.00273715	520.00	7.000377
239	180.280	0.00228823	0.00273764	520.00	7.000379
240	180.280	0.00228834	0.00273813	520.00	7.000381
241	180.280	0.00228845	0.00273862	520.00	7.000383
242	180.280	0.00228856	0.00273911	520.00	7.000385
243	180.280	0.00228867	0.00273960	520.00	7.000387
244	180.280	0.00228878	0.00274009	520.00	7.000389
245	180.280	0.00228889	0.00274058	520.00	7.000391
246	180.280	0.00228900	0.00274107	520.00	7.000393
247	180.280	0.00228911	0.00274156	520.00	7.000395
248	180.280	0.00228922	0.00274205	520.00	7.000397
249	180.280	0.00228933	0.00274254	520.00	7.000399
250	180.280	0.00228944	0.00274303	520.00	7.000401
251	180.280	0.00228955	0.00274352	520.00	7.000403
252	180.280	0.00228966	0.00274401	520.00	7.000405
253	180.280	0.00228977	0.00274450	520.00	7.000407
254	180.280	0.00228988	0.00274499	520.00	7.000409
255	180.280	0.00228999	0.00274548	520.00	7.000411
256	180.280	0.00229010	0.00274597	520.00	7.000413
257	180.280	0.00229021	0.00274646	520.00	7.000415
258	180.280	0.00229032	0.00274695	520.00	7.000417
259	180.280	0.00229043	0.00274744	520.00	7.000419
260	180.280	0.00229054	0.00274793	520.00	7.000421
261	180.280	0.00229065	0.00274842	520.00	7.000423
262	180.280	0.00229076	0.00274891	520.00	7.000425
263	180.280	0.00229087	0.00274940	520.00	7.000427
264	180.280	0.00229098	0.00274989	520.00	7.000429
265	180.280	0.00229109	0.00275038	520.00	7.000431
266	180.280	0.00229120	0.00275087	520.00	7.000433
267	180.280	0.00229131	0.00275136	520.00	7.000435
268	180.280	0.00229142	0.00275185	520.00	7.000437
269	180.280	0.00229153	0.00275234	520.00	7.000439
270	180.280	0.00229164	0.00275283	520.00	7.000441
271	180.280	0.00229175	0.00275332	520.00	7.000443
272	180.280	0.00229186	0.00275381	520.00	7.000445
273	180.280	0.00229197	0.00275430	520.00	7.000447
274	180.280	0.00229208	0.00275479	520.00	7.000449
275	180.280	0.00229219	0.00275528	520.00	7.000451
276	180.280	0.00229230	0.00275577	520.00	7.000453
277	180.280	0.00229241	0.00275626	520.00	7.000455
278	180.280	0.00229252	0.00275675	520.00	7.000457
279	180.280	0.00229263	0.00275724	520.00	7.000459
280	180.280	0.00229274	0.00275773	520.00	7.000461
281	180.280	0.00229285	0.00275822	520.00	7.000463
282	180.280	0.00229296	0.00275871	520.00	7.000465
283	180.280	0.00229307	0.00275920	520.00	7.000467
284	180.280	0.00229318	0.00275969	520.00	7.000469
285	180.280	0.00229329	0.00276018	520.00	7.000471
286	180.280	0.00229340	0.00276067	520.00	7.000473
287	180.280	0.00229351	0.00276116	520.00	7.000475
288	180.280	0.00229362	0.00276165	520.00	7.000477
289	180.280	0.00229373	0.00276214	520.00	7.000479
290	180.280	0.00229384	0.00276263	520.00	7.000481
291	180.280	0.00229395	0.00276312	520.00	7.000483
292	180.280	0.00229406	0.00276361	520.00	7.000485
293	180.280	0.00229417	0.00276410	520.00	7.000487
294	180.280	0.00229428	0.00276459	520.00	7.000489
295	180.280	0.00229439	0.00276508	520.00	7.000491
296	180.280	0.00229450	0.00276557	520.00	7.000493
297	180.280	0.00229461	0.00276606	520.00	7.000495
298	180.280	0.00229472	0.00276655	520.00	7.000497
299	180.280	0.00229483	0.00276704	520.00	7.000499
300	180.280	0.00229494	0.00276753	520.00	7.000501

ORIGINAL PAGE IS
OF POOR QUALITY

DATA POINT	TIME (SECS)	ANGLE-OF-ATTACK RATE (RADIAN/SEC)	ALTITUDE (FT)	ALTITUDE RATE (FT/SEC)	ALT. ACCEL. (FT/SEC**2)	VERT. ACCEL. (FT/SEC**2)	ELEV. DEFLECT. (RADIAN)
1	0.010	-0.003801821	1000.00	0.01	0.09	0.0	0.0
2	0.020	-0.003770723	1000.00	0.02	0.01	0.0	0.0
3	0.030	-0.003739628	1000.00	0.03	0.02	0.0	0.0
4	0.040	-0.003708538	1000.00	0.04	0.03	0.0	0.0
5	0.050	-0.003677455	1000.00	0.05	0.04	0.0	0.0
6	0.060	-0.003646376	1000.00	0.06	0.05	0.0	0.0
7	0.070	-0.003615298	1000.00	0.07	0.06	0.0	0.0
8	0.080	-0.003584221	1000.01	0.11	1.01	0.0	0.0
9	0.120	-0.003429318	1000.01	0.12	1.01	0.0	0.0
10	0.160	-0.003274417	1000.01	0.13	1.01	0.0	0.0
11	0.200	-0.003119518	1000.02	0.20	1.02	0.0	0.0
12	0.240	-0.002964622	1000.03	0.24	1.03	0.0	0.0
13	0.280	-0.002809721	1000.04	0.27	1.04	0.0	0.0
14	0.320	-0.002654821	1000.05	0.31	1.05	0.0	0.0
15	0.360	-0.002500000	1000.07	0.35	1.07	0.0	0.0
16	0.400	-0.002345181	1000.11	0.39	1.08	0.0	0.0
17	0.440	-0.002190361	1000.15	0.43	1.09	0.0	0.0
18	0.480	-0.002035541	1000.20	0.47	1.10	0.0	0.0
19	0.520	-0.001880721	1000.24	0.51	1.11	0.0	0.0
20	0.560	-0.001725901	1000.29	0.55	1.12	0.0	0.0
21	0.600	-0.001571081	1000.33	0.59	1.13	0.0	0.0
22	0.640	-0.001416261	1000.38	0.63	1.14	0.0	0.0
23	0.680	-0.001261441	1000.42	0.67	1.15	0.0	0.0
24	0.720	-0.001106621	1000.47	0.71	1.16	0.0	0.0
25	0.760	-0.000951801	1000.51	0.75	1.17	0.0	0.0
26	0.800	-0.000796981	1000.56	0.79	1.18	0.0	0.0
27	0.840	-0.000642161	1000.60	0.83	1.19	0.0	0.0
28	0.880	-0.000487341	1000.65	0.87	1.20	0.0	0.0
29	0.920	-0.000332521	1000.69	0.91	1.21	0.0	0.0
30	0.960	-0.000177701	1000.74	0.95	1.22	0.0	0.0
31	1.000	0.000000000	1000.78	0.99	1.23	0.0	0.0
32	1.040	0.000177701	1000.83	1.03	1.24	0.0	0.0
33	1.080	0.000355401	1000.87	1.07	1.25	0.0	0.0
34	1.120	0.000533101	1000.92	1.11	1.26	0.0	0.0
35	1.160	0.000710801	1000.96	1.15	1.27	0.0	0.0
36	1.200	0.000888501	1001.01	1.19	1.28	0.0	0.0
37	1.240	0.001066201	1001.05	1.23	1.29	0.0	0.0
38	1.280	0.001243901	1001.10	1.27	1.30	0.0	0.0
39	1.320	0.001421601	1001.14	1.31	1.31	0.0	0.0
40	1.360	0.001599301	1001.19	1.35	1.32	0.0	0.0
41	1.400	0.001777001	1001.23	1.39	1.33	0.0	0.0
42	1.440	0.001954701	1001.28	1.43	1.34	0.0	0.0
43	1.480	0.002132401	1001.32	1.47	1.35	0.0	0.0
44	1.520	0.002310101	1001.37	1.51	1.36	0.0	0.0
45	1.560	0.002487801	1001.41	1.55	1.37	0.0	0.0
46	1.600	0.002665501	1001.46	1.59	1.38	0.0	0.0
47	1.640	0.002843201	1001.50	1.63	1.39	0.0	0.0
48	1.680	0.003020901	1001.55	1.67	1.40	0.0	0.0
49	1.720	0.003198601	1001.59	1.71	1.41	0.0	0.0
50	1.760	0.003376301	1001.64	1.75	1.42	0.0	0.0
51	1.800	0.003554001	1001.68	1.79	1.43	0.0	0.0
52	1.840	0.003731701	1001.73	1.83	1.44	0.0	0.0
53	1.880	0.003909401	1001.77	1.87	1.45	0.0	0.0
54	1.920	0.004087101	1001.82	1.91	1.46	0.0	0.0
55	1.960	0.004264801	1001.86	1.95	1.47	0.0	0.0
56	2.000	0.004442501	1001.91	1.99	1.48	0.0	0.0
57	2.040	0.004620201	1001.95	2.03	1.49	0.0	0.0
58	2.080	0.004797901	1002.00	2.07	1.50	0.0	0.0
59	2.120	0.004975601	1002.04	2.11	1.51	0.0	0.0
60	2.160	0.005153301	1002.09	2.15	1.52	0.0	0.0
61	2.200	0.005331001	1002.13	2.19	1.53	0.0	0.0
62	2.240	0.005508701	1002.18	2.23	1.54	0.0	0.0
63	2.280	0.005686401	1002.22	2.27	1.55	0.0	0.0
64	2.320	0.005864101	1002.27	2.31	1.56	0.0	0.0
65	2.360	0.006041801	1002.31	2.35	1.57	0.0	0.0
66	2.400	0.006219501	1002.36	2.39	1.58	0.0	0.0
67	2.440	0.006397201	1002.40	2.43	1.59	0.0	0.0
68	2.480	0.006574901	1002.45	2.47	1.60	0.0	0.0
69	2.520	0.006752601	1002.49	2.51	1.61	0.0	0.0
70	2.560	0.006930301	1002.54	2.55	1.62	0.0	0.0
71	2.600	0.007108001	1002.58	2.59	1.63	0.0	0.0
72	2.640	0.007285701	1002.63	2.63	1.64	0.0	0.0
73	2.680	0.007463401	1002.67	2.67	1.65	0.0	0.0
74	2.720	0.007641101	1002.72	2.71	1.66	0.0	0.0
75	2.760	0.007818801	1002.76	2.75	1.67	0.0	0.0
76	2.800	0.007996501	1002.81	2.79	1.68	0.0	0.0
77	2.840	0.008174201	1002.85	2.83	1.69	0.0	0.0
78	2.880	0.008351901	1002.90	2.87	1.70	0.0	0.0
79	2.920	0.008529601	1002.94	2.91	1.71	0.0	0.0
80	2.960	0.008707301	1002.99	2.95	1.72	0.0	0.0
81	3.000	0.008885001	1003.03	2.99	1.73	0.0	0.0
82	3.040	0.009062701	1003.08	3.03	1.74	0.0	0.0
83	3.080	0.009240401	1003.12	3.07	1.75	0.0	0.0
84	3.120	0.009418101	1003.17	3.11	1.76	0.0	0.0
85	3.160	0.009595801	1003.21	3.15	1.77	0.0	0.0
86	3.200	0.009773501	1003.26	3.19	1.78	0.0	0.0
87	3.240	0.009951201	1003.30	3.23	1.79	0.0	0.0
88	3.280	0.010128901	1003.35	3.27	1.80	0.0	0.0
89	3.320	0.010306601	1003.39	3.31	1.81	0.0	0.0
90	3.360	0.010484301	1003.44	3.35	1.82	0.0	0.0
91	3.400	0.010662001	1003.48	3.39	1.83	0.0	0.0
92	3.440	0.010839701	1003.53	3.43	1.84	0.0	0.0
93	3.480	0.011017401	1003.57	3.47	1.85	0.0	0.0
94	3.520	0.011195101	1003.62	3.51	1.86	0.0	0.0
95	3.560	0.011372801	1003.66	3.55	1.87	0.0	0.0
96	3.600	0.011550501	1003.71	3.59	1.88	0.0	0.0
97	3.640	0.011728201	1003.75	3.63	1.89	0.0	0.0
98	3.680	0.011905901	1003.80	3.67	1.90	0.0	0.0
99	3.720	0.012083601	1003.84	3.71	1.91	0.0	0.0
100	3.760	0.012261301	1003.89	3.75	1.92	0.0	0.0
101	3.800	0.012439001	1003.93	3.79	1.93	0.0	0.0
102	3.840	0.012616701	1003.98	3.83	1.94	0.0	0.0
103	3.880	0.012794401	1004.02	3.87	1.95	0.0	0.0
104	3.920	0.012972101	1004.07	3.91	1.96	0.0	0.0
105	3.960	0.013149801	1004.11	3.95	1.97	0.0	0.0
106	4.000	0.013327501	1004.16	3.99	1.98	0.0	0.0
107	4.040	0.013505201	1004.20	4.03	1.99	0.0	0.0
108	4.080	0.013682901	1004.25	4.07	2.00	0.0	0.0
109	4.120	0.013860601	1004.29	4.11	2.01	0.0	0.0
110	4.160	0.014038301	1004.34	4.15	2.02	0.0	0.0
111	4.200	0.014216001	1004.38	4.19	2.03	0.0	0.0
112	4.240	0.014393701	1004.43	4.23	2.04	0.0	0.0
113	4.280	0.014571401	1004.47	4.27	2.05	0.0	0.0
114	4.320	0.014749101	1004.52	4.31	2.06	0.0	0.0
115	4.360	0.014926801	1004.56	4.35	2.07	0.0	0.0
116	4.400	0.015104501	1004.61	4.39	2.08	0.0	0.0
117	4.440	0.015282201	1004.65	4.43	2.09	0.0	0.0
118	4.480	0.015459901	1004.70	4.47	2.10	0.0	0.0
119	4.520	0.015637601	1004.74	4.51	2.11	0.0	0.0
120	4.560	0.015815301	1004.79	4.55	2.12	0.0	0.0
121	4.600	0.015993001	1004.83	4.59	2.13	0.0	0.0
122	4.640	0.016170701	1004.88	4.63	2.14	0.0	0.0
123	4.680	0.016348401	1004.92	4.67	2.15	0.0	0.0
124	4.720	0.016526101	1004.97	4.71	2.16	0.0	0.0
125	4.760	0.016703801	1005.01	4.75	2.17	0.0	0.0

126	11e380	-0e007630629	119e60	18.22	-0e18	0e0	0e0
127	11e400	-0e00775064	119e65	18e00	-0e27	0e0	0e0
128	11e420	-0e00787066	119e68	18e07	-0e39	0e0	0e0
129	11e440	-0e00799068	120e80	18e12	-0e50	0e0	0e0
130	11e460	-0e007970705	120e18	12e07	-0e61	0e0	0e0
131	11e480	-0e007970687	120e08	12e08	-0e71	0e0	0e0
132	11e500	-0e007939906	120e88	11e32	-0e81	0e0	0e0
133	12e000	-0e007971366	120e08	10e04	-0e91	0e0	0e0
134	12e100	-0e007972313	120e71	9e04	-0e00	0e0	0e0
135	12e200	-0e007236362	120e07	9e26	-0e10	0e0	0e0
136	12e300	-0e007760706	120e16	8e26	-0e18	0e0	0e0
137	12e400	-0e0079007021	120e38	7e00	-0e26	0e0	0e0
138	12e500	-0e007926367	121e12	7e07	-0e36	0e0	0e0
139	12e600	-0e006550687	121e76	6e33	-0e41	0e0	0e0
140	12e700	-0e006800321	121e36	5e35	-0e46	0e0	0e0
141	12e800	-0e006822388	121e01	4e36	-0e50	0e0	0e0
142	12e900	-0e006753636	121e38	4e08	-0e52	0e0	0e0
143	13e000	-0e006806021	121e72	3e32	-0e56	0e0	0e0
144	13e100	-0e006811855	121e02	2e33	-0e57	0e0	0e0
145	13e200	-0e006806762	121e23	1e77	-0e58	0e0	0e0
146	13e300	-0e006877660	121e37	0e66	-0e52	0e0	0e0
147	13e400	-0e006800762	121e63	-0e10	-0e59	0e0	0e0
148	13e500	-0e006837623	121e63	-0e10	-0e59	0e0	0e0
149	13e600	-0e006830282	121e37	-0e08	-0e56	0e0	0e0
150	13e700	-0e006822388	121e23	-0e18	-0e57	0e0	0e0
151	13e700	-0e006816080	121e01	-0e30	-0e50	0e0	0e0
152	13e800	-0e006800196	121e72	-0e36	-0e53	0e0	0e0
153	13e900	-0e006800562	121e36	-0e17	-0e06	0e0	0e0
154	14e000	-0e006800290	121e68	-0e01	-0e06	0e0	0e0
155	14e100	-0e005972682	121e36	-0e50	-0e10	0e0	0e0
156	14e200	-0e005900663	121e72	-0e01	-0e11	0e0	0e0
157	14e300	-0e005972683	121e02	-0e42	-0e11	0e0	0e0
158	14e400	-0e005963502	120e23	-0e42	-0e13	0e0	0e0
159	14e500	-0e005970688	120e37	-0e35	-0e13	0e0	0e0
160	14e600	-0e005900195	120e62	-0e04	-0e13	0e0	0e0
161	14e700	-0e005930706	120e60	-0e07	-0e13	0e0	0e0
162	14e800	-0e005938797	120e25	-0e10	-0e14	0e0	0e0
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164	15e000	-0e005907766	120e63	-0e11	-0e08	0e0	0e0
165	15e100	-0e005933185	120e48	-0e01	-0e07	0e0	0e0
166	15e200	-0e005900319	120e08	-0e12	-0e03	0e0	0e0
167	15e300	-0e005908076	119e68	-0e26	-0e03	0e0	0e0
168	15e400	-0e005912056	119e96	-0e32	-0e09	0e0	0e0
169	15e500	-0e005908076	119e27	-0e12	-0e09	0e0	0e0
170	15e600	-0e005908126	119e22	-0e09	-0e12	0e0	0e0
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172	15e800	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
173	15e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
174	16e000	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
175	16e100	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
176	16e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
177	16e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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179	16e500	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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181	16e700	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
182	16e800	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
183	16e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
184	17e000	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
185	17e100	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
186	17e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
187	17e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
188	17e400	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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190	17e600	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
191	17e700	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
192	17e800	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
193	17e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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196	18e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
197	18e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
198	18e400	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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202	18e800	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
203	18e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
204	19e000	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
205	19e100	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
206	19e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
207	19e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
208	19e400	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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211	19e700	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
212	19e800	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
213	19e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
214	20e000	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
215	20e100	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
216	20e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
217	20e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
218	20e400	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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220	20e600	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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223	20e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
224	21e000	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
225	21e100	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
226	21e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
227	21e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
228	21e400	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
229	21e500	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
230	21e600	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
231	21e700	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
232	21e800	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
233	21e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
234	22e000	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
235	22e100	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
236	22e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
237	22e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
238	22e400	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
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240	22e600	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
241	22e700	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
242	22e800	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
243	22e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
244	23e000	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
245	23e100	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
246	23e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
247	23e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
248	23e400	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
249	23e500	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
250	23e600	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
251	23e700	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
252	23e800	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
253	23e900	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
254	24e000	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
255	24e100	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
256	24e200	-0e005908076	119e70	-0e09	-0e10	0e0	0e0
257	24e300	-0e005908076	119e70	-0e09	-0e10	0e0	0e0

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204	24a90	-0408008877	436.26	-854.17	3a13	3a3	3a3
210	24a30	-0408008778	414.58	-854.58	2a33	3a3	3a3
213	24a00	-0408006265	477.12	-853.31	3a48	0a3	0a3
261	24a70	-0408082687	622.88	-866.16	3a00	0a3	0a3
262	34a08	-0408077887	818.68	-871.74	3a00	0a3	0a3
263	24a08	-0408033318	813.83	-866.81	3a00	0a3	0a3
264	24a00	-0408029071	804.21	-854.01	4a02	0a3	3a3
268	24a10	-0403050195	608.82	-632.80	4a18	0a3	3a3
269	24a00	-0408045111	605.40	-632.40	4a00	3a3	3a3
270	24a10	-04030326373	701.96	-827.24	4a00	3a3	3a3
271	24a00	-0403025952	787.73	-816.62	4a00	3a3	3a3
272	24a00	-0403009124	786.57	-816.57	4a00	3a3	3a3
273	24a00	-0403000666	779.46	-846.66	4a00	3a3	3a3
274	24a00	-040301149201	773.40	-846.36	5a11	0a3	0a3
276	24a00	-0403006053	767.48	-836.48	5a08	0a3	0a3
277	24a00	-0403013647	763.63	-837.77	5a36	0a3	0a3
278	24a10	-04030018836	760.08	-836.41	5a36	0a3	0a3
279	24a00	-0403008811	759.88	-837.88	5a36	0a3	0a3
280	24a00	-0403007932	752.15	-837.08	5a36	0a3	0a3
281	24a00	-04030289908	746.48	-836.47	5a37	0a3	0a3
282	24a00	-04030287314	746.48	-836.47	5a37	0a3	0a3
283	24a00	-04030080822	744.32	-836.32	5a37	0a3	0a3
284	24a00	-04030087732	737.41	-836.43	5a31	3a3	3a3
285	24a00	-0403021008	736.36	-836.36	5a32	3a3	3a3
286	24a00	-04030074905	731.03	-836.18	5a36	3a3	3a3
287	24a00	-04030084411	727.71	-832.69	5a36	3a3	3a3
288	24a00	-04030105196	724.47	-832.02	5a36	3a3	3a3
289	24a30	-04030122163	721.36	-831.36	5a36	3a3	3a3
290	24a00	-0403011187	718.21	-830.23	5a36	3a3	3a3
291	24a00	-0403011673	716.68	-829.95	7a04	0a3	0a3
292	24a00	-040301621729	712.22	-829.26	7a18	2a3	3a3
293	24a00	-0403026794	709.33	-828.33	7a23	2a3	3a3
294	24a00	-04030104418	706.91	-827.77	7a32	3a3	3a3
295	24a00	-04030176735	703.77	-827.14	7a43	3a3	3a3
296	24a10	-040301014715	701.61	-826.31	7a43	3a3	3a3
297	24a00	-0403017213	699.96	-826.56	7a36	3a3	3a3
298	24a00	-04030338796	696.96	-826.93	7a36	3a3	3a3
299	24a00	-040301014715	696.96	-826.93	7a36	3a3	3a3
300	24a00	-040303014721	691.18	-823.29	7a31	0a3	0a3

.....
 * PATH PERFORMANCE ANALYSIS ITERATION NO. 1
 * (ALTITUDE AND AIRSPEED ASSUMED CORRECT)
 *

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PATH PERFORMANCE DRAG AND LIFT COEFFICIENT UPDATE

GLU	UCLA	HEU
1159154118000-U	=001181060903J310-02	=J0362421190200000140-00
115915410000-U J1	=0020000J3177000000-01	=J032393510431783101 01
115915410000-U J2	=001131033000007000 J2	=000
115915410000-U J3	=001130000000000000 J3	=J0117320000003313393J 01
115915410000-U J4	=00113275502700004200-U	=04348472337000000000-02
115915410000-U J5	=00110715002700007000-J5	=J063760000003370010 01
115915410000-U J6		=063830010163847740 01

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1.278000 U	1.211300 U	1.253120 U	1.282500 U	1.268800 U	1.267300 U	1.263770 U	1.269610 U
1.284000 U	1.211910 U	1.253740 U	1.283800 U	1.269800 U	1.269770 U	1.268280 U	1.271280 U
1.294000 U	1.212280 U	1.254450 U	1.284800 U	1.270800 U	1.269880 U	1.269080 U	1.272780 U
1.304000 U	1.212900 U	1.255160 U	1.285800 U	1.271800 U	1.270880 U	1.270080 U	1.273780 U
1.314000 U	1.213280 U	1.255780 U	1.286400 U	1.272400 U	1.271880 U	1.271080 U	1.274780 U
1.324000 U	1.213800 U	1.256700 U	1.287700 U	1.273400 U	1.272880 U	1.272080 U	1.275780 U
1.334000 U	1.214280 U	1.257320 U	1.288300 U	1.274000 U	1.273400 U	1.272600 U	1.276780 U
1.344000 U	1.214800 U	1.257940 U	1.288900 U	1.274600 U	1.274000 U	1.273200 U	1.277780 U
1.354000 U	1.215300 U	1.258560 U	1.289500 U	1.275200 U	1.274600 U	1.273800 U	1.278780 U
1.364000 U	1.215800 U	1.259180 U	1.290100 U	1.275800 U	1.275200 U	1.274400 U	1.279780 U
1.374000 U	1.216300 U	1.259800 U	1.290700 U	1.276400 U	1.275800 U	1.275000 U	1.280780 U
1.384000 U	1.216800 U	1.260420 U	1.291300 U	1.277000 U	1.276400 U	1.275600 U	1.281780 U
1.394000 U	1.217300 U	1.261040 U	1.291900 U	1.277600 U	1.277000 U	1.276200 U	1.282780 U
1.404000 U	1.217800 U	1.261660 U	1.292500 U	1.278200 U	1.277600 U	1.276800 U	1.283780 U
1.414000 U	1.218300 U	1.262280 U	1.293100 U	1.278800 U	1.278200 U	1.277400 U	1.284780 U
1.424000 U	1.218800 U	1.262900 U	1.293700 U	1.279400 U	1.278800 U	1.278000 U	1.285780 U
1.434000 U	1.219300 U	1.263520 U	1.294300 U	1.280000 U	1.279400 U	1.278600 U	1.286780 U
1.444000 U	1.219800 U	1.264140 U	1.294900 U	1.280600 U	1.280000 U	1.279200 U	1.287780 U
1.454000 U	1.220300 U	1.264760 U	1.295500 U	1.281200 U	1.280600 U	1.279800 U	1.288780 U
1.464000 U	1.220800 U	1.265380 U	1.296100 U	1.281800 U	1.281200 U	1.280400 U	1.289780 U
1.474000 U	1.221300 U	1.266000 U	1.296700 U	1.282400 U	1.281800 U	1.281000 U	1.290780 U
1.484000 U	1.221800 U	1.266620 U	1.297300 U	1.283000 U	1.282400 U	1.281600 U	1.291780 U
1.494000 U	1.222300 U	1.267240 U	1.297900 U	1.283600 U	1.283000 U	1.282200 U	1.292780 U
1.504000 U	1.222800 U	1.267860 U	1.298500 U	1.284200 U	1.283600 U	1.282800 U	1.293780 U
1.514000 U	1.223300 U	1.268480 U	1.299100 U	1.284800 U	1.284200 U	1.283400 U	1.294780 U
1.524000 U	1.223800 U	1.269100 U	1.299700 U	1.285400 U	1.284800 U	1.284000 U	1.295780 U
1.534000 U	1.224300 U	1.269720 U	1.300300 U	1.286000 U	1.285400 U	1.284600 U	1.296780 U
1.544000 U	1.224800 U	1.270340 U	1.300900 U	1.286600 U	1.286000 U	1.285200 U	1.297780 U
1.554000 U	1.225300 U	1.270960 U	1.301500 U	1.287200 U	1.286600 U	1.285800 U	1.298780 U
1.564000 U	1.225800 U	1.271580 U	1.302100 U	1.287800 U	1.287200 U	1.286400 U	1.299780 U
1.574000 U	1.226300 U	1.272200 U	1.302700 U	1.288400 U	1.287800 U	1.287000 U	1.300780 U
1.584000 U	1.226800 U	1.272820 U	1.303300 U	1.289000 U	1.288400 U	1.287600 U	1.301780 U
1.594000 U	1.227300 U	1.273440 U	1.303900 U	1.289600 U	1.289000 U	1.288200 U	1.302780 U
1.604000 U	1.227800 U	1.274060 U	1.304500 U	1.290200 U	1.289600 U	1.288800 U	1.303780 U
1.614000 U	1.228300 U	1.274680 U	1.305100 U	1.290800 U	1.290200 U	1.289400 U	1.304780 U
1.624000 U	1.228800 U	1.					

PITCH-ANGLE GAIN = 1.000151472E30 00
PITCH-ANGLE BIAS = 5.034592357010-06 RADIAN

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PATH PERFORMANCE DRAG AND LIFT COEFFICIENT UPDATE

BATH PERFORMANCE SITUATION 2

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2439000 J1	6131500 J2	2400100 J2	14197800 J2	14888800-02	14709900 J1	14626800 J2	14904260 J2	14863000 J2
2439000 J1	6148200 J2	2411600 J2	14198500 J2	14889400-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6150310 J2	24128600 J2	14199000 J2	14890000-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6150710 J2	24130800 J2	14199700 J2	14890600-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6150900 J2	24132000 J2	14200000 J2	14891200-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6150940 J2	24132400 J2	14200300 J2	14891500-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6151450 J2	24134200 J2	14201000 J2	14892000-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6151750 J2	24136900 J2	14201900 J2	14892600-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152000 J2	24138000 J2	14202500 J2	14893000-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152100 J2	24138500 J2	14202800 J2	14893300-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152150 J2	24138800 J2	14203000 J2	14893500-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152180 J2	24139000 J2	14203200 J2	14893700-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152200 J2	24139200 J2	14203400 J2	14893900-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152220 J2	24139400 J2	14203600 J2	14894100-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152240 J2	24139600 J2	14203800 J2	14894300-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152260 J2	24139800 J2	14204000 J2	14894500-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152280 J2	24140000 J2	14204200 J2	14894700-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152300 J2	24140200 J2	14204400 J2	14894900-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152320 J2	24140400 J2	14204600 J2	14895100-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152340 J2	24140600 J2	14204800 J2	14895300-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152360 J2	24140800 J2	14205000 J2	14895500-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152380 J2	24141000 J2	14205200 J2	14895700-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152400 J2	24141200 J2	14205400 J2	14895900-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152420 J2	24141400 J2	14205600 J2	14896100-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152440 J2	24141600 J2	14205800 J2	14896300-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152460 J2	24141800 J2	14206000 J2	14896500-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152480 J2	24142000 J2	14206200 J2	14896700-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152500 J2	24142200 J2	14206400 J2	14896900-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152520 J2	24142400 J2	14206600 J2	14897100-02	14697000 J1	14626800-02	14904260 J2	14863000 J2
2439000 J1	6152540 J2	2						

PITCH-ANGLE GAIN = 1.030000000000 00
PITCH-ANGLE DEAS = 3.304748909170-17 FAULAN

MODEL SOLUTIONS

```

*****
* MODEL 12      P1 = 4e0544525226b8200 04      C00 = 3e4V5070e3e5431100-02
*               P1 = 0e0                          C01 = 0e0
* PCINT         P2 = 1e229093001030e100 03      C02 = 1e3114075999210400 00
* FAILURES      P3 = 4e01810590331312400 00      C03 = 0e0
*               P4 = 0e0                          C04 = 1e9564933370e8200 03
*
* FIT ERROR= 7e034e0e70e1e1V000-0e

```

MODEL 12 FOUND TO BE BEST FIT

LIFT COEFFICIENTS: BY LEAST SQUARE METHOD

CLAU=J.366J254462154020-02
CLA = 0.63826072733712540 01
CLAS=0.5695004420363163 00
EXPM = 0.2050130619302380 01
CLM 0.0

ESTIMATED SPECIFIC FUEL CONSUMPTION W. 2.027100J383070-07 LBF/LBT-LNF/SEC/SEC

 * PATH PERFORMANCE ANALYSIS ITERATION NO. 3
 * (ALTITUDE AND AIRSPEED ASSUMED CORRECT)
 * *****

PATH PERFORMANCE SUPPLEMENTAL I									
TIME (SEC/S)	ALTITUDE (FT)	AIRSPEED (FT/SEC)	GAMMA (RAD)	ALPHA (RAD)	CL	CU	WEIGHT (LBS)	POWER (FT/LB/SEC)	
C-0	1.000000 03	1.007360 02	1.024200 00	1.024200 00	1.024200 00	1.024200 00	4.000000 00	1.007360 00	
1.000000-02	1.000000 03	1.007460 02	1.024200 00	1.024200 00	1.024200 00	1.024200 00	4.000000 00	1.007360 00	
1.000000-01	1.000000 03	1.008320 02	1.024200 00	1.024200 00	1.024200 00	1.024200 00	4.000000 00	1.007360 00	
1.000000-00	1.000000 03	1.008320 02	1.024200 00	1.024200 00	1.024200 00	1.024200 00	4.000000 00	1.007360 00	
1.000000-01	1.000000 03	1.008320 02	1.024200 00	1.024200 00	1.024200 00	1.024200 00	4.000000 00	1.007360 00	
1.000000-02	1.000000 03	1.008320 02	1.024200 00	1.024200 00	1.024200 00	1.024200 00	4.000000 00	1.007360 00	

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1.278000 U1	1.121120 Z3	1.164290 Z2	1.032050-Z2	1.401240-Z2	1.617330-Z1	1.432780-Z2	1.369810 Z3	1.155180 Z0
1.278000 U1	1.121130 Z3	1.164310 Z2	1.032100-Z2	1.401300-Z2	1.617360-Z1	1.432800-Z2	1.369830 Z3	1.155210 Z0
1.278000 U1	1.121140 Z3	1.164330 Z2	1.032150-Z2	1.401350-Z2	1.617390-Z1	1.432820-Z2	1.369850 Z3	1.155240 Z0
1.278000 U1	1.121150 Z3	1.164350 Z2	1.032200-Z2	1.401400-Z2	1.617420-Z1	1.432840-Z2	1.369870 Z3	1.155270 Z0
1.278000 U1	1.121160 Z3	1.164370 Z2	1.032250-Z2	1.401450-Z2	1.617450-Z1	1.432860-Z2	1.369890 Z3	1.155300 Z0
1.278000 U1	1.121170 Z3	1.164390 Z2	1.032300-Z2	1.401500-Z2	1.617480-Z1	1.432880-Z2	1.369910 Z3	1.155330 Z0
1.278000 U1	1.121180 Z3	1.164410 Z2	1.032350-Z2	1.401550-Z2	1.617510-Z1	1.432900-Z2	1.369930 Z3	1.155360 Z0
1.278000 U1	1.121190 Z3	1.164430 Z2	1.032400-Z2	1.401600-Z2	1.617540-Z1	1.432920-Z2	1.369950 Z3	1.155390 Z0
1.278000 U1	1.121200 Z3	1.164450 Z2	1.032450-Z2	1.401650-Z2	1.617570-Z1	1.432940-Z2	1.369970 Z3	1.155420 Z0
1.278000 U1	1.121210 Z3	1.164470 Z2	1.032500-Z2	1.401700-Z2	1.617600-Z1	1.432960-Z2	1.369990 Z3	1.155450 Z0
1.278000 U1	1.121220 Z3	1.164490 Z2	1.032550-Z2	1.401750-Z2	1.617630-Z1	1.432980-Z2	1.370010 Z3	1.155480 Z0
1.278000 U1	1.121230 Z3	1.164510 Z2	1.032600-Z2	1.401800-Z2	1.617660-Z1	1.433000-Z2	1.370030 Z3	1.155510 Z0
1.278000 U1	1.121240 Z3	1.164530 Z2	1.032650-Z2	1.401850-Z2	1.617690-Z1	1.433020-Z2	1.370050 Z3	1.155540 Z0
1.278000 U1	1.121250 Z3	1.164550 Z2	1.032700-Z2	1.401900-Z2	1.617720-Z1	1.433040-Z2	1.370070 Z3	1.155570 Z0
1.278000 U1	1.121260 Z3	1.164570 Z2	1.032750-Z2	1.401950-Z2	1.617750-Z1	1.433060-Z2	1.370090 Z3	1.155600 Z0
1.278000 U1	1.121270 Z3	1.164590 Z2	1.032800-Z2	1.402000-Z2	1.617780-Z1	1.433080-Z2	1.370110 Z3	1.155630 Z0
1.278000 U1	1.121280 Z3	1.164610 Z2	1.032850-Z2	1.402050-Z2	1.617810-Z1	1.433100-Z2	1.370130 Z3	1.155660 Z0
1.278000 U1	1.121290 Z3	1.164630 Z2	1.032900-Z2	1.402100-Z2	1.617840-Z1	1.433120-Z2	1.370150 Z3	1.155690 Z0
1.278000 U1	1.121300 Z3	1.164650 Z2	1.032950-Z2	1.402150-Z2	1.617870-Z1	1.433140-Z2	1.370170 Z3	1.155720 Z0
1.278000 U1	1.121310 Z3	1.164670 Z2	1.033000-Z2	1.402200-Z2	1.617900-Z1	1.433160-Z2	1.370190 Z3	1.155750 Z0
1.278000 U1	1.121320 Z3	1.164690 Z2	1.033050-Z2	1.402250-Z2	1.617930-Z1	1.433180-Z2	1.370210 Z3	1.155780 Z0
1.278000 U1	1.121330 Z3	1.164710 Z2	1.033100-Z2	1.402300-Z2	1.617960-Z1	1.433200-Z2	1.370230 Z3	1.155810 Z0
1.278000 U1	1.121340 Z3	1.164730 Z2	1.033150-Z2	1.402350-Z2	1.617990-Z1	1.433220-Z2	1.370250 Z3	1.155840 Z0
1.278000 U1	1.121350 Z3	1.164750 Z2	1.033200-Z2	1.402400-Z2	1.618020-Z1	1.433240-Z2	1.370270 Z3	1.155870 Z0
1.278000 U1	1.121360 Z3	1.164770 Z2	1.033250-Z2	1.402450-Z2	1.618050-Z1	1.433260-Z2	1.370290 Z3	1.155900 Z0
1.278000 U1	1.121370 Z3	1.164790 Z2	1.033300-Z2	1.402500-Z2	1.618080-Z1	1.433280-Z2	1.370310 Z3	1.155930 Z0
1.278000 U1	1.121380 Z3	1.164810 Z2	1.033350-Z2	1.402550-Z2	1.618110-Z1	1.433300-Z2	1.370330 Z3	1.155960 Z0
1.278000 U1	1.121390 Z3	1.164830 Z2	1.033400-Z2	1.402600-Z2	1.618140-Z1	1.433320-Z2	1.370350 Z3	1.155990 Z0
1.278000 U1	1.121400 Z3	1.164850 Z2	1.033450-Z2	1.402650-Z2	1.618170-Z1	1.433340-Z2	1.370370 Z3	1.156020 Z0
1.278000 U1	1.121410 Z3	1.164870 Z2	1.033500-Z2					

PATH PERFORMANCE DIAG AND LIFT COEFFICIENT UPDATE.

OLU DELTA

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PATH PERFORMANCE, SIMILITATION 2

690

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PITCH-ANGLE GAIN = 1.00000000000000 30
PITCH-ANGLE BIAS = 0.039267403390-17 RADIAN

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*
* MODEL 12  P0 = 2.665797+7JJ5218800 04  C03 = 3.49723499+013200-02
*           P1 = 3.0J  C01 = 0.00
* MCINT      P2 = 1.127491120JJ2273800 03  C02 = 1.3111770089305000 00
* FAILURES  P3 = -2.1535237J407816000 00  C03 = 3.00
*           P4 = 0.0  C04 = 1.6670367132075800 03
*

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MODEL 12 FOUND TO BE BEST FIT

LIFT COEFFICIENTS: BY LEAST SQUARE DISTANCE

CLAG=00J3900030701002540-02
CLA = 000J70027033907010 01
CLAG=0003030032039000J20 00
EPRN= 000007000010000000 01
CLQ0 020

ESTIMATED SPECIFIC FUEL CONSUMPTION = 2.5270903964350-07 LBF/(FT-LBF/SEC)/SEA

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[illegible]

PATH PERFORMANCE DRAG AND LIFT COEFFICIENT UPDATES

	OLD	DELTA	NEW
C00	1	0.335673211959046850-2	0
C01	0.00	0	0.00
C02	1	0.335673211959046850-2	0
C03	0.00	0	0.00
C04	1	0.335673211959046850-2	0
C05	0.00	0	0.00
C06	1	0.335673211959046850-2	0
C07	0.00	0	0.00
C08	1	0.335673211959046850-2	0
C09	0.00	0	0.00
C10	1	0.335673211959046850-2	0
C11	0.00	0	0.00
C12	1	0.335673211959046850-2	0
C13	0.00	0	0.00
C14	1	0.335673211959046850-2	0
C15	0.00	0	0.00
C16	1	0.335673211959046850-2	0
C17	0.00	0	0.00
C18	1	0.335673211959046850-2	0
C19	0.00	0	0.00
C20	1	0.335673211959046850-2	0
C21	0.00	0	0.00
C22	1	0.335673211959046850-2	0
C23	0.00	0	0.00
C24	1	0.335673211959046850-2	0
C25	0.00	0	0.00
C26	1	0.335673211959046850-2	0
C27	0.00	0	0.00
C28	1	0.335673211959046850-2	0
C29	0.00	0	0.00
C30	1	0.335673211959046850-2	0
C31	0.00	0	0.00
C32	1	0.335673211959046850-2	0
C33	0.00	0	0.00
C34	1	0.335673211959046850-2	0
C35	0.00	0	0.00
C36	1	0.335673211959046850-2	0
C37	0.00	0	0.00
C38	1	0.335673211959046850-2	0
C39	0.00	0	0.00
C40	1	0.335673211959046850-2	0
C41	0.00	0	0.00
C42	1	0.335673211959046850-2	0
C43	0.00	0	0.00
C44	1	0.335673211959046850-2	0
C45	0.00	0	0.00
C46	1	0.335673211959046850-2	0
C47	0.00	0	0.00
C48	1	0.335673211959046850-2	0
C49	0.00	0	0.00
C50	1	0.335673211959046850-2	0
C51	0.00	0	0.00
C52	1	0.335673211959046850-2	0
C53	0.00	0	0.00
C54	1	0.335673211959046850-2	0
C55	0.00	0	0.00
C56	1	0.335673211959046850-2	0
C57	0.00	0	0.00
C58	1	0.335673211959046850-2	0
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C60	1	0.335673211959046850-2	0
C61	0.00	0	0.00
C62	1	0.335673211959046850-2	0
C63	0.00	0	0.00
C64	1	0.335673211959046850-2	0
C65	0.00	0	0.00
C66	1	0.335673211959046850-2	0
C67	0.00	0	0.00
C68	1	0.335673211959046850-2	0
C69	0.00	0	0.00
C70	1	0.335673211959046850-2	0
C71	0.00	0	0.00
C72	1	0.335673211959046850-2	0
C73	0.00	0	0.00
C74	1	0.335673211959046850-2	0
C75	0.00	0	0.00
C76	1	0.335673211959046850-2	0
C77	0.00	0	0.00
C78	1	0.335673211959046850-2	0
C79	0.00	0	0.00
C80	1	0.335673211959046850-2	0
C81	0.00	0	0.00
C82	1	0.335673211959046850-2	0
C83	0.00	0	0.00
C84	1	0.335673211959046850-2	0
C85	0.00	0	0.00
C86	1	0.335673211959046850-2	0
C87	0.00	0	0.00
C88	1	0.335673211959046850-2	0
C89	0.00	0	0.00
C90	1	0.335673211959046850-2	0

PATH PERFORMANCE SUBITERGATION 2

TIME	ALTITUDE (FT)	ALPSPEC (PT/SEC)	GAMMA (RAD)	ALPHA (RAD)	CL	CD	WEIGHT (LBF)	POWER (FT-LB/SEC)
0.000000	1.000000 Q	1.446730 Z	1.516240-J	0.632740-I	1.025030 Q	1.025220-Q	0.000000 Q	1.446930 Q
0.000000	1.000000 Q	1.447860 Z	1.516240-J	0.632740-I	1.025070 Q	1.025440-Q	0.000000 Q	1.446930 Q
0.000000	1.000000 Q	1.448320 Z	1.516700-J	0.632940-I	1.025120 Q	1.025590-Q	0.000000 Q	1.446960 Q
0.000000	1.000000 Q	1.448780 Z	1.517160-J	0.633140-I	1.025170 Q	1.025740-Q	0.000000 Q	1.446960 Q
0.000000	1.000000 Q	1.449250 Z	1.517620-J	0.633340-I	1.025220 Q	1.025790-Q	0.000000 Q	1.446980 Q
0.000000	1.000000 Q	1.449710 Z	1.518080-J	0.633540-I	1.025270 Q	1.026240-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.450170 Z	1.518540-J	0.633740-I	1.025320 Q	1.026290-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.450630 Z	1.519000-J	0.633940-I	1.025370 Q	1.026340-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.451090 Z	1.519460-J	0.634140-I	1.025420 Q	1.026390-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.451550 Z	1.519920-J	0.634340-I	1.025470 Q	1.026440-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.452010 Z	1.520380-J	0.634540-I	1.025520 Q	1.026490-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.452470 Z	1.520840-J	0.634740-I	1.025570 Q	1.026540-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.452930 Z	1.521300-J	0.634940-I	1.025620 Q	1.026590-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.453390 Z	1.521760-J	0.635140-I	1.025670 Q	1.026640-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.453850 Z	1.522220-J	0.635340-I	1.025720 Q	1.026690-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.454310 Z	1.522680-J	0.635540-I	1.025770 Q	1.026740-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.454770 Z	1.523140-J	0.635740-I	1.025820 Q	1.026790-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.455230 Z	1.523600-J	0.635940-I	1.025870 Q	1.026840-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.455690 Z	1.524060-J	0.636140-I	1.025920 Q	1.026890-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.456150 Z	1.524520-J	0.636340-I	1.025970 Q	1.026940-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.456610 Z	1.524980-J	0.636540-I	1.026020 Q	1.026990-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.457070 Z	1.525440-J	0.636740-I	1.026070 Q	1.027040-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.457530 Z	1.525900-J	0.636940-I	1.026120 Q	1.027090-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.457990 Z	1.526360-J	0.637140-I	1.026170 Q	1.027140-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.458450 Z	1.526820-J	0.637340-I	1.026220 Q	1.027190-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.458910 Z	1.527280-J	0.637540-I	1.026270 Q	1.027240-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.459370 Z	1.527740-J	0.637740-I	1.026320 Q	1.027290-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.459830 Z	1.528200-J	0.637940-I	1.026370 Q	1.027340-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.460290 Z	1.528660-J	0.638140-I	1.026420 Q	1.027390-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.460750 Z	1.529120-J	0.638340-I	1.026470 Q	1.027440-Q	0.000000 Q	1.446970 Q
0.000000	1.000000 Q	1.461210 Z	1.529580-J	0.638540-I	1.026520 Q</			

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1.669820	01	1.669820	03	1.669790	02	1.669810	01	7.661860	-02	6.666120	-01	7.667900	02	7.667330	03	7.667320	08
1.669930	01	1.669930	01	1.669930	02	1.669930	03	7.662290	-02	6.667810	-01	7.668950	02	7.668330	03	7.668310	08
1.670030	01	1.670030	01	1.670030	02	1.670030	03	7.669890	-02	6.669280	-01	7.670590	02	7.670000	03	7.670000	08
1.670130	01	1.670130	01	1.670130	02	1.670130	03	7.670970	-02	6.670690	-01	7.671670	02	7.671000	03	7.671000	08
1.670230	01	1.670230	01	1.670230	02	1.670230	03	7.671950	-02	6.671790	-01	7.672650	02	7.672000	03	7.672000	08
1.670330	01	1.670330	01	1.670330	02	1.670330	03	7.672930	-02	6.672770	-01	7.673590	02	7.673000	03	7.673000	08
1.670430	01	1.670430	01	1.670430	02	1.670430	03	7.673910	-02	6.673750	-01	7.674470	02	7.674000	03	7.674000	08
1.670530	01	1.670530	01	1.670530	02	1.670530	03	7.674890	-02	6.674730	-01	7.675450	02	7.675000	03	7.675000	08
1.670630	01	1.670630	01	1.670630	02	1.670630	03	7.675870	-02	6.675710	-01	7.676370	02	7.676000	03	7.676000	08
1.670730	01	1.670730	01	1.670730	02	1.670730	03	7.676850	-02	6.676690	-01	7.677350	02	7.677000	03	7.677000	08
1.670830	01	1.670830	01	1.670830	02	1.670830	03	7.677830	-02	6.677670	-01	7.678330	02	7.678000	03	7.678000	08
1.670930	01	1.670930	01	1.670930	02	1.670930	03	7.678810	-02	6.678650	-01	7.679310	02	7.679000	03	7.679000	08
1.671030	01	1.671030	01	1.671030	02	1.671030	03	7.679790	-02	6.679630	-01	7.680290	02	7.680000	03	7.680000	08
1.671130	01	1.671130	01	1.671130	02	1.671130	03	7.680770	-02	6.680550	-01	7.681270	02	7.681000	03	7.681000	08
1.671230	01	1.671230	01	1.671230	02	1.671230	03	7.681750	-02	6.681530	-01	7.682250	02	7.682000	03	7.682000	08
1.671330	01	1.671330	01	1.671330	02	1.671330	03	7.682730	-02	6.682510	-01	7.683230	02	7.683000	03	7.683000	08
1.671430	01	1.671430	01	1.671430	02	1.671430	03	7.683710	-02	6.683490	-01	7.684290	02	7.684000	03	7.684000	08
1.671530	01	1.671530	01	1.671530	02	1.671530	03	7.684690	-02	6.684470	-01	7.685170	02	7.685000	03	7.685000	08
1.671630	01	1.671630	01	1.671630	02	1.671630	03	7.685670	-02	6.685450	-01	7.686150	02	7.686000	03	7.686000	08
1.671730	01	1.671730	01	1.671730	02	1.671730	03	7.686650	-02	6.686430	-01	7.686930	02	7.687000	03	7.687000	08
1.671830	01	1.671830	01	1.671830	02	1.671830	03	7.687630	-02	6.687410	-01	7.687910	02	7.688000	03	7.688000	08
1.671930	01	1.671930	01	1.671930	02	1.671930	03	7.688610	-02	6.688390	-01	7.688890	02	7.689000	03	7.689000	08
1.672030	01</																

PITCH-ANGLE GAIN = 1.0000000000000000 UO

MODEL SOLUTIONS:

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MODEL 12 FOUND TO BE BEST FIT
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CLAS=06J2023082822007540-UZ
CLAS=JabJ7906J215484v9JD 01
CLAS=06b019570278671600 00
FAPK=062084180416v164980 01
CLAS 06

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*****
1  PATH PERFORMANCE ANALYSIS ITERATION NO. 3
2  (ALTITUDE AND AIRSPEED ASSUMED CORRECT)
3  *****

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[illegible]

[illegible]

MODEL SOLUTIONS

MODEL 12 FOUND TO BE BEST FIT

CLAS=0.30663552 323089930-02
CLA = 0.63779684-50010283 01
CLAX=0.4669762614n172130 00
EXPX 0.2063587946408340 01
CLG= 0.0

PATH PERFORMANCE SUBSTITUTION

703

704

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[illegible]

[illegible]

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PITCH=ANGLE GAIN = 1.000000000000 30
PITCH=ANGLE UAS = 5.523142937630-17 RADIANS
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ORIGINAL PAGE IS
OF POOR QUALITY

DATA POINT	TIME (SECS)	DENSITY (SLUG/FT ³)	ANGLE UP ATTACK (RAD/ANS)	TEMPERATURE (DEG-F)	ACCELERATION (FT/SEC ²)
1	0.010	0.00230978	0.1020492	520.00	0.00000
2	0.010	0.00230978	0.1020492	520.00	0.00000
3	0.010	0.00230978	0.1020492	520.00	0.00000
4	0.010	0.00230978	0.1020492	520.00	0.00000
5	0.010	0.00230978	0.1020492	520.00	0.00000
6	0.010	0.00230978	0.1020492	520.00	0.00000
7	0.010	0.00230978	0.1020492	520.00	0.00000
8	0.010	0.00230978	0.1020492	520.00	0.00000
9	0.010	0.00230978	0.1020492	520.00	0.00000
10	0.010	0.00230978	0.1020492	520.00	0.00000
11	0.010	0.00230978	0.1020492	520.00	0.00000
12	0.010	0.00230978	0.1020492	520.00	0.00000
13	0.010	0.00230978	0.1020492	520.00	0.00000
14	0.010	0.00230978	0.1020492	520.00	0.00000
15	0.010	0.00230978	0.1020492	520.00	0.00000
16	0.010	0.00230978	0.1020492	520.00	0.00000
17	0.010	0.00230978	0.1020492	520.00	0.00000
18	0.010	0.00230978	0.1020492	520.00	0.00000
19	0.010	0.00230978	0.1020492	520.00	0.00000
20	0.010	0.00230978	0.1020492	520.00	0.00000
21	0.010	0.00230978	0.1020492	520.00	0.00000
22	0.010	0.00230978	0.1020492	520.00	0.00000
23	0.010	0.00230978	0.1020492	520.00	0.00000
24	0.010	0.00230978	0.1020492	520.00	0.00000
25	0.010	0.00230978	0.1020492	520.00	0.00000
26	0.010	0.00230978	0.1020492	520.00	0.00000
27	0.010	0.00230978	0.1020492	520.00	0.00000
28	0.010	0.00230978	0.1020492	520.00	0.00000
29	0.010	0.00230978	0.1020492	520.00	0.00000
30	0.010	0.00230978	0.1020492	520.00	0.00000
31	0.010	0.00230978	0.1020492	520.00	0.00000
32	0.010	0.00230978	0.1020492	520.00	0.00000
33	0.010	0.00230978	0.1020492	520.00	0.00000
34	0.010	0.00230978	0.1020492	520.00	0.00000
35	0.010	0.00230978	0.1020492	520.00	0.00000
36	0.010	0.00230978	0.1020492	520.00	0.00000
37	0.010	0.00230978	0.1020492	520.00	0.00000
38	0.010	0.00230978	0.1020492	520.00	0.00000
39	0.010	0.00230978	0.1020492	520.00	0.00000
40	0.010	0.00230978	0.1020492	520.00	0.00000
41	0.010	0.00230978	0.1020492	520.00	0.00000
42	0.010	0.00230978	0.1020492	520.00	0.00000
43	0.010	0.00230978	0.1020492	520.00	0.00000
44	0.010	0.00230978	0.1020492	520.00	0.00000
45	0.010	0.00230978	0.1020492	520.00	0.00000
46	0.010	0.00230978	0.1020492	520.00	0.00000
47	0.010	0.00230978	0.1020492	520.00	0.00000
48	0.010	0.00230978	0.1020492	520.00	0.00000
49	0.010	0.00230978	0.1020492	520.00	0.00000
50	0.010	0.00230978	0.1020492	520.00	0.00000
51	0.010	0.00230978	0.1020492	520.00	0.00000
52	0.010	0.00230978	0.1020492	520.00	0.00000
53	0.010	0.00230978	0.1020492	520.00	0.00000
54	0.010	0.00230978	0.1020492	520.00	0.00000
55	0.010	0.00230978	0.1020492	520.00	0.00000
56	0.010	0.00230978	0.1020492	520.00	0.00000
57	0.010	0.00230978	0.1020492	520.00	0.00000
58	0.010	0.00230978	0.1020492	520.00	0.00000
59	0.010	0.00230978	0.1020492	520.00	0.00000
60	0.010	0.00230978	0.1020492	520.00	0.00000
61	0.010	0.00230978	0.1020492	520.00	0.00000
62	0.010	0.00230978	0.1020492	520.00	0.00000
63	0.010	0.00230978	0.1020492	520.00	0.00000
64	0.010	0.00230978	0.1020492	520.00	0.00000
65	0.010	0.00230978	0.1020492	520.00	0.00000
66	0.010	0.00230978	0.1020492	520.00	0.00000
67	0.010	0.00230978	0.1020492	520.00	0.00000
68	0.010	0.00230978	0.1020492	520.00	0.00000
69	0.010	0.00230978	0.1020492	520.00	0.00000
70	0.010	0.00230978	0.1020492	520.00	0.00000

ORIGINAL PAGE IS
OF POOR QUALITY

207	19.700	0.00230444	0.0055962	520.00	0.70000
208	19.700	0.00230473	0.0055962	520.00	0.71000
209	19.700	0.00230502	0.0055962	520.00	0.72000
210	19.700	0.00230532	0.0055962	520.00	0.73000
211	19.700	0.00230561	0.0055962	520.00	0.74000
212	19.700	0.00230591	0.0055962	520.00	0.75000
213	19.700	0.00230621	0.0055962	520.00	0.76000
214	19.700	0.00230651	0.0055962	520.00	0.77000
215	19.700	0.00230681	0.0055962	520.00	0.78000
216	19.700	0.00230711	0.0055962	520.00	0.79000
217	19.700	0.00230741	0.0055962	520.00	0.80000
218	19.700	0.00230771	0.0055962	520.00	0.81000
219	19.700	0.00230801	0.0055962	520.00	0.82000
220	19.700	0.00230831	0.0055962	520.00	0.83000
221	19.700	0.00230861	0.0055962	520.00	0.84000
222	19.700	0.00230891	0.0055962	520.00	0.85000
223	19.700	0.00230921	0.0055962	520.00	0.86000
224	19.700	0.00230951	0.0055962	520.00	0.87000
225	19.700	0.00230981	0.0055962	520.00	0.88000
226	19.700	0.00231011	0.0055962	520.00	0.89000
227	19.700	0.00231041	0.0055962	520.00	0.90000
228	19.700	0.00231071	0.0055962	520.00	0.91000
229	19.700	0.00231101	0.0055962	520.00	0.92000
230	19.700	0.00231131	0.0055962	520.00	0.93000
231	19.700	0.00231161	0.0055962	520.00	0.94000
232	19.700	0.00231191	0.0055962	520.00	0.95000
233	19.700	0.00231221	0.0055962	520.00	0.96000
234	19.700	0.00231251	0.0055962	520.00	0.97000
235	19.700	0.00231281	0.0055962	520.00	0.98000
236	19.700	0.00231311	0.0055962	520.00	0.99000
237	19.700	0.00231341	0.0055962	520.00	1.00000
238	19.700	0.00231371	0.0055962	520.00	1.01000
239	19.700	0.00231401	0.0055962	520.00	1.02000
240	19.700	0.00231431	0.0055962	520.00	1.03000
241	19.700	0.00231461	0.0055962	520.00	1.04000
242	19.700	0.00231491	0.0055962	520.00	1.05000
243	19.700	0.00231521	0.0055962	520.00	1.06000
244	19.700	0.00231551	0.0055962	520.00	1.07000
245	19.700	0.00231581	0.0055962	520.00	1.08000
246	19.700	0.00231611	0.0055962	520.00	1.09000
247	19.700	0.00231641	0.0055962	520.00	1.10000
248	19.700	0.00231671	0.0055962	520.00	1.11000
249	19.700	0.00231701	0.0055962	520.00	1.12000
250	19.700	0.00231731	0.0055962	520.00	1.13000
251	19.700	0.00231761	0.0055962	520.00	1.14000
252	19.700	0.00231791	0.0055962	520.00	1.15000
253	19.700	0.00231821	0.0055962	520.00	1.16000
254	19.700	0.00231851	0.0055962	520.00	1.17000
255	19.700	0.00231881	0.0055962	520.00	1.18000
256	19.700	0.00231911	0.0055962	520.00	1.19000
257	19.700	0.00231941	0.0055962	520.00	1.20000
258	19.700	0.00231971	0.0055962	520.00	1.21000
259	19.700	0.00232001	0.0055962	520.00	1.22000
260	19.700	0.00232031	0.0055962	520.00	1.23000
261	19.700	0.00232061	0.0055962	520.00	1.24000
262	19.700	0.00232091	0.0055962	520.00	1.25000
263	19.700	0.00232121	0.0055962	520.00	1.26000
264	19.700	0.00232151	0.0055962	520.00	1.27000
265	19.700	0.00232181	0.0055962	520.00	1.28000
266	19.700	0.00232211	0.0055962	520.00	1.29000
267	19.700	0.00232241	0.0055962	520.00	1.30000
268	19.700	0.00232271	0.0055962	520.00	1.31000
269	19.700	0.00232301	0.0055962	520.00	1.32000
270	19.700	0.00232331	0.0055962	520.00	1.33000
271	19.700	0.00232361	0.0055962	520.00	1.34000
272	19.700	0.00232391	0.0055962	520.00	1.35000
273	19.700	0.00232421	0.0055962	520.00	1.36000
274	19.700	0.00232451	0.0055962	520.00	1.37000
275	19.700	0.00232481	0.0055962	520.00	1.38000
276	19.700	0.00232511	0.0055962	520.00	1.39000
277	19.700	0.00232541	0.0055962	520.00	1.40000
278	19.700	0.00232571	0.0055962	520.00	1.41000
279	19.700	0.00232601	0.0055962	520.00	1.42000
280	19.700	0.00232631	0.0055962	520.00	1.43000
281	19.700	0.00232661	0.0055962	520.00	1.44000
282	19.700	0.00232691	0.0055962	520.00	1.45000
283	19.700	0.00232721	0.0055962	520.00	1.46000
284	19.700	0.00232751	0.0055962	520.00	1.47000
285	19.700	0.00232781	0.0055962	520.00	1.48000
286	19.700	0.00232811	0.0055962	520.00	1.49000
287	19.700	0.00232841	0.0055962	520.00	1.50000
288	19.700	0.00232871	0.0055962	520.00	1.51000
289	19.700	0.00232901	0.0055962	520.00	1.52000
290	19.700	0.00232931	0.0055962	520.00	1.53000
291	19.700	0.00232961	0.0055962	520.00	1.54000
292	19.700	0.00232991	0.0055962	520.00	1.55000
293	19.700	0.00233021	0.0055962	520.00	1.56000
294	19.700	0.00233051	0.0055962	520.00	1.57000
295	19.700	0.00233081	0.0055962	520.00	1.58000
296	19.700	0.00233111	0.0055962	520.00	1.59000
297	19.700	0.00233141	0.0055962	520.00	1.60000
298	19.700	0.00233171	0.0055962	520.00	1.61000
299	19.700	0.00233201	0.0055962	520.00	1.62000
300	19.700	0.00233231	0.0055962	520.00	1.63000

DATA POINT	TIME (SEC)	ANGLE-OF-ATTACK RATE (RADIAN/SEC)	ALTITUDE (FT)	ALTITUDE RATE (FT/SEC)	ALT. ACCEL. (FT/SEC**2)	VERT. ACCEL. (FT/SEC**2)	ELEV. DEFLECT. (RADIAN)
1	0.0	-0.003601021	1000.00	0.01	0.00	0.0	0.0
2	0.010	-0.003770723	1000.00	0.02	0.01	0.0	0.0
3	0.020	-0.003940425	1000.00	0.03	0.02	0.0	0.0
4	0.030	-0.004110127	1000.00	0.04	0.03	0.0	0.0
5	0.040	-0.004279829	1000.00	0.05	0.04	0.0	0.0
6	0.050	-0.004449531	1000.00	0.06	0.05	0.0	0.0
7	0.060	-0.004619233	1000.00	0.07	0.06	0.0	0.0
8	0.070	-0.004788935	1000.00	0.08	0.07	0.0	0.0
9	0.080	-0.004958637	1000.00	0.09	0.08	0.0	0.0
10	0.090	-0.005128339	1000.00	0.10	0.09	0.0	0.0
11	0.100	-0.005298041	1000.00	0.11	0.10	0.0	0.0
12	0.110	-0.005467743	1000.00	0.12	0.11	0.0	0.0
13	0.120	-0.005637445	1000.00	0.13	0.12	0.0	0.0
14	0.130	-0.005807147	1000.00	0.14	0.13	0.0	0.0
15	0.140	-0.005976849	1000.00	0.15	0.14	0.0	0.0
16	0.150	-0.006146551	1000.00	0.16	0.15	0.0	0.0
17	0.160	-0.006316253	1000.00	0.17	0.16	0.0	0.0
18	0.170	-0.006485955	1000.00	0.18	0.17	0.0	0.0
19	0.180	-0.006655657	1000.00	0.19	0.18	0.0	0.0
20	0.190	-0.006825359	1000.00	0.20	0.19	0.0	0.0
21	0.200	-0.006995061	1000.00	0.21	0.20	0.0	0.0
22	0.210	-0.007164763	1000.00	0.22	0.21	0.0	0.0
23	0.220	-0.007334465	1000.00	0.23	0.22	0.0	0.0
24	0.230	-0.007504167	1000.00	0.24	0.23	0.0	0.0
25	0.240	-0.007673869	1000.00	0.25	0.24	0.0	0.0
26	0.250	-0.007843571	1000.00	0.26	0.25	0.0	0.0
27	0.260	-0.008013273	1000.00	0.27	0.26	0.0	0.0
28	0.270	-0.008182975	1000.00	0.28	0.27	0.0	0.0
29	0.280	-0.008352677	1000.00	0.29	0.28	0.0	0.0
30	0.290	-0.008522379	1000.00	0.30	0.29	0.0	0.0
31	0.300	-0.008692081	1000.00	0.31	0.30	0.0	0.0
32	0.310	-0.008861783	1000.00	0.32	0.31	0.0	0.0
33	0.320	-0.009031485	1000.00	0.33	0.32	0.0	0.0

ORIGINAL PAGE IS
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164	15.290	-0.0000000000	1200.00	-14.72	-0.00	0.00	0.00
165	15.300	-0.0000000000	1199.99	-14.82	-0.02	0.00	0.00
166	15.310	-0.0000000000	1199.98	-14.92	-0.04	0.00	0.00
167	15.320	-0.0000000000	1199.97	-15.02	-0.06	0.00	0.00
168	15.330	-0.0000000000	1199.96	-15.12	-0.08	0.00	0.00
169	15.340	-0.0000000000	1199.95	-15.22	-0.10	0.00	0.00
170	15.350	-0.0000000000	1199.94	-15.32	-0.12	0.00	0.00
171	15.360	-0.0000000000	1199.93	-15.42	-0.14	0.00	0.00
172	15.370	-0.0000000000	1199.92	-15.52	-0.16	0.00	0.00
173	15.380	-0.0000000000	1199.91	-15.62	-0.18	0.00	0.00
174	15.390	-0.0000000000	1199.90	-15.72	-0.20	0.00	0.00
175	15.400	-0.0000000000	1199.89	-15.82	-0.22	0.00	0.00
176	15.410	-0.0000000000	1199.88	-15.92	-0.24	0.00	0.00
177	15.420	-0.0000000000	1199.87	-16.02	-0.26	0.00	0.00
178	15.430	-0.0000000000	1199.86	-16.12	-0.28	0.00	0.00
179	15.440	-0.0000000000	1199.85	-16.22	-0.30	0.00	0.00
180	15.450	-0.0000000000	1199.84	-16.32	-0.32	0.00	0.00
181	15.460	-0.0000000000	1199.83	-16.42	-0.34	0.00	0.00
182	15.470	-0.0000000000	1199.82	-16.52	-0.36	0.00	0.00
183	15.480	-0.0000000000	1199.81	-16.62	-0.38	0.00	0.00
184	15.490	-0.0000000000	1199.80	-16.72	-0.40	0.00	0.00
185	15.500	-0.0000000000	1199.79	-16.82	-0.42	0.00	0.00
186	15.510	-0.0000000000	1199.78	-16.92	-0.44	0.00	0.00
187	15.520	-0.0000000000	1199.77	-17.02	-0.46	0.00	0.00
188	15.530	-0.0000000000	1199.76	-17.12	-0.48	0.00	0.00
189	15.540	-0.0000000000	1199.75	-17.22	-0.50	0.00	0.00
190	15.550	-0.0000000000	1199.74	-17.32	-0.52	0.00	0.00
191	15.560	-0.0000000000	1199.73	-17.42	-0.54	0.00	0.00
192	15.570	-0.0000000000	1199.72	-17.52	-0.56	0.00	0.00
193	15.580	-0.0000000000	1199.71	-17.62	-0.58	0.00	0.00
194	15.590	-0.0000000000	1199.70	-17.72	-0.60	0.00	0.00
195	15.600	-0.0000000000	1199.69	-17.82	-0.62	0.00	0.00
196	15.610	-0.0000000000	1199.68	-17.92	-0.64	0.00	0.00
197	15.620	-0.0000000000	1199.67	-18.02	-0.66	0.00	0.00
198	15.630	-0.0000000000	1199.66	-18.12	-0.68	0.00	0.00
199	15.640	-0.0000000000	1199.65	-18.22	-0.70	0.00	0.00
200	15.650	-0.0000000000	1199.64	-18.32	-0.72	0.00	0.00
201	15.660	-0.0000000000	1199.63	-18.42	-0.74	0.00	0.00
202	15.670	-0.0000000000	1199.62	-18.52	-0.76	0.00	0.00
203	15.680	-0.0000000000	1199.61	-18.62	-0.78	0.00	0.00
204	15.690	-0.0000000000	1199.60	-18.72	-0.80	0.00	0.00
205	15.700	-0.0000000000	1199.59	-18.82	-0.82	0.00	0.00
206	15.710	-0.0000000000	1199.58	-18.92	-0.84	0.00	0.00
207	15.720	-0.0000000000	1199.57	-19.02	-0.86	0.00	0.00
208	15.730	-0.0000000000	1199.56	-19.12	-0.88	0.00	0.00
209	15.740	-0.0000000000	1199.55	-19.22	-0.90	0.00	0.00
210	15.750	-0.0000000000	1199.54	-19.32	-0.92	0.00	0.00
211	15.760	-0.0000000000	1199.53	-19.42	-0.94	0.00	0.00
212	15.770	-0.0000000000	1199.52	-19.52	-0.96	0.00	0.00
213	15.780	-0.0000000000	1199.51	-19.62	-0.98	0.00	0.00
214	15.790	-0.0000000000	1199.50	-19.72	-1.00	0.00	0.00
215	15.800	-0.0000000000	1199.49	-19.82	-1.02	0.00	0.00
216	15.810	-0.0000000000	1199.48	-19.92	-1.04	0.00	0.00
217	15.820	-0.0000000000	1199.47	-20.02	-1.06	0.00	0.00
218	15.830	-0.0000000000	1199.46	-20.12	-1.08	0.00	0.00
219	15.840	-0.0000000000	1199.45	-20.22	-1.10	0.00	0.00
220	15.850	-0.0000000000	1199.44	-20.32	-1.12	0.00	0.00
221	15.860	-0.0000000000	1199.43	-20.42	-1.14	0.00	0.00
222	15.870	-0.0000000000	1199.42	-20.52	-1.16	0.00	0.00
223	15.880	-0.0000000000	1199.41	-20.62	-1.18	0.00	0.00
224	15.890	-0.0000000000	1199.40	-20.72	-1.20	0.00	0.00
225	15.900	-0.0000000000	1199.39	-20.82	-1.22	0.00	0.00
226	15.910	-0.0000000000	1199.38	-20.92	-1.24	0.00	0.00
227	15.920	-0.0000000000	1199.37	-21.02	-1.26	0.00	0.00
228	15.930	-0.0000000000	1199.36	-21.12	-1.28	0.00	0.00
229	15.940	-0.0000000000	1199.35	-21.22	-1.30	0.00	0.00
230	15.950	-0.0000000000	1199.34	-21.32	-1.32	0.00	0.00
231	15.960	-0.0000000000	1199.33	-21.42	-1.34	0.00	0.00
232	15.970	-0.0000000000	1199.32	-21.52	-1.36	0.00	0.00
233	15.980	-0.0000000000	1199.31	-21.62	-1.38	0.00	0.00
234	15.990	-0.0000000000	1199.30	-21.72	-1.40	0.00	0.00
235	16.000	-0.0000000000	1199.29	-21.82	-1.42	0.00	0.00
236	16.010	-0.0000000000	1199.28	-21.92	-1.44	0.00	0.00
237	16.020	-0.0000000000	1199.27	-22.02	-1.46	0.00	0.00
238	16.030	-0.0000000000	1199.26	-22.12	-1.48	0.00	0.00
239	16.040	-0.0000000000	1199.25	-22.22	-1.50	0.00	0.00
240	16.050	-0.0000000000	1199.24	-22.32	-1.52	0.00	0.00
241	16.060	-0.0000000000	1199.23	-22.42	-1.54	0.00	0.00
242	16.070	-0.0000000000	1199.22	-22.52	-1.56	0.00	0.00
243	16.080	-0.0000000000	1199.21	-22.62	-1.58	0.00	0.00
244	16.090	-0.0000000000	1199.20	-22.72	-1.60	0.00	0.00
245	16.100	-0.0000000000	1199.19	-22.82	-1.62	0.00	0.00
246	16.110	-0.0000000000	1199.18	-22.92	-1.64	0.00	0.00
247	16.120	-0.0000000000	1199.17	-23.02	-1.66	0.00	0.00
248	16.130	-0.0000000000	1199.16	-23.12	-1.68	0.00	0.00
249	16.140	-0.0000000000	1199.15	-23.22	-1.70	0.00	0.00
250	16.150	-0.0000000000	1199.14	-23.32	-1.72	0.00	0.00
251	16.160	-0.0000000000	1199.13	-23.42	-1.74	0.00	0.00
252	16.170	-0.0000000000	1199.12	-23.52	-1.76	0.00	0.00
253	16.180	-0.0000000000	1199.11	-23.62	-1.78	0.00	0.00
254	16.190	-0.0000000000	1199.10	-23.72	-1.80	0.00	0.00
255	16.200	-0.0000000000	1199.09	-23.82	-1.82	0.00	0.00
256	16.210	-0.0000000000	1199.08	-23.92	-1.84	0.00	0.00
257	16.220	-0.0000000000	1199.07	-24.02	-1.86	0.00	0.00
258	16.230	-0.0000000000	1199.06	-24.12	-1.88	0.00	0.00
259	16.240	-0.0000000000	1199.05	-24.22	-1.90	0.00	0.00
260	16.250	-0.0000000000	1199.04	-24.32	-1.92	0.00	0.00
261	16.260	-0.0000000000	1199.03	-24.42	-1.94	0.00	0.00
262	16.270	-0.0000000000	1199.02	-24.52	-1.96	0.00	0.00
263	16.280	-0.0000000000	1199.01	-24.62	-1.98	0.00	0.00
264	16.290	-0.0000000000	1199.00	-24.72	-2.00	0.00	0.00
265	16.300	-0.0000000000	1198.99	-24.82	-2.02	0.00	0.00
266	16.310	-0.0000000000	1198.98	-24.92	-2.04	0.00	0.00
267	16.320	-0.0000000000	1198.97	-25.02	-2.06	0.00	0.00
268	16.330	-0.0000000000	1198.96	-25.12	-2.08	0.00	0.00
269	16.340	-0.0000000000	1198.95	-25.22	-2.10	0.00	0.00
270	16.350	-0.0000000000	1198.94	-25.32	-2.12	0.00	0.00
271	16.360	-0.0000000000	1198.93	-25.42	-2.14	0.00	0.00
272	16.370	-0.0000000000	1198.92	-25.52	-2.16	0.00	0.00
273	16.380	-0.0000000000	1198.91	-25.62	-2.18	0.00	0.00
274	16.390	-0.0000000000	1198.90	-25.72	-2.20	0.00	0.00
275	16.400	-0.0000000000	1198.89	-25.82	-2.22	0.00	0.00
276	16.410	-0.0000000000	1198.88	-25.92	-2.24	0.00	0.00
277	16.420	-0.0000000000	1198.87	-26.02	-2.26	0.00	0.00
278	16.430	-0.0000000000	1198.86	-26.12	-2.28	0.00	0.00
279	16.440	-0.0000000000	1198.85	-26.22	-2.30	0.00	0.00
280	16.450	-0.0000000000	1198.84	-26.32	-2.32	0.00	0.00
281	16.460	-0.0000000000	1198.83	-26.42	-2.34	0.00	0.00
282	16.470	-0.0000000000	1198.82	-26.52	-2.36	0.00	0.00
283	16.480	-0.0000000000	1198.81	-26.62	-2.38	0.00	0.00
284	16.490	-0.0000000000	1198.80	-26.72	-2.40	0.00	0.00
285	16.500	-0.0000000000	1198.79	-26.82	-2.42	0.00	0.00
286	16.510	-0.0000000000	1198.78	-26.92	-2.44	0.00	0.00
287	16.520	-0.0000000000	1198.77	-27.02	-2.46	0.00	0.00
288	16.530	-0.0000000000	1198.76	-27.12	-2.48	0.00	0.00
289	16.540	-0.0000000000	1198.75	-27.22	-2.50	0.00	0.00
290	16.550	-0.0000000000	1198.74	-27.32	-2.52	0.00	0.00
291	16.560	-0.0000000000	1198.73	-27.42	-2.54	0.00	0.00
292	16.570	-0.0000000000	1198.72	-27.52	-2.56	0.00	0.00
293	16.580	-0.0000000000	1198.71	-27.62	-2.58	0.00	0.00
294	16.590	-0.0000000000	1198.70	-27.72	-2.60	0.00	0.00
295	16.600	-0.0000000000	1198.69	-27.82	-2.62	0.00	0.00
296	16.610	-0.0000000000	1198.68	-27.92	-2.64	0.00	0.00
297	16.620	-0.0000000000	1198.67	-28.02	-2.66	0.00	0.00

2.179000	01	5.673730	02	2.119810	02	-2.068880	01	5.647490	02	3.814510	01	3.988660	02	3.999120	03	1.740600	05	8.216470	05
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2.197000	01	5.526250	02	2.131850	02	-2.013500	01	5.578750	02	3.792530	01	3.978900	02	3.999120	03	1.742560	05	8.305880	05
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2.209000	01	5.427870	02	2.143890	02	-1.958100	01	5.509990	02	3.769530	01	3.969140	02	3.999120	03	1.744520	05	8.395400	05
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2.221000	01	5.329490	02	2.155930	02	-1.902700	01	5.441230	02	3.746030	01	3.959380	02	3.999120	03	1.746480	05	8.484920	05
2.227000	01	5.280300	02	2.161950	02	-1.875000	01	5.406850	02	3.734280	01	3.954500	02	3.999120	03	1.747460	05	8.529680	05
2.233000	01	5.231110	02	2.167970	02	-1.847300	01	5.372470	02	3.722530	01	3.949620	02	3.999120	03	1.748440	05	8.574440	05
2.239000	01	5.181920	02	2.173990	02	-1.819600	01	5.338090	02	3.710780	01	3.944740	02	3.999120	03	1.749420	05	8.619200	05
2.245000	01	5.132730	02	2.179990	02	-1.791900	01	5.303710	02	3.698300	01	3.939860	02	3.999120	03	1.750400	05	8.663960	05
2.251000	01	5.083540	02	2.186010	02	-1.764200	01	5.269330	02	3.686420	01	3.934980	02	3.999120	03	1.751380	05	8.708720	05
2.257000	01	5.034350	02	2.192010	02	-1.736500	01	5.234950	02	3.674540	01	3.930100	02	3.999120	03	1.752360	05	8.753480	05
2.263000	01	4.985160	02	2.198010	02	-1.708800	01	5.200570	02	3.662660	01	3.925220	02	3.999120	03	1.753340	05	8.798240	05
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2.377000	01	4.050260	02	2.312010	02	-1.182500	01	4.547350	02	3.436940	01	3.832500	02	3.999120	03	1.771960	05	9.648680	05
2.383000	01	4.001050	02	2.318010	02	-1.154800	01	4.512970	02	3.425060	01	3.827620	02	3.999120	03	1.772940	05	9.693440	05
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2.413000	01	3.755000	02	2.348010	02	-1.016300	01	4.341070	02	3.365660	01	3.803220	02	3.999120	03	1.777840	05	9.917240	05
2.419000	01	3.705790	02	2.354010	02	-0.988600	01	4.306690	02	3.353780	01	3.798340	02	3.999120	03	1.778820	05	9.962000	05
2.425000	01	3.656580	02	2.360010	02	-0.960900	01	4.272310	02	3.341900	01	3.793460	02	3.999120	03	1.779800	05	10.006760	05
2.431000	01	3.607370	02	2.366010	02	-0.933200	01	4.237930	02	3.330020	01	3.788580	02	3.999120	03	1.780780	05	10.051520	05
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2.467000	01	3.312110	02	2.402010	02	-0.767000	01	4.031650	02	3.258740	01	3.759300	02	3.999120	03	1.786660	05	10.320080	05
2.473000	01	3.262900	02	2.408010	02	-0.739300	01	3.997270	02	3.246860	01	3.754420	02	3.999120	03	1.787640	05	10.364840	05
2.479000	01	3.213690	02	2.414010	02	-0.711600	01	3.962890	02	3.234980	01	3.749540	02	3.999120	03	1.788620	05	10.409600	05
2.485000	01	3.164480	02	2.420010	02	-0.683900	01	3.928510	02	3.223100	01	3.744660	02	3.999120	03	1.789600	05	10.454360	05
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2.503000	01	3.016850	02	2.438010	02	-0.600800	01	3.825370	02	3.187460	01	3.730020	02	3.999120	03	1.792540	05	10.588640	05
2.509000	01	2.967640	02	2.444010	02	-0.573100	01	3.790990	02	3.175580	01	3.725140	02	3.999120	03	1.793520	05	10.633400	05
2.515000	01	2.918430	02	2.450010	02	-0.545400	01	3.756610	02	3.163700	01	3.720260	02	3.999120	03	1.794500	05	10.678160	05
2.521000	01	2.869220	02	2.456010	02	-0.517700	01	3.722230	02	3.151820	01	3.715380	02	3.999120	03	1.795480	05	10.722920	05
2.527000	01	2.819990	02	2.462010	02	-0.490000	01	3.687850	02	3.139940	01	3.710500	02	3.999120	03	1.796460	05	10.767680	05
2.533000	01	2.770780	02	2.468010	02	-0.462300	01	3.653470	02	3.128060	01	3.705620	02	3.999120	03	1.797440	05	10.812440	05
2.539000	01	2.721570																	

[illegible]

720

722

1.757000 J	1.139172 J	2.252530 J	1.4659840 J	7.367310 J	0.4565900 J	3.483500 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.151810 J	2.253630 J	1.467990 J	7.373250 J	0.4623700 J	3.473370 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.162290 J	2.254990 J	1.469350 J	7.379200 J	0.4681400 J	3.468810 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.171810 J	2.256510 J	1.470910 J	7.385150 J	0.4739100 J	3.464280 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.181330 J	2.258030 J	1.472470 J	7.391100 J	0.4796800 J	3.459750 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.190850 J	2.259550 J	1.474030 J	7.397050 J	0.4854500 J	3.455220 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.200370 J	2.261070 J	1.475590 J	7.403000 J	0.4912200 J	3.450690 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.209890 J	2.262590 J	1.477150 J	7.408950 J	0.4969900 J	3.446160 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.219410 J	2.264110 J	1.478710 J	7.414900 J	0.5027600 J	3.441630 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.228930 J	2.265630 J	1.480270 J	7.420850 J	0.5085300 J	3.437100 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.238450 J	2.267150 J	1.481830 J	7.426800 J	0.5143000 J	3.432570 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.247970 J	2.268670 J	1.483390 J	7.432750 J	0.5200700 J	3.428040 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.257490 J	2.270190 J	1.484950 J	7.438700 J	0.5258400 J	3.423510 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.267010 J	2.271710 J	1.486510 J	7.444650 J	0.5316100 J	3.418980 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.276530 J	2.273230 J	1.488070 J	7.450600 J	0.5373800 J	3.414450 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.286050 J	2.274750 J	1.489630 J	7.456550 J	0.5431500 J	3.409920 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.295570 J	2.276270 J	1.491190 J	7.462500 J	0.5489200 J	3.405390 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.305090 J	2.277790 J	1.492750 J	7.468450 J	0.5546900 J	3.400860 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.314610 J	2.279310 J	1.494310 J	7.474400 J	0.5604600 J	3.396330 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.324130 J	2.280830 J	1.495870 J	7.480350 J	0.5662300 J	3.391800 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.333650 J	2.282350 J	1.497430 J	7.486300 J	0.5720000 J	3.387270 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.343170 J	2.283870 J	1.498990 J	7.492250 J	0.5777700 J	3.382740 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.352690 J	2.285390 J	1.500550 J	7.498200 J	0.5835400 J	3.378210 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.362210 J	2.286910 J	1.502110 J	7.504150 J	0.5893100 J	3.373680 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.371730 J	2.288430 J	1.503670 J	7.510100 J	0.5950800 J	3.369150 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.381250 J	2.289950 J	1.505230 J	7.516050 J	0.6008500 J	3.364620 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.390770 J	2.291470 J	1.506790 J	7.522000 J	0.6066200 J	3.360090 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.400290 J	2.292990 J	1.508350 J	7.527950 J	0.6123900 J	3.355560 J	3.569300 J	0.999000 J	0.999000 J
1.757000 J	1.409810 J	2							

CCST FUNCTION (J) = 2.366417070W610E5UD-02

08TH: ALTITUDE TOLERANCE = 0.52296309264130-02
FLIGHT-PATH-ANGLE TOLERANCE = 0.03776780758660-09
FLIGHT-PATH-ANGLE-DERIVATIVE TOLERANCE = 0.00385254472860-10
WEIGHT TOLERANCE = 0.0
ENERGY TOLERANCE = 0.05229671017420-02
ANGLE-OF-ATTACK TOLERANCE = 0.0

PREVIOUS COEFFICIENT

LABORATORY

NEW EFFICIENT

0.207314143100D 03	+ 1.000 0.0	= 0.207314143100D 03	(FROZEN)
0.0	+ 1.000 0.0	= 0.0	(FROZEN)
0.1120042000000D 04	+ 1.000 0.0	= 0.1120042000000D 04	(FROZEN)
-0.217016371200D 01	+ 1.000 0.0	= -0.217016371200D 01	(FROZEN)
0.0	+ 1.000 0.0	= 0.0	(FROZEN)

(FROZEN)

ITERATION 2

724

ORIGINAL PAGE IS
OF POOR QUALITY

1.646400 U	1.174820 J2	1.373180-01	1.149800-01	7.269800-02	3.999610 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.380890 J2	1.149840-01	7.269800-02	3.999720 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.388600 J4	1.149880-01	7.269800-02	3.999750 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.396310 J2	1.149920-01	7.269800-02	3.999780 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.404020 J2	1.149960-01	7.269800-02	3.999810 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.411730 J2	1.149990-01	7.269800-02	3.999840 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.419440 J2	1.150020-01	7.269800-02	3.999870 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.427150 J2	1.150050-01	7.269800-02	3.999900 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.434860 J2	1.150080-01	7.269800-02	3.999930 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.442570 J2	1.150110-01	7.269800-02	3.999960 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.450280 J2	1.150140-01	7.269800-02	3.999990 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.457990 J2	1.150170-01	7.269800-02	4.000020 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.465700 J2	1.150200-01	7.269800-02	4.000050 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.473410 J2	1.150230-01	7.269800-02	4.000080 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.481120 J2	1.150260-01	7.269800-02	4.000110 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.488830 J2	1.150290-01	7.269800-02	4.000140 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.496540 J2	1.150320-01	7.269800-02	4.000170 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.504250 J2	1.150350-01	7.269800-02	4.000200 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.511960 J2	1.150380-01	7.269800-02	4.000230 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.519670 J2	1.150410-01	7.269800-02	4.000260 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.527380 J2	1.150440-01	7.269800-02	4.000290 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.535090 J2	1.150470-01	7.269800-02	4.000320 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.542800 J2	1.150500-01	7.269800-02	4.000350 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.550510 J2	1.150530-01	7.269800-02	4.000380 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.558220 J2	1.150560-01	7.269800-02	4.000410 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.565930 J2	1.150590-01	7.269800-02	4.000440 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.573640 J2	1.150620-01	7.269800-02	4.000470 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.581350 J2	1.150650-01	7.269800-02	4.000500 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.589060 J2	1.150680-01	7.269800-02	4.000530 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.596770 J2	1.150710-01	7.269800-02	4.000560 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.604480 J2	1.150740-01	7.269800-02	4.000590 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.612190 J2	1.150770-01	7.269800-02	4.000620 J3	1.822690 J8	1.628770 J9
1.646400 U	1.174820 J2	1.619900 J2	1.150800-01	7.269800-02	4.000650 J3		

```
CEST FUNCTION (J) = 3.0616855296001260D-04
@TIME
ALTITUDE TOLERANCE = 0.000171902440JD-04
FLIGHT-PATH-ANGLE TOLERANCE = 0.050000000000000000-10
FLIGHT-PATH-ANGLE-UNSTABILITY TOLERANCE = 0.001236000000000000-10
HEIGHT TOLERANCE = 0.00
ENERGY TOLERANCE = 0.00012773383550D-04
ANGLE-OF-ATTACK TOLERANCE = 0.00
```

PREVIOUS COEFFICIENT **IS JOUELTA**

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J=27751614310300 U3 1:1000 U=0 0:287301614310300 05 (PROZEN)
1:1000 U=0 U=0 0:0
J=27751620820000 U3 1:1000 U=0 U=1126677777777777 05 (PROZEN)
U=17016371203030 J1 1:1000 U=0 U=17016371203030 01 (PROZEN)
U=0 U=0 0:0
J=27751637620300-J1 1:1000 U=0 U=36102572720300 05 (PROZEN)
U=1000 U=0 U=0 0:0
J=27751643920000 U1 1:1000 U=0 U=1286677777777777 01 (PROZEN)
U=0 U=0 U=0 0:0
J=277523175876100 U3 1:1000 U=0 U=17587610300000 04
U=7776677575430100 J1 1:1000 U=0 U=7776677575430100 05
U=1000 U=0 U=0 0:0
J=2775235776160000 U3 1:1000 U=0 U=7776677576160000 05
U=1000 U=0 U=0 0:0
J=2775235776160000 U3 1:1000 U=0 U=7776677576160000 05
U=1000 U=0 U=0 0:0

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FLIGHT PATH TRAJECTORY PREDICTION

ITERATION 0

726

[illegible]

728

730

[illegible]

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CUST FUNCTION (J) = 2.983876435+23507-02
ETH1:
  ALTITUDE TOLERANCE = 0.0008091177564D-02
  FLIGHT-PATH-ANGLE TOLERANCE = 0.10566617724570-08
  FLIGHT-PATH-ANGLE-DERIVATIVE TOLERANCE = 0.10801379774500-02
  HEIGHT TOLERANCE = 0.0J
  ENERGY TOLERANCE = 0.046D79840238093-02
  ANGLE-OF-ATTACK TOLERANCE = 0.0J

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[illegible]

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U=2741514113105 05  + 1:000 J=0      = 274735141131005 05  (FROZEN)
J=0      + 1:000 U=0      = 0      = 0      (FROZEN)
G=112062500000000 00  + 1:000 G=0      = 0      = 0      (FROZEN)
G=217010312120490 01  + 1:000 G=0      = -J=217013127120930 01  (FROZEN)
J=0      + 1:000 J=0      = 0      = 0      (FROZEN)
U=1010506750300000 01  + 1:000 U=1012060632705 05  (FROZEN)
J=0      + 1:000 J=0      = 0      = 0      (FROZEN)
J=0      + 1:000 J=0      = 0      = 0      (FROZEN)
J=2746812510030 01  + 1:000 J=27468125040 01  (FROZEN)
J=0      + 1:000 U=0      = 0      = 0      (FROZEN)
J=0      + 1:000 J=0      = 0      = 0      (FROZEN)
U=274212288700000 05  + 1:000 U=2742122887000 05  (FROZEN)
G=1178937000000000 00  + 1:000 G=1178937000000 00  (FROZEN)
G=209000777683000 01  + 1:000 G=117833900750 05  (FROZEN)
G=1173000000000000 00  + 1:000 G=1173000000000 00  (FROZEN)

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MODEL SOLUTIONS

.....

ANGLE-OF-ATTACK CONFIDENCE = J.08+90JVO+92030-06
PITCH ANGLE CONFIDENCE = U.10+14J0100000-07

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=====
/8
/8
/8      ****INITIALIZE WING/VAL EXPRESSIONS FOR PLUCK, UNAL CEFICIENT, AND LIFT CEFICIENT
/8
/8
/8      P = P0 + P1*VW + P2*VW**2 + P3*VW**3 + P4*VW**4 + P5*VW**5 + P6*VW**6 + P7*VW**7 + P8*VW**8 + P9*VW**9 + P10*VW**10
/8
/8      CD = CD0 + CD1*P + CD2*P**2 + CD3*P**3 + CD4*P**4
/8
/8      CL = CL0 + CL1*P + CL2*P**2 + CL3*P**3 + CL4*P**4 + CL5*P**5
/8
/8      WHERE:
/8
/8      V = AIRSPEED (FT/SEC)
/8      A = ANGLE OF ATTACK (RADIAN)
/8      W = PITCH RATE (RAD/SEC)
/8
/8      P0 = 0.27517870022 05      C0 = 0.326284184500 J1      CL0 = -3.04972980110E-05
/8      P1 = 0.000000000000      C1 = 0.000000000000      CL1 = 0.000000000000 J1
/8      P2 = 0.000000000000      C2 = 0.000000000000      CL2 = 0.000000000000 J1
/8      P3 = 0.000000000000      C3 = 0.000000000000      CL3 = 0.000000000000 J1
/8      P4 = 0.000000000000      C4 = 0.000000000000      CL4 = 0.000000000000 J1
/8      P5 = 0.000000000000      C5 = 0.000000000000      CL5 = 0.000000000000 J1
/8      P6 = 0.000000000000      C6 = 0.000000000000      CL6 = 0.000000000000 J1
/8      P7 = 0.000000000000      C7 = 0.000000000000      CL7 = 0.000000000000 J1
/8      P8 = 0.000000000000      C8 = 0.000000000000      CL8 = 0.000000000000 J1
/8      P9 = 0.000000000000      C9 = 0.000000000000      CL9 = 0.000000000000 J1
/8      P10 = 0.000000000000      C10 = 0.000000000000      CL10 = 0.000000000000 J1
/8
/8
=====

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732

		TEMPERATURE	= 0.262000 U3 DEG/SEC=H	DWAG COEFFICIENT CL 10	= 0.108150 00
		ACCELERATION	= 0.062900 U1 FT/SEC=H2	ALTIMETER RATE	= 0.161710 06 FT-LB/SEC
		ANGLE-UP-ATTACK RATE	= 0.060820 U3 RADI/SEC	FLIGHT PATH ANGLE	= 0.013300 03 RADI/AN
		HEIGHT	= 0.400000 04 LBP	ALTITUDE	= 0.100000 04 FT
		PITCH ANGLE	= 0.103200 U0 RADI/AN	ALTITUDE RATE	= 0.089720 01 FT/SEC
		PITCH RATE	= 0.074800 U2 RADI/SEC	ALTITUDE-RATE RATE	= 0.003300 01 FT/SEC=H2
		AIRSPEED	= 0.187110 U3 FT/SEC	VERTICAL ACCELERATION	= 0.0
		DENSITY	= 0.200000 U2 SLUG/FT=H3	ELEVATOR DEFLECTION	= 0.0
		ANGLE OF ATTACK	= 0.162800 U3 DEG/SEC=H	LIFT COEFFICIENT CL 10	= 0.102500 01
		TEMPERATURE	= 0.020000 U3 DEG/SEC=H	DWAG COEFFICIENT CL 10	= 0.108170 06
		ACCELERATION	= 0.061000 U1 FT/SEC=H2	POWER AVAILABLE	= 0.147180 06 FT-LB/SEC
		ANGLE-UP-ATTACK RATE	= 0.067600 U3 RADI/SEC	FLIGHT PATH ANGLE	= 0.088200 U3 RADI/AN
		HEIGHT	= 0.400000 04 LBP	ALTITUDE	= 0.100000 04 FT
		PITCH ANGLE	= 0.103400 U0 RADI/AN	ALTITUDE RATE	= 0.074800 01 FT/SEC
		PITCH RATE	= 0.161000 U2 RADI/SEC	ALTITUDE-RATE RATE	= 0.110600 01 FT/SEC=H2
		AIRSPEED	= 0.147200 U3 FT/SEC	VERTICAL ACCELERATION	= 0.0
		DENSITY	= 0.200000 U2 SLUG/FT=H3	ELEVATOR DEFLECTION	= 0.0
		ANGLE OF ATTACK	= 0.162800 U3 DEG/SEC=H	LIFT COEFFICIENT CL 10	= 0.108000 01
		TEMPERATURE	= 0.020000 U3 DEG/SEC=H	DWAG COEFFICIENT CL 10	= 0.108170 06
		ACCELERATION	= 0.060400 U1 FT/SEC=H2	POWER AVAILABLE	= 0.147200 06 FT-LB/SEC
		ANGLE-UP-ATTACK RATE	= 0.066700 U3 RADI/SEC	FLIGHT PATH ANGLE	= 0.072700 U3 RADI/AN
		HEIGHT	= 0.400000 04 LBP	ALTITUDE	= 0.100000 04 FT
		PITCH ANGLE	= 0.103070 00 RADI/AN	ALTITUDE RATE	= 0.102000 01 FT/SEC
		PITCH RATE	= 0.084300 U2 RADI/SEC	ALTITUDE-RATE RATE	= 0.114900 01 FT/SEC=H2
		AIRSPEED	= 0.147200 U3 FT/SEC	VERTICAL ACCELERATION	= 0.0
		DENSITY	= 0.200000 U2 SLUG/FT=H3	ELEVATOR DEFLECTION	= 0.0
		ANGLE OF ATTACK	= 0.162800 U3 DEG/SEC=H	LIFT COEFFICIENT CL 10	= 0.102510 01
		TEMPERATURE	= 0.020000 U3 DEG/SEC=H	DWAG COEFFICIENT CL 10	= 0.108170 06
		ACCELERATION	= 0.059200 U1 FT/SEC=H2	POWER AVAILABLE	= 0.147200 06 FT-LB/SEC
		ANGLE-UP-ATTACK RATE	= 0.068500 U3 RADI/SEC	FLIGHT PATH ANGLE	= 0.082400 U3 RADI/AN
		HEIGHT	= 0.400000 04 LBP	ALTITUDE	= 0.100000 04 FT
		PITCH ANGLE	= 0.103700 00 RADI/AN	ALTITUDE RATE	= 0.103300 01 FT/SEC
		PITCH RATE	= 0.067000 U2 RADI/SEC	ALTITUDE-RATE RATE	= 0.109000 01 FT/SEC=H2
		AIRSPEED	= 0.147300 U3 FT/SEC	VERTICAL ACCELERATION	= 0.0
		DENSITY	= 0.200000 U2 SLUG/FT=H3	ELEVATOR DEFLECTION	= 0.0
		ANGLE OF ATTACK	= 0.162700 U3 DEG/SEC=H	LIFT COEFFICIENT CL 10	= 0.102520 01
		TEMPERATURE	= 0.020000 U3 DEG/SEC=H	DWAG COEFFICIENT CL 10	= 0.108170 06
		ACCELERATION	= 0.057800 U1 FT/SEC=H2	POWER AVAILABLE	= 0.147200 06 FT-LB/SEC
		ANGLE-UP-ATTACK RATE	= 0.064700 U3 RADI/SEC	FLIGHT PATH ANGLE	= 0.080800 02 RADI/AN
		HEIGHT	= 0.400000 04 LBP	ALTITUDE	= 0.100000 04 FT
		PITCH ANGLE	= 0.103610 U0 RADI/AN	ALTITUDE RATE	= 0.020780 01 FT/SEC
		PITCH RATE	= 0.092000 U2 RADI/SEC	ALTITUDE-RATE RATE	= 0.127700 01 FT/SEC=H2
		AIRSPEED	= 0.147970 U3 FT/SEC	VERTICAL ACCELERATION	= 0.0
		DENSITY	= 0.200000 U2 SLUG/FT=H3	ELEVATOR DEFLECTION	= 0.0
		ANGLE OF ATTACK	= 0.162700 U3 DEG/SEC=H	LIFT COEFFICIENT CL 10	= 0.102530 01
		TEMPERATURE	= 0.020000 U3 DEG/SEC=H	DWAG COEFFICIENT CL 10	= 0.108170 06
		ACCELERATION	= 0.058400 U1 FT/SEC=H2	POWER AVAILABLE	= 0.147380 06 FT-LB/SEC
		ANGLE-UP-ATTACK RATE	= 0.031800 U3 RADI/SEC	FLIGHT PATH ANGLE	= 0.137420 U2 RADI/AN
		HEIGHT	= 0.400000 04 LBP	ALTITUDE	= 0.100000 04 FT
		PITCH ANGLE	= 0.104800 00 RADI/AN	ALTITUDE RATE	= 0.255900 01 FT/SEC
		PITCH RATE	= 0.078070 U2 RADI/SEC	ALTITUDE-RATE RATE	= 0.136200 01 FT/SEC=H2
		AIRSPEED	= 0.147700 U3 FT/SEC	VERTICAL ACCELERATION	= 0.0
		DENSITY	= 0.200000 U2 SLUG/FT=H3	ELEVATOR DEFLECTION	= 0.0
		ANGLE OF ATTACK	= 0.162700 U3 DEG/SEC=H	LIFT COEFFICIENT CL 10	= 0.102550 01
		TEMPERATURE	= 0.020000 U3 DEG/SEC=H	DWAG COEFFICIENT CL 10	= 0.108170 06
		ACCELERATION	= 0.052600 U1 FT/SEC=H2	POWER AVAILABLE	= 0.147600 06 FT-LB/SEC

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		TEMPERATURE	* 0.258900-03 DEG/SEC#2	DWAG COEFFICIENT C1	* 0.106870 00		
		ACCELERATION	* 0.239900 01 FT/SEC#2	POWER AVAILABLE	* 0.149800 00	FT-LW/SEC	
		ANGLE-OF-ATTACK RATE	* 0.227130-03 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.226080-01 RADIAN		
		WEIGHT	* 0.209900 04 LBF	ALTITUDE	* 0.011870 34 FT		
		PITCH ANGLE	* 0.133010 00 RADIAN	ALTITUDE RATE	* 0.118000 01 FT/SEC		
		PITCH RATE	* 0.224800-01 RADIAN/SEC	ALTITUDE-RATE RATE	* 0.307400 01 FT/SEC#2		
		AIRSPED	* 0.191300 01 FT/SEC	VERTICAL ACCELERATION	* 0.00	FT/SEC#2	
		DENSITY	* 0.131000-02 SLUG/FT#3	ELEVATION DEFLECTION	* 0.00	RADIAN	
		ANGLE OF ATTACK	* 0.101000 00 RADIAN	LIFT COEFFICIENT CL	* 0.112700 01		
		TEMPERATURE	* 0.270000 03 DEG/SEC#2	DWAG COEFFICIENT C1	* 0.106810 00		
		ACCELERATION	* 0.226310 01 FT/SEC#2	POWER AVAILABLE	* 0.101900 36 FT-LW/SEC		
		ANGLE-OF-ATTACK RATE	* 0.201000-03 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.227090-01 RADIAN		
		WEIGHT	* 0.235500 04 LBF	ALTITUDE	* 0.101030 34 FT		
		PITCH ANGLE	* 0.116000 00 RADIAN	ALTITUDE RATE	* 0.118000 01 FT/SEC		
		PITCH RATE	* 0.227130-01 RADIAN/SEC	ALTITUDE-RATE RATE	* 0.227320 01 FT/SEC#2		
		AIRSPED	* 0.151400 01 FT/SEC	VERTICAL ACCELERATION	* 0.00	FT/SEC#2	
		DENSITY	* 0.230910-02 SLUG/FT#3	ELEVATION DEFLECTION	* 0.00	RADIAN	
		ANGLE OF ATTACK	* 0.101000 00 RADIAN	LIFT COEFFICIENT CL	* 0.106730 01		
		TEMPERATURE	* 0.220400 03 DEG/SEC#2	DWAG COEFFICIENT C1	* 0.106730 00		
		ACCELERATION	* 0.217800 01 FT/SEC#2	POWER AVAILABLE	* 0.105400 36 FT-LW/SEC		
		ANGLE-OF-ATTACK RATE	* 0.203900-03 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.226700-01 RADIAN		
		WEIGHT	* 0.235500 04 LBF	ALTITUDE	* 0.101030 34 FT		
		PITCH ANGLE	* 0.116000 00 RADIAN	ALTITUDE RATE	* 0.118000 01 FT/SEC		
		PITCH RATE	* 0.226200-01 RADIAN/SEC	ALTITUDE-RATE RATE	* 0.227320 01 FT/SEC#2		
		AIRSPED	* 0.151400 01 FT/SEC	VERTICAL ACCELERATION	* 0.00	FT/SEC#2	
		DENSITY	* 0.230910-02 SLUG/FT#3	ELEVATION DEFLECTION	* 0.00	RADIAN	
		ANGLE OF ATTACK	* 0.101000 00 RADIAN	LIFT COEFFICIENT CL	* 0.106730 01		
		TEMPERATURE	* 0.220400 03 DEG/SEC#2	DWAG COEFFICIENT C1	* 0.106730 00		
		ACCELERATION	* 0.217800 01 FT/SEC#2	POWER AVAILABLE	* 0.105400 36 FT-LW/SEC		
		ANGLE-OF-ATTACK RATE	* 0.203910-03 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.226730-01 RADIAN		
		WEIGHT	* 0.235500 04 LBF	ALTITUDE	* 0.101030 34 FT		
		PITCH ANGLE	* 0.116000 00 RADIAN	ALTITUDE RATE	* 0.118000 01 FT/SEC		
		PITCH RATE	* 0.227080-01 RADIAN/SEC	ALTITUDE-RATE RATE	* 0.227320 01 FT/SEC#2		
		AIRSPED	* 0.151400 01 FT/SEC	VERTICAL ACCELERATION	* 0.00	FT/SEC#2	
		DENSITY	* 0.230910-02 SLUG/FT#3	ELEVATION DEFLECTION	* 0.00	RADIAN	
		ANGLE OF ATTACK	* 0.101000 00 RADIAN	LIFT COEFFICIENT CL	* 0.106730 01		
		TEMPERATURE	* 0.220400 03 DEG/SEC#2	DWAG COEFFICIENT C1	* 0.106730 00		
		ACCELERATION	* 0.217800 01 FT/SEC#2	POWER AVAILABLE	* 0.105400 36 FT-LW/SEC		
		ANGLE-OF-ATTACK RATE	* 0.203910-03 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.226730-01 RADIAN		
		WEIGHT	* 0.235500 04 LBF	ALTITUDE	* 0.101030 34 FT		
		PITCH ANGLE	* 0.116000 00 RADIAN	ALTITUDE RATE	* 0.118000 01 FT/SEC		
		PITCH RATE	* 0.227080-01 RADIAN/SEC	ALTITUDE-RATE RATE	* 0.227320 01 FT/SEC#2		
		AIRSPED	* 0.151400 01 FT/SEC	VERTICAL ACCELERATION	* 0.00	FT/SEC#2	
		DENSITY	* 0.230910-02 SLUG/FT#3	ELEVATION DEFLECTION	* 0.00	RADIAN	
		ANGLE OF ATTACK	* 0.101000 00 RADIAN	LIFT COEFFICIENT CL	* 0.106730 01		
		TEMPERATURE	* 0.220400 03 DEG/SEC#2	DWAG COEFFICIENT C1	* 0.106730 00		
		ACCELERATION	* 0.217800 01 FT/SEC#2	POWER AVAILABLE	* 0.105400 36 FT-LW/SEC		
		ANGLE-OF-ATTACK RATE	* 0.203910-03 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.226730-01 RADIAN		
		WEIGHT	* 0.235500 04 LBF	ALTITUDE	* 0.101030 34 FT		

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		TEMPERATURE	#	0236200 J3 DEGR/SEC	FLIGHT PATH ANGLE	#	0100950 J4
		ACCELERATION	#	0100290 J3 FT/SEC	POWER AVAILABLE	#	0125140 J3 FT-LBF/SEC
		ANGLE-UP-ATTACK RATE	#	0230000 J3 RADIAN/SEC	FLIGHT PATH ANGLE	#	0123900 J3 RADIAN
		WEIGHT	#	0235700 J4 LBF	ALTITUDE	#	0132300 J4 FT
		PITCH ANGLE	#	0230700 J3 RADIAN	ALTITUDE RATE	#	0150110 J2 FT/SEC
		PITCH RATE	#	0231200 J3 RADIAN/SEC	ALTITUDE-RATE RATE	#	0237450 J3 FT/SEC**2
		AIRSPEED	#	0230000 J3 FT/SEC	VERTICAL ACCELERATION	#	0237450 J3 FT/SEC**2
		DENSITY	#	0230770 J2 SLUG/FT**3	ELEVATION DEFLECTION	#	0237450 J3 RADIAN
		ANGLE UP ATTACK	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		TEMPERATURE	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		ACCELERATION	#	0231300 J3 DEGR/SEC	UWAG COEFFICIENT C1	#	0100000 J3
		ANGLE-UP-ATTACK RATE	#	0231300 J3 RADIAN/SEC	POWER AVAILABLE	#	0125140 J3 FT-LBF/SEC
					FLIGHT PATH ANGLE	#	0123900 J3 RADIAN
		WEIGHT	#	0235700 J4 LBF	ALTITUDE	#	0102400 J4 FT
		PITCH ANGLE	#	0230700 J3 RADIAN	ALTITUDE RATE	#	0150110 J2 FT/SEC
		PITCH RATE	#	0231200 J3 RADIAN/SEC	ALTITUDE-RATE RATE	#	0237450 J3 FT/SEC**2
		AIRSPEED	#	0230000 J3 FT/SEC	VERTICAL ACCELERATION	#	0237450 J3 FT/SEC**2
		DENSITY	#	0230770 J2 SLUG/FT**3	ELEVATION DEFLECTION	#	0237450 J3 RADIAN
		ANGLE UP ATTACK	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		TEMPERATURE	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		ACCELERATION	#	0231300 J3 DEGR/SEC	UWAG COEFFICIENT C1	#	0100000 J3
		ANGLE-UP-ATTACK RATE	#	0231300 J3 RADIAN/SEC	POWER AVAILABLE	#	0125140 J3 FT-LBF/SEC
					FLIGHT PATH ANGLE	#	0123900 J3 RADIAN
		WEIGHT	#	0235700 J4 LBF	ALTITUDE	#	0102400 J4 FT
		PITCH ANGLE	#	0230700 J3 RADIAN	ALTITUDE RATE	#	0150110 J2 FT/SEC
		PITCH RATE	#	0231200 J3 RADIAN/SEC	ALTITUDE-RATE RATE	#	0237450 J3 FT/SEC**2
		AIRSPEED	#	0230000 J3 FT/SEC	VERTICAL ACCELERATION	#	0237450 J3 FT/SEC**2
		DENSITY	#	0230770 J2 SLUG/FT**3	ELEVATION DEFLECTION	#	0237450 J3 RADIAN
		ANGLE UP ATTACK	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		TEMPERATURE	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		ACCELERATION	#	0231300 J3 DEGR/SEC	UWAG COEFFICIENT C1	#	0100000 J3
		ANGLE-UP-ATTACK RATE	#	0231300 J3 RADIAN/SEC	POWER AVAILABLE	#	0125140 J3 FT-LBF/SEC
					FLIGHT PATH ANGLE	#	0123900 J3 RADIAN
		WEIGHT	#	0235700 J4 LBF	ALTITUDE	#	0102400 J4 FT
		PITCH ANGLE	#	0230700 J3 RADIAN	ALTITUDE RATE	#	0150110 J2 FT/SEC
		PITCH RATE	#	0231200 J3 RADIAN/SEC	ALTITUDE-RATE RATE	#	0237450 J3 FT/SEC**2
		AIRSPEED	#	0230000 J3 FT/SEC	VERTICAL ACCELERATION	#	0237450 J3 FT/SEC**2
		DENSITY	#	0230770 J2 SLUG/FT**3	ELEVATION DEFLECTION	#	0237450 J3 RADIAN
		ANGLE UP ATTACK	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		TEMPERATURE	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		ACCELERATION	#	0231300 J3 DEGR/SEC	UWAG COEFFICIENT C1	#	0100000 J3
		ANGLE-UP-ATTACK RATE	#	0231300 J3 RADIAN/SEC	POWER AVAILABLE	#	0125140 J3 FT-LBF/SEC
					FLIGHT PATH ANGLE	#	0123900 J3 RADIAN
		WEIGHT	#	0235700 J4 LBF	ALTITUDE	#	0102400 J4 FT
		PITCH ANGLE	#	0230700 J3 RADIAN	ALTITUDE RATE	#	0150110 J2 FT/SEC
		PITCH RATE	#	0231200 J3 RADIAN/SEC	ALTITUDE-RATE RATE	#	0237450 J3 FT/SEC**2
		AIRSPEED	#	0230000 J3 FT/SEC	VERTICAL ACCELERATION	#	0237450 J3 FT/SEC**2
		DENSITY	#	0230770 J2 SLUG/FT**3	ELEVATION DEFLECTION	#	0237450 J3 RADIAN
		ANGLE UP ATTACK	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		TEMPERATURE	#	0231300 J3 DEGR/SEC	LIFT COEFFICIENT CL	#	0100000 J3
		ACCELERATION	#	0231300 J3 DEGR/SEC	UWAG COEFFICIENT C1	#	0100000 J3
		ANGLE-UP-ATTACK RATE	#	0231300 J3 RADIAN/SEC	POWER AVAILABLE	#	0125140 J3 FT-LBF/SEC
					FLIGHT PATH ANGLE	#	0123900 J3 RADIAN

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	TEMPERATURE	# 0.340000 U3 DEGREES-H	UNAV COEFFICIENT CD	# 0.0085700-01
	ACCELERATION	# 0.302150 U3 FT/SEC**2	POWER AVAILABLE	# 0.118820 J1 FT-LB/SEC
	ANGLE-UP-ATTACK RATE	# 0.013500-02 RADIANS/SEC	FLIGHT PATH ANGLE	# 0.173840 U0 RADIANS
	HEIGHT	# 0.356970 U4 LBP	ALTITUDE	# 0.112730 U0 FT
	PITCH ANGLE	# 0.338630 U0 RADIANS	ALTITUDE RATE	# 0.270700 U0 FT/SEC
	PITCH RATE	# 0.000000-01 RADIANS/SEC	ALTITUDE-RATE RATE	# 0.103920 U1 FT/SEC**2
	AIRSPED	# 0.131710 J3 FT/SEC	VERTICAL ACCELERATION	# 0.00 FT/SEC**2
	DENSITY	# 0.004700-02 SLUG/FT**3	ELEVATION DEFLECTION	# 0.00 RADIANS
	ANGLE OF ATTACK	# 0.340000 U3 DEGREES-H	LIFT COEFFICIENT CL	# 0.032630 U0
	TEMPERATURE	# 0.340000 U3 DEGREES-H	DWAG COEFFICIENT CD	# 0.008180-01
	ACCELERATION	# 0.290500 U3 FT/SEC**2	POWER AVAILABLE	# 0.118820 J1 FT-LB/SEC
	ANGLE-UP-ATTACK RATE	# 0.018120-02 RADIANS/SEC	FLIGHT PATH ANGLE	# 0.173330 U0 RADIANS
	HEIGHT	# 0.356970 U4 LBP	ALTITUDE	# 0.112970 U0 FT
	PITCH ANGLE	# 0.338630 U0 RADIANS	ALTITUDE RATE	# 0.269440 U2 FT/SEC
	PITCH RATE	# 0.000000-01 RADIANS/SEC	ALTITUDE-RATE RATE	# 0.128600 U1 FT/SEC**2
	AIRSPED	# 0.131710 J3 FT/SEC	VERTICAL ACCELERATION	# 0.00 FT/SEC**2
	DENSITY	# 0.004700-02 SLUG/FT**3	ELEVATION DEFLECTION	# 0.00 RADIANS
	ANGLE OF ATTACK	# 0.340000 U3 DEGREES-H	LIFT COEFFICIENT CL	# 0.033000 U0
	TEMPERATURE	# 0.340000 U3 DEGREES-H	DWAG COEFFICIENT CD	# 0.008200-01
	ACCELERATION	# 0.290500 U3 FT/SEC**2	POWER AVAILABLE	# 0.118820 J1 FT-LB/SEC
	ANGLE-UP-ATTACK RATE	# 0.018220-02 RADIANS/SEC	FLIGHT PATH ANGLE	# 0.173290 U0 RADIANS
	HEIGHT	# 0.356970 U4 LBP	ALTITUDE	# 0.113240 U0 FT
	PITCH ANGLE	# 0.338630 U0 RADIANS	ALTITUDE RATE	# 0.268640 U2 FT/SEC
	PITCH RATE	# 0.000000-01 RADIANS/SEC	ALTITUDE-RATE RATE	# 0.128600 U1 FT/SEC**2
	AIRSPED	# 0.131710 J3 FT/SEC	VERTICAL ACCELERATION	# 0.00 FT/SEC**2
	DENSITY	# 0.004700-02 SLUG/FT**3	ELEVATION DEFLECTION	# 0.00 RADIANS
	ANGLE OF ATTACK	# 0.340000 U3 DEGREES-H	LIFT COEFFICIENT CL	# 0.033000 U0
	TEMPERATURE	# 0.340000 U3 DEGREES-H	DWAG COEFFICIENT CD	# 0.008200-01
	ACCELERATION	# 0.290500 U3 FT/SEC**2	POWER AVAILABLE	# 0.118820 J1 FT-LB/SEC
	ANGLE-UP-ATTACK RATE	# 0.018230-02 RADIANS/SEC	FLIGHT PATH ANGLE	# 0.173100 U0 RADIANS
	HEIGHT	# 0.356970 U4 LBP	ALTITUDE	# 0.113300 U0 FT
	PITCH ANGLE	# 0.338630 U0 RADIANS	ALTITUDE RATE	# 0.268640 U2 FT/SEC
	PITCH RATE	# 0.000000-01 RADIANS/SEC	ALTITUDE-RATE RATE	# 0.128600 U1 FT/SEC**2
	AIRSPED	# 0.131710 J3 FT/SEC	VERTICAL ACCELERATION	# 0.00 FT/SEC**2
	DENSITY	# 0.004700-02 SLUG/FT**3	ELEVATION DEFLECTION	# 0.00 RADIANS
	ANGLE OF ATTACK	# 0.340000 U3 DEGREES-H	LIFT COEFFICIENT CL	# 0.033000 U0
	TEMPERATURE	# 0.340000 U3 DEGREES-H	DWAG COEFFICIENT CD	# 0.008200-01
	ACCELERATION	# 0.290500 U3 FT/SEC**2	POWER AVAILABLE	# 0.118820 J1 FT-LB/SEC
	ANGLE-UP-ATTACK RATE	# 0.018230-02 RADIANS/SEC	FLIGHT PATH ANGLE	# 0.173100 U0 RADIANS
	HEIGHT	# 0.356970 U4 LBP	ALTITUDE	# 0.113370 U0 FT
	PITCH ANGLE	# 0.338630 U0 RADIANS	ALTITUDE RATE	# 0.268640 U2 FT/SEC
	PITCH RATE	# 0.000000-01 RADIANS/SEC	ALTITUDE-RATE RATE	# 0.128600 U1 FT/SEC**2
	AIRSPED	# 0.131710 J3 FT/SEC	VERTICAL ACCELERATION	# 0.00 FT/SEC**2
	DENSITY	# 0.004700-02 SLUG/FT**3	ELEVATION DEFLECTION	# 0.00 RADIANS
	ANGLE OF ATTACK	# 0.340000 U3 DEGREES-H	LIFT COEFFICIENT CL	# 0.033000 U0
	TEMPERATURE	# 0.340000 U3 DEGREES-H	DWAG COEFFICIENT CD	# 0.008200-01
	ACCELERATION	# 0.290500 U3 FT/SEC**2	POWER AVAILABLE	# 0.118820 J1 FT-LB/SEC
	ANGLE-UP-ATTACK RATE	# 0.018230-02 RADIANS/SEC	FLIGHT PATH ANGLE	# 0.173100 U0 RADIANS
	HEIGHT	# 0.356970 U4 LBP	ALTITUDE	# 0.113370 U0 FT
	PITCH ANGLE	# 0.338630 U0 RADIANS	ALTITUDE RATE	# 0.268640 U2 FT/SEC
	PITCH RATE	# 0.000000-01 RADIANS/SEC	ALTITUDE-RATE RATE	# 0.128600 U1 FT/SEC**2
	AIRSPED	# 0.131710 J3 FT/SEC	VERTICAL ACCELERATION	# 0.00 FT/SEC**2
	DENSITY	# 0.004700-02 SLUG/FT**3	ELEVATION DEFLECTION	# 0.00 RADIANS
	ANGLE OF ATTACK	# 0.340000 U3 DEGREES-H	LIFT COEFFICIENT CL	# 0.033000 U0
	TEMPERATURE	# 0.340000 U3 DEGREES-H	DWAG COEFFICIENT CD	# 0.008200-01
	ACCELERATION	# 0.290500 U3 FT/SEC**2	POWER AVAILABLE	# 0.118820 J1 FT-LB/SEC
	ANGLE-UP-ATTACK RATE	# 0.018230-02 RADIANS/SEC	FLIGHT PATH ANGLE	# 0.173100 U0 RADIANS
	HEIGHT	# 0.356970 U4 LBP	ALTITUDE	# 0.113370 U0 FT
	PITCH ANGLE	# 0.338630 U0 RADIANS	ALTITUDE RATE	# 0.268640 U2 FT/SEC
	PITCH RATE	# 0.000000-01 RADIANS/SEC	ALTITUDE-RATE RATE	# 0.128600 U1 FT/SEC**2
	AIRSPED	# 0.131710 J3 FT/SEC	VERTICAL ACCELERATION	# 0.00 FT/SEC**2
	DENSITY	# 0.004700-02 SLUG/FT**3	ELEVATION DEFLECTION	# 0.00 RADIANS
	ANGLE OF ATTACK	# 0.340000 U3 DEGREES-H	LIFT COEFFICIENT CL	# 0.033000 U0

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	TEMPERATURE	#	0e250000 U3	DEGREES-H	0MAG COEFFICIENT CD	#	0e0e2720-01		
	ACCELERATION	#	0e1e5700 U1	FT/SEC**2	POWER AVAILABLE	#	0e0e2720 00	FT-LB/SEC	SEC
	ANGLE-UP-ATTACK RATE	#	0e2e9500-02	RADIAN/SEC	FLIGHT PATH ANGLE	#	0e131550 00	RADIAN	
	WEIGHT	#	0e309000 U0	LB	ALTITUDE	#	0e118000 00	FT	
	PITCH ANGLE	#	0e4e3200 U0	RADIAN	ALTITUDE RATE	#	0e0e2200 00	FT/SEC	
	PITCH RATE	#	-0e013020-01	RADIAN/SEC	ALTITUDE-RATE RATE	#	-0e0e0e10 U1	FT/SEC**2	
	AIRSPEED	#	0e103800 U3	FT/MIN	VERTICAL ACCELERATION	#	0e0	FT/SEC**2	
	DENSITY	#	0e250700-01	RADIAN/SEC	VERTICAL ACCELERATION	#	0e0	FT/SEC**2	
	ANGLE-UP-ATTACK	#	0e1e4210 U0	RADIAN	LIFT COEFFICIENT CL	#	0e171900 U0		
	TEMPERATURE	#	0e200000 U3	DEGREES-H	DRAW COEFFICIENT CD	#	0e593010-01		
	ACCELERATION	#	0e250700 U1	FT/SEC**2	LIFT COEFFICIENT CL	#	0e0e2720 00	FT-LB/SEC	SEC
	ANGLE-UP-ATTACK RATE	#	-0e0e2150-02	RADIAN/SEC	FLIGHT PATH ANGLE	#	0e120120 00	RADIAN	
	WEIGHT	#	0e309000 U0	LB	ALTITUDE	#	0e118020 00	FT	
	PITCH ANGLE	#	0e4e3190 U0	RADIAN	ALTITUDE RATE	#	0e0e2200 00	FT/SEC	
	PITCH RATE	#	-0e013020-01	RADIAN/SEC	ALTITUDE-RATE RATE	#	-0e0e0e10 U1	FT/SEC**2	
	AIRSPEED	#	0e103800 U3	FT/MIN	VERTICAL ACCELERATION	#	0e0	FT/SEC**2	
	DENSITY	#	0e250600-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0e0	RADIAN	
	ANGLE-UP-ATTACK	#	0e1e4210 U0	RADIAN	LIFT COEFFICIENT CL	#	0e171900 U0		
	TEMPERATURE	#	0e200000 U3	DEGREES-H	DRAW COEFFICIENT CD	#	0e593010-01		
	ACCELERATION	#	0e250700 U1	FT/SEC**2	POWER AVAILABLE	#	0e120020 00	FT-LB/SEC	SEC
	ANGLE-UP-ATTACK RATE	#	-0e0e2150-02	RADIAN/SEC	FLIGHT PATH ANGLE	#	0e120020 00	RADIAN	
	WEIGHT	#	0e309000 U0	LB	ALTITUDE	#	0e118050 00	FT	
	PITCH ANGLE	#	0e4e3200 U0	RADIAN	ALTITUDE RATE	#	0e0e2200 00	FT/SEC	
	PITCH RATE	#	-0e013020-01	RADIAN/SEC	ALTITUDE-RATE RATE	#	-0e0e0e10 U1	FT/SEC**2	
	AIRSPEED	#	0e103800 U3	FT/MIN	VERTICAL ACCELERATION	#	0e0	FT/SEC**2	
	DENSITY	#	0e250600-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0e0	RADIAN	
	ANGLE-UP-ATTACK	#	0e1e4210 U0	RADIAN	LIFT COEFFICIENT CL	#	0e171900 U0		
	TEMPERATURE	#	0e200000 U3	DEGREES-H	DRAW COEFFICIENT CD	#	0e593010-01		
	ACCELERATION	#	0e250700 U1	FT/SEC**2	POWER AVAILABLE	#	0e120020 00	FT-LB/SEC	SEC
	ANGLE-UP-ATTACK RATE	#	-0e0e2150-02	RADIAN/SEC	FLIGHT PATH ANGLE	#	0e121300 00	FT-LB/SEC	SEC
	WEIGHT	#	0e309000 U0	LB	ALTITUDE	#	0e118050 00	FT	
	PITCH ANGLE	#	0e4e3200 U0	RADIAN	ALTITUDE RATE	#	0e0e2200 00	FT/SEC	
	PITCH RATE	#	-0e013020-01	RADIAN/SEC	ALTITUDE-RATE RATE	#	-0e0e0e10 U1	FT/SEC**2	
	AIRSPEED	#	0e103800 U3	FT/MIN	VERTICAL ACCELERATION	#	0e0	FT/SEC**2	
	DENSITY	#	0e250600-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0e0	RADIAN	
	ANGLE-UP-ATTACK	#	0e1e4210 U0	RADIAN	LIFT COEFFICIENT CL	#	0e171900 U0		
	TEMPERATURE	#	0e200000 U3	DEGREES-H	DRAW COEFFICIENT CD	#	0e593010-01		
	ACCELERATION	#	0e250700 U1	FT/SEC**2	POWER AVAILABLE	#	0e120020 00	FT-LB/SEC	SEC
	ANGLE-UP-ATTACK RATE	#	-0e0e2150-02	RADIAN/SEC	FLIGHT PATH ANGLE	#	0e121300 00	FT-LB/SEC	SEC
	WEIGHT	#	0e309000 U0	LB	ALTITUDE	#	0e118050 00	FT	
	PITCH ANGLE	#	0e4e3200 U0	RADIAN	ALTITUDE RATE	#	0e0e2200 00	FT/SEC	
	PITCH RATE	#	-0e013020-01	RADIAN/SEC	ALTITUDE-RATE RATE	#	-0e0e0e10 U1	FT/SEC**2	
	AIRSPEED	#	0e103800 U3	FT/MIN	VERTICAL ACCELERATION	#	0e0	FT/SEC**2	
	DENSITY	#	0e250600-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0e0	RADIAN	
	ANGLE-UP-ATTACK	#	0e1e4210 U0	RADIAN	LIFT COEFFICIENT CL	#	0e171900 U0		
	TEMPERATURE	#	0e200000 U3	DEGREES-H	DRAW COEFFICIENT CD	#	0e593010-01		
	ACCELERATION	#	0e250700 U1	FT/SEC**2	POWER AVAILABLE	#	0e120020 00	FT-LB/SEC	SEC

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	TEMPERATURE	#	0.520000-03	DEGREES-H	DRAQ COEFFICIENT CL I	#	0.447120-03	FT-LBF/SEC
	ACCELERATION	#	0.427500-01	FT/SEC**2	POWER AVAILABLE	#	0.515070-03	FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	#	0.707800-02	RADIANS/SEC	FLIGHT PATH ANGLE	#	0.630240-01	RADIANS
	WEIGHT	#	0.340000-04	LBF	ALTITUDE	#	0.121000-04	FT
	PITCH ANGLE	#	0.113720-00	RADIANS	ALTITUDE RATE	#	0.633470-01	FT/SEC
	PITCH RATE	#	0.303100-01	FT/SEC	ALTITUDE-RATE RATE	#	0.071280-01	FT/SEC**2
	AIR-SPEED	#	0.014680-03	FT/SEC	VERTICAL ACCELERATION	#	0.00	FT/SEC**2
	DENSITY	#	0.289000-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0.00	RADIANS
	ANGLE OF ATTACK	#	0.072640-03	DEGREES-H	LIFT COEFFICIENT CL I	#	0.012800-00	0.00
	TEMPERATURE	#	0.820000-03	DEGREES-H	DRAQ COEFFICIENT CL I	#	0.084400-01	FT-LBF/SEC
	ACCELERATION	#	0.427500-01	FT/SEC**2	POWER AVAILABLE	#	0.515070-03	FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	#	0.707800-02	RADIANS/SEC	FLIGHT PATH ANGLE	#	0.284340-01	RADIANS
	WEIGHT	#	0.340000-04	LBF	ALTITUDE	#	0.121140-04	FT
	PITCH ANGLE	#	0.113980-00	RADIANS	ALTITUDE RATE	#	0.633610-01	FT/SEC
	PITCH RATE	#	0.311000-01	FT/SEC	ALTITUDE-RATE RATE	#	0.071460-01	FT/SEC**2
	AIR-SPEED	#	0.106310-03	FT/SEC	VERTICAL ACCELERATION	#	0.00	FT/SEC**2
	DENSITY	#	0.290000-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0.00	RADIANS
	ANGLE OF ATTACK	#	0.062800-01	DEGREES-H	LIFT COEFFICIENT CL I	#	0.008440-00	0.00
	TEMPERATURE	#	0.820000-03	DEGREES-H	DRAQ COEFFICIENT CL I	#	0.082153-01	FT-LBF/SEC
	ACCELERATION	#	0.424940-01	FT/SEC**2	POWER AVAILABLE	#	0.198230-06	FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	#	0.693510-02	RADIANS/SEC	FLIGHT PATH ANGLE	#	0.338200-01	RADIANS
	WEIGHT	#	0.340000-04	LBF	ALTITUDE	#	0.121190-04	FT
	PITCH ANGLE	#	0.112900-00	RADIANS	ALTITUDE RATE	#	0.633800-01	FT/SEC
	PITCH RATE	#	0.333200-01	RADIANS/SEC	ALTITUDE-RATE RATE	#	0.071580-01	FT/SEC**2
	AIR-SPEED	#	0.106310-03	FT/SEC	VERTICAL ACCELERATION	#	0.00	FT/SEC**2
	DENSITY	#	0.289000-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0.00	RADIANS
	ANGLE OF ATTACK	#	0.062800-01	DEGREES-H	LIFT COEFFICIENT CL I	#	0.008440-00	0.00
	TEMPERATURE	#	0.820000-03	DEGREES-H	DRAQ COEFFICIENT CL I	#	0.071780-01	FT-LBF/SEC
	ACCELERATION	#	0.408890-01	FT/SEC**2	POWER AVAILABLE	#	0.130420-06	FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	#	0.698610-02	RADIANS/SEC	FLIGHT PATH ANGLE	#	0.291890-01	RADIANS
	WEIGHT	#	0.340000-04	LBF	ALTITUDE	#	0.121240-04	FT
	PITCH ANGLE	#	0.111740-00	RADIANS	ALTITUDE RATE	#	0.630770-01	FT/SEC
	PITCH RATE	#	0.333240-01	RADIANS/SEC	ALTITUDE-RATE RATE	#	0.071610-01	FT/SEC**2
	AIR-SPEED	#	0.106250-03	FT/SEC	VERTICAL ACCELERATION	#	0.00	FT/SEC**2
	DENSITY	#	0.289000-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0.00	RADIANS
	ANGLE OF ATTACK	#	0.062140-01	DEGREES-H	LIFT COEFFICIENT CL I	#	0.009810-00	0.00
	TEMPERATURE	#	0.820000-03	DEGREES-H	DRAQ COEFFICIENT CL I	#	0.071620-01	FT-LBF/SEC
	ACCELERATION	#	0.408890-01	FT/SEC**2	POWER AVAILABLE	#	0.130420-06	FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	#	0.679270-02	RADIANS/SEC	FLIGHT PATH ANGLE	#	0.284840-01	RADIANS
	WEIGHT	#	0.340000-04	LBF	ALTITUDE	#	0.121270-04	FT
	PITCH ANGLE	#	0.114420-00	RADIANS	ALTITUDE RATE	#	0.633110-01	FT/SEC
	PITCH RATE	#	0.333200-01	RADIANS/SEC	ALTITUDE-RATE RATE	#	0.071710-01	FT/SEC**2
	AIR-SPEED	#	0.106740-03	FT/SEC	VERTICAL ACCELERATION	#	0.00	FT/SEC**2
	DENSITY	#	0.289000-02	SLUG/FT**3	ELEVATION DEFLECTION	#	0.00	RADIANS
	ANGLE OF ATTACK	#	0.062140-01	DEGREES-H	LIFT COEFFICIENT CL I	#	0.009810-00	0.00
	TEMPERATURE	#	0.820000-03	DEGREES-H	DRAQ COEFFICIENT CL I	#	0.071620-01	FT-LBF/SEC
	ACCELERATION	#	0.408890-01	FT/SEC**2	POWER AVAILABLE	#	0.130420-06	FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	#	0.679200-02	RADIANS/SEC	FLIGHT PATH ANGLE	#	0.198840-01	RADIANS

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	TEMPERATURE	= 0.620000 03 DEG/SEC-R	UWAG COEFFICIENTS CD	= 0.444903-01
	ACCELERATION	= 0.705000 01 FT/SEC^2	POWER AVAILABLE	= 0.139350 06 FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	= -0.549080 -02 RADIAN/SEC	FLIGHT PATH ANGLE	= -0.558810 -01 RADIAN
	HEIGHT	= 0.309940 04 LRF	ALTITUDE	= 0.120840 05 FT
	PITCH ANGLE	= -0.337080 -01 RADIAN	ALTITUDE RATE	= -0.126740 02 FT/SEC
	PITCH RATE	= -0.446870 -01 RADIAN/SEC	ALTITUDE-RATE RATE	= -0.081235 01 FT/SEC^2
	AIR-SPEED	= 0.177400 03 FT/SEC	ELEVATION DEFLECTION	= 0.002350 01 FT/SEC^2
	DENSITY	= 0.285300 -02 SLUG/FT^3	ELEVATION DEFLECTION	= 0.00 RADIAN
	ANGLE OF ATTACK	= 0.001400 -01 RADIAN	LIFT COEFFICIENT CL	= 0.028840 00
	TEMPERATURE	= 0.620000 03 DEG/SEC-R	UWAG COEFFICIENT CD	= 0.444903 -01
	ACCELERATION	= 0.705000 01 FT/SEC^2	POWER AVAILABLE	= 0.139780 06 FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	= -0.541770 -02 RADIAN/SEC	FLIGHT PATH ANGLE	= -0.600250 -01 RADIAN
	HEIGHT	= 0.309940 04 LRF	ALTITUDE	= 0.120830 05 FT
	PITCH ANGLE	= -0.337080 -01 RADIAN	ALTITUDE RATE	= -0.126840 02 FT/SEC
	PITCH RATE	= -0.446870 -01 RADIAN/SEC	ALTITUDE-RATE RATE	= -0.081150 01 FT/SEC^2
	AIR-SPEED	= 0.178130 03 FT/SEC	VERTICAL ACCELERATION	= -0.00 FT/SEC^2
	DENSITY	= 0.225400 -02 SLUG/FT^3	ELEVATION DEFLECTION	= 0.00 RADIAN
	ANGLE OF ATTACK	= 0.001780 02 FT/SEC	LIFT COEFFICIENT CL	= 0.025240 00
	TEMPERATURE	= 0.538020 03 DEG/SEC-R	UWAG COEFFICIENT CD	= 0.442350 -01
	ACCELERATION	= 0.727860 01 FT/SEC^2	POWER AVAILABLE	= 0.139780 06 FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	= -0.530510 -02 RADIAN/SEC	FLIGHT PATH ANGLE	= -0.604820 -01 RADIAN
	HEIGHT	= 0.309940 04 LRF	ALTITUDE	= 0.120410 06 FT
	PITCH ANGLE	= -0.340380 -01 RADIAN	ALTITUDE RATE	= -0.122970 02 FT/SEC
	PITCH RATE	= -0.478810 -01 RADIAN/SEC	ALTITUDE-RATE RATE	= -0.081340 01 FT/SEC^2
	AIR-SPEED	= 0.174880 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC^2
	DENSITY	= 0.225400 -02 SLUG/FT^3	ELEVATION DEFLECTION	= 0.00 RADIAN
	ANGLE OF ATTACK	= 0.002880 02 FT/SEC	LIFT COEFFICIENT CL	= 0.022950 00
	TEMPERATURE	= 0.520000 03 DEG/SEC-R	UWAG COEFFICIENT CD	= 0.440840 -01
	ACCELERATION	= 0.738480 01 FT/SEC^2	POWER AVAILABLE	= 0.100480 06 FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	= -0.527290 -02 RADIAN/SEC	FLIGHT PATH ANGLE	= -0.608070 -01 RADIAN
	HEIGHT	= 0.309940 04 LRF	ALTITUDE	= 0.120280 06 FT
	PITCH ANGLE	= -0.328810 -02 RADIAN	ALTITUDE RATE	= -0.131970 02 FT/SEC
	PITCH RATE	= -0.473020 -01 RADIAN/SEC	ALTITUDE-RATE RATE	= -0.080800 01 FT/SEC^2
	AIR-SPEED	= 0.176800 03 FT/SEC	VERTICAL ACCELERATION	= -0.00 FT/SEC^2
	DENSITY	= 0.225400 -02 SLUG/FT^3	ELEVATION DEFLECTION	= 0.00 RADIAN
	ANGLE OF ATTACK	= 0.002320 -01 RADIAN	LIFT COEFFICIENT CL	= 0.031800 00
	TEMPERATURE	= 0.520000 03 DEG/SEC-R	UWAG COEFFICIENT CD	= 0.443100 -01
	ACCELERATION	= 0.740820 01 FT/SEC^2	POWER AVAILABLE	= 0.100530 06 FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	= -0.520110 -02 RADIAN/SEC	FLIGHT PATH ANGLE	= -0.730410 -01 RADIAN
	HEIGHT	= 0.309940 04 LRF	ALTITUDE	= 0.120150 06 FT
	PITCH ANGLE	= -0.328780 -02 RADIAN	ALTITUDE RATE	= -0.130150 02 FT/SEC
	PITCH RATE	= -0.473020 -01 RADIAN/SEC	ALTITUDE-RATE RATE	= -0.080940 01 FT/SEC^2
	AIR-SPEED	= 0.173380 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC^2
	DENSITY	= 0.225400 -02 SLUG/FT^3	ELEVATION DEFLECTION	= 0.00 RADIAN
	ANGLE OF ATTACK	= 0.002980 01 RADIAN	LIFT COEFFICIENT CL	= 0.031530 00
	TEMPERATURE	= 0.520000 03 DEG/SEC-R	UWAG COEFFICIENT CD	= 0.443700 -01
	ACCELERATION	= 0.750730 01 FT/SEC^2	POWER AVAILABLE	= 0.100700 06 FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	= -0.512490 -02 RADIAN/SEC	FLIGHT PATH ANGLE	= -0.772270 -01 RADIAN
	HEIGHT	= 0.309940 04 LRF	ALTITUDE	= 0.120000 06 FT
	PITCH ANGLE	= -0.326720 -03 RADIAN	ALTITUDE RATE	= -0.131820 02 FT/SEC
	PITCH RATE	= -0.464100 -01 RADIAN/SEC	ALTITUDE-RATE RATE	= -0.081400 01 FT/SEC^2
	AIR-SPEED	= 0.171120 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC^2
	DENSITY	= 0.225400 -02 SLUG/FT^3	ELEVATION DEFLECTION	= 0.00 RADIAN
	ANGLE OF ATTACK	= 0.001290 -01 RADIAN	LIFT COEFFICIENT CL	= 0.032130 00
	TEMPERATURE	= 0.520000 03 DEG/SEC-R	UWAG COEFFICIENT CD	= 0.443700 -01
	ACCELERATION	= 0.750480 01 FT/SEC^2	POWER AVAILABLE	= 0.101040 06 FT-LBF/SEC
	ANGLE-OF-ATTACK RATE	= -0.535930 -02 RADIAN/SEC	FLIGHT PATH ANGLE	= -0.813630 -01 RADIAN
	HEIGHT	= 0.309940 04 LRF	ALTITUDE	= 0.119950 06 FT
	PITCH ANGLE	= -0.326450 -02 RADIAN	ALTITUDE RATE	= -0.135640 02 FT/SEC
	PITCH RATE	= -0.		

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TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.112000-01
ACCELERATION	= 0.92470 01 FT/SEC**2	POWER AVAILABLE	= 0.167800 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= 0.336480-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.109340 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.112900 04 FT
PITCH ANGLE	= -0.101610 00 RADIANS	ALTITUDE RATE	= -0.031360 02 FT/SEC
PITCH RATE	= -0.240000-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.208700 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230000-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.004900-01 RADIANS	LIFT COEFFICIENT CL 1=	0.439070 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.410750-01
ACCELERATION	= 0.92530 01 FT/SEC**2	POWER AVAILABLE	= 0.167800 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= 0.331150-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.171400 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.112900 04 FT
PITCH ANGLE	= -0.101610 00 RADIANS	ALTITUDE RATE	= -0.031360 02 FT/SEC
PITCH RATE	= -0.240000-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.208700 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230000-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.004900-01 RADIANS	LIFT COEFFICIENT CL 1=	0.437200 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.410110-01
ACCELERATION	= 0.92530 01 FT/SEC**2	POWER AVAILABLE	= 0.167800 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= 0.332880-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.173790 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.112900 04 FT
PITCH ANGLE	= -0.101610 00 RADIANS	ALTITUDE RATE	= -0.031360 02 FT/SEC
PITCH RATE	= -0.240000-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.208700 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230000-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.004900-01 RADIANS	LIFT COEFFICIENT CL 1=	0.439460 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.408470-01
ACCELERATION	= 0.920860 01 FT/SEC**2	POWER AVAILABLE	= 0.168300 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= 0.330070-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.175910 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.111920 04 FT
PITCH ANGLE	= -0.109230 00 RADIANS	ALTITUDE RATE	= -0.036930 02 FT/SEC
PITCH RATE	= -0.232000-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.208640 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230130-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.007260-01 RADIANS	LIFT COEFFICIENT CL 1=	0.432960 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.408850-01
ACCELERATION	= 0.903140 01 FT/SEC**2	POWER AVAILABLE	= 0.168800 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= -0.315330-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.177900 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.111400 04 FT
PITCH ANGLE	= -0.111310 00 RADIANS	ALTITUDE RATE	= -0.037800 02 FT/SEC
PITCH RATE	= -0.226000-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.208600 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230150-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.008130-01 RADIANS	LIFT COEFFICIENT CL 1=	0.433080 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.408240-01
ACCELERATION	= 0.900100 01 FT/SEC**2	POWER AVAILABLE	= 0.168700 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= -0.310400-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.179920 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.111070 04 FT
PITCH ANGLE	= -0.111310 00 RADIANS	ALTITUDE RATE	= -0.038730 02 FT/SEC
PITCH RATE	= -0.226000-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.208570 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230180-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.008100-01 RADIANS	LIFT COEFFICIENT CL 1=	0.429040 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.407650-01
ACCELERATION	= 0.906420 01 FT/SEC**2	POWER AVAILABLE	= 0.168900 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= -0.330530-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.181810 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.110690 04 FT
PITCH ANGLE	= -0.115030 00 RADIANS	ALTITUDE RATE	= -0.038630 02 FT/SEC
PITCH RATE	= -0.226170-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.211510 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230200-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.007800-01 RADIANS	LIFT COEFFICIENT CL 1=	0.427140 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.407370-01
ACCELERATION	= 0.906830 01 FT/SEC**2	POWER AVAILABLE	= 0.169080 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= -0.330680-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.183330 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.110300 04 FT
PITCH ANGLE	= -0.117870 00 RADIANS	ALTITUDE RATE	= -0.039160 02 FT/SEC
PITCH RATE	= -0.220200-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.212500 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230220-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.007050-01 RADIANS	LIFT COEFFICIENT CL 1=	0.425240 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.406500-01
ACCELERATION	= 0.909040 01 FT/SEC**2	POWER AVAILABLE	= 0.169280 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= -0.329540-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.185260 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.109940 04 FT
PITCH ANGLE	= -0.119840 00 RADIANS	ALTITUDE RATE	= -0.039470 02 FT/SEC
PITCH RATE	= -0.219280-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.211470 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230240-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.007210-01 RADIANS	LIFT COEFFICIENT CL 1=	0.423410 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.405950-01
ACCELERATION	= 0.907060 01 FT/SEC**2	POWER AVAILABLE	= 0.169440 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= -0.290700-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.187080 00 RADIANS
=====			
HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.109500 04 FT
PITCH ANGLE	= -0.121720 00 RADIANS	ALTITUDE RATE	= -0.040210 02 FT/SEC
PITCH RATE	= -0.214820-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.211840 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230280-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.006920-01 RADIANS	LIFT COEFFICIENT CL 1=	0.421590 00
TEMPERATURE	= 0.820000 03 DEGREES-R	DMAQ COEFFICIENT CD 1=	0.404400-01
ACCELERATION	= 0.907140 01 FT/SEC**2	POWER AVAILABLE	= 0.169640 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	= -0.280900-02 RADIANS/SEC	FLIGHT PATH ANGLE	= -0.188640 00 RADIANS
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HEIGHT	= 0.349930 04 LBF	ALTITUDE	= 0.109100 04 FT
PITCH ANGLE	= -0.123820 00 RADIANS	ALTITUDE RATE	= -0.040780 02 FT/SEC
PITCH RATE	= -0.217600-01 RADIANS/SEC	ALTITUDE-RATE RATE	= -0.015033 01 FT/SEC**2
AIRSPEED	= 0.211840 03 FT/SEC	VERTICAL ACCELERATION	= 0.00 FT/SEC**2
DENSITY	= 0.230300-02 SLUG/FT**3	ELEVATOR DEFLECTION	= 0.00 RADIANS
ANGLE OF ATTACK	= 0.006730-01 RADIANS	LIFT COEFFICIENT CL 1=	0.419810 00

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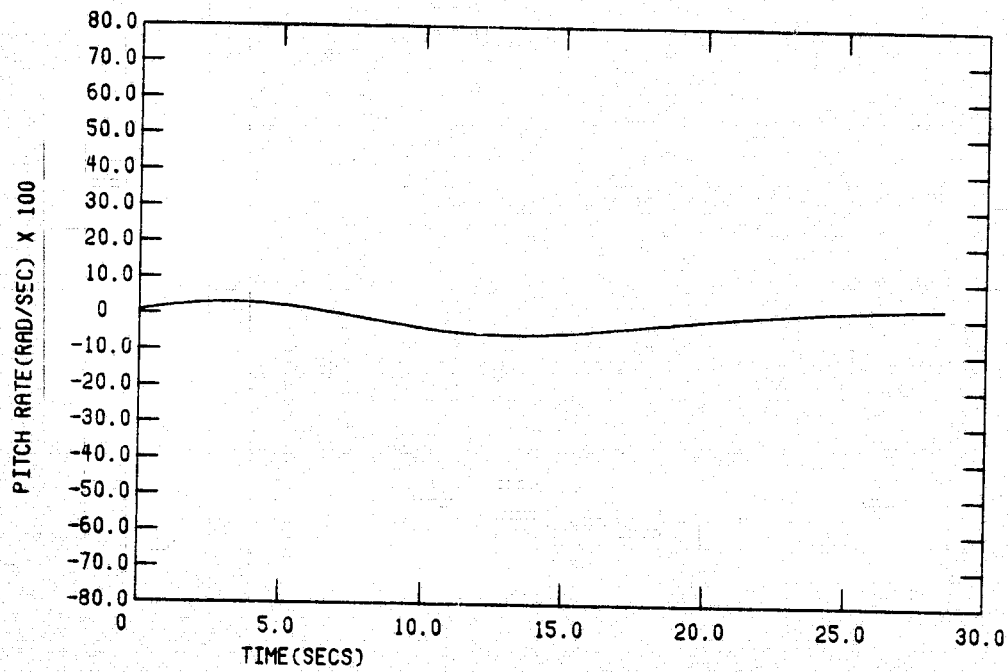
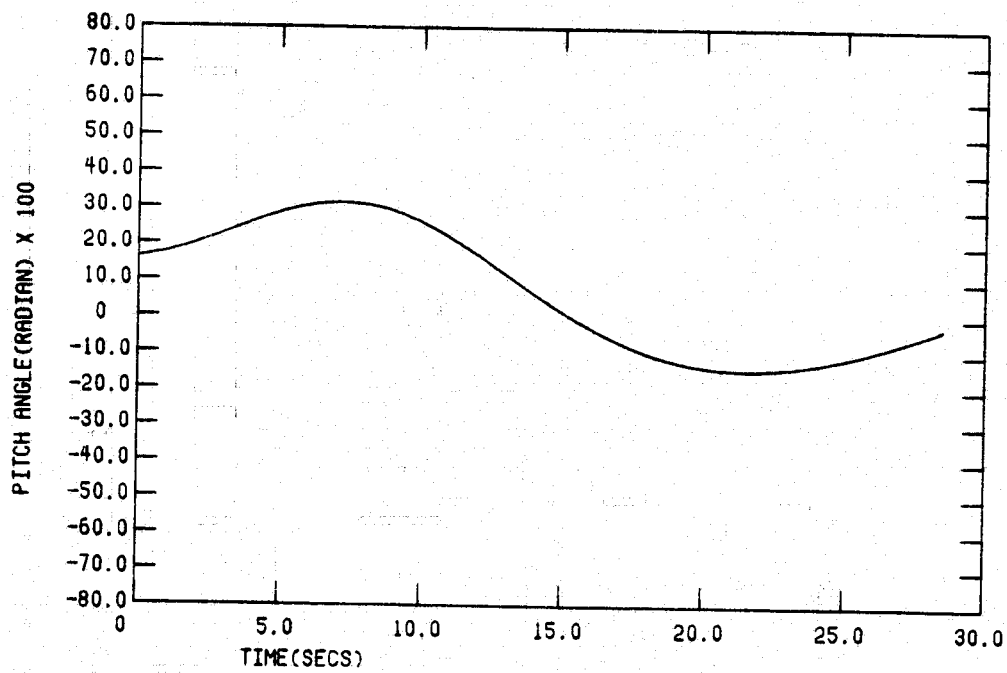
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WEIGHT	* 0.590000 U3 DEG/SEC	ALTITUDE	* 0.736000 U3 FT
PITCH ANGLE	* 0.655800 U1 FT/SEC	ALTITUDE RATE	* 0.472900 U3 FT/SEC
PITCH RATE	* 0.770000 U3 RADIAN/SEC	PITCH PATH ANGLE	* 0.153200 U3 RADIAN
AIRSPEED	* 0.349000 U4 LBF	ALTITUDE	* 0.777400 U3 FT
DENSITY	* 0.694300 U1 RADIAN/SEC	ALTITUDE RATE	* 0.408800 U3 FT/SEC
ANGLE OF ATTACK	* 0.217100 U3 FT/SEC	ALTITUDE-RATE RATE	* 0.497400 U1 FT/SEC
TEMPERATURE	* 0.623800 U2 SLUG/FT	VERTICAL ACCELERATION	* 0.00 FT/SEC
ACCELERATION	* 0.502000 U3 DEG/SEC	ELEVATION DEFLECTION	* 0.00 RADIAN
ANGLE-OF-ATTACK RATE	* 0.080000 U1 FT/SEC	LIFT COEFFICIENT CL	* 0.308000 U0
	* 0.700000 U3 RADIAN/SEC	DRAG COEFFICIENT CD	* 0.308000 U0
		PURCH AVAILABLE	* 0.191800 U3 FT-LBF/SEC
		FLIGHT PATH ANGLE	* 0.151800 U3 RADIAN
WEIGHT	* 0.358800 U4 LBF	ALTITUDE	* 0.775400 U3 FT
PITCH ANGLE	* 0.693300 U1 RADIAN/SEC	ALTITUDE RATE	* 0.403300 U3 FT/SEC
PITCH RATE	* 0.678000 U3 FT/SEC	ALTITUDE-RATE RATE	* 0.410700 U1 FT/SEC
AIRSPEED	* 0.623800 U2 SLUG/FT	VERTICAL ACCELERATION	* 0.00 FT/SEC
DENSITY	* 0.694300 U1 RADIAN/SEC	ELEVATION DEFLECTION	* 0.00 RADIAN
ANGLE OF ATTACK	* 0.217100 U3 FT/SEC	LIFT COEFFICIENT CL	* 0.308000 U0
TEMPERATURE	* 0.502000 U3 DEG/SEC	DRAG COEFFICIENT CD	* 0.308000 U0
ACCELERATION	* 0.080000 U1 FT/SEC	PURCH AVAILABLE	* 0.191800 U3 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	* 0.700000 U3 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.151800 U3 RADIAN
WEIGHT	* 0.359800 U4 LBF	ALTITUDE	* 0.771300 U3 FT
PITCH ANGLE	* 0.691700 U1 RADIAN/SEC	ALTITUDE RATE	* 0.403800 U3 FT/SEC
PITCH RATE	* 0.678000 U3 FT/SEC	ALTITUDE-RATE RATE	* 0.410700 U1 FT/SEC
AIRSPEED	* 0.623800 U2 SLUG/FT	VERTICAL ACCELERATION	* 0.00 FT/SEC
DENSITY	* 0.694300 U1 RADIAN/SEC	ELEVATION DEFLECTION	* 0.00 RADIAN
ANGLE OF ATTACK	* 0.217100 U3 FT/SEC	LIFT COEFFICIENT CL	* 0.308000 U0
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ACCELERATION	* 0.080000 U1 FT/SEC	PURCH AVAILABLE	* 0.191800 U3 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	* 0.700000 U3 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.151800 U3 RADIAN
WEIGHT	* 0.359800 U4 LBF	ALTITUDE	* 0.767300 U3 FT
PITCH ANGLE	* 0.691700 U1 RADIAN/SEC	ALTITUDE RATE	* 0.403800 U3 FT/SEC
PITCH RATE	* 0.678000 U3 FT/SEC	ALTITUDE-RATE RATE	* 0.410700 U1 FT/SEC
AIRSPEED	* 0.623800 U2 SLUG/FT	VERTICAL ACCELERATION	* 0.00 FT/SEC
DENSITY	* 0.694300 U1 RADIAN/SEC	ELEVATION DEFLECTION	* 0.00 RADIAN
ANGLE OF ATTACK	* 0.217100 U3 FT/SEC	LIFT COEFFICIENT CL	* 0.308000 U0
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WEIGHT	* 0.359800 U4 LBF	ALTITUDE	* 0.763300 U3 FT
PITCH ANGLE	* 0.691700 U1 RADIAN/SEC	ALTITUDE RATE	* 0.403800 U3 FT/SEC
PITCH RATE	* 0.678000 U3 FT/SEC	ALTITUDE-RATE RATE	* 0.410700 U1 FT/SEC
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ANGLE-OF-ATTACK RATE	* 0.700000 U3 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.151800 U3 RADIAN
WEIGHT	* 0.359800 U4 LBF	ALTITUDE	* 0.759800 U3 FT
PITCH ANGLE	* 0.691700 U1 RADIAN/SEC	ALTITUDE RATE	* 0.403800 U3 FT/SEC
PITCH RATE	* 0.678000 U3 FT/SEC	ALTITUDE-RATE RATE	* 0.410700 U1 FT/SEC
AIRSPEED	* 0.623800 U2 SLUG/FT	VERTICAL ACCELERATION	* 0.00 FT/SEC
DENSITY	* 0.694300 U1 RADIAN/SEC	ELEVATION DEFLECTION	* 0.00 RADIAN
ANGLE OF ATTACK	* 0.217100 U3 FT/SEC	LIFT COEFFICIENT CL	* 0.308000 U0
TEMPERATURE	* 0.502000 U3 DEG/SEC	DRAG COEFFICIENT CD	* 0.308000 U0
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ANGLE-OF-ATTACK RATE	* 0.700000 U3 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.151800 U3 RADIAN
WEIGHT	* 0.359800 U4 LBF	ALTITUDE	* 0.755800 U3 FT
PITCH ANGLE	* 0.691700 U1 RADIAN/SEC	ALTITUDE RATE	* 0.403800 U3 FT/SEC
PITCH RATE	* 0.678000 U3 FT/SEC	ALTITUDE-RATE RATE	* 0.410700 U1 FT/SEC
AIRSPEED	* 0.623800 U2 SLUG/FT	VERTICAL ACCELERATION	* 0.00 FT/SEC
DENSITY	* 0.694300 U1 RADIAN/SEC	ELEVATION DEFLECTION	* 0.00 RADIAN
ANGLE OF ATTACK	* 0.217100 U3 FT/SEC	LIFT COEFFICIENT CL	* 0.308000 U0
TEMPERATURE	* 0.502000 U3 DEG/SEC	DRAG COEFFICIENT CD	* 0.308000 U0
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ANGLE-OF-ATTACK RATE	* 0.700000 U3 RADIAN/SEC	FLIGHT PATH ANGLE	* 0.151800 U3 RADIAN
WEIGHT	* 0.359800 U4 LBF	ALTITUDE	* 0.751800 U3 FT
PITCH ANGLE	* 0.691700 U1 RADIAN/SEC	ALTITUDE RATE	* 0.403800 U3 FT/SEC
PITCH RATE	* 0.678000 U3 FT/SEC	ALTITUDE-RATE RATE	* 0.410700 U1 FT/SEC
AIRSPEED	* 0.623800 U2 SLUG/FT	VERTICAL ACCELERATION	

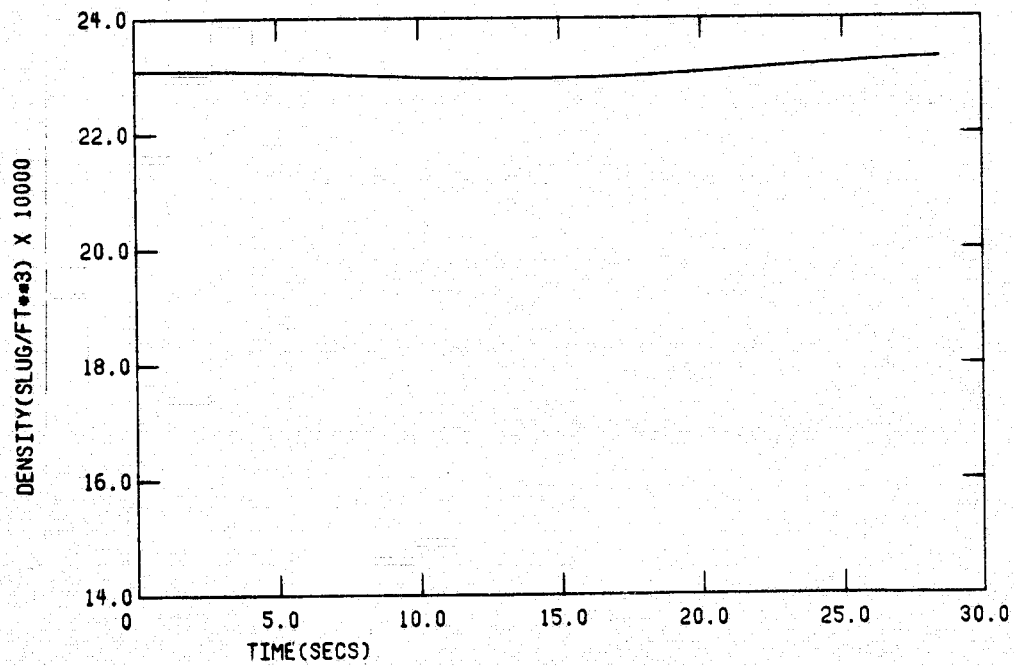
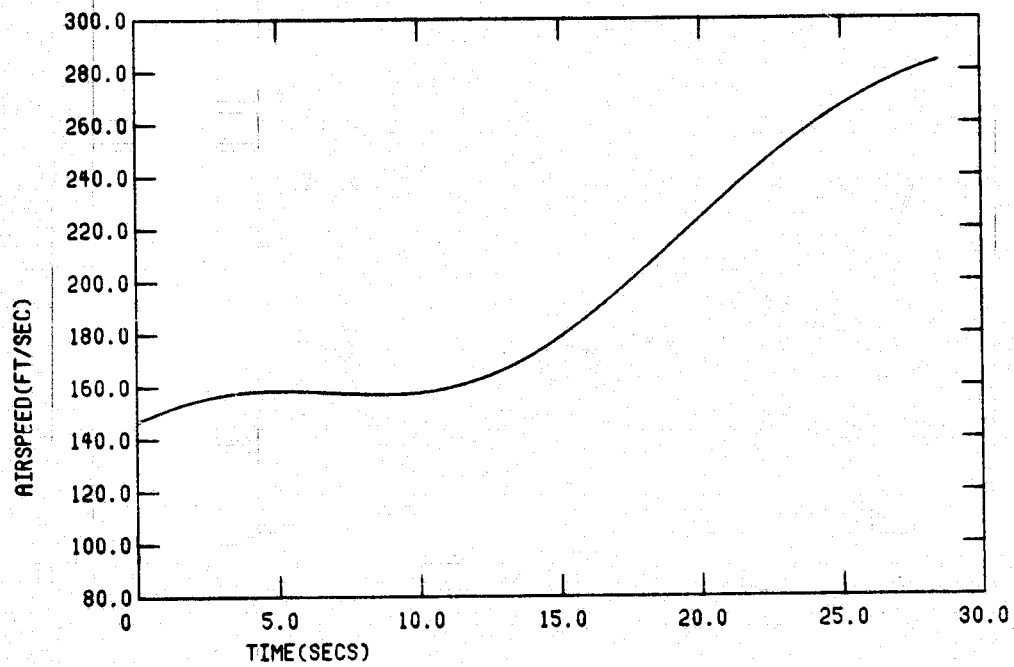
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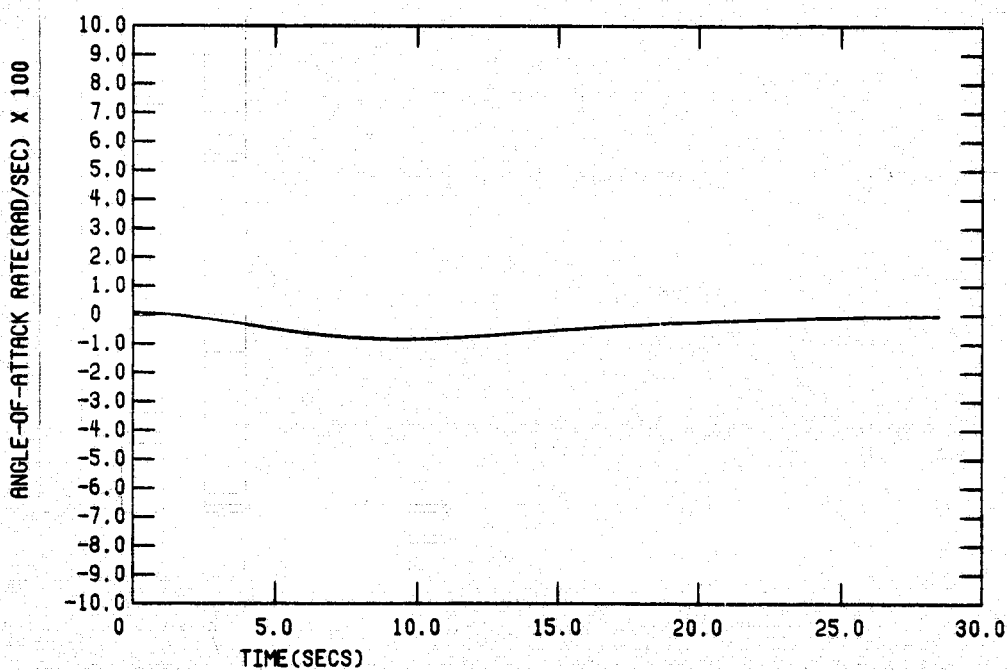
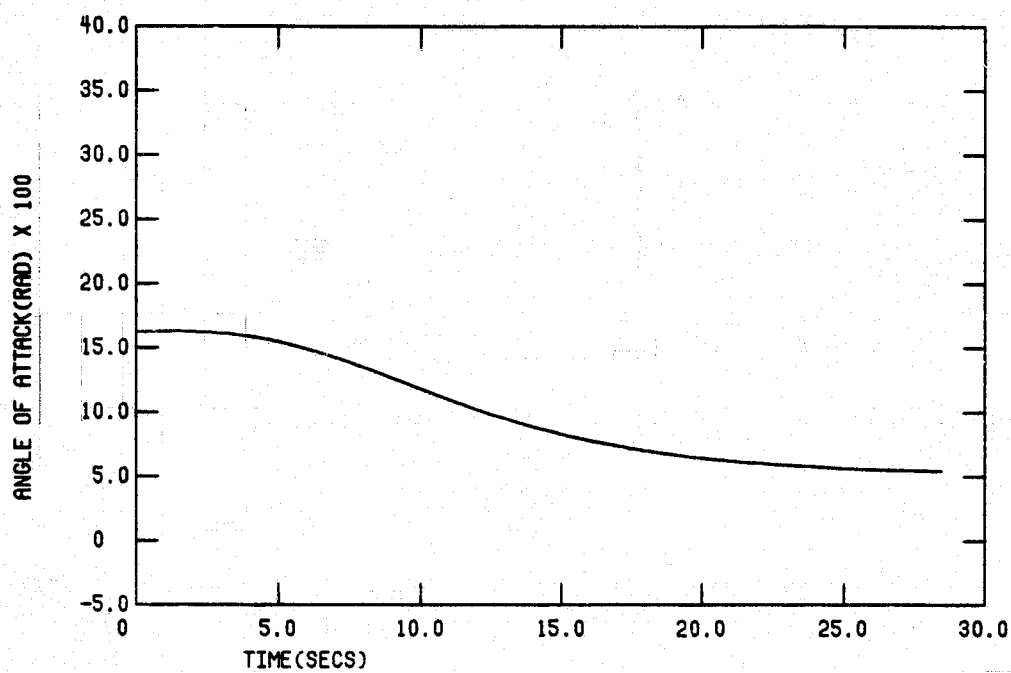
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ACCELERATION	0.318880 J1 FT/SEC	POWER AVAILABLE	0.171940 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	0.313510 J3 RADIAN/SEC	FLIGHT PATH ANGLE	0.068900 31 RADIAN
=====			
WEIGHT	0.314480 04 LBF	ALTITUDE	0.703770 03 FT
PITCH ANGLE	0.417580 J1 RADIAN	ALTITUDE RATE	0.270360 02 FT/SEC
PITCH RATE	0.272360 J1 RADIAN/SEC	ALTITUDE-RATE RATE	0.740740 01 FT/SEC
AIR SPEED	0.281740 J3 FT/SEC	VERTICAL ACCELERATION	0.00 FT/SEC
DENSITY	0.228950 J2 SLUG/FT	ELEVATOR DEFLECTION	0.00 RADIAN
ANGLE OF ATTACK	0.544310 J1 RADIAN	LIFT COEFFICIENT CL	0.342900 08
TEMPERATURE	0.362000 J3 DEG/SEC	UNAG COEFFICIENT CD	0.384710 01
ACCELERATION	0.318880 J1 FT/SEC	POWER AVAILABLE	0.171880 08 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	0.313510 J3 RADIAN/SEC	FLIGHT PATH ANGLE	0.068187 01 RADIAN
=====			
WEIGHT	0.314480 04 LBF	ALTITUDE	0.701100 03 FT
PITCH ANGLE	0.417580 J1 RADIAN	ALTITUDE RATE	0.269330 02 FT/SEC
PITCH RATE	0.272360 J1 RADIAN/SEC	ALTITUDE-RATE RATE	0.740740 01 FT/SEC
AIR SPEED	0.281740 J3 FT/SEC	VERTICAL ACCELERATION	0.00 FT/SEC
DENSITY	0.228950 J2 SLUG/FT	ELEVATOR DEFLECTION	0.00 RADIAN
ANGLE OF ATTACK	0.544310 J1 RADIAN	LIFT COEFFICIENT CL	0.342900 08
TEMPERATURE	0.362000 J3 DEG/SEC	UNAG COEFFICIENT CD	0.384660 01
ACCELERATION	0.318880 J1 FT/SEC	POWER AVAILABLE	0.171880 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	0.313510 J3 RADIAN/SEC	FLIGHT PATH ANGLE	0.068310 01 RADIAN
=====			
WEIGHT	0.314480 04 LBF	ALTITUDE	0.698510 03 FT
PITCH ANGLE	0.417580 J1 RADIAN	ALTITUDE RATE	0.268600 02 FT/SEC
PITCH RATE	0.272360 J1 RADIAN/SEC	ALTITUDE-RATE RATE	0.740740 01 FT/SEC
AIR SPEED	0.281740 J3 FT/SEC	VERTICAL ACCELERATION	0.00 FT/SEC
DENSITY	0.228950 J2 SLUG/FT	ELEVATOR DEFLECTION	0.00 RADIAN
ANGLE OF ATTACK	0.544310 J1 RADIAN	LIFT COEFFICIENT CL	0.342900 08
TEMPERATURE	0.362000 J3 DEG/SEC	UNAG COEFFICIENT CD	0.384660 01
ACCELERATION	0.318880 J1 FT/SEC	POWER AVAILABLE	0.171880 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	0.313510 J3 RADIAN/SEC	FLIGHT PATH ANGLE	0.068220 01 RADIAN
=====			
WEIGHT	0.314480 04 LBF	ALTITUDE	0.695890 03 FT
PITCH ANGLE	0.417580 J1 RADIAN	ALTITUDE RATE	0.267890 02 FT/SEC
PITCH RATE	0.272360 J1 RADIAN/SEC	ALTITUDE-RATE RATE	0.740740 01 FT/SEC
AIR SPEED	0.281740 J3 FT/SEC	VERTICAL ACCELERATION	0.00 FT/SEC
DENSITY	0.228950 J2 SLUG/FT	ELEVATOR DEFLECTION	0.00 RADIAN
ANGLE OF ATTACK	0.544310 J1 RADIAN	LIFT COEFFICIENT CL	0.342900 08
TEMPERATURE	0.362000 J3 DEG/SEC	UNAG COEFFICIENT CD	0.384660 01
ACCELERATION	0.318880 J1 FT/SEC	POWER AVAILABLE	0.171880 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	0.313510 J3 RADIAN/SEC	FLIGHT PATH ANGLE	0.068180 01 RADIAN
=====			
WEIGHT	0.314480 04 LBF	ALTITUDE	0.693350 03 FT
PITCH ANGLE	0.417580 J1 RADIAN	ALTITUDE RATE	0.267080 02 FT/SEC
PITCH RATE	0.272360 J1 RADIAN/SEC	ALTITUDE-RATE RATE	0.740740 01 FT/SEC
AIR SPEED	0.281740 J3 FT/SEC	VERTICAL ACCELERATION	0.00 FT/SEC
DENSITY	0.228950 J2 SLUG/FT	ELEVATOR DEFLECTION	0.00 RADIAN
ANGLE OF ATTACK	0.544310 J1 RADIAN	LIFT COEFFICIENT CL	0.342900 08
TEMPERATURE	0.362000 J3 DEG/SEC	UNAG COEFFICIENT CD	0.384660 01
ACCELERATION	0.318880 J1 FT/SEC	POWER AVAILABLE	0.171880 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	0.313510 J3 RADIAN/SEC	FLIGHT PATH ANGLE	0.068030 01 RADIAN
=====			
WEIGHT	0.314480 04 LBF	ALTITUDE	0.691180 03 FT
PITCH ANGLE	0.417580 J1 RADIAN	ALTITUDE RATE	0.266250 02 FT/SEC
PITCH RATE	0.272360 J1 RADIAN/SEC	ALTITUDE-RATE RATE	0.740740 01 FT/SEC
AIR SPEED	0.281740 J3 FT/SEC	VERTICAL ACCELERATION	0.00 FT/SEC
DENSITY	0.228950 J2 SLUG/FT	ELEVATOR DEFLECTION	0.00 RADIAN
ANGLE OF ATTACK	0.544310 J1 RADIAN	LIFT COEFFICIENT CL	0.342900 08
TEMPERATURE	0.362000 J3 DEG/SEC	UNAG COEFFICIENT CD	0.384660 01
ACCELERATION	0.318880 J1 FT/SEC	POWER AVAILABLE	0.171880 36 FT-LBF/SEC
ANGLE-OF-ATTACK RATE	0.313510 J3 RADIAN/SEC	FLIGHT PATH ANGLE	0.068130 01 RADIAN

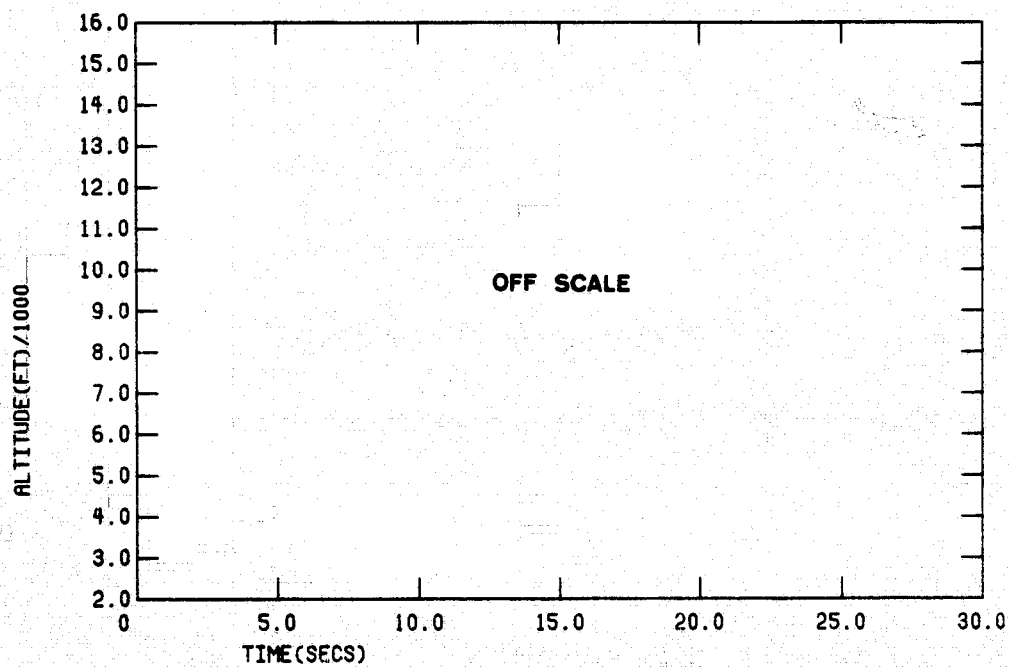
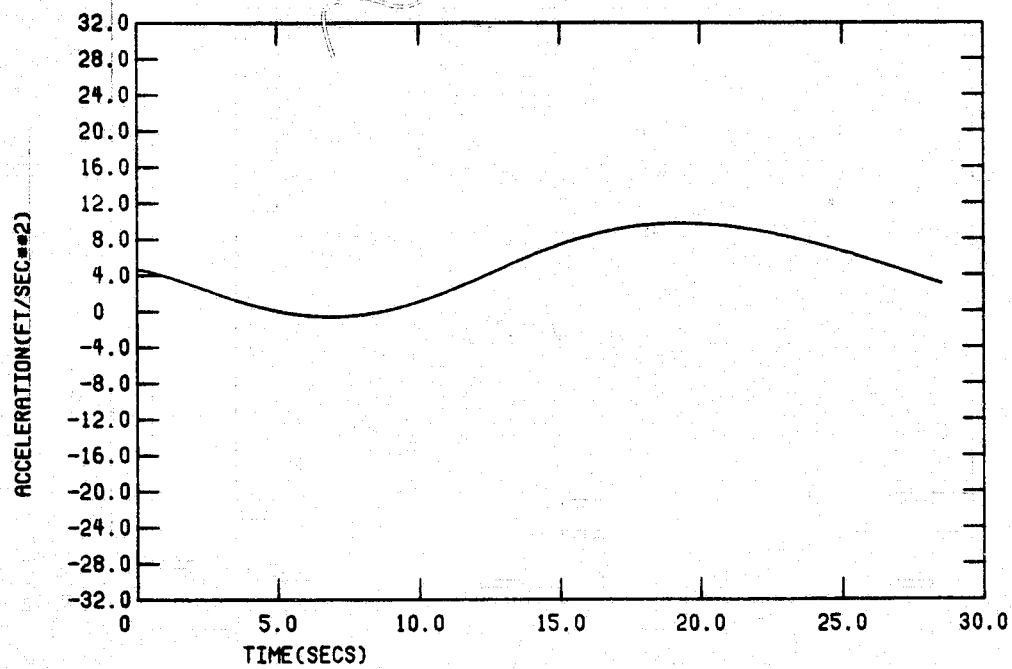


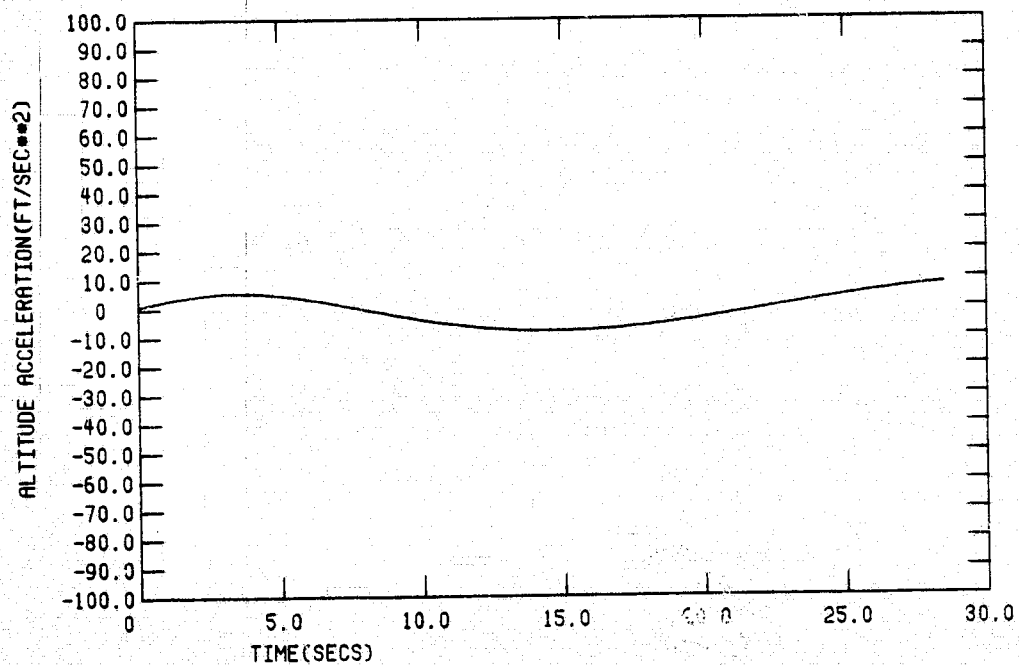
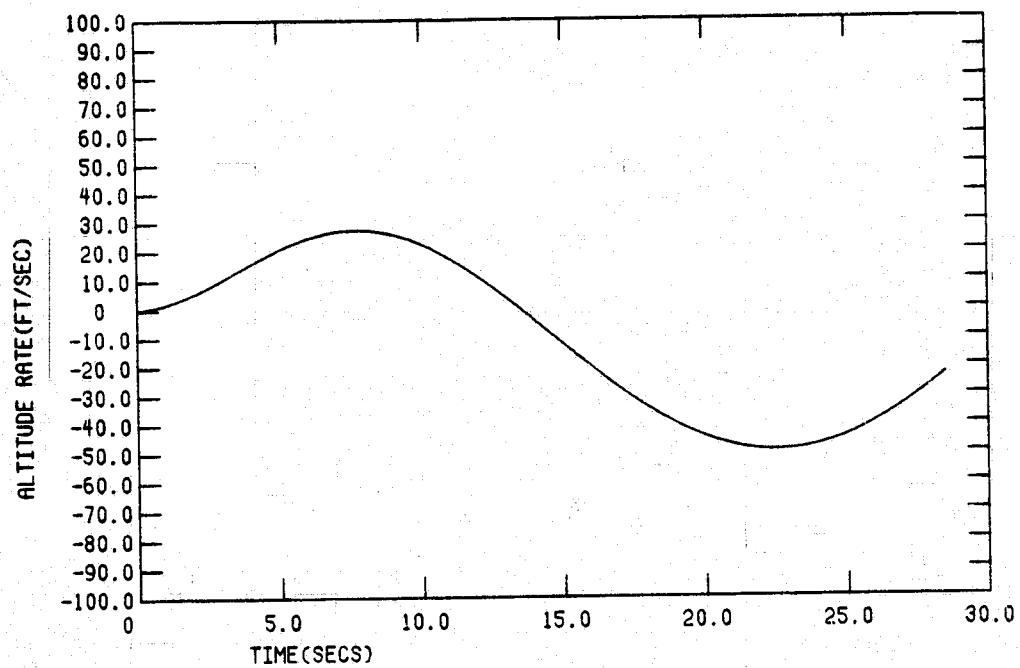
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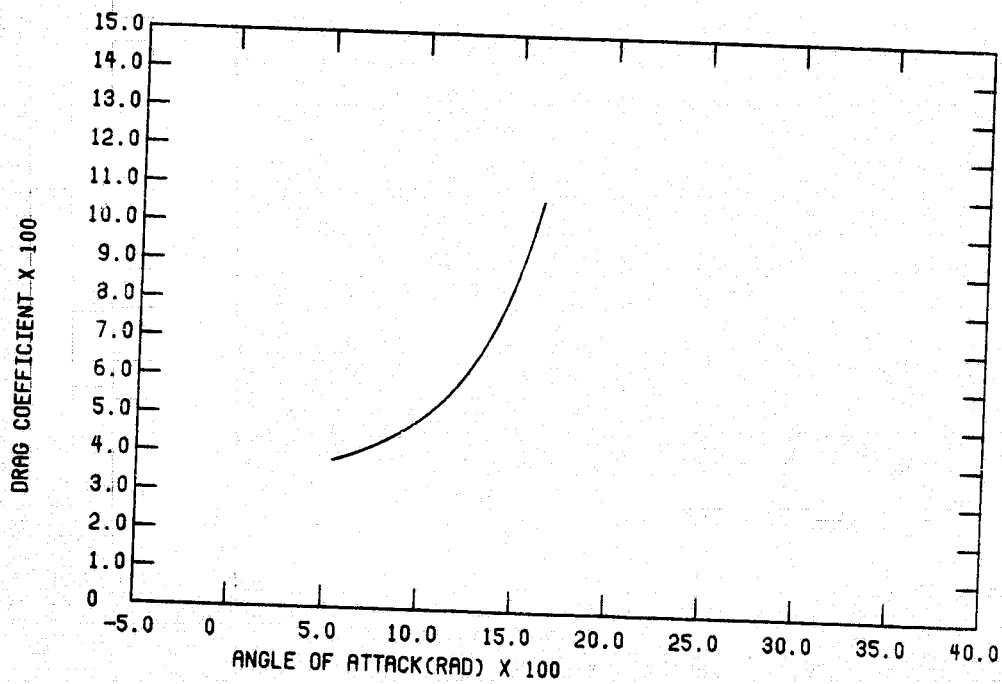
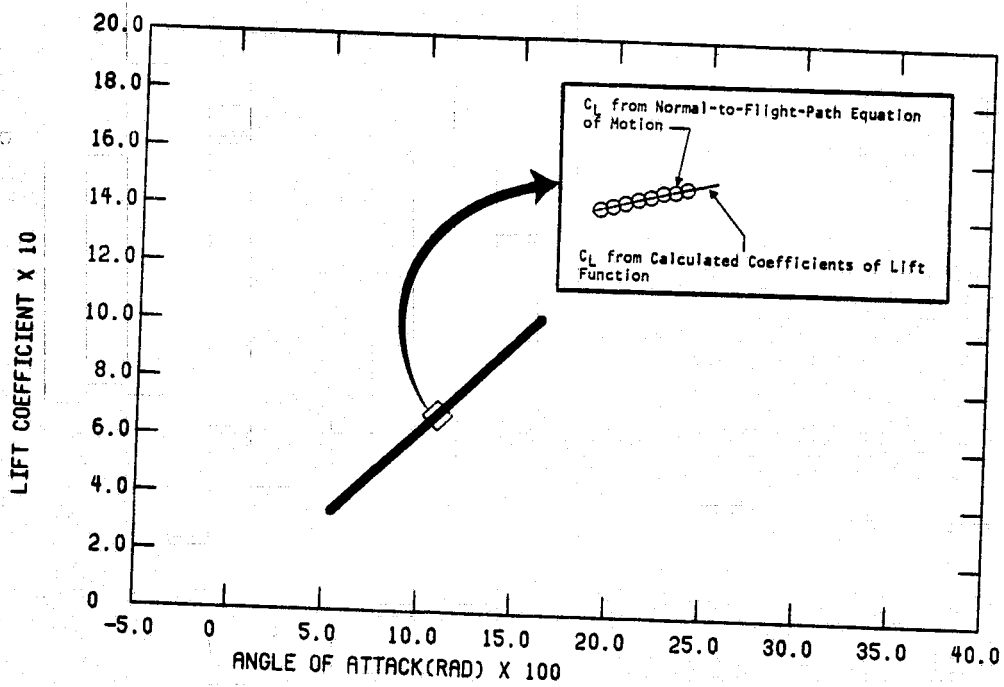


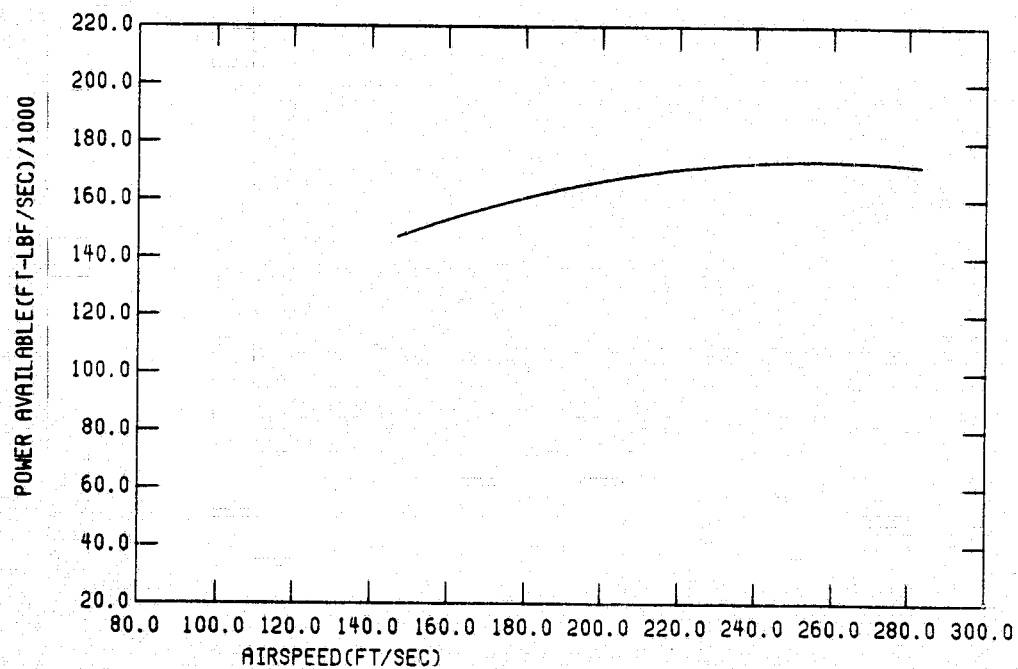
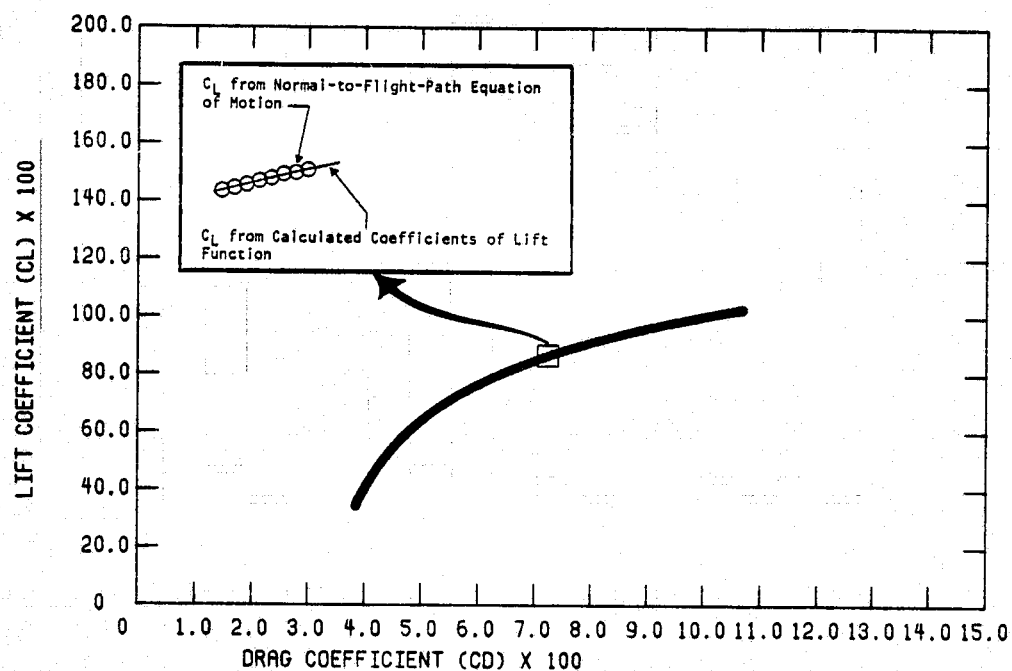
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The sample output reproduced here is intended to show generally the type of output which will be obtained from the program, including the final data format and the plotted results. Because only six iterations of the Newton-Raphson procedure were used in the interests of saving computer time and report space, the results are not as accurate as those which can be obtained with additional iterations. As mentioned earlier, with 29 iterations a fit error of 1.33×10^{-13} was obtained in contrast to the present value of 5×10^{-9} . Each additional iteration requires an average of 7 minutes of computer time on the local computer (IBM 370/165). Approximately 4 minutes is required for compilation and linking and 20 minutes for execution of the preliminary procedures, final data computation, and plotting. A full 29 iterations would therefore require about 227 minutes. The results shown here accomplished compile, link, and go in 55 minutes. All times are approximate because actual computational time is dependent on the computer workload at the time the job is processed.

One final note: FDR2 employs the subroutine LLSQAR to solve systems of equations of the type $Ax = b$ by obtaining the pseudo-inverse of A . This is a computing center library routine. It was selected from among the available library routines after some experimentation because it yielded the best results. The superior results are thought to be due to its use of double length words (i.e., 32 decimal digits) for the matrix multiplications and additions, a feature shared by none of the other library routines. Since the A matrices found in FDR2 are always somewhat ill-conditioned, this additional precision is apparently necessary to obtain reasonable results. In fact, additional precision beyond 32 decimal digits would be desirable because tests of the product AA^{-1} or $A^{-1}A$ indicate that the size of the off-diagonal elements may vary from 10^{-7} to 10^{-18} times the size of the diagonal elements. Since the routines which perform the double word arithmetic in LLSQAR are available locally only in assembler versions, they are not reproduced here. The reader desiring to install FDR2 at his own installation should substitute some alternate matrix solver for LLSQAR, taking care to provide at least 32 decimal digit precision.